

# Challenges and Progress Toward Efficient Gradual Typing

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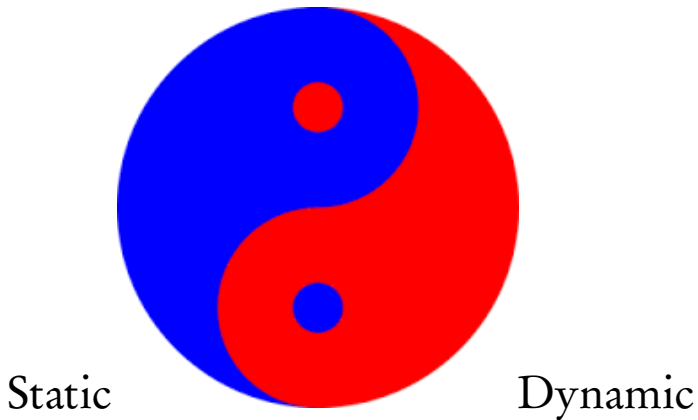


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Dynamic Languages  
Symposium  
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# Gradual Typing



# Efficient gradual typing

- ▶ Background on Gradual Typing
- ▶ Challenges to Efficiency
- ▶ Space-efficient Coercions
- ▶ Monotonic Coercions
- ▶ Performance Comparison

# Gradual typing includes dynamic typing

An untyped program:

```
let  
   $f = \lambda y. 1 + y$   
   $h = \lambda g. g \ 3$   
in  
   $h \ f$   
→  
4
```

# Gradual typing includes dynamic typing

A buggy untyped program:

```
let  
   $f = \lambda y. 1 + y$   
   $h = \lambda g. g$  true  
in  
   $h\ f$   
 $\longrightarrow$   
blame  $\ell_2$ 
```

Just like dynamic typing, the error is caught at run time.

# Gradual typing includes static typing

A typed program:

```
let  
   $f = \lambda y:\text{Int}. 1 + y$   
   $h = \lambda g:\text{Int} \rightarrow \text{Int}. g\ 3$   
in  
   $h\ f$   
 $\longrightarrow$   
  4
```

# Gradual typing includes static typing

An ill-typed program:

```
let  
   $f = \lambda y:\text{Int}. 1 + y$   
   $h = \lambda g:\text{Int} \rightarrow \text{Int}. g$  true  
in  
   $h\ f$ 
```

Just like static typing, the error is caught at compile time.

# Gradual typing provides fine-grained mixing

A partially typed program:

```
let  
   $f = \lambda y:\text{Int}. 1 + y$   
   $h = \lambda g. g \ 3$   
in  
   $h \ f$   
→  
4
```



# Gradual typing protects type invariants

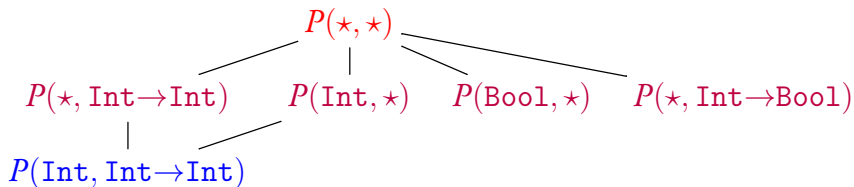
A buggy, partially typed program:

```
let  
   $f = \lambda y: \text{Int}. 1 + y$   
   $h = \lambda g.g \text{ true}$   
in  
   $h f$   
→  
  blame  $\ell_3$ 
```

The error is caught at runtime when the value is cast to an inconsistent type.

# Gradual typing enables migration

$$P(T_1, T_2) \equiv \begin{array}{l} \text{let} \\ \quad f = \lambda y:T_1. 1 + y \\ \quad h = \lambda g:T_2. g \ 3 \\ \text{in} \\ \quad h \ f \end{array}$$



“Configuration Lattice”

# Gradual type systems

The **consistency** relation governs implicit casts involving  $\star$ .

