# **Human Activity Recognition**

Can different human activities be distinguished using data automatically collected by sensors attached to the actor's body? We explore this question with the Weight Lifting Exercise Dataset described here: http://groupware.les.inf.puc-rio.br/har

The data concerns dumbbell bicep curls done in one of five different manners (one correct, four incorrect) by 6 young subjects. If poor exercise technique can be automatically detected and diagnosed, efficiencies in training for exercises could be achieved. More information on published work with the data is available here:

Velloso, E.; Bulling, A.; Gellersen, H.; Ugulino, W.; Fuks, H. Qualitative Activity Recognition of Weight Lifting Exercises. Proceedings of 4th International Conference in Cooperation with SIGCHI (Augmented Human '13). Stuttgart, Germany: ACM SIGCHI, 2013.

#### Getting the data

The data is available for downloading from the internet.

```
if (!file.exists("pmltraining.csv")){
      urlTrain <- "http://d396qusza40orc.cloudfront.net/predmachlearn/pml-training.csv"
      download.file(url=urlTrain, destfile="./pmltraining.csv")
}
if (!file.exists("pmltesting.csv")){
      urlTest <- "http://d396qusza40orc.cloudfront.net/predmachlearn/pml-testing.csv"
      download.file(url=urlTest, destfile="./pmltesting.csv")
}
pmltraining <- read.csv("./pmltraining.csv")
pmltesting <- read.csv("./pmltesting.csv")</pre>
```

```
dim(pmltraining)
```

```
## [1] 19622 160
```

```
dim(pmltesting)
```

```
## [1] 20 160
```

It's a large data set, 19622 cases and 160 variables. There are 20 cases provided as "unknowns" to used as test cases.

The first 159 variables are potential predictors. Variable 160 is the response variable, "classe", for the training set. for the testing set, variable 160, "problem\_id", gives the problem number, keyed to the 20 problems to be submitted to the Coursera/Johns Hopkins Practical Machine Learning course.

```
class(pmltraining[,160])
## [1] "factor"
table(pmltraining[,160])
```

```
## # A B C D E
## 5580 3797 3422 3216 3607
```

There are 5 response levels, A, B, C, D, and E. Given values for the first 159 variables, our task is to predict the response A, B, C, D, and E.

#### Cleaning the data

There is plenty of missing data. Let's quantify that observation, checking the fraction of NAs for each variable.

```
##
             names.pmltraining. naFraction
## 1
                                      0.0000
## 2
                                      0.0000
                       user_name
## 3
           raw_timestamp_part_1
                                      0.0000
## 4
           raw_timestamp_part_2
                                      0.0000
## 5
                                      0.0000
                  cvtd_timestamp
## 6
                      new_window
                                      0.0000
## 7
                      num_window
                                      0.0000
## 8
                       roll_belt
                                      0.0000
## 9
                      pitch_belt
                                      0.0000
## 10
                        yaw_belt
                                      0.0000
## 11
                total_accel_belt
                                      0.0000
## 12
             kurtosis roll belt
                                      0.0000
## 13
            kurtosis_picth_belt
                                      0.0000
## 14
              kurtosis_yaw_belt
                                      0.0000
              skewness_roll_belt
                                      0.0000
## 15
## 16
           skewness_roll_belt.1
                                      0.0000
## 17
              skewness_yaw_belt
                                      0.0000
## 18
                   max_roll_belt
                                      0.9793
## 19
                  max_picth_belt
                                      0.9793
## 20
                    max_yaw_belt
                                      0.0000
## 21
                   min_roll_belt
                                      0.9793
## 22
                                      0.9793
                  min_pitch_belt
## 23
                    min_yaw_belt
                                      0.0000
## 24
            amplitude_roll_belt
                                      0.9793
## 25
           amplitude_pitch_belt
                                      0.9793
## 26
             amplitude_yaw_belt
                                      0.0000
## 27
           var_total_accel_belt
                                      0.9793
## 28
                   avg_roll_belt
                                      0.9793
## 29
                stddev_roll_belt
                                      0.9793
                                      0.9793
## 30
                   var_roll_belt
```

```
## 31
                  avg_pitch_belt
                                      0.9793
## 32
                                      0.9793
              stddev_pitch_belt
## 33
                  var_pitch_belt
                                      0.9793
## 34
                                      0.9793
                    avg_yaw_belt
## 35
                 stddev_yaw_belt
                                      0.9793
## 36
                                      0.9793
                    var_yaw_belt
## 37
                    gyros_belt_x
                                      0.0000
## 38
                    gyros_belt_y
                                      0.0000
## 39
                    gyros_belt_z
                                      0.0000
## 40
                                      0.0000
                    accel_belt_x
## 41
                    accel_belt_y
                                      0.0000
## 42
                    accel_belt_z
                                      0.0000
## 43
                   magnet_belt_x
                                      0.0000
## 44
                   magnet_belt_y
                                      0.0000
## 45
                                      0.0000
                   magnet_belt_z
## 46
                        roll_arm
                                      0.0000
## 47
                                      0.0000
                       pitch_arm
## 48
                                      0.0000
                         yaw_arm
## 49
                                      0.0000
                 total_accel_arm
## 50
                   var_accel_arm
                                      0.9793
## 51
                    avg_roll_arm
                                      0.9793
## 52
                 stddev_roll_arm
                                      0.9793
## 53
                                      0.9793
                    var_roll_arm
## 54
                                      0.9793
                   avg_pitch_arm
## 55
                                      0.9793
                stddev_pitch_arm
## 56
                   var_pitch_arm
                                      0.9793
## 57
                                      0.9793
                     avg_yaw_arm
## 58
                                      0.9793
                  stddev_yaw_arm
## 59
                                      0.9793
                     var_yaw_arm
## 60
                                      0.0000
                     gyros_arm_x
## 61
                     gyros_arm_y
                                      0.0000
## 62
                     gyros_arm_z
                                      0.0000
## 63
                     accel_arm_x
                                      0.0000
## 64
                                      0.0000
                     accel_arm_y
## 65
                     accel_arm_z
                                      0.0000
## 66
                                      0.0000
                    magnet_arm_x
## 67
                    magnet_arm_y
                                      0.0000
## 68
                                      0.0000
                    magnet_arm_z
## 69
              kurtosis_roll_arm
                                      0.0000
## 70
                                      0.0000
             kurtosis_picth_arm
## 71
                                      0.0000
               kurtosis_yaw_arm
## 72
              skewness_roll_arm
                                      0.0000
## 73
                                      0.0000
             skewness_pitch_arm
## 74
                                      0.0000
               skewness_yaw_arm
## 75
                                      0.9793
                    max_roll_arm
## 76
                                      0.9793
                   max_picth_arm
## 77
                     max_yaw_arm
                                      0.9793
## 78
                                      0.9793
                    min_roll_arm
## 79
                   min_pitch_arm
                                      0.9793
