

<https://iopscience.iop.org/article/10.1088/1361-6382/ad2194>

<https://dcc.ligo.org/P2500368>

Building GSpyNetTree

A signal-vs-glitch classifier for gravitational-wave event candidates

ICERM SciML for GW astronomy @ Brown - Day 5

Sofía Álvarez-López, Mervyn Chan, Franz Herbst, Dhatri Raghunathan, Airene Ahuja, Annudesh Liyanage, Julian Ding, Raymond Ng, Jess McIver.

Gravitational-waves are really cool, and we can do a lot of great science with them!

- But we need to make sure our detector data is clean to get the most science out of gravitational-waves.
- **Glitches** (short duration non-Gaussian noise) are problematic:

Modeling and Reduction of High Frequency Scatter Noise at LIGO Livingston.

Subtracting glitches from gravitational-wave detector data during the third observing run

D Davis¹, T B Littenberg², I M Romero-Shaw^{3,4,5}, M Millhouse⁶, J McIver⁷, F Di Renzo^{8,9}, G Ashton¹⁰

Siddharth Soni¹, Jane Glanzer², Anamaria Effler³, Valera Frolov³, Gabriela González², Arnaud Pele⁴, Robert Schofield⁵

LIGO Detector Characterization in the Second and Third Observing Runs

D Davis¹, J S Areeda², B K Berger³, R Bruntz⁴, A Effler⁵, R C Essick⁶, R P Fisher⁴, P Godwin⁷, E Goetz^{8,9,10},

Simulating Transient Noise Bursts in LIGO with Generative Adversarial Networks

Melissa Lopez,^{1, 2}, ^a Vincent Boudart,³ Kerwin Buijsman,^{4, 5}, ^b Amit Reza,^{1, 2} and Sarah Caudill^{1, 2}

B. Berger, “Identification and mitigation of advanced LIGO noise sources”, Journal of Physics: Conference Series 957, 012004 (2018).

D. Davis et al., “LIGO Detector Characterization in the Second and Third Observing Runs”, Classical and Quantum Gravity 38, arXiv:2101.11673 [astro-ph, physics:gr-qc], 135014 (2021).

B. P. Abbott et al., “Effects of data quality vetoes on a search for compact binary coalescences in Advanced LIGO’s first observing run”, Classical and Quantum Gravity 35, 065010, 065010 (2018).

J. Powell, “Parameter estimation and model selection of gravitational wave signals contaminated by transient detector noise glitches”, Classical and Quantum Gravity 35, 155017 (2018).

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- But we need to make sure our detector data is clean to get the most science out of gravitational-waves.
- **Glitches** (short duration non-Gaussian noise) are problematic:

Generate false-positive candidates.

Corrupt data.

Bias astrophysical parameter estimation.

B. Berger, “Identification and mitigation of advanced LIGO noise sources”, Journal of Physics: Conference Series 957, 012004 (2018).

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Gravitational-waves are really cool, and we can do a lot of great science with them!

- But we need to make sure our detector data is clean to get the most science out of gravitational-waves.
- **Glitches** (short duration non-Gaussian noise) pollute our data.

How do we tell apart a glitch from a gravitational-wave in a timely (and hopefully automated) fashion?

GSpyNetTree is a **signal-vs-glitch** classifier
for gravitational-wave event candidates.

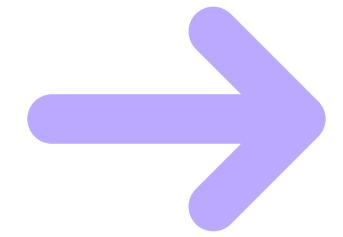
Running as a LIGO-Virgo-KAGRA event validation tool since ER15 (right before O4 started)!

Where do we need a signal-vs-glitch classifier?



A new GW candidate
is detected

Where do we need a signal-vs-glitch classifier?



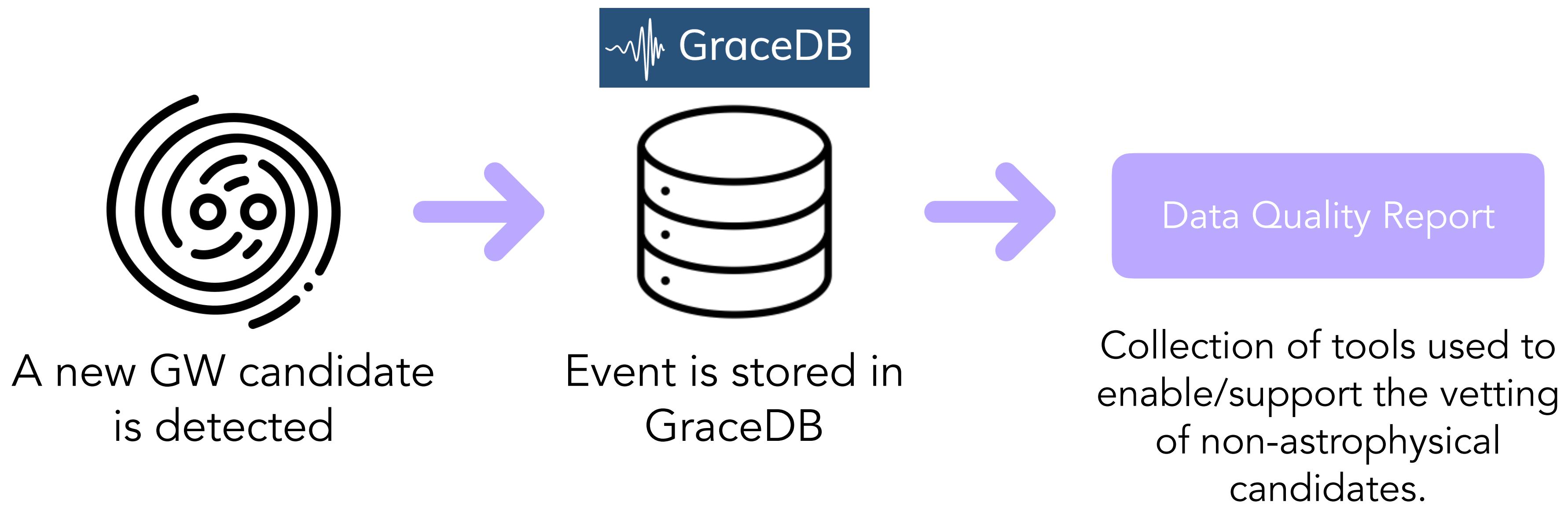
GraceDB



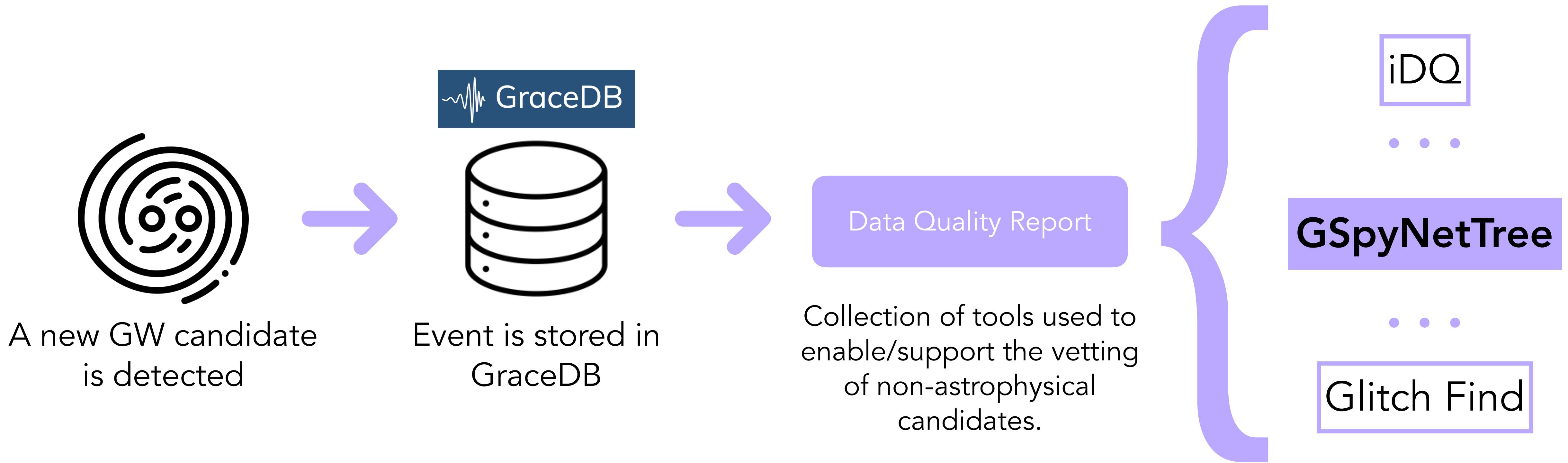
A new GW candidate
is detected

Event is stored in
GraceDB

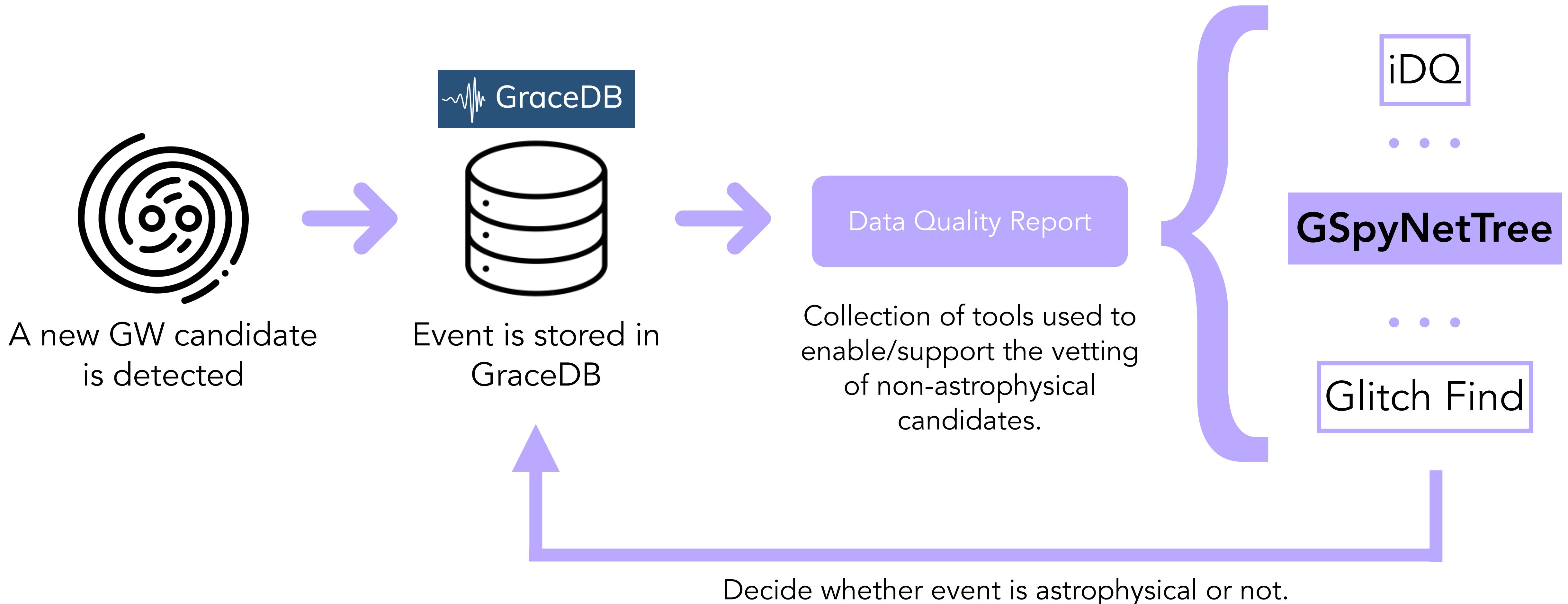
Where do we need a signal-vs-glitch classifier?



Where do we need a signal-vs-glitch classifier?

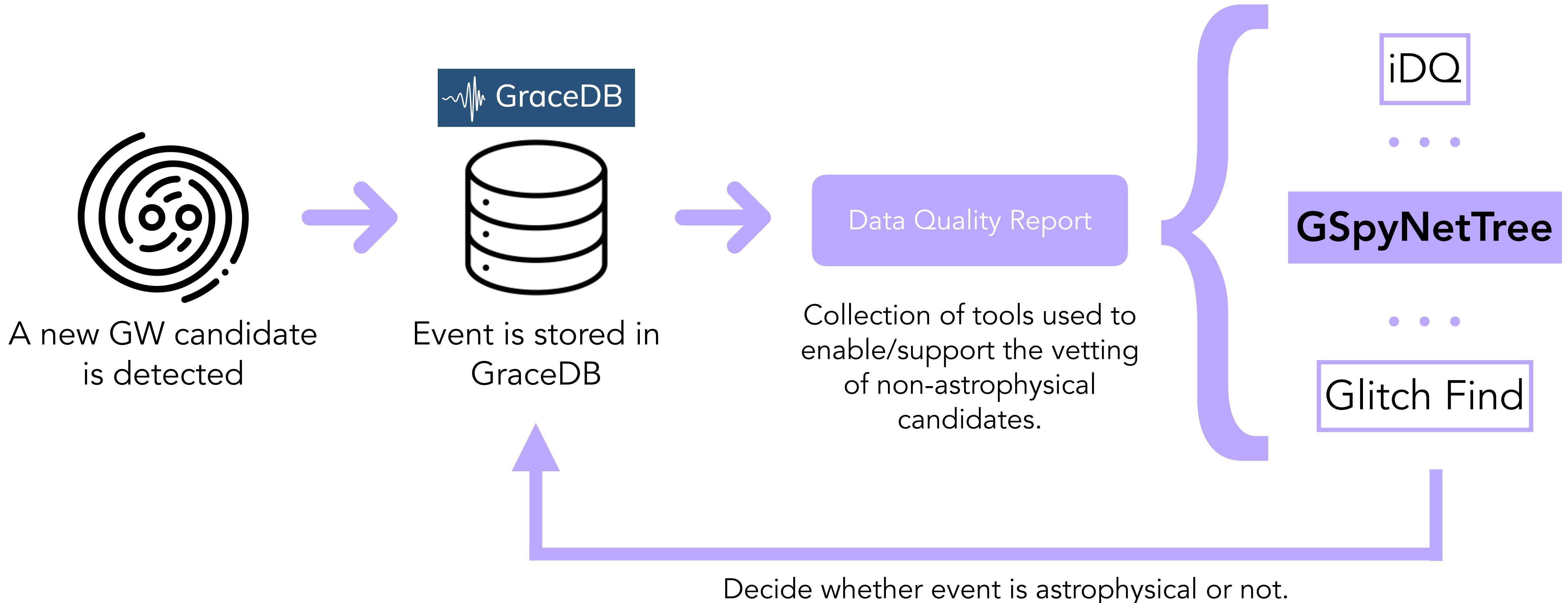


Where do we need a signal-vs-glitch classifier?



Where do we need a signal-vs-glitch classifier?

In our initial pipeline! To tell whether candidate event is (or not) a glitch.



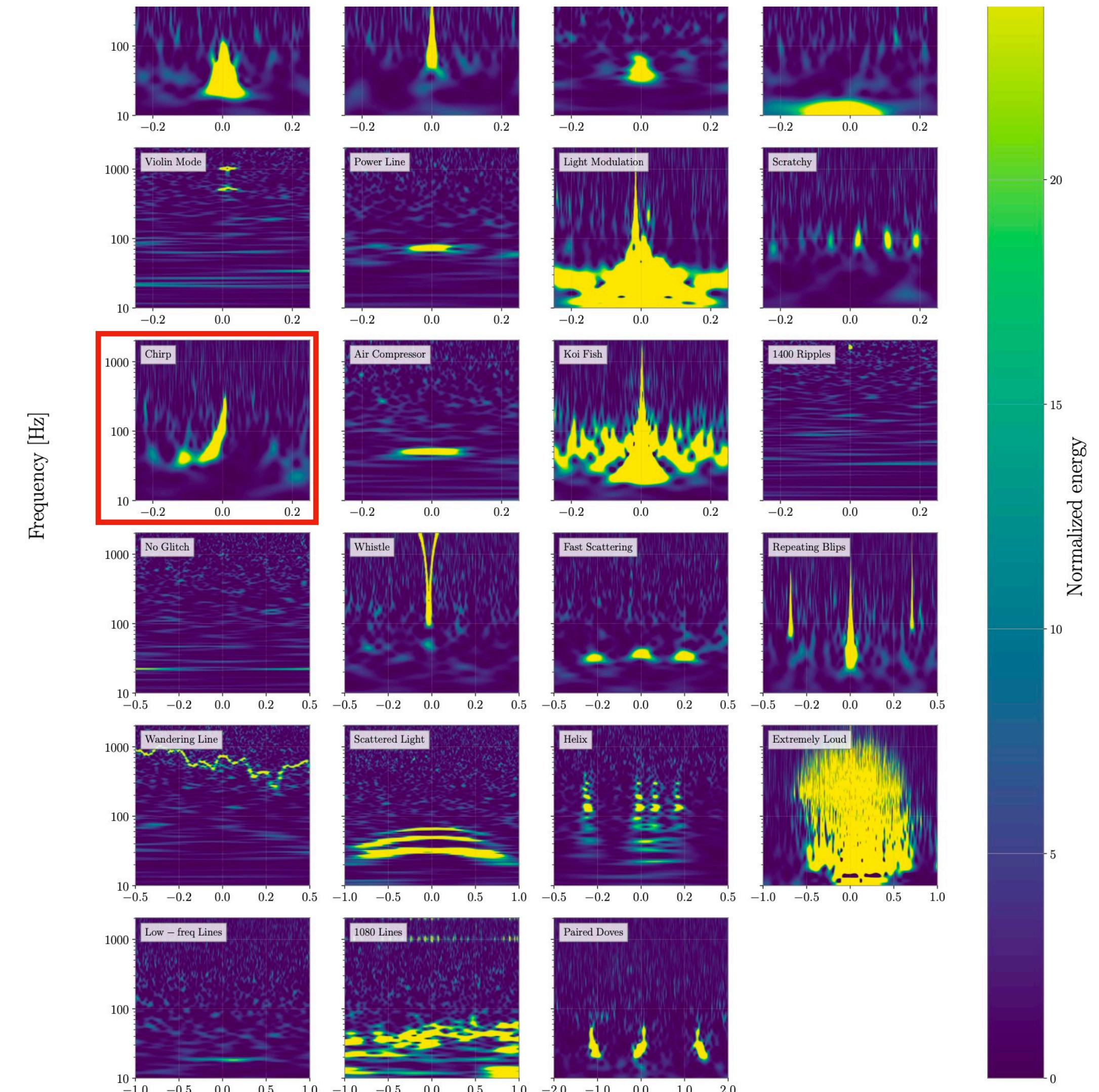
What considerations should we take into account to build a signal-vs-glitch classifier?

1 . Glitches come in various time-frequency morphologies.

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We saw this in **Gravity Spy!**

A MULTI-CLASS Convolutional Neural Network
(CNN) image classifier

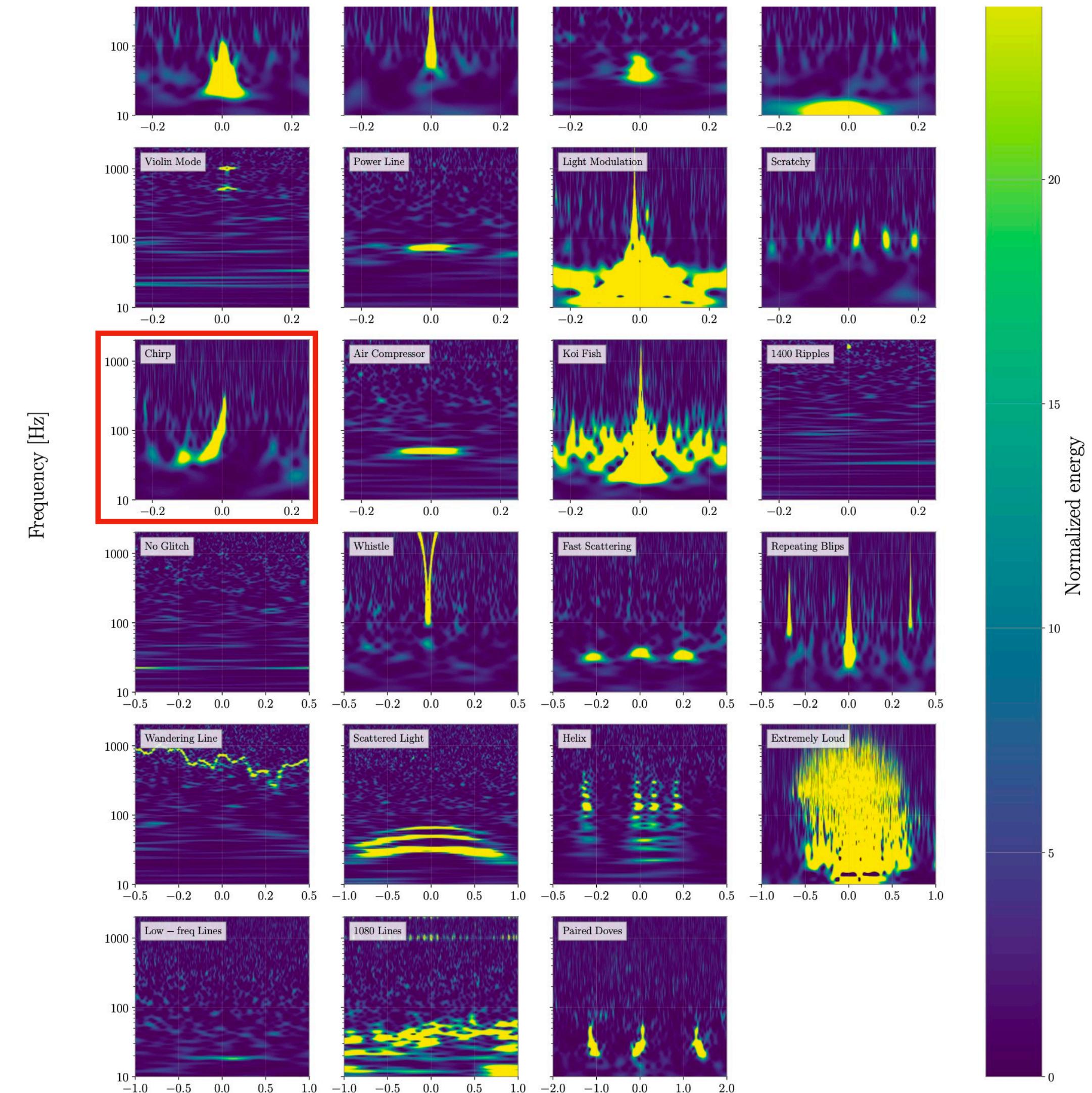


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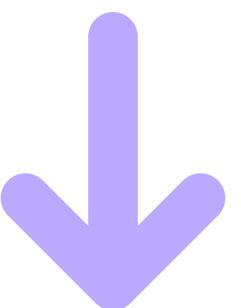
We saw this in **Gravity Spy!**

A MULTI-CLASS Convolutional Neural Network
(CNN) image classifier

- CNNs: Machine Learning architecture used for image classification tasks.
- MULTI-CLASS: Distinguishes 20 different glitch classes and 1 Chirp class (red box) via spectrograms.
- Successful glitch classification in previous observing runs.

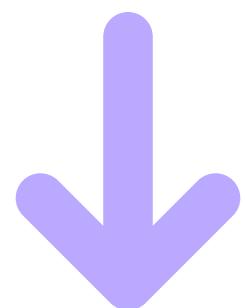


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They are particularly challenging when they mimic the form of GW events.

