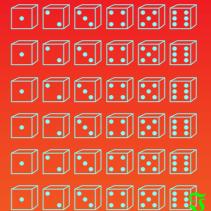
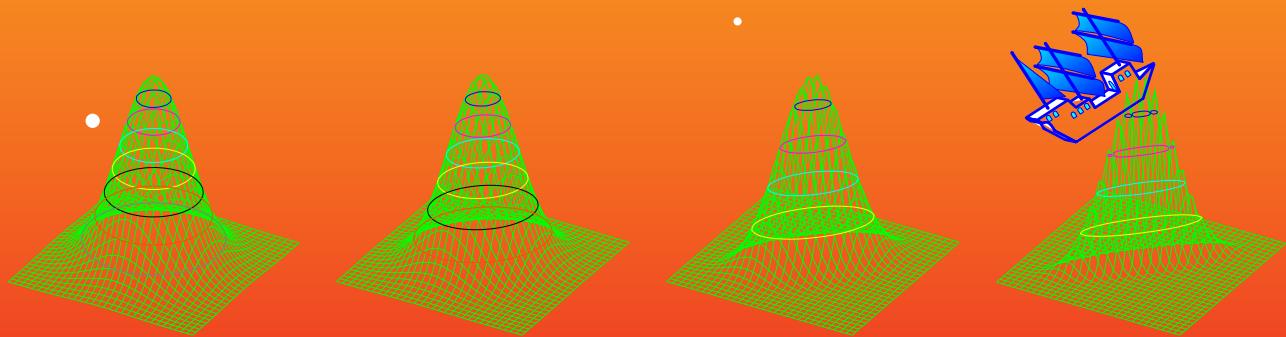
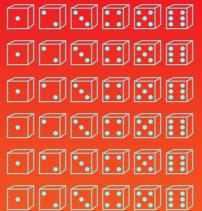


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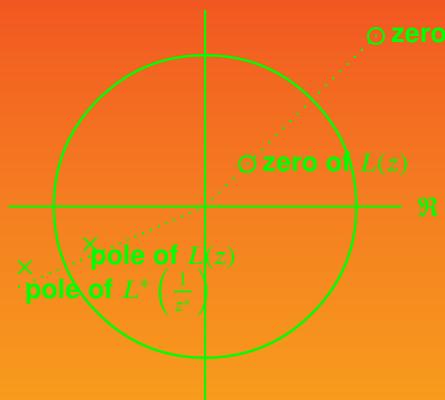
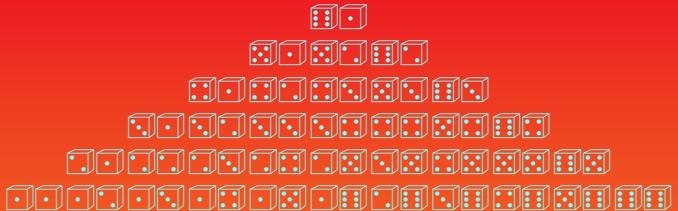
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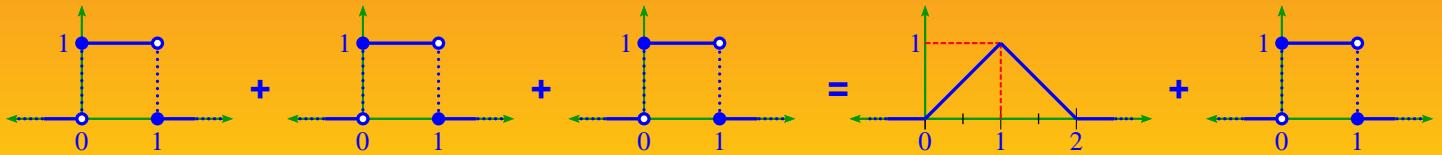
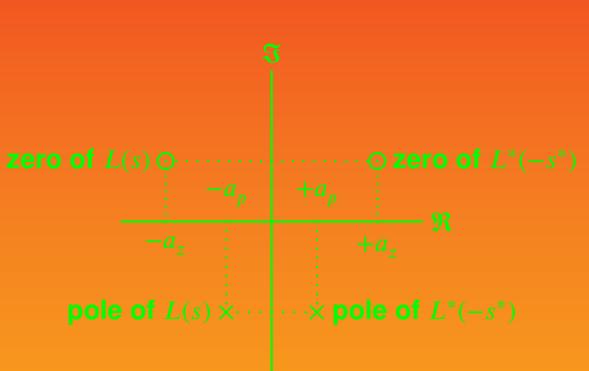
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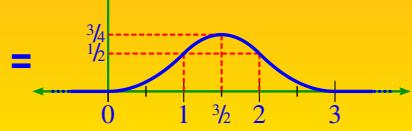
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Daniel J. Greenhoe



Signal Processing ABCs series
volume 2







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The ship appearing throughout this text is loosely based on the *Golden Hind*, a sixteenth century English galleon famous for circumnavigating the globe.¹



¹  Paine (2000) page 63 (Golden Hind)

“Here, on the level sand,
Between the sea and land,
What shall I build or write
Against the fall of night? ”



“Tell me of runes to grave
That hold the bursting wave,
Or bastions to design
For longer date than mine. ”

Alfred Edward Housman, English poet (1859–1936) ²



“The uninitiated imagine that one must await inspiration in order to create. That is a mistake. I am far from saying that there is no such thing as inspiration; quite the opposite. It is found as a driving force in every kind of human activity, and is in no wise peculiar to artists. But that force is brought into action by an effort, and that effort is work. Just as appetite comes by eating so work brings inspiration, if inspiration is not discernible at the beginning. ”

Igor Fyodorovich Stravinsky (1882–1971), Russian-born composer ³



“As I think about acts of integrity and grace, I realise that there is nothing in my knowledge to compare with Frege's dedication to truth. His entire life's work was on the verge of completion, much of his work had been ignored to the benefit of men infinitely less capable, his second volume was about to be published, and upon finding that his fundamental assumption was in error, he responded with intellectual pleasure clearly submerging any feelings of personal disappointment. It was almost superhuman and a telling indication of that of which men are capable if their dedication is to creative work and knowledge instead of cruder efforts to dominate and be known. ”

Bertrand Russell (1872–1970), British mathematician, in a 1962 November 23 letter to Dr. van Heijenoort. ⁴



² quote:  Housman (1936), page 64 (“Smooth Between Sea and Land”),  Hardy (1940) (section 7)

image: <http://en.wikipedia.org/wiki/Image:Housman.jpg>

³ quote:  Ewen (1961), page 408,  Ewen (1950)

image: http://en.wikipedia.org/wiki/Image:Igor_Stravinsky.jpg

⁴ quote:  Heijenoort (1967), page 127

image: <http://www-history.mcs.st-andrews.ac.uk/PictDisplay/Russell.html>

SYMBOLS

“rugula XVI. Quae vero praesentem mentis attentionem non requirunt, etiamsi ad conclusionem necessaria sint, illa melius est per brevissimas notas designare quam per integras figuras: ita enim memoria non poterit falli, nec tamen interim cogitatio distrahetur ad haec retinenda, dum aliis deducendis incumbit.”



“Rule XVI. As for things which do not require the immediate attention of the mind, however necessary they may be for the conclusion, it is better to represent them by very concise symbols rather than by complete figures. It will thus be impossible for our memory to go wrong, and our mind will not be distracted by having to retain these while it is taken up with deducing other matters.”

René Descartes (1596–1650), French philosopher and mathematician ⁵



“In signs one observes an advantage in discovery which is greatest when they express the exact nature of a thing briefly and, as it were, picture it; then indeed the labor of thought is wonderfully diminished.”

Gottfried Leibniz (1646–1716), German mathematician, ⁶

Symbol list

symbol	description
numbers:	
\mathbb{Z}	integers
\mathbb{W}	whole numbers
\mathbb{N}	natural numbers
\mathbb{Z}^+	non-positive integers

...continued on next page...

⁵quote: [Descartes \(1684a\)](#) (rugula XVI), translation: [Descartes \(1684b\)](#) (rule XVI), image: Frans Hals (circa 1650), <http://en.wikipedia.org/wiki/Descartes>, public domain

⁶quote: [Cajori \(1993\)](#) (paragraph 540), image: http://en.wikipedia.org/wiki/File:Gottfried_Wilhelm_von_Leibniz.jpg, public domain

symbol	description
\mathbb{Z}^-	negative integers $\dots, -3, -2, -1$
\mathbb{Z}_o	odd integers $\dots, -3, -1, 1, 3, \dots$
\mathbb{Z}_e	even integers $\dots, -4, -2, 0, 2, 4, \dots$
\mathbb{Q}	rational numbers $\frac{m}{n}$ with $m \in \mathbb{Z}$ and $n \in \mathbb{Z} \setminus 0$
\mathbb{R}	real numbers completion of \mathbb{Q}
\mathbb{R}^+	non-negative real numbers $[0, \infty)$
\mathbb{R}^-	non-positive real numbers $(-\infty, 0]$
\mathbb{R}^+	positive real numbers $(0, \infty)$
\mathbb{R}^-	negative real numbers $(-\infty, 0)$
\mathbb{R}^*	extended real numbers $\mathbb{R}^* \triangleq \mathbb{R} \cup \{-\infty, \infty\}$
\mathbb{C}	complex numbers
\mathbb{F}	arbitrary field (often either \mathbb{R} or \mathbb{C})
∞	positive infinity
$-\infty$	negative infinity
π	pi 3.14159265 ...
relations:	
\circledR	relation
\circledcirc	relational and
$X \times Y$	Cartesian product of X and Y
(Δ, ∇)	ordered pair
$ z $	absolute value of a complex number z
$=$	equality relation
\triangleq	equality by definition
\rightarrow	maps to
\in	is an element of
\notin	is not an element of
$D(\circledR)$	domain of a relation \circledR
$I(\circledR)$	image of a relation \circledR
$R(\circledR)$	range of a relation \circledR
$N(\circledR)$	null space of a relation \circledR
set relations:	
\subseteq	subset
\subsetneq	proper subset
\supseteq	super set
\supsetneq	proper superset
$\not\subseteq$	is not a subset of
$\not\subsetneq$	is not a proper subset of
operations on sets:	
$A \cup B$	set union
$A \cap B$	set intersection
$A \Delta B$	set symmetric difference
$A \setminus B$	set difference
A^c	set complement
$ \cdot $	set order
$\mathbb{1}_A(x)$	set indicator function or characteristic function
logic:	
1	“true” condition
0	“false” condition
\neg	logical NOT operation

...continued on next page...

symbol	description
\wedge	logical AND operation
\vee	logical inclusive OR operation
\oplus	logical exclusive OR operation
\Rightarrow	“implies”;
\Leftarrow	“implied by”;
\Leftrightarrow	“if and only if”;
\forall	universal quantifier:
\exists	existential quantifier:
order on sets:	
\vee	join or least upper bound
\wedge	meet or greatest lower bound
\leq	reflexive ordering relation
\geq	reflexive ordering relation
$<$	irreflexive ordering relation
$>$	irreflexive ordering relation
measures on sets:	
$ X $	order or counting measure of a set X
distance spaces:	
d	metric or distance function
linear spaces:	
$\ \cdot\ $	vector norm
$\ \cdot\ $	operator norm
$\langle \Delta \nabla \rangle$	inner-product
$\text{span}(V)$	span of a linear space V
algebras:	
\Re	real part of an element in a $*$ -algebra
\Im	imaginary part of an element in a $*$ -algebra
set structures:	
T	a topology of sets
R	a ring of sets
A	an algebra of sets
\emptyset	empty set
2^X	power set on a set X
sets of set structures:	
$\mathcal{T}(X)$	set of topologies on a set X
$\mathcal{R}(X)$	set of rings of sets on a set X
$\mathcal{A}(X)$	set of algebras of sets on a set X
classes of relations/functions/operators:	
2^{XY}	set of <i>relations</i> from X to Y
Y^X	set of <i>functions</i> from X to Y
$S_j(X, Y)$	set of <i>surjective</i> functions from X to Y
$I_j(X, Y)$	set of <i>injective</i> functions from X to Y
$B_j(X, Y)$	set of <i>bijective</i> functions from X to Y
$B(X, Y)$	set of <i>bounded</i> functions/operators from X to Y
$L(X, Y)$	set of <i>linear bounded</i> functions/operators from X to Y
$C(X, Y)$	set of <i>continuous</i> functions/operators from X to Y
specific transforms/operators:	
\tilde{F}	<i>Fourier Transform</i> operator (Definition P.2 page 333)
\hat{F}	<i>Fourier Series</i> operator

...continued on next page...

symbol	description
\check{F}	<i>Discrete Time Fourier Series operator</i> (Definition Q.1 page 343)
Z	<i>Z-Transform operator</i> (Definition R.4 page 354)
$\tilde{f}(\omega)$	<i>Fourier Transform of a function $f(x) \in L^2_{\mathbb{R}}$</i>
$\check{x}(\omega)$	<i>Discrete Time Fourier Transform of a sequence $(x_n \in \mathbb{C})_{n \in \mathbb{Z}}$</i>
$\check{x}(z)$	<i>Z-Transform of a sequence $(x_n \in \mathbb{C})_{n \in \mathbb{Z}}$</i>

SYMBOL INDEX

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Part I

Statistical Analysis

CHAPTER 1

EXPECTATION OPERATOR

1.1 Definitions

In a *probability space* (Ω, \mathbb{E}, P) (Definition A.2 page 151), all probability information is contained in the *measure* P . Often times this information is overwhelming and a simpler statistic, which does not offer so much information, is sufficient. Some of the most common statistics can be conveniently expressed in terms of the *expectation operator* E .

Definition 1.1. Let (Ω, \mathbb{E}, P) be a PROBABILITY SPACE (Definition A.2 page 151) and X a RANDOM VARIABLE (Definition B.1 page 160) on (Ω, \mathbb{E}, P) with PROBABILITY DENSITY FUNCTION p_x .

D E F The *expectation operator* E_x on X is defined as

$$E_x X \triangleq \int_{x \in \mathbb{E}} x p_x(x) dx.$$

We already said that a *random variable* X is neither random nor a variable, but is rather a function of an underlying process that does appear to be random. However, because it is a function of a process that does appear random, the *random variable* X also appears to be random. That is, if we don't know the outcome of the underlying experimental process, then we also don't know for sure what X is, and so X does indeed appear to be random. However, even though X appears to be random, the expected value $E_x X$ of X is **not random**. Rather it is a fixed value (like 0 or 7.9 or -2.6).

Two common statistics that are conveniently expressed in terms of the expectation operator are the *mean* and *variance*. The mean is an indicator of the “middle” of a probability distribution and the variance is an indicator of the “spread”.

Definition 1.2. Let X be a RANDOM VARIABLE on the PROBABILITY SPACE (Ω, \mathbb{E}, P) .

- D E F**
- (1). The **mean** μ_X of X is $\mu_X \triangleq E_x X$
 - (2). The **variance** $\text{Var}(X)$ or σ_X^2 of X is $\text{Var}(X) \triangleq E_x [(X - E_x X)^2]$

1.2 Expectation as a linear operator

The next theorem demonstrates that the operator E is a *linear operator* (Definition O.3 page 304)—which in turn makes E part of a distinguished club of operators along with fellow member operators differentiation $\frac{d}{dx}$, integration $\int dx$, Laplace L , Fourier \tilde{F} , z-transform Z , etc. Because E is a linear operator, it immediately inherits all the properties that its linear operator birthright grants it (Corollary 1.1 page 4).

Theorem 1.1 (Linearity of E). ¹ Let X be a RANDOM VARIABLE on a PROBABILITY SPACE (Ω, \mathbb{E}, P) .

T H M	$E_x(aX + bY + c) = (aE_x X) + (bE_x Y) + c \quad \forall a, b, c \in \mathbb{R} \quad (\text{LINEAR})$
-------------	---

PROOF:

$$\begin{aligned}
 E_{xy}(aX + bY + c) &\triangleq \int_{x \in \mathbb{R}} \int_{y \in \mathbb{R}} [ax + by + c] p_{xy}(x, y) dy dx \quad \text{by definition of } E \text{ (Definition 1.1 page 3)} \\
 &= \int_{x \in \mathbb{R}} \int_{y \in \mathbb{R}} ax p_{xy}(x, y) dy dx + \int_{x \in \mathbb{R}} \int_{y \in \mathbb{R}} by p_{xy}(x, y) dy dx + \int_{x \in \mathbb{R}} \int_{y \in \mathbb{R}} c p_{xy}(x, y) dy dx \\
 &= \int_{x \in \mathbb{R}} ax \underbrace{\int_{y \in \mathbb{R}} p_{xy}(x, y) dy}_{p_x(x)} dx + \int_{y \in \mathbb{R}} by \underbrace{\int_{x \in \mathbb{R}} p_{xy}(x, y) dx}_{p_y(y)} dy + c \underbrace{\int_{y \in \mathbb{R}} \int_{x \in \mathbb{R}} p_{xy}(x, y) dx dy}_{1} \\
 &= a \underbrace{\int_{x \in \mathbb{R}} x p_x(x) dx}_{EX} + b \underbrace{\int_{y \in \mathbb{R}} y p_y(y) dy}_{EY} + c \\
 &= \boxed{(aE_x X) + (bE_y Y) + c}
 \end{aligned}$$



Corollary 1.1. Let E be the EXPECTATION OPERATOR over a PROBABILITY SPACE (Ω, \mathbb{E}, P) . Let $sPLL$ be a VECTOR SPACE OF RANDOM VARIABLES over (Ω, \mathbb{E}, P) .

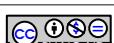
C O R	(1). $E\emptyset = \emptyset$ and (2). $E(-X) = -(EX) \quad \forall X \in L^2_F$ and (3). $E(X - Y) = EX - EY \quad \forall X, Y \in L^2_F$ and	(4). $E\left(\sum_{n=1}^N \alpha_n X_n\right) = \sum_{n=1}^N \alpha_n (EX_n) \quad \forall \alpha_n \in \mathbb{F}, \quad \forall X \in L^2_F$
-------------	---	--

PROOF: These all follow immediately from the fact that E is a *linear operator* and from Theorem O.1 (page 304). ⇒

Remark 1.1. Projecting a stochastic process onto a basis often yields valuable insights into the nature of the underlying data. Typical projection operators include the Fourier operator \tilde{F} , Laplace L , and z-transform Z ...not to mention wavelet operators. But note that any such projection on a random sequence simply produces another random sequence. For example, the Fourier transform $\tilde{F}x(n)$ of a random sequence $x(n)$ is another random sequence.

One way to overcome this difficulty is to simply invoke a *sampling* operator $Sx(n)$, yielding a deterministic sequence, and then take the Fourier transform of the resulting deterministic sequence. The problem here is that every time you resample the sequence, you will very likely get a different Fourier transform.

¹ Haykin (2014) page 107 (“PROPERTY 1 Linearity”), Wilks (1963b), page 73 §§3.2 “Mean value of a random variable”



Arguably a better approach (and the standard one at that) is to first invoke the expectation operator $E(n)$, also yielding a deterministic sequence.

The good news here is that because E and all the above mentioned operators are *linear*, we can do all the standard arithmetic acrobatics associated with linear algebra operators (next corollary).

Corollary 1.2. Let M and N be LINEAR OPERATORS (Definition O.3 page 304).

C O R	1. $E(MN) = (EM)N \quad \forall E \in \mathcal{L}(Z, W), M \in \mathcal{L}(Y, Z), N \in \mathcal{L}(X, Y)$	(ASSOCIATIVE)
	2. $E(M + N) = (EM) + (EN) \quad \forall E \in \mathcal{L}(Y, Z), M \in \mathcal{L}(X, Y), N \in \mathcal{L}(X, Y)$	(LEFT DISTRIBUTIVE)
	3. $(E + M)N = (EN) + (MN) \quad \forall E \in \mathcal{L}(Y, Z), M \in \mathcal{L}(Y, Z), N \in \mathcal{L}(X, Y)$	(RIGHT DISTRIBUTIVE)
	4. $\alpha(EM) = (\alpha E)M = E(\alpha M) \quad \forall E \in \mathcal{L}(Y, Z), M \in \mathcal{L}(X, Y), \alpha \in \mathbb{F}$	(HOMOGENEOUS)

PROOF: These all follow immediately from the fact that E is a *linear operator* (Theorem 1.1 page 4) and from properties of all linear operators (Theorem O.4 page 307). \Rightarrow

Corollary 1.3. Let X be a RANDOM VARIABLE on a PROBABILITY SPACE (Ω, \mathbb{E}, P) .

C O R	$\text{Var}(aX + b) = a^2 \text{Var}(X) \quad \forall a, b \in \mathbb{R}$
	$\text{Var}(X) = E_x(X^2) - (E_x X)^2$

PROOF:

$$\begin{aligned}
 \text{Var}(X) &\triangleq E_x[(X - E_x X)^2] && \text{by definition of } \text{Var} && (\text{Definition 1.2 page 3}) \\
 &= E_x[X^2 - 2XE_x X + (E_x X)^2] && \text{by Binomial Theorem} \\
 &= E_x X^2 - E_x[2XE_x X] + E_x(E_x X)^2 && \text{by linearity of } E && (\text{Theorem 1.1 page 4}) \\
 &= E_x X^2 - 2(E_x X)[E_x X] + (E_x X)^2 \\
 &= E_x(X^2) - (E_x X)^2 \\
 \text{Var}(aX + b) &= E_x(aX + b)^2 - [E_x(aX + b)]^2 \\
 &= E_x(a^2 X^2 + 2abX + b^2) - [a(E_x X) + b]^2 \\
 &= a^2 E_x X^2 + 2abE_x X + b^2 - [a^2 [E_x X]^2 + 2abE_x X + b^2] && \text{by linearity of } E && (\text{Theorem 1.1 page 4}) \\
 &= a^2 [E_x X^2 - (E_x X)^2] \\
 &\triangleq a^2 \text{Var}(X) && \text{by previous result}
 \end{aligned}$$

\Rightarrow

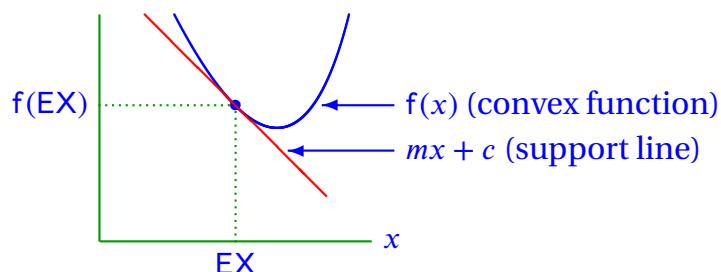


Figure 1.1: Jensen's inequality

Jensen's inequality is an extremely useful application of *convexity* (Definition M.9 page 284) to the *expectation* operator. Jensen's inequality is stated in Corollary 1.4 (next) and illustrated in Figure 1.1 (page 5).

Corollary 1.4 (Jensen's inequality). ² Let f be a function in $\mathbb{R}^{\mathbb{R}}$ and X be a RANDOM VARIABLE on (Ω, \mathbb{E}, P) .

C O R	$\{f \text{ is CONVEX}\} \implies \{f(\mathbb{E}X) \leq \mathbb{E}f(X)\}$
-------------	---

PROOF:

1. Proof 1: Let $mx + c$ be a “support line” under $f(x)$ (Figure 1.1 page 5) such that

$$\begin{aligned} mx + c &< f(x) \quad \text{for } x \neq \mathbb{E}X \\ mx + c &= f(x) \quad \text{for } x = \mathbb{E}X. \end{aligned}$$

Then

$$\begin{aligned} f(\mathbb{E}X) &= m[\mathbb{E}X] + c \\ &= \mathbb{E}[mX + c] \\ &\leq \mathbb{E}f(X) \end{aligned}$$

2. Proof 2 (alternate proof):

$$\begin{aligned} f(\mathbb{E}X) &\triangleq f\left(\sum_{x \in \mathbb{E}} x P(x)\right) \\ &\leq \sum_{x \in \mathbb{E}} f(x)P(x) \quad \text{by Jensen's inequality for convex sets} \quad (\text{Theorem M.1 page 284}) \end{aligned}$$

Example 1.1. ³ Some examples of *Jensen's Inequality* (Corollary 1.4 page 6) applied to the *expectation operator* are the following:

E X	$(\mathbb{E}X)^{-1} < \mathbb{E}(X^{-1})$ $\mathbb{E}(\log X) < \log(\mathbb{E}X)$ $e^{-\mathbb{E}X} \leq \mathbb{E}[e^{-X}]$
--------	---

Theorem 1.2 (Law of the Unconscious Statistician). ⁴

T H M	$\mathbb{E}[g(X)] = \int_{x \in \mathbb{R}} g(x)p_x(x) dx$
-------------	--

1.3 Expectation inequalities

Theorem 1.3 (Markov's inequality). ⁵ Let $X : \Omega \rightarrow [0, \infty)$ be a non-negative valued RANDOM VARIABLE and $a \in (0, \infty)$. Then

T H M	$P\{X \geq a\} \leq \frac{1}{a} \mathbb{E}X$
-------------	--

² Shao (2003) page 31 (“1.3 Distributions and Their Characteristics”), Cover and Thomas (1991), page 25, Jensen (1906), pages 179–180

³ Shao (2003) pages 31–32 (“Example 1.18”), Dekking et al. (2006) page 110 (“8.5 Solutions to the quick exercises”)

⁴ Suhov et al. (2005) page 145 ((2.69)), Allen (2018) page 490 (18.3.4 The Law of the Unconscious Statistician), Papoulis (1990) page 124 (Fundamental Theorem)

⁵ Ross (1998), page 395



PROOF:

$$\begin{aligned} I &\triangleq \begin{cases} 1 & \text{for } X \geq a \\ 0 & \text{for } X < a \end{cases} \\ aI &\leq X \\ I &\leq \frac{1}{a}X \\ EI &\leq E\left(\frac{1}{a}X\right) \end{aligned}$$

$$\begin{aligned} P\{X \geq a\} &= 1 \cdot P\{X \geq a\} + 0 \cdot P\{X < a\} \\ &= EI \\ &\leq E\left(\frac{1}{a}X\right) \\ &= \frac{1}{a}EX \end{aligned}$$



Theorem 1.4 (Chebyshev's inequality). ⁶ Let X be a RANDOM VARIABLE with mean μ and variance σ^2 .

T H M	$P\{ X - \mu \geq a\} \leq \frac{\sigma^2}{a^2}$
-------------	---

PROOF:

$$\begin{aligned} P\{|X - \mu| \geq a\} &= P\{(X - \mu)^2 \geq a^2\} \\ &\leq \frac{1}{a^2} E(X - \mu)^2 && \text{by Markov's inequality} && (\text{Theorem 1.3 page 6}) \\ &= \frac{\sigma^2}{a^2} \end{aligned}$$



Theorem 1.5 (Kolmogorov's inequality). ⁷ Let X be a RANDOM VARIABLE with mean μ and variance σ^2 .

T H M	$\left\{ \begin{array}{ll} (A). & (x_n) \text{ are INDEPENDENT} \\ (B). & \text{Each } x_n \text{ has ZERO-MEAN} \\ (C). & \text{Each } x_n \text{ has variance } \sigma^2 \end{array} \text{ and } \right\} \implies P\left[\left \sum_{n=1}^N x_n\right < \lambda \sum_{n=1}^N x_n^2\right] \geq 1 - \frac{1}{\lambda^2}$
-------------	--

1.4 Conditional expectation

Sometimes the problem of finding the expected value of a *random variable* X can be simplified by “conditioning X on Y ”. It has already been pointed out in Section 1.1 (page 3) that the expected value $E_x X$ of X is **not random**. On the other hand, note that $E(X|Y)$ is **random**. This is because $E(X|Y)$ is a function of Y . That is, once we know that Y equals some fixed value y (like 0 or 2.7 or -5.1) then $E(X|Y = y)$ is also fixed. However, if we don't know the value of Y , then Y is still a *random variable* and the expression $E(X|Y)$ is also random (a function of *random variable* Y).

⁶ Ross (1998), page 396

⁷ Wilks (1963b), page 107 (§4.5 “Kolmogorov's inequality”)

Theorem 1.6. ⁸ Let X and Y be RANDOM VARIABLES. Then

T H M	$E_x X = E_y E_{x y}(X Y)$
-------------	----------------------------

PROOF:

$$\begin{aligned}
 E_y E_{x|y}(X|Y) &\triangleq E_y \left[\int_{x \in \mathbb{R}} x p(X=x|Y) dx \right] && \text{by definition of } E && (\text{Definition 1.1 page 3}) \\
 &\triangleq \int_{y \in \mathbb{R}} \left[\int_{x \in \mathbb{R}} x p(x|Y=y) dx \right] p(y) dy && \text{by definition of } E && (\text{Definition 1.1 page 3}) \\
 &= \int_{y \in \mathbb{R}} \int_{x \in \mathbb{R}} x p(x|y) p(y) dx dy \\
 &= \int_{x \in \mathbb{R}} x \int_{y \in \mathbb{R}} p(x,y) dy dx && \text{by Theorem B.3 page 161} \\
 &= \int_{x \in \mathbb{R}} x p(x) dx && \text{by Theorem B.3 page 161} \\
 &\triangleq E_x X && \text{by definition of } E && (\text{Definition 1.1 page 3})
 \end{aligned}$$



1.5 Expectation inner product space

When possible, we like to generalize any given mathematical structure to a more general mathematical structure and then take advantage of the properties of that more general structure. Such a generalization can be done with *random variables*. Random variables can be viewed as vectors in a vector space. Furthermore, the expectation of the product of two *random variables* (e.g. $E(XY)$) can be viewed as an *inner product* in an *inner product space*. Since we have an *inner product space*, we can then immediately use all the properties of *inner product spaces*, *normed spaces*, *vector spaces*, *metric spaces*, and *topological spaces*.

Theorem 1.7. ⁹ Let R be a ring, (Ω, \mathbb{E}, P) be a PROBABILITY SPACE, E the expectation operator, and $V = \{X|X : \Omega \rightarrow R\}$ be the set of all random vectors in PROBABILITY SPACE (Ω, \mathbb{E}, P) .

- | | |
|-------------|--|
| T
H
M | (1). $V \triangleq \{X X : \Omega \rightarrow R\}$ is a VECTOR SPACE.
(2). $\langle X Y \rangle \triangleq E(XY^*)$ is an INNER PRODUCT.
(3). $\ X\ \triangleq \sqrt{E(XX^*)}$ is a NORM.
(4). $(V, \langle \Delta \nabla \rangle)$ is an INNER PRODUCT SPACE. |
|-------------|--|

PROOF:

⁸ Jazwinski (1970), page 40 (“Theorem 2.9 (Conditional Expectations)”), Jazwinski (2007) page 40

⁹ Lindquist and Picci (2015) pages 25–26 (2.1 Hilbert Space of Second-Order Random Variables. $\langle \xi | \eta \rangle = E\{\xi \bar{\eta}\}$), Caines (1988) page 21 ($\langle Exy = \int_{\Omega} x(\omega)y(\omega)dP(\omega) \rangle$), Caines (2018) page 21 ($\langle Exy = \int_{\Omega} x(\omega)y(\omega)dP(\omega) \rangle$), Moon and Stirling (2000), pages 105–106

1. Proof that \mathbf{V} is a vector space:

1) $\forall X, Y, Z \in \mathbf{V}$	$(X + Y) + Z = X + (Y + Z)$	(+ is associative)
2) $\forall X, Y \in \mathbf{V}$	$X + Y = Y + X$	(+ is commutative)
3) $\exists 0 \in \mathbf{V}$ such that $\forall X \in \mathbf{V}$	$X + 0 = X$	(+ identity)
4) $\forall X \in \mathbf{V} \exists Y \in \mathbf{V}$ such that	$X + Y = 0$	(+ inverse)
5) $\forall \alpha \in S$ and $X, Y \in \mathbf{V}$	$\alpha \cdot (X + Y) = (\alpha \cdot X) + (\alpha \cdot Y)$	(· distributes over +)
6) $\forall \alpha, \beta \in S$ and $X \in \mathbf{V}$	$(\alpha + \beta) \cdot X = (\alpha \cdot X) + (\beta \cdot X)$	(· pseudo-distributes over +)
7) $\forall \alpha, \beta \in S$ and $X \in \mathbf{V}$	$\alpha(\beta \cdot X) = (\alpha \cdot \beta) \cdot X$	(· associates with ·)
8) $\forall X \in \mathbf{V}$	$1 \cdot X = X$	(· identity)

2. Proof that $\langle X | Y \rangle \triangleq E(XY^*)$ is an *inner product*.

1) $E(XX^*)$	≥ 0	$\forall X \in \mathbf{V}$	(non-negative)
2) $E(XX^*)$	$= 0 \iff X = 0$	$\forall X \in \mathbf{V}$	(non-degenerate)
3) $E(\alpha XY^*)$	$= \alpha E(XY^*)$	$\forall X, Y \in \mathbf{V}, \forall \alpha \in \mathbb{C}$	(homogeneous)
4) $E[(X + Y)Z^*]$	$= E(XZ^*) + E(YZ^*)$	$\forall X, Y, Z \in \mathbf{V}$	(additive)
5) $E(XY^*)$	$= E(YX^*)$	$\forall X, Y \in \mathbf{V}$	(conjugate symmetric).

3. Proof that $\|X\| \triangleq \sqrt{E(XX^*)}$ is a *norm*: This *norm* is simply induced by the above *inner product*.

4. Proof that $(\mathbf{V}, \langle \cdot | \cdot \rangle)$ is an *inner product space*: Because \mathbf{V} is a vector space and $\langle \cdot | \cdot \rangle$ is an *inner product*, $(\mathbf{V}, \langle \cdot | \cdot \rangle)$ is an *inner product space*.



The next theorem gives some results that follow directly from vector space properties:

Theorem 1.8. Let (Ω, \mathcal{E}, P) be a PROBABILITY SPACE with EXPECTATION functional E .

T H M	$(1). \quad \sqrt{E\left(\sum_{n=1}^N X_n\right)} \leq \sum_{n=1}^N E(X_n X_n^*) \quad \text{(GENERALIZED TRIANGLE INEQUALITY)}$ $(2). \quad E(XY^*) ^2 \leq E(XX^*) E(YY^*) \quad \text{(CAUCHY-SCHWARTZ INEQUALITY)}$ $(3). \quad 2E(XX^*) + 2E(YY^*) = E[(X + Y)(X + Y)^*] + E[(X - Y)(X - Y)^*] \quad \text{(PARALLELOGRAM LAW)}$
----------------------	--

PROOF:

1. $(\mathbb{R}^\Omega, E(x, y))$ is an *inner product space*. Proof: Theorem 1.7 (page 8).

2. Because $(\mathbb{R}^\Omega, E(x, y))$ is an *inner product space*, the other properties follow:

1. Generalized triangle inequality: Theorem L.1 page 271
2. Cauchy-Schwartz inequality: Theorem K.2 page 256
3. Parallelogram Law: Theorem K.7 page 263





CHAPTER 2

RANDOM SEQUENCES



“A likely impossibility is always preferable to an unconvincing possibility.”¹
Aristotle (384 BC – 322 BC)



“We are quite in danger of sending highly trained and highly intelligent young men out into the world with tables of erroneous numbers under their arms, and with a dense fog in the place where their brains ought to be. In this century, of course, they will be working on guided missiles and advising the medical profession on the control of disease, and there is no limit to the extent to which they could impede every sort of national effort.”

Ronald A. Fisher, (1890–1962), Statistician, at a lecture in 1958 at Michigan State University²

2.1 Definitions

Definition 2.1.

D E F A **random sequence** is a **SEQUENCE**
over a **PROBABILITY SPACE** (Definition A.2 page 151).

Definition 2.2.³ Let $x(n)$ and $y(n)$ be RANDOM SEQUENCES.

¹ quote: <http://en.wikiquote.org/wiki/Aristotle>
image: <http://en.wikipedia.org/wiki/Aristotle>

² quote: [Yates and Mather \(1963\)](#) page 107. image: <http://www.genetics.org/content/154/4/1419>

³ [Papoulis \(1984\)](#) page 263 $\langle R_{xy}(m) = E\{x(m)y^*(0)\} \rangle$, [Wilks \(1963b\)](#), page 77 §3.4 “Moments of two-dimensional random variables”, [Cadzow \(1987\)](#) page 341 $\langle r_{xy}(m) = E[x(m)y^*(0)] \rangle$, [MatLab \(2018b\)](#) $\langle R_{xy}(m) = E\{x_{n+m}y_n^*\} \rangle$, [MatLab \(2018a\)](#) $\langle R_{xy}(m) = E\{x_{n+m}y_n^*\} \rangle$

D E F	The mean	$\mu_X(n)$	of $x(n)$ is	$\mu_X(n) \triangleq E[x(n)]$
	The variance	$\sigma_X^2(n)$	of $x(n)$ is	$\sigma_X^2(n) \triangleq E([x(n) - \mu_X(n)]^2)$
	The cross-correlation	$R_{xy}(n, m)$	of $x(n)$ and $y(n)$ is	$R_{xy}(n, m) \triangleq E[x(n + m)y^*(n)]$
	The auto-correlation	$R_{xx}(n, m)$	of $x(n)$ is	$R_{xx}(n, m) \triangleq R_{xy}(n, m) _{y=x}$

2.2 Properties

Theorem 2.1.

T H M	$R_{xx}(n, m) = R_{xx}^*(n + m, -m)$
	$R_{xy}(n, m) = R_{yx}^*(n + m, -m)$

PROOF:

$$\begin{aligned}
 R_{xy}(n, m) &\triangleq E[x(n + m)y^*(n)] && \text{by definition of } R_{xy}(n, m) \quad (\text{Definition 2.2 page 11}) \\
 &= E[y^*(n)x(n + m)] && \text{by commutative property of } (\mathbb{C}, +, \cdot, 0, 1) \quad (\text{Definition F.5 page 192}) \\
 &= (E[y(n)x^*(n + m)])^* && \text{by distributive property of } *-\text{algebras} \quad (\text{Definition J.3 page 250}) \\
 &= (E[y(n + m - m)x^*(n + m)])^* && \text{by additive identity property of } (\mathbb{R}, +, \cdot, 0, 1) \quad (\text{Definition F.5 page 192}) \\
 &\triangleq R_{yx}^*(n + m, -m) && \text{by definition of } R_{xy}(n, m) \quad (\text{Definition 2.2 page 11})
 \end{aligned}$$

$$\begin{aligned}
 R_{xx}(n, m) &= R_{xy}(n, m)|_{y=x} && \text{by } y = x \text{ constraint} \\
 &= R_{xy}^*(n + m, -m)|_{y=x} && \text{by previous result} \\
 &= R_{xx}^*(n + m, -m) && \text{by } y = x \text{ constraint}
 \end{aligned}$$



2.3 Wide Sense Stationary processes

Definition 2.3. Let $x(n)$ be a RANDOM SEQUENCE with MEAN $\mu_X(n)$ and VARIANCE $\sigma_X^2(n)$ (Definition 2.2 page 11).

D E F	$x(n)$ is wide sense stationary (WSS) if
	1. $\mu_X(n)$ is CONSTANT with respect to n (STATIONARY IN THE 1ST MOMENT) and
	2. $\sigma_X^2(n)$ is CONSTANT with respect to n (STATIONARY IN THE 2ND MOMENT)

Definition 2.4.⁴ Let $x(n)$ be a RANDOM SEQUENCE with statistics $\mu_X(n)$, $\sigma_X^2(n)$, $R_{xx}(n, m)$, and $R_{xy}(n, m)$ (Definition 2.2 page 11).

D E F	$\{x \text{ and } y \text{ are WIDE SENSE STATIONARY}\} \implies$
	$ \left\{ \begin{array}{lll} \text{(1). The mean} & \mu_X & \text{of } x(n) \text{ is} & \mu_X \triangleq E[x(0)] \\ \text{(2). The variance} & \sigma_X^2 & \text{of } x(n) \text{ is} & \sigma_X^2 \triangleq E([x(0) - \mu_X]^2) \\ \text{(4). The cross-correlation} & R_{xy}(m) & \text{of } x(n) \text{ and } y(n) \text{ is} & R_{xy}(m) \triangleq E[x(m)y^*(0)] \\ \text{(3). The auto-correlation} & R_{xx}(m) & \text{of } x(n) \text{ is} & R_{xx}(m) \triangleq R_{xy}(m) _{y=x} \end{array} \right\} $

⁴ Papoulis (1984) page 263 “ $R_{xy}(\tau) = E\{x(t + \tau)y^*(t)\}$ ”, Cadzow (1987) page 341 $\langle r_{xy}(n) = E[x(k + n)y^*(k)] \rangle$ (10.41)»

Remark 2.1. The $R_{xy}(n, m)$ of Definition 2.2 (page 11) and the $R_{xy}(m)$ of Definition 2.4 (page 12) (etc.) are examples of *function overload*—that is, functions that use the same mnemonic but are distinguished by different domains. Perhaps a more common example of function overload is the “+” mnemonic. Traditionally it is used with domain of the natural numbers \mathbb{N} as in $3 + 2$. Later it was extended for domain real numbers \mathbb{R} as in $\sqrt{3} + \sqrt{2}$, or even complex numbers \mathbb{C} as in $(\sqrt{3} + i\sqrt{2}) + (e + i\pi)$. And it was even more dramatically extended for use with domain $\mathbb{R}^N \times \mathbb{R}^M$ in “linear algebra” as in

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} + \begin{bmatrix} 5 & 6 \\ 7 & 8 \end{bmatrix} = \begin{bmatrix} 6 & 8 \\ 10 & 12 \end{bmatrix}$$

Remark 2.2. ⁵ The definition for $R_{xy}(m)$ can be defined with the conjugate $*$ on either x or y , or on neither or both; and moreover x may either lead or lag y . In total, there are $2 \times 2 \times 2 = 8$ different ways to define $R_{xy}(m)$. ⁶ and $R_{xx}(m)$ involve complex numbers. This may seem curious when typical ADCs provide real-valued sequences. Note however that complex-valued sequences often come up in signal processing due to some common system architectures:

1. The presence of an *FFT* operator in the signal processing path
2. The *complex envelope* $x_l(t)$ of a modulated *narrowband* communications signal $x(t)$.
3. Communications channel processing involving phase discrimination (e.g. PSK and QAM).

In the case of a narrowband signal $x(t)$ modulated by a sinusoid at center frequency f_c , we have three canonical forms. These can be shown to be equivalent:

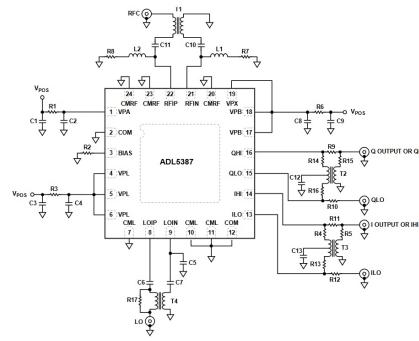
$$\begin{aligned}
 x(t) &\triangleq \underbrace{a(t)\cos[2\pi f_c t + \phi(t)]}_{\text{amplitude-phase form}} && \text{amplitude and phase form} \\
 &= \underbrace{a(t)\cos[\phi(t)]\cos[2\pi f_c t]}_{p(t)} - \underbrace{a(t)\sin[\phi(t)]\sin[2\pi f_c t]}_{q(t)} && \text{by double angle formulas} \\
 &= \underbrace{p(t)\cos[2\pi f_c t] - q(t)\sin[2\pi f_c t]}_{\text{quadrature form}} && \text{quadrature form} \\
 &= \mathbf{R}_e([p(t) + iq(t)][\cos(2\pi f_c t) + isin(2\pi f_c t)]) && \text{by definitions of } \mathbf{R}_e \\
 &= \underbrace{\mathbf{R}_e[x_l(t)e^{i2\pi f_c t}]}_{\text{complex envelope form}} && \text{by Euler's identity}
 \end{aligned}$$

Note that in these equivalent forms, the *complex envelope* $x_l(t)$ is conveniently represented as a *complex-valued* function in terms of the *quadrature component* $p(t)$ and the *inphase component* $q(t)$ such that $x_l(t) = p(t) + iq(t)$.

⁵  S. Lawrence Marple (1987) pages 51–53 (“APPENDIX 2.A SOURCE OF COMPLEX-VALUED SIGNALS”),  S. Lawrence Marple (2019) pages 48–50 (§“2.12 Extra: Source of Complex-Valued Signals”),  Greenhoe (2019b) (Chapter 2: Narrowband Signals)

⁶  Greenhoe (2019a)

In practice (with real hardware), you will likely first have access to the quadrature components $p(t)$ and $q(t)$. Take for example the *Analog Devices ADL5387 Quadrature Demodulator* and evaluation board, as illustrated to the right.⁷ Note that *quadrature component* $p(t)$ is available at connector “Q OUTPUT” and *inphase component* $q(t)$ is available at connector “I OUTPUT”.



PROOF:

$R_{xy}(m) = R_{xy}(n, m)$	by Proposition 2.1 page 14	and hypotheses (A),(B)
$= R_{yx}^*(n + m, -m)$	by Theorem 2.1 page 12	and hypothesis (B)
$= R_{yx}^*(-m)$	by Proposition 2.1 page 14	and hypothesis (A)
$R_{xx}(m) = R_{xx}(n, m)$	by Proposition 2.1 page 14	and hypothesis (A)
$= R_{xx}^*(n + m, -m)$	by Theorem 2.1 page 12	and hypothesis (B)
$= R_{xx}^*(-m)$	by Proposition 2.1 page 14	and hypothesis (A)



2.4 Spectral density

Definition 2.5. Let $x(n)$ and $y(n)$ be WIDE SENSE STATIONARY RANDOM SEQUENCES with auto-correlation $R_{xx}(m)$ and cross-correlation $R_{xy}(m)$. Let Z be the Z-TRANSFORM OPERATOR (Definition R.4 page 354).

D
E
F

The z-domain cross spectral density (CSD) $\check{S}_{xy}(z)$ of x and y is

$$\check{S}_{xy}(z) \triangleq ZR_{xy}(m) \triangleq \sum_{m \in \mathbb{Z}} R_{xy}(m)z^{-m}$$

The z-domain power spectral density (PSD) $\check{S}_{xx}(z)$ of x is

$$\check{S}_{xx}(z) \triangleq \check{S}_{xy}(z)|_{y(n)=x(n)}$$

D
E
F

Definition 2.6. Let $x(n)$ and $y(n)$ be WIDE SENSE STATIONARY RANDOM SEQUENCES with auto-correlation $R_{xx}(m)$ and cross-correlation $R_{xy}(m)$. Let \check{F} be the DISCRETE TIME FOURIER TRANSFORM (DTFT) operator (Definition Q.1 page 343).

D
E
F

The auto-spectral density

$$\check{S}_{xx}(z) \text{ of } x \text{ is} \quad \check{S}_{xx}(z) \triangleq \check{F}R_{xx}(m) \triangleq \sum_{m \in \mathbb{Z}} R_{xx}(m)e^{-i\omega m}$$

The cross spectral density

$$(CSD) \check{S}_{xy}(z) \text{ of } x \text{ and } y \text{ is} \quad \check{S}_{xy}(z) \triangleq \check{F}R_{xy}(m) \triangleq \sum_{m \in \mathbb{Z}} R_{xy}(m)e^{-i\omega m}$$

The auto-spectral density is also called power spectral density (PSD).

T
H
M

$$\left\{ x \text{ and } y \text{ are WIDE SENSE STATIONARY} \right\} \implies \left\{ \begin{array}{l} (1). \check{S}_{xx}(z) = \check{S}_{xx}^*\left(\frac{1}{z^*}\right) \text{ and} \\ (2). \check{S}_{yx}(z) = \check{S}_{xy}^*\left(\frac{1}{z^*}\right) \end{array} \right\}$$

PROOF:

$\check{S}_{yx}(z) \triangleq ZR_{yx}(m)$	by definition of $\check{S}_{xy}(z)$	(Definition 2.6 page 15)
$\triangleq \sum_{m \in \mathbb{Z}} R_{yx}(m)z^{-m}$	by definition of Z	(Definition R.4 page 354)
$\triangleq \sum_{m \in \mathbb{Z}} R_{xy}^*(-m)z^{-m}$	by Corollary 2.1 page 14	
$= \left[\sum_{m \in \mathbb{Z}} R_{xy}(-m)(z^*)^{-m} \right]^*$	by antiautomorphic property of *-algebras	(Definition J.3 page 250)

$$\begin{aligned}
 &= \left[\sum_{-p \in \mathbb{Z}} R_{xy}(p)(z^*)^p \right]^* \quad \text{where } p \triangleq -m \quad \Rightarrow m = -p \\
 &= \left[\sum_{p \in \mathbb{Z}} R_{xy}(p)(z^*)^p \right]^* \quad \text{by } \textit{absolutely summable} \text{ property} \quad (\text{Definition R.2 page 353}) \\
 &= \left[\sum_{p \in \mathbb{Z}} R_{xy}(p) \left(\frac{1}{z^*} \right)^{-p} \right]^* \\
 &= \check{S}_{xy}^* \left(\frac{1}{z^*} \right) \quad \text{by definition of } \mathbf{Z} \quad (\text{Definition R.4 page 354}) \\
 \check{S}_{xx}(z) &= \check{S}_{xy}(z)|_{y=x} \\
 &= \check{S}_{yx}^*(z)|_{y=x} \\
 &= \check{S}_{xy}^* \left(\frac{1}{z^*} \right) \Big|_{y=x} \quad \text{by (2)—previous result} \\
 &= \check{S}_{xx}^* \left(\frac{1}{z^*} \right)
 \end{aligned}$$

⇒

Corollary 2.2. Let \mathbf{S} be a system with IMPULSE RESPONSE $h(n)$, INPUT $x(n)$, and OUTPUT $y(n)$.

C O R	$\left\{ \begin{array}{l} (A). \quad h \text{ is LTI and} \\ (B). \quad x \text{ and } y \text{ are WSS} \end{array} \right\} \Rightarrow \left\{ \begin{array}{ll} (1). \quad \tilde{S}_{xy}^*(\omega) &= \tilde{S}_{yx}(\omega) \quad (\text{CONJUGATE-SYMMETRIC}) \quad \text{and} \\ (2). \quad \tilde{S}_{xx}^*(\omega) &= \tilde{S}_{xx}(\omega) \quad (\text{CONJUGATE SYMMETRIC}) \quad \text{and} \\ (3). \quad \tilde{S}_{xx}(\omega) &\in \mathbb{R} \quad (\text{REAL-VALUED}) \end{array} \right\}$
-------------	--

PROOF:

$$\begin{aligned}
 \tilde{S}_{xy}^*(\omega) &= \check{S}_{xy}^*(z)|_{z=e^{i\omega}} \quad \text{by definition of DTFT} \quad (\text{Definition Q.1 page 343}) \\
 &= \check{S}_{yx}^{**} \left(\frac{1}{z^*} \right) \Big|_{z=e^{i\omega}} \quad \text{by Theorem 2.2 page 15} \\
 &= \check{S}_{yx} \left(\frac{1}{z^*} \right) \Big|_{z=e^{i\omega}} \quad \text{by } \textit{involutory} \text{ property of } *-\text{algebras} \quad (\text{Definition J.3 page 250}) \\
 &= \check{S}_{yx} \left(\frac{1}{e^{i\omega*}} \right) \\
 &= \check{S}_{yx} (e^{i\omega}) \\
 &= \tilde{S}_{yx}(\omega) \quad \text{by definition of DTFT} \quad (\text{Definition Q.1 page 343}) \\
 \tilde{S}_{xx}^*(\omega) &= \check{S}_{xx}^*(z)|_{z=e^{i\omega}} \quad \text{by definition of DTFT} \quad (\text{Definition Q.1 page 343}) \\
 &= \check{S}_{xx}^{**} \left(\frac{1}{z^*} \right) \Big|_{z=e^{i\omega}} \quad \text{by Theorem 2.2 page 15} \\
 &= \check{S}_{xx} \left(\frac{1}{z^*} \right) \Big|_{z=e^{i\omega}} \quad \text{by } \textit{involutory} \text{ property of } *-\text{algebras} \quad (\text{Definition J.3 page 250}) \\
 &= \check{S}_{xx} \left(\frac{1}{e^{i\omega*}} \right) \\
 &= \check{S}_{xx} (e^{i\omega}) \\
 &= \tilde{S}_{xx}(\omega) \quad \text{by definition of DTFT} \quad (\text{Definition Q.1 page 343}) \\
 \implies \tilde{S}_{xx}(\omega) &\text{ is real-valued} \\
 \tilde{S}_{xx}^*(\omega) &= \tilde{S}_{xy}^*(\omega)|_{y=x} \\
 &= \tilde{S}_{yx}(\omega)|_{y=x} \quad \text{by previous result} \\
 &= \tilde{S}_{xx}(\omega)
 \end{aligned}$$

⇒



2.5 Spectral Power

The term “*spectral power*” is a bit of an oxymoron because “spectral” deals with leaving the time-domain for the frequency-domain, howbeit the concept of power is solidly founded on the concept of time in that power = energy per time.

However, *Parseval's Theorem* (Proposition H.2 page 216) demonstrates that power in time can also be calculated in frequency. So, it makes some sense to speak of the term “spectral power”. Moreover, one way to estimate this power is to average the Fourier Transforms of the product $|x(n)|^2 = x(n)x^*(n)$...that is, to use an estimate of the auto-spectral density $\tilde{S}_{xx}(\omega)$. Thus, an alternate name for *auto-spectral density* is **power spectral density** (PSD).



CHAPTER 3

CONTINUOUS RANDOM PROCESSES



“*A likely impossibility is always preferable to an unconvincing possibility.*”¹
Aristotle (384 BC – 322 BC)

3.1 Definitions

Definition 3.1. ² Let $(\Omega, \mathbb{E}, \mathbb{P})$ be a PROBABILITY SPACE.

D E F The function $x : \Omega \rightarrow \mathbb{R}$ is a **random variable**.
The function $y : \mathbb{R} \times \Omega \rightarrow \mathbb{R}$ is a **random process**.

The random process $x(t, \omega)$, where t commonly represents time and $\omega \in \Omega$ is an outcome of an experiment, can take on more specialized forms depending on whether t and ω are fixed or allowed to vary. These forms are illustrated in Figure 3.1 page 19³ and Figure 3.2 page 20.

$x(t, \omega)$	fixed t	variable t
fixed ω	number	time function
variable ω	random variable	random process

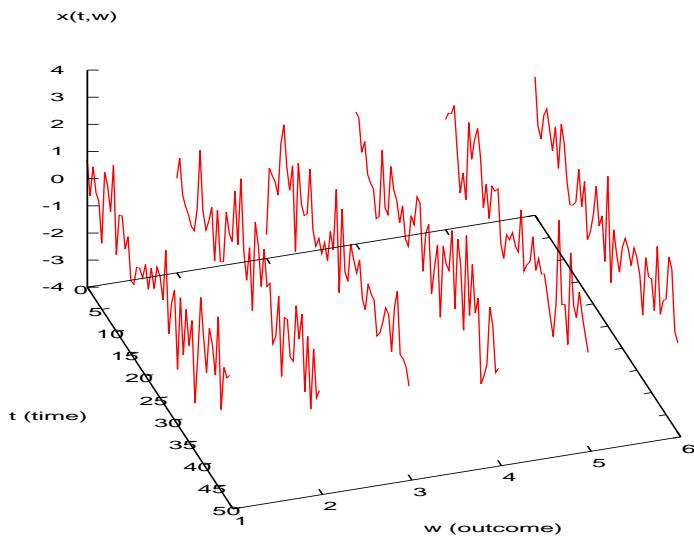
Figure 3.1: Specialized forms of a random process $x(t, \omega)$

¹ quote: <http://en.wikiquote.org/wiki/Aristotle>

image: <http://en.wikipedia.org/wiki/Aristotle>

² [Papoulis \(1991\) page 63](#), [Papoulis \(1991\) page 285](#)

³ [Papoulis \(1991\) pages 285–286](#)

Figure 3.2: Example of a random process $x(t, \omega)$

Definition 3.2.⁴ Let $x(t)$ and $y(t)$ be random processes.

DEF	The mean $\mu_X(t)$ of $x(t)$ is	$\mu_X(t) \triangleq E[x(t)]$
	The cross-correlation $R_{xy}(t, u)$ of $x(t)$ and $y(t)$ is	$R_{xy}(t, u) \triangleq E[x(t)y^*(u)]$
	The auto-correlation function $R_{xx}(t, u)$ of $x(t)$ is	$R_{xx}(t, u) \triangleq E[x(t)x^*(u)]$

*Remark 3.1.*⁵ The equation $\int_{u \in \mathbb{R}} R_{xx}(t, u)f(u) du$ is a *Fredholm integral equation of the first kind* and $R_{xx}(t, u)$ is the *kernel* of the equation.

3.2 Properties

Theorem 3.1. Let $x(t)$ and $y(t)$ be random processes with cross-correlation $R_{xy}(t, u)$ and let $R_{xx}(t, u)$ be the auto-correlation of $x(t)$.

THM	$R_{xx}(t, u) = R_{xx}^*(u, t)$ (CONJUGATE SYMMETRIC)
	$R_{xy}(t, u) = R_{yx}^*(u, t)$

PROOF:

$$\begin{aligned} R_{xx}(t, u) &\triangleq E[x(t)x^*(u)] &= E[x^*(u)x(t)] = (E[x(u)x^*(t)])^* &\triangleq R_{xx}^*(u, t) \\ R_{xy}(t, u) &\triangleq E[x(t)y^*(u)] &= E[y^*(u)x(t)] = (E[y(u)x^*(t)])^* &\triangleq R_{yx}^*(u, t) \end{aligned}$$

⇒

⁴ Papoulis (1984) page 216 $\langle R_{xy}(t_1, t_2) = E\{x(t_1)y^*(t_2)\} \rangle$ (9-35),

⁵ Fredholm (1900), Fredholm (1903) page 365, Michel and Herget (1993) page 97, Keener (1988) page 101

CHAPTER 4

RANDOM PROCESS EIGEN-ANALYSIS

4.1 Definitions

Definition 4.1. Let $x(t)$ be random processes with continuous AUTO-CORRELATION $R_{xx}(t, u)$ (Definition 3.2 page 20) or discrete AUTO-CORRELATION $R_{xx}(n, m)$ (Definition 2.2 page 11).

The auto-correlation operator \mathbf{R} of $x(t)$ is defined as

$$\begin{aligned} \text{DEF} \quad \mathbf{R}\mathbf{f} &\triangleq \underbrace{\int_{u \in \mathbb{R}} R_{xx}(t, u)\mathbf{f}(u) du}_{(\text{continuous case})} \quad \text{or} \quad \mathbf{R}\mathbf{f} \triangleq \sum_{n \in \mathbb{Z}} R_{xx}(n, m)\mathbf{f}(m) \\ &\quad \underbrace{\sum_{m \in \mathbb{Z}}}_{(\text{discrete case})} \end{aligned}$$

Definition 4.2. Let $x(t)$ be a RANDOM PROCESS with AUTO-CORRELATION $R_{xx}(\tau)$ (Definition 3.2 page 20).

DEF A RANDOM PROCESS $x(t)$ is **white** if $R_{xx}(\tau) = \delta(\tau)$

If a random process $x(t)$ is **white** (Definition 4.2 page 21) and the set $\Psi = \{\psi_1(t), \psi_2(t), \dots, \psi_N(t)\}$ is **any** set of orthonormal basis functions, then the innerproducts $\langle n(t) | \psi_n(t) \rangle$ and $\langle n(t) | \psi_m(t) \rangle$ are *uncorrelated* for $m \neq n$. However, if $x(t)$ is **colored** (not white), then the innerproducts are not in general uncorrelated. But if the elements of Ψ are chosen to be the eigenfunctions of \mathbf{R} such that $\mathbf{R}\psi_n = \lambda_n\psi_n$, then by Theorem 3.1 (page 20), the set $\{\psi_n(t)\}$ are *orthogonal* and the innerproducts are *uncorrelated* even though $x(t)$ is not white. This criterion is called the Karhunen-Loève criterion for $x(t)$.

4.2 Properties

Theorem 4.1. Let \mathbf{R} be an AUTO-CORRELATION operator.

$$\begin{aligned} \text{THM} \quad \left\{ \begin{array}{l} (A). \quad \langle x | y \rangle \triangleq \int_{t \in \mathbb{R}} x(t)y^*(t) dt \quad \text{OR} \\ (B). \quad \langle x | y \rangle \triangleq \sum_{n \in \mathbb{Z}} x(n)y^*(n) \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} (1). \quad \langle \mathbf{Rx} | x \rangle \geq 0 \quad (\text{NON-NEGATIVE}) \quad \text{and} \\ (2). \quad \langle \mathbf{Rx} | y \rangle = \langle x | \mathbf{Ry} \rangle \quad (\text{SELF-ADJOINT}) \end{array} \right\} \end{aligned}$$

PROOF:

1. Proof that \mathbf{R} is *non-negative* under hypothesis (A):

$$\begin{aligned}
 \langle \mathbf{R}y | y \rangle &= \left\langle \int_{u \in \mathbb{R}} R_{xx}(t, u)y(u) du | y(t) \right\rangle && \text{by definition of } \mathbf{R} && (\text{Definition 4.1 page 21}) \\
 &= \left\langle \int_{u \in \mathbb{R}} E[x(t)x^*(u)]y(u) du | y(t) \right\rangle && \text{by definition of } R_{xx}(t, u) && (\text{Definition 3.2 page 20}) \\
 &= E \left[\left\langle \int_{u \in \mathbb{R}} x(t)x^*(u)y(u) du | y(t) \right\rangle \right] && \text{by linearity of } \langle \Delta | \nabla \rangle \text{ and } \int && (\text{Definition K.1 page 255}) \\
 &= E \left[\int_{u \in \mathbb{R}} x^*(u)y(u) du \langle x(t) | y(t) \rangle \right] && \text{by additivity property of } \langle \Delta | \nabla \rangle && (\text{Definition K.1 page 255}) \\
 &= E[\langle y(u) | x(u) \rangle \langle x(t) | y(t) \rangle] && \text{by local definition of } \langle \Delta | \nabla \rangle && \\
 &= E[\langle x(u) | y(u) \rangle^* \langle x(t) | y(t) \rangle] && \text{by conjugate symmetry prop.} && (\text{Definition K.1 page 255}) \\
 &= E|\langle x(t) | y(t) \rangle|^2 && \text{by definition of } |\cdot| && (\text{Definition F.4 page 192}) \\
 &\geq 0 && \text{by strictly positive property of norms} && (\text{Definition L.1 page 271})
 \end{aligned}$$

2. Proof that \mathbf{R} is *self-adjoint* under hypothesis (A):

$$\begin{aligned}
 \langle [\mathbf{R}x](t) | y \rangle &= \left\langle \int_{u \in \mathbb{R}} R_{xx}(t, u)x(u) du | y(t) \right\rangle && \text{by definition of } \mathbf{R} && (\text{Definition 4.1 page 21}) \\
 &= \int_{u \in \mathbb{R}} x(u) \langle R_{xx}(t, u) | y(t) \rangle du && \text{by additive property of } \langle \Delta | \nabla \rangle && (\text{Definition K.1 page 255}) \\
 &= \int_{u \in \mathbb{R}} x(u) \langle y(t) | R_{xx}(t, u) \rangle^* du && \text{by conjugate symmetry prop.} && (\text{Definition K.1 page 255}) \\
 &= \langle x(u) | \langle y(t) | R_{xx}(t, u) \rangle \rangle && \text{by local definition of } \langle \Delta | \nabla \rangle && \\
 &= \left\langle x(u) | \int_{t \in \mathbb{R}} y(t) R_{xx}^*(t, u) dt \right\rangle && (\text{Definition K.1 page 255}) && \\
 &= \left\langle x(u) | \int_{t \in \mathbb{R}} y(t) R_{xx}(u, t) dt \right\rangle && \text{by property of } R_{xx} && (\text{Theorem 3.1 page 20}) \\
 &= \left\langle x(u) | \underbrace{\mathbf{R}y}_{\mathbf{R}^*} \right\rangle && \text{by definition of } \mathbf{R} && (\text{Definition 4.1 page 21}) \\
 \implies \mathbf{R} &= \mathbf{R}^* && \text{by definition of adjoint } \mathbf{R}^* && (\text{Definition O.6 page 313}) \\
 \implies \mathbf{R} &\text{ is self-adjoint} && \text{by definition of self-adjoint} && (\text{Definition O.8 page 320})
 \end{aligned}$$

3. Proofs under hypothesis (B): substitute $\sum_{n \in \mathbb{Z}}$ operator for $\int_{t \in \mathbb{R}}$ dt operator in above proofs.



Theorem 4.2. ¹ Let $(\lambda_n)_{n \in \mathbb{Z}}$ be the eigenvalues and $(\psi_n)_{n \in \mathbb{Z}}$ be the eigenfunctions of operator \mathbf{R} such that $\mathbf{R}\psi_n = \lambda_n\psi_n$.

T H M	(1). $\lambda_n \in \mathbb{R}$ (2). $\lambda_n \neq \lambda_m \implies \langle \psi_n \psi_m \rangle = 0$ (3). $\ \psi_n(t)\ ^2 > 0 \implies \lambda_n \geq 0$ (4). $\ \psi_n(t)\ ^2 > 0, \langle \mathbf{R}\mathbf{f} \mathbf{f} \rangle > 0 \implies \lambda_n > 0$	(REAL-VALUED) (ORTHOGONAL) (NON-NEGATIVE) (R POSITIVE DEFINITE $\implies \lambda_n$ POSITIVE)
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PROOF:

¹ Keener (1988), pages 114–119



1. Proof that eigenvalues are *real-valued*: Because \mathbf{R} is *self-adjoint*, its eigenvalues are real (Theorem O.18 page 320).
2. Proof that eigenfunctions associated with distinct eigenvalues are orthogonal: Because \mathbf{R} is *self-adjoint*, this property follows (Theorem O.18 page 320).
3. Proof that eigenvalues are *non-negative*:

$$\begin{aligned}
 0 &\leq \langle \mathbf{R}\psi_n | \psi_n \rangle && \text{by definition of } \textit{non-negative definite} \\
 &= \langle \lambda_n \psi_n | \psi_n \rangle && \text{by hypothesis} \\
 &= \lambda_n \langle \psi_n | \psi_n \rangle && \text{by definition of inner-products} \\
 &= \lambda_n \|\psi_n\|^2 && \text{by definition of norm induced by inner-product}
 \end{aligned}$$

4. Proof that eigenvalues are *positive* if \mathbf{R} is *positive definite*:

$$\begin{aligned}
 0 &< \langle \mathbf{R}\psi_n | \psi_n \rangle && \text{by definition of } \textit{positive definite} \\
 &= \langle \lambda_n \psi_n | \psi_n \rangle && \text{by hypothesis} \\
 &= \lambda_n \langle \psi_n | \psi_n \rangle && \text{by } \textit{homogeneous property of } \langle \cdot | \cdot \rangle \quad (\text{Definition K.1 page 255}) \\
 &= \lambda_n \|\psi_n\|^2 && \text{by } \textit{induced norm theorem} \quad (\text{Theorem K.4 page 260})
 \end{aligned}$$



Theorem 4.3 (Karhunen-Loëve Expansion). ² Let \mathbf{R} be the AUTO-CORRELATION OPERATOR (Definition 4.1 page 21) of a RANDOM PROCESS $x(t)$. Let $(\lambda_n)_{n \in \mathbb{Z}}$ be the eigenvalues of \mathbf{R} and $(\psi_n)_{n \in \mathbb{Z}}$ are the eigenfunctions of \mathbf{R} such that $\mathbf{R}\psi_n = \lambda_n \psi_n$.

T H M	$\underbrace{\ \psi_n(t)\ = 1}_{\{\psi_n(t)\} \text{ are NORMALIZED}} \implies E \left(\underbrace{\left x(t) - \sum_{n \in \mathbb{Z}} \langle x(t) \psi_n(t) \rangle \psi_n(t) \right ^2}_{\text{CONVERGENCE IN PROBABILITY}} \right) = 0 \quad (\{\psi_n(t)\} \text{ is a BASIS for } x(t))$
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PROOF:

1. Define $\dot{x}_n \triangleq \langle x(t) | \psi_n(t) \rangle$
2. Define $\mathbf{Rx}(t) \triangleq \int_{u \in \mathbb{R}} R_{xx}(t, u)x(u) du$
3. lemma: $E[x(t)x(t)] = \sum_{n \in \mathbb{Z}} \lambda_n |\psi_n(t)|^2$. Proof:

$$E[x(t)x(t)] = \sum_{n \in \mathbb{Z}} \lambda_n |\psi_n(t)|^2 \quad \begin{matrix} \text{by } \textit{non-negative property} & (\text{Theorem 4.1 page 21}) \\ \text{and } \textit{Mercer's Theorem} & (\text{Theorem D.4 page 178}) \end{matrix}$$

² Keener (1988), pages 114–119

4. lemma:

$$\begin{aligned}
 & \mathbb{E} \left[x(t) \left(\sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(t) \right)^* \right] \\
 & \triangleq \mathbb{E} \left[x(t) \left(\sum_{n \in \mathbb{Z}} \int_{u \in \mathbb{R}} x(u) \psi_n^*(u) du \psi_n(t) \right)^* \right] && \text{by definition of } \dot{x} && (\text{definition 1 page 23}) \\
 & = \sum_{n \in \mathbb{Z}} \left(\int_{u \in \mathbb{R}} \mathbb{E}[x(t)x^*(u)] \psi_n(u) du \right) \psi_n^*(t) && \text{by linearity} && (\text{Theorem 1.1 page 4}) \\
 & \triangleq \sum_{n \in \mathbb{Z}} \left(\int_{u \in \mathbb{R}} R_{xx}(t, u) \psi_n(u) du \right) \psi_n^*(t) && \text{by definition of } R_{xx}(t, u) && (\text{Definition 3.2 page 20}) \\
 & \triangleq \sum_{n \in \mathbb{Z}} (\mathbf{R} \psi_n(t) \psi_n^*(t)) && \text{by definition of } \mathbf{R} && (\text{definition 2 page 23}) \\
 & = \sum_{n \in \mathbb{Z}} \lambda_n \psi_n(t) \psi_n^*(t) && \text{by property of eigen-system} \\
 & = \sum_{n \in \mathbb{Z}} \lambda_n |\psi_n(t)|^2
 \end{aligned}$$

5. lemma:

$$\begin{aligned}
 & \mathbb{E} \left[\sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(t) \left(\sum_{m \in \mathbb{Z}} \dot{x}_m \psi_m(t) \right)^* \right] \\
 & \triangleq \mathbb{E} \left[\sum_{n \in \mathbb{Z}} \int_{u \in \mathbb{R}} x(u) \psi_n^*(u) du \psi_n(t) \left(\sum_{m \in \mathbb{Z}} \int_v x(v) \psi_m^*(v) dv \psi_m(t) \right)^* \right] && \text{by definition of } \dot{x} && (\text{definition 1 page 23}) \\
 & = \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} \int_u \left(\int_v \mathbb{E}[x(u)x^*(v)] \psi_m(v) dv \right) \psi_n^*(u) du \psi_n(t) \psi_m^*(t) && \text{by linearity} && (\text{Theorem 1.1 page 4}) \\
 & = \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} \int_u \left(\int_v R_{xx}(u, v) \psi_m(v) dv \right) \psi_n^*(u) du \psi_n(t) \psi_m^*(t) && \text{by definition of } R_{xx}(t, u) && (\text{Definition 3.2 page 20}) \\
 & = \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} \int_u (\mathbf{R} \psi_m(u)) \psi_n^*(u) du \psi_n(t) \psi_m^*(t) && \text{by definition of } \mathbf{R} && (\text{definition 2 page 23}) \\
 & = \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} \int_u (\lambda_m \psi_m(u)) \psi_n^*(u) du \psi_n(t) \psi_m^*(t) && \text{by property of eigen-system} \\
 & = \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} \lambda_m \left(\int_{u \in \mathbb{R}} \psi_m(u) \psi_n^*(u) du \right) \psi_n(t) \psi_m^*(t) && \text{by linearity} \\
 & = \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} \lambda_m \|\psi(t)\|^2 \bar{\delta}_{mn} \psi_n(t) \psi_m^*(t) && \text{by orthogonal property} && (\text{Theorem 4.2 page 22}) \\
 & = \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} \lambda_m \bar{\delta}_{mn} \psi_n(t) \psi_m^*(t) && \text{by normalized hypothesis} \\
 & = \sum_{n \in \mathbb{Z}} \lambda_n \psi_n(t) \psi_n^*(t) && \text{by definition of Kronecker delta } \bar{\delta} && (\text{Definition K.3 page 267}) \\
 & = \sum_{n \in \mathbb{Z}} \lambda_n |\psi_n(t)|^2
 \end{aligned}$$

6. Proof that $\{\psi_n(t)\}$ is a basis for $x(t)$:

$$\mathbb{E} \left(\left| x(t) - \sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(t) \right|^2 \right)$$



$$\begin{aligned}
&= E \left(\left[x(t) - \sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(t) \right] \left[x(t) - \sum_{m \in \mathbb{Z}} \dot{x}_m \psi_m(t) \right]^* \right) \\
&= E \left(x(t)x^*(t) - x(t) \left[\sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(t) \right]^* - x^*(t) \sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(t) + \left[\sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(t) \right] \left[\sum_{m \in \mathbb{Z}} \dot{x}_m \psi_m(t) \right]^* \right) \\
&= E(x(t)x^*(t)) - E \left[x(t) \left[\sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(t) \right]^* \right] - E \left[x^*(t) \sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(t) \right] + E \left[\sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(t) \left[\sum_{m \in \mathbb{Z}} \dot{x}_m \psi_m(t) \right]^* \right] \\
&\quad \text{by linearity of } E \text{ (Theorem 1.1 page 4)} \\
&= \underbrace{\sum_{n \in \mathbb{Z}} \lambda_n |\psi_n(t)|^2}_{\text{by (3) lemma}} - \underbrace{\sum_{n \in \mathbb{Z}} \lambda_n |\psi_n(t)|^2}_{\text{by (4) lemma}} - \underbrace{\left[\sum_{n \in \mathbb{Z}} \lambda_n |\psi_n(t)|^2 \right]^*}_{\text{by (4) lemma}} + \underbrace{\sum_{n \in \mathbb{Z}} \lambda_n |\psi_n(t)|^2}_{\text{by (5) lemma}} \\
&= 0
\end{aligned}$$



4.3 Quasi-basis

The *auto-correlation operator* \mathbf{R} (Definition 4.1 page 21) in the discrete case can be approximated using a *correlation matrix*. In the *zero-mean* case, this becomes

$$\mathbf{R} \triangleq \begin{bmatrix} E[y_1 y_1] & E[y_1 y_2] & \cdots & E[y_1 y_n] \\ E[y_2 y_1] & E[y_2 y_2] & & E[y_2 y_n] \\ \vdots & \vdots & \ddots & \vdots \\ E[y_n y_1] & E[y_n y_2] & \cdots & E[y_n y_n] \end{bmatrix}$$

The eigen-vectors (and hence a quasi-basis) for \mathbf{R} can be found using a *Cholesky Decomposition*.

Proposition 4.1.³

P
R
P

The AUTO-CORRELATION MATRIX \mathbf{R} is **Toeplitz**.

Remark 4.1. For more information about the properties of **Toeplitz matrices**, see [Grenander and Szegö \(1958\)](#), [Widom \(1965\)](#), [Gray \(1971\)](#), [Smylie et al. \(1973\) page 408](#) (§“B. PROPERTIES OF THE TOEPLITZ MATRIX”), [GRENANDER AND SZEGÖ \(1984\)](#), [HAYKIN AND KESLER \(1979\)](#), [HAYKIN AND KESLER \(1983\)](#), [S. LAWRENCE MARPLE \(1987\) PAGES 80–92](#) (§“3.8 THE TOEPLITZ MATRIX”), [BÖTTCHER AND SILBERMANN \(1999\) \(ISBN:9780387985701\)](#), [GRAY \(2006\)](#), [S. LAWRENCE MARPLE \(2019\) PAGES 80–93](#) (§“3.8 THE TOEPLITZ MATRIX”).

³See [Clarkson \(1993\) page 131](#) (§“Appendix 3A — Positive Semi-Definite Form of the Autocorrelation Matrix”)



Part II

Statistical Processing

CHAPTER 5

OPERATIONS ON RANDOM VARIABLES

5.1 Functions of one random variable

Proposition 5.1. Let $(\Omega, \mathbb{E}, \mathbb{P})$ be a probability space, and X a RANDOM VARIABLE with CUMULATIVE DISTRIBUTION FUNCTION $c_X(x)$.

P R P	$\left\{ \begin{array}{l} X \text{ is UNIFORMLY DISTRIBUTED} \\ (\text{Definition C.1 page 165}) \end{array} \right\} \iff c_X(x) = \begin{cases} 0 & \text{for } x < 0 \\ x & \text{for } 0 < x \leq 1 \\ 1 & \text{otherwise} \end{cases}$
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Theorem 5.1 (Probability integral transform). ¹ Let $(\Omega, \mathbb{E}, \mathbb{P})$ be a probability space. Let X be a RANDOM VARIABLE with PROBABILITY DENSITY FUNCTION $p_X(x)$ and CUMULATIVE DISTRIBUTION FUNCTION $c_X(x)$. Let Y be a RANDOM VARIABLE CUMULATIVE DISTRIBUTION FUNCTION $c_Y(y)$.

T H M	$\left\{ \begin{array}{l} (1). Y = c_X(X) \\ (2). p_X(x) \text{ is CONTINUOUS} \end{array} \text{ and } \right\} \implies \left\{ \begin{array}{l} Y \text{ is UNIFORMLY DISTRIBUTED} \\ (\text{Definition C.1 page 165}) \end{array} \right\}$
----------------------	---

PROOF:

$$\begin{aligned}
 c_Y(y) &\triangleq \mathbb{P}\{Y \leq y\} && \text{by definition of cdf} && (\text{Definition B.2 page 160}) \\
 &= \mathbb{P}\{c_X(X) \leq y\} && \text{by hypothesis (1)} \\
 &= \mathbb{P}\{X \leq c_X^{-1}(y)\} && \text{by hypothesis (2) and} && \text{Proposition A.2 page 154} \\
 &\triangleq c_X[c_X^{-1}(y)] && \text{by definition of cdf} && (\text{Definition B.2 page 160}) \\
 &= y \\
 \implies Y &\text{ is uniformly distributed} && \text{by} && \text{Proposition 5.1 page 29}
 \end{aligned}$$

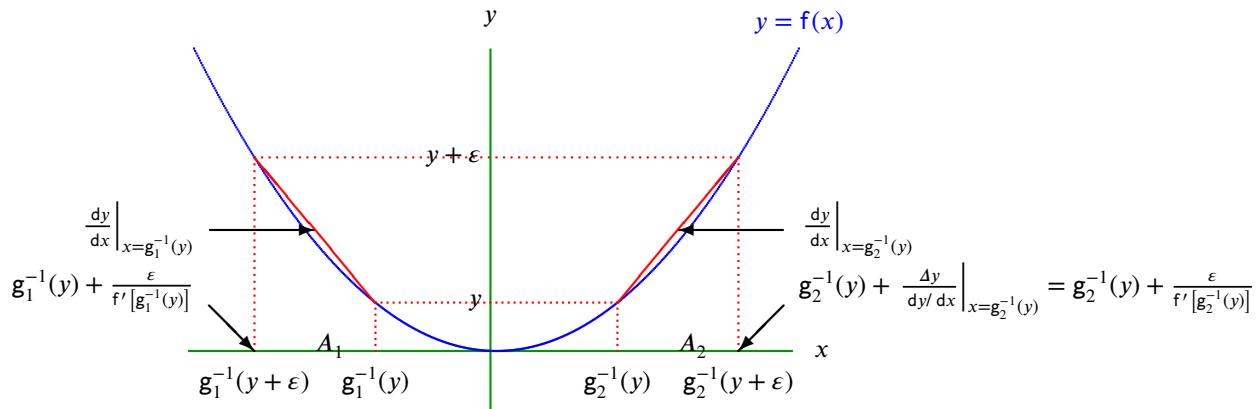
⇒

Theorem 5.2 (Inverse probability integral transform). ² Let $(\Omega, \mathbb{E}, \mathbb{P})$ be a probability space. Let X be a RANDOM VARIABLE with PROBABILITY DENSITY FUNCTION $p_X(x)$ and CUMULATIVE DISTRIBUTION FUNCTION $c_X(x)$. Let Y be a RANDOM VARIABLE CUMULATIVE DISTRIBUTION FUNCTION $c_Y(y)$.

T H M	$\left\{ \begin{array}{l} (1). Y = c_X^{-1}(X) \\ (2). Y \text{ is UNIFORMLY DISTRIBUTED} \\ (3). p_X(x) \text{ is CONTINUOUS} \end{array} \text{ and } \right\} \implies \left\{ \begin{array}{l} p_Y(y) = p_X(c_X^{-1}(y)) \\ (Y \text{ has distribution } p_X(c_X^{-1}(y))) \end{array} \right\}$
----------------------	--

¹ Angus (1994), Roussas (2014) page 232 (Theorem 10), Devroye (1986) page 28 (Theorem 2.1)

² Devroye (1986) page 28 (Theorem 2.1), Balakrishnan and Lai (2009) page 624 (14.2.1 Introduction)

Figure 5.1: $Y = f(X)$

PROOF:

$$\begin{aligned}
 c_Y(y) &\triangleq P\{Y \leq y\} && \text{by definition of } c_Y && (\text{Definition B.2 page 160}) \\
 &= P\{c_Z^{-1}(X) \leq y\} && \text{by hypothesis (1)} && \\
 &= P\{X \leq c_Z(y)\} && \text{by hypothesis (3) and} && \text{Proposition A.2 page 154} \\
 &\triangleq c_X[c_Z(y)] && \text{by definition of } c_X && (\text{Definition B.2 page 160}) \\
 &= c_Z(y) && \text{because } 0 \leq c_Z(y) \leq 1 \text{ and by} && \text{Proposition 5.1 page 29} \\
 \implies p_Y(y) &= p_Z(y) && (\text{Y has the distribution of Z}) &&
 \end{aligned}$$

⇒

Definition 5.1.³ Let $f(x)$ be a DIFFERENTIABLE FUNCTION in $\mathbb{R}^{\mathbb{R}}$.

D E F A point $p \in \mathbb{R}$ is a **critical point** off(x) if $f'(p) = 0$.

Theorem 5.3.⁴ Let X and Y be RANDOM VARIABLES in $\mathbb{R}^{\mathbb{R}}$. Let f be a DIFFERENTIABLE FUNCTION in $\mathbb{R}^{\mathbb{R}}$ with N CRITICAL POINTS (Definition 5.1 page 30). Let the range of X be partitioned into $N + 1$ partitions $\{A_n | n = 1, 2, \dots, N + 1\}$ with partition boundaries set at the N CRITICAL POINTS off(x)—as illustrated in Figure 5.1 (page 30). Let $g_n(x) \triangleq f(x)$ but with domain restricted to $x \in A_n$.