## 80
                                      0.9793
                     min_yaw_arm
## 81
                                      0.9793
             amplitude_roll_arm
                                      0.9793
## 82
             amplitude_pitch_arm
## 83
              amplitude_yaw_arm
                                      0.9793
## 84
                   roll dumbbell
                                      0.0000
```

```
## 85
                  pitch_dumbbell
                                      0.0000
## 86
                                      0.0000
                    yaw_dumbbell
## 87
         kurtosis roll dumbbell
                                      0.0000
## 88
        kurtosis_picth_dumbbell
                                      0.0000
##
  89
          kurtosis_yaw_dumbbell
                                      0.0000
##
  90
         skewness roll dumbbell
                                      0.0000
## 91
                                      0.0000
        skewness_pitch_dumbbell
## 92
          skewness_yaw_dumbbell
                                      0.0000
## 93
              max_roll_dumbbell
                                      0.9793
##
  94
             max_picth_dumbbell
                                      0.9793
##
  95
               max_yaw_dumbbell
                                      0.0000
## 96
              min_roll_dumbbell
                                      0.9793
  97
##
             min_pitch_dumbbell
                                      0.9793
## 98
                                      0.0000
               min_yaw_dumbbell
## 99
        amplitude_roll_dumbbell
                                      0.9793
## 100
       amplitude_pitch_dumbbell
                                      0.9793
## 101
                                      0.0000
         amplitude_yaw_dumbbell
## 102
           total accel dumbbell
                                      0.0000
## 103
             var_accel_dumbbell
                                      0.9793
## 104
              avg_roll_dumbbell
                                      0.9793
## 105
           stddev_roll_dumbbell
                                      0.9793
## 106
              var_roll_dumbbell
                                      0.9793
## 107
             avg_pitch_dumbbell
                                      0.9793
          stddev_pitch_dumbbell
## 108
                                      0.9793
## 109
             var_pitch_dumbbell
                                      0.9793
## 110
                avg_yaw_dumbbell
                                      0.9793
## 111
            stddev_yaw_dumbbell
                                      0.9793
## 112
                var_yaw_dumbbell
                                      0.9793
## 113
                gyros_dumbbell_x
                                      0.0000
## 114
                gyros_dumbbell_y
                                      0.0000
## 115
                gyros_dumbbell_z
                                      0.0000
## 116
                accel_dumbbell_x
                                      0.0000
## 117
                accel_dumbbell_y
                                      0.0000
## 118
                accel_dumbbell_z
                                      0.0000
## 119
              magnet dumbbell x
                                      0.0000
## 120
                                      0.0000
              magnet_dumbbell_y
## 121
              magnet_dumbbell_z
                                      0.0000
## 122
                    roll_forearm
                                      0.0000
## 123
                   pitch_forearm
                                      0.0000
## 124
                                      0.0000
                     yaw_forearm
          kurtosis_roll_forearm
## 125
                                      0.0000
## 126
         kurtosis_picth_forearm
                                      0.0000
## 127
           kurtosis_yaw_forearm
                                      0.0000
## 128
          skewness_roll_forearm
                                      0.0000
## 129
                                      0.0000
         skewness_pitch_forearm
## 130
           skewness_yaw_forearm
                                      0.0000
## 131
               max_roll_forearm
                                      0.9793
## 132
              max_picth_forearm
                                      0.9793
## 133
                max_yaw_forearm
                                      0.0000
## 134
               min_roll_forearm
                                      0.9793
## 135
                                      0.9793
              min_pitch_forearm
## 136
                min_yaw_forearm
                                      0.0000
## 137
         amplitude_roll_forearm
                                      0.9793
## 138
        amplitude_pitch_forearm
                                      0.9793
```

```
## 139
          amplitude_yaw_forearm
                                     0.0000
## 140
            total_accel_forearm
                                     0.0000
                                     0.9793
## 141
              var_accel_forearm
## 142
               avg_roll_forearm
                                     0.9793
## 143
            stddev_roll_forearm
                                     0.9793
## 144
               var_roll_forearm
                                     0.9793
## 145
              avg_pitch_forearm
                                     0.9793
## 146
           stddev_pitch_forearm
                                     0.9793
## 147
              var_pitch_forearm
                                     0.9793
## 148
                avg_yaw_forearm
                                     0.9793
## 149
             stddev_yaw_forearm
                                     0.9793
## 150
                var_yaw_forearm
                                     0.9793
## 151
                gyros_forearm_x
                                     0.0000
## 152
                gyros_forearm_y
                                     0.0000
## 153
                                     0.0000
                gyros_forearm_z
## 154
                accel_forearm_x
                                     0.0000
## 155
                accel_forearm_y
                                     0.0000
## 156
                accel_forearm_z
                                     0.0000
## 157
                                     0.0000
               magnet_forearm_x
## 158
               magnet_forearm_y
                                     0.0000
## 159
               magnet_forearm_z
                                     0.0000
## 160
                          classe
                                     0.0000
```

