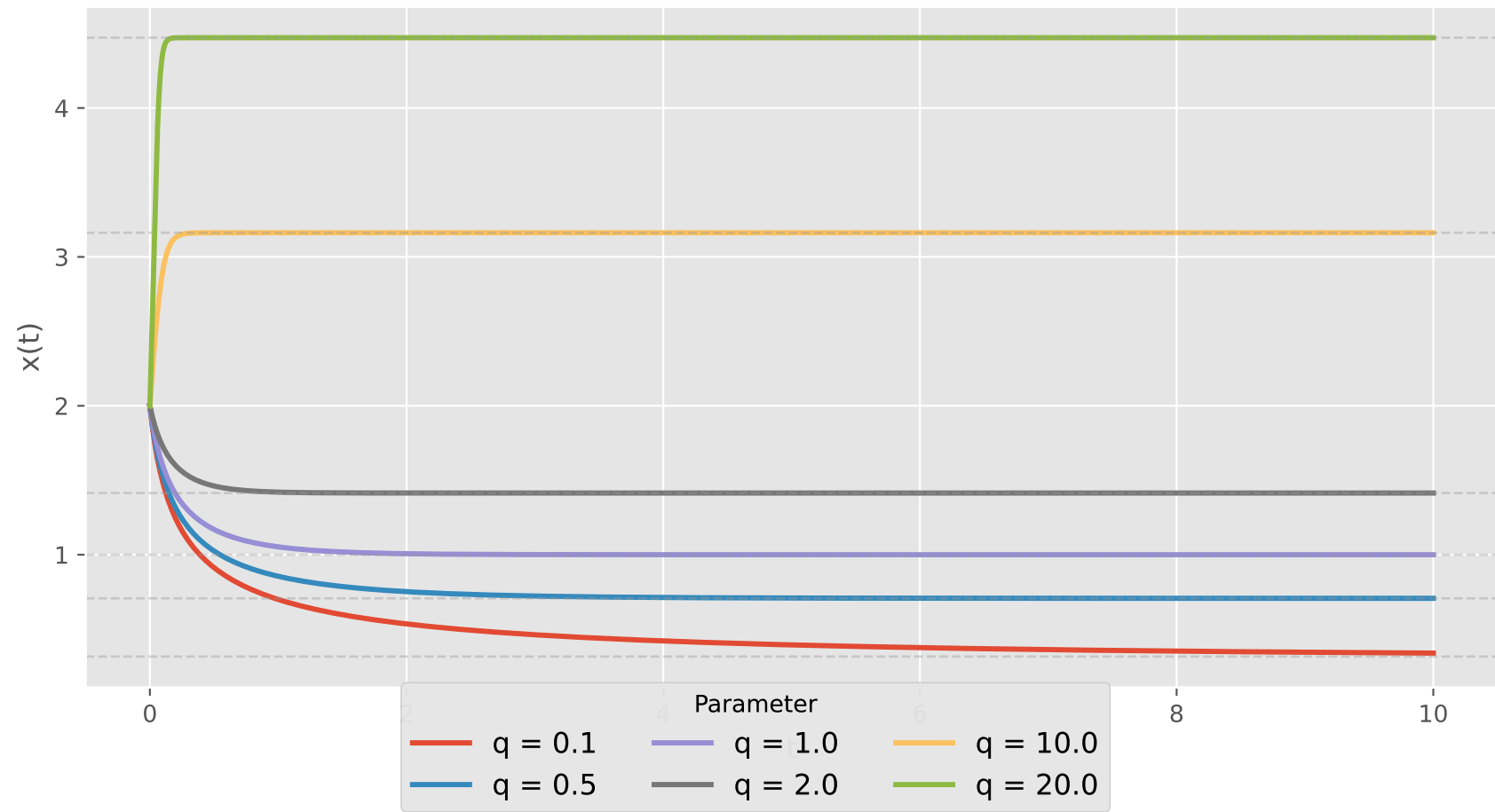