T H M $\left\{ \begin{array}{l} (1). \quad Y = f(X) \\ (2). \quad f \text{ is DIFFERENTIABLE} \end{array} \right. \text{ and } \Rightarrow \left\{ p_Y(y) = \sum_{n=1}^{N+1} \frac{p_X(g_n^{-1}(y))}{|f'(g_n^{-1}(y))|} \right\}$

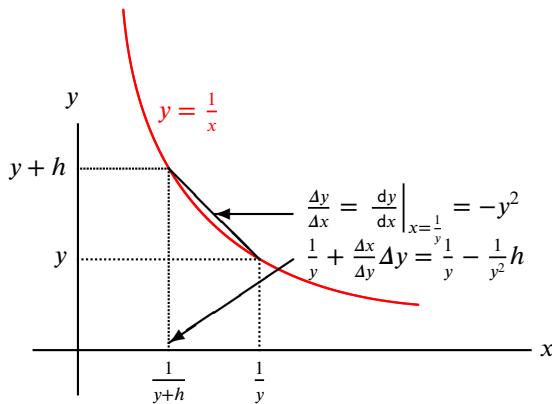
PROOF:

1. The problem with a function $f(x)$ with at least $N = 1$ critical point is that $f^{-1}(y)$ is *not invertible*. That is, $f^{-1}(y)$ has more than one solution (and thus the *relation* $f^{-1}(y)$ is not a *function*). However, note that in each partition A_n , $f(x)$ is *invertible* and thus $f^{-1}(y)$ in that partition has a *unique* solution. Thus, each $g_n(x)$ is *invertible* in its domain (and each $g_n^{-1}(y)$ exists as a function).

³ Callahan (2010) page 189 (Definition 6.1)⁴ Papoulis (1984) pages 95–96 (“Fundamental Theorem”), Papoulis (1990) page 157 (“Fundamental Theorem”), Papoulis (1991), page 93, Haykin (1994) page 235 (0471571768)§“4.5 TRANSFORMATIONS OF RANDOM VARIABLES”, Proakis (2001), page 30,

2. Using item (1), the remainder of the proof follows ...

$$\begin{aligned}
 p_Y(y) &\triangleq \frac{d}{dy} P\{Y \leq y\} && \text{by definition of } p_Y \text{ (Definition B.2 page 160)} \\
 &= \frac{d}{dy} P\{f(X) \leq y\} && \text{by hypothesis (1)} \\
 &= \frac{d}{dy} \sum_{n=1}^{N+1} P\{f(X) \leq y | X \in A_n\} && \text{by sum of products (Theorem A.3 page 153)} \\
 &= \frac{d}{dy} \sum_{n=1}^{N+1} P\{f(X) \leq y | X \in A_n\} P\{X \in A_n\} && \text{by definition of } P\{X|Y\} \text{ (Definition A.4 page 152)} \\
 &= \frac{d}{dy} \sum_{n=1}^{N+1} P\{g_n(X) \leq y | X \in A_n\} P\{X \in A_n\} && \text{by definition of } g_n(x) \\
 &= \frac{d}{dy} \left\{ \begin{array}{ll} \sum_{n=1}^{N+1} P\{X \leq g_n^{-1}(y) | X \in A_n\} P\{X \in A_n\} & \text{for } f'(x) \geq 0 \\ \sum_{n=1}^{N+1} P\{X \geq g_n^{-1}(y) | X \in A_n\} P\{X \in A_n\} & \text{otherwise} \end{array} \right\} && \text{by item (1)} \\
 &= \frac{d}{dy} \left\{ \begin{array}{ll} \sum_{n=1}^{N+1} P\{X \leq g_n^{-1}(y) | X \in A_n\} P\{X \in A_n\} & \text{for } f'(x) \geq 0 \\ \sum_{n=1}^{N+1} [1 - P\{X \leq g_n^{-1}(y) | X \in A_n\} P\{X \in A_n\}] & \text{otherwise} \end{array} \right\} \\
 &= \frac{d}{dy} \left\{ \begin{array}{ll} \sum_{n=1}^{N+1} P\{X \leq g_n^{-1}(y) | X \in A_n\} & \text{for } f'(x) \geq 0 \\ \sum_{n=1}^{N+1} [1 - P\{X \leq g_n^{-1}(y) | X \in A_n\}] & \text{otherwise} \end{array} \right\} && \text{by definition of } P\{X|Y\} \\
 &= \frac{d}{dy} \left\{ \begin{array}{ll} \sum_{n=1}^{N+1} (P\{X \leq g_n^{-1}(y)\} - P\{X < \min A_{n-1}\}) & \text{for } f'(x) \geq 0 \\ \sum_{n=1}^{N+1} [1 - (P\{X \leq g_n^{-1}(y)\} - P\{X < \min A_{n-1}\})] & \text{otherwise} \end{array} \right\} \\
 &= \frac{d}{dy} \left\{ \begin{array}{ll} \sum_{n=1}^{N+1} P\{X \leq g_n^{-1}(y)\} & \text{for } f'(x) \geq 0 \\ \sum_{n=1}^{N+1} [1 - P\{X \leq g_n^{-1}(y)\}] & \text{otherwise} \end{array} \right\} && \text{because } \frac{d}{dy} P\{X < \text{a constant}\} = 0 \\
 &= \left\{ \begin{array}{ll} \sum_{n=1}^{N+1} \frac{d}{dy} c_x[g_n^{-1}(y)] & \text{for } f'(x) \geq 0 \\ \sum_{n=1}^{N+1} \frac{d}{dy} [1 - c_x(g_n^{-1}(y))] & \text{otherwise} \end{array} \right\} && \text{by linearity of } \frac{d}{dy} \text{ operator} \\
 &= \left\{ \begin{array}{ll} \sum_{n=1}^{N+1} p_x[g_n^{-1}(y)] \frac{d}{dy}[g_n^{-1}(y)] & \text{for } f'(x) \geq 0 \\ \sum_{n=1}^{N+1} \left[-p_x[g_n^{-1}(y)] \frac{d}{dy}[g_n^{-1}(y)] \right] & \text{otherwise} \end{array} \right\} && \text{by definition of } p_x \text{ (Definition B.2 page 160) and the chain rule}
 \end{aligned}$$

Figure 5.2: $Y = \frac{1}{X}$

$$\begin{aligned}
 &= \sum_{n=1}^{N+1} p_x(g_n^{-1}(y)) \left| \frac{d}{dy}[g_n^{-1}(y)] \right| \\
 &= \sum_{n=1}^{N+1} \frac{p_x(g_n^{-1}(y))}{|f'(g_n^{-1}(y))|} \quad \text{by Lemma ?? page ??}
 \end{aligned}$$

⇒

Corollary 5.1. ⁵ Let X and Y be RANDOM VARIABLES in $\mathbb{R}^{\mathbb{R}}$. Let $a, b \in \mathbb{R}$.

C O R	$\left\{ \begin{array}{l} (1). \quad Y = aX + b \quad \text{and} \\ (2). \quad a \neq 0 \end{array} \right\} \implies \left\{ p_Y(y) = \frac{1}{ a } p_X\left(\frac{y-b}{a}\right) \right\}$
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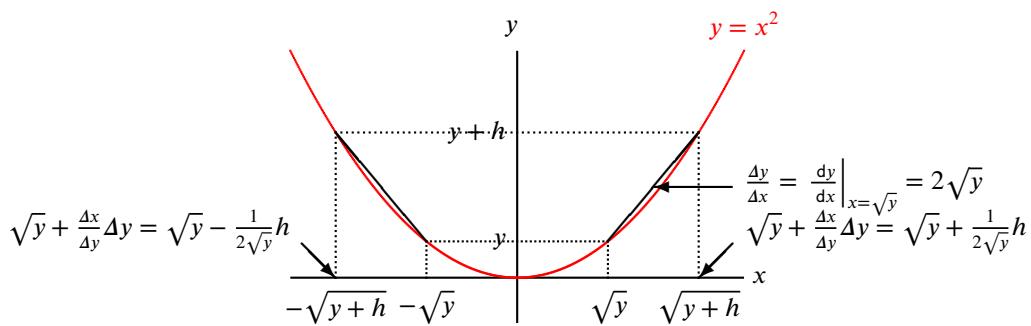
PROOF:

1. Note that $f(x) = ax + b$ is a *differentiable function* with $N = 0$ *critical points* and $f'(x) = a$.
2. The inverse of $f(x)$ is $g_1(y) = f^{-1}(y) = \frac{y-b}{a}$.
3. It follows that

$$\begin{aligned}
 p_Y(y) &= \sum_{n=1}^{N+1} \frac{p_x(g_n^{-1}(y))}{|f'(g_n^{-1}(y))|} \quad \text{by Theorem 5.3 (page 30)} \\
 &= \frac{p_x(f^{-1}(y))}{|f'(f^{-1}(y))|} \quad \text{because } N = 0 \\
 &= \frac{p_x(f^{-1}(y))}{|a|} \quad \text{by item (1)} \\
 &= \frac{1}{|a|} p_X\left(\frac{y-b}{a}\right) \quad \text{by item (2)}
 \end{aligned}$$

⇒

⁵ Papoulis (1984) page 96 (“Illustrations” 1), Papoulis (1991), page 95, Proakis (2001), page 29

Figure 5.3: $Y = rVX^2$ **Corollary 5.2.**⁶

COR $\left\{ Y = \frac{1}{X} \right\} \implies \left\{ p_Y(y) = \frac{1}{y^2} p_X\left(\frac{1}{y}\right) \text{ for } y > 0 \right\}$

PROOF:

1. Note that $f(x) = 1/x$ is a *differentiable function* in $x > 0$ with $N = 0$ *critical points* and $f'(x) = -1/x^2$.
2. The inverse of $f(x)$ is $g_1(y) = f^{-1}(y) = \frac{1}{y}$.
3. It follows that

$$\begin{aligned}
 p_Y(y) &= \sum_{n=1}^{N+1} \frac{p_X(g_n^{-1}(y))}{|f'(g_n^{-1}(y))|} && \text{by Theorem 5.3 (page 30)} \\
 &= \frac{p_X(f^{-1}(y))}{|f'(f^{-1}(y))|} && \text{because } N = 0 \\
 &= \frac{1}{|-1/(1/y)^2|} p_X\left(\frac{1}{y}\right) \\
 &= \frac{1}{y^2} p_X\left(\frac{1}{y}\right)
 \end{aligned}$$

**Corollary 5.3.**⁷ Let X and Y be RANDOM VARIABLES.

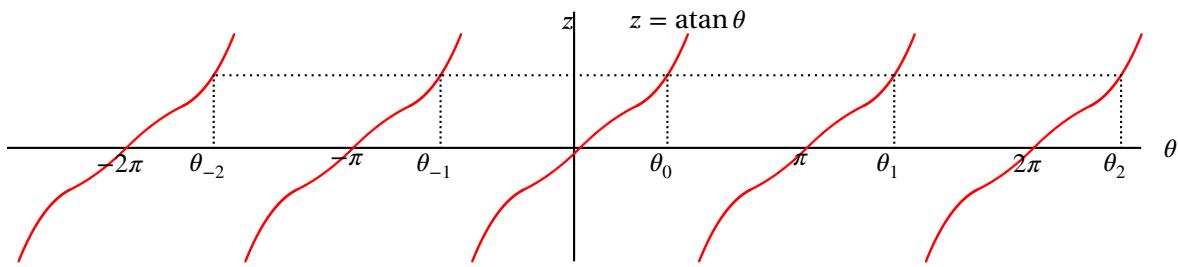
COR $\left\{ Y = X^2 \right\} \implies \left\{ p_Y(y) = \frac{1}{2\sqrt{y}} [p_X(-\sqrt{y}) + p_X(\sqrt{y})] \right\}$

PROOF:

1. The roots of $y = x^2$ are $x_1 = -\sqrt{y}$ and $x_2 = +\sqrt{y}$.
2. The derivative of $f(x) \triangleq y = x^2$ is $f'(x) = 2x$.

⁶ Papoulis (1984) page 97 (Example 5-10), Papoulis (1991), page 94

⁷ Papoulis (1984) page 95 (Example 5-9), Devroye (1986) page 27 (Example 4.4), Papoulis (1991), page 95, Proakis (2001), page 29

Figure 5.4: $Z = \tan \Theta$

3. And so it follows that ...

$$\begin{aligned}
 p_Y(y) &= \sum_{n=1}^N \frac{p_X(x_n)}{|f'(x_n)|} && \text{by Theorem 5.3 page 30} \\
 &= \frac{p_X(x_1)}{|f'(x_1)|} + \frac{p_X(x_2)}{|f'(x_2)|} && \text{by definition of } \sum \\
 &= \frac{p_X(-\sqrt{y})}{|f'(-\sqrt{y})|} + \frac{p_X(\sqrt{y})}{|f'(\sqrt{y})|} && \text{by item (1)} \\
 &= \frac{p_X(-\sqrt{y})}{2\sqrt{y}} + \frac{p_X(\sqrt{y})}{2\sqrt{y}} && \text{by item (2)} \\
 &= \frac{1}{2\sqrt{y}} \left[p_X(-\sqrt{y}) + p_X(\sqrt{y}) \right] && \text{by } \textit{linearity} \text{ of } + \text{ operation}
 \end{aligned}$$

⇒

Corollary 5.4.⁸ Let $Z = \tan \Theta$. Then

C	O	R	$\{Z = \tan \Theta\} \implies \left\{ p_Z(z) = \frac{1}{1+z^2} \sum_{n \in Z} p_\theta(\tan(z) + n\pi) \right\}$
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PROOF:

1. The roots of $z = \tan \theta$ are $\{\theta_n = \arctan z + n\pi | n \in \mathbb{Z}\}$.
2. The derivative of $z = \tan \theta$ is $f'(\theta) = \sec^2 \theta$.
3. It follows that

$$\begin{aligned}
 p_Z(z) &= \sum_{n=1}^N \frac{p_\theta(\theta_n)}{|f'(\theta_n)|} \\
 &= \sum_n \frac{p_\theta(\arctan z + n\pi)}{|f'(\arctan z + n\pi)|} \\
 &= \sum_n \frac{p_\theta(\arctan z + n\pi)}{|\sec^2(\arctan z + n\pi)|} \\
 &= \sum_n \cos^2(\arctan z + n\pi) p_\theta(\arctan z + n\pi)
 \end{aligned}$$

⁸ Papoulis (1991), pages 99–100

$$\begin{aligned}
 &= \cos^2(\tan z) \sum_n p_\theta(\tan z + n\pi) \\
 &= \frac{1}{1+z^2} \sum_n p_\theta(\tan z + n\pi)
 \end{aligned}$$



5.2 Functions of two random variables

Theorem 5.4. ⁹ Let X , Y , and Z be RANDOM VARIABLES. Let \star be the CONVOLUTION operator (Definition P.3 page 336).

T H M	$\left\{ \begin{array}{l} (1). \quad Z \triangleq X + Y \\ (2). \quad X \text{ and } Y \text{ are INDEPENDENT} \end{array} \right. \quad \text{and} \quad \begin{array}{l} \text{(Definition A.3 page 151)} \\ \hline \end{array} \right\} \Rightarrow \{p_Z(z) = p_X(z) \star p_Y(z)\}$
----------------------------------	--

PROOF:

$$\begin{aligned}
 p_Z(z) &\triangleq \frac{d}{dz} c_Z(z) && \text{by definition of } p_Z && \text{(Definition B.2 page 160)} \\
 &\triangleq \frac{d}{dz} P\{Z \leq z\} && \text{by definition of } c_Z && \text{(Definition B.2 page 160)} \\
 &= \frac{d}{dz} P\{X + Y \leq z\} && \text{by hypothesis (1)} && \\
 &= \frac{d}{dz} \lim_{\epsilon \rightarrow 0} \sum_{n \in \mathbb{Z}} P\{X + Y \leq z | y + n\epsilon < Y \leq y + (n+1)\epsilon\} && \text{by sum of products} && \text{(Theorem A.3 page 153)} \\
 &= \frac{d}{dz} \int_{y \in \mathbb{R}} P\{X + Y \leq z | Y = y\} p_Y(y) dy && \text{by definiton of } P\{X | Y\} && \text{(Definition A.4 page 152)} \\
 &= \frac{d}{dz} \int_{y \in \mathbb{R}} P\{X \leq z - y | Y = y\} p_Y(y) dy && \\
 &= \frac{d}{dz} \int_{y \in \mathbb{R}} P\{X \leq z - y\} p_Y(y) dy && \text{by hypothesis (2)} && \\
 &\triangleq \frac{d}{dz} \int_{y \in \mathbb{R}} c_X(z - y) p_Y(y) dy && \text{by definition of } c_X && \text{(Definition B.2 page 160)} \\
 &= \int_{y \in \mathbb{R}} \frac{d}{dy} [c_X(z - y) p_Y(y)] dy && \text{by linearity of } \frac{d}{dz} && \\
 &= \int_{y \in \mathbb{R}} \left[\frac{d}{dy} c_X(z - y) \right] p_Y(y) dy && \text{because } y \text{ is fixed inside the integral} && \\
 &\triangleq \int_y p_X(z - y) p_Y(y) dy && \text{by definition of } p_X && \text{(Definition B.2 page 160)} \\
 &= p_X(z) \star p_Y(z) && \text{by definition of } \star && \text{(Definition P.3 page 336)}
 \end{aligned}$$



Theorem 5.5. Let

- X_1 and X_2 be random variables with joint distribution $p_{X_1, X_2}(x_1, x_2)$
- $Y_1 = f_1(x_1, x_2)$ and $Y_2 = f_2(x_1, x_2)$

⁹ Papoulis (1990) page 160 (Example 5.16)

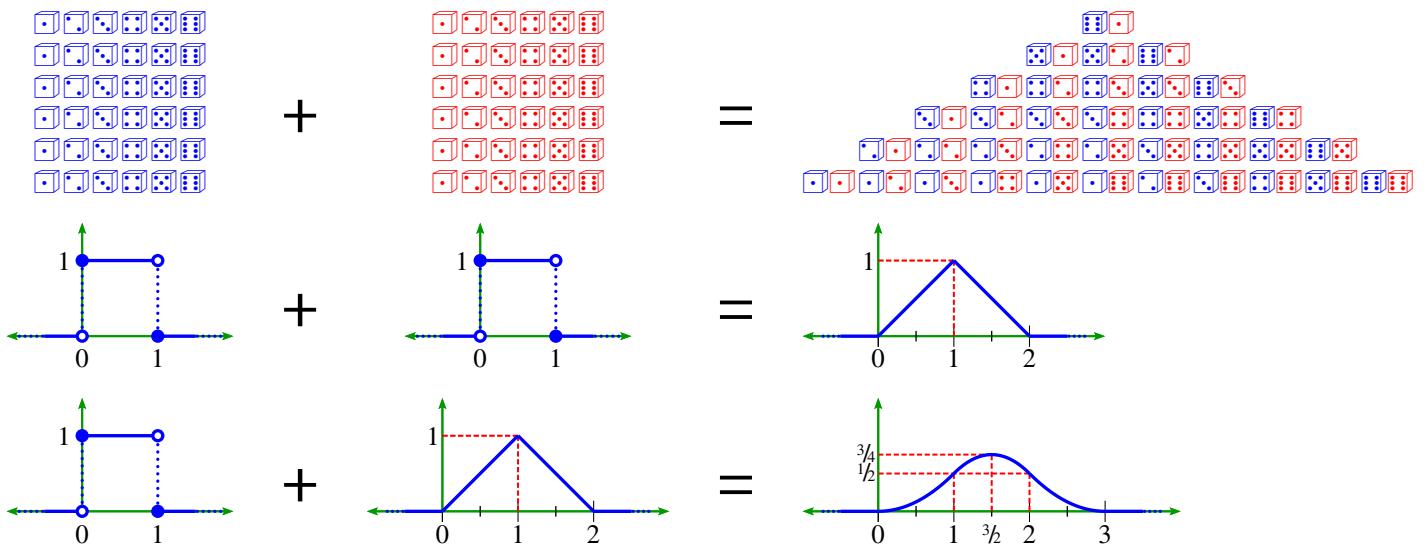


Figure 5.5: Sum of random variables yields convolution of pdfs (Theorem 5.4 page 35)

Then the joint distribution of Y_1 and Y_2 is

$$\text{T H M} \quad p_{Y_1, Y_2}(y_1, y_2) = \frac{p_{X_1, X_2}(x_1, x_2)}{|J(x_1, x_2)|} = \frac{p_{X_1, X_2}(x_1, x_2)}{\begin{vmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} \end{vmatrix}} = \frac{p_{X_1, X_2}(x_1, x_2)}{\frac{\partial f_1}{\partial x_1} \frac{\partial f_2}{\partial x_2} - \frac{\partial f_1}{\partial x_2} \frac{\partial f_2}{\partial x_1}}$$

Proposition 5.2. Let X and Y be random variables with joint distribution $p_{XY}(x, y)$ and

$$R^2 \triangleq X^2 + Y^2 \quad \Theta \triangleq \tan^{-1} \frac{Y}{X}.$$

Then

$$\text{P R P} \quad p_{R, \Theta}(r, \theta) = r p_{XY}(r \cos \theta, r \sin \theta)$$

PROOF:

$$\begin{aligned} p_{R, \Theta}(r, \theta) &= \frac{p_{XY}(x, y)}{|J(x, y)|} = \frac{p_{XY}(x, y)}{\begin{vmatrix} \frac{\partial R}{\partial x} & \frac{\partial R}{\partial y} \\ \frac{\partial \theta}{\partial x} & \frac{\partial \theta}{\partial y} \end{vmatrix}} = \frac{p_{XY}(x, y)}{\begin{vmatrix} \frac{x}{\sqrt{x^2+y^2}} & \frac{y}{\sqrt{x^2+y^2}} \\ \frac{-y}{x^2+y^2} & \frac{x}{x^2+y^2} \end{vmatrix}} \\ &= \frac{p_{XY}(x, y)}{\frac{x}{\sqrt{x^2+y^2}} \frac{x}{x^2+y^2} - \frac{y}{\sqrt{x^2+y^2}} \frac{-y}{x^2+y^2}} \\ &= \frac{p_{XY}(x, y)}{\frac{x^2+y^2}{(x^2+y^2)^{3/2}}} \\ &= p_{XY}(x, y) \frac{(x^2+y^2)^{3/2}}{x^2+y^2} \\ &= p_{XY}(r \cos \theta, r \sin \theta) \frac{r^3}{r^2} \\ &= r p_{XY}(r \cos \theta, r \sin \theta) \end{aligned}$$

Proposition 5.3. Let $X \sim N(0, \sigma^2)$ and $Y \sim N(0, \sigma^2)$ be independent random variables and

$$R^2 \triangleq X^2 + Y^2 \quad \Theta \triangleq \tan^{-1} \frac{Y}{X}.$$



Then

- | | |
|----------------------------------|---|
| P
R
P | 1. <i>R and Θ are independent with joint distribution</i> $p_{R,\Theta}(r, \theta) = p_R(r)p_\theta(\theta)$
2. <i>R has Rayleigh distribution</i> $p_R(r) = \frac{r}{\sigma^2} \exp \frac{-r^2}{2\sigma^2}$
3. <i>Θ has uniform distribution</i> $p_\theta(\theta) = \frac{1}{2\pi}$ |
|----------------------------------|---|

PROOF:

$$\begin{aligned}
 p_{R,\Theta}(r, \theta) &= r p_{XY}(r\cos\theta, r\sin\theta) && \text{by Proposition 5.2 (page 36)} \\
 &= r p_X(r\cos\theta) p_Y(r\sin\theta) && \text{by independence hypothesis} \\
 &= r \frac{1}{\sqrt{2\pi\sigma^2}} \exp \frac{(r\cos\theta - 0)^2}{-2\sigma^2} \frac{1}{\sqrt{2\pi\sigma^2}} \exp \frac{(r\sin\theta - 0)^2}{-2\sigma^2} \\
 &= \frac{1}{2\pi\sigma^2} r \exp \frac{r^2(\cos^2\theta + \sin^2\theta)}{-2\sigma^2} \\
 &= \frac{1}{2\pi\sigma^2} r \exp \frac{r^2}{-2\sigma^2} \\
 &= \left[\frac{1}{2\pi} \right] \left[\frac{r}{\sigma^2} \exp \frac{r^2}{-2\sigma^2} \right]
 \end{aligned}$$

by Proposition 5.2 (page 36)

by independence hypothesis

Proposition 5.4. Let X and Y be RANDOM VARIABLES with covariance σ_{xy} on a PROBABILITY SPACE (Ω, \mathbb{E}, P) .

P R P	$\left\{ \begin{array}{l} (A). X \text{ is GAUSSIAN with } N(\mu_X, \sigma_X^2) \text{ and} \\ (B). Y \text{ is GAUSSIAN with } N(\mu_Y, \sigma_Y^2) \text{ and} \\ (C). \sigma_{xy} = \text{cov}[X, Y] \end{array} \right\} \Rightarrow \left\{ P\{X > Y\} = Q\left(\frac{-\mu_X + \mu_Y}{\sigma_X^2 + \sigma_Y^2 - 2\sigma_{xy}} \right) \right\}$
----------------------------------	---

PROOF: Because X and Y are jointly Gaussian, their linear combination $Z = rvX - Y$ is also Gaussian. A Gaussian distribution is completely defined by its mean and variance. So, to determine the distribution of Z , we just have to determine the mean and variance of Z .

$$\begin{aligned}
 EZ &= EX - EY \\
 &= \mu_X - \mu_Y
 \end{aligned}$$

$$\begin{aligned}
 \text{var } Z &= EZ^2 - (EZ)^2 \\
 &= E(X - Y)^2 - (EX - EY)^2 \\
 &= E(X^2 - 2XY + Y^2) - [(EX)^2 - 2EXEY + (EY)^2] \\
 &= [EX^2 - (EX)^2] + [Y^2 - (EY)^2] - 2[EXY - EXEY] \\
 &= \text{var } X + \text{var } Y - 2\text{cov}[X, Y] \\
 &\triangleq \sigma_X^2 + \sigma_Y^2 - 2\sigma_{xy}
 \end{aligned}$$

$$\begin{aligned}
 P\{X > Y\} &= P\{X - Y > 0\} \\
 &= P\{Z > 0\} \\
 &= Q\left(\frac{z - EZ}{\text{var } Z} \right) \Big|_{z=0} \\
 &= Q\left(\frac{0 - \mu_X + \mu_Y}{\sigma_X^2 + \sigma_Y^2 - 2\sigma_{xy}} \right)
 \end{aligned}$$



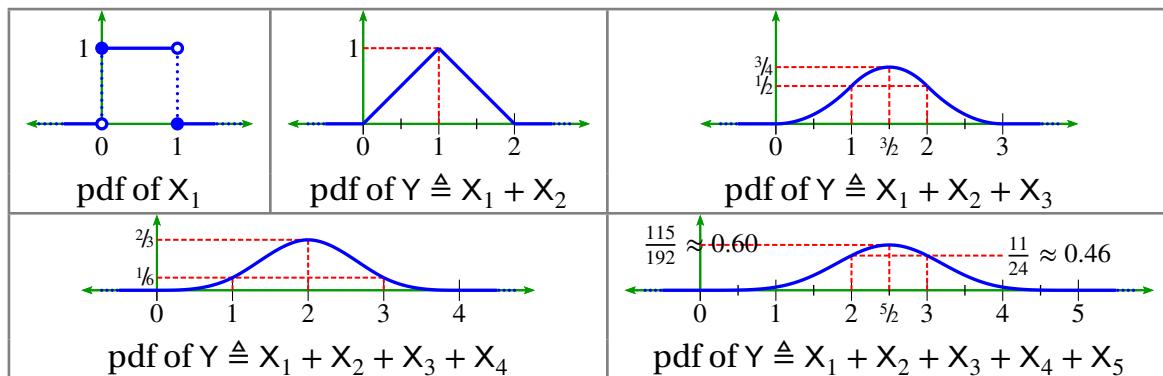


Figure 5.6: The distributions of sums of independent uniformly distributed random variables (Example 5.1 page 38)

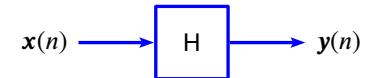
Example 5.1. Let (X_1, X_2, X_3, \dots) be a sequence of *independent* (Definition A.3 page 151) *uniformly distributed* random variables. Let $p_n(x)$ be the *probability density function* of $Y \triangleq \sum_{n=1}^N X_n$. Some of these distributions are illustrated in Figure 5.6 (page 38). Note that the distributions of the sequence (p_1, p_2, p_3, \dots) are all *B-splines* (Definition S.2 page 367) and all form a *partition of unity*.

CHAPTER 6

OPERATORS ON DISCRETE RANDOM SEQUENCES

6.1 LTI operators on random sequences

Theorem 6.1. ¹ Let $x(n)$ be a RANDOM SEQUENCE with MEAN μ_X and $y(n)$ a RANDOM SEQUENCE with MEAN μ_Y . Let S be a system with IMPULSE RESPONSE $h(n)$, INPUT $x(n)$, and OUTPUT $y(n)$.



T H M

$$\{ \text{S is (LTI)} \} \implies \left\{ \begin{array}{lcl} (1). & \mu_Y(n) &= \sum_{k \in \mathbb{Z}} h(k) \mu_X(n-k) & \triangleq h(n) \star \mu_X(n) \quad \text{and} \\ (2). & R_{xy}(n, m) &= \sum_{k \in \mathbb{Z}} h^*(k) R_{xx}(n-k, m+k) & \\ (3). & R_{yy}(n, m) &= \sum_{k \in \mathbb{Z}} h^*(k) R_{yx}(n-k, m+k) & \end{array} \right\}$$

PROOF:

$$\begin{aligned}
 \mu_Y(n) &\triangleq E[y(n)] && \text{by definition of } \mu_Y && (\text{Definition 2.2 page 11}) \\
 &= E\left[\sum_{k \in \mathbb{Z}} h(k)x(n-k)\right] && \text{by LTI hypothesis} \\
 &= \sum_{k \in \mathbb{Z}} h(k)E[x(n-k)] && \text{by linear property} \\
 &= \sum_{k \in \mathbb{Z}} h(k)\mu_X(n-k) && \text{by definition of } \mu_X && (\text{Definition 2.2 page 11}) \\
 &\triangleq h(n) \star \mu_X(n) && \text{by definition of convolution} && (\text{Definition R.3 page 353})
 \end{aligned}$$

$$\begin{aligned}
 R_{xy}(n, m) &\triangleq E[x(n+m)y^*(n)] && \text{by definition of } R_{xy}(n, m) && (\text{Definition 2.2 page 11}) \\
 &= E[x(n+m)(h(n) \star x(n))^*] && \text{by LTI hypothesis} \\
 &\triangleq E\left[x(n+m)\left(\sum_{k \in \mathbb{Z}} h(k)x(n-k)\right)^*\right] && \text{by definition of convolution } \star && (\text{Definition R.3 page 353}) \\
 &= E\left[x(n+m) \sum_{k \in \mathbb{Z}} h^*(k)x^*(n-k)\right] && \text{by distributive property of } *-\text{algebras} && (\text{Definition J.3 page 250})
 \end{aligned}$$

¹ Papoulis (1991), page 310

$$\begin{aligned}
 &= E \left[\sum_{k \in \mathbb{Z}} h^*(k) x(n+m) x^*(n-k) \right] && \text{by } \textit{distributive} \text{ property of } (\mathbb{C}, +, \cdot, 0, 1) \quad (\text{Definition F.5 page 192}) \\
 &= \sum_{k \in \mathbb{Z}} h^*(k) E[x(n-k+k+m)x^*(n-k)] && \text{by } \textit{linear} \text{ property of } E \quad (\text{Theorem 1.1 page 4}) \\
 &\triangleq \sum_{k \in \mathbb{Z}} h^*(k) R_{xx}(n-k, m+k) && \text{by definition of } R_{xx}(n, m) \quad (\text{Definition 2.2 page 11})
 \end{aligned}$$

$$\begin{aligned}
 R_{yy}(n, m) &\triangleq E[y(n+m)y^*(n)] && \text{by definition of } R_{xy}(n, m) \quad (\text{Definition 2.2 page 11}) \\
 &= E[y(n+m)(h(n) \star x(n))^*] && \text{by LTI hypothesis} \\
 &\triangleq E \left[y(n+m) \left(\sum_{k \in \mathbb{Z}} h(k) x(n-k) \right)^* \right] && \text{by definition of convolution} \quad (\text{Definition R.3 page 353}) \\
 &= E \left[y(n+m) \sum_{k \in \mathbb{Z}} h^*(k) x^*(n-k) \right] && \text{by } \textit{distributive} \text{ property of } *-\text{algebras} \quad (\text{Definition J.3 page 250}) \\
 &= E \left[\sum_{k \in \mathbb{Z}} h^*(k) y(n+m) x^*(n-k) \right] && \text{by } \textit{distributive} \text{ property of } (\mathbb{C}, +, \cdot, 0, 1) \quad (\text{Definition F.5 page 192}) \\
 &= \sum_{k \in \mathbb{Z}} h^*(k) E[y(n-k+k+m)x^*(n-k)] && \text{by } \textit{linear} \text{ property of } E \quad (\text{Theorem 1.1 page 4}) \\
 &\triangleq \sum_{k \in \mathbb{Z}} h^*(k) R_{yx}(n-k, m+k) && \text{by definition of } R_{xy}(n, m) \quad (\text{Definition 2.2 page 11})
 \end{aligned}$$

⇒

6.2 LTI operators on WSS random sequences

Corollary 6.1. Let S be the system defined in Theorem 6.1 (page 39).

COR

$$\left. \begin{array}{l} (A). \quad S \text{ is LTI} \\ (B). \quad x(n) \text{ is WSS} \end{array} \right\} \implies \left\{ \begin{array}{ll} (1). & \mu_Y = \mu_X \sum_{n \in \mathbb{Z}} h(k) \quad \text{and} \\ (2). & R_{xy}(m) = R_{xx}(m) \star h^*(-m) \triangleq \sum_{k \in \mathbb{Z}} h^*(k) R_{xx}(m+k) \quad \text{and} \\ (3). & R_{yy}(m) = R_{yx}(m) \star h^*(-m) \triangleq \sum_{k \in \mathbb{Z}} h^*(k) R_{xy}(m+k) \quad \text{and} \\ (4). & R_{yy}(m) = R_{xx}^*(m) \star h(-m) \star h^*(-m) \end{array} \right.$$

PROOF:

$$\begin{aligned}
 \mu_Y &= \mu_Y(n) && \text{by Proposition 2.1 page 14} && \text{and hypothesis (A)} \\
 &= \sum_{n \in \mathbb{Z}} h(k) \mu_X(n-k) && \text{by Theorem 2.1 page 12} && \text{and hypothesis (B)} \\
 &= \sum_{n \in \mathbb{Z}} h(k) \mu_X(0) && \text{by Definition 7.1 page 47} && \text{and hypothesis (B)} \\
 &= \mu_X(0) \sum_{n \in \mathbb{Z}} h(k) && \text{by linear property of } \sum && \\
 &= \mu_X \sum_{n \in \mathbb{Z}} h(k) && \text{by Proposition 2.1 page 14} &&
 \end{aligned}$$

¹  Papoulis (1991), page 323



$$\begin{aligned}
R_{xy}(m) &\triangleq R_{xy}(0, m) && \text{by Proposition 2.1 page 14} && \text{and hypothesis (A)} \\
&= \sum_{k \in \mathbb{Z}} h^*(k) R_{xx}(0 - k, m + k) && \text{by Theorem 6.1 page 39} && \text{and hypothesis (B)} \\
&= \sum_{k \in \mathbb{Z}} h^*(k) R_{xx}(m + k) && \text{by Proposition 2.1 page 14} && \text{and hypothesis (A)} \\
&= h^*(-m) \star R_{xx}(m) && \text{by Proposition R.2 page 354} && \\
R_{yy}(m) &\triangleq R_{yy}(0, m) && \text{by Proposition 2.1 page 14} && \text{and hypothesis (A)} \\
&= \sum_{k \in \mathbb{Z}} h^*(k) R_{yx}(n - k, m + k) && \text{by Theorem 6.1 page 39} && \text{and hypothesis (B)} \\
&= \sum_{k \in \mathbb{Z}} h^*(k) R_{yx}(m + k) && \text{by Proposition 2.1 page 14} && \text{and hypothesis (A)} \\
&= h^*(-m) \star R_{yx}(m) && \text{by Proposition R.2 page 354} && \\
R_{yy}(m) &= h^*(-m) \star R_{yx}(m) && \text{by result (2)} && \\
&= h^*(-m) \star R_{xy}^*(m) && \text{by Corollary 2.1 page 14} && \\
&= h^*(-m) \star [h^*(-m) \star R_{xx}(m)]^* && \text{by result (1)} && \\
&= h^*(-m) \star h(-m) \star R_{xx}^*(m) && \text{by } \textit{distributive property of } *-\textbf{algebras} && \text{(Definition J.3 page 250)}
\end{aligned}$$

⇒

Corollary 6.2. ² Let \mathbf{S} be a system with IMPULSE RESPONSE $h(n)$, INPUT $x(n)$, and OUTPUT $y(n)$.

COR $\left\{ \begin{array}{l} (A). \quad h \text{ is LINEAR TIME INVARIANT and} \\ (B). \quad x \text{ and } y \text{ are WIDE SENSE STATIONARY} \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} (1). \quad \check{S}_{xy}(z) = \check{S}_{xx}(z)\check{H}^*\left(\frac{1}{z^*}\right) \text{ and} \\ (2). \quad \check{S}_{yy}(z) = \check{S}_{yx}(z)\check{H}^*\left(\frac{1}{z^*}\right) \text{ and} \\ (3). \quad \check{S}_{yy}(z) = \check{S}_{xx}(z)\check{H}(z)\check{H}^*\left(\frac{1}{z^*}\right) \end{array} \right\}$

⇒

PROOF: The proof is given in Proposition ?? (page ??) (1).

Corollary 6.3. Let \mathbf{S} be a system with IMPULSE RESPONSE $h(n)$, INPUT $x(n)$, and OUTPUT $y(n)$.

COR $\left\{ \begin{array}{l} (A). \quad h \text{ is LTI and} \\ (B). \quad x \text{ and } y \text{ are WSS} \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} (1). \quad \tilde{S}_{xy}(\omega) = \tilde{S}_{xx}(\omega)\tilde{H}^*(\omega) \text{ and} \\ (2). \quad \tilde{S}_{yy}(\omega) = \tilde{S}_{xy}(\omega)\tilde{H}(\omega) \text{ and} \\ (3). \quad \tilde{S}_{yy}(\omega) = \tilde{S}_{xx}(\omega)|\tilde{H}(\omega)|^2 \end{array} \right\}$

⇒

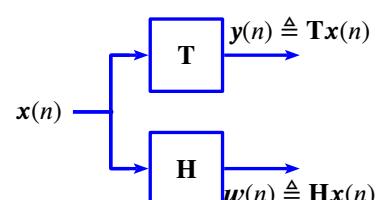
PROOF: The proof is given in Proposition ?? (page ??) (1).

6.3 Parallel operators on WSS random sequences

Theorem 6.2. Let \mathbf{S} be the SYSTEM illustrated to the right, where \mathbf{T} is NOT NECESSARILY LINEAR. Let

$$(\mathbf{h}(n)) \triangleq \mathbf{H}\delta(n) \triangleq \sum_{m \in \mathbb{Z}} h(m)\delta(n - m)$$

be the IMPULSE RESPONSE of \mathbf{H} .



² Papoulis (1991), page 323

THEOREM

$$\left\{ \begin{array}{l} \text{(A). } x(n) \text{ is WSS and} \\ \text{(B). } H \text{ is LTI} \end{array} \right\} \Rightarrow$$

$$\left\{ \begin{array}{ll} \text{(1). } R_{wy}(m) &= \sum_{n \in \mathbb{Z}} h(n)R_{xy}(m-n) \quad (\text{convolution}) \\ &\triangleq h(m) \star R_{xy}(m) \quad \text{and} \\ \text{(2). } \check{S}_{wy}(z) &= \check{H}(z)\check{S}_{xy}(z) \quad \text{and} \\ \text{(3). } \tilde{S}_{wy}(\omega) &= \tilde{H}(\omega)\tilde{S}_{xy}(\omega) \end{array} \right\}$$

PROOF:

$R_{wy}(m) \triangleq E[w(m)y^*(0)]$	by (A) and definition of R_{wy}	(Definition 2.4 page 12)
$\triangleq E([Hx](m)y^*(0))$	by definition of S	
$= HE(x(m)y^*(0))$	by LTI hypothesis	(B)
$\triangleq HR_{xy}(m)$	by definition of R_{xy}	(Definition 2.4 page 12)
$= \sum_{n \in \mathbb{Z}} h(n)R_{xy}(m-n)$	by definition of H impulse response ($h(n)$)	
$= [h(m) \star R_{xy}(m)]$	by definition of convolution	(Definition R.3 page 353)
$\check{S}_{wy}(z) \triangleq ZR_{wy}(m)$	by definition of \check{S}_{wy}	(Definition 2.5 page 15)
$= [h(m) \star R_{xy}(m)]$	by previous result	
$= \check{H}(z)\check{S}_{xy}(z)$	by Convolution Theorem	(Theorem R.2 page 356)
$\tilde{S}_{wy}(\omega) \triangleq \check{F}R_{wy}(m)$	by definition of \tilde{S}_{wy}	(Definition 7.3 page 48)
$= [h(m) \star R_{xy}(m)]$	by previous result	
$= \tilde{H}(\omega)\tilde{S}_{xy}(\omega)$	by Convolution Theorem	(Theorem R.2 page 356)



6.4 Whitening discrete random sequences

Note that if $L(z)$ has a root at $z = re^{i\theta}$, then $L^*(1/z^*)$ has a root at

$$\frac{1}{z^*} = \frac{1}{(re^{i\theta})^*} = \frac{1}{re^{-i\theta}} = \frac{1}{r}e^{i\theta}.$$

That is, if $L(z)$ has a root inside the unit circle, then $L^*(1/z^*)$ has a root directly opposite across the unit circle boundary (see Figure 6.1 page 43). A causal stable filter $\check{H}(z)$ must have all of its poles inside the unit circle. A filter has *minimum phase* (Definition R.5 page 357) if both its poles and zeros are inside the unit circle. One advantage of a minimum phase filter is that its inverse (zeros become poles and poles become zeros) is also causal and stable.

The next theorem demonstrates a method for “whitening” a *random sequence* $x(n)$ with a filter constructed from a decomposition of $R_{xx}(m)$. The technique is stated precisely in Theorem 6.3 page 42 and illustrated in Figure 6.2 page 43. Both imply two filters with impulse responses $l(n)$ and $\gamma(n)$. Filter $l(n)$ is referred to as the **innovations filter** (because it generates or “innovates” $x(n)$ from a white noise process $w(n)$) and $\gamma(n)$ is referred to as the **whitening filter** because it produces a white noise sequence when the input sequence is $x(n)$.³

Theorem 6.3. Let $x(n)$ be a WSS RANDOM SEQUENCE with auto-correlation $R_{xx}(m)$ and spectral density $\check{S}_{xx}(z)$. If $\check{S}_{xx}(z)$ has a rational expression, then the following are true:

³ Papoulis (1991), pages 401–402



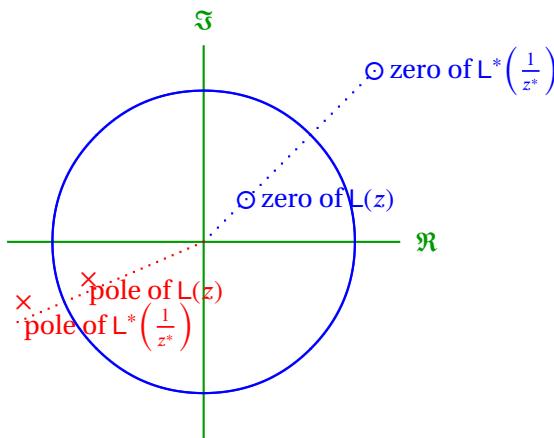


Figure 6.1: Mirrored roots in complex-z plane

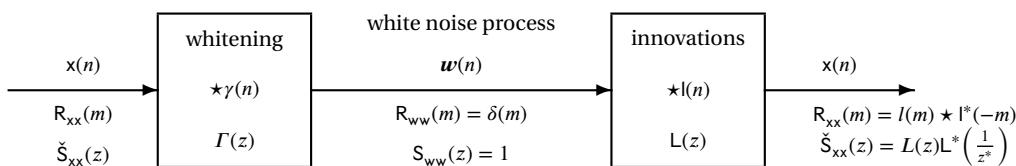


Figure 6.2: Innovations and whitening filters

1. There exists a rational expression $L(z)$ with minimum phase such that

$$\check{S}_{xx}(z) = L(z)L^*\left(\frac{1}{z^*}\right).$$

2. An LTI filter for which the Laplace transform of the impulse response $\gamma(n)$ is

$$\Gamma(z) = \frac{1}{L(z)}$$

is both causal and stable.

3. If $x(n)$ is the input to the filter $\gamma(n)$, the output $y(n)$ is a **white noise sequence** such that

$$S_{yy}(z) = 1 \quad R_{yy}(m) = \bar{\delta}(m).$$

PROOF:

$$\begin{aligned}
 S_{ww}(z) &= \Gamma(z)\Gamma^*\left(\frac{1}{z^*}\right)\check{S}_{xx}(z) \\
 &= \frac{1}{L(z)} \frac{1}{L^*\left(\frac{1}{z^*}\right)} \check{S}_{xx}(z) \\
 &= \frac{1}{L(z)} \frac{1}{L^*\left(\frac{1}{z^*}\right)} L(z)L^*\left(\frac{1}{z^*}\right) \\
 &= 1
 \end{aligned}$$



CHAPTER 7

OPERATORS ON CONTINUOUS RANDOM SEQUENCES

7.1 LTI Operations on non-stationary random processes

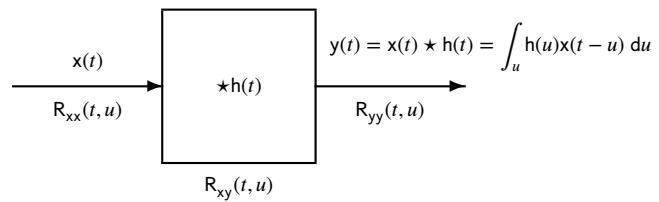


Figure 7.1: Linear system with random process input and output

Theorem 7.1. ¹ Let $h : \mathbb{R} \rightarrow \mathbb{C}$ be the impulse response of a linear time-invariant system and let $y(t) = h(t) \star x(t) \triangleq \int_{u \in \mathbb{R}} h(u)x(t-u) du$ as illustrated in Figure 7.1 page 45. Then

Correlation functions

$$\begin{aligned} R_{xy}(t,u) &= R_{xx}(t,u) \star h^*(u) &\triangleq \int_v h^*(v)R_{xx}(t,u-v) dv \\ R_{yy}(t,u) &= R_{xy}(t,u) \star h(t) &\triangleq \int_v h(v)R_{xy}(t-v,u) dv \\ R_{yy}(t,u) &= R_{xx}(t,u) \star h(t) \star h^*(u) &\triangleq \int_w h^*(w) \int_v h(v)R_{xx}(t-v,u-w) dv dw \end{aligned}$$

Laplace power spectral density functions

$$\begin{aligned} \check{S}_{xy}(s,r) &= \check{S}_{xx}(s,r)\check{h}^*(r^*) \\ \check{S}_{yy}(s,r) &= \check{S}_{xy}(s,r)\check{h}(s) \\ \check{S}_{yy}(s,r) &= \check{S}_{xx}(s,r)\check{h}(s)\check{h}^*(r^*) \end{aligned}$$

Power spectral density functions

$$\begin{aligned} S_{xy}(f,g) &= S_{xx}(f,g)\tilde{h}^*(-g) \\ S_{yy}(f,g) &= S_{xy}(f,g)\tilde{h}(\omega) \\ S_{yy}(f,g) &= S_{xx}(f,g)\tilde{h}(\omega)\tilde{h}^*(-g) \end{aligned}$$

PROOF:

$$\begin{aligned}
 R_{xy}(t, u) &\triangleq E[x(t)y^*(u)] \\
 &= E\left[x(t)\left(\int_v h(v)x(u-v) dv\right)^*\right] \\
 &= E\left[x(t)\int_v h^*(v)x^*(u-v) dv\right] \\
 &= \int_v h^*(v)E[x(t)x^*(u-v)] dv \\
 &= \int_v h^*(v)R_{xx}(t, u-v) dv \\
 &\triangleq R_{xx}(t, u) \star h^*(u)
 \end{aligned}$$

$$\begin{aligned}
 R_{yy}(t, u) &\triangleq E[y(t)y^*(u)] \\
 &= E\left[\left(\int_v h(v)x(t-v) dv\right)y^*(u)\right] \\
 &= \int_v h(v)E[x(t-v)y^*(u)] dv \\
 &= \int_v h(v)R_{xy}(t-v, u) dv \\
 &\triangleq R_{xy}(t, u) \star h(t)
 \end{aligned}$$

$$\begin{aligned}
 R_{yy}(t, u) &\triangleq E[y(t)y^*(u)] \\
 &= E\left[\left(\int_v h(v)x(t-v) dv\right)\left(\int_w h(w)x(u-w) dw\right)^*\right] \\
 &= \int_w h^*(w) \int_v h(v)E[x(t-v)x^*(u-w)] dv dw \\
 &= \int_w h^*(w) \int_v h(v)R_{xx}(t-v, u-w) dv dw \\
 &= \int_w h^*(w)[R_{xx}(t, u-w) \star h(t)] dw \\
 &\triangleq R_{xx}(t, u) \star h(t) \star h^*(u)
 \end{aligned}$$

$$\begin{aligned}
 \check{S}_{xy}(s, r) &\triangleq LR_{xy}(t, u) \\
 &= L[R_{xx}(t, u) \star h^*(u)] \\
 &= L[R_{xx}(t, u)]L[h^*(u)] \\
 &= \check{S}_{xx}(s, r) \int_{u \in \mathbb{R}} h^*(u)e^{-ru} du \\
 &= \check{S}_{xx}(s, r) \left[\int_{u \in \mathbb{R}} h(u)e^{-r^*u} du \right]^* \\
 &= \check{S}_{xx}(s, r) \check{h}^*(r^*)
 \end{aligned}$$

$$\begin{aligned}
 \check{S}_{yy}(s, r) &\triangleq LR_{yy}(t, u) \\
 &= L[R_{xy}(t, u) \star h(t)] \\
 &= L[R_{xy}(t, u)]L[h(t)] \\
 &= \check{S}_{xy}(s, r) \check{h}(s)
 \end{aligned}$$



$$\begin{aligned}
 &= \check{S}_{xy}(s, r) \check{h}(s) \\
 &= \check{S}_{xx}(s, r) \check{h}^*(r^*) \check{h}(s) \\
 &= \check{S}_{xx}(s, r) \check{h}(s) \check{h}^*(r^*)
 \end{aligned}$$

$$\begin{aligned}
 S_{xy}(f, g) &\triangleq \tilde{\mathbf{F}}\mathbf{R}_{xy}(t, u) \\
 &= \tilde{\mathbf{F}}[\mathbf{R}_{xx}(t, u) \star h^*(u)] \\
 &= \tilde{\mathbf{F}}[\mathbf{R}_{xx}(t, u)] \tilde{\mathbf{F}}[h^*(u)] \\
 &= S_{xx}(f, g) \int_{u \in \mathbb{R}} h^*(u) e^{-i2\pi gu} du \\
 &= S_{xx}(f, g) \left[\int_{u \in \mathbb{R}} h(u) e^{i2\pi gu} du \right]^* \\
 &= S_{xx}(f, g) \left[\int_{u \in \mathbb{R}} h(u) e^{-i2\pi(-g)u} du \right]^* \\
 &= S_{xx}(f, g) \tilde{h}^*(-g)
 \end{aligned}$$

$$\begin{aligned}
 S_{yy}(f, g) &\triangleq \tilde{\mathbf{F}}\mathbf{R}_{yy}(t, u) \\
 &= \tilde{\mathbf{F}}[\mathbf{R}_{xy}(t, u) \star h(t)] \\
 &= \tilde{\mathbf{F}}[\mathbf{R}_{xy}(t, u)] \tilde{\mathbf{F}}[h(t)] \\
 &= S_{xy}(f, g) \tilde{h}(\omega) \\
 &= S_{xy}(f, g) \tilde{h}(\omega) \\
 &= S_{xx}(f, g) \tilde{h}^*(-g) \tilde{h}(\omega)
 \end{aligned}$$



7.2 LTI Operations on WSS random processes

Definition 7.1.

DEF A random process $x(t)$ is **wide sense stationary (WSS)** if

- (1). $\mu_X(t)$ is CONSTANT with respect to t (STATIONARY IN THE MEAN) and
- (2). $R_{xx}(t + \tau, t)$ is CONSTANT with respect to t (STATIONARY IN CORRELATION)

If a process $x(t)$ is *wide sense stationary*, mean and correlation are often written μ_X and $R_{xx}(\tau)$, respectively. If a pair of processes $x(t)$ and $y(t)$ are WSS, then their cross-correlation is commonly written $R_{xy}(\tau)$.

Definition 7.2. Let $x(t)$ and $y(t)$ be WSS random processes.

DEF

$\check{S}_{xx}(s) \triangleq \mathbf{L}\mathbf{R}_{xx}(\tau) \triangleq \int_{\tau \in \mathbb{R}} R_{xx}(\tau) e^{-s\tau} d\tau$
$\check{S}_{yy}(s) \triangleq \mathbf{L}\mathbf{R}_{yy}(\tau) \triangleq \int_{\tau \in \mathbb{R}} R_{yy}(\tau) e^{-s\tau} d\tau$
$\check{S}_{xy}(s) \triangleq \mathbf{L}\mathbf{R}_{xy}(\tau) \triangleq \int_{\tau \in \mathbb{R}} R_{xy}(\tau) e^{-s\tau} d\tau$
$\check{S}_{yx}(s) \triangleq \mathbf{L}\mathbf{R}_{yx}(\tau) \triangleq \int_{\tau \in \mathbb{R}} R_{yx}(\tau) e^{-s\tau} d\tau$

Definition 7.3. Let $x(t)$ and $y(t)$ be WSS random processes.

DEF

$$\begin{aligned}\tilde{S}_{xx}(\omega) &\triangleq [\tilde{\mathbf{F}}R_{xx}(\tau)](\omega) \triangleq \int_{\tau \in \mathbb{R}} R_{xx}(\tau) e^{-i\omega\tau} d\tau \\ \tilde{S}_{yy}(\omega) &\triangleq [\tilde{\mathbf{F}}R_{yy}(\tau)](\omega) \triangleq \int_{\tau \in \mathbb{R}} R_{yy}(\tau) e^{-i\omega\tau} d\tau \\ \tilde{S}_{xy}(\omega) &\triangleq [\tilde{\mathbf{F}}R_{xy}(\tau)](\omega) \triangleq \int_{\tau \in \mathbb{R}} R_{xy}(\tau) e^{-i\omega\tau} d\tau \\ \tilde{S}_{yx}(\omega) &\triangleq [\tilde{\mathbf{F}}R_{yx}(\tau)](\omega) \triangleq \int_{\tau \in \mathbb{R}} R_{yx}(\tau) e^{-i\omega\tau} d\tau\end{aligned}$$

Definition 7.4. ² Let $x(t)$ be a random variable that is STATIONARY IN THE MEAN such that $E[x(t)]$ is constant with respect to t .

DEF

$x(t)$ is ergodic in the mean if

$$E[\underbrace{x(t)}_{\text{ENSEMBLE AVERAGE}}] = \lim_{\tau \rightarrow \infty} \frac{1}{2\tau} \underbrace{\int_{-\tau}^{+\tau} x(t) dt}_{\text{TIME AVERAGE}}$$

Proposition 7.1.

PRP

$$\{x(t) \text{ is NON-STATIONARY}\} \implies \{x(t) \text{ is NOT ERGODIC IN THE MEAN}\}$$

PROOF: If $x(t)$ is non-stationary, then $E[x(t)]$ is not constant with time. But $\lim_{\tau \rightarrow \infty} \frac{1}{2\tau} \int_{-\tau}^{+\tau} x(t) dt$ must be a constant (if it is convergent). \Rightarrow

Definition 7.5. ³ Let $x(t)$ be a WIDE SENSE STATIONARY random process.

DEF

- (1). The average power $P_{\text{avg}} x(t)$ is $P_{\text{avg}} x(t) \triangleq \lim_{\tau \rightarrow \infty} \frac{1}{2\tau} \int_{t \in \mathbb{R}} |x(t)|^2 dt$
- (2). The energy spectral density $|\tilde{x}(\omega)|^2$ of $x(t)$ is $|\tilde{x}(\omega)|^2 \triangleq |\tilde{\mathbf{F}}x(t)|^2$

Remark 7.1 (spectral power). Why does $\tilde{S}_{xx}(\omega)$ deserve the name *power spectral density*? This is answered by Theorem 7.2 (next). But to elaborate further, note that \tilde{S}_{xx} is the spectral representation of the statistical relationship (the *variance*) between samples of $x(t)$. For example, if there is no relationship, then $\tilde{S}_{xx}(\omega) = 1$. But in the case that $x(t)$ is ergodic in the mean, then \tilde{S}_{xx} takes on an additional meaning—it describes the “spectral power” present in $x(t)$. This is demonstrated by the next theorem.

Theorem 7.2. Let $x(t)$ be a RANDOM PROCESS.

THM

$$\left\{ \begin{array}{l} (A). \quad x(t) \text{ is ERGODIC IN THE MEAN} \quad \text{and} \\ (B). \quad \tilde{x}(\omega) \text{ EXISTS} \end{array} \right\} \implies \left\{ \begin{array}{l} (1). \quad \tilde{S}_{xx}(\omega) = \lim_{\tau \rightarrow \infty} \frac{1}{2\tau} \underbrace{\int_{-\tau}^{+\tau} x(t) dt}_{(\text{ESD})} \quad \text{and} \\ (2). \quad P_{\text{avg}}[x(t)] = \int_{\omega \in \mathbb{R}} \tilde{S}_{xx}(\omega) d\omega \end{array} \right\}$$

² Papoulis (1984) page 246 (Mean-Ergodic processes), Papoulis (2002) page 523 (12-1 ERGODICITY), KAY (1988) PAGE 58 (3.6 ERGODICITY OF THE AUTOCORRELATION FUNCTION), MANOLAKIS ET AL. (2005) PAGE 106 (ERGODIC RANDOM PROCESSES), KOOPMANS (1995) PAGES 53–61, CADZOW (1987) PAGE 378 (11.13 ERGODIC TIME SERIES), HELSTROM (1991) PAGE 336

³ Bendat and Piersol (2010) page 177



PROOF:

$$\begin{aligned}
 \tilde{S}_{xx}(\omega) &\triangleq \int_{\tau \in \mathbb{R}} R_{xx}(\tau) e^{-i\omega\tau} d\tau && \text{by definition of } \tilde{S}_{xx}(\omega) && (\text{Definition 7.3 page 48}) \\
 &= \int_{\tau \in \mathbb{R}} E[x(t + \tau)x^*(t)] e^{-i\omega\tau} d\tau && \text{by definition of } R_{xx}(t) && (\text{Definition 3.2 page 20}) \\
 &= E\left[x^*(t) \int_{\tau \in \mathbb{R}} x(t + \tau)e^{-i\omega\tau} d\tau\right] && \text{by linearity of } E \text{ operator} \\
 &= E\left[x^*(t) \int_{u \in \mathbb{R}} x(u)e^{-i\omega(u-t)} du\right] && \text{where } u \triangleq t + \tau \implies \tau = u - t \\
 &= E\left[x^*(t)e^{i\omega t} \int_{u \in \mathbb{R}} x(u)e^{-i\omega u} du\right] && \\
 &= E[x^*(t)e^{i\omega t}\tilde{x}(\omega)] && \text{by definition of Fourier Transform} && (\text{Definition P.2 page 333}) \\
 &= E[x^*(t)e^{i\omega t}\tilde{x}(\omega)] && \text{by hypothesis (B)} \\
 &= \left[\lim_{\tau \rightarrow \infty} \frac{1}{2\tau} \int_{-\tau}^{+\tau} x^*(t)e^{i\omega t} dt \right] \tilde{x}(\omega) && \text{by ergodic in the mean hypothesis} && (\text{Definition 7.4 page 48}) \\
 &= \lim_{\tau \rightarrow \infty} \frac{1}{2\tau} \left[\int_{t \in \mathbb{R}} x(t)e^{-i\omega t} dt \right]^* \tilde{x}(\omega) \\
 &= \lim_{\tau \rightarrow \infty} \frac{1}{2\tau} \tilde{x}^*(\omega)\tilde{x}(\omega) && \text{by hypothesis (B)} \\
 &= \lim_{\tau \rightarrow \infty} \frac{1}{2\tau} |\tilde{x}(\omega)|^2
 \end{aligned}$$

$$\begin{aligned}
 \int_{\omega \in \mathbb{R}} \tilde{S}_{xx}(\omega) d\omega &= \int_{\omega \in \mathbb{R}} \lim_{\tau \rightarrow \infty} \frac{1}{2\tau} |\tilde{x}(\omega)|^2 d\omega \\
 &= \lim_{\tau \rightarrow \infty} \frac{1}{2\tau} \int_{\omega \in \mathbb{R}} |\tilde{x}(\omega)|^2 d\omega \\
 &= \lim_{\tau \rightarrow \infty} \frac{1}{2\tau} \int_{t \in \mathbb{R}} |x(t)|^2 dt && \text{by Plancheral's formula} && (\text{Theorem P.3 page 335, Theorem H.9 page 218}) \\
 &= P_{avg} && \text{by definition of } P_{avg} && (\text{Definition 7.5 page 48})
 \end{aligned}$$

Thus, $\tilde{S}_{xx}(\omega)$ is the power density of $x(t)$ in the frequency domain.

⇒

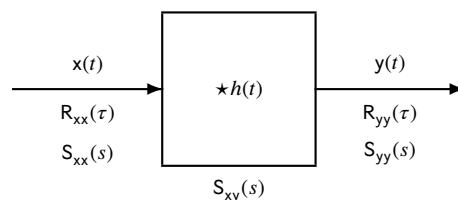


Figure 7.2: Linear system with WSS random process input and output

Theorem 7.3. ⁴ Let $h : \mathbb{R} \rightarrow \mathbb{C}$ be the impulse response of a linear time-invariant system and let $y(t) = h(t) \star x(t) \triangleq \int_{u \in \mathbb{R}} h(u)x(t-u) du$ as illustrated in Figure 7.1 page 45. Then

⁴ Papoulis (1991) pages 323–324

T H M	$\begin{aligned} R_{xy}(\tau) &= R_{xx}(\tau) \star h^*(-\tau) &\triangleq \int_{u \in \mathbb{R}} h^*(-u) R_{xx}(\tau - u) du \\ R_{yy}(\tau) &= R_{xy}(\tau) \star h(\tau) &\triangleq \int_{u \in \mathbb{R}} h(u) R_{xy}(\tau - u) du \\ R_{yy}(\tau) &= R_{xx}(\tau) \star h(\tau) \star h^*(-\tau) &\triangleq \int_v \int_{u \in \mathbb{R}} h(u - v) h^*(-v) R_{xx}(\tau - u - v) du dv \end{aligned}$ $\begin{aligned} S_{xy}(s) &= S_{xx}(s) \hat{h}^*(-s^*) \\ S_{yy}(s) &= S_{xy}(s) \hat{h}(s) \\ S_{yy}(s) &= S_{xx}(s) \hat{h}(s) \hat{h}^*(-s^*) \end{aligned}$ $\begin{aligned} \tilde{S}_{xy}(\omega) &= \tilde{S}_{xx}(\omega) \tilde{h}^*(\omega) \\ \tilde{S}_{yy}(\omega) &= \tilde{S}_{xy}(\omega) \tilde{h}(\omega) \\ \tilde{S}_{yy}(\omega) &= \tilde{S}_{xx}(\omega) \tilde{h}(\omega) ^2 \end{aligned}$
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PROOF:

$$\begin{aligned} R_{xx}(\tau) \star h^*(-\tau) &\triangleq \int_{u \in \mathbb{R}} h^*(-u) R_{xx}(\tau - u) du \\ &= \int_{u \in \mathbb{R}} h^*(-u) E[x(t)x^*(t - \tau + u)] du \\ &= E \left[x(t) \int_{u \in \mathbb{R}} h^*(-u) x^*(t - \tau + u) du \right] \\ &= E \left[x(t) \int_{u \in \mathbb{R}} h^*(u') x^*(t - \tau - u') du' \right] \\ &= E[x(t)y^*(t - \tau)] \\ &\triangleq R_{xy}(\tau) \end{aligned}$$

$$\begin{aligned} R_{xy}(\tau) \star h(\tau) &\triangleq \int_{u \in \mathbb{R}} h(u) R_{xy}(\tau - u) du \\ &= \int_{u \in \mathbb{R}} h(u) E[x(t + \tau - u)y^*(t)] du \\ &= E \left[y^*(t) \int_{u \in \mathbb{R}} h(u) x(t + \tau - u) du \right] \\ &= E[y^*(t)y(t + \tau)] \\ &= E[y(t + \tau)y^*(t)] \\ &\triangleq R_{yy}(\tau) \end{aligned}$$

$$\begin{aligned} R_{yy}(\tau) &= R_{xy}(\tau) \star h(\tau) \\ &= R_{xx}(\tau) \star h^*(-\tau) \star h(\tau) \\ &= R_{xx}(\tau) \star h(\tau) \star h^*(-\tau) \end{aligned}$$

$$\begin{aligned} S_{xy}(s) &\triangleq LR_{xy}(\tau) \\ &\triangleq \int_{\tau \in \mathbb{R}} R_{xy}(\tau) e^{-s\tau} d\tau \\ &= \int_{\tau \in \mathbb{R}} [R_{xx}(\tau) \star h^*(-\tau)] e^{-s\tau} d\tau \\ &= \int_{\tau \in \mathbb{R}} \left[\int_{u \in \mathbb{R}} h^*(-u) R_{xx}(\tau - u) du \right] e^{-s\tau} d\tau \\ &= \int_{u \in \mathbb{R}} h^*(-u) \int_{\tau \in \mathbb{R}} R_{xx}(\tau - u) e^{-s\tau} d\tau du \end{aligned}$$



$$\begin{aligned}
&= \int_{u \in \mathbb{R}} h^*(-u) \int_v R_{xx}(v) e^{-s(v+u)} dv du \\
&= \int_{u \in \mathbb{R}} h^*(-u) e^{-su} du \int_v R_{xx}(v) e^{-sv} dv \\
&= \int_{u \in \mathbb{R}} h^*(u) e^{-s(-u)} du \int_v R_{xx}(v) e^{-sv} dv \\
&= \left(\int_{u \in \mathbb{R}} h(u) e^{-(s^*)u} du \right)^* \int_v R_{xx}(v) e^{-sv} dv \\
&\triangleq \hat{h}^*(-s^*) S_{xx}(s)
\end{aligned}$$

where $v = \tau - u \iff \tau = v + u$

$$\begin{aligned}
S_{yy}(s) &\triangleq \mathbf{L}R_{yy}(\tau) \\
&\triangleq \int_{\tau \in \mathbb{R}} R_{yy}(\tau) e^{-s\tau} d\tau \\
&= \int_{\tau \in \mathbb{R}} [R_{xy}(\tau) \star h(\tau)] e^{-s\tau} d\tau \\
&= \int_{\tau \in \mathbb{R}} \left[\int_{u \in \mathbb{R}} h(u) R_{xy}(\tau - u) du \right] e^{-s\tau} d\tau \\
&= \int_{u \in \mathbb{R}} h(u) \int_{\tau \in \mathbb{R}} R_{xy}(\tau - u) e^{-s\tau} d\tau du \\
&= \int_{u \in \mathbb{R}} h(u) \int_{\tau \in \mathbb{R}} R_{xy}(v) e^{-s(v+u)} d\tau du \\
&= \int_{u \in \mathbb{R}} h(u) e^{-su} du \int_{\tau \in \mathbb{R}} R_{xy}(v) e^{-sv} d\tau \\
&\triangleq \hat{h}(s) S_{xy}(s)
\end{aligned}$$

where $v = \tau - u \iff \tau = v + u$

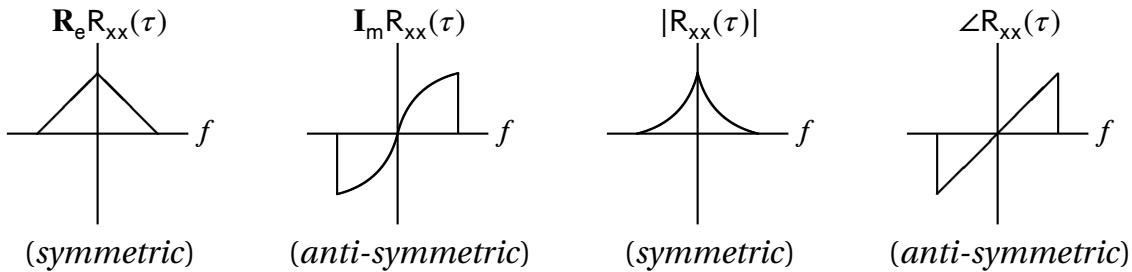
$$\begin{aligned}
S_{yy}(s) &= \hat{h}(s) S_{xy}(s) \\
&= \hat{h}(s) \hat{h}^*(-s^*) S_{xx}(s)
\end{aligned}$$

$$\begin{aligned}
\tilde{S}_{xy}(\omega) &= S_{xy}(s) \Big|_{s=j\omega} \\
&= \hat{h}^*(-s^*) S_{xx}(s) \Big|_{s=j\omega} \\
&= \left(\int_{u \in \mathbb{R}} h(u) e^{-(s^*)u} du \right)^* \int_v R_{xx}(v) e^{-sv} dv \Big|_{s=j\omega} \\
&= \left(\int_{u \in \mathbb{R}} h(u) e^{(-j\omega)^*u} du \right)^* \int_v R_{xx}(v) e^{-j\omega v} dv \\
&= \left(\int_{u \in \mathbb{R}} h(u) e^{-j\omega u} du \right)^* \int_v R_{xx}(v) e^{-j\omega v} dv \\
&\triangleq \tilde{h}^*(\omega) \tilde{S}_{xx}(\omega)
\end{aligned}$$

$$\begin{aligned}
\tilde{S}_{yy}(\omega) &= S_{yy}(s) \Big|_{s=j\omega} \\
&= \hat{h}(s) S_{xy}(s) \Big|_{s=j\omega} \\
&= \int_{u \in \mathbb{R}} h(u) e^{-su} du \int_{\tau \in \mathbb{R}} R_{xy}(v) e^{-sv} d\tau \Big|_{s=j\omega} \\
&= \int_{u \in \mathbb{R}} h(u) e^{-j\omega u} du \int_{\tau \in \mathbb{R}} R_{xy}(v) e^{-j\omega v} d\tau \\
&= \tilde{h}(\omega) \tilde{S}_{xy}(\omega)
\end{aligned}$$

$$\begin{aligned}\tilde{S}_{yy}(\omega) &= \tilde{h}(\omega)\tilde{S}_{xy}(\omega) \\ &= \tilde{h}(\omega)\tilde{h}^*(\omega)\tilde{S}_{xx}(\omega) \\ &= |\tilde{h}(\omega)|^2\tilde{S}_{xx}(\omega)\end{aligned}$$

⇒

Figure 7.3: auto-correlation $R_{xx}(\tau)$

Theorem 7.4. Let $x : \mathbb{R} \rightarrow \mathbb{C}$ be a WSS random process with auto-correlation $R_{xx}(\tau)$. Then $R_{xx}(\tau)$ is conjugate symmetric such that (see Figure 7.3 page 52)

T H M	$R_{xx}(\tau) = R_{xx}^*(-\tau)$ (CONJUGATE SYMMETRIC) $R_e [R_{xx}(\tau)] = R_e [R_{xx}^*(-\tau)]$ (SYMMETRIC) $I_m [R_{xx}(\tau)] = -I_m [R_{xx}^*(-\tau)]$ (ANTI-SYMMETRIC) $ R_{xx}(\tau) = R_{xx}^*(-\tau) $ (SYMMETRIC) $\angle R_{xx}(\tau) = \angle R_{xx}^*(-\tau)$ (ANTI-SYMMETRIC).
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PROOF:

$$\begin{aligned}R_{xx}^*(\tau) &\triangleq (E[x(t-\tau)x^*(t)])^* \\ &= E[x^*(t-\tau)x(t)] \\ &= E[x(t)x^*(t-\tau)] \\ &= E[x(u+\tau)x^*(u)] \\ &\triangleq R_{xx}(\tau) \quad \text{where } u \triangleq t-\tau \iff t=u+\tau \\ R_e [R_{xx}(\tau)] &= R_e [R_{xx}^*(-\tau)] \\ I_m [R_{xx}(\tau)] &= I_m [R_{xx}^*(-\tau)] \\ abs R_{xx}(\tau) &= |R_{xx}^*(-\tau)| \\ \angle R_{xx}(\tau) &= \angle R_{xx}^*(-\tau) \\ &= R_e [R_{xx}(-\tau)] \\ &= -I_m [R_{xx}(-\tau)] \\ &= |R_{xx}(-\tau)| \\ &= -\angle R_{xx}(-\tau)\end{aligned}$$

⇒

7.3 Whitening continuous random sequences

Simple algebraic operations on white noise processes (processes with autocorrelation $R_{xx}(\tau) = \delta(\tau)$) often produce *colored* noise (processes with autocorrelation $R_{xx}(\tau) \neq \delta(\tau)$). Sometimes we would like to process a colored noise process to produce a white noise process. This operation is known as *whitening*. Reasons for why we may want to whiten a noise process include

1. Samples from a white noise process are uncorrelated. If the noise process is Gaussian, then these samples are also independent which often greatly simplifies analysis.



2. Any orthonormal basis can be used to decompose a white noise process. This is not true of a colored noise process. Karhunen–Loève expansion can be used to decompose colored noise.⁵

Definition 7.6. A **rational expression** $p(s)$ is a polynomial divided by a polynomial such that

DEF

$$p(s) = \frac{\sum_{n=0}^N b_n s^n}{\sum_{n=0}^M a_n s^n}$$

The **zeros** of a rational expression are the roots of its numerator polynomial.

The **poles** of a rational expression are the roots of its denominator polynomial.

Definition 7.7. Let $\check{h}(s)$ be the Laplace transform of the impulse response of a filter. If $\check{h}(s)$ can be expressed as a rational expression with poles and zeros at $a_n + ib_n$, then the filter is **minimum phase** if each $a_n < 0$ (all roots lie in the left hand side of the complex s -plane).

Note that if $L(s)$ has a root at $s = -a + ib$, then $L^*(-s^*)$ has a root at

$$-s^* = -(-a + ib)^* = -(-a - ib) = a + ib.$$

That is, if $L(s)$ has a root in the left hand plane, then $L^*(-s^*)$ has a root directly opposite across the imaginary axis in the right hand plane (see Figure 7.4 page 53). A causal stable filter $\hat{h}(s)$ must have all of its poles in the left hand plane. A minimum phase filter is a filter with both its poles and zeros in the left hand plane. One advantage of a minimum phase filter is that its reciprocal (zeros become poles and poles become zeros) is also causal and stable.

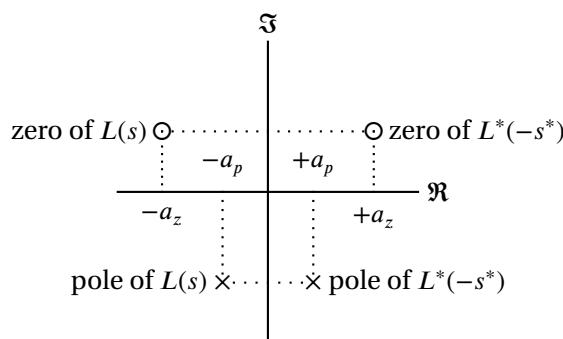


Figure 7.4: Mirrored roots in complex-s plane

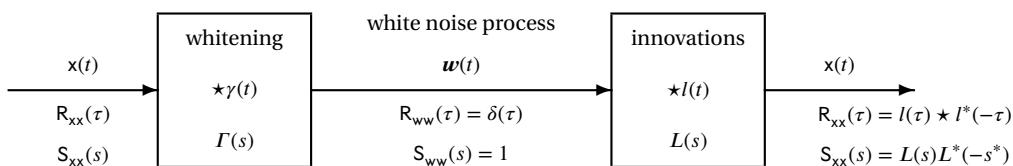


Figure 7.5: Innovations and whitening filters

The next theorem demonstrates a method for “whitening” a random process $x(t)$ with a filter constructed from a decomposition of $R_{xx}(\tau)$. The technique is stated precisely in Theorem 7.5 page 54

⁵ Karhunen–Loève expansion: Section 4.1 page 21

and illustrated in Figure 7.5 page 53. Both imply two filters with impulse responses $l(t)$ and $\gamma(t)$. Filter $l(t)$ is referred to as the **innovations filter** (because it generates or “innovates” $x(t)$ from a white noise process $w(t)$) and $\gamma(t)$ is referred to as the **whitening filter** because it produces a white noise sequence when the input sequence is $x(t)$.⁶

Theorem 7.5. Let $x(t)$ be a WSS random process with autocorrelation $R_{xx}(\tau)$ and spectral density $S_{xx}(s)$. If $S_{xx}(s)$ has a **rational expression**, then the following are true:

1. There exists a rational expression $L(s)$ with minimum phase such that

$$S_{xx}(s) = L(s)L^*(-s^*).$$

2. An LTI filter for which the Laplace transform of the impulse response $\gamma(t)$ is

$$\Gamma(s) = \frac{1}{L(s)}$$

is both causal and stable.

3. If $x(t)$ is the input to the filter $\gamma(t)$, the output $y(t)$ is a **white noise sequence** such that

$$S_{yy}(s) = 1 \quad R_{yy}(\tau) = \delta(\tau).$$

PROOF:

$$\begin{aligned} S_{ww}(s) &= \Gamma(s)\Gamma^*(-s^*)S_{xx}(s) \\ &= \frac{1}{L(s)} \frac{1}{L^*(-s^*)} S_{xx}(s) \\ &= \frac{1}{L(s)} \frac{1}{L^*(-s^*)} L(s)L^*(-s^*) \\ &= 1 \end{aligned}$$



⁶ Papoulis (1991) pages 401–402

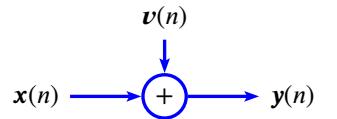


CHAPTER 8

ADDITIVE NOISE ON RANDOM SEQUENCES

8.1 Additive noise and correlation

Theorem 8.1. Let S be the system illustrated to the right, where T is NOT NECESSARILY LINEAR.



T H M	(A). $x(n)$ is WSS and (B). $x(n)$ and $v(n)$ are uncorrelated and (C). $v(n)$ is zero-mean and	$\left\{ \begin{array}{l} (1). R_{yy}(m) = R_{vv}(m) \\ (2). R_{xy}(m) = R_{xx}(m) \\ (3). R_{yy}(m) = R_{xx}(m) + R_{vv}(m) \\ (4). R_{xx}(m) = R_{yy}(m) + R_{vv}(m) - 2R_e R_{yy}(m) \end{array} \right.$
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PROOF:

$R_{yy}(m) \triangleq E[y(m)y^*(0)]$ $\triangleq E[(x(m) + v(m))v^*(0)]$ $= E[x(m)v^*(0)] + E[v(m)v^*(0)]$ $= Ex(m)Ev^*(0) + E[v(m)v^*(0)]$ $= Ex(m)Ev^*(0) + E[v(m)v^*(0)]$ $= R_{vv}(m)$	by (A) and definition of R_{yy} by definition of y by linearity of E by <i>uncorrelated</i> hypothesis by <i>zero-mean</i> hypothesis by definition of R_{vv}	(Definition 2.4 page 12) (Theorem 1.1 page 4) (B) (C) (Definition 2.4 page 12) (Definition 2.4 page 12)
$R_{xy}(m) \triangleq E[x(m)y^*(0)]$ $\triangleq E(x(m)[x(0) + v(0)]^*)$ $= E[x(m)x^*(0)] + E[x(m)v^*(0)]$ $= E[x(m)x^*(0)] + E[x(m)]E[v^*(0)]$ $= E[x(m)x^*(0)] + E[x(m)]E[v^*(0)]$ $= R_{xx}(m)$	by (A) and definition of R_{xy} by definition of y by linearity of E by <i>uncorrelated</i> hypothesis by <i>zero-mean</i> hypothesis by definition of R_{xx}	(Definition 2.4 page 12) (Theorem 1.1 page 4) (B) (C) (Definition 2.4 page 12)
$R_{yy}(m) \triangleq E[y(m)y^*(0)]$ $\triangleq E[(x(m) + v(m))(x(0) + v(0))^*]$ $= E[x(m)x^*(0)] + E[x(m)v^*(0)] + E[v(m)x^*(0)] + E[v(m)v^*(0)]$ $= E[x(m)x^*(0)] + Ex(m)Ev^*(0) + Ev(m)Ex^*(0) + E[v(m)v^*(0)]$ $= E[x(m)x^*(0)] + Ex(m)Ev^*(0) + Ev(m)Ex^*(0) + E[v(m)v^*(0)]$	by (A) and definition of R_{yy} by definition of y by <i>uncorrelated</i> hypothesis (B) by <i>zero-mean</i> hypothesis (C)	

$$\begin{aligned}
 &= R_{xx}(m) + R_{vv}(m) && \text{by definition of } R_{xx} \\
 R_{xx}(m) &\triangleq E[x(m)x^*(0)] \\
 &\triangleq E([y(m) - v(m)][y(0) - v(0)]^*) \\
 &= E[y(m)y^*(0)] - E[y(m)v^*(0)] - E[v(m)y^*(0)] + E[v(m)v^*(0)] \\
 &\triangleq R_{yy}(m) - R_{yy}(m) - R_{vy}(m) + R_{vv}(m) \\
 &= R_{yy}(m) + R_{vv}(m) - 2R_e R_{vy}(m)
 \end{aligned}$$

⇒

Remark 8.1. Because in Theorem 8.1 $y = x + v$ and $R_{yy} = R_{xx} + R_{vv}$, one might assume that R is a kind of *linear operator* (Definition O.3 page 304) and further assume that because $x = y - v$ and $R_{(-v)(-v)} = R_{vv}$, that $R_{xx} = R_{yy} + R_{vv}$. As Theorem 8.1 demonstrates, this is simply **not the case**. The problem here is that y and v are very much *correlated*—in fact y is obviously a *function* of v .

Corollary 8.1. Let S be the system illustrated in Theorem 8.1 (page 55).