- ▶ For nominal type systems  
Anderson and Drossopoulou, WOOD 2003.

$$T_1 \sim T_2 \text{ iff } T_1 = T_2 \text{ or } T_1 = \star \text{ or } T_2 = \star$$

- ▶ For structural type systems  
Siek and Taha, SFP 2006.

$$\frac{}{T \sim \star} \quad \frac{}{\star \sim T} \quad \text{Int} \sim \text{Int}$$
$$\frac{T_1 \sim T_3 \quad T_2 \sim T_4}{T_1 \rightarrow T_2 \sim T_3 \rightarrow T_4}$$

Consistency is symmetric but not transitive.

1. Replace equality with consistency
2. Add rules for the unknown type  $\star$

Typing rules for functions:

$$\frac{\Gamma, x : T \vdash e : T'}{\Gamma \vdash (\lambda x : T. e) : T \rightarrow T'} \quad \frac{\Gamma \vdash e_1 : T \rightarrow T' \quad \Gamma \vdash e_2 : T}{\Gamma \vdash e_1 \ e_2 : T'}$$

Gradual typing rules for functions:

$$\frac{\Gamma, x : T \vdash e : T'}{\Gamma \vdash (\lambda x : T. e) : T \rightarrow T'}$$

$$\frac{\Gamma \vdash e_1 : T \rightarrow T' \quad \Gamma \vdash e_2 : T_2 \quad T \sim T_2}{\Gamma \vdash e_1 \ e_2 : T'} \quad \frac{\Gamma \vdash e_1 : \star \quad \Gamma \vdash e_2 : T_2}{\Gamma \vdash e_1 \ e_2 : \star}$$

# Protecting the static from the dynamic

Recall the following buggy, partially typed program:

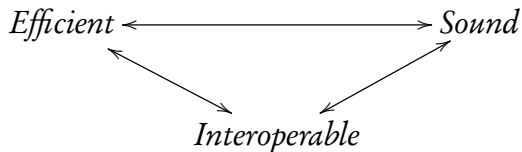
```
let
   $f = \lambda y : \text{Int}. 1 + y$ 
   $h = \lambda g. g \text{ true}$ 
in
   $h f$ 
```

The untyped code tries to pass the Boolean `true` to parameter  $y$  of type `Int`.

Alternative ways to deal with this:

- ▶ erase types,
- ▶ insert casts, or
- ▶ limit interoperability.

# There is tension in the design space



Approach	Sound	Efficient	Interoperable
erase types	◐	◐	●
insert casts	●	◐	●
limit interop.	●	●	◐

# Approach: limit interoperability

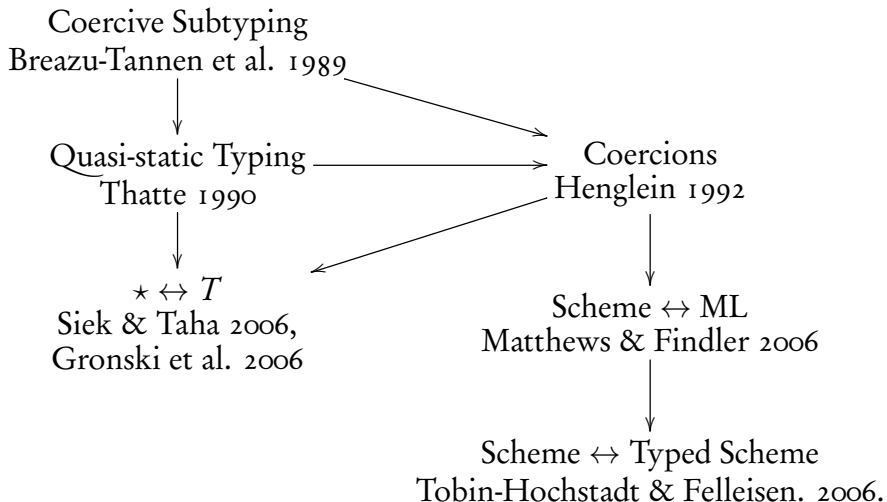
A number of proposed designs place restrictions on passing values between static and dynamic regions.

- ▶ Siek and Taha. SFP 2006. (wrt. mutable references)
- ▶ Wrigstad et al. POPL 2010.
- ▶ Allende et al. OOPSLA 2014.
- ▶ Swamy et al. POPL 2014.

It's debatable whether these designs support gradual typing.

In particular, they do not satisfy the *gradual guarantee*.  
(*Refined Criteria for Gradual Typing*. Siek et al. SNAPL 2015.)

