

Supervised learning

Inteligencia Artificial en los Sistemas de Control Autónomo
Máster en Ciencia y Tecnología desde el Espacio

Departamento de Automática

Objectives

1. Extend supervised learning algorithms
2. Apply supervised learning to real-world problems

Bibliography

- Müller, Andreas C., Guido, Sarah. Introduction to Machine Learning with Python. O'Reilly. 2016
- Géron, Aurélien. Hands-On Machine Learning with Scikit-Learn, Keras & TensorFlow. 2nd Edition. O'Reilly. 2019

Most figures have been taken from (A. Müller) and (A. Géron)

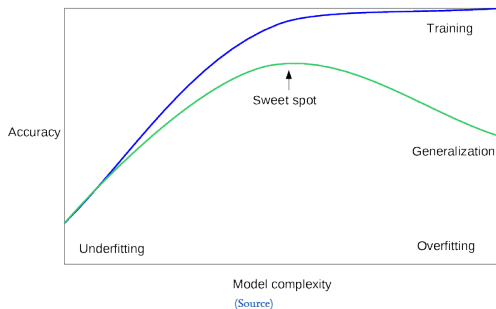
Table of Contents

1. Generalization, overfitting and underfitting
2. k-Nearest Neighbors
 - k-NN classification
 - kNN regression
 - Summary
3. Linear models
 - Ordinary least squares
 - Linear regression
 - Regularized linear models
 - Ridge regression
 - Lasso regression
 - ElasticNet
 - Regularized linear models comparison
 - Linear models for classification
 - Summary
4. Decision Trees
 - Building decision trees
 - Controlling complexity of decision trees
 - Analyzing decision trees
 - Feature importance in trees
 - Decision trees in regression
 - Summary
5. Ensembles of Decision Trees
 - Ensembles
 - Random forests
 - Analyzing random forests
 - Summary: Random forest
 - Gradient boosted regression trees
 - Summary
6. Support Vector Machines
 - Linear SVM
 - Linear models and nonlinear features
 - The kernel trick
 - Understanding SVMs
 - Summary

Generalization, overfitting and underfitting

Generalization: accurate predictions on unseen data

- i.e. there is no overfitting neither underfitting
- Depends on model complexity and data variability

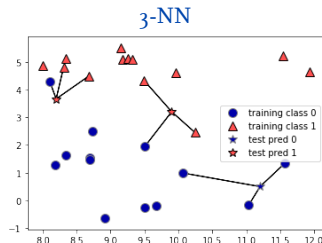
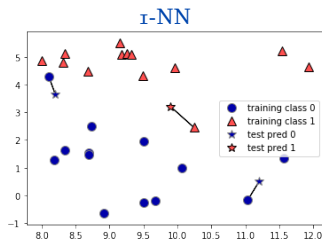


k-Nearest Neighbors

k-NN classification (I)

k-NN (k-Nearest Neighbors): Likely, the simplest learner

- Given a data point, it takes its k closest neighbors
- Same prediction than the majority of its neighbors
- k uses to be an odd number (1-NN, 3-NN, 5-NN, ...)

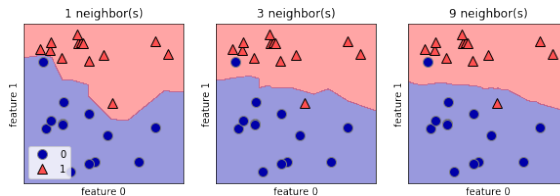


k-NN does not generate a model

- The whole dataset must be stored

k-Nearest Neighbors

k-NN classification (II)



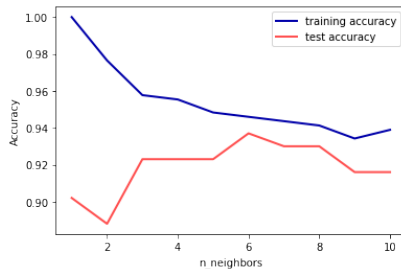
k determines the model complexity

- Smoother boundaries in larger k values
- Model complexity decreases with k

How to figure out the best k ?