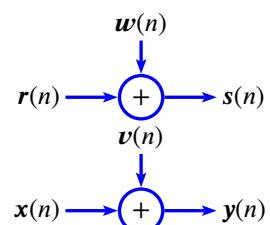
COR

$$\left. \begin{array}{l} \text{hypotheses of} \\ \text{Theorem 8.1 (page 55)} \end{array} \right\} \Rightarrow \left\{ \begin{array}{ll} (1). \quad \check{S}_{yy}(z) &= \check{S}_{xx}(z) + \check{S}_{vv}(z) & \text{and} \\ (2). \quad \check{S}_{yv}(z) &= \check{S}_{vv}(z) & \text{and} \\ (3). \quad \check{S}_{yv}(z) &= \check{S}_{yy}(z) + \check{S}_{vv}(z) + \check{S}_{yv}(z) + \check{S}_{yv}^*(z^*) & \text{and} \\ (4). \quad \tilde{S}_{yy}(\omega) &= \tilde{S}_{xx}(\omega) + \tilde{S}_{vv}(\omega) & \text{and} \\ (5). \quad \tilde{S}_{yv}(\omega) &= \tilde{S}_{vv}(\omega) & \text{and} \\ (6). \quad \tilde{S}_{yv}(\omega) &= \tilde{S}_{yy}(\omega) + \tilde{S}_{vv}(\omega) + \tilde{S}_{yv}(\omega) + \tilde{S}_{yv}^*(-\omega) & \end{array} \right.$$

PROOF:

$$\begin{aligned}
 \check{S}_{yy}(z) &\triangleq ZR_{yy}(m) && \text{by definition of } \check{S}_{yy} && (\text{Definition 2.5 page 15}) \\
 &= ZR_{qq}(m) + ZR_{vv}(m) && \text{by previous result} && (1) \\
 &= \check{S}_{qq}(z) + \check{S}_{vv}(z) && \text{by definition of } \check{S}_{yy} && (\text{Definition 7.3 page 48}) \\
 \tilde{S}_{yy}(\omega) &\triangleq \check{F}R_{yy}(m) && \text{by definition of } \tilde{S}_{yy} && (\text{Definition 7.3 page 48}) \\
 &= \check{F}R_{qq}(m) + \check{F}R_{vv}(m) && \text{by previous result} && (1) \\
 &= \tilde{S}_{qq}(\omega) + \tilde{S}_{vv}(\omega) && \text{by definition of } \tilde{S}_{yy} && (\text{Definition 7.3 page 48})
 \end{aligned}$$

⇒



Theorem 8.2. Let S be the system illustrated to the right:

THM

$$\left\{ \begin{array}{ll} \text{(A). } x(n) \text{ and } r(n) \text{ are wide sense stationary} & \text{and} \\ \text{(B). } E[x(n)w(n)] = Ex(n)Ew(n) \text{ (uncorrelated)} & \text{and} \\ \text{(C). } E[r(n)v(n)] = Er(n)Ev(n) \text{ (uncorrelated)} & \text{and} \\ \text{(D). } E[w(n)v(n)] = Ew(n)Ev(n) \text{ (uncorrelated)} & \text{and} \\ \text{(E). } Ev(n) = Ew(n) = 0 \text{ (zero-mean)} & \end{array} \right\} \Rightarrow \left\{ \begin{array}{ll} R_{sy}(m) &= R_{sx}(m) \\ &= R_{ry}(m) \\ &= R_{rx}(m) \end{array} \right\}$$



PROOF:

$$\begin{aligned}
 R_{sy}(m) &\triangleq E[s(m)y^*(0)] && \text{by definition of } R_{xy} && (\text{Definition 2.4 page 12}) \\
 &\triangleq E([r(m) + w(m)][x(0) + v(0)]^*) && \text{by definition of } S \\
 &= E[r(m)x^*(0)] + E[r(m)v^*(0)] + E[w(m)x^*(0)] + E[w(m)v^*(0)] \\
 &= E[r(m)x^*(0)] + Er(m)Ev^*(0) \\
 &\quad + Ew(m)Ex^*(0) + Ew(m)Ev^*(0) && \text{by uncorrelated hypotheses} && (\text{B), (C), and (D)}) \\
 &= E[r(m)x^*(0)] + Er(m)Ev^*(0) \\
 &\quad + Ew(m)Ex^*(0) + Ew(m)Ev^*(0) && \text{by zero-mean hypothesis} && (\text{E}) \\
 &= R_{rx}(m) && \text{by definition of } R_{rx} && (\text{Definition 2.4 page 12}) \\
 R_{sx}(m) &\triangleq E[s(m)x^*(0)] && \text{by definition of } R_{xy} && (\text{Definition 2.4 page 12}) \\
 &\triangleq E([r(m) + w(m)]x^*(0)) \\
 &= E[r(m)x^*(0)] + Ew(m)Ex^*(0) && \text{by uncorrelated hypothesis} && (\text{B}) \\
 &= E[r(m)x^*(0)] + Ew(m)Ex^*(0) && \text{by zero-mean hypothesis} && (\text{E}) \\
 &= R_{rx}(m) && \text{by definition of } R_{rx} && (\text{Definition 2.4 page 12}) \\
 R_{ry}(m) &\triangleq E[r(m)y^*(0)] && \text{by definition of } R_{xy} && (\text{Definition 2.4 page 12}) \\
 &\triangleq E(r(m)[x(0) + v(0)]^*) \\
 &= E[r(m)x^*(0)] + Er(m)Ev^*(0) && \text{by uncorrelated hypothesis} && (\text{C}) \\
 &= E[r(m)x^*(0)] + Er(m)Ev^*(0) \\
 &= R_{rx}(m) && \text{by definition of } R_{rx} && (\text{Definition 2.4 page 12})
 \end{aligned}$$



Corollary 8.2. Let S be the system illustrated in Theorem 8.2 (page 56).

COR	$\left\{ \begin{array}{l} \text{hypotheses of} \\ \text{Theorem 8.2 (page 56)} \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} (1). \check{S}_{sy}(z) = \check{S}_{sx}(z) = \check{S}_{ry}(z) = \check{S}_{rx}(z) \text{ and} \\ (2). \tilde{S}_{sy}(\omega) = \tilde{S}_{sx}(\omega) = \tilde{S}_{ry}(\omega) = \tilde{S}_{rx}(\omega) \end{array} \right\}$
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PROOF:

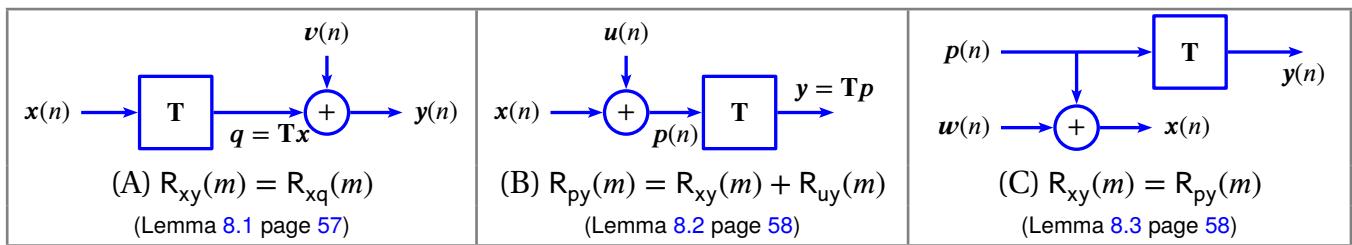
$$\begin{aligned}
 \check{S}_{sy}(\omega) &\triangleq ZR_{sy}(m) && \text{by definition of } \check{S}_{xy} && (\text{Definition 2.5 page 15}) \\
 &= ZR_{rx}(m) && \text{by previous result} && (1) \\
 &= \check{S}_{rx}(z) && \text{by definition of } \check{S}_{xy} && (\text{Definition 2.5 page 15}) \\
 \tilde{S}_{sy}(\omega) &\triangleq \check{F}R_{sy}(m) && \text{by definition of } \check{S}_{xy} && (\text{Definition 7.3 page 48}) \\
 &= \check{F}R_{rx}(m) && \text{by previous result} && (1) \\
 &= \tilde{S}_{rx}(\omega) && \text{by definition of } \check{S}_{xy} && (\text{Definition 7.3 page 48})
 \end{aligned}$$



8.2 Additive noise and operators

Lemma 8.1. Let S be the system illustrated in Figure 8.2 (page 59) (A).

LEM	$\left\{ \begin{array}{l} (A). R_{xx}(n_1, m) = R_{xx}(n_2, m) \text{ (WSS)} \quad \text{and} \\ (B). E[x(n)v(n)] = Ex(n)Ev(n) \text{ (UNCORRELATED)} \quad \text{and} \\ (E). Ev(n) = 0 \text{ (ZERO-MEAN)} \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} (1). R_{xy}(m) = R_{xq}(m) \text{ and} \\ (2). \check{S}_{xy}(z) = \check{S}_{xq}(z) \text{ and} \\ (3). \tilde{S}_{xy}(\omega) = \tilde{S}_{xq}(\omega) \end{array} \right\}$
-----	---

Figure 8.1: Additive noise with *linear/non-linear* operator **T**

PROOF:

$$\begin{aligned}
 R_{xy}(m) &\triangleq E[x(m)y^*(0)] && \text{by definition of } R_{xy} && (\text{Definition 2.4 page 12}) \\
 &\triangleq E[x(m)(q(0) + v(0))^*] && \text{by definition of } S && (\text{Figure 8.2 page 59}) (A) \\
 &= E[x(m)q^*(0) + p(m)v^*(0)] \\
 &= E[x(m)q^*(0)] + E[x(m)v^*(0)] \\
 &= E[x(m)q^*(0)] + [E x(m)][E v^*(0)] \\
 &= E[x(m)q^*(0)] + [E p(m)][E v^*(0)]^{\cancel{0}} && \text{by uncorrelated hypothesis} && (B) \\
 &= E[x(m)q^*(0)] && \text{by zero-mean hypothesis} && (E) \\
 &= R_{xq}(m) && \text{by definition of } R_{xq} && (\text{Definition 2.4 page 12}) \\
 \check{S}_{xy}(z) &\triangleq ZR_{xy}(m) && \text{by definition of } \check{S}_{xy} && (\text{Definition 2.5 page 15}) \\
 &= ZR_{xq}(m) && \text{by previous result} && (1) \\
 &= \check{S}_{xq}(z) && \text{by definition of } \check{S}_{xq} && (\text{Definition 2.5 page 15}) \\
 \tilde{S}_{xy}(\omega) &\triangleq \check{F}R_{xy}(m) && \text{by definition of } \tilde{S}_{xy} && (\text{Definition 7.3 page 48}) \\
 &= \check{F}R_{xq}(m) && \text{by previous result} && (1) \\
 &= \tilde{S}_{xq}(\omega) && \text{by definition of } \tilde{S}_{xq} && (\text{Definition 7.3 page 48})
 \end{aligned}$$

⇒

Lemma 8.2. Let **S** be the system illustrated in Figure 8.2 (page 59) (B).

L E M	$\left\{ \begin{array}{ll} (A). & x(n) \text{ is (WSS)} \\ (B). & u(n) \text{ is (ZERO-MEAN)} \\ (C). & x(n) \text{ and } u(n) \text{ are (UNCORRELATED)} \end{array} \right. \text{ and } \right\} \implies \left\{ \begin{array}{ll} (1). & R_{pq}(m) = R_{xy}(m) + R_{uy}(m) \text{ and} \\ (2). & \check{S}_{pq}(z) = \check{S}_{xy}(z) + \check{S}_{uy}(z) \text{ and} \\ (3). & \tilde{S}_{pq}(\omega) = \tilde{S}_{xy}(\omega) + \tilde{S}_{uy}(\omega) \end{array} \right\}$
----------------------	--

PROOF:

$$\begin{aligned}
 R_{xy}(m) &\triangleq E[x(m)y^*(0)] && \text{by definition of } R_{xy} && (\text{Definition 2.4 page 12}) \\
 &\triangleq E([p(m) - u(m)]y^*(0)) && \text{by definition of } S \\
 &= E[p(m)y^*(0) - u(m)y^*(0)] \\
 &= E[p(m)y^*(0)] - E[u(m)y^*(0)] && \text{because } E \text{ is a linear operator} && (\text{Theorem 1.1 page 4}) \\
 &\triangleq R_{py}(m) - R_{uy}(m) && \text{by definition of } R_{xy} && (\text{Definition 2.4 page 12})
 \end{aligned}$$

⇒

Lemma 8.3. Let **S** be the system illustrated in Figure 8.2 (page 59) (C).

L E M	$\left\{ \begin{array}{ll} (A). & x(n) \text{ is (WSS)} \\ (B). & u(n) \text{ is (ZERO-MEAN)} \\ (C). & x(n) \text{ and } u(n) \text{ are (UNCORRELATED)} \end{array} \right. \text{ and } \right\} \implies \left\{ \begin{array}{ll} (1). & R_{xy}(m) = R_{py}(m) \text{ and} \\ (2). & \check{S}_{xy}(z) = \check{S}_{py}(z) \text{ and} \\ (3). & \tilde{S}_{xy}(\omega) = \tilde{S}_{py}(\omega) \end{array} \right\}$
----------------------	---



PROOF:

$$\begin{aligned}
 R_{xy}(m) &\triangleq E[x(m)y^*(0)] && \text{by definition of } R_{py} && (\text{Definition 2.4 page 12}) \\
 &\triangleq E[p(m) + u(m)]y^*(0) && \text{by definition of } S \\
 &= E[p(m)y^*(0) + u(m)y^*(0)] && \text{by field properties of } (\mathbb{R}, +, \cdot, 0, 1) \\
 &= E[p(m)y^*(0)] + E[u(m)y^*(0)] && \text{because } E \text{ is a linear operator} && (\text{Theorem 1.1 page 4}) \\
 &= E[p(m)y^*(0)] + E[u(m)]E[y^*(0)] && \text{by uncorrelated hypothesis} && (C) \\
 &= E[p(m)y^*(0)] + E[u(m)]\cancel{E[y^*(0)]}^0 && \text{by zero-mean hypothesis} && (B) \\
 &\triangleq R_{py}(m) && \text{by definition of } R_{xy} && (\text{Definition 2.4 page 12})
 \end{aligned}$$

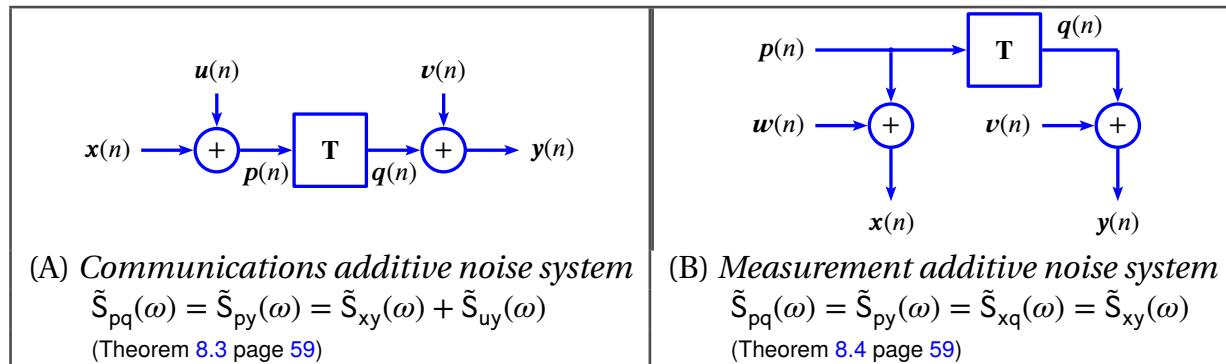


Figure 8.2: linear / non-linear additive noise systems

Theorem 8.3 (communications additive noise cross-correlation).

Let S be the system illustrated in Figure 8.2 page 59 (A).

T H M	(A). $x(n)$ is WSS (B). $u(n)$ is ZERO-MEAN (C). $v(n)$ is ZERO-MEAN (D). $x(n), u(n), v(n)$ are UNCORRELATED	and and and UNCORRELATED	\Rightarrow	(1). $R_{pq}(m) = R_{py}(m) = R_{xy}(m) + R_{uy}(m)$ and (2). $\tilde{S}_{pq}(z) = \tilde{S}_{py}(z) = \tilde{S}_{xy}(z) + \tilde{S}_{uy}(z)$ and (3). $\tilde{S}_{pq}(\omega) = \tilde{S}_{py}(\omega) = \tilde{S}_{xy}(\omega) + \tilde{S}_{uy}(\omega)$
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PROOF:

$$\begin{aligned}
 R_{pq}(m) &= R_{py}(m) && \text{by Lemma 8.1 page 57} \\
 R_{pq}(m) &= R_{xq}(m) + R_{uq}(m) && \text{by Lemma 8.2 page 58} \\
 R_{py}(m) &\triangleq E[p(m)y^*(0)] && \text{by definition } R_{py} && (\text{Definition 2.4 page 12}) \\
 &\triangleq E[(x(m) + u(m))y^*(0)] && \text{by definition } S && (\text{Figure 8.2 page 59}) (A) \\
 &= E[x(m)y^*(0) + u(m)y^*(0)] && \\
 &= E[x(m)y^*(0)] + E[u(m)y^*(0)] && \text{by linearity of } E && (\text{Theorem 1.1 page 4}) \\
 &= R_{xy}(m) + R_{uy}(m) && \text{by definitions } R_{xy} \text{ and } R_{uy} && (\text{Definition 2.4 page 12})
 \end{aligned}$$



Theorem 8.4 (measurement additive noise cross-correlation).

Let S be the system illustrated in Figure 8.2 page 59 (B).

T H M	(A). $x(n)$ is WSS (B). $u(n)$ is ZERO-MEAN (C). $v(n)$ is ZERO-MEAN (D). $x(n), u(n), v(n)$ are UNCORRELATED	and and and UNCORRELATED	\Rightarrow	(1). $R_{pq}(m) = R_{py}(m) = R_{xq}(m) = R_{xy}(m)$ and (2). $\tilde{S}_{pq}(z) = \tilde{S}_{py}(z) = \tilde{S}_{xq}(z) = \tilde{S}_{xy}(z)$ and (3). $\tilde{S}_{pq}(\omega) = \tilde{S}_{py}(\omega) = \tilde{S}_{xq}(\omega) = \tilde{S}_{xy}(\omega)$
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PROOF:

$$\begin{aligned}
 R_{pq}(m) &= R_{py}(m) && \text{by Lemma 8.1 page 57} \\
 R_{pq}(m) &= R_{xq}(m) && \text{by Lemma 8.3 page 58} \\
 R_{xy}(m) &\triangleq E[x(m)y^*(0)] && \text{by definition } R_{xy} \quad (\text{Definition 2.4 page 12}) \\
 &\triangleq E([p(m) + u(m)]y^*(0)) && \text{by definition } S \\
 &= E[p(m)y^*(0) + u(m)y^*(0)] && (\text{Figure 8.2 page 59}) \text{ (B)} \\
 &= E[p(m)y^*(0)] + E[u(m)y^*(0)] && \text{by linearity of } E \quad (\text{Theorem 1.1 page 4}) \\
 &= E[p(m)y^*(0)] + E\underline{[u(m)y^*(0)]}^0 && \text{by uncorrelated hypothesis} \quad (\text{D}) \\
 &= R_{py}(m) && \text{by definition of } R_{py} \quad (\text{Definition 2.4 page 12})
 \end{aligned}$$

⇒

8.3 Additive noise and LTI operators

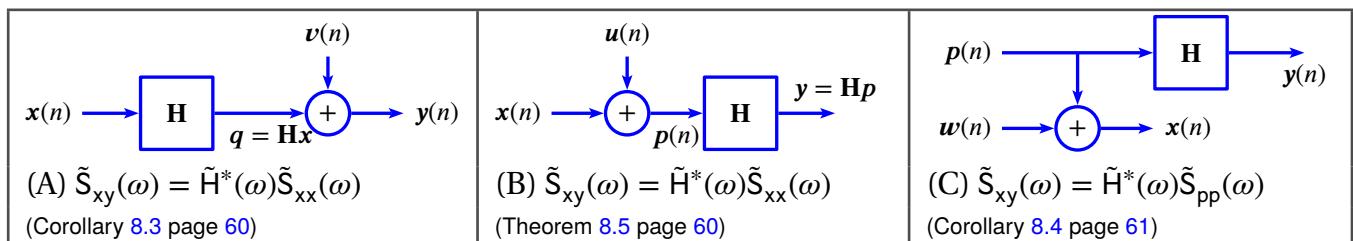


Figure 8.3: Additive noise with LTI operator \mathbf{H}

Corollary 8.3. Let S be the system illustrated in Figure 8.3 (page 60) (A).

COR	$\left\{ \begin{array}{ll} (A). & x(n) \text{ is (WSS)} \\ (B). & u(n) \text{ is (ZERO-MEAN)} \\ (C). & x(n) \text{ and } u(n) \text{ are (UNCORRELATED)} \\ (D). & \mathbf{H} \text{ is (LTI)} \end{array} \right. \text{ and } \right\} \Rightarrow \left\{ \begin{array}{l} \tilde{S}_{xy}(\omega) = \tilde{H}^*(\omega)\tilde{S}_{xx}(\omega) \end{array} \right\}$
-----	---

PROOF:

$$\begin{aligned}
 \tilde{S}_{xy}(\omega) &= \tilde{S}_{xq}(\omega) && \text{by Lemma 8.1 page 57} \\
 &= \tilde{H}^*(\omega)\tilde{S}_{xx}(\omega) && \text{by Corollary 6.3 page 41}
 \end{aligned}$$

⇒

Theorem 8.5. Let S be the system illustrated in Figure 8.3 (page 60) (B).

THM	$\left\{ \begin{array}{ll} (A). & x(n) \text{ is (WSS)} \\ (B). & u(n) \text{ is (ZERO-MEAN)} \\ (C). & x(n) \text{ and } u(n) \text{ are (UNCORRELATED)} \\ (D). & \mathbf{H} \text{ is (LTI)} \end{array} \right. \text{ and } \right\} \Rightarrow \left\{ \begin{array}{ll} (1). & R_{yx}(m) = h(m) \star R_{xx}(m) \text{ and} \\ (2). & \tilde{S}_{yx}(z) = \check{h}(z)\tilde{S}_{xx}(z) \text{ and} \\ (3). & \tilde{S}_{xy}(\omega) = \tilde{H}^*(\omega)\tilde{S}_{xx}(\omega) \end{array} \right\}$
-----	--

PROOF:

- definition: Let $(h(n))$ be the *impulse response* of operator \mathbf{H} such that
$$H\delta(n) \triangleq \sum_{m \in \mathbb{Z}} h(m)\delta(n-m)$$



2. lemma: $\mathbf{Hx}(n) = \sum_{m \in \mathbb{Z}} h(n)x(m-n) = h(n) \star R_{xx}(n)$.

Proof: by the *linear time-invariant* hypotheses (D) and definition of *convolution* operator \star (Definition P.3 page 336)

3. Proof that $R_{yx}(m) = h(m) \star R_{xx}(m)$:

$$\begin{aligned}
 R_{yx}(m) &\triangleq E[y(m)x^*(0)] && \text{by definition of } R_{py} && (\text{Definition 2.4 page 12}) \\
 &= E([\mathbf{Hx}(m) + \mathbf{Hu}(m)]x^*(0)) && \text{by linear hypothesis} && (\text{D}) \\
 &= E([\mathbf{Hx}^*(m)]x^*(0) + [\mathbf{Hu}(0)]x^*(0)) && \text{by linearity of } E && (\text{Theorem ?? page ??}) \\
 &= \mathbf{HE}[x(m)x^*(0)] + \mathbf{HE}[u(0)x^*(0)] && \text{by LTI hypotheses} && (\text{D}) \\
 &= \mathbf{HE}[x(m)x^*(0)] + \mathbf{HE}u(m)\mathbf{Ex}^*(0) && \text{by uncorrelated hypothesis} && (\text{C}) \\
 &= \mathbf{HE}[x(m)x^*(0)] + \mathbf{HE}\cancel{u(m)}\mathbf{Ex}^*(0) && \text{by zero-mean hypothesis} && (\text{B}) \\
 &= \mathbf{HR}_{xx}(m) && \text{by definition of } R_{xx} && (\text{Definition 2.4 page 12}) \\
 &= h(m) \star R_{xx}(m) && \text{by (2) lemma} &&
 \end{aligned}$$



When \mathbf{H} is *LTI*, what effect does the additive uncorrelated noise sources have on the cross-statistical properties of x and y ? Corollary 8.5 (next) demonstrates that, amazingly, under very general conditions, the noise sources have **no effect**.

Corollary 8.4. Let \mathbf{S} be the system illustrated in Figure 8.3 (page 60) (C).

COR	$\left\{ \begin{array}{ll} (A). & x(n) \text{ is} \\ (B). & u(n) \text{ is} \\ (C). & x(n) \text{ and } w(n) \text{ are} \\ (D). & \mathbf{H} \text{ is} \end{array} \right. \begin{array}{l} (\text{WSS}) \\ (\text{ZERO-MEAN}) \\ (\text{UNCORRELATED}) \\ (\text{LTI}) \end{array} \text{ and } \right\} \Rightarrow \left\{ \tilde{S}_{xy}(\omega) = \tilde{H}^*(\omega)\tilde{S}_{pp}(\omega) \right\}$
-----	--

PROOF:

$$\begin{aligned}
 \tilde{S}_{xy}(\omega) &= \tilde{S}_{py}(\omega) && \text{by Lemma 8.3 page 58} \\
 &= \tilde{H}^*(\omega)\tilde{S}_{pp}(\omega) && \text{by Corollary 6.3 page 41}
 \end{aligned}$$

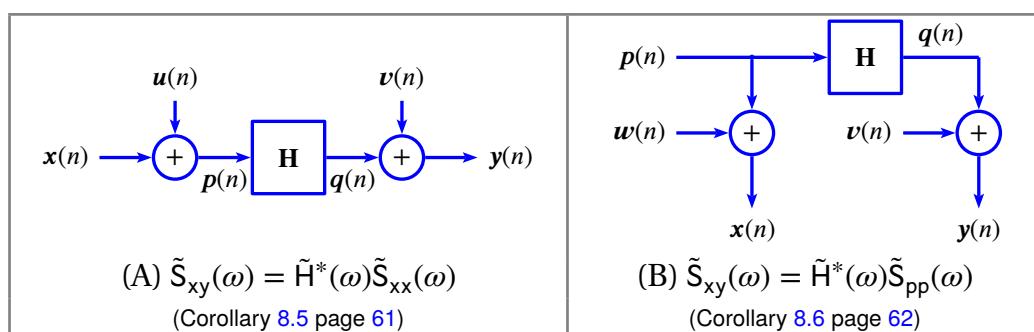


Figure 8.4:

Corollary 8.5. Let \mathbf{S} be the system illustrated in Figure 8.4 page 61 (A).

COR	$\left\{ \begin{array}{ll} (A). & x(n) \text{ is} \\ (B). & u(n) \text{ is} \\ (C). & v(n) \text{ is} \\ (D). & x(n), u(n), v(n) \text{ are} \\ (E). & \mathbf{H} \text{ is} \end{array} \right. \begin{array}{l} (\text{WSS}) \\ (\text{ZERO-MEAN}) \\ (\text{ZERO-MEAN}) \\ (\text{UNCORRELATED}) \\ (\text{LTI}) \end{array} \text{ and } \right\} \Rightarrow \left\{ \tilde{S}_{xy}(\omega) = \tilde{H}^*(\omega)\tilde{S}_{xx}(\omega) \right\}$
-----	--

PROOF:

$$\begin{aligned}\tilde{S}_{yx}(\omega) &= \tilde{S}_{qx}(\omega) && \text{by Lemma 8.1 page 57} \\ &= \tilde{H}(\omega)\tilde{S}_{xx}(\omega) && \text{by Corollary 6.3 page 41}\end{aligned}$$

⇒

Corollary 8.6. Let S be the system illustrated in Figure 8.4 page 61 (B).

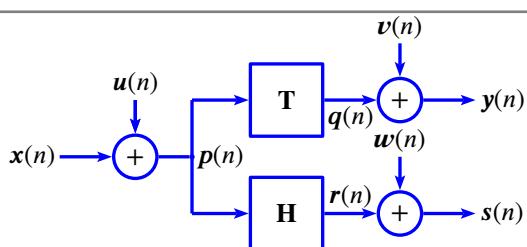
COR	$\left\{ \begin{array}{lll} (A). & x(n) \text{ is} & \text{WSS} \\ (B). & w(n) \text{ is} & \text{ZERO-MEAN} \\ (C). & v(n) \text{ is} & \text{ZERO-MEAN} \\ (D). & x(n), w(n), v(n) \text{ are} & \text{UNCORRELATED} \\ (E). & H \text{ is} & \text{LTI} \end{array} \right. \text{ and } \left\{ \begin{array}{l} \tilde{S}_{xy}(\omega) = \tilde{H}^*(\omega)\tilde{S}_{pp}(\omega) \end{array} \right. \right\} \Rightarrow \left\{ \begin{array}{l} \tilde{S}_{xy}(\omega) = \tilde{H}^*(\omega)\tilde{S}_{pp}(\omega) \end{array} \right\}$
-----	--

PROOF:

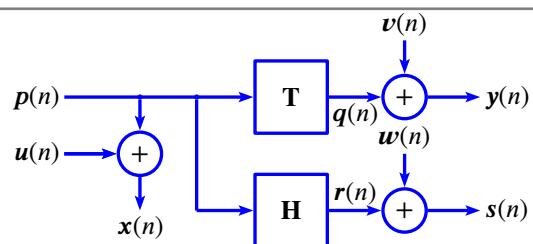
$$\begin{aligned}\tilde{S}_{yx}(\omega) &= \tilde{S}_{qx}(\omega) && \text{by Lemma 8.1 page 57} \\ &= \tilde{S}_{qp}(\omega) && \text{by Lemma 8.1 page 57} \\ &= \tilde{H}(\omega)\tilde{S}_{pp}(\omega) && \text{by Corollary 6.3 page 41}\end{aligned}$$

⇒

8.4 Additive noise and dual operators



(A) dual communications additive noise system
(Corollary 8.7 page 62)



(B) dual measurement additive noise system
(Corollary 8.8 page 63)

Figure 8.5: Dual Additive Noise Systems

Corollary 8.7. Let S be the system illustrated in Figure 8.5 (page 62) (A).

COR	$\left\{ \begin{array}{lll} (A). & H \text{ is} & \text{LTI} \\ (B). & x(n) \text{ is} & \text{WSS} \\ (C). & u \text{ and } v \text{ are} & \text{ZERO-MEAN} \\ (D). & x, u, v \text{ are} & \text{UNCORRELATED} \end{array} \right. \text{ and } \left\{ \begin{array}{l} \check{S}_{sy}(z) = \check{H}(z)[\check{S}_{xy}(z) + \check{S}_{uy}(z)] \\ (2). \quad \tilde{S}_{sy}(\omega) = \tilde{H}(\omega)[\tilde{S}_{xy}(\omega) + \tilde{S}_{uy}(\omega)] \end{array} \right. \text{ and } \right\}$
-----	--

PROOF:

$$\begin{aligned}\check{S}_{sy}(z) &= \check{S}_{rq}(z) && \text{by Corollary 8.2 page 57} && \text{and (B), (C) and (D)} \\ &= \check{H}(z)\check{S}_{pq}(z) && \text{by Theorem 6.2 page 41} && \text{and (A)} \\ &= \check{H}(z)[\check{S}_{xq}(z) + \check{S}_{uq}(z)] && \text{by Lemma 8.2 page 58} \\ &= \check{H}(z)[\check{S}_{xy}(z) + \check{S}_{uy}(z)] && \text{by Lemma 8.1 page 57} \\ \tilde{S}_{sy}(\omega) &= \check{S}_{sy}(z)|_{z=e^{i\omega}} && && \\ &= \check{H}(z)[\check{S}_{xy}(z) + \check{S}_{uy}(z)]|_{z=e^{i\omega}} && \text{by previous result} && (1) \\ &= \tilde{H}(\omega)[\tilde{S}_{xy}(\omega) + \tilde{S}_{uy}(\omega)] && &&\end{aligned}$$





Corollary 8.8. Let \mathbf{S} be the system illustrated in Figure 8.5 (page 62) (B).

COR	$\left\{ \begin{array}{ll} (A). & \mathbf{H} \text{ is LTI} \\ (B). & \mathbf{x}(n) \text{ is WSS} \\ (C). & \mathbf{u} \text{ and } \mathbf{v} \text{ are ZERO-MEAN} \\ (D). & \mathbf{p}, \mathbf{u}, \mathbf{v} \text{ are UNCORRELATED} \end{array} \right. \text{ and } \right\} \Rightarrow \left\{ \begin{array}{ll} (1). & \check{\mathbf{S}}_{sy}(z) = \check{\mathbf{H}}(z)\check{\mathbf{S}}_{xy}(z) \text{ and} \\ (2). & \tilde{\mathbf{S}}_{sy}(\omega) = \tilde{\mathbf{H}}(\omega)\tilde{\mathbf{S}}_{xy}(\omega) \end{array} \right\}$
-----	---

PROOF:

$$\begin{aligned}
 \check{\mathbf{S}}_{sy}(z) &= \check{\mathbf{S}}_{rq}(z) && \text{by Corollary 8.2 page 57} && \text{and (B), (C) and (D)} \\
 &= \check{\mathbf{H}}(z)\check{\mathbf{S}}_{pq}(z) && \text{by Theorem 6.2 page 41} && \text{and (A)} \\
 &= \check{\mathbf{H}}(z)\check{\mathbf{S}}_{xq}(z) && \text{by Lemma 8.3 page 58} \\
 &= \check{\mathbf{H}}(z)\check{\mathbf{S}}_{xy}(z) && \text{by Lemma 8.1 page 57} \\
 \tilde{\mathbf{S}}_{sy}(\omega) &= \check{\mathbf{S}}_{sy}(z) \Big|_{z=e^{j\omega}} && \text{by definition of } \mathbf{Z} && (\text{Definition R.4 page 354}) \\
 &= \check{\mathbf{H}}(z)\check{\mathbf{S}}_{xy}(z) \Big|_{z=e^{j\omega}} && \text{by previous result} && (1) \\
 &= \tilde{\mathbf{H}}(\omega)\tilde{\mathbf{S}}_{xy}(\omega)
 \end{aligned}$$



Part III

Statistical Estimation

CHAPTER 9

ESTIMATION OVERVIEW

9.1 Model-based estimation

Starting in the 1980s and continuing into 2019, James V. Candy has proposed the **model-based approach**¹ to estimation. This approach partitions the task of estimation into three parts:

1. The **model**:² The presumed system architecture, “the form of which is usually suggested by prior knowledge, physical understanding or guesswork.”³ A very common example is the *additive noise model*.
2. The **algorithm**: The operation used to calculate the estimate. An *algorithm* may also be called a **processor**, **filter**, or **method**.
3. The **criterion function**: A *function* which measures the performance of the algorithm. This function may also be called a **cost function**.

9.1.1 Estimation models

Estimation modeling includes several sub-models:

1. The signal model (parametric, nonparametric)—more on this below.
2. The noise model—this can be assumed (Guassian is a common choice) or estimated (CHAPTER 16 page 141).
3. The model architecture (Figure 9.1 page 68)—additive noise model is a common choice, with justification from *Wold's Theorem*.

¹  Candy (1985) (ISBN:9780070097254),  Candy (1988) (ISBN:9780070097513),  Candy and Sullivan (1992),  Candy (2005) page 5,  Candy (2019) page 7. “Dr. Candy received the IEEE Distinguished Technical Achievement Award for the *development of model-based signal processing in ocean acoustics*”:  Rossing (Springer) page 1234

²  Box and Jenkins (1976), pages 173–207 (Chapter 6 “Model Identification”)

³  Scargle (1979), page 5

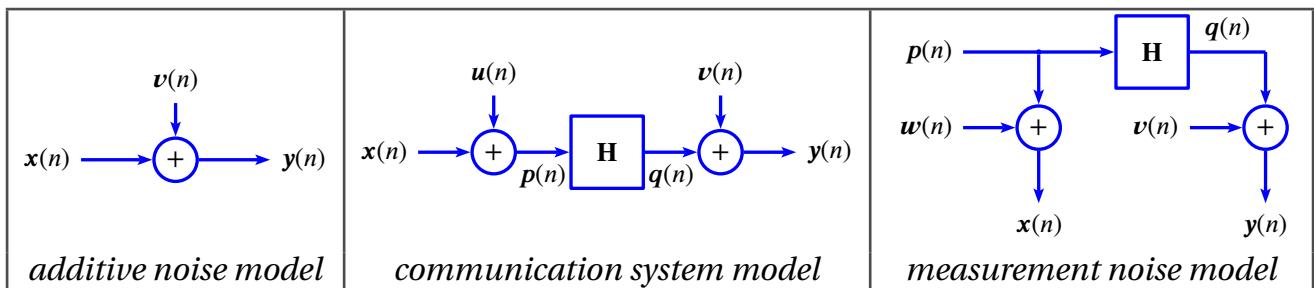


Figure 9.1: Some estimation models

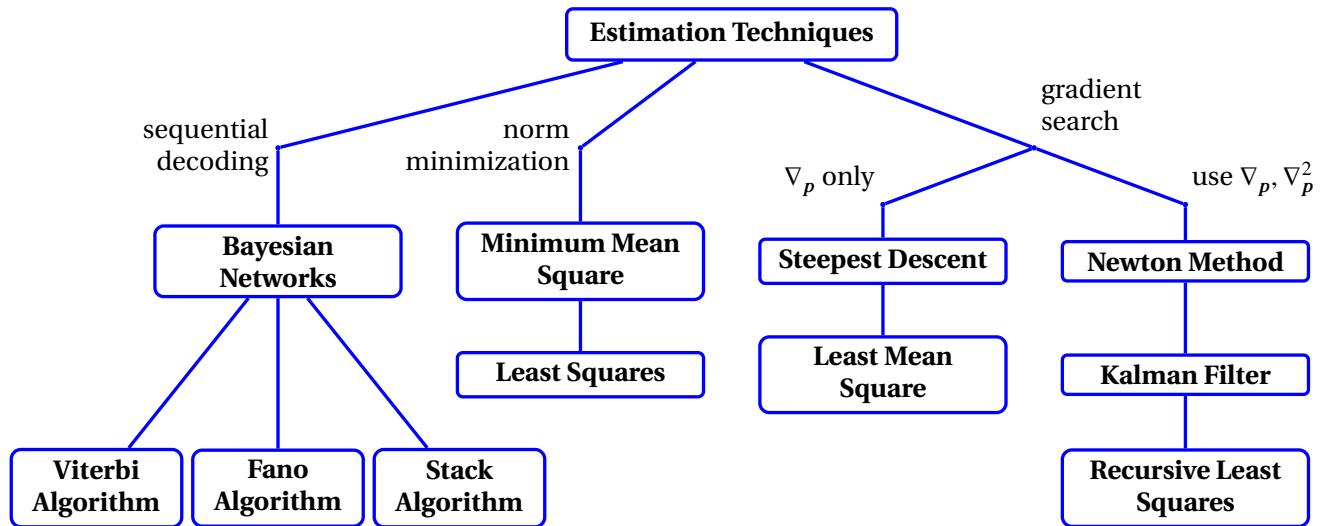


Figure 9.2: Estimation Algorithms

As for the the signal model, let $x(t; \theta)$ be a signal with parameter θ . There are three basic types of signal models, leading to three fundamental types of estimation:

1. detection:

- The waveform $x(t; \theta_n)$ is known except for the value of parameter θ_n .
- The parameter θ_n is one of a finite set of values.
- Estimate θ_n and thereby also estimate $x(t; \theta)$.

2. parametric estimation:

- The waveform $x(t; \theta)$ is known except for the value of parameter θ .
- The parameter θ is one of an infinite set of values.
- Estimate θ and thereby also estimate $x(t; \theta)$.

3. nonparametric estimation:

- The waveform $x(t)$ is unknown and assumed without any parameter θ .
- Estimate $x(t)$.

9.1.2 Estimation algorithms

Estimation algorithms include the following (Figure 9.2 page 68):⁴

⁴ [Nelles \(2001\) page 26](#) (“Fig 2.2 Overview of linear and nonlinear optimization techniques”), [Nelles \(2001\) page 33](#) (“Fig 2.5 The Bayes method is the most general approach but...”), [Nelles \(2001\) page 63](#) (“Table 3.3 Relationship between linear recursive and nonlinear optimization techniques”), [Nelles \(2001\) page 66](#), [Clarkson](#)

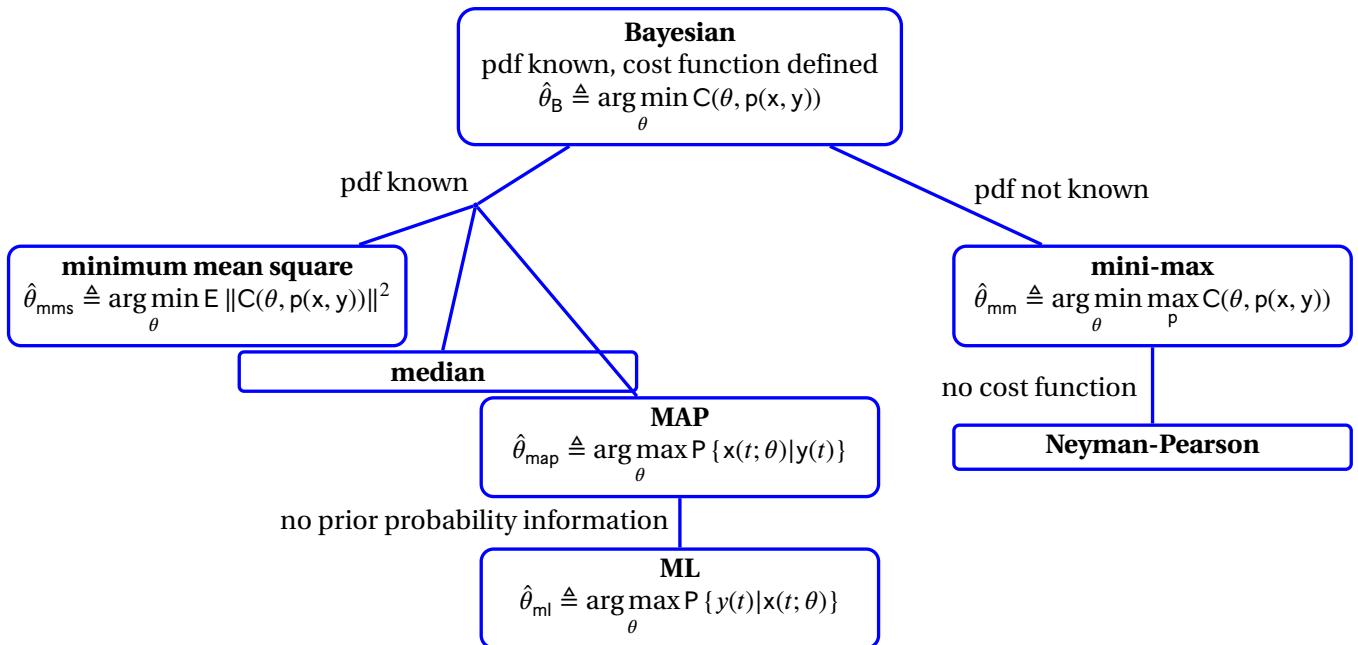


Figure 9.3: Estimation criterion

1. Bayesian Networks (CHAPTER 12 page 101)
2. Gradient Search
3. Bayesian signal processing
4. Neural Networks
5. Direct search

Bayesian signal processing involves estimating the joint-pdf of a process (CHAPTER 16 page 141), and then integrating over a portion of the this (possibly high dimensional) pdf to find an MAP estimate. The integration itself may be estimated using *Monte Carlo Integration*.⁵

9.1.3 Estimation criterion function

Optimization requires a criterion against which the quality of an estimate is measured.⁶ The most demanding and general criterion is the *Bayesian* criterion. The Bayesian criterion requires knowledge of the probability distribution functions and the definition of a *cost function*. Other criterion are special cases of the Bayesian criterion such that the cost function is defined in a special way, no cost function is defined, and/or the distribution is not known (Figure 9.2 page 68).

Definition 9.1. Let

- (A). $x(t; \theta)$ be a random process with unknown parameter θ
- (B). $y(t)$ an observed random process which is statistically dependent on $x(t; \theta)$
- (C). $C(\theta, p(x, y))$ be a cost function.

Then the following estimates are defined as follows:

⁵ (1993) page 276 ('Figure 6.1.1 Options for the adaptive algorithm design.'), ⁶ Vaseghi (2000) pages 4–5 ('1.2 Signal Processing Methods')

⁵ Candy (2009) pages 4–7 ('1.3 SIMULATION-BASED APPROACH TO BAYESIAN PROCESSING'), ⁶ Liu (2013) page 1 ('1.1 The Need of Monte Carlo Techniques')

⁶ Srinath et al. (1996) (013125295X).

DEF

(1). Bayesian estimate	$\hat{\theta}_B \triangleq \arg \min_{\theta} C(\theta, p(x, y))$
(2). Mean square estimate (“MS estimate”)	$\hat{\theta}_{mms} \triangleq \arg \min_{\theta} E \ C(\theta, p(x, y))\ ^2$
(3). mini-max estimate (“MM estimate”)	$\hat{\theta}_{mm} \triangleq \arg \min_{\theta} \max_p C(\theta, p(x, y))$
(4). maximum a-posteriori probability estimate (“MAP estimate”)	$\hat{\theta}_{map} \triangleq \arg \max_{\theta} P\{x(t; \theta) y(t)\}$
(5). maximum likelihood estimate (“ML estimate”)	$\hat{\theta}_{ml} \triangleq \arg \max_{\theta} P\{y(t) x(t; \theta)\}$

Theorem 9.1. Let $x(t; \theta)$ be a random process with unknown parameter θ .

THM

$$\{P\{\theta\} = \text{CONSTANT}\} \implies \{\hat{\theta}_{map} = \hat{\theta}_{ml}\}$$

PROOF:

$$\begin{aligned}
 \hat{\theta}_{map} &\triangleq \arg \max_{\theta} P\{x(t; \theta) | y(t)\} && \text{by definition of } \hat{\theta}_{map} && (\text{Definition 9.1 page 69}) \\
 &\triangleq \arg \max_{\theta} \frac{P\{x(t; \theta) \wedge y(t)\}}{P\{r(t)\}} && \text{by definition of } \text{conditional probability} && (\text{Definition A.4 page 152}) \\
 &\triangleq \arg \max_{\theta} \frac{P\{r(t) | x(t; \theta)\} P\{x(t; \theta)\}}{P\{y(t)\}} && \text{by definition of } \text{conditional probability} && (\text{Definition A.4 page 152}) \\
 &= \arg \max_{\theta} P\{y(t) | x(t; \theta)\} P\{x(t; \theta)\} && \text{because } y(t) \text{ is independent of } \theta \\
 &= \arg \max_{\theta} P\{y(t) | x(t; \theta)\} \\
 &\triangleq \hat{\theta}_{ml} && \text{by definition of } \hat{\theta}_{ml} && (\text{Definition 9.1 page 69})
 \end{aligned}$$

⇒

9.2 Estimation applications

Applications of estimation include the following:

1. **prediction**—for speech processing, financial markets, etc.
2. **deconvolution**—estimate a system transfer function $\hat{H}(z)$ and calculate its inverse $\hat{H}^{-1}(z)$.
3. **de-noising**—estimate a signal $x(t)$ that is buried in noise $v(t)$.

9.3 Measures of estimator quality

Definition 9.2. ⁷

D E F	The mean square error $\text{mse}(\hat{\theta})$ of an estimate $\hat{\theta}$ of a parameter θ is defined as	$\text{mse}(\hat{\theta}) \triangleq E[(\hat{\theta} - \theta)^2]$
-------------	---	--

⁷ Silverman (1986) page 35 (“1.3.2 Measures of discrepancy...”), Clarkson (1993) page 50 (“c) Mean-Squared Error”), Bendat and Piersol (2010) (“1.4.3 Error Analysis Criteria”), Bendat and Piersol (1966), page 183 “5.3 Statistical Errors for Parameter Estimates”



Definition 9.3.⁸

D E F The **normalized rms error** $\epsilon(\hat{\theta})$ of an estimate $\hat{\theta}$ of a parameter θ is defined as

$$\epsilon(\hat{\theta}) \triangleq \frac{\sqrt{\text{mse}(\hat{\theta})}}{\theta} \triangleq \frac{\sqrt{\mathbb{E}[(\hat{\theta} - \theta)^2]}}{\theta}$$
Definition 9.4.⁹

D E F The **mean integrated square error** $\text{mse}(\hat{\theta})$ of an estimate $\hat{\theta}$ of a parameter θ is defined as

$$\text{mse}(\hat{\theta}) \triangleq \mathbb{E} \int_{\theta \in \mathbb{R}} [(\hat{\theta} - \theta)^2]$$

The *mean square error* of $\hat{\theta}$ can be expressed as the sum of two components: the variance of $\hat{\theta}$ and the bias of $\hat{\theta}$ squared (next Theorem). For an example of Theorem 9.2 in action, see the proof for the $\text{mse}(\hat{\mu})$ of the *arithmetic mean estimate* as provided in Theorem 15.1 (page 133).

Theorem 9.2.¹⁰ Let $\text{mse}(\hat{\theta})$ be the **MEAN SQUARE ERROR** (Definition 9.2 page 70) and $\epsilon(\hat{\theta})$ the **NORMALIZED RMS ERROR** (Definition 9.3 page 71) of an estimator $\hat{\theta}$.

T H M	$\text{mse}(\hat{\theta}) = \underbrace{\mathbb{E}[(\hat{\theta} - \mathbb{E}\hat{\theta})^2]}_{\text{variance of } \hat{\theta}} + \underbrace{[\mathbb{E}\hat{\theta} - \theta]^2}_{\text{bias of } \hat{\theta} \text{ squared}}$	$\epsilon(\hat{\theta}) = \frac{\sqrt{\mathbb{E}[(\hat{\theta} - \mathbb{E}\hat{\theta})^2] + [\mathbb{E}\hat{\theta} - \theta]^2}}{\theta}$
-------	--	--

☞ PROOF:

$$\begin{aligned}
 \text{mse}(\hat{\theta}) &\triangleq \mathbb{E}[(\hat{\theta} - \theta)^2] && \text{by definition of mse} \quad (\text{Definition 9.2 page 70}) \\
 &= \mathbb{E}\left[\left(\hat{\theta} - \underbrace{\mathbb{E}\hat{\theta} + \mathbb{E}\hat{\theta}}_0 - \theta\right)^2\right] && \text{by additive identity property of } (\mathbb{C}, +, \cdot, 0, 1) \\
 &= \mathbb{E}\left[(\hat{\theta} - \mathbb{E}\hat{\theta})^2 + \underbrace{(\mathbb{E}\hat{\theta} - \theta)^2}_{\text{constant}} - 2(\hat{\theta} - \mathbb{E}\hat{\theta})(\mathbb{E}\hat{\theta} - \theta)\right] && \text{by Binomial Theorem} \\
 &= \mathbb{E}(\hat{\theta} - \mathbb{E}\hat{\theta})^2 + (\mathbb{E}\hat{\theta} - \theta)^2 - 2\mathbb{E}[\hat{\theta}\mathbb{E}\hat{\theta} - \hat{\theta}\theta - \mathbb{E}\hat{\theta}\hat{\theta} + \mathbb{E}\hat{\theta}\theta] && \text{by linearity of E} \quad (\text{Theorem 1.1 page 4}) \\
 &= \mathbb{E}(\hat{\theta} - \mathbb{E}\hat{\theta})^2 + (\mathbb{E}\hat{\theta} - \theta)^2 - 2\underbrace{[\mathbb{E}\hat{\theta}\mathbb{E}\hat{\theta} - \mathbb{E}\hat{\theta}\mathbb{E}\theta - \mathbb{E}\hat{\theta}\mathbb{E}\hat{\theta} + \mathbb{E}\hat{\theta}\mathbb{E}\theta]}_0 && \text{by linearity of E} \quad (\text{Theorem 1.1 page 4}) \\
 &= \mathbb{E}(\hat{\theta} - \mathbb{E}\hat{\theta})^2 + (\mathbb{E}\hat{\theta} - \theta)^2
 \end{aligned}$$

☞

Definition 9.5.¹¹

D E F An estimate $\hat{\theta}$ of a parameter θ is a **minimum variance unbiased estimator (MVUE)** if

- (1). $\mathbb{E}\hat{\theta} = \theta$ (UNBIASED) and
- (2). no other unbiased estimator $\hat{\phi}$ has smaller variance $\text{var}(\hat{\phi})$

⁸ ☰ Bendat and Piersol (2010) §“1.4.3 Error Analysis Criteria”

⁹ ☰ Silverman (1986) page 35 §“1.3.2 Measures of discrepancy...”, ☱ Rosenblatt (1956) page 835 (“integrated mean square error”)

¹⁰ ☰ Choi (1978) page 76, ☰ Kay (1988) page 45 §“3.3 ESTIMATION THEORY”, ☰ STUART AND ORD (1991) PAGE 629 (“MINIMUM MEAN-SQUARE-ERROR ESTIMATION”), ☰ CLARKSON (1993) PAGE 51 §“2.6 ESTIMATION OF MOMENTS”, ☰ BENDAT AND PIERSOL (2010) §“1.4.3 ERROR ANALYSIS CRITERIA”, ☰ BENDAT AND PIERSOL (1966), PAGE 183§“5.3 STATISTICAL ERRORS FOR PARAMETER ESTIMATES”, ☰ BENDAT AND PIERSOL (1980) PAGE 39 §“2.4.1 BIAS VERSUS RANDOM ERRORS”

¹¹ ☰ Choi (1978) page 76, ☰ Shao (2003) page 161 §“The UMVUE”, ☰ Bolstad (2007) page 164 §“Minimum Variance Unbiased Estimator”

CHAPTER 10

LEAST SQUARES ALGORITHMS WHEN MODEL IS UNKNOWN

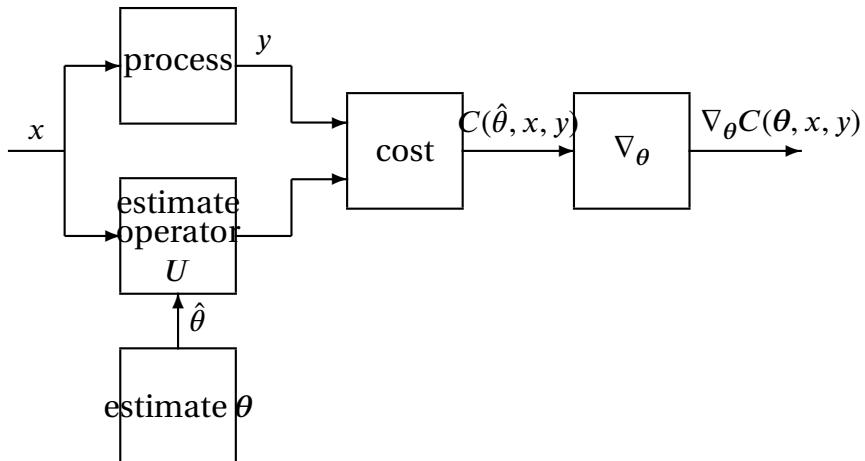


Figure 10.1: Estimation using gradient of cost function

Norm minimization techniques are useful when the system model is unknown.¹ In this section we present two types of norm minimization:²

1. minimum mean square estimation (MMSE):

The MMS estimate is a *stochastic* estimate. To compute the MMS estimate, we do not need to know the actual data values, but we must know certain system statistics which are the input data autocorrelation and input/output crosscorrelation. The cost function is the expected value of the norm squared error.

2. least square estimation (LSE).³

The LS estimate is a *deterministic* estimate. To compute the LS estimate, we must know the actual data values (although these may be “noisy” measurements). The cost function is the norm squared error.

¹ [Clarkson \(1993\) page 1](#) (chapter one Introduction)

²The Least Squares algorithm is nothing new to mathematics. It was first published by Legendre in 1805, but there is a credible claim by Gauss that he had it as far back as 1795. Gauss, by the way, was also the first to discover the FFT. References: [Sorenson \(1970\)](#) page 63, [Plackett \(1972\)](#), [Stigler \(1981\)](#), [Dutka \(1995\)](#)

³ [Scargle \(1979\)](#), page 5

Solutions to both are given in terms of two matrices:

Y : Autocorrelation matrix

W : Crosscorrelation matrix.

10.1 Minimum mean square estimation

Definition 10.1. Let the following vectors, matrices, and functions be defined as follows:

DEF	$x \in \mathbb{C}^m$ DATA VECTOR	$U \in \mathbb{C}_{mn}$ REGRESSION MATRIX
	$y \in \mathbb{C}^n$ PROCESSED DATA VECTOR	$R \in \mathbb{C}_{mm}$ AUTOCORRELATION MATRIX
	$\hat{y} \in \mathbb{C}^n$ PROCESSED DATA ESTIMATE VECTOR	$W \in \mathbb{C}^m$ CROSS-CORRELATION VECTOR
	$e \in \mathbb{C}^n$ ERROR VECTOR	$C : \mathbb{R}^m \rightarrow \mathbb{R}^+$ COST FUNCTION
	$\theta \in \mathbb{R}^m$ PARAMETER VECTOR	

Theorem 10.1 (Minimum mean square estimation). Let

$$\begin{aligned}\hat{y}(\theta) &\triangleq U^H \theta \\ e(\theta) &\triangleq \hat{y} - y \\ C(\theta) &\triangleq E \|e\|^2 \triangleq E[e^H e] \\ \hat{\theta}_{\text{mms}} &\triangleq \arg \min_{\theta} C(\theta) \\ R &\triangleq E[UU^H] \\ W &\triangleq E[Uy]\end{aligned}$$

Then

THM	$\begin{aligned}\hat{\theta}_{\text{mms}} &= (R_e Y)^{-1} (R_e W) \\ C(\theta) &= \theta^H R \theta - (W^H \theta)^* - W^H \theta + E y^H y \\ \nabla_{\theta} C(\theta) &= 2R_e[Y]\theta - 2R_e W \\ C(\hat{\theta}_{\text{mms}}) &= \begin{cases} E y^H y + (R_e W^H)(R_e Y)^{-1} R (R_e Y)^{-1} (R_e W) - 2(R_e W^H)(R_e Y)^{-1} (R_e W) \\ E y^H y - (R_e W^H) R^{-1} (R_e W) \quad \text{if } R \text{ is real-valued} \end{cases}\end{aligned}$
-----	---

PROOF: See APPENDIX E (page 179) for a Matrix Calculus reference.

1. Proof that cost $C(\theta) = \theta^H R \theta - (W^H)^* \theta - W^H \theta + E y^H y$:

$$\begin{aligned}C(\theta) &\triangleq E \|e\|^2 && \text{by definition of cost function } C \\ &\triangleq E[e^H e] && \text{by definition of norm } \|\cdot\| \\ &\triangleq E[(\hat{y} - y)^H (\hat{y} - y)] && \text{by definition of error vector } e \\ &\triangleq E[(U^H \theta - y)^H (U^H \theta - y)] && \text{by definition of estimate } \hat{y} \\ &= E[(\theta^H U - y^H)(U^H \theta - y)] && \text{by distributive prop. of } *-\text{algebras (Definition J.3 page 250)} \\ &= E[\theta^H U U^H \theta - \theta^H U y - y^H U^H \theta + y^H y] && \text{by matrix algebra ring property} \\ &= \theta^H E[UU^H] \theta - \theta^H E[Uy] - E[y^H U^H] \theta + E y^H y && \text{by linearity } E \text{ (Theorem 1.1 page 4)} \\ &= \theta^H E[UU^H] \theta - (E[Uy])^H \theta - E[Uy]^H \theta + E y^H y \\ &\triangleq \theta^H R \theta - (W^H \theta)^H - W^H \theta + E y^H y && \text{by definitions of } R \text{ and } W \\ &= \theta^H R \theta - (W^H \theta)^* - W^H \theta + E y^H y && \text{because } W^H \theta \text{ is a scalar} \\ &= \boxed{\theta^H R \theta - (W^H)^* \theta - W^H \theta + E y^H y} \\ &= \theta^H R \theta - 2R_e[W^H] \theta + E y^H y\end{aligned}$$



2. Proof that optimal $\theta_{\text{opt}} = (\mathbf{R}_e Y)^{-1}(\mathbf{R}_e W)$:

$$\begin{aligned}
 \nabla_{\theta} C(\theta) &= \nabla_{\theta} [\theta^H \mathbf{R} \theta - (\mathbf{W}^H)^* \theta - \mathbf{W}^H \theta + \mathbf{E} y^H y] \\
 &= \mathbf{R} \theta + \mathbf{R}^T \theta - \nabla_{\theta} [(\mathbf{W}^H)^* \theta + \mathbf{W}^H \theta] + 0 \\
 &= \mathbf{R} \theta + \mathbf{R}^T \theta - [(\mathbf{W}^H)^*]^T - [\mathbf{W}^H]^T \\
 &= \mathbf{R} \theta + (\mathbf{R}^H)^* \theta - \mathbf{W} - \mathbf{W}^* \\
 &= \mathbf{R} \theta + \mathbf{R}^* \theta - \mathbf{W} - \mathbf{W}^* \\
 &= (\mathbf{R} + \mathbf{R}^*) \theta - (\mathbf{W} + \mathbf{W}^*) \\
 &= 2(\mathbf{R}_e Y) \theta - 2\mathbf{R}_e \mathbf{W} \\
 \implies \theta_{\text{opt}} &= (\mathbf{R}_e Y)^{-1}(\mathbf{R}_e \mathbf{W})
 \end{aligned}$$

by item (1)
by quadratic form result (Theorem E.6 page 184)
by affine equations result (Theorem E.3 page 183)
by definition of Hermitian Transpose H
because R is Hermitian symmetric
by ring property
by definition of \mathbf{R}_e (Definition J.5 page 251)
by setting $\nabla_{\theta} C(\theta) = 0$

3. Cost of optimal θ_{opt} :

$$\begin{aligned}
 C(\theta_{\text{opt}}) &= \theta_{\text{opt}}^H \mathbf{R} \theta_{\text{opt}} - 2\mathbf{R}_e [\mathbf{W}^H] \theta_{\text{opt}} + \mathbf{E} y^H y \\
 &= [(\mathbf{R}_e Y)^{-1}(\mathbf{R}_e \mathbf{W})]^H \mathbf{R} [(\mathbf{R}_e Y)^{-1}(\mathbf{R}_e \mathbf{W})] - 2\mathbf{R}_e [\mathbf{W}^H] [(\mathbf{R}_e Y)^{-1}(\mathbf{R}_e \mathbf{W})] + \mathbf{E} y^H y \quad \text{by item (2)} \\
 &= (\mathbf{R}_e \mathbf{W}^H)(\mathbf{R}_e Y)^{-H} \mathbf{R} (\mathbf{R}_e Y)^{-1}(\mathbf{R}_e \mathbf{W}) - 2\mathbf{R}_e [\mathbf{W}^H](\mathbf{R}_e Y)^{-1}(\mathbf{R}_e \mathbf{W}) + \mathbf{E} y^H y \\
 &= (\mathbf{R}_e \mathbf{W}^H)(\mathbf{R}_e \mathbf{R}^H)^{-1} \mathbf{R} (\mathbf{R}_e Y)^{-1}(\mathbf{R}_e \mathbf{W}) - 2\mathbf{R}_e [\mathbf{W}^H](\mathbf{R}_e Y)^{-1}(\mathbf{R}_e \mathbf{W}) + \mathbf{E} y^H y \\
 &= (\mathbf{R}_e \mathbf{W}^H)(\mathbf{R}_e Y)^{-1} \mathbf{R} (\mathbf{R}_e Y)^{-1}(\mathbf{R}_e \mathbf{W}) - 2(\mathbf{R}_e \mathbf{W}^H)(\mathbf{R}_e Y)^{-1}(\mathbf{R}_e \mathbf{W}) + \mathbf{E} y^H y
 \end{aligned}$$

$$\begin{aligned}
 C(\theta_{\text{opt}})|_{\mathbf{R} \text{ real}} &= (\mathbf{R}_e \mathbf{W}^H)(\mathbf{R}_e Y)^{-1} \mathbf{R} (\mathbf{R}_e Y)^{-1}(\mathbf{R}_e \mathbf{W}) - 2(\mathbf{R}_e \mathbf{W}^H)(\mathbf{R}_e Y)^{-1}(\mathbf{R}_e \mathbf{W}) + \mathbf{E} y^H y \\
 &= (\mathbf{R}_e \mathbf{W}^H) \mathbf{R}^{-1} \mathbf{R} \mathbf{R}^{-1} (\mathbf{R}_e \mathbf{W}) - 2(\mathbf{R}_e \mathbf{W}^H) \mathbf{R}^{-1} (\mathbf{R}_e \mathbf{W}) + \mathbf{E} y^H y \\
 &= (\mathbf{R}_e \mathbf{W}^H) \mathbf{R}^{-1} (\mathbf{R}_e \mathbf{W}) - 2(\mathbf{R}_e \mathbf{W}^H) \mathbf{R}^{-1} (\mathbf{R}_e \mathbf{W}) + \mathbf{E} y^H y \\
 &= \mathbf{E} y^H y - (\mathbf{R}_e \mathbf{W}^H) \mathbf{R}^{-1} (\mathbf{R}_e \mathbf{W})
 \end{aligned}$$

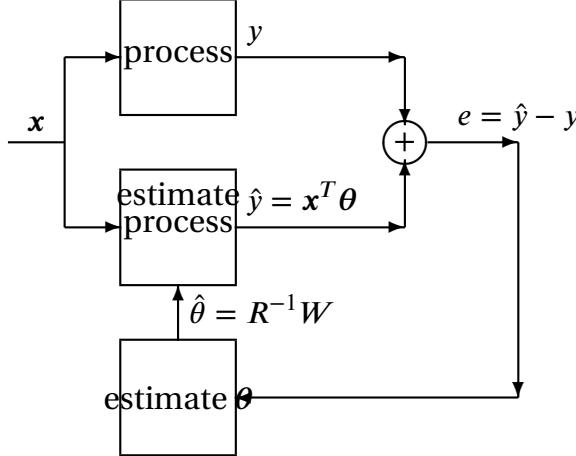


Figure 10.2: Adaptive filter example

In many adaptive filter and equalization applications, the autocorrelation matrix U is simply the m -element random data vector $\mathbf{x}(k)$ at time k , as in the *Wiener-Hopf equations* (next).

Corollary 10.1 (Wiener-Hopf equations). ⁴

⁴ ↗ Ifeachor and Jervis (1993) pages 547–549 (§“9.3 Basic Wiener filter theory”), ↗ Ifeachor and Jervis (2002) pages 651–654 (§“10.3 Basic Wiener filter theory”), ↗ Kay (1988) page 51 (§“3.3.3 Random Parameters”)

COR

$$\left\{ U \triangleq \mathbf{x}(k) \triangleq \begin{bmatrix} x(k) \\ x(k-1) \\ x(k-2) \\ \vdots \\ x(k-m+1) \end{bmatrix} \right\} \Rightarrow \left\{ \begin{array}{lcl} \hat{\theta}_{\text{mms}} & = & R^{-1}W \\ C(\hat{\theta}_{\text{mms}}) & = & W^T R^{-1} R R^{-1} W - 2W^T R^{-1} W + E y^T y \end{array} \right\}$$

PROOF: This is a special case of the more general case discussed in Theorem 10.1 (page 74). Here, the dimension of U is $m \times 1$ ($n=1$). As a result, y , \hat{y} , and e are simply scalar quantities (not vectors). In this special case, we have the following results (Figure 10.2 page 75):

$$\begin{aligned} \hat{y}(\theta) &\triangleq \mathbf{x}^T \theta \\ e(\theta) &\triangleq \hat{y} - y \\ C(\theta) &\triangleq E \|e\|^2 \triangleq E[e^2] \\ \hat{\theta}_{\text{mms}} &\triangleq \arg \min_{\theta} C(\theta) \\ R &\triangleq E[\mathbf{x}\mathbf{x}^T] \\ W &\triangleq E[\mathbf{x}y] \\ C(\theta) &= \theta^T R \theta - 2W^T \theta + E[y^T y] \\ \nabla_{\theta} C(\theta) &= 2R\theta - 2W \\ C(\hat{\theta}_{\text{mms}})|_{R \text{ real}} &= E y^T y - W^T R^{-1} W. \end{aligned}$$



10.2 Least squares

Theorem 10.2 (Least squares). *Let*

$$\begin{aligned} \hat{y}(\theta) &\triangleq U^H \theta \\ e(\theta) &\triangleq \hat{y} - y \\ C(\theta) &\triangleq \|e\|^2 \triangleq e^H e \\ \hat{\theta}_{\text{ls}} &\triangleq \arg \min_{\theta} C(\theta) \\ R &\triangleq UU^H \\ W &\triangleq Uy. \end{aligned}$$

Then

$$\begin{aligned} \hat{\theta}_{\text{ls}} &= (\mathbf{R}_e Y)^{-1} (\mathbf{R}_e W) \\ C(\theta) &= \theta^H R \theta - (W^H \theta)^* - W^H \theta + E y^H y \\ \nabla_{\theta} C(\theta) &= 2\mathbf{R}_e [Y]\theta - 2\mathbf{R}_e W \\ C(\hat{\theta}_{\text{ls}}) &= (\mathbf{R}_e W^H) (\mathbf{R}_e Y)^{-1} R (\mathbf{R}_e Y)^{-1} (\mathbf{R}_e W) - 2(\mathbf{R}_e W^H) (\mathbf{R}_e Y)^{-1} (\mathbf{R}_e W) + E y^H y \\ C(\hat{\theta}_{\text{ls}})|_{R \text{ real}} &= E y^H y - (\mathbf{R}_e W^H) R^{-1} (\mathbf{R}_e W). \end{aligned}$$

PROOF: See APPENDIX E (page 179) for a Matrix Calculus reference.



$$\begin{aligned}
C(\theta) &\triangleq \|e\|^2 \\
&= e^H e \\
&= (\hat{y} - y)^H (\hat{y} - y) \\
&= (U^H \theta - y)^H (U^H \theta - y) \\
&= (\theta^H U - y^H) (U^H \theta - y) \\
&= \theta^H U U^H \theta - \theta^H U y - y^H U^H \theta + y^H y \\
&= \theta^H R \theta - (W^H \theta)^H - W^H \theta + y^H y \\
&= \theta^H R \theta - (W^H \theta)^* - W^H \theta + y^H y \\
&= \theta^H R \theta - (W^H)^* \theta - W^H \theta + y^H y \\
&= \theta^H R \theta - 2R_e [W^H] \theta + y^H y
\end{aligned}$$

$$\begin{aligned}
\nabla_{\theta} C(\theta) &= \nabla_{\theta} [\theta^H R \theta - (W^H)^* \theta - W^H \theta + y^H y] \\
&= R \theta + R^T \theta - [(W^H)^*]^T - [W^H]^T + 0 \\
&= R \theta + (R^H)^* \theta - W - W^* \\
&= R \theta + R^* \theta - W - W^* \\
&= (R + R^*) \theta - (W + W^*) \\
&= 2(R_e Y) \theta - 2R_e W
\end{aligned}$$

$$\theta_{\text{opt}} = (R_e Y)^{-1} (R_e W)$$

$$\begin{aligned}
C(\theta_{\text{opt}}) &= \theta_{\text{opt}}^H R \theta_{\text{opt}} - 2R_e [W^H] \theta_{\text{opt}} + y^H y \\
&= [(R_e Y)^{-1} (R_e W)]^H R [(R_e Y)^{-1} (R_e W)] - 2R_e [W^H] [(R_e Y)^{-1} (R_e W)] + y^H y \\
&= (R_e W^H) (R_e Y)^{-H} R (R_e Y)^{-1} (R_e W) - 2R_e [W^H] (R_e Y)^{-1} (R_e W) + y^H y \\
&= (R_e W^H) (R_e R^H)^{-1} R (R_e Y)^{-1} (R_e W) - 2R_e [W^H] (R_e Y)^{-1} (R_e W) + y^H y \\
&= (R_e W^H) (R_e Y)^{-1} R (R_e Y)^{-1} (R_e W) - 2(R_e W^H) (R_e Y)^{-1} (R_e W) + y^H y
\end{aligned}$$

$$\begin{aligned}
C(\theta_{\text{opt}})|_{R \text{ real}} &= (R_e W^H) (R_e Y)^{-1} R (R_e Y)^{-1} (R_e W) - 2(R_e W^H) (R_e Y)^{-1} (R_e W) + y^H y \\
&= (R_e W^H) R^{-1} R R^{-1} (R_e W) - 2(R_e W^H) R^{-1} (R_e W) + y^H y \\
&= (R_e W^H) R^{-1} (R_e W) - 2(R_e W^H) R^{-1} (R_e W) + y^H y \\
&= y^H y - (R_e W^H) R^{-1} (R_e W)
\end{aligned}$$

⇒

Example 10.1 (Polynomial approximation).

Suppose we **know** the locations $\{(x_n, y_n) | n = 1, 2, 3, 4, 5\}$ of 5 data points. Let x and y represent the locations of these points such that

$$x \triangleq \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} \quad y \triangleq \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \\ y_5 \end{bmatrix}$$

Suppose we want to find a second order polynomial

$$cx^2 + bx + a$$

that best approximates these 5 points in the least squares sense. We define the matrix U (known) and vector $\hat{\theta}$ (to be computed) as follows:

$$U^H \triangleq \underbrace{\begin{bmatrix} 1 & x_1 & x_1^2 \\ 1 & x_2 & x_2^2 \\ 1 & x_3 & x_3^2 \\ 1 & x_4 & x_4^2 \\ 1 & x_5 & x_5^2 \end{bmatrix}}_{\text{Vandermonde matrix}}^H \quad \hat{\theta} \triangleq \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

Then, using Theorem 10.2 (page 76), the best coefficients $\hat{\theta}$ for the polynomial are

$$\begin{aligned} \hat{\theta} &= \begin{bmatrix} a \\ b \\ c \end{bmatrix} \\ &= R^{-1}W \\ &= (UU^H)^{-1}(Uy) \\ &= \left(\begin{bmatrix} 1 & x_1 & x_1^2 \\ 1 & x_2 & x_2^2 \\ 1 & x_3 & x_3^2 \\ 1 & x_4 & x_4^2 \\ 1 & x_5 & x_5^2 \end{bmatrix}^H \begin{bmatrix} 1 & x_1 & x_1^2 \\ 1 & x_2 & x_2^2 \\ 1 & x_3 & x_3^2 \\ 1 & x_4 & x_4^2 \\ 1 & x_5 & x_5^2 \end{bmatrix} \right)^{-1} \left(\begin{bmatrix} 1 & x_1 & x_1^2 \\ 1 & x_2 & x_2^2 \\ 1 & x_3 & x_3^2 \\ 1 & x_4 & x_4^2 \\ 1 & x_5 & x_5^2 \end{bmatrix}^H \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \\ y_5 \end{bmatrix} \right) \end{aligned}$$

10.3 Recursive forms

One of the biggest advantages of using a recursive form / gradient search technique is that it can be implemented *recursively* as shown in the next equation. The general form of the gradient search parameter estimation techniques is⁶

THM	$\theta_n = \theta_{n-1} - \eta_{n-1} R [\nabla_{\theta} C(\theta_n)]$	where at time n
-----	--	-------------------

- θ_n is the *state* (vector)
- η_n is the *step size* (scalar)
- R is the *direction* (matrix)
- $\nabla_{\theta} C(\theta_n)$ is the *gradient* of the cost function $C(\theta_n)$ (vector)

Two major categories of gradient search techniques are

- ➊ steepest descent (includes LMS)
- ➋ Newton's method (includes RLS and Kalman filters).

The key difference between the two is that **steepest descent uses only first derivative information**, while **Newton's method uses both first and second derivative information** making it converge much faster but with significantly higher complexity.

⁵  Horn and Johnson (1990)29

⁶  Nelles (2001), page 90

First derivative techniques

Steepest descent. In this algorithm, $R = I$ (identity matrix). First derivative information is contained in ∇C . Second derivative information, if present, is contained in Y . Thus, steepest descent algorithms do not use second derivative information.

T
H
M

$$\theta_n = \theta_{n-1} - \eta_{n-1} [\nabla_{\theta} C(\theta_n)]$$

Least Mean Squares (LMS). ⁷ This is a special case of *steepest descent*. In minimum mean square estimation (Section 10.1 page 74), the cost function $C(\theta)$ is defined as a *statistical average* of the error vector such that $C(\theta) = E [e^H e]$. In this case the gradient ∇C is difficult to compute. However, the LMS algorithm greatly simplifies the problem by instead defining the cost function as a function of the *instantaneous error* such that

$$\begin{aligned} y &= y(n) \\ \hat{y} &= \hat{y}(n) \\ C(\theta) &= \|e(n)\|^2 \\ &= e^2(n) \\ &= (\hat{y}(n) - y(n))^2 \end{aligned}$$

Computing the gradient of this cost function is then just a special case of *least squares estimation* (Section 10.2 page 76). Using LS, we let $U = \mathbf{x}^T$ and hence

$$\begin{aligned} \nabla_{\theta} C(\theta) &= 2U^T U \theta - 2U^T y && \text{by Theorem 10.2 page 76} \\ &= 2\mathbf{x}\mathbf{x}^T \theta - 2\mathbf{x}y && \text{by above definitions} \\ &= 2\mathbf{x}\hat{y} - 2\mathbf{x}y \\ &= 2\mathbf{x}(\hat{y} - y) \\ &= 2\mathbf{x}e(n) \end{aligned}$$

The LMS algorithm uses this instantaneous gradient for ∇C , lets $R = I$, and uses a constant step size η to give

T
H
M

$$\theta_n = \theta_{n-1} - 2\eta \mathbf{x}_n e(n)$$

Second derivative techniques

Newton's Method. This algorithm uses the *Hessian* matrix H , which is the second derivative of the cost function $C(\theta)$, and lets $R = H^{-1}$.

$$\begin{aligned} H_n &\triangleq && \nabla_{\theta} \nabla_{\theta} C(\theta_n) \\ \theta_n &= \theta_{n-1} - \eta_{n-1} H_n^{-1} [\nabla_{\theta} C(\theta_n)] \end{aligned}$$

⁷  Manolakis et al. (2000) page 526

Kalman filtering ⁸

$$\begin{aligned}\gamma(k) &= \frac{1}{x^T(k)P(k-1)x(k)+1} P(k-1)x(k) \\ P(k) &= (I - \gamma(k)x^T(k))P(k-1) + V \\ e(k) &= y(k) - x^T(k)\hat{\theta}(k-1) \\ \hat{\theta}(k) &= \hat{\theta}(k-1) + \gamma(k)e(k)\end{aligned}$$

Recursive Least Squares (RLS) ⁹ This algorithm is a special case of either the RLS with forgetting or the Kalman filter.

$$\begin{aligned}\gamma(k) &= \frac{1}{x^T(k)P(k-1)x(k)+1} P(k-1)x(k) \\ P(k) &= (I - \gamma(k)x^T(k))P(k-1) \\ e(k) &= y(k) - x^T(k)\hat{\theta}(k-1) \\ \hat{\theta}(k) &= \hat{\theta}(k-1) + \gamma(k)e(k)\end{aligned}$$

10.4 Direct search

A direct search algorithm may be used in cases where the cost function over θ has several local minima, making convergence difficult. Furthermore, direct search algorithms can be very computationally demanding.

⁸  Nelles (2001), page 66

⁹  Nelles (2001), page 66

CHAPTER 11

PROJECTION STATISTIC ALGORITHMS FOR ADDITIVE NOISE MODELS

11.1 Projection Statistics

Theorem 11.1 (page 83) (next) shows that the finite set $Y \triangleq \{\dot{y}_n | n = 1, 2, \dots, N\}$ (a finite number of values) provides just as good an estimate as having the entire $y(t; \theta)$ waveform (an uncountably infinite number of values) with respect to the following cases:

1. the conditional probability of $x(t; \theta)$ given $y(t; \theta)$
2. the *MAP estimate* of the sequence
3. the *ML estimate* of the sequence.

That is, even with a drastic reduction in the number of statistics from uncountably infinite to finite N , no quality is lost with respect to the estimators listed above. This amazing result is very useful in practical system implementation and also for proving other theoretical results (notably estimation and detection theorems).

But first, some definitions (next) that are used repeatedly in this chapter.

Definition 11.1. Let $\Psi \triangleq \{\psi_n | n = 1, 2, \dots, N\}$ be an ORTHONORMAL BASIS for a parameterized function $x(t; \theta)$ with parameter θ . Let $y(t; \theta)$ be $x(t; \theta)$ plus a RANDOM PROCESS $v(t)$ such that

$$y(t; \theta) \triangleq x(t; \theta) + v(t)$$

Let \dot{y}_n , \dot{x}_n , and \dot{v}_n be PROJECTIONS (Definition O.7 page 318) onto the BASIS VECTOR $\psi_n(t)$ such that

$$\begin{aligned}\dot{y}_n(\theta) &\triangleq \mathbf{P}_n y(t; \theta) \triangleq \langle y(t; \theta) | \psi_n(t) \rangle \triangleq \int_{t \in \mathbb{R}} y(t; \theta) \psi_n(t) dt \\ \dot{x}_n(\theta) &\triangleq \mathbf{P}_n x(t) \triangleq \langle x(t; \theta) | \psi_n(t) \rangle \triangleq \int_{t \in \mathbb{R}} x(t; \theta) \psi_n(t) dt \\ \dot{v}_n &\triangleq \mathbf{P}_n v(t) \triangleq \langle v(t) | \psi_n(t) \rangle \triangleq \int_{t \in \mathbb{R}} v(t) \psi_n(t) dt\end{aligned}$$

Let the set Y be defined as $Y \triangleq \{\dot{y}_n(\theta) | 1, 2, \dots, N\}$. Let $\hat{\theta}_{\text{map}}$ be the MAP ESTIMATE and $\hat{\theta}_{\text{ml}}$ be the ML ESTIMATE (Definition 9.1 page 69) of θ .

Lemma 11.1. Let Ψ , $v(t)$, \dot{v}_n , and Y be defined as in Definition 11.1 (page 81).

LEM

$$\{ \mathbb{E}v(t) = 0 \text{ (ZERO-MEAN)} \} \implies \{ \mathbb{E}\dot{v}_n = 0 \text{ (ZERO-MEAN)} \}$$

PROOF:

$$\begin{aligned} \mathbb{E}\dot{v}_n &= \mathbb{E}\langle v(t) | \psi_n(t) \rangle && \text{by definition of } \dot{v}_n \\ &= \langle \mathbb{E}v(t) | \psi_n(t) \rangle && \text{by linearity of } \langle \cdot | \cdot \rangle \\ &= \langle 0 | \psi_n(t) \rangle && \text{by zero-mean hypothesis} \\ &= 0 \end{aligned} \quad \text{(Definition 11.1 page 81)}$$

⇒

Lemma 11.2. Let Ψ , $v(t)$, \dot{v}_n , and Y be defined as in Definition 11.1 (page 81).