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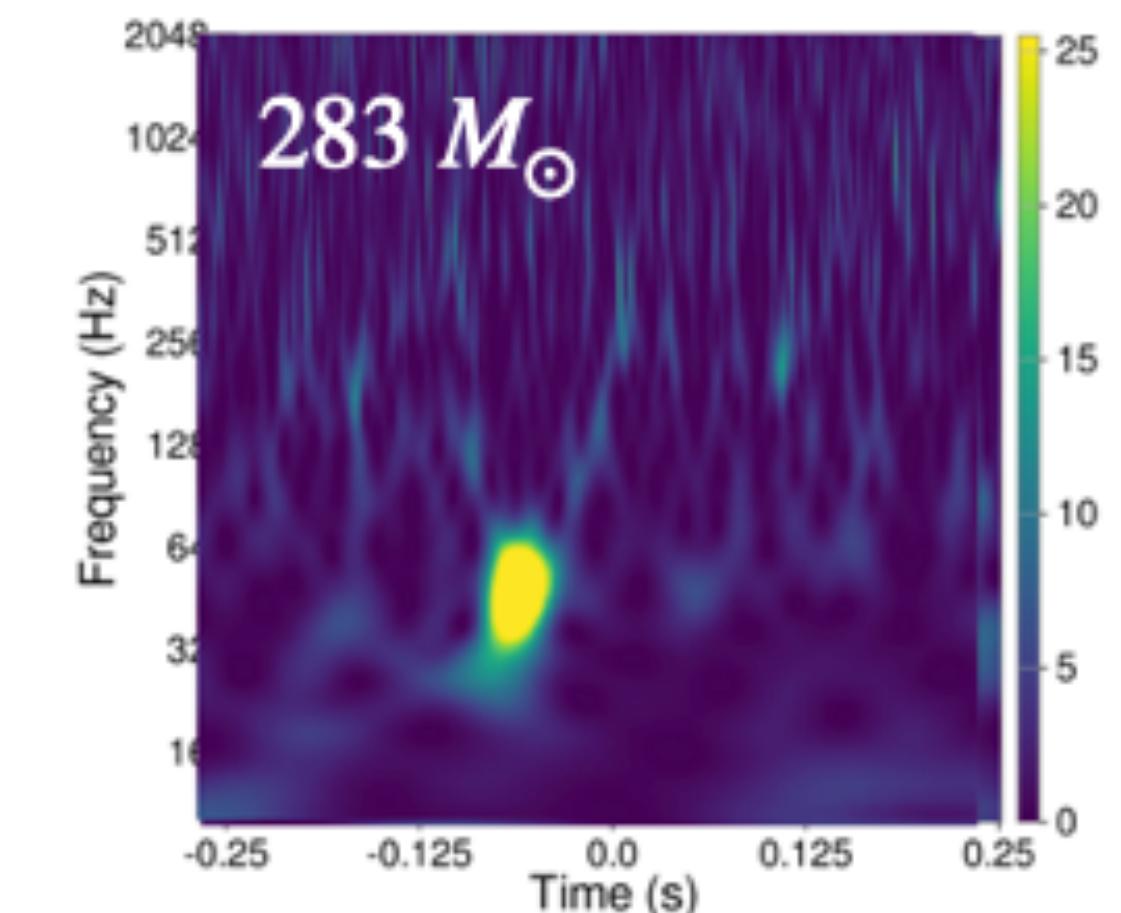
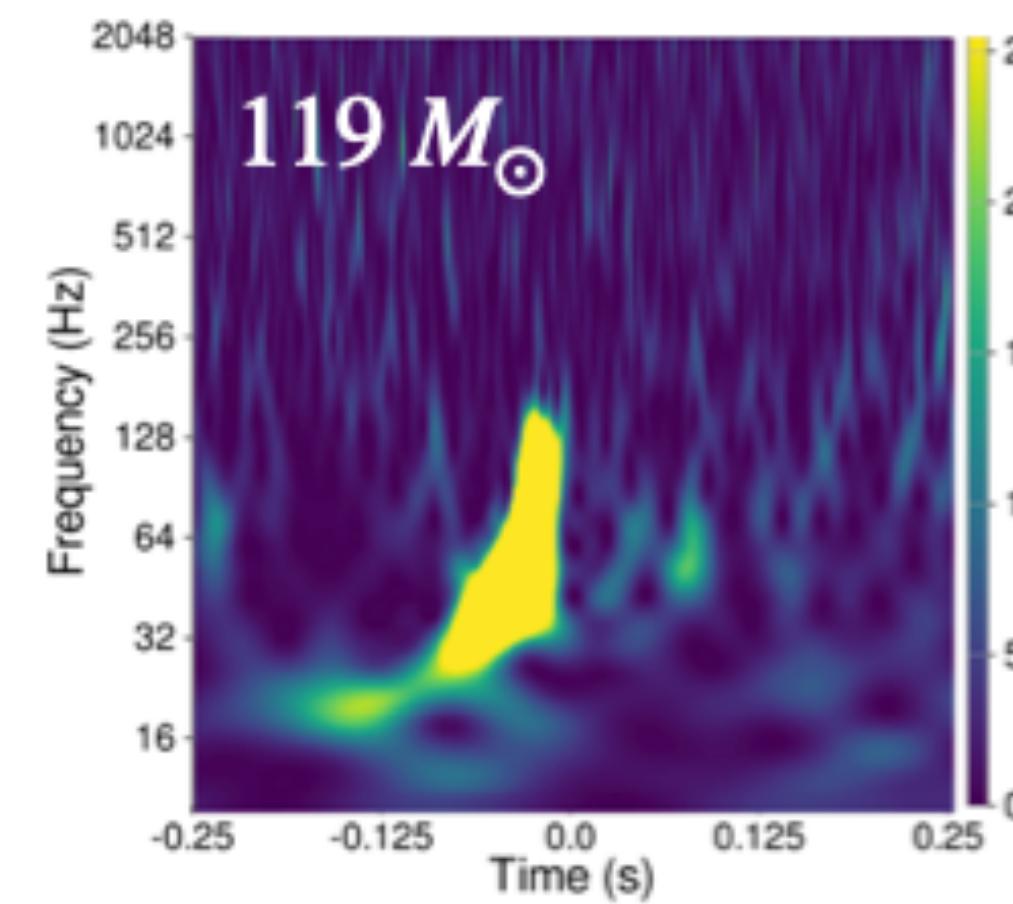
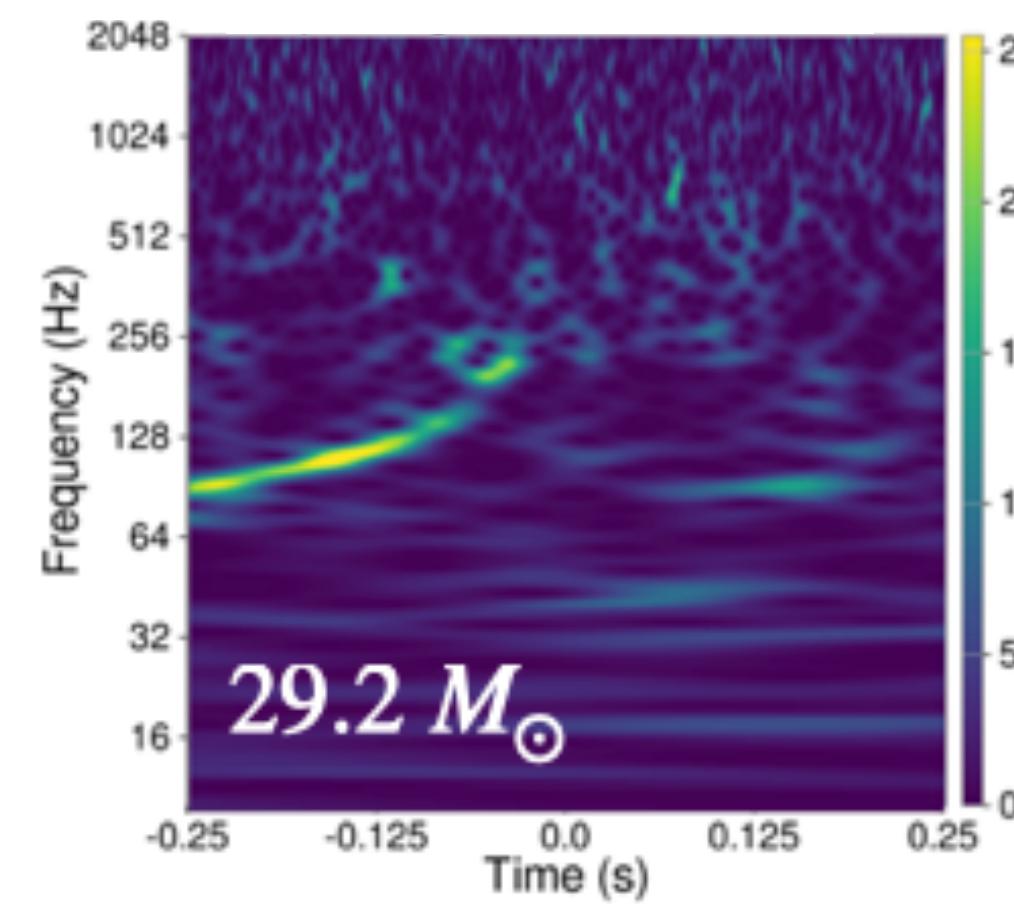
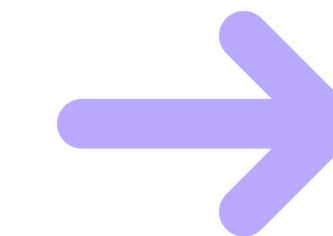
Potential to use Gravity Spy's architecture to build

GSpyNetTree

Gravity Spy Convolutional Neural Network Decision Tree

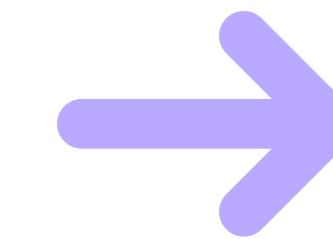
Why a decision tree?

Important effect of candidate mass on GW morphology in time-frequency visualizations.

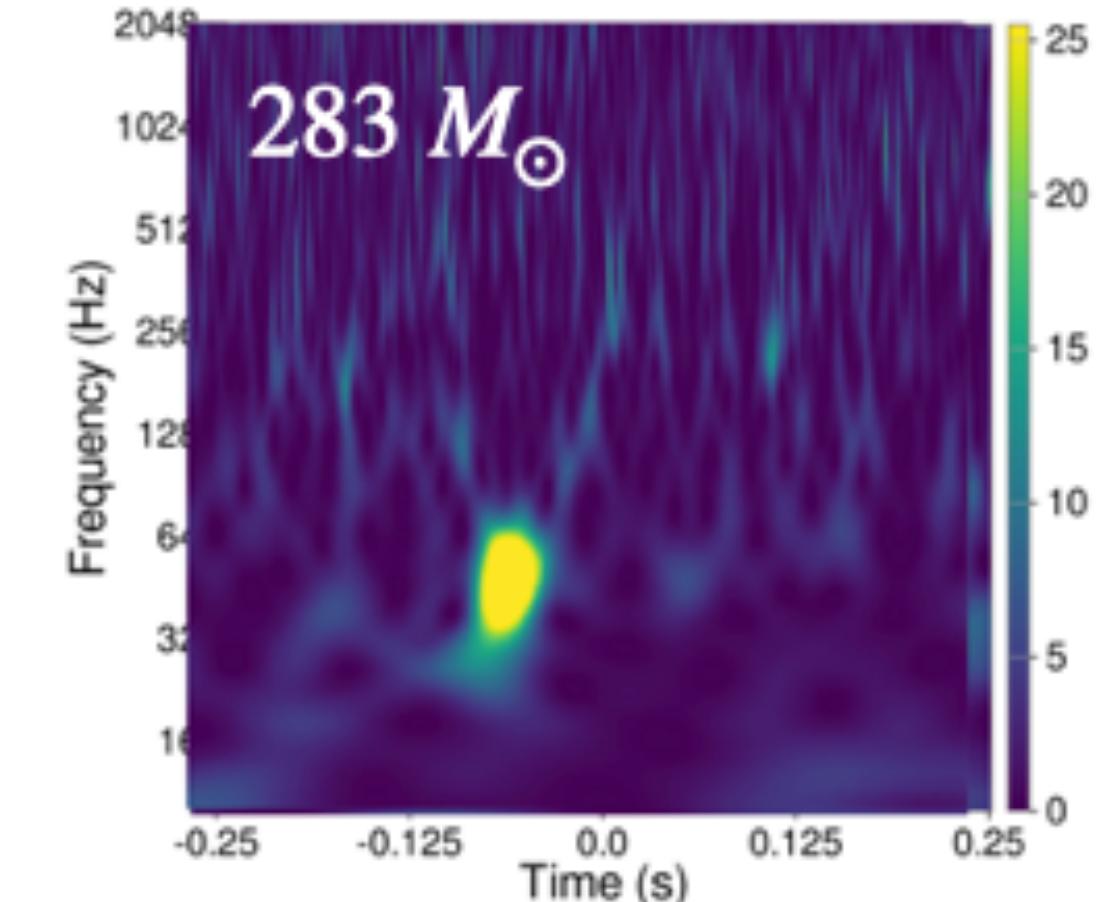
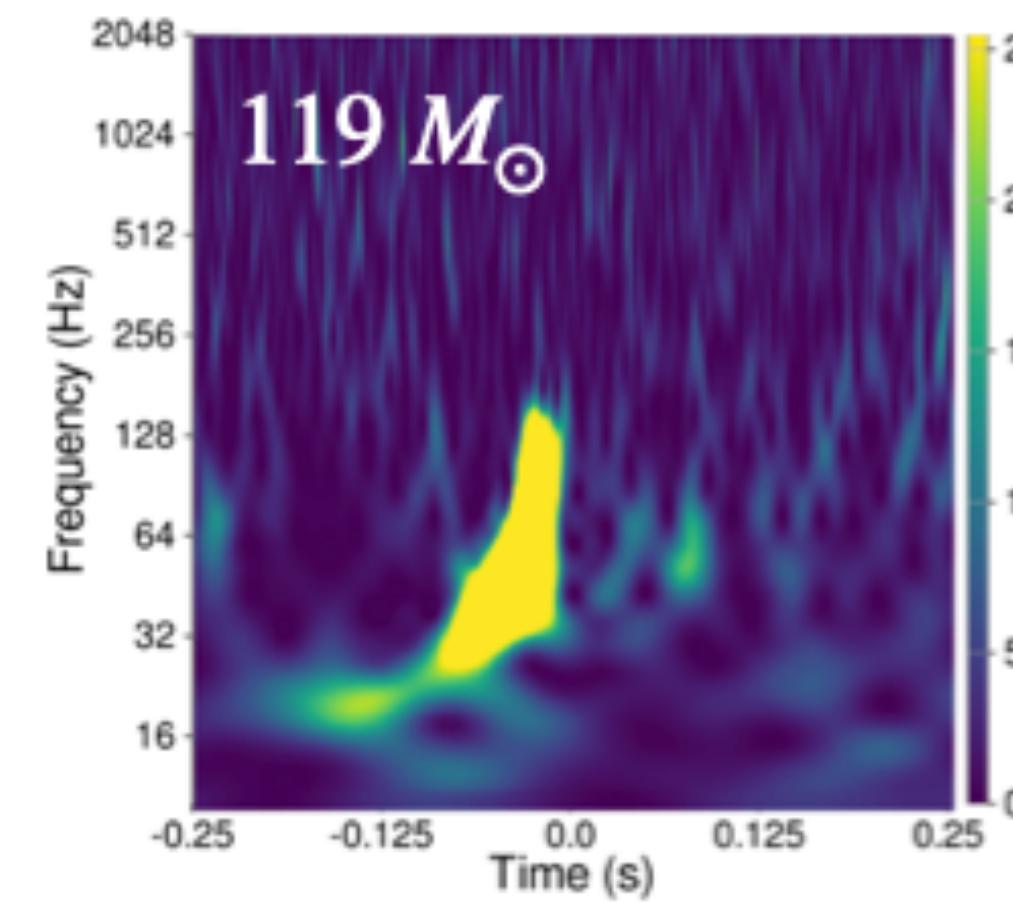
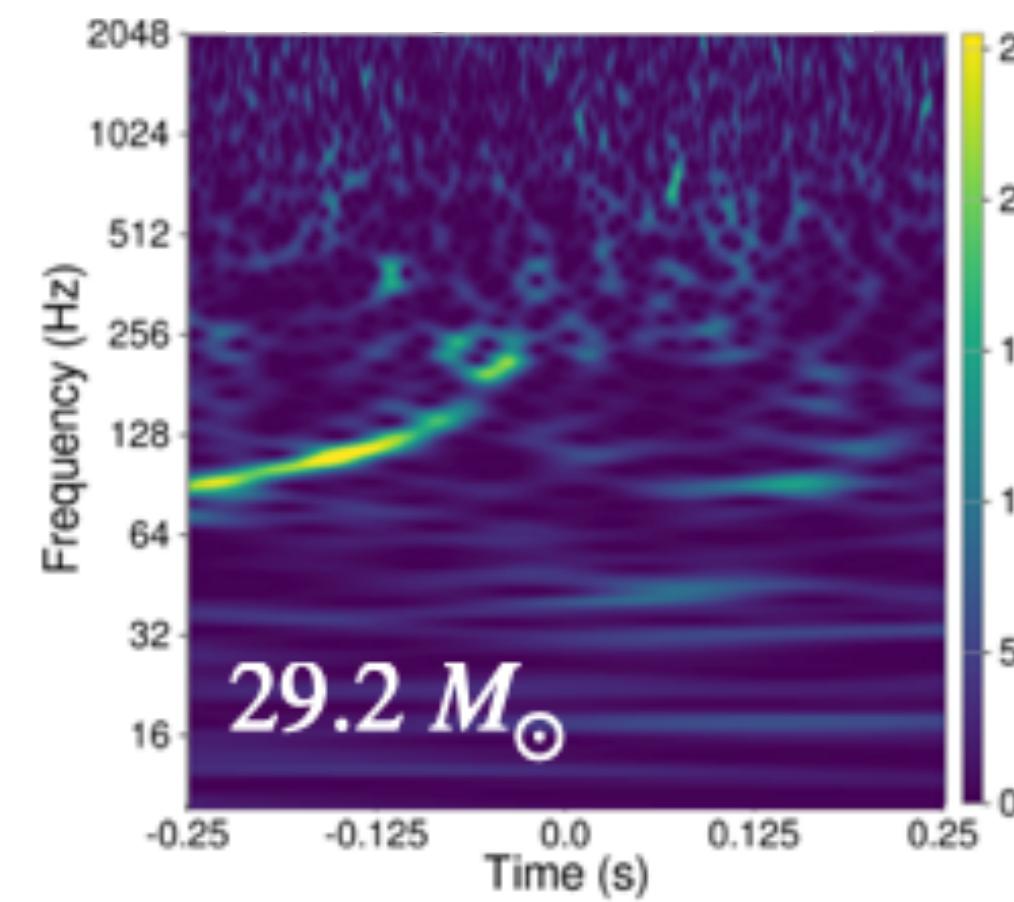


Why a decision tree?

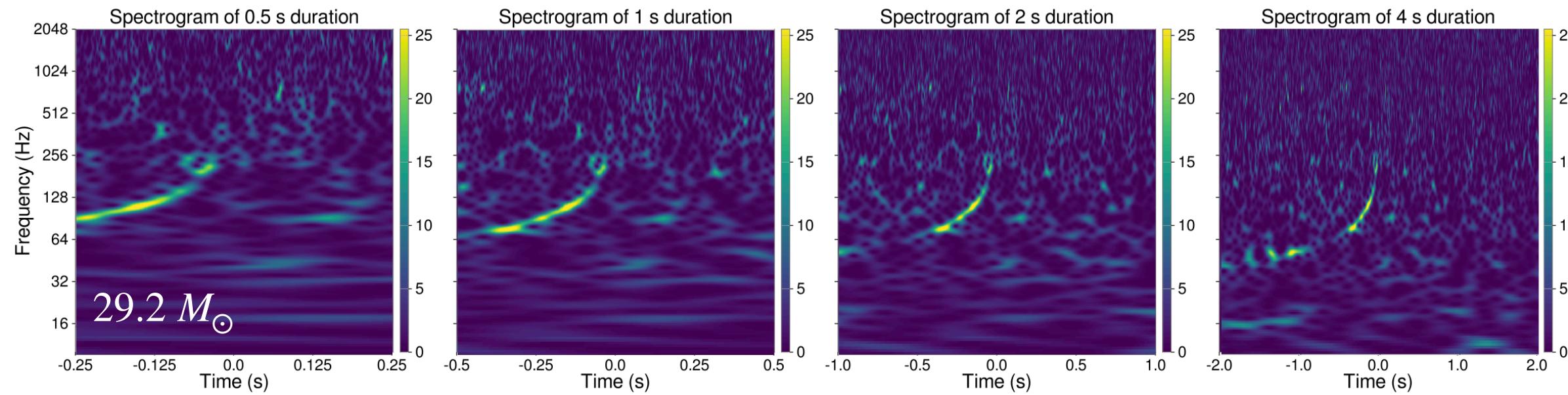
Important effect of candidate mass on GW morphology in time-frequency visualizations.



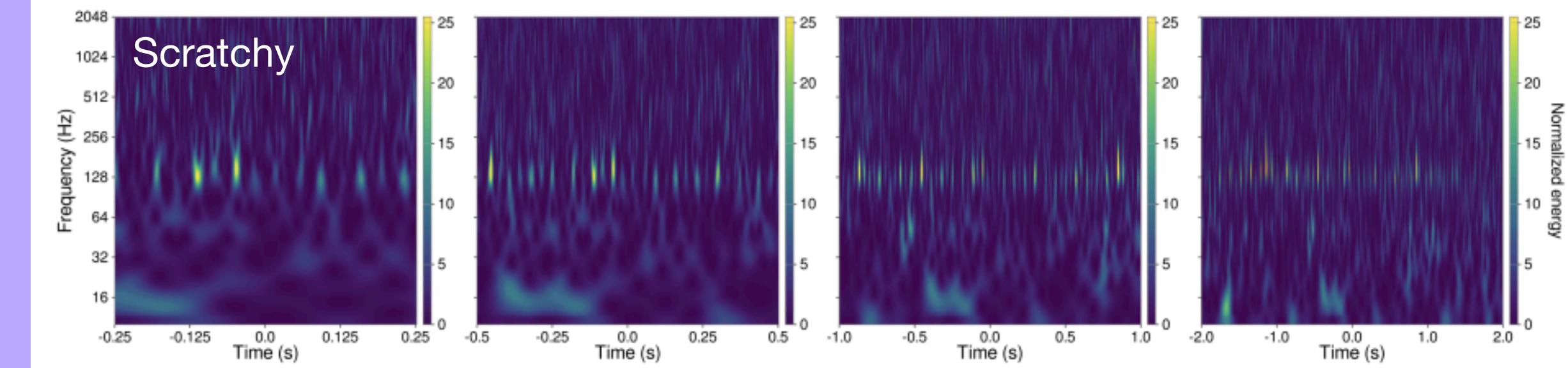
Depending on their total mass, some candidates are more morphologically similar to certain types of glitches.



