

# PSD@CBM firmware description (draft, for internal use)

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Actual version of the document is available at github:  
[https://github.com/dfinogee/PSD-readout-manual/raw/main/PSD\\_readout\\_manual.pdf](https://github.com/dfinogee/PSD-readout-manual/raw/main/PSD_readout_manual.pdf)

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# 1 ADC data processing

PSD\_data\_readout component receive data from all ADCs, process waveform and output data in GBT packets. Schematic of component is presented on fig. 1.

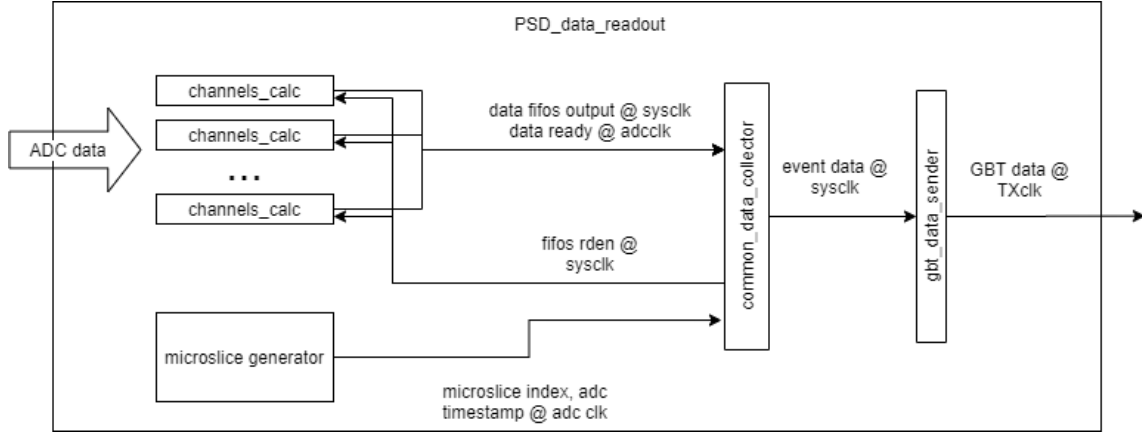


Figure 1: ADC data readout scheme

## 1.1 Component channels\_calc

Channel\_calc component scheme is presented on figure 2. ADC data inverted for negative signals, zero level and RMS are calculated and available from slow control.

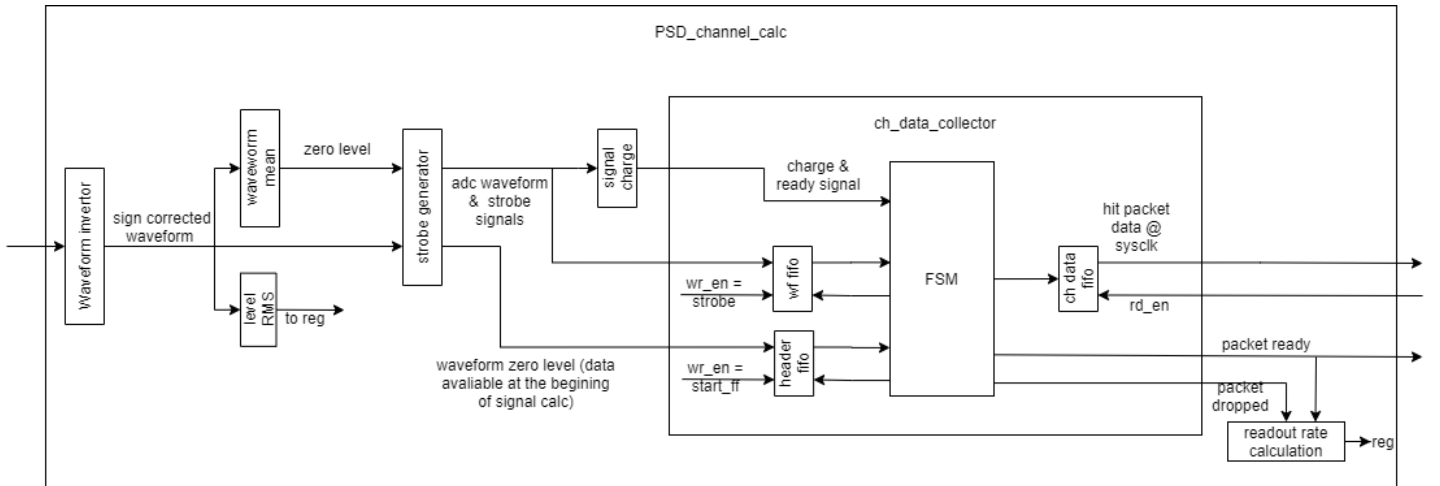


Figure 2: Channel data processing scheme

Strobe\_generator component forms waveform gate, start and stop signals by threshold crossing taking waveform length and offset parameters. Waveform data that are available from the start (zero level) are latched while strobe. Signal diagram of the component is presented on figure 3 To reduce the probability of being triggered by a noise event, three neighboring points are compared with threshold. Central point is compared with the threshold value and two side points with half of threshold value.

