

**Question 1**

Let  $X = \{(x, y) \in \mathbb{R}^2 | y = \pm 1\}$ , and we define the equivalence relation  $\sim$  where  $(x, 1) \sim (x, -1)$  for  $x \neq 0$ . Then  $Y = X / \sim$  is the set of equivalence classes of  $x$  values and two zeros,  $(0, -1)$  and  $(0, +1)$ .

We first see that  $X$  is a topological space by the relative topology. To see that  $X$  is also Hausdorff, consider  $(x_1, y_1), (x_2, y_2) \in X$  distinct. Then, suppose  $U_1, U_2 \subset X$  as open sets. By the relative topology of  $\mathbb{R}^2$ , we can always choose open balls in  $\mathbb{R}^2$  small enough so that the intersection of  $X$  with that open set is not disjoint. In particular, this means that the open set will be an open interval on either the line  $y = 1$  or  $y = -1$ .

Then, if  $y_1 \neq y_2$ , we have that  $U_1 \cap U_2 = \emptyset$  by construction. Suppose that  $y_1 = y_2$ , then we need to consider only the distinct points  $x_1$  and  $x_2$  on  $\mathbb{R}$ , but since the relative topology here will just be the standard topology of  $\mathbb{R}$ , we get Hausdorff for free. So  $X$  is Hausdorff for sure.

Now consider  $Y$ . In particular, to see that  $Y$  is not Hausdorff, we choose the distinct points  $(0, -1)$  and  $(0, +1)$ . We note that open sets are defined in  $Y$  by the quotient topology, and we use open sets in  $X$  under the equivalence relation to get our topology,  $\bar{\tau}$ .

In particular, suppose again we can pick open balls small enough in  $\mathbb{R}^2$  around the two points so that the intersection of the open ball with  $X$  is restricted to a single line. Call these two open sets  $U_1 = B_r((0, 1)) \cap X$  and  $U_2 = B_r((0, -1)) \cap X$ , where  $r < 2$ . Suppose that  $p_1 \in U_1$ , then  $\exists x \in \mathbb{R} \setminus \{0\}$  such that  $p_1 = (x, 1) \sim (x, -1) \in U_2$ . So, in  $Y$ , the open sets will never be disjoint around  $(0, 1)$  and  $(0, -1)$ .

Thus  $Y$  is not Hausdorff.

**Question 2**

**Question 3**

(a) Suppose  $x \in \mathbb{S}^n \setminus \{N\}$ , then we can parameterize the line connecting  $x$  and  $N$  by the following equation,

$$y = t(x - N) + N \quad t \in \mathbb{R}$$

In particular, we can find the  $t$  for which this line intersects the subspace defined by  $x_{n+1} = 0 \subset \mathbb{R}^{n+1}$ ,

$$(y_1, \dots, y_n, 0) = tx + N(1 - t) = (tx_1, \dots, tx_n, tx_{n+1} + 1 - t)$$

$$\implies t(x_{n+1} - 1) + 1 = 0 \iff t = \frac{1}{1 - x_{n+1}}$$

Hence, we see that the intersection of the line connecting  $N$  and  $x$  with the subspace setting  $x_{n+1} = 0$  is just,

$$\frac{(x_1, \dots, x_n, 0)}{1 - x_{n+1}} = (u, 0) = (\sigma(x), 0)$$

as expected. We do the same for  $S$ , and we see that

$$y = t(x - S) + S$$

and again, for the subspace defined by  $x_{n+1} = 0$ , we get,

$$(y_1, \dots, y_n, 0) = (tx_1, \dots, tx_n, tx_{n+1} - 1 + t)$$

$$\implies tx_{n+1} - 1 + t = 0 \iff t = \frac{1}{1 + x_{n+1}}$$

Hence, the intersection point will be,

$$\frac{(x_1, \dots, x_n, 0)}{1 + x_{n+1}} = -\frac{(-x_1, \dots, -x_n, 0)}{1 - (-x_{n+1})} = (-\sigma(-x), 0) = (\tilde{\sigma}(x), 0)$$

again as we would expect.

(b) First we show injection. To see this, suppose that  $x, y \in \mathbb{S}^n \setminus \{N\}$ . Then, as we showed in (a), we can relate the image under  $\sigma$  of these points to the intersection of the line connecting the point and  $N$  with the subspace that sets the  $n^{th} + 1$  component to 0. That is to say, if  $\sigma(x) = \sigma(y)$ , then  $(\sigma(x), 0) = (\sigma(y), 0)$ , which is to say that the two lines would intersect at that point in the plane defined by setting the  $n^{th} + 1$  component to 0. Yet, these two lines necessarily intersect at  $N$  as well, so they must be the same line.