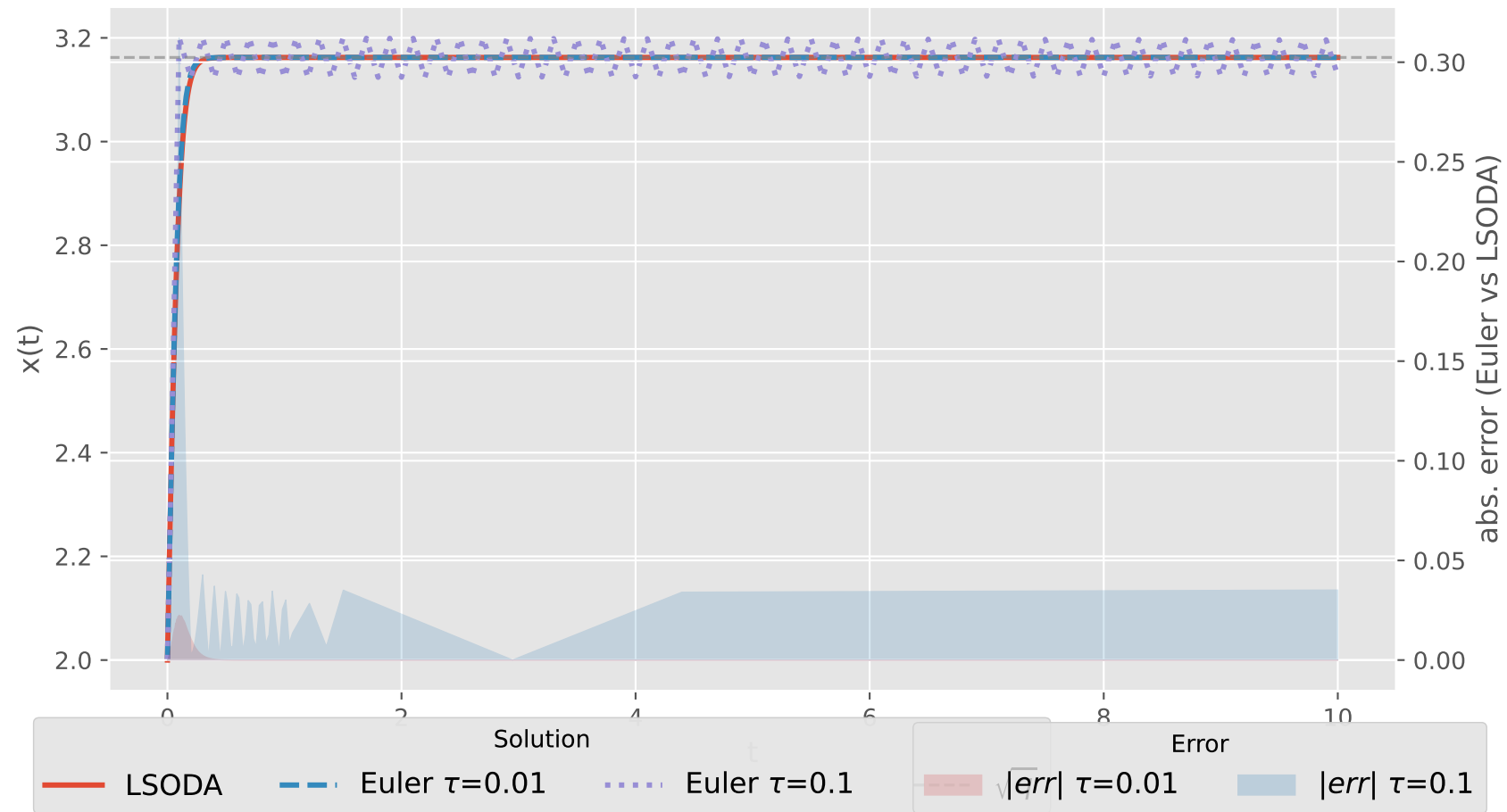


