

Homework 1 - Math 4803

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1 Theoretical Problems

1. (Finding LSS)

Using row reduction, we can see that:

$$\left(\begin{array}{cc|c} 1 & 1 & 0 \\ 1 & 2 & 0 \\ 1 & 3 & 6 \end{array}\right) \xrightarrow[R_2=R_2-R_1]{R_3=R_3-R_1} \left(\begin{array}{cc|c} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 2 & 6 \end{array}\right)$$

Note here that $x_2 = 0$ from row 2 but $2x_2 = 6 \rightarrow x_2 = 3$ from row 3, making a perfect solution impossible. So, we will solve this system by solving the normal equation:

$$A^T b = A^T A x^* \rightarrow x^* = (A^T A)^{-1} A^T b$$

First, we compute $(A^T A)^{-1}$:

$$\begin{aligned} & \left(\begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \end{pmatrix} * \begin{pmatrix} 1 & 1 \\ 1 & 2 \\ 1 & 3 \end{pmatrix} \right)^{-1} \\ &= \left(\begin{pmatrix} 3 & 6 \\ 6 & 14 \end{pmatrix} \right)^{-1} \end{aligned}$$

Note that the determinant of this matrix is:

$$\det(A^T A) = 3(14) - 6(6) = 6$$

So, we find the inverse:

$$(A^T A)^{-1} = \frac{1}{6} \begin{pmatrix} 14 & -6 \\ -6 & 3 \end{pmatrix} = \begin{pmatrix} \frac{7}{3} & -1 \\ -1 & \frac{1}{2} \end{pmatrix}$$

Then, we multiply $A^T b$:

$$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \end{pmatrix} * \begin{pmatrix} 0 \\ 0 \\ 6 \end{pmatrix} = \begin{pmatrix} 6 \\ 18 \end{pmatrix}$$

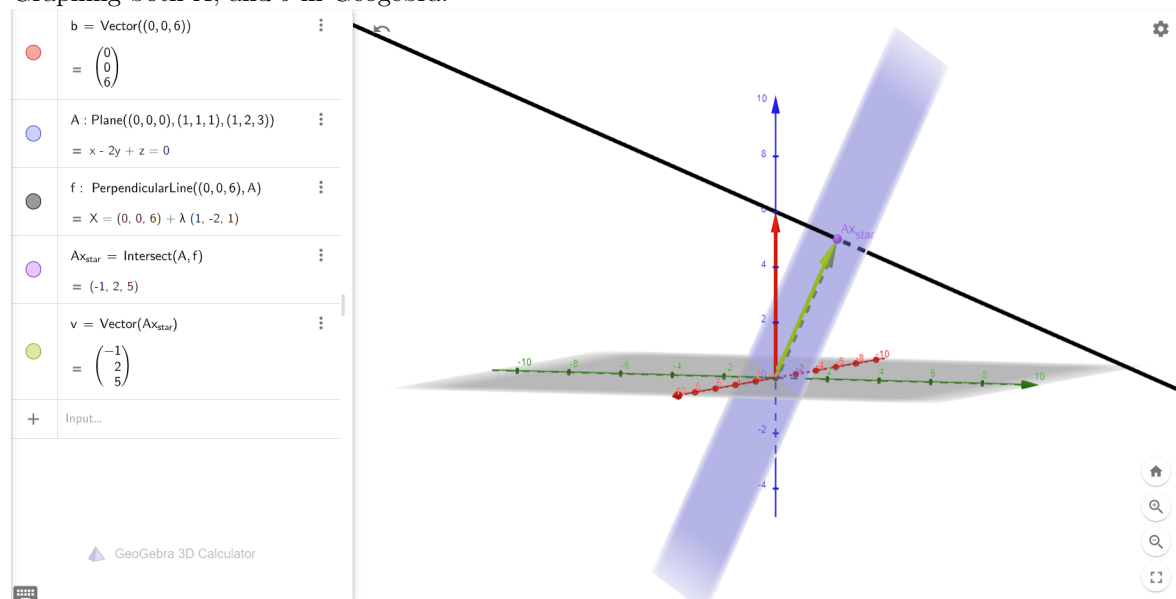
Then, we multiply $(A^T A)^{-1} A^T b$:

$$x^* = (A^T A)^{-1} A^T b = \begin{pmatrix} \frac{7}{3} & -1 \\ -1 & \frac{1}{2} \end{pmatrix} * \begin{pmatrix} 6 \\ 18 \end{pmatrix} = \begin{pmatrix} -4 \\ 3 \end{pmatrix}$$

Note that:

$$Ax^* = \begin{pmatrix} 1 & 1 \\ 1 & 2 \\ 1 & 3 \end{pmatrix} * \begin{pmatrix} -4 \\ 3 \end{pmatrix} = \begin{pmatrix} -1 \\ 2 \\ 5 \end{pmatrix}$$

Graphing both A , and b in Geogebra:



Here, A is the plane of the two columns going through the origin point. Note that the intersection point of the perpendicular line to b and the plane is $(-1, 2, 5)$, which is exactly Ax^* . Thus, Ax^* is the **orthogonal projection** of b onto the plane created by the columns of A going through the origin.