k-Nearest Neighbors

k-NN classification (III)



k-Nearest Neighbors

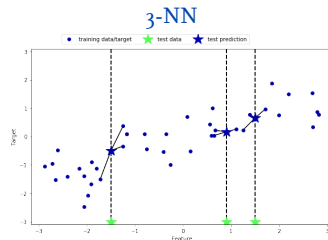
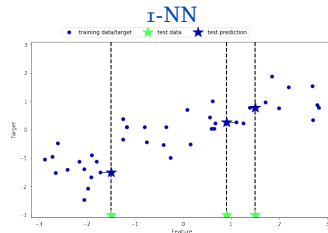
kNN regression (I)

k-NN regression

Given a data point

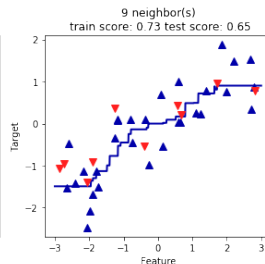
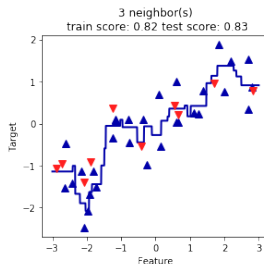
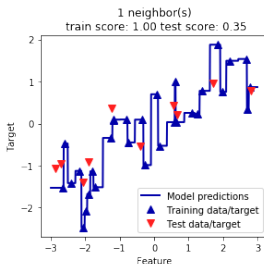
1. Take the k closest data points
2. Predict same target value (1-NN) or averaged target value (k-NN)

Performance is measured with a regression metric



k-Nearest Neighbors

kNN regression (II)



k determines the boundary smoothness

- With large k values, fit is smoother

k-Nearest Neighbors

Summary

Hyperparameters	Advantages	Disadvantages
k	Simple	Slow with large datasets
Distance	Baseline	Bad performance with hundreds or more attributes
		No model
		Dataset must be stored in memory

Linear models

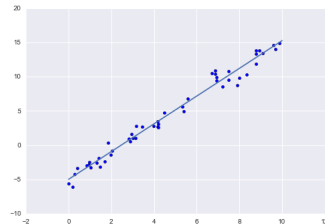
Linear model (I)

Linear model

$$y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \dots + \beta_n x_n$$

for a single feature $y = \beta_0 + \beta_1 x_1$, where

- β_0 is the intercept
- β_1 is the slope



Lineal models assume a linear relationship among variables

- This limitation can be easily overcome
- Surprisingly good results in high dimensional spaces

Intepretable model

Linear models

Linear regression

Different linear models for regression

- The difference lies in how β_i parameters are learned

Ordinary Least Squares (OLS): Minimizes mean squared error

- OLS does not have any hyperparameter
- No complexity control

$$\text{MSE} = \frac{1}{m} \sum_{i=1}^m (y_i - \hat{y}_i)^2$$

where m is the number of instances

Linear models

Regularized linear models

Regularization: Term that penalizes complexity

- Added to the cost function
- Linear models remain the same
- Train to minimize cost function and penalty
- Intercepts are not part of regularization

Three regularizations

- L1 (Lasso regression), L2 (Ridge regression) and ElasticNet (L1 and L2)

Lasso (L1)

$$\alpha \sum_{j=1}^n |\beta_j|$$

Ridge (L2)

$$\alpha \sum_{j=1}^n \beta_j^2$$

ElasticNet

$$\alpha \left(r \sum_{j=1}^n |\beta_j| + (1 - r) \sum_{j=1}^n \beta_j^2 \right)$$

Linear models

Ridge regression

Ridge regression (or L2 regularization) adds a new term to cost function

$$\text{MSE} + \alpha \sum_{i=1}^n \beta_i^2$$

α controls the penalty

- If $\alpha = 0$ Ridge becomes a regular linear regression
- Optimal α depends on the problem

Ridge by default

Linear models

Lasso regression (I)

Lasso regression (or L_1 regularization) adds a new term to cost function

$$\text{MSE} + \alpha \frac{1}{2} \sum_{i=1}^n |\beta_i|$$

α controls the penalty (and model complexity)

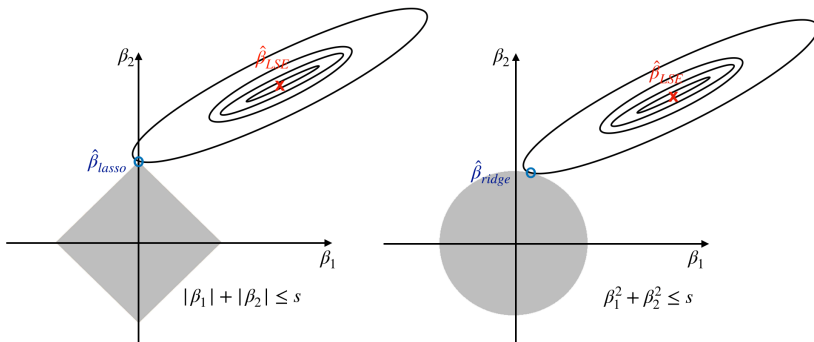
- If $\alpha = 0$ Lasso becomes a regular linear regression
- Optimal α depends on the problem