Waveform offset parameter determine waveform position in gate, if it is 0, first point in waveform strobe is the point above threshold (the third point compared to half of threshold value). Maximum offset value is 13. Latched baseline level is value before point above threshold.

If one channel in common trigger mask parameter cross threshold, common trigger is generated. All channels in common trigger output parameter take waveform similar to they has threshold crossing together.

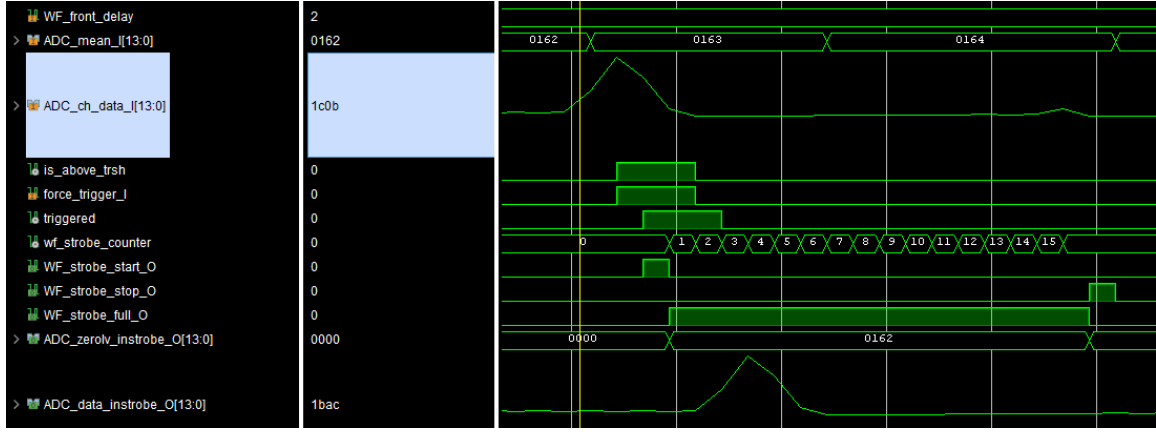


Figure 3: Signal waveform strobe (length 16, offset 3)

Ch\_data\_collector store waveform point in raw\_fifo by strobe signal and start waveform data (zero level) by start signal. When charge ready signal raised, charge and start data from header\_fifo stored in data\_fifo as hit packed header. This allow to upgrade charge calculation with fitting procedure and change calculation delay. In next cycle waveform points are read from raw\_fifo and (if sending wf points parameter is set on) stored as hit data in ch\_data\_fifo. After hit packet stored, ready signal raised or dropped signal in case fifo was full and hit packet was dropped. Ready and dropped signals are synchronous to threshold crossing and used for event ADC timestamp. Signals diagram of the component is presented on figure 4. The write size of ch\_data\_fifo should be equal to  $\text{ceil}(\text{calculation\_delay} / \text{waveform\_length}) * \text{waveform\_length}$ . The size of ch\_header\_fifo should be  $\text{ceil}(\text{calculation\_delay} / \text{waveform\_length})$ . Write rate for mentioned fifo is equal to read rate. In case data-fifo is full while charge ready signal, hit is dropped and dropped-hits counter increased by 1. Dropped-hits counter is available in channel status and reset after each register reading.

Readout-rate component allow to measure hit rate per channel. Waveform-start signals counted with 16bit counter and 70Hz rate. Each 70 Hz cycle, count is stored in 128 shift register. Rate-mean register store the summ of values stored in shift register. Two modes: low-rate and normal are available for rate reading. In normal mode for 16 bit status register available rate-mean[22 downto 7] and result is rate/70Hz. In low-rate mode (channel-low-rate-count bit) rate-mean[15 downto 0] available for status register and result is rate/70\*128Hz.