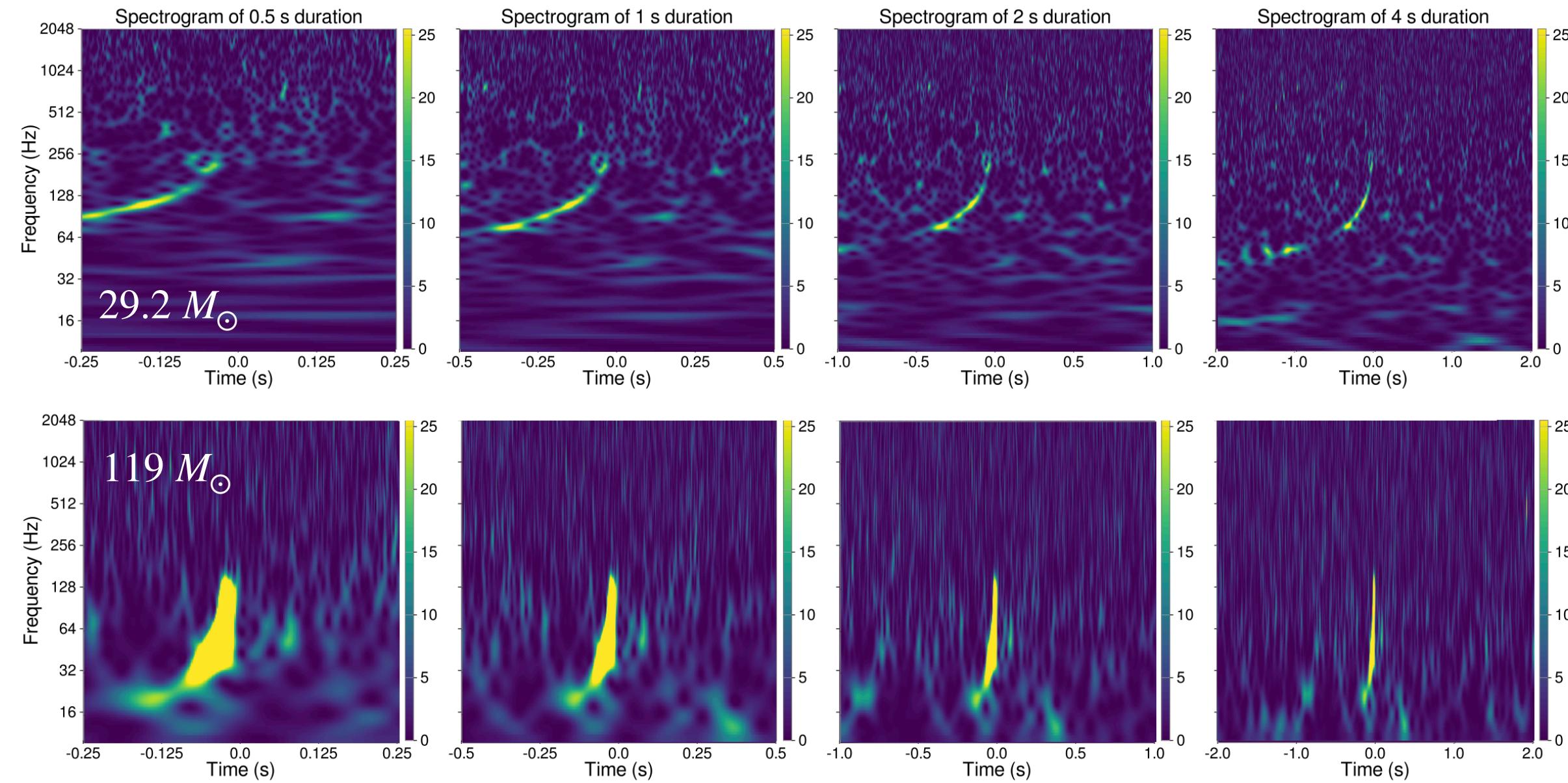
GW samples



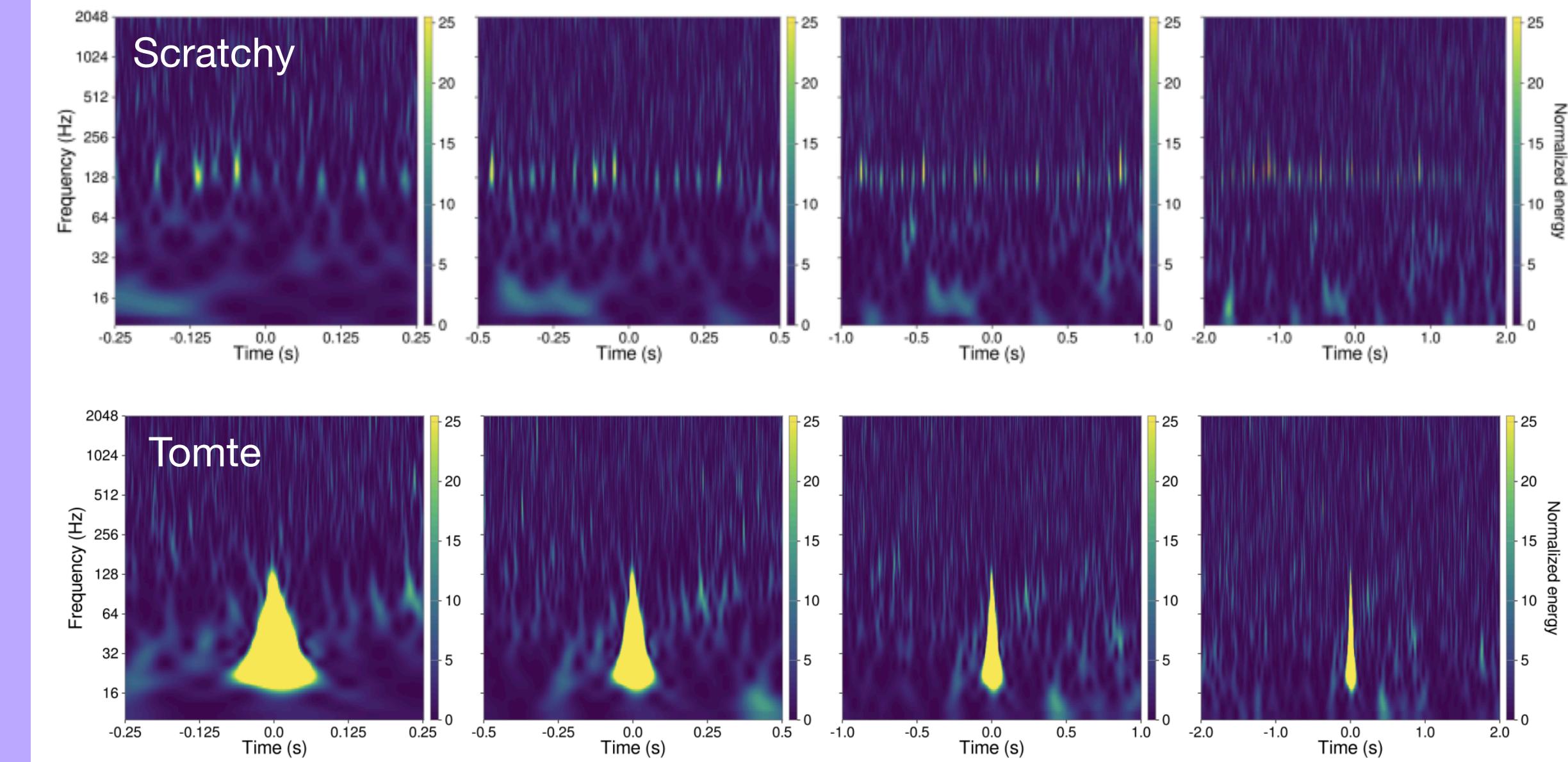
Glitch samples



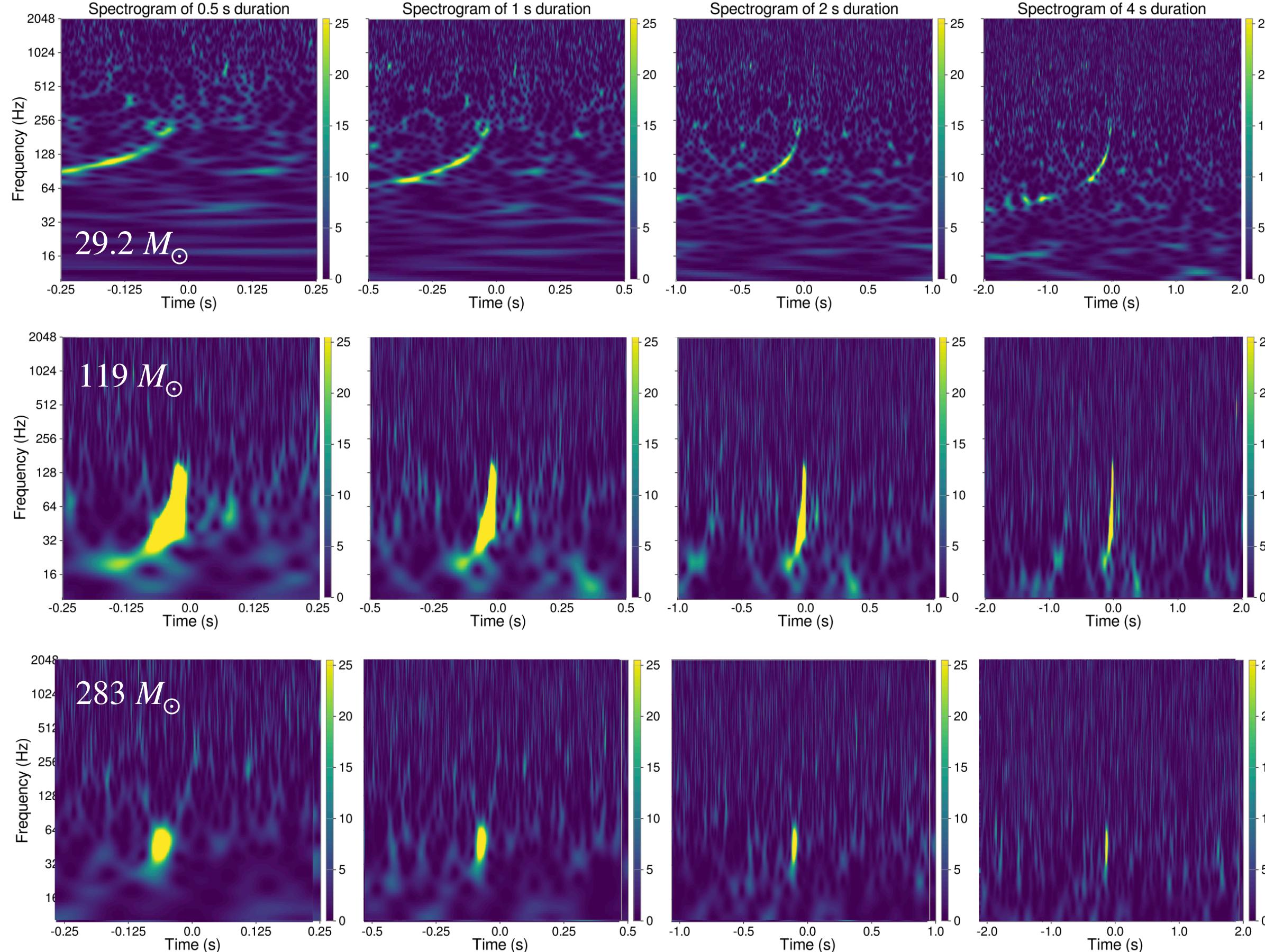
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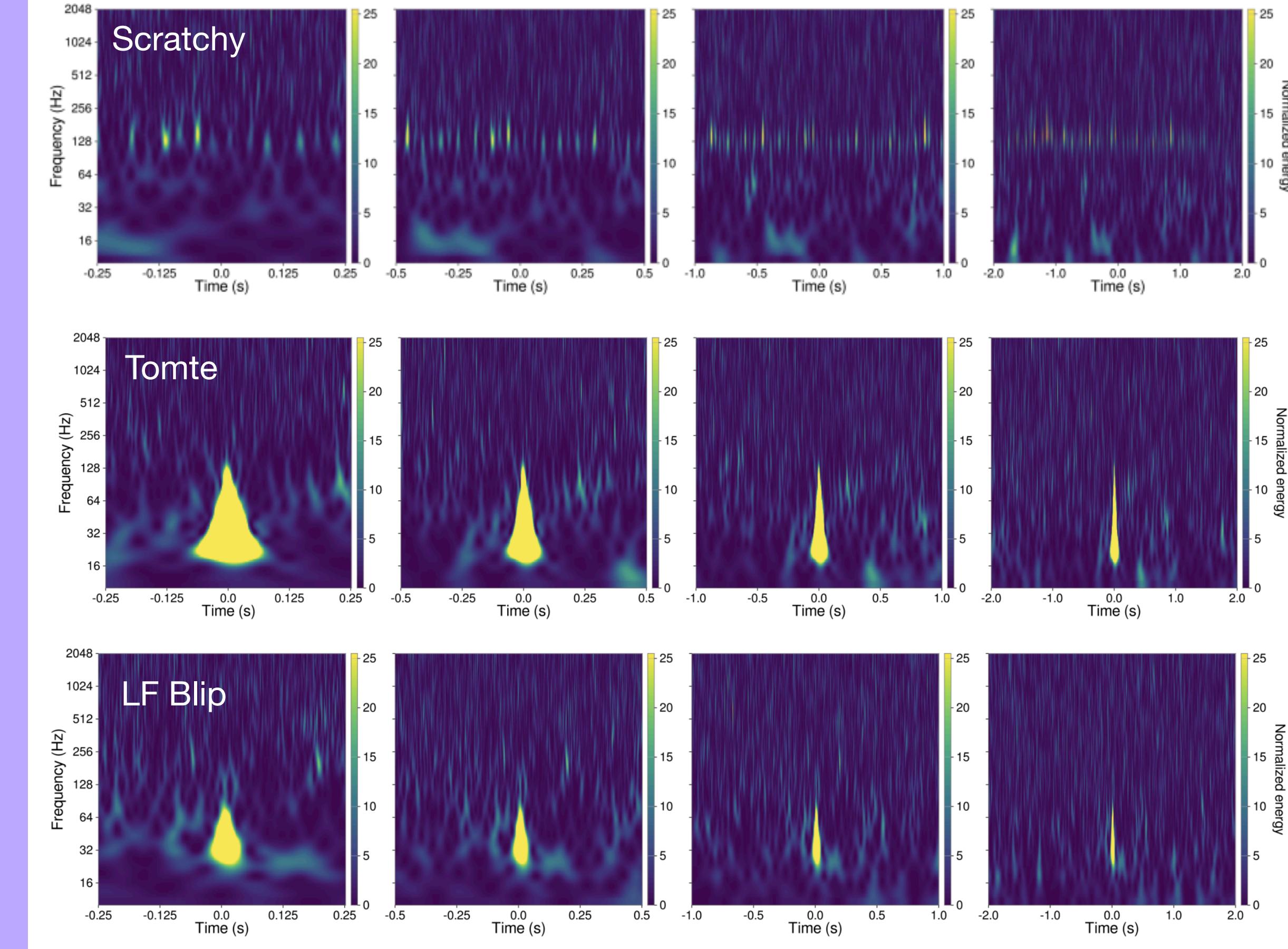
Glitch samples



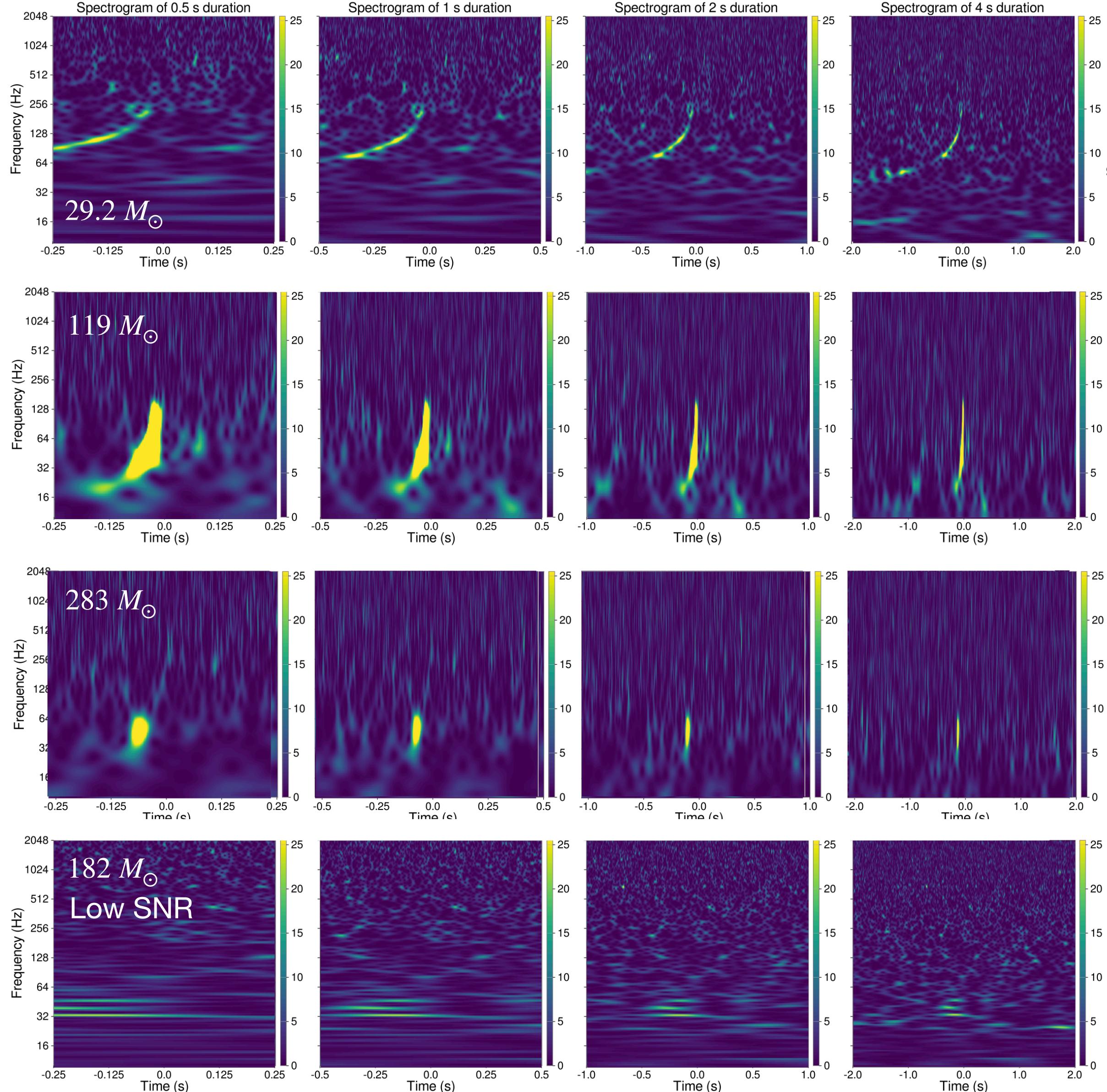
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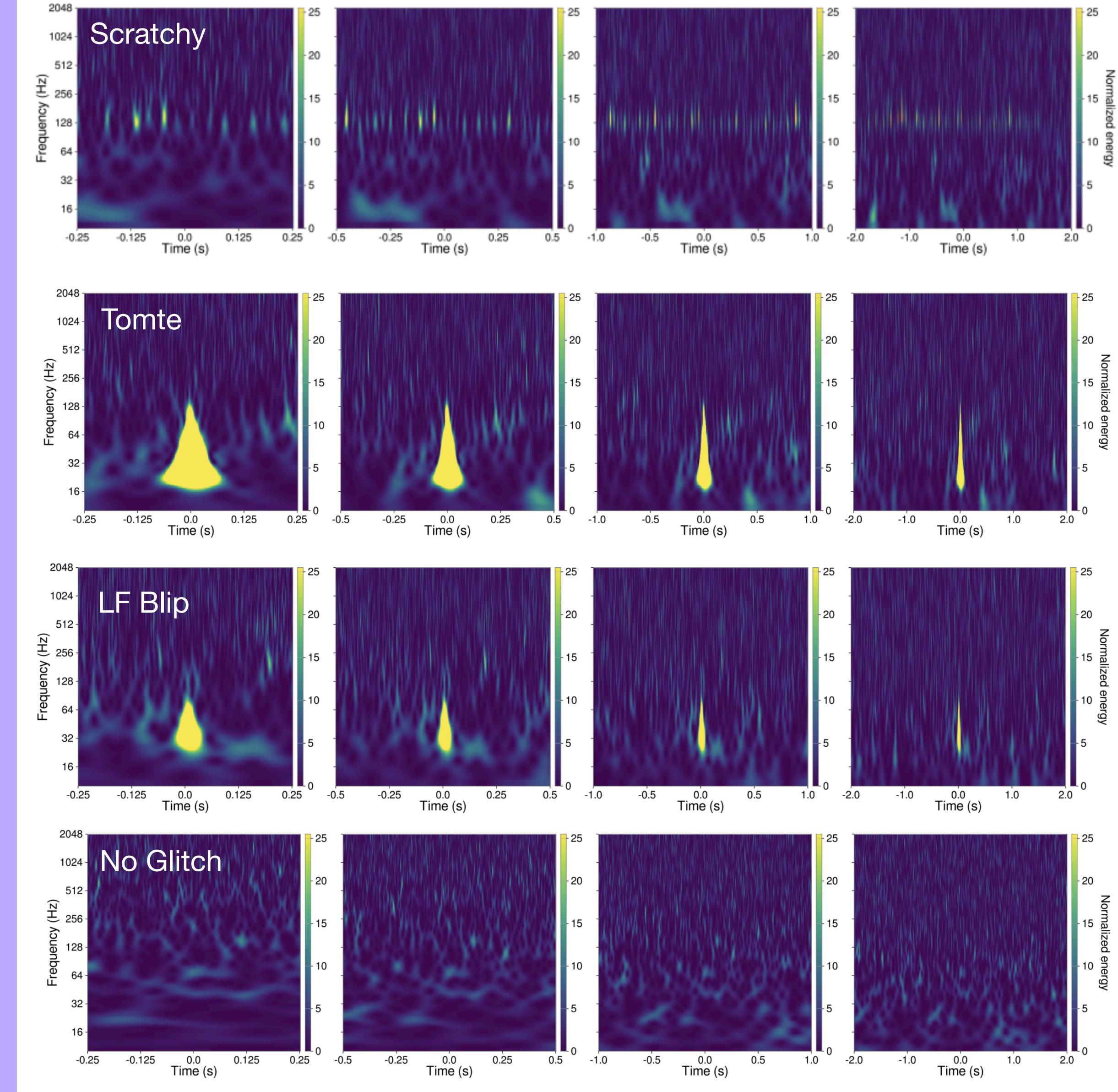
Glitch samples



GW samples



Glitch samples



GSpyNetTree's philosophy is:

Different morphologies, separate classifiers

GSpyNetTree considers three classifiers, depending on the total mass of the candidate.

Low-mass classifier
 $5 - 50 M_{\odot}$

High-mass classifier
 $50 - 250 M_{\odot}$

Extremely high-mass classifier
 $> 250 M_{\odot}$

GSpyNetTree's philosophy is:

Different morphologies, separate classifiers

GSpyNetTree considers three classifiers along with **morphologically similar glitches**.

Low-mass classifier
 $5 - 50 M_{\odot}$

1. Blip
2. Low-frequency Blip
3. Koi Fish
4. Scratchy

High-mass classifier
 $50 - 250 M_{\odot}$

1. Blip
2. Low-frequency Blip
3. Koi Fish
4. Tomte

Extremely high-mass classifier
 $> 250 M_{\odot}$

1. Blip
2. Low-frequency Blip

GSpyNetTree's philosophy is:

Different morphologies, separate classifiers

GSpyNetTree considers three classifiers along with **morphologically similar glitches**. We also include **No Glitch** samples to account for low SNR GWs.