# Approach: insert casts





# Approach: insert casts

Compile the GTLC to STLC + casts.

A cast has the form

$$e' : T_1 \Rightarrow T_2$$

$$\boxed{\Gamma \vdash e \rightsquigarrow e' : T}$$

$$\frac{\Gamma \vdash e_1 \rightsquigarrow e'_1 : T \rightarrow T' \quad \Gamma \vdash e_2 \rightsquigarrow e'_2 : T_2 \quad T_2 \sim T}{\Gamma \vdash e_1 \ e_2 \rightsquigarrow e'_1 \ (e'_2 : T_2 \Rightarrow T) : T'}$$
$$\frac{\Gamma \vdash e_1 \rightsquigarrow e'_1 : \star \quad \Gamma \vdash e_2 \rightsquigarrow e'_2 : T_2}{\Gamma \vdash e_1 \ e_2 \rightsquigarrow (e'_1 : \star \Rightarrow \star \rightarrow \star) \ (e'_2 : T_2 \Rightarrow \star) : \star}$$

# Operational semantics of casts

Base types	$B ::= \text{Int} \mid \text{Bool}$
Injection types	$I ::= B \mid \star \rightarrow \star$
Values	$v ::= n \mid b \mid \lambda x:T. e \mid$ $v : I \Rightarrow \star \mid v : T \rightarrow T \Rightarrow T \rightarrow T$

$$(v : I \Rightarrow \star) : \star \Rightarrow I \longrightarrow v$$

$$(v : I \Rightarrow \star) : \star \Rightarrow I' \longrightarrow \text{blame} \quad \text{if } I \neq I'$$

$$v : B \Rightarrow B \longrightarrow v$$

$$v : \star \Rightarrow \star \longrightarrow v$$

$$(v : T_1 \rightarrow T_2 \Rightarrow T'_1 \rightarrow T'_2) \ v' \longrightarrow v \ (v' : T'_1 \Rightarrow T_1) : T_2 \Rightarrow T'_2$$

$$v : T \Rightarrow \star \longrightarrow (v : T \Rightarrow I) : I \Rightarrow \star^\dagger$$

$$v : \star \Rightarrow T \longrightarrow (v : \star \Rightarrow I) : I \Rightarrow T^\dagger$$

$^\dagger$  if  $T \sim I$ ,  $T \neq I$ , and  $T \neq \star$

# The Buggy Example Revisited

```
let
  f = λy:Int. 1 + y
  h = λg:★. (g : ★ ⇒ ★→★) (true : Bool ⇒ ★)
in
  h (f : Int→Int ⇒ ★)
  →*
  (f : Int→Int ⇒ ★→★) (true : Bool ⇒ ★)
  →
  (f (true : Bool ⇒ ★ ⇒ Int) : Int ⇒ ★)
  →
  (f blame) : Int ⇒ ★
  →
  blame
```

# Efficient gradual typing

- ▶ Background on Gradual Typing
- ▶ **Challenges to Efficiency**
- ▶ Space-efficient Coercions
- ▶ Monotonic Coercions
- ▶ Performance Comparison

# Casts can consume unbounded space

```
let rec even(n:Int) : ★ =  
  if n = 0 then true  
  else odd(n - 1)
```

```
let rec odd(n:Int) : Bool =  
  if n = 0 then false  
  else even(n - 1)
```

# Casts can consume unbounded space

```
let rec even(n:Int) : ★ =  
  if n = 0 then (true : Bool ⇒ ★)  
  else (odd(n - 1) : Bool ⇒ ★)
```

```
let rec odd(n:Int) : Bool =  
  if n = 0 then false  
  else (even(n - 1) : ★ ⇒ Bool)
```

# Casts can consume unbounded space

*even*(5)