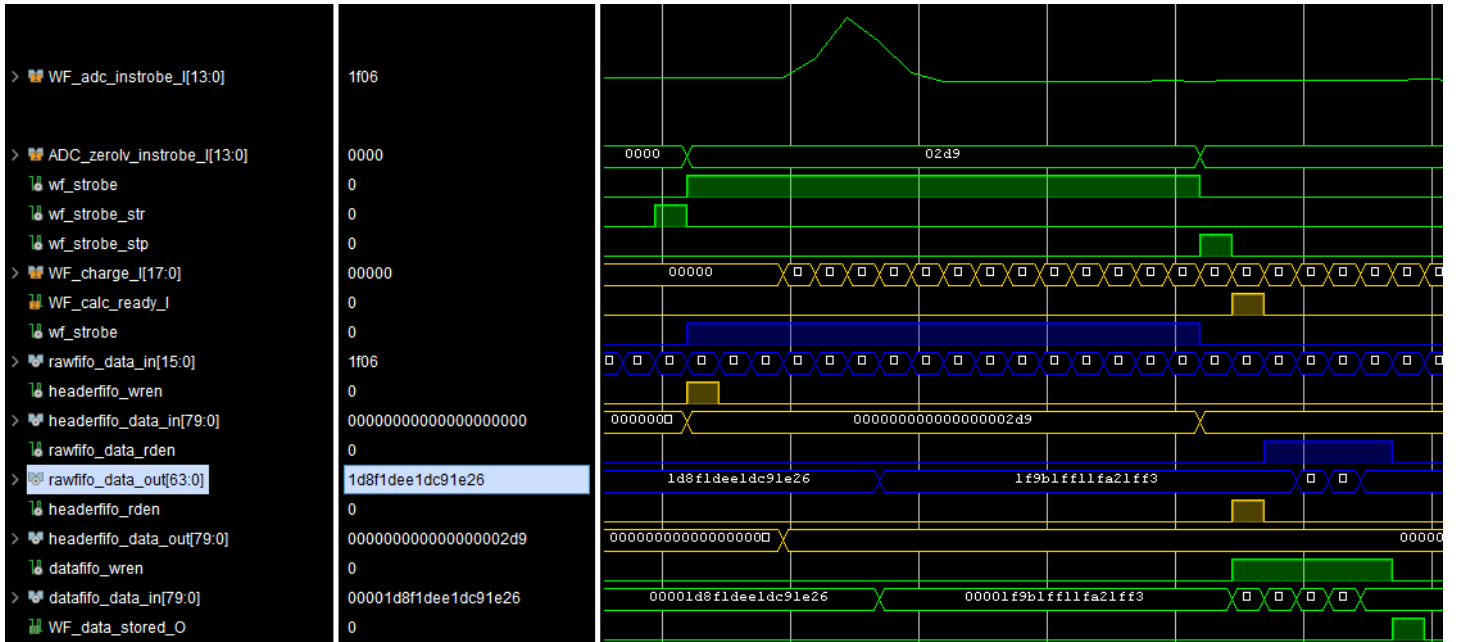


Figure 4: Channel data collecting signals

Signals could be processed one after another without dead time. If next adc point after waveform gate is higher than threshold, new signal gate is formed. Signal time is next adc cycle after first gate, not is real time of second waveform threshold crossing. Signal diagram for such case is presented on figure 5.

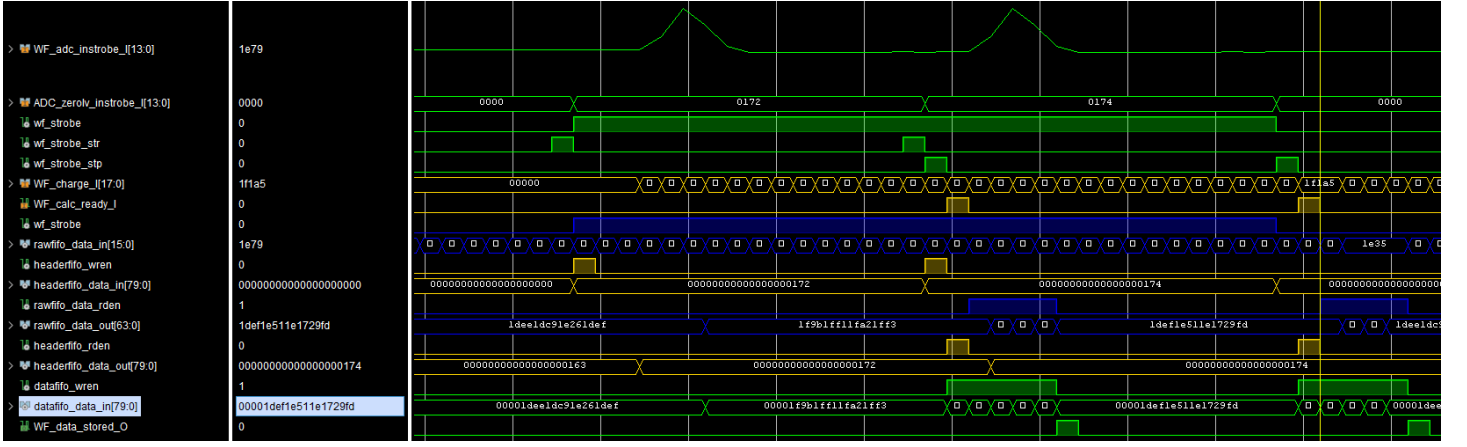


Figure 5: Channel data collecting signals

## 1.2 Component common\_data\_collector

Each channel generate single strobe with fixed latency to threshold crossing indicating waveform measurement. 32 bit strobe word is stored to data\_wf\_calc\_fifo with mc index and ADC timestamp. FSM read stored strobes and collect data from fired channels storing outputs to common\_data\_fifo, each event header word with timing and data size info stored in common\_header\_fifo. Schematic represented on figure 3.