LEM

$$\{ v(t) \sim N(0, \sigma^2) \text{ (GAUSSIAN)} \} \implies \{ \dot{v}_n \sim N(0, \sigma^2) \text{ (GAUSSIAN)} \}$$

⇒

PROOF: The distribution follows because it is a linear operation on a Gaussian process.

Lemma 11.3. Let Ψ , $y(t; \theta)$, $x(t)$, $v(t)$, \dot{y}_n , \dot{x}_n , \dot{v}_n , and Y be defined as in Definition 11.1 (page 81).

LEM

$$\left\{ \begin{array}{l} (A). \mathbb{E}[v(t)] = 0 \\ (B). \text{cov}[v(t), v(u)] = \sigma^2 \delta(t-u) \end{array} \text{ and } \right\} \implies \left\{ \begin{array}{l} (1). \mathbb{E}\dot{v}_n = 0 \text{ (ZERO-MEAN)} \\ (2). \text{cov}[\dot{v}_n, \dot{v}_m] = \sigma^2 \bar{\delta}_{n-m} \text{ (UNCORRELATED)} \end{array} \right\}$$

PROOF:

1.

$$\mathbb{E}\dot{v}_n = 0 \quad \text{by additive property and Theorem 11.2 page 86}$$

2.

$$\begin{aligned} \text{cov}[\dot{v}_m, \dot{v}_n] &= \text{cov}[\langle v(t) | \psi_m(t) \rangle, \langle v(t) | \psi_n(t) \rangle] && \text{by def. of } \dot{v}_n \quad (\text{Definition 11.1 page 81}) \\ &= \text{cov}\left[\left(\int_{t \in \mathbb{R}} v(t) \psi_m(t) dt\right), \left(\int_{u \in \mathbb{R}} v(u) \psi_n(u) du\right)\right] && \text{by def. of } \langle \cdot | \cdot \rangle \quad (\text{Definition 11.1 page 81}) \\ &= \mathbb{E}\left[\left(\int_{t \in \mathbb{R}} v(t) \psi_m(t) dt\right)\left(\int_{u \in \mathbb{R}} v(u) \psi_n(u) du\right)\right] && \text{by def. of Cov} \\ &= \mathbb{E}\left[\int_{t \in \mathbb{R}} \int_{u \in \mathbb{R}} v(t)v(u) \psi_m(t) \psi_n(u) dt du\right] \\ &= \int_{t \in \mathbb{R}} \int_{u \in \mathbb{R}} \mathbb{E}[v(t)v(u)] \psi_m(t) \psi_n(u) dt du \\ &= \int_{t \in \mathbb{R}} \int_{u \in \mathbb{R}} \sigma^2 \delta(t-u) \psi_m(t) \psi_n(u) dt du && \text{by white hyp.} \quad (B) \\ &= \sigma^2 \int_{t \in \mathbb{R}} \psi_m(t) \psi_n(u) dt \\ &= \sigma^2 \langle \psi_m(t) | \psi_n(u) \rangle && \text{by def. of } \langle \cdot | \cdot \rangle \quad (\text{Definition 11.1 page 81}) \\ &= \begin{cases} \sigma^2 & \text{for } n = m \\ 0 & \text{for } n \neq m. \end{cases} && \text{by orthonormal prop.} \quad (\text{Definition 11.1 page 81}) \end{aligned}$$

⇒



Lemma 11.4. Let Ψ , $y(t; \theta)$, $x(t)$, $v(t)$, \dot{y}_n , \dot{x}_n , \dot{v}_n , and Y be defined as in Definition 11.1 (page 81).

L E M	$\left. \begin{array}{l} (A). \text{ COV}[v(t), v(u)] = \sigma^2 \delta(t-u) \text{ and} \\ (B). \quad v(t) \sim N(0, \sigma^2) \text{ and} \\ (C). \quad \langle \psi_n \psi_m \rangle = \bar{\delta}_{mn} \end{array} \right\} \Rightarrow \left\{ \begin{array}{ll} (1). & \dot{v}_n \sim N(0, \sigma^2) & \text{(GAUSSIAN)} \\ (2). & \text{COV}[\dot{v}_n, \dot{v}_m] = \sigma^2 \bar{\delta}_{nm} & \text{(UNCORRELATED)} \\ (3). & P\{\dot{v}_n \wedge \dot{v}_m\} = P\{\dot{v}_n\}P\{\dot{v}_m\} & \text{(INDEPENDENT)} \end{array} \right.$
----------------------	--

PROOF:

1. Because the operations are *linear* on processes are *Gaussian* (hypothesis C).

2.

$$\begin{aligned} E\dot{v}_n &= 0 && \text{by AWN properties and Theorem 11.4 page 87} \\ \text{cov}[\dot{v}_m, \dot{v}_n] &= \sigma^2 \bar{\delta}_{mn} && \text{by AWN properties and Lemma 11.3 page 82} \end{aligned}$$

3. Because the processes are *Gaussian, uncorrelated* implies *independent*.



11.2 Sufficient Statistics

Theorem 11.1 (Sufficient Statistic Theorem). ¹ Let Ψ , $y(t; \theta)$, $x(t)$, $v(t)$, \dot{y}_n , \dot{x}_n , \dot{v}_n , and Y be defined as in Definition 11.1 (page 81). Let $\hat{\theta}_{\text{map}}$ be the MAP ESTIMATE and $\hat{\theta}_{\text{ml}}$ be the ML ESTIMATE (Definition 9.1 page 69) of θ .

T H M	$\left. \begin{array}{l} (A). \quad v(t) \text{ is ZERO-MEAN} \quad \text{and} \\ (B). \quad v(t) \text{ is WHITE} \quad \text{and} \\ (C). \quad v(t) \text{ is GAUSSIAN} \end{array} \right\} \Rightarrow \underbrace{\left\{ \begin{array}{ll} (1). & P\{x(t; \theta) y(t; \theta)\} = P\{x(t; \theta) Y\} \quad \text{and} \\ (2). & \hat{\theta}_{\text{map}} = \arg \max_{\hat{\theta}} P\{x(t; \theta) Y\} \quad \text{and} \\ (3). & \hat{\theta}_{\text{ml}} = \arg \max_{\hat{\theta}} P\{Y x(t; \theta)\} \end{array} \right\}}_{\text{the } N \text{ element set } Y \text{ is a SUFFICIENT STATISTIC for estimating } x(t; \theta)}$
----------------------	---

PROOF:

1. definition: Let $v'(t) \triangleq v(t) - \sum_{n=1}^N \dot{v}_n \psi_n(t)$.

¹ Fisher (1922) page 316 (“Criterion of Sufficiency”)

2. lemma: The relationship between Y and $v'(t)$ is given by

$$\begin{aligned}
 & y(t; \theta) \\
 &= \sum_{n=1}^N \langle y(t; \theta) | \psi_n(t) \rangle \psi_n(t) + \left[y(t; \theta) - \sum_{n=1}^N \langle y(t; \theta) | \psi_n(t) \rangle \psi_n(t) \right] && \text{by } \textit{additive identity} \text{ property} \\
 &\triangleq \sum_{n=1}^N \langle y(t; \theta) | \psi_n(t) \rangle \psi_n(t) + \left[y(t; \theta) - \sum_{n=1}^N \langle x(t) + v(t) | \psi_n(t) \rangle \psi_n(t) \right] && \text{by definition of } y(t; \theta) \\
 &= \sum_{n=1}^N \dot{y}_n \psi_n(t) + \underbrace{x(t) + v(t)}_{y(t; \theta)} - \underbrace{\sum_{n=1}^N \langle x(t) | \psi_n(t) \rangle \psi_n(t)}_{x(t)} - \underbrace{\sum_{n=1}^N \langle v(t) | \psi_n(t) \rangle \psi_n(t)}_{v(t) - v'(t)} && \text{by definition of } \dot{y}_n \text{ and} \\
 &&& \text{additive property of } \langle \Delta | \nabla \rangle \\
 &&& (\text{Definition K.1 page 255}) \\
 &= \sum_{n=1}^N \dot{y}_n \psi_n(t) + x(t) + v(t) - x(t) - [v(t) - v'(t)] \\
 &= \boxed{\sum_{n=1}^N \dot{y}_n \psi_n(t) + v'(t)}
 \end{aligned}$$

3. lemma: $E[\dot{v}_n v(t)] = N_o \psi_n(t)$. Proof:

$$\begin{aligned}
 & E[\dot{v}_n v(t)] \\
 &\triangleq E\left[\left(\int_{t \in \mathbb{R}} v(u) \psi_n(u) du\right) v(t)\right] && \text{by definition of } \dot{v}_n(t) \\
 &= E\left[\int_{t \in \mathbb{R}} v(u) v(t) \psi_n(u) du\right] && \text{by } \textit{linearity} \text{ of } \int du \text{ operator} \\
 &= \int_{t \in \mathbb{R}} E[v(u)v(t)] \psi_n(u) du && \text{by } \textit{linearity} \text{ of } E \\
 &= \int_{t \in \mathbb{R}} N_o \delta(u - t) \psi_n(u) du && \text{by } \textit{white hypothesis} \\
 &= N_o \psi_n(t) && \text{by property of } \textit{Dirac delta} \delta(t)
 \end{aligned}$$

4. lemma: Y and $v'(t)$ are *uncorrelated*: Proof:

$$\begin{aligned}
 & E[\dot{y}_n v'(t)] \\
 &\triangleq E\left[\langle y(t; \theta) | \psi_n(t) \rangle \left(v(t) - \sum_{n=1}^N \langle v(t) | \psi_n(t) \rangle \psi_n(t) \right)\right] && \text{by definitions of } \dot{y}_n \text{ and } v'(t) \\
 &\triangleq E\left[\langle x(t) + v(t) | \psi_n(t) \rangle \left(v(t) - \sum_{n=1}^N \langle v(t) | \psi_n(t) \rangle \psi_n(t) \right)\right] && \text{by definition of } y(t; \theta) \\
 &= E\left[\left(\langle x(t) | \psi_n(t) \rangle + \langle v(t) | \psi_n(t) \rangle \right) \left(v(t) - \sum_{n=1}^N \langle v(t) | \psi_n(t) \rangle \psi_n(t) \right)\right] && \text{by } \textit{additive property of} \\
 &&& \langle \Delta | \nabla \rangle (\text{Definition K.1 page 255}) \\
 &= E\left[\left(\dot{x}_n + \dot{v}_n \right) \left(v(t) - \sum_{n=1}^N \dot{v}_n \psi_n(t) \right)\right] && \text{by definitions of } \dot{x}_n \text{ and } \dot{v}_n \\
 &= E\left[\dot{x}_n v(t) - \dot{x}_n \sum_{n=1}^N \dot{v}_n \psi_n(t) + \dot{v}_n v(t) - \dot{v}_n \sum_{n=1}^N \dot{v}_n \psi_n(t)\right] && (\text{Definition 11.1 page 81}) \\
 &= E[\dot{x}_n v(t)] - E\left[\dot{x}_n \sum_{n=1}^N \dot{v}_n \psi_n(t)\right] + E[\dot{v}_n v(t)] - E\left[\sum_{m=1}^N \dot{v}_n \dot{v}_m \psi_m(t)\right] && \text{by } \textit{linearity} \text{ of } E \\
 &&& (\text{Theorem 1.1 page 4})
 \end{aligned}$$



$$\begin{aligned}
 &= \dot{x}_n E[\nu(t)] - \dot{x}_n \sum_{n=1}^N E[\dot{\psi}_n] \psi_n(t) + E[\dot{\psi}_n \nu(t)] - \sum_{m=1}^N E[\dot{\psi}_n \dot{\psi}_m] \psi_m(t) \\
 &= 0 - 0 + E[\dot{\psi}_n \nu(t)] - \sum_{m=1}^N N_o \delta_{mn} \psi_m(t) \\
 &= N_o \psi_n(t) - N_o \psi_n(t) \\
 &= 0
 \end{aligned}$$

by *linearity* of E
(Theorem 1.1 page 4)

by *white hypothesis*

by (3) lemma

⇒ uncorrelated

5. lemma: Y and $\nu'(t)$ are *independent*. Proof: By (4) lemma, \dot{y}_n and $\nu'(t)$ are *uncorrelated*. By hypothesis, they are *Gaussian*, and thus are also **independent**.

6. Proof that $P\{x(t; \theta) | y(t; \theta)\} = P\{x(t; \theta) | \dot{y}_1, \dot{y}_2, \dots, \dot{y}_N\}$:

$$\begin{aligned}
 P\{x(t; \theta) | y(t; \theta)\} &= P\left\{x(t; \theta) \mid \sum_{n=1}^N \dot{y}_n \psi_n(t) + \nu'(t)\right\} \\
 &= P\{x(t; \theta) | Y, \nu'(t)\} \\
 &= \frac{P\{Y, \nu'(t) | x(t; \theta)\} P\{x(t; \theta)\}}{P\{Y, \nu'(t)\}} \\
 &= \frac{P\{Y | x(t; \theta)\} P\{\nu'(t) | x(t; \theta)\} P\{x(t; \theta)\}}{P\{Y\} P\{\nu'(t)\}} \\
 &= \frac{P\{Y | x(t; \theta)\} P\{\nu'(t)\} P\{x(t; \theta)\}}{P\{Y\} P\{\nu'(t)\}} \\
 &= \frac{P\{Y | x(t; \theta)\} P\{x(t; \theta)\}}{P\{Y\}} \\
 &= \frac{P\{Y, x(t; \theta)\}}{P\{Y\}} \\
 &= P\{x(t; \theta) | Y\}
 \end{aligned}$$

because Y and $\nu'(t)$ can be extracted by $\langle \dots | \psi_n(t) \rangle$

by *independence* of Y and $\nu'(t)$ ((5) lemma page 85)

by *independence* of x and ν

by definition of *conditional probability*
(Definition A.4 page 152)

7. Proof that Y is a *sufficient statistic* for the *MAP estimate*:

$$\begin{aligned}
 \hat{\theta}_{\text{map}} &\triangleq \arg \max_{\hat{\theta}} P\{x(t; \theta) | y(t; \theta)\} \\
 &= \arg \max_{\hat{\theta}} P\{x(t; \theta) | Y\}
 \end{aligned}$$

by definition of *MAP estimate* (Definition 9.1 page 69)

by item (6)

8. Proof that Y is a *sufficient statistic* for the *ML estimate*:

$$\begin{aligned}
 \hat{\theta}_{\text{ml}} &\triangleq \arg \max_{\hat{\theta}} P\{y(t; \theta) | x(t; \theta)\} \\
 &= \arg \max_{\hat{\theta}} P\left\{ \sum_{n=1}^N \dot{y}_n \psi_n(t) + \nu'(t) | x(t; \theta) \right\} \\
 &= \arg \max_{\hat{\theta}} P\{Y, \nu'(t) | x(t; \theta)\} \\
 &= \arg \max_{\hat{\theta}} P\{Y | x(t; \theta)\} P\{\nu'(t)\} x(t; \theta) \\
 &= \arg \max_{\hat{\theta}} P\{Y | x(t; \theta)\} P\{\nu'(t)\} \\
 &= \arg \max_{\hat{\theta}} P\{Y | x(t; \theta)\}
 \end{aligned}$$

by definition of *ML estimate* (Definition 9.1 page 69)

because Y and $\nu'(t)$ can be extracted by $\langle \dots | \psi_n(t) \rangle$

by *independence* of Y and $\nu'(t)$ ((5) lemma page 85)

by *independence* of $x(t)$ and $\nu'(t)$

by *independence* of $\nu'(t)$ and θ



11.3 Additive noise

Theorem 11.2 (Additive noise projection statistics). Let Ψ , $y(t; \theta)$, $x(t)$, $v(t)$, \dot{y}_n , \dot{x}_n , \dot{v}_n , and Y be defined as in Definition 11.1 (page 81).

T H M	$\left\{ \begin{array}{ll} (A). & y(t; \theta) \triangleq x(t; \theta) + v(t) \quad (\text{additive}) \\ (B). & E[v(t)] = 0 \quad (\text{ZERO-MEAN}) \\ (C). & x(t) \subseteq \text{span } \Psi \quad (\Psi \text{ SPANS } x(t)) \\ (D). & \langle \psi_n \psi_m \rangle = \delta_{mn} \quad (\text{ORTHONORMAL}) \end{array} \right. \text{ and } \left\{ \begin{array}{l} \text{and} \\ \text{and} \\ \text{and} \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} E[\dot{y}_n(\theta)] = \dot{x}_n(\theta) \end{array} \right\}$
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PROOF:

$$\begin{aligned}
 E[\dot{y}_n(\theta)] &\triangleq E[\langle y(t; \theta) | \psi_n(t) \rangle] && \text{by definition of } \dot{y}_n \\
 &= E\langle x(t; \theta) + v(t) | \psi_n(t) \rangle && \text{by additive hypothesis} \\
 &= E[\langle x(t; \theta) \psi_n(t) | + \rangle \langle v(t) | \psi_n(t) \rangle] && \text{by additive property of } \langle \Delta | \nabla \rangle \\
 &= E\left[\left\langle \sum_{k=1}^N \dot{x}_k(\theta) \psi_k(t) | \psi_n(t) \right\rangle + \dot{v}_n \right] && \text{by basis hypothesis} \\
 &= E\left[\sum_{k=1}^N \dot{x}_k(\theta) \langle \psi_k(t) | \psi_n(t) \rangle + \dot{v}_n \right] && \text{by additive property of } \langle \Delta | \nabla \rangle \\
 &= E\left[\sum_{k=1}^N \dot{x}_k(\theta) \bar{\delta}_{k-n}(t) + \dot{v}_n \right] && \text{by orthonormal hypothesis} \\
 &= E[\dot{x}_n(\theta) + \dot{v}_n] && \text{by definition of } \bar{\delta} \\
 &= E[\dot{x}_n(\theta) + \dot{v}_n] && \text{by linearity of } E \\
 &= \dot{x}_n(\theta) + E\dot{v}_n && \text{(Theorem 1.1 page 4)} \\
 &= \dot{x}_n(\theta) && \text{by (B) and Lemma 11.1 page 81}
 \end{aligned}$$

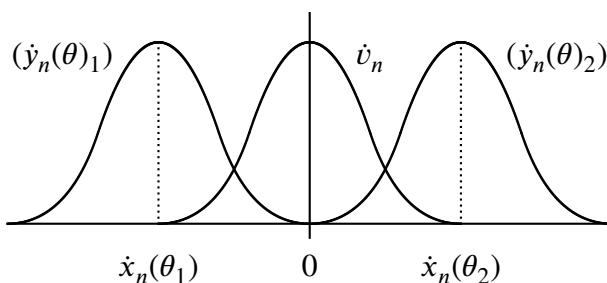


Figure 11.1: Additive Gaussian noise channel Statistics

Theorem 11.3 (Additive Gaussian noise projection statistics). Let Ψ , $y(t; \theta)$, $x(t)$, $v(t)$, \dot{y}_n , \dot{x}_n , \dot{v}_n , and Y be defined as in Definition 11.1 (page 81).

T H M	$\left\{ \begin{array}{ll} (A). & y(t; \theta) \triangleq x(t) + v(t) \quad (\text{additive}) \\ (B). & v(t) \sim N(0, \sigma^2) \quad (\text{Gaussian}) \\ (C). & x(t) \subseteq \text{span } \Psi \quad (\Psi \text{ SPANS } x(t)) \\ (D). & \langle \psi_n \psi_m \rangle = \delta_{mn} \quad (\text{ORTHONORMAL}) \end{array} \right. \text{ and } \left\{ \begin{array}{l} \text{and} \\ \text{and} \\ \text{and} \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} \dot{y}_n(\theta) \sim N(\dot{x}_n(\theta), \sigma^2) \quad (\text{GAUSSIAN}) \end{array} \right\}$
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ADDITIVE GAUSSIAN system



PROOF:

1. Proof for (1): By hypothesis (B) and Lemma 11.1 page 81.

2. Proof for (2):

$$\begin{aligned}
 E[\dot{y}_n(\theta)] &\triangleq E[\langle y(t; \theta) | \psi_n(t) \rangle | \theta] && \text{by definition of } \dot{y}_n \\
 &= E[\langle x(t; \theta) + v(t) | \psi_n(t) \rangle] && \text{by additive hypothesis} \\
 &= E[\langle x(t; \theta) | \psi_n(t) \rangle] + E[\langle v(t) | \psi_n(t) \rangle] && \text{by additive property of } \langle \Delta | \nabla \rangle \quad (\text{Definition K.1 page 255}) \\
 &= E \left\langle \sum_{k=1}^N \dot{x}_k(\theta) \psi_k(t) | \psi_n(t) \right\rangle + E \dot{v}_n && \text{by basis hypothesis} \quad (C) \\
 &= \sum_{k=1}^N E[\dot{x}_k(\theta)] \langle \psi_k(t) | \psi_n(t) \rangle + E \dot{v}_n && \text{by additive property of } \langle \Delta | \nabla \rangle \quad (\text{Definition K.1 page 255}) \\
 &= \sum_{k=1}^N E[\dot{x}_k(\theta)] \bar{\delta}_{k-n}(t) + E \dot{v}_n && \text{by orthonormal hypothesis} \quad (D) \\
 &= E \dot{x}_n(\theta) + E \dot{v}_n && \text{by definition of } \bar{\delta} \quad (\text{Definition K.3 page 267}) \\
 &= \dot{x}_n(\theta) + 0 && \text{by Lemma 11.1 page 81}
 \end{aligned}$$

3. Proof for (3): The distribution follows because the process is a linear operations on a Gaussian process.



Theorem 11.4 (Additive white noise projection statistics). Let Ψ , $y(t; \theta)$, $x(t)$, $v(t)$, \dot{y}_n , \dot{x}_n , \dot{v}_n , and Y be defined as in Definition 11.1 (page 81).

T H M	$ \left. \begin{array}{l} (A). \quad y(t; \theta) \triangleq x(t) + v(t) \quad \text{and} \\ (B). \quad \text{cov}[v(t), v(u)] = \sigma^2 \delta(t - u) \quad \text{and} \\ (C). \quad E[v(t)] = 0 \quad \text{and} \\ (E). \quad x(t) \subseteq \text{span}\Psi \quad \text{and} \\ (E). \quad \langle \psi_n \psi_m \rangle = \bar{\delta}_{mn} \end{array} \right\} \xrightarrow{\text{ADDITIVE WHITE system}} \left. \begin{array}{l} (1). \quad E \dot{v}_n = 0 \quad (\text{ZERO-MEAN}) \\ (2). \quad E(\dot{y}_n(\theta)) = \dot{x}_n(\theta) \\ (3). \quad \text{cov}[\dot{v}_n, \dot{v}_m] = \sigma^2 \bar{\delta}_{nm} \quad (\text{UNCORRELATED}) \\ (4). \quad \text{cov}[\dot{y}_n(\theta), \dot{y}_m \theta] = \sigma^2 \bar{\delta}_{nm} \quad (\text{UNCORRELATED}) \end{array} \right\} $
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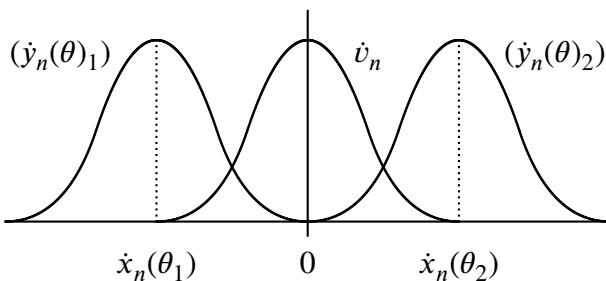
PROOF:

1. Because the noise is *additive* (hypothesis A)...

$$\begin{aligned}
 E \dot{v}_n &= 0 && \text{by additive property and Theorem 11.2 page 86} \\
 (\dot{y}_n(\theta)) &= \dot{x}_n(\theta) + \dot{v}_n && \text{by additive property and Theorem 11.2 page 86} \\
 E(\dot{y}_n | \theta) &= \dot{x}_n(\theta) && \text{by additive property and Theorem 11.2 page 86}
 \end{aligned}$$

2. Proof for (4):

$$\begin{aligned}
 \text{cov}[\dot{y}_n(\theta), \dot{y}_m | \theta] &= E[\dot{y}_n \dot{y}_m | \theta] - [E \dot{y}_n(\theta)][E \dot{y}_m | \theta] \\
 &= E[(\dot{x}_n(\theta) + \dot{v}_n)(\dot{x}_m(\theta) + \dot{v}_m)] - \dot{x}_n(\theta) \dot{x}_m(\theta) \\
 &= E[\dot{x}_n(\theta) \dot{x}_m(\theta) + \dot{x}_n(\theta) \dot{v}_m + \dot{v}_n \dot{x}_m(\theta) + \dot{v}_n \dot{v}_m] - \dot{x}_n(\theta) \dot{x}_m(\theta) \\
 &= \dot{x}_n(\theta) \dot{x}_m(\theta) + \dot{x}_n(\theta) E[\dot{v}_m] + E[\dot{v}_n] \dot{x}_m(\theta) + E[\dot{v}_n \dot{v}_m] - \dot{x}_n(\theta) \dot{x}_m(\theta) \\
 &= 0 + \dot{x}_n(\theta) \cdot 0 + 0 \cdot \dot{x}_m(\theta) + \text{cov}[\dot{v}_n, \dot{v}_m] + [E \dot{v}_n][E \dot{v}_m] \\
 &= \sigma^2 \bar{\delta}_{nm} + 0 \cdot 0 && \text{by Lemma 11.3} \\
 &= \begin{cases} \sigma^2 & \text{for } n = m \\ 0 & \text{for } n \neq m \end{cases}
 \end{aligned}$$

Figure 11.2: Additive white *Gaussian* noise channel statistics

Theorem 11.5 (AWGN projection statistics). *Let Ψ , $y(t; \theta)$, $x(t)$, $v(t)$, \dot{y}_n , \dot{x}_n , \dot{v}_n , and Y be defined as in Definition 11.1 (page 81).*

T H M	$\left. \begin{array}{l} (A). \quad y(t; \theta) \triangleq x(t) + v(t) \text{ and} \\ (B). \quad \text{cov}[v(t), v(u)] = \sigma^2 \delta(t - u) \text{ and} \\ (C). \quad v(t) \sim N(0, \sigma^2) \text{ and} \\ (D). \quad x(t) \subseteq \text{span } \Psi \text{ and} \\ (E). \quad \langle \psi_n \psi_m \rangle = \bar{\delta}_{mn} \end{array} \right\} \Rightarrow \left\{ \begin{array}{ll} (1). & \dot{y}_n(\theta) \sim N(\dot{x}_n(\theta), \sigma^2) & (\text{GAUSSIAN}) \\ (2). & \text{cov}[\dot{y}_n, \dot{y}_m] = \sigma^2 \bar{\delta}_{nm} & (\text{UNCORRELATED}) \\ (3). & P\{\dot{y}_n \wedge \dot{y}_m\} = P\{\dot{y}_n\} P\{\dot{y}_m\} & (\text{INDEPENDENT}) \end{array} \right.$
ADDITIVE WHITE GAUSSIAN system	

PROOF:

1. Proof for (1) follow because the operations are *linear* on processes are *Gaussian* (hypothesis C).

2.

$$\begin{aligned}
 E\dot{v}_n &= 0 && \text{by AWN properties and Theorem 11.4 page 87} \\
 \dot{y}_n &= \dot{x}_n + \dot{v}_n && \text{by AWN properties and Theorem 11.4 page 87} \\
 E\dot{y}_n &= \dot{x}_n && \text{by AWN properties and Theorem 11.4 page 87} \\
 \text{cov}[\dot{y}_n, \dot{y}_m] &= \sigma^2 \bar{\delta}_{mn} && \text{by AWN properties and Theorem 11.4 page 87}
 \end{aligned}$$

3. Because the processes are *Gaussian*, *uncorrelated* implies *independent*.



11.4 ML estimates

The AWGN projection statistics provided by Theorem 11.5 (page 88) help generate the optimal ML-estimates for a number of communication systems. These ML-estimates can be expressed in either of two standard forms:

- ➊ **Spectral decomposition:** The optimal estimate is expressed in terms of *projections* of signals onto orthonormal basis functions.
- ➋ **Matched signal:** The optimal estimate is expressed in terms of the (noisy) received signal correlated with (“matched” with) the (noiseless) transmitted signal.



Theorem 11.6 (page 89) (next) expresses the general optimal *ML estimate* in both of these forms.

Parameter detection is a special case of parameter estimation. In parameter detection, the estimate is a member of a finite set. In parameter estimation, the estimate is a member of an infinite set (Section 11.4 page 88).

Theorem 11.6 (General ML estimation). *Let Ψ , $y(t; \theta)$, $x(t)$, $v(t)$, \dot{y}_n , \dot{x}_n , \dot{v}_n , and Y be defined as in Definition 11.1 (page 81). Let $\hat{\theta}_{\text{ml}}$ be the ML ESTIMATE (Definition 9.1 page 69) of θ .*

THM	$\begin{aligned}\hat{\theta}_{\text{ml}} &= \arg \min_{\hat{\theta}} \left[\sum_{n=1}^N [\dot{y}_n - \dot{x}_n(\hat{\theta})]^2 \right] && (\text{spectral decomposition}) \\ &= \arg \max_{\hat{\theta}} \left[2 \langle y(t; \theta) x(t; \theta) \rangle - \ x(t; \theta)\ ^2 \right] && (\text{matched signal})\end{aligned}$
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PROOF:

$$\begin{aligned}\hat{\theta}_{\text{ml}} &= \arg \max_{\hat{\theta}} P \{ y(t; \theta) | x(t; \theta) \} \\ &= \arg \max_{\hat{\theta}} P \{ \dot{y}_1, \dot{y}_2, \dots, \dot{y}_N | x(t; \theta) \}\end{aligned} \quad \text{by Theorem 11.1 (page 83)}$$

$$\begin{aligned}&= \arg \max_{\hat{\theta}} \prod_{n=1}^N P \{ \dot{y}_n | x(t; \theta) \} \\ &= \arg \max_{\hat{\theta}} \prod_{n=1}^N p[\dot{y}_n | x(t; \theta)] \\ &= \arg \max_{\hat{\theta}} \prod_{n=1}^N \frac{1}{\sqrt{2\pi\sigma^2}} \exp \frac{[\dot{y}_n - \dot{x}_n(\hat{\theta})]^2}{-2\sigma^2}\end{aligned} \quad \text{by Theorem 11.5 (page 88)}$$

$$\begin{aligned}&= \arg \max_{\hat{\theta}} \left(\frac{1}{\sqrt{2\pi\sigma^2}} \right)^N \exp \frac{-1}{2\sigma^2} \sum_{n=1}^N [\dot{y}_n - \dot{x}_n(\hat{\theta})]^2 \\ &= \arg \max_{\hat{\theta}} \left[- \sum_{n=1}^N [\dot{y}_n - \dot{x}_n(\hat{\theta})]^2 \right]\end{aligned}$$

$$= \arg \max_{\hat{\theta}} \left[- \lim_{N \rightarrow \infty} \sum_{n=1}^N [\dot{y}_n - \dot{x}_n(\hat{\theta})]^2 \right] \quad \text{by Theorem 11.1 (page 83)}$$

$$= \arg \max_{\hat{\theta}} [- \|y(t; \theta) - x(t; \theta)\|^2] \quad \text{by Plancheral's formula (Theorem H.9 page 218)}$$

$$= \arg \max_{\hat{\theta}} [- \|y(t; \theta)\|^2 + 2 \mathbf{R}_e \langle y(t; \theta) | x(t; \theta) \rangle - \|x(t; \theta)\|^2]$$

$$= \arg \max_{\hat{\theta}} [2 \langle y(t; \theta) | x(t; \theta) \rangle - \|x(t; \theta)\|^2] \quad \text{because } y(t; \theta) \text{ independent of } \hat{\theta}$$

Theorem 11.7 (ML amplitude estimation). ² Let S be an additive white gaussian noise system.

² Srinath et al. (1996) pages 158–159

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$$\left\{ \begin{array}{l} (A). \quad v(t) \text{ is AWGN} \\ (B). \quad y(t; a) = x(t; a) + v(t) \quad \text{and} \\ (C). \quad x(t; a) \triangleq a\lambda(t). \end{array} \right\} \implies \left\{ \begin{array}{ll} (1). & \hat{a}_{\text{ml}} = \frac{1}{\|\lambda(t)\|^2} \sum_{n=1}^N \dot{y}_n \dot{\lambda}_n \\ (2). & E\hat{a}_{\text{ml}} = a \\ (3). & \text{var } \hat{a}_{\text{ml}} = \frac{\sigma^2}{\|\lambda(t)\|^2} \\ (4). & \text{var } \hat{a}_{\text{ml}} = CR \text{ lower bound} \quad (\text{EFFICIENT}) \end{array} \right\}$$

PROOF:

1. *ML estimate* in “matched signal” form:

$$\begin{aligned} \hat{a}_{\text{ml}} &= \arg \max_a [2 \langle y(t; \theta) | x(t; \theta) \rangle - \|x(t; \phi)\|^2] && \text{by Theorem 11.6 (page 89)} \\ &= \arg \max_a [2 \langle y(t; \theta) | a\lambda(t) \rangle - \|a\lambda(t)\|^2] && \text{by hypothesis} \\ &= \arg_a \left[\frac{\partial}{\partial a} 2a \langle y(t; \theta) | \lambda(t) \rangle - \frac{\partial}{\partial a} a^2 \|\lambda(t)\|^2 = 0 \right] \\ &= \arg_a [2 \langle y(t; \theta) | \lambda(t) \rangle - 2a \|\lambda(t)\|^2 = 0] \\ &= \arg_a [\langle y(t; \theta) | \lambda(t) \rangle = a \|\lambda(t)\|^2] \\ &= \frac{1}{\|\lambda(t)\|^2} \langle y(t; \theta) | \lambda(t) \rangle \end{aligned}$$

2. *ML estimate* in “spectral decomposition” form:

$$\begin{aligned} \hat{a}_{\text{ml}} &= \arg \min_a \left(\sum_{n=1}^N [\dot{y}_n - \dot{x}_n(a)]^2 \right) && \text{by Theorem 11.6 (page 89)} \\ &= \arg_a \left(\frac{\partial}{\partial a} \sum_{n=1}^N [\dot{y}_n - \dot{x}_n(a)]^2 = 0 \right) \\ &= \arg_a \left(2 \sum_{n=1}^N [\dot{y}_n - \dot{x}_n(a)] \frac{\partial}{\partial a} \dot{x}_n(a) = 0 \right) \\ &= \arg_a \left(\sum_{n=1}^N [\dot{y}_n - \langle a\lambda(t) | \psi_n(t) \rangle] \frac{\partial}{\partial a} \langle a\lambda(t) | \psi_n(t) \rangle = 0 \right) \\ &= \arg_a \left(\sum_{n=1}^N [\dot{y}_n - a \langle \lambda(t) | \psi_n(t) \rangle] \frac{\partial}{\partial a} (a \langle \lambda(t) | \psi_n(t) \rangle) = 0 \right) \\ &= \arg_a \left(\sum_{n=1}^N [\dot{y}_n - a\dot{\lambda}_n] \langle \lambda(t) | \psi_n(t) \rangle = 0 \right) \\ &= \arg_a \left(\sum_{n=1}^N [\dot{y}_n - a\dot{\lambda}_n] \dot{\lambda}_n = 0 \right) \\ &= \arg_a \left(\sum_{n=1}^N \dot{y}_n \dot{\lambda}_n = \sum_{n=1}^N a\dot{\lambda}_n^2 \right) \\ &= \left(\frac{1}{\sum_{n=1}^N \dot{\lambda}_n^2} \right) \sum_{n=1}^N \dot{y}_n \dot{\lambda}_n \\ &= \frac{1}{\|\lambda(t)\|^2} \sum_{n=1}^N \dot{y}_n \dot{\lambda}_n \end{aligned}$$



3. Prove that the estimate \hat{a}_{ml} is **unbiased**:

$$\begin{aligned}
 E\hat{a}_{\text{ml}} &= E \frac{1}{\|\lambda(t)\|^2} \int_{t \in \mathbb{R}} y(t; \theta) \lambda(t) dt && \text{by previous result} \\
 &= E \frac{1}{\|\lambda(t)\|^2} \int_{t \in \mathbb{R}} [a\lambda(t) + v(t)] \lambda(t) dt && \text{by hypothesis} \\
 &= \frac{1}{\|\lambda(t)\|^2} \int_{t \in \mathbb{R}} E[a\lambda(t) + v(t)] \lambda(t) dt && \text{by linearity of } \int \cdot dt \text{ and } E \\
 &= \frac{1}{\|\lambda(t)\|^2} a \int_{t \in \mathbb{R}} \lambda^2(t) dt && \text{by } E \text{ operation} \\
 &= \frac{1}{\|\lambda(t)\|^2} a \|\lambda(t)\|^2 && \text{by definition of } \|\cdot\|^2 \\
 &= a
 \end{aligned}$$

4. Compute the variance of \hat{a}_{ml} :

$$\begin{aligned}
 E\hat{a}_{\text{ml}}^2 &= E \left[\frac{1}{\|\lambda(t)\|^2} \int_{t \in \mathbb{R}} y(t; \theta) \lambda(t) dt \right]^2 \\
 &= E \left[\frac{1}{\|\lambda(t)\|^4} \int_{t \in \mathbb{R}} y(t; \theta) \lambda(t) dt \int_v y(v) \lambda(v) dv \right] \\
 &= E \left[\frac{1}{\|\lambda(t)\|^4} \int_{t \in \mathbb{R}} \int_v [a\lambda(t) + v(t)][a\lambda(v) + v(v)] \lambda(t) \lambda(v) dv dt \right] \\
 &= E \left[\frac{1}{\|\lambda(t)\|^4} \int_{t \in \mathbb{R}} \int_v [a^2 \lambda(t) \lambda(v) + a\lambda(t)v(v) + a\lambda(v)v(t) + v(t)v(v)] \lambda(t) \lambda(v) dv dt \right] \\
 &= \left[\frac{1}{\|\lambda(t)\|^4} \int_{t \in \mathbb{R}} \int_v [a^2 \lambda(t) \lambda(v) + 0 + 0 + \sigma^2 \delta(t - v)] \lambda(t) \lambda(v) dv dt \right] \\
 &= \frac{1}{\|\lambda(t)\|^4} \int_{t \in \mathbb{R}} \int_v a^2 \lambda^2(t) \lambda^2(v) dv dt + \frac{1}{\|\lambda(t)\|^4} \int_{t \in \mathbb{R}} \int_v \sigma^2 \delta(t - v) \lambda(t) \lambda(v) dv dt \\
 &= \frac{1}{\|\lambda(t)\|^4} a^2 \int_{t \in \mathbb{R}} \lambda^2(t) dt \int_v \lambda^2(v) dv + \frac{1}{\|\lambda(t)\|^4} \sigma^2 \int_{t \in \mathbb{R}} \lambda^2(t) dt \\
 &= a^2 \frac{1}{\|\lambda(t)\|^4} \|\lambda(t)\|^2 \|\lambda(v)\|^2 + \frac{1}{\|\lambda(t)\|^4} \sigma^2 \|\lambda(t)\|^2 \\
 &= a^2 + \frac{\sigma^2}{\|\lambda(t)\|^2}
 \end{aligned}$$

$$\begin{aligned}
 \text{var } \hat{a}_{\text{ml}} &= E\hat{a}_{\text{ml}}^2 - (E\hat{a}_{\text{ml}})^2 \\
 &= \left(a^2 + \frac{\sigma^2}{\|\lambda(t)\|^2} \right) - \left(a^2 \right) \\
 &= \frac{\sigma^2}{\|\lambda(t)\|^2}
 \end{aligned}$$

5. Compute the Cramér-Rao Bound:

$$\begin{aligned}
 p[y(t; \theta) | x(t; a)] &= p[\dot{y}_1, \dot{y}_2, \dots, \dot{y}_N | x(t; a)] \\
 &= \prod_{n=1}^N \frac{1}{\sqrt{2\pi\sigma^2}} \exp \frac{(\dot{y}_n - a\dot{\lambda}_n)^2}{-2\sigma^2} \\
 &= \left(\frac{1}{\sqrt{2\pi\sigma^2}} \right)^N \exp \frac{1}{-2\sigma^2} \sum_{n=1}^N (\dot{y}_n - a\dot{\lambda}_n)^2
 \end{aligned}$$

$$\begin{aligned}
\frac{\partial}{\partial a} \ln p[y(t; \theta) | x(t; a)] &= \frac{\partial}{\partial a} \ln \left(\frac{1}{\sqrt{2\pi\sigma^2}} \right)^N \exp \frac{1}{-2\sigma^2} \sum_{n=1}^N (\dot{y}_n - a\dot{\lambda}_n)^2 \\
&= \frac{\partial}{\partial a} \ln \left(\frac{1}{\sqrt{2\pi\sigma^2}} \right)^N + \frac{\partial}{\partial a} \ln \exp \frac{1}{-2\sigma^2} \sum_{n=1}^N (\dot{y}_n - a\dot{\lambda}_n)^2 \\
&= \frac{\partial}{\partial a} \left[\frac{1}{-2\sigma^2} \sum_{n=1}^N (\dot{y}_n - a\dot{\lambda}_n)^2 \right] \\
&= \frac{1}{-2\sigma^2} \sum_{n=1}^N 2(\dot{y}_n - a\dot{\lambda}_n)(-\dot{\lambda}_n) \\
&= \frac{1}{\sigma^2} \sum_{n=1}^N \dot{\lambda}_n (\dot{y}_n - a\dot{\lambda}_n)
\end{aligned}$$

$$\begin{aligned}
\frac{\partial^2}{\partial a^2} \ln p[y(t; \theta) | x(t; a)] &= \frac{\partial}{\partial a} \frac{\partial}{\partial a} \ln p[y(t; \theta) | x(t; a)] \\
&= \frac{\partial}{\partial a} \frac{1}{\sigma^2} \sum_{n=1}^N \dot{\lambda}_n (\dot{y}_n - a\dot{\lambda}_n) \\
&= \frac{1}{\sigma^2} \sum_{n=1}^N \dot{\lambda}_n (-\dot{\lambda}_n) \\
&= \frac{-1}{\sigma^2} \sum_{n=1}^N \dot{\lambda}_n^2 \\
&= \frac{-\|\lambda(t)\|^2}{\sigma^2}
\end{aligned}$$

$$\begin{aligned}
\text{var } \hat{a}_{\text{ml}} &\triangleq E[\hat{a}_{\text{ml}} - E\hat{a}_{\text{ml}}]^2 \\
&= E[\hat{a}_{\text{ml}} - a]^2 \\
&\geq \frac{-1}{E\left(\frac{\partial^2}{\partial a^2} \ln p[y(t; \theta) | x(t; a)]\right)} \\
&= \frac{-1}{E\left(\frac{-\|\lambda(t)\|^2}{\sigma^2}\right)} \\
&= \frac{\sigma^2}{\|\lambda(t)\|^2} \quad (\text{Cramér-Rao lower bound of the variance})
\end{aligned}$$

6. Proof that \hat{a}_{ml} is an *efficient* estimate:

An estimate is *efficient* if $\text{var } \hat{a}_{\text{ml}} = \text{CR lower bound}$. We have already proven this, so \hat{a}_{ml} is an *efficient* estimate.

Also, even without explicitly computing the variance of \hat{a}_{ml} , the variance equals the *Cramér-Rao lower bound* (and hence \hat{a}_{ml} is an *efficient* estimate) if and only if



$$\begin{aligned}
 \hat{a}_{\text{ml}} - a &= \left(\frac{-1}{\mathbb{E} \left[\frac{\partial^2}{\partial a^2} \ln p [y(t; \theta) | x(t; a)] \right]} \right) \left(\frac{\partial}{\partial a} \ln p [y(t; \theta) | x(t; a)] \right) \\
 &\left(\frac{-1}{\mathbb{E} \left(\frac{\partial^2}{\partial a^2} \ln p [y(t; \theta) | x(t; a)] \right)} \right) \left(\frac{\partial}{\partial a} \ln p [y(t; \theta) | x(t; a)] \right) = \left(\frac{\sigma^2}{\|\lambda(t)\|^2} \right) \left(\frac{1}{\sigma^2} \sum_{n=1}^N \dot{\lambda}(\dot{y} - a\dot{\lambda}) \right) \\
 &= \frac{1}{\|\lambda(t)\|^2} \sum_{n=1}^N \dot{\lambda}\dot{y} - \frac{1}{\|\lambda(t)\|^2} \sum_{n=1}^N \dot{\lambda}^2 \\
 &= \hat{a}_{\text{ml}} - a
 \end{aligned}$$

⇒

Theorem 11.8 (ML phase estimation). ³

T H M	$\left\{ \begin{array}{ll} (A). & v(t) \text{ is AWGN} \\ (B). & y(t; \phi) = x(t; \phi) + v(t) \\ (C). & x(t; \phi) \triangleq A \cos(2\pi f_c t + \phi) \end{array} \right. \text{ and } \right\} \Rightarrow \left\{ \hat{\phi}_{\text{ml}} = -\text{atan} \left(\frac{\langle y(t; \theta) \sin(2\pi f_c t) \rangle}{\langle y(t; \theta) \cos(2\pi f_c t) \rangle} \right) \right\}$
----------------------------------	--

PROOF:

$$\begin{aligned}
 \hat{\phi}_{\text{ml}} &= \arg \max_{\phi} [2 \langle y(t; \phi) | x(t; \phi) \rangle - \|x(t; \phi)\|^2] && \text{by Theorem 11.6 (page 89)} \\
 &= \arg \max_{\phi} [2 \langle y(t; \phi) | x(t; \phi) \rangle] && \text{because } \|x(t; \phi)\| \text{ does not depend on } \phi \\
 &= \arg_{\phi} \left[\frac{\partial}{\partial \phi} \langle y(t; \phi) | x(t; \phi) \rangle = 0 \right] \\
 &= \arg_{\phi} \left[\left\langle y(t; \phi) | \frac{\partial}{\partial \phi} x(t; \phi) \right\rangle = 0 \right] && \text{because } \langle \Delta | \nabla \rangle \text{ is linear} \\
 &= \arg_{\phi} \left[\left\langle y(t; \phi) | \frac{\partial}{\partial \phi} A \cos(2\pi f_c t + \phi) \right\rangle = 0 \right] && \text{by definition of } x(t; \phi) \\
 &= \arg_{\phi} [\langle y(t; \phi) | -A \sin(2\pi f_c t + \phi) \rangle = 0] && \text{because } \frac{\partial}{\partial \phi} \cos(x) = -\sin(x) \\
 &= \arg_{\phi} [-A \langle y(t; \phi) | \cos(2\pi f_c t) \sin\phi + \sin(2\pi f_c t) \cos\phi \rangle = 0] && \text{by double angle formulas} \\
 &= \arg_{\phi} [\sin\phi \langle y(t; \phi) | \cos(2\pi f_c t) \rangle = -\cos\phi \langle y(t; \phi) | \sin(2\pi f_c t) \rangle] \\
 &= \arg_{\phi} \left[\frac{\sin\phi}{\cos\phi} = -\frac{\langle y(t; \phi) | \sin(2\pi f_c t) \rangle}{\langle y(t; \phi) | \cos(2\pi f_c t) \rangle} \right] \\
 &= \arg_{\phi} \left[\tan\phi = -\frac{\langle y(t; \phi) | \sin(2\pi f_c t) \rangle}{\langle y(t; \phi) | \cos(2\pi f_c t) \rangle} \right] \\
 &= -\text{atan} \left(\frac{\langle y(t; \phi) | \sin(2\pi f_c t) \rangle}{\langle y(t; \phi) | \cos(2\pi f_c t) \rangle} \right)
 \end{aligned}$$

⇒

Theorem 11.9 (ML estimation of a function of a parameter). ⁴ Let S be an additive white gaussian noise system such that $y(t; \theta) = x(t; \theta) + v(t)$
 $x(t; \theta) = g(\theta)$

and g is ONE-TO-ONE AND ONTO (INVERTIBLE).

³ Srinath et al. (1996) pages 159–160

⁴ Srinath et al. (1996) pages 142–143

THM

Then the optimal ML-estimate of parameter θ is

$$\hat{\theta}_{\text{ml}} = g^{-1} \left(\frac{1}{N} \sum_{n=1}^N \dot{y}_n \right).$$

If an ML ESTIMATE $\hat{\theta}_{\text{ml}}$ is unbiased ($E\hat{\theta}_{\text{ml}} = \theta$) then

$$\text{var } \hat{\theta}_{\text{ml}} \geq \frac{\sigma^2}{N} \frac{1}{\left[\frac{\partial g(\theta)}{\partial \theta} \right]^2}.$$

If $g(\theta) = \theta$ then $\hat{\theta}_{\text{ml}}$ is an **efficient** estimate such that $\text{var } \hat{\theta}_{\text{ml}} = \frac{\sigma^2}{N}$.

PROOF:

$$\begin{aligned}
 \hat{\theta}_{\text{ml}} &= \arg \min_{\theta} \left[\sum_{n=1}^N [\dot{y}_n - g(\theta)]^2 \right] && \text{by Theorem 11.6 page 89} \\
 &= \arg_{\theta} \left[\frac{\partial}{\partial \theta} \sum_{n=1}^N [\dot{y}_n - g(\theta)]^2 = 0 \right] && \text{because form is quadratic} \\
 &= \arg_{\theta} \left[2 \sum_{n=1}^N [\dot{y}_n - g(\theta)] \frac{\partial}{\partial \theta} g(\theta) = 0 \right] \\
 &= \arg_{\theta} \left[2 \sum_{n=1}^N [\dot{y}_n - g(\theta)] = 0 \right] \\
 &= \arg_{\theta} \left[\sum_{n=1}^N \dot{y}_n = N g(\theta) \right] \\
 &= \arg_{\theta} \left[g(\theta) = \frac{1}{N} \sum_{n=1}^N \dot{y}_n \right] \\
 &= \arg_{\theta} \left[\theta = g^{-1} \left(\frac{1}{N} \sum_{n=1}^N \dot{y}_n \right) \right] \\
 &= g^{-1} \left(\frac{1}{N} \sum_{n=1}^N \dot{y}_n \right)
 \end{aligned}$$

If $\hat{\theta}_{\text{ml}}$ is unbiased ($E\hat{\theta}_{\text{ml}} = \theta$), we can use the *Cramér-Rao bound* to find a lower bound on the variance:

$$\begin{aligned}
 \text{var } \hat{\theta}_{\text{ml}} &\triangleq E[\hat{\theta}_{\text{ml}} - E\hat{\theta}_{\text{ml}}]^2 \\
 &= E[\hat{\theta}_{\text{ml}} - \theta]^2 \\
 &\geq \frac{-1}{E \left(\frac{\partial^2}{\partial \theta^2} \ln p[y(t; \theta) | x(t; \theta)] \right)} && \text{by Cramér-Rao Inequality} \\
 &= \frac{-1}{E \left(\frac{\partial^2}{\partial \theta^2} \ln p[\dot{y}_1, \dot{y}_2, \dots, \dot{y}_N | x(t; \theta)] \right)} && \text{by Sufficient Statistic Theorem} \\
 &&& (\text{Theorem 11.1 page 83}) \\
 &= \frac{-1}{E \left(\frac{\partial^2}{\partial \theta^2} \ln \left[\left(\frac{1}{\sqrt{2\pi\sigma^2}} \right)^N \exp \left(\frac{-1}{2\sigma^2} \sum_{n=1}^N [\dot{y}_n - g(\theta)]^2 \right) \right] \right)} && \text{by AWGN hypothesis} \\
 &&& \text{and Theorem 11.5 page 88}
 \end{aligned}$$



$$\begin{aligned}
&= \frac{-1}{\mathbb{E}\left(\frac{\partial^2}{\partial\theta^2} \ln \left[\left(\frac{1}{\sqrt{2\pi\sigma^2}} \right)^N \right] + \frac{\partial^2}{\partial\theta^2} \ln \left[\exp \frac{-1}{2\sigma^2} \sum_{n=1}^N [\dot{y}_n - g(\theta)]^2 \right] \right)} \\
&= \frac{-1}{\mathbb{E}\left(\frac{\partial^2}{\partial\theta^2} \left(\frac{-1}{2\sigma^2} \sum_{n=1}^N [\dot{y}_n - g(\theta)]^2 \right) \right)} \\
&= \frac{2\sigma^2}{\mathbb{E}\left(\frac{\partial}{\partial\theta} \frac{\partial}{\partial\theta} \sum_{n=1}^N [\dot{y}_n - g(\theta)]^2\right)} \\
&= \frac{2\sigma^2}{\mathbb{E}\left(-2 \frac{\partial}{\partial\theta} \frac{\partial g(\theta)}{\partial\theta} \sum_{n=1}^N [\dot{y}_n - g(\theta)]\right)} && \text{by } \textit{Chain Rule} \\
&= \frac{-\sigma^2}{\mathbb{E}\left(\frac{\partial g^2(\theta)}{\partial\theta^2} \sum_{n=1}^N [\dot{y}_n - g(\theta)] + \frac{\partial g(\theta)}{\partial\theta} \frac{\partial}{\partial\theta} \sum_{n=1}^N [\dot{y}_n - g(\theta)]\right)} && \text{by } \textit{Product Rule} \\
&= \frac{-\sigma^2}{\mathbb{E}\left(\frac{\partial g^2(\theta)}{\partial\theta^2} \sum_{n=1}^N [\dot{y}_n - g(\theta)] - N \frac{\partial g(\theta)}{\partial\theta} \frac{\partial g(\theta)}{\partial\theta}\right)} \\
&= \frac{-\sigma^2}{\frac{\partial g^2(\theta)}{\partial\theta^2} \sum_{n=1}^N \mathbb{E}[\dot{y}_n - g(\theta)] - N \frac{\partial g(\theta)}{\partial\theta} \frac{\partial g(\theta)}{\partial\theta}} \\
&= \frac{-\sigma^2}{-N \frac{\partial g(\theta)}{\partial\theta} \frac{\partial g(\theta)}{\partial\theta}} && \text{because derivative of constant} = 0 \\
&= \frac{\sigma^2}{N \left[\frac{\partial g(\theta)}{\partial\theta} \right]^2}
\end{aligned}$$

The inequality becomes equality (an *efficient* estimate) if and only if

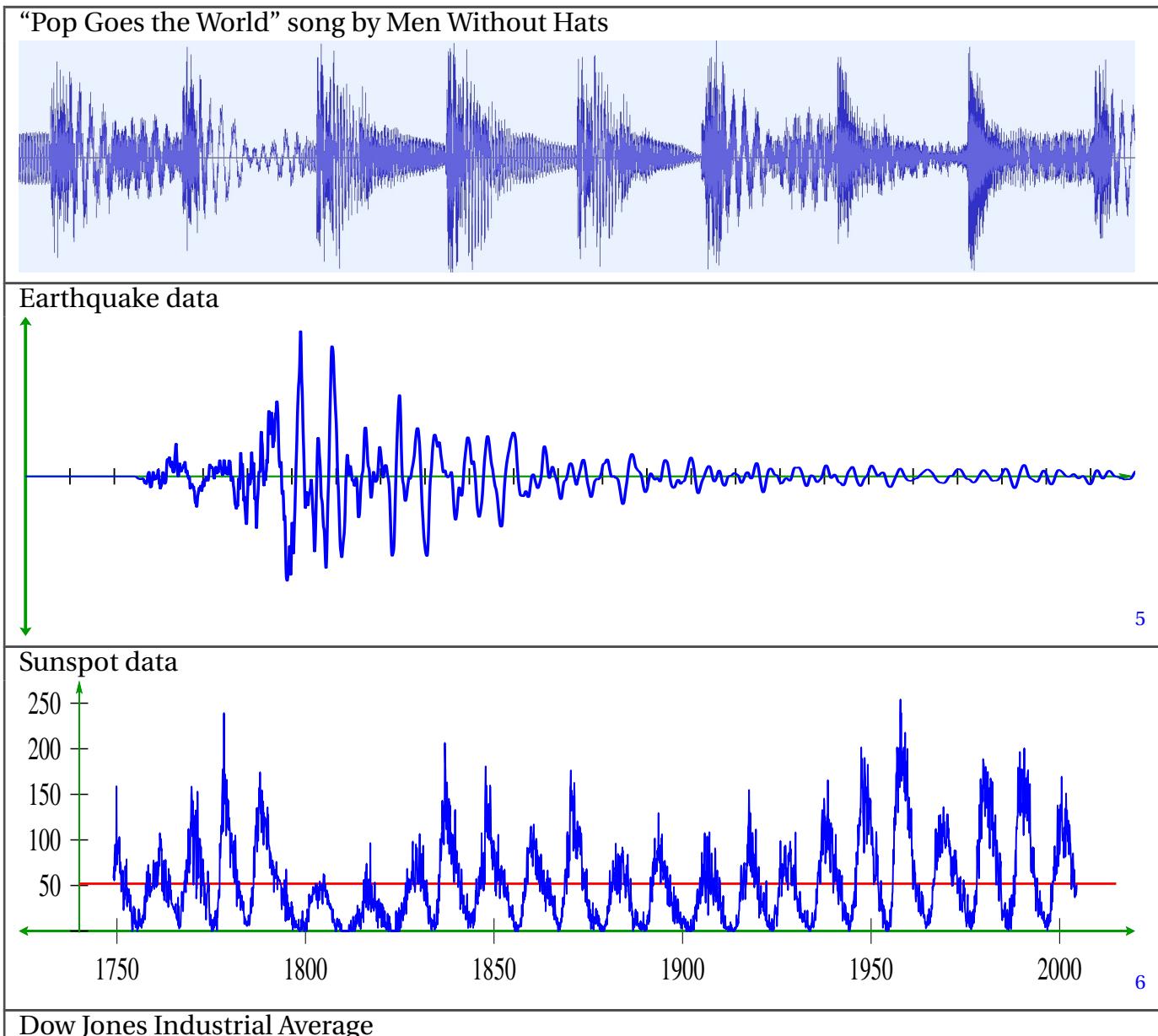
$$\hat{\theta}_{\text{ml}} - \theta = \left(\frac{-1}{\mathbb{E}\left(\frac{\partial^2}{\partial\theta^2} \ln p[y(t; \theta) | x(t; \theta)]\right)} \right) \left(\frac{\partial}{\partial\theta} \ln p[y(t; \theta) | x(t; \theta)] \right).$$

$$\begin{aligned}
&\left(\frac{-1}{\mathbb{E}\left(\frac{\partial^2}{\partial\theta^2} \ln p[y(t; \theta) | x(t; \theta)]\right)} \right) \left(\frac{\partial}{\partial\theta} \ln p[y(t; \theta) | x(t; \theta)] \right) = \left(\frac{\sigma^2}{N} \frac{1}{\left[\frac{\partial g(\theta)}{\partial\theta} \right]^2} \right) \left(\frac{-1}{2\sigma^2} \left(2 \frac{\partial g(\theta)}{\partial\theta} \sum_{n=1}^N [\dot{y}_n - g(\theta)] \right) \right) \\
&= -\frac{1}{N} \frac{1}{\frac{\partial g(\theta)}{\partial\theta}} \left(\sum_{n=1}^N [\dot{y}_n - g(\theta)] \right) \\
&= -\frac{1}{\frac{\partial g(\theta)}{\partial\theta}} \left(\frac{1}{N} \sum_{n=1}^N \dot{y}_n - g(\theta) \right) \\
&= -\frac{1}{\frac{\partial g(\theta)}{\partial\theta}} (\hat{\theta}_{\text{ml}} - g(\theta))
\end{aligned}$$

$$= -(\hat{\theta}_{\text{ml}} - \theta)$$

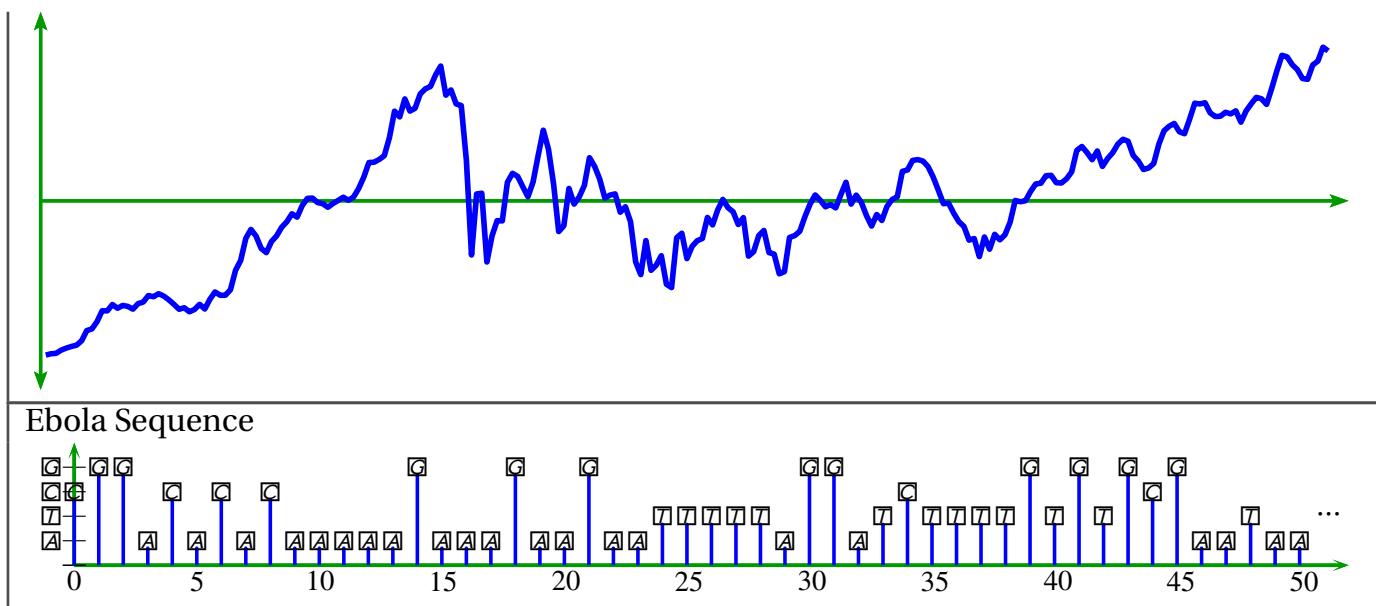
⇒

11.5 Example data



⁵https://www.iris.edu/wilber3/find_stations/10953070

⁶<https://d32ogoqmya1dw8.cloudfront.net/files/introgeo/teachingwdata/examples/GreenwichSSNvstime.txt>



11.6 Matched Filter Algorithm

Let S be the set of transmitted waveforms and Y be a set of orthonormal basis functions that span S . *Signal matching* computes the innerproducts of a received signal $y(t; \theta)$ with each signal from S . *Orthonormal decomposition* computes the innerproducts of $y(t; \theta)$ with each signal from the set Y .

In the case where $|S|$ is large, often $|Y| \ll |S|$ making orthonormal decomposition much easier to implement. For example, in a QAM-64 modulation system, signal matching requires $|S| = 64$ innerproduct calculations, while orthonormal decomposition only requires $|Y| = 2$ innerproduct calculations because all 64 signals in S can be spanned by just 2 orthonormal basis functions.

Maximizing SNR. Theorem 11.1 (page 83) shows that the innerproducts of $y(t; \theta)$ with basis functions of Y is *sufficient* for optimal detection. Theorem 11.10 (page 97) (next) shows that a receiver can maximize the SNR of a received signal when signal matching is used.

Theorem 11.10. Let $x(t)$ be a transmitted signal, $v(t)$ noise, and $y(t; \theta)$ the received signal in an AWGN channel. Let the SIGNAL TO NOISE RATIO SNR be defined as

$$\text{SNR}[y(t; \theta)] \triangleq \frac{|\langle x(t) | x(t) \rangle|^2}{\mathbb{E} [|\langle v(t) | x(t) \rangle|^2]}.$$

T H M $\text{SNR}[y(t; \theta)] \leq \frac{2 \|x(t)\|^2}{N_o}$ and is maximized (equality) when $x(t) = ax(t)$, where $a \in \mathbb{R}$.

PROOF:

$$\begin{aligned} \text{SNR}[y(t; \theta)] &\triangleq \frac{|\langle x(t) | x(t) \rangle|^2}{\mathbb{E} [|\langle v(t) | x(t) \rangle|^2]} \\ &= \frac{|\langle x(t) | f(t) \rangle|^2}{\mathbb{E} \left[\left[\int_{t \in \mathbb{R}} v(t)x^*(t) dt \right] \left[\int_{\hat{\theta}} n(\hat{\theta})f^*(\hat{\theta}) du \right]^* \right]} \\ &= \frac{|\langle x(t) | x(t) \rangle|^2}{\mathbb{E} \left[\int_{t \in \mathbb{R}} \int_{\hat{\theta}} v(t)n^*(\hat{\theta})x^*(t)x(\hat{\theta}) dt du \right]} \end{aligned}$$

$$\begin{aligned}
&= \frac{|\langle \mathbf{x}(t) | f(t) \rangle|^2}{\int_{t \in \mathbb{R}} \int_{\hat{\theta}} \mathbb{E}[\mathbf{v}(t)n^*(\hat{\theta})] \mathbf{x}^*(t)\mathbf{x}(\hat{\theta}) dt du} \\
&= \frac{|\langle \mathbf{x}(t) | \mathbf{x}(t) \rangle|^2}{\int_{t \in \mathbb{R}} \int_{\hat{\theta}} \frac{1}{2} N_o \delta(t - \hat{\theta}) \mathbf{x}^*(t)\mathbf{x}(\hat{\theta}) dt du} \\
&= \frac{|\langle \mathbf{x}(t) | \mathbf{x}(t) \rangle|^2}{\frac{1}{2} N_o \int_{t \in \mathbb{R}} \mathbf{x}^*(t)\mathbf{x}(t) dt} \\
&= \frac{|\langle \mathbf{x}(t) | \mathbf{x}(t) \rangle|^2}{\frac{1}{2} N_o \|\mathbf{x}(t)\|^2} \\
&\leq \frac{\|\mathbf{x}(t)\| \|\mathbf{x}(t)\|^2}{\frac{1}{2} N_o \|\mathbf{x}(t)\|^2} \quad \text{by Cauchy-Schwarz Inequality (Theorem K.2 page 256)} \\
&= \frac{2 \|\mathbf{x}(t)\|^2}{N_o}
\end{aligned}$$

The Cauchy-Schwarz Inequality becomes an equality (SNR is maximized) when $\mathbf{x}(t) = a\mathbf{x}(t)$. \Rightarrow

Implementation. The innerproduct operations can be implemented using either

1. a correlator or
2. a matched filter.

A correlator is simply an integrator of the form $\langle \mathbf{y}(t; \theta) | f(t) \rangle = \int_0^T \mathbf{y}(t; \theta) f(t) dt$.

A matched filter introduces a function $h(t)$ such that $h(t) = \mathbf{x}(T - t)$ (which implies $\mathbf{x}(t) = h(T - t)$) giving

$$\underbrace{\langle \mathbf{y}(t; \theta) | \mathbf{x}(t) \rangle}_{\text{correlator}} = \int_0^T \mathbf{y}(t; \theta) \mathbf{x}(t) dt = \underbrace{\int_0^\infty \mathbf{x}(\tau) h(t - \tau) d\tau \Big|_{t=T}}_{\text{matched filter}} = \mathbf{x}(t) \star h(t)|_{t=T}.$$

This shows that $h(t)$ is the impulse response of a filter operation sampled at time τ . By Theorem 11.10 (page 97), the optimal impulse response is $h(\tau - t) = f(t) = \mathbf{x}(t)$. That is, the optimal $h(t)$ is just a “flipped” and shifted version of $\mathbf{x}(t)$.

11.7 Colored noise

This chapter presented several theorems whose results depended on the noise being white. However if the noise is **colored**, then these results are invalid. But there is still hope for colored noise. Processing colored signals can be accomplished using two techniques:

1. Karhunen-Loëve basis functions (Section 4.1 page 21)
2. whitening filter ⁷

⁷ Continuous data whitening: Section 7.3 page 52
Discrete data whitening: Section 6.4 page 42



Karhunen-Loëve. If the noise is *white*, the set $\{\langle y(t; \theta) | \psi_n(t) \rangle \mid n = 1, 2, \dots, N\}$ is a *sufficient statistic* regardless of which set $\{\psi_n(t)\}$ of orthonormal basis functions are used. If the noise is *colored*, and if $\{\psi_n(t)\}$ satisfy the Karhunen-Loëve criterion

$$\int_{t_2} R_{xx}(t, u) \psi_n(u) du = \lambda_n \psi_n(t)$$

then the set $\{\langle y(t; \theta) | \psi_n(t) \rangle\}$ is still a *sufficient statistic*.

Whitening filter. The whitening filter makes the received signal $y(t; \theta)$ statistically white (uncorrelated in time). In this case, any orthonormal basis set can be used to generate sufficient statistics.

Wavelets. Wavelets have the property that they tend to whiten data. For more information, see [Walter and Shen \(2001\) pages 329–350](#) (“Chapter 14 Orthogonal Systems and Stochastic Processes”), [Mallat \(1999\)](#) (ISBN:9780124666061), [Johnstone and Silverman \(1997\)](#), [Wornell and Oppenheim \(1992\)](#), and [Vidakovic \(1999\) pages 10–14](#) (“Example 1.2.5 Wavelets whiten data”) (first four references cited by B. Vidakovic).

CHAPTER 12

BAYESIAN NETWORK ALGORITHMS WHEN JOINT-PDF MODEL IS KNOWN

12.1 Sequential decoding

It has been shown that the Viterbi algorithm (trellis) produces an optimal estimate in the maximal likelihood (ML) sense. A Verterbi trellis is shown in Figure 12.1 (page 101).

12.2 References

1. [Ben-Gal \(2008\) \(ISBN:9780470018613\)](#): Introduction to Bayesian Networks

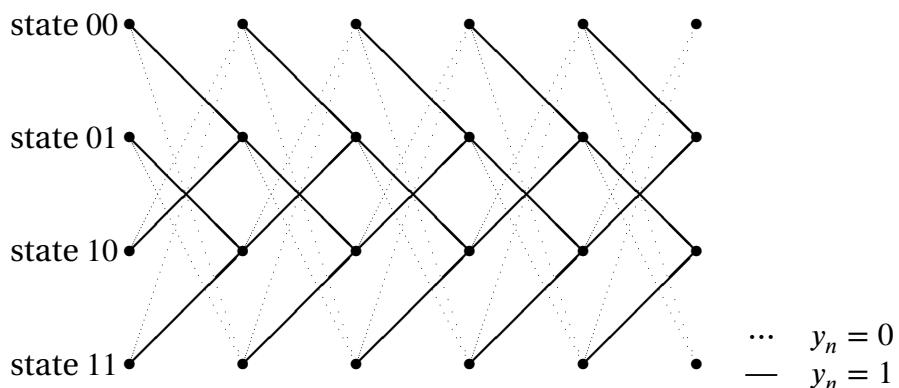


Figure 12.1: Viterbi Algorithm trellis

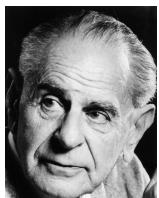
2.  [Pourret et al. \(2008\)](#) (ISBN:9780470994542): A number of real-life examples including
 -  Chapter 2: “Medical diagnosis”
 -  Chapter 4: “Complex genetic models”
 -  Chapter 5: “Crime risk factors analysis”
 -  Chapter 7: “Inference problems in forensic science”
 -  Chapter 12: “An information retrieval system”
 -  Chapter 14: “Terrorism risk management”
 -  Chapter 20: “Risk management in robotics”
 -  Chapter 21: “Enhancing Human Cognition”
 -  Section 22.1: “An artificial intelligence perspective”
 -  Section 22.2: “A rational approach of knowledge”
3.  [Darwiche \(2009\)](#) (ISBN:9780521884389)
 -  Chapter 17: “Learning: The Maximum Likelihood Approach”
 -  Chapter 18: “Learning: The Bayesian Approach”
4.  [Fenton and Neil \(2018\)](#) (ISBN:9781351978965): Risk assessment using Bayesian Networks
5.  [Jensen \(2013\)](#) (ISBN:9781475735024): Relationship between Decision Graphs and Bayesian Networks
6.  [Chapmann \(2017\)](#) (ISBN:9781978304871): HMM and Bayesian Networks
7.  [Fano \(1963\)](#)

Part IV

System Estimation / Modeling

CHAPTER 13

TRANSFER FUNCTION ESTIMATION



“I can therefore gladly admit that falsificationists like myself much prefer an attempt to solve an interesting problem by a bold conjecture, even (and especially) if it so turns out to be false, to any recital of a sequence of irrelevant truisms. We prefer this because we believe that this is the way in which we can learn from our mistakes and that in finding that our conjecture was false we shall have learned much about the truth, and shall have got nearer to the truth.”

Karl R. Popper (1902–1994)¹

13.1 Estimation techniques

Let \mathbf{S} be a system with *impulse response* $h(n)$ with *DTFT* $\tilde{H}(\omega)$, input $x(n)$, and output $y(n)$. Often in the field of “digital signal processing” (DSP), \mathbf{S} is a “filter” with known $h(n)$ and $\tilde{H}(\omega)$ because the filter \mathbf{S} was designed by a designer who had direct control over $h(n)$.

However in many other practical situations, \mathbf{S} is some other system for which $h(n)$ and $\tilde{H}(\omega)$ are *not* known...but which we may want to *estimate*. Examples of such \mathbf{S} is a device on an industrial shaker table, a communication channel, or the entire earth.

Determining $h(n)$ and/or $\tilde{H}(\omega)$ is part of an operation called “*system identification*”. Determining $\tilde{H}(\omega)$ in particular is referred to as “*Frequency Response Identification*”² or as “*Frequency Response Function*” (“*FRF*”) estimation.³ *FRF* estimation is a challenging problem and one that many have devoted much effort to. This chapter describes some of that effort.

In the early days, people used a rather obvious technique for determining $\tilde{H}(\omega)$ —the humble *sine sweep*. That is, they drove the input with a sine wave with slowly increasing (or decreasing) frequency while measuring the resulting output. This technique, although effective, was “very slow”.⁴

¹ quote: [Popper \(1962\)](#), page 231, [Popper \(1963\)](#) page 313

image: https://en.wikipedia.org/wiki/File:Karl_Popper.jpg, “no known copyright restrictions”

² [Shin and Hammond \(2008\)](#) page 292

³ [Cobb \(1988\)](#) page 1 (FRF “measurement”)

⁴ [Leuridan et al. \(1986\)](#) 911 “Stepped Sine Testing”, [Cobb \(1988\)](#) page 1 (Chapter 1—Introduction), [Ewins](#)

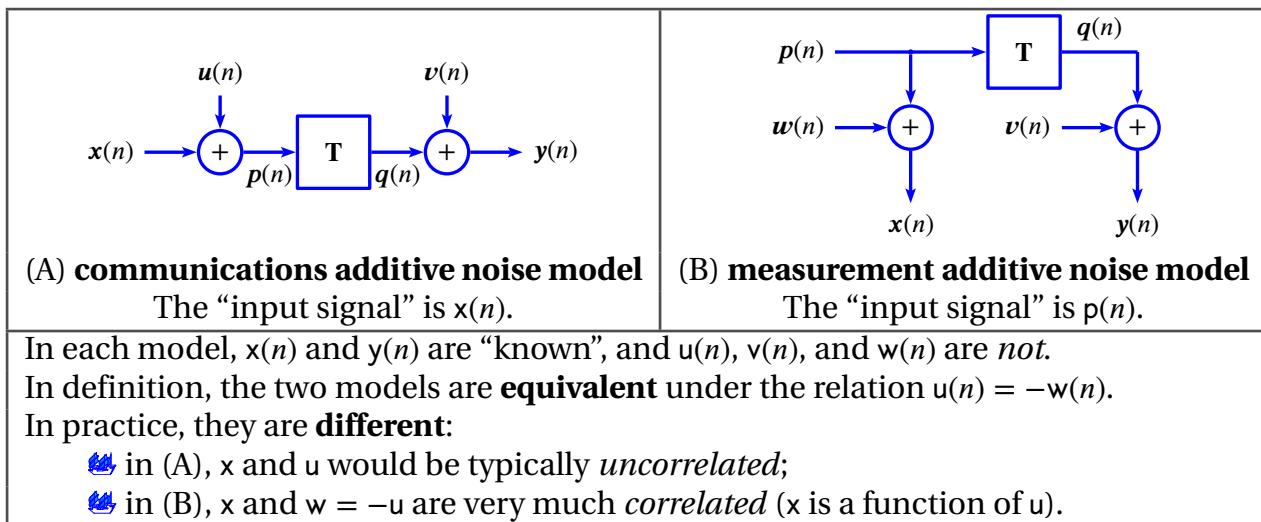


Figure 13.1: Additive noise systems with *linear/non-linear* operator \mathbf{T}

And there is another problem here—we don't always have control over the input signal. Examples of this include earthquake and volcanic activity analysis.

An alternative to the sine-sweep input is *random sequence* input. All the techniques that follow in this chapter are of this type. A problem with using random sequences directly for estimating $\hat{H}(\omega)$ is that the estimate $\hat{H}(\omega)$ is itself also random. This is not what we want. We want an estimate that we can actually write down on paper or at least plot on paper.

A solution to this is to not use the random sequences directly to estimate $\hat{H}(\omega)$, but instead to first use the *expectation* operator E (Definition 1.1 page 3). The expectation operator takes a quantity X that is inherently “random” (with some probability distribution $p(x)$) and turns it into a deterministic “constant” EX .

The operator E is also used by the spectral density functions $\tilde{S}_{xx}(\omega)$ and $\tilde{S}_{xy}(\omega)$ (Definition 7.3 page 48). And $\tilde{S}_{xx}(\omega)$ and $\tilde{S}_{xy}(\omega)$ are what are typically used to calculate an estimate $\hat{H}(\omega)$.

13.2 Additive noise system models

Consider the additive noise systems illustrated in Figure 14.1 (page 131).

- The illustration on the left is suitable for modeling a communications system where x is the transmitted signal, y is the received signal, u and v are thermal noise, and the “transfer function” H is the communications channel (air, water, wires, etc.) that one wishes to estimate.
- The illustration on the right is suitable for modeling a testing system where p is an input test signal (from an industrial shaker or from a naturally occurring signal originating from geophysical activity), w is measurement noise, x is the measured input contaminated by noise, and H is the device under test (a piece of equipment, a building, or the entire earth).

Note that the two models are an equivalent system S under the relation $u = -w$. But although one might expect such a sign difference to wreak mathematical havoc in resulting equations, this is

(1986) pages 125–140 {3.7 USE OF DIFFERENT EXCITATION TYPES}



simply not the case here because

$$\tilde{S}_{ww} = \tilde{\mathbf{F}}\mathbf{E}[w(m)w * (0)] = \tilde{\mathbf{F}}\mathbf{E}[(-u(m))(-u^*(0))] = \tilde{\mathbf{F}}\mathbf{E}[(u(m))(u^*(0))] = \tilde{S}_{uu}$$

So the sign difference is not that big of a difference after all. But there are some key differences in practice:

- In the communications model (on the left), the “input signal” is $x(n)$ and the frequency-domain input *signal-to-noise ratio (SNR)* is $\tilde{S}_{xx}(\omega)/\tilde{S}_{uu}(\omega)$. In the measurement model (on the right), the “input signal” is $p(n)$ and the frequency-domain input *signal-to-noise ratio (SNR)* is $\tilde{S}_{pp}(\omega)/\tilde{S}_{ww}(\omega) = \tilde{S}_{pp}(\omega)/\tilde{S}_{uu}(\omega)$.
- On the left, x and u would be typically *uncorrelated*; on the right, x and $w = -u$ are very much *correlated* (x is a function of u).

13.3 Transfer function estimate definitions and interpretation

As a first attempt at estimating the transfer function \mathbf{H} of \mathbf{S} , or at least the magnitude squared of \mathbf{H} , we might assume \mathbf{H} to be *LTI*, take a cue from the relation $\tilde{S}_{yy} = \tilde{S}_{xx}|\tilde{\mathbf{H}}|^2$ of Corollary 6.3 (page 41), and arrive at a function called “*transmissibility*” (next definition).

Definition 13.1. ⁵ Let \mathbf{S} be a system with input $x(n)$ and output $y(n)$.

D E F

The **transmissibility** function $\tilde{T}_{xy}(\omega)$ is defined as

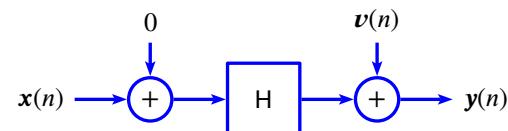
$$\tilde{T}_{xy}(\omega) \triangleq \sqrt{\frac{\tilde{S}_{yy}(\omega)}{\tilde{S}_{xx}(\omega)}}$$

Transmissibility is in essence the ratio of “*spectral power*” (Remark 7.1 page 48) output to *spectral power* input. Note that it is a real-valued function (because \tilde{S}_{xx} and \tilde{S}_{yy} are real-valued). We might suspect that we could attain better estimates of \mathbf{H} by allowing the estimates to be complex-valued. And in fact, all the remaining estimates in this section are in general complex-valued.

And so to start (again), and in the very special (a.k.a unrealistic) case of \mathbf{S} having *zero measurement noise (zero measurement error)* ($v = u = w = 0$), $\mathbf{h}(n)$ being *linear time invariant (LTI)*, and input $x(n)$ being *wide sense stationary*...then we can determine (a.k.a “identify”) $\mathbf{h}(n)$ or $\tilde{\mathbf{H}}(\omega)$ exactly by $\tilde{\mathbf{H}}(\omega) = \tilde{S}_{yx}(\omega)/\tilde{S}_{xx}(\omega)$ (Corollary 6.3 page 41).

However, in practical situations, there is measurement noise/error. Examples may include “road noise” from a test being performed in a moving vehicle or *quantization noise* from an *analog-to-digital converter (ADC)*.

If the measurement error is at the output only (and under the assumptions of *LTI* and *WSS*) then $\hat{\mathbf{H}}_1$ (next definition) is the ideal estimator in the sense that $\hat{\mathbf{H}}_1 = \tilde{\mathbf{H}}$ (Corollary 13.4 page 125).



Definition 13.2. ⁶ Let \mathbf{S} be a system with input $x(n)$ and output $y(n)$.