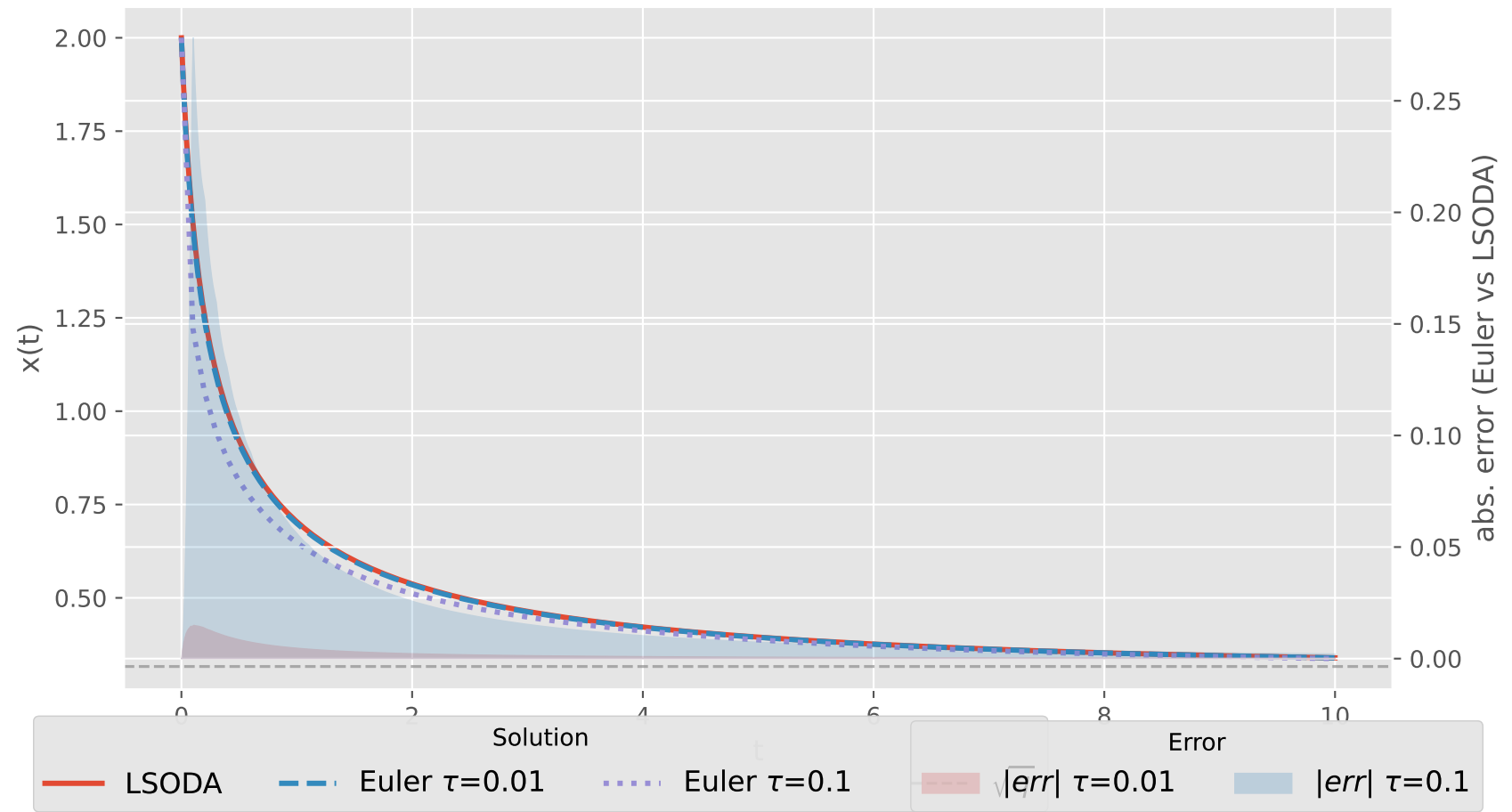
Cubic ODE parameter sweep (equilibria shown)



