

Detecting File Fragmentation Point Using Sequential Hypothesis Testing

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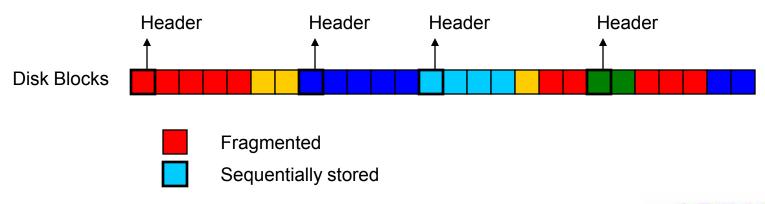
File Carving Using Sequential Hypothesis Testing

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- File Carving: recovery without file system meta-data.
 - □ Recovery based on file structure/content
 - □ Great for sequentially stored data
 - □ Problems with fragmented data









- Data Recovery
- File Systems
- Fragmentation Problem
- File Carvers
- Sequential Hypothesis Testing
- Experiments and Results





Data Recovery attempts to recover data from a digital device.





- Used in:
 - □ Disaster Recovery
 - □ Digital Forensics
 - □ E-Discovery









File Systems

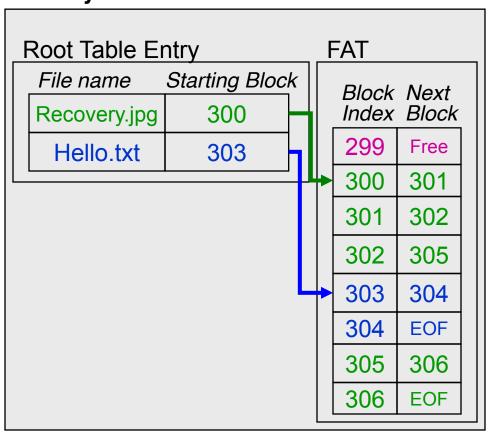
- Files are typically stored in file systems (FS)
 - Windows
 - FAT 12/16/32
 - NTFS
 - □ Mac
 - HFS
 - HFS+
- FS typically store data in clusters or blocks.



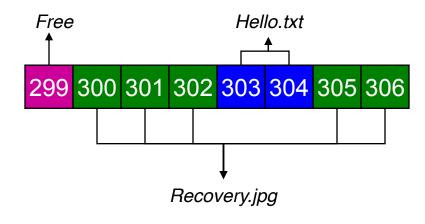
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File Allocation in FAT Example

File System Structures



Disk Data Block Area



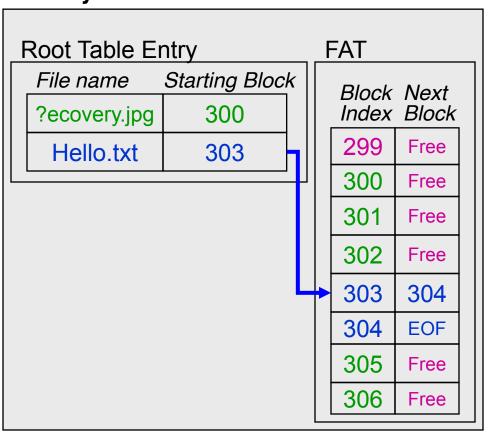




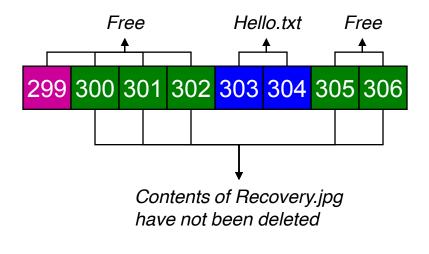
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File Deletion in FAT Example

File System Structures



Disk Data Block Area









Traditional Recovery

- Use File System Information to recover "deleted" files
 - Most File Systems do not actually delete the files.
 - Thank god, this keeps us in business and research!
 - □ Simply removes link to file in the file table.
 - Sets blocks to "free/available"
 - □ Recovery occurs by going to starting cluster of deleted file, checking that subsequent clusters are unallocated and then recovering.







File System Problems

- Reasons why a FS should not be trusted
 - Corruption
 - Missing File Information
 - Intentionally Modified
 - □ Unknown
- So how do we recover data without using FS information?
 - □ File Carving!





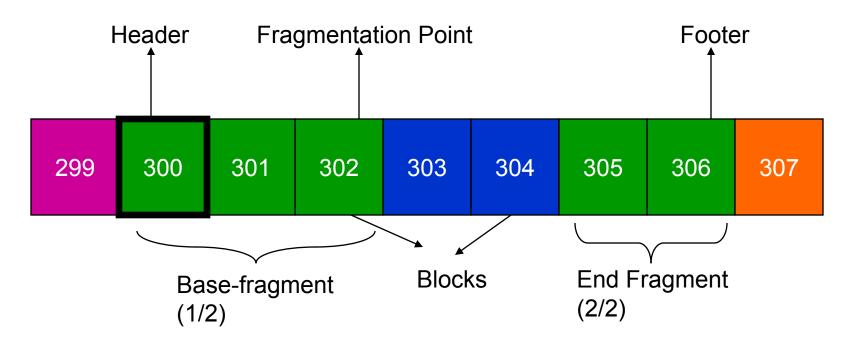
File Carving (cont'd)

- Traditional File Carving:
 - □ Recover From Known Header to Footer:
 - Jpeg: "FFD8" header and "FFD9" footer
 - □ Recover From Known Header based on Size:
 - 24-bit BMP: "BM" header followed by size
- Carving occurs sequentially from the header
- Most file carvers can not handle fragmented files





Fragmentation occurs when a file is not stored in sequential blocks.









How Important Is Fragmentation?

- From Simson Garfinkel's 350 disk corpus
 - □ Average fragmentation was 6%
 - Forensically important files had higher fragmentation rates:

Jpegs: 16%

PST: 58%

■ DOC: 17%

 Majority of fragments are bi-fragmented (two fragments) (40%)





Causes of Fragmentation

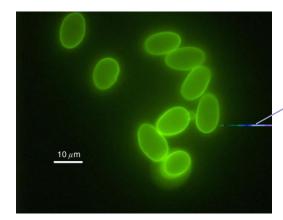
 Disk gets full after multiple additions and deletions

- Appending of data
- File System forces fragmentation
- Wear-Leveling in SSDs



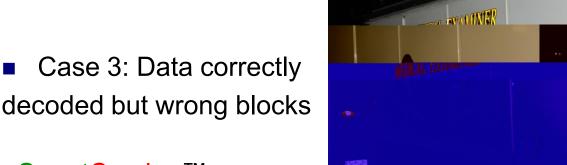
Traditional File Carving on Fragmented Data

Case 1: Data between two fragments



HTML data

 Case 2: Data incorrectly decoded and missing blocks









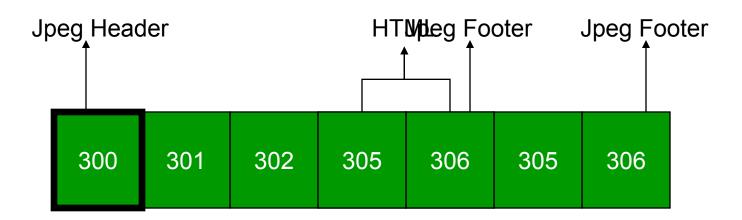
Carving Techniques For Fragmentation

- Simple Carving: Removing full files or known data like text between fragments.
- Graph Theoretic Carving: Reformulating the fragmentation problem as a graph optimization problem.
- Bi-fragmented Gap Carving: Trying all possibilities between a header and footer



Simple Carving

Identify and remove blocks that belong to another file and then carve.