2. (Fitting function to $f(t) = c + p \sin(t) + q \cos(t)$)

a) We are given:

$$A_n \begin{bmatrix} c_n \\ p_n \\ q_n \end{bmatrix} = \vec{y}$$

For the the specific fitting outlined, we must structure A in the following way:

$$A_n = \begin{bmatrix} 1 & \sin(a_0) & \cos(a_0) \\ 1 & \sin(a_1) & \cos(a_1) \\ \vdots & \vdots & \vdots \\ 1 & \sin(a_n) & \cos(a_n) \end{bmatrix}$$

Then, to fit to the right set of points, we structure y the following way:

$$\vec{y} = \begin{bmatrix} g(a_0) \\ g(a_1) \\ \vdots \\ g(a_n) \end{bmatrix}$$

b) Let us compute $A_n^T A_n$:

$$\begin{aligned} A_n^T A_n &= \begin{bmatrix} 1 & 1 & \dots & 1 \\ \sin(a_0) & \sin(a_1) & \dots & \sin(a_n) \\ \cos(a_0) & \cos(a_1) & \dots & \cos(a_n) \end{bmatrix} * \begin{bmatrix} 1 & \sin(a_0) & \cos(a_0) \\ 1 & \sin(a_1) & \cos(a_1) \\ \vdots & \vdots & \vdots \\ 1 & \sin(a_n) & \cos(a_n) \end{bmatrix} \\ &= \begin{bmatrix} n & \sum_{i=0}^n \sin(a_i) & \sum_{i=0}^n \cos(a_i) \\ \sum_{i=0}^n \sin(a_i) & \sum_{i=0}^n \sin^2(a_i) & \sum_{i=0}^n \sin(a_i) \cos(a_i) \\ \sum_{i=0}^n \cos(a_i) & \sum_{i=0}^n \sin(a_i) \cos(a_i) & \sum_{i=0}^n \cos^2(a_i) \end{bmatrix} \end{aligned}$$

Then, we multiply by a factor of $\frac{2\pi}{n}$:

$$\frac{2\pi}{n} A_n^T A_n = \begin{bmatrix} 2\pi & \frac{2\pi}{n} \sum_{i=0}^n \sin(a_i) & \frac{2\pi}{n} \sum_{i=0}^n \cos(a_i) \\ \frac{2\pi}{n} \sum_{i=0}^n \sin(a_i) & \frac{2\pi}{n} \sum_{i=0}^n \sin^2(a_i) & \frac{2\pi}{n} \sum_{i=0}^n \sin(a_i) \cos(a_i) \\ \frac{2\pi}{n} \sum_{i=0}^n \cos(a_i) & \frac{2\pi}{n} \sum_{i=0}^n \sin(a_i) \cos(a_i) & \frac{2\pi}{n} \sum_{i=0}^n \cos^2(a_i) \end{bmatrix}$$

To take the limit of each of these terms, we note that $\lim 2\pi = 2\pi$ so we don't have to worry about that. Taking the rest of these as Riemann integrals, we calculate each individually:

$$\begin{aligned} \int_0^{2\pi} \sin(a) da &= -\cos(a) \Big|_0^{2\pi} = 1 - 1 = 0 \\ \int_0^{2\pi} \cos(a) da &= \sin(a) \Big|_0^{2\pi} = 0 - 0 = 0 \end{aligned}$$

For the next integral, we will use integration by parts and the trigonometric identity that $\sin^2(a) + \cos^2(a) = 1$:

$$\begin{aligned}
\int_0^{2\pi} \sin^2(a) da &= -\sin(a) \cos(a) \Big|_0^{2\pi} + \int_0^{2\pi} \cos^2(a) da \\
&\rightarrow \int_0^{2\pi} \sin^2(a) da = 0 + \int_0^{2\pi} (1 - \sin^2(a)) da \\
&\rightarrow \int_0^{2\pi} \sin^2(a) da = \int_0^{2\pi} 1 da - \int_0^{2\pi} \sin^2(a) da \\
&\rightarrow 2 \int_0^{2\pi} \sin^2(a) da = 2\pi \\
&\rightarrow \int_0^{2\pi} \sin^2(a) da = \pi
\end{aligned}$$

Using the trigonometric identity again:

$$\begin{aligned}
\int_0^{2\pi} \cos^2(a) da &= \int_0^{2\pi} (1 - \sin^2(a)) da = \int_0^{2\pi} 1 da - \int_0^{2\pi} \sin^2(a) \\
&= 2\pi - \pi \\
&= \pi
\end{aligned}$$

For the final integral, we use u-substitution, where $u = \sin(a)$:

$$\int_0^{2\pi} \sin(a) \cos(a) da = \int_0^0 u du = 0$$

As a result:

$$\lim_{n \rightarrow \infty} \frac{2\pi}{n} A_n^T A_n = \begin{bmatrix} 2\pi & 0 & 0 \\ 0 & \pi & 0 \\ 0 & 0 & \pi \end{bmatrix}$$