Low-mass classifier
 $5 - 50 M_{\odot}$

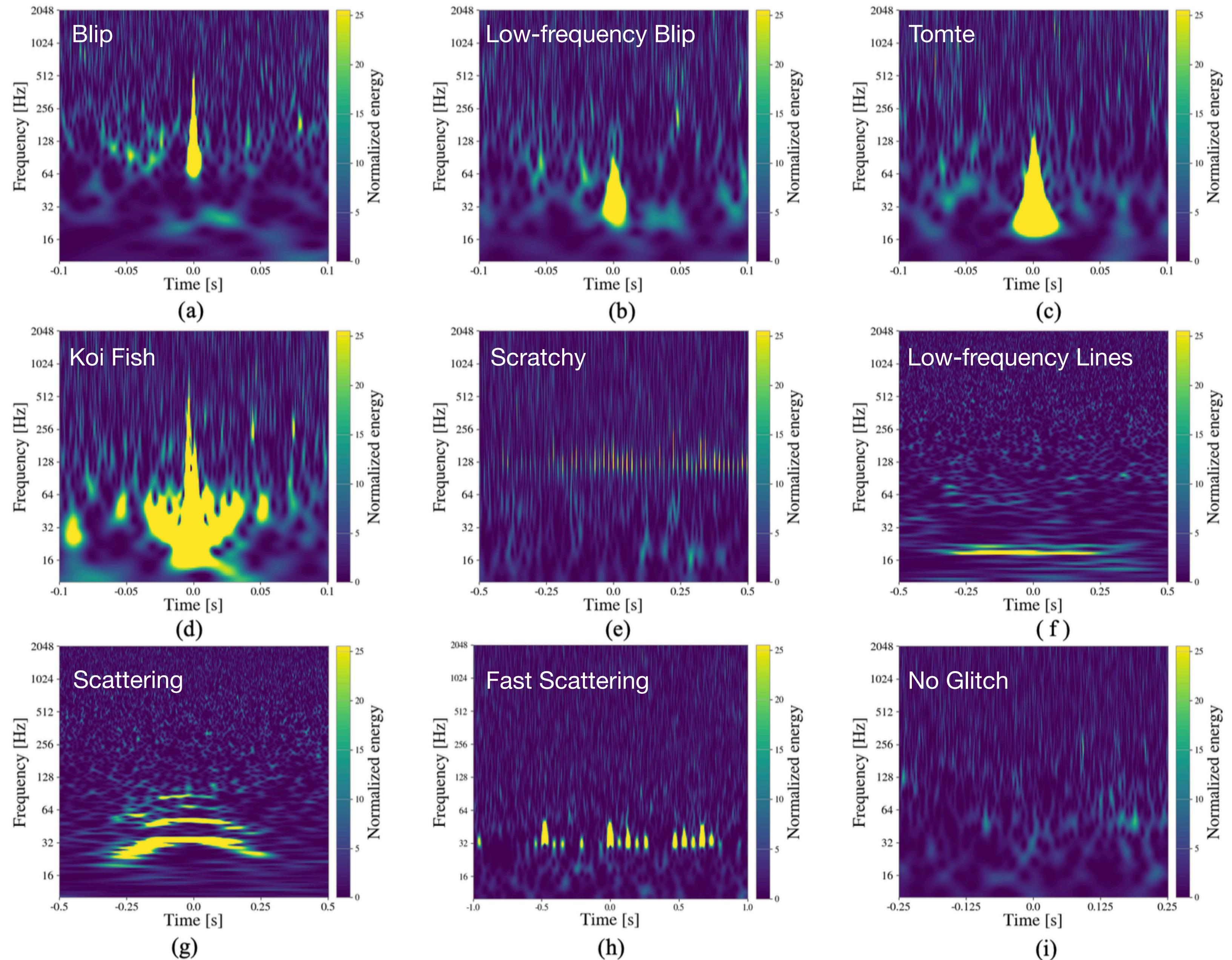
1. Blip
2. Low-frequency Blip
- 3. No Glitch**
4. Koi Fish
5. Scratchy

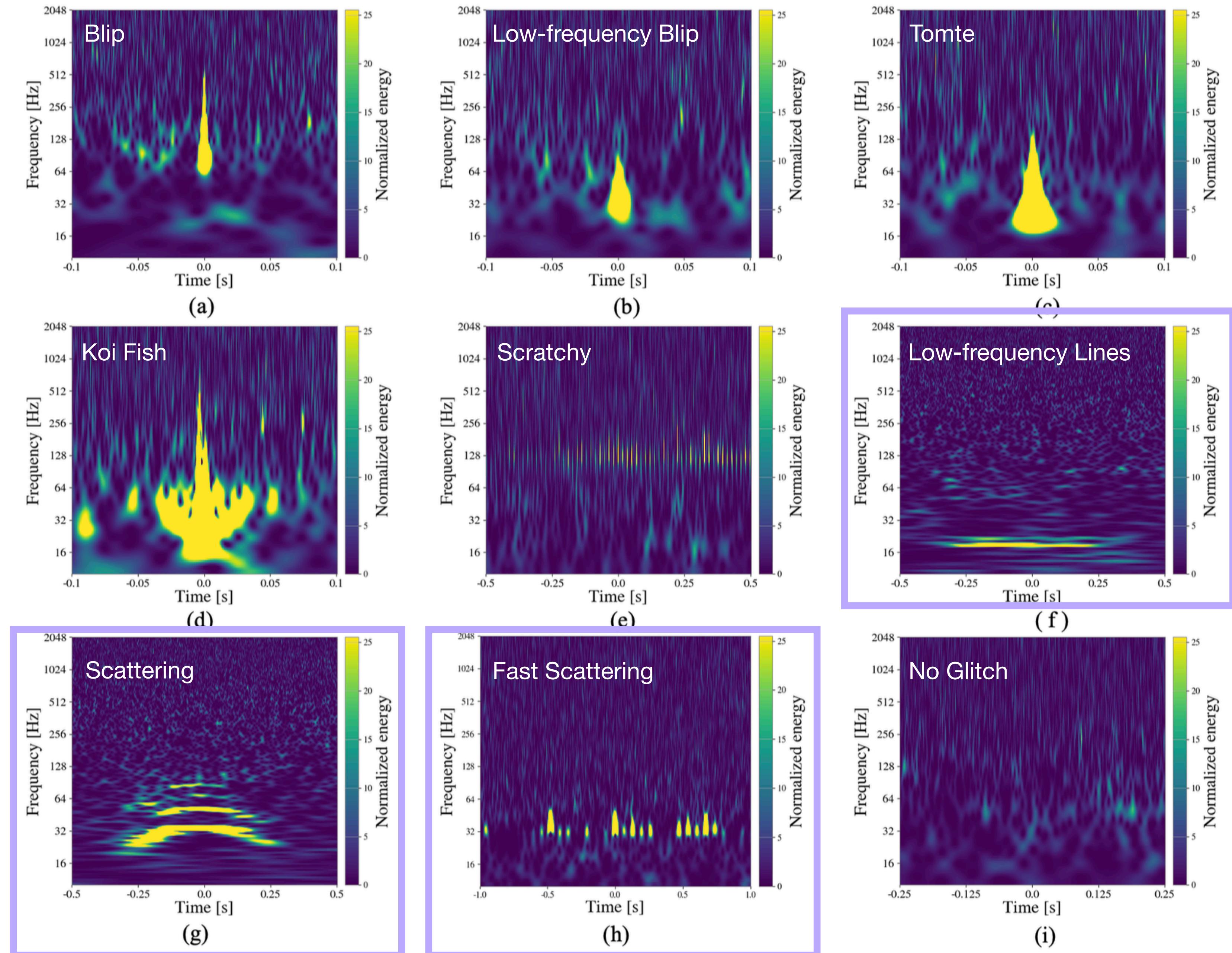
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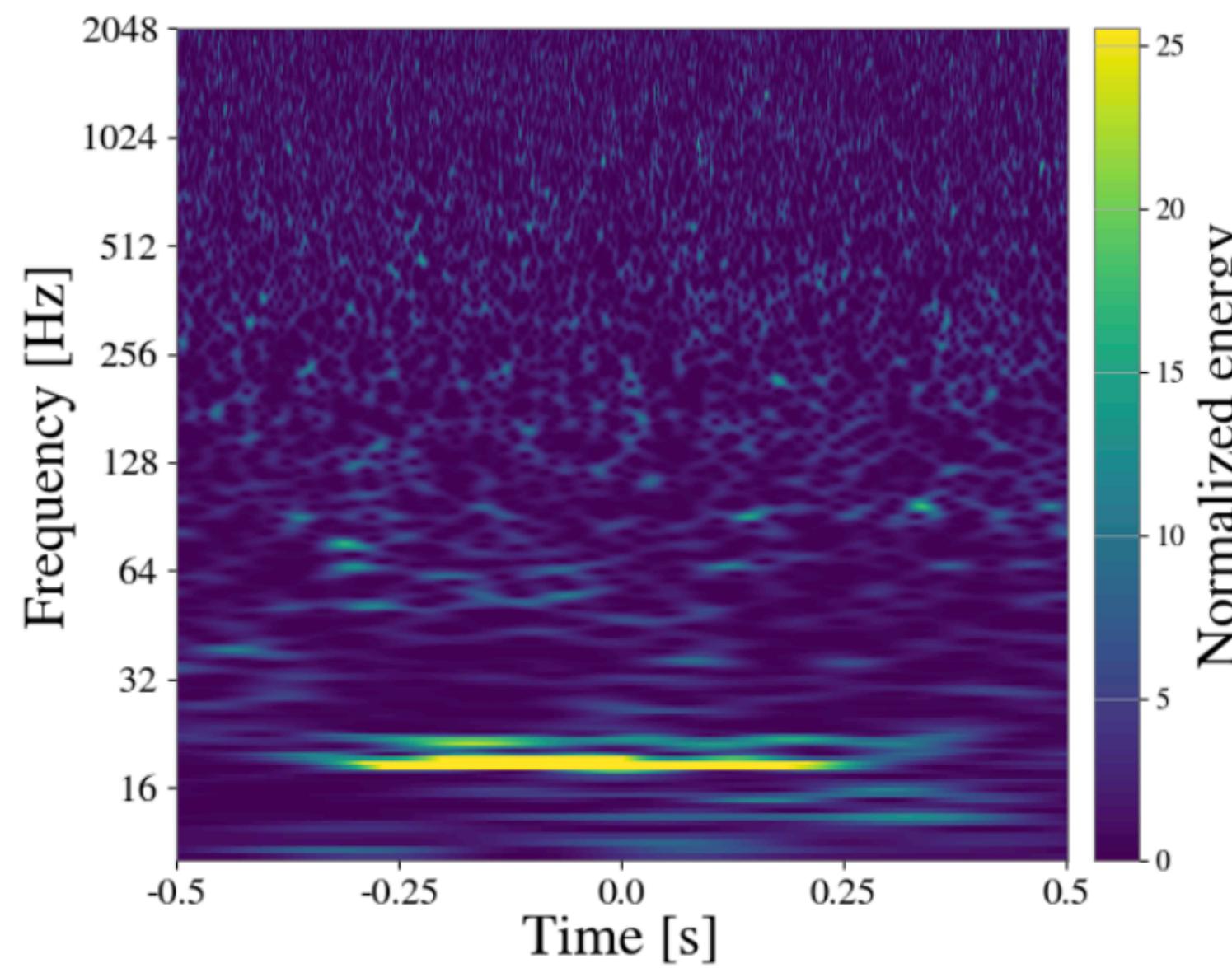
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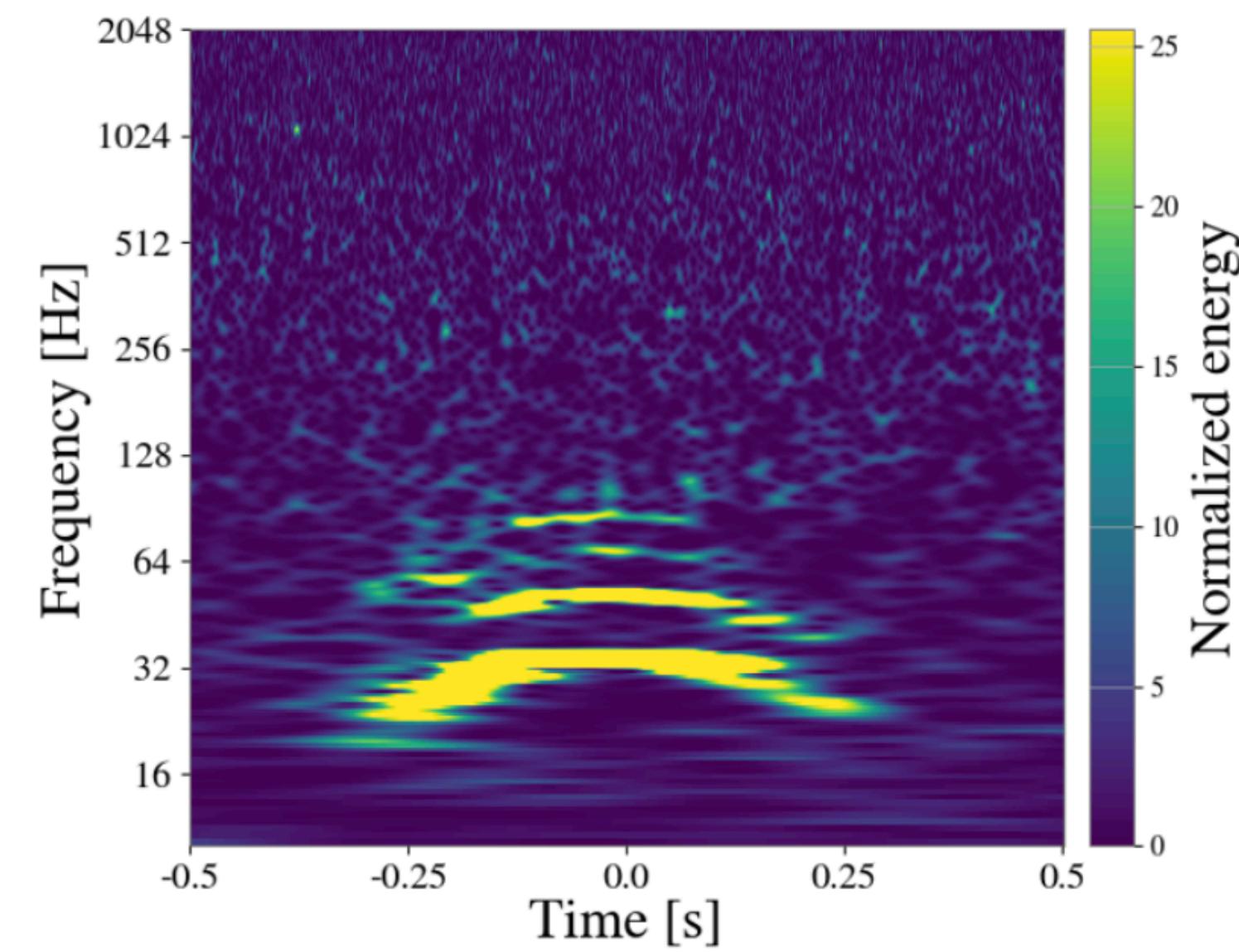


Why include these three types of glitches in all classifiers?

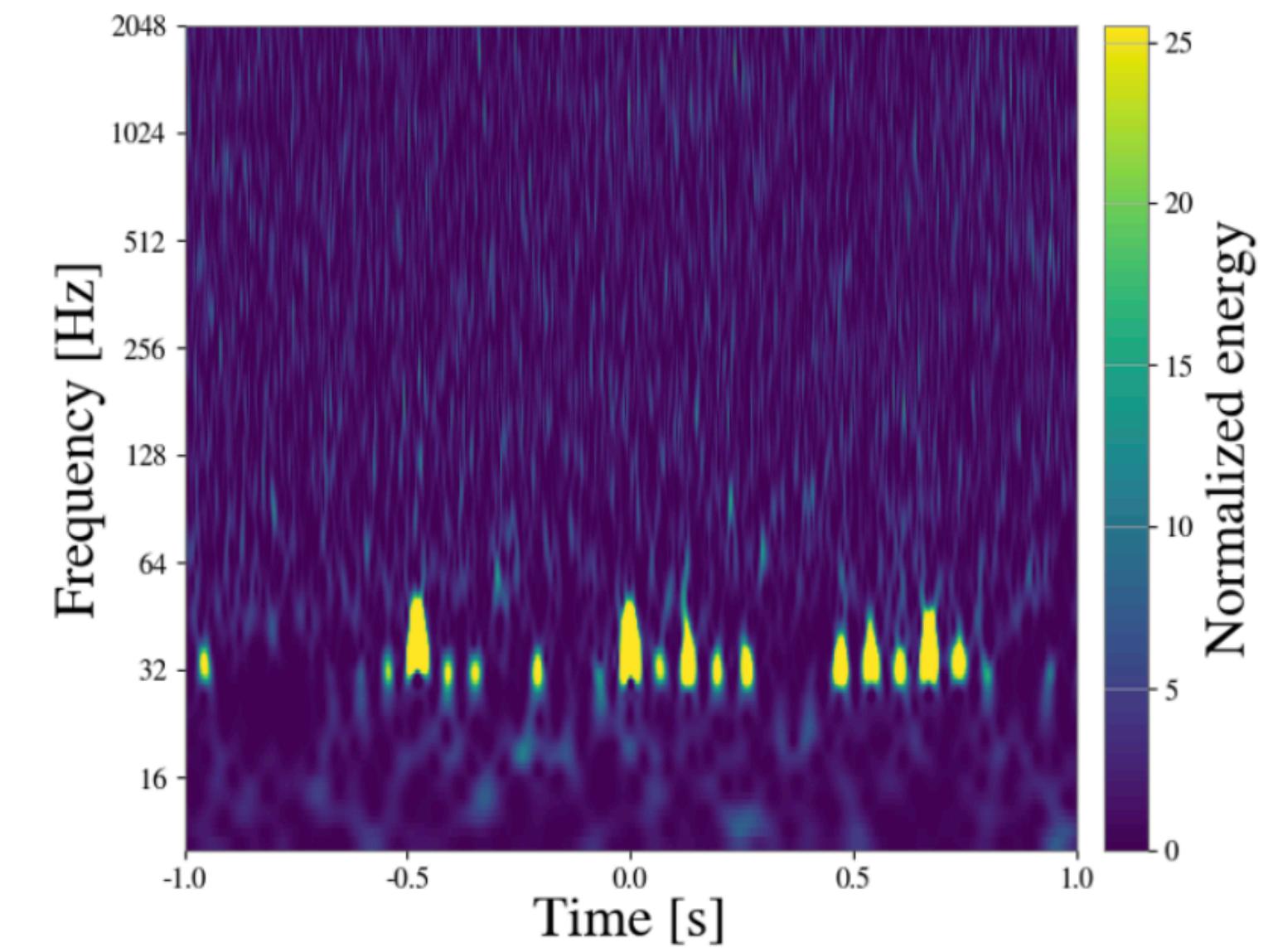
Low-frequency Lines



Scattering



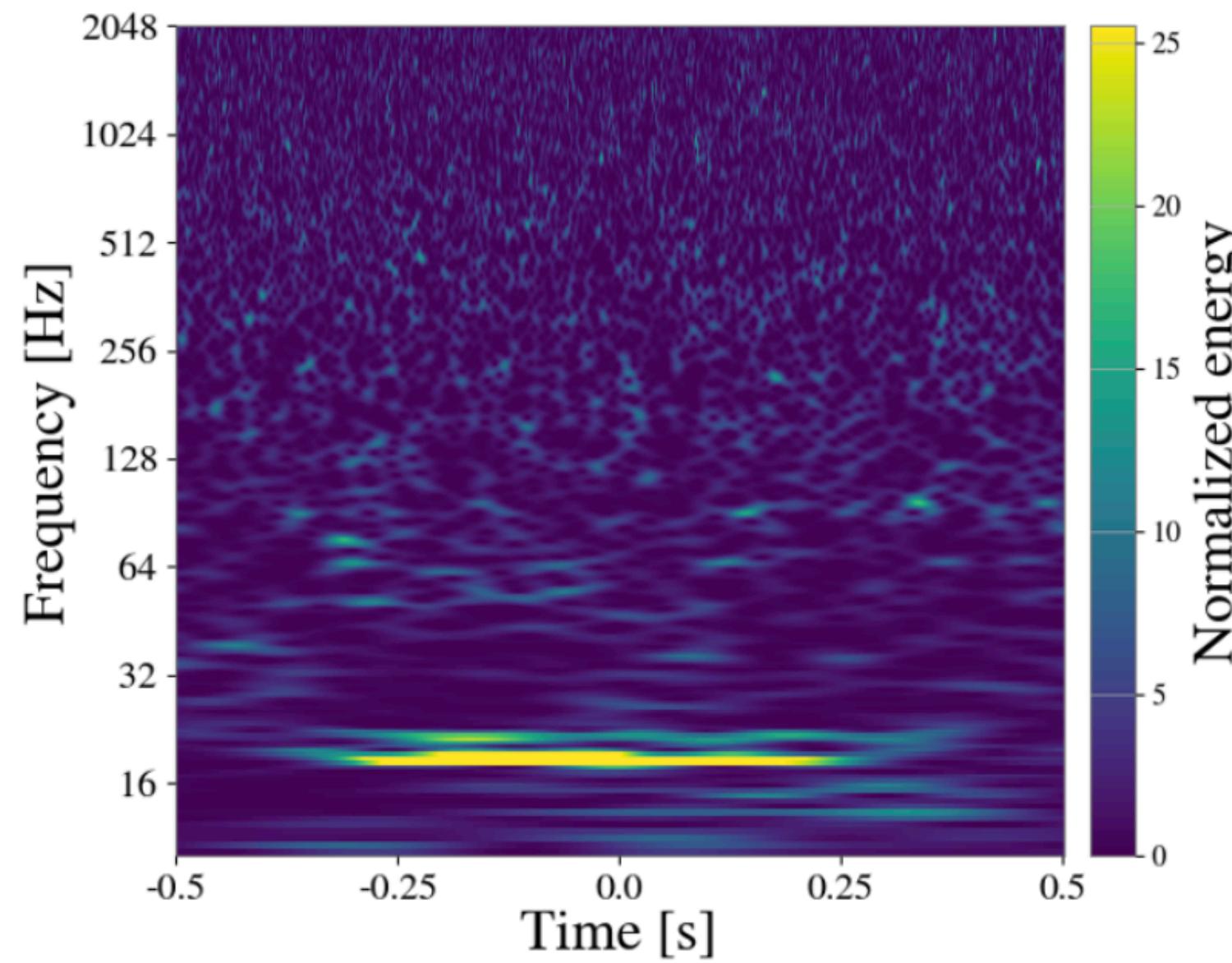
Fast Scattering



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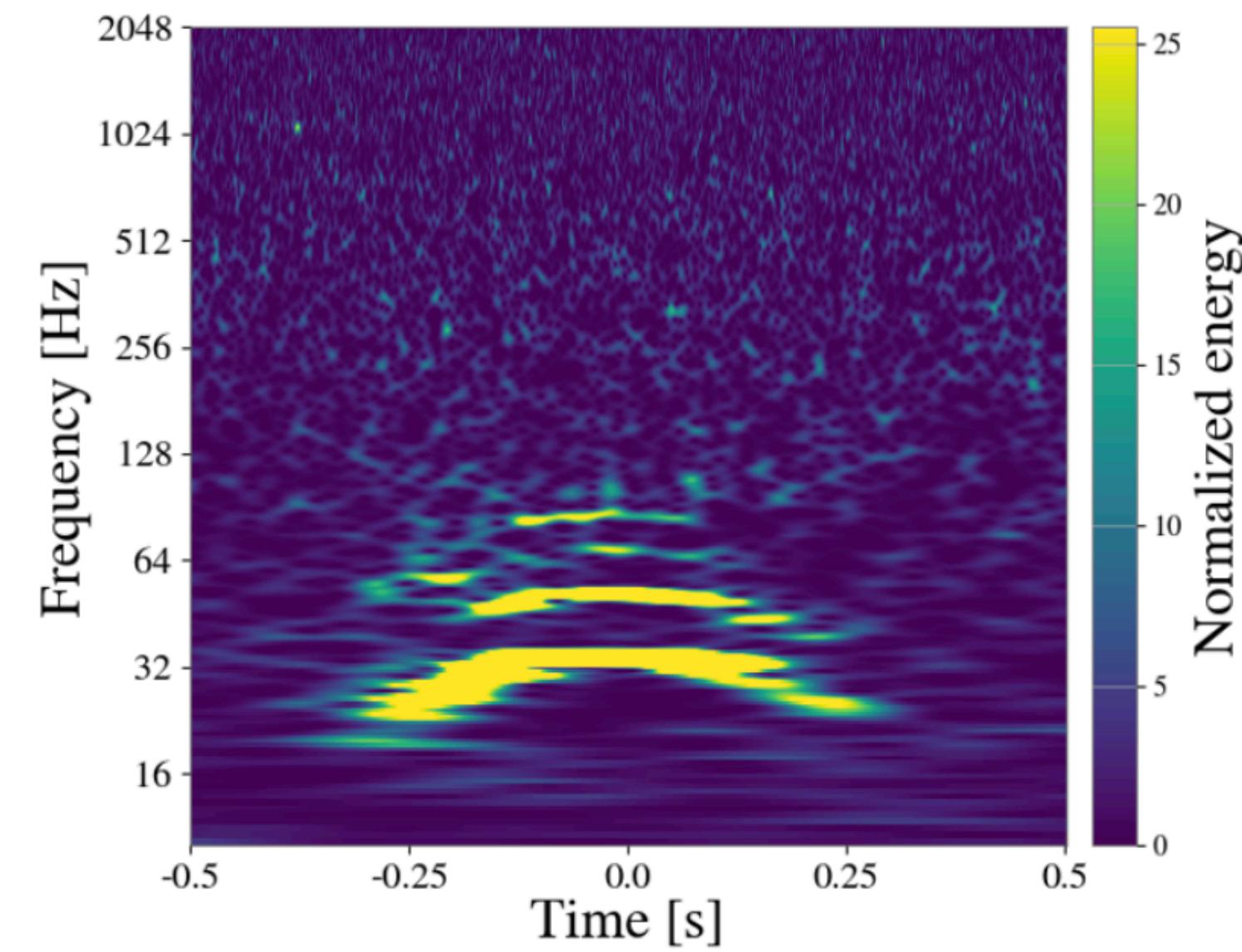
Because they are the most common!

