



(A VERY BRIEF) INTRODUCTION TO NUMERICAL RELATIVITY



MPAGS: BLACK HOLES AND GRAVITATIONAL WAVES - PART 3

LECTURER: DR PATRICIA SCHMIDT

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RECAP:

- ▶ Introduced foliation-adapted coordinates

- ▶ Constraint equations:

$${}^{(3)}R + K^2 - K_{ij}K^{ij} = 16\pi\rho$$

$$D_j(K^{ij} - \gamma^{ij}K) = 8\pi S^i$$

- ▶ Evolution equations:

$$\partial_t\gamma_{ij} = -2\alpha K_{ij} + D_i\beta_j + D_j\beta_i$$

$$\partial_t K_{ij} = -D_i D_j \alpha + \alpha \left(R_{ij} + K K_{ij} - 2K_{ik}K_j^k + 4\pi[(S - \rho)\gamma_{ij} - 2S_{ij}] \right)$$

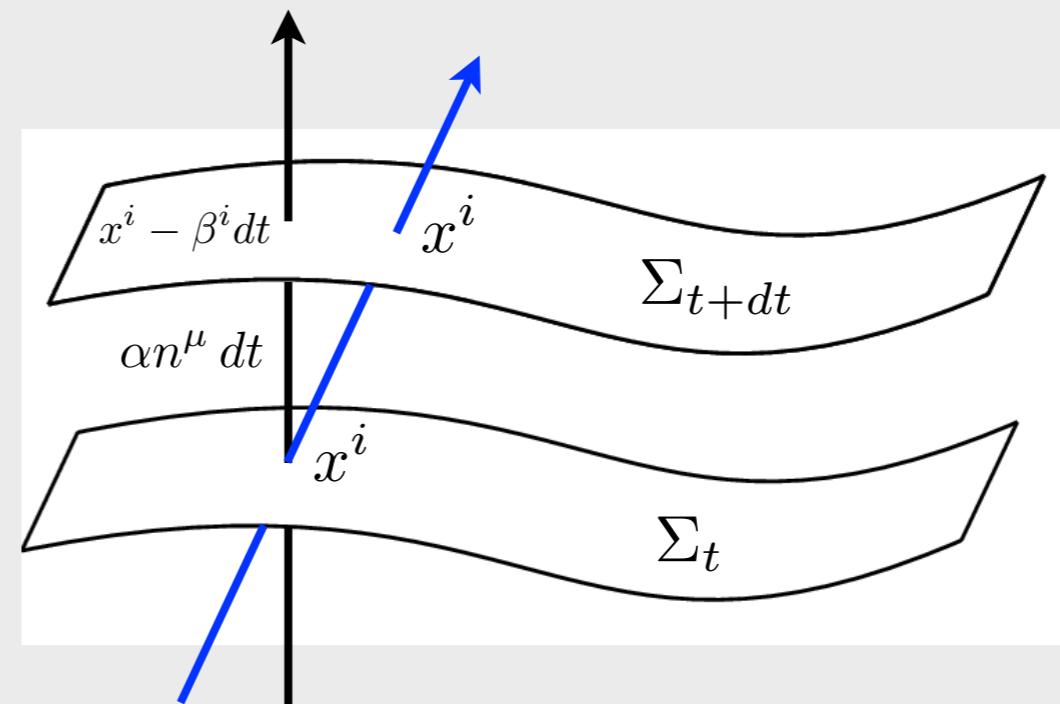
$$+ \beta^k D_k K_{ij} + K_{ik} D_j \beta^k + K_{kj} D_i \beta^k$$

- ▶ Initial data: conformal transverse-traceless vs conformal thin sandwich
- ▶ Gauge choices

GEODESIC SLICING

- ▶ Simplest possible choice:

$$\alpha = 1, \quad \beta^i = 0$$



- ▶ Coordinate observers coincide with normal observers
- ▶ Normal observers are freely falling ($a_\mu = 0$) and hence follow geodesics
- ▶ Unfortunately, coordinate singularities develop very quickly as geodesics focus near gravitating sources, which can be seen from the expansion:

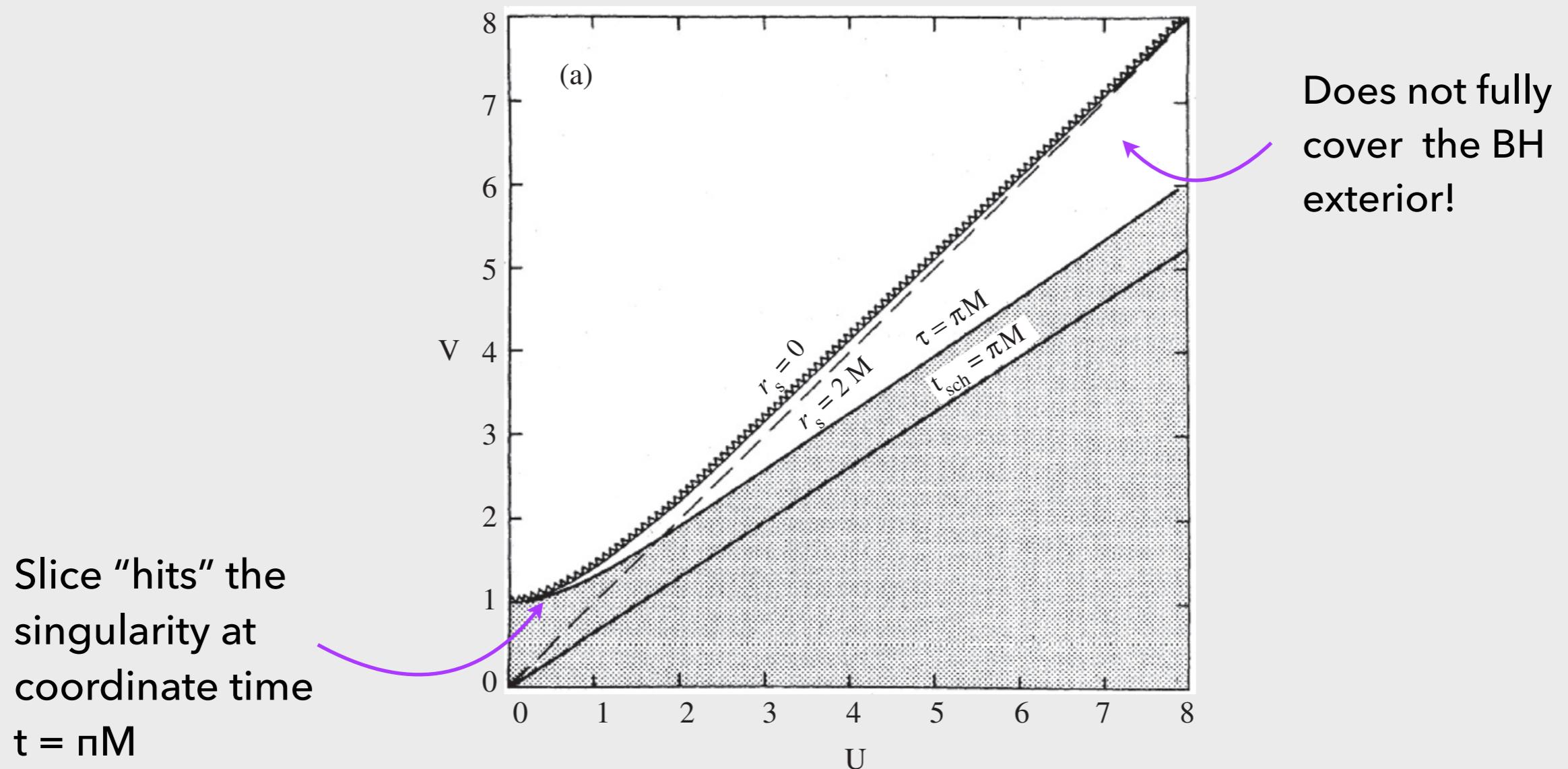
$$\nabla_\mu n^\mu = -K$$

K grows monotonically in time

$$\partial_t K \geq 0$$

GEODESIC SLICING

- ▶ Example: Schwarzschild spacetime (in Kruskal coordinates U,V)



Taken from Baumgarte & Shapiro, Numerical Relativity

MAXIMAL SLICING

- ▶ To control the divergence of normal observers, we need to impose a suitable condition on K
- ▶ A common choice is “maximal” slicing (for all times),

$$K = 0 = \partial_t K$$

- ▶ Maximal slicing is volume preserving along congruences of n^μ
- ▶ From the contraction of the evolution equation for K_{ij} , we find:

$$D^2\alpha = \alpha(K_{ij}K^{ij} + 4\pi(\rho - S))$$

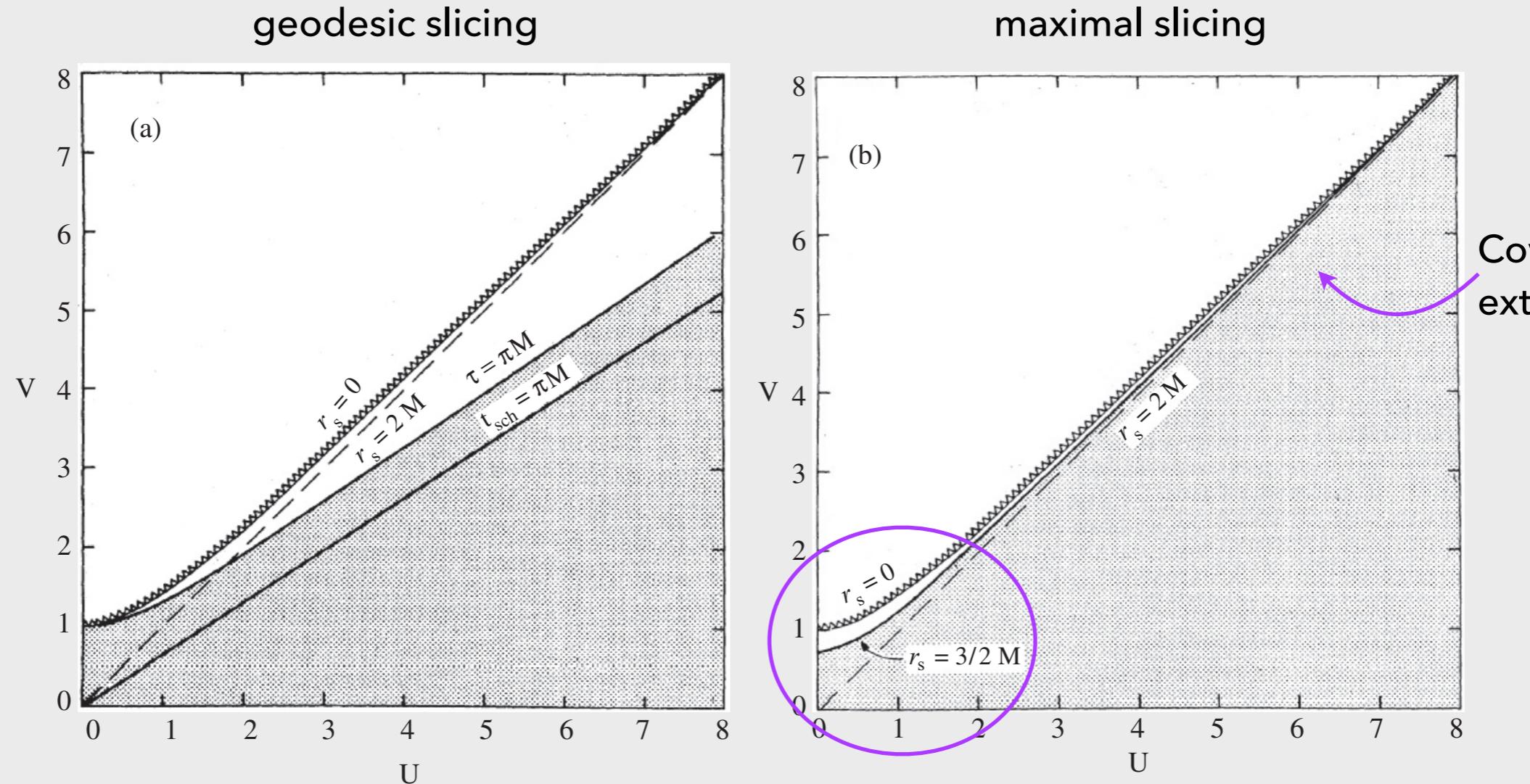
- ▶ Or in the conformal decomposition:

$$\bar{D}^2(\alpha\psi) = \alpha\psi \left(\frac{7}{8}\psi^{-8}\bar{A}_{ij}\bar{A}^{ij} + \frac{1}{8}\bar{R} + 2\pi\psi^4(\rho + 2S) \right)$$

- ▶ Note: Elliptic equations are costly. We can recast the equation into a parabolic one via “approximate” maximal slicing, i.e. $\partial_t K = -cK$

GEODESIC VS MAXIMAL SLICES

- Example: Schwarzschild spacetime (in Kruskal coordinates)



Maximal slices penetrate the BH interior but avoid the singularity asymptoting to the limiting surface at $r_S = 3M/2$.

SOME OTHER GAUGE CHOICES

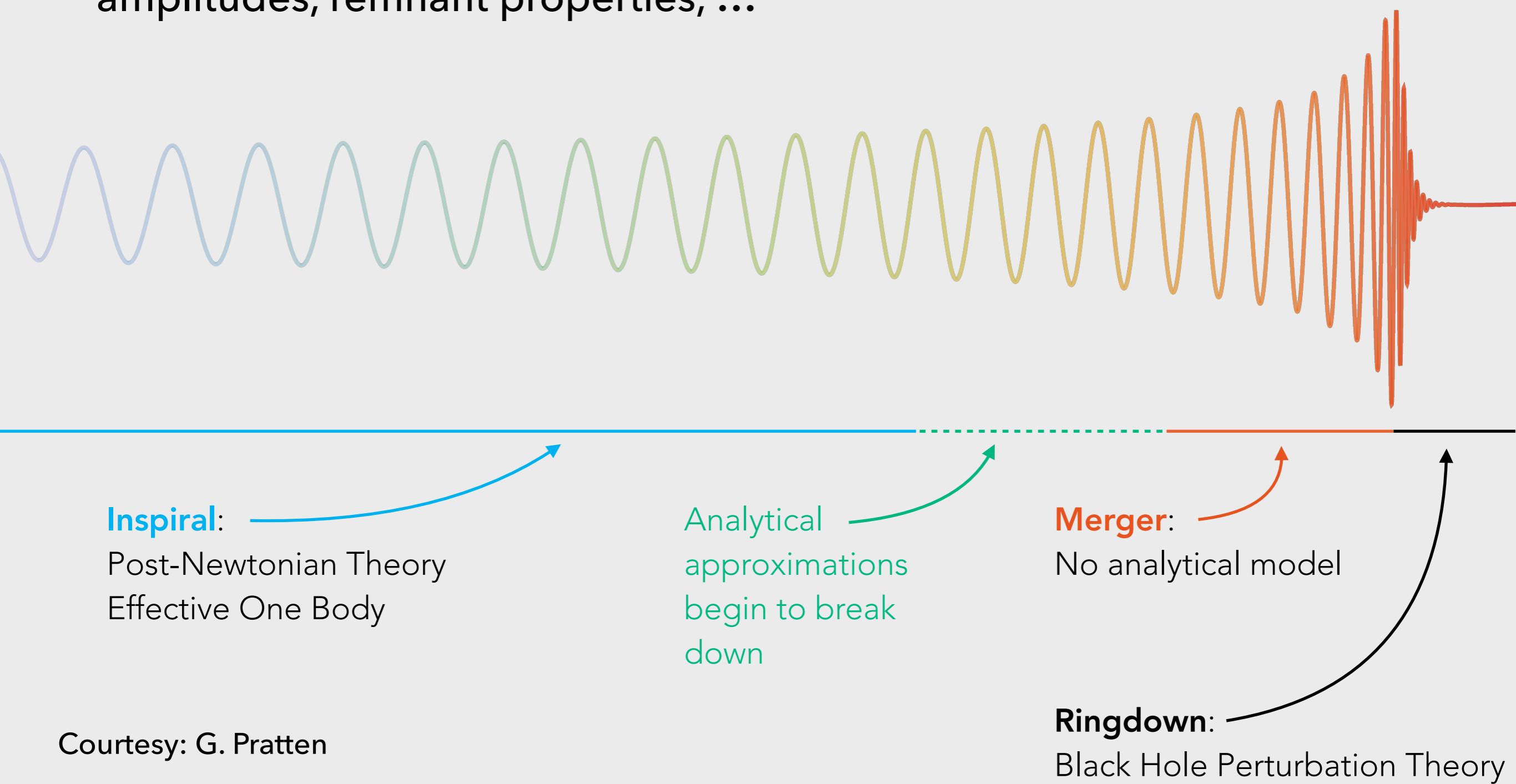
- ▶ Minimal distortion: minimise the time rate of change of $\bar{\gamma}_{ij}$
- ▶ Harmonic coordinates: $(^{(4)}\Gamma^\mu = 0)$
- ▶ 1+log slicing: Popular (algebraic) slicing condition is
$$\alpha = 1 + \ln \gamma \quad (\text{here } \beta^i = 0 \text{ is assumed})$$
- ▶ Or more general: $(\partial_t - \beta^j \partial_j)\alpha = -2\alpha K$
- ▶ (Hyperbolic) Gamma-driver shift condition:

$$\partial_t \beta^i = \frac{3}{4} B^i, \quad \partial_t B^i = \partial_t \bar{\Gamma}^i - \eta B^i$$

SIMULATING BINARY BLACK HOLES

WHY BINARY BLACK HOLES?

- ▶ GR in the strong-field regime, gravitational waves, ringdown amplitudes, remnant properties, ...



NR CODES

- ▶ About a dozen (proprietary) codes exist
 - ▶ Proprietary codes (not exhaustive): SpEC (Caltech-Cornell-AEI), BAM (Jena-Cardiff-Balearic Islands), LEAN (Cambridge), Maya (UTT), LazEv (RIT), ...
 - ▶ Public code: Einstein Toolkit (<https://einstein toolkit.org/>) - community supported by the NSF
 - ▶ Note: Many public codes use the framework of the Einstein Toolkit with customised BSSN drivers or alternative evolution schemes
- ▶ Some core differences across codes:
 - ▶ Formulation: **BSSN** vs. **generalised harmonic**
 - ▶ Handling of singularities: **moving punctures** vs. **excision**
 - ▶ Numerical methods: **finite differencing** vs. **spectral methods**