Some coefficients may be exactly zero

- Implicit feature selection
- Easier interpretation
- Better with large number of attributes

Linear models

Lasso regression (II)



(Source)

Linear models

ElasticNet

Lasso and Ridge can be combined

$$\text{MSE} + \alpha \left(r \sum_{i=1}^n |\beta_i| + (1 - r) \sum_{i=1}^n \beta_i^2 \right)$$

Two hyperparameters

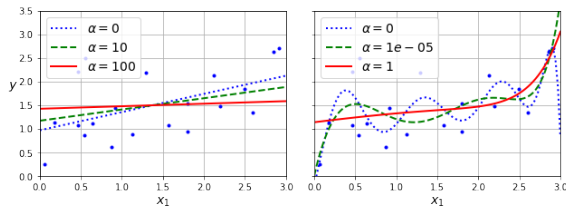
- α controls the model complexity
- r balances between L_1 and L_2

ElasticNet is not a neural network!

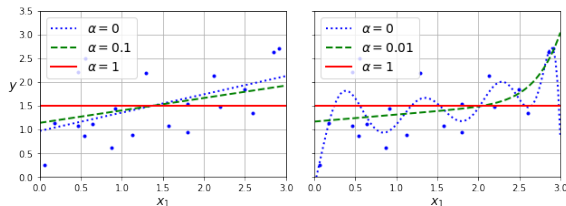
Linear models

Regularized linear models comparison

Ridge - L2



Lasso - L1



Linear models

Linear models for classification (I)

A linear regression can be used as classifier

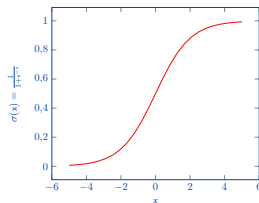
- Just compare the prediction with a threshold (0, for instance)
 - If $\hat{y} > 0$, assign C_1 ; if $\hat{y} \leq 0$, assign C_2
- The decision boundary is a line, plane or hyperplane

A **logistic regression** is a generalization of a linear regression

- Probabilistic binary classifier

$$\hat{p} = \sigma \left(\beta_0 + \sum_{i=1}^n \beta_i x_i \right), \hat{y} = \begin{cases} C_1, & \text{if } \hat{p} < 0,5 \\ C_2, & \text{if } \hat{p} \geq 0,5 \end{cases}$$

where $\sigma(t)$ is the logistic function, defined as $\sigma(t) = \frac{1}{1+e^{-t}}$



Linear models

Summary

Hyperparameters	Advantages	Disadvantages
	Fast train and predict	Limited in low dimensional spaces
α (L1, L2, ElasticNet)	Scales well to large datasets	Limited generalization
l1_ratio (ElasticNet)	Better in high dimensional spaces Few hyperparameters Interpretable	

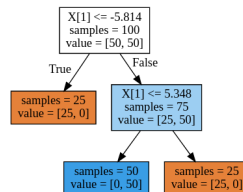
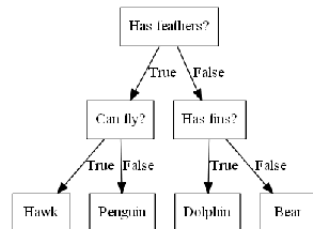
Decision Trees

Decision trees are a family of algorithms

- Classification, regression and anomaly detection
- They learn a tree data structure
- Hierarchy of if/else questions (test, or node)
- Decision (terminal node or leaf)

Usually, datasets does not contain binary attributes

- Continuous features
- Is feature i larger than value a ?