Low-frequency Lines



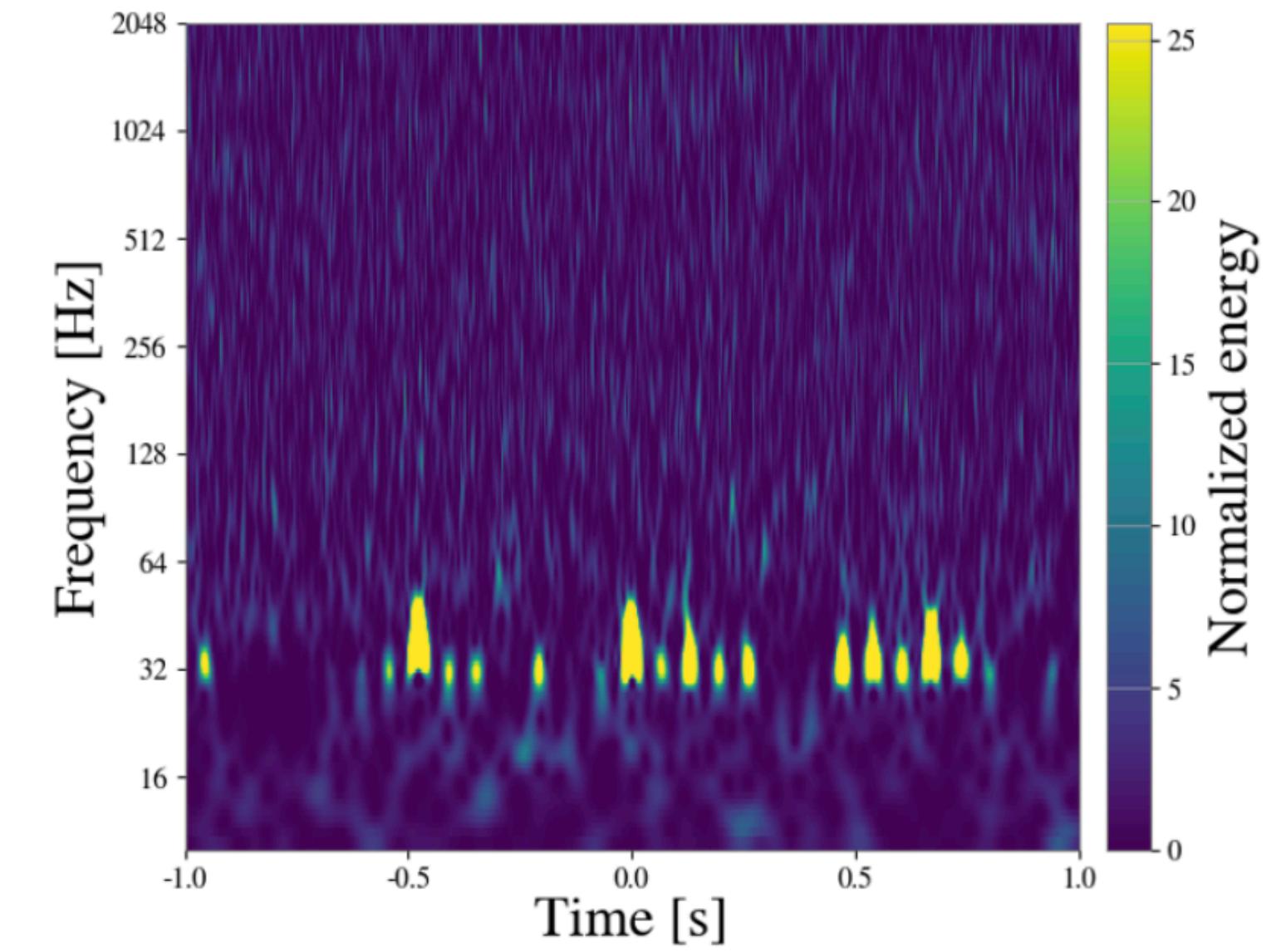
Low-frequency noise was very common during ER15.

Scattering



Most common glitches in O3, responsible for broad ranges of vetted times.

Fast Scattering



GSpyNetTree's philosophy is:

Different morphologies, separate classifiers

+ most common glitches!

GSpyNetTree considers three classifiers along with morphologically similar glitches and most common detector glitches. We also include **No Glitch** samples to account for low SNR GWs.

Low-mass classifier
 $5 - 50 M_{\odot}$

1. Blip
2. Low-frequency Blip
- 3. No Glitch**
4. Koi Fish
5. Scratty
6. Low-frequency Lines
7. Scattering
8. Fast Scattering

High-mass classifier
 $50 - 250 M_{\odot}$

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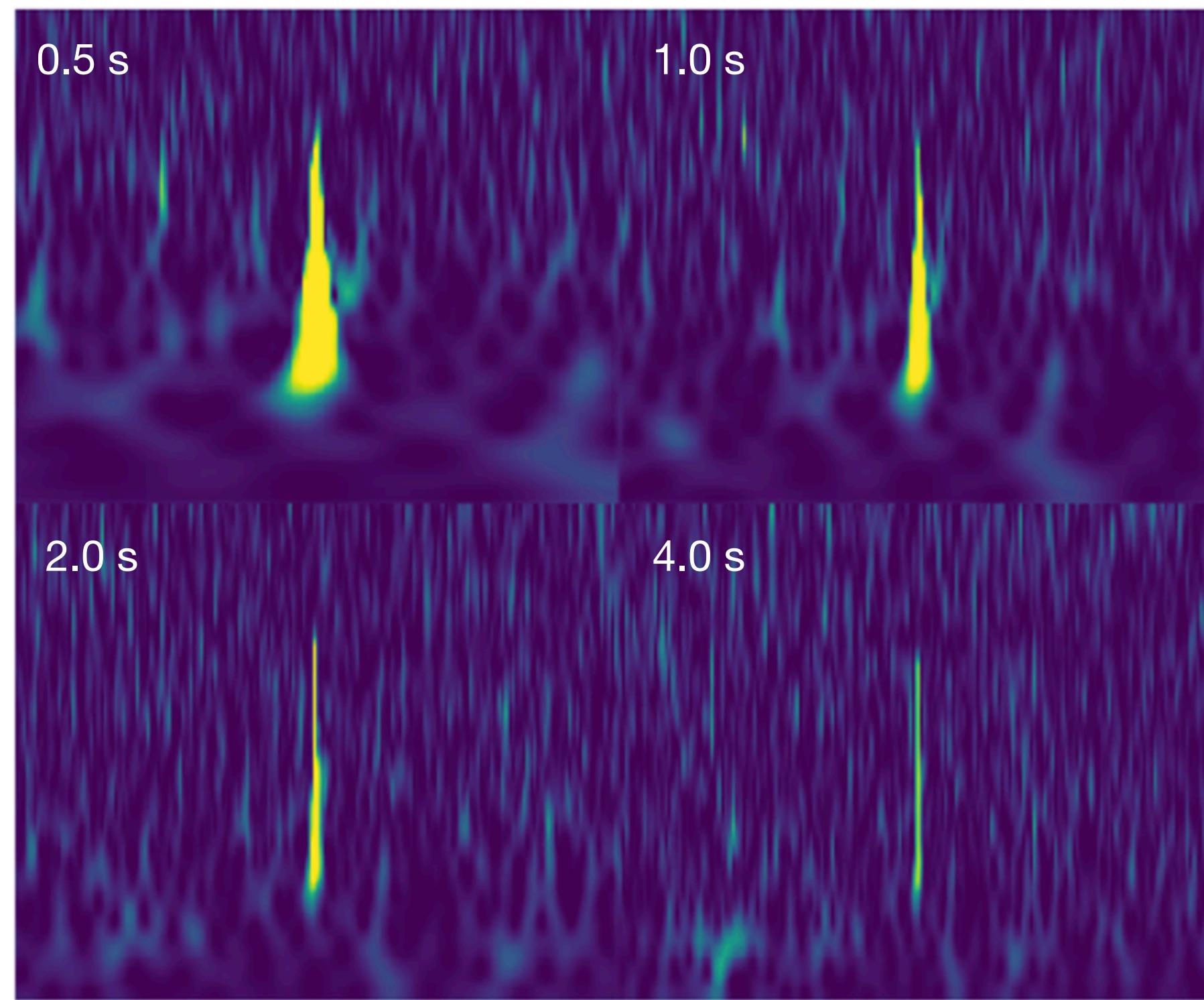
Extremely high-mass classifier
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5. Scattering
6. Fast Scattering

How to account for shorter/longer morphologies?

Just like in Gravity Spy, we use a 2x2 matrix of spectrograms of different durations

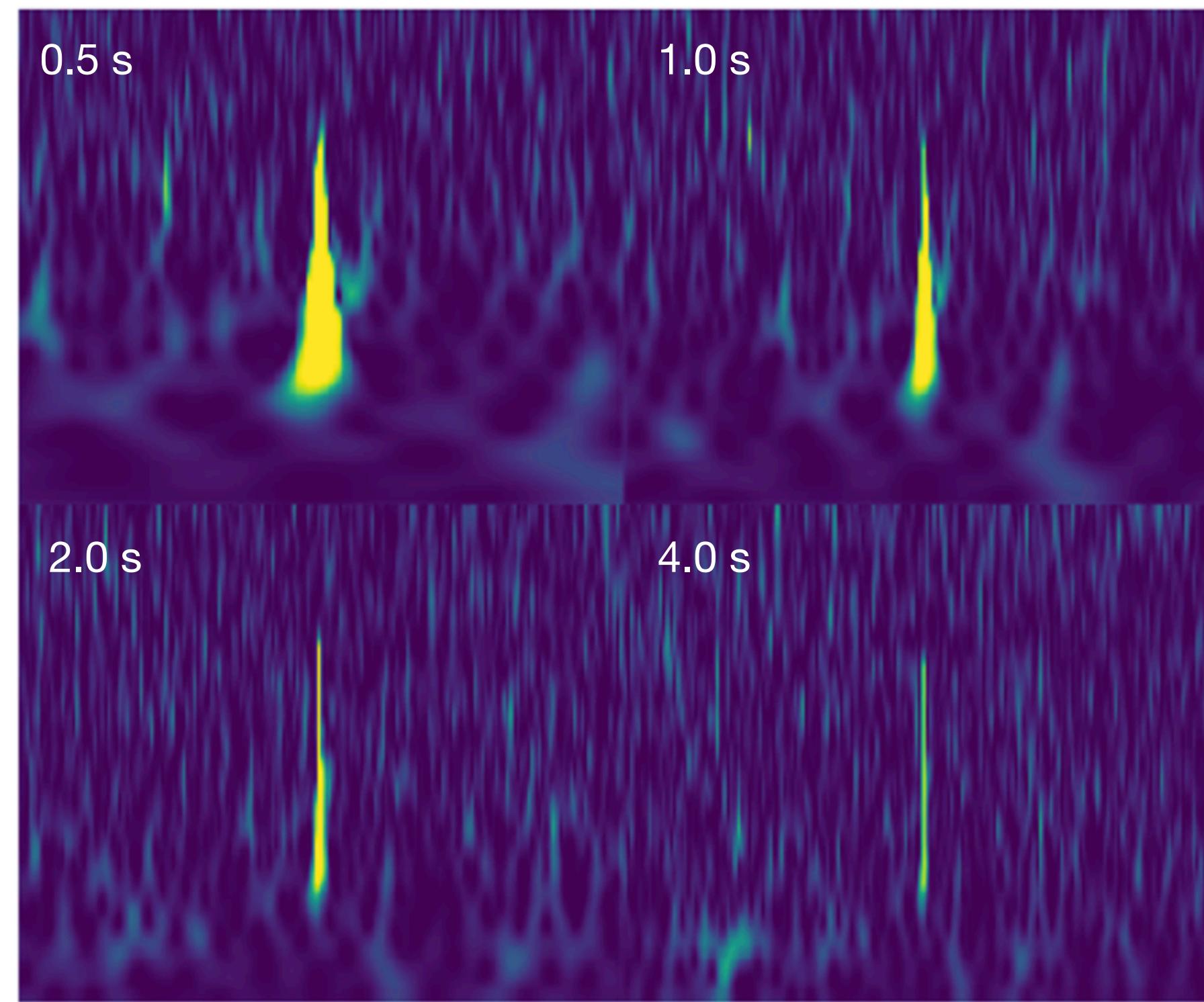
- 4 spectrograms, 0.5 s, 1 s, 2 s, and 4 s in duration arranged in a 2x2 matrix.



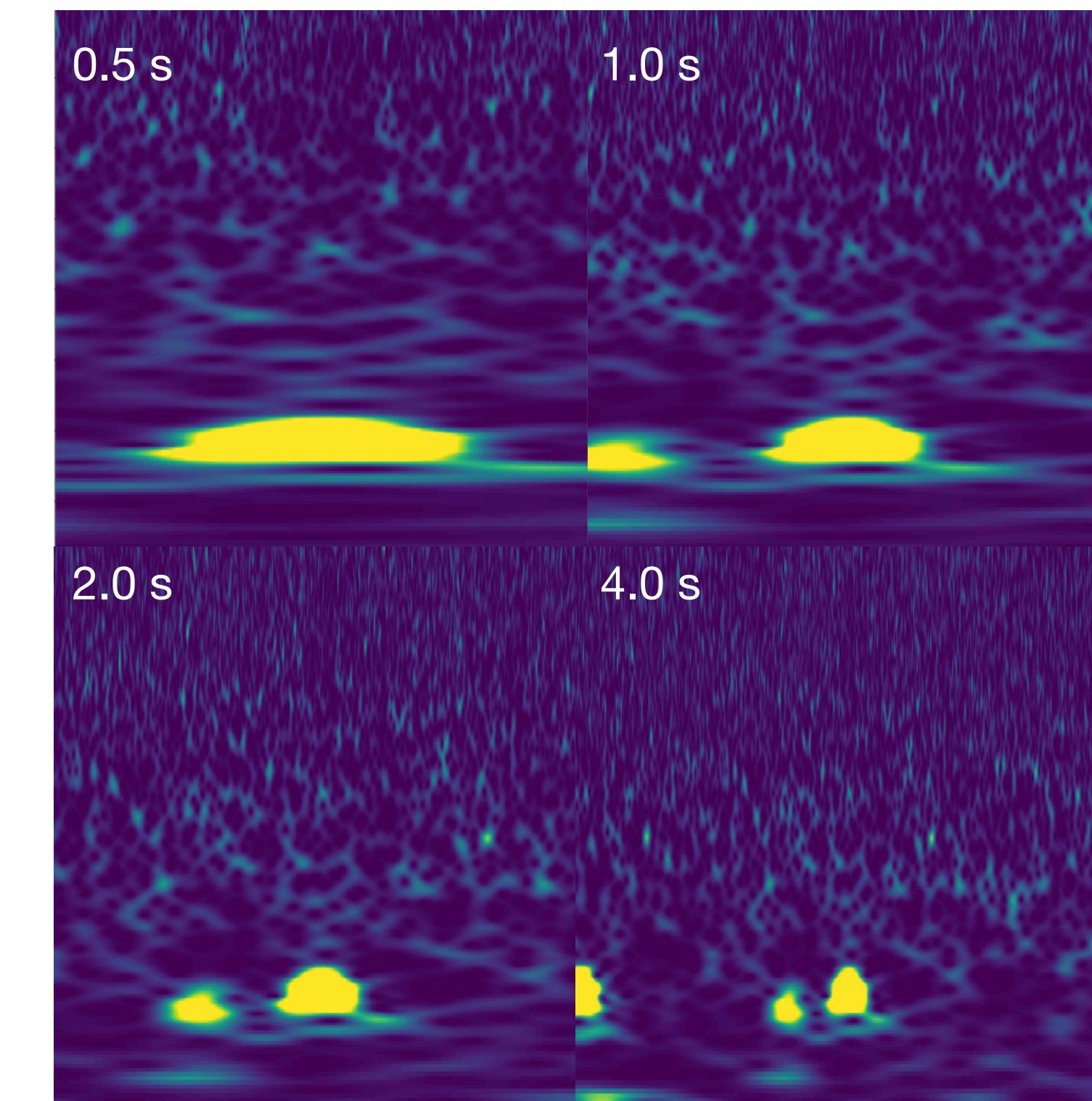
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- 4 spectrograms, 0.5 s, 1 s, 2 s, and 4 s in duration arranged in a 2x2 matrix.



Blip



Fast Scattering

What considerations should we take into account when building a signal-vs-glitch classifier?

1

- Glitches come in various time-frequency morphologies.
 - 1.1 Some glitches are more common than others.
 - 1.2 How to account for long/short morphologies?

What considerations should we take into account when building a signal-vs-glitch classifier?

1

- Glitches come in various time-frequency morphologies.



Three separate classifiers sorted via candidate mass

1.1

- Some glitches are more common than others.



Include most common glitches during O3/ER15.

1.2

- How to account for short/long morphologies?



Consider spectrograms of 4 different durations.

?

What if new glitch classes show up?

What considerations should we take into account when building a signal-vs-glitch classifier?

1

- Glitches come in various time-frequency morphologies.



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1.1

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Include most common glitches during O3/ER15.

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Consider spectrograms of 4 different durations.

2.

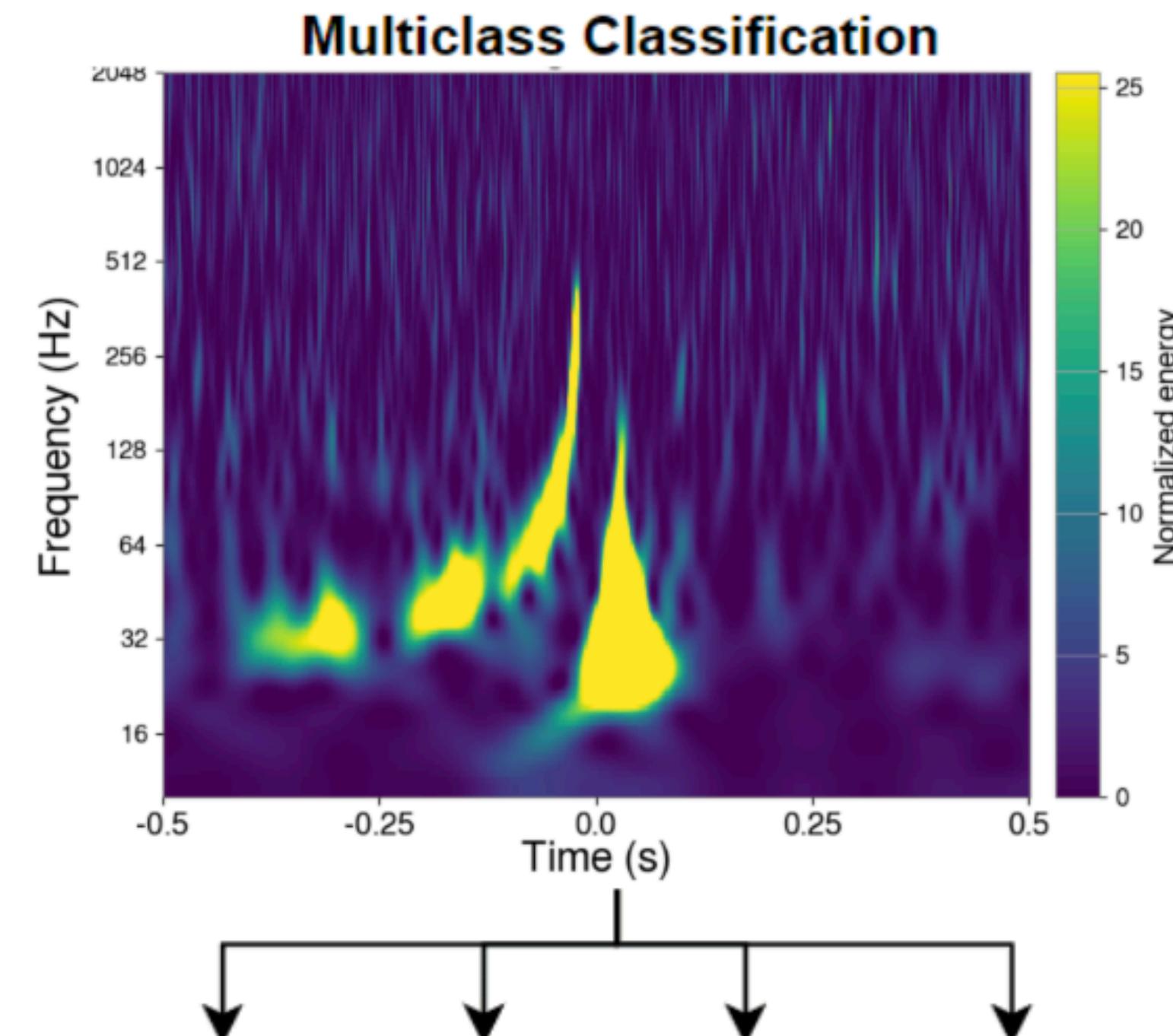
- Glitch rate is about ~1/minute

2. Glitch rate is about ~1/minute

Probability that glitch overlaps/occurs in the close proximity of GW candidate is ~high.

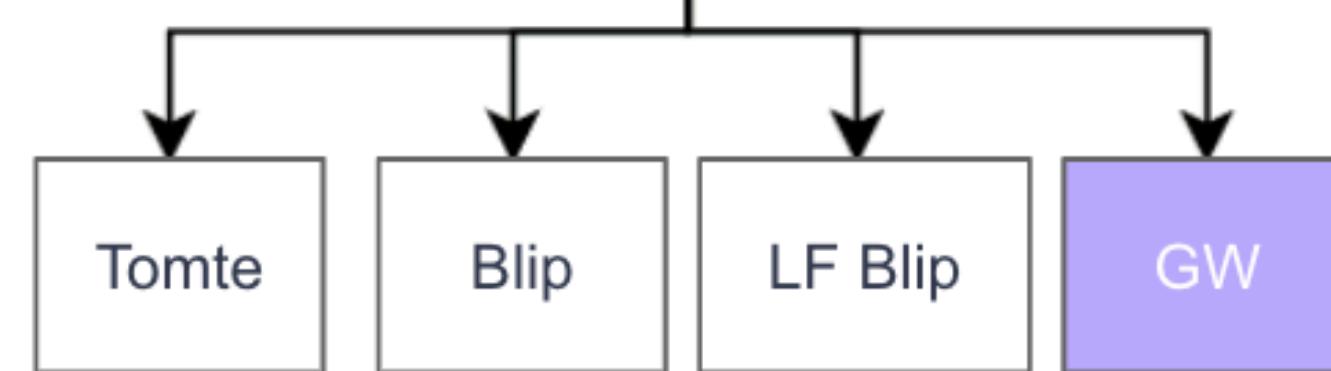
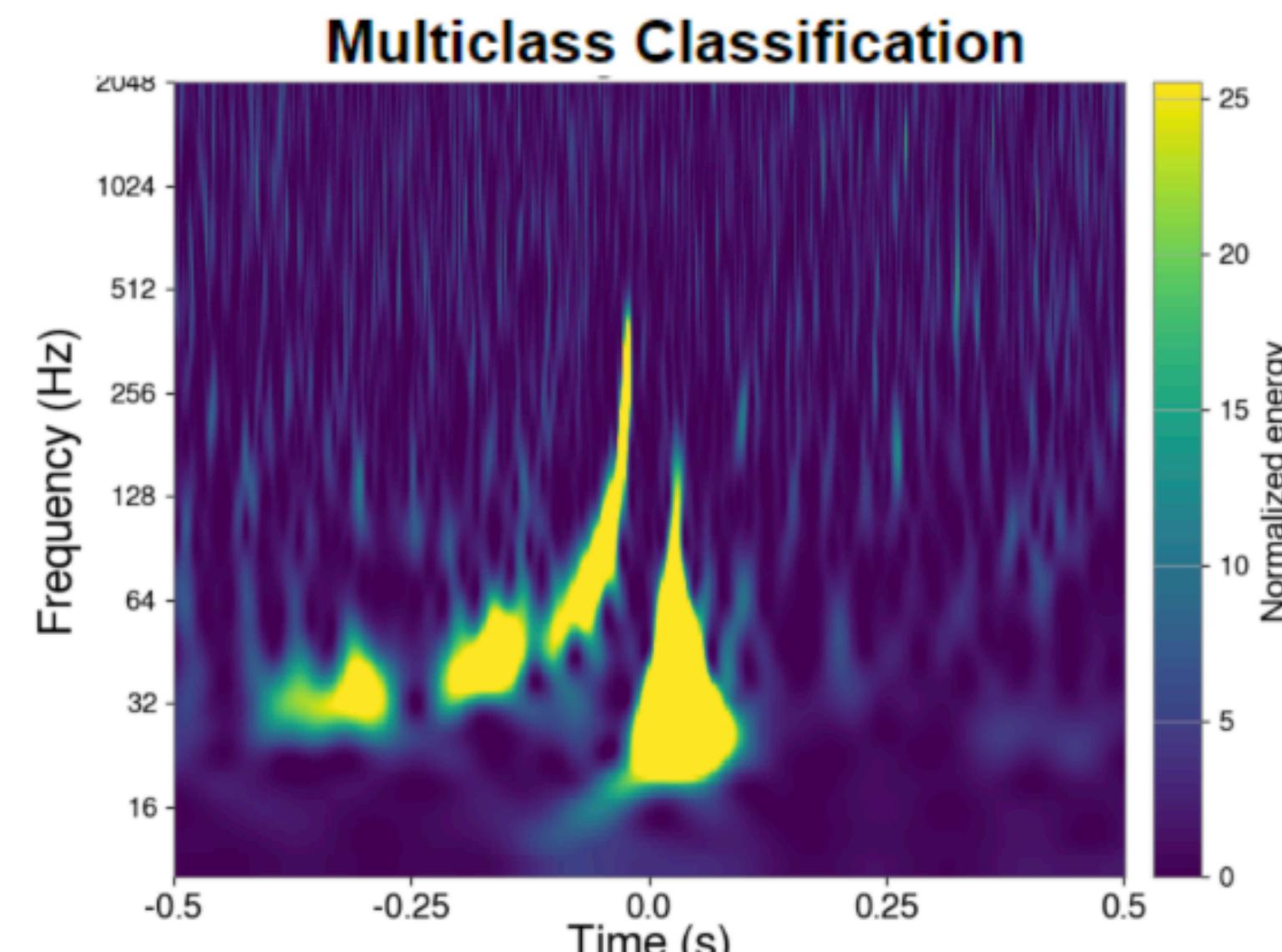
- May lead to unnecessarily vetoed candidates.
- Needs to be addressed! Happened in **24% of O3 candidates**, and has happened in O4.