HOW TO HANDLE SINGULARITIES

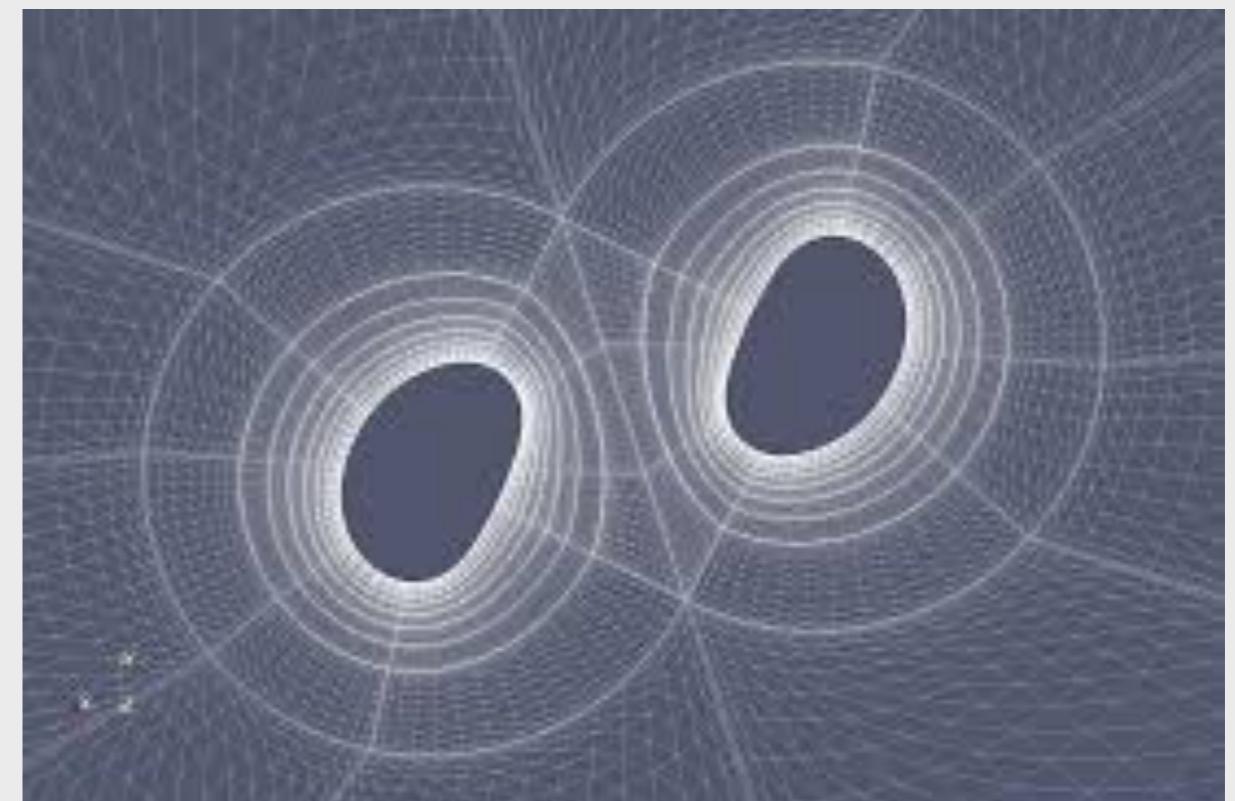
EXCISION

- ▶ The black hole horizon is a causal boundary. Anything inside the horizon is causally disconnected from the exterior region and hence cannot affect the physics there.
 - ▶ Singularity “hidden” inside the horizon
 - ▶ Remove the BH interior, and hence the physical (or coordinate) singularity from the computational domain
- ▶ 2 ingredients needed:
 1. A boundary inside the BH horizon such that the BH interior is removed
 2. A non-zero shift vector β^i that keeps the horizon at a roughly constant coordinate location during the evolution

BLACK HOLE EXCISION

- ▶ Problem: The BH horizon (event horizon) is a globally defined quantity and to determine it we require the entire future development of the spacetime
 - ▶ Proxy: apparent horizon (AH) with $r_{\text{AH}} < r_{\text{EH}}$ defined on every time slice
 - ▶ Definition:

An apparent horizon is the outermost 2-surface embedded in a spatial hypersurface Σ , whose outgoing future null geodesics have vanishing expansion everywhere.



HOW TO HANDLE SINGULARITIES

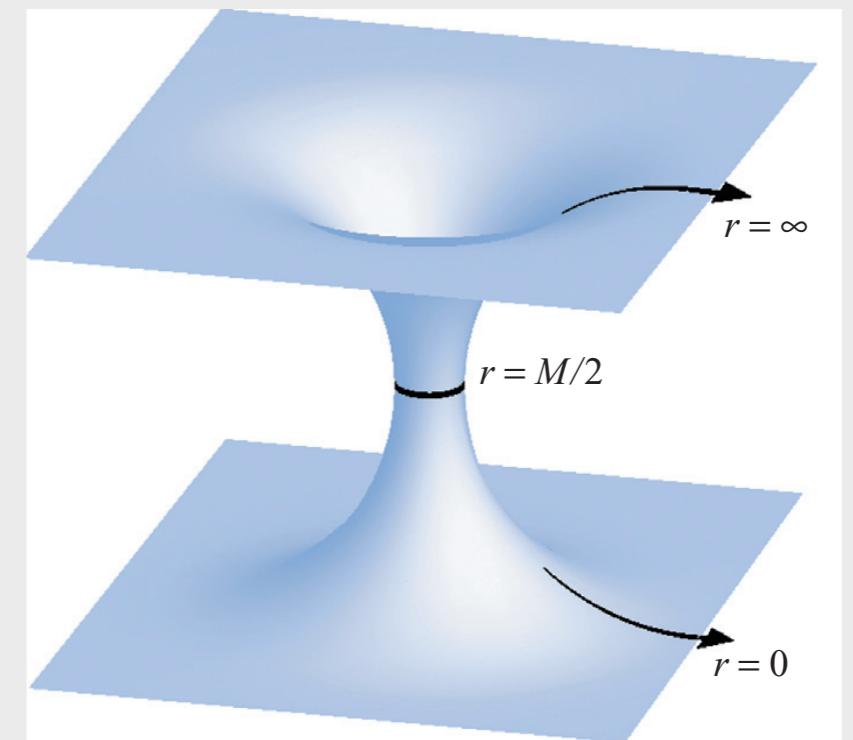
MOVING PUNCTURES

- ▶ Alternatively, we can keep the (coordinate) singularities but make sure that the singularity never coincides with a grid point, where the calculations are performed. This is controlled via appropriate gauge conditions.
- ▶ 1+log slicing & gamma-driver shift

$$\psi_{\text{BL}} = 1 + \sum_{i=1}^N \frac{m_i}{2r_i}$$

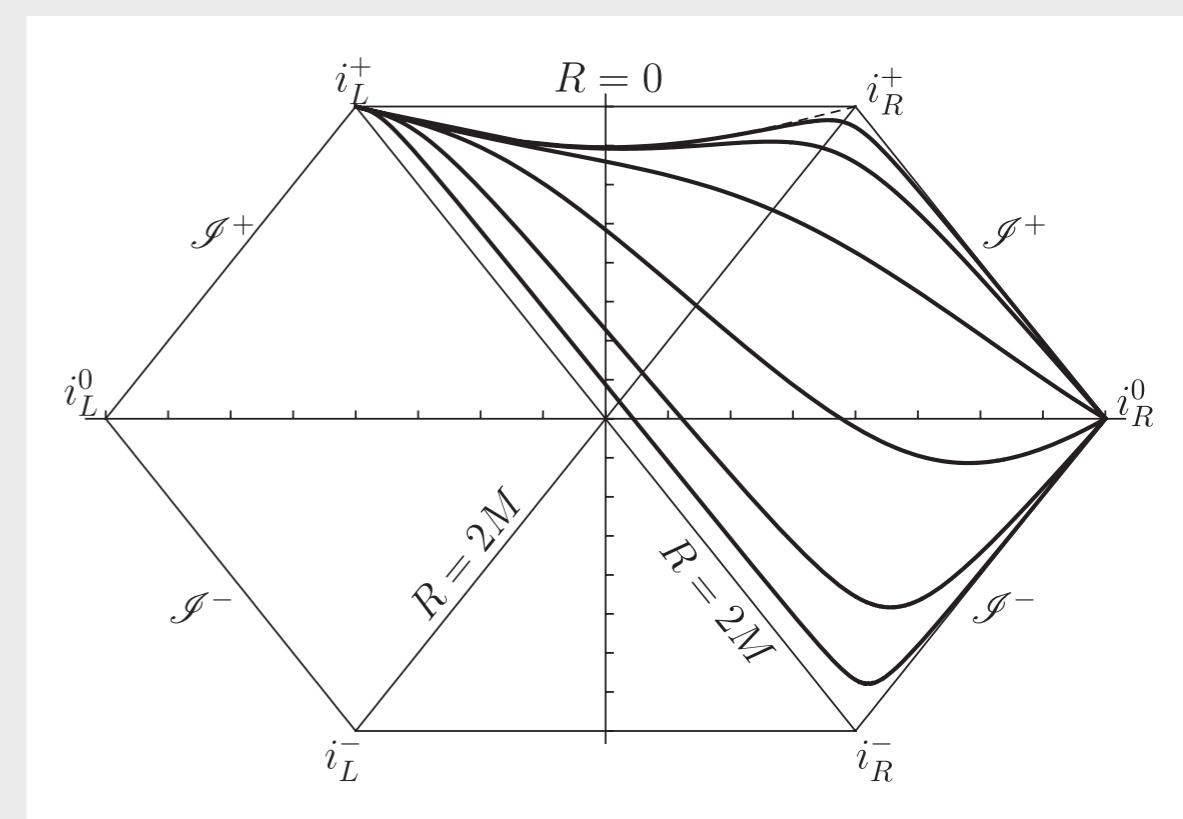
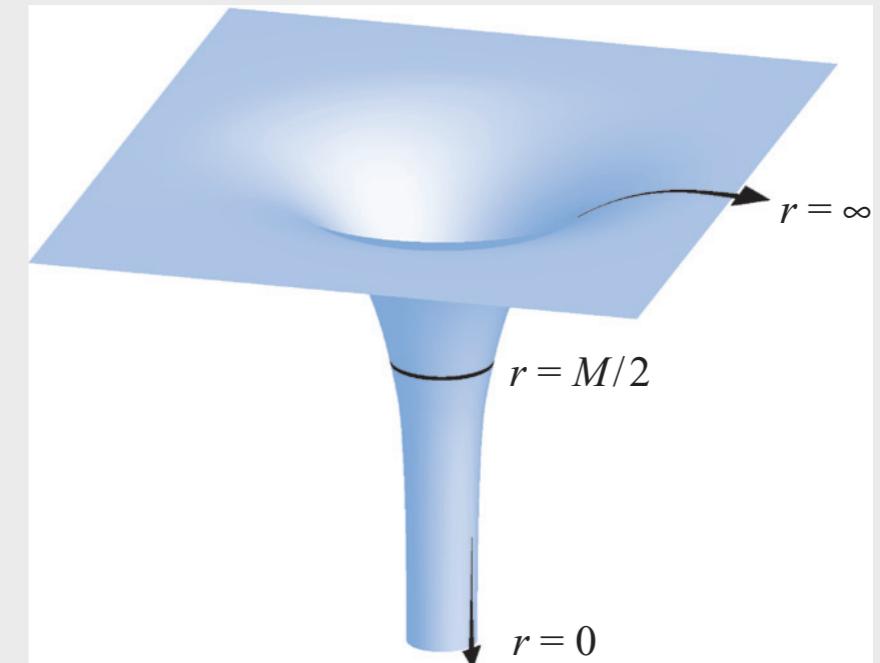
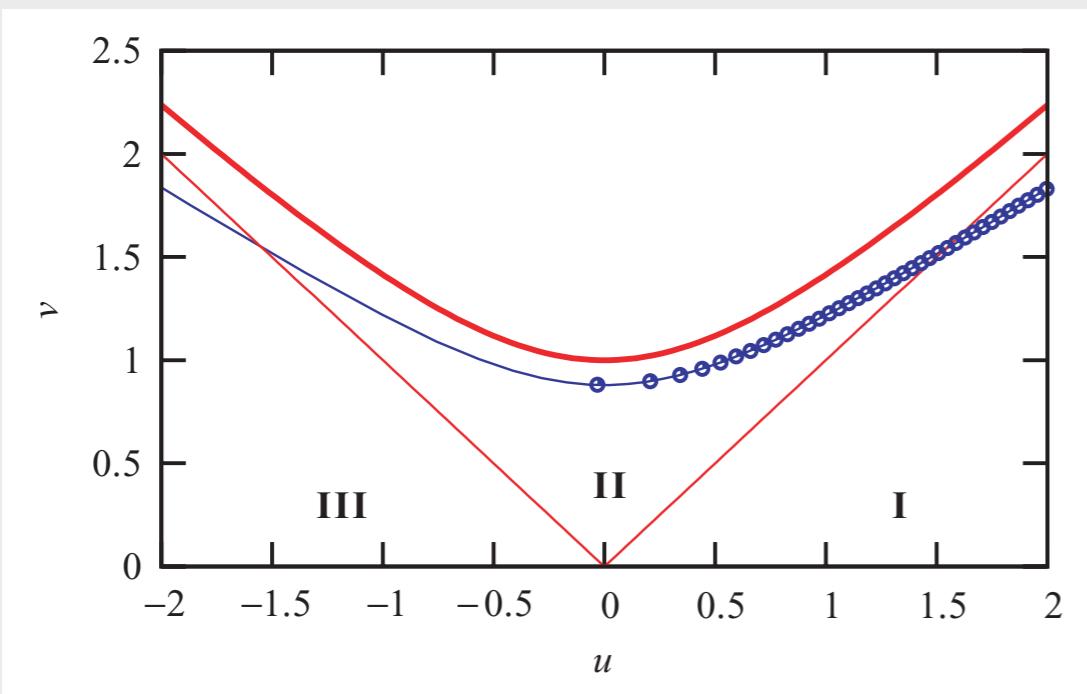
Singularity can be identified with spatial infinity (regular)

Topology of the initial slice is a wormhole connecting two asymptotically flat copies



MOVING PUNCTURES

- As we evolve the initial data with the 1+log slicing condition, the topology of the slices changes for a short time before the topology settles down.
- The conformal factor now diverges at $1/\sqrt{r}$. Such a slice terminates on a finite limit surface at $r = 3M/2$ that does not reach the singularity.



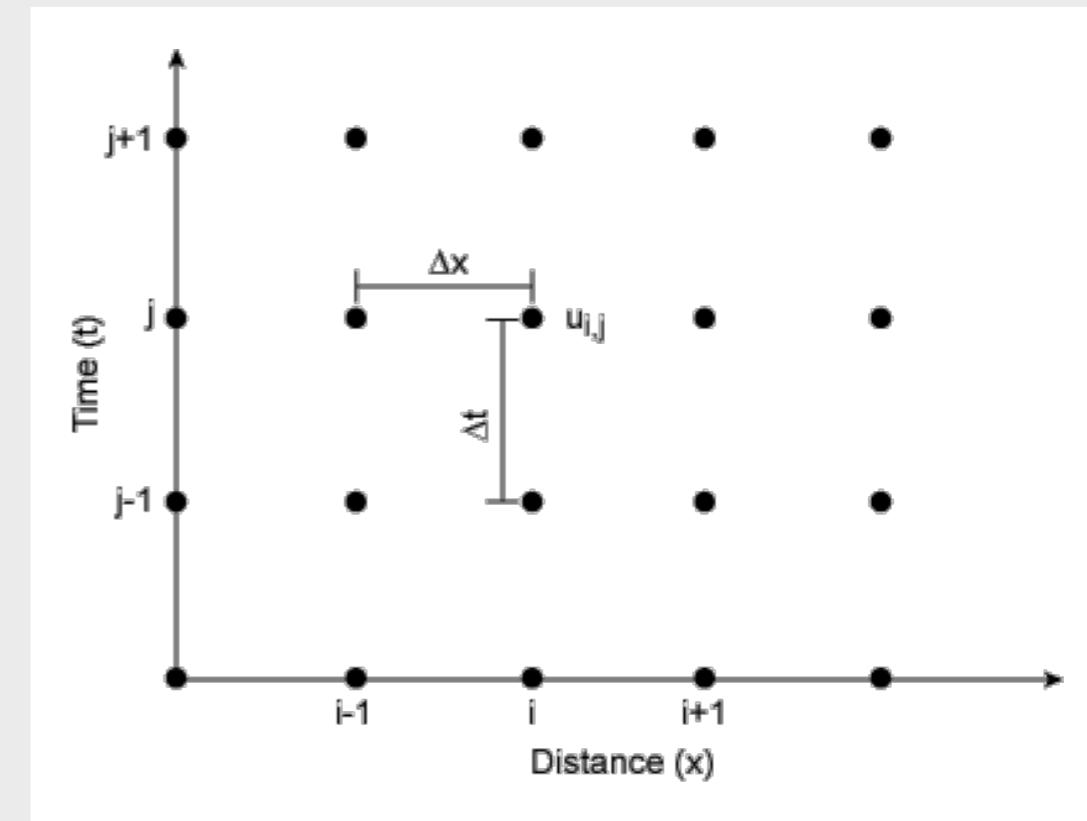
NUMERICAL METHODS

FINITE DIFFERENCING

- Given a continuous function $f(t, x)$, we approximate it by its value at a discrete set of points:

$$f_{ij} = f(t_j, x_i) + \text{truncation error}$$

- Substitute a continuous spacetime with a set of discrete points (grid or mesh)
- Replace differential operators by finite differences (algebraic equation)
- Note: Numerical grids are not infinite - appropriate (outer) boundary conditions have to be chosen



Example 2nd order scheme (centred):

$$\partial_x f|_{x_i} = \frac{f_{i+1} - f_{i-1}}{2\Delta x} + \mathcal{O}(\Delta x^2)$$

$$\partial_x^2 f|_{x_i} = \frac{f_{i+1} - 2f_i + f_{i-1}}{(\Delta x)^2} + \mathcal{O}(\Delta x^2)$$

FINITE DIFFERENCING

- ▶ Example: advective equation (hyperbolic)

$$\partial_t u + v \partial_x u = 0$$

- ▶ Solution: $u(t, x) = u(x - vt)$

- ▶ FD representation: $\partial_x u|_{x_i}^{t_j} = \frac{u_{i+1}^j - u_{i-1}^j}{2\Delta x} + \mathcal{O}(\Delta x^2)$ (centred spatial difference)

$$\partial_t u|_{x_i}^{t_j} = \frac{u_i^{j+1} - u_i^j}{\Delta t} + \mathcal{O}(\Delta t)$$
 (forward time difference)

- ▶ Explicit forward scheme:

$$u_i^{j+1} = u_i^j - \frac{v}{2} \frac{\Delta t}{\Delta x} (u_{i+1}^j - u_{i-1}^j)$$

- ▶ Stability criterion: $|v| \frac{\Delta t}{\Delta x} \leq 1$ Courant factor

NUMERICAL METHODS

SPECTRAL METHODS

- ▶ Represent the solution to a differential equation, e.g. $u(x)$ as a truncated series in a complete set of basis function $\phi_k(x)$:

$$u(x) \simeq u^{(N)}(x) = \sum_{k=0}^N \tilde{u}_k \phi_k(x)$$


spectral coefficients

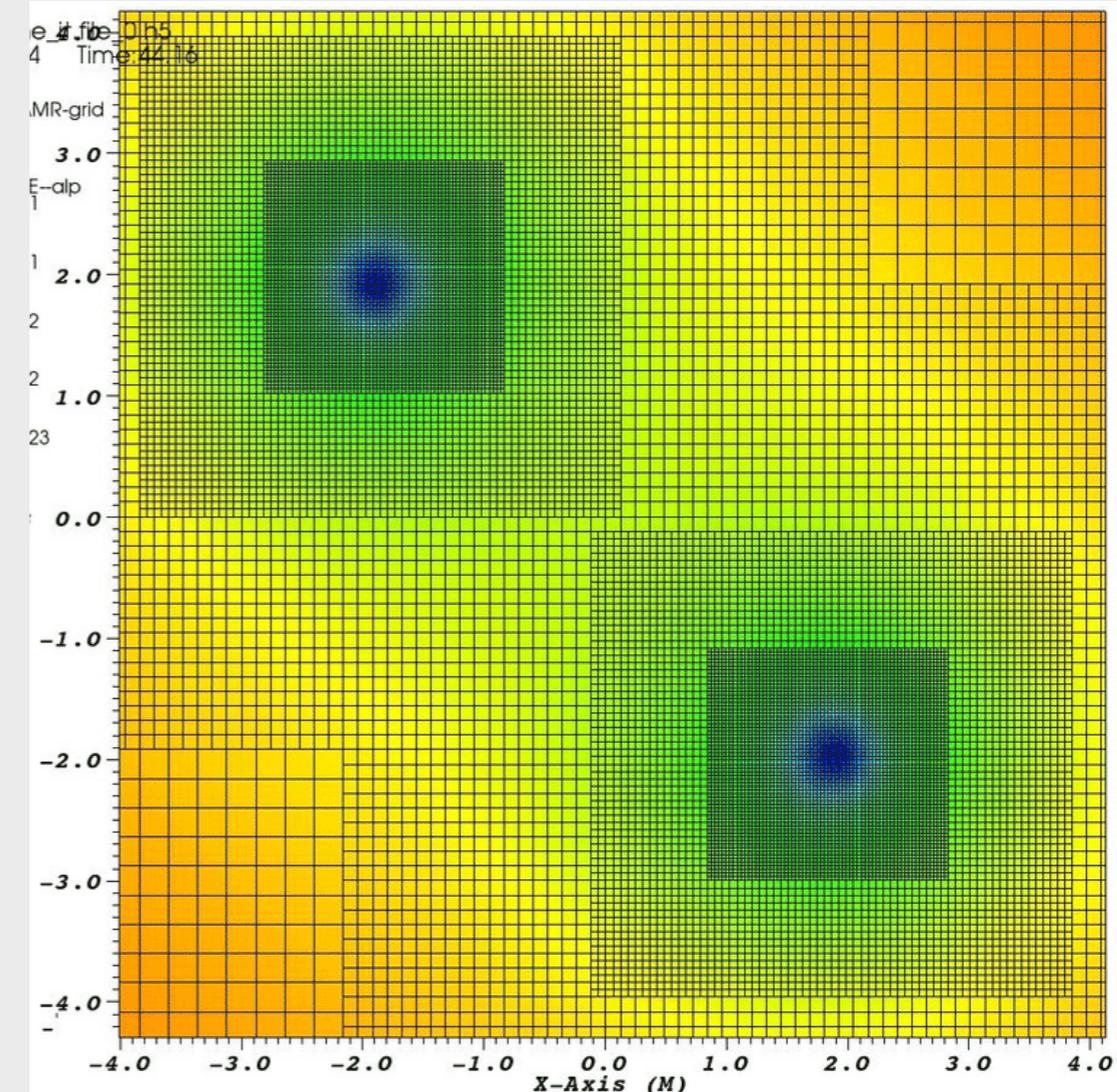
- ▶ Derivatives can be expressed analytically:

$$\partial_x u(x) \simeq \partial_x u^{(N)}(x) = \sum_{k=0}^N \tilde{u}_k \partial_x \phi_k(x)$$

- ▶ Advantage: Numerical error often drops exponentially with N. Often fewer computational resources needed for the same accuracy as FD.
- ▶ Disadvantage: More difficult to implement. Discontinuities are a problem.

MESH REFINEMENT

- ▶ BBH simulations span a “dynamic range” that we want to resolve, i.e. the dynamics of the black holes in a relatively small area of the grid and GWs in the wave zone far from the black holes.
- ▶ BUT: A uniform numerical grid across the dynamic range is very expensive!
- ▶ Perform the simulation using a multi-grid structure with a different spatial resolution on each grid as required.
- ▶ Note: Special care needs to be taken at grid boundaries.



Adaptive mesh: boxes move with the BHs

GRAVITATIONAL WAVE EXTRACTION

- ▶ Different methods to extract GWs, e.g. **Newman-Penrose formalism**
 - ▶ 10 independent components of the Weyl tensor can be expressed as 5 scalars ψ_0, \dots, ψ_4 , which are formed by contracting the Weyl tensor with a null tetrad.
 - ▶ For certain tetrads (quasi-Kinnersley), we can interpret ψ_0 and ψ_4 as ingoing and outgoing null rays:

$$\psi_4 = -{}^{(4)}C_{abcd} k^a \bar{m}^b k^c \bar{m}^d$$

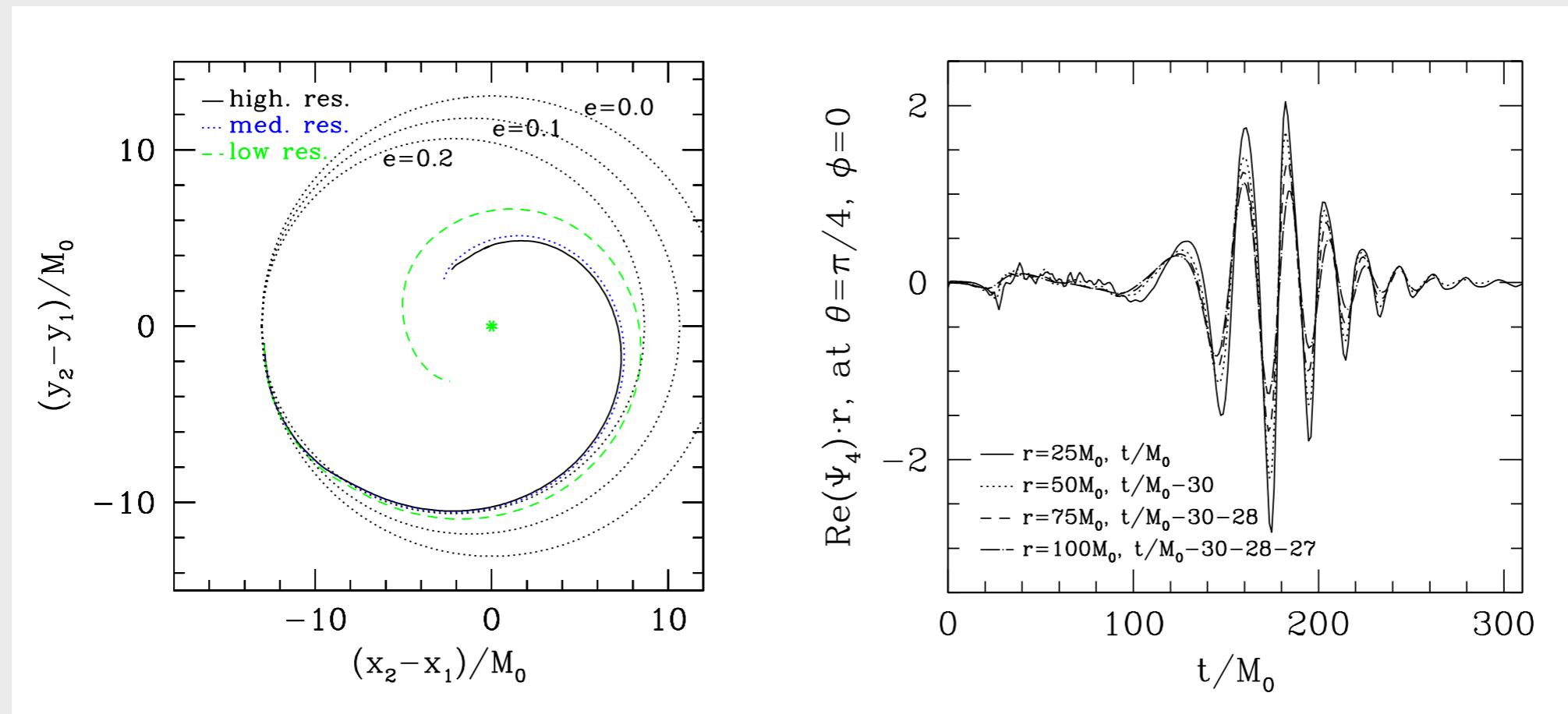
- ▶ Where l and k are real radially outgoing and ingoing null vectors; m is a complex vector such that $-l^a k_a = 1 = m^a \bar{m}_a$.
- ▶ In the TT gauge we find

$$\psi_4 = \ddot{h}_+ - i \ddot{h}_x$$

- ▶ Requires the 4D Riemann tensor, which is constructed from spatial 3D quantities on each slice.

THE BREAKTHROUGH IN 2005

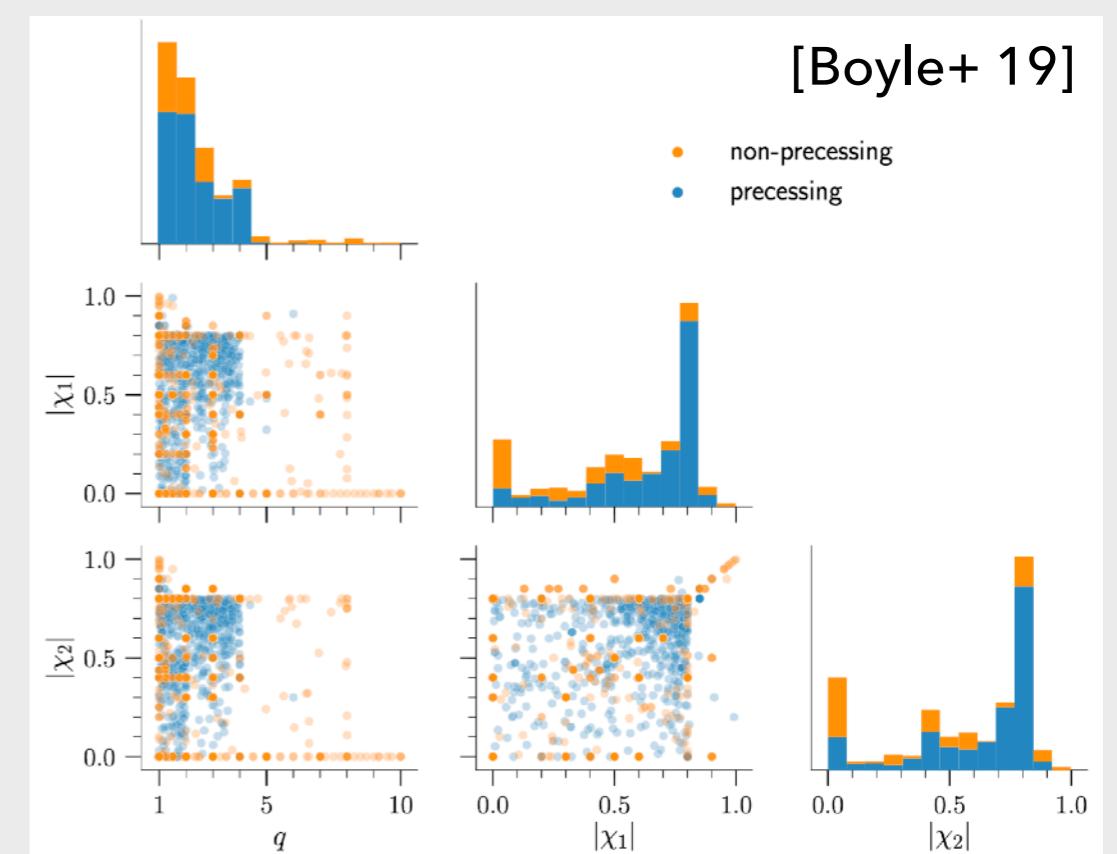
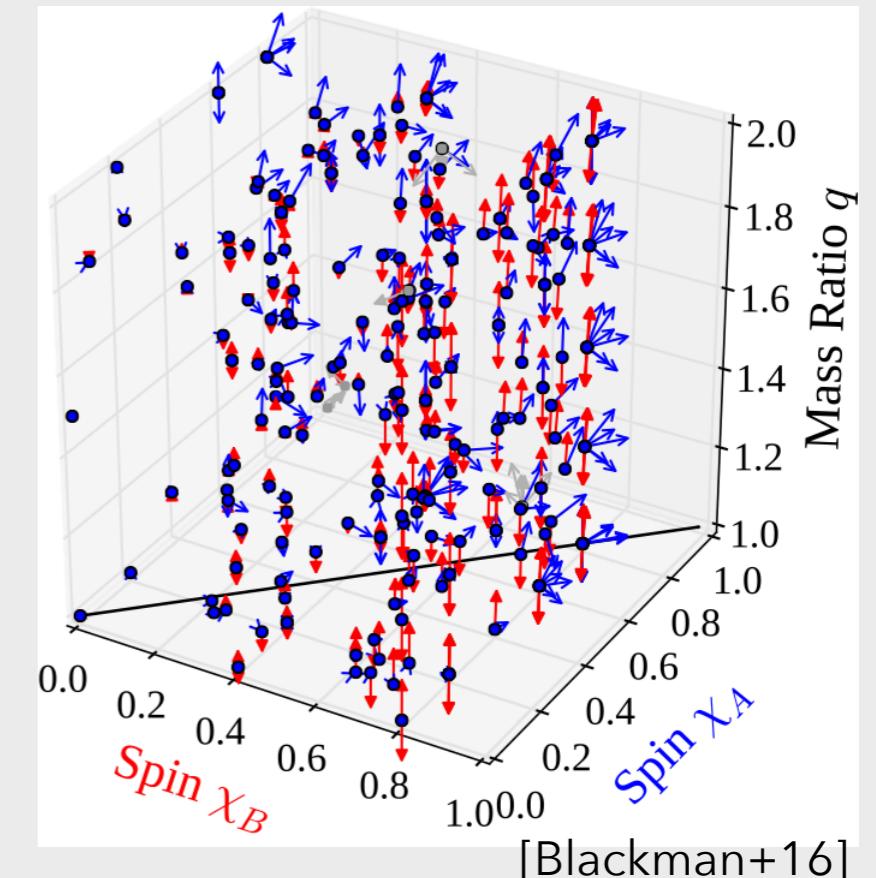
- ▶ In 2005, Frans Pretorius produced the first successful numerical relativity simulation of two equal mass black holes
 - ▶ Generalised harmonic formulation, excision, finite differencing



Figures from F. Pretorius, PRL 95, 121101 (2005)

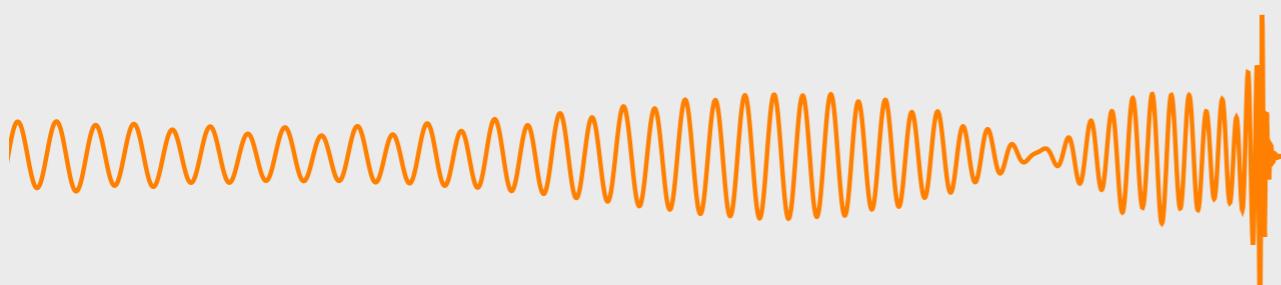
STATE-OF-THE-ART

- ▶ Today, several thousands of waveforms from merging black holes have been produced by several different codes
- ▶ These waveforms are
 - ▶ Crucial for the development of inspiral-merger-ringdown (IMR) waveform models (calibration)
 - ▶ Directly used in GW data analysis applications
 - ▶ Important to gauge systematics
 - ▶ Crucial to derive the remnant properties

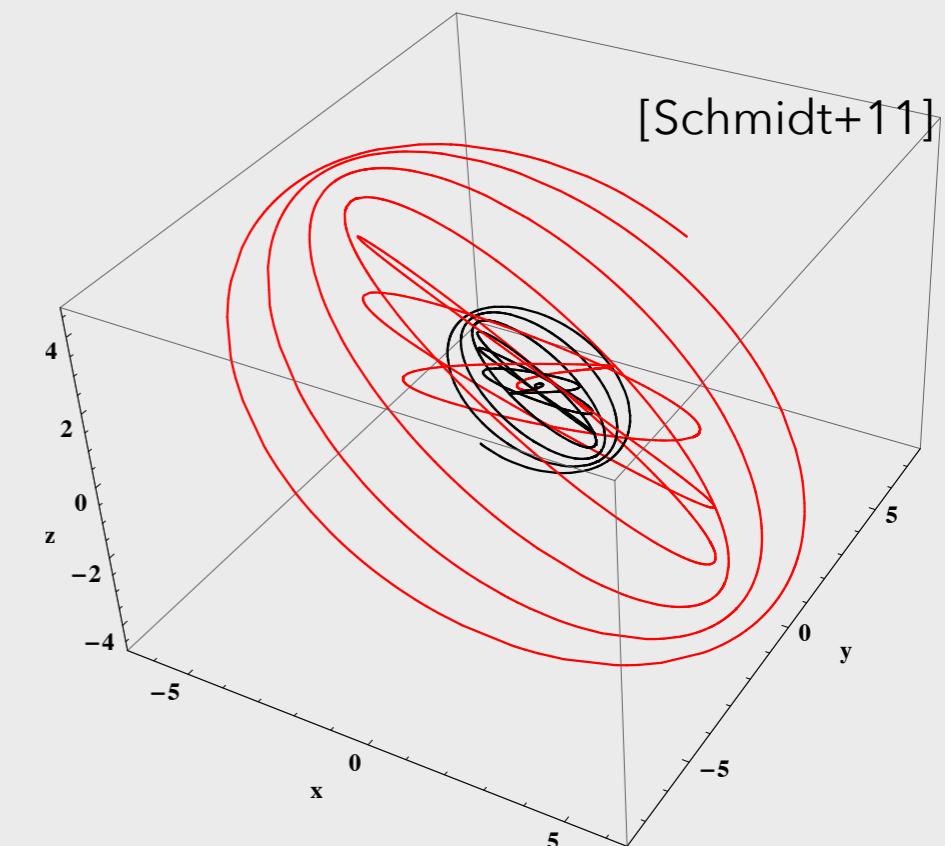
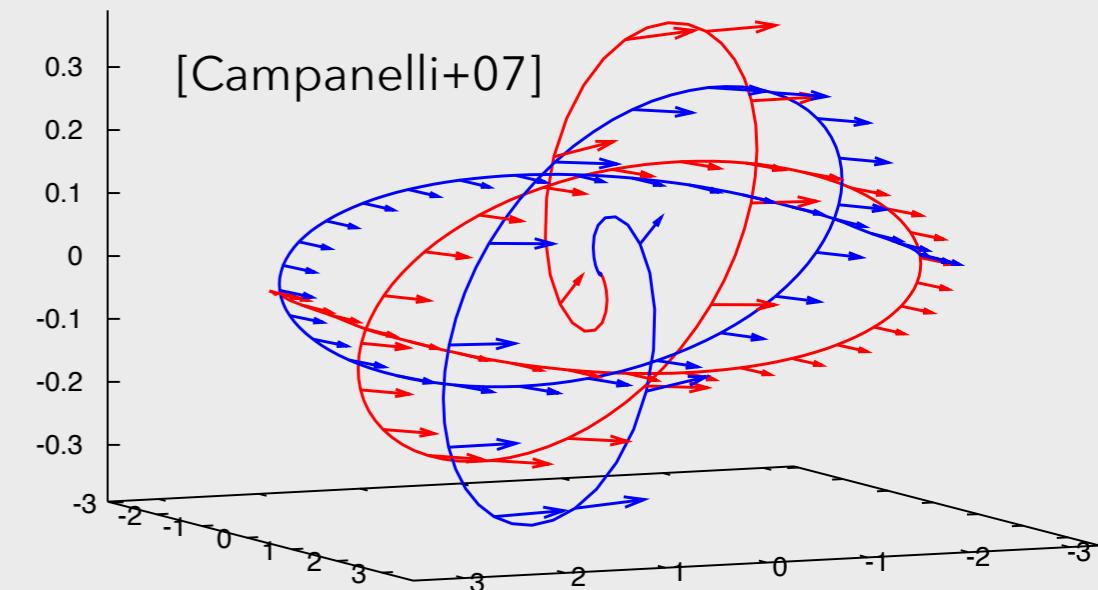


PRECESSION

- ▶ Occurs when spins are misaligned with the orbital angular momentum
 - ▶ Induces amplitude & phase modulations

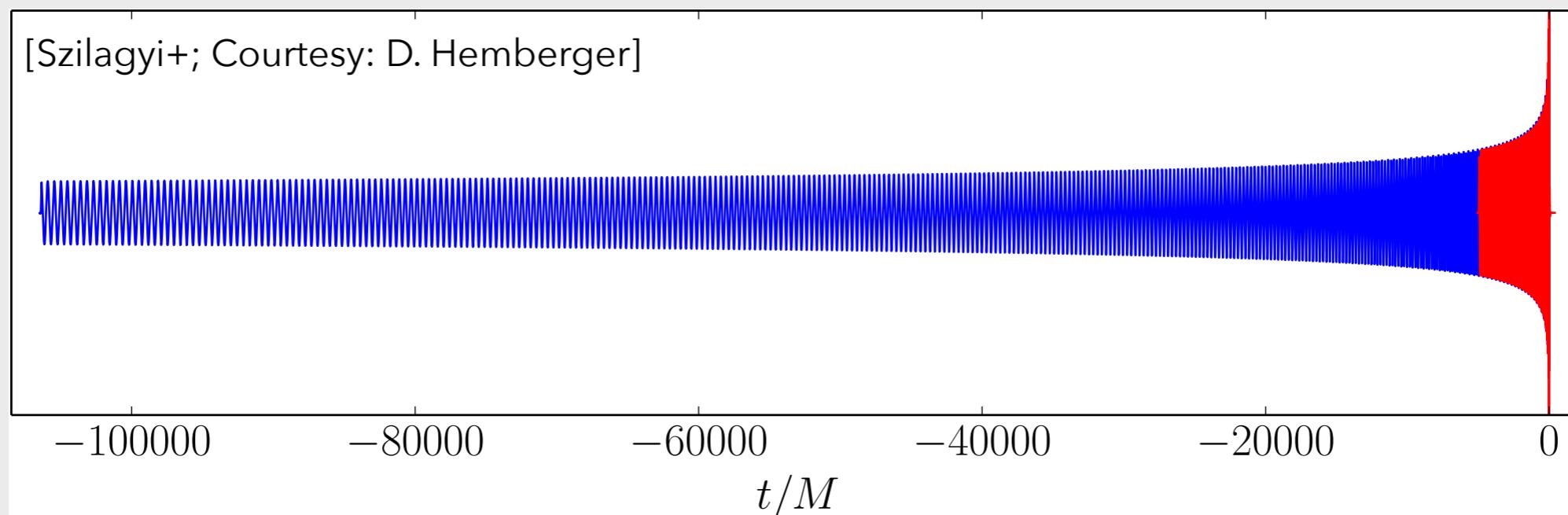


- ▶ First simulations performed as early as 2006 [Campanelli+]
- ▶ 7D parameter space $(q, \vec{a}_1, \vec{a}_2)$
 - ▶ Difficult to sample
 - ▶ NR simulations concentrated around $q=1-4$
 - ▶ Long simulations required to resolve a complete precession cycle



LONG SIMULATIONS

- ▶ Long simulations desirable to probe the consistency between early inspiral models
- ▶ Resolve a precession cycle?
- ▶ Stable evolutions longer than ~ 20 orbits are difficult & expensive
 - ▶ Gauge drifts
 - ▶ Build-up of numerical errors
- ▶ 2015: ~ 175 orbit long non-spinning simulation with $q=7$



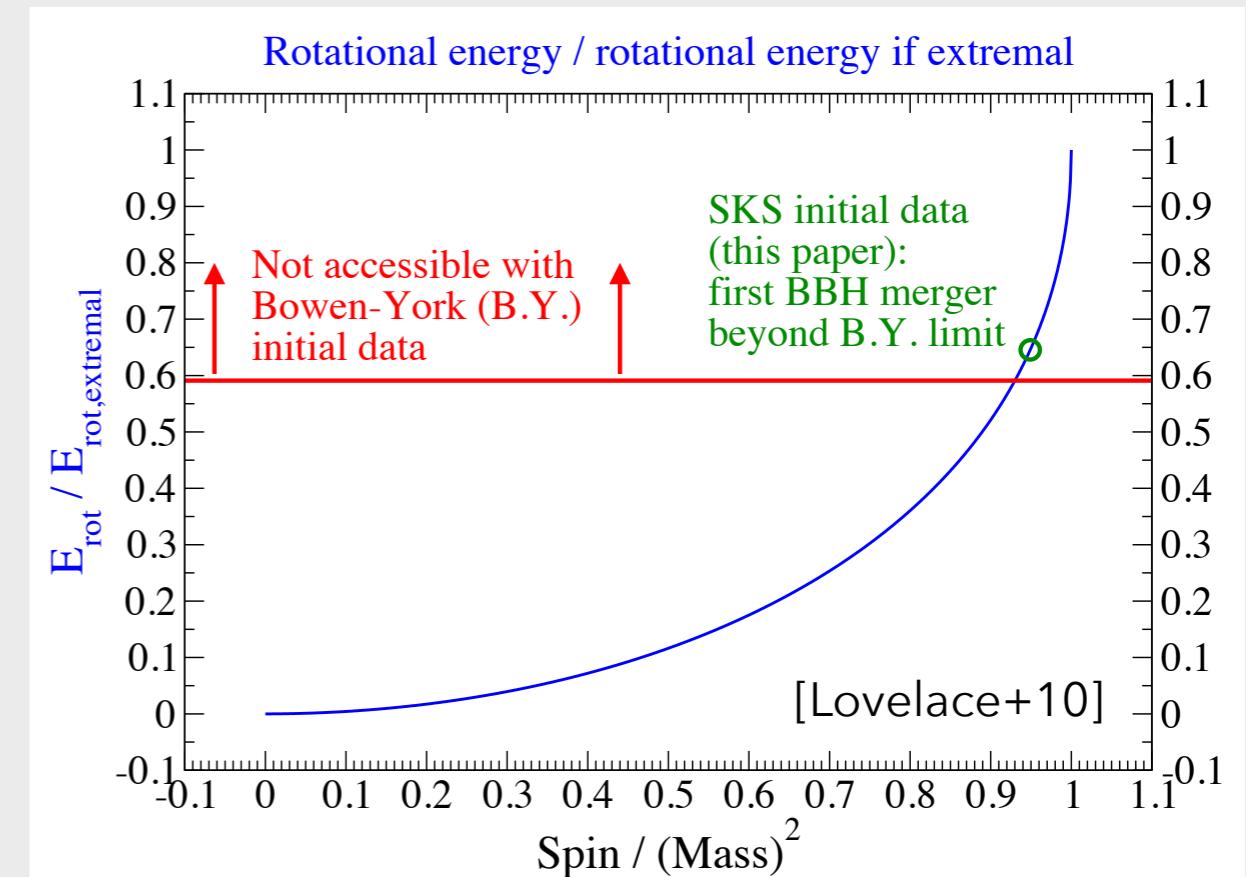
EXTREME SPINS

- ▶ Extreme spin: First breakthroughs in 2011 for quasi-equilibrium initial data [Lovelace+11]

- ▶ Fundamental spin limit for Bowen-York (BY) initial data

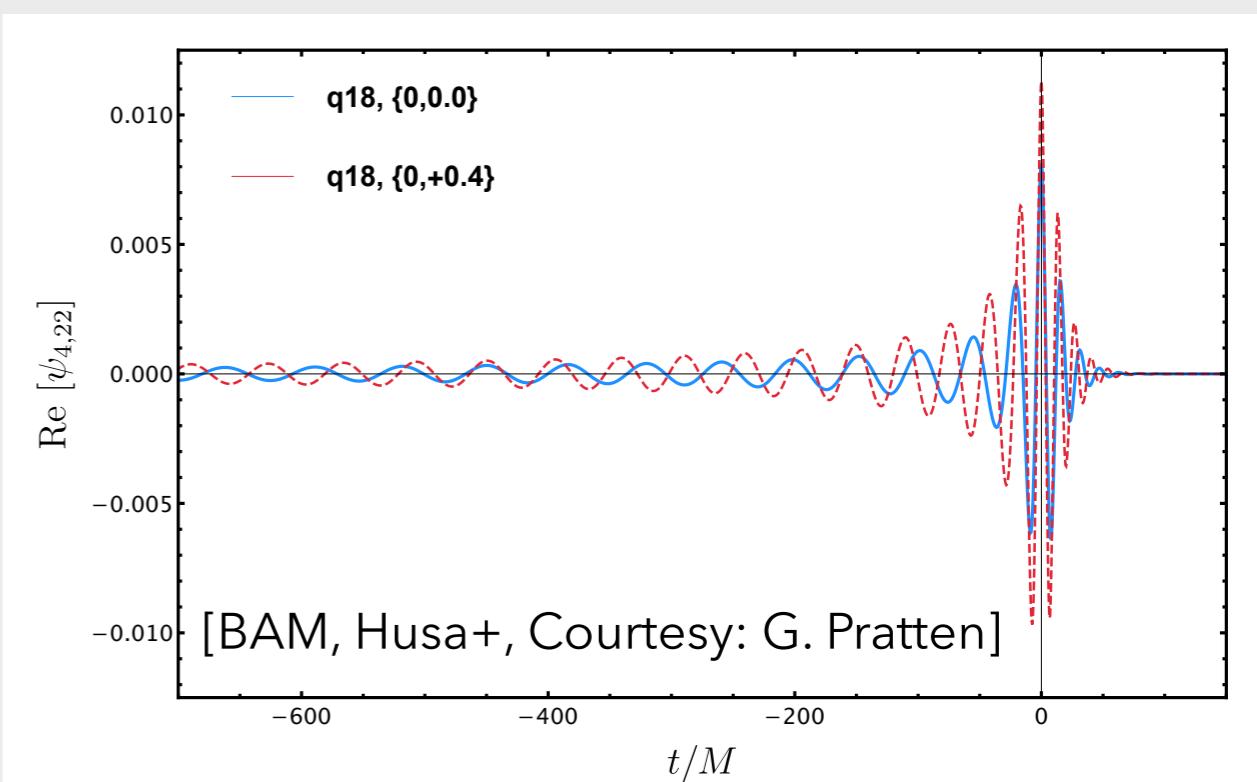
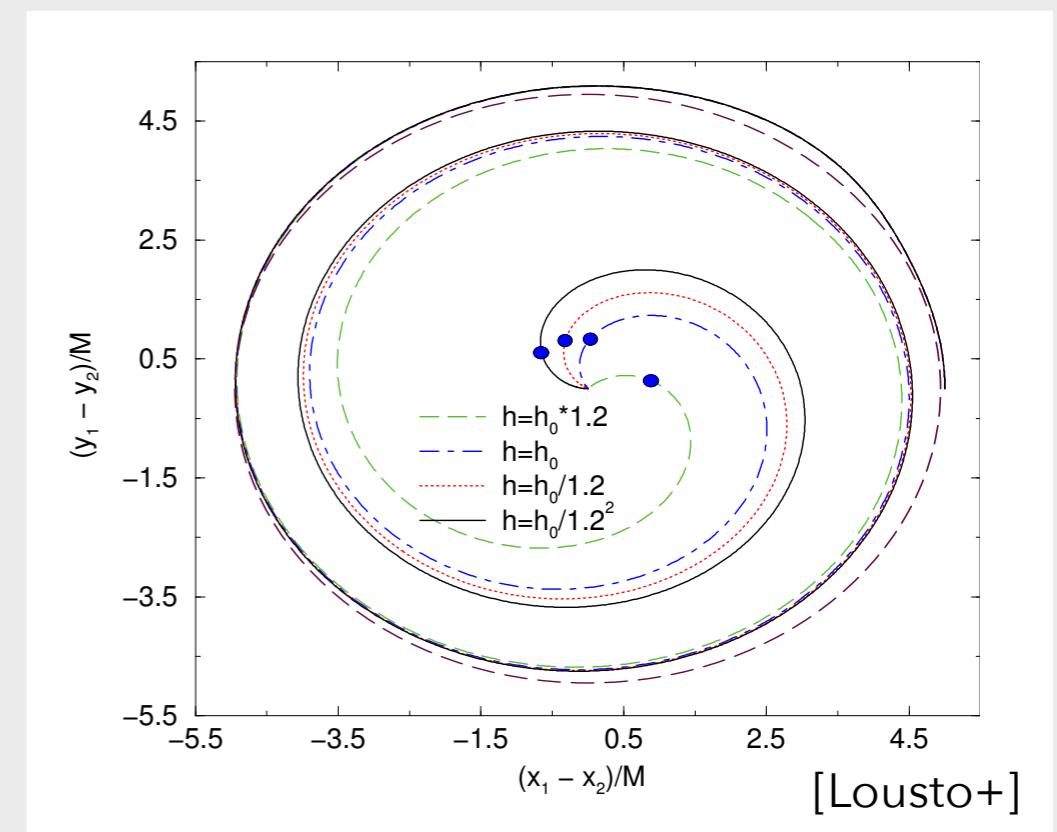
$$a_{\max} \leq 0.93 \quad [\text{Dain+}]$$