Graph Theoretic Carvers

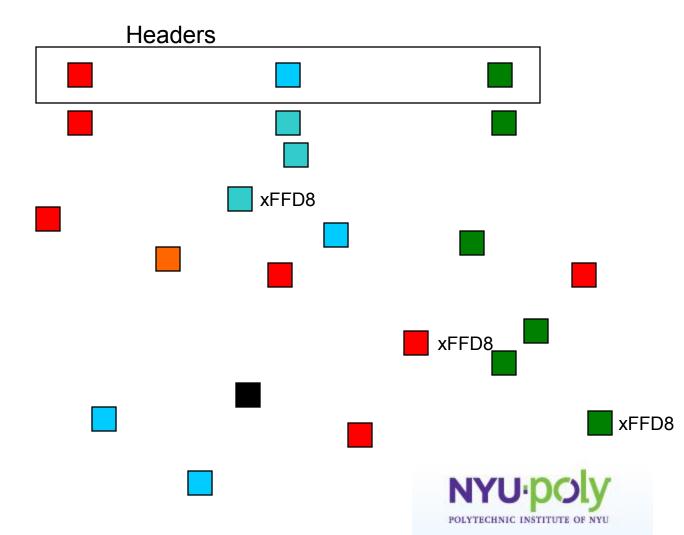
Assume blocks are completely randomized





Graph Theoretic Carvers

- Identify headers using keywords/ signatures
- Jpeg: xFFD8

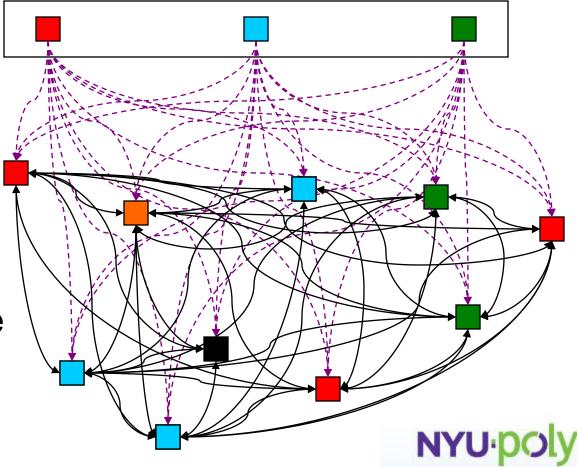






 Create a fully connected weighted graph (other than headers)

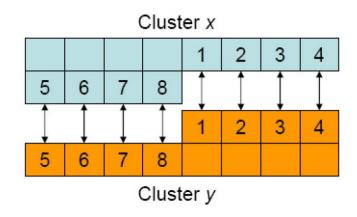
Each edge
has a value
defined as the
matching
metric.

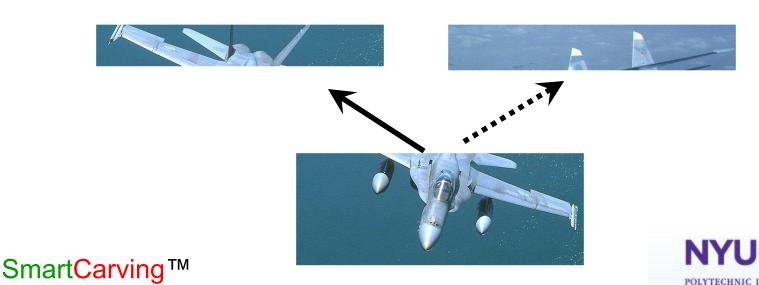




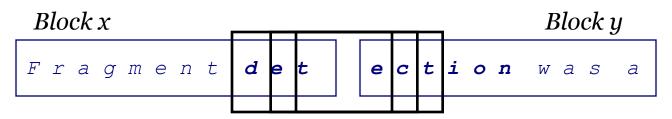
Matching Metric between blocks (Images)

For images we look at boundary formed by addition of new block





Matching metric between blocks (Text)