Is Gravity Spy's multi-class architecture sufficient?



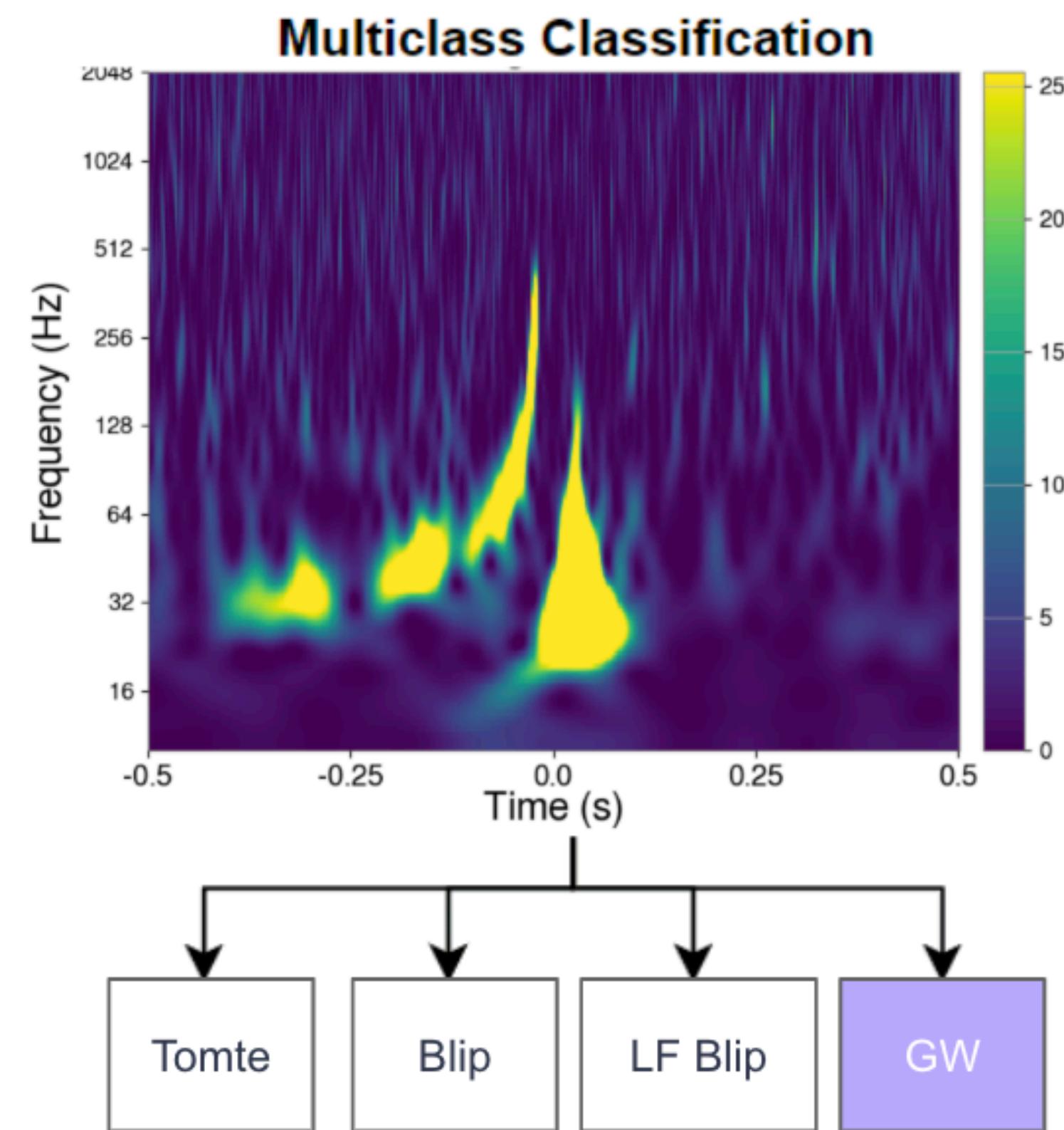
↓ ↓ ↓ ↓

Is Gravity Spy's multi-class architecture sufficient?

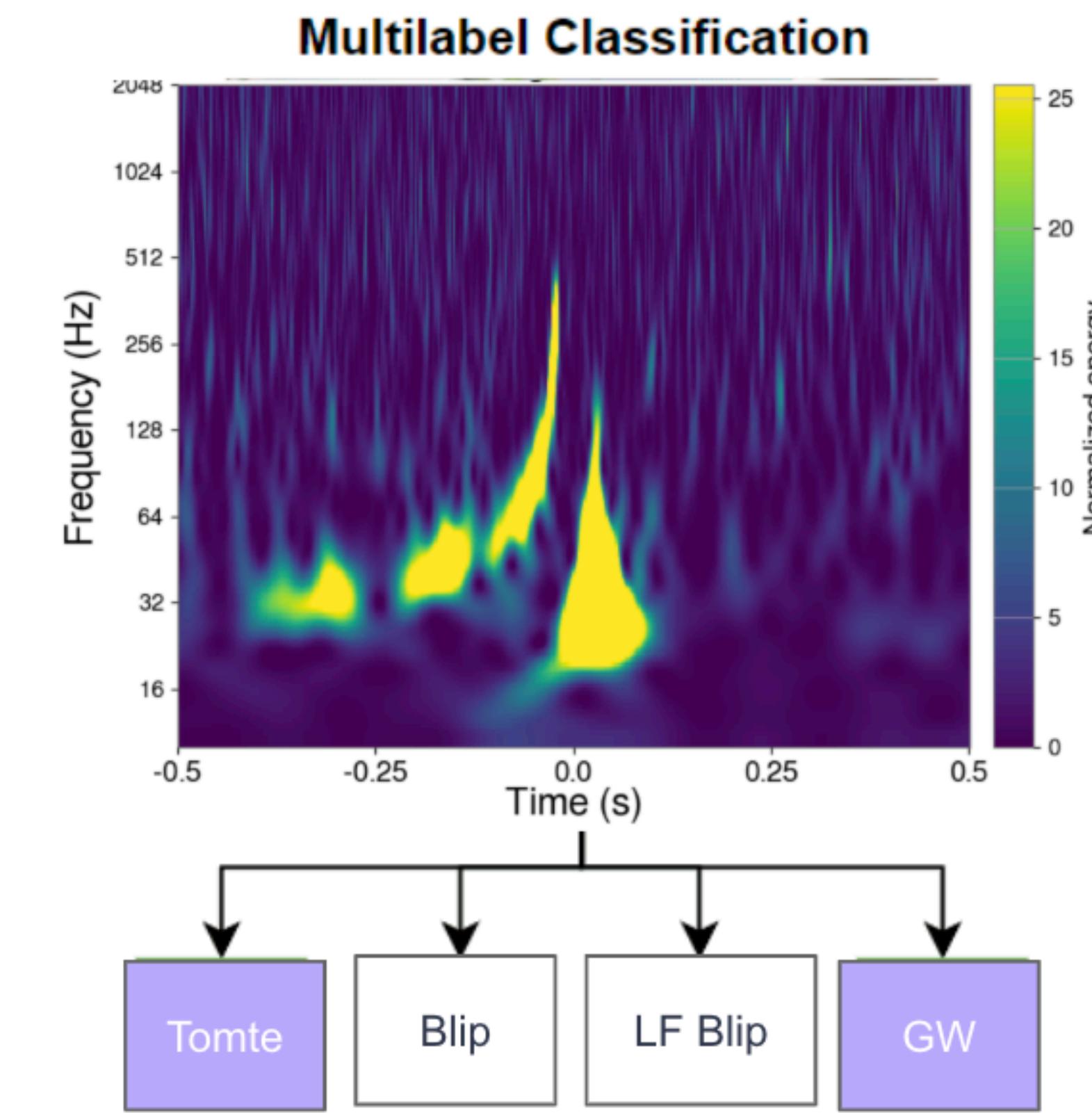


CNN can only output one class
(Tomte class is ignored)

Use a multilabel architecture instead!

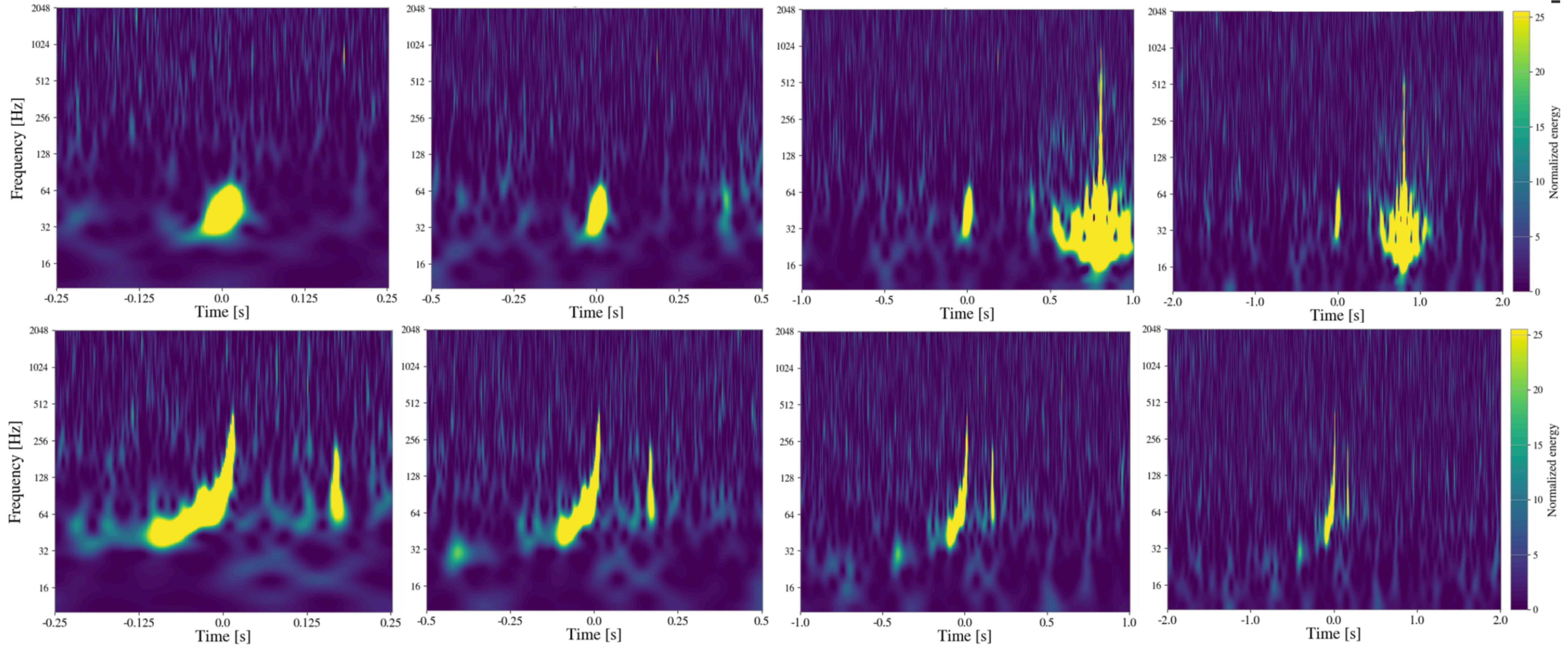


CNN can only output one class
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CNN may predict 0+ classes.

Making GSpyNetTree robust to overlapping samples of GWs and glitches



What considerations should we take into account when building a signal-vs-glitch classifier?

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Three separate classifiers sorted via candidate mass

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Include most common glitches during O3/ER15.



1.2

- How to account for short/long morphologies?

Consider spectrograms of 4 different durations.



2.

- Glitch rate is about ~1/minute

What considerations should we take into account when building a signal-vs-glitch classifier?

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3.

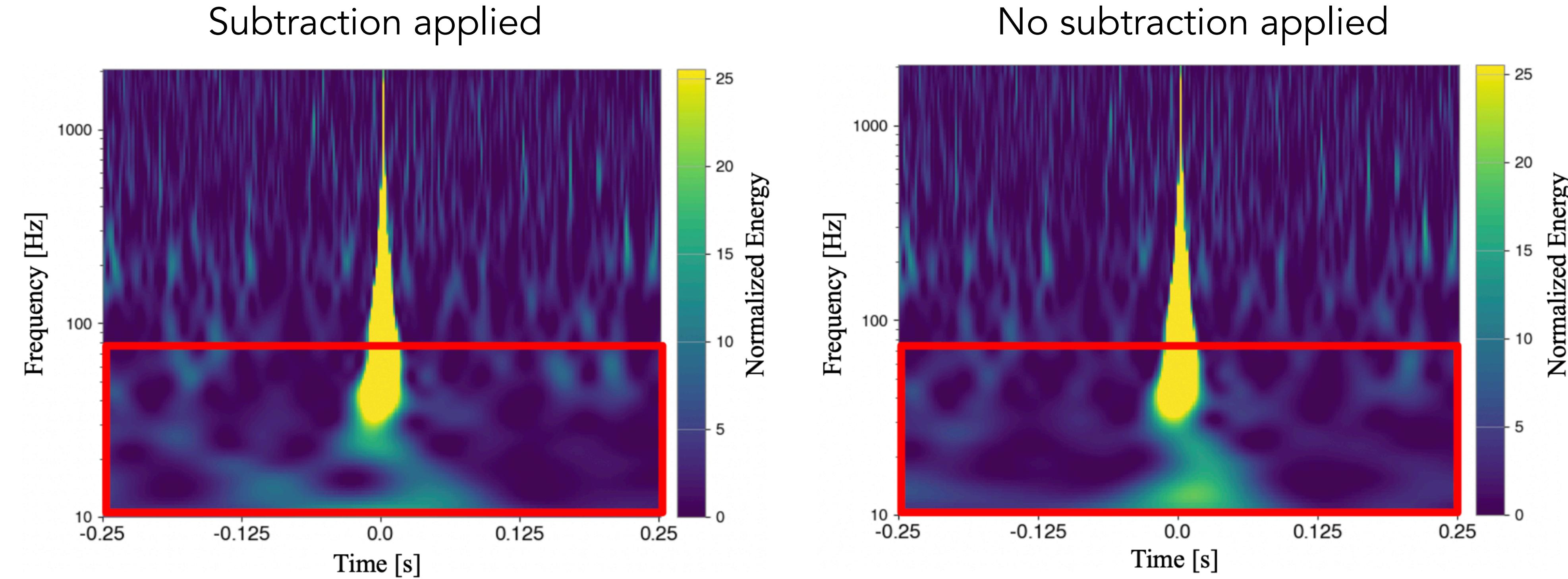
- Effect of (changes in) background noise in spectrogram classification.

3. Effect of (changes in) background noise in spectrogram classification.

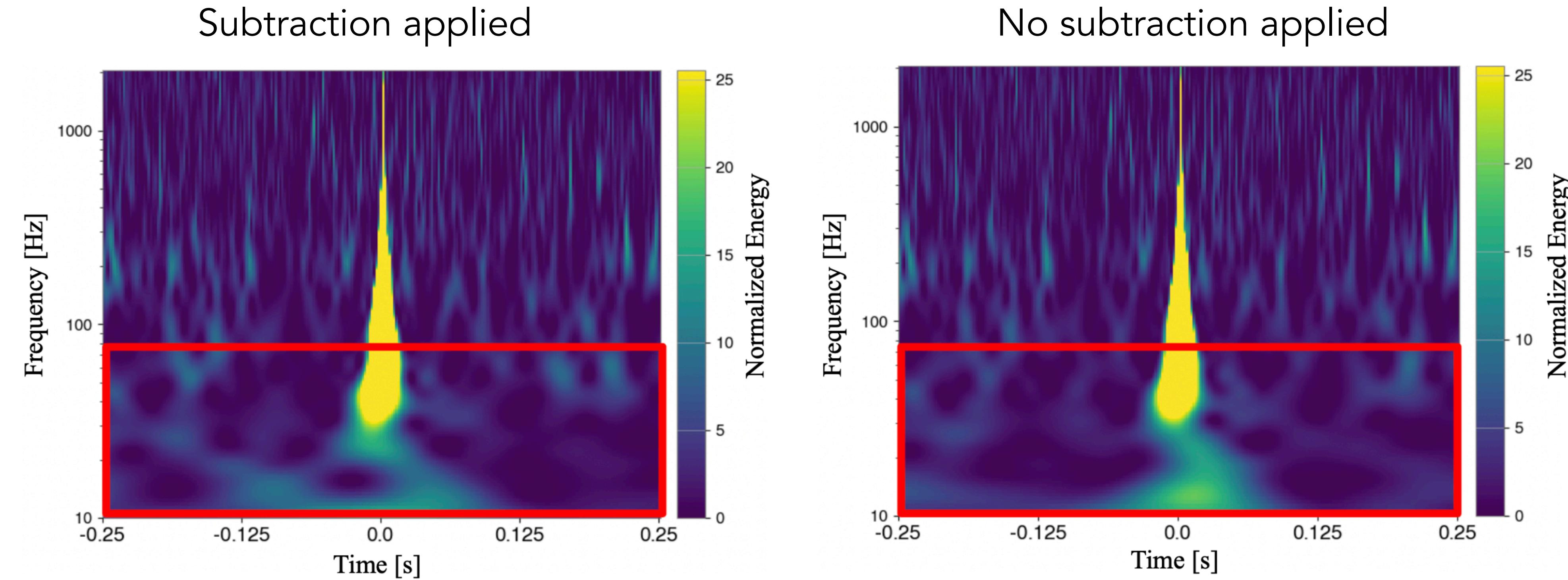
What is the problem?

- Background noise changes from one observing run to another (due to new calibrations in the detectors).
- Background noise also changes between interferometers.

We expected O4 low-latency data to apply a non-linear subtraction of 60 Hz power artifacts.



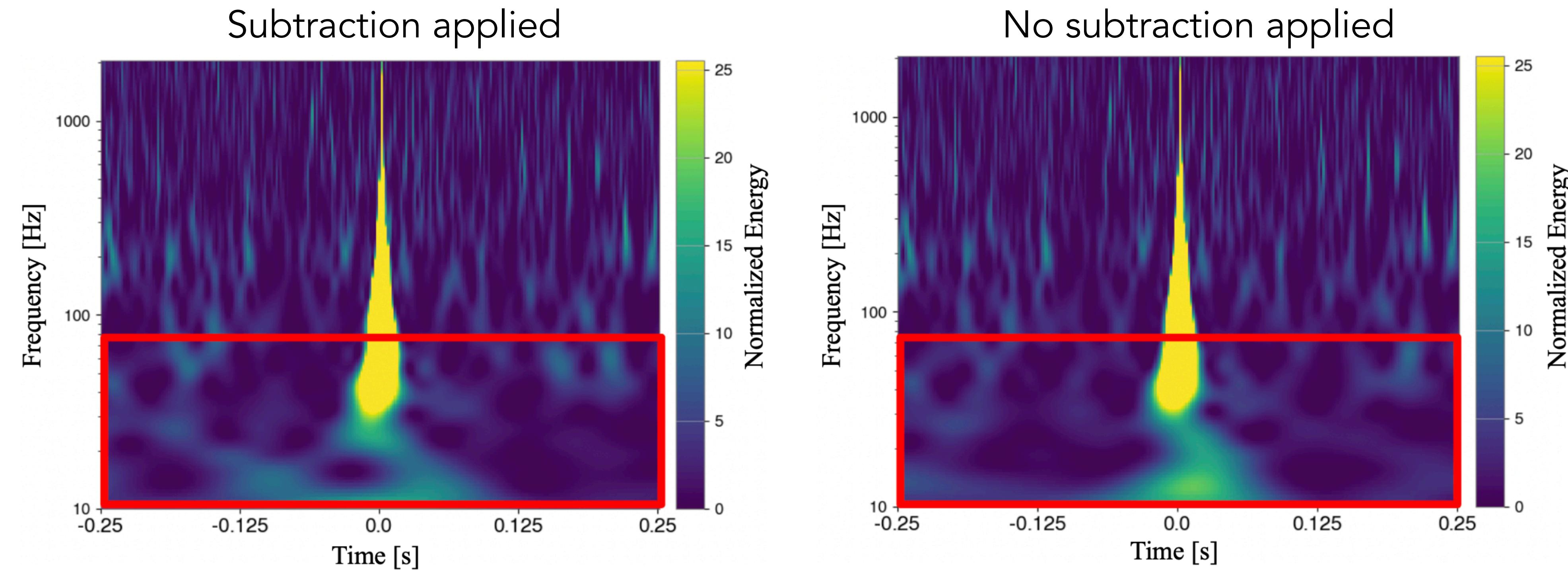
We expected O4 low-latency data to apply a non-linear subtraction of 60 Hz power artifacts.



We did an experiment:

If GSpyNetTree is trained on right-like samples,
how accurate are its predictions on left-like
samples?

We expected O4 low-latency data to apply a non-linear subtraction of 60 Hz power artifacts.



We did an experiment:

If GSpyNetTree is trained on left-like samples, how accurate are its predictions on right-like samples?



When tested on these glitches, the pre-O4 version of GSpyNetTree reduced its glitch classification accuracy in ~20%

Part of the solution

- GSpyNetTree is really sensitive in changes in background noise.
- O4 GSpyNetTree includes data for both LIGO detectors using “normal” data and data applying the non-linear subtraction of 60 Hz AC power artifacts, to be robust to a broad array of noise.
- We also include Virgo glitches, but Virgo does not implement this subtraction.



Although we get great results in this version of GSpyNetTree... is this enough for the future?

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Include most common glitches during O3/ER15.

1.2

- How to account for short/long morphologies?



Consider spectrograms of 4 different durations.

2.

- As detectors become more sensitive, glitches become more common.



3.

- Effect of (changes in) background noise in spectrogram classification.

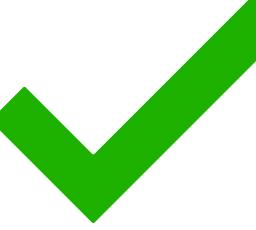


Building a training set

A training set must be:

- Robust
- Balanced
- Hopefully large
- Should also apply data augmentation techniques

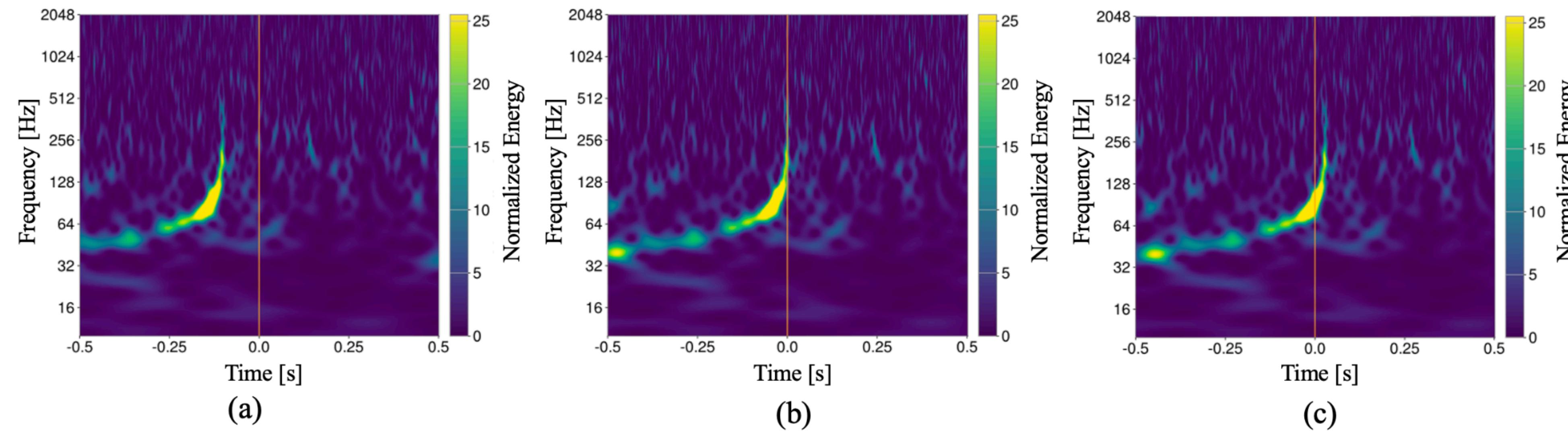
A training set must be:

- Robust 
- Balanced* 
- Hopefully large 
- Should also apply data augmentation techniques 

*The Low-frequency Lines class is underrepresented, as we could only manually verify ~300 samples before O4 started.

Making GSpyNetTree robust to candidate events not centered in $t = 0$ s.

- Including 4 extra time offsets (± 0.5 s).
- Data augmentation has proven useful for CNNs to generalize on a training set and avoid over-fitting.