→ *odd*(4) : Bool ⇒ \*

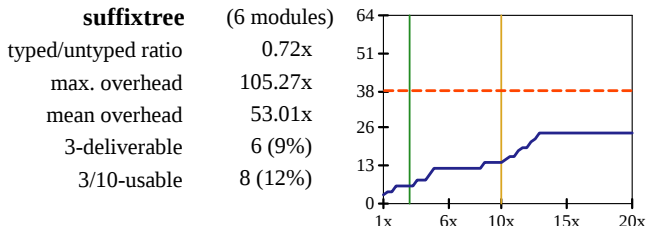
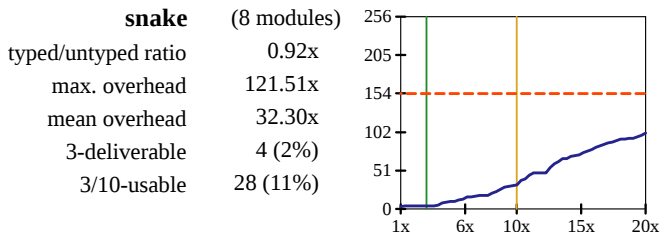
→ *even*(3) : \* ⇒ Bool ⇒ \*

→ *odd*(2) : Bool ⇒ \* ⇒ Bool ⇒ \*

→ *even*(1) : \* ⇒ Bool ⇒ \* ⇒ Bool ⇒ \*

→ *odd*(0) : Bool ⇒ \* ⇒ Bool ⇒ \* ⇒ Bool ⇒ \*

# Casts can cause catastrophic slowdowns



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*Is sound gradual typing dead?* Takikawa et al. POPL 2016



# Grift: an experimental compiler

- ▶ An ahead-of-time compiler for gradual typing.
- ▶ The input is a minimal functional language, output is C (e.g. no continuations).
- ▶ Benchmarking to-date is limited due to amount of language support.
- ▶ The compiler specializes casts when their source and/or target type is known at compile time.
- ▶ The runtime system implements **coercions** and **monotonic references**.

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# Compress casts via coercion reduction

$$\text{odd}(\circ) : \text{Bool} \Rightarrow \star \xRightarrow{\ell} \text{Bool} \Rightarrow \star \xRightarrow{m} \text{Bool} \Rightarrow \star$$

$$\text{odd}(\circ) \langle \text{Bool}! \rangle \langle \text{Bool}?\ell \rangle \langle \text{Bool}! \rangle \langle \text{Bool}?^m \rangle \langle \text{Bool}! \rangle$$

$\longrightarrow$

$$\text{odd}(\circ) \langle \text{id}_{\text{Bool}} \rangle \langle \text{Bool}! \rangle \langle \text{Bool}?^m \rangle \langle \text{Bool}! \rangle$$

$\longrightarrow$

$$\text{odd}(\circ) \langle \text{Bool}! \rangle \langle \text{Bool}?^m \rangle \langle \text{Bool}! \rangle$$

$\longrightarrow$

$$\text{odd}(\circ) \langle \text{id}_{\text{Bool}} \rangle \langle \text{Bool}! \rangle$$

$\longrightarrow$

$$\text{odd}(\circ) \langle \text{Bool}! \rangle$$

# Coercion Calculus

## Syntax

$$c, d ::= \text{id}_T \mid I! \mid I?^\ell \mid c \rightarrow d \mid c ; d \mid \perp^\ell$$

## Reduction

$$c; \text{id}_T \longrightarrow c$$

$$\text{id}_T; c \longrightarrow c$$

$$I!; I?^\ell \longrightarrow \text{id}_I$$

$$I!; I'?^\ell \longrightarrow \perp^\ell \qquad I \neq I'$$

$$(c \rightarrow d); (c' \rightarrow d') \longrightarrow (c'; c) \rightarrow (d; d')$$

$$(\text{id}_T \rightarrow \text{id}_{T'}) \longrightarrow \text{id}_{T \rightarrow T'}$$

$$\perp^\ell; c \longrightarrow \perp^\ell$$

$$c; \perp^\ell \longrightarrow \perp^\ell \qquad \text{if } c \neq I?^{\ell'}$$

# Normalize adjacent coercions

$e ::= \dots \mid e\langle c \rangle$	Terms
$u ::= n \mid \lambda x:T. e$	Uncoerced Values
$v ::= u \mid u\langle c \rightarrow d \rangle \mid u\langle I! \rangle$	Values

$$\begin{aligned}(u\langle c \rightarrow d \rangle) \ v &\longrightarrow (u \ v\langle c \rangle)\langle d \rangle \\ u\langle \text{id}_T \rangle &\longrightarrow u \\ e\langle c \rangle\langle d \rangle &\longrightarrow e\langle c' \rangle && \text{if } (c; d) \longrightarrow^* c' \\ u\langle \perp^\ell \rangle &\longrightarrow \text{blame } \ell\end{aligned}$$