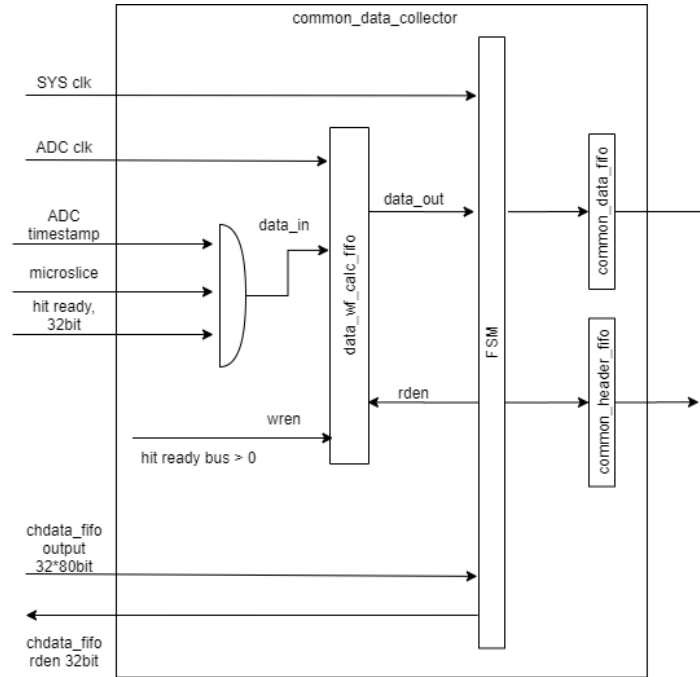


Figure 6: Data collecting scheme from all channels fifos

FSM is switched from wait to start state when data\_wf\_calc\_fifo\_isempty became '0' and fifo output is latched. Priority encoder show next fired channel from strobe and data collected from fired channel to common\_data\_fifo with hit\_packet\_iterator. Input to priory encoder is shifted to bit after fired channel when iterator reach last fired channel. Priority encoder could be equal or less than 32 bit. Simulation outputs presented on figure 4.



word type	79 .. 76	75 .. 72	71 .. 64	63 .. 48	47 .. 40	39 .. 32	31 .. 16	15 .. 0
ms header	0xA	0x0		ms index				
event header	0xB	ADC idx**	0x0		n fired channels	words in packet *	adc time	
hit header	hit header (tab. 1)							
hit data	hit data (tab. 2)							
hit data	hit data (tab. 2)							
hit data	hit data (tab. 2)							
hit data	hit data (tab. 2)							
...								
event header	0xB	ADC idx**	0x0		n fired channels	words in packet *	adc time	
	...							

Table 1: GBT data format. [\* number of GBT words in event packet: event header + all hit packets] [\*\* ADC board index]

word	79 .. 72	71 .. 64	63 .. 36	35 .. 16	15 .. 0
1	channel	words in packet *	0x0	signal charge	waveform zero level

Table 2: hit packet header. [\* total GBT words in hit packet: header + data words]

word	79 .. 64	63 .. 48	47 .. 32	31 .. 16	15 .. 0
1	0x0	waveform point n	waveform point n+1	waveform point n+2	waveform point n+3

Table 3: hit packet data word.

## 2 ADC control

### 2.1 ADC control units

Status and Control of ADC and EvB are 64 arrays each of 32 bit words. ADC control system include 4 firmware units: gbt-control-sender, gbt-control-reader, gbt-status-sender, gbt-status-reader.

gbt-control-sender send control packet (129 X 16bit) via gbt to ADC by start command initiated by software. Packet could be send at any time and is not in conflict with microslice flow to ADC. gbt-control-reader receive control packet, and update registers array with received strobe.

word	value
0	0xABBA
1	control(0)(15 .. 0)
2	control(0)(31 .. 16)
3	control(1)(15 .. 0)
4	control(1)(31 .. 16)
	....
127	control(63)(15 .. 0)
128	control(63)(31 .. 16)

Table 4: Control packet to ADC.

gbt-status-sender send status or control registers from ADC (packet 32 X 80bit). The transaction is initiated periodically, also control registers is sent back after each new configuration. Status sent back after I2C transaction finished or monitor channel changed. Also control word 0xABBB and 0xABBC initiate control/status packet from ADC corespondent. Status/control packet is prioritized to data flow, and gbt-data-fifo is not readed while transaction. To separate data flow status word starts with 0xE, control with 0xF.

bits	79 .. 76	75 .. 64	63 .. 32	31 .. 0
word	code	addr	reg1	reg0
0	E	0	status(1)	status(0)
1	E	2	status(3)	status(2)
....				
31	E	30	status(31)	status(30)

Table 5: Status packet from ADC.

bits	79 .. 76	75 .. 64	63 .. 32	31 .. 0
word	code	addr	reg1	reg0
0	F	0	control(1)	control(0)
1	F	2	control(3)	control(2)
....				
31	F	30	control(31)	control(30)

Table 6: Control packet from ADC.

gbt-status-reader read each gbt word starts with 0xE or 0xF and update control or status registers. Two counters indicate the time passed from last update. Read back control register is compared with actual one.