- ▶ 2014 onwards: incorporation of non-conformally flat initial data into the moving punctures framework [Ruchlin+14, Zlochower+17] to go beyond the BY limit



HIGH MASS RATIOS

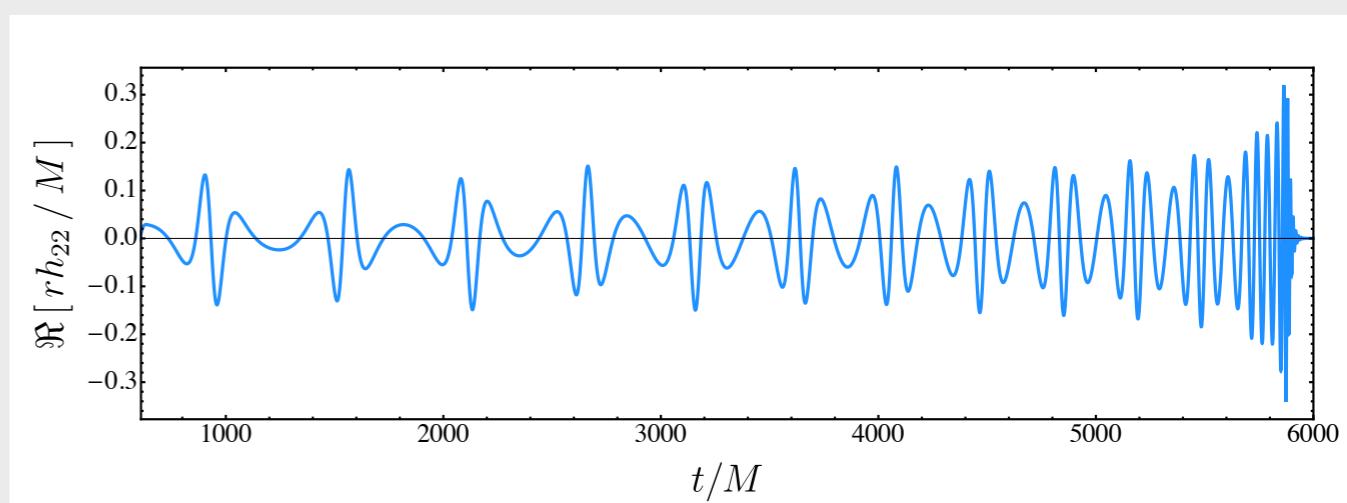
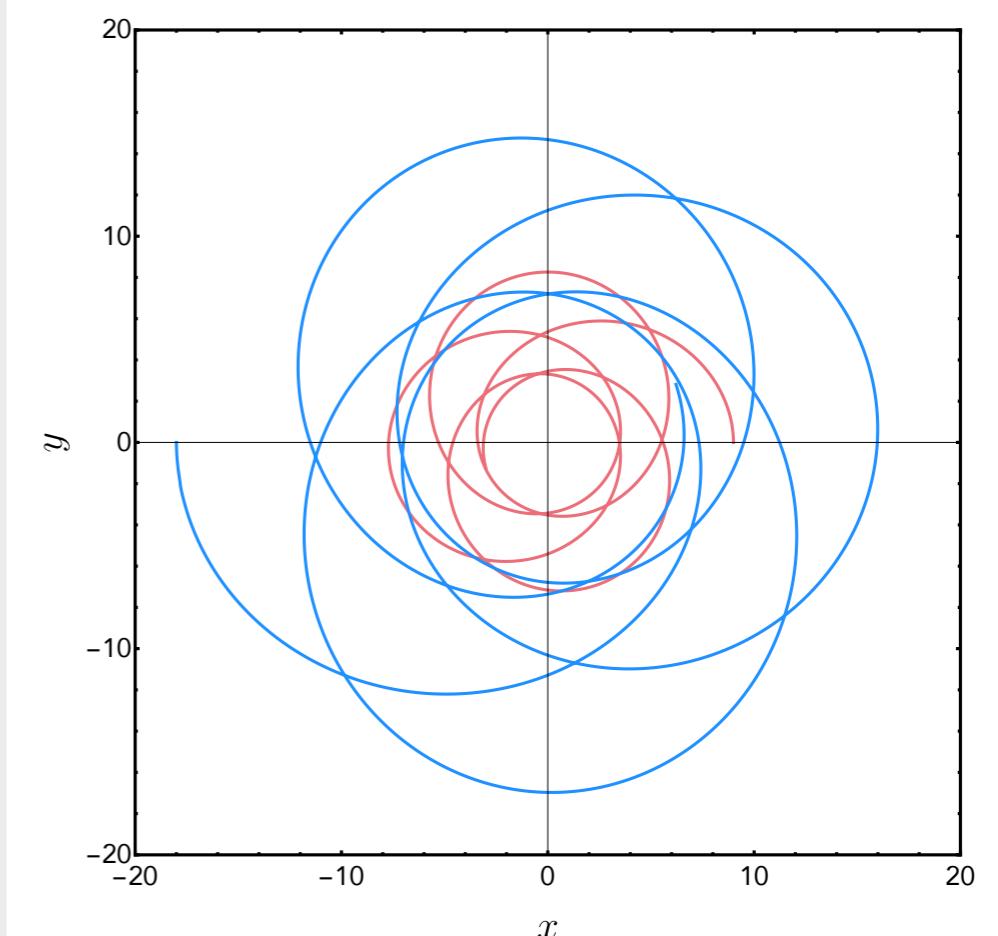
- ▶ Very few points beyond mass ratio $q=8$
 - ▶ non-spinning $q=100$ [Lousto+]
 - ▶ non-spinning $q=10$ [SXS]
 - ▶ aligned-spin $q=18$ [BAM, Husa+15]
- ▶ Waveform models are poorly calibrated in the high mass regime due to the lack of NR simulations!
 - ▶ Test particle limit information included
- ▶ Problems:
 - ▶ Large difference in horizon size
 - ▶ Difficult to resolve the smaller BH
 - ▶ Spins additionally distort the horizon
 - ▶ Computationally very expensive



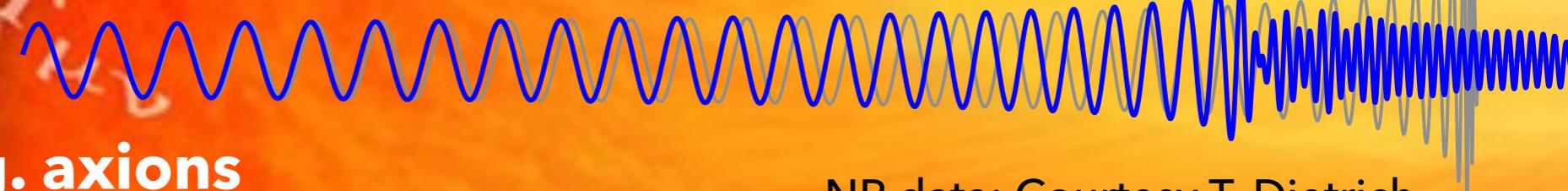
ECCENTRIC BINARIES

- ▶ Radiation-reaction circularises orbit
- ▶ 3-body encounters, dynamical capture could produce highly eccentric orbits with not enough time to circularise before merger
 - ▶ e.g. interactions in globular clusters
- ▶ Advance of the periastron (pure GR)
- ▶ Bursts of radiation
- ▶ Zoom-whirl behaviour

Courtesy: G. Pratten



LOTS MORE WORK TO DO

- ▶ Improve
- ▶ Accuracy
- ▶ Efficiency
- ▶ Parameter space coverage
- ▶ Include more (realistic) physics
 - ▶ Regular matter, e.g. neutron stars
 - ▶ Exotic matter 
 - ▶ Extra fields, e.g. axions
- ▶ Going beyond General Relativity

NR data: Courtesy T. Dietrich