Descomposición en valores singulares (SVD)

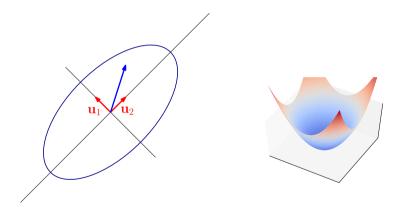
■ SVD: Matrices $m \times n$

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- Formulación SVD.

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- Interpretación.

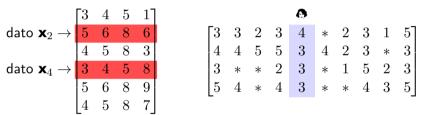
- SVD: Matrices $m \times n$
- Formulación SVD.
- Interpretación.

Matriz $\mathbf{A} \in \mathbb{R}^{n \times n}$ simétrica positiva definida



 $\mathbf{A} = \mathbf{S} \boldsymbol{\Lambda} \mathbf{S}^T$

Matriz $\mathbf{A} \in \mathbb{R}^{m \times n}$



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- Algo similar?

$$\mathbf{x} \in \mathbb{R}^n \longrightarrow \mathbf{A} \longrightarrow \mathbf{y} = \mathbf{A}\mathbf{x} \in \mathbb{R}^m$$

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 \mathbf{A} $\mathbf{y} = \mathbf{A}\mathbf{x} \in \mathbb{R}^m$

$$egin{array}{c} egin{array}{c} oldsymbol{^{m imes n}} \ oldsymbol{^{A}} oldsymbol{\mathbf{v}}_i = \sigma_i oldsymbol{\mathbf{u}}_i \end{array}$$

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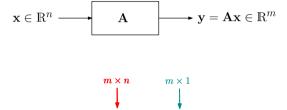




$$\mathbf{x} \in \mathbb{R}^n$$
 \mathbf{A} $\mathbf{y} = \mathbf{A}\mathbf{x} \in \mathbb{R}^m$



 \mathbf{v}_i : Base ortonormal del espacio expandido por las filas de \mathbf{A} .



- \mathbf{v}_i : Base ortonormal del espacio expandido por las filas de \mathbf{A} .
- \mathbf{u}_i : Base ortonormal del espacio expandido por las columnas de \mathbf{A} .

$$\begin{bmatrix} \mathbf{A}\mathbf{v}_1 & \mathbf{A}\mathbf{v}_2 & \dots & \mathbf{A}\mathbf{v}_r \end{bmatrix} = \begin{bmatrix} \sigma_1\mathbf{u}_1 & \sigma_2\mathbf{u}_2 & \dots & \sigma_r\mathbf{u}_r \end{bmatrix}$$

$$\begin{bmatrix} \mathbf{A}\mathbf{v}_1 & \mathbf{A}\mathbf{v}_2 & \dots & \mathbf{A}\mathbf{v}_r & \mathbf{A}\mathbf{v}_{r+1} & \dots & \mathbf{A}\mathbf{v}_n \end{bmatrix} = \begin{bmatrix} \sigma_1\mathbf{u}_1 & \sigma_2\mathbf{u}_2 & \dots & \sigma_r\mathbf{u}_r & \mathbf{0} & \dots & \mathbf{0} \end{bmatrix}$$

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 $AV = U\Sigma$

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 $\mathbf{AV} = \mathbf{U}\mathbf{\Sigma}$ $\mathbf{AVV}^T = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^T$

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$$\mathbf{AV} = \mathbf{U}\mathbf{\Sigma}$$
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Descomposición en valores singulares de A.

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- Descomposición en valores singulares de A.
- **U**, **∑**, **V** ?

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$$\mathbf{A} \begin{bmatrix} \mathbf{v}_1 & \mathbf{v}_2 & \dots & \mathbf{v}_n \end{bmatrix} = \begin{bmatrix} \mathbf{u}_1 & \mathbf{u}_2 & \dots & \mathbf{u}_n \end{bmatrix} \begin{bmatrix} \sigma_1 & 0 & \cdots & 0 \\ 0 & \sigma_2 & \cdots & \vdots \\ \vdots & 0 & \ddots & \\ 0 & \cdots & \sigma_n \end{bmatrix}$$

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- Descomposición en valores singulares de A.
- **U**, **∑**, **V**?
 - **U**, **V** con columnas ortonormales.
 - **Av**_i = σ_i **u**_i, con $\sigma_i > 0$.

 $n \times n$.

- \blacksquare $n \times n$.
- Simétrica.

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- Positiva (semi) definida:

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Podemos factorizar:

$$\mathbf{A}^T\mathbf{A} = \mathbf{V}\Lambda\mathbf{V}^T$$

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$$\mathbf{A}^{\mathsf{T}}\mathbf{A} = \mathbf{V}\boldsymbol{\Sigma}\mathbf{U}^{\mathsf{T}}\mathbf{U}\boldsymbol{\Sigma}\mathbf{V}^{\mathsf{T}} = \mathbf{V}\boldsymbol{\Sigma}^{2}\mathbf{V}^{\mathsf{T}}$$

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- Entonces:
 - \blacksquare Columnas de **V** son vectores propios de $\mathbf{A}^T\mathbf{A}$ ortonormales.

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- Entonces:
 - \blacksquare Columnas de **V** son vectores propios de $\mathbf{A}^T\mathbf{A}$ ortonormales.
 - Valores propios $\lambda_i = \sigma_i^2$.

 $\mathbf{A}\mathbf{v}_i = \sigma_i \mathbf{u}_i$

$$\mathbf{A}\mathbf{v}_i = \sigma_i \mathbf{u}_i \Rightarrow \mathbf{u}_i = \frac{1}{\sigma_i} \mathbf{A}\mathbf{v}_i$$

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$$\mathbf{u}_i^T \mathbf{u}_i$$

$$\mathbf{A}\mathbf{v}_i = \sigma_i \mathbf{u}_i \Rightarrow \mathbf{u}_i = \frac{1}{\sigma_i} \mathbf{A}\mathbf{v}_i$$

$$\mathbf{u}_i^T \mathbf{u}_j = \frac{1}{\sigma_i} (\mathbf{A} \mathbf{v}_i)^T$$

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$$\mathbf{u}_i^T \mathbf{u}_j = \frac{1}{\sigma_i} (\mathbf{A} \mathbf{v}_i)^T \frac{1}{\sigma_i} \mathbf{A} \mathbf{v}_j$$

$$\mathbf{A}\mathbf{v}_i = \sigma_i \mathbf{u}_i \Rightarrow \mathbf{u}_i = \frac{1}{\sigma_i} \mathbf{A}\mathbf{v}_i$$

$$\mathbf{u}_{i}^{T}\mathbf{u}_{j} = \frac{1}{\sigma_{i}}(\mathbf{A}\mathbf{v}_{i})^{T}\frac{1}{\sigma_{i}}\mathbf{A}\mathbf{v}_{j} = \frac{1}{\sigma_{i}\sigma_{j}}\mathbf{v}_{i}\mathbf{A}^{T}\mathbf{A}\mathbf{v}_{j}$$

$\mathbf{A}\mathbf{v}_i = \sigma_i \mathbf{u}_i \Rightarrow \mathbf{u}_i = \frac{1}{\sigma_i} \mathbf{A}\mathbf{v}_i$

$$\mathbf{u}_i{}^T\mathbf{u}_j = \frac{1}{\sigma_i}(\mathbf{A}\mathbf{v}_i)^T\frac{1}{\sigma_i}\mathbf{A}\mathbf{v}_j = \frac{1}{\sigma_i\sigma_i}\mathbf{v}_i\mathbf{A}^T\mathbf{A}\mathbf{v}_j = \frac{1}{\sigma_i\sigma_i}\sigma_i^2\mathbf{v}_i^T\mathbf{v}_j$$

$$\mathbf{A}\mathbf{v}_i = \sigma_i \mathbf{u}_i \Rightarrow \mathbf{u}_i = \frac{1}{\sigma_i} \mathbf{A}\mathbf{v}_i$$

$$\mathbf{u}_{i}{}^{\mathsf{T}}\mathbf{u}_{j} = \frac{1}{\sigma_{i}}(\mathbf{A}\mathbf{v}_{i}){}^{\mathsf{T}}\frac{1}{\sigma_{j}}\mathbf{A}\mathbf{v}_{j} = \frac{1}{\sigma_{i}\sigma_{j}}\mathbf{v}_{i}\mathbf{A}^{\mathsf{T}}\mathbf{A}\mathbf{v}_{j} = \frac{1}{\sigma_{i}\sigma_{j}}\sigma_{j}^{2}\mathbf{v}_{i}^{\mathsf{T}}\mathbf{v}_{j} = \begin{cases} 1 & i = j \\ 0 & i \neq j \end{cases}$$

