Sol HW 10

May 13, 2018

$$\begin{bmatrix} \frac{\hbar\omega_0}{4}\sqrt{2} & \frac{\hbar\omega_0}{4}\sqrt{2} \\ \frac{\hbar\omega_0}{4}\sqrt{2} & -\frac{\hbar\omega_0}{4}\sqrt{2} \end{bmatrix}$$

$$\left[\left(-\frac{\hbar\omega_0}{2}, \quad 1, \quad \left[\begin{bmatrix} -\frac{\sqrt{2}\hbar\omega_0}{4\left(\frac{\hbar\omega_0}{4}\sqrt{2} + \frac{\hbar\omega_0}{2}\right)} \\ 1 \end{bmatrix} \right] \right), \quad \left(\frac{\hbar\omega_0}{2}, \quad 1, \quad \left[\begin{bmatrix} -\frac{2\sqrt{2}}{\hbar\omega_0}\left(-\frac{\hbar\omega_0}{2} - \frac{\hbar\omega_0}{4}\sqrt{2}\right) \\ 1 \end{bmatrix} \right] \right]$$

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'sn dn'
                                                                                                   -0.38268343236509
                                                                                                   0.923879532511287
'sn_up'
                                                                                                   0.923879532511287
0.38268343236509
In [4]: th, phi, w = symbols('theta phi omega', real=True)
                       chi_n_up = Matrix([[cos(th/2)],[sin(th/2)*exp(I*phi)]])
                       chi_n_dn = Matrix([[sin(th/2)], [-cos(th/2)*exp(I*phi)]])
                       sn_up = chi_n_up.subs(th,pi/4).subs(phi,0)
                       sn_dn = chi_n_dn.subs(th,pi/4).subs(phi,0)
                       display('sn_up',sn_up.evalf())
                       display('sn_dn',sn_dn.evalf())
'sn_up'
                                                                                                   0.923879532511287
0.38268343236509
'sn_dn'
                                                                                               0.38268343236509
-0.923879532511287
In [5]: asq, bsq,t = symbols('a^2 b^2 t', positive=True, real=True)
                       minus = Matrix([[0], [1]])
                       solve(Eq(minus[0], asq*vec1[0] + bsq*vec2[0]), (asq,bsq))[0][asq]
                       solve(Eq(minus[1], asq*vec1[1] + bsq*vec2[1]), (asq,bsq))[0][asq]
                       b = solve(Eq(solve(Eq(minus[0], asq*vec1[0] + bsq*vec2[0]),\
                                                                                 (asq,bsq))[0][asq],solve(Eq(minus[1], asq*vec1[1] + bsq*vec2[1]), (asq.bsq))[0][asq],solve(Eq(minus[1], asq*vec1[1] + bsq*vec2[1]), (asq.bsq))[0][asq.bsq)[asq.bsq],solve(Eq(minus[1], asq*vec1[1] + bsq*vec2[1]), (asq.bsq)[asq.bsq],solve(Eq(minus[1], asq.bsq))[asq.bsq],solve(Eq(minus[1], asq.bsq))[a
                       a = solve(Eq(minus[1], asq*vec1[1] + bsq*vec2[1]), (asq,bsq))[0][asq].subs(bsq, b)
                       display('P_sn_dn=a**2',(a**2).evalf(),'P_sn_up=b**2',(b**2).evalf())
                        #Se pueden obtener -hw/2 con probabilidad a**2 y hw/2 con probabilidad b**2
'P_sn_dn=a**2'
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'P_sn_up=b**2'
```

0.146446609406726

$$\begin{bmatrix} -0.353553390593274e^{\frac{i\omega_0}{2}t} + 0.353553390593274e^{-\frac{i\omega_0}{2}t} \\ 0.853553390593274e^{\frac{i\omega_0}{2}t} + 0.146446609406726e^{-\frac{i\omega_0}{2}t} \end{bmatrix}$$

$$-\frac{\hbar}{2}\sin^2\left(\frac{\omega_0t}{2}\right)$$

2 Problema 7

'S1y'

$$\begin{bmatrix} 0 & 0 & -\frac{i\hbar}{2} & 0 \\ 0 & 0 & 0 & -\frac{i\hbar}{2} \\ \frac{i\hbar}{2} & 0 & 0 & 0 \\ 0 & \frac{i\hbar}{2} & 0 & 0 \end{bmatrix}$$

In [9]: S1y.eigenvects()

Out[9]:

$$\left[\left(-\frac{\hbar}{2}, 2, \begin{bmatrix} \begin{bmatrix} i \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ i \\ 0 \\ 1 \end{bmatrix} \right), \left(\frac{\hbar}{2}, 2, \begin{bmatrix} \begin{bmatrix} -i \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ -i \\ 0 \\ 1 \end{bmatrix} \right) \right]$$

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In [10]: a, b, g, d = symbols('alpha beta gamma delta', real=False)
              Ket_p = Matrix([[1],[0]])
              Ket_m = Matrix([[0],[1]])
              Ket_pp = TP(Ket_p,Ket_p)
              Ket_pm = TP(Ket_p,Ket_m)
              Ket_mp = TP(Ket_m, Ket_p)
              Ket_mm = TP(Ket_m, Ket_m)
              init = a*Ket_pp + b*Ket_pm + g*Ket_mp + d*Ket_mm
              init
    Out[10]:
In [11]: sx = [chi_n_up.subs(th,pi/2).subs(phi,0),chi_n_dn.subs(th,pi/2).subs(phi,0)]
              sy = [chi_n_up.subs(th,pi/2).subs(phi,pi/2),chi_n_dn.subs(th,pi/2).subs(phi,pi/2)]
              Ket_pxpy = TP(sx[0], sy[0])
              Ket_pxmy = TP(sx[0], sy[1])
              Ket_mxpy = TP(sx[1], sy[0])
              Ket_mxmy = TP(sx[1], sy[1])
              Base_change=Matrix([Ket_pxpy,Ket_pxmy,Ket_mxpy, Ket_mxmy]).reshape(4,4).transpose()
              init_sxsy = Dagger(Base_change)*init
              display(init_sxsy)
                                                      \begin{bmatrix} \frac{\alpha}{2} - \frac{i\beta}{2} - \frac{i\delta}{2} + \frac{\gamma}{2} \\ \frac{\alpha}{2} + \frac{i\beta}{2} + \frac{i\delta}{2} + \frac{\gamma}{2} \\ \frac{\alpha}{2} - \frac{i\beta}{2} + \frac{i\delta}{2} - \frac{\gamma}{2} \\ \frac{\alpha}{2} + \frac{i\beta}{2} - \frac{i\delta}{2} - \frac{\gamma}{2} \end{bmatrix}
In [12]: 1, m, n, o = symbols('l m n o', real=False)
              Ket_z1 = 1*Ket_p + m*Ket_m
              Ket_z2 = n*Ket_p + o*Ket_m
              state= expand(TP(Ket_z1,Ket_z2))
              state_sxsy = simplify(Dagger(Base_change)*state)
              display(state_sxsy)
              solve(init_sxsy-state_sxsy)
                                                    \begin{bmatrix} \frac{\ln}{2} - \frac{il}{2}o + \frac{mn}{2} - \frac{im}{2}o \\ \frac{\ln}{2} + \frac{il}{2}o + \frac{mn}{2} + \frac{im}{2}o \\ \frac{\ln}{2} - \frac{il}{2}o - \frac{mn}{2} + \frac{im}{2}o \\ \frac{\ln}{2} + \frac{il}{2}o - \frac{mn}{2} - \frac{im}{2}o \end{bmatrix}
    Out[12]:
                                          [\{\alpha: ln, \beta: lo, \delta: mo, \gamma: mn\}]
```

```
In [13]: Ket_pypy = TP(sy[0],sy[0])
                    Ket_pymy = TP(sy[0], sy[1])
                    Ket_mypy = TP(sy[1], sy[0])
                    Ket_mymy = TP(sy[1], sy[1])
                    Base_change=Matrix([Ket_pypy,Ket_pymy,Ket_mypy, Ket_mymy]).reshape(4,4).transpose()
                    init_sysy = Dagger(Base_change)*init
                    display(init_sysy)
                                                                           \begin{bmatrix} \frac{\alpha}{2} - \frac{i\beta}{2} - \frac{\delta}{2} - \frac{i\gamma}{2} \\ \frac{\alpha}{2} + \frac{i\beta}{2} + \frac{\delta}{2} - \frac{i\gamma}{2} \\ \frac{\alpha}{2} - \frac{i\beta}{2} + \frac{\delta}{2} + \frac{i\gamma}{2} \\ \frac{\alpha}{2} + \frac{i\beta}{2} - \frac{\delta}{2} + \frac{i\gamma}{2} \end{bmatrix}
In [14]: state_sysy = simplify(Dagger(Base_change)*state)
                    display(state_sysy)
                    solve(init_sysy-state_sysy)

\begin{bmatrix}
\frac{\ln}{2} - \frac{il}{2}o - \frac{im}{2}n - \frac{mo}{2} \\
\frac{\ln}{2} + \frac{il}{2}o - \frac{im}{2}n + \frac{mo}{2} \\
\frac{\ln}{2} - \frac{il}{2}o + \frac{im}{2}n + \frac{mo}{2} \\
\frac{\ln}{2} + \frac{il}{2}o + \frac{im}{2}n - \frac{mo}{2}
\end{bmatrix}

      Out[14]:
                                                          [\{\alpha: ln, \beta: lo, \delta: mo, \gamma: mn\}]
In [15]: #De b:
                    Pb = init_sxsy.conjugate().multiply_elementwise(init_sxsy)
                    display('Psy-, b', factor(Pb[1]+Pb[3]))
                    #De c:
                    Pc = init_sysy.conjugate().multiply_elementwise(init_sysy)
                    display('Psy-,c', factor(Pc[1]+Pc[3]))
'Psy-, b'
                                            -rac{1}{2}\left(-lpha\overline{lpha}+ilpha\overline{eta}-ieta\overline{lpha}-eta\overline{eta}-\delta\overline{\delta}-i\delta\overline{\gamma}+i\gamma\overline{\delta}-\gamma\overline{\gamma}
ight)
'Psy-,c'
                                            -rac{1}{2}\left(-lpha\overline{lpha}+ilpha\overline{eta}-ieta\overline{lpha}-eta\overline{eta}-\delta\overline{\delta}-i\delta\overline{\gamma}+i\gamma\overline{\delta}-\gamma\overline{\gamma}
ight)
```