Next, we calculate $A_n^T \vec{y}$:

$$\begin{bmatrix} 1 & 1 & \dots & 1 \\ \sin(a_0) & \sin(a_1) & \dots & \sin(a_n) \\ \cos(a_0) & \cos(a_1) & \dots & \cos(a_n) \end{bmatrix} * \begin{bmatrix} g(a_0) \\ g(a_1) \\ \vdots \\ g(a_n) \end{bmatrix} = \begin{bmatrix} \sum_{i=0}^n g(a_i) \\ \sum_{i=0}^n \sin(a_i) g(a_i) \\ \sum_{i=0}^n \cos(a_i) g(a_i) \end{bmatrix}$$

Then, multiplying by $\frac{2\pi}{n}$ to put it in the correct form and taking the limit to infinity, effectively creating a Riemann integral, we get:

$$\lim_{n \rightarrow \infty} \frac{2\pi}{n} A_n^T \vec{y} = \begin{bmatrix} \int_0^{2\pi} g(a) da \\ \int_0^{2\pi} \sin(a) g(a) da \\ \int_0^{2\pi} \cos(a) g(a) da \end{bmatrix}$$

c) If we multiply both sides of the original linear system by $\frac{2\pi}{n}A_n^T$ and take the limit as $n \rightarrow \infty$, we get the new system:

$$\begin{bmatrix} 2\pi & 0 & 0 \\ 0 & \pi & 0 \\ 0 & 0 & \pi \end{bmatrix} * \begin{bmatrix} c_\infty \\ p_\infty \\ q_\infty \end{bmatrix} = \begin{bmatrix} \int_0^{2\pi} g(a)da \\ \int_0^{2\pi} \sin(a)g(a)da \\ \int_0^{2\pi} \cos(a)g(a)da \end{bmatrix}$$

A simple matrix multiplication and 1 step of algebra gets us our coefficients:

$$\begin{bmatrix} c_\infty \\ p_\infty \\ q_\infty \end{bmatrix} = \begin{bmatrix} \frac{1}{2\pi} \int_0^{2\pi} g(a)da \\ \frac{1}{\pi} \int_0^{2\pi} \sin(a)g(a)da \\ \frac{1}{\pi} \int_0^{2\pi} \cos(a)g(a)da \end{bmatrix}$$

d) No, it is not necessarily true that all functions will be fit perfectly to $g(t)$ by $f_\infty(t)$. Some functions are not periodic, and therefore cannot be fit with periodic components and a constant term ($g(t) = t$ is an example). However, if the function was periodic, than you could find a perfect $f_\infty(t) = g(t)$ fit, because you have oscillating periodic components.

3. Section 2.4 Exercise 7

a) The test point is $X_1 = X_2 = X_3 = 0$. Now, we must compute the ℓ_2 norm of the difference to find euclidean distance. We calculate, in order of listed observation:

$$\begin{aligned} \left| \begin{pmatrix} 0 \\ 3 \\ 0 \end{pmatrix} - \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \right|_2 &= \sqrt{(0-0)^2 + (3-0)^2 + (0-0)^2} = 3 \\ \left| \begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix} - \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \right|_2 &= \sqrt{(2-0)^2 + (0-0)^2 + (0-0)^2} = 2 \\ \left| \begin{pmatrix} 0 \\ 1 \\ 3 \end{pmatrix} - \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \right|_2 &= \sqrt{(0-0)^2 + (1-0)^2 + (3-0)^2} = \sqrt{10} \\ \left| \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix} - \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \right|_2 &= \sqrt{(0-0)^2 + (1-0)^2 + (2-0)^2} = \sqrt{5} \\ \left| \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} - \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \right|_2 &= \sqrt{(-1-0)^2 + (0-0)^2 + (1-0)^2} = \sqrt{2} \\ \left| \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} - \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \right|_2 &= \sqrt{(1-0)^2 + (1-0)^2 + (1-0)^2} = \sqrt{3} \end{aligned}$$

b) The K-nearest neighbors classifier formula is as follows:

$$\mathbb{P}(y = j | X = x_0) = \frac{1}{K} \sum_{i \in N_0} 1_j(Y_i = j)$$

Here, N_0 is the set of K -nearest neighbors, and 1_j is the indicator function. When $K = 1$, we are only dealing with the nearest neighbor. As indicated by the Euclidean distances, the nearest neighbor to $X_1 = X_2 = X_3 = 0$ is observation 5. Note that $Y_5 = \text{green}$. Let us call our test point y_t . So:

$$\mathbb{P}(y_t = \text{green} | X_1 = X_2 = X_3 = 0) = 1$$

Thus, our prediction is that the test point is **green**, as this is higher than 0.5, which was the defined decision boundary.

c) Since $K = 3$, we must now find the 3 closest neighbors to y_t . By euclidean distance, these are Observation 5, Observation 6, and Observation 2. Observation 5, as previously stated, was observed green, but Observations 2 and 6 were observed red. Therefore:

$$\mathbb{P}(y_t = \text{red} | X_0 = X_1 = X_2 = 0) = \frac{2}{3} > 0.5$$

Thus, our prediction is that the test point is **red**.

d) For an extremely non-linear set, we would expect the best value of K , or

the one closest to the bayes classifier, to be **small**. This is because, due to the non-linearity, we need a flexible decision boundary, which is achievable with smaller K values.

4. Section 3.7 Exercise 3

a) **iv** is correct. Note that the equation is:

$$\widehat{salary}_i = 50 + 20GPA_i + .07IQ_i + 35Level_i + .01(GPA_i * IQ_i) - 10(GPA_i * Level_i)$$

To find the marginal effect of *Level* on the salary, we take the derivative with respect to level to get:

$$\frac{d\widehat{salary}_i}{d(Level_i)} = 35 - 10(GPA_i)$$

Note that, for $GPA > 3.5$, this marginal effect is positive, meaning that, for college students with high enough GPA, graduating college (so having a *Level* = 1) actually increases their starting salary; so, iv is true.

b) Thus is a specific observation where $IQ_i = 110$, $GPA_i = 4.0$, $Level_i = 1$. So:

$$\begin{aligned}\widehat{salary}_i &= 50 + 20GPA_i + .07IQ_i + 35Level_i + .01(GPA_i * IQ_i) - 10(GPA_i * Level_i) \\ &= 50 + 20(4.0) + .07(110) + 35(1) + .01(4.0 * 110) - 10(4.0 * 1) \\ &= 137.1\end{aligned}$$

The predicted starting salary is \$137,100.

c) **False.** GPA and IQ, when multiplied together, will likely produce very large values. So, even though the coefficient is small, the impact in any given observation may still be significant. In addition, we don't know the standard error of the coefficient, so we cannot comment on its statistical significance.

5. Section 3.7 Exercise 4

- a) The **RSS for the cubic regression would likely be lower than the RSS for the linear regression for the training dataset**. This is because the cubic regression takes more observation information into account and thus can fit to the training data set more accurately. In the worst possible case, where a squared term or a cubic term have no bearing on the training data, their coefficients can be lowered to near zero to have a smaller effect, which would effectively approximate an almost-linear regression. Thus, the RSS for cubic regression would be at or lower the RSS for linear regression.
- b) Since the true relationship is linear, the **RSS for the linear regression would likely be lower than the RSS for the cubic regression for the testing dataset**. Since the model is first trained on the training dataset, the cubic regression, with its extra and irrelevant terms, is likely overfit to the training dataset. Therefore, it will be less accurate as it is less generalizable, and thus have a higher RSS than the linear regression, that is more indicative of the actual data.
- c) Once again, the **RSS for the cubic regression would likely be lower than the RSS for linear regression in the training dataset**. Despite the relationship between X and Y changing from part a), what has not changed is the fact that the features in the linear regression are just a subset of the features in the cubic regression. Thus, the cubic regression would have more features that and thus be more flexible, making the residual sum of squares at least as good, if not lower.
- d) **We do not have enough information to tell which RSS would be smaller**. Because the non-linearity between X and Y is not specified, we cannot conclude which model, cubic or linear, is more generalizable to this relationship. For this reason, we cannot make an educated guess on this question.

6. Section 3.7 Exercise 5

Proof. We can substitute the formula for $\hat{\beta}$ into the formula and algebraically manipulating:

$$\begin{aligned}
 \hat{y}_i &= x_i \hat{\beta} \\
 &= x_i * \frac{\sum_{i=1}^n x_i y_i}{\sum_{i'=1}^n x_{i'}^2} \\
 &= y_1 \left(\frac{x_1 x_i}{\sum_{i'=1}^n x_{i'}^2} \right) + y_2 \left(\frac{x_2 x_i}{\sum_{i'=1}^n x_{i'}^2} \right) + \dots + y_n \left(\frac{x_n x_i}{\sum_{i'=1}^n x_{i'}^2} \right) \\
 &= a_1 y_1 + a_2 y_2 + \dots + a_n y_n \\
 &= \sum_{i'=1}^n a_{i'} y_{i'}
 \end{aligned}$$

Here:

$$a_{i'} = \frac{x_{i'} x_i}{\sum_{i'=1}^n x_{i'}^2}$$

□

7. Section 3.7 Exercise 6

Proof. The simple linear regression model is as follows:

$$y_i = \beta_0 + \beta_1 x_i$$

Given a sample, equation 3.4 in the textbook gives us the estimators for the coefficients that minimize the residual sum of squares:

$$\hat{\beta}_1 = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sum_{i=1}^n (x_i - \bar{x})^2}$$
$$\hat{\beta}_0 = \bar{y} - \hat{\beta}_1 \bar{x}$$