Descomposición de A en valores singulares (SVD)

$$\mathbf{A} = \underbrace{\begin{bmatrix} \mathbf{u}_1 & \mathbf{u}_2 & \dots & \mathbf{u}_r \end{bmatrix}}_{\text{base span de columnas}} \underbrace{\begin{bmatrix} \sigma_1 & 0 & \dots & 0 \\ 0 & \sigma_2 & \dots & \vdots \\ \vdots & 0 & \ddots \\ 0 & \dots & \sigma_r \end{bmatrix}}_{\text{valores singulares}} \begin{bmatrix} \mathbf{v}_1^T \\ \mathbf{v}_2^T \\ \vdots \\ \mathbf{v}_r^T \end{bmatrix} \right\}_{\text{base span de filas}}$$

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 $\mathbf{A} = \sigma_1 \mathbf{u}_1 \mathbf{v}_1^T + \sigma_2 \mathbf{u}_2 \mathbf{v}_2^T + \cdots + \sigma_r \mathbf{u}_r \mathbf{v}_r^T$

Descomposición de A en valores singulares (SVD)

$$\mathbf{A} = \begin{bmatrix} \mathbf{u}_1 & \mathbf{u}_2 & \dots & \mathbf{u}_r \\ \mathbf{u}_1 & \mathbf{u}_2 & \dots & \mathbf{u}_r \end{bmatrix} \begin{bmatrix} \sigma_1 & 0 & \dots & 0 \\ 0 & \sigma_2 & \dots & \vdots \\ \vdots & 0 & \ddots & \\ 0 & \dots & \sigma_r \end{bmatrix} \begin{bmatrix} \mathbf{v}_1^T \\ \mathbf{v}_2^T \\ \vdots \\ \mathbf{v}_r^T \end{bmatrix}$$
base span de filas valores singulares

 $\mathbf{A} = \sigma_1 \mathbf{u}_1 \mathbf{v}_1^T + \sigma_2 \mathbf{u}_2 \mathbf{v}_2^T + \dots + \sigma_r \mathbf{u}_r \mathbf{v}_r^T$

r matrices de rango 1

Teorema de Eckart-Young

$$\mathbf{A} = \sigma_1 \mathbf{u}_1 \mathbf{v}_1^T + \sigma_2 \mathbf{u}_2 \mathbf{v}_2^T + \dots + \sigma_k \mathbf{u}_k \mathbf{v}_k^T + \dots + \sigma_r \mathbf{u}_r \mathbf{v}_r^T$$

Teorema de Eckart-Young

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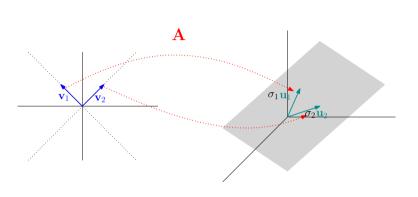
$$\mathbf{A}_k = \underbrace{\sigma_1 \mathbf{u}_1 \mathbf{v}_1^T + \sigma_2 \mathbf{u}_2 \mathbf{v}_2^T + \dots + \sigma_k \mathbf{u}_k \mathbf{v}_k^T}_{\text{rango } k}$$

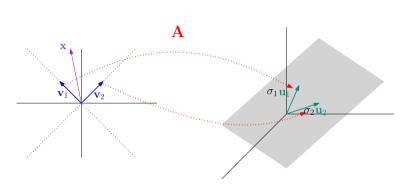
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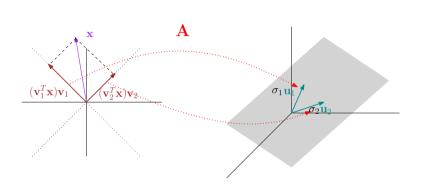
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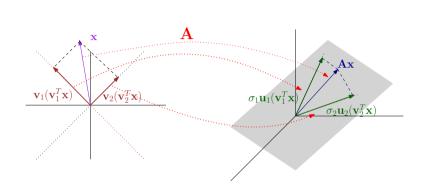
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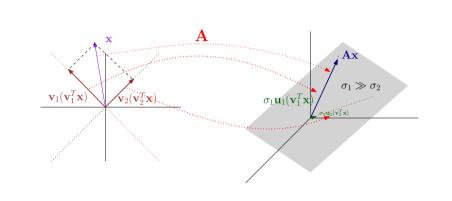
 \blacksquare A_k es la mejor aproximación de rango k de A











Resumen

■ SVD: Relación entre bases de espacio de filas y espacio de columnas.

Resumen

- SVD: Relación entre bases de espacio de filas y espacio de columnas.
- lacktriangle Magnitud valores singulares o Aproximar matriz original por una matriz de rango menor.