⁵ Bendat and Piersol (2010) page 469 $\langle |H(f)| = [G_{yy}(f)/G_{xx}(f)]^{1/2} \rangle$, Yan and Ren (2012) page 204 $\langle (1) [G_{YY}(s)] = [H(s)][G_{FF}(s)][H^*(s)]^T \rangle$, Goldman (1999) page 179 \langle Transmissibility ... $H'_{ab} = G_{bb}/G_{aa}$ (note: differs by $\sqrt{\cdot}$ from Bendat and Piersol), Zhang et al. (2016), Zhou and Wahab (2018) page 824, https://link.springer.com/chapter/10.1007/978-3-319-54109-9_4

⁶ Bendat and Piersol (1993) pages 106–109 \langle 5.1.1 Optimality of Calculations \rangle , Bendat and Piersol (2010) page 185 $\langle H_1(f) = G_{xy}(f)/G_{xx}(f) \rangle$ (6.37), Shin and Hammond (2008) page 293 $\langle H_1(f) = \tilde{S}_{xy}(f)/\tilde{S}_{xx}(f) \rangle$ (9.63); which dif-

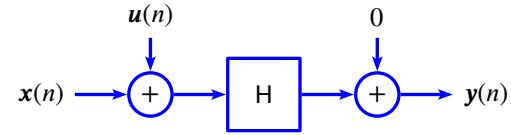
**D
E
F**

The Least Squares transfer function estimate $\hat{H}_1(\omega)$ of S is defined as $\hat{H}_1(\omega) \triangleq \frac{\tilde{S}_{yx}(\omega)}{\tilde{S}_{xx}(\omega)}$

The estimator \hat{H}_1 is a good start. However in the early 1980s, L. D. Mitchell pointed out that in the presence of input noise, \hat{H}_1 is far from ideal in that it is *biased* with respect to \tilde{H} ; in fact, \hat{H}_1 *under estimates* \tilde{H} (Corollary 13.4 page 125). Mitchell proposed a new estimator \hat{H}_2 (next definition).

This estimator has the special property that when there is input noise but no output noise (and under LTI, WSS, and *uncorrelated* assumptions), then it is ideal in the sense that $\hat{H}_2(\omega) = \tilde{H}(\omega)$ (Corollary 13.4 page 125).

Note also that in the case of both no input and no output noise, then $\hat{H}_1 = \hat{H}_2$ (Corollary 6.3 page 41).



Definition 13.3. ⁷ Let S be a SYSTEM with input $x(n)$ and output $y(n)$.

**D
E
F**

The Inverse Method transfer function estimate $\hat{H}_2(\omega)$ of S is defined as $\hat{H}_2(\omega) \triangleq \frac{\tilde{S}_{yy}(\omega)}{\tilde{S}_{xy}(\omega)}$

Mitchell's \hat{H}_2 contribution "generated a flurry of activity"⁸ and soon more \tilde{H} estimators appeared. So far we have

- \hat{H}_1 which is ideal when there is no input noise but *under estimates* \tilde{H} when there is (Corollary 13.4 page 125)
- \hat{H}_2 which is ideal when there is no output noise but *over estimates* \tilde{H} when there is (Corollary 13.4 page 125).

But what about estimators for when there is noise on both input and output? Armed with two estimators that between them account for both input and output noise, an "ad hoc" solution might be to somehow take mean values of \hat{H}_1 and \hat{H}_2 to induce new estimators—this approach summarizes the next three definitions. An arguably more mature approach is to find estimators that are optimal with respect to least squares measures—and this approach summarizes Definition 13.9 – Definition 13.7 (page 111).

Definition 13.4. Let S be a SYSTEM with input $x(n)$ and output $y(n)$.

**D
E
F**

The Arithmetic Mean transfer function estimate $\hat{H}_{am}(\omega)$ of S is defined as

$$\hat{H}_{am}(\omega) \triangleq \frac{|\tilde{S}_{xy}(\omega)|^2 + \tilde{S}_{xx}(\omega)\tilde{S}_{yy}(\omega)}{2\tilde{S}_{xx}(\omega)\tilde{S}_{xy}(\omega)}$$

fers from Definition 13.2, but see [Greenhoe \(2019a\)](#), [Bendat \(1978\)](#)cited by Cobb(1988)—variance estimate for \hat{H}_1 , [Allemand et al. \(1979\)](#) (cited by Shin(2008)), [Leuridan et al. \(1986\)](#) page 910 *(Least Squares Technique*; (8) $[G_{xx}](H) = [G_{xy}]$, [Abom \(1986\)](#)cited by Cobb(1988)—variance estimate for \hat{H}_1 , [Allemand et al. \(1987\)](#) pages 54–55 *(5.3.1 H₁ Technique; [H] = [G_{XF}][G_{FF}]⁻¹* (11)), [Cobb \(1988\)](#) page 2 *(¹H(f) = $\hat{G}_{yx}(f)/\hat{G}_{xx}(f)$ (1))*, [Goyder \(1984\)](#) page 438 *(H(iω) = S_{qp}/S_{pp} (3))*, [Pintelon and Schoukens \(2012\)](#) page 233 *($\hat{G}(\Omega_k) = S_{yu}(j\omega_k)S_{uu}^{-1}(j\omega_k)$ (7-30))*, [White et al. \(2006\)](#) page 678 *(H₁(f) = $\hat{S}_{x_my_m}(f)/\hat{S}_{x_mx_m}(f)$ (1))* which differs by conjugate, references Bendat and Piersol,

⁷ [Shin and Hammond \(2008\)](#) page 293 *(H₂(f) = $\tilde{S}_{yy}(f)/\tilde{S}_{yx}(f)$ (9.65))*; which differs from Definition 13.3, but see [Greenhoe \(2019a\)](#), [Bendat and Piersol \(2010\)](#) page 186 *(H₂(f) = $G_{yy}(f)/G_{yx}(f)$ (6.42))*, [Mitchell \(1980\)](#) (cited by Cobb(1988)), [Mitchell \(1982\)](#) page 278 "*Define what will be called an inverse method for calculation of a FRF as...*"; $H_2(f) = G_{yy}/G_{yx}$ (6); Note this differs with Definition 13.3 by a conjugate, but note that Mitchell seems to follow Bendat (see his [3] and [4]), which would explain this difference), [Cobb \(1988\)](#) page 3 *(²H(f) = $\hat{G}_{yy}(f)/\hat{G}_{xy}(f)$ (1))*, [White et al. \(2006\)](#) page 678 *(H₂(f) = $\hat{S}_{y_my_m}(f)/\hat{S}_{y_mx_m}(f)$ (2))* which differs by conjugate, references Bendat and Piersol)

⁸ [Cobb \(1988\)](#) page 3



Proposition 13.1. ⁹ Let \mathbf{S} be a system with input $x(n)$ and output $y(n)$.

P R P	$\hat{H}_{\text{am}}(\omega) = \frac{\hat{H}_1(\omega) + \hat{H}_2(\omega)}{2} \quad (\text{arithmetic mean of } \hat{H}_1 \text{ and } \hat{H}_2)$
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PROOF:

$$\begin{aligned}
 \hat{H}_{\text{am}}(\omega) &\triangleq \frac{|\tilde{S}_{xy}(\omega)|^2 + \tilde{S}_{xx}(\omega)\tilde{S}_{yy}(\omega)}{2\tilde{S}_{xx}(\omega)\tilde{S}_{xy}(\omega)} \quad \text{by definition of } \hat{H}_{\text{am}} \quad (\text{Definition 13.4 page 108}) \\
 &= \frac{\tilde{S}_{xy}(\omega)\tilde{S}_{xy}^*(\omega)}{2\tilde{S}_{xx}(\omega)\tilde{S}_{xy}(\omega)} + \frac{\tilde{S}_{xx}(\omega)\tilde{S}_{yy}(\omega)}{2\tilde{S}_{xx}(\omega)\tilde{S}_{xy}(\omega)} = \frac{\tilde{S}_{xy}^*(\omega)}{\tilde{S}_{xx}(\omega)} + \frac{\tilde{S}_{yy}(\omega)}{\tilde{S}_{xy}(\omega)} \\
 &= \frac{\hat{H}_1(\omega) + \hat{H}_2(\omega)}{2} \quad \text{by definitions of } \hat{H}_1 \text{ and } \hat{H}_2 \quad (\text{Definition 13.2 page 107, Definition 13.3 page 108})
 \end{aligned}$$



Definition 13.5. Let \mathbf{S} be a system with input $x(n)$ and output $y(n)$.

D E F	<i>The Geometric mean transfer function estimate $\hat{H}_{\text{gm}}(\omega)$ of \mathbf{S} is defined as</i>
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$$\hat{H}_{\text{gm}}(\omega) \triangleq \sqrt{\frac{\tilde{S}_{xy}^*(\omega)}{|\tilde{S}_{xy}(\omega)|}} \sqrt{\frac{\tilde{S}_{yy}(\omega)}{\tilde{S}_{xx}(\omega)}}$$

Proposition 13.2. ¹⁰ Let \mathbf{S} be a system with input $x(n)$ and output $y(n)$.

P R P	$\pm \hat{H}_{\text{gm}}(\omega) = \sqrt{\hat{H}_1(\omega)\hat{H}_2(\omega)} \quad (\text{geometric mean of } \hat{H}_1 \text{ and } \hat{H}_2)$
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PROOF:

$$\begin{aligned}
 \pm \hat{H}_{\text{gm}}(\omega) &\triangleq \pm \sqrt{\frac{\tilde{S}_{xy}^*(\omega)}{|\tilde{S}_{xy}(\omega)|}} \sqrt{\frac{\tilde{S}_{yy}(\omega)}{\tilde{S}_{xx}(\omega)}} \quad \text{by definition of } \hat{H}_{\text{gm}} \quad (\text{Definition 13.5 page 109}) \\
 &= \sqrt{\frac{[\tilde{S}_{xy}^*(\omega)]^2 \tilde{S}_{yy}(\omega)}{|\tilde{S}_{xy}(\omega)|^2 \tilde{S}_{xx}(\omega)}} = \sqrt{\frac{\tilde{S}_{xy}^*(\omega) \tilde{S}_{yy}(\omega)}{\tilde{S}_{xy}(\omega) \tilde{S}_{xx}(\omega)}} = \sqrt{\frac{\tilde{S}_{xy}^*(\omega) \tilde{S}_{yy}(\omega)}{\tilde{S}_{xx}(\omega) \tilde{S}_{xy}(\omega)}} \\
 &= \sqrt{\hat{H}_1(\omega)\hat{H}_2(\omega)} \quad \text{by definitions of } \hat{H}_1 \text{ and } \hat{H}_2 \quad (\text{Definition 13.2 page 107, Definition 13.3 page 108}) \\
 &= \text{Geometric mean of } \hat{H}_1(\omega) \text{ and } \hat{H}_2(\omega)
 \end{aligned}$$

Note that for a complex number $z \triangleq |z|e^{i\phi}$, \sqrt{z} has two solutions:¹¹

$$\sqrt{z} = \sqrt{|z|e^{i\phi}} = \{z_1, z_2\} = \left\{ \sqrt{|z|}e^{i(\phi/2)}, \sqrt{|z|}e^{i(\phi/2+\pi)} \right\} = \pm \sqrt{|z|}e^{i(\phi/2)}$$

because $z_1^2 = z$ and $z_2^2 = z$.



Note that the *geometric mean estimator* (Definition 13.5 page 109) and *transmissibility* (Definition 13.1 page 107) are closely related (next).

⁹ Mitchell (1982) page 279 (“Frequency Response Calculation: The Average Method”), Zheng et al. (2002) page 918 (“1.3 Arithmetic Mean Estimator H_3 ”)

¹⁰ Zheng et al. (2002) page 918 (“1.4 Geometric Mean Estimator H_4 ”)

¹¹ Many many thanks to Ben Cleveland for his help with this!!!

Proposition 13.3. Let $\phi(\omega)$ be the PHASE of $\tilde{S}_{xy}(\omega)$ such that $\tilde{S}_{xy}(\omega) \triangleq |\tilde{S}_{xy}(\omega)|e^{-i\phi(\omega)}$

P	R	P	$\hat{H}_{gm}(\omega) = \tilde{T}_{xy}(\omega) e^{-i\phi(\omega)} \quad \left(\begin{array}{l} \hat{H}_{gm}(\omega) = \tilde{T}_{xy}(\omega) \text{ is the MAGNITUDE of } \hat{H}_{gm}(\omega) \text{ and} \\ \angle \hat{H}_{gm}(\omega) = -\angle \tilde{S}_{xy}(\omega) \text{ is the PHASE of } \hat{H}_{gm}(\omega) \end{array} \right)$
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PROOF: Let $\phi(\omega)$ be the *phase* of

$$\begin{aligned}
 \hat{H}_{gm}(\omega) &\triangleq \sqrt{\hat{H}_1(\omega)\hat{H}_2(\omega)} && \text{by definition of } \hat{H}_{gm} && (\text{Definition 13.5 page 109}) \\
 &\triangleq \sqrt{\frac{\tilde{S}_{xy}^*(\omega)\tilde{S}_{yy}(\omega)}{\tilde{S}_{xx}(\omega)\tilde{S}_{xy}(\omega)}} && \text{by definitions of } \hat{H}_1 \text{ and } \hat{H}_2 && (\text{Definition 13.2 page 107, Definition 13.3 page 108}) \\
 &= \sqrt{\frac{\tilde{S}_{yy}(\omega)\tilde{S}_{xy}^*(\omega)}{\tilde{S}_{xx}(\omega)\tilde{S}_{xy}(\omega)}} \\
 &= \tilde{T}_{xy}(\omega) \sqrt{\frac{\tilde{S}_{xy}^*(\omega)}{\tilde{S}_{xy}(\omega)}} && \text{by definition of } \tilde{T}_{xy} && (\text{Definition 13.1 page 107}) \\
 &= \tilde{T}_{xy}(\omega) \sqrt{\frac{|\tilde{S}_{xy}(\omega)|e^{-i\phi(\omega)}}{|\tilde{S}_{xy}(\omega)|e^{i\phi(\omega)}}} && \text{where } \tilde{S}_{xy}(\omega) \triangleq |\tilde{S}_{xy}(\omega)|e^{-i\phi(\omega)} \\
 &= \tilde{T}_{xy}(\omega) \sqrt{e^{-i2\phi(\omega)}} \\
 &= \tilde{T}_{xy}(\omega) e^{-i\phi(\omega)}
 \end{aligned}$$



Remark 13.1. Transmissibility \tilde{T}_{xy} is a kind of “black sheep” of the system identification function family. All the other members of this family (\hat{H}_1 , \hat{H}_2 , \hat{H}_v , \hat{H}_s) are *complex-valued*, but \tilde{T}_{xy} is only *real-valued*—a seemingly ordinary Joe born into a super-hero family. But Proposition 13.3 suggests that \tilde{T}_{xy} is not simply a “black sheep”, but rather a “dark horse” with abilities that can easily be unleashed by slight redefinition. In particular, Proposition 13.3 demonstrates that \tilde{T}_{xy} is the *magnitude* of the geometric mean of \hat{H}_1 and \hat{H}_2 . We can thus justifiably define a **complex transmissibility** function as \hat{H}_{gm} ...and the magnitude of this *complex transmissibility* function is the *ordinary transmissibility* function of Definition 13.1 (page 107).

**R
E
M**

The **complex transmissibility** function $\tilde{T}'_{xy}(\omega) \triangleq \hat{H}_{gm}(\omega)$

Definition 13.6. Let S be a SYSTEM with input $x(n)$ and output $y(n)$.

**D
E
F** The **Harmonic mean transfer function estimate** $\hat{H}_{hm}(\omega)$ of S is defined as

$$\hat{H}_{hm}(\omega) \triangleq \frac{2\tilde{S}_{yy}(\omega)\tilde{S}_{xy}^*(\omega)}{\tilde{S}_{xx}(\omega)\tilde{S}_{yy}(\omega) + |\tilde{S}_{xy}(\omega)|^2}$$

Proposition 13.4.¹² Let S be a SYSTEM with input $x(n)$ and output $y(n)$.

P	R	P	$\hat{H}_{hm}(\omega) = \frac{2}{\frac{1}{\hat{H}_1(\omega)} + \frac{1}{\hat{H}_2(\omega)}} \quad (\text{Harmonic mean of } \hat{H}_1 \text{ and } \hat{H}_2)$
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¹² Carne and Dohrmann (2006) $\langle H_C = [H_A^{-1} + H_B^{-1}]^{-1} \rangle$

PROOF:

$$\begin{aligned}
 \hat{H}_{\text{hm}}(\omega) &\triangleq \frac{2\tilde{S}_{yy}(\omega)\tilde{S}_{xy}^*(\omega)}{\tilde{S}_{xx}(\omega)\tilde{S}_{yy}(\omega) + |\tilde{S}_{xy}(\omega)|^2} \quad \text{by definition of } \hat{H}_{\text{hm}} \quad (\text{Definition 13.6 page 110}) \\
 &= \frac{2}{\frac{\tilde{S}_{xx}(\omega)\tilde{S}_{yy}(\omega) + |\tilde{S}_{xy}(\omega)|^2}{\tilde{S}_{yy}(\omega)\tilde{S}_{xy}^*(\omega)}} = \frac{2}{\frac{\tilde{S}_{xx}(\omega)}{\tilde{S}_{xy}^*(\omega)} + \frac{\tilde{S}_{xy}(\omega)}{\tilde{S}_{yy}(\omega)}} \\
 &= \frac{2}{\frac{1}{\hat{H}_1(\omega)} + \frac{1}{\hat{H}_2(\omega)}} \quad \text{by definitions of } \hat{H}_1 \text{ and } \hat{H}_2 \quad (\text{Definition 13.2 page 107, Definition 13.3 page 108}) \\
 &= \text{Harmonic mean of } \hat{H}_1(\omega) \text{ and } \hat{H}_2(\omega)
 \end{aligned}$$



A bit of review reveals \hat{H}_1 at the low end of the estimation problem, \hat{H}_2 at the high end, and \hat{H}_{hm} , \hat{H}_{gm} , and \hat{H}_{am} somewhere between. But these three “between” estimates are not shown to be optimal in any sense—they are just conceptually interesting. What we might really like is a family of estimators that

- include \hat{H}_1 and \hat{H}_2 as limiting cases
- include the between cases
- are optimal in some sense

The estimator $\hat{H}_\kappa(\omega; \kappa)$ is one such estimator (next definition) that

- has \hat{H}_1 and \hat{H}_2 as limiting cases (Theorem 13.1 page 113),
- is optimal in the least squares sense (Theorem 13.6 page 126), and
- allows for a system designer to specify an output-input spectral noise ratio $\kappa(\omega)$ that can vary with frequency ω .

Moreover, $\hat{H}_\kappa(\omega)$ includes some special cases:

- In the case of constant κ , \hat{H}_κ simplifies to the *Scaling transfer function estimate* \hat{H}_s (Definition 13.8 page 111).
- In the case of $\kappa = 1$, \hat{H}_κ and \hat{H}_s simplify to the *Total least squares transfer function estimate* \hat{H}_v (Definition 13.9 page 112).

Definition 13.7. ¹³ Let S be a system with input $x(n)$ and output $y(n)$.

D E F The **transfer function estimate** $\hat{H}_\kappa(\omega; \kappa)$ with **scaling function** $\kappa(\omega)$ is defined as

$$\hat{H}_\kappa(\omega; \kappa) \triangleq \frac{\tilde{S}_{yy}(\omega) - \kappa(\omega)\tilde{S}_{xx}(\omega) + \sqrt{[\tilde{S}_{yy}(\omega) - \kappa(\omega)\tilde{S}_{xx}(\omega)]^2 + 4\kappa(\omega)|\tilde{S}_{xy}(\omega)|^2}}{2\tilde{S}_{xy}(\omega)}$$

Definition 13.8. ¹⁴ Let S be a system with input $x(n)$ and output $y(n)$.

D E F The **Scaling transfer function estimate** $\hat{H}_s(\omega; s)$ of S with **scaling parameter** $s \in [0 : \infty)$ is defined as $\hat{H}_s(\omega; s) \triangleq \hat{H}_\kappa(\omega; \kappa)$ with $\kappa(\omega) \triangleq s^2$

¹³ White et al. (2006) page 679 ((6)), Shin and Hammond (2008) page 293 ((9.67))

¹⁴ Shin and Hammond (2008) page 293 ((9.67) with $\kappa(\omega) = s^2$), White et al. (2006) page 679 ((6) with $\kappa(\omega) = s^2$), Leclerc et al. (2014) ((10) $\kappa(f) = 1/s^2$ and x and y swapped), Wicks and Vold (1986) page 898 (has additional s in denominator), Zheng et al. (2002) page 918 ((10), seems to differ)

Definition 13.9. ¹⁵ Let \mathbf{S} be a system with input $x(n)$ and output $y(n)$.

D E F The Total Least Squares transfer function estimate $\hat{H}_v(\omega)$ of \mathbf{S} is defined as
 $\hat{H}_v(\omega) \triangleq \hat{H}_k(\omega; \kappa)$ with $\kappa(\omega) = 1$

The previous estimators all assumed two signals: an input $x(n)$ and an output $y(n)$. However, in many practical systems, there is a third signal that is “driving” the system. In 1984 Goyder proposed an estimator (next definition) that is based on three signals.

Definition 13.10 (Three channel estimate). ¹⁶ Let \mathbf{S} be a system with input $x(n)$, output $y(n)$, and a driver $p(n)$.

D E F The transfer function estimate $\hat{H}_c(\omega)$ is defined as
 $\hat{H}_c(\omega) \triangleq \frac{\tilde{S}_{py}(\omega)}{\tilde{S}_{px}(\omega)}$

13.4 Estimator relationships

Lemma 13.1.

LEM	$\frac{d}{dp} \left[\tilde{S}_{yy} - p\tilde{S}_{xx} + \sqrt{(\tilde{S}_{yy} - p\tilde{S}_{xx})^2 + 4p \tilde{S}_{xy} ^2} \right] = \frac{\tilde{S}_{xx}(p\tilde{S}_{xx} - \tilde{S}_{yy}) + 2 \tilde{S}_{xy} ^2 - \tilde{S}_{xx}\sqrt{(p\tilde{S}_{xx} - \tilde{S}_{yy})^2 + 4p \tilde{S}_{xy} ^2}}{\sqrt{(p\tilde{S}_{xx} - \tilde{S}_{yy})^2 + 4p \tilde{S}_{xy} ^2}}$ $\frac{d}{dp} \left[p\tilde{S}_{yy} - \tilde{S}_{xx} + \sqrt{(p\tilde{S}_{yy} - \tilde{S}_{xx})^2 + 4p \tilde{S}_{xy} ^2} \right] = \frac{\tilde{S}_{yy}(p\tilde{S}_{yy} - \tilde{S}_{xx}) + 2 \tilde{S}_{xy} ^2 + \tilde{S}_{yy}\sqrt{(p\tilde{S}_{yy} - \tilde{S}_{xx})^2 + 4p \tilde{S}_{xy} ^2}}{\sqrt{(p\tilde{S}_{yy} - \tilde{S}_{xx})^2 + 4p \tilde{S}_{xy} ^2}}$
-----	--

PROOF:

$$\begin{aligned} \frac{d}{dp} \left[\tilde{S}_{yy} - p\tilde{S}_{xx} + \sqrt{(\tilde{S}_{yy} - p\tilde{S}_{xx})^2 + 4p|\tilde{S}_{xy}|^2} \right] &= -\tilde{S}_{xx} + \frac{-2\tilde{S}_{xx}(\tilde{S}_{yy} - p\tilde{S}_{xx}) + 4|\tilde{S}_{xy}|^2}{2\sqrt{(\tilde{S}_{yy} - p\tilde{S}_{xx})^2 + 4p|\tilde{S}_{xy}|^2}} \\ &= \frac{4|\tilde{S}_{xy}|^2 - 2\tilde{S}_{xx}(\tilde{S}_{yy} - p\tilde{S}_{xx}) - 2\tilde{S}_{xx}\sqrt{(\tilde{S}_{yy} - p\tilde{S}_{xx})^2 + 4p|\tilde{S}_{xy}|^2}}{2\sqrt{(\tilde{S}_{yy} - p\tilde{S}_{xx})^2 + 4p|\tilde{S}_{xy}|^2}} \\ &= \frac{\tilde{S}_{xx}(p\tilde{S}_{xx} - \tilde{S}_{yy}) + 2|\tilde{S}_{xy}|^2 - \tilde{S}_{xx}\sqrt{(p\tilde{S}_{xx} - \tilde{S}_{yy})^2 + 4p|\tilde{S}_{xy}|^2}}{\sqrt{(p\tilde{S}_{xx} - \tilde{S}_{yy})^2 + 4p|\tilde{S}_{xy}|^2}} \end{aligned}$$

$$\begin{aligned} \frac{d}{dp} \left[p\tilde{S}_{yy} - \tilde{S}_{xx} + \sqrt{(p\tilde{S}_{yy} - \tilde{S}_{xx})^2 + 4p|\tilde{S}_{xy}|^2} \right] &= \tilde{S}_{yy} + \frac{2\tilde{S}_{yy}(p\tilde{S}_{yy} - \tilde{S}_{xx}) + 4|\tilde{S}_{xy}|^2}{2\sqrt{(p\tilde{S}_{yy} - \tilde{S}_{xx})^2 + 4p|\tilde{S}_{xy}|^2}} \\ &= \frac{4|\tilde{S}_{xy}|^2 + 2\tilde{S}_{yy}(p\tilde{S}_{yy} - \tilde{S}_{xx}) + 2\tilde{S}_{yy}\sqrt{(p\tilde{S}_{yy} - \tilde{S}_{xx})^2 + 4p|\tilde{S}_{xy}|^2}}{2\sqrt{(p\tilde{S}_{yy} - \tilde{S}_{xx})^2 + 4p|\tilde{S}_{xy}|^2}} \end{aligned}$$

¹⁵ White et al. (2006) page 679 ((6)), Shin and Hammond (2008) page 294 ((9.69))

¹⁶ Shin and Hammond (2008) page 297 $\langle H_3(f) = S_{ry}(f)/S_{rx}(f) \rangle$ (9.78), Cobb (1988) page 4 $\langle {}^c \hat{H}(f) = \hat{G}_{ys}(f)/\hat{G}_{xs}(f) \rangle$ (1.4), Goyder (1984) page 440 $\langle H(i\omega) = S_{qz}/S_{pz} \rangle$ (5), Cobb and Mitchell (1990) page 450 ((1)), Pintelon and Schoukens (2012) page 241 $\langle \hat{G}(\Omega_k) = \hat{G}_{ry}(\Omega_k)\hat{G}_{ru}^{-1}(\Omega_k) \rangle$ (7-49)

$$= \frac{\tilde{S}_{yy}(p\tilde{S}_{yy} - \tilde{S}_{xx}) + 2|\tilde{S}_{xy}|^2 + \tilde{S}_{yy}\sqrt{(p\tilde{S}_{yy} - \tilde{S}_{xx})^2 + 4p|\tilde{S}_{xy}|^2}}{\sqrt{(p\tilde{S}_{yy} - \tilde{S}_{xx})^2 + 4p|\tilde{S}_{xy}|^2}}$$

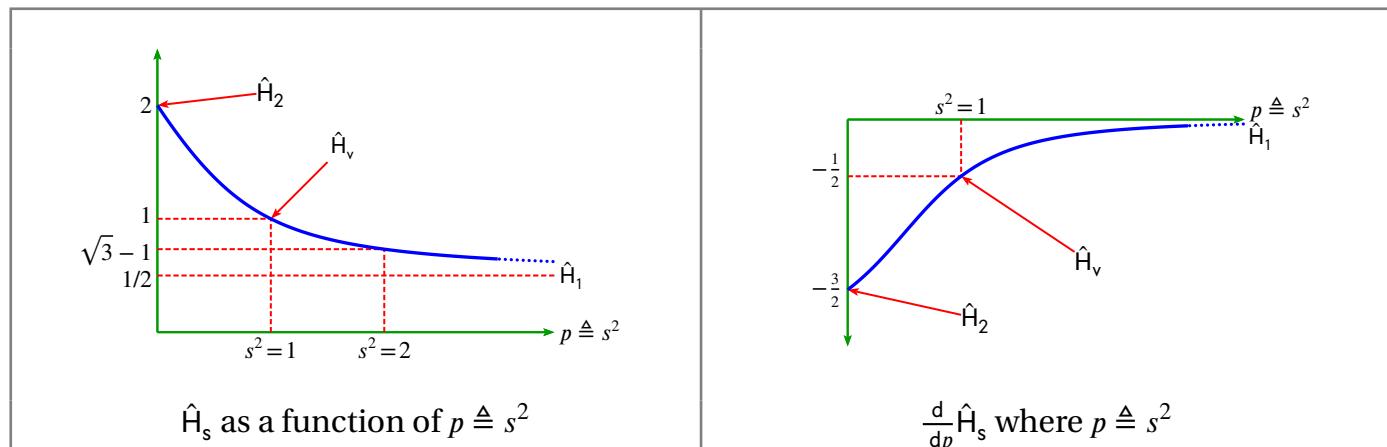
**Lemma 13.2.**

LEM	$\tilde{S}_{yy} - p\tilde{S}_{xx} + \sqrt{(\tilde{S}_{yy} - p\tilde{S}_{xx})^2 + 4p \tilde{S}_{xy} ^2} \geq 0$
	$p\tilde{S}_{yy} - \tilde{S}_{xx} + \sqrt{(p\tilde{S}_{yy} - \tilde{S}_{xx})^2 + 4p \tilde{S}_{xy} ^2} \geq 0$

PROOF:

$$\begin{aligned}
 & \tilde{S}_{yy} - p\tilde{S}_{xx} + \sqrt{(\tilde{S}_{yy} - p\tilde{S}_{xx})^2 + 4p|\tilde{S}_{xy}|^2} \geq 0 \\
 \Leftrightarrow & \sqrt{(p\tilde{S}_{xx} - \tilde{S}_{yy})^2 + 4p|\tilde{S}_{xy}|^2} \geq p\tilde{S}_{xx} - \tilde{S}_{yy} \\
 \Leftrightarrow & (p\tilde{S}_{xx} - \tilde{S}_{yy})^2 + 4p|\tilde{S}_{xy}|^2 \geq (p\tilde{S}_{xx} - \tilde{S}_{yy})^2 \\
 \Leftrightarrow & 4p|\tilde{S}_{xy}|^2 \geq 0 \\
 \Leftrightarrow & |\tilde{S}_{xy}| \geq 0
 \end{aligned}$$

$$\begin{aligned}
 & p\tilde{S}_{yy} - \tilde{S}_{xx} + \sqrt{(p\tilde{S}_{yy} - \tilde{S}_{xx})^2 + 4p|\tilde{S}_{xy}|^2} \geq 0 \\
 \Leftrightarrow & \sqrt{(\tilde{S}_{xx} - p\tilde{S}_{yy})^2 + 4p|\tilde{S}_{xy}|^2} \geq \tilde{S}_{xx} - p\tilde{S}_{yy} \\
 \Leftrightarrow & (\tilde{S}_{xx} - p\tilde{S}_{yy})^2 + 4p|\tilde{S}_{xy}|^2 \geq (\tilde{S}_{xx} - p\tilde{S}_{yy})^2 \\
 \Leftrightarrow & 4p|\tilde{S}_{xy}|^2 \geq 0 \\
 \Leftrightarrow & |\tilde{S}_{xy}| \geq 0
 \end{aligned}$$

Figure 13.2: \hat{H}_s with $\tilde{S}_{xx} = \tilde{S}_{yy} = 1$ and $\tilde{S}_{xy} = \frac{1}{2}$ **Theorem 13.1.** Let \hat{H}_s be defined as in Definition 13.8 (page 111).

THM	$\{s_1 < s_2\} \implies \hat{H}_s(\omega; s_2) \leq \hat{H}_s(\omega; s_1)$ (\hat{H}_s is monotonically decreasing in s)
	$ \hat{H}_1(\omega) \leq \hat{H}_s(\omega; s) \leq \hat{H}_2(\omega) $
	$\hat{H}_s(\omega; s) _{s=0} = \hat{H}_2(\omega)$
	$\hat{H}_s(\omega; s) _{s=1} = \hat{H}_v(\omega)$
	$\lim_{s \rightarrow \infty} \hat{H}_s(\omega; s) = \hat{H}_1(\omega)$

PROOF: I. Proofs for equalities:

$$\begin{aligned}
 \hat{H}_s(\omega; s) \Big|_{s=0} &\triangleq \frac{\tilde{S}_{yy} - s^2\tilde{S}_{xx} + \sqrt{[\tilde{S}_{yy} - s^2\tilde{S}_{xx}]^2 + 4s^2|\tilde{S}_{xy}|^2}}{2\tilde{S}_{xy}} \Big|_{s=0} && \text{by def. of } \hat{H}_s && \text{(Definition 13.8 page 111)} \\
 &= \frac{\tilde{S}_{yy} - 0 + \sqrt{[\tilde{S}_{yy} - 0]^2 + 0}}{2\tilde{S}_{xy}} = \frac{\tilde{S}_{yy}}{\tilde{S}_{xy}} && && \\
 &\triangleq \hat{H}_2 && \text{by def. of } \hat{H}_2 && \text{(Definition 13.3 page 108)} \\
 \hat{H}_s(\omega; s) \Big|_{s=1} &\triangleq \frac{\tilde{S}_{yy} - s^2\tilde{S}_{xx} + \sqrt{[\tilde{S}_{yy} - s^2\tilde{S}_{xx}]^2 + 4s^2|\tilde{S}_{xy}|^2}}{2\tilde{S}_{xy}} \Big|_{s=1} && \text{by def. of } \hat{H}_s && \text{(Definition 13.8 page 111)} \\
 &= \frac{\tilde{S}_{yy} - \tilde{S}_{xx} + \sqrt{[\tilde{S}_{yy} - \tilde{S}_{xx}]^2 + 4|\tilde{S}_{xy}|^2}}{2\tilde{S}_{xy}} && && \\
 &\triangleq \hat{H}_v && \text{by def. of } \hat{H}_v && \text{(Definition 13.9 page 112)} \\
 \lim_{s \rightarrow \infty} \hat{H}_s(\omega; s) &\triangleq \lim_{s \rightarrow \infty} \frac{\tilde{S}_{yy} - s^2\tilde{S}_{xx} + \sqrt{[\tilde{S}_{yy} - s^2\tilde{S}_{xx}]^2 + 4s^2|\tilde{S}_{xy}|^2}}{2\tilde{S}_{xy}} && \text{by def. of } \hat{H}_s && \text{(Definition 13.8 page 111)} \\
 &\triangleq \lim_{p \rightarrow 0} \frac{\tilde{S}_{yy} - \frac{1}{p}\tilde{S}_{xx} + \sqrt{[\tilde{S}_{yy} - \frac{1}{p}\tilde{S}_{xx}]^2 + 4\frac{1}{p}|\tilde{S}_{xy}|^2}}{2\tilde{S}_{xy}} && && \\
 &= \lim_{p \rightarrow 0} \frac{p\tilde{S}_{yy} - \tilde{S}_{xx} + \sqrt{[p\tilde{S}_{yy} - \tilde{S}_{xx}]^2 + 4p|\tilde{S}_{xy}|^2}}{2p\tilde{S}_{xy}} && \text{where } p \triangleq \frac{1}{s^2} && \\
 &= \lim_{p \rightarrow 0} \frac{\frac{d}{dp} \left[p\tilde{S}_{yy} - \tilde{S}_{xx} + \sqrt{[p\tilde{S}_{yy} - \tilde{S}_{xx}]^2 + 4p|\tilde{S}_{xy}|^2} \right]}{\frac{d}{dp} [2p\tilde{S}_{xy}]} && \text{by mult. by } 1 = \frac{p}{p} && \\
 &= \lim_{p \rightarrow 0} \frac{\tilde{S}_{yy}(p\tilde{S}_{yy} - \tilde{S}_{xx}) + 2|\tilde{S}_{xy}|^2 + \tilde{S}_{yy}\sqrt{(p\tilde{S}_{yy} - \tilde{S}_{xx})^2 + 4p|\tilde{S}_{xy}|^2}}{2\tilde{S}_{xy}} && \text{by l'Hôpital's rule} && \\
 &= \lim_{p \rightarrow 0} \frac{\tilde{S}_{yy}(p\tilde{S}_{yy} - \tilde{S}_{xx}) + 2|\tilde{S}_{xy}|^2 + \tilde{S}_{yy}\sqrt{(p\tilde{S}_{yy} - \tilde{S}_{xx})^2 + 4p|\tilde{S}_{xy}|^2}}{2\tilde{S}_{xy}} && && \text{by Lemma 13.1 page 112} \\
 &= \frac{\tilde{S}_{yy}(-\tilde{S}_{xx}) + 2|\tilde{S}_{xy}|^2 + \tilde{S}_{yy}\sqrt{(-\tilde{S}_{xx})^2}}{2\tilde{S}_{xy}\sqrt{(-\tilde{S}_{xx})^2}} && && \\
 &= \frac{2|\tilde{S}_{xy}|^2}{2\tilde{S}_{xx}\tilde{S}_{xy}} = \frac{\tilde{S}_{xy}^*}{\tilde{S}_{xx}} \triangleq \hat{H}_1 && \text{by def. of } \hat{H}_1 && \text{(Definition 13.2 page 107)}
 \end{aligned}$$

II. Proof for monotonicity:

1. Let $p \triangleq s^2$

2. lemma:

$$\begin{aligned}
& \left[2|\tilde{S}_{xy}|^2 + \tilde{S}_{xx}(p\tilde{S}_{xx} - \tilde{S}_{yy}) \right]^2 \\
&= 4|\tilde{S}_{xy}|^4 + 4\tilde{S}_{xx}|\tilde{S}_{xy}|^2(p\tilde{S}_{xx} - \tilde{S}_{yy}) + \tilde{S}_{xx}^2(p\tilde{S}_{xx} - \tilde{S}_{yy})^2 \\
&\leq 4|\tilde{S}_{xy}|^2\tilde{S}_{xx}\tilde{S}_{yy} + 4p\tilde{S}_{xx}|\tilde{S}_{xy}|^2\tilde{S}_{xx} - 4\tilde{S}_{xx}|\tilde{S}_{xy}|^2\tilde{S}_{yy} + \tilde{S}_{xx}^2(p\tilde{S}_{xx} - \tilde{S}_{yy})^2 \quad \left(\begin{array}{l} \text{by Cauchy Schwartz Inequality} \\ (\text{Theorem K.2 page 256}) \end{array} \right) \\
&= 4\cancel{\tilde{S}_{xx}}\cancel{\tilde{S}_{yy}}|\tilde{S}_{xy}|^2 + 4p\tilde{S}_{xx}|\tilde{S}_{xy}|^2\tilde{S}_{xx} - 4\cancel{\tilde{S}_{xx}}\cancel{\tilde{S}_{yy}}|\tilde{S}_{xy}|^2 + \tilde{S}_{xx}^2(p\tilde{S}_{xx} - \tilde{S}_{yy})^2 \\
&= \tilde{S}_{xx}^2[(p\tilde{S}_{xx} - \tilde{S}_{yy})^2 + 4p|\tilde{S}_{xy}|^2] \\
&= \left[\tilde{S}_{xx}\sqrt{(p\tilde{S}_{xx} - \tilde{S}_{yy})^2 + 4p|\tilde{S}_{xy}|^2} \right]^2
\end{aligned}$$

3. lemma: $2|\tilde{S}_{xy}|^2 + \tilde{S}_{xx}(p\tilde{S}_{xx} - \tilde{S}_{yy}) \leq \tilde{S}_{xx}\sqrt{(p\tilde{S}_{xx} - \tilde{S}_{yy})^2 + 4p|\tilde{S}_{xy}|^2}$. Proof:

$$\begin{aligned}
& 2|\tilde{S}_{xy}|^2 + \tilde{S}_{xx}(p\tilde{S}_{xx} - \tilde{S}_{yy}) \leq \tilde{S}_{xx}\sqrt{(p\tilde{S}_{xx} - \tilde{S}_{yy})^2 + 4p|\tilde{S}_{xy}|^2} \\
&\Leftrightarrow [2|\tilde{S}_{xy}|^2 + \tilde{S}_{xx}(p\tilde{S}_{xx} - \tilde{S}_{yy})]^2 \leq \left[\tilde{S}_{xx}\sqrt{(p\tilde{S}_{xx} - \tilde{S}_{yy})^2 + 4p|\tilde{S}_{xy}|^2} \right]^2 \quad \left(\begin{array}{l} \text{because } f(x) \triangleq x^2 \text{ is} \\ \text{strictly monotonic increasing} \end{array} \right)
\end{aligned}$$

The previous inequality is true by (2) lemma, so (3) lemma also true.

4. Proof that $\frac{d}{dp}|\hat{H}_s| \leq 0$:

$$\begin{aligned}
\frac{d}{dp}|\hat{H}_s| &\triangleq \frac{d}{dp} \left| \frac{\tilde{S}_{yy} - s^2\tilde{S}_{xx} + \sqrt{(\tilde{S}_{yy} - s^2\tilde{S}_{xx})^2 + 4s^2|\tilde{S}_{xy}|^2}}{2\tilde{S}_{xy}} \right| \quad \text{by def. of } \hat{H}_s \text{ (Definition 13.8 page 111)} \\
&\triangleq \frac{d}{dp} \left| \frac{\tilde{S}_{yy} - p\tilde{S}_{xx} + \sqrt{(\tilde{S}_{yy} - p\tilde{S}_{xx})^2 + 4p|\tilde{S}_{xy}|^2}}{2\tilde{S}_{xy}} \right| \quad \text{by definition of } p \text{ (item (1) page 115)} \\
&= \frac{d}{dp} \left| \frac{\tilde{S}_{yy} - p\tilde{S}_{xx} + \sqrt{(\tilde{S}_{yy} - p\tilde{S}_{xx})^2 + 4p|\tilde{S}_{xy}|^2}}{|2\tilde{S}_{xy}|} \right| \\
&= \frac{d}{dp} \left| \frac{\tilde{S}_{yy} - p\tilde{S}_{xx} + \sqrt{(\tilde{S}_{yy} - p\tilde{S}_{xx})^2 + 4p|\tilde{S}_{xy}|^2}}{2|\tilde{S}_{xy}|} \right| \quad \text{by Lemma 13.2 page 113} \\
&= \frac{\tilde{S}_{yy} - p\tilde{S}_{xx} + \sqrt{(\tilde{S}_{yy} - p\tilde{S}_{xx})^2 + 4p|\tilde{S}_{xy}|^2}}{2|\tilde{S}_{xy}|} \\
&= \frac{\tilde{S}_{xx}(p\tilde{S}_{xx} - \tilde{S}_{yy}) + 2|\tilde{S}_{xy}|^2 - \tilde{S}_{xx}\sqrt{(p\tilde{S}_{xx} - \tilde{S}_{yy})^2 + 4p|\tilde{S}_{xy}|^2}}{\sqrt{(\tilde{S}_{yy} - p\tilde{S}_{xx})^2 + 4p|\tilde{S}_{xy}|^2}} \quad \text{by Lemma 13.1 page 112} \\
&= \frac{\tilde{S}_{xx}(p\tilde{S}_{xx} - \tilde{S}_{yy}) + 2|\tilde{S}_{xy}|^2 - \tilde{S}_{xx}\sqrt{(p\tilde{S}_{xx} - \tilde{S}_{yy})^2 + 4p|\tilde{S}_{xy}|^2}}{2|\tilde{S}_{xy}|\sqrt{(\tilde{S}_{yy} - p\tilde{S}_{xx})^2 + 4p|\tilde{S}_{xy}|^2}} \\
&\leq 0 \quad \text{by (3) lemma}
\end{aligned}$$



Theorem 13.2. Let S be a system with input $x(n)$ and output $y(n)$.

T	H	M	$ \hat{H}_1(\omega) \leq \hat{H}_{\text{hm}}(\omega) \leq \hat{H}_{\text{gm}}(\omega) \leq \hat{H}_{\text{am}}(\omega) \leq \hat{H}_2(\omega) $
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PROOF:

1. lemma: $\hat{H}_1(\omega) \leq \hat{H}_2(\omega)$. Proof:

$$\begin{aligned}
 |\hat{H}_1| &\triangleq \left| \frac{\tilde{S}_{yx}(\omega)}{\tilde{S}_{xx}(\omega)} \right| && \text{by definition of } \hat{H}_1 && (\text{Definition 13.2 page 107}) \\
 &= \left| \frac{\langle y | x \rangle}{\|x\|^2} \right| = \frac{|\langle y | x \rangle|}{\|x\|^2} \\
 &\leq \frac{|\langle y | x \rangle|}{\|x\|^2} \left| \frac{\|x\| \|y\|}{\langle y | x \rangle} \right|^2 && \text{by Cauchy Schwartz Inequality} && \text{Theorem K.2 page 256} \\
 &= \frac{\|y\|^2}{|\langle y | x \rangle|} = \left| \frac{\|y\|^2}{\langle x | y \rangle} \right| = \left| \frac{\tilde{S}_{yy}(\omega)}{\tilde{S}_{xy}(\omega)} \right| \\
 &= |\hat{H}_2| && \text{by definition of } \hat{H}_2 && (\text{Definition 13.3 page 108})
 \end{aligned}$$

2. remainder of the proof:

$$\begin{aligned}
 |\hat{H}_1(\omega)| &= \min \{ \hat{H}_1(\omega), \hat{H}_2(\omega) \} && \text{by (1) lemma} \\
 &\leq |\hat{H}_{\text{hm}}(\omega)| && \text{by Corollary N.1 page 295} && \text{with } \lambda_1 = \lambda_2 = \frac{1}{2} \\
 &\leq |\hat{H}_{\text{gm}}(\omega)| && \text{by Corollary N.1 page 295} && \text{with } \lambda_1 = \lambda_2 = \frac{1}{2} \\
 &\leq |\hat{H}_{\text{am}}(\omega)| && \text{by Corollary N.1 page 295} && \text{with } \lambda_1 = \lambda_2 = \frac{1}{2} \\
 &\leq \max \{ \hat{H}_1(\omega), \hat{H}_2(\omega) \} && \text{by Corollary N.1 page 295} && \text{with } \lambda_1 = \lambda_2 = \frac{1}{2} \\
 &= |\hat{H}_2(\omega)| && \text{by (1) lemma} &&
 \end{aligned}$$



Theorem 13.2 (page 116) compared the magnitudes of several transfer function estimates and demonstrated a simple *linear* relationship. What about phase? The phase of those estimates is even simpler than the magnitude, as demonstrated next.

Proposition 13.5 (Estimator phase). Let $z \triangleq |z|e^{i\phi}$ be a COMPLEX number in the set of complex numbers \mathbb{C} . Let $\angle z \triangleq \phi$ be the PHASE of z .

P	R	P	$\angle \hat{H}_1(\omega) = \angle \hat{H}_{\text{hm}}(\omega) = \angle \hat{H}_{\text{gm}}(\omega) = \angle \hat{H}_{\text{am}}(\omega) = \angle \hat{H}_2(\omega) = \angle \hat{H}_s(\omega) = \angle \hat{H}_v(\omega) = \angle \hat{H}_k(\omega)$
---	---	---	---



PROOF:



$$\begin{aligned}
 \angle \hat{H}_1 &\triangleq \angle \frac{\tilde{S}_{yx}}{\tilde{S}_{xx}} & = & = \angle \tilde{S}_{xy}^* = -\angle \tilde{S}_{xy} \\
 &\uparrow \text{(Definition 13.2 page 107)} & & \\
 \angle \hat{H}_{hm} &\triangleq \angle \frac{2\tilde{S}_{yy}\tilde{S}_{xy}^*}{\tilde{S}_{xx}\tilde{S}_{yy} + |\tilde{S}_{xy}|^2} & = & = \angle \tilde{S}_{xy}^* = -\angle \tilde{S}_{xy} \\
 &\uparrow \text{(Definition 13.6 page 110)} & & \\
 \angle \hat{H}_{gm} &\triangleq \angle \frac{\tilde{S}_{xy}^*}{|\tilde{S}_{xy}|} \sqrt{\frac{\tilde{S}_{yy}}{\tilde{S}_{xx}}} & = & = \angle \tilde{S}_{xy}^* = -\angle \tilde{S}_{xy} \\
 &\uparrow \text{(Definition 13.5 page 109)} & & \\
 \angle \hat{H}_{am} &\triangleq \angle \frac{|\tilde{S}_{xy}|^2 + \tilde{S}_{xx}\tilde{S}_{yy}}{2\tilde{S}_{xx}\tilde{S}_{xy}} & = \angle \frac{1}{\tilde{S}_{xy}} & = \angle \tilde{S}_{xy}^* = -\angle \tilde{S}_{xy} \\
 &\uparrow \text{(Definition 13.4 page 108)} & & \\
 \angle \hat{H}_2 &\triangleq \angle \frac{\tilde{S}_{yy}}{\tilde{S}_{xy}} & = \angle \frac{1}{\tilde{S}_{xy}} & = \angle \tilde{S}_{xy}^* = -\angle \tilde{S}_{xy} \\
 &\uparrow \text{(Definition 13.3 page 108)} & & \\
 \angle \hat{H}_s &\triangleq \angle \frac{\tilde{S}_{yy} - s^2\tilde{S}_{xx} + \sqrt{[\tilde{S}_{yy} - s^2\tilde{S}_{xx}]^2 + 4s^2|\tilde{S}_{xy}|^2}}{2\tilde{S}_{xy}} & = \angle \frac{1}{\tilde{S}_{xy}} & = \angle \tilde{S}_{xy}^* = -\angle \tilde{S}_{xy} \\
 &\uparrow \text{(Definition 13.8 page 111)} & & \\
 \angle \hat{H}_v &\triangleq \angle \frac{\tilde{S}_{yy} - \tilde{S}_{xx} + \sqrt{[\tilde{S}_{yy} - \tilde{S}_{xx}]^2 + 4|\tilde{S}_{xy}|^2}}{2\tilde{S}_{xy}} & = \angle \frac{1}{\tilde{S}_{xy}} & = \angle \tilde{S}_{xy}^* = -\angle \tilde{S}_{xy} \\
 &\uparrow \text{(Definition 13.9 page 112)} & & \\
 \angle \hat{H}_\kappa &\triangleq \angle \frac{\tilde{S}_{yy} - \kappa\tilde{S}_{xx} + \sqrt{[\tilde{S}_{yy} - \kappa\tilde{S}_{xx}]^2 + 4\kappa|\tilde{S}_{xy}|^2}}{2\tilde{S}_{xy}} & = \angle \frac{1}{\tilde{S}_{xy}} & = \angle \tilde{S}_{xy}^* = -\angle \tilde{S}_{xy} \\
 &\uparrow \text{(Definition 13.7 page 111)} & & \\
 \angle C_{xy} &\triangleq \angle \frac{\tilde{S}_{xy}^*}{\sqrt{\tilde{S}_{xx}\tilde{S}_{yy}}} & = & = \angle \tilde{S}_{xy}^* = -\angle \tilde{S}_{xy} \\
 &\uparrow \text{(Definition 13.12 page 128)} & & \\
 \Rightarrow & & &
 \end{aligned}$$

13.5 Alternate forms

Any standard kit of algebraic tricks should arguably always include the ability to swap the location of a square root between numerator and denominator. If you are of this persuasion, after travelling from the definition of \hat{H}_s on page 111, you won't be disappointed when arriving at the next proposition (Proposition 13.6 page 117). But it has more use than just allowing you to entertain friends at social occasions. It also makes it very easy to see (using only algebra) what previously employed *l'Hôpital's rule* (using calculus) in the proof of Theorem 13.1—that $\lim_{s \rightarrow \infty} \hat{H}_s = \hat{H}_1$.

Proposition 13.6. ¹⁷ Let $\hat{H}_\kappa(\omega; \kappa)$ be defined as in Definition 13.7 (page 111).

¹⁷  Shin and Hammond (2008) page 293 ((9.67)),  Leclere et al. (2014) ((10) $\kappa(f) = 1/s^2$ and x and y swapped)

P
R
P

$$\hat{H}_\kappa(\omega; s) = \frac{2\kappa(\omega)\tilde{S}_{yx}(\omega)}{\kappa(\omega)\tilde{S}_{xx}(\omega) - \tilde{S}_{yy}(\omega) + \sqrt{[\kappa(\omega)\tilde{S}_{xx}(\omega) - \tilde{S}_{yy}(\omega)]^2 + 4\kappa(\omega)|\tilde{S}_{xy}(\omega)|^2}}$$

$$= \frac{2\tilde{S}_{xy}^*}{\tilde{S}_{xx} - \frac{1}{\kappa(\omega)}\tilde{S}_{yy} + \sqrt{[\tilde{S}_{xx} - \frac{1}{\kappa(\omega)}\tilde{S}_{yy}]^2 + \frac{4}{\kappa(\omega)}|\tilde{S}_{xy}|^2}}$$

PROOF: We can transform \hat{H}_κ from that found in Definition 13.8 (page 111) to the forms in this proposition by the technique of “rationalizing the denominator”¹⁸

$$\begin{aligned} \hat{H}_\kappa &\triangleq \frac{\tilde{S}_{yy} - \kappa\tilde{S}_{xx} + \sqrt{[\tilde{S}_{yy} - \kappa\tilde{S}_{xx}]^2 + 4\kappa|\tilde{S}_{xy}|^2}}{2\tilde{S}_{xy}} && \text{by definition of } \hat{H}_\kappa \text{ (Definition 13.8 page 111)} \\ &= \frac{\left[\tilde{S}_{yy} - \kappa\tilde{S}_{xx} + \sqrt{[\tilde{S}_{yy} - \kappa\tilde{S}_{xx}]^2 + 4\kappa|\tilde{S}_{xy}|^2} \right] \overbrace{\left[\tilde{S}_{yy} - \kappa\tilde{S}_{xx} - \sqrt{[\tilde{S}_{yy} - \kappa\tilde{S}_{xx}]^2 + 4\kappa|\tilde{S}_{xy}|^2} \right]}^{\text{"rationalizing factor"}}}{2\tilde{S}_{xy} \underbrace{\left[\tilde{S}_{yy} - \kappa\tilde{S}_{xx} - \sqrt{[\tilde{S}_{yy} - \kappa\tilde{S}_{xx}]^2 + 4\kappa|\tilde{S}_{xy}|^2} \right]}_{\text{"rationalizing factor}}} \\ &= \frac{[\tilde{S}_{yy} - \kappa\tilde{S}_{xx}]^2 - [\tilde{S}_{yy} - \kappa\tilde{S}_{xx}]^2 - 4\kappa|\tilde{S}_{xy}|^2}{2\tilde{S}_{xy} \left[\tilde{S}_{yy} - \kappa\tilde{S}_{xx} - \sqrt{[\tilde{S}_{yy} - \kappa\tilde{S}_{xx}]^2 + 4\kappa|\tilde{S}_{xy}|^2} \right]} = \frac{-4\kappa|\tilde{S}_{xy}|^2}{2\tilde{S}_{xy} \left[\tilde{S}_{yy} - \kappa\tilde{S}_{xx} - \sqrt{[\tilde{S}_{yy} - \kappa\tilde{S}_{xx}]^2 + 4\kappa|\tilde{S}_{xy}|^2} \right]} \\ &= \frac{2\kappa\tilde{S}_{xy}^*}{\kappa\tilde{S}_{xx} - \tilde{S}_{yy} + \sqrt{[\kappa\tilde{S}_{xx} - \tilde{S}_{yy}]^2 + 4\kappa|\tilde{S}_{xy}|^2}} = \frac{2\frac{\kappa}{\kappa}\tilde{S}_{xy}^*}{\frac{\kappa}{\kappa}\tilde{S}_{xx} - \frac{1}{\kappa}\tilde{S}_{yy} + \sqrt{\frac{1}{s^4}[\kappa\tilde{S}_{xx} - \tilde{S}_{yy}]^2 + \frac{4\kappa}{s^4}|\tilde{S}_{xy}|^2}} \\ &= \frac{2\tilde{S}_{xy}^*}{\tilde{S}_{xx} - \frac{1}{\kappa}\tilde{S}_{yy} + \sqrt{[\tilde{S}_{xx} - \frac{1}{\kappa}\tilde{S}_{yy}]^2 + \frac{4}{\kappa}|\tilde{S}_{xy}|^2}} \end{aligned}$$

Integrity check for $s = 0$ and $s \rightarrow \infty$ cases: Let $p \triangleq \kappa$.

$$\begin{aligned} \lim_{p \rightarrow \infty} \hat{H}_\kappa &= \lim_{p \rightarrow \infty} \frac{2\tilde{S}_{yx}}{\tilde{S}_{xx} - \frac{1}{p}\tilde{S}_{yy} + \sqrt{[\tilde{S}_{xx} - \frac{1}{p}\tilde{S}_{yy}]^2 + \frac{4}{p}|\tilde{S}_{xy}|^2}} = \frac{2\tilde{S}_{yx}}{\tilde{S}_{xx} + \sqrt{[\tilde{S}_{xx}]^2}} \\ &= \frac{\tilde{S}_{yx}}{\tilde{S}_{xx}} \triangleq \hat{H}_1 && \text{by def. of } \hat{H}_1 \text{ (Definition 13.2 page 107)} \end{aligned}$$

$$\begin{aligned} \lim_{p \rightarrow 0} \hat{H}_\kappa &= \lim_{p \rightarrow 0} \frac{2p\tilde{S}_{yx}}{p\tilde{S}_{xx} - \tilde{S}_{yy} + \sqrt{[p\tilde{S}_{xx} - \tilde{S}_{yy}]^2 + 4p|\tilde{S}_{xy}|^2}} \\ &= \lim_{p \rightarrow 0} \frac{\frac{d}{dp}(2p\tilde{S}_{yx})}{\frac{d}{dp}\left(p\tilde{S}_{xx} - \tilde{S}_{yy} + \sqrt{[p\tilde{S}_{xx} - \tilde{S}_{yy}]^2 + 4p|\tilde{S}_{xy}|^2}\right)} && \text{by l'Hôpital's rule} \end{aligned}$$

¹⁸ Slaught and Lennes (1915), page 274 (“197. Rationalizing the Denominator.”) <https://archive.org/details/elementaryalgebr00slaurich/page/274> Note that the operation in the proof of Proposition 13.6 is being performed essentially in reverse...or rather “rationalizing the numerator”.



$$\begin{aligned}
 &= \lim_{p \rightarrow 0} -\frac{2\tilde{S}_{yx}}{\tilde{S}_{xx}(p\tilde{S}_{xx} - \tilde{S}_{yy}) + 2|\tilde{S}_{xy}|^2 + \tilde{S}_{xx}\sqrt{(p\tilde{S}_{xx} - \tilde{S}_{yy})^2 + 4p|\tilde{S}_{xy}|^2}} \\
 &\quad \text{by Lemma 13.1 page 112} \\
 &= \frac{2\tilde{S}_{yy}\tilde{S}_{yx}}{-\tilde{S}_{xx}\tilde{S}_{yy} + 2|\tilde{S}_{xy}|^2 + \tilde{S}_{xx}\tilde{S}_{yy}} = \frac{2\tilde{S}_{yy}\tilde{S}_{yx}}{2|\tilde{S}_{xy}|^2} = \frac{\tilde{S}_{yy}}{\tilde{S}_{xy}} \\
 &\triangleq \hat{H}_2 \quad \text{by def. of } \hat{H}_2 \text{ (Definition 13.3 page 108)}
 \end{aligned}$$

⇒

13.6 Least squares estimates of non-linear systems

“The legendary Hungarian mathematician John von Neumann once referred to the theory of nonequilibrium systems as the “theory of non-elephants,” ... Nevertheless, such a theory of non-elephants will be attempted here.”

Per Bak, in “how nature works...” ¹⁹

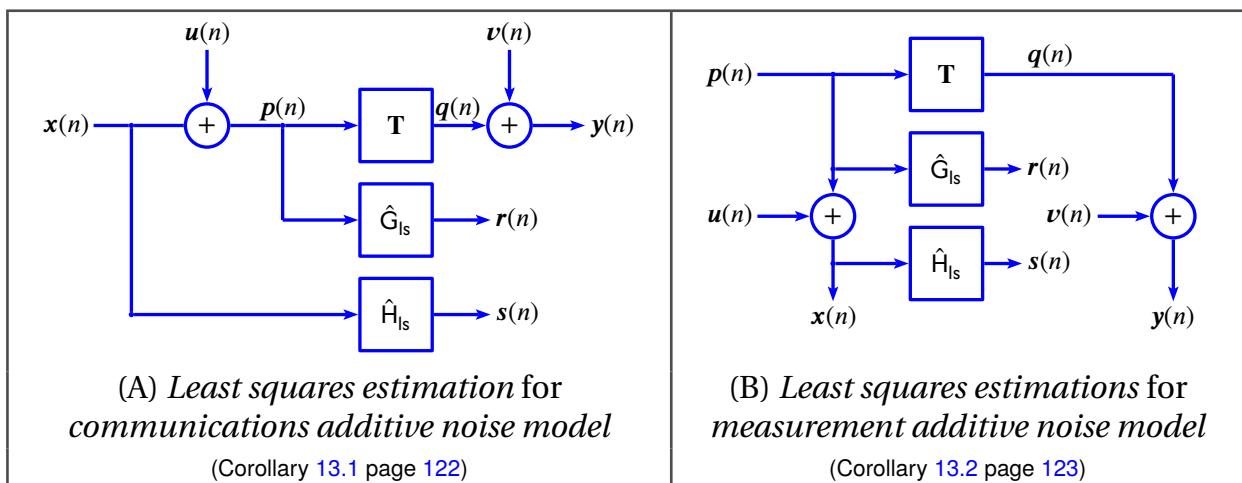
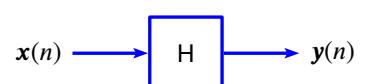


Figure 13.3: Least Square estimation (Theorem 13.3 page 120)

Let \mathbf{S} be the system illustrated to the right. If there is no measurement noise on the input and output and if \mathbf{H} is linear time invariant, then $\tilde{\mathbf{H}} = \tilde{S}_{xy}/\tilde{S}_{xx}$ (Corollary 6.1 page 40). But what if there is output measurement noise? And what if \mathbf{H} is not LTI? What is the best least-squares estimate of $\tilde{\mathbf{H}}$? The answer depends on how you define “the best”.



The definition of “best” or “optimal” is given by a cost function $C(\hat{\mathbf{H}})$. There are several possible cost functions. Definition 13.11 provides some. Theorem 13.3 then demonstrate optimal solutions with respect to these definitions.

Definition 13.11. Let \mathbf{S} be a system defined as in Figure 13.3 (page 119) (A) or (B). Define the following COST FUNCTIONS for spectral LEAST-SQUARES estimates:

DEF	$C_{rq}(\hat{\mathbf{G}}) \triangleq \tilde{\mathbf{F}} \ r(n) - q(n)\ ^2 \triangleq \tilde{\mathbf{F}} \langle r(n) - q(n) r(0) - q(0) \rangle \triangleq \tilde{\mathbf{F}} \mathbf{E} ([r(n) - q(n)] [r(0) - q(0)]^*)$
	$C_{sy}(\hat{\mathbf{H}}) \triangleq \tilde{\mathbf{F}} \ s(n) - y(n)\ ^2 \triangleq \tilde{\mathbf{F}} \langle s(n) - y(n) s(0) - y(0) \rangle \triangleq \tilde{\mathbf{F}} \mathbf{E} ([s(n) - y(n)] [s(0) - y(0)]^*)$

¹⁹ Bak (2013) page 29 § Systems in Balance Are Not Complex

Lemma 13.3. Let $C_{rq}(\hat{G})$ and $C_{sy}(\hat{H})$ be defined as in Definition 13.11 (page 119).

LEM	$C_{rq}(\hat{G}) = \tilde{S}_{pp}(\omega) \hat{G}(\omega) ^2 - \tilde{S}_{py}(\omega) \hat{G}(\omega) - \tilde{S}_{py}^*(\omega) \hat{G}^*(\omega) + \tilde{S}_{qq}(\omega)$
	$C_{sy}(\hat{H}) = \tilde{S}_{xx}(\omega) \hat{H}(\omega) ^2 - \tilde{S}_{xy}(\omega) \hat{H}(\omega) - \tilde{S}_{xy}^*(\omega) \hat{H}^*(\omega) + \tilde{S}_{yy}(\omega)$

PROOF:

$$C_{rq}(\hat{G})$$

$$\begin{aligned} &\triangleq \check{\mathbf{E}} \left([r(n) - q(n)] [r(0) - q(0)]^* \right) && \text{by definition of } C_{rq} \quad (\text{Definition 13.11 page 119}) \\ &= \check{\mathbf{F}} [\mathbf{E}[r(n)r^*(0)] - \mathbf{E}[r(n)q^*(0)] - \mathbf{E}[q(n)r^*(0)] + \mathbf{E}[q(n)q^*(0)]] && \text{by linearity of } \mathbf{E} \quad (\text{Theorem 1.1 page 4}) \\ &\triangleq \check{\mathbf{F}} [R_{rr}(m) - R_{rq}(m) - R_{qr}(m) + R_{qq}(m)] && \text{by definition of } R_{xy} \quad (\text{Definition 2.4 page 12}) \\ &\triangleq [\tilde{S}_{rr}(\omega) - \tilde{S}_{rq}(\omega) - \tilde{S}_{qr}(\omega) + \tilde{S}_{qq}(\omega)] && \text{by definition of } \tilde{S}_{xy} \quad (\text{Definition 7.3 page 48}) \\ &= [\tilde{S}_{pp}(\omega) |\hat{G}(\omega)|^2 - \tilde{S}_{py}(\omega) \hat{G}(\omega) - \tilde{S}_{py}^*(\omega) \hat{G}^*(\omega) + \tilde{S}_{qq}(\omega)] && \text{by (A)-(D) and Corollary 8.8 page 63} \end{aligned}$$

$$C_{sy}(\hat{H})$$

$$\begin{aligned} &\triangleq \check{\mathbf{E}} \left([s(n) - y(n)] [s(0) - y(0)]^* \right) && \text{by definition of } C_{sy} \quad (\text{Definition 13.11 page 119}) \\ &= \check{\mathbf{F}} [\mathbf{E}[s(n)s^*(0)] - \mathbf{E}[s(n)y^*(0)] - \mathbf{E}[y(n)s^*(0)] + \mathbf{E}[y(n)y^*(0)]] && \text{by linearity of } \mathbf{E} \quad (\text{Theorem 1.1 page 4}) \\ &\triangleq \check{\mathbf{F}} [R_{ss}(m) - R_{sy}(m) - R_{ys}(m) + R_{yy}(m)] && \text{by definition of } R_{xy} \quad (\text{Definition 2.4 page 12}) \\ &\triangleq [\tilde{S}_{ss}(\omega) - \tilde{S}_{sy}(\omega) - \tilde{S}_{ys}(\omega) + \tilde{S}_{yy}(\omega)] && \text{by definition of } \tilde{S}_{xy} \quad (\text{Definition 7.3 page 48}) \\ &= [\tilde{S}_{xx}(\omega) |\hat{H}(\omega)|^2 - \tilde{S}_{xy}(\omega) \hat{H}(\omega) - \tilde{S}_{xy}^*(\omega) \hat{H}^*(\omega) + \tilde{S}_{yy}(\omega)] && \text{by (A)-(D) and Corollary 8.8 (page 63)} \end{aligned}$$



Theorem 13.3. Let \mathbf{S} be the system illustrated in Figure 13.3 page 119 (A) or (B).

THM	$\left. \begin{array}{l} (A). \ x, u, \text{ and } v \text{ are WSS} \\ (B). \ x, u, \text{ and } v \text{ are UNCORRELATED} \\ (C). \ Eu = Ev = 0 \text{ (ZERO-MEAN)} \\ (D). \ \hat{G}_{ls} \text{ and } \hat{H}_{ls} \text{ are LTI} \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} (1). \ \arg \min_{\hat{G}} C_{rq}(\hat{G}) = \frac{\tilde{S}_{yp}(\omega)}{\tilde{S}_{pp}(\omega)} \\ (2). \ \arg \min_{\hat{H}} C_{sy}(\hat{H}) = \frac{\tilde{S}_{yx}(\omega)}{\tilde{S}_{xx}(\omega)} \end{array} \right.$
-----	---

PROOF:

1. Define shorthand function names $\hat{G} \triangleq \hat{G}_{ls}$ and $\hat{H} \triangleq \hat{H}_{ls}$.

2. lemma:

$$0 = \frac{\partial}{\partial \hat{G}_R} C_{rq}(\hat{G}) = \frac{\partial}{\partial \hat{G}_R} \left(\tilde{S}_{pp} |\hat{G}|^2 - \hat{G} \tilde{S}_{py} - \hat{G}^* \tilde{S}_{py}^* + \tilde{S}_{qq} \right)$$

by Lemma 13.3 page 120

$$= \frac{\partial}{\partial \hat{G}_R} \left(\tilde{S}_{pp} [\hat{G}_R^2 + \hat{G}_I^2] - (\hat{G}_R + i\hat{G}_I) \tilde{S}_{py} - (\hat{G}_R + i\hat{G}_I)^* \tilde{S}_{py}^* + \tilde{S}_{qq} \right)$$

$$= 2\hat{G}_R \tilde{S}_{pp} - \tilde{S}_{py} - \tilde{S}_{py}^* + \frac{\partial}{\partial \hat{G}_R} \tilde{S}_{qq} \stackrel{0}{\rightarrow}$$

because q does not vary with \hat{G}

$$= 2\hat{G}_R \tilde{S}_{pp} - 2\mathbf{R}_e \tilde{S}_{py}$$

$$= 2\hat{G}_R \tilde{S}_{pp} - 2\mathbf{R}_e \tilde{S}_{yp}$$

by Corollary 2.2 page 16

$$\Rightarrow \hat{G}_R(\omega) = \frac{\mathbf{R}_e \tilde{S}_{yp}(\omega)}{\tilde{S}_{pp}(\omega)}$$

3. lemma:

$$\begin{aligned}
 0 &= \frac{\partial}{\partial \hat{G}_I} C_{rq}(\hat{G}) \\
 &= \frac{\partial}{\partial \hat{G}_I} \left(\tilde{S}_{pp} |\hat{G}|^2 - \hat{G} \tilde{S}_{py} - \hat{G}^* \tilde{S}_{py}^* + \tilde{S}_{qq} \right) && \text{by Lemma 13.3 page 120} \\
 &= \frac{\partial}{\partial \hat{G}_I} [\tilde{S}_{pp} [\hat{G}_R^2 + \hat{G}_I^2] - (\hat{G}_R + i\hat{G}_I) \tilde{S}_{py} - (\hat{G}_R - i\hat{G}_I) \tilde{S}_{py}^* + \tilde{S}_{qq}] \\
 &= 2\hat{G}_I \tilde{S}_{pp} - i\tilde{S}_{py} + i\tilde{S}_{py}^* + \frac{\partial}{\partial \hat{G}_I} \tilde{S}_{qq} \xrightarrow{0} && \text{because } q \text{ does not vary with } \hat{G} \\
 &= 2\hat{G}_I \tilde{S}_{pp} - 2i(i\mathbf{I}_m \tilde{S}_{py}) \\
 &= 2\hat{G}_I \tilde{S}_{pp} + 2i(i\mathbf{I}_m \tilde{S}_{yp}) && \text{by Corollary 2.2 page 16} \\
 \implies \hat{G}_I(\omega) &= \frac{\mathbf{I}_m \tilde{S}_{yp}(\omega)}{\tilde{S}_{pp}(\omega)}
 \end{aligned}$$

4. Proof for $\hat{G} \triangleq \hat{G}_{ls}$ expression:

$$\begin{aligned}
 \hat{G}(\omega) &= \hat{G}_R(\omega) + i\hat{G}_I(\omega) \\
 &= \frac{\mathbf{R}_e \tilde{S}_{yp}(\omega)}{\tilde{S}_{pp}(\omega)} + \frac{i\mathbf{I}_m \tilde{S}_{yp}(\omega)}{\tilde{S}_{pp}(\omega)} && \text{by (2) lemma and (3) lemma} \\
 &= \frac{\tilde{S}_{yp}(\omega)}{\tilde{S}_{pp}(\omega)}
 \end{aligned}$$

5. lemma:

$$\begin{aligned}
 0 &= \frac{\partial}{\partial \hat{H}_R} C_{sy}(\hat{H}) \\
 &= \frac{\partial}{\partial \hat{H}_R} \left(\tilde{S}_{xx} |\hat{H}|^2 - \hat{H} \tilde{S}_{xy} - \hat{H}^* \tilde{S}_{xy}^* + \tilde{S}_{yy} \right) && \text{by Lemma 13.3 page 120} \\
 &= \frac{\partial}{\partial \hat{H}_R} (\tilde{S}_{xx} [\hat{H}_R^2 + \hat{H}_I^2] - (\hat{H}_R + i\hat{H}_I) \tilde{S}_{xy} - (\hat{H}_R - i\hat{H}_I)^* \tilde{S}_{xy}^* + \tilde{S}_{yy}) \\
 &= 2\hat{H}_R \tilde{S}_{xx} - \tilde{S}_{xy} - \tilde{S}_{xy}^* + \frac{\partial}{\partial \hat{H}_R} \tilde{S}_{yy} \xrightarrow{0} && \text{because } y \text{ does not vary with } \hat{H} \\
 &= 2\hat{H}_R \tilde{S}_{xx} - 2\mathbf{R}_e \tilde{S}_{xy} \\
 &= 2\hat{H}_R \tilde{S}_{xx} - 2\mathbf{R}_e \tilde{S}_{yx} && \text{by Corollary 2.2 page 16} \\
 \implies \hat{H}_R(\omega) &= \frac{\mathbf{R}_e \tilde{S}_{yx}(\omega)}{\tilde{S}_{xx}(\omega)}
 \end{aligned}$$

6. lemma:

$$\begin{aligned}
 0 &= \frac{\partial}{\partial \hat{H}_I} C_{sy}(\hat{H}) \\
 &= \frac{\partial}{\partial \hat{H}_I} \left(\tilde{S}_{xx} |\hat{H}|^2 - \tilde{S}_{xy} \hat{H} - \tilde{S}_{xy}^* \hat{H}^* + \tilde{S}_{yy} \right) && \text{by Lemma 13.3 page 120} \\
 &= \frac{\partial}{\partial \hat{H}_I} [\tilde{S}_{xx} [\hat{H}_R^2 + \hat{H}_I^2] - \tilde{S}_{xy} (\hat{H}_R + i\hat{H}_I) - \tilde{S}_{xy}^* (\hat{H}_R - i\hat{H}_I) + \tilde{S}_{yy}] \\
 &= 2\hat{H}_I \tilde{S}_{xx} - i\tilde{S}_{xy} + i\tilde{S}_{xy}^* + \frac{\partial}{\partial \hat{H}_R} \tilde{S}_{yy} \xrightarrow{0} && \text{because } q \text{ does not vary with } \hat{H}
 \end{aligned}$$

$$\begin{aligned}
 &= 2\hat{H}_I \tilde{S}_{xx} - 2i(i\mathbf{I}_m \tilde{S}_{xy}) \\
 &= 2\hat{H}_I \tilde{S}_{xx} + 2i(i\mathbf{I}_m \tilde{S}_{yx}) \\
 &= 2\hat{H}_I \tilde{S}_{xx} - 2\mathbf{I}_m \tilde{S}_{yx} \\
 \implies \hat{H}_I(\omega) &= \frac{\mathbf{I}_m \tilde{S}_{yx}(\omega)}{\tilde{S}_{xx}(\omega)}
 \end{aligned}$$

by Corollary 2.2 page 16

7. Proof for $\hat{H} \triangleq \hat{H}_{ls}$ expression:

$$\begin{aligned}
 \boxed{\hat{H}(\omega)} &= \hat{H}_R(\omega) + i\hat{H}_I(\omega) \\
 &= \frac{\mathbf{R}_e \tilde{S}_{yp}(\omega)}{\tilde{S}_{xx}(\omega)} + \frac{i\mathbf{I}_m \tilde{S}_{yp}(\omega)}{\tilde{S}_{xx}(\omega)} \\
 &= \frac{\mathbf{R}_e \tilde{S}_{yx}(\omega)}{\tilde{S}_{xx}(\omega)} + \frac{i\mathbf{I}_m \tilde{S}_{yx}(\omega)}{\tilde{S}_{xx}(\omega)} \\
 &= \boxed{\frac{\tilde{S}_{yx}(\omega)}{\tilde{S}_{xx}(\omega)}}
 \end{aligned}$$

by (5) lemma and (6) lemma
by Theorem 8.4 page 59



Using Theorem 13.3 (previous) we can see that the optimal **least-squares** operators \hat{G}_{ls} and \hat{H}_{ls} for the **non-linear** operator \mathbf{T} in Figure 13.3 (page 119) (A) and (B) are (next two corollaries)

- | | | |
|------|---|------------------------------|
| (1). | $\hat{G}_{ls}(\omega) = \frac{\tilde{S}_{yx}(\omega)}{\tilde{S}_{xx}(\omega) + \tilde{S}_{uu}(\omega)}$ | for (A)—communication system |
| (2). | $\hat{G}_{ls}(\omega) = \frac{\tilde{S}_{yx}(\omega)}{\tilde{S}_{xx}(\omega) - \tilde{S}_{uu}(\omega)}$ | for (B)—measurement system |
| (3). | $\hat{H}_{ls}(\omega) = \frac{\tilde{S}_{yx}(\omega)}{\tilde{S}_{xx}(\omega)}$ | for either (A) or (B) |

Corollary 13.1. Let \mathbf{S} be the system illustrated in Figure 13.3 page 119 (A).

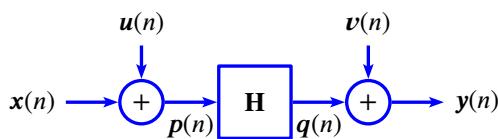
T H M

$$\left\{ \begin{array}{l} \text{hypotheses of Theorem 13.3} \\ \text{page 120} \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} (1). \quad \arg \min_{\hat{G}_{ls}} C_{rq}(\hat{G}_{ls}) = \frac{\tilde{S}_{yx}(\omega)}{\tilde{S}_{xx}(\omega) + \tilde{S}_{uu}(\omega)} \\ (2). \quad \arg \min_{\hat{H}_{ls}} C_{sy}(\hat{H}_{ls}) = \frac{\tilde{S}_{yx}(\omega)}{\tilde{S}_{xx}(\omega)} \end{array} \right\}$$

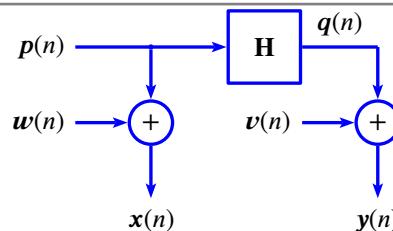
PROOF:

$$\begin{aligned}
 \hat{G}_{ls} &= \frac{\tilde{S}_{yx}(\omega)}{\tilde{S}_{pp}(\omega)} && \text{by Theorem 13.3 page 120} \\
 &= \frac{\tilde{S}_{yx}(\omega)}{\tilde{S}_{xx}(\omega) + \tilde{S}_{uu}(\omega)} && \text{by Theorem 8.1 page 55} \\
 \hat{H}_{ls} &= \frac{\tilde{S}_{yx}(\omega)}{\tilde{S}_{xx}(\omega)} && \text{by Theorem 13.3 page 120}
 \end{aligned}$$





(A) communications LTI additive noise model



(B) measurement LTI additive noise model

Figure 13.4: Additive noise systems with LTI operator \mathbf{H}

Corollary 13.2. Let \mathbf{S} be the system illustrated in Figure 13.3 page 119 (B).

THM	$\left\{ \begin{array}{l} \text{hypotheses of Theorem 13.3} \\ \text{page 120} \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} (1). \quad \arg \min_{\hat{\mathbf{G}}_{ls}} C_{rq}(\hat{\mathbf{G}}_{ls}) = \frac{\tilde{S}_{yx}(\omega)}{\tilde{S}_{xx}(\omega) - \tilde{S}_{uu}(\omega)} \\ (2). \quad \arg \min_{\hat{\mathbf{H}}_{ls}} C_{sy}(\hat{\mathbf{H}}_{ls}) = \frac{\tilde{S}_{yx}(\omega)}{\tilde{S}_{xx}(\omega)} \end{array} \right\}$
-----	--

PROOF:

$$\begin{aligned} \hat{\mathbf{G}} &= \frac{\tilde{S}_{yx}(\omega)}{\tilde{S}_{pp}(\omega)} && \text{by Theorem 13.3 page 120} \\ &= \frac{\tilde{S}_{yx}(\omega)}{\tilde{S}_{xx}(\omega) - \tilde{S}_{uu}(\omega)} && \text{by Theorem 8.1 page 55} \\ \hat{\mathbf{H}} &= \frac{\tilde{S}_{yx}(\omega)}{\tilde{S}_{xx}(\omega)} && \text{by Theorem 13.3 page 120} \end{aligned}$$

It follows immediately from Corollary 13.1 (page 122) and Corollary 13.2 (page 123) that, in the special case of no input noise ($u(n) = 0$), $\hat{\mathbf{H}}_1$ is the optimal least-squares estimate of $\tilde{\mathbf{H}}$ (next corollary).

Corollary 13.3.²⁰ Let \mathbf{S} be the system illustrated in Figure 13.3 page 119 (A) or (B).

COR	$\left\{ \begin{array}{l} (1). \quad \text{hypotheses of Theorem 13.3 and} \\ (2). \quad u(n) = 0 \end{array} \right\} \Rightarrow \left\{ \hat{\mathbf{G}}_{ls}(\omega) = \hat{\mathbf{H}}_{ls}(\omega) = \hat{\mathbf{H}}_1(\omega) \right\}$
-----	---

13.7 Least squares estimates of linear systems

The previous section did assume the estimates $\hat{\mathbf{H}}_1$ and $\hat{\mathbf{H}}_2$ to be *linear time invariant (LTI)*, but it did *not* assume that the system transfer function \mathbf{T} itself to be *LTI*. But making the LTI assumption on \mathbf{H} yields some interesting and insightful results, such as those in this section.

Theorem 13.4 (Estimating \mathbf{H} in communication additive noise system). Let \mathbf{S} be the system illustrated in Figure 13.4 page 123 (A).