Thus it turns out that the variables divide neatly into two sets, those with no missing data and those with over 97 percent NAs. We begin to build the cleaner *training* and *testing* sets we will actually use by selecting just the variables without missing data.

```
goodvarsL <- naFraction < 0.01
sum(goodvarsL)

## [1] 93

max(naCount[goodvarsL])

## [1] 0

training <- pmltraining[, names(pmltraining)[goodvarsL]]
testing <- pmltesting[, names(pmltesting)[goodvarsL]]
dim(training)

## [1] 19622 93

dim(testing)</pre>
```

We have reduced the number of variables from 160 to 93.

## [1] 20 93

The variable X is a unique identifier for the cases, so it is not useful for prediction. We drop it.

```
training <- training[ , !names(training)=="X"]
testing <- testing[ , !names(testing)=="X"]</pre>
```

We will build our predictor with a random forest. We plan to use the caret package, which calls randomForest command, which at present does not accept categorical predictor variables with 32 or more levels. Since there are some in the training data set, we remove them.

## [1] 68

So we only keep 67 predictor variables and the 1 response variable.

```
train1 <- training[,varkeep]
test <- testing[,varkeep]
dim(train1)</pre>
```

```
## [1] 19622 68
```

But now we note that 9 of the variables in the 20 case test set are missing all data. We remove those variables from the data set.

```
badTestVars <- c("kurtosis_yaw_belt", "skewness_yaw_belt", "amplitude_yaw_belt", "kurtosis_yaw_dumbbell
train1 <- train1[,!(names(train1) %in% badTestVars )]
dim(train1)

## [1] 19622 59
test <- test[,!(names(test) %in% badTestVars )]</pre>
```

```
## [1] 20 59
```

dim(test)

So in the end we only keep 58 predictor variables and the 1 response variable.

### Separating off a cross-validation set for checking out-of-sample accuracy

Because it takes so long to run the full data set, we run it on only part of the data. We take a random selection of 10000 of the 19622 observations

```
set.seed(12345)
nsample <- 10000
samples <- sample(nrow(train1), size = nsample)
train1 <- train1[samples,]</pre>
```

We partition our training data set train1 into two subsets: train2 contains 90% of the cases and will be used to train the predictor. crossval2 contains 10% of the cases and will be used to make an out of sample estimate of the accuracy.

```
long <- nrow(train1)
trainrows <- sample(long, size = round(0.9*long))
crossvrows <- c(1:long)[is.na(pmatch(x=c(1:long), table = trainrows))]
train2 <- train1[trainrows,]
crossval2 <- train1[crossvrows,]
dim(train2)

## [1] 9000 59</pre>

## [1] 1000 59
```

# Building and evaluating the predictor

We use the caret package to build a random forest predictor. It takes about 5 hours to run on our reduced data set, so we save the predictor as an RDS file for future use, enabling us to deactivate the train command command during final editing of the rmd file. During the editing, we read in the modFit1 file that the train command produced the first time through.

```
library(caret)
modFit1 <- train(classe~ ., data=train2, method="rf", prox=TRUE)</pre>
modFit1
saveRDS(modFit1, "model10000alt.RDS")
modFit1 = readRDS("model10000alt.RDS")
modFit1
## Random Forest
##
## 9000 samples
     58 predictors
##
      5 classes: 'A', 'B', 'C', 'D', 'E'
##
##
## No pre-processing
## Resampling: Bootstrapped (25 reps)
##
## Summary of sample sizes: 9000, 9000, 9000, 9000, 9000, 9000, ...
## Resampling results across tuning parameters:
```

```
##
##
    mtry Accuracy Kappa Accuracy SD Kappa SD
                                         0.003
##
                            0.002
                            0.001
                                         0.002
##
     40
           1
                     1
                                         0.002
##
     80
           1
                            0.002
##
## Accuracy was used to select the optimal model using the largest value.
## The final value used for the model was mtry = 41.
```

Now for a prediction on the cross validation set. We are able to compare the predictions with the true values on 1000 cases that are not part of the training set.

```
predictCrossVal <- predict(modFit1, crossval2)

## Warning: package 'randomForest' was built under R version 3.1.1

rightOrWrong <- predictCrossVal == crossval2[, "classe"]

table(rightOrWrong)

## rightOrWrong

## FALSE TRUE

## 1 999

accuracy <- sum(rightOrWrong)/length(rightOrWrong)
accuracy</pre>
```

The predictor was correct in 999 out of 1000 cases in the cross-validation set, an accuracy of 99.9%. The estimated out-of-sample error rate is 0.1%.

## Predicting the unknown test set

## [1] 0.999

## Levels: A B C D E

Finally, we use our predictor to classify the twenty observations with unknown solution that constitute the Practical Machine Learning course problem set.

```
predictVars1 <- predict(modFit1, test)
predictVars1
## [1] B A B A A E D B A A B C B A E E A B B B</pre>
```