## 2.2 ADC Control registers

addr	31 .. 30	29 .. 28	27 .. 24	23 .. 20	19 .. 16	15 .. 14	13 .. 12	11 .. 8	7 .. 4	3 .. 0
0	0x0	threshold ch1				0x0	threshold ch0			
1	0x0	threshold ch3				0x0	threshold ch2			
2	0x0	threshold ch5				0x0	threshold ch4			
3	0x0	threshold ch7				0x0	threshold ch6			
4	0x0	threshold ch9				0x0	threshold ch8			
5	0x0	threshold ch11				0x0	threshold ch10			
6	0x0	threshold ch13				0x0	threshold ch12			
7	0x0	threshold ch15				0x0	threshold ch14			
8	0x0	threshold ch17				0x0	threshold ch16			
9	0x0	threshold ch19				0x0	threshold ch18			
10	0x0	threshold ch21				0x0	threshold ch20			
11	0x0	threshold ch23				0x0	threshold ch22			
12	0x0	threshold ch25				0x0	threshold ch24			
13	0x0	threshold ch27				0x0	threshold ch26			
14	0x0	threshold ch29				0x0	threshold ch28			
15	0x0	threshold ch31				0x0	threshold ch30			

Table 7: ADC channels threshold control.

addr	31 .. 28	27 .. 24	23 .. 20	19 .. 16	15 .. 12	11 .. 8	7 .. 4	3 .. 0
16	0x0		status ch sel		waveform length 0..3 [(reg+1)*4]	strobe offset 0..12	control bits	
17	negative channel mask ibit = ich							
18	I2C HV bus							
19	microslice gen counter@25ns							
20	microslice period							
21	common trigger OR mask							
22	common trigger output							
23	trigger pulser rate [count @ ADC clock] (0x0 = off)							
24	status send rate (0x0 = off)				control send rate (0x0 = off)			
25	common trigger AND mask							

Table 8: ADC readout control.

bit	description
0	send waveform
1	ms gen standalone
2	readout fsm reset
3	errors reset
4	channel low rate count
5	reset channels drop counter

Table 9: Control bits

addr	31 .. 25	24 .. 24	23 .. 23	22 .. 16	15 .. 8	7 .. 0
18	0x0	start	WR	i2c dev addr	mem addr	data

Table 10: HV control via I2C.

## 2.3 ADC Status registers

Status registers map is presented on table 11.

addr	31 .. 30	29 .. 28	27 .. 24	23 .. 20	19 .. 16	15 .. 14	13 .. 12	11 .. 8	7 .. 4	3 .. 0
0	microslice index 31 .. 0									
1	microslice index 63 .. 32									
2	ADC time									
3	RX wrclk err cnt					RX err frclk cnt				
4	RX err detect cnt					I2C HV bus				
5	0x0								temp	
6	sel. channel baseline rms					sel. channel baseline				
7	sel. channel dropped hits					sel. channel hit rate				
8	GBT event dropped					GBT fifo count				

Table 11: ADC channels threshold control.

addr	15 .. 10	9 .. 9	8 .. 8	7 .. 0
4	0x0	error ack	busy	DATA

Table 12: HV status via I2C.

Status registers comments:

- RX err detect cnt - counter@RXclk of RX error detected bit.
- RX err frclk cnt - counter@RXclk of state when frame clock is not ready.
- RX wrclk err cnt - counter@RXclk of state when word clock is not ready.

## 2.4 EvB Control

range	description
0 .. 63	EvB control
64 .. 127	ADC control
128 .. 191	EvB status
192 .. 255	ADC status
256	EvB GBT readout
257	EvB readout fifo count

Table 13: EvB registers mapping



addr	31 .. 28	27 .. 24	23 .. 20	19 .. 16	15 .. 12	11 .. 8	7 .. 4	3 .. 0
0	0x0						control word	
1	microslice gen counter@25ns							
2	microslice period							

Table 14: Evaluation board control registers.

bit	description
0	data processing reset
1	error reset

Table 15: Control word bits

addr	31 .. 28	27 .. 24	23 .. 20	19 .. 16	15 .. 12	11 .. 8	7 .. 4	3 .. 0
0	0x0			control status	GBT status			
1	sorter ms dropped				sorter hit dropped			
2	gbt reader link 1 ms dropped				gbt reader link 0 ms dropped			
3	status age				control age			

Table 16: Evaluation board status registers.

bit	description
0	MGT phalin cpll lock
1	RX word clock ready
2	RX frame clock ready
3	MGT link ready
4	TX reset done
5	TX FSM reset done
6	RX ready
7	RX error detected
8	RX error latched