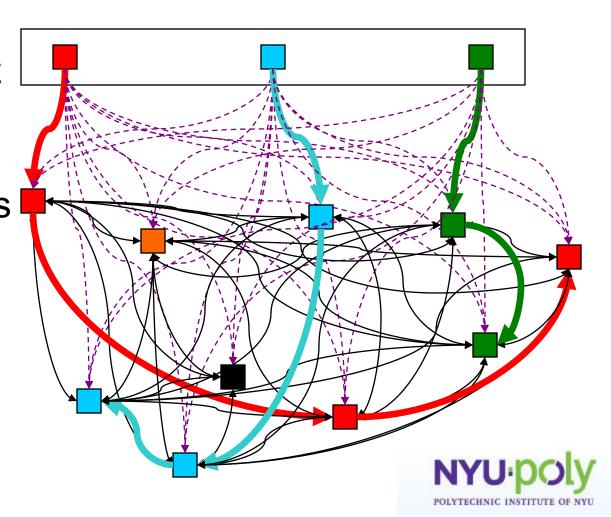


- Slide a window of size d from one fragment into the other
- At each position, use the window as context and calculate the score as the probability (p_i) of next symbol
- Matching Metric = $(p_0^* p_1^* ... p_d)$





Problem then becomes that of finding kdisjoint shortest paths based on the weight in a fully connected graph

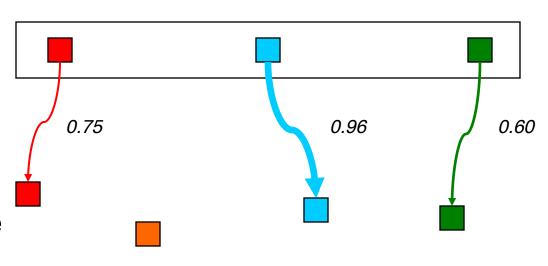




Parallel Unique Path

 For each header find best match (using matching metric)

Then choose the best of the best matches.



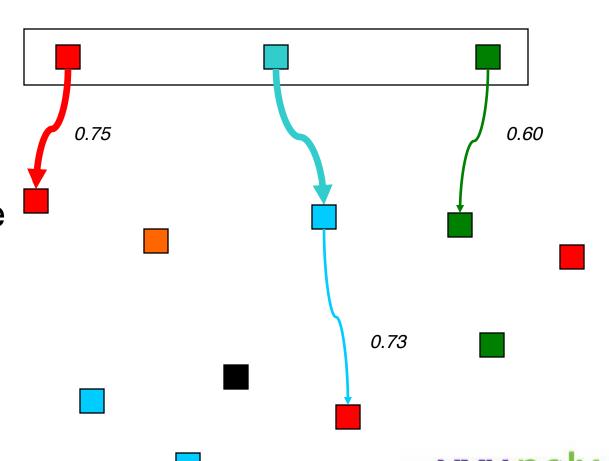




Parallel Unique Path

Find best
match for
recently
added node

Then choose the best of the best matches again.