# Coercions in normal form & composition

$$s, t ::= \text{id}_\star \mid (I^{?\ell} ; i) \mid i$$

$$i ::= (g ; I!) \mid g \mid \perp^\ell$$

$$g, h ::= \text{id}_{\text{Int}} \mid (s \rightarrow t)$$

$$\boxed{s \circ t = s}$$

$$\text{id}_{\text{Int}} \circ t = \text{id}_\star \circ t = t$$

$$(s \rightarrow t) \circ (s' \rightarrow t') = (s' \circ s) \rightarrow (t \circ t')$$

$$(g ; I!) \circ \text{id}_\star = g ; I!$$

$$(I^{?\ell} ; i) \circ t = I^{?\ell} ; (i \circ t)$$

$$g \circ (h ; I!) = (g \circ h) ; I!$$

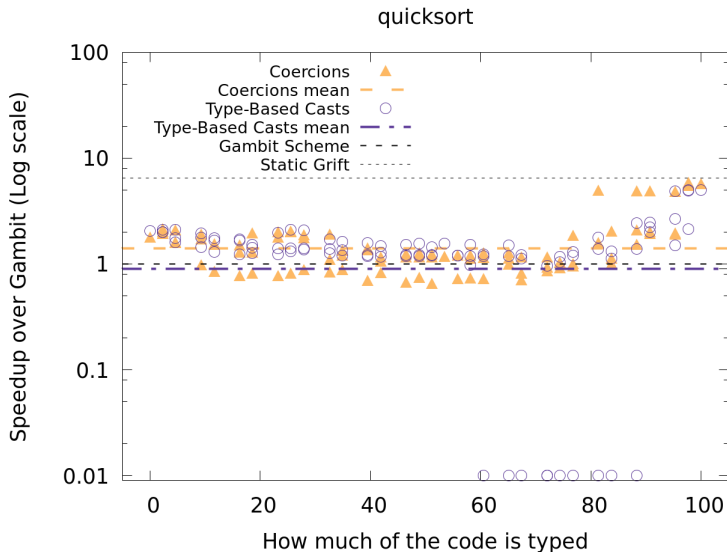
$$(g ; I!) \circ (I^{?\ell} ; i) = g \circ i$$

$$(g ; I!) \circ (I'^{?\ell} ; i) = \perp^\ell \quad \text{if } I \neq I'$$

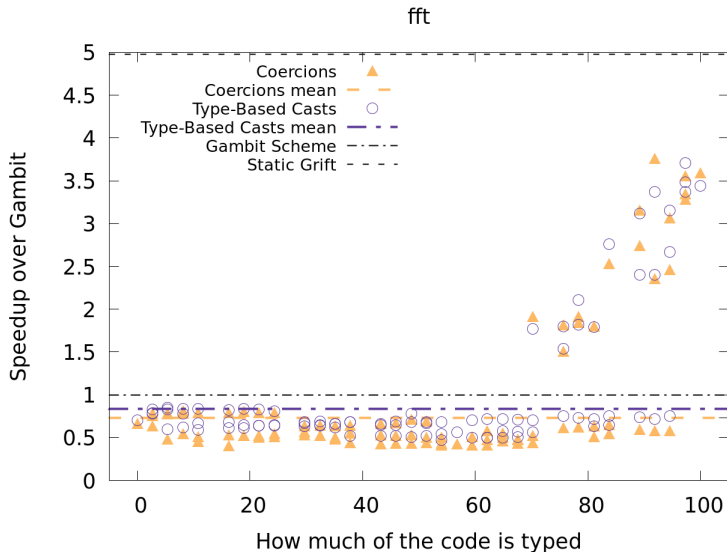
$$\perp^\ell \circ s = g \circ \perp^\ell = \perp^\ell$$

$$\mathcal{F}[e\langle s \rangle \langle t \rangle] \longrightarrow \mathcal{F}[e\langle s \circ t \rangle]$$