Table 17: GBT status bits

bit	addr	description
0	16	control readback correct

Table 18: control status bits

### 3 CRI modules

#### 3.1 PSD CRI data sorting

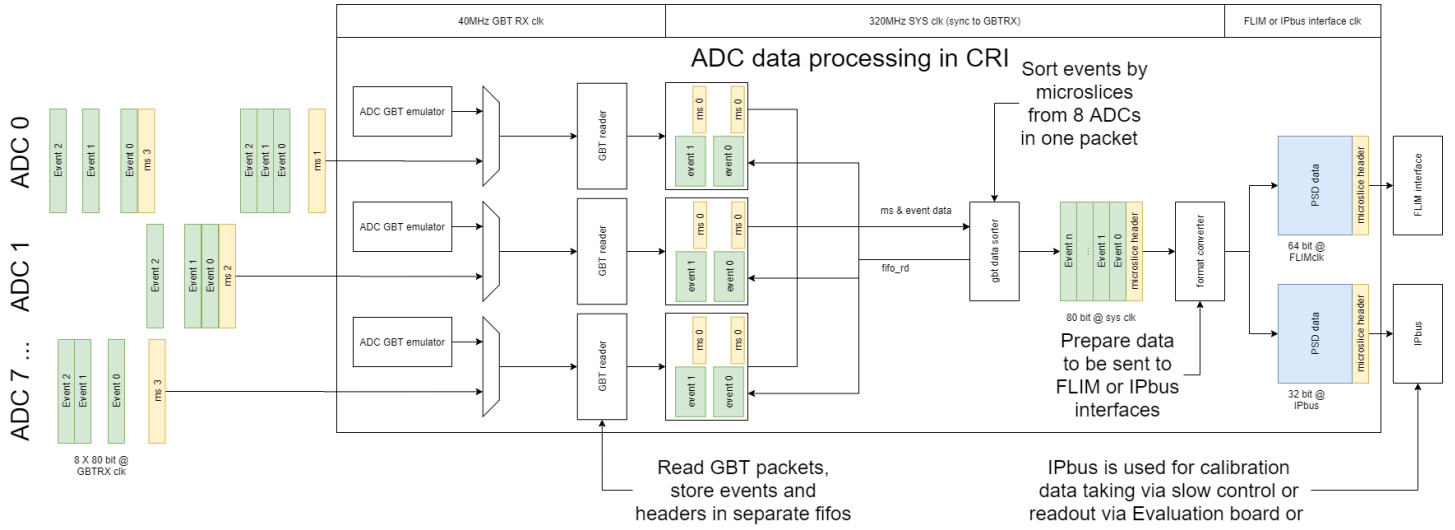


Figure 9: PSD data processing in CRI

#### 3.2 ADC GBT emulator

ADC GBT emulator generate GBT ADC packets filling hit packages with continuous hit counter. Parameters are:

- ms\_index - current microslice index @GBTclk to generate ms headers.
- event\_rate is number of GBT clock cycles between packets (from start to start). If previous packet was not sent, and is time to generate new one, new one skipped.
- nch\_in\_even - number of hits per event 1 ... 32. Emulate fired channels.
- hit\_packet\_len - number of hit packet words, including hit header 1 ... 5.

Emulator FSM is based on three counters, signals diagram is presented on figure 10; generated data format is presented on figure 11.