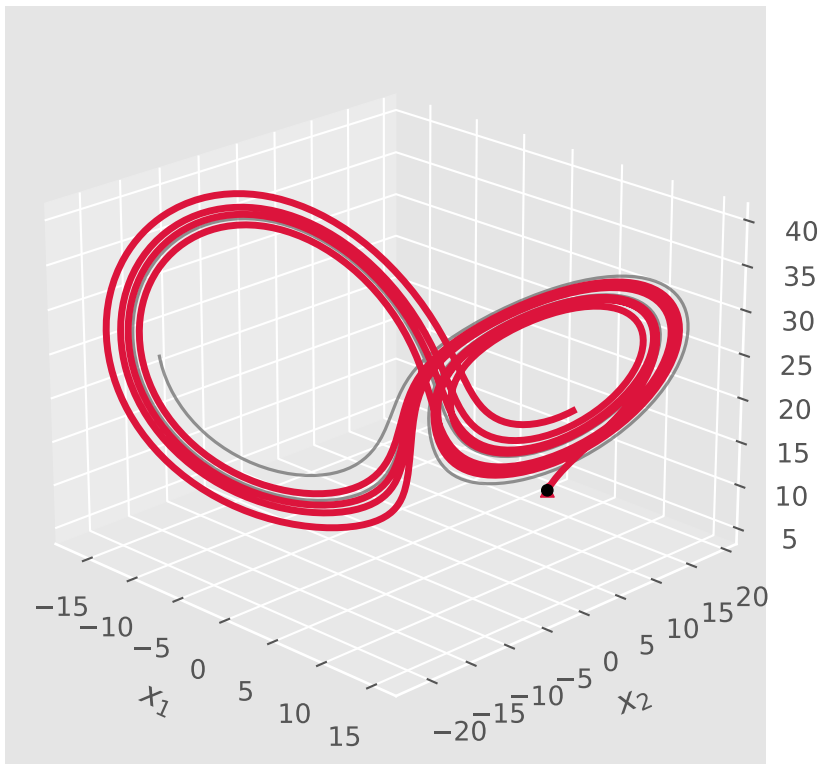
Method comparison for $q = 10.0$



Method comparison for $q = 0.1$

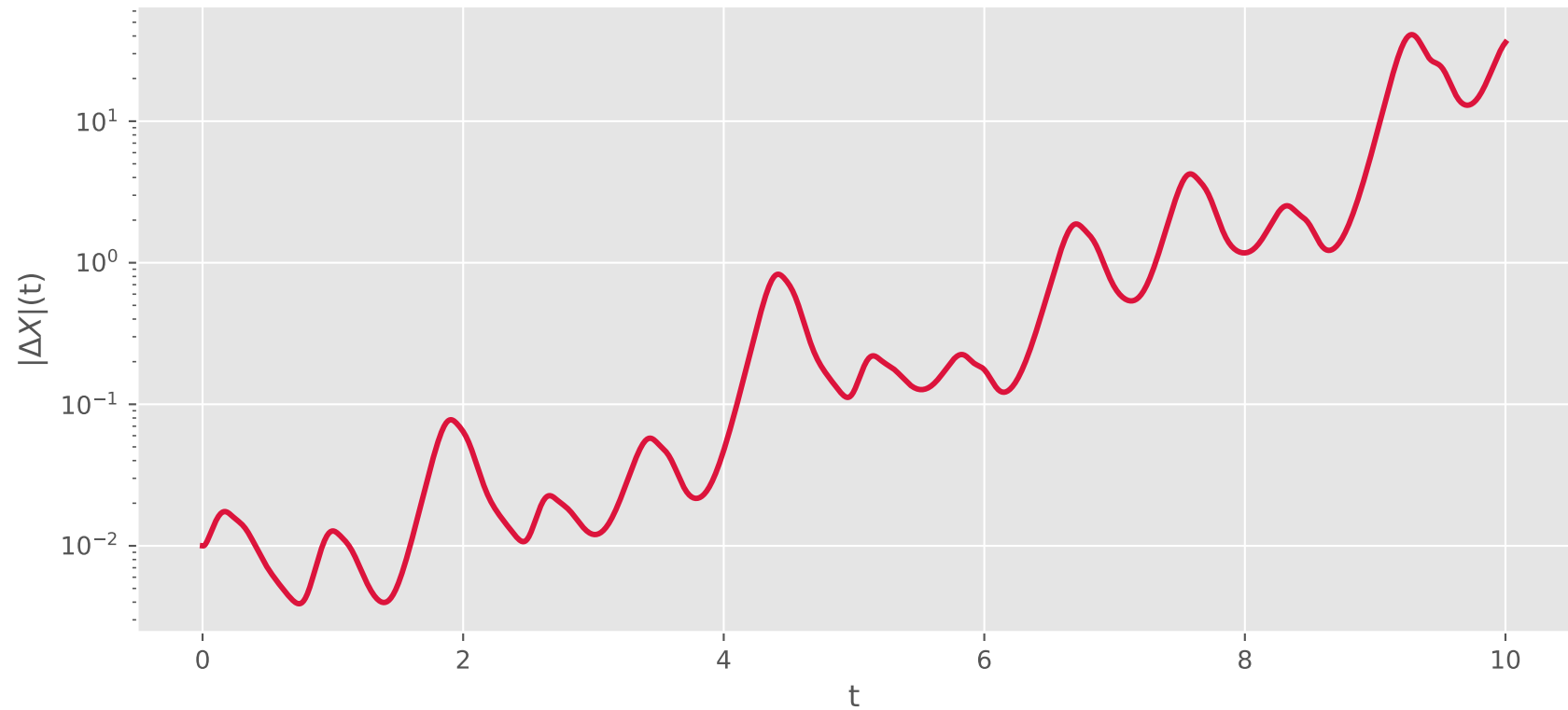


Lorenz sensitivity to perturbing $x_2(0)$



— Baseline — $x_2(0) = 5.01$ perturbed

Lorenz trajectory separation



Answers

(b) Long-term behaviour as a function of q

\textbf{(b) Long-term behaviour as a function of q .}

We solve $x'(t) = qx - x^3$ with $x(0) = 2$ and $q > 0$. The equilibria are 0 and $\pm\sqrt{q}$. For $q > 0$, $x = 0$ is unstable and $x = \pm\sqrt{q}$ are asymptotically stable since $f'(x) = q - 3x^2$ implies $f'(\pm\sqrt{q}) = -2q < 0$.

With $x(0) = 2 > 0$, the trajectory approaches the stable equilibrium $+\sqrt{q}$:

```
\[
\begin{cases}
q < 4 \!: & \sqrt{q} < 2 \rightarrow x(t) \text{ decreases monotonically to } \sqrt{q}, \\[2pt]
q = 4 \!: & x(t) \equiv 2 \text{ (equilibrium; adding this case gives a flat line at } 2), \\[2pt]
q > 4 \!: & \sqrt{q} > 2 \rightarrow x(t) \text{ increases monotonically to } \sqrt{q}.
\end{cases}
```

This matches the parameter-sweep plot: for small q the approach to \sqrt{q} is slower, so at $T = 10$ the solution can still be slightly above the limiting value.

(c) Method comparison (Euler vs. LSODA) and effect of q

\textbf{(c) Method comparison (Euler vs. LSODA) and effect of q .}

We compare explicit Euler with step sizes $\tau = 0.1$ and $\tau = 0.01$ against an LSODA reference on $[0, 10]$.

\emph{Accuracy order.} Explicit Euler is first order: the global error scales as $\mathcal{O}(\tau)$ for smooth problems on a fixed time horizon. Hence, reducing τ from 0.1 to 0.01 should reduce the error by about a factor of 10 (modulo transients).

\emph{Linear stability near the attractor.} Linearizing at the stable equilibrium $x^* = \sqrt{q}$ gives $y' = f'(x^*)y = -2qy$. For the test equation $y' = \lambda y$ with $\lambda = -2q$, explicit Euler is stable iff

