Deep Learning

Inteligencia Artificial en los Sistemas de Control Autónomo Máster en Ciencia y Tecnología desde el Espacio

Departamento de Automática





Objectives

- 1. Define Machine Learning (ML)
- 2. Delimite ML scope
- 3. Introduce the main ML tasks4. Recognize problems as ML tasks

Bibliography

- Bishop, Christopher M. Pattern Recognition and Machine Learning. 2nd edition. Springer-Verlag. 2011
- Müller, Andreas C., Guido, Sarah. Introduction to Machine Learning with Python. O'Reilly. 2016

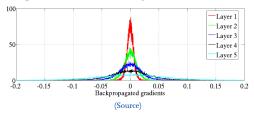
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Deep neural networks (I)

Deep Learning is not just a network with many layers

- Gradient vanishing
- Multiple local optima -> difficult training



Usual solutions

- Careful weights initialization
- ReLU and Leaky ReLU activation functions
- Regularization through dropout

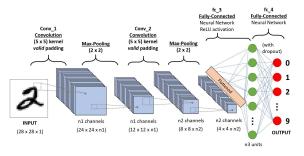


Deep neural networks (II)

Two popular types of deep networks

- Convolutional Neural Networks (CNNs)
- Long Short-Term Memory (LSTM)
- ... we use both

In Deep Learning, we think in layers







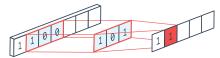
1D convolution

CNNs are popular for Computer Vision applications

- Networks with convolutional layers
- Convolutions in NN use to be 2D
- (Conv 2D example)

Univariable time series are 1D

• TD convolution



Related concept: deconvolution

Max-pooling

Max-pooling down-samples data instances

- Given a matrix, it takes its maximum value
- Usually the matrix is nxn (2D)

Benefits

- Dimensionality reduction
- Filters irrelevant information

12	20	30	0			
8	12	2	0	2×2 Max-Pool	20	30
34	70	37	4		112	37
112	100	25	12			

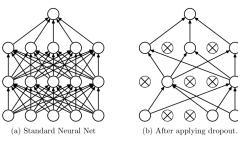
Dropout

Dropout is a regularization technique for neural networks

• Dropout deactivates a neuron with probability p for each iteration

Related concept: dense layers

• In Keras, it is just a fully connected layer with regular neurons



(Srivastava et al. (2010))

LSTM networks

Recurrent neural networks

TODO



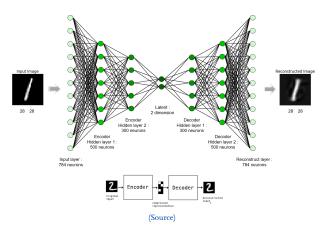
LSTM networks

LSTM

TODO



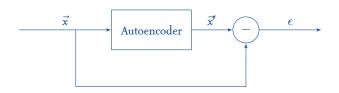
Autoencoders



Important concepts: latent space and latent variables



Autoencoders for anomaly detection (I)

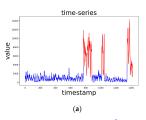


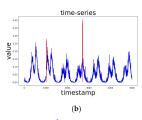
Reconstruction error is an anomality measure

- A norm can be computed to provide a global measure (MAE/MSE), or ...
- ... keep reconstruction error as vector

PCA may be used, less powerfull than autoencoders

Autoencoders for anomaly detection (II)





(Source: Niu, Z.; Yu, K.; Wu, X. LSTM-Based VAE-GAN for Time-Series Anomaly Detection. Sensors 2020, 20, 3738.)

Great flexibility to handle reconstruction error

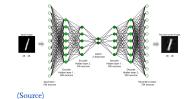
- Trigger an alarm based on a threshold
- Analize the time-series
- Feed a classifier

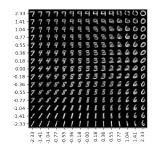


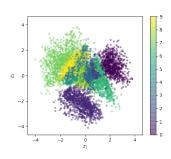
Autoencoders as generative models (I)

Any autoencoder may be used as a generative model

• The decoder can reconstruct an instance from a latent space sample

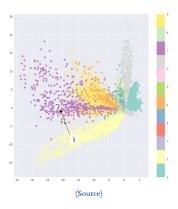






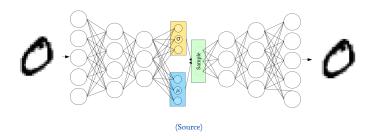
Autoencoders as generative models (II)

Regular autoencoders are not a good choice for generative models





Variational Autoencoders (I)

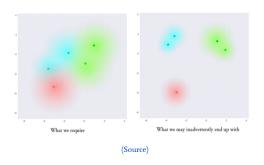


VAEs encodes latent variables as probability distributions

- ullet Gaussian distributions with μ and σ
- Decoder sample the distributions



Variational Autoencoders (II)



We want a structured latent space

- Penalty based on Kullback-Leibler (KL) divergence
 - KL measures divergente between two probability distributions



VAE semantics (I)

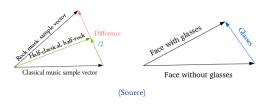
Astonishing VAE feature: latent space has semantics!



(Source)

VAE semantics (II)

Another incredible VAE property: 'semantic' arithmetic operations



GANs VAEs

Adversarial examples