Augmenting the training set

Results

Some key points

- For the purpose of GSpyNetTree, the most important thing is to **detect a glitch responsible for or in the presence of a GW**.

Some key points

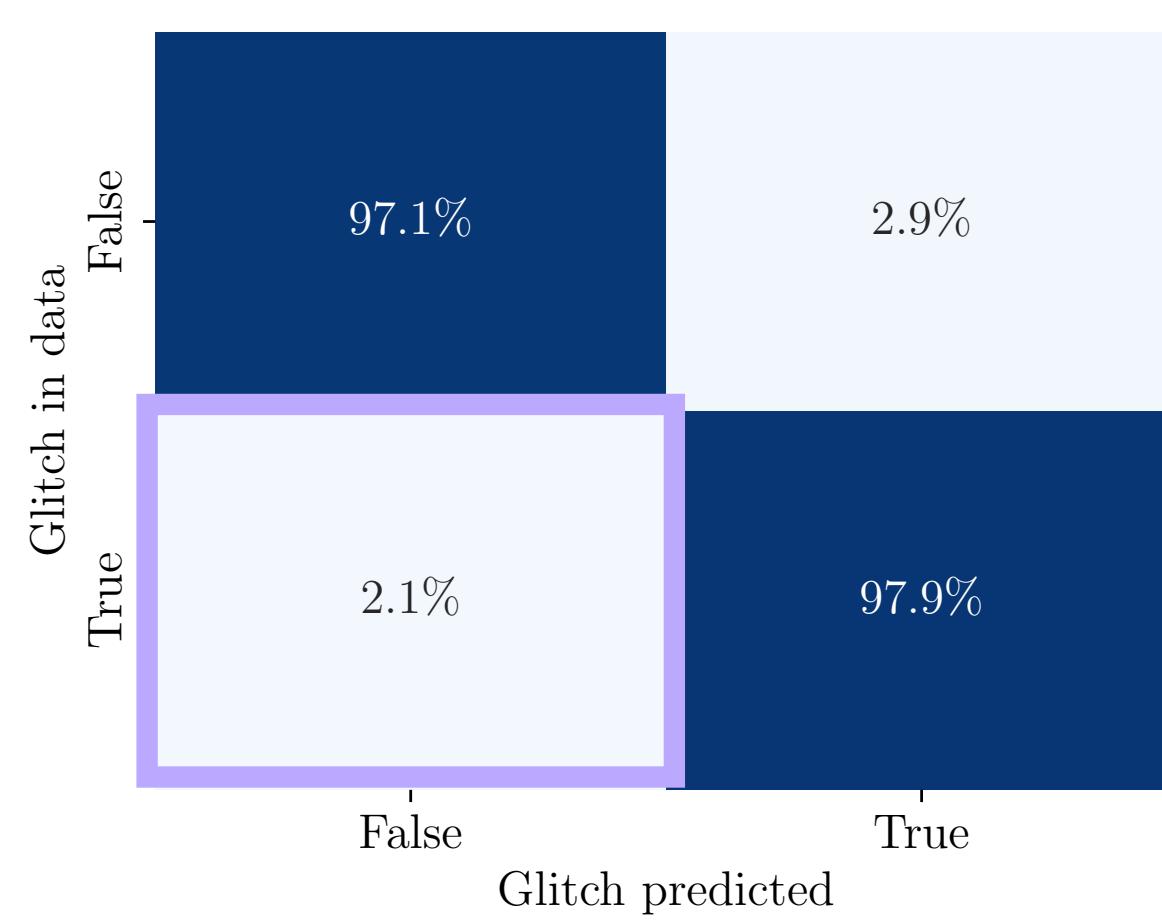
- For the purpose of GSpyNetTree, the most important thing is to **detect a glitch responsible for or in the presence of a GW**.
 - While not desirable, a glitch misclassified as another type of glitch is okay.
 - While not desirable, a GW misclassified as No Glitch is okay. Both cases mean no Data Quality issue was identified.

Some key points

- For the purpose of GSpyNetTree, the most important thing is to **detect a glitch responsible for or in the presence of a GW**.
 - While not desirable, a glitch misclassified as another type of glitch is okay.
 - While not desirable, a GW misclassified as No Glitch is okay. Both cases mean no Data Quality issue was identified.
- Worst case is:
 - **Glitch misclassified as GW/No Glitch (Data Quality issue missed)**.
 - **False positive glitch (Glitch was not there but GSpyNetTree found one)**.

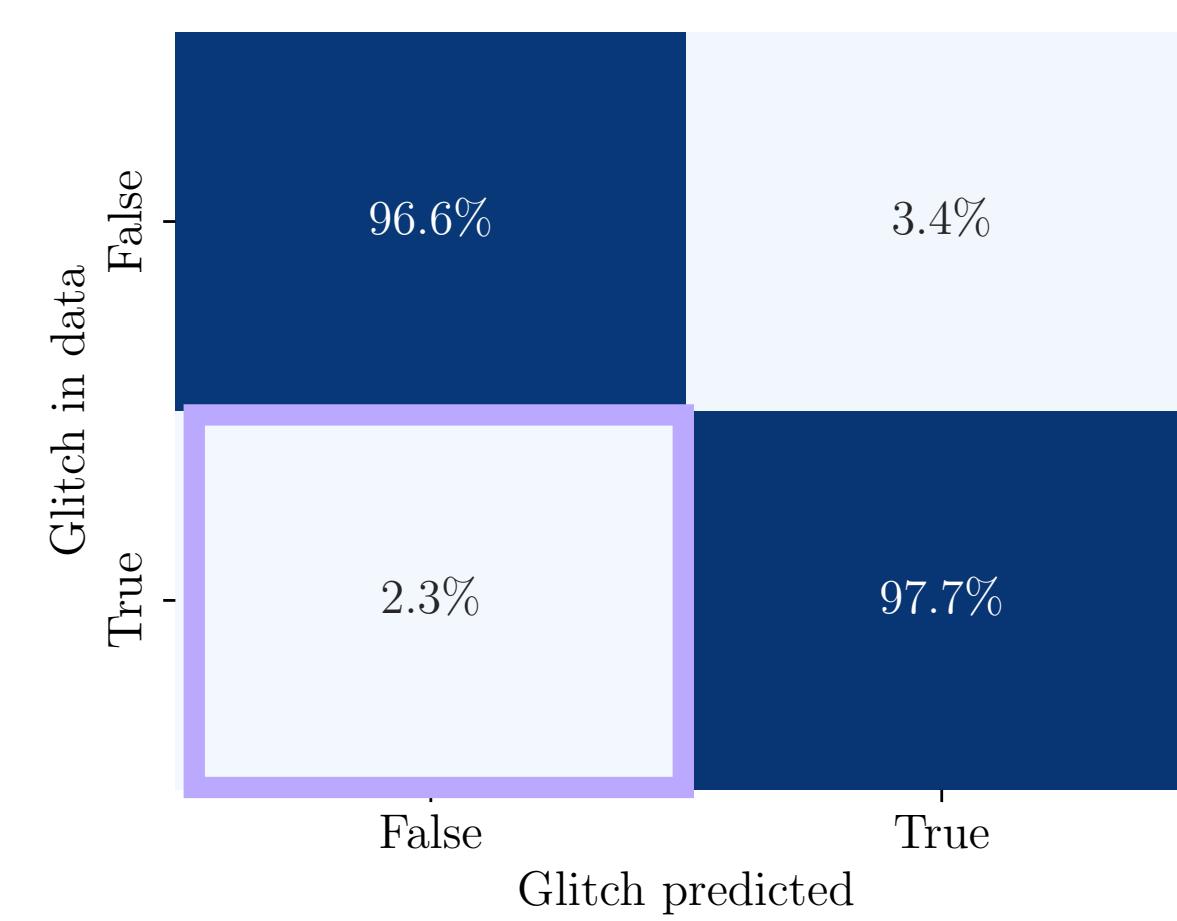
Results on test data for glitches per classifier (using recall)

LM Classifier



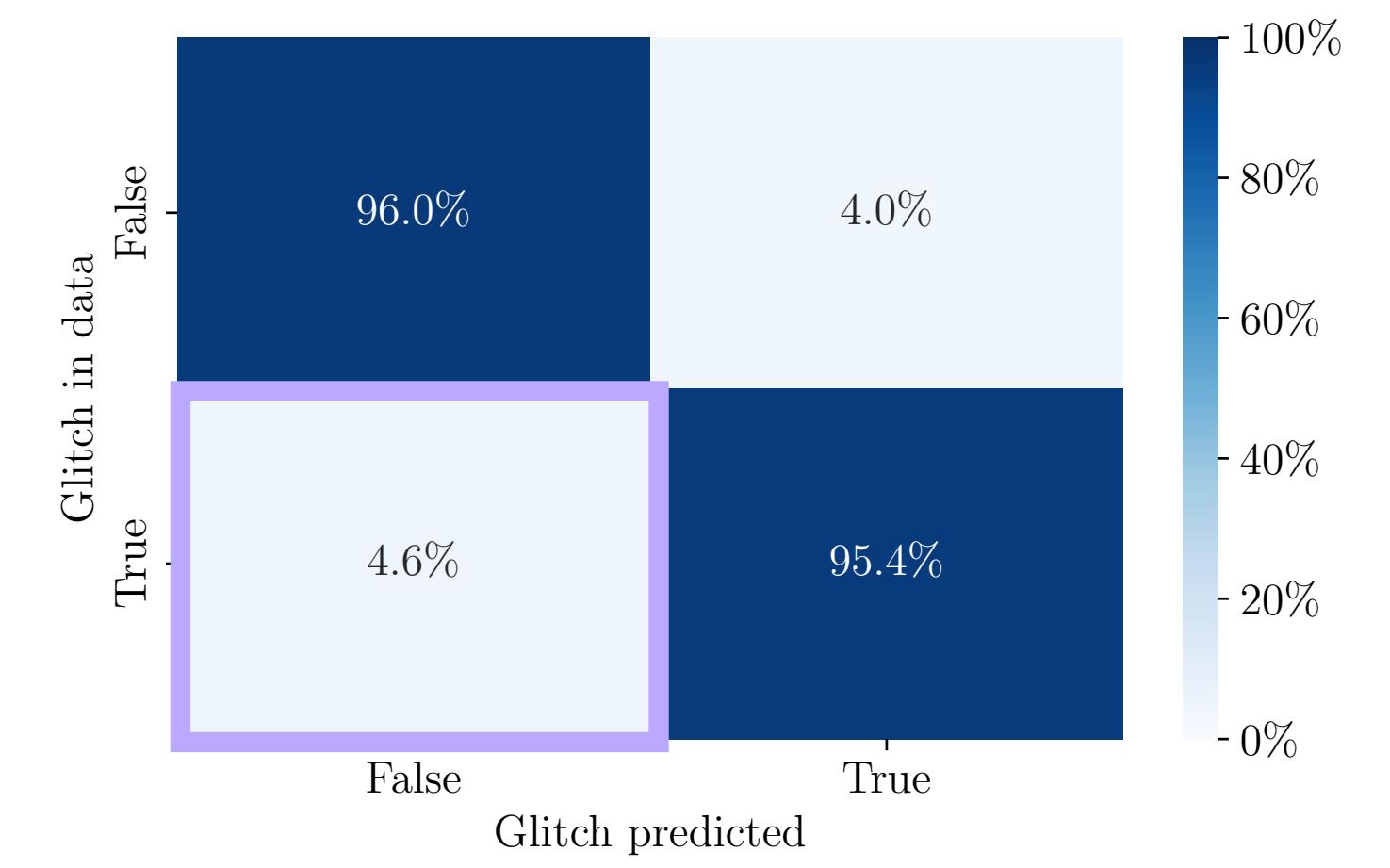
Only 2.1% of glitches are missed

HM Classifier



Only 2.3% of glitches are missed

EHM Classifier



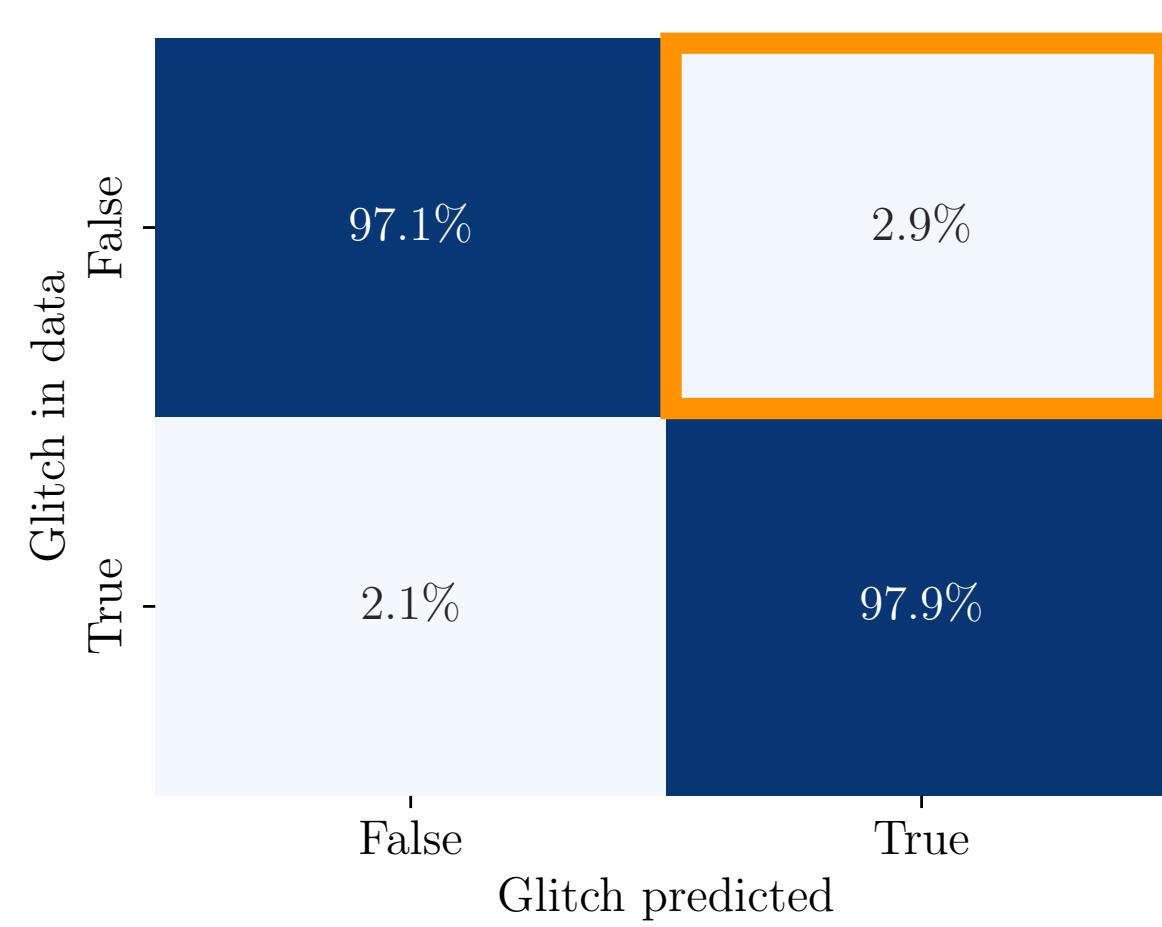
Only 4.6% of glitches are missed



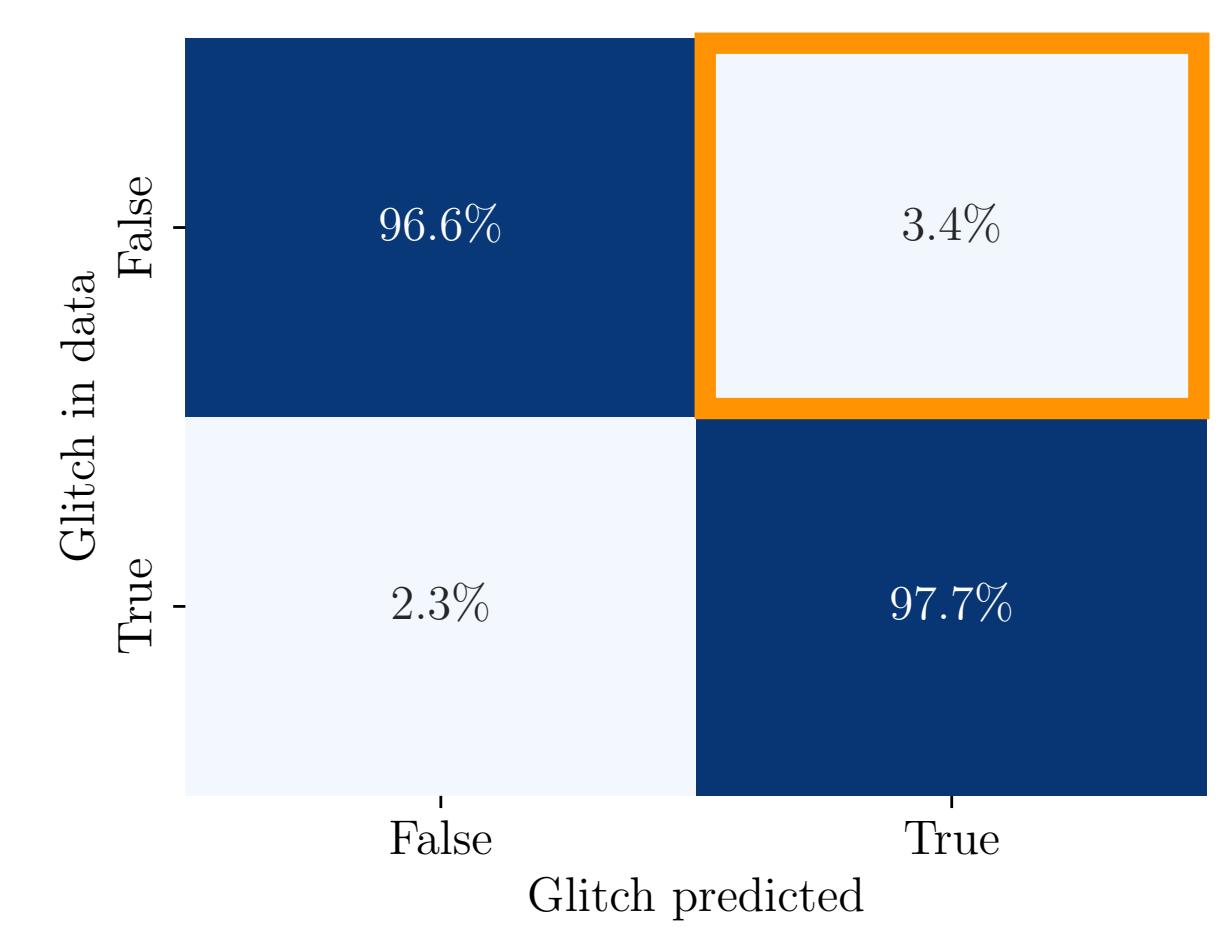
In general, all three classifiers detect a high rate of glitches (>96%).

Results on test data for glitches per classifier (using recall)

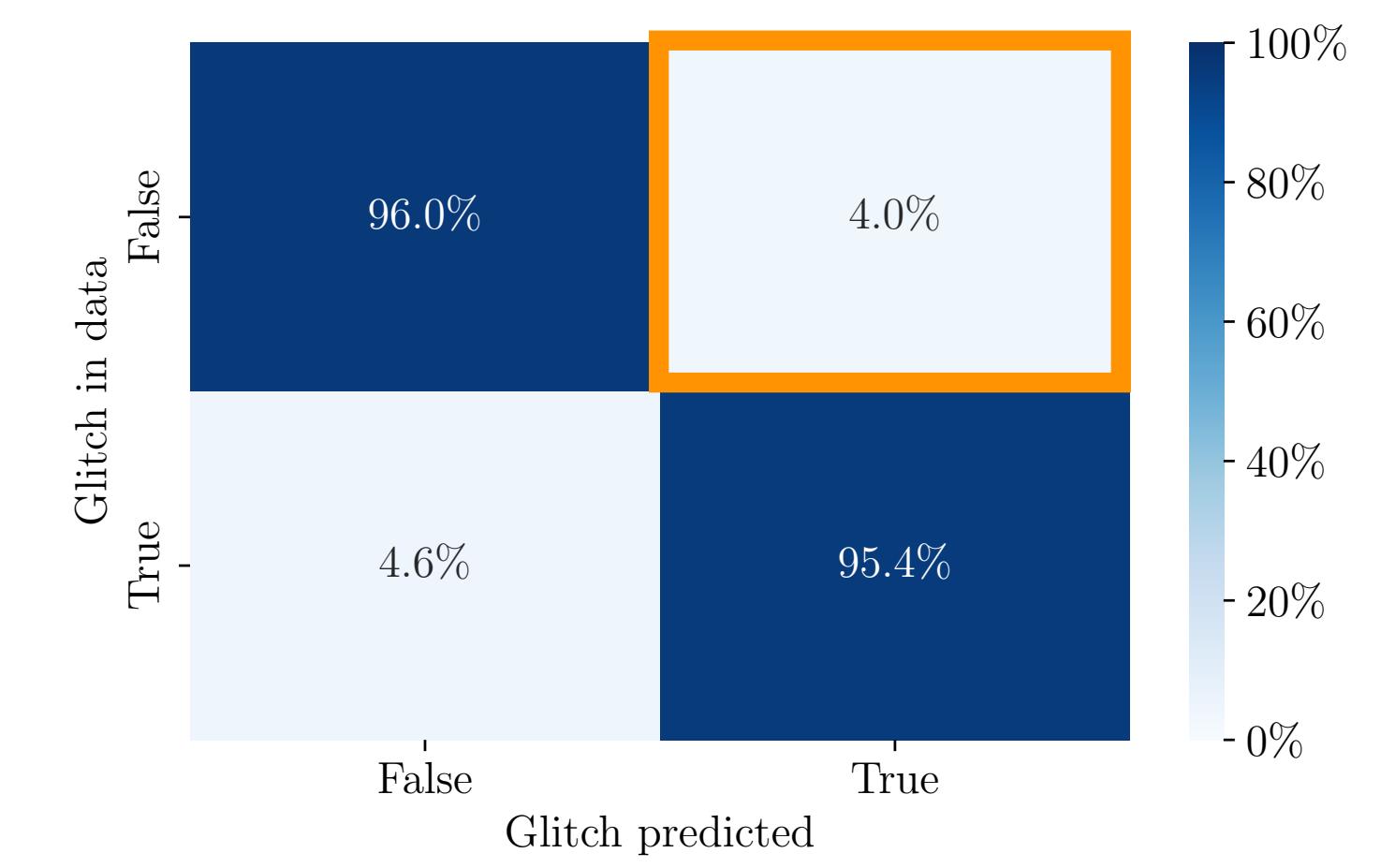
LM Classifier



HM Classifier



EHM Classifier



Only 2.1% of glitches are missed
False alarm glitch rate: 2.9%

Only 2.3% of glitches are missed
False alarm glitch rate: 3.4%

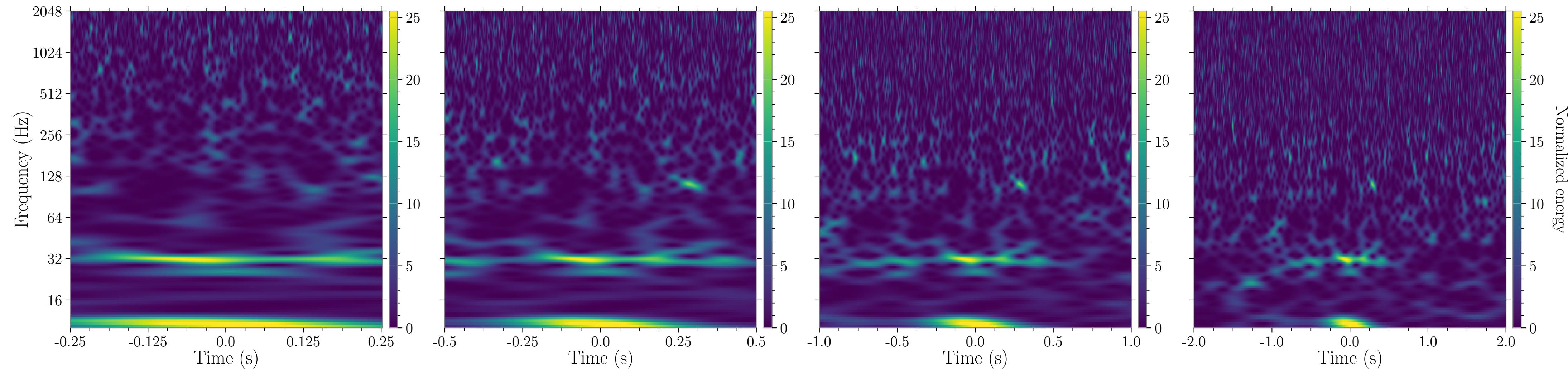
Only 4.6% of glitches are missed
False alarm glitch rate: 4.0%



The false alarm is low, which makes GSpyNetTree's classifications reliable.