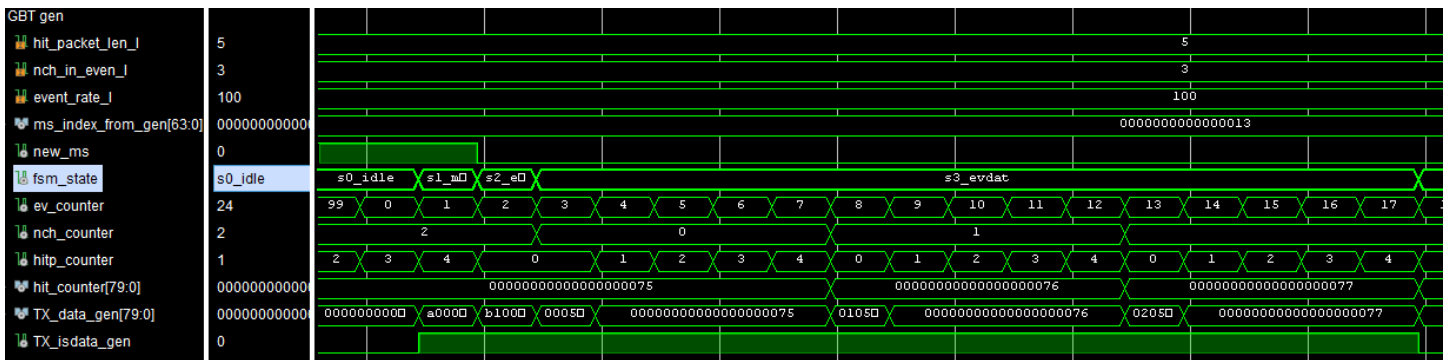


Figure 10: ADC GBT emulator signals

word type	79 .. 76	75 .. 72	71 .. 64	63 .. 48	47 .. 40	39 .. 32	31 .. 16	15 .. 0
ms header	0xA	0x0			ms index			
event header	0xB	ADC idx**	0x0		n hits	packet len *	0x0	
hit header	hit number		words in hit packet ***	ms index				
hit data	hit counter [79 ..0]							
hit data	hit counter [79 ..0]							
hit data	hit counter [79 ..0]							
hit data	hit counter [79 ..0]							
	...							
event header	0xB	ADC idx**	0x0		n hits	packet len *	0x0	
	...							

Table 19: GBT data format. [\* number of GBT words in event packet: event header + all hit packets] [\*\* ADC board index] [\*\*\* total words in hit packet, including hit header]

### 3.3 ADC GBT reader

ADC GBT reader reads GBT packets from one GBT link and store its to fifo-event\_fifo. With last packet data word header word pushed to separate fifo-header\_fifo with packet length and microslice index. Event packet skipped when one of fifos is full. After reset fsm starts wait microslice header. Packets reads according to size in header and fsm wait next packet or microslice header. If next word after packet is neither ms or packet header, fsm starts wait ms header. Data drop info state is not implemented yet. Signal diagram is presented on figure 13.

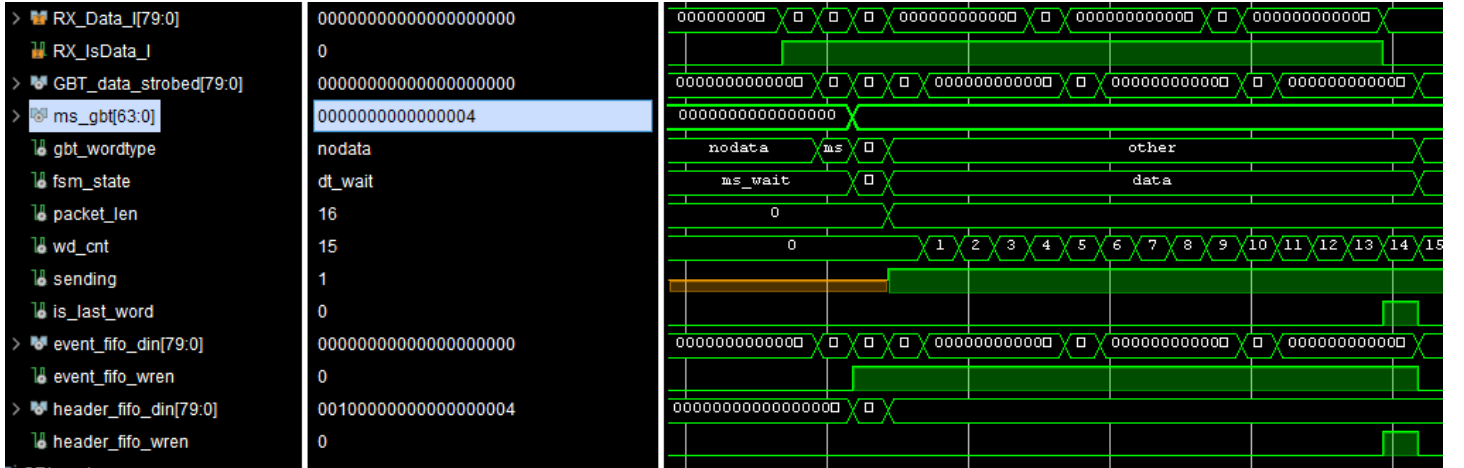
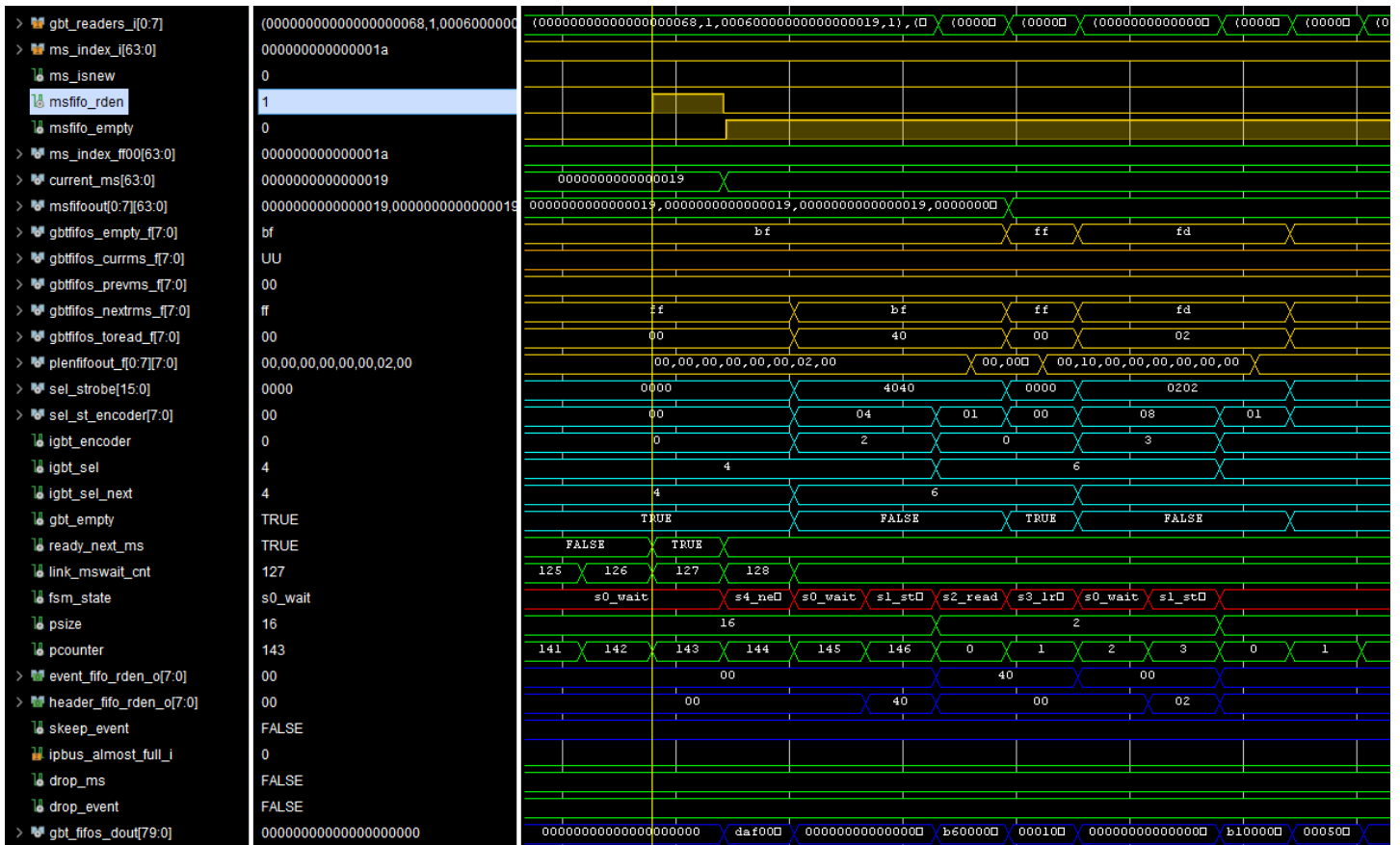