²⁰ Bendat and Piersol (1980) pages 98–100 (5.1.1 Optimal Character of Calculations; note: proof minimizing \tilde{S}_{vv} but yields same result), Bendat and Piersol (1993) pages 106–109 (5.1.1 Optimality of Calculations), Bendat and Piersol (2010) pages 187–190 (6.1.4 Optimum Frequency Response Functions)

THM

$$\left\{ \begin{array}{l} (A). \quad \mathbf{H} \text{ is} \\ (B). \quad \mathbf{x}(n) \text{ is} \\ (C). \quad \mathbf{x}(n), \mathbf{u}(n), \text{ and } \mathbf{v}(n) \text{ are} \end{array} \right. \begin{array}{l} \text{LINEAR TIME INVARIANT (LTI) and} \\ \text{WIDE-SENSE STATIONARY (WSS) and} \\ \text{UNCORRELATED} \end{array} \right\}$$

$$\Rightarrow \left\{ \begin{array}{l} (1). \quad \hat{\mathbf{H}}_1(\omega) = \tilde{\mathbf{H}}(\omega) \\ (2). \quad \hat{\mathbf{H}}_2(\omega) = \frac{\tilde{S}_{vv}(\omega)}{\tilde{H}^*(\omega)\tilde{S}_{xx}(\omega)} + \tilde{\mathbf{H}}(\omega) \left[1 + \frac{\tilde{S}_{uu}(\omega)}{\tilde{S}_{xx}(\omega)} \right] \end{array} \right. \text{and} \right\}$$

PROOF:

$$\begin{aligned} \hat{\mathbf{H}}_1(\omega) &\triangleq \frac{\tilde{S}_{yx}(\omega)}{\tilde{S}_{xx}(\omega)} \\ &= \frac{\tilde{\mathbf{H}}(\omega)\tilde{S}_{xx}(\omega)}{\tilde{S}_{xx}(\omega)} \\ &= \tilde{\mathbf{H}}(\omega) \end{aligned}$$

by definition of $\hat{\mathbf{H}}_1$ (Definition 13.2 page 107)

$$\begin{aligned} \hat{\mathbf{H}}_2(\omega) &\triangleq \frac{\tilde{S}_{yy}(\omega)}{\tilde{S}_{xy}(\omega)} \\ &= \frac{\tilde{S}_{yy}(\omega)}{\tilde{\mathbf{H}}^*(\omega)\tilde{S}_{xx}(\omega)} \\ &= \frac{\tilde{S}_{vv}(\omega) + \tilde{S}_{qq}(\omega)}{\tilde{\mathbf{H}}^*(\omega)\tilde{S}_{xx}(\omega)} \\ &= \frac{\tilde{S}_{vv}(\omega) + \tilde{\mathbf{H}}^*(\omega)\tilde{\mathbf{H}}(\omega)\tilde{S}_{pp}(\omega)}{\tilde{\mathbf{H}}^*(\omega)\tilde{S}_{xx}(\omega)} \\ &= \frac{\tilde{S}_{vv}(\omega)}{\tilde{\mathbf{H}}^*(\omega)\tilde{S}_{xx}(\omega)} + \frac{\tilde{\mathbf{H}}^*(\omega)\tilde{\mathbf{H}}(\omega)[\tilde{S}_{xx}(\omega) + \tilde{S}_{uu}(\omega)]}{\tilde{\mathbf{H}}^*(\omega)\tilde{S}_{xx}(\omega)} \\ &= \frac{\tilde{S}_{vv}(\omega)}{\tilde{\mathbf{H}}^*(\omega)\tilde{S}_{xx}(\omega)} + \tilde{\mathbf{H}}(\omega) \left[1 + \frac{\tilde{S}_{uu}(\omega)}{\tilde{S}_{xx}(\omega)} \right] \end{aligned}$$

by Corollary 8.5 page 61

by definition of $\hat{\mathbf{H}}_2$ (Definition 13.3 page 108)

by Corollary 8.5 page 61

by Theorem 8.1 page 55

by Corollary 6.3 page 41

⇒

Theorem 13.5 (Estimating \mathbf{H} in measurement additive noise system). ²¹ Let \mathbf{S} be the system illustrated in Figure 13.4 page 123 (B).

$$\left\{ \begin{array}{l} (A). \quad \mathbf{H} \text{ is} \\ (B). \quad \mathbf{x}(n) \text{ is} \\ (C). \quad \mathbf{x}(n), \mathbf{u}(n), \text{ and } \mathbf{v}(n) \text{ are} \end{array} \right. \begin{array}{l} \text{LINEAR TIME INVARIANT and} \\ \text{WIDE-SENSE STATIONARY and} \\ \text{UNCORRELATED} \end{array} \right\}$$

$$\Rightarrow \left\{ \begin{array}{l} (1). \quad \hat{\mathbf{H}}_1(\omega) = \tilde{\mathbf{H}}(\omega) \left[\frac{1}{1 + \frac{\tilde{S}_{ww}(\omega)}{\tilde{S}_{pp}(\omega)}} \right] \text{ (UNDER-ESTIMATED) and} \\ (2). \quad \hat{\mathbf{H}}_2(\omega) = \tilde{\mathbf{H}}(\omega) \left[1 + \frac{\tilde{S}_{vv}(\omega)}{\tilde{S}_{qq}(\omega)} \right] \text{ (OVER-ESTIMATED)} \end{array} \right\}$$

²¹ Shin and Hammond (2008) page 294 ($H_1(f) = H(f)$ (9.70); $H_2(f) = H(f)(1 + S_{n_y n_y}(f)/S_{yy}(f))$ (9.71)), Shin and Hammond (2008) page 294 ($H_1(f) = H(f)/(1 + S_{n_x n_x}/S_{xx}(f))$ (9.72); $H_2(f) = H(f)$ (9.73)), Mitchell (1982) page 277 ($H_1(f) = H_0(f)/(1 + G_{nn}/G_{uu})$) Mitchell (1982) page 278 ($H_2(f) = H_0(f)(1 + G_{mm}/G_{vv})$)



PROOF:

$$\begin{aligned}
 \hat{H}_1(\omega) &\triangleq \frac{\tilde{S}_{yx}(\omega)}{\tilde{S}_{xx}(\omega)} && \text{by definition of } \hat{H}_1 && (\text{Definition 13.2 page 107}) \\
 &= \frac{\tilde{S}_{pp}(\omega)\tilde{H}(\omega)}{\tilde{S}_{xx}(\omega)} && \text{by Corollary 8.4 page 61} \\
 &= \frac{\tilde{S}_{pp}(\omega)\tilde{H}(\omega)}{\tilde{S}_{pp}(\omega) + \tilde{S}_{ww}(\omega)} && \text{by hypothesis (A)} && \text{and Corollary 6.3 page 41} \\
 &= \tilde{H}(\omega) \left[\frac{1}{1 + \frac{\tilde{S}_{ww}(\omega)}{\tilde{S}_{pp}(\omega)}} \right] \\
 \hat{H}_2(\omega) &\triangleq \frac{\tilde{S}_{yy}(\omega)}{\tilde{S}_{xy}(\omega)} && \text{by definition of } \hat{H}_2 && (\text{Definition 13.3 page 108}) \\
 &= \frac{\tilde{S}_{qq}(\omega) + \tilde{S}_{vv}(\omega)}{\tilde{S}_{xy}(\omega)} && \text{by hypothesis (C)} && \text{and Corollary 8.1 page 56} \\
 &= \frac{\tilde{S}_{qq}(\omega) + \tilde{S}_{vv}(\omega)}{\tilde{S}_{xq}(\omega)} && \text{by hypothesis (C)} && \text{and Theorem 8.4 page 59} \\
 &= \frac{\tilde{S}_{qq}(\omega) + \tilde{S}_{vv}(\omega)}{\tilde{S}_{pq}(\omega)} && \text{by hypothesis (C)} && \text{and Lemma 8.3 page 58} \\
 &= \frac{\tilde{S}_{qq}(\omega) + \tilde{S}_{vv}(\omega)}{\tilde{S}_{qq}(\omega)/\tilde{H}(\omega)} && \text{by LTI hypothesis (A)} && \text{and Corollary 6.3 page 41} \\
 &= \tilde{H}(\omega) \left[1 + \frac{\tilde{S}_{vv}(\omega)}{\tilde{S}_{qq}(\omega)} \right] && \text{by hypotheses (A) and (B)} && \text{and Corollary 6.3 page 41}
 \end{aligned}$$



Corollary 13.4. Let S be the system illustrated in Figure 13.4 (page 123).

COR	$\left\{ \begin{array}{l} (A). \text{ hypotheses of Theorem 13.5 and} \\ (B). u(n) = u(n) = 0 \quad (\text{NO INPUT NOISE}) \end{array} \right\} \implies \left\{ \begin{array}{l} \hat{H}_1(\omega) = \tilde{H}(\omega) \quad (\text{UNBIASED}) \end{array} \right\}$
	$\left\{ \begin{array}{l} (A). \text{ hypotheses of Theorem 13.5 and} \\ (B). v(n) = 0 \quad (\text{NO OUTPUT NOISE}) \end{array} \right\} \implies \left\{ \begin{array}{l} \hat{H}_2(\omega) = \tilde{H}(\omega) \quad (\text{UNBIASED}) \end{array} \right\}$

Lemma 13.4. Let S be the system illustrated in Figure 13.4 (page 123).

LEM	$\left\{ \begin{array}{l} \text{There exists } \kappa(\omega) \text{ such that } \tilde{S}_{vv}(\omega) = \kappa(\omega)\tilde{S}_{uu}(\omega) \end{array} \right\}$ $\implies \left\{ \begin{array}{l} \tilde{S}_{uu}(\omega) = \frac{ \hat{H}(\omega) ^2 \tilde{S}_{xx}(\omega) - \hat{H}(\omega)\tilde{S}_{xy}(\omega) - \hat{H}^*(\omega)\tilde{S}_{xy}^*(\omega) + \tilde{S}_{yy}(\omega)}{\kappa(\omega) + \hat{H}(\omega) ^2} \end{array} \right\}$
-----	---

PROOF:

1. Development based on results of previous chapters:

$$\begin{aligned}
 \tilde{S}_{vv} &= \tilde{S}_{yy} - \tilde{S}_{qq} && \text{by Corollary 8.1 page 56} \\
 &= \tilde{S}_{yy} - \tilde{S}_{pq}\hat{H} && \text{by Corollary 6.3 page 41} \\
 &= \tilde{S}_{yy} - \tilde{S}_{xy}\hat{H} && \text{by Theorem 8.4 page 59} \\
 \tilde{S}_{uu} &= \tilde{S}_{xx} - \tilde{S}_{pp} && \text{by Corollary 8.1 page 56}
 \end{aligned}$$

$$\begin{aligned}
&= \tilde{S}_{xx} - \frac{\tilde{S}_{qp}}{\hat{H}} && \text{by Corollary 6.3 page 41} \\
&= \tilde{S}_{xx} - \frac{\tilde{S}_{yx}}{\hat{H}} && \text{by Theorem 8.4 page 59} \\
\tilde{S}_{uu} \left[|\hat{H}|^2 + \kappa \right] &= |\hat{H}|^2 \tilde{S}_{uu} + \kappa \tilde{S}_{uu} \\
&\triangleq \tilde{S}_{uu} |\hat{H}|^2 + \tilde{S}_{vv} && \text{by definition of } \kappa(\omega) \\
&= |\hat{H}|^2 \left[\tilde{S}_{xx} - \frac{\tilde{S}_{yx}}{\hat{H}} \right] + [\tilde{S}_{yy} - \tilde{S}_{xy} \hat{H}] \\
&= |\hat{H}|^2 \tilde{S}_{xx} - \hat{H}^* \tilde{S}_{yx} - \tilde{S}_{xy} \hat{H} + \tilde{S}_{yy} \\
\implies \tilde{S}_{uu}(\omega) &= \frac{|\hat{H}(\omega)|^2 \tilde{S}_{xx}(\omega) - \hat{H}(\omega) \tilde{S}_{xy}(\omega) - \hat{H}^*(\omega) \tilde{S}_{xy}^*(\omega) + \tilde{S}_{yy}(\omega)}{\kappa(\omega) + |\hat{H}(\omega)|^2}
\end{aligned}$$

2. Development of Wicks and Vold ([Wicks and Vold \(1986\)](#)):

$$\begin{aligned}
\tilde{Y} - \tilde{V} &= \tilde{Q} = \hat{H} \tilde{P} = \hat{H}(\tilde{X} - \tilde{U}) && \text{by definition of } \hat{H} \\
\hat{H}\tilde{U} - \tilde{V} &= \hat{H}\tilde{X} - \tilde{Y} && \text{by left distributive property (Theorem O.4 page 307)} \\
E([\hat{H}\tilde{U} - \tilde{V}] [\hat{H}\tilde{U} - \tilde{V}]^*) &= E([\hat{H}\tilde{X} - \tilde{Y}] [\hat{H}\tilde{X} - \tilde{Y}]^*) \\
|\hat{H}|^2 \tilde{S}_{uu} - \hat{H} \cancel{\tilde{S}_{uv}}^0 - \hat{H}^* \cancel{\tilde{S}_{vu}}^0 + \tilde{S}_{vv} &= |\hat{H}|^2 \tilde{S}_{xx} - \hat{H} \tilde{S}_{xy} - \hat{H}^* \tilde{S}_{xy}^* + \tilde{S}_{yy} && \text{because } u \text{ and } v \text{ are uncorrelated} \\
|\hat{H}|^2 \tilde{S}_{uu} + \kappa \tilde{S}_{uu} &= |\hat{H}|^2 \tilde{S}_{xx} - \hat{H} \tilde{S}_{xy} - \hat{H}^* \tilde{S}_{xy}^* + \tilde{S}_{yy} && \text{by hypothesis}
\end{aligned}$$

⇒

Theorem 13.6. [22](#) Let S be the system illustrated in Figure 13.4 (page 123). Let $\hat{H}_k(\omega)$ be the transfer function estimate defined in Definition 13.7 (page 111).

T H M	$\left\{ \begin{array}{l} (1). \quad \text{There exists } \kappa(\omega) \text{ such that} \\ (2). \quad \tilde{S}_{vv}(\omega) = \kappa(\omega) \tilde{S}_{uu}(\omega) \end{array} \right. \text{ and } \right\} \implies \left\{ \begin{array}{l} \arg \min_{\hat{H}} C(\hat{H}) = \hat{H}_k(\omega) \\ (\hat{H}_k \text{ is the "optimal" estimator for minimizing system noise}) \end{array} \right\}$
-------------	--

PROOF:

1. Let $F \triangleq |\hat{H}(\omega)|^2 \tilde{S}_{xx}(\omega) - \hat{H}(\omega) \tilde{S}_{xy}(\omega) - \hat{H}^*(\omega) \tilde{S}_{xy}^*(\omega) + \tilde{S}_{yy}(\omega)$ (numerator in Lemma 13.4) and
 $G \triangleq \kappa(\omega) + |\hat{H}(\omega)|^2$ (denominator in Lemma 13.4)

2. lemma $\left(\frac{\partial}{\partial \hat{H}_R} \tilde{S}_{uu} \right)$:

$$\begin{aligned}
\boxed{0} &= \frac{1}{2} G^2 0 = \frac{1}{2} G^2 \frac{\partial}{\partial \hat{H}_R} \tilde{S}_{uu} && \text{set } \frac{\partial}{\partial \hat{H}_R} \tilde{S}_{uu} = 0 \text{ to find optimum } \hat{H}_R \\
&= \frac{1}{2} G^2 \frac{\partial}{\partial \hat{H}_R} \frac{F}{G} && \text{by Lemma 13.4 page 125} \\
&= \frac{1}{2} G^2 \frac{(F'G - G'F)}{G^2} && \text{by Quotient Rule} \\
&= \frac{1}{2}(F'G - G'F)
\end{aligned}$$

²² [Wicks and Vold \(1986\)](#) page 898 (has additional s in denominator), [Shin and Hammond \(2008\)](#) page 293 (9.67), [White et al. \(2006\)](#) page 679 (6)

$$\begin{aligned}
 &= \frac{1}{2} [2\hat{H}_R \tilde{S}_{xx} - \tilde{S}_{xy} - \tilde{S}_{xy}^*] G - \frac{1}{2} 2\hat{H}_R F \quad \text{by definition of } F, G \\
 &= \boxed{\hat{H}_R \tilde{S}_{xx} G - G \mathbf{R}_e \tilde{S}_{xy} - \hat{H}_R F}
 \end{aligned}$$

(item (1) page 126)

3. lemma $\left(\frac{\partial}{\partial \hat{H}_I} \tilde{S}_{uu}\right)$:

$$\begin{aligned}
 \boxed{0} &= \frac{1}{2} G^2 0 = \frac{1}{2} G^2 \frac{\partial}{\partial \hat{H}_I} \tilde{S}_{uu} && \text{set } \frac{\partial}{\partial \hat{H}_I} \tilde{S}_{uu} = 0 \text{ to find optimum } \hat{H}_I \\
 &= \frac{1}{2} G^2 0 = \frac{1}{2} G^2 \frac{\partial}{\partial \hat{H}_I} \frac{F}{G} && \text{by Lemma 13.4 page 125} \\
 &= \frac{1}{2} G^2 \frac{(F'G - G'F)}{G^2} && \text{by Quotient Rule} \\
 &= \frac{1}{2} (F'G - G'F) \\
 &= \frac{1}{2} [2\hat{H}_I \tilde{S}_{xx} - i\tilde{S}_{xy} + i\tilde{S}_{xy}^*] G - \frac{1}{2} 2\hat{H}_I F \quad \text{by definition of } F, G \\
 &= \boxed{\hat{H}_I \tilde{S}_{xx} G + G \mathbf{I}_m \tilde{S}_{xy} - \hat{H}_I F}
 \end{aligned}$$

(item (1) page 126)

4. Solve for \hat{H} ...

$$\begin{aligned}
 0 = 0 + i0 &= \frac{1}{2} G^2 0 + \frac{1}{2} G^2 0 = \frac{1}{2} G^2 \frac{\partial}{\partial \hat{H}_R} \tilde{S}_{uu} + i \frac{1}{2} G^2 \frac{\partial}{\partial \hat{H}_I} \tilde{S}_{uu} \\
 &= [\hat{H}_R \tilde{S}_{xx} G - G \mathbf{R}_e \tilde{S}_{xy} - \hat{H}_R F] + i[\hat{H}_I \tilde{S}_{xx} G + G \mathbf{I}_m \tilde{S}_{xy} - \hat{H}_I F] \quad \text{by (2) lemma and (3) lemma} \\
 &= \hat{H} \tilde{S}_{xx} G - \tilde{S}_{xy}^* G - \hat{H} F \quad \text{because } \mathbf{R}_e(z) + i\mathbf{I}_m(z) = z \text{ and } \mathbf{R}_e(z) - i\mathbf{I}_m(z) = z^* \\
 &= \hat{H} \tilde{S}_{xx} G - \tilde{S}_{yx} G - \hat{H} F \quad \text{by Corollary 2.2 page 16} \\
 &= \hat{H} \tilde{S}_{xx} (\kappa + |\hat{H}|^2) - \tilde{S}_{yx} (\kappa + |\hat{H}|^2) - \hat{H} (|\hat{H}|^2 \tilde{S}_{xx} - \hat{H} \tilde{S}_{xy} - \hat{H}^* \tilde{S}_{xy}^* + \tilde{S}_{yy}) \quad \text{by } F, G \text{ defs.} \\
 &= \hat{H} \tilde{S}_{xx} \left(\kappa + |\hat{H}|^2 \right) - \tilde{S}_{yx} \left(\kappa + |\hat{H}|^2 \right) - \hat{H} \left(|\hat{H}|^2 \tilde{S}_{xx} - \hat{H} \tilde{S}_{xy} - \hat{H}^* \tilde{S}_{xy}^* + \tilde{S}_{yy} \right) \\
 &= \kappa \hat{H} \tilde{S}_{xx} - \tilde{S}_{yx} \left(\kappa + |\hat{H}|^2 \right) + \left(\hat{H}^2 \tilde{S}_{xy} + |\hat{H}|^2 \tilde{S}_{xy}^* - \hat{H} \tilde{S}_{yy} \right) \\
 &= \kappa \hat{H} \tilde{S}_{xx} - \kappa \tilde{S}_{yx} - \tilde{S}_{yx} |\hat{H}|^2 + \left(\hat{H}^2 \tilde{S}_{xy} + |\hat{H}|^2 \tilde{S}_{xy}^* - \hat{H} \tilde{S}_{yy} \right) \\
 &= \hat{H}^2 \tilde{S}_{xy} + \hat{H} [\kappa \tilde{S}_{xx} - \tilde{S}_{yy}] - \kappa \tilde{S}_{xy}^* \\
 \Rightarrow \hat{H} &= \frac{(\tilde{S}_{yy} - \kappa \tilde{S}_{xx}) \pm \sqrt{(\tilde{S}_{yy} - \kappa \tilde{S}_{xx})^2 + 4\kappa |\tilde{S}_{xy}|^2}}{2\tilde{S}_{xy}}
 \end{aligned}$$

by Quadratic Equation



13.8 Coherence

13.8.1 Application

Coherence has two basic purposes:

1. The *coherence* of x and y is a measure of how closely x and y are statistically related. That is, it is an indication of how much x and y “cohere” or “stick” together

2. The *coherence* of x and y is a measure of how reliable are the estimates \hat{H}_1 and \hat{H}_2 (Definition 13.2 page 107, Definition 13.3 page 108). If the coherence is 0.70 or above, then we can have high confidence that the estimates \hat{H}_1 and \hat{H}_2 are “good” estimates.²³

13.8.2 Definitions

Definition 13.12. ²⁴ Let S be a system with input $x(n)$ and output $y(n)$.

DEF

The **complex coherence function** is defined as $C_{xy}(\omega) \triangleq \frac{\tilde{S}_{xy}^*(\omega)}{\sqrt{\tilde{S}_{xx}(\omega)\tilde{S}_{yy}(\omega)}}$

The **ordinary coherence function** is defined as $\gamma_{xy}^2(\omega) \triangleq \frac{|\tilde{S}_{xy}(\omega)|^2}{\tilde{S}_{xx}(\omega)\tilde{S}_{yy}(\omega)}$

Proposition 13.7.

P R P
$$\gamma_{xy}^2(\omega) = \frac{\hat{H}_1(\omega)}{\hat{H}_2(\omega)}$$

PROOF:

$$\boxed{\gamma_{xy}^2(\omega)} \triangleq \frac{|\tilde{S}_{xy}|^2}{\tilde{S}_{xx}\tilde{S}_{yy}} \quad \text{by definition of } \gamma_{xy}^2 \quad (\text{Definition 13.12 page 128})$$

$$= \frac{\tilde{S}_{xy}^*/\tilde{S}_{xx}}{\tilde{S}_{yy}/\tilde{S}_{xy}} \triangleq \boxed{\frac{\hat{H}_1}{\hat{H}_2}} \quad \text{by definitions of } \hat{H}_1 \text{ and } \hat{H}_2 \quad (\text{Definition 13.2 page 107, Definition 13.3 page 108})$$

Remark 13.2. Note that the *complex transmissibility* \tilde{T}'_{xy} of Remark 13.1 provides a nice mathematical symmetry (always a good sign of good direction) with *coherence* in the system identification family tree. In particular, note that the following:

R E M
$$C_{xy} \triangleq \sqrt{\frac{\hat{H}_1^*}{\hat{H}_2}} \text{ whereas } \tilde{T}'_{xy} \triangleq \sqrt{\hat{H}_1 \hat{H}_2}$$

PROOF:

$$\sqrt{\frac{\hat{H}_1^*(\omega)}{\hat{H}_2(\omega)}} \quad \text{by definition of } \hat{H}_{gm} \quad (\text{Definition 13.5 page 109})$$

13.8.3 A warning

Estimators yield, as the name implies, estimates. These estimates in general contain some error.

²³  Liang and Lee (2015) pages 363–365 (7.4.2 COHERENCE FUNCTION)

²⁴  Chen et al. (2012) page 4699(1), (2),  Liang and Lee (2015) pages 363–365 (7.4.2 Coherence function),  Ewins (1986) page 131 ($\gamma^2 = H_1(\omega)/H_2(\omega)$ (3.8))

Example 13.1 (The K=1 Welch estimate of coherence). Suppose we have two *uncorrelated* stationary sequences $x(n)$ and $y(n)$. Then, there CSD $S_{xy}(\omega)$ should be 0 because

$$\begin{aligned} S_{xy}(\omega) &\triangleq \check{\mathbf{F}}\mathbf{E}_{xy}(m) \\ &= \check{\mathbf{F}}\mathbf{E}[x(n)y[n+m]] \\ &= \check{\mathbf{F}}[\mathbf{E}_x(n)][\mathbf{E}_y[n+m]] \\ &= \check{\mathbf{F}}[0][0] \\ &= 0 \end{aligned}$$

This will give a coherence of 0 also:

$$C(\omega) = \frac{S_{xy}}{\sqrt{S_{xx}S_{yy}}} = 0$$

However, the Welch estimate with $K = 1$ will yield

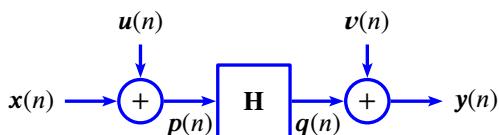
$$\begin{aligned} |C(\omega)| &= \left| \frac{S_{xy}}{\sqrt{S_{xx}S_{yy}}} \right| \\ &= \left| \frac{(\tilde{\mathbf{F}}x)(\tilde{\mathbf{F}}y)^*}{\sqrt{|\tilde{\mathbf{F}}x|^2|\tilde{\mathbf{F}}y|^2}} \right| \\ &= 1 \end{aligned}$$

CHAPTER 14

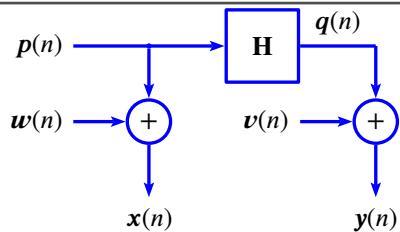
NOISE ESTIMATION

Estimating noise in a system is difficult and many estimation methods are possible.

1. [Thong et al. \(2001\)](#)
2. [Zheng et al. \(2002\)](#)
3. [Kim and Kamel \(2003\)](#)
4. [Kamel and Sim \(2004\)](#)



(A) **communications LTI additive noise model**



(B) **measurement LTI additive noise model**

Figure 14.1: Additive noise systems with LTI operator \mathbf{H}

CHAPTER 15

MOMENT ESTIMATION

15.1 Mean Estimation

Theorem 15.1. Let $\hat{\mu} \triangleq \sum_{n=1}^N \lambda_n x_n$ with $\sum_{n=1}^N \lambda_n = 1$ be the ARITHMETIC MEAN (Definition N.4 page 295).

T
H
M

$$\left\{ \begin{array}{l} (A). (\{x_n\}) \text{ is WIDE SENSE STATIONARY} \\ (B). \mu \triangleq E x_n \\ (C). (\{x_n\}) \text{ is UNCORRELATED} \\ (D). \hat{\mu} \triangleq \sum_{n=1}^N \lambda_n x_n \quad (\text{ARITHMETIC MEAN}) \end{array} \right. \text{ and } \left\{ \begin{array}{l} (1). E \hat{\mu} = \mu \quad (\text{UNBIASED}) \text{ and} \\ (2). \text{var}(\hat{\mu}) = \sigma^2 \sum_{n=1}^N \lambda_n^2 \quad \text{and} \\ (3). \text{mse}(\hat{\mu}) = \sigma^2 \sum_{n=1}^N \lambda_n^2 \end{array} \right. \Rightarrow$$

PROOF:

$$\begin{aligned}
 E\hat{\mu} &\triangleq E \sum_{n \in \mathbb{Z}} \lambda_n x_n && \text{by definition of } \textit{arithmetic mean} \quad (\text{Definition N.4 page 295}) \\
 &= \sum_{n \in \mathbb{Z}} \lambda_n E x_n && \text{by } \textit{linearity of } E \quad (\text{Theorem 1.1 page 4}) \\
 &= \mu \sum_{n \in \mathbb{Z}} \lambda_n && \text{by } \textit{WSS hypothesis} \quad (\text{A}) \\
 &= \mu && \text{by } \sum \lambda_n = 1 \text{ hypothesis} \quad (\text{Definition N.4 page 295}) \\
 \text{var}(\hat{\mu}) &\triangleq E(\hat{\mu} - E\hat{\mu})^2 && \text{by definition of } \textit{variance} \\
 &= E(\hat{\mu} - \mu)^2 && \text{by previous result} \\
 &= E \left(\sum_{n=1}^N \lambda_n x_n - \mu \right)^2 && \text{by definition of } \hat{\mu} \\
 &= E \left[\sum_{n=1}^N \lambda_n x_n - \mu \underbrace{\sum_{n=1}^N \lambda_n}_1 \right]^2 && \text{by } \sum \lambda_n = 1 \text{ hypothesis} \quad (\text{Definition N.4 page 295})
 \end{aligned}$$

$$\begin{aligned}
&= E \left[\sum_{n=1}^N \lambda_n (x_n - \mu) \right]^2 \\
&= E \left[\sum_{n=1}^N \lambda_n (x_n - \mu) \sum_{m=1}^N \lambda_m (x_m - \mu) \right] \\
&= \sum_{n=1}^N \sum_{m=1}^N \lambda_n \lambda_m (E[(x_n - \mu)(x_m - \mu)]) \\
&= \sum_{n=1}^N \sum_{m=1}^N \lambda_n \lambda_m (E[x_n x_m] - \mu E[x_n] - \mu E[x_m] + \mu^2) \\
&= \sum_{n=1}^N \sum_{m=1}^N \lambda_n \lambda_m (E[x_n x_m] - \mu^2 - \mu^2 + \mu^2) \\
&= \sum_{n=1}^N \sum_{m=1}^N \lambda_n \lambda_m (E[x_n x_m] - \mu^2) \\
&= \sum_{n=1}^N \lambda_n^2 (E[x_n^2] - \mu^2) + \sum_{n=1}^N \sum_{m \neq n} \lambda_n \lambda_m (E[x_n x_m] - \mu^2) \\
&= \sum_{n=1}^N \lambda_n^2 (E[x_n^2] - \mu^2) + \sum_{n=1}^N \sum_{m \neq n} \lambda_n \lambda_m (E x_n E x_m - \mu^2) \\
&= \sum_{n=1}^N \lambda_n^2 \sigma^2 + \sum_{n=1}^N \sum_{m \neq n} \lambda_n \lambda_m (\mu \mu - \mu^2) \quad \text{by WSS hypothesis} \\
&= \sigma^2 \sum_{n=1}^N \lambda_n^2
\end{aligned} \tag{A}$$

$$\text{mse}(\hat{\mu}) = E(\hat{\mu} - E\hat{\mu})^2 + (E\hat{\mu} - \mu)^2 \quad \text{by Theorem 9.2 page 71}$$

$$\begin{aligned}
&= \sigma^2 \sum_{n=1}^N \lambda_n^2 + (\mu - \mu)^2 \quad \text{by previous results} \\
&= \sigma^2 \sum_{n=1}^N \lambda_n^2
\end{aligned}$$

⇒

Definition 15.1.

D E F The **average** $\hat{\mu}$ of a length N sequence $(x_n)_1^N$ is defined as $\hat{\mu} \triangleq \frac{1}{N} \sum_{n=1}^N x_n$

Corollary 15.1.¹

C O R	$ \left\{ \begin{array}{l} (A). \quad (x_n) \text{ is WIDE SENSE STATIONARY} \quad \text{and} \\ (B). \quad \mu \triangleq E x_n \quad \text{and} \\ (C). \quad (x_n) \text{ is UNCORRELATED} \quad \text{and} \\ (D). \quad \hat{\mu} \triangleq \frac{1}{N} \sum_{n=1}^N x_n \quad (\text{AVERAGE}) \end{array} \right. $	$ \Rightarrow \left\{ \begin{array}{l} (1). \quad E \hat{\mu} = \mu \quad (\text{UNBIASED}) \quad \text{and} \\ (2). \quad \text{var}(\hat{\mu}) = \frac{\sigma^2}{N} \quad \text{and} \\ (3). \quad \text{mse}(\hat{\mu}) = \frac{\sigma^2}{N} \quad (\text{CONSISTENT}) \end{array} \right. $
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¹  Kay (1988) page 45 (§“3.3 ESTIMATION THEORY”),  CLARKSON (1993) PAGES 52–54 (§“2.6.2 ESTIMATION OF MOMENTS — TIME AVERAGES”),

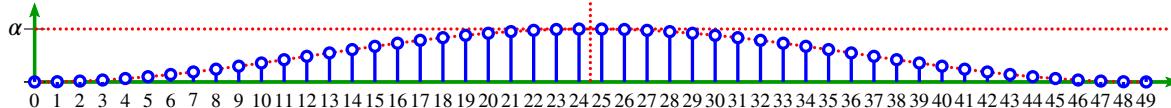


PROOF: These results follow from Theorem 15.1 (page 133) with $\lambda_n = \frac{1}{N}$.

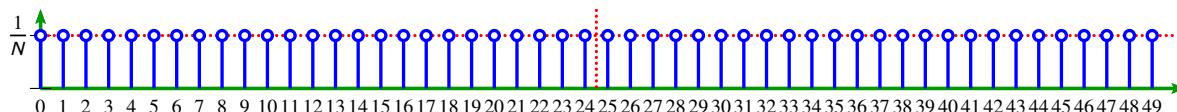
The *arithmetic mean* estimator $\hat{\mu} \triangleq \sum \lambda_n x_n$ is *unbiased* and *consistent* for any $\sum \lambda_n = 1$ and yields *mean square error* $\text{mse}(\hat{\mu}) = \sigma^2 \sum \lambda_n^2$ (Theorem 15.1 page 133). But...

1. Said qualitatively: "What is the 'best' sequence (λ_n) to use?"
2. Said quantitatively: "What sequence (λ_n) yields the smallest $\text{mse}(\hat{\mu})$?"

For example, would fashioning (λ_n) to be a scaled version of a standard window function, like the *Hanning window*² illustrated below, yield the best $\text{mse}(\hat{\mu})$?



Theorem 15.2 (page 136) answers question (2) stating that the best sequence in terms of minimal mse is the sequence $(\lambda_n) \triangleq \frac{1}{N} (\dots, 1, 1, 1, \dots)$, which is the *average* estimator, which yields $\text{mse}(\hat{\mu}) = \frac{\sigma^2}{N}$ (Corollary 15.1 page 134).



That is, it turns out that $\frac{1}{N} \leq \sum \lambda_n^2$ for all possible sequences (λ_n) . This fact is demonstrated by Lemma 15.1 (next), which in turn follows more or less directly from the ubiquitous *Cauchy-Schwarz Inequality* (Theorem N.6 page 298, Theorem K.2 page 256).

Even further strengthening the average as choice estimator is Corollary 16.1 (page 141) which demonstrates that in the case where (x_n) is *uncorrelated* and *Gaussian*, then the optimal maximum likelihood estimator is the average.

Lemma 15.1.

LEM	$\left\{ \sum_{n=1}^N \lambda_n = 1 \right\}$	\Rightarrow	$\left\{ \frac{1}{N} \leq \sum_{n=1}^N \lambda_n^2 \right\}$
-----	---	---------------	--

PROOF:

1. Let the sequence (a_n) be defined as $(a_n) \triangleq (\dots, 1, 1, 1, \dots)$
2. Let *inner product* $\langle a_n | b_n \rangle$ be defined as $\langle a_n | b_n \rangle \triangleq \sum_{n=1}^N a_n b_n$
3. Let *norm* $\|a_n\|$ be defined as $\|a_n\| \triangleq \sqrt{\sum_{n=1}^N a_n^2}$
4. Proof of lemma:

$$\begin{aligned}
 \left[\frac{1}{N} \right] &= \frac{1}{N} \left(\sum_{n=1}^N \lambda_n \right)^2 && \text{by } \sum_{n=1}^N \lambda_n = 1 \text{ hypothesis} \\
 &= \frac{1}{N} \left(\sum_{n=1}^N a_n \lambda_n \right)^2 && \text{by } (a_n) \triangleq (\dots, 1, 1, 1, \dots) \text{ definition} && \text{(definition 1 page 135)} \\
 &\leq \frac{1}{N} \left(\sum_{n=1}^N a_n^2 \right) \left(\sum_{n=1}^N \lambda_n^2 \right) && \text{by Cauchy-Schwartz inequality} && \text{(Theorem N.6 page 298)}
 \end{aligned}$$

² Abdaheer (2009), page 130

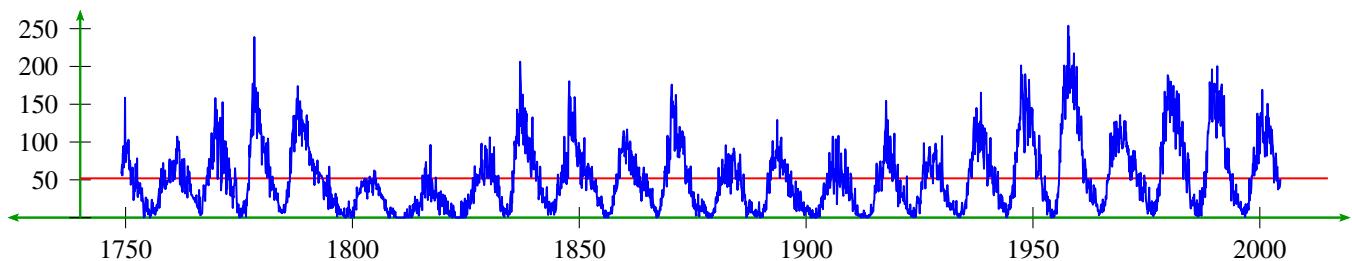


Figure 15.1: Sunspots data from 1749 into 2004

$$\begin{aligned} &\triangleq \frac{1}{N} \left(\sum_{n=1}^N 1^2 \right) \left(\sum_{n=1}^N \lambda_n^2 \right) \quad \text{by definition of } (\lambda_n) \\ &= \boxed{\sum_{n=1}^N \lambda_n^2} \end{aligned} \quad \text{(definition 1 page 135)}$$

⇒

Theorem 15.2. Let $\text{mse}(\text{average mean})$ be the mean square error of the AVERAGE estimator (Corollary 15.1 page 134) and $\text{mse}(\text{arithmetic mean})$ be the mean square error of the ARITHMETIC estimator (Theorem 15.1 page 133).

P R P $\text{mse}(\text{average mean}) \leq \text{mse}(\text{arithmetic mean})$

PROOF:

$$\begin{aligned} \text{mse}(\text{average mean}) &= \sigma^2 \frac{1}{N} && \text{by Corollary 15.1 page 134} \\ &\leq \sigma^2 \sum_{n=1}^N \lambda_n^2 && \text{by Lemma 15.1 page 135} \\ &= \text{mse}(\text{arithmetic mean}) && \text{by Theorem 15.1 page 133} \end{aligned}$$

⇒

Example 15.1. The R code to the right calculates the *average* (Definition N.4 page 295) number of sunspots from 1749 into 2013 (Figure 15.1 page 136).

```

1 data(sunspots);
2 x    = sunspot.month;
3 N    = length(x);
4 avg = sum(x) / N;
5 print(avg);
6 plot(x, col="blue");
7 lines(c(start(x)[1], end(x)[1]), c(avg, avg), col="red");

```

15.2 Variance Estimation

If we know the true *mean* μ of a stationary random process (x_n) , then a reasonable estimate of the variance might be $\frac{1}{N} \sum_{n=1}^N (x_n - \mu)^2$. This estimate has the highly touted property of being *unbiased*:

$$E\left[\frac{1}{N} \sum_{n=1}^N (x_n - \mu)^2\right] = \frac{1}{N} \sum_{n=1}^N E[(x_n - \mu)^2] = \frac{1}{N} \sum_{n=1}^N \sigma^2 = \sigma^2$$

Very good. However, in many cases we don't know the **true mean** μ , but rather only have an **estimated mean** $\hat{\mu} \triangleq \frac{1}{N} = \sum_{n=1}^N x_n$. In this case, substituting in the estimated mean for the true mean as in $\hat{\text{var}}_B(\langle x_n \rangle)$ (next definition) yields a *biased* variance estimate (next theorem).

Definition 15.2. ³ Let $\hat{\mu}$ be an estimate of the mean of a random sequence $\langle x_n \rangle$.

DEF

The **sample variance** $\hat{\text{var}}(\langle x_n \rangle)$ is defined as

$$\hat{\text{var}}(\langle x_n \rangle) \triangleq \frac{1}{N-1} \sum_{n=1}^N (x_n - \hat{\mu})^2$$

The **biased sample variance** $\hat{\text{var}}_B(\langle x_n \rangle)$ is here defined as

$$\hat{\text{var}}_B(\langle x_n \rangle) \triangleq \frac{1}{N} \sum_{n=1}^N (x_n - \hat{\mu})^2$$

The factor $\frac{N}{N-1}$ such that $\hat{\text{var}}(\langle x_n \rangle) = \frac{N}{N-1} \hat{\text{var}}_B(\langle x_n \rangle)$ is known as "*Bessel's correction*". Why such "correction" would be useful at all is demonstrated by Theorem 15.3 (next). Theorem 15.3 demonstrates that the *biased sample variance* $\hat{\text{var}}_B(\langle x_n \rangle)$ is *biased*, and multiplication by $\frac{N}{N-1}$ makes it *unbiased*.

Theorem 15.3. ⁴ Let $\hat{\mu}$ be the AVERAGE (Definition N.4 page 295) of a sequence $\langle x_n \rangle$. Let $\mu^4 \triangleq E[(x_n - \mu)^4]$ be the 4TH CENTRAL MOMENT of x_n .

THM

$$\left. \begin{array}{l} (A). \quad \langle x_n \rangle \text{ is WSS and} \\ (B). \quad \mu \triangleq E x_n \quad \text{and} \\ (C). \quad \langle x_n \rangle \text{ is UNCORRELATED} \end{array} \right\} \Rightarrow \left\{ \begin{array}{ll} (1). & E \hat{\text{var}}_B(x_n) = \frac{N-1}{N} \sigma^2 & \text{(BIASED)} \quad \text{and} \\ (2). & E \hat{\text{var}}(x_n) = \sigma^2 & \text{(UNBIASED)} \quad \text{and} \\ (3). & \text{var}[\hat{\text{var}}(x_n)] = \frac{1}{N} \left[\mu^4 - \left(\frac{N-3}{N-1} \right) \sigma^4 \right] & \text{(CONSISTENT)} \end{array} \right.$$

PROOF:

1. lemma: $E(x_n \hat{\mu}) = \frac{1}{N} \sigma^2 + \mu^2$. Proof:

$$\begin{aligned} E(x_n \hat{\mu}) &\triangleq E\left(x_n \frac{1}{N} \sum_{m=1}^N x_m\right) && \text{by definition of average} && \text{(Definition N.4 page 295)} \\ &= E\left(\frac{1}{N} \sum_{m=1}^N x_n x_m\right) \\ &= \frac{1}{N} \sum_{m=1}^N E(x_n x_m) && \text{by linearity of } E && \text{(Theorem 1.1 page 4)} \\ &= \frac{1}{N} \left[E x_n^2 + \sum_{m \neq n} E(x_n x_m) \right] \\ &= \frac{1}{N} \left[E x_n^2 + \sum_{m \neq n} (E x_n)(E x_m) \right] && \text{by uncorrelated hypothesis} && \text{(C)} \\ &= \frac{1}{N} [(\sigma^2 + \mu^2) + (N-1)\mu^2] && \text{by Corollary 1.3 (page 5)} \\ &= \frac{1}{N} \sigma^2 + \mu^2 \end{aligned}$$

³ Wilks (1963a), page 199 (§“8.2 MEANS AND VARIANCES OF MEAN, VARIANCE,...”), Wilks (1963b), PAGE 199 (§“(B) MEAN AND VARIANCE OF SAMPLE VARIANCE”), Kenney (1947), PAGE 125 (“BESSEL'S CORRECTION”), Bajpai (1967), PAGE 509 (???)

⁴ Wilks (1963a), page 199 (§“8.2 MEANS AND VARIANCES OF MEAN, VARIANCE,...”), Tucker (1965) PAGE 111 (§“8.2 UNBIASED AND CONSISTENT ESTIMATES”), Stuart and Ord (1991) PAGE 609 (§“UNBIASED ESTIMATORS”)

2. Proof for (1):

$$\begin{aligned}
 \text{Evár}_B((x_n)) &\triangleq E\left[\frac{1}{N} \sum_{n=1}^N (x_n - \hat{\mu})^2\right] && \text{by definition of } \text{vár}_B \quad (\text{Definition 15.2 page 137}) \\
 &= \frac{1}{N} E\left[\sum_{n=1}^N \left(x_n - \underbrace{\mu + \mu - \hat{\mu}}_0\right)^2\right] \\
 &= \frac{1}{N} \sum_{n=1}^N \left[E(x_n - \mu)^2 + 2E[(x_n - \mu)(\mu - \hat{\mu})] + E\left(\mu - \underbrace{\hat{\mu}}_{E\mu}\right)^2 \right] \\
 &= \frac{1}{N} \sum_{n=1}^N \left[\sigma^2 + 2E[x_n \mu - x_n \hat{\mu} - \mu^2 + \mu \hat{\mu}] + \frac{1}{N} \sigma^2 \right] \\
 &= \frac{1}{N} \sum_{n=1}^N \left[\sigma^2 + 2[\mu^2 - E(x_n \hat{\mu}) - \mu^2 + \mu^2] + \frac{1}{N} \sigma^2 \right] \quad \text{by Corollary 15.1 page 134} \\
 &= \frac{1}{N} \sum_{n=1}^N \left[\sigma^2 + 2\left[\mu^2 - \left(\mu^2 + \frac{1}{N} \sigma^2\right)\right] + \frac{1}{N} \sigma^2 \right] \quad \text{by } \textit{unbiased prop. of } \hat{\mu} \quad ((1) \text{ lemma page 137}) \\
 &= \frac{1}{N} \sum_{n=1}^N \left[\sigma^2 - \frac{1}{N} \sigma^2 \right] \\
 &= \frac{N-1}{N} \sigma^2
 \end{aligned}$$

3. Proof for (2):

$$\begin{aligned}
 \text{Evár}((x_n)) &\triangleq E\left[\frac{1}{N-1} \sum_{n=1}^N (x_n - \hat{\mu})^2\right] && \text{by definition of } \text{vár} \quad (\text{Definition 15.2 page 137}) \\
 &= \frac{N}{N-1} E\left[\frac{1}{N} \sum_{n=1}^{N-1} (x_n - \hat{\mu})^2\right] && \text{by } \textit{linearity of } E \quad (\text{Theorem 1.1 page 4}) \\
 &= \frac{N}{N-1} \left[\frac{N-1}{N} \sigma^2 \right] && \text{by } \text{vár}_B \text{ result} \quad (\text{item (2) page 138}) \\
 &= \sigma^2
 \end{aligned}$$

4. lemma: $E[(\text{vár})^2] = \frac{\mu^4}{N} + \frac{(N-1)^2+2}{N(N-1)} \sigma^4$. Proof: No proof here at this time. The assertion is made by  Wilks (1963a), page 199 who also without there supplying a proof says, “Carrying out similar mean value operations we find after some reduction that” the result follows.

$$\begin{aligned}
 E[(\text{vár})^2] &\triangleq E\left[\left(\frac{1}{N-1} \sum_{n=1}^N (x_n - \hat{\mu})^2\right)^2\right] && \text{by definition of } \text{vár} \quad (\text{Definition 15.2 page 137}) \\
 &= E\left[\left(\frac{1}{N-1} \sum_{n=1}^N (x_n - \hat{\mu})^2\right) \left(\frac{1}{N-1} \sum_{m=1}^N (x_m - \hat{\mu})^2\right)\right] \\
 &= \left(\frac{1}{N-1}\right)^2 E\left[\sum_{n=1}^N \sum_{m=1}^N (x_n - \hat{\mu})^2 (x_m - \hat{\mu})^2\right] \\
 &= \left(\frac{1}{N-1}\right)^2 E\left[\sum_{n=1}^N \sum_{m=1}^N (x_n^2 - 2x_n \hat{\mu} + \hat{\mu}^2) (x_m^2 - 2x_m \hat{\mu} + \hat{\mu}^2)\right]
 \end{aligned}$$



$$\begin{aligned}
&= \left(\frac{1}{N-1} \right)^2 E \left[\sum_{n=1}^N \sum_{m=1}^N \left[+ (x_n^2 x_m^2 - 2\hat{\mu} x_n^2 x_m + \hat{\mu}^2 x_n^2) + (-2\hat{\mu} x_n x_m^2 + 4\hat{\mu}^2 x_n x_m - 2x_n \hat{\mu}^3) \right] \right] \\
&= \left(\frac{1}{N-1} \right)^2 \sum_{n=1}^N \sum_{m=1}^N \left[+ E[x_n^2 x_m^2] - 2E[\hat{\mu} x_n^2 x_m] - 2E[\hat{\mu} x_n x_m^2] + E[\hat{\mu}^2 x_n^2] + E[\hat{\mu}^2 x_m^2] \right. \\
&\quad \left. + 4E[\hat{\mu}^2 x_n x_m] - 2E[\hat{\mu}^3 x_n] - 2E[\hat{\mu}^3 x_m] + E[\hat{\mu}^4] \right] \\
&= \left(\frac{1}{N-1} \right)^2 \sum_{n=1}^N \sum_{m=1}^N \left[+ E[x_n^2 x_m^2] - 4E[\hat{\mu} x_n^2 x_m] + 2E[\hat{\mu}^2 x_n^2] \right. \\
&\quad \left. + 4E[\hat{\mu}^2 x_n x_m] - 4E[\hat{\mu}^3 x_n] + E[\hat{\mu}^4] \right] \\
&\stackrel{?}{=} \frac{\mu^4}{N} + \frac{(N-1)^2 + 2}{N(N-1)} \sigma^4
\end{aligned}$$

5. Proof for (3):

$$\begin{aligned}
\text{var}[\hat{\text{var}}(x_n)] &\triangleq E[(\hat{\text{var}} - E\hat{\text{var}})^2] && \text{by definition of } \hat{\text{var}} && (\text{Definition 15.2 page 137}) \\
&= E[(\hat{\text{var}} - \sigma^2)^2] && \text{by (2)} && (\text{item (3) page 138}) \\
&= E[(\hat{\text{var}})^2 - 2\sigma^2 \hat{\text{var}} + (\sigma^2)^2] && \text{by Binomial Theorem} \\
&= E[(\hat{\text{var}})^2] - 2\sigma^2 E[\hat{\text{var}}] + E[(\sigma^2)^2] && \text{by linearity of } E && (\text{Theorem 1.1 page 4}) \\
&= E[(\hat{\text{var}})^2] - 2(\sigma^2)^2 + (\sigma^2)^2 && \text{by (2)} && (\text{item (3) page 138}) \\
&= \left[\frac{\mu^4}{N} + \left(\frac{(N-1)^2 + 2}{N(N-1)} \right) \sigma^4 \right] - \sigma^4 && \text{by (4) lemma} \\
&= \frac{1}{N} \left[\mu^4 + \left(\frac{(N^2 - N + 1) + 2 - N(N-1)}{N-1} \right) \sigma^4 \right] \\
&= \frac{1}{N} \left[\mu^4 - \left(\frac{N-3}{N-1} \right) \sigma^4 \right]
\end{aligned}$$



15.3 Estimates in terms of moment estimates

Definition 15.3.

The **order- k moment estimate** is here defined as

DEF

$$\hat{M}_k(x_n) \triangleq \frac{1}{N} \sum_{n=1}^N x_n^k$$

Proposition 15.1.

P	$\hat{\mu}(x_n) = \hat{M}_1$
P	$\hat{\text{var}}(x_n) = \frac{N}{N-1} \hat{M}_2 - \frac{N}{N-1} \hat{M}_1^2$

PROOF:

$$\begin{aligned}\hat{\mu}(x_n) &\triangleq \frac{1}{N} \sum_{n=1}^N x_n && \text{by definition of } \hat{\mu} && (\text{Definition N.4 page 295}) \\ &\triangleq \hat{M}_1 && \text{by definition of } \hat{M}_1 && (\text{Definition 15.3 page 139})\end{aligned}$$

$$\begin{aligned}\hat{v}\hat{a}\hat{r}(x_n) &\triangleq \frac{1}{N-1} \sum_{n=1}^N (x_n - \hat{\mu})^2 && \text{by definition of } \hat{v}\hat{a}\hat{r} && (\text{Definition 15.2 page 137}) \\ &= \frac{1}{N-1} \sum_{n=1}^N (x_n^2 - 2x_n\hat{\mu} + (\hat{\mu})^2) \\ &= \frac{1}{N-1} \sum_{n=1}^N x_n^2 - 2\frac{1}{N-1} \sum_{n=1}^N x_n\hat{\mu} + \frac{1}{N-1} \sum_{n=1}^N (\hat{\mu})^2 \\ &= \frac{N}{N-1} \underbrace{\frac{1}{N} \sum_{n=1}^N x_n^2}_{\hat{M}_2} - 2\hat{\mu} \underbrace{\frac{N}{N-1} \frac{1}{N} \sum_{n=1}^N x_n}_{\hat{M}_1} + \frac{N}{N-1} \underbrace{(\hat{\mu})^2}_{\hat{M}_1^2} \\ &= \frac{N}{N-1} \hat{M}_2 - \frac{N}{N-1} \hat{M}_1^2\end{aligned}$$

⇒

15.4 Recursive forms

In software/firmware implementations, recursive forms are very useful and efficient.

Proposition 15.2.⁵

P	R	P	$\hat{\mu}_N = \underbrace{\hat{\mu}_{N-1}}_{\text{new}} + \underbrace{\frac{1}{N} \underbrace{[x_N - \hat{\mu}_{N-1}]}_{\text{error}}}_{\text{previous weight}}$
---	---	---	---

PROOF:

$$\begin{aligned}\hat{\mu}_N &\triangleq \frac{1}{N} \sum_{n=1}^N x_n && \text{by definition of average} && (\text{Definition N.4 page 295}) \\ &= \frac{1}{N} x_N + \frac{1}{N} \sum_{n=1}^{N-1} x_n \\ &= \frac{1}{N} x_N + \frac{N-1}{N} \left(\frac{1}{N-1} \right) \sum_{n=1}^{N-1} x_n \\ &\triangleq \frac{1}{N} x_N + \frac{N-1}{N} \hat{\mu}_{N-1} && \text{by definition of average} && (\text{Definition N.4 page 295}) \\ &= \frac{1}{N} x_N + \hat{\mu}_{N-1} - \frac{1}{N} \hat{\mu}_{N-1} \\ &= \hat{\mu}_{N-1} + \frac{1}{N} [x_N - \hat{\mu}_{N-1}]\end{aligned}$$

⇒

⁵ Candy (2009) pages 11–12 (Example 1.3), Candy (2016) pages 12–13 (Example 1.3)



CHAPTER 16

DENSITY ESTIMATION

16.1 Introduction

Moment estimation is extremely useful for model-building when a *type* of parameterized *probability density function (pdf)* $p_x(x)$ (Definition B.2 page 160) is known or more likely *assumed*, but the *parameters* themselves are *not known*. Examples of parameterized pdfs include the following:

- The *Uniform Distribution* with parameter mean μ (Definition C.1 page 165).
- The *Gamma Distribution* with parameter b (Definition C.3 page 167).
- The *Chi-square Distribution* with parameter variance σ^2 (Definition C.5 page 168).
- The *Gaussian Distribution* with parameters mean μ and variance σ^2 (Definition C.2 page 166).
- The *Rayleigh Distribution* with parameters radius r and variance σ^2 (Definition C.10 page 171).

In the case of distributions with mean and/or variance parameters, these parameters can be estimated using the techniques in this chapter, and the technique of estimating the pdf in this manner is called **parametric density estimation**.¹ If a distribution type is not known and not assumed, then the distribution itself must be estimated using **nonparametric density estimation** (CHAPTER 16 page 141)

16.2 Parametric density estimation

Corollary 16.1.

COR

$$\left\{ \begin{array}{l} (A). \quad (\mathbf{x}_n) \text{ is UNCORRELATED} \quad \text{and} \\ (B). \quad \mathbf{x}_n \text{ is GAUSSIAN} \end{array} \right\} \implies \left\{ \begin{array}{l} (1). \quad \hat{\mu}_{\text{ml}} = \frac{1}{N} \sum_{n=1}^N \mathbf{x}_n \quad \text{and} \\ (2). \quad \hat{\mu}_{\text{ml}} \text{ is CONSISTENT} \quad \text{and} \\ (3). \quad \hat{\mu}_{\text{ml}} \text{ is EFFICIENT} \end{array} \right\}$$

PROOF: This result follows directly from Theorem 11.9 (page 93) with

¹ Gramacki (2017) page 2 (§“1.1 Background”)

$$\begin{aligned}
 y(t) &\triangleq x(t; \theta) + v(t) && \text{where } v(t) \text{ is a zero-mean white Gaussian noise process} \\
 x(t; \theta) &\triangleq g(\theta) \\
 &\triangleq \theta \\
 &\triangleq \mu \\
 x_n &\triangleq \dot{y}_n \\
 &\triangleq \langle y(t) | \psi_n(t) \rangle \\
 &\triangleq \langle y(t) | \delta(t - n\tau) \rangle \\
 &\triangleq \int_{t \in \mathbb{R}} y(t) \delta(t - n\tau) dt \\
 &= y(n\tau)
 \end{aligned}$$

Alternatively, the results follow from Theorem 11.7 (page 89). 

16.3 Nonparametric density estimation

Some techniques of *nonparametric density estimation* include²

- ➊ Histogram
- ➋ Average Shifted Histogram
- ➌ Kernel Density Estimation (KDE)
- ➍ Fourier-based
- ➎ Wavelet-based
- ➏ Fast Gauss Transform

KDE's are conceptually quite simple, but do have some difficulties:

- ➊ KDEs are good for 6 dimensions or less—the “curse of dimensionality”³
- ➋ KDEs have a *bandwidth* parameter and the computation of this parameter can be quite demanding.

²  Silverman (1986) (ISBN:9780412246203),  Tsybakov (2008) pages 1–27 (§1.1–§1.3),  Gramacki (2017) (ISBN:9783319716886),  Vidakovic (1999) pages 217–245 (Chapter 7 “Density Estimation”)

³  Bellman (1954), page 206,  Bellman (1961), page 94 (§“5.16 The Curse of Dimensionality”),  Bellman (1971), page 44,  Gramacki (2017) page 59 (§“The Curse of Dimensionality”)



CHAPTER 17

CORRELATION ESTIMATION

17.1 Time series method

Definition 17.1. ¹

The **windowed auto-correlation estimate** $\hat{R}_{xx}(m)$ is defined as

$$\hat{R}_{xx}(m) \triangleq \frac{1}{N} \sum_{n=0}^{N-|m|} x(n)x(n+m)$$

Theorem 17.1. ²

$$E[\hat{R}_{xx}(m)] = \left(1 - \frac{|m|}{N}\right) R_{xx}(m) \quad (\text{ASYMPTOTICALLY UNBIASED})$$

$$\text{var}[\hat{R}_{xx}(m)] = \frac{1}{N} \sum_{n \in \mathbb{Z}} [R_{xx}^2(n) + R_{xx}(n-m)R_{xx}(n+m)] \quad (\text{CONSISTENT})$$

17.2 Spectral methods

Here are two methods for estimating correlation using spectral methods:

1. Calculate the estimate $\hat{H}(\omega)$ (CHAPTER 13 page 105) of the true system model $H(\omega)$ and then calculate the *Inverse Fourier Transform* of $\hat{H}(\omega)$.
2. Calculate an *AR*, *MA*, or *ARMA* estimate of the true system model $H(z)$ and then compute the *Inverse Z-Transform* of the estimate.³

¹ Jenkins and Watts (1968), pages 180–183 (§“5.3.4 Discrete time autocovariance estimates”), Vaseghi (2000) page 271 (§“9.3.3 Energy-Spectral Density and Power-Spectral Density”)

² Jenkins and Watts (1968), Clarkson (1993) pages 54–56 (§“2.6.2 Estimation of Moments — Time Averages”), Vaseghi (2000) page 272 (§“9.3.3 Energy-Spectral Density and Power-Spectral Density”)

³ Clarkson (1993) pages 56–59 (§“Appendix 2A — Calculating the Correlation via Contour Integration”)

CHAPTER 18

SPECTRAL ESTIMATION

“Sometimes we come to life's crossroads
and view what we think is the end.
But God has a much wider vision
and He knows that it's only a bend....”

Helen Steiner Rice (1900–1981); from *A Bend in the Road*¹

18.1 Nonparametric spectral estimation

Quality of spectral estimators²

THM

Periodogram:	$Q = 1$
Welch Method 0% overlap:	$Q = 0.78N\Delta f$
Welch Method 50% overlap:	$Q = 1.39N\Delta f$
Bartlett Method:	$Q = 1.11N\Delta f$
Blackman-Tukey Method:	$Q = 2.34N\Delta f$

Example 18.1. ³ Using the PSD, we can estimate the periodicity of sunspots (Figure 18.1 page 146) as

¹  Rice (2012) page 116 (Note: not sure about page number). Many many thanks to Mary L. Greenhoe for bringing this poem to the author's attention.

²  Proakis (2002) pages 452–457 (§“8.2.4 Performance Characteristics of Nonparametric Power Spectrum Estimators”),  Proakis and Manolakis (1996) pages 916–919 (§“12.2.4 Performance Characteristics of Nonparametric Power Spectrum Estimators”),  Rao and Swamy (2018) page 731 (“Table 12.1 Comparison of performance of classical methods”),  Salivahanan and Vallavaraj (2001) page 606 (§“12.5 Power Spectrum Estimation: Non-Parametric Methods”),  Ifeachor and Jervis (2002) pages 706–707 (§“11.3.7 Comparison of the power spectral density estimation methods”),  J.S.Chitode (2009b) page P-100,  Abdaheer (2009), page 204

³  SILSO World Data Center (2019) (http://www.sidc.be/silso/DATA/SN_m_tot_V2.0.txt),  rdocumentation.org (2013)

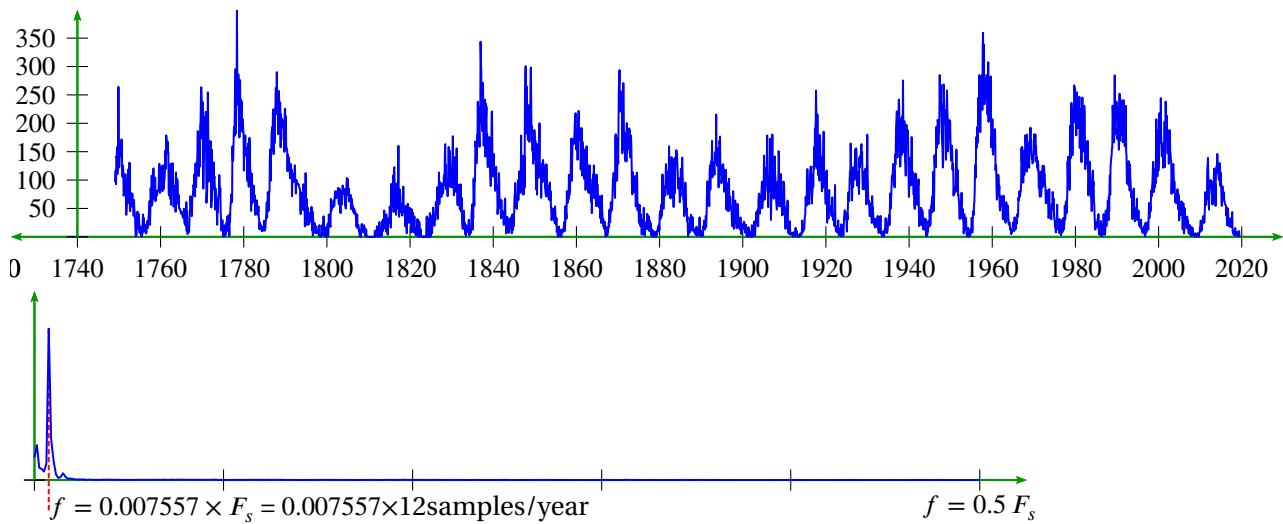


Figure 18.1: Estimation of sunspot periodicity using Welch PSD estimation

E X	number of segments = 2	estimated periodicty = 11.027777777777786 years
	number of segments = 3	estimated periodicty = 11.020833333333321 years
	number of segments = 4	estimated periodicty = 11.027777777777786 years
	number of segments = 8	estimated periodicty = 11.000000000000000 years

That is, period = $\frac{1}{f} = \frac{1}{0.007557 \times 12} \approx 11.0273$ years. Here is some R code that can be used to experiment with:

```

1 require(stats);
2 require(graphics);
3 require(datasets);
4 require(ramify);
5 require(bspec);
6 data(sunspots, package="datasets");
7 mypsd = function(x, numSegments=4)
8 {
9   xts      = as.ts(as.vector(x)); # year indices seems to confuse welchPSD
10  N        = length(xts);          # length of time series
11  Fs       = 12;                  # sample rate = 12 samples per year
12  estMean  = mean(xts);          # estimated mean
13  segLength = N / numSegments;   # segment length
14  xpsd     = bspec::welchPSD(xts - estMean, seglength = segLength);
15  psdMax   = max(xpsd$power);    # maximum PSD value
16  binMax   = ramify::argmax(as.matrix(xpsd$power), rows = FALSE);
17  freqMax  = xpsd$frequency[binMax] * Fs; # dominate non-DC frequency
18  periodT  = 1 / freqMax;        # estimated period
19  plot(xpsd$power, type="b", xlim=c(1,50), ylim=c(0,psdMax), col="blue");
20  periodT;                      # return estimated period
21 }
22 estT = mypsd(x, numSegments=4);
23 print(sprintf("estimated period = %.16f years", estT));

```

18.2 Bandwidth-Time Product

BT-product references:

1. [Haykin \(2014\) pages 25–28](#) (§“2.4 The Inverse Relationship between Time-Domain and Frequency-Domain Representations”),
2. [S. Lawrence Marple \(1987\) pages 144–146](#) (§“5.4 RESOLUTION AND THE STABILITY-TIME-BANDWIDTH PRODUCT”)

Part V

Appendices

APPENDIX A

PROBABILITY SPACE

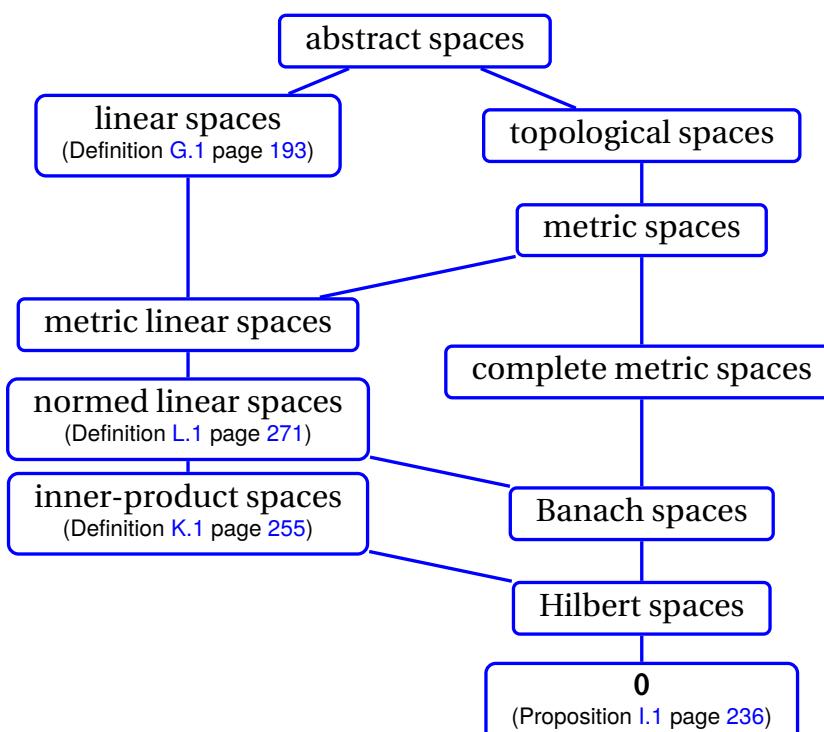


Figure A.1: Lattice of mathematical spaces



“It is not certain that everything is certain.”
Blaise Pascal (1623–1662), mathematician ¹

¹ quote: http://en.wikiquote.org/wiki/Blaise_Pascal
image: http://en.wikipedia.org/wiki/Image:Blaise_pascal.jpg

A.1 Probability functions

Definition A.1. ² Let $(X, \vee, \wedge, \neg, 0, 1; \leq)$ be a LATTICE WITH NEGATION.

The function P is a **probability function** if

- | | | |
|-----|---|-------------------------|
| DEF | (1). $P(1) = 1$ | (NORMALIZED) and |
| | (2). $P(x) \geq 0 \quad \forall x \in X$ | (NONNEGATIVE) and |
| | $\bigwedge_{n=1}^{\infty} x_n = 0 \implies P\left(\bigvee_{n=1}^{\infty} x_n\right) = \sum_{n=1}^{\infty} P(x_n) \quad \forall x_n \in X$ | (σ -ADDITIVE) . |

Remark A.1. The advantage of this definition is that P is a *measure*, and hence all the power of measure theory is subsequently at one's disposal in using P . However, it has often been argued that the requirement of σ -additivity is unnecessary for a probability function. Even as early as 1930, de Finetti argued against it, in what became a kind of polite running debate with Fréchet.³ In fact, Kolmogorov himself provided some argument against σ -additivity when referring to the closely related *Axiom of Continuity* saying, "Since the new axiom is essential for infinite fields of probability only, it is almost impossible to elucidate its empirical meaning...For, in describing any observable random process we can obtain only finite fields of probability...." But in its support he added, "This limitation has been found expedient in researches of the most diverse sort."⁴

There are several other definitions of probability that only require *additivity* rather than σ -additivity. On a *Boolean lattice*, the **traditional probability** function is defined as⁵

- | | |
|---|-------------------|
| (1). $P(1) = 1$ | (normalized) and |
| (2). $P(x) \geq 0 \quad \forall x \in X$ | (nonnegative) and |
| (3). $x \wedge y = 0 \implies P(x \vee y) = P(x) + P(y) \quad \forall x, y \in X$ | (additive) . |

This definition implies (on a *Boolean lattice*) that

- | | |
|---|---------------------|
| (a). $P(0) = 0$ | (nondegenerate) and |
| (b). $P(x) \leq 1 \quad \forall x \in X$ | (upper bounded) and |
| (c). $P(x) = 1 - P(x^\perp) \quad \forall x \in X$ | and |
| (d). $P(x \vee y) \leq P(x) + P(y) \quad \forall x, y \in X$ | (subadditive) and |
| (e). $P(x \vee y) = P(x) + P(y) - P(x \wedge y) \quad \forall x, y \in X$ | and |
| (f). $x \leq y \implies P(x) \leq P(y) \quad \forall x, y \in X$ | (monotone) . |

On a *distributive pseudocomplemented lattice*, the **generalized probability** function has been defined as⁶

- | | |
|---|---------------------|
| (1). $P(0) = 0$ | (nondegenerate) and |
| (2). $P(1) = 1$ | (normalized) and |
| (3). $0 \leq P(1) \leq 1$ | and |
| (4). $P(x \vee y) = P(x) + P(y) - P(x \wedge y) \quad \forall x, y \in X$ | . . |

On an *orthomodular lattice*, or a *finite modular lattice*, the **quantum probability** function is defined as⁷

- | | |
|--|---------------------|
| (1). $P(0) = 0$ | (nondegenerate) and |
| (2). $P(1) = 1$ | (normalized) and |
| (3). $x \perp y \implies P(x \vee y) = P(x) + P(y) \quad \forall x, y \in X$ | (additive) . |

However, for lattices that are not *distributive*, *modular*, or *orthomodular*, none of these definitions

² Billingsley (1995) pages 22–23 (Probability Measures), Kolmogorov (1933a), Kolmogorov (1933b), page 16 (field of probability), Pap (1995) pages 8–9 (Definition 2.3(13)), Kalmbach (1986) page 27

³ de Finetti (1930a), Fréchet (1930a), de Finetti (1930b), Fréchet (1930b), de Finetti (1930c), Cifarelli and Regazzini (1996) pages 258–260

⁴ Kolmogorov (1933b), page 15

⁵ Papoulis (1991) pages 21–22, Kolmogorov (1933b), page 2 (§1. Axioms I–V)

⁶ Narens (2014) page 118, Narens (2007) (ISBN:9812708014)

⁷ Greechie (1971) page 126 (DEFINITIONS), Narens (2014) page 118



work out so well. Take for example the O_6 lattice with the “very reasonable” probability function given in Example ?? (page ??). This probability space (O_6, P) fails to be any of the 4 probability functions defined in this Remark. It fails to be a *measure-theoretic* or *traditional probability* function because

$$a \wedge b = 0 \quad \text{but} \quad P(a \vee b) = P(1) = 1 \neq \frac{1}{3} + \frac{1}{2} = P(a) + P(b).$$

It fails to be a *generalized probability* function because

$$P(a \vee b) = P(1) = 1 \neq \frac{1}{3} + \frac{1}{2} - 0 = P(a) + P(b) - P(0) = P(a) + P(b) - P(a \wedge b).$$

It fails to be an *quantum probability* function because

$$a \perp b = 0 \quad \text{but} \quad P(a \vee b) = P(1) = 1 \neq \frac{1}{3} + \frac{1}{2} = P(a) + P(b).$$

In each of these cases, the function P fails to be *additive*. The solution of Definition A.1 (page 150) is simply to “switch off” *additivity* when the lattice is not *distributive*. This method is a little “crude”, but at least it allows us to define probability on a very wide class of lattices, while retaining compatibility with the *Boolean* case.

A.2 Probability Space

In mathematics, a *space* is simply a set and in the most general definition, nothing else. However, normally for a space to actually be useful, some additional structure is added. One of the most general additional structures is a *topology*; and a space together with a topology is called a *topological space*. A topological space imposes additional structure on a space in the form of subsets and guarantees that these subsets are closed under such fundamental operations as set *union* and set *intersection*. With the additional structure available in a topological space, we are able to analyze such basic concepts as continuity, convergence, and connectivity.

However for a great number of mathematical applications, we need to *measure* mathematical objects—the most general measurement being measures on subsets of some set. Examples of measurement in mathematics include integration and probability. Before measurement can be effectively performed on a set, the set must be equipped with a subset structure. In analysis, arguably the most fundamental subset structure is the humble *topology* (Definition ?? page ??). However, a simple topology does not provide sufficient structure for effective measurement. For example, often we would not only like to measure some subset A , but also its complement A^c . A topology is not closed under the complement operation. So instead of a topology only, we equip the space with a more powerful (and thus less general) structure called a σ -*algebra* (*sigma-algebra*) (Definition ?? page ??). A σ -*algebra* is a subset structure that is closed under set complement. A set together with a σ -*algebra* is called a *measurable space*. And a set together with a σ -*algebra* and a *measure* on that σ -*algebra* is called a *measure space* (Definition ?? page ??).

The next definition presents a very important measure space—the *probability space*.

Definition A.2.

D E F The triple (Ω, \mathbb{E}, P) is a **probability space** if

- (1). Ω is a SET
- (2). \mathbb{E} is a σ -ALGEBRA on Ω (Definition ?? page ??) and
- (3). $P : \mathbb{E} \rightarrow [0, 1]$ is a MEASURE on \mathbb{E} (Definition ?? page ??) .

If $S \triangleq (\Omega, \mathbb{E}, P)$ is a PROBABILITY SPACE then x is an **outcome** in S if $x \in \Omega$, A is an **event** in S if $A \in \mathbb{E}$, and PA is the **probability** of A in S if A is an EVENT in S .

Definition A.3.⁸ Let (Ω, \mathbb{E}, P) be a PROBABILITY SPACE (Definition A.2 page 151).

⁸  Papoulis (1990) page 52 (Independent Events)

D E F Two EVENTS A and B in \mathbb{E} are **independent** if
 $P(A \cap B) = P(A)P(B)$

Definition A.4. ⁹ Let (Ω, \mathbb{E}, P) be a PROBABILITY SPACE (Definition A.2 page 151). Let x and y be EVENTS in \mathbb{L} .

D E F The **conditional probability** of x given y is defined as
 $P(A|B) \triangleq \frac{P(A \cap B)}{P(B)}$

A.3 Properties

Proposition A.1.

P R P (Ω, \mathbb{E}, P) is a PROBABILITY SPACE \implies (Ω, \mathbb{E}, P) is a MEASURE SPACE
(every probability space is a measure space)

Theorem A.1. ¹⁰ Let (Ω, \mathbb{E}, P) be a PROBABILITY SPACE (Definition A.2 page 151).

T H M

- (1). $0 \leq P(x) \leq 1 \quad \forall x \in X$ (BOUNDED) and
- (2). $P(x) = 1 - P(x^\perp) \quad \forall x \in X$ (PARTITION OF UNITY) and
- (3). $x \leq y \implies P(y^\perp) \leq P(x^\perp) \quad \forall x, y \in X$ (ANTITONE)

PROOF:

1. Proof for $0 \leq P(x) \leq 1$:

$$\begin{aligned} 0 &= P(0) && \text{by by nondegenerate property of } P \text{ (Definition A.2 page 151)} \\ &\leq P(x) \\ &\leq P(1) && \text{because } 0 \leq x \text{ and monotone property of } P \\ &= 1 && \text{because } x \leq 1 \text{ and monotone property of } P \\ & && \text{by normalized property of } P \end{aligned}$$

2. Proof for $P(x) = 1 - P(x^\perp)$:

(a) Proof that P is *additive* (Definition A.2 page 151) over $\{0, x, x^\perp\} \subseteq X$:

- i. $\{0, x, x^\perp\}$ is *distributive*.
- ii. $x \wedge x^\perp = 0$ for all $x \in X$ by the *non-contradiction* property of *orthocomplemented lattices*.
- iii. Therefore, by Definition A.2, P is *additive* over $\{0, x, x^\perp\}$.

(b) Then ...

$$\begin{aligned} 1 - P(x^\perp) &= P(1) - P(x^\perp) && \text{by normalized property of } P \quad (\text{Definition A.2 page 151}) \\ &= P(x \vee x^\perp) - P(x^\perp) && \text{by excluded middle property of ortho. lat.} \\ &= P(x) + P(x^\perp) - P(x^\perp) && \text{by additive property of } (\Omega, \mathbb{E}, P) \quad (\text{item (2a) page 152}) \\ &= P(x) && \text{by field property of } (\mathbb{R}, +, \cdot, 0, 1) \end{aligned}$$

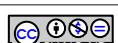
3. Proof for $x \leq y \implies P(y^\perp) \leq P(x^\perp)$:

$$\begin{aligned} x \leq y &\implies y^\perp \leq x^\perp && \text{by antitone property of orthocomplemented lattices} \\ &\implies P(y^\perp) \leq P(x^\perp) && \text{by monotone property of } P \end{aligned}$$

(Definition A.2 page 151)

⁹  Papoulis (1990) page 45 (2-3 Conditional Probability and Independence)

¹⁰ property (1):  Papoulis (1991) page 21 ((2-11))





Theorem A.2. ¹¹ Let (Ω, \mathbb{E}, P) be a PROBABILITY SPACE (Definition A.2 page 151).

T H M	L is BOOLEAN (Definition ?? page ??)	$\left\{ \begin{array}{l} 1. \quad P(x \vee y) = P(x) + P(y) - P(x \wedge y) \quad \forall x, y \in X \quad \text{and} \\ 2. \quad P(x \vee y) \leq P(x) + P(y) \quad \forall x, y \in X \quad (\text{BOOLE'S INEQUALITY}) \end{array} \right.$
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PROOF:

1. lemma: Proof that $P((\neg x) \wedge y) = P(y) - P(x \wedge y)$:

$$\begin{aligned} P(y) - P(xy) &= P(1 \wedge y) - P(xy) \\ &= P[(x \vee x^\perp)y] - P(xy) \\ &= P(xy \vee x^\perp y) - P(xy) \\ &= P(xy) + P(x^\perp y) - P(xy) \\ &= P(x^\perp y) \end{aligned}$$

by definition of 1 and \wedge
by *excluded middle* property of Boolean lattices
by *distributive* property of Boolean lattices
because $(xy)(x^\perp y) = 0$ and by *additive* property

2. Proof that $P(x \vee y) = P(x) + P(y) - P(x \wedge y)$:

$$\begin{aligned} P(x \vee y) &= P(x \vee x^\perp y) \\ &= P(x) + P(x^\perp y) \\ &= P(x) + P(y) - P(x \wedge y) \end{aligned}$$

by property of Boolean lattices
because $(x)(x^\perp y) = 0$ and by *additive* property
by item (1) (page 153)



Theorem A.3 (sum of products). Let $(X, \vee, \wedge, 0, 1 ; \leq)$ be a BOUNDED LATTICE, (Ω, \mathbb{E}, P) a PROBABILITY SPACE (Definition A.2 page 151), and $\{y, x_1, x_2, x_3, \dots\}$ a subset of X .

T H M	$\left\{ \begin{array}{l} 1. \quad L \text{ is DISTRIBUTIVE} \\ 2. \quad \{x_1, x_2, \dots\} \text{ is a PARTITION of } y \end{array} \right. \text{ and }$	$\Rightarrow \left\{ \begin{array}{l} 1. \quad P(y) = \sum_n P(x_n) \quad \text{and} \\ 2. \quad P(y) = \sum_n P(y \wedge x_n) \quad \text{and} \\ 3. \quad P(z \wedge y) = \sum_n P(z \wedge x_n) \end{array} \right. \right\}$
----------------------	---	--

PROOF:

1. Proof that P is *additive* (Definition A.2 page 151) on (Ω, \mathbb{E}, P) :

(a) Proof that $(yx_n) \wedge (yx_m) = 0$ for $n \neq m$:

$$\begin{aligned} (yx_n) \wedge (yx_m) &= y(x_n x_m) \quad \text{by definition of } \wedge \\ &= y \wedge 0 \quad \text{by } \textit{mutually exclusive} \text{ property of partitions} \\ &= 0 \quad \text{by } \textit{lower bounded} \text{ property of bounded lattices} \end{aligned}$$

(b) Proof that L is *distributive*: by *distributive* hypothesis

2. Proof that $P(y) = \sum_n P(x_n)$

$$\begin{aligned} P(y) &= P(yx_1 \vee yx_2 \vee \dots \vee yx_n) \\ &= \sum_n P(yx_n) \quad \text{by item (1) and } \textit{additive} \text{ property} \quad (\text{Definition A.2 page 151}) \\ &= \sum_n P(y|x_n)P(x_n) \quad \text{by } \textit{conditional probability} \quad (\text{Definition A.4 page 152}) \end{aligned}$$

¹¹ Papoulis (1991) page 21 ((2-13)), Feller (1970) pages 22–23 ((7.4),(7.6))



As described in Definition A.2 (page 151), every *probability space* (Ω, \mathbb{E}, P) contains a probability *measure* $P : \mathbb{E} \rightarrow [0, 1]$. This probability *measure* has some basic properties as described in Theorem A.4 (next).

Theorem A.4. Let (Ω, \mathbb{E}, P) be a PROBABILITY SPACE. Let B be a set and $\{B_n | n = 1, 2, \dots, N\}$ a set of sets.

**T
H
M**

$\left\{ \begin{array}{l} \{B_n | n = 1, 2, \dots, N\} \text{ is a} \\ \text{PARTITION of } B. \end{array} \right\}$

$$\Rightarrow \left\{ \begin{array}{l} (1). \quad P(B) = \sum_{n=1}^N P(B_n) \quad \forall B \in \mathbb{E} \quad \text{and} \\ (2). \quad P(AB) = \sum_{n=1}^N P(AB_n) \quad \forall A, B \in \mathbb{E} \end{array} \right\}$$



PROOF: P is a *measure* and by Definition ?? (page ??).