Decision Trees

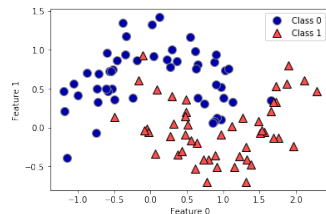
Building decision trees (I)

Tree learning algorithm

1. Begin with the root node
2. Searches all possible tests (according to a purity measure)
3. The most informative test is taken
4. Repeat recursively

Prediction of a new data point

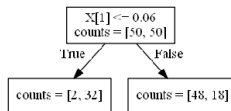
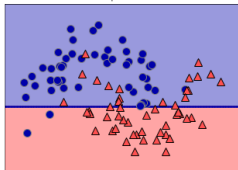
- Classification: Majority class in the partition
- Regression: Average value of target values in the partition



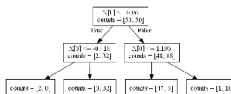
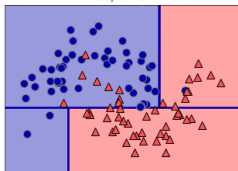
Decision Trees

Building decision trees (II)

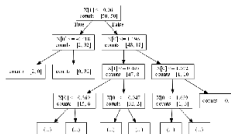
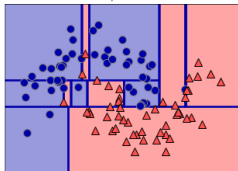
depth = 1



depth = 2



depth = 9



Decision Trees

Building decision trees (III)

We need a measure of ‘impurity’: Gini and entropy

- Let C be the number of classes and p_i is the probability of class i in the dataset S
- Gini: $G(S) = 1 - \sum_i^C p_i^2$
- Entropy: $H(S) = - \sum_i^C p_i \log_2 p_i$

Both measures are used to learn trees

- Gini is faster
- Entropy is preferred with unbalanced datasets

Decision Trees

Controlling complexity of decision trees

Trees tend to grow until all leaves are pure

- Very big trees in real problems
- Big trees use to be overfitted models

Two strategies to prevent overfitting

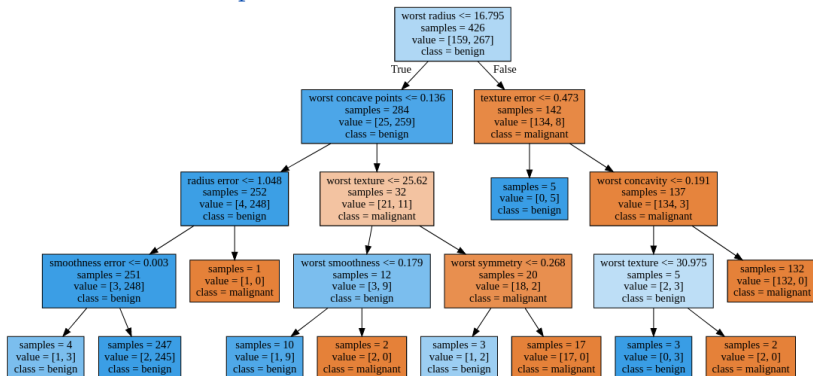
- Pre-pruning: Stop the creation of the tree early according to some criteria
 - Maximum depth, number of leaves, minimum number of points in a node, ...
 - Implemented in Scikit-Learn
- Post-pruning: Build the tree and then remove nodes with little information

Decision Trees

Analyzing decision trees

Decision trees are easily explained to nonexperts

- Interpretable models
- Deep trees are overwhelming
- Trick: Observe the path with most data

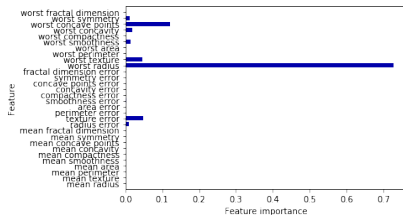


Decision Trees

Analyzing decision trees: Feature importance

Feature importance is a metric that summarizes features

- Number between 0 (not used at all) and 1 (perfect prediction)
- Feature importances sum to one
- Useful for feature selection and model interpretation



Some considerations

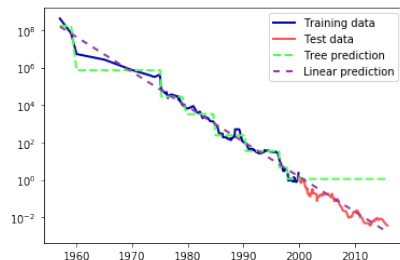
- It does not inform about the relationship between attribute and target
- It quantifies the importance in the tree

Decision Trees

Decision trees in regression

Decision trees are not able to extrapolate

- i. e. to predict outside of the range of the training data
- It is specially important in regression problems



Decision Trees

Summary

Hyperparameters	Advantages	Disadvantages
max_depth	Visualization	Tend to overfit
max_leaf_nodes	Interpretable by non-experts	Poor generalization
min_samples_leaf	Invariant to scale	
criterion	Mix of categorical and numerical data	