```
\[
|1 - \tau\lambda| < 1 \quad \Longleftrightarrow \quad 0 < \tau < \frac{1}{q}.
```

\emph{Case $q = 10$.} The stability bound is $\tau < 0.1$, so $\tau = 0.1$ lies on the boundary and yields visible phase/amplitude error and mild oscillation around the equilibrium; $\tau = 0.01$ is well inside the stable region and closely tracks LSODA. Empirically, the absolute error curve for $\tau = 0.1$ sits roughly an order of magnitude above that for $\tau = 0.01$ over most of $[0, 10]$, consistent with first-order convergence and the stability-edge effect at $\tau = 0.1$.

\emph{Case $q = 0.1$.} The bound is $\tau < 10$, so both $\tau = 0.1$ and 0.01 are deep inside the stability region and the dynamics are slow. Both Euler solutions lie very close to LSODA; the $\tau = 0.01$ error is still smaller (by about the expected $\sim 10\times$ factor), but the difference is barely visible in the solution plot because all errors are small.

(d) Sensitivity for the Lorenz system

\textbf{(d) Sensitivity for the Lorenz system.}

With standard parameters $(a, b, c) = (10, 25, 8/3)$ the Lorenz system exhibits sensitive dependence on initial conditions (positive largest Lyapunov exponent). We integrate on $[0, 10]$ with explicit Euler ($\tau = 0.001$) from $(x_1(0), x_2(0), x_3(0)) = (10, 5, 12)$ and from the perturbed $(10, 5.01, 12)$.

The two trajectories coincide initially but separate clearly after a short time, ultimately exploring different parts of the attractor. This is the expected behaviour for a chaotic system: for a small perturbation $\|\delta x(0)\|$ the separation typically grows like $\|\delta x(t)\| \approx \|\delta x(0)\| e^{\lambda t}$ with $\lambda > 0$.

\emph{Conclusion.} Yes, the solution changes significantly when $x_2(0)$ is perturbed to 5.01; the 3D plot makes this divergence clearly visible.