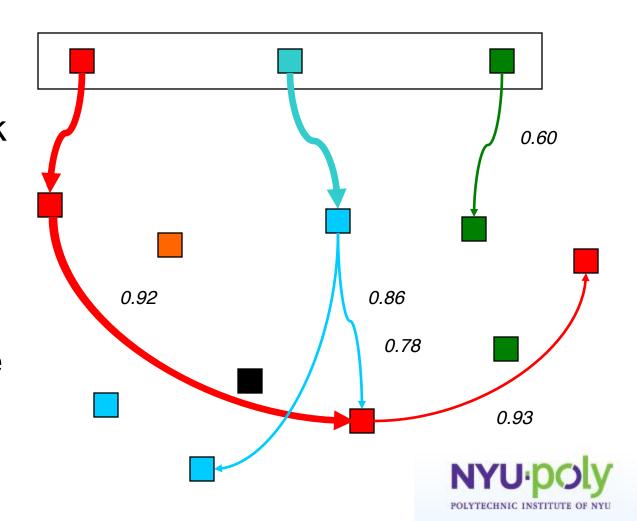








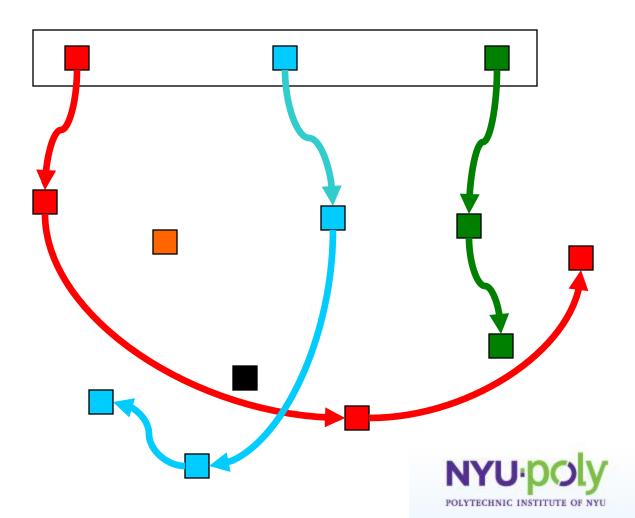
- Repeat process
- Now a block is the best match for two files
- Choose the better of the two and continue





Parallel Unique Path

Repeat until all files are built or no more nodes can be chosen.







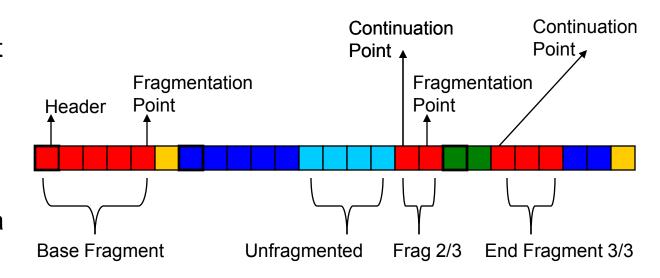
Problems with PUP

- Does not scale
 - □ n² weights are pre-generated
- Disk Geometry is not taken into account
 - ☐ Files normally do not have most of their blocks scattered randomly on the disk





- Garfinkel showed fragmentation normally does not result in a huge number of fragments.
- This means that a large number of sequential blocks belong together even in a fragmented file

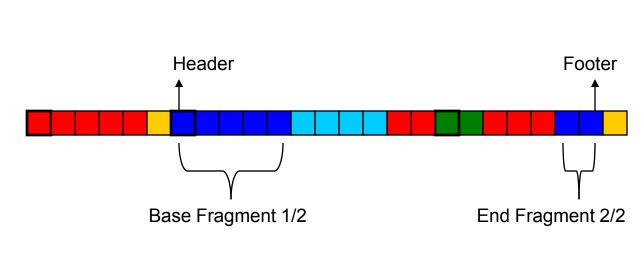






Bi-fragment Gap Carving (BGC)

- BGC can only be used for files that are fragmented into two fragments.
- Requires a validator/decoder to determine success.



Bi-fragmented (2 fragments)

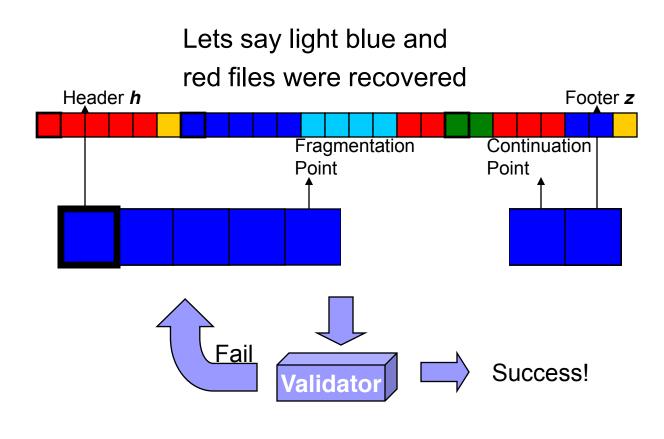




Bi-fragment Gap Carving Steps

Step 1: Identify Header (*h*) and footer (*z*)

Step 2: Brute Force all possible combinations by excluding blocks and validating (in essence trying all possible fragmentation and continuation points).









Bi-fragment Gap Carving Problems

- Won't work with > 2 fragments
- Worst case n²
 - □ n² whenever missing or corrupt blocks
- Validation does not always mean correct reassembly.





Importance of Disk Geometry

- BGC shows disk geometry is important to take into consideration.
 - Blocks are not scattered all over the disk typically and a large number of consecutive blocks will *probabalistically* belong together.
- So how do we use this information?
 - We propose a new technique called SmartCarving.



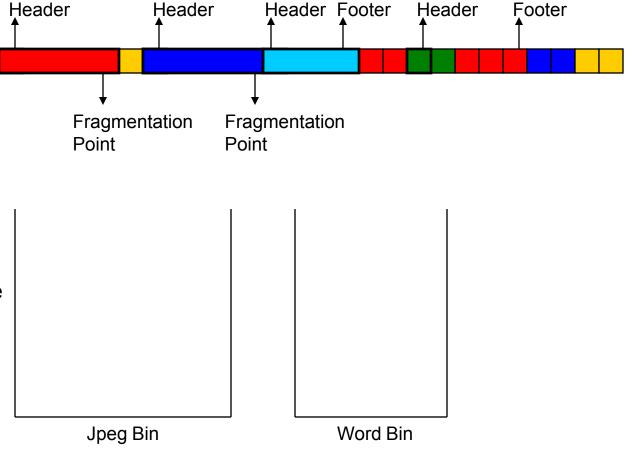


Step 1: Collation

a) Identify Headers, Footers

b) Merge Sequential Blocks and find Fragmentation Point

c) Identify Blocks including loose or unattached blocks

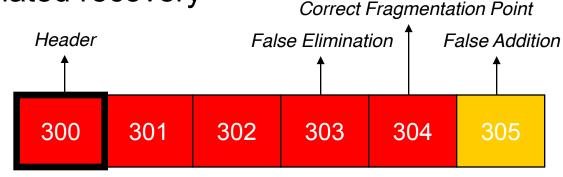






Reliable Fragmentation Point Detection

 Accurate fragmentation point detection is crucial for automated recovery



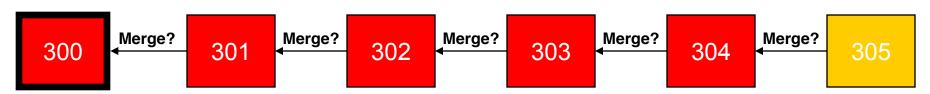
- Blocks have to be analyzed individually before being merged into a fragment.
- So how does one do this?
 - Sequential Hypothesis Testing!





Fragmentation Point Detection using Sequential Hypothesis Testing

Core Problem



- Generic Case
 - □ A fragment consisting of blocks b₁, b₂ ... b_{n-1}
 - □ Does the next block b_n belong to the same fragment?
- Formally we have two hypotheses
 - \square H₀: b_n belongs with blocks b₁, b₂... b_{n-1} in sequence
 - \square H₁: b_n does not belong with blocks b₁, b₂... b_{n-1} in sequence







- We define a decision statistic λ
 - \square We accept one of the hypotheses if λ is decisive.
 - □ Otherwise we don't make a decision and consider the next sequential block(s).
- SHT will adaptively decide the number of blocks before a decision can be made.
 - \square **Y** = Y₁, Y₂, ... Y_n where Y_i = Matching Metric(b₁ ... b_{i-1}, b_i)

Probability of blocks not belonging to fragment

$$\Lambda(\mathbf{Y}) = \frac{Pr(\mathbf{Y}|H_1)}{Pr(\mathbf{Y}|H_0)}.$$

Probability of blocks belonging to fragment



SHT (cont'd)

3 possible outcomes

outcome of test =
$$\begin{cases} H_1, & \Lambda(\mathbf{Y}) > \tau^+ \\ H_0, & \Lambda(\mathbf{Y}) < \tau_- \\ inconclusive, \tau^- < \Lambda(Y) < \tau^+ \end{cases}$$

■ When the matching metrics Y_i are independent

$$\Lambda(Y) \equiv \frac{Pr(\mathbf{Y}|H_1)}{Pr(\mathbf{Y}|H_0)} = \prod_{i=1}^n \frac{Pr(Y_i|H_1)}{Pr(Y_i|H_0)}.$$

$$\tau^{+} = \frac{1 - P_{fe}}{P_{fa}}; \text{ and}; \tau^{-} = \frac{P_{fe}}{1 - P_{fa}}.$$

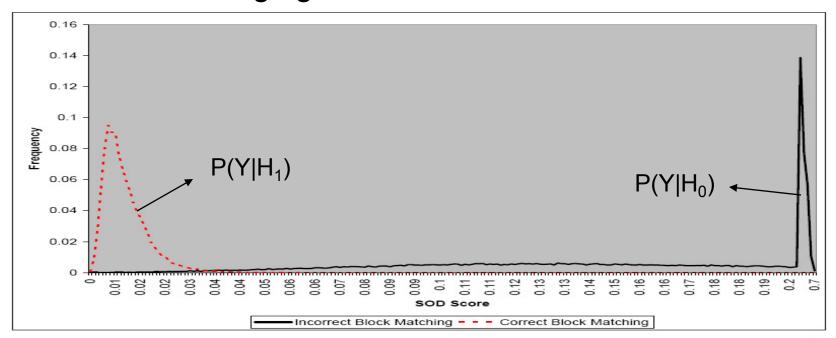
P_{fe} = Probability of false elimination

 P_{fa} = Probability of false addition.



Building Models for use with SHT

- Models built using a training set.
- Jpeg: clear distinction between the scores that result in "correct mergings" and those that are "incorrect"

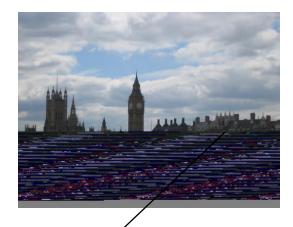






SHT Stopping Conditions

- Fragmentation Point Detection for a fragment stops when
 - H₀ is true (block decidedly does not belong to fragment)
 - □ End of File
 - □ End of Line



First Undecided

End of Line

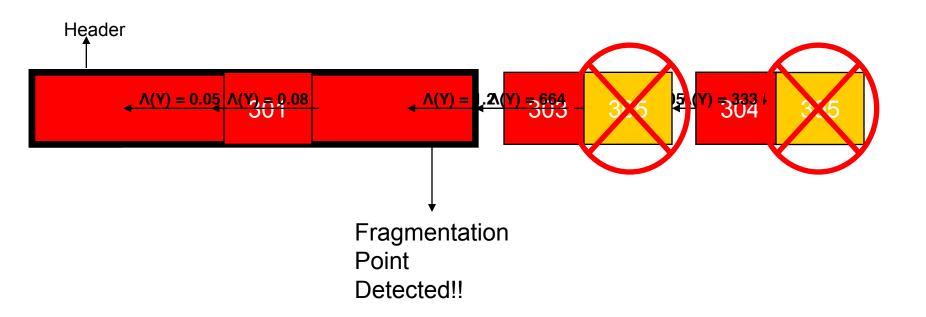




Fragmentation Point Detection Example

$$T^+ = 1000$$

 $T^- = 0.06$



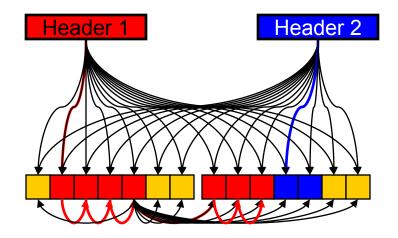




SmartCarving - Reassembly

Step 2: Reassembly

- a) Find Continuation Point from those in Bin
 - Check Within x number of blocks
 - ii) Prioritize based on geometry
- b) Find next fragmentation point or end of file
 - Using Sequential Hypothesis Testing
- c) If not end of file repeat (a) (b)