Note that, if we plug in \bar{x} for our explanatory variable, using these estimators for β_0 and β_1 gives us:

$$\begin{aligned} y_i &= \hat{\beta}_0 + \hat{\beta}_1 \bar{x} \\ &= \bar{y} - \hat{\beta}_1 \bar{x} + \hat{\beta}_1 \bar{x} \\ &= \bar{y} \end{aligned}$$

So, the least squares line indeed passes through (\bar{x}, \bar{y}) . □

2 Programming Problems

Programming Problem 1

1) Done in HW1_coding.py

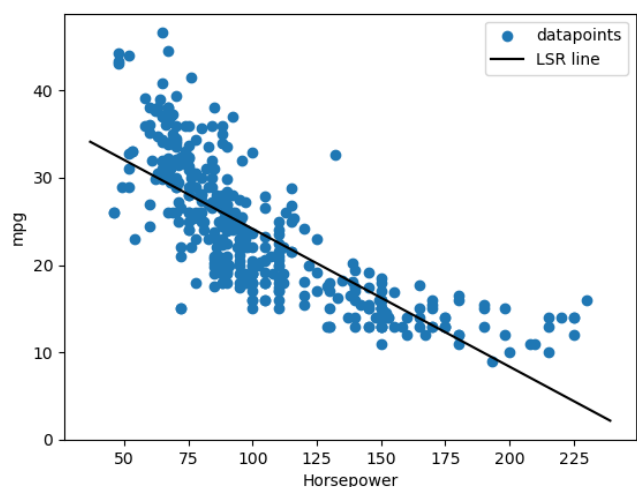
2) After running the regression (and removing the rows of data with unknown horsepower) we obtain the following regression:

```
=====
Dep. Variable:          mpg      R-squared:          0.606
Model:                  OLS      Adj. R-squared:       0.605
Method:                 Least Squares      F-statistic:    599.7
Date:                  Wed, 25 Jan 2023      Prob (F-statistic): 7.03e-81
Time:                  13:54:46      Log-Likelihood:   -1178.7
No. Observations:      392      AIC:                2361.
Df Residuals:          390      BIC:                2369.
Df Model:              1
Covariance Type:       nonrobust
=====
              coef      std err          t      P>|t|      [0.025      0.975]
-----
Intercept      39.9359      0.717      55.660      0.000      38.525      41.347
horsepower     -0.1578      0.006     -24.489      0.000      -0.171      -0.145
=====
Omnibus:                 16.432      Durbin-Watson:          0.920
Prob(Omnibus):            0.000      Jarque-Bera (JB):        17.305
Skew:                     0.492      Prob(JB):                0.000175
Kurtosis:                 3.299      Cond. No.                322.
=====

Notes:
[1] Standard Errors assume that the covariance matrix of the errors is correctly specified.
Sum of squared Residuals: 9385.915871932419
```

So, $\widehat{mpg} = 39.9359 - .1578(horsepower)$.

3) After creating the graph, the plot looked as follows:



4) The regression line **does not seem to fit the data well** because the relationship looks non-linear (likely exponential decay), and the RSS is high, as $RSS = 9385.916$.

Programming Problem 2

1) The correlation is as follows:

	mpg	cylinders	displacement	horsepower	weight	acceleration	year	origin
mpg	1.000000	-0.777618	-0.805127	-0.778427	-0.832244	0.423329	0.580541	0.565209
cylinders	-0.777618	1.000000	0.950823	0.842983	0.897527	-0.504683	-0.345647	-0.568932
displacement	-0.805127	0.950823	1.000000	0.897257	0.932994	-0.543800	-0.369855	-0.614535
horsepower	-0.778427	0.842983	0.897257	1.000000	0.864538	-0.689196	-0.416361	-0.455171
weight	-0.832244	0.897527	0.932994	0.864538	1.000000	-0.416839	-0.309120	-0.585005
acceleration	0.423329	-0.504683	-0.543800	-0.689196	-0.416839	1.000000	0.290316	0.212746
year	0.580541	-0.345647	-0.369855	-0.416361	-0.309120	0.290316	1.000000	0.181528
origin	0.565209	-0.568932	-0.614535	-0.455171	-0.585005	0.212746	0.181528	1.000000

The variables that appear highly correlated (having an absolute value of correlation above .8) are:

- mpg and displacement; mpg and weight
- cylinders and displacement, cylinders and horsepower, cylinders and weight
- displacement and weight
- horsepower and weight

2) After running the regression, we get:

OLS Regression Results						
=====						
Dep. Variable:	mpg	R-squared:	0.821			
Model:	OLS	Adj. R-squared:	0.818			
Method:	Least Squares	F-statistic:	252.4			
Date:	Thu, 26 Jan 2023	Prob (F-statistic):	2.04e-139			
Time:	16:56:48	Log-Likelihood:	-1023.5			
No. Observations:	392	AIC:	2063.			
Df Residuals:	384	BIC:	2095.			
Df Model:	7					
Covariance Type:	nonrobust					
=====						
	coef	std err	t	P> t	[0.025	0.975