Other interesting results

- Due to its multilabel nature, GSpyNetTree can predict two or more glitches in an individual sample, even if it was not trained on them.
- The following sample was classified by the EHM classifier as Light Scattering ($f \approx 32$ Hz)+Low-frequency Lines ($f \approx 12$ Hz), while the original Gravity Spy classification was only Light Scattering.



Brief comment on O4a results

Some key points

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- All GSpyNetTree glitch detections were subsequently validated by 5-minute and 1-hour tier DQR tasks.
- GSpyNetTree correctly detected glitches in five of the six retracted events due to DQ issues in O4a.

More than one O4 candidate associated with glitches in close proximity of GWs

S230708t

S230708t is an event of interest because its false alarm rate, as estimated by the online analysis, is $4.3\text{e}{-8}$ Hz, or about one in 8 months. The event's properties can be found at this URL:

<https://gracedb.ligo.org/superevents/S230708t>

The classification of the GW signal, in order of descending probability, is BBH (97%), Terrestrial (3%), NSBH (<1%), or BNS (<1%).

There was a high rate of noise transients (glitches) in the LIGO Hanford detector which may affect the parameters or the significance of the candidate.

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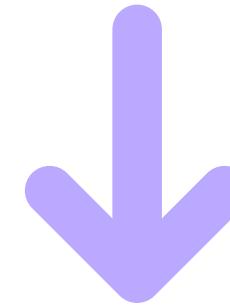
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These glitches detected by GSpyNetTree!

Shows full potential of multi-label architecture!

GSpyNetTree is only part of the
solution

1. What happens when we test
GSpyNetTree on Gravity Spy glitches
not included in the original training set?

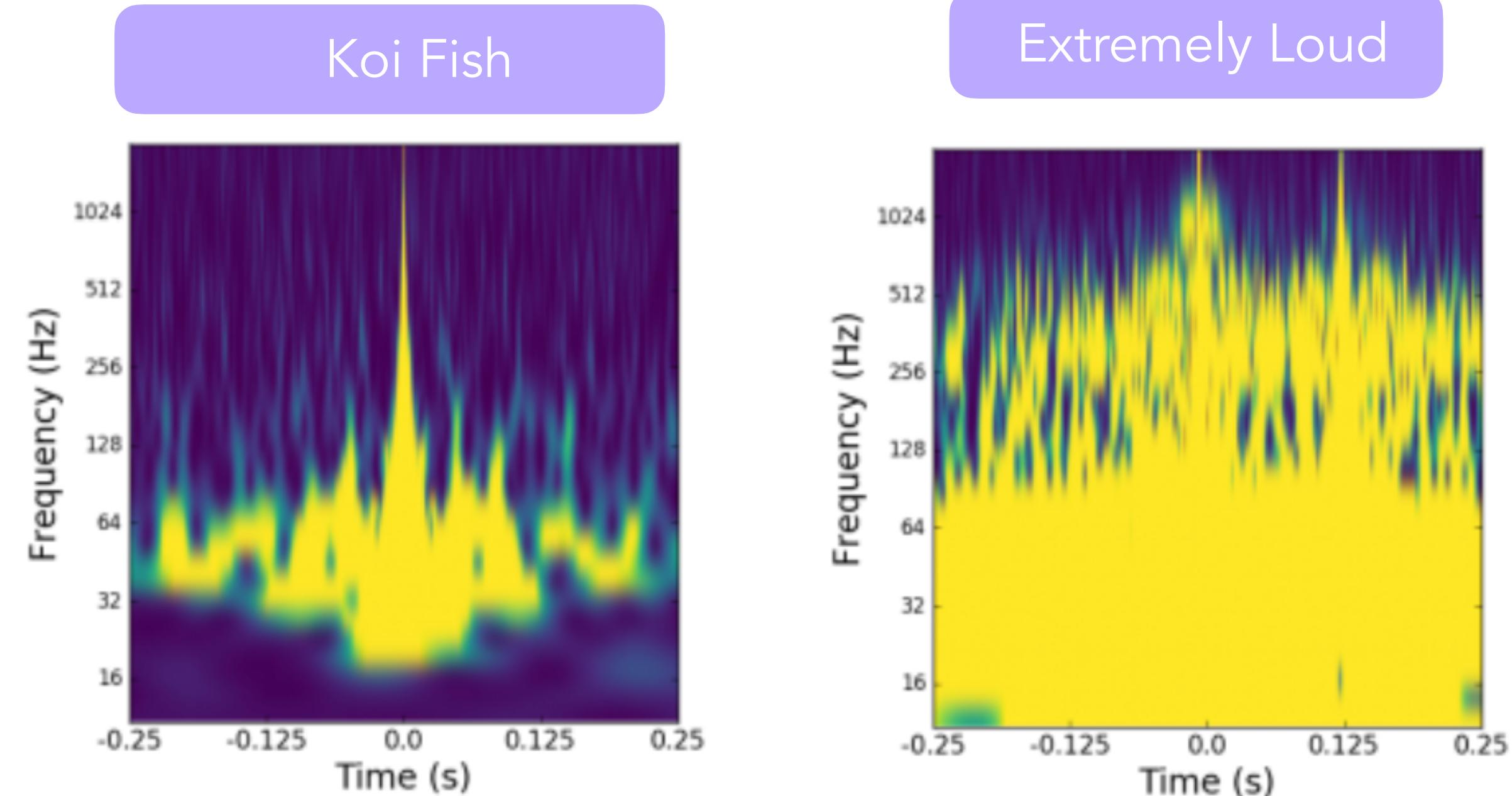
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Extremely loud glitches are morphologically similar to Koi Fish glitches (both are very loud): more than 98% accurate classifications.



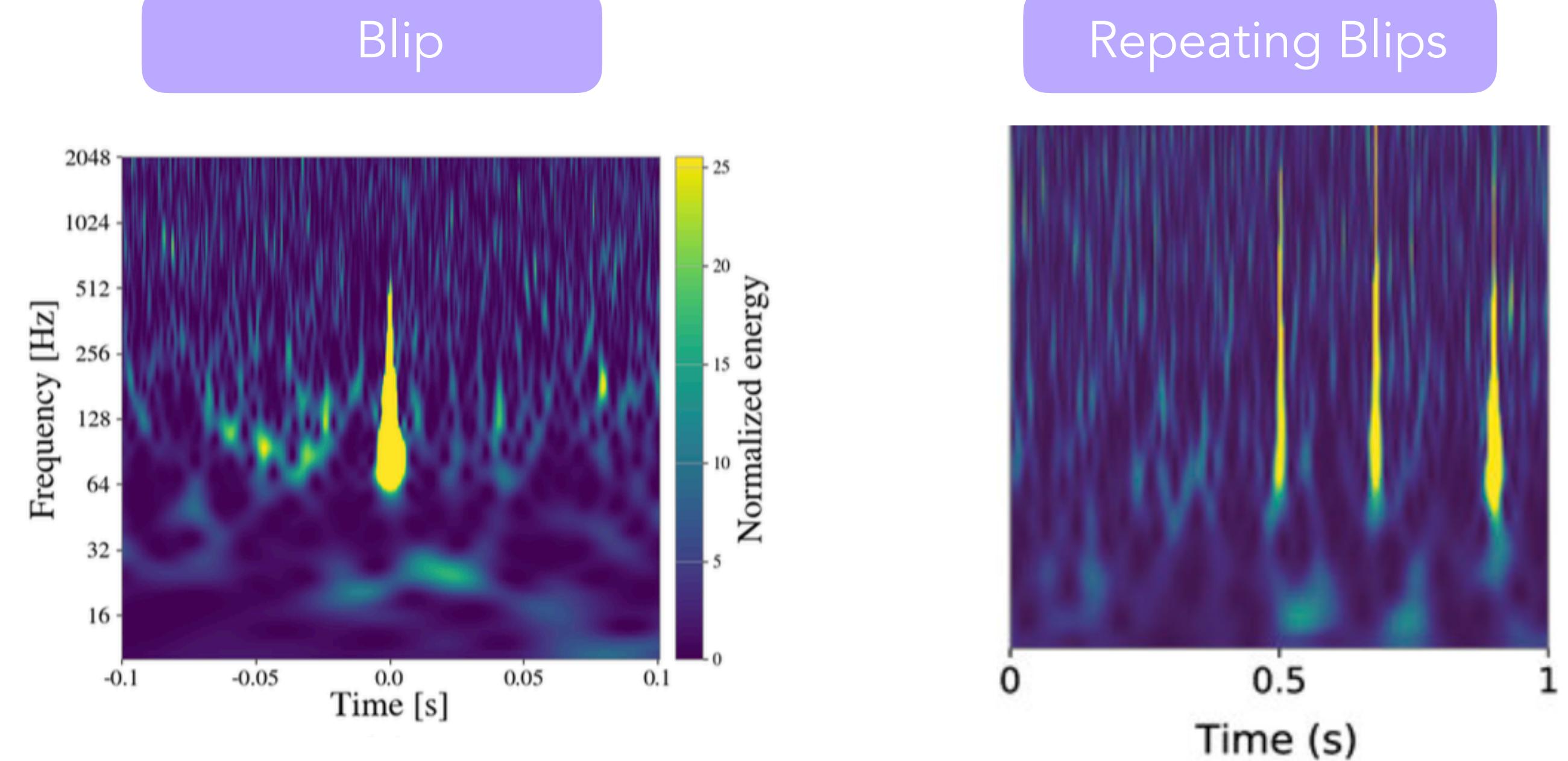
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96% accurate glitch identification
(but in a significant number of samples, one (or more) of the power artifacts mistaken as GW).



How to identify multiple occurrences of the same glitch without flagging one of them as a GW?



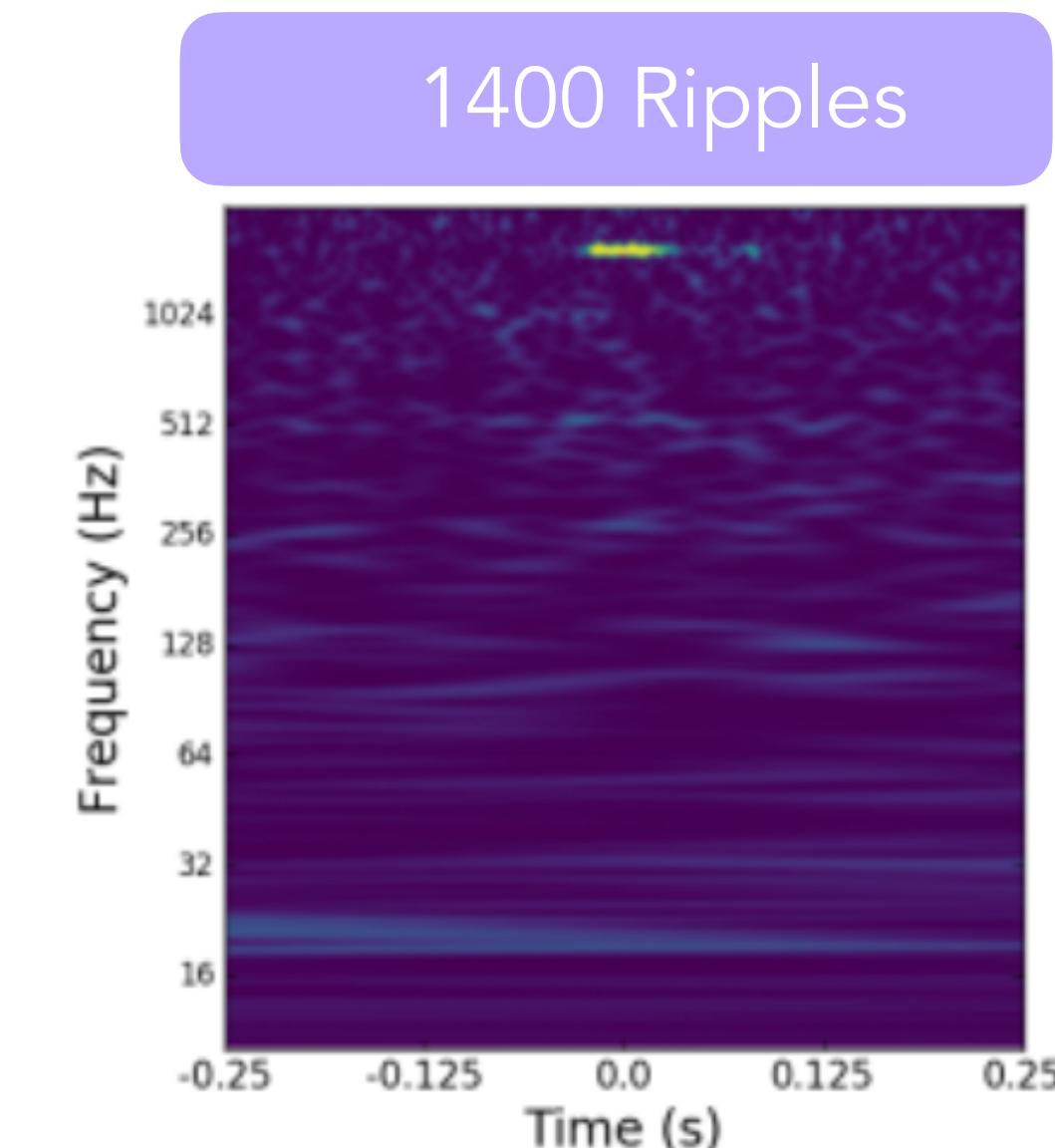
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- Poor identification of high-frequency glitches:
GSpyNetTree does not include any high frequency glitches.



How to identify types of glitches not originally included in the training set without increasing the number of classes?



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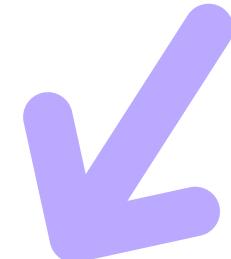


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But building the training sets requires a lot of person power.



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Future work: looking towards O5

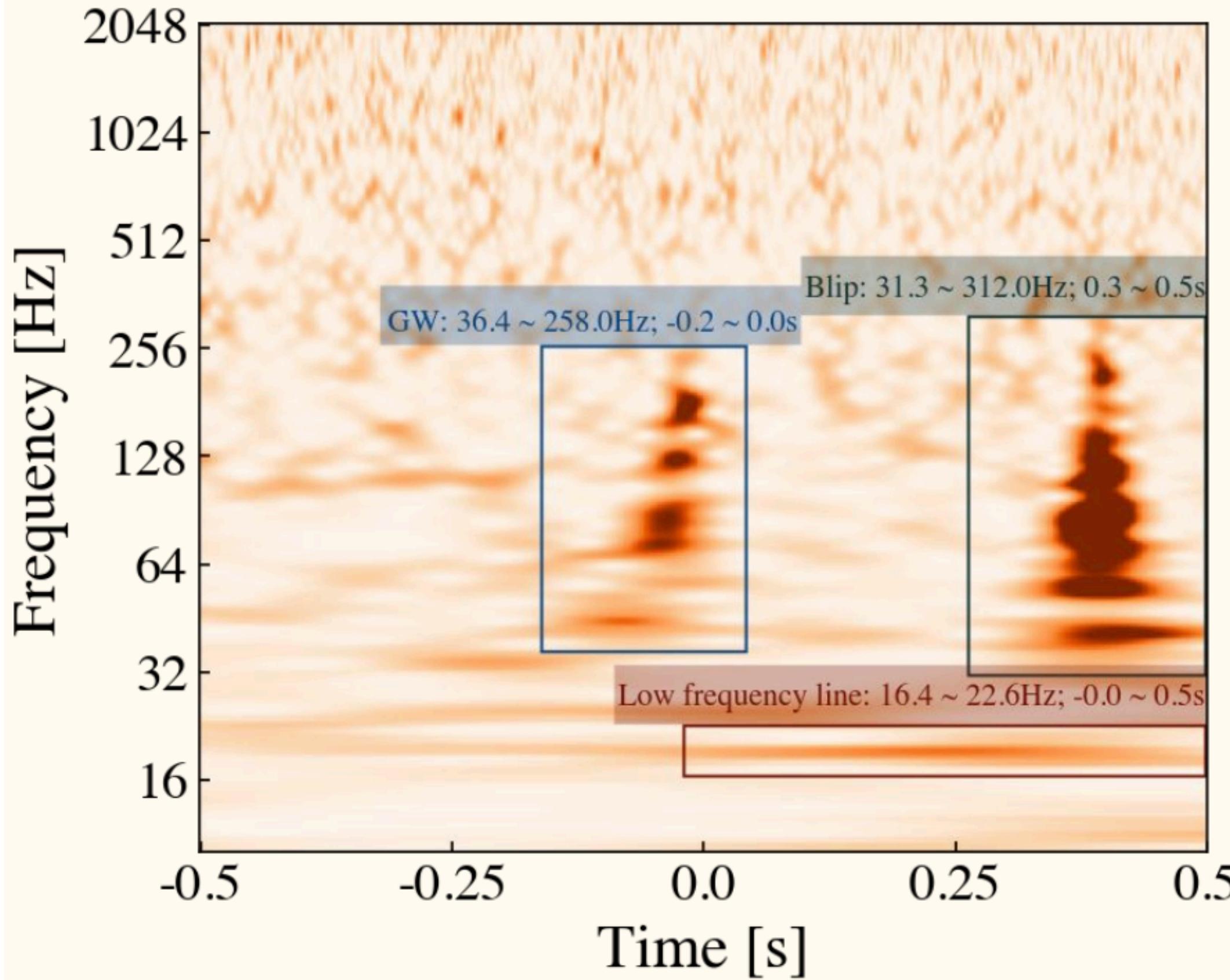
How can we improve GSpyNetTree?

- GSpyNetTree is an ensemble of CNNs:
 - Uncertainty on output is hard to quantify.
 - Tend to be overconfident.
 - Possibility to extend to make Bayesian CNNs instead (currently led by Shreeja Bandyadhyay @ UBC).
- GSpyNetTree-S (Chan+25, in prep.)

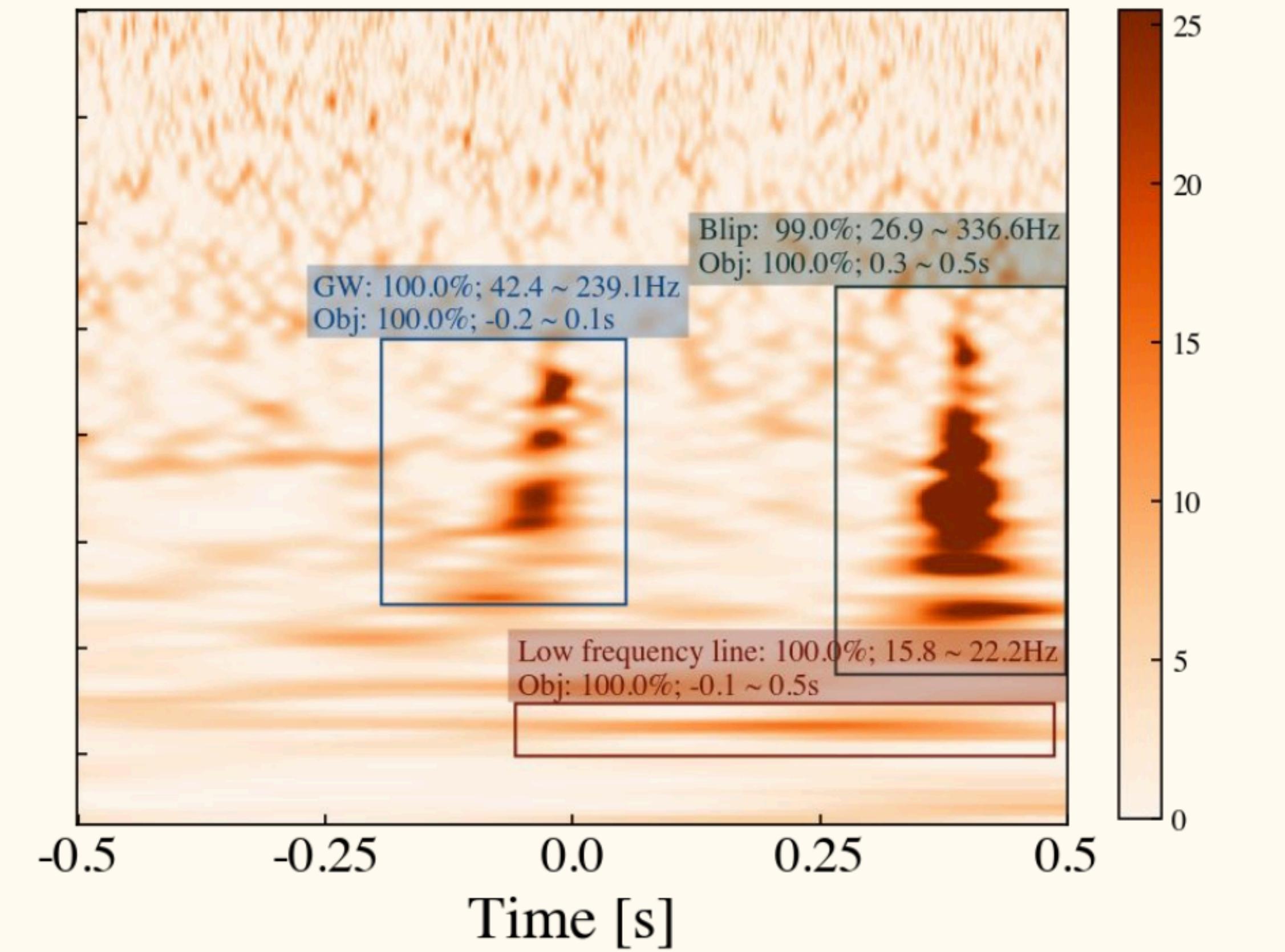
Performance: IoU visualization



Ground truth - three regions of power excess



GSpyNetTreeS - three regions of power excess predicted



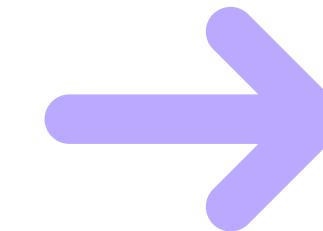
[https://dcc.ligo.org/DocDB/0196/
G2401842/001/GSpyNetTreeS.pdf](https://dcc.ligo.org/DocDB/0196/G2401842/001/GSpyNetTreeS.pdf)

GSpyNetTree has been a very successful tool during O4!

Some open questions



Building training sets requires a lot of person power... is it time to evolve from supervised learning?



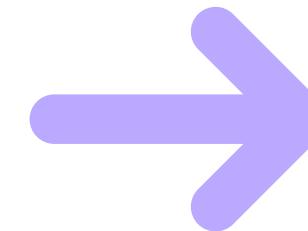
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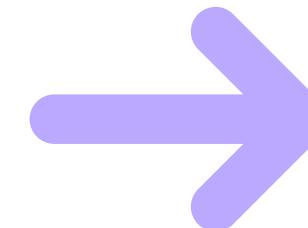
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How to automate the event validation process? (Especially in the future with higher event rate)?



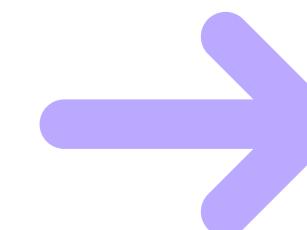
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GSpyNetTree has been a very successful tool during O4!

Some questions to make our tool even more robust for future observing runs...



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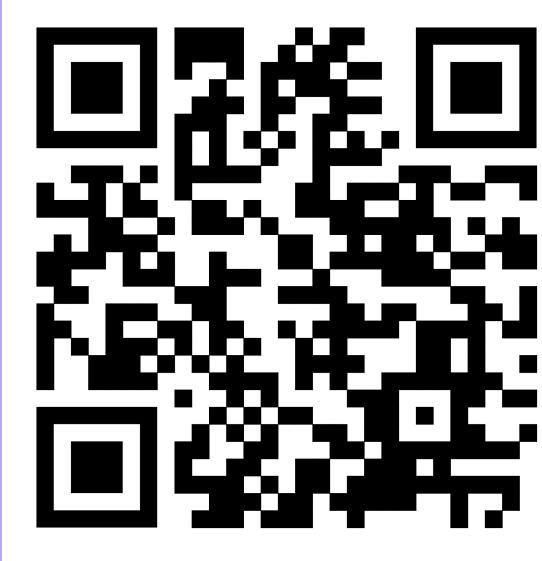


Are spectrograms our best way to do signal-vs-glitch classification? Do we have anything better?



How to identify multiple occurrences of the same glitch without flagging one of them as a GW?

We need your help to improve signal-vs-glitch classification!



<https://iopscience.iop.org/article/10.1088/1361-6382/ad2194>

<https://dcc.ligo.org/P2500368>

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