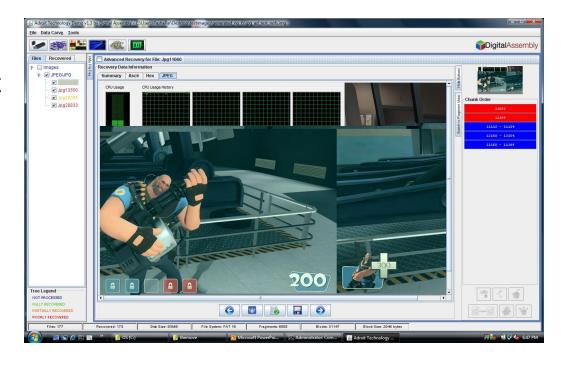
- d) We can do this in Parallel using PUP!!!
 - i) Find the best of the best continuation points and then do SHT on that
 - ii) Repeat process exactly as in PUP







- Step 3 Allow user to specify changes
 - Indicate blocks don't belong together
 - Manually merge blocks
 - Move blocks between bins
- Reiterate based on user input.







SmarCarving - User Interaction (II)







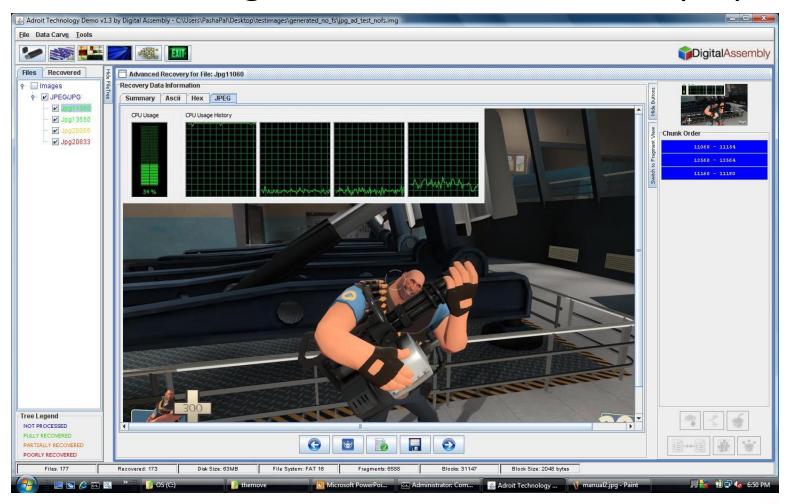
SmartCarving – User Interaction (III)







SmartCarving – User Interaction (IV)







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SmartCarving - Advantages

- Don't have to pre-compute all weights.
- Recovers multi-fragmented files
- Scales to millions of blocks
- Keys to success:
 - □ Finding continuation points
 - SHT to merge consecutive blocks and find fragmentation points



Experiments and Results

Disk Images	DFRWS06	DFRWS07	Real-1	Real-2	Gen-1
Fragmented Images	7	17	20	21	24
Bi-fragment Gap Carving					
Recovered Fragmented	7	1	-	-	_
Time Taken	9 sec	hours	-	-	1
SHT – PUP					
Recovered Fragmented	7	16*	18	16	20
Time Taken	13 sec	3.6 min	3.5 min	3.2 min	2.5

^{*}Some images were not fully recovered due to missing or corrupt blocks.







Future Work

- Currently conducting SHT experiments with Office and HTML
- Work needs to be done to score video, audio and other formats.
- Work needs to be done to optimize continuation point algorithms for different file types.
- SSDs and file carving, how difficult will the problem be?