Proposition A.2. Let (Ω, \mathbb{E}, P) be a probability space, and X a RANDOM VARIABLE (Definition B.1 page 160) with PROBABILITY DENSITY FUNCTION $p_x(x)$ and CUMULATIVE DISTRIBUTION FUNCTION $c_x(x)$.

**P
R
P**

- (1). $c_x(x)$ is MONOTONE and
- (2). $p_x(x)$ is CONTINUOUS $\Rightarrow c_x(x)$ is STRICTLY MONOTONE and
- (3). $p_x(x)$ is CONTINUOUS $\Rightarrow c_x(x)$ is INVERTIBLE

Theorem A.5 (Bayes' Rule). ¹²

**T
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M**

$$P(X|Y) = \frac{P(Y|X)P(X)}{P(Y)}$$

$$\begin{aligned} P(X|Y) &\triangleq \frac{P(X \cap Y)}{P(Y)} && \text{by definition of conditional probability} \\ &= \frac{P(Y \cap X)}{P(Y)} && \text{by commutative property of } \cap \\ &= \frac{P(Y|X)P(X)}{P(Y)} && \text{by definition of conditional probability} \end{aligned}$$

(Definition A.4 page 152)

by commutative property of \cap

(Definition A.4 page 152)

A.4 Examples

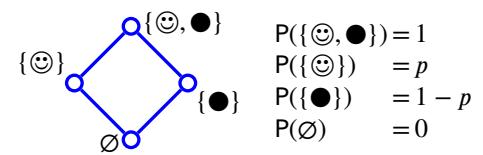
Example A.1 (single coin toss). Let \odot represent “heads” and \bullet represent “tails” in a coin toss. Let $0 < p < 1$ be the probability of a head. A *probability space* (Ω, \mathbb{E}, P) for a single coin toss is as follows:

**E
X**

$$\Omega = \{\odot, \bullet\}$$

$$\mathbb{E} = \left\{ \begin{array}{l} \emptyset, \{\odot\}, \{\bullet\}, \{\odot, \bullet\} \\ \text{neither heads tails heads or tails} \end{array} \right\}$$

$$P(X) = \left\{ \begin{array}{lll} 0 & \text{for } X = \emptyset & (\text{neither heads nor tails}) \\ p & \text{for } X = \{\odot\} & (\text{heads}) \\ 1-p & \text{for } X = \{\bullet\} & (\text{tails}) \\ 1 & \text{for } X = \{\odot, \bullet\} & (\text{either heads or tails}) \end{array} \right\}$$



$$\begin{aligned} P(\{\odot, \bullet\}) &= 1 \\ P(\{\odot\}) &= p \\ P(\{\bullet\}) &= 1 - p \\ P(\emptyset) &= 0 \end{aligned}$$

¹² Haykin (2014) page 95 (“Bayes’ Rule”)



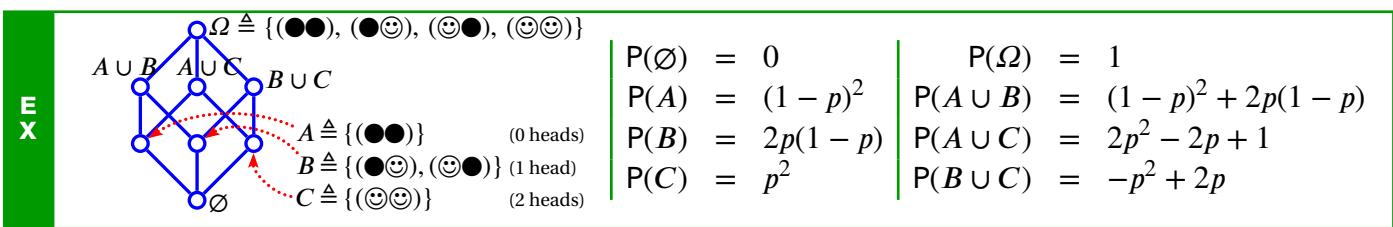


Figure A.2: Double coin toss (Example A.2 page 155)

Example A.2 (Double coin toss). Let \circ represent “heads” and \bullet represent “tails” in a double coin toss in which each toss is *independent* (Definition A.3 page 151) of the other. Let $0 < p < 1$ be the probability of a head. The *probability space* (Ω, \mathbb{E}, P) is illustrated in Figure A.2 (page 155).

PROOF:

$$\begin{aligned}
 P(\Omega) &= 1 && \text{by } \textit{normalized} \text{ property of } P && \text{(Definition A.1 page 150)} \\
 P(C) &= P\{\circ\circ\} && \text{by definition of } C \\
 &= P(\circ)P(\circ) && \text{by definition of } \textit{independence} && \text{(Definition A.3 page 151)} \\
 &= p^2 && \text{by definition of } p \\
 P(A) &= P\{\bullet\bullet\} && \text{by definition of } A \\
 &= P(\bullet)P(\bullet) && \text{by definition of } \textit{independence} && \text{(Definition A.3 page 151)} \\
 &= \{1 - P(\circ)\}\{1 - P(\circ)\} && \text{by } \textit{antitone} \text{ property of } P && \text{(Theorem A.1 page 152)} \\
 &= (1-p)^2 && \text{by definition of } p \\
 P(B) &= P\{(\bullet\circ), (\circ\bullet)\} && \text{by definition of } B \\
 &= P\{\bullet\circ\} + P\{\circ\bullet\} && \text{by } \textit{additive} \text{ property of } P && \text{(Definition A.1 page 150)} \\
 &= P(\bullet)P(\circ) + P(\circ)P(\bullet) && \text{by definition of } \textit{independence} && \text{(Definition A.3 page 151)} \\
 &= (1-p)p + p(1-p) && \text{by } \textit{antitone} \text{ property of } P && \text{(Theorem A.1 page 152) and definition of } p \\
 &= -2p^2 + p + 1 \\
 P(A \cup B) &= P(A) + P(B) - P(A \cap B) && \text{by Theorem A.2} \\
 &= P(A) + P(B) - P(\emptyset) \\
 &= (1-p)^2 + (-2p^2 + p + 1) + 0 && \text{by previous results} \\
 &= -p^2 - p + 1 \\
 P(\emptyset) &= 0 && \text{by } \textit{nondegenerate} \text{ property of } P && \text{(Definition A.1 page 150)}
 \end{aligned}$$

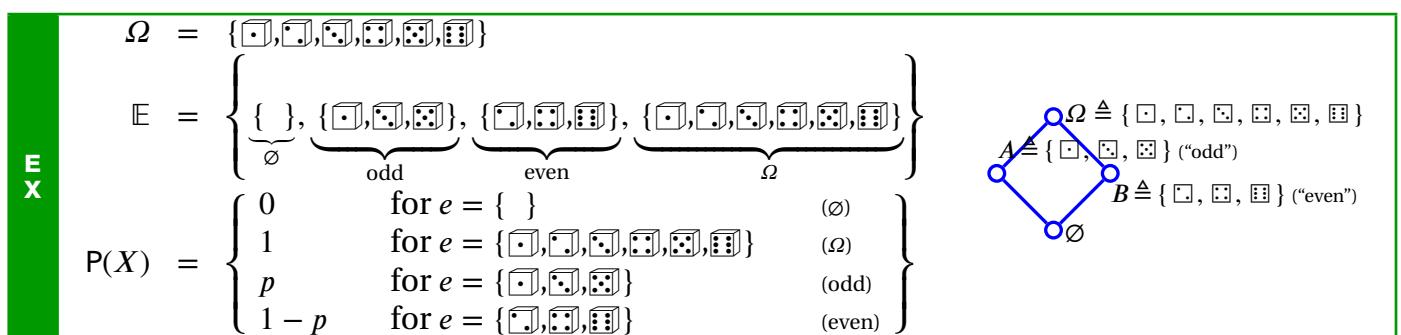


Figure A.3: even/odd die probability space (Example A.3 page 155)

Example A.3 (even/odd die toss). The *probability space* for an **even/odd die toss**, with $0 < p < 1$ being the probability of the die toss being odd, is illustrated in Figure A.3 (page 155).

PROOF:

$P(\Omega) = 1$	by <i>normalized</i> property of P	(Definition A.1 page 150)
$P(C) = P\{\text{⊕⊕}\}$	by definition of C	
$= P(\text{⊕})P(\text{⊕})$	by definition of <i>independence</i>	(Definition A.3 page 151)
$= p^2$	by definition of p	
$P(A) = P\{\text{◻}, \text{◻}, \text{◻}\}$	by definition of A	
$= p$	by definition of p	
$P(B) = P\{\text{◻}, \text{◻}, \text{◻}\}$	by definition of B	
$= P\{\text{◻}, \text{◻}, \text{◻}\}^c$	by definition of set complement c	
$= PA^c$	by definition of A	
$= P(\neg A)$	by definition of \neg	
$= 1 - P(A)$	by Theorem A.1 page 152	
$= 1 - p$	by definition of p	
$P(\emptyset) = 0$	by <i>nondegenerate</i> property of P	(Definition A.1 page 150)



The two previous *even/odd die* example (Example A.5 page 156) is in essence the same as the *single coin toss* (Example A.1 page 154). The next offers a little more complexity.

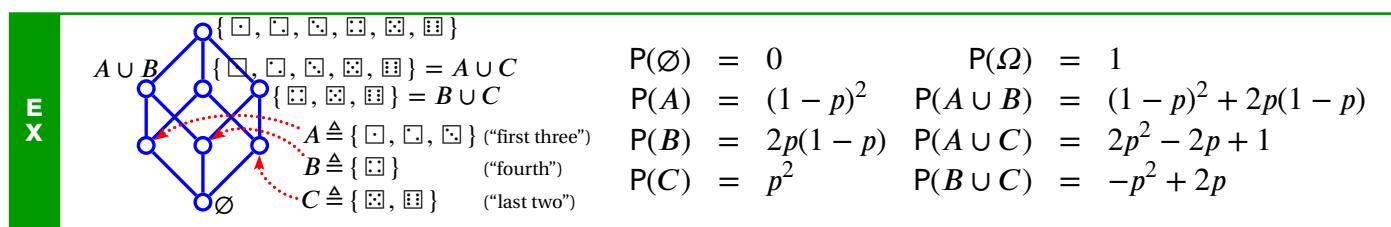


Figure A.4: 3-4-2 die example (Example A.4 page 156)

Example A.4. Suppose we have a “fair” die and we are primarily interested in the events of the first three $\{\text{◻}, \text{◻}, \text{◻}\}$, the next two, $\{\text{◻}, \text{◻}\}$ and the final one $\{\text{◻}\}$. The resulting *probability space* is illustrated in Figure A.4 (page 156).

The two previous examples (Example A.5 page 156, Example A.4 page 156) illustrate a *probability spaces* in which the events are *mutually exclusive*. The (next) illustrates one where events are *not*.

Example A.5. Suppose we have a “fair” die and we are primarily interested in the events of the first four ($\{\text{◻}, \text{◻}, \text{◻}, \text{◻}\}$) (that is, whether one roll of the die will produce a value in the set $\{\text{◻}, \text{◻}, \text{◻}, \text{◻}\}$) and the last three ($\{\text{◻}, \text{◻}, \text{◻}\}$). However, these events do not by themselves form a σ -algebra. Rather under the \cap and \cup operations, these two events generate a total of eight possible events that together form a σ -algebra. The resulting *probability space* is illustrated in Figure A.5 (page 157).

But why go through all the trouble of requiring a σ -algebra? Having a σ -algebra in place ensures that anything we might possibly want to measure *can* be measured. It makes sure all possible combinations are taken into account. And why go through the additional trouble of requiring a measure space? With a measure space available, expressing the measure over a complex set is often greatly simplified because the measure space provides nice algebraic properties (namely the σ -*additive* property). Example A.6 (next) illustrates how a rather complex σ -algebra (64 elements) can be compactly represented in a measure space.



EX	$\Omega = \{\square, \square, \square, \square, \square, \square\}$ $\mathbb{E} = \left\{ \underbrace{\{\}}_{\emptyset}, \underbrace{\{\square, \square, \square, \square, \square, \square\}}_{\Omega}, \underbrace{\{\square, \square, \square, \square, \square\}}_{\text{first four}}, \underbrace{\{\square, \square, \square\}}_{\text{last three}}, \right.$
	$\left. \begin{array}{l} \underbrace{\{\square, \square\}}_{\{1234\} \cap \{456\}}, \underbrace{\{\square, \square, \square, \square, \square\}}_{\{4\}^c}, \underbrace{\{\square, \square\}}_{\{4\}^c \cap \{456\}}, \underbrace{\{\square, \square, \square\}}_{\{1234\} \cap \{4\}^c} \end{array} \right\}$ $P(e) = \begin{cases} 0 & \text{for } e = \{\} \\ 1 & \text{for } e = \{\square, \square, \square, \square, \square, \square\} \\ \frac{1}{2} & \text{for } e = \{\square, \square, \square, \square, \square\} \\ \frac{1}{3} & \text{for } e = \{\square, \square, \square, \square\} \\ \frac{1}{4} & \text{for } e = \{\square, \square, \square\} \\ \frac{1}{5} & \text{for } e = \{\square, \square\} \\ \frac{1}{6} & \text{for } e = \{\square\} \end{cases}$

Figure A.5: First 4 / last 3 die example (Example A.5 page 156)

Example A.6. Suppose we have a “fair” dice and we are interested in measuring over the power set of events (largest possible algebra— $2^6 = 64$ events). This leads to the probability space (Ω, \mathbb{E}, P) where

EX	$\Omega = \{\square, \square, \square, \square, \square, \square\}$ $\mathbb{E} = \mathcal{P}(\Omega)$ $P(e) = \frac{1}{6} e $	(the power-set of Ω) $(\frac{1}{6} \text{ times the number of possible outcomes in event } e)$
----	--	---

Example A.7 (Gaussian distribution on \mathbb{R}). Let \mathbf{B} be the *Borel algebra* on \mathbb{R} . Let $\mathbf{L} \triangleq (\mathbf{B}, \subseteq)$ be the lattice formed by the elements of \mathbf{B} —this lattice is a *Boolean algebra*. Let

$$P(A) \triangleq \frac{1}{\sqrt{2\pi\sigma^2}} \int_A e^{-\frac{x^2}{2\sigma^2}} dx \text{ for } A \subseteq \mathbf{B}$$

and where \int is the *Lebesgue integral* (Definition ?? page ??). Then (\mathbf{L}, P) is a **probability space**.

Example A.8 (Gaussian noise). Let $X \sim N(0, \sigma^2)$ be a random variable with Gaussian distribution. We can construct the following probability space (Ω, \mathbb{E}, P) :

EX	$\Omega = \mathbb{R}$ $\mathbb{E} = \{\emptyset, \Omega\} \cup \{(a, b) a, b \in \mathbb{R}, a < b\}$ $P_x = \begin{cases} 0 & \text{for } x = \emptyset \\ 1 & \text{for } x = \Omega \\ \frac{1}{\sqrt{2\pi\sigma^2}} \int_a^b e^{-\frac{x^2}{2\sigma^2}} dx & \text{otherwise} \end{cases}$
----	--

Example A.9. The set of outcomes Ω can also be a set of waveforms:

EX	$\Omega = \left\{ \begin{array}{c} \text{[waveform diagram]} \\ \vdots \\ \text{[waveform diagram]} \end{array} \right\}$ $\mathbb{E} = \mathcal{P}(\Omega)$ $P(e) = \frac{1}{7} e $
----	--

A.5 Probability subspaces

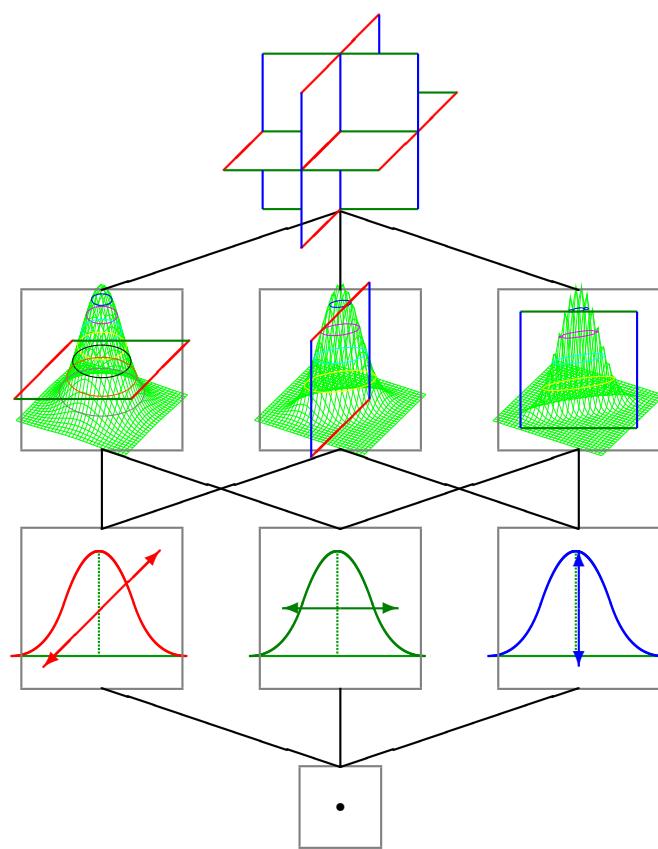
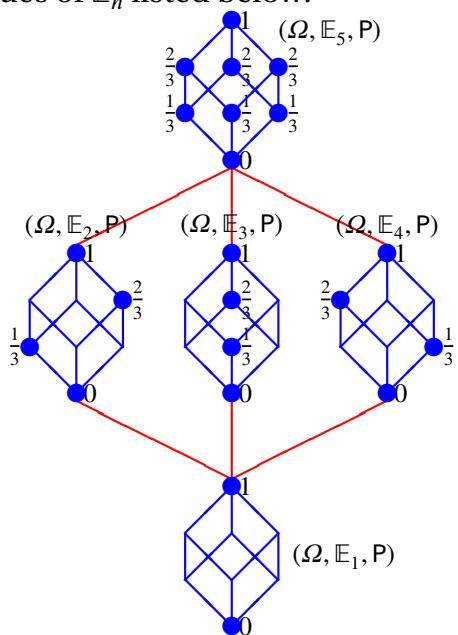


Figure A.6: Euclidean 3-dimensional space partitioned as a power lattice

Example A.10. Suppose a random process is capable of producing three values $\Omega \triangleq \{x, y, z\}$. There are five *algebras of sets* on Ω and therefore five probability spaces $(\Omega, \mathbb{E}_n, P)$ on Ω with the five values of \mathbb{E}_n listed below: ¹³



$$\begin{aligned}
 \mathbb{E}_1 &= \{ \emptyset, X \} \\
 \mathbb{E}_2 &= \{ \emptyset, \{x\}, \{y, z\}, X \} \\
 \mathbb{E}_3 &= \{ \emptyset, \{y\}, \{x, z\}, X \} \\
 \mathbb{E}_4 &= \{ \emptyset, \{z\}, \{x, y\}, X \} \\
 \mathbb{E}_5 &= \{ \emptyset, \{x\}, \{y\}, \{z\}, \{x, y\}, \{x, z\}, \{y, z\}, X \}
 \end{aligned}$$

Suppose the samples of Ω are generated by a physical process such that they are all equally likely to occur. Then by varying the σ -algebra \mathbb{E}_n effectively varies the probability distribution of the probability space $(\Omega, \mathbb{E}_n, P)$. This is illustrated by the figure to the left.

¹³ algebra of sets: Definition ?? page ??

APPENDIX B

PROBABILITY DENSITY FUNCTIONS



“While writing my book I had an argument with Feller. He asserted that everyone said “random variable” and I asserted that everyone said “chance variable.” We obviously had to use the same name in our books, so we decided the issue by a stochastic procedure. That is, we tossed for it and he won.”¹

Joseph Leonard Doob (1910–2004), pioneer of and key contributor to mathematical probability¹

B.1 Random variables

The concept of the *random variable* is widely used in probability and random processes. Before discussing what a *random variable* is, note two things that a *random variable* is *not* (next remark).

Remark B.1. ² As pointed out by others, the term “random variable” is a “misnomer”:

RE
M

- A *random variable* is **not random**.
- A *random variable* is **not a variable**.

What is it then? It is a *function* (next definition). In particular, it is a function that maps from an underlying stochastic process into \mathbb{R} . Any “*randomness*” (whatever that means) it may *appear* to have comes from the stochastic process it is mapping *from*. But the function itself (the *random*

¹ quote: [Snell \(1997\)](#), page 307, [Snell \(2005\)](#), page 251

image: <http://www.dartmouth.edu/~chance/Doob/conversation.html>

² [Miller \(2006\)](#) page 130, [Feldman and Valdez-Flores \(2010\)](#) page 4 (“The name “random variable” is actually a misnomer, since it is not random and not a variable....the *random variable* simply maps each point (outcome) in the sample space to a number on the real line...Technically, the space into which the *random variable* maps the sample space may be more general than the real line...”), [Curry and Feldman \(2010\)](#) page 4, [Trivedi \(2016\)](#) page 2.1 (“The term “random variable” is actually a misnomer, since a *random variable* X is really a function whose domain is the sample space S , and whose range is the set of all real numbers, \mathbb{R} .”)

variable itself) is very deterministic and well-defined. What gives it the appearance of being random is that the outcome ω of the experiment appears to be random to the observer. So the *random variable* $X(\omega)$ is simply a function of an underlying mechanism that appears to be random.

Definition B.1.³ Let (Ω, \mathbb{E}, P) be a PROBABILITY SPACE (Definition A.2 page 151).

D E F A **random variable** X is any function in \mathbb{R}^{Ω} .

B.2 Probability distributions

The probability information about σ -algebra \mathbb{E} in a *probability space* (Definition A.2 page 151) is completely specified by *measure* P . However, sometimes it is more convenient to express this same *measure* information in terms of the *probability density function* or the *cummulative distribution function* of the *probability space*.

Definition B.2.⁴ Let X be a RANDOM VARIABLE (Definition B.1 page 160) on a PROBABILITY SPACE (Ω, \mathbb{E}, P) .

D E F

X has cummulative distribution function (cdf) $c_X(x)$ if $c_X(x) \triangleq P\{x \in \mathbb{E} X < x\}$	X probability density function (pdf) $p_X(x)$ if $p_X(x) \triangleq \frac{d}{dx}c_X(x) \triangleq \frac{d}{dx}P\{x \in \mathbb{E} X < x\}$
---	--

Remark B.2. Suppose X be a *random variable* on a *probability space* (Ω, \mathbb{E}, P) . Note that

- Both X and \mathbb{E} are *functions*.
- But X is a function that maps from Ω to \mathbb{R} ,
- whereas P is a function that maps from \mathbb{E} to \mathbb{R} .

Definition B.3. Let (Ω, \mathbb{E}, P) be a PROBABILITY SPACE (Definition A.2 page 151) and X and $Y : \Omega \rightarrow \mathbb{R}$ random variables. Then a **joint probability density function** $p_{XY} : \mathbb{E} \times \Omega \rightarrow [0 : 1]$ and a **joint cumulative distribution function** $c_{XY} : \mathbb{E} \times \Omega \rightarrow [0 : 1]$ are defined as

D E F

$c_{XY}(x, y) \triangleq P\{X \leq x Y \leq y\}$ (JOINT CUMULATIVE DISTRIBUTION FUNCTION)	$p_{XY}(x, y) \triangleq \frac{d}{dy} \frac{d}{dx} c_{XY}(x, y)$ (JOINT PROBABILITY DENSITY FUNCTION)
---	---

Definition B.4. Let (Ω, \mathbb{E}, P) be a PROBABILITY SPACE (Definition A.2 page 151) and X a random variable. Then a **conditional probability density function** $p_X : \mathbb{E} \times \Omega \rightarrow [0 : 1]$ and a **conditional cumulative distribution function** $c_X : \mathbb{E} \times \Omega \rightarrow [0 : 1]$ are defined as

D E F

$c_X(x y) \triangleq P\{X \leq x Y = y\}$ (CONDITIONAL CUMULATIVE DISTRIBUTION FUNCTION—CDF)	$p_X(x y) \triangleq \frac{d}{dx} c_X(x y)$ (CONDITIONAL PROBABILITY DENSITY FUNCTION—PDF)
--	--

B.3 Properties

Definition B.2 (page 160) defines the pdf and cdf of a *probability space* (Ω, \mathbb{E}, P) in terms of *measure* P . Conversely, the probability *measure* $P\{a \leq X < b\}$ of an event $\{a \leq X < b\}$ can be expressed in terms of either the pdf or cdf.

³  Papoulis (1991), page 63

⁴  von der Linden et al. (2014) page 93 (Definitions 7.1, 7.2)

Proposition B.1. Let X a RANDOM VARIABLE with PDF p_x and CDF c_x (Definition B.2 page 160) on the PROBABILITY SPACE (Ω, \mathbb{E}, P) (Definition A.2 page 151).

P R P	$\begin{aligned} & \left\{ \begin{array}{l} (1). \quad c_x(x) \text{ and } c_y(y) \text{ are CONTINUOUS} \\ (2). \quad p_x(x) \text{ and } p_y(y) \text{ are CONTINUOUS} \end{array} \text{ OR } \right\} \\ \implies & \left\{ \begin{array}{l} p_x(x) = \lim_{\epsilon \rightarrow 0} \frac{1}{\epsilon} P\{x \leq X < x + \epsilon\} \\ p_{xy}(x, y) = \lim_{\epsilon \rightarrow 0} \frac{1}{\epsilon} P\{x \leq X < x + \epsilon \wedge y \leq Y < y + \epsilon\} \end{array} \right\} \end{aligned}$
-------------	--

PROOF:

$$\begin{aligned} p_x(x) &\triangleq \frac{d}{dx} c_x(x) && \text{by definition of } p_x && (\text{Definition B.2 page 160}) \\ &= \lim_{\epsilon \rightarrow 0} \frac{1}{\epsilon} P\{x \in \mathbb{R} | x \leq X < x + \epsilon\} && \text{by definition of } \frac{d}{dx} && (\text{Definition ?? page ??}) \end{aligned}$$



Theorem B.1. Let (Ω, \mathbb{E}, P) be a probability space, X be a random variable, and (a, b) a real interval.

T H M	$\left\{ \begin{array}{l} (1). \quad c_x(x) \text{ is CONTINUOUS} \\ (2). \quad p_x(x) \text{ is CONTINUOUS} \end{array} \text{ OR } \right\} \implies \left\{ P\{a < X \leq b\} = c_x(b) - c_x(a) = \int_a^b p_x(x) dx \right\}$
-------------	---

PROOF:

$$\begin{aligned} P\{a < X \leq b\} &= P\{X \leq b\} - P\{X < a\} && \text{by sum of products} && (\text{Theorem A.3 page 153}) \\ &= P\{X \leq b\} - P\{X \leq a\} && \text{by continuity hypothesis} \\ &\triangleq c_x(b) - c_x(a) && \text{by definition of } c_x && (\text{Definition B.2 page 160}) \end{aligned}$$

$$\begin{aligned} \int_a^b p_x(x) dx &\triangleq \int_a^b \left[\frac{d}{dx} c_x(x) \right] dx && \text{by definition of } p_x && (\text{Definition B.2 page 160}) \\ &= c_x(x)|_{x=b} - c_x(x)|_{x=a} && \text{by Fundamental theorem of calculus} \\ &= c_x(b) - c_x(a) \end{aligned}$$



Theorem B.2. Let (Ω, \mathbb{E}, P) be a PROBABILITY SPACE, X be a RANDOM VARIABLE, and $(a : b)$ a REAL INTERVAL.

T H M	$P\{a \leq X < b\} = \int_a^b p_x(x) dx = \int_{-\infty}^b c_x(x) dx - \int_{-\infty}^a c_x(x) dx$
-------------	--

The properties of the pdf follow closely the properties of measure P .

Theorem B.3. ⁵

T H M	$\left\{ \begin{array}{l} (A). \quad c_x(x) \text{ is CONTINUOUS} \\ (B). \quad p_x(x) \text{ is CONTINUOUS} \end{array} \text{ OR } \right\} \implies \left\{ \begin{array}{l} (1). \quad p_{xy}(x y) = \frac{p_{xy}(x, y)}{p_y(y)} \text{ and} \\ (2). \quad p_x(x) = \int_{y \in \mathbb{R}} p_{xy}(x, y) dy \end{array} \right\}$
-------------	---

⁵ Papoulis (1990) page 158 (Auxiliary Variable), Jazwinski (1970), page 39 (“(2.102)”), Jazwinski (2007) page 39 (“(2.102)”).

PROOF:

$$\begin{aligned}
 p_{X|Y}(x|y) &\triangleq \frac{d}{dx} c_{X|Y}(x|y) && \text{by definition of } c_X \quad (\text{Definition A.4 page 152}) \\
 &\triangleq \lim_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} P\{x \leq X < x + \varepsilon | Y = y\} && \text{by definition of } \frac{d}{dx} \quad (\text{Definition ?? page ??}) \\
 &\triangleq \lim_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} \frac{P\{(x \leq X < x + \varepsilon) \wedge (Y = y)\}}{P\{Y = y\}} && \text{by definition of } P\{A|B\} \quad (\text{Definition A.4 page 152}) \\
 &= \lim_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} \frac{P\{(x \leq X < x + \varepsilon) \wedge (y \leq Y < y + \varepsilon)\}}{P\{y \leq Y < y + \varepsilon\}} && \text{by continuity hypothesis} \\
 &= \frac{\lim_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} P\{(x \leq X < x + \varepsilon) \wedge (y \leq Y < y + \varepsilon)\}}{\lim_{\varepsilon \rightarrow 0} P\{y \leq Y < y + \varepsilon\}} && \text{by property of } \lim_{\varepsilon \rightarrow 0} \\
 &= \frac{p_{XY}(x, y)}{p_Y(y)} && \text{by Proposition B.1 page 161}
 \end{aligned}$$

$$\begin{aligned}
 \int_{y \in \mathbb{R}} p_{XY}(x, y) dy &\triangleq \int_{y \in \mathbb{R}} \left[\frac{d}{dy} \frac{d}{dx} c_{XY}(x, y) \right] dy && \text{by definition of } p_X \quad (\text{Definition B.2 page 160}) \\
 &= \frac{d}{dx} c_{XY}(x, y) && \\
 &\triangleq \lim_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} \int_{y \in \mathbb{R}} P\{x \leq X < x + \varepsilon, y \leq Y < y + \varepsilon\} dy && \text{by definition of } \frac{d}{dx} \quad (\text{Definition ?? page ??}) \\
 &= \lim_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} P\{x \leq X < x + \varepsilon\} && \\
 &= p_X(x) && \text{by Proposition B.1 page 161}
 \end{aligned}$$

⇒

Theorem B.4.

T	$c_X(\sup \mathbb{R}) = 1$
H	$c_X(\inf \mathbb{R}) = 0$

PROOF:

$$\begin{aligned}
 c_X(\sup \mathbb{R}) &\triangleq P\{X \leq \sup \mathbb{R}\} && \text{by definition of } c_X \quad (\text{Definition B.2 page 160}) \\
 &= 1 \\
 c_X(\inf \mathbb{R}) &\triangleq P\{X \leq \inf \mathbb{R}\} && \text{by definition of } c_X \quad (\text{Definition B.2 page 160}) \\
 &= 0
 \end{aligned}$$

⇒

The properties of the pdf follow closely the properties of measure P.

Theorem B.5.

T	$c_{X Y}(x y) = \frac{\frac{d}{dy} c_{XY}(x, y)}{p_Y(y)}$	$p_{X Y}(x y) = \frac{p_{XY}(x, y)}{p_Y(y)}$
---	---	--



PROOF:

$$\begin{aligned}
 c_{X|Y}(x|y) &\triangleq P\{X \leq x | Y = y\} && \text{by definition of } c_{X|Y} && (\text{Definition B.4 page 160}) \\
 &\triangleq \frac{P\{X \leq x | Y = y\}}{P\{Y = y\}} && \text{by definition of } P\{X|Y\} && (\text{Definition A.4 page 152}) \\
 &= \lim_{\epsilon \rightarrow 0} \frac{P\{X \leq x | y < Y \leq y + \epsilon\}}{P\{y < Y \leq y + \epsilon\}} \\
 &= \lim_{\epsilon \rightarrow 0} \frac{[P\{X \leq x | Y \leq y + \epsilon\} - P\{X \leq x | Y \leq y\}]/\epsilon}{[P\{Y \leq y + \epsilon\} - P\{Y \leq y\}]/\epsilon} \\
 &\triangleq \lim_{\epsilon \rightarrow 0} \frac{[c_{XY}(x, y + \epsilon) - c_{XY}(x, y)]/\epsilon}{[c_Y(y + \epsilon) - c_Y(y)]/\epsilon} && \text{by definition of } c_{XY} && (\text{Definition B.3 page 160}) \\
 &\triangleq \frac{\frac{d}{dy}c_{XY}(x, y)}{\frac{d}{dy}c_Y(y)} && \text{by definition of } \frac{d}{dy}f(y) \\
 &\triangleq \frac{\frac{d}{dy}c_{XY}(x, y)}{p_Y(y)} && \text{by definition of } p_Y && (\text{Definition B.2 page 160}) \\
 &= \frac{\frac{d}{dy}c_{XY}(x, y)}{p_Y(y)} && \text{because } y \text{ is fixed}
 \end{aligned}$$

$$\begin{aligned}
 p_{X|Y}(x|y) &\triangleq \frac{d}{dx}c_{X|Y}(x|y) && \text{by definition of } p_{X|Y} && (\text{Definition B.4 page 160}) \\
 &= \frac{d}{dx} \frac{\frac{d}{dy}c_{XY}(x, y)}{p_Y(y)} && \text{by previous result} \\
 &= \frac{\frac{d}{dx}\frac{d}{dy}c_{XY}(x, y)}{p_Y(y)} && \text{because } p_Y(y) \text{ is not a function of } x \\
 &\triangleq \frac{p_{XY}(x, y)}{p_Y(y)} && \text{by definition of } p_{XY}(x, y) && (\text{Definition B.3 page 160})
 \end{aligned}$$

Theorem B.6. Let (Ω, \mathbb{E}, P) be a probability space.

T H M	$\int_{x \in \mathbb{R}} p_X(x) dx = 1$ $\int_{y \in \mathbb{R}} p_{XY}(x, y) dy = p_X(x) \quad \forall x \in \Omega$	$\int_{x \in \mathbb{R}} p_{X Y}(x y) dx = 1$ $\int_{x \in \mathbb{R}} \int_{y \in \mathbb{R}} p_{XY}(x, y) dy dx = 1$
----------------------	--	---

PROOF:

$$\begin{aligned}
 \int_{\mathbb{R}} p_X(x) dx &= c_X(\sup \mathbb{R}) - c_X(\inf \mathbb{R}) && \text{by Theorem B.1 page 161} \\
 &= 1 - 0 \\
 &= 1 && \text{because 0 is the additive identity element in } (\mathbb{R}, +, \cdot, 0, 1) \\
 \int_{x \in \mathbb{R}} p_{X|Y}(x|y) dx &\triangleq \int_{x \in \mathbb{R}} \frac{d}{dx}c_{X|Y}(x|y) dx && \text{by definition of } p_{X|Y}(x|y) (\text{Definition B.4 page 160}) \\
 &= c_{X|Y}(\sup \mathbb{R}|y) - c_{X|Y}(\inf \mathbb{R}|y) && \text{by Fundamental theorem of calculus}
 \end{aligned}$$

$$= 1 - 0$$

$$= 1$$

because 0 is the additive identity element in $(\mathbb{R}, +, \cdot, 0, 1)$

$$\int_{y \in \mathbb{R}} p_{XY}(x, y) dy = \int_{y \in \mathbb{R}} p_{YX}(y, x) dy$$

$$= \int_{y \in \mathbb{R}} p_{Y|X}(y|x) p_X(x) dy$$

by Theorem B.5 page 162

$$= p_X(x) \int_{y \in \mathbb{R}} p_{Y|X}(y|x) dy$$

because $p_X(x)$ is not a function of y

$$= p_X(x) \cdot 1$$

by previous result

$$= p_X(x)$$

because 1 is the multiplicative identity element in $(\mathbb{R}, +, \cdot, 0, 1)$

$$\int_{x \in \mathbb{R}} \int_{y \in \mathbb{R}} p_{XY}(x, y) dy dx = \int_{x \in \mathbb{R}} p_X(x) dx$$

by previous result

$$= 1$$

by previous result



APPENDIX C

SOME PROBABILITY DENSITY FUNCTIONS

C.1 Discrete distributions

Example C.1. ¹ Suppose we throw two “fair” dice and want to know the probabilities of their sum. Let X represent the sum of the face values of the two dice. The resulting probability distribution is illustrated in Figure C.1 (page 166) and has probability space as follows:

EX	$\Omega = \{\square\square, \square\bullet\square, \square\square\bullet, \dots, \bullet\bullet\bullet\}$
	$\mathbb{E} = \{2^{n=2,3,\dots,10,11, \text{ or } 12}\}$
	$P(e) = \frac{1}{36} e $

C.2 Continuous distributions

C.2.1 Uniform distribution

Definition C.1. The **uniform distribution** $p_x(x)$ is defined as

DEF	$p_x(x) \triangleq \begin{cases} 1 & \text{for } 0 < x \leq 1 \\ 0 & \text{otherwise} \end{cases}$
-----	--

Note that although “simple” in form, in light of Wold's Theorem,² the value of the *uniform distribution* should *not* be taken lightly.

¹  Osgood (2002)

²  Wold (1938),  Wold (1954),  Scargle (1979)

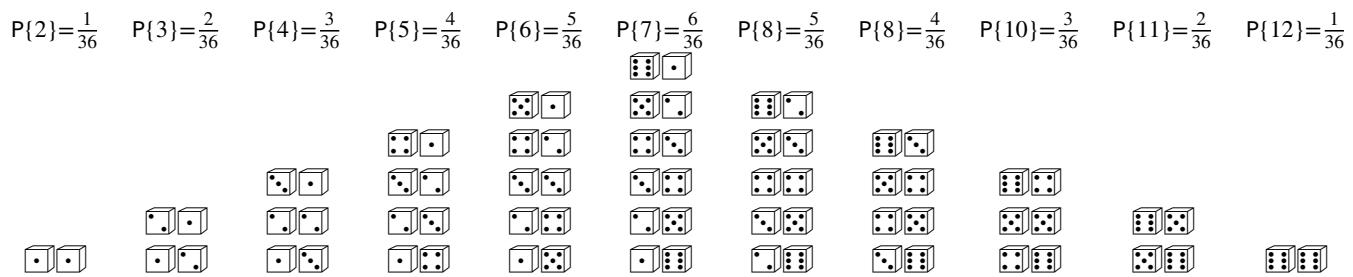


Figure C.1: Probability distribution for two dice (see Example C.1 page 165)

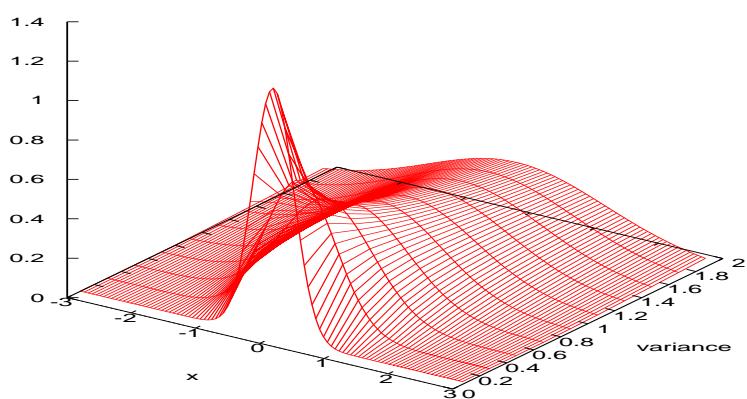
C.2.2 Gaussian distribution

“Tout le monde y croit cependant, me disait un jour M. Lippmann, car les expérimentateurs s’imagine que c’est un théorème de mathématiques, et les mathématiciens que c’est un fait expérimental.”



“Everyone believes in it [(the normal distribution)] however, said to me one day Mr. Lippmann, because the experimenters imagine that it is a theorem of mathematics, and mathematicians that it is an experimental fact.”

Bernard A. Lippmann as told by Henri Poincaré ³

Figure C.2: Gaussian pdf with $\mu = 0$ and $\sigma \in [0.1, 2]$.

Definition C.2.

³ quote: Poincaré (1912), page 171
translation: assisted by Google Translate
image:



The **Gaussian distribution** (or **normal distribution**) has pdf

$$p_x(x) \triangleq \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

A random variable X with this distribution is denoted

$$X \sim N(\mu, \sigma^2)$$

The function $Q(x)$ is defined as the area under a Gaussian PDF with zero mean and variance equal to one from x to infinity such that

$$Q(x) \triangleq \frac{1}{\sqrt{2\pi}} \int_x^\infty e^{-\frac{u^2}{2}} du$$

C.2.3 Gamma distribution

Definition C.3. ⁴ Let $b \in \mathbb{R}$. The **gamma function** $\Gamma(b)$ is

$$\text{DEF } \Gamma(b) \triangleq \int_0^\infty x^{b-1} e^{-x} dx$$

Proposition C.1. ⁵ Let $b \in \mathbb{R}$ and $n \in \mathbb{N}$.

$$\begin{aligned} \text{P} & \Gamma(b) = (b-1)\Gamma(b-1) \\ \text{R} & \Gamma(n) = (n-1)! \end{aligned}$$

PROOF: Let

$$\begin{aligned} u &= x^{b-1} & du &= (b-1)x^{b-2} dx \\ dv &= e^{-x} dx & v &= -e^{-x} \end{aligned}$$

$$\begin{aligned} \Gamma(b) &\triangleq \int_0^\infty x^{b-1} e^{-x} dx \\ &= \int_{x=0}^\infty u dv \\ &= uv|_{x=0}^\infty - \int_{x=0}^\infty v du \\ &= -x^{b-1} e^{-x}|_{x=0}^\infty + (b-1) \int_{x=0}^\infty e^{-x} x^{b-1} dx \\ &= (-0+0) + (b-1)\Gamma(b-1) \end{aligned}$$

Note that

$$\Gamma(1) = \int_0^\infty x^{1-1} e^{-x} dx = \int_0^\infty e^{-x} dx = -e^{-x}|_0^\infty = -0+1=1$$

$$\begin{aligned} \Gamma(n) &= (n-1)\Gamma(n-1) \\ &= (n-1)(n-2)\Gamma(n-2) \\ &= (n-1)(n-2)(n-3)\Gamma(n-3) \\ &\vdots \\ &= (n-1)(n-2)(n-3)\cdots(1)\Gamma(1) \\ &= (n-1)(n-2)(n-3)\cdots(1) \\ &\triangleq (n-1)! \end{aligned}$$

⁴ Papoulis (1991), page 79, Ross (1998), page 222

⁵ Ross (1998), page 223



Definition C.4. A **Gamma distribution** (b, λ) has pdf

D E F $p_x(x) \triangleq \frac{\lambda}{\Gamma(b)} e^{-\lambda x} (\lambda x)^{b-1}$

Theorem C.1. ⁶ Let X and Y be RANDOM VARIABLES on a PROBABILITY SPACE (Ω, \mathbb{E}, P) .

T H M $\left\{ \begin{array}{ll} (A). & X \text{ and } Y \text{ are INDEPENDENT} \\ (B). & X \text{ has GAMMA DISTRIBUTION } (a, \lambda) \quad \text{and} \\ (C). & Y \text{ has GAMMA DISTRIBUTION } (b, \lambda) \quad \text{and} \\ (D). & Z \triangleq X + Y \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} Z \text{ has Gamma distribution} \\ (a+b, \lambda). \end{array} \right\}$

PROOF:

$$p_z(z) = p_x(z) \star p_y(z)$$

$$= \int_{u \in \mathbb{R}} p_x(u) p_y(z-u) du$$

by definition of *convolution* (Definition P.3 page 336)

$$= \int_0^z \frac{1}{\Gamma(a)} \lambda e^{-\lambda u} (\lambda u)^{a-1} \frac{1}{\Gamma(b)} \lambda e^{-\lambda(z-u)} (\lambda(z-u))^{b-1} du$$

$$= \frac{1}{\Gamma(a)} \frac{1}{\Gamma(b)} e^{-\lambda z} \lambda^{1+1+a-1+b-1} \int_0^z u^{a-1} (z-u)^{b-1} du$$

$$= \frac{1}{\Gamma(a)} \frac{1}{\Gamma(b)} \lambda e^{-\lambda z} \lambda^{a+b-1} \int_0^1 (vz)^{a-1} (z-vz)^{b-1} z dv$$

$$= \frac{1}{\Gamma(a)} \frac{1}{\Gamma(b)} \lambda e^{-\lambda z} \lambda^{a+b-1} z^{a-1+b-1+1} \int_0^1 v^{a-1} (1-v)^{b-1} dv$$

$$= \left[\frac{1}{\Gamma(a)} \frac{1}{\Gamma(b)} \int_0^1 v^{a-1} (1-v)^{b-1} dv \right] \lambda e^{-\lambda z} (\lambda z)^{a+b-1}$$

$$= C \lambda e^{-\lambda z} (\lambda z)^{a+b-1}$$

where C is some constant

$$= \frac{\lambda}{\Gamma(a+b)} e^{-\lambda z} (\lambda z)^{a+b-1}$$

C must be the value that makes $\int_z p_z(z) = 1$

$\Rightarrow p_z(z)$ is a $(a+b, \lambda)$ Gamma distribution



C.2.4 Chi-squared distributions

Definition C.5. ⁷ Let $p(x)$ be a PROBABILITY DENSITY FUNCTION on a PROBABILITY SPACE (Ω, \mathbb{E}, P) .

D E F $p(x)$ is a **chi-square distribution** if

$$p(x) \triangleq \begin{cases} 0 & \text{if } x < 0 \\ \frac{1}{\sqrt{2\pi\sigma^2 x}} \exp\left[-\frac{x}{2\sigma^2}\right] & \text{if } x \geq 0 \end{cases} \quad \text{for } \sigma > 0$$

Theorem C.2. ⁸

⁶ Ross (1998), page 266

⁷ Proakis (2001), page 41, Papoulis (1990) page 219 (7-4 Special Distributions of Statistics, (7-78))

⁸ Ross (1998), page 267

THM

The following distributions are equivalent:

- (1). chi-squared distribution and
- (2). distribution of X^2 where $X \sim N(0, \sigma^2)$ and
- (3). Gamma distribution $\left(\frac{1}{2}, \frac{1}{2\sigma^2}\right)$

PROOF:

1. Proof that X^2 has chi-squared distribution:

$$\begin{aligned} p_Y(y) &= \frac{1}{2\sqrt{y}} \left[p_X(-\sqrt{y}) + p_X(\sqrt{y}) \right] && \text{by Corollary 5.3 page 33} \\ &= \frac{1}{2\sqrt{y}} \left[\frac{1}{\sqrt{2\pi\sigma^2}} \exp -\frac{(-\sqrt{y}-0)^2}{2\sigma^2} + \frac{1}{\sqrt{2\pi\sigma^2}} \exp -\frac{(+\sqrt{y}-0)^2}{2\sigma^2} \right] \\ &= \frac{1}{2\sqrt{y}} \left[2 \frac{1}{\sqrt{2\pi\sigma^2}} \exp -\frac{y}{2\sigma^2} \right] \\ &= \frac{1}{\sqrt{2\pi\sigma^2 y}} \exp -\frac{y}{2\sigma^2} \end{aligned}$$

2. Proof that chi-distribution is a Gamma distribution (b, λ) :

$$\begin{aligned} b &\triangleq \frac{1}{2} \\ \lambda &\triangleq \frac{1}{2\sigma^2} \end{aligned}$$

$$\begin{aligned} \frac{1}{\sqrt{2\pi\sigma^2 y}} \exp -\frac{y}{2\sigma^2} &= \frac{1}{\sqrt{\pi}} \lambda^{1/2} \lambda^{1/2} (\lambda y)^{-1/2} e^{-\lambda y} \\ &= \frac{\lambda}{\sqrt{\pi}} (\lambda y)^{b-1} e^{-\lambda y} \end{aligned}$$



Definition C.6. ⁹ The Chi-squared distribution with n degrees of freedom has pdf

$$\begin{array}{|c|} \hline \text{DEF} \\ \hline \end{array} p_Y(y) \triangleq \begin{cases} 0 & : y < 0 \\ \frac{1}{2\sigma^2 \Gamma(n/2)} \left(\frac{y}{2\sigma^2}\right)^{\frac{n}{2}-1} \exp -\frac{y}{2\sigma^2} & : y \geq 0 \end{cases}$$

Theorem C.3. ¹⁰ The following distributions are equivalent:

1. chi-squared distribution with n degrees of freedom

2. the distribution of $\sum_{k=1}^n X_k^2$ where $\{X_k | X_k \sim N(0, \sigma^2), k = 1, 2, \dots, n\}$ are independent random variables.

3. Gamma distribution $\left(\frac{n}{2}, \frac{1}{2\sigma^2}\right)$.

⁹ Proakis (2001), page 41

¹⁰ Ross (1998), page 267

PROOF:

- Prove chi-squared distribution with n degrees of freedom is the Gamma distribution $\left(\frac{n}{2}, \frac{1}{2\sigma^2}\right)$:

$$\begin{aligned} \lambda &\triangleq \frac{1}{2\sigma^2} \\ b &\triangleq \frac{1}{2} \\ \frac{1}{2\sigma^2 \Gamma(n/2)} \left(\frac{y}{2\sigma^2}\right)^{\frac{n}{2}-1} \exp -\frac{y}{2\sigma^2} &= \frac{\lambda}{\Gamma(nb)} (\lambda y)^{nb-1} \exp -\lambda y \end{aligned}$$

- Prove $\sum_{k=1}^n X_k^2$ is Gamma $\left(\frac{n}{2}, \frac{1}{2\sigma^2}\right)$:

(a) By Theorem C.2, X_k has Gamma distribution $\left(\frac{1}{2}, \frac{1}{2\sigma^2}\right)$.

(b) By Theorem C.1, $\sum_{k=1}^n X_k^2$ has distribution $\left(\frac{n}{2}, \frac{1}{2\sigma^2}\right)$.



Definition C.7. ¹¹ A **noncentral chi-square distribution** (μ, σ^2) has pdf

D E F $p_Y(y) = \frac{1}{\sqrt{2\pi\sigma^2 y}} \exp \frac{y + \mu^2}{-2\sigma^2} \cosh \frac{\mu\sqrt{y}}{\sigma^2}$

Theorem C.4.

T H M The following distributions are equivalent:

- (1). NON-CENTRAL CHI-SQUARED DISTRIBUTION (μ, σ^2)
- (2). distribution of X^2 where $X \sim N(\mu, \sigma^2)$

PROOF:

- Proof that $Y = X^2$ has a non-central chi-squared distribution:

$$\begin{aligned} p_Y(y) &= \frac{1}{2\sqrt{y}} \left[p_X(-\sqrt{y}) + p_X(\sqrt{y}) \right] \quad \text{by Corollary 5.3 page 33} \\ &= \frac{1}{2\sqrt{y}} \left[\frac{1}{\sqrt{2\pi\sigma^2}} \exp -\frac{(-\sqrt{y} - \mu)^2}{2\sigma^2} + \frac{1}{\sqrt{2\pi\sigma^2}} \exp -\frac{(+\sqrt{y} - \mu)^2}{2\sigma^2} \right] \\ &= \frac{1}{2\sqrt{y}} \left[\frac{1}{\sqrt{2\pi\sigma^2}} \exp -\frac{y + \mu^2}{2\sigma^2} \exp \frac{-2\mu\sqrt{y}}{2\sigma^2} + \frac{1}{\sqrt{2\pi\sigma^2}} \exp -\frac{y + \mu^2}{2\sigma^2} \exp \frac{2\mu\sqrt{y}}{2\sigma^2} \right] \\ &= \frac{1}{\sqrt{2\pi\sigma^2 y}} \exp -\frac{y + \mu^2}{2\sigma^2} \frac{1}{2} \left[\exp \frac{2\mu\sqrt{y}}{2\sigma^2} + \exp \frac{-2\mu\sqrt{y}}{2\sigma^2} \right] \\ &= \frac{1}{\sqrt{2\pi\sigma^2 y}} \exp \frac{y + \mu^2}{-2\sigma^2} \cosh \frac{\mu\sqrt{y}}{\sigma^2} \end{aligned}$$



¹¹ Proakis (2001), page 42

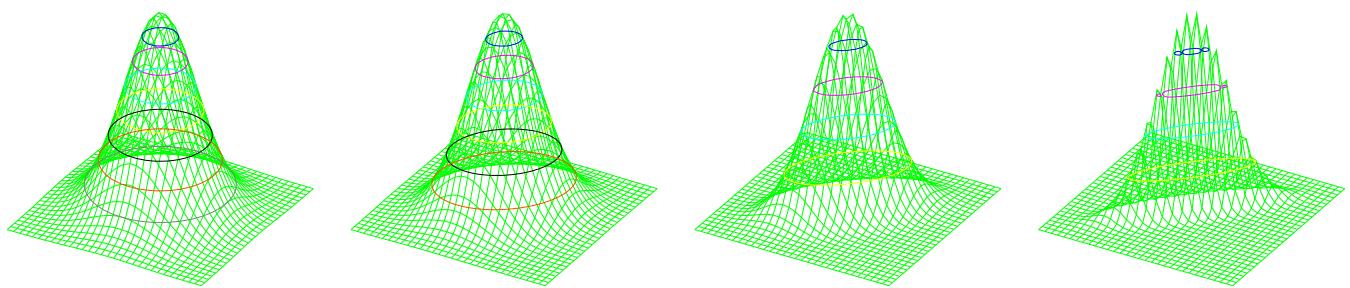


Figure C.3: *Joint Gaussian distributions $p_{xy}(x, y)$ with varying correlations*

Definition C.8. ¹² The α th-order modified Bessel function of the first kind $I_\alpha(x)$ is

$$\text{DEF } I_\alpha(x) = \sum_{k=0}^{\infty} \frac{1}{k! \Gamma(\alpha + k + 1)} \left(\frac{x}{2}\right)^{\alpha+2k}$$

Definition C.9. ¹³ The noncentral chi-square with n -degrees of freedom distribution has pdf

$$\text{DEF } p_Y(y) = \frac{1}{2\sigma^2} \left(\frac{y}{s^2}\right)^{\frac{n-2}{4}} \exp \frac{y+s^2}{-2\sigma^2} I_{n/2-1} \left(\sqrt{y} \frac{s}{\sigma^2}\right) \quad \text{where } s^2 \triangleq \sum_{k=1}^n \mu_k^2$$

C.2.5 Radial distributions

Definition C.10. ¹⁴ The Rayleigh distribution is the pdf

$$\text{DEF } p_R(r) = \begin{cases} 0 & \text{for } r < 0 \\ \frac{r}{\sigma^2} \exp -\frac{r^2}{2\sigma^2} & \text{for } r \geq 0 \end{cases}$$

Note that by Proposition 5.3, this distribution is equivalent to the distribution of $R = \sqrt{X^2 + Y^2}$ where X and Y are independent random variables each with distribution $N(0, \sigma^2)$.

Definition C.11. ¹⁵ The Rice distribution is the pdf

$$\text{DEF } p_R(r) = \begin{cases} 0 & \text{for } r < 0 \\ \frac{r}{\sigma^2} \exp \frac{r^2+s^2}{-2\sigma^2} I_o \left(\frac{rs}{\sigma^2}\right) & \text{for } r \geq 0 \end{cases}$$

C.3 Joint Gaussian distributions

Definition C.12 (Joint Gaussian pdf). ¹⁶

$$p(x_1, x_2, \dots, x_n) \triangleq \frac{1}{\sqrt{(2\pi)^n |\mathbf{M}|}} \exp -\frac{1}{2}(\mathbf{x} - \mathbf{E}\mathbf{x})^T \mathbf{M}^{-1}(\mathbf{x} - \mathbf{E}\mathbf{x}) \quad (\text{Gaussian joint pdf})$$

DEF

$$\begin{aligned} \mathbf{x} &\triangleq \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \\ Z_k &\triangleq X_k - \mathbf{E}X_k \end{aligned} \quad (\text{zero mean random variables})$$

$$\mathbf{M} \triangleq \begin{bmatrix} E[Z_1Z_1] & E[Z_1Z_2] & \cdots & E[Z_1Z_n] \\ E[Z_2Z_1] & E[Z_2Z_2] & \ddots & E[Z_2Z_n] \\ \vdots & \vdots & \ddots & \vdots \\ E[Z_nZ_1] & E[Z_nZ_2] & \cdots & E[Z_nZ_n] \end{bmatrix} \quad (\text{correlation matrix})$$

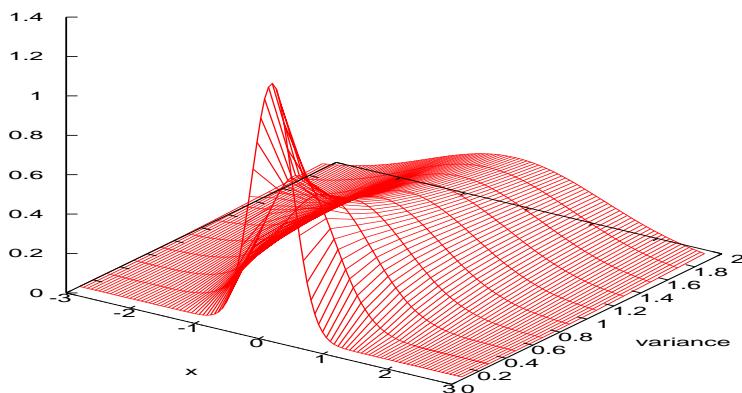


Figure C.4: Gaussian pdf with $\mu = 0$ and $\sigma \in [0.1, 2]$.

Example C.2 (1 variable joint Gaussian pdf). The **Gaussian distribution** (or **normal distribution**) has pdf

$$\mathbf{E}_{\mathbf{X}} p_x(x) \triangleq \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

¹² Proakis (2001), page 43

¹³ Proakis (2001), page 43

¹⁴ Proakis (2001), page 44

¹⁵ Proakis (2001), page 46

¹⁶ Anderson (1984) page 21 (THEOREM 2.3.1), ANDERSON (1958), PAGE 14 (§“2.3 THE MULTIVARIATE NORMAL DISTRIBUTION”), PROAKIS (2001), PAGE 49, MOON AND STIRLING (2000), PAGE 34

$$\begin{aligned}
t &= \arg_t \min_t \left[\frac{1}{2} \int_t^\infty \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}} + \frac{1}{2} \int_{-\infty}^t \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\eta)^2}{2\sigma^2}} \right] \\
&= \arg_t \left\{ \frac{\partial}{\partial t} \left[\frac{1}{2} \int_t^\infty \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}} + \frac{1}{2} \int_{-\infty}^t \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\eta)^2}{2\sigma^2}} \right] = 0 \right\} \\
&= \arg_t \left\{ \frac{1}{2\sqrt{2\pi\sigma^2}} \left[\frac{\partial}{\partial t} \int_t^\infty e^{-\frac{(x-\mu)^2}{2\sigma^2}} + \frac{\partial}{\partial t} \int_{-\infty}^t e^{-\frac{(x-\eta)^2}{2\sigma^2}} \right] = 0 \right\} \\
&= \arg_t \left\{ \left[\left(e^{-\frac{(\infty-\mu)^2}{2\sigma^2}} 0 - e^{-\frac{(t-\mu)^2}{2\sigma^2}} 1 \right) + \left(e^{-\frac{(t-\eta)^2}{2\sigma^2}} 1 - e^{-\frac{(\infty-\eta)^2}{2\sigma^2}} 0 \right) \right] = 0 \right\} \\
&= \arg_t \left\{ \left[e^{-\frac{(t-\eta)^2}{2\sigma^2}} - e^{-\frac{(t-\mu)^2}{2\sigma^2}} \right] = 0 \right\} \\
&= \arg_t \{ (t - \eta)^2 = (t - \mu)^2 \} \\
&= \frac{\mu + \eta}{2}
\end{aligned}$$

Example C.3 (2 variable joint Gaussian pdf).

EX	$ \begin{aligned} z_1 &\triangleq x_1 - \mathbb{E}x_1 \\ z_2 &\triangleq x_2 - \mathbb{E}x_2 \\ M &\triangleq \mathbb{E}[z_1 z_1] \mathbb{E}[z_2 z_2] - \mathbb{E}[z_1 z_2] \mathbb{E}[z_1 z_2] \\ p(x_1, x_2) &\triangleq \frac{1}{2\pi\sqrt{ M }} \exp\left(\frac{z_1^2 \mathbb{E}[z_2 z_2] - 2z_1 z_2 \mathbb{E}[z_1 z_2] + z_2^2 \mathbb{E}[z_1 z_1]}{-2 M }\right) \end{aligned} $
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APPENDIX D

SPECTRAL THEORY

D.1 Operator Spectrum

Definition D.1. ¹ Let $\mathbf{A} \in \mathcal{B}(X, Y)$ be an operator over the linear spaces $X = (X, F, \oplus, \otimes)$ and $Y \triangleq (Y, F, \oplus, \otimes)$. Let $\mathcal{N}(\mathbf{A})$ be the NULL SPACE of \mathbf{A} .

D E F An **eigenvalue** of \mathbf{A} is any value λ such that there exists \mathbf{x} such that $\mathbf{Ax} = \lambda\mathbf{x}$.

The **eigenspace** H_λ of \mathbf{A} at eigenvalue λ is $\mathcal{N}(\mathbf{A} - \lambda\mathbf{I})$.

An **eigenvector** of \mathbf{A} associated with eigenvalue λ is any element of $\mathcal{N}(\mathbf{A} - \lambda\mathbf{I})$.

Example D.1. ² Let \mathbf{D} be the differential operator.

E X The set $\{e^{\lambda x} | \lambda \in \mathbb{C}\}$ are the eigenvectors of \mathbf{D} .

$\rho(\mathbf{D}) = \emptyset$ (\mathbf{D} has no non-spectral points whatsoever)

$\sigma_p(\mathbf{D}) = \sigma(\mathbf{D})$ (the spectrum of \mathbf{D} is all eigenvalues)

$\sigma_c(\mathbf{D}) = \emptyset$ (\mathbf{D} has no continuous spectrum)

$\sigma_r(\mathbf{D}) = \emptyset$ (\mathbf{D} has no resolvent spectrum)

PROOF:

$$\begin{aligned} (\mathbf{D} - \lambda\mathbf{I})e^{\lambda x} &= \mathbf{D}e^{\lambda x} - \lambda\mathbf{I}e^{\lambda x} \\ &= \lambda e^{\lambda x} - \lambda e^{\lambda x} \\ &= 0 \end{aligned} \quad \forall \lambda \in \mathbb{C}$$

This theorem and proof needs more work and investigation to prove/disprove its claims. ⇒

Definition D.2. ³ Let $\mathbf{A} \in \mathcal{B}(X, Y)$ be an operator over the linear spaces $X = (X, F, \oplus, \otimes)$ and $Y \triangleq (Y, F, \oplus, \otimes)$.

¹ Bollobás (1999), page 168, Descartes (1637), Descartes (1954), Cayley (1858), Hilbert (1904), page 67, Hilbert (1912),

² Pedersen (2000), page 79

³ Michel and Herget (1993), page 439

quantity	$\mathcal{N}(\mathbf{A} - \lambda\mathbf{I}) = \{\mathbf{0}\}$ ($\mathbf{x} = \mathbf{0}$ is the only solution)	$\overline{\mathcal{R}(\mathbf{A} - \lambda\mathbf{I})} = \mathbf{X}$ (dense)	$(\mathbf{A} - \lambda\mathbf{I})^{-1} \in \mathcal{B}(\mathbf{X}, \mathbf{Y})$ (continuous/bounded)
$\rho(\mathbf{A})$ (resolvent set)	1	1	1
$\sigma_p(\mathbf{A})$ (point spectrum)	0		
$\sigma_r(\mathbf{A})$ (residual spectrum)	1	0	
$\sigma_c(\mathbf{A})$ (continuous spectrum)	1	1	0

Table D.1: Spectrum of an operator \mathbf{A}

The **resolvent set** $\rho(\mathbf{A})$ of operator \mathbf{A} is defined as

$$\text{DEF } \rho(\mathbf{A}) \triangleq \left\{ \lambda \in F \mid \begin{array}{l} 1. \quad \mathcal{N}(\mathbf{A} - \lambda\mathbf{I}) = \{\mathbf{0}\} \\ 2. \quad \overline{\mathcal{R}(\mathbf{A} - \lambda\mathbf{I})} = \mathbf{X} \\ 3. \quad (\mathbf{A} - \lambda\mathbf{I})^{-1} \in \mathcal{B}(\mathbf{X}, \mathbf{Y}) \end{array} \right. \begin{array}{l} \text{(no non-zero eigenvectors)} \\ \text{(the range is dense in } \mathbf{X} \text{).} \\ \text{(inverse is continuous/bounded).} \end{array} \right\} \text{and and}$$

The **spectrum** $\sigma(\mathbf{A})$ of operator \mathbf{A} is defined as

$$\sigma(\mathbf{A}) \triangleq F \setminus \rho(\mathbf{A}).$$

Definition D.3. ⁴ Let $\mathbf{A} \in \mathcal{B}(\mathbf{X}, \mathbf{Y})$ be an operator over the linear spaces $\mathbf{X} = (X, F, \oplus, \otimes)$ and $\mathbf{Y} \triangleq (Y, F, \oplus, \otimes)$.

The **point spectrum** $\sigma_p(\mathbf{A})$ of operator \mathbf{A} is defined as

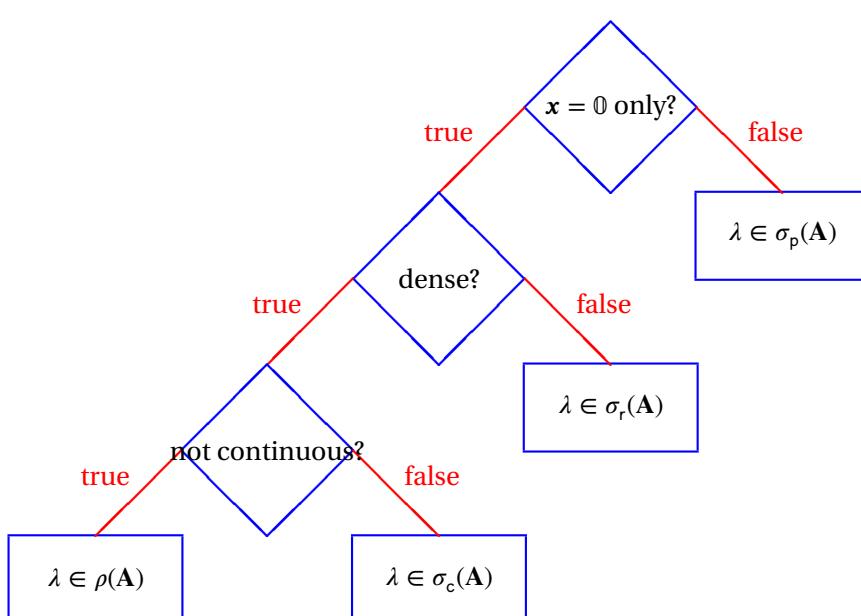
$$\sigma_p(\mathbf{A}) \triangleq \left\{ \lambda \in F \mid \begin{array}{l} 1. \quad \mathcal{N}(\mathbf{A} - \lambda\mathbf{I}) \supsetneq \{\mathbf{0}\} \\ \text{(has non-zero eigenvector)} \end{array} \right\}$$

The **residual spectrum** $\sigma_r(\mathbf{A})$ of operator \mathbf{A} is defined as

$$\sigma_r(\mathbf{A}) \triangleq \left\{ \lambda \in F \mid \begin{array}{l} 1. \quad \mathcal{N}(\mathbf{A} - \lambda\mathbf{I}) = \{\mathbf{0}\} \\ 2. \quad \overline{\mathcal{R}(\mathbf{A} - \lambda\mathbf{I})} \neq \mathbf{X} \\ \text{(not dense in } \mathbf{X} \text{—has gaps).} \end{array} \right\} \text{and}$$

The **continuous spectrum** $\sigma_c(\mathbf{A})$ of operator \mathbf{A} is defined as

$$\sigma_c(\mathbf{A}) \triangleq \left\{ \lambda \in F \mid \begin{array}{l} 1. \quad \mathcal{N}(\mathbf{A} - \lambda\mathbf{I}) = \{\mathbf{0}\} \\ 2. \quad \overline{\mathcal{R}(\mathbf{A} - \lambda\mathbf{I})} = \mathbf{X} \\ 3. \quad (\mathbf{A} - \lambda\mathbf{I})^{-1} \notin \mathcal{B}(\mathbf{X}, \mathbf{Y}) \end{array} \right. \begin{array}{l} \text{(no non-zero eigenvectors)} \\ \text{(dense in } \mathbf{X}.) \\ \text{(not continuous / not bounded)} \end{array} \right\} \text{and and}$$



The spectral components' definitions are illustrated in the figure to the left and summarized in Table D.1 (page 176). Let a family of operators $\mathbf{B}(\lambda)$ be defined with respect to an operator \mathbf{A} such that $\mathbf{B}(\lambda) \triangleq (\mathbf{A} - \lambda\mathbf{I})$. Normally, we might expect a “normal” or “regular” or even “mundane” operator $\mathbf{B}(\lambda)$ to have the properties

1. $\mathbf{B}(\lambda)\mathbf{x} = \mathbf{0}$ if and only if $\mathbf{x} = \mathbf{0}$
2. $\mathbf{B}(\lambda)\mathbf{x}$ spans virtually all of \mathbf{X} as we vary \mathbf{x}
3. $\mathbf{B}^{-1}(\lambda)$ is continuous.

After all, these are the properties that we would have if $\mathbf{B}(\lambda)$ were simply an affine operator in the

⁴ [Bollobás \(1999\)](#), page 168, [Hilbert \(1906\)](#) pages 169–172

field of real numbers— such as $[\mathbf{B}(\lambda)](x) \triangleq [\lambda](x) = \lambda x$ which is 0 if and only if $x = 0$, has range $\mathcal{R}(\lambda) = \mathbb{R}$, and its inverse $\lambda^{-1}x$ is continuous.

If for some λ the operator $\mathbf{B}(\lambda)$ does have all these “regular” properties, then that λ part of the *resolvent set* of \mathbf{A} and λ is called *regular*. However if for some λ the operator $\mathbf{B}(\lambda)$ fails any of these conditions, then that λ part of the *spectrum* of \mathbf{A} . And which conditions it fails determines which component of the spectrum it is in.

Theorem D.1. ⁵ Let $\mathbf{A} \in \mathcal{B}(X, Y)$ be an operator.

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$$\sigma(\mathbf{A}) = \sigma_p(\mathbf{A}) \cup \sigma_c(\mathbf{A}) \cup \sigma_r(\mathbf{A})$$

Theorem D.2 (Spectral Theorem). ⁶ Let $\mathbf{N} \in Y^X$ be an operator.

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$$\left. \begin{array}{l} (A). \underbrace{\mathbf{N}^* \mathbf{N} = \mathbf{N} \mathbf{N}^*}_{\mathbf{N} \text{ is NORMAL}} \\ (B). \mathbf{N} \text{ is COMPACT} \end{array} \right\} \Rightarrow$$

$$\left\{ \begin{array}{l} (1). \mathbf{N} = \sum_n \lambda_n \mathbf{P}_n \\ (2). \sum_n \mathbf{P}_n = \mathbf{I} \\ (3). \mathbf{P}_n \mathbf{P}_m = \bar{\delta}_{n-m} \mathbf{P}_n \\ (4). \dim(\mathcal{H}_n) < \infty \\ (5). |\{\lambda_n | \lambda_n \neq 0\}| \text{ is COUNTABLY INFINITE} \end{array} \right.$$

where

$$\begin{aligned} (\lambda_n)_{n \in \mathbb{Z}} &\triangleq \sigma_p(\mathbf{N}) && \text{(eigenvalues of } \mathbf{N}) \\ \mathcal{H}_n &\triangleq \mathcal{N}(\mathbf{N} - \lambda_n \mathbf{I}) && \text{(\lambda}_n \text{ is the eigenspace of } \mathbf{N} \text{ at } \lambda_n \text{ in } Y) \\ \mathbf{H}_n &= \mathbf{P}_n Y && \text{(\mathbf{P}_n \text{ is the projection operator that generates } \mathcal{H}_n)} \end{aligned}$$

D.2 Fredholm kernels

Definition D.4. ⁷

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F

A **Fredholm operator** \mathbf{K} is defined as

$$[\mathbf{K}\mathbf{f}](t) \triangleq \underbrace{\int_a^b \kappa(t, s)\mathbf{f}(s) ds}_{\text{kernel}} \quad \forall \mathbf{f} \in L_2([a, b])$$

*Fredholm integral equation of the first kind*⁸

Example D.2. Examples of Fredholm operators include

- | | | |
|------------------------------|--|--------------------------------|
| 1. Fourier Transform | $[\tilde{\mathbf{F}}\mathbf{x}](f) = \int_t x(t)e^{-i2\pi ft} dt$ | $\kappa(t, f) = e^{-i2\pi ft}$ |
| 2. Inverse Fourier Transform | $[\tilde{\mathbf{F}}^{-1}\tilde{\mathbf{x}}](t) = \int_f \tilde{\mathbf{x}}(f)e^{i2\pi ft} df$ | $\kappa(f, t) = e^{i2\pi ft}$ |
| 3. Laplace operator | $[\mathbf{L}\mathbf{x}](s) = \int_t x(t)e^{-st} dt$ | $\kappa(t, s) = e^{-st}$ |
| 4. autocorrelation operator | $[\mathbf{R}\mathbf{x}](t) = \int_s R(t, s)x(s) ds$ | $\kappa(t, s) = R(t, s)$ |

Theorem D.3. Let \mathbf{K} be a Fredholm operator with kernel $\kappa(t, s)$ and adjoint \mathbf{K}^* .

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$$[\mathbf{K}\mathbf{f}](t) = \int_A \kappa(t, s)\mathbf{f}(s) ds \iff [\mathbf{K}^*\mathbf{f}](t) = \int_A \kappa^*(s, t)\mathbf{f}(s) ds$$

⁵ Michel and Herget (1993), page 440

⁶ Michel and Herget (1993), page 457, Bollobás (1999), page 200, Hilbert (1906), Hilbert (1912), von Neumann (1929), de Witt (1659)

⁷ Michel and Herget (1993), page 425

⁸The equation $\int_u \kappa(t, s)\mathbf{f}(s) ds$ is a **Fredholm integral equation of the first kind** and $\kappa(t, u)$ is the **kernel** of the equation. References: Fredholm (1900), Fredholm (1903), page 365, Michel and Herget (1993), page 97, Keener (1988), page 101

PROOF:

$$\begin{aligned}
 [\mathbf{K}\mathbf{f}](t) &= \int_A \kappa(t, s)\mathbf{f}(s) \, ds \\
 \iff \langle [\mathbf{K}\mathbf{f}](t) | g(t) \rangle &= \left\langle \int_s \kappa(t, s)\mathbf{f}(s) \, ds | g(t) \right\rangle \quad \text{by left hypothesis} \\
 &= \int_s \mathbf{f}(s) \langle \kappa(t, s) | g(t) \rangle \, ds \quad \text{by additivity property of } \langle \Delta | \nabla \rangle \text{ (Definition K.1 page 255)} \\
 &= \int_s \mathbf{f}(s) \langle g(t) | \kappa(t, s) \rangle^* \, ds \quad \text{by conjugate symmetry property of } \langle \Delta | \nabla \rangle \text{ (Definition K.1 page 255)} \\
 &= \langle \mathbf{f}(s) | \langle g(t) | \kappa(t, s) \rangle \rangle \quad \text{by local definition of } \langle \Delta | \nabla \rangle \\
 &= \left\langle \mathbf{f}(s) | \underbrace{\int_t \kappa^*(t, s)g(t) \, dt}_{[\mathbf{K}^*\mathbf{g}](s)} \right\rangle \quad \text{by local definition of } \langle \Delta | \nabla \rangle \\
 \iff [\mathbf{K}^*\mathbf{g}](s) &= \int_A \kappa^*(t, s)g(t) \, dt \quad \text{by right hypothesis} \\
 \iff [\mathbf{K}^*\mathbf{g}](\sigma) &= \int_A \kappa^*(\tau, \sigma)g(\tau) \, d\tau \quad \text{by change of variable: } \tau = t, \sigma = s \\
 \iff [\mathbf{K}^*\mathbf{f}](t) &= \int_A \kappa^*(s, t)\mathbf{f}(s) \, ds \quad \text{by change of variable: } t = \sigma, s = \tau, \mathbf{f} = \mathbf{g}
 \end{aligned}$$

⇒

Corollary D.1. ⁹ Let \mathbf{K} be an Fredholm operator with kernel $\kappa(t, s)$ and adjoint \mathbf{K}^* .

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$$\mathbf{K} = \mathbf{K}^* \iff \underbrace{\kappa(t, s)}_{\text{kernel is conjugate symmetric}} = \underbrace{\kappa^*(s, t)}_{\text{kernel is conjugate symmetric}}$$

PROOF:

$$\begin{aligned}
 \mathbf{K} = \mathbf{K}^* &\iff \int_A \kappa(t, s)\mathbf{f}(s) \, ds = \int_A \kappa^*(s, t)\mathbf{f}(s) \, ds \quad \text{by Theorem D.3 page 177} \\
 &\iff \kappa(t, s) = \kappa^*(s, t)
 \end{aligned}$$

⇒

Theorem D.4 (Mercer's Theorem). ¹⁰ Let \mathbf{K} be an Fredholm operator with kernel $\kappa(t, s)$ and eigen-system $((\lambda_n, \phi_n(t)))_{n \in \mathbb{Z}}$.

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$$\left\{ \begin{array}{l} (A). \underbrace{\int_a^b \int_a^b \kappa(t, s)\mathbf{f}(t)\mathbf{f}^*(s) \, dt \geq 0}_{\text{positive}} \quad \text{and} \\ (B). \kappa(t, s) \text{ is CONTINUOUS on} \\ [a : b] \times [a : b] \end{array} \right\} \implies \left\{ \begin{array}{l} (1). \kappa(t, s) = \sum_n \lambda_n \phi_n(t) \phi_n^*(s) \quad \text{and} \\ (2). \kappa(t, s) \text{ CONVERGES ABSOLUTELY} \\ \text{and UNIFORMLY on} \\ [a : b] \times [a : b] \end{array} \right\}$$

⁹ Michel and Herget (1993), page 430

¹⁰ Gohberg et al. (2003), page 198, Courant and Hilbert (1930), pages 138–140, Mercer (1909), page 439

APPENDIX E

MATRIX CALCULUS

Optimization problems often require finding the value of some parameter which results in some measure reaching a minimum or maximum value. Often this optimal parameter value can be found by solving the single equation generated by the partial derivative of the measure with respect to the parameter. When there are several parameters, optimization often requires several simultaneous equations generated by the partial derivatives of the measure with respect to each parameter. The need for several partial derivatives and several simultaneous equations leads to a natural union of two branches of mathematics—partial differential equations and linear algebra. In general, we would like to not only be able to take the partial derivative of a scalar with respect to another scalar, but to be able to take the partial derivative of a vector with respect to another vector. This generalization is the problem addressed in this section. Other references are also available.¹

E.1 First derivative of a vector with respect to a vector

Definition E.1.

\mathbf{x} is a vector with the following properties:

$$1. \quad \mathbf{x} \triangleq \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \quad (\text{n element column vector})$$

$$2. \quad \frac{\partial}{\partial x_k} x_j = \delta_{kj} \quad ((x_1, x_2, \dots, x_n) \text{ are mutually independent})$$

Definition E.2 (Jacobian matrix). ² The gradient of \mathbf{y} with respect to \mathbf{x} , as well as the gradient of \mathbf{y}^T with respect to \mathbf{x} , is defined as

¹ [Graham \(1981\)](#) (Chapter 4), [Haykin \(2001\)](#) (Appendix B), [Moon and Stirling \(2000\)](#) (Appendix E), [Scharf \(1991\)](#), pages 274–276, [Trees \(2002\)](#) (Section A.7), [Felippa \(1999\)](#)

² [Graham \(1981\)](#), page 52, [Graham \(2018\)](#), page 529780486824178§“4.2 The Derivatives of Vectors”, [Scharf \(1991\)](#), page 274, [Trees \(2002\)](#), page 1398, [Anderson \(1984\)](#) page 13 (§“2.2.5 Transformation of Variables”), [Anderson \(1958\)](#), page 11 (§“2.2.5 Transformation of Variables”)

D E F $\frac{\partial \mathbf{y}}{\partial \mathbf{x}} \triangleq \frac{\partial \mathbf{y}^T}{\partial \mathbf{x}} \triangleq \underbrace{\begin{bmatrix} \frac{\partial y_1}{\partial x_1} & \frac{\partial y_2}{\partial x_1} & \dots & \frac{\partial y_m}{\partial x_1} \\ \frac{\partial y_1}{\partial x_2} & \frac{\partial y_2}{\partial x_2} & \dots & \frac{\partial y_m}{\partial x_2} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial y_1}{\partial x_n} & \frac{\partial y_2}{\partial x_n} & \dots & \frac{\partial y_m}{\partial x_n} \end{bmatrix}}_{n \times m \text{ matrix}}$ $\forall \mathbf{y} \in \mathbb{C}^m$

Remark E.1. Depending on whether \mathbf{x} and \mathbf{y} are scalars or vectors, $\frac{\partial \mathbf{y}}{\partial \mathbf{x}}$ takes on the following forms:³

	y scalar	y vector
x scalar	$\frac{\partial y}{\partial x}$	$\frac{\partial \mathbf{y}}{\partial x} = \begin{bmatrix} \frac{\partial y_1}{\partial x} & \frac{\partial y_2}{\partial x} & \dots & \frac{\partial y_m}{\partial x} \end{bmatrix}$
x vector	$\frac{\partial y}{\partial \mathbf{x}} = \begin{bmatrix} \frac{\partial y}{\partial x_1} \\ \frac{\partial y}{\partial x_2} \\ \vdots \\ \frac{\partial y}{\partial x_n} \end{bmatrix}$	$\frac{\partial \mathbf{y}}{\partial \mathbf{x}} \triangleq \begin{bmatrix} \frac{\partial y_1}{\partial x_1} & \frac{\partial y_2}{\partial x_1} & \dots & \frac{\partial y_m}{\partial x_1} \\ \frac{\partial y_1}{\partial x_2} & \frac{\partial y_2}{\partial x_2} & \dots & \frac{\partial y_m}{\partial x_2} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial y_1}{\partial x_n} & \frac{\partial y_2}{\partial x_n} & \dots & \frac{\partial y_m}{\partial x_n} \end{bmatrix}$

Lemma E.1. Let $\mathbf{x} \in \mathbb{R}^n$ be a vector. Then

L E M $\frac{\partial}{\partial x_k} x_i x_j = \bar{\delta}_{ik} x_j + \bar{\delta}_{jk} x_i = \begin{cases} 2x_k & \text{for } i = j = k \\ x_j & \text{for } i = k \text{ and } j \neq k \\ x_i & \text{for } i \neq k \text{ and } j = k \\ 0 & \text{otherwise} \end{cases}$

Lemma E.2.