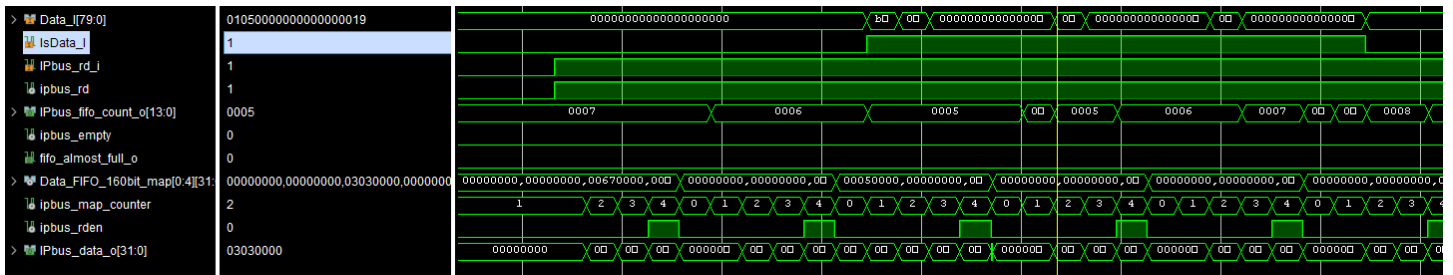
Figure 11: ADC GBT packets reader

### 3.4 GBT Data Sorter component

Components header\_fifo and event\_fifo from adc-gbt-readers for all gbt links are connected to gbt-data-sorter component. Each new microslice value collected in ms-fifo. FSM switch thought all gbt links and read all one by one links with microslice less or equal to current microslice. Data for links with equal microslice to current-ms output from the sorter, for links with less microslice data is dropped. When all links have ms higher than current ms or are empty means that all data for current microslice are read. Such condition starts counter to wait data from all links. Then counter reach value 127, FSM switched to next-ms state. Next microslice read from fifo and header with new ms value sent to output stream. Signal diagram presented on figure 12 Output data represent combined GBT packets from all GBT link. All events from GBT links for one microslice follows one after another. Data for different microslices divided by microslice header with format 0xDAF0 + microslice (64bit).



### 3.5 IPbus face component



### 3.6 Evaluation Board for readout