# Coercions eliminate catastrophic slowdowns

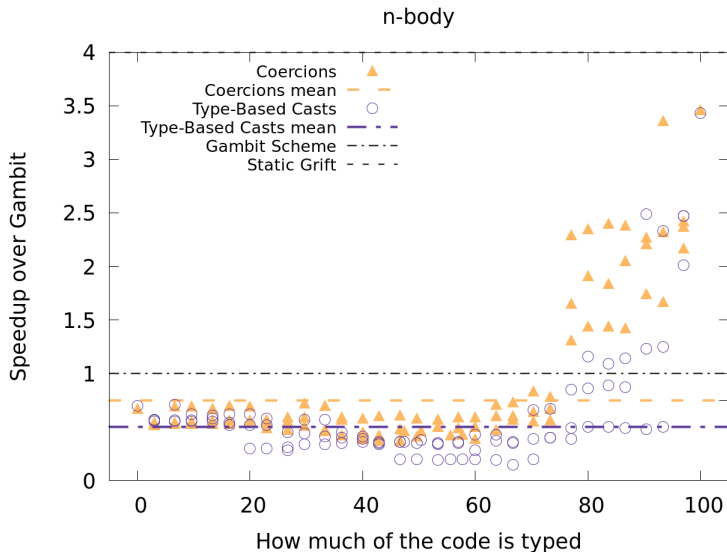


# Coercions sometimes incur overhead





# Coercions sometimes pay for themselves



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- ▶ Performance Comparison

# Gradual typing with mutable references

$$\begin{aligned} T &::= \dots \mid \text{Ref } T \\ e &::= \dots \mid \text{ref } e \mid !^{\ell} e \mid e :=^{\ell} e \end{aligned}$$

Consistency

$$\boxed{T \sim T}$$

$$\dots \quad \frac{T_1 \sim T_2}{\text{Ref } T_1 \sim \text{Ref } T_2}$$

Coercions

$$c ::= \dots \mid \text{Ref } (c_1, c_2)$$

Compile Casts to Coercions

$$\langle\langle \text{Ref } T_1 \xRightarrow{\ell} \text{Ref } T_2 \rangle\rangle = \text{Ref } (\langle\langle T_1 \xRightarrow{\ell} T_2 \rangle\rangle, \langle\langle T_2 \xRightarrow{\ell} T_1 \rangle\rangle)$$

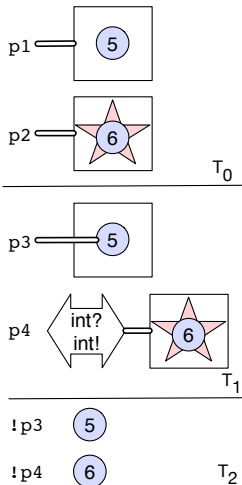
# Example of overhead in reference access

```
fun f(p3:Ref Int, p4:Ref Int)=  
    !p3 + !p4;
```

```
val p1 = ref 5;  
val p2 = ref (6<Int!>);
```

```
f(p1, p2<Ref(Int?,Int!)>);
```

```
ref(Int?,Int!)  
  : Ref *  $\Rightarrow$  Ref Int
```



Problem: generated code for  $!p3$  and  $!p4$  must branch at run-time for the two kinds of references.

# Root of the problem

## Theorem (Canonical Forms)

*Suppose  $\emptyset \vdash v : T$ . If  $T = \text{Ref } T$ , then either*

- ▶  *$v = a$  for some address  $a$ , or*
- ▶  *$v = a \langle \text{Ref } (c_1, c_2) \rangle$ .*

## Two rules for dereference

$$\begin{aligned} !a, \mu &\longrightarrow \mu(a), \mu \\ !(a \langle \text{Ref } (c_1, c_2) \rangle), \mu &\longrightarrow (!a) \langle c_1 \rangle, \mu \end{aligned}$$

## Two rules for update

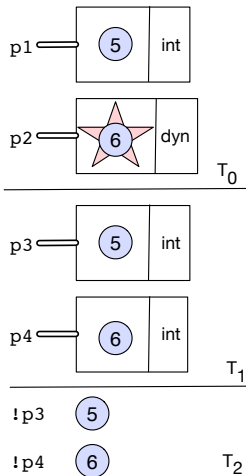
$$\begin{aligned} a := v, \mu &\longrightarrow a, \mu(a \mapsto v) \\ a \langle \text{Ref } (c_1, c_2) \rangle := v, \mu &\longrightarrow a := v \langle c_2 \rangle, \mu \end{aligned}$$

# Monotonic References

```
fun f(p3:Ref Int, p4:Ref Int)=  
    !p3 + !p4;
```

```
val p1 = ref 5;  
val p2 = ref (6<Int!>);
```

```
f(p1, p2<Ref(Int)>);
```



Update the reference cell to the meet of the current RTTI and the target of the cast.