Intercept	-17.2184	4.644	-3.707	0.000	-26.350	-8.08
cylinders	-0.4934	0.323	-1.526	0.128	-1.129	0.14
displacement	0.0199	0.008	2.647	0.008	0.005	0.03
horsepower	-0.0170	0.014	-1.230	0.220	-0.044	0.01
weight	-0.0065	0.001	-9.929	0.000	-0.008	-0.00
acceleration	0.0806	0.099	0.815	0.415	-0.114	0.27
year	0.7508	0.051	14.729	0.000	0.651	0.85
origin	1.4261	0.278	5.127	0.000	0.879	1.97
=====						
Omnibus:	31.906	Durbin-Watson:	1.309			
Prob(Omnibus):	0.000	Jarque-Bera (JB):	53.100			
Skew:	0.529	Prob(JB):	2.95e-12			
Kurtosis:	4.460	Cond. No.	8.59e+04			

The residual sum of squares is:

Sum of squared Residuals: 4252.212530440175

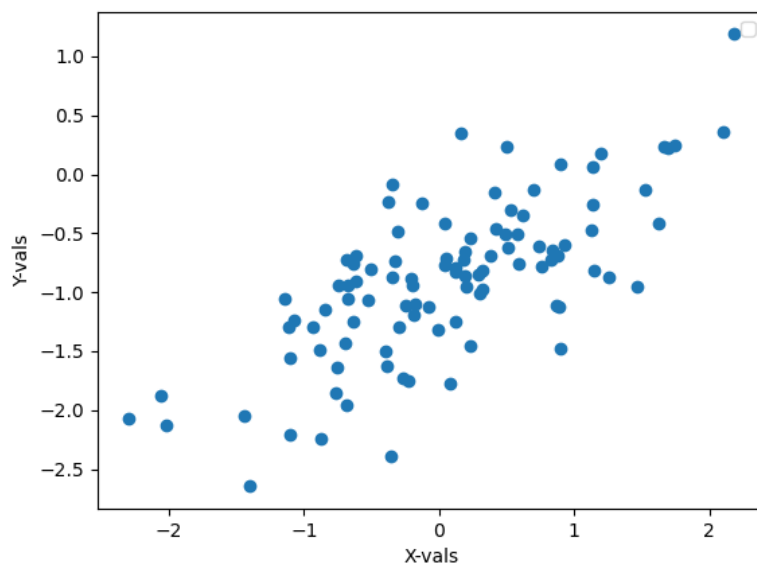
3) The multiple regression seems better, as it has a lower SSR and higher R-squared. However, the high correlation between predictor variables may leave some coefficients biased. This leads me to deduce that the simple linear regression is actually better.

Programming Problem 3

- a) Done in HW1_coding.py
- b) Done in HW1_coding.py
- c) The resultant Y vector had a length of 100; here $\beta_0 = -1$ and $\beta_1 = .5$. Here was the Y vector generated:

```
Y: [-0.4113916 -0.69362435 -1.06234006 -1.23969505 -1.11475211 -2.06607813
 0.24268411 -1.85745375 -0.9735897 -1.10837791 -0.95550469 -1.87249066
-0.73812828 -1.62178515 -0.25784229 -2.20608734 -1.10556186 -2.24681539
-0.41818427 -0.50414212 -1.56261807 -0.81521895 0.08767333 0.23479804
-1.47856296 -0.72378191 -0.24761974 -1.29887887 -1.73357806 -0.30314961
-1.43629053 -1.50033708 -1.95861542 -1.14733407 -0.93921963 -1.31809766
-1.29836701 -1.45496285 0.2308316 -0.60569427 -1.18920266 -1.49468742
-0.93913607 0.22143312 -0.70986346 -1.24964722 -0.86563169 0.3593177
-0.82367324 -0.35012274 -1.00497323 -2.39354381 -1.0518468 -0.08118154
-0.88376489 -0.75676602 -0.64873067 -0.59397605 -0.84850163 -1.11843878
-1.6357462 -0.87207934 -0.61913551 -1.29736699 -0.50813526 -1.12513744
0.05898229 -0.13332464 1.18813757 -2.64642863 -2.04551525 -0.80148949
0.34418139 -0.68623293 -0.82034803 -2.12425773 -0.48737345 -0.72966661
-0.54491771 -0.77889521 -1.74744345 -0.94360517 -0.6551269 -0.14836124
-0.95607365 -1.24917671 -1.05395059 -0.69084956 -0.79875683 -0.4718144
0.17962822 -0.72267543 -0.23531312 -0.76383685 -0.45872792 -1.77504914
-0.8707672 -0.76806047 -0.90452459 -0.12876294]
```

- d) The following scatterplot was generated:



There does appear a strong correlation and a linear one at that.

