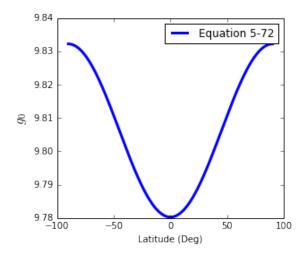
Tarea 3 Geodinamica

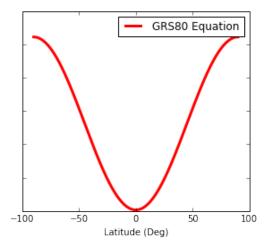
September 18, 2016

```
In [2]: import numpy as np
         import matplotlib.pyplot as plt
         %matplotlib inline
   Problem 5-5 from Turcotte and Schubert: Determine the values of the acceleration of gravity at the
equator and the poles using GRS 80 and the quadratic approximation given in Equation (5–72).
   Equation 5-72:
   g_0 = \frac{GM}{a^2} \left( 1 + \frac{3}{2} J_2 \cos^2 \phi \right) + a\omega^2 (\sin^2 \phi - \cos^2 \phi).
   GRS80 equation from T&S:
              9.7803267715(1 + 0.0052790414\sin^2\phi + 0.0000232718\sin^4\phi + 0.0000001262\sin^6\phi +
0.00000000007 \sin^8 \phi
   From Wikipedia's GRS80 page:
   Defining geometrical constants:
   • Semi-major axis = Equatorial Radius =
   $ a=6378137m$
   Defining physical constants:
   • Geocentric gravitational constant, including mass of the atmosphere
   GM = 3986005 \times 10^8 m^3/s^2
   • Dynamical form factor
   J_2 = 108263 \times 10^{-8}
   • Angular velocity of rotation
   \omega=7292115\times 10^{-11} rad/s
In [3]: def GRS_g0(phi):
              #returns gravity acceleration according to GRS80 standard
              # in m/s^2
              return 9.7803267715*(1+0.0052790414*(np.sin(phi))**2+\
                                     0.0000232718*(np.sin(phi))**4+
                                     0.0000001262*(np.sin(phi))**6+
                                     0.0000000007*(np.sin(phi))**8)
         a=6378137. #m
         GM=3986005e8 #m^3/s^2
         J2=108263e-8 #dimensionless
         omega=7292115e-11 #rad/s
         def g0(phi):
```

#returns gravity acceleration according to GRS80 constants and T&S' equation 5-72

```
# in m/s^2
            global a
            global GM
            global J2
            global omega
            return (GM/(a**2))*(1+1.5*J2*(np.cos(phi))**2)
                        +(a*omega**2)*((np.sin(phi))**2-(np.cos(phi))**2)
In [17]: #usingEquation=[northPole, southPole, equator]
         usingGRS=np.array([GRS_g0(np.pi/2), GRS_g0(-np.pi/2), GRS_g0(0.)])
         usingEq572=np.array([g0(np.pi/2), g0(-np.pi/2), g0(0.)])
         print 'The value for gravity at the north and south poles n \
         from GRS80 equation are respectively %(north).6f \n and %(south)\
         .6f, while for the equator it is \%(equator).6f \n '\
         %{'north':usingGRS[0],'south':usingGRS[1], 'equator':usingGRS[2]}
         print 'The value for gravity at the north and south poles n \
         from equation 5-72 are respectively %(north).6f \n and <math>%(south) \
         .6f, while for the equator it is %(equator).6f \n '\
         %{'north':usingEq572[0],'south':usingEq572[1], 'equator':usingEq572[2]}
         errPerc=abs(100.*(usingEq572-usingGRS)/usingEq572)
         print 'The percentage difference between methods is \n of the order of 4e-4%.',errPerc
The value for gravity at the north and south poles
from GRS80 equation are respectively 9.832186
and 9.832186, while for the equator it is 9.780327
The value for gravity at the north and south poles
from equation 5-72 are respectively 9.832203
and 9.832203, while for the equator it is 9.780283
The percentage difference between methods is
of the order of 4e-4%. [ 0.00016525 0.00016525 0.0004467 ]
  It is possible to see that there are slight differences between methods, but these are truly negligible as
the percentual differences between values are of the order of 10^{-4}\%.
In [5]: latitude=np.linspace(-np.pi/2, np.pi/2, 1000)
        gravities, ax=plt.subplots(1, 2, sharey=True, figsize=(10,4))
        ax[0].plot(np.rad2deg(latitude), g0(latitude), label='Equation 5-72', lw=3)
        ax[1].plot(np.rad2deg(latitude), GRS_g0(latitude), label='GRS80 Equation', c='r', lw=3)
        for i in range(len(ax)):
            ax[i].set_xlabel('Latitude (Deg)')
            ax[i].legend(loc=0)
        ax[0].set_ylabel('$g_0$', fontsize=15)
Out[5]: <matplotlib.text.Text at 0x6fd23c8>
```





In []: