CS 294-115 Algorithmic Human-Robot Interaction

Fall 2016

Lecture 7: Trajectory Optimisation Part III

Scribes: Daniel Filan and Davis Foote

7.1 What & Why

This lecture will have two sections: first, an explanation of why and how to change the inner product implicitly used to define functional gradient descent, and secondly, a discussion of how student paper presentations will work, and why they will work that way.