Ensembles of Decision Trees

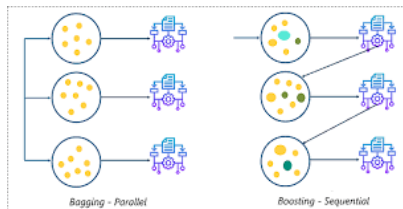
Ensembles

Ensembles, in ML, refers to the combination of several models

- For instance, an ensemble of three classifiers voting

Two common approaches to build ensembles

- **Bagging** (or bootstrap) samples the dataset with replacement
 - The ensemble make prediction by aggregating its predictors
- **Boosting** trains models to correct previous models



(Source)

Ensembles of Decision Trees

Random forests

A tree is good doing his job, but does not generalize well

- Different trees could overfit in different ways
- Idea: Use many trees and aggregate their results

Random forest is a popular algorithm based on ensembles of trees

- Classification and regression
- Limits overfitting found in trees

It encourages tree diversity through training set and feature selection

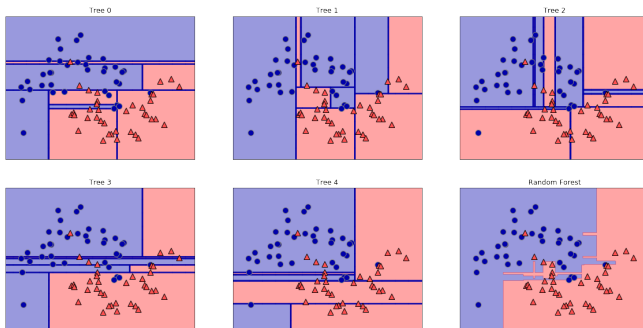
- Selecting data: Bootstrap
- Selecting features in each test
 - It does not look for the best test
 - It looks for the best test involving a random subset of features
 - The size of the features subset is a critical hyperparameter

Same hyperparameters than decision trees

Ensembles of Decision Trees

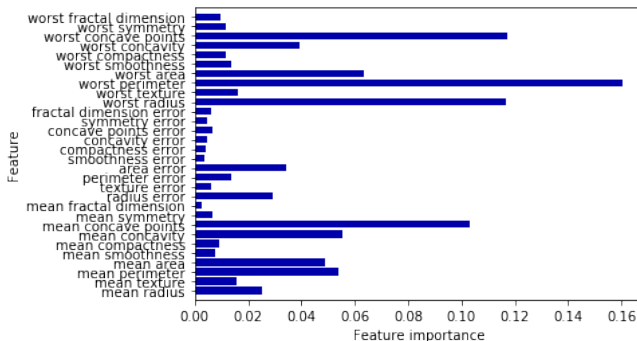
Analyzing random forests (I)

Random forest with five trees



Ensembles of Decision Trees

Analyzing random forests (II)



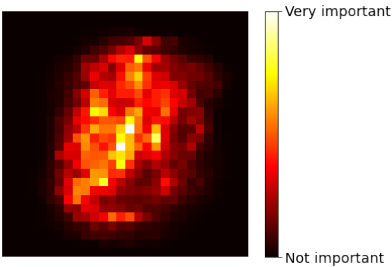
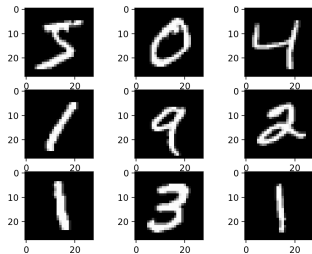
Feature importance can be aggregated

- More informative than single trees
- The algorithm must consider many possible explanations

Ensembles of Decision Trees

Analyzing random forests (III)

Random forest classifier with MNIST dataset



Ensembles of Decision Trees

Summary: Random forest

Hyperparameters	Advantages	Disadvantages
Same than trees	Same than trees	Interpretation
Number of trees	High performance	High dimensional data
Number of features	Robust	Sparse data
	Widely used	Memory and CPU
	Parallelized	

Ensembles of Decision Trees

Gradient boosted regression trees (I)

Gradient **boosting** trees is an ensemble of trees

- Based on boosting, builds trees in a serial manner
- One tree corrects the mistakes of the previous one

A set of *weak learners* is used

- Shallow trees (by default, 3 in Sklearn)
- No data randomization, strong pre-pruning

A new hyperparameter: *learning rate*

- How strongly each tree tries to correct
- High learning rate makes stronger corrections: More complex models
- More trees also adds more complexity