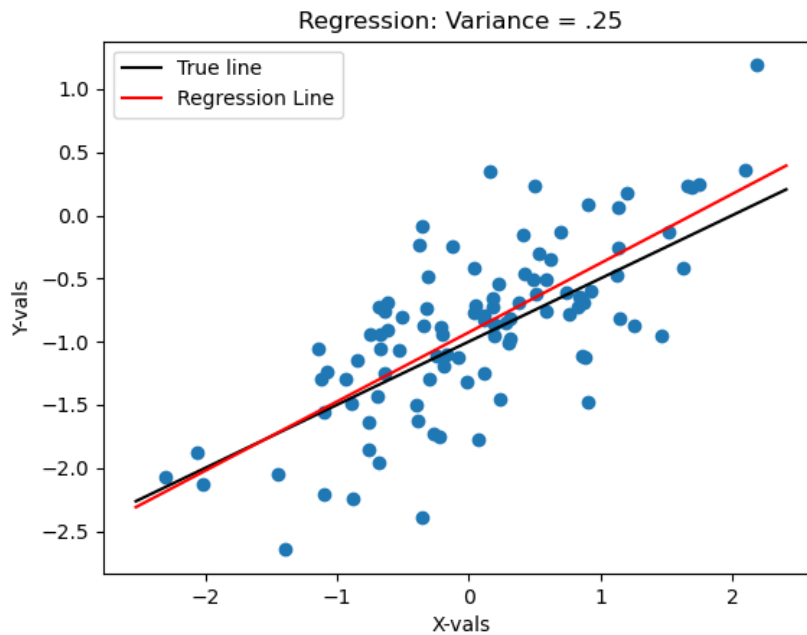
- e) The regression produced the following:

OLS Regression Results						
=====						
Dep. Variable:	y	R-squared:	0.522			
Model:	OLS	Adj. R-squared:	0.517			
Method:	Least Squares	F-statistic:	107.0			
Date:	Thu, 26 Jan 2023	Prob (F-statistic):	2.20e-17			
Time:	19:02:11	Log-Likelihood:	-65.124			
No. Observations:	100	AIC:	134.2			
Df Residuals:	98	BIC:	139.5			
Df Model:	1					
Covariance Type:	nonrobust					
=====						
	coef	std err	t	P> t	[0.025	0.975]

Intercept	-0.9265	0.047	-19.717	0.000	-1.020	-0.833
xvars	0.5477	0.053	10.342	0.000	0.443	0.653
=====						
Omnibus:	0.898	Durbin-Watson:	2.157			
Prob(Omnibus):	0.638	Jarque-Bera (JB):	0.561			
Skew:	-0.172	Prob(JB):	0.755			
Kurtosis:	3.127	Cond. No.	1.15			
=====						

Here $\widehat{\beta}_0 = -0.9265$ and $\widehat{\beta}_1 = 0.5477$. They are fairly close to the true parameters in the model.

f) The population regression and least squares regression are shown here:



Here, the "true line" represents population regression, and the "regression line" represents the least squares regression.

g) After running the regression with x^2 , we get:

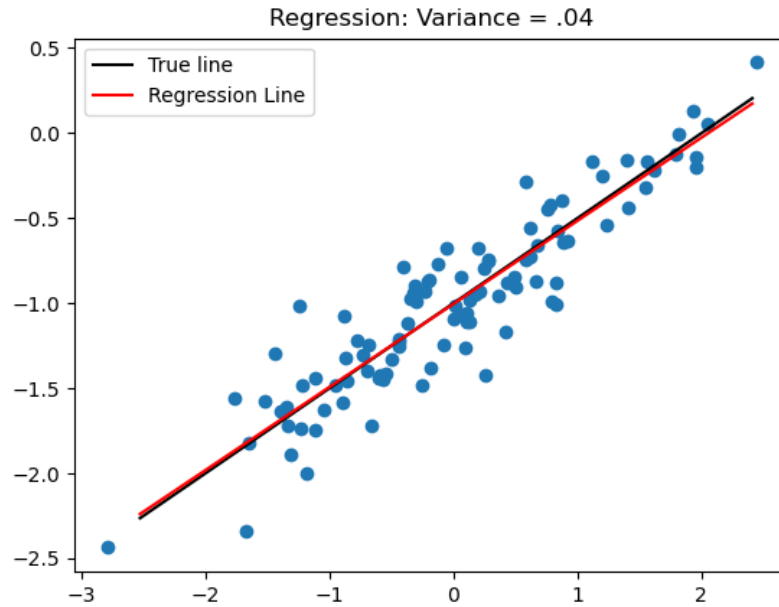
OLS Regression Results						
=====						
Dep. Variable:	y	R-squared:	0.522			
Model:	OLS	Adj. R-squared:	0.512			
Method:	Least Squares	F-statistic:	52.96			
Date:	Thu, 26 Jan 2023	Prob (F-statistic):	2.83e-16			
Time:	22:25:03	Log-Likelihood:	-65.107			
No. Observations:	100	AIC:	136.2			
Df Residuals:	97	BIC:	144.0			
Df Model:	2					
Covariance Type:	nonrobust					
=====						
	coef	std err	t	P> t	[0.025	0.975]

