$$\dot{M} = \rho \frac{V_{\rm MB}}{t_{\rm MB}} \tag{1}$$

$$\dot{Q}_{\rm R} = \dot{W}_{\rm R} = c\dot{M}(T_{\rm Zu} - T_{\rm Ab}) \tag{2}$$

$$\dot{Q}_1 = c\dot{M}(T_{\rm Zu} - T_{\rm Ab}) \tag{3}$$

$$-\dot{Q}_2 = c\rho V_{\rm P} \dot{T} \tag{4}$$

$$\dot{W} = \dot{Q}_1 - \dot{Q}_2 + \dot{W}_{\mathrm{R}} \tag{5}$$

$$\varepsilon = \frac{|Q_2|}{|W|} \tag{6}$$

$$Q = c\rho V_{\rm P}(T_2 - T_1) \tag{7}$$

$$Q_{\rm G} = Q_2(t_2 - t_1) + Q \tag{8}$$

$$Q_{\rm S} = -Q_2(t_2 - t_1) \tag{9}$$