State of the art results

- Widely adopted by industry
- Comparable in performance with deep neural networks

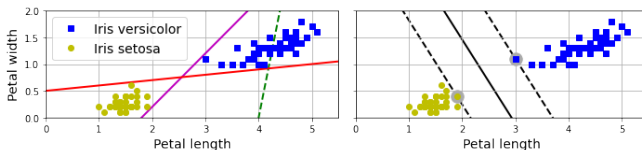
Ensembles of Decision Trees

Summary: Gradient boosting

Hyperparameters	Advantages	Disadvantages
Same than trees	Very high performance	Slow
Number of trees	Invariant to scale	High dimensional data
Learning rate	Mix of categorial and numerical data	Tricky hyperparameter tuning
		Overfitting

Support Vector Machines

Linear SVM (II)

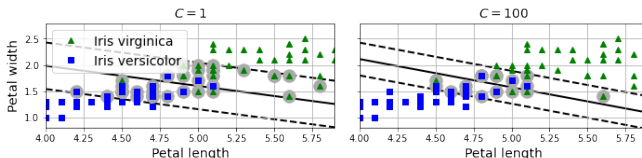


Two big problems with hard margins

- Most datasets are not linearly separable and outliers

We look for a balance between good fit and margin violations: C

- C sets the tolerance to margin violations
- Low $C \rightarrow$ High tolerance

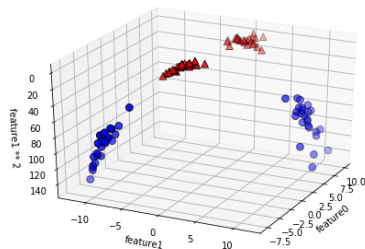
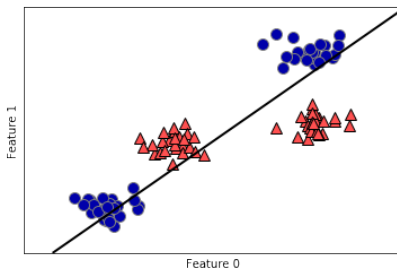


Support Vector Machines

Linear models and nonlinear features (I)

Plain SVMs are limited in low-dimensional spaces

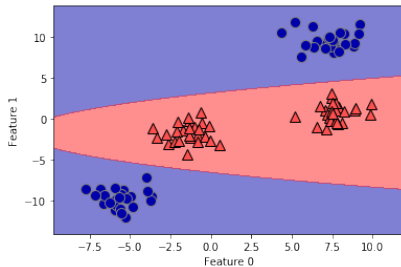
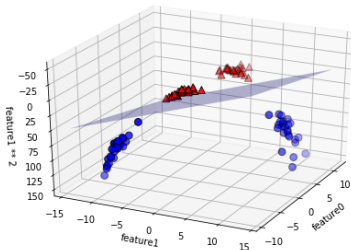
- Lines, planes and hyperplanes
- Adding new features is a way to overcome this limitation



$$\text{feature_2} = \text{feature_1}^2$$

Support Vector Machines

Linear models and nonlinear features (II)



Support Vector Machines

The kernel trick

Adding nonlinear attributes makes linear models much more powerful

- Which features should we add?
- How we compute interactions in a 100-dimensional feature space?

Some mathematical magic: The *kernel trick*

- It computes data distances for expanded feature representation ...
- ... without computing the expansion!

It applies a function named **kernel**

- Polynomial kernel, up to a certain degree
- Radial basis function (RBF) kernel (Gaussian kernel)
- Linear kernel, no expansion is done

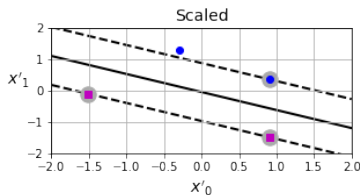
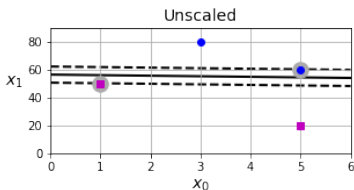
The kernel trick can be used in other techniques like PCA

Support Vector Machines

Understanding SVMs (III)

SVM is very sensitive to scale

- Always use standardized or normalized data



Support Vector Machines

Summary

Hyperparameters	Advantages	Disadvantages
C	Powerful	Memory and CPU
γ	Low and high dimensional	Number of samples
Kernel	Flexible	Scaling No interpretable