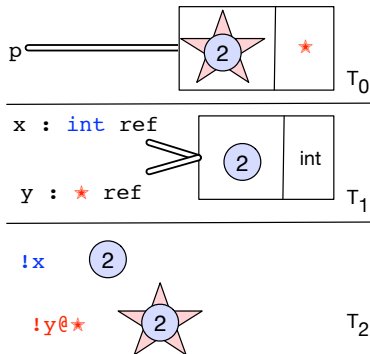
# Aliasing and Static vs. Dynamic Dereference

```
fun f(x:Ref Int, y:Ref ★)=  
  !x + !y@★;
```

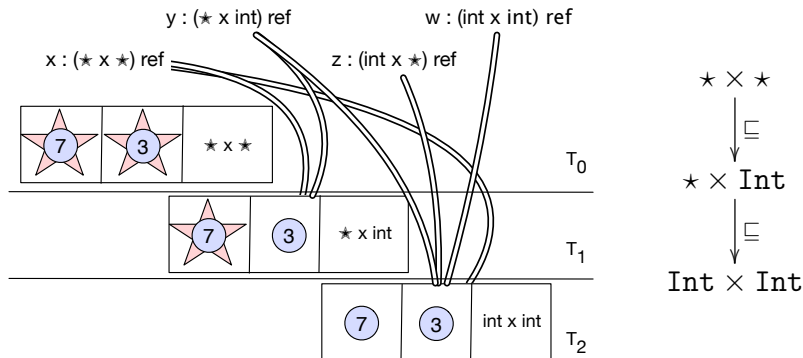
```
p = ref (2<Int!>);  
f(p, p);
```

Compile-time choice:

- Fast static deref.
- Slow dynamic dereference



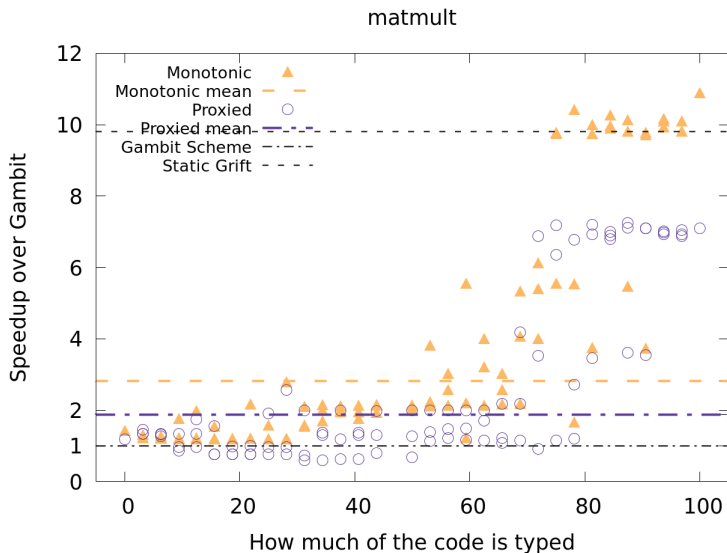
# The Monotonic Invariant



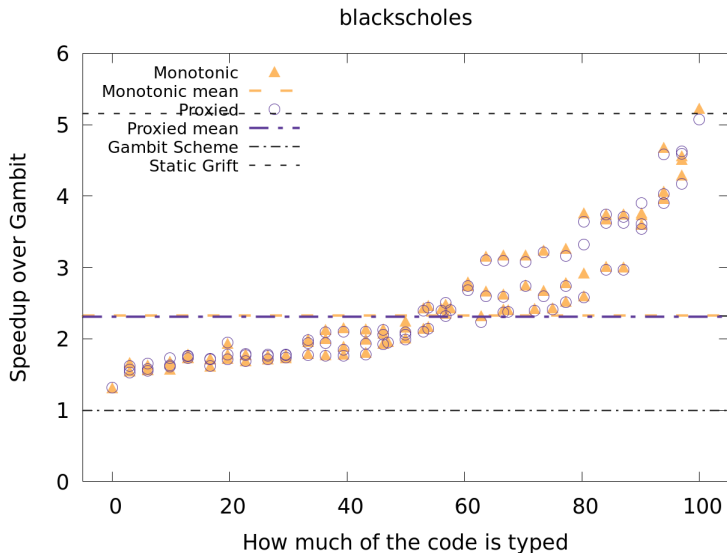
- ▶ The RTTI of a cell may become more precise.
- ▶ Every reference is less or equally precise as the RTTI.
- ▶ If a reference is fully static (e.g.  $w$ ), then so is the cell.



# Monotonic eliminates overhead in static code



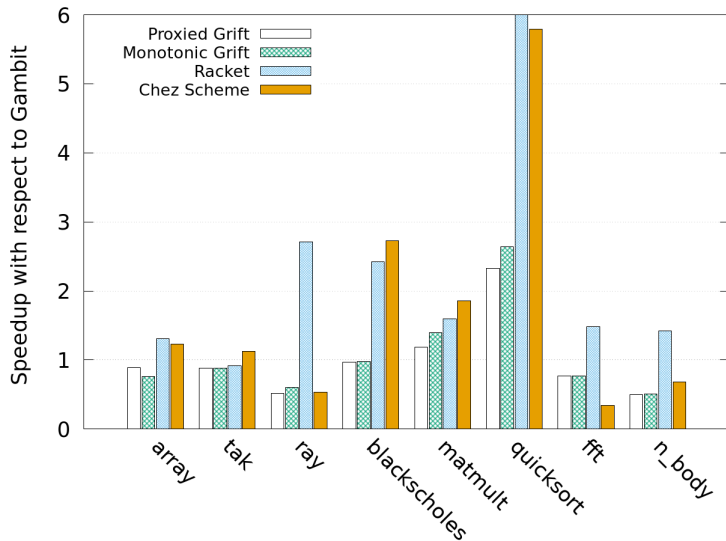
# Monotonic doesn't matter for some programs



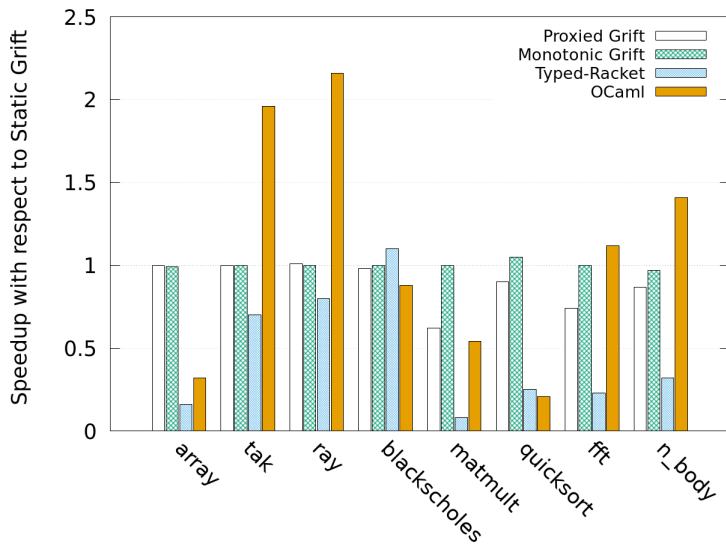
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# Comparison on dynamically typed programs



# Comparison on statically typed programs



# Conclusion

- ▶ Gradual typing can be efficient!
- ▶ On dynamically typed code: competitive with Gambit.
- ▶ On statically typed code: competitive with OCaml.
- ▶ On partially typed code, performance varies roughly between %50 of untyped impl. to %100 of typed impl.
- ▶ Use **coercions** to eliminate catastrophic slowdowns in partially typed code.
- ▶ Use **monotonic references** to reduce overhead in statically typed code.

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Caveat: on the 8 benchmarks we have working so far.