Then, we have that this line intersects  $\mathbb{S}^n$  at  $N$ , by necessity, and both  $x$  and  $y$ . But this is impossible, since a straight line in  $\mathbb{R}^{n+1}$  will only intersect a sphere at most twice. Further, by supposition,  $x \neq N$  and  $y \neq N$ , and hence it must be that  $x = y$ . Thus we have that  $\sigma$  is injective.

Now we check surjection. The image lies in  $\mathbb{R}^n$ , so suppose  $u \in \mathbb{R}^n$ . In particular, we can again use the fact that  $\sigma$  is simply the intersection of the line connecting  $N$  and a point on  $\mathbb{S}^n$  with the plane defined by setting the last component to 0. In particular, we then associate  $u$  with  $(u, 0)$ . Then, the line connecting this point and  $N$  is defined by,

$$y = t((u, 0) - N) + N = (tu, 0) + N(1 - t) = (tu, 1 - t)$$

for  $t \in \mathbb{R}$ . To find the point  $y \in \mathbb{S}^n \setminus \{N\}$  with which this line intersects, we use the definition of  $\mathbb{S}^n$

$$\begin{aligned} 1 &= \sum_{i=1}^{n+1} y_i^2 = \sum_{i=1}^n (tu_i)^2 + (1-t)^2 \\ 1 - (1 - 2t + t^2) &= t^2 |u|^2 \\ 2 - t &= t|u|^2 \iff t = \frac{2}{|u|^2 + 1} \end{aligned}$$

Thus, we have that

$$y = \left( \frac{2u}{|u|^2 + 1}, 1 - \frac{2}{|u|^2 + 1} \right) = \frac{(2u_1, \dots, 2u_n, |u|^2 - 1)}{|u|^2 + 1}$$

Hence we have that every  $u \in \mathbb{R}^n$  has a preimage on  $\mathbb{S}^n \setminus \{N\}$ , and thus  $\sigma$  is surjective.

We can now conclude that  $\sigma$  is a bijection, with the inverse stated above.

**(c)** We note that  $\tilde{\sigma} \circ \sigma^{-1} : \mathbb{R}^n \rightarrow \mathbb{R}^n$ , since both stereographic projections are bijective. Then, suppose that  $u \in \mathbb{R}^n$ , and from the inverse computed in **(b)** we see

$$\tilde{\sigma}(\sigma^{-1}(u)) = \tilde{\sigma} \left( \frac{(2u_1, \dots, 2u_n, |u|^2 - 1)}{|u|^2 + 1} \right)$$

and by definition, we recall that  $\tilde{\sigma}(x) = -\sigma(-x)$ , thus,

$$\tilde{\sigma}(\sigma^{-1}(u)) = -\sigma \left( -\frac{(2u_1, \dots, 2u_n, |u|^2 - 1)}{|u|^2 + 1} \right) = -\sigma \left( \frac{(-2u_1, \dots, -2u_n, -|u|^2 + 1)}{|u|^2 + 1} \right)$$

and applying the definition of  $\sigma$  we see,

$$\tilde{\sigma}(\sigma^{-1}(u)) = -\sigma \left( \frac{(-2u_1, \dots, -2u_n, -|u|^2 + 1)}{|u|^2 + 1} \right) = -\frac{(-2u_1, \dots, -2u_n)}{(|u|^2 + 1)(1 + |u|^2 - 1)} = \frac{(2u_1, \dots, 2u_n)}{(|u|^2 + 1)|u|^2}$$

Which is smooth except at the origin, which makes sense considering the stereographic projections get the origin from opposite poles. Further, we recall that both  $\sigma$  and  $\tilde{\sigma}$  are invertible, and inverse will thus also be smooth. Then, we have a diffeomorphism and hence the two charts are smoothly compatible, and hence the atlas  $\{(\sigma, \mathbb{S}^n \setminus \{N\}), (\tilde{\sigma}, \mathbb{S}^n \setminus \{S\})\}$  is a smooth atlas and gives a smooth structure on  $\mathbb{S}^n$ .

**(d) FINISH ME**

**Question 4**

(a)