Intercept	-0.9325	0.058	-16.158	0.000	-1.047	-0.818
xvars	0.5468	0.053	10.229	0.000	0.441	0.653
xvarssq	0.0077	0.043	0.181	0.856	-0.077	0.092
=====						
Omnibus:	0.893	Durbin-Watson:	2.152			
Prob(Omnibus):	0.640	Jarque-Bera (JB):	0.552			
Skew:	-0.170	Prob(JB):	0.759			
Kurtosis:	3.132	Cond. No.	2.10			
=====						

Note that there is very little statistical significance to the x^2 term, and the R^2 term does not change at all. This points to no improvement in fit with the inclusion of the x^2 term.

h) Here was the result with the standard deviation reduced to .2:

OLS Regression Results						
Dep. Variable:	y	R-squared:	0.842			
Model:	OLS	Adj. R-squared:	0.841			
Method:	Least Squares	F-statistic:	523.3			
Date:	Thu, 26 Jan 2023	Prob (F-statistic):	4.35e-41			
Time:	22:39:15	Log-Likelihood:	12.946			
No. Observations:	100	AIC:	-21.89			
Df Residuals:	98	BIC:	-16.68			
Df Model:	1					
Covariance Type:	nonrobust					
	coef	std err	t	P> t	[0.025	0.975]
Intercept	-1.0040	0.021	-46.749	0.000	-1.047	-0.961
xvars	0.4888	0.021	22.876	0.000	0.446	0.531
Omnibus:	0.426	Durbin-Watson:	1.977			
Prob(Omnibus):	0.808	Jarque-Bera (JB):	0.121			
Skew:	-0.045	Prob(JB):	0.941			
Kurtosis:	3.145	Cond. No.	1.01			



Note that $\widehat{\beta}_0 = -1.004$ and $\widehat{\beta}_1 = .4888$, which are much closer estimates to the true parameters, and the regression line is almost exactly overlapping the true line. This makes sense, as our deviation from said line was lowered.

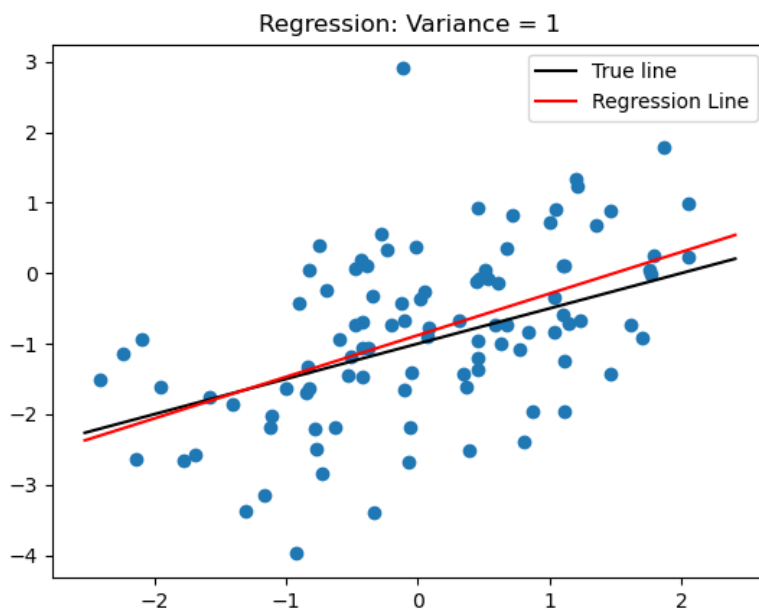
i) With the standard deviation (and variance) increased to 1, we run the same regression with newly generated points:

OLS Regression Results

Dep. Variable:	y	R-squared:	0.257
Model:	OLS	Adj. R-squared:	0.250
Method:	Least Squares	F-statistic:	33.96
Date:	Thu, 26 Jan 2023	Prob (F-statistic):	7.19e-08
Time:	22:54:49	Log-Likelihood:	-145.66
No. Observations:	100	AIC:	295.3
Df Residuals:	98	BIC:	300.5
Df Model:	1		
Covariance Type:	nonrobust		

	coef	std err	t	P> t	[0.025	0.975]
Intercept	-0.8802	0.105	-8.375	0.000	-1.089	-0.672
xvars	0.5903	0.101	5.828	0.000	0.389	0.791

Omnibus:	3.633	Durbin-Watson:	1.972
Prob(Omnibus):	0.163	Jarque-Bera (JB):	3.566
Skew:	0.192	Prob(JB):	0.168
Kurtosis:	3.842	Cond. No.	1.07



Note that $\widehat{\beta}_0 = -0.8802$ and $\widehat{\beta}_1 = .5903$, which are further estimates to the true parameters than in the original $\sigma_\epsilon^2 = .25$ case as well as the reduced $\sigma_\epsilon^2 = .04$ case. This makes sense, as the points vary further away due to the increase in variance of error.