L E M $(\mathbf{x}^H \mathbf{A} \mathbf{x}) = \sum_{i=1}^n \sum_{j=1}^n a_{ij} x_i^* x_j \quad \forall \begin{array}{l} \mathbf{A} \in (\mathbb{C}^n \times \mathbb{C}^n) \quad (n \times n \text{ array}) \\ \mathbf{x} \in \mathbb{C}^n \quad (n \text{ element column vector}) \end{array}$ and

PROOF:

$$\begin{aligned}
 \mathbf{x}^H \mathbf{A} \mathbf{x} &\triangleq [x_1 \ x_2 \ \dots \ x_n]^* \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \quad \text{by definitions of } \mathbf{A} \text{ and } \mathbf{x} \\
 &= [x_1 \ x_2 \ \dots \ x_n]^* \sum_{i=1}^n x_i \begin{bmatrix} a_{1i} \\ a_{2i} \\ \vdots \\ a_{ni} \end{bmatrix} \\
 &= \sum_{i=1}^n x_i [x_1 \ x_2 \ \dots \ x_n]^* \begin{bmatrix} a_{1i} \\ a_{2i} \\ \vdots \\ a_{ni} \end{bmatrix} \\
 &= \sum_{i=1}^n x_i \sum_{j=1}^n a_{ji} x_j^*
 \end{aligned}$$

³For the generalization of the partial derivative of a matrix with respect to a matrix, see [Graham \(1981\)](#) (chapter 6). Graham uses *kronecker products* to handle the additional dimensions(?)



$$= \sum_{i=1}^n \sum_{j=1}^n a_{ij} x_i^* x_j$$

**Lemma E.3.****L
E
M**

$$\frac{\partial}{\partial \mathbf{x}} [a(\mathbf{x}) b(\mathbf{x})] = a(\mathbf{x}) \left[\frac{\partial}{\partial \mathbf{x}} b(\mathbf{x}) \right] + \left[\frac{\partial}{\partial \mathbf{x}} a(\mathbf{x}) \right] b(\mathbf{x})$$

$\underbrace{\forall a, b : \mathbb{R}^n \rightarrow \mathbb{R}}$

$a(\mathbf{x}), b(\mathbf{x})$ are functions from a vector \mathbf{x} to a scalar in \mathbb{R}

PROOF:

$$\begin{aligned} \frac{\partial}{\partial \mathbf{x}} [a(\mathbf{x}) b(\mathbf{x})] &= \begin{bmatrix} \frac{\partial}{\partial x_1} [a(\mathbf{x}) b(\mathbf{x})] \\ \frac{\partial}{\partial x_2} [a(\mathbf{x}) b(\mathbf{x})] \\ \vdots \\ \frac{\partial}{\partial x_n} [a(\mathbf{x}) b(\mathbf{x})] \end{bmatrix} && \text{by definition of } \frac{\partial}{\partial \mathbf{x}} && (\text{Definition E.2 page 179}) \\ &= \begin{bmatrix} a(\mathbf{x}) \frac{\partial b(\mathbf{x})}{\partial x_1} + b(\mathbf{x}) \frac{\partial a(\mathbf{x})}{\partial x_1} \\ a(\mathbf{x}) \frac{\partial b(\mathbf{x})}{\partial x_2} + b(\mathbf{x}) \frac{\partial a(\mathbf{x})}{\partial x_2} \\ \vdots \\ a(\mathbf{x}) \frac{\partial b(\mathbf{x})}{\partial x_n} + b(\mathbf{x}) \frac{\partial a(\mathbf{x})}{\partial x_n} \end{bmatrix} && \text{by linearity of } \frac{\partial}{\partial \mathbf{x}} \\ &= \begin{bmatrix} a(\mathbf{x}) \frac{\partial b(\mathbf{x})}{\partial x_1} \\ a(\mathbf{x}) \frac{\partial b(\mathbf{x})}{\partial x_2} \\ \vdots \\ a(\mathbf{x}) \frac{\partial b(\mathbf{x})}{\partial x_n} \end{bmatrix} + \begin{bmatrix} \frac{\partial a(\mathbf{x})}{\partial x_1} b(\mathbf{x}) \\ \frac{\partial a(\mathbf{x})}{\partial x_2} b(\mathbf{x}) \\ \vdots \\ \frac{\partial a(\mathbf{x})}{\partial x_n} b(\mathbf{x}) \end{bmatrix} && \text{by linearity of vector addition} \\ &= a(\mathbf{x}) \left[\frac{\partial b(\mathbf{x})}{\partial \mathbf{x}} \right] + \left[\frac{\partial a(\mathbf{x})}{\partial \mathbf{x}} \right] b(\mathbf{x}) \end{aligned}$$

**Theorem E.1.** ⁴**L
E
M**

$$\frac{\partial}{\partial \mathbf{x}} \mathbf{x} = \mathbf{I} \quad \forall \mathbf{x} \in \mathbb{R}^n$$

PROOF:

$$\begin{aligned} \frac{\partial}{\partial \mathbf{x}} \mathbf{x} &= \begin{bmatrix} \frac{\partial x_1}{\partial x_1} & \frac{\partial x_2}{\partial x_1} & \dots & \frac{\partial x_n}{\partial x_1} \\ \frac{\partial x_1}{\partial x_2} & \frac{\partial x_1}{\partial x_2} & \dots & \frac{\partial x_1}{\partial x_2} \\ \frac{\partial x_1}{\partial x_2} & \frac{\partial x_2}{\partial x_2} & \dots & \frac{\partial x_2}{\partial x_2} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial x_1}{\partial x_n} & \frac{\partial x_2}{\partial x_n} & \dots & \frac{\partial x_n}{\partial x_n} \end{bmatrix} && \text{by Definition E.2 page 179} \\ &= \begin{bmatrix} \bar{\delta}_{11} & \bar{\delta}_{21} & \dots & \bar{\delta}_{n1} \\ \bar{\delta}_{12} & \bar{\delta}_{22} & \dots & \bar{\delta}_{n2} \\ \vdots & \vdots & \ddots & \vdots \\ \bar{\delta}_{1n} & \bar{\delta}_{2n} & \dots & \bar{\delta}_{nn} \end{bmatrix} && \text{by Definition E.1 page 179 (mutual independence property)} \end{aligned}$$

⁴ Scharf (1991), page 274, Trees (2002), page 1398

$$\begin{aligned}
 &= \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 \end{bmatrix} && \text{by definition of kronecker delta function } \delta \\
 &= \mathbf{I} && \text{by definition of identity operator } \mathbf{I}
 \end{aligned}$$

⇒

Theorem E.2.

T H M $\frac{\partial}{\partial \mathbf{x}}(\mathbf{A}\mathbf{x}) = \mathbf{A}^T + \sum_{i=1}^n \left(\frac{\partial}{\partial \mathbf{x}} \begin{bmatrix} a_{1i} & a_{2i} & \cdots & a_{mi} \end{bmatrix} \right) \mathbf{x}_i \quad \forall \mathbf{x} \in \mathbb{R}^n, \mathbf{A} \in \mathbb{C}^m \times \mathbb{C}^n$

PROOF: Let

$$\mathbf{x} \triangleq \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \quad \mathbf{A} \triangleq \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}$$

$$\begin{aligned}
 \frac{\partial}{\partial \mathbf{x}} (\mathbf{A}\mathbf{x}) &= \frac{\partial}{\partial \mathbf{x}} \left(\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \right) && \text{by definition of } A \text{ and } \mathbf{x} \\
 &= \frac{\partial}{\partial \mathbf{x}} \begin{bmatrix} \sum_{i=1}^n a_{1i}x_i \\ \sum_{i=1}^n a_{2i}x_i \\ \vdots \\ \sum_{i=1}^n a_{mi}x_i \end{bmatrix} && \text{by matrix multiplication} \\
 &= \frac{\partial}{\partial \mathbf{x}} \sum_{i=1}^n \begin{bmatrix} a_{1i}x_i \\ a_{2i}x_i \\ \vdots \\ a_{mi}x_i \end{bmatrix} \\
 &= \sum_{i=1}^n \frac{\partial}{\partial \mathbf{x}} \begin{bmatrix} a_{1i}x_i \\ a_{2i}x_i \\ \vdots \\ a_{mi}x_i \end{bmatrix} \\
 &= \sum_{i=1}^n \begin{bmatrix} \frac{\partial a_{1i}x_i}{\partial x_1} & \frac{\partial a_{2i}x_i}{\partial x_1} & \cdots & \frac{\partial a_{mi}x_i}{\partial x_1} \\ \frac{\partial a_{1i}x_i}{\partial x_2} & \frac{\partial a_{2i}x_i}{\partial x_2} & \cdots & \frac{\partial a_{mi}x_i}{\partial x_2} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial a_{1i}x_i}{\partial x_n} & \frac{\partial a_{2i}x_i}{\partial x_n} & \cdots & \frac{\partial a_{mi}x_i}{\partial x_n} \end{bmatrix} && \text{by Definition E.2 page 179} \\
 &= \sum_{i=1}^n \begin{bmatrix} a_{1i} \frac{\partial x_i}{\partial x_1} + \frac{\partial a_{1i}}{\partial x_1} x_i & a_{2i} \frac{\partial x_i}{\partial x_1} + \frac{\partial a_{2i}}{\partial x_1} x_i & \cdots & a_{mi} \frac{\partial x_i}{\partial x_1} + \frac{\partial a_{mi}}{\partial x_1} x_i \\ a_{1i} \frac{\partial x_i}{\partial x_2} + \frac{\partial a_{1i}}{\partial x_2} x_i & a_{2i} \frac{\partial x_i}{\partial x_2} + \frac{\partial a_{2i}}{\partial x_2} x_i & \cdots & a_{mi} \frac{\partial x_i}{\partial x_2} + \frac{\partial a_{mi}}{\partial x_2} x_i \\ \vdots & \vdots & \ddots & \vdots \\ a_{1i} \frac{\partial x_i}{\partial x_n} + \frac{\partial a_{1i}}{\partial x_n} x_i & a_{2i} \frac{\partial x_i}{\partial x_n} + \frac{\partial a_{2i}}{\partial x_n} x_i & \cdots & a_{mi} \frac{\partial x_i}{\partial x_n} + \frac{\partial a_{mi}}{\partial x_n} x_i \end{bmatrix} && \text{by Lemma E.3 page 181}
 \end{aligned}$$



$$= \sum_{i=1}^n \begin{bmatrix} a_{1i} \frac{\partial x_i}{\partial x_1} & a_{2i} \frac{\partial x_i}{\partial x_1} & \cdots & a_{mi} \frac{\partial x_i}{\partial x_1} \\ a_{1i} \frac{\partial x_i}{\partial x_2} & a_{2i} \frac{\partial x_i}{\partial x_2} & \cdots & a_{mi} \frac{\partial x_i}{\partial x_2} \\ \vdots & \vdots & \ddots & \vdots \\ a_{1i} \frac{\partial x_i}{\partial x_n} & a_{2i} \frac{\partial x_i}{\partial x_n} & \cdots & a_{mi} \frac{\partial x_i}{\partial x_n} \end{bmatrix} + \sum_{i=1}^n \begin{bmatrix} \frac{\partial a_{1i}}{\partial x_1} x_i & \frac{\partial a_{2i}}{\partial x_1} x_i & \cdots & \frac{\partial a_{mi}}{\partial x_1} x_i \\ \frac{\partial a_{1i}}{\partial x_2} x_i & \frac{\partial a_{2i}}{\partial x_2} x_i & \cdots & \frac{\partial a_{mi}}{\partial x_2} x_i \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial a_{1i}}{\partial x_n} x_i & \frac{\partial a_{2i}}{\partial x_n} x_i & \cdots & \frac{\partial a_{mi}}{\partial x_n} x_i \end{bmatrix}$$

$$= \sum_{i=1}^n \begin{bmatrix} a_{1i} \bar{\delta}_{i1} & a_{2i} \bar{\delta}_{i1} & \cdots & a_{mi} \bar{\delta}_{i1} \\ a_{1i} \bar{\delta}_{i2} & a_{2i} \bar{\delta}_{i2} & \cdots & a_{mi} \bar{\delta}_{i2} \\ \vdots & \vdots & \ddots & \vdots \\ a_{1i} \bar{\delta}_{in} & a_{2i} \bar{\delta}_{in} & \cdots & a_{mi} \bar{\delta}_{in} \end{bmatrix} + \sum_{i=1}^n \left(\frac{\partial}{\partial \mathbf{x}} [a_{1i} \ a_{2i} \ \cdots \ a_{mi}] \right) x_i \quad \text{by Lemma E.1}$$

$$= \begin{bmatrix} a_{11} & a_{21} & \cdots & a_{m1} \\ a_{12} & a_{22} & \cdots & a_{m2} \\ \vdots & \vdots & \ddots & \vdots \\ a_{1n} & a_{2n} & \cdots & a_{mn} \end{bmatrix} + \sum_{i=1}^n \left(\frac{\partial}{\partial \mathbf{x}} [a_{1i} \ a_{2i} \ \cdots \ a_{mi}] \right) x_i \quad \text{by definition of } \bar{\delta}$$

$$= \mathbf{A}^T + \sum_{i=1}^n \left(\frac{\partial}{\partial \mathbf{x}} [a_{1i} \ a_{2i} \ \cdots \ a_{mi}] \right) x_i$$

⇒

Theorem E.3 (Affine equations).⁵**T
H
M**

$$\mathbf{A} \text{ and } \mathbf{B} \text{ are independent of } \mathbf{x} \implies \begin{cases} \frac{\partial}{\partial \mathbf{x}} (\mathbf{A}\mathbf{x}) = \mathbf{A}^T & \forall \mathbf{x} \in \mathbb{R}^n, \mathbf{A} \in \mathbb{C}^m \times \mathbb{C}^n \\ \frac{\partial}{\partial \mathbf{x}} (\mathbf{x}^T \mathbf{B}) = \mathbf{B} & \forall \mathbf{x} \in \mathbb{R}^n, \mathbf{B} \in \mathbb{C}^n \times \mathbb{C}^m \end{cases}$$

PROOF: Let $\mathbf{B} \triangleq \mathbf{A}^T$.1. Proof that $\frac{\partial}{\partial \mathbf{x}} (\mathbf{A}\mathbf{x}) = \mathbf{A}^T$:

$$\begin{aligned} \frac{\partial}{\partial \mathbf{x}} (\mathbf{A}\mathbf{x}) &= \mathbf{A}^T + \sum_{i=1}^n \left(\frac{\partial}{\partial \mathbf{x}} [a_{1i} \ a_{2i} \ \cdots \ a_{mi}] \right) x_i && \text{by Theorem E.2 page 182} \\ &= \mathbf{A}^T + \sum_{i=1}^n \left[\frac{\partial}{\partial \mathbf{x}} a_{1i} \ \frac{\partial}{\partial \mathbf{x}} a_{2i} \ \cdots \ \frac{\partial}{\partial \mathbf{x}} a_{mi} \right] x_i \\ &= \mathbf{A}^T + \sum_{i=1}^n \left[\underset{\text{red}}{0} \underset{\text{red}}{0} \cdots \underset{\text{red}}{0} \overset{0}{\rightarrow} \right] x_i && \text{by left hypothesis} \\ &= \mathbf{A}^T \end{aligned}$$

2. Proof that $\frac{\partial}{\partial \mathbf{x}} (\mathbf{x}^T \mathbf{B}) = \mathbf{B}$:

$$\begin{aligned} \frac{\partial}{\partial \mathbf{x}} (\mathbf{x}^T \mathbf{B}) &= \frac{\partial}{\partial \mathbf{x}} (\mathbf{x}^T \mathbf{A}^T) && \text{by definition of } \mathbf{B} \\ &= \frac{\partial}{\partial \mathbf{x}} [(\mathbf{A}\mathbf{x})^T] && \\ &= \frac{\partial}{\partial \mathbf{x}} (\mathbf{A}\mathbf{x}) && \text{by Definition E.2 page 179} \\ &= \mathbf{A}^T && \text{by Theorem E.3 page 183} \\ &= \mathbf{B} && \text{by definition of } \mathbf{B} \end{aligned}$$

⇒

⁵ Graham (1981), page 54, Graham (2018), page 549780486824178§“4.2 The Derivatives of Vectors”

Theorem E.4 (Product rule). ⁶ Let \mathbf{y} and \mathbf{z} be functions of \mathbf{x} and

T H M	$\frac{\partial}{\partial \mathbf{x}} \mathbf{z}^T \mathbf{y} = \frac{\partial \mathbf{z}}{\partial \mathbf{x}} \mathbf{y} + \frac{\partial \mathbf{y}}{\partial \mathbf{x}} \mathbf{z}$	$\forall \mathbf{x} \in \mathbb{R}^n, \mathbf{y} \in \mathbb{R}^m, \mathbf{z} \in \mathbb{R}^m$
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PROOF:

$$\begin{aligned}
 \frac{\partial}{\partial \mathbf{x}} \mathbf{z}^T \mathbf{y} &= \frac{\partial}{\partial \mathbf{x}} \sum_{k=1}^m z_k y_k \\
 &= \sum_{k=1}^m \frac{\partial}{\partial \mathbf{x}} z_k y_k \\
 &= \sum_{k=1}^m \frac{\partial z_k}{\partial \mathbf{x}} y_k + \sum_{k=1}^m \frac{\partial y_k}{\partial \mathbf{x}} z_k \quad \text{by Lemma E.3 page 181} \\
 &= \left[\begin{array}{cccc} \frac{\partial z_1}{\partial x_1} y_1 & + & \frac{\partial z_2}{\partial x_1} y_2 & + \cdots + \frac{\partial z_n}{\partial x_1} y_n \\ \frac{\partial z_1}{\partial x_1} y_1 & + & \frac{\partial z_2}{\partial x_1} y_2 & + \cdots + \frac{\partial z_n}{\partial x_1} y_n \\ \vdots & & \ddots & \vdots \\ \frac{\partial z_1}{\partial x_1} y_1 & + & \frac{\partial z_2}{\partial x_1} y_2 & + \cdots + \frac{\partial z_n}{\partial x_1} y_n \end{array} \right] + \left[\begin{array}{cccc} \frac{\partial y_1}{\partial x_1} z_1 & + & \frac{\partial y_2}{\partial x_1} z_2 & + \cdots + \frac{\partial y_n}{\partial x_1} z_n \\ \frac{\partial y_1}{\partial x_1} z_1 & + & \frac{\partial y_2}{\partial x_1} z_2 & + \cdots + \frac{\partial y_n}{\partial x_1} z_n \\ \vdots & & \ddots & \vdots \\ \frac{\partial y_1}{\partial x_1} z_1 & + & \frac{\partial y_2}{\partial x_1} z_2 & + \cdots + \frac{\partial y_n}{\partial x_1} z_n \end{array} \right] \\
 &= \left[\begin{array}{ccc} \frac{\partial z_1}{\partial x_1} & \frac{\partial z_2}{\partial x_1} & \cdots & \frac{\partial z_n}{\partial x_1} \\ \frac{\partial z_1}{\partial x_1} & \frac{\partial z_2}{\partial x_1} & \cdots & \frac{\partial z_n}{\partial x_1} \\ \vdots & \ddots & \vdots & \vdots \\ \frac{\partial z_1}{\partial x_1} & \frac{\partial z_2}{\partial x_1} & \cdots & \frac{\partial z_n}{\partial x_1} \end{array} \right] \left[\begin{array}{c} y_1 \\ y_2 \\ \vdots \\ y_n \end{array} \right] + \left[\begin{array}{ccc} \frac{\partial y_1}{\partial x_1} & \frac{\partial y_2}{\partial x_1} & \cdots & \frac{\partial y_n}{\partial x_1} \\ \frac{\partial y_1}{\partial x_1} & \frac{\partial y_2}{\partial x_1} & \cdots & \frac{\partial y_n}{\partial x_1} \\ \vdots & \ddots & \vdots & \vdots \\ \frac{\partial y_1}{\partial x_1} & \frac{\partial y_2}{\partial x_1} & \cdots & \frac{\partial y_n}{\partial x_1} \end{array} \right] \left[\begin{array}{c} z_1 \\ z_2 \\ \vdots \\ z_n \end{array} \right] \\
 &= \frac{\partial \mathbf{z}}{\partial \mathbf{x}} \mathbf{y} + \frac{\partial \mathbf{y}}{\partial \mathbf{x}} \mathbf{z}
 \end{aligned}$$

⇒

Theorem E.5.

T H M	$\frac{\partial}{\partial \mathbf{x}} (\mathbf{x}^T \mathbf{A} \mathbf{x}) = \mathbf{A} \mathbf{x} + \mathbf{A}^T \mathbf{x} + \left[\sum_{i=1}^n \left(\frac{\partial}{\partial \mathbf{x}} [a_{1i} \ a_{2i} \ \cdots \ a_{ni}] \right) x_i \right] \mathbf{x}$	$\forall \mathbf{x} \in \mathbb{R}^n, \mathbf{A} \in \mathbb{R}^n \times \mathbb{R}^n$
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PROOF:

$$\begin{aligned}
 \frac{\partial}{\partial \mathbf{x}} (\mathbf{x}^T \mathbf{A} \mathbf{x}) &= \left[\frac{\partial}{\partial \mathbf{x}} \mathbf{x} \right] \mathbf{A} \mathbf{x} + \left[\frac{\partial}{\partial \mathbf{x}} \mathbf{A} \mathbf{x} \right] \mathbf{x} && \text{by Theorem E.4 page 184} \\
 &= \mathbf{I} \mathbf{A} \mathbf{x} + \left[\mathbf{A}^T + \sum_{i=1}^n \left(\frac{\partial}{\partial \mathbf{x}} [a_{1i} \ a_{2i} \ \cdots \ a_{ni}] \right) x_i \right] \mathbf{x} && \text{by Theorem E.1 and Theorem E.2} \\
 &= \mathbf{A} \mathbf{x} + \mathbf{A}^T \mathbf{x} + \left[\sum_{i=1}^n \left(\frac{\partial}{\partial \mathbf{x}} [a_{1i} \ a_{2i} \ \cdots \ a_{ni}] \right) x_i \right] \mathbf{x} && \text{by definition of identity operator } \mathbf{I}
 \end{aligned}$$

⇒

Theorem E.6 (Quadratic form). ⁷

T H M	\mathbf{A} is independent of \mathbf{x} $\implies \frac{\partial}{\partial \mathbf{x}} (\mathbf{x}^T \mathbf{A} \mathbf{x}) = \mathbf{A} \mathbf{x} + \mathbf{A}^T \mathbf{x}$	$\forall \mathbf{x} \in \mathbb{R}^n, \mathbf{A} \in \mathbb{R}^n \times \mathbb{R}^n$
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⁶ Scharf (1991), page 274, Trees (2002), page 1398

⁷ Graham (1981), page 54



PROOF:

$$\begin{aligned}\frac{\partial}{\partial \mathbf{x}}(\mathbf{x}^T \mathbf{A} \mathbf{x}) &= \left[\frac{\partial}{\partial \mathbf{x}} \mathbf{x} \right] \mathbf{A} \mathbf{x} + \left[\frac{\partial}{\partial \mathbf{x}} \mathbf{A} \mathbf{x} \right] \mathbf{x} && \text{by Theorem E.4 page 184} \\ &= \mathbf{I} \mathbf{A} \mathbf{x} + \mathbf{A}^T \mathbf{x} && \text{by Theorem E.1 page 181 and Theorem E.3 page 183}\end{aligned}$$

Corollary E.1.⁸

COR	$\frac{\partial}{\partial \mathbf{x}}(\mathbf{x}^T \mathbf{x}) = 2\mathbf{x} \quad \forall \mathbf{x} \in \mathbb{R}^n$
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PROOF:

$$\begin{aligned}\frac{\partial}{\partial \mathbf{x}}(\mathbf{x}^T \mathbf{x}) &= \frac{\partial}{\partial \mathbf{x}}(\mathbf{x}^T \mathbf{I} \mathbf{x}) && \text{by property of identity operator } \mathbf{I} \\ &= \mathbf{I} \mathbf{x} + \mathbf{I}^T \mathbf{x} && \text{by previous result 3.} \\ &= \mathbf{x} + \mathbf{x} && \text{by property of identity operator } \mathbf{I} \\ &= 2\mathbf{x}\end{aligned}$$

Theorem E.7 (Chain rule).⁹ Let \mathbf{z} be a function of \mathbf{y} and \mathbf{y} a function of \mathbf{x} and

$$\mathbf{x} \triangleq \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \quad \mathbf{y} \triangleq \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix} \quad \mathbf{z} \triangleq \begin{bmatrix} z_1 \\ z_2 \\ \vdots \\ z_k \end{bmatrix}$$

THM	$\frac{\partial}{\partial \mathbf{x}} \mathbf{z} = \frac{\partial \mathbf{y}}{\partial \mathbf{x}} \frac{\partial \mathbf{z}}{\partial \mathbf{y}}$
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PROOF:

$$\begin{aligned}\frac{\partial \mathbf{z}}{\partial \mathbf{x}} &= \begin{bmatrix} \frac{\partial z_1}{\partial x_1} & \frac{\partial z_2}{\partial x_1} & \cdots & \frac{\partial z_k}{\partial x_1} \\ \frac{\partial z_1}{\partial x_2} & \frac{\partial z_2}{\partial x_2} & \cdots & \frac{\partial z_k}{\partial x_2} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial z_1}{\partial x_n} & \frac{\partial z_2}{\partial x_n} & \cdots & \frac{\partial z_k}{\partial x_n} \end{bmatrix} \\ &= \begin{bmatrix} \sum_{j=0}^m \frac{\partial z_1}{\partial y_j} \frac{\partial y_j}{\partial x_1} & \sum_{j=0}^m \frac{\partial z_2}{\partial y_j} \frac{\partial y_j}{\partial x_1} & \cdots & \sum_{j=0}^m \frac{\partial z_k}{\partial y_j} \frac{\partial y_j}{\partial x_1} \\ \sum_{j=0}^m \frac{\partial z_1}{\partial y_j} \frac{\partial y_j}{\partial x_2} & \sum_{j=0}^m \frac{\partial z_2}{\partial y_j} \frac{\partial y_j}{\partial x_2} & \cdots & \sum_{j=0}^m \frac{\partial z_k}{\partial y_j} \frac{\partial y_j}{\partial x_2} \\ \vdots & \vdots & \ddots & \vdots \\ \sum_{j=0}^m \frac{\partial z_1}{\partial y_j} \frac{\partial y_j}{\partial x_n} & \sum_{j=0}^m \frac{\partial z_2}{\partial y_j} \frac{\partial y_j}{\partial x_n} & \cdots & \sum_{j=0}^m \frac{\partial z_k}{\partial y_j} \frac{\partial y_j}{\partial x_n} \end{bmatrix} \\ &= \begin{bmatrix} \frac{\partial y_1}{\partial x_1} & \frac{\partial y_2}{\partial x_1} & \cdots & \frac{\partial y_m}{\partial x_1} \\ \frac{\partial y_1}{\partial x_2} & \frac{\partial y_2}{\partial x_2} & \cdots & \frac{\partial y_m}{\partial x_2} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial y_1}{\partial x_n} & \frac{\partial y_2}{\partial x_n} & \cdots & \frac{\partial y_m}{\partial x_n} \end{bmatrix} \begin{bmatrix} \frac{\partial z_1}{\partial y_1} & \frac{\partial z_2}{\partial y_1} & \cdots & \frac{\partial z_k}{\partial y_1} \\ \frac{\partial z_1}{\partial y_2} & \frac{\partial z_2}{\partial y_2} & \cdots & \frac{\partial z_k}{\partial y_2} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial z_1}{\partial y_m} & \frac{\partial z_2}{\partial y_m} & \cdots & \frac{\partial z_k}{\partial y_m} \end{bmatrix} \\ &= \frac{\partial \mathbf{y}}{\partial \mathbf{x}} \frac{\partial \mathbf{z}}{\partial \mathbf{y}}\end{aligned}$$

⁸ Graham (1981), page 54⁹ Graham (1981), pages 54–55



E.2 First derivative of a matrix with respect to a scalar

Definition E.3. Let $x \in \mathbb{R}$, $\{y_{jk} \in \mathbb{C} | j = 1, 2, \dots, m; k = 1, 2, \dots, n\}$ and

$$Y = \underbrace{\begin{bmatrix} y_{11} & y_{12} & \cdots & y_{1n} \\ y_{21} & y_{22} & \cdots & y_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ y_{m1} & y_{m2} & \cdots & y_{mn} \end{bmatrix}}_{m \times n \text{ matrix}}$$

The derivative of Y with respect to x is

D E F

$$\frac{dY}{dx} \triangleq \underbrace{\begin{bmatrix} \frac{dy_{11}}{dx} & \frac{dy_{12}}{dx} & \cdots & \frac{dy_{1n}}{dx} \\ \frac{dy_{21}}{dx} & \frac{dy_{22}}{dx} & \cdots & \frac{dy_{2n}}{dx} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{dy_{m1}}{dx} & \frac{dy_{m2}}{dx} & \cdots & \frac{dy_{mn}}{dx} \end{bmatrix}}_{m \times n \text{ matrix}}$$

Theorem E.8.¹⁰ Let $x \in \mathbb{R}$, $\{y_{jp} \in \mathbb{C} | j = 1, 2, \dots, m; p = 1, 2, \dots, n\}$, $\{w_{jp} \in \mathbb{C} | j = 1, 2, \dots, n; p = 1, 2, \dots, k\}$, and

$$Y = \underbrace{\begin{bmatrix} y_{11} & y_{12} & \cdots & y_{1n} \\ y_{21} & y_{22} & \cdots & y_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ y_{m1} & y_{m2} & \cdots & y_{mn} \end{bmatrix}}_{m \times n \text{ matrix}} \quad W = \underbrace{\begin{bmatrix} w_{11} & w_{12} & \cdots & w_{1k} \\ w_{21} & w_{22} & \cdots & w_{2k} \\ \vdots & \vdots & \ddots & \vdots \\ w_{p1} & w_{p2} & \cdots & w_{pk} \end{bmatrix}}_{p \times k \text{ matrix}}$$

T H M

$\frac{d}{dx}(Y + W) = \frac{d}{dx}Y + \frac{d}{dx}W$	(for $p = m, k = n$)
$\frac{d}{dx}(YW) = \left(\frac{d}{dx}Y\right)W + Y\left(\frac{d}{dx}W\right)$	(for $p = n$)
$\frac{d}{dx}(Y^T) = \left(\frac{d}{dx}Y\right)^T$	
$\frac{d}{dx}(Y^{-1}) = -Y^{-1}\left(\frac{d}{dx}Y\right)Y^{-1}$	(for $m = n$ and Y invertible)

PROOF:

$$\begin{aligned} \frac{d}{dx}(Y + W) &= \frac{d}{dx} \left(\begin{bmatrix} y_{11} & y_{12} & \cdots & y_{1n} \\ y_{21} & y_{22} & \cdots & y_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ y_{m1} & y_{m2} & \cdots & y_{mn} \end{bmatrix} + \begin{bmatrix} w_{11} & w_{12} & \cdots & w_{1n} \\ w_{21} & w_{22} & \cdots & w_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ w_{m1} & w_{m2} & \cdots & w_{mn} \end{bmatrix} \right) \\ &= \frac{d}{dx} \begin{bmatrix} y_{11} + w_{11} & y_{12} + w_{12} & \cdots & y_{1n} + w_{1n} \\ y_{21} + w_{21} & y_{22} + w_{22} & \cdots & y_{2n} + w_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ y_{m1} + w_{m1} & y_{m2} + w_{m2} & \cdots & y_{mn} + w_{mn} \end{bmatrix} \end{aligned}$$

¹⁰ Gradshteyn and Ryzhik (1980), pages 1106–1107

$$\begin{aligned}
&= \begin{bmatrix} (y_{11} + w_{11})' & (y_{12} + w_{12})' & \cdots & (y_{1n} + w_{1n})' \\ (y_{21} + w_{21})' & (y_{22} + w_{22})' & \cdots & (y_{2n} + w_{2n})' \\ \vdots & \vdots & \ddots & \vdots \\ (y_{m1} + w_{m1})' & (y_{m2} + w_{m2})' & \cdots & (y_{mn} + w_{mn})' \end{bmatrix} \\
&= \begin{bmatrix} y'_{11} + w'_{11} & y'_{12} + w'_{12} & \cdots & y'_{1n} + w'_{1n} \\ y'_{21} + w'_{21} & y'_{22} + w'_{22} & \cdots & y'_{2n} + w'_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ y'_{m1} + w'_{m1} & y'_{m2} + w'_{m2} & \cdots & y'_{mn} + w'_{mn} \end{bmatrix} \\
&= \begin{bmatrix} y'_{11} & y'_{12} & \cdots & y'_{1n} \\ y'_{21} & y'_{22} & \cdots & y'_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ y'_{m1} & y'_{m2} & \cdots & y'_{mn} \end{bmatrix} + \begin{bmatrix} w'_{11} & w'_{12} & \cdots & w'_{1n} \\ w'_{21} & w'_{22} & \cdots & w'_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ w'_{m1} & w'_{m2} & \cdots & w'_{mn} \end{bmatrix} \\
&= \frac{d}{dx} \begin{bmatrix} y_{11} & y_{12} & \cdots & y_{1n} \\ y_{21} & y_{22} & \cdots & y_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ y_{m1} & y_{m2} & \cdots & y_{mn} \end{bmatrix} + \frac{d}{dx} \begin{bmatrix} w_{11} & w_{12} & \cdots & w_{1n} \\ w_{21} & w_{22} & \cdots & w_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ w_{m1} & w_{m2} & \cdots & w_{mn} \end{bmatrix} \\
&= \frac{d}{dx} Y + \frac{d}{dx} W
\end{aligned}$$

$$\begin{aligned}
\frac{d}{dx}(YW) &= \frac{d}{dx} \left(\begin{bmatrix} y_{11} & y_{12} & \cdots & y_{1n} \\ y_{21} & y_{22} & \cdots & y_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ y_{m1} & y_{m2} & \cdots & y_{mn} \end{bmatrix} \begin{bmatrix} w_{11} & w_{12} & \cdots & w_{1k} \\ w_{21} & w_{22} & \cdots & w_{2k} \\ \vdots & \vdots & \ddots & \vdots \\ w_{n1} & w_{n2} & \cdots & w_{nk} \end{bmatrix} \right) \\
&= \frac{d}{dx} \begin{bmatrix} \sum_{j=1}^n y_{1j} w_{j1} & \sum_{j=1}^n y_{1j} w_{j2} & \cdots & \sum_{j=1}^n y_{1j} w_{jk} \\ \sum_{j=1}^n y_{2j} w_{j1} & \sum_{j=1}^n y_{2j} w_{j2} & \cdots & \sum_{j=1}^n y_{2j} w_{jk} \\ \vdots & \vdots & \ddots & \vdots \\ \sum_{j=1}^n y_{mj} w_{j1} & \sum_{j=1}^n y_{mj} w_{j2} & \cdots & \sum_{j=1}^n y_{mj} w_{jk} \end{bmatrix} \\
&= \frac{d}{dx} \sum_{j=1}^n \begin{bmatrix} y_{1j} w_{j1} & y_{1j} w_{j2} & \cdots & y_{1j} w_{jk} \\ y_{2j} w_{j1} & y_{2j} w_{j2} & \cdots & y_{2j} w_{jk} \\ \vdots & \vdots & \ddots & \vdots \\ y_{mj} w_{j1} & y_{mj} w_{j2} & \cdots & y_{mj} w_{jk} \end{bmatrix} \\
&= \sum_{j=1}^n \frac{d}{dx} \begin{bmatrix} y_{1j} w_{j1} & y_{1j} w_{j2} & \cdots & y_{1j} w_{jk} \\ y_{2j} w_{j1} & y_{2j} w_{j2} & \cdots & y_{2j} w_{jk} \\ \vdots & \vdots & \ddots & \vdots \\ y_{mj} w_{j1} & y_{mj} w_{j2} & \cdots & y_{mj} w_{jk} \end{bmatrix} \\
&= \sum_{j=1}^n \begin{bmatrix} \frac{d}{dx}(y_{1j} w_{j1}) & \frac{d}{dx}(y_{1j} w_{j2}) & \cdots & \frac{d}{dx}(y_{1j} w_{jk}) \\ \frac{d}{dx}(y_{2j} w_{j1}) & \frac{d}{dx}(y_{2j} w_{j2}) & \cdots & \frac{d}{dx}(y_{2j} w_{jk}) \\ \vdots & \vdots & \ddots & \vdots \\ \frac{d}{dx}(y_{mj} w_{j1}) & \frac{d}{dx}(y_{mj} w_{j2}) & \cdots & \frac{d}{dx}(y_{mj} w_{jk}) \end{bmatrix} \\
&= \sum_{j=1}^n \begin{bmatrix} \vdots & \vdots & \ddots & \vdots \\ y'_{1j} w_{j1} + y_{1j} w'_{j1} & y'_{1j} w_{j2} + y_{1j} w'_{j2} & \cdots & y'_{1j} w_{jk} + y_{1j} w'_{jk} \\ y'_{2j} w_{j1} + y_{2j} w'_{j1} & y'_{2j} w_{j2} + y_{2j} w'_{j2} & \cdots & y'_{2j} w_{jk} + y_{2j} w'_{jk} \\ y'_{mj} w_{j1} + y_{mj} w'_{j1} & y'_{mj} w_{j2} + y_{mj} w'_{j2} & \cdots & y'_{mj} w_{jk} + y_{mj} w'_{jk} \end{bmatrix}
\end{aligned}$$

$$\begin{aligned}
&= \sum_{j=1}^n \left(\begin{bmatrix} y'_{1j} w_{j1} & y'_{1j} w_{j2} & \cdots & y'_{1j} w_{jk} \\ y'_{2j} w_{j1} & y'_{2j} w_{j2} & \cdots & y'_{2j} w_{jk} \\ \vdots & \vdots & \ddots & \vdots \\ y'_{mj} w_{j1} & y'_{mj} w_{j2} & \cdots & y'_{mj} w_{jk} \end{bmatrix} + \begin{bmatrix} y_{1j} w'_{j1} & y_{1j} w'_{j2} & \cdots & y_{1j} w'_{jk} \\ y_{2j} w'_{j1} & y_{2j} w'_{j2} & \cdots & y_{2j} w'_{jk} \\ \vdots & \vdots & \ddots & \vdots \\ y_{mj} w'_{j1} & y_{mj} w'_{j2} & \cdots & y_{mj} w'_{jk} \end{bmatrix} \right) \\
&= \left(\frac{d}{dx} Y \right) W + Y \left(\frac{d}{dx} W \right)
\end{aligned}$$

$$\begin{aligned}
\frac{d}{dx} (Y^T) &= \frac{d}{dx} \left(\begin{bmatrix} y_{11} & y_{12} & \cdots & y_{1n} \\ y_{21} & y_{22} & \cdots & y_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ y_{m1} & y_{m2} & \cdots & y_{mn} \end{bmatrix}^T \right) \\
&= \frac{d}{dx} \begin{bmatrix} y_{11} & y_{21} & \cdots & y_{n1} \\ y_{12} & y_{22} & \cdots & y_{n2} \\ \vdots & \vdots & \ddots & \vdots \\ y_{1n} & y_{2n} & \cdots & y_{nn} \end{bmatrix} \\
&= \begin{bmatrix} y'_{11} & y'_{21} & \cdots & y'_{n1} \\ y'_{12} & y'_{22} & \cdots & y'_{n2} \\ \vdots & \vdots & \ddots & \vdots \\ y'_{1n} & y'_{2n} & \cdots & y'_{nn} \end{bmatrix} \\
&= \begin{bmatrix} y'_{11} & y'_{12} & \cdots & y'_{1n} \\ y'_{21} & y'_{22} & \cdots & y'_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ y'_{m1} & y'_{m2} & \cdots & y'_{mn} \end{bmatrix}^T \\
&= \left(\frac{d}{dx} \begin{bmatrix} y_{11} & y_{12} & \cdots & y_{1n} \\ y_{21} & y_{22} & \cdots & y_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ y_{m1} & y_{m2} & \cdots & y_{mn} \end{bmatrix} \right)^T
\end{aligned}$$

$$\begin{aligned}
\frac{d}{dx} (Y^{-1}) &= \frac{d}{dx} \frac{\text{adj} Y}{|Y|} \\
&\vdots \\
&\text{no proof at this time} \\
&\vdots \\
&= -Y^{-1} \left(\frac{d}{dx} Y \right) Y^{-1}
\end{aligned}$$

⇒

E.3 Second derivative of a scalar with respect to a vector

Definition E.4. ¹¹ Let

$$\mathbf{x} \triangleq \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

¹¹ Lieb and Loss (2001), page 240, Horn and Johnson (1990), page 167



The **Hessian matrix** of a scalar y with respect to the vector \mathbf{x} is

DEF

$$\frac{\partial^2 y}{\partial \mathbf{x}^2} = \frac{\partial}{\partial \mathbf{x}} \left(\frac{\partial y}{\partial \mathbf{x}} \right) = \frac{\partial}{\partial \mathbf{x}} \begin{bmatrix} \frac{\partial y}{\partial x_1} \\ \frac{\partial y}{\partial x_2} \\ \vdots \\ \frac{\partial y}{\partial x_n} \end{bmatrix} = \underbrace{\begin{bmatrix} \frac{\partial}{\partial x_1} \frac{\partial y}{\partial x_1} & \frac{\partial}{\partial x_1} \frac{\partial y}{\partial x_2} & \cdots & \frac{\partial}{\partial x_1} \frac{\partial y}{\partial x_n} \\ \frac{\partial}{\partial x_2} \frac{\partial y}{\partial x_1} & \frac{\partial}{\partial x_2} \frac{\partial y}{\partial x_2} & \cdots & \frac{\partial}{\partial x_2} \frac{\partial y}{\partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial}{\partial x_n} \frac{\partial y}{\partial x_1} & \frac{\partial}{\partial x_n} \frac{\partial y}{\partial x_2} & \cdots & \frac{\partial}{\partial x_n} \frac{\partial y}{\partial x_n} \end{bmatrix}}_{n \times n \text{ matrix}}$$

E.4 Multiple derivatives of a vector with respect to a scalar

Definition E.5. Let

$$\mathbf{y} \triangleq \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix}$$

The derivative of a vector \mathbf{y} with respect to the scalar x is

DEF

$$\begin{bmatrix} \mathbf{y} \\ \frac{d}{dx} \mathbf{y} \\ \frac{d^2}{dx^2} \mathbf{y} \\ \vdots \\ \frac{d^n}{dx^n} \mathbf{y} \end{bmatrix} = \underbrace{\begin{bmatrix} y_1 & y_2 & \cdots & y_m \\ \frac{d}{dx} y_1 & \frac{d}{dx} y_2 & \cdots & \frac{d}{dx} y_m \\ \frac{d^2}{dx^2} y_1 & \frac{d^2}{dx^2} y_2 & \cdots & \frac{d^2}{dx^2} y_m \\ \vdots & \vdots & \ddots & \vdots \\ \frac{d^n}{dx^n} y_1 & \frac{d^n}{dx^n} y_2 & \cdots & \frac{d^n}{dx^n} y_m \end{bmatrix}}_{(n+1) \times m \text{ matrix}}$$



APPENDIX F

ALGEBRAIC STRUCTURES



“In this book, learned reader, you have the rules of algebra... It unties the knot not only where one term is equal to another or two to one but also where two are equal to two or three to one.... this most abstruse and unsurpassed treasury of the entire arithmetic being brought to light and, as in a theater, exposed to the sight of all...”

Gerolamo Cardano (1501–1576), Italian mathematician, physician, and astrologer¹

A set together with one or more operations forms several standard mathematical structures:

group \supseteq ring \supseteq commutative ring \supseteq integral domain \supseteq field

Definition E.1. ² Let X be a set and $\diamond : X \times X \rightarrow X$ be an operation on X .

The pair (X, \diamond) is a **group** if

- | | |
|-----|---|
| DEF | 1. $\exists e \in X$ such that $e \diamond x = x \diamond e = x \quad \forall x \in X$ (IDENTITY element) and |
| | 2. $\exists (-x) \in X$ such that $(-x) \diamond x = x \diamond (-x) = e \quad \forall x \in X$ (INVERSE element) and |
| | 3. $x \diamond (y \diamond z) = (x \diamond y) \diamond z \quad \forall x, y, z \in X$ (ASSOCIATIVE) |

Definition E.2. ³ Let $+ : X \times X \rightarrow X$ and $* : X \times X \rightarrow X$ be operations on a set X . Furthermore, let the operation $*$ also be represented by juxtaposition as in $a * b \equiv ab$.

The triple $(X, +, *)$ is a **ring** if

- | | |
|-----|---|
| DEF | 1. $(X, +)$ is a group. (additive group) and |
| | 2. $x(yz) = (xy)z \quad \forall x, y, z \in X$ (ASSOCIATIVE with respect to $*$) and |
| | 3. $x(y + z) = (xy) + (xz) \quad \forall x, y, z \in X$ ($*$ is LEFT DISTRIBUTIVE over $+$) and |
| | 4. $(x + y)z = (xz) + (yz) \quad \forall x, y, z \in X$ ($*$ is RIGHT DISTRIBUTIVE over $+$). and |

Definition E.3. ⁴

¹ quote: Cardano (1545), page 1

image: <http://en.wikipedia.org/wiki/Image:Cardano.jpg>

² Durbin (2000), page 29

³ Durbin (2000), pages 114–115

⁴ Durbin (2000), page 118

D E F A triple $(X, +, *)$ is a **commutative ring** if

1. $(X, +, *)$ is a RING and
2. $xy = yx \quad \forall x, y \in X$ (COMMUTATIVE).

Definition F.4. ⁵ Let R be a COMMUTATIVE RING (Definition F.3 page 191).

A function $|\cdot|$ in \mathbb{R} is an **absolute value** (or **modulus**) if

- | | | | |
|--------------|---|-----|--|
| D E F | 1. $ x \geq 0 \quad x \in \mathbb{R}$ (NON-NEGATIVE) | and | |
| | 2. $ x = 0 \iff x = 0 \quad x \in \mathbb{R}$ (NONDEGENERATE) | and | |
| | 3. $ xy = x \cdot y \quad x, y \in \mathbb{R}$ (HOMOGENEOUS / SUBMULTIPLICATIVE) | and | |
| | 4. $ x + y \leq x + y \quad x, y \in \mathbb{R}$ (SUBADDITIVE / TRIANGLE INEQUALITY) | | |

Definition F.5. ⁶

The structure $F \triangleq (X, +, \cdot, 0, 1)$ is a **field** if

- | | | | |
|--------------|--|-----|--|
| D E F | 1. $(X, +, *)$ is a ring (ring) | and | |
| | 2. $xy = yx \quad \forall x, y \in X$ (commutative with respect to $*$) | and | |
| | 3. $(X \setminus \{0\}, *)$ is a group (group with respect to $*$). | | |

Definition F.6. ⁷ Let $V = (F, +, \cdot)$ be a vector space and $\otimes : V \times V \rightarrow V$ be a vector-vector multiplication operator.

An **algebra** is any pair (V, \otimes) that satisfies (\otimes is represented by juxtaposition)

- | | | | |
|--------------|---|-----|--|
| D E F | 1. $(ux)y = u(xy) \quad \forall u, x, y \in V$ (ASSOCIATIVE) | and | |
| | 2. $u(x + y) = (ux) + (uy) \quad \forall u, x, y \in V$ (LEFT DISTRIBUTIVE) | and | |
| | 3. $(u + x)y = (uy) + (xy) \quad \forall u, x, y \in V$ (RIGHT DISTRIBUTIVE) | and | |
| | 4. $\alpha(xy) = (\alpha x)y = x(\alpha y) \quad \forall x, y \in V \text{ and } \alpha \in F$ (SCALAR COMMUTATIVE) | . | |

⁵ Cohn (2002) page 312

⁶ Durbin (2000), page 123, Weber (1893)

⁷ Abramovich and Aliprantis (2002), page 3, Michel and Herget (1993), page 56

APPENDIX G

LINEAR SPACES



“The geometric calculus, in general, consists in a system of operations on geometric entities, and their consequences, analogous to those that algebra has on the numbers. It permits the expression in formulas of the results of geometric constructions, the representation with equations of propositions of geometry, and the substitution of a transformation of equations for a verbal argument.”¹

Giuseppe Peano (1858–1932), Italian mathematician, credited with being one of the first to introduce the concept of the *linear space* (*vector space*).¹

G.1 Definition and basic results

A *metric space* is a set together with nothing else save a *metric* that gives the space a *topology* (Definition ?? page ??). A *linear space* (next definition) in general has no topology but does have some additional *algebraic structure* (APPENDIX F page 191) that is useful in generalizing a number of mathematical concepts. If one wishes to have both algebraic structure and a topology, then this can be accomplished by appending a *topology* to a *linear space* giving a *topological linear space* (Definition ?? page ??), a *metric* giving a *metric linear space*, an *inner product* giving an *inner product space* (Definition K.1 page 255), or a *norm* giving a *normed linear space* (Definition L.1 page 271).

Definition G.1. ² Let $(\mathbb{F}, +, \cdot, 0, 1)$ be a FIELD (Definition F.5 page 192). Let X be a set, let $+$ be an OPERATOR (Definition O.1 page 303) in X^{X^2} , and let \otimes be an operator in $X^{\mathbb{F} \times X}$.

¹ quote: Peano (1888b), page ix

image http://en.wikipedia.org/wiki/File:Giuseppe_Peano.jpg, public domain

² Kubrusly (2001) pages 40–41 (Definition 2.1 and following remarks), Haaser and Sullivan (1991), page 41, Halmos (1948), pages 1–2, Peano (1888a) (Chapter IX), Peano (1888b), pages 119–120, Banach (1922) pages 134–135

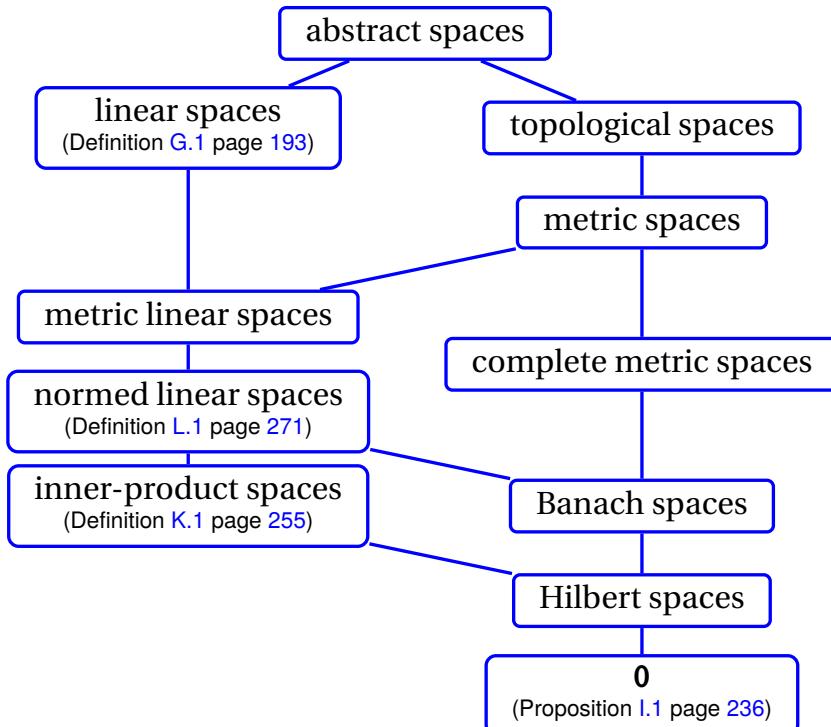


Figure G.1: Lattice of mathematical spaces

The structure $\Omega \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ is a **linear space** over $(\mathbb{F}, +, \cdot, 0, 1)$ if

- | | | |
|-----|---|-------------------------------|
| DEF | 1. $\exists \mathbb{0} \in X$ such that $x + \mathbb{0} = x \quad \forall x \in X$ | (+ IDENTITY) |
| | 2. $\exists y \in X$ such that $x + y = \mathbb{0} \quad \forall x \in X$ | (+ INVERSE) |
| | 3. $(x + y) + z = x + (y + z) \quad \forall x, y, z \in X$ | (+ is ASSOCIATIVE) |
| | 4. $x + y = y + x \quad \forall x, y \in X$ | (+ is COMMUTATIVE) |
| | 5. $1 \cdot x = x \quad \forall x \in X$ | (· IDENTITY) |
| | 6. $\alpha \cdot (\beta \cdot x) = (\alpha \cdot \beta) \cdot x \quad \forall \alpha, \beta \in S \text{ and } x \in X$ | (· ASSOCIATES with ·) |
| | 7. $\alpha \cdot (x + y) = (\alpha \cdot x) + (\alpha \cdot y) \quad \forall \alpha \in S \text{ and } x, y \in X$ | (· DISTRIBUTES over +) |
| | 8. $(\alpha + \beta) \cdot x = (\alpha \cdot x) + (\beta \cdot x) \quad \forall \alpha, \beta \in S \text{ and } x \in X$ | (· PSEUDO-DISTRIBUTES over +) |

The set X is called the **underlying set**. The elements of X are called **vectors**. The elements of \mathbb{F} are called **scalars**. A LINEAR SPACE is also called a **vector space**. If $\mathbb{F} \triangleq \mathbb{R}$, then Ω is a **real linear space**. If $\mathbb{F} \triangleq \mathbb{C}$, then Ω is a **complex linear space**.

Definition G.2. Let $L_1 \triangleq (X_1, +, \cdot, (\mathbb{F}_1, \dot{+}, \dot{\times}))$ and $L_2 \triangleq (X_2, +, \cdot, (\mathbb{F}_2, \dot{+}, \dot{\times}))$.

Ω_2 is a **linear subspace** of Ω_1 if

- | | |
|-----|--|
| DEF | 1. L_1 is a LINEAR SPACE (Definition G.1 page 193) and |
| | 2. L_2 is a LINEAR SPACE (Definition G.1 page 193) and |
| | 3. $\mathbb{F}_2 \subseteq \mathbb{F}_1$ and |
| | 4. $X_2 \subseteq X_1$ and |

Remark G.1.³ By the first four conditions (*) listed in Definition G.1, $(X, +)$ is a **commutative group** (or **abelian group**).

³ Akhiezer and Glazman (1993), page 1, Haaser and Sullivan (1991), page 41

Often when discussing a linear space, the operator \cdot is simply expressed with juxtaposition (e.g. αx is equivalent to $\alpha \cdot x$). In doing this, there is no risk of ambiguity between scalar-vector multiplication and scalar-scalar multiplication because the operands uniquely identify the precise operator.⁴

Example G.1 (tuples in \mathbb{F}^N).⁵ Let $(x_n)_1^N$ be an N -tuple (Definition R.1 page 353) over a field (Definition F.5 page 192) $(\mathbb{F}, +, \cdot, 0, 1)$.

EX	$\begin{aligned} X &\triangleq \{(x_n)_1^N \mid x_n \in \mathbb{F}\} && \text{and} \\ (x_n)_1^N + (y_n)_1^N &\triangleq (x_n + y_n)_1^N && \forall [x_n] \in X \quad \text{and} \\ \alpha \cdot (x_n)_1^N &\triangleq (\alpha \dot{x}_n)_1^N && \forall [x_n] \in X, \alpha \in \mathbb{F}. \end{aligned}$
----	--

Then the structure $(X, +, \cdot, (\mathbb{F}, +, \cdot))$ is a *linear space*.

Example G.2 (real numbers).⁶ Let $(\mathbb{R}, +, \cdot, 0, 1)$ be the field of real numbers.

EX	<p>The structure $(\mathbb{R}, +, \cdot, (\mathbb{R}, +, \cdot))$ is a <i>linear space</i>. That is, the field of real numbers forms a linear space over itself.</p>
----	---

Example G.3 (functions).⁷ Let $(\mathbb{F}, +, \cdot, 0, 1)$ be a field. Let Y^X be the set of all functions with domain X and range Y .

EX	$\begin{aligned} [f + g](x) &\triangleq f(x) + g(x) && \forall f, g \in Y^X \quad (\text{pointwise addition}) \quad \text{and} \\ [\alpha \cdot f](x) &\triangleq \alpha \cdot [f(x)] && \forall f \in Y^X, \alpha \in \mathbb{F}. \end{aligned}$
----	---

Then the structure $(Y^X, +, \cdot, (\mathbb{F}, +, \cdot))$ is a *linear space*.

Example G.4 (functions onto \mathbb{F}).⁸ Let $(\mathbb{F}, +, \cdot, 0, 1)$ be a field. Let \mathbb{F}^X be the set of all functions with domain X and range \mathbb{F} .

EX	$\begin{aligned} [f + g](x) &\triangleq f(x) + g(x) && \forall f, g \in \mathbb{F}^X \quad (\text{pointwise addition}) \quad \text{and} \\ [\alpha \cdot f](x) &\triangleq \alpha \cdot [f(x)] && \forall f \in \mathbb{F}^X, \alpha \in \mathbb{F}. \end{aligned}$
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Then the structure $(\mathbb{F}^X, +, \cdot, (\mathbb{F}, +, \cdot))$ is a *linear space*.

Theorem G.1 (Additive identity properties).⁹ Let $(X, +, \cdot, (\mathbb{F}, +, \cdot))$ be a linear space, 0 the ADDITIVE IDENTITY ELEMENT (Definition F.1 page 191) with respect to $\dot{+}$, and 0 the ADDITIVE IDENTITY ELEMENT with respect to $+$.

THM	$\begin{aligned} 1. \quad 0x &= 0 && \forall x \in X \\ 2. \quad \alpha 0 &= 0 && \forall \alpha \in \mathbb{F} \\ 3. \quad \alpha x &= 0 \implies \alpha = 0 \text{ or } x = 0 \\ 4. \quad x + x &= x \implies x = 0 \\ 5. \quad \alpha \neq 0 \text{ and } x \neq 0 &\implies \alpha x \neq 0 \end{aligned}$
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PROOF:

⁴ *Operator overload* is a technique in which two fundamentally different operators or functions share the same symbol or label. It is inherent in the programming language C++ and is therein called *operator overload*. In C++, you can define two (or more) operators or functions that share the same symbol or name, but yet are completely different. Two such operators (or functions) are distinguished from each other by the type of their operands. So for example, in C++, you can define an $m \times n$ matrix *type* and use operator overload to define a $+$ operator that operates on this new matrix type. So if variables x and y are of floating point type and A and B are of the matrix type, you can then add either type using the same syntax style:

$x+y$ (add two floating point numbers)
 $A+B$ (add two matrices)

Even though both of these operations “look” the same, they are of course fundamentally different.

⁵  Kubrusly (2001) page 41 (Example 2D)

⁶  Kubrusly (2001) page 41 (Example 2D),  Hamel (1905)

⁷  Kubrusly (2001) page 42 (Example 2F)

⁸  Kubrusly (2001) page 41 (Example 2E)

⁹  Berberian (1961) page 6 (Theorem 1),  Michel and Herget (1993) page 77

1. Proof that $0x = \emptyset$:

$$\begin{aligned}
 0x &= 0x + 0\emptyset && \text{by definition of } + \text{ additive identity element} \\
 &= 0x + 0x + (-0x) && \text{by definition of } + \text{ additive inverse} \\
 &= (0 + 0)x + (-0 \cdot x) && \text{by definition of } + \text{ additive identity element} \\
 &= 0x + (-0x) && \text{by Definition G.1 property 4} \\
 &= \emptyset && \text{by definition of } + \text{ additive identity element}
 \end{aligned}$$

2. Proof that $\alpha\emptyset = \emptyset$:

$$\begin{aligned}
 \alpha\emptyset &= \alpha(0x) && \text{by item 1} \\
 &= (\alpha 0)x && \text{by Definition G.1 property 6} \\
 &= 0x \\
 &= \emptyset && \text{by item 1}
 \end{aligned}$$

3. Proof that $\alpha \neq 0$ and $x \neq \emptyset \implies \alpha x \neq \emptyset$: Suppose $\alpha x = \emptyset$. Then

$$\begin{aligned}
 x &= \left(\frac{1}{\alpha}\right)x \\
 &= \frac{1}{\alpha}(\alpha x) \\
 &= \frac{1}{\alpha}\emptyset \\
 &= \emptyset && \text{by item 2} \\
 \implies x &= \emptyset
 \end{aligned}$$

This is a *contradiction* and so $\alpha x \neq \emptyset$.

4. Proof that $\alpha x = \emptyset \implies \alpha = 0$ or $x = \emptyset$: contrapositive argument of item 3

5. Proof that $x + x = x \implies x = \emptyset$:

$$\begin{aligned}
 x &= x + \emptyset && \text{by } \textit{additive identity property} \text{ (Definition G.1 page 193)} \\
 &= x + [x + (-x)] && \text{by } \textit{additive inverse property} \text{ (Definition G.1 page 193)} \\
 &= [x + x] + (-x) && \text{by } \textit{associative property} \text{ (Definition G.1 page 193)} \\
 &= x + (-x) && \text{by left hypothesis} \\
 &= \emptyset && \text{by } \textit{additive inverse property} \text{ (Definition G.1 page 193)}
 \end{aligned}$$

Definition G.3. ¹⁰ Let $\Omega \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ be a linear space with vectors $x, y \in X$. Let $-y$ be the additive inverse of y such that $y + (-y) = \emptyset$.

D E F The **difference** of x and y is $x + (-y)$ and is denoted $x - y$.

Theorem G.2 (Additive inverse properties). ¹¹ Let $\Omega \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ be a linear space, \emptyset the ADDITIVE IDENTITY ELEMENT with respect to $+$, and $-x$ the ADDITIVE INVERSE (Definition F.1 page 191) of x with respect to $+$.

T H M	1. $x + y = \emptyset \implies x = -y \quad \forall x, y \in X \quad (\text{additive inverse is UNIQUE})$
	2. $(-\alpha)x = -(\alpha x) = \alpha(-x) \quad \forall x \in X, \alpha \in \mathbb{F}$
	3. $\alpha(x - y) = \alpha x - \alpha y \quad \forall x, y \in X, \alpha \in \mathbb{F} \quad (\text{DISTRIBUTIVE})$
	4. $(\alpha - \beta)x = \alpha x - \beta x \quad \forall x \in X, \alpha, \beta \in \mathbb{F} \quad (\text{DISTRIBUTIVE})$

¹⁰ Berberian (1961) page 7 (Definition 1)

¹¹ Berberian (1961) page 7 (Corollary 1), Michel and Herget (1993) page 77, Peano (1888a) (Chapter IX), Peano (1888b) pages 119–120, Banach (1922) pages 134–135



PROOF:

1. Proof that $x + y = 0 \implies x = -y$:

$$\begin{aligned} x &= x - 0 \\ &= x - (x + y) && \text{by left hypothesis} \\ &= (x - x) - y \\ &= 0 - y \\ &= -y \end{aligned}$$

2. Proof that $(-\alpha)x = -(\alpha x)$:

$$\begin{aligned} 0 &= 0x && \text{by Theorem G.1 page 195} \\ &= (\alpha - \alpha)x && \text{by field property of } \mathbb{F} \\ &= [\alpha + (-\alpha)]x && \text{by field property of } \mathbb{F} \\ &= \alpha x + (-\alpha)x && \text{by Definition G.1 page 193} \\ \implies -(\alpha x) &= (-\alpha)x && \text{by item (1) page 197} \end{aligned}$$

3. Proof that $\alpha(-x) = -(\alpha x)$:

$$\begin{aligned} 0 &= \alpha 0 && \text{by Theorem G.1 page 195} \\ &= \alpha[x + (-x)] && \text{by definition of additive identity element } -x \\ &= \alpha x + \alpha(-x) && \text{by Definition G.1 page 193} \\ &= \alpha x + \alpha(-x) \\ \implies -(\alpha x) &= \alpha(-x) && \text{by item (1) page 197} \end{aligned}$$

4. Proof that $\alpha(x - y) = \alpha x - \alpha y$:

$$\begin{aligned} \alpha(x - y) &= \alpha[x + (-y)] && \text{by Definition G.3 page 196} \\ &= \alpha x + \alpha(-y) && \text{by Definition G.1 page 193} \\ &= \alpha x + (-\alpha y) && \text{by item (3) page 197} \\ &= \alpha x - \alpha y && \text{by Definition G.3 page 196} \end{aligned}$$

5. Proof that $(\alpha - \beta)x = \alpha x - \beta x$:

$$\begin{aligned} (\alpha - \beta)x &= [\alpha + (-\beta)]x && \text{by field properties of } \mathbb{F} \\ &= \alpha x + (-\beta)x && \text{by Definition G.1} \\ &= \alpha x + [-(\beta x)] && \text{by item (2) page 197} \\ &= \alpha x - (\beta x) && \text{by Definition G.3 page 196} \end{aligned}$$

⇒

Theorem G.3. ¹² Let $(X, +, \cdot, (\mathbb{F}, +, \dot{\times}))$ be a linear space, 0 the additive identity element with respect to $+$, and $-x$ additive inverse of x with respect to $+$.

T
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1. $\alpha x = \alpha y$ and $\alpha \neq 0 \implies x = y \quad \forall x, y \in X$
2. $\alpha x = \beta x$ and $x \neq 0 \implies \alpha = \beta \quad \forall x, y \in X, \alpha, \beta \in \mathbb{F}$
3. $z + x = z + y \implies x = y \quad \forall x, y, z \in X$

¹² Michel and Herget (1993) page 77, Peano (1888a) (Chapter IX), Peano (1888b) pages 119–120, Banach (1922) pages 134–135

PROOF:

1. Proof that $\alpha\mathbf{x} = \alpha\mathbf{y}$ and $\alpha \neq 0 \implies \mathbf{x} = \mathbf{y}$:

$$\begin{aligned} 0 &= \frac{1}{\alpha}(0) && \text{by left hypothesis } (\alpha \neq 0) \\ &= \frac{1}{\alpha}(\alpha\mathbf{x} - \alpha\mathbf{y}) && \text{by left hypothesis } (\alpha\mathbf{x} = \alpha\mathbf{y}) \\ &= \frac{1}{\alpha}\alpha(\mathbf{x} - \mathbf{y}) && \text{by Definition G.1 page 193} \\ &= \mathbf{x} - \mathbf{y} \end{aligned}$$

2. Proof that $\alpha\mathbf{x} = \beta\mathbf{x}$ and $\mathbf{x} \neq 0 \implies \alpha = \beta$:

$$\begin{aligned} 0 &= \alpha\mathbf{x} + (-\alpha\mathbf{x}) && \text{by definition of additive inverse} \\ &= \beta\mathbf{x} + (-\alpha\mathbf{x}) && \text{by left hypothesis} \\ &= \beta\mathbf{x} + (-\alpha)\mathbf{x} && \text{by Theorem G.2 page 196} \\ &= [\beta + (-\alpha)]\mathbf{x} && \text{by Definition G.1 page 193} \\ \implies \beta - \alpha &= 0 && \text{by Theorem G.1 page 195} \\ \implies \alpha &= \beta && \text{by field properties of } \mathbb{F} \end{aligned}$$

3. Proof that $\mathbf{z} + \mathbf{x} = \mathbf{z} + \mathbf{y} \implies \mathbf{x} = \mathbf{y}$:

$$\begin{aligned} 0 &= (\mathbf{z} + \mathbf{x}) - (\mathbf{z} + \mathbf{y}) && \text{by Definition G.1 property 1} \\ &= (\mathbf{x} + \mathbf{z}) - (\mathbf{z} + \mathbf{y}) && \text{by Definition G.1 property 3} \\ &= (\mathbf{x} + \mathbf{z}) + [(-1)\mathbf{z} + (-1)\mathbf{y}] && \text{by previous result 2.} \\ &= (\mathbf{x} + \mathbf{z}) + (-\mathbf{z} - \mathbf{y}) \\ &= \mathbf{x} + (\mathbf{z} - \mathbf{z}) - \mathbf{y} \\ &= \mathbf{x} - \mathbf{y} \end{aligned}$$

⇒

G.2 Order on Linear Spaces

Definition G.4. ¹³ Let $\Omega \triangleq (X, +, \cdot, (\mathbb{R}, \dot{+}, \dot{\times}))$ be a real linear space.

The pair (Ω, \leq) is an ordered linear space if

- | | | |
|--------------|--|-----|
| D E F | 1. $\mathbf{x} \leq \mathbf{y} \implies \mathbf{x} + \mathbf{z} \leq \mathbf{y} + \mathbf{z} \quad \forall \mathbf{z} \in X$ | and |
| | 2. $\mathbf{x} \leq \mathbf{y} \implies \alpha\mathbf{x} \leq \alpha\mathbf{y} \quad \forall \alpha \in \mathbb{F}$ | |

A vector \mathbf{x} is positive if $0 \leq \mathbf{x}$.

The positive cone X^+ of (X, \leq) is the set $X^+ \triangleq \{\mathbf{x} \in X \mid 0 \leq \mathbf{x}\}$.

Definition G.5. ¹⁴ Let (X, \leq) be an ordered linear space.

D E F The tuple $L \triangleq (X, \vee, \wedge; \leq)$ is a Riesz space if L is a lattice.

A RIESZ SPACE is also called a vector lattice.

Theorem G.4. ¹⁵ Let $(X, \vee, \wedge; \leq)$ be a Riesz space (Definition G.5 page 198).

T H M	$\mathbf{x} \vee \mathbf{y} = -[(-\mathbf{x}) \wedge (-\mathbf{y})]$ $\mathbf{x} + (\mathbf{y} \vee \mathbf{z}) = (\mathbf{x} + \mathbf{y}) \vee (\mathbf{x} + \mathbf{z})$ $\alpha(\mathbf{x} \vee \mathbf{y}) = (\alpha\mathbf{x}) \vee (\alpha\mathbf{y})$ $\mathbf{x} + \mathbf{y} = (\mathbf{x} \wedge \mathbf{y}) + (\mathbf{x} \vee \mathbf{y})$	$\mathbf{x} \wedge \mathbf{y} = -[(-\mathbf{x}) \vee (-\mathbf{y})]$ $\mathbf{x} + (\mathbf{y} \wedge \mathbf{z}) = (\mathbf{x} + \mathbf{y}) \wedge (\mathbf{x} + \mathbf{z})$ $\alpha(\mathbf{x} \wedge \mathbf{y}) = (\alpha\mathbf{x}) \wedge (\alpha\mathbf{y})$ $\forall \mathbf{x}, \mathbf{y} \in X$ $\forall \mathbf{x}, \mathbf{y}, \mathbf{z} \in X$ $\forall \mathbf{x}, \mathbf{y} \in X, \alpha \geq 0$ $\forall \mathbf{x}, \mathbf{y} \in X, \alpha \in \mathbb{F}$
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¹³ Aliprantis and Burkinshaw (2006) pages 1-2

¹⁴ Aliprantis and Burkinshaw (2006) page 2

¹⁵ Aliprantis and Burkinshaw (2006) page 3 (Theorem 1.2)



PROOF:

1. Proof that $x \vee y = -[(-x) \wedge (-y)]$:

$(-x) \wedge (-y) \leq -x$	$(-x) \wedge (-y) \leq -y$
$x \leq -[(-x) \wedge (-y)]$	$y \leq -[(-x) \wedge (-y)]$
$x \vee y \leq -[(-x) \wedge (-y)]$	
$x \leq x \vee y$	$y \leq x \vee y$
$-(x \vee y) \leq -x$	$-(x \vee y) \leq -y$
$-(x \vee y) \leq (-x) \wedge (-y)$	
$-[(-x) \wedge (-y)] \leq x \vee y$	

2. Proof that $x \wedge y = -[(-x) \vee (-y)]$:

$x \vee y = -[(-x) \wedge (-y)]$	by item (1)
$(-x) \vee (-y) = -[(-(-x)) \wedge (-(-y))]$	replace x with $-x$ and y with y
$(-x) \vee (-y) = -[x \wedge y]$	$-(-x) = x$
$-[x \wedge y] = (-x) \vee (-y)$	by symmetry of $=$ relation
$x \wedge y = -[(-x) \vee (-y)]$	multiply both sides by -1

3. Proof that $x + (y \vee z) = (x + y) \vee (x + z)$:

$x + y \leq x + (y \vee z)$	$x + z \leq x + (y \vee z)$
$(x + y) \vee (x + z) \leq x + (y \vee z)$	
$y = -x + (x + y)$	$z = -x + (x + z)$
$\leq -x + [(x + y) \vee (x + z)]$	$\leq -x + [(x + y) \vee (x + z)]$
$y \vee z \leq -x + [(x + y) \vee (x + z)]$	
$x + (y \vee z) \leq (x + y) \vee (x + z)$	

4. Proof that $x + (y \wedge z) = (x + y) \wedge (x + z)$:

$x + y \geq x + (y \wedge z)$	$x + z \geq x + (y \wedge z)$
$(x + y) \wedge (x + z) \geq x + (y \wedge z)$	
$y = -x + (x + y)$	$z = -x + (x + z)$
$\geq -x + [(x + y) \wedge (x + z)]$	$\geq -x + [(x + y) \wedge (x + z)]$
$y \wedge z \geq -x + [(x + y) \wedge (x + z)]$	
$x + (y \wedge z) \geq (x + y) \wedge (x + z)$	

5. Proof that $\alpha(x \vee y) = (\alpha x) \vee (\alpha y)$ for $\alpha \geq 0$:

$x \leq x \vee y$	$y \leq x \vee y$	
$\alpha x \leq \alpha(x \vee y)$	$\alpha y \leq \alpha(x \vee y)$	by Definition G.4 page 198
$(\alpha x) \vee (\alpha y) \leq \alpha(x \vee y)$		
$\alpha x \leq (\alpha x) \vee (\alpha y)$	$\alpha y \leq (\alpha x) \vee (\alpha y)$	
$x \leq \alpha^{-1}(\alpha x) \vee (\alpha y)$	$y \leq \alpha^{-1}(\alpha x) \vee (\alpha y)$	
$x \vee y \leq \alpha^{-1}(\alpha x) \vee (\alpha y)$		
$\alpha(x \vee y) \leq (\alpha x) \vee (\alpha y)$		

6. Proof that $\alpha(x \wedge y) = (\alpha x) \wedge (\alpha y)$ for $\alpha \geq 0$:

$x \geq x \wedge y$	$y \geq x \wedge y$	
$\alpha x \geq \alpha(x \wedge y)$	$\alpha y \geq \alpha(x \wedge y)$	
$(\alpha x) \wedge (\alpha y) \geq \alpha(x \wedge y)$		by Definition G.4 page 198

$\alpha x \geq (\alpha x) \wedge (\alpha y)$	$\alpha y \geq (\alpha x) \wedge (\alpha y)$	
$x \geq \alpha^{-1}(\alpha x) \wedge (\alpha y)$	$y \geq \alpha^{-1}(\alpha x) \wedge (\alpha y)$	
$x \wedge y \geq \alpha^{-1}(\alpha x) \wedge (\alpha y)$		
$\alpha(x \wedge y) \geq (\alpha x) \wedge (\alpha y)$		

7. Proof that $x + y = (x \wedge y) + (x \vee y)$:

$x \leq x \vee y$	$y \leq x \vee y$
$x + y \leq (x \vee y) + y$	$x + vy \leq x + (x \vee y)$
$x + y - (x \vee y) \leq y$	$x + vy - (x \vee y) \leq x$
$x + y - (x \vee y) \leq x \wedge y$	
$x + y \leq (x \vee y) + (x \wedge y)$	
$x \wedge y \leq x$	$x \wedge y \leq y$
$0 \leq x - (x \wedge y)$	$0 \leq y - (x \wedge y)$
$y \leq y + x - (x \wedge y)$	$x \leq x + y - (x \wedge y)$
$y \leq x + y - (x \wedge y)$	$x \leq x + y - (x \wedge y)$
$x \vee y \leq x + y - (x \wedge y)$	
$(x \wedge y) + (x \vee y) \leq x + y$	

⇒

Definition G.6. ¹⁶ Let $(X, \vee, \wedge; \leq)$ be a RIESZ SPACE (Definition G.5 page 198).

D E F x^+ is defined as $x^+ \triangleq x \vee \emptyset$ and is called the **positive part** of x .
 x^- is defined as $x^- \triangleq (-x) \vee \emptyset$ and is called the **negative part** of x .
 $|x|$ is defined as $|x| \triangleq x \vee (-x)$ and is called the **absolute value** of x .

Theorem G.5. ¹⁷ Let $(X, \vee, \wedge; \leq)$ be a RIESZ SPACE (Definition G.5 page 198).

T H M	$y - z = x$ and $y \wedge z = \emptyset$	\Leftrightarrow	$\left\{ \begin{array}{l} y = x^+ \text{ and} \\ z = x^- \end{array} \right.$
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PROOF:

1. Proof that left hypothesis \Rightarrow right hypothesis:

$$\begin{aligned}
 x^+ &= x \vee \emptyset && \text{by definition of } x^+ \text{ Definition G.6 page 200} \\
 &= (y - z) \vee \emptyset && \text{by left hypothesis} \\
 &= (y - z) \vee (z - z) \\
 &= (y \vee z) - z && \text{by Theorem G.4 page 198} \\
 &= [y + z - (y \wedge z)] - z && \text{by Theorem G.4 page 198} \\
 &= y - (y \wedge z) \\
 &= y - \emptyset && \text{by left hypothesis} \\
 &= y \\
 x^- &= (-x) \vee \emptyset && \text{by definition of } x^- \text{ Definition G.6 page 200} \\
 &= (z - y) \vee \emptyset && \text{by left hypothesis} \\
 &= (z - y) \vee (y - y) \\
 &= (z \vee y) - y && \text{by Theorem G.4 page 198}
 \end{aligned}$$

¹⁶ Aliprantis and Burkinshaw (2006) page 4, Istrătescu (1987) page 129

¹⁷ Aliprantis and Burkinshaw (2006) page 4 (Theorem 1.3)

$$\begin{aligned}
 &= [z + y - (z \wedge y)] - z && \text{by Theorem G.4 page 198} \\
 &= z - (z \wedge y) \\
 &= z - \emptyset && \text{by left hypothesis} \\
 &= z
 \end{aligned}$$

2. Proof that left hypothesis \iff right hypothesis:

$$\begin{aligned}
 y - z &= x^+ - x^- && \text{by right hypothesis} \\
 &= [x \vee \emptyset] - [(-x) \vee \emptyset] && \text{by Definition G.6 page 200} \\
 &= (x \vee \emptyset) + (x \wedge \emptyset) && \text{by Theorem G.4 page 198} \\
 &= x && \text{by Theorem G.4 page 198} \\
 y \wedge z &= x^+ \wedge x^- && \text{by right hypothesis} \\
 &= [x^- + (x^+ - x^-)] \wedge [x^- + \emptyset] && \\
 &= x^- + [(x^+ - x^-) \wedge \emptyset] && \text{by Theorem G.4 page 198} \\
 &= x^- + [(y - z) \wedge \emptyset] && \text{by right hypothesis} \\
 &= x^- + (x \wedge \emptyset) && \text{by previous result} \\
 &= x^- - [-x \vee \emptyset] && \text{by Theorem G.4 page 198} \\
 &= x^- - x && \text{by definition of } x^- \text{ (Definition G.6 page 200)} \\
 &= \emptyset
 \end{aligned}$$



Theorem G.6.¹⁸ Let $(X, \vee, \wedge; \leq)$ be a RIESZ SPACE (Definition G.5 page 198). Let x^+ the POSITIVE PART of $x \in X$, x^- the NEGATIVE PART of $x \in X$, and $|x|$ the ABSOLUTE VALUE (Definition G.6 page 200) of $x \in X$.

T H M	$ x = x^+ + x^-$ $x = (x - y)^+ + (x \wedge y)$ $\forall x \in X$
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PROOF:

$$\begin{aligned}
 |x| &= x \vee (-x) && \text{by definition of } |x| \text{ (Definition G.6 page 200)} \\
 &= (2x - x) \vee (\emptyset - x) \\
 &= (-x + 2x) \vee (-x + \emptyset) && \text{by } \textit{commutative property} \text{ (Definition G.1 page 193)} \\
 &= (-x) + (2x \vee \emptyset) && \text{by Theorem G.4 page 198} \\
 &= (2x \vee \emptyset) - x && \text{by the } \textit{commutative property} \text{ (Definition G.1 page 193)} \\
 &= 2(x \vee \emptyset) - x && \text{by Theorem G.4 page 198} \\
 &= 2x^+ - x && \text{by definition of } x^+ \text{ (Definition G.6 page 200)} \\
 &= 2x^+ - (x^+ - x^-) && \text{by 1} \\
 &= x^+ + x^- \\
 x &= x + \emptyset \\
 &= (x \vee y) + (x \wedge y) - y && \text{by Theorem G.4 page 198} \\
 &= [(x - y) \vee (y - y)] + (x \wedge y) && \text{by Theorem G.4 page 198} \\
 &= [(x - y) \vee \emptyset] + (x \wedge y) \\
 &= (x - y)^+ + (x \wedge y) && \text{by definition of } x^+ \text{ (Definition G.6 page 200)}
 \end{aligned}$$



¹⁸ Aliprantis and Burkinshaw (2006) page 4

Theorem G.7. ¹⁹ Let $(X, \vee, \wedge; \leq)$ be a RIESZ SPACE (Definition G.5 page 198). Let x^+ the POSITIVE PART of $x \in X$, x^- the NEGATIVE PART of $x \in X$, and $|x|$ the ABSOLUTE VALUE (Definition G.6 page 200) of $x \in X$.

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1. $x \vee y = \frac{1}{2}(x + y + |x - y|) \quad \forall x, y \in X$
2. $x \wedge y = \frac{1}{2}(x + y - |x - y|) \quad \forall x, y \in X$
3. $|x - y| = (x \vee y) - (x \wedge y) \quad \forall x, y \in X$
4. $|x| \vee |y| = \frac{1}{2}(|x + y| + |x - y|) \quad \forall x, y \in X$
5. $|x| \wedge |y| = \frac{1}{2}(|x + y| - |x - y|) \quad \forall x, y \in X$

PROOF:

$$\begin{aligned}
 (x + y + |x - y|) &= (x + y) + [(x - y) \vee (y - x)] && \text{by Definition G.6 page 200} \\
 &= [(x + y) + (x - y)] \vee [(x + y) + (y - x)] && \text{by Theorem G.4 page 198} \\
 &= (2x) \vee (2y) \\
 &= 2(x \vee y) && \text{by Theorem G.4 page 198} \\
 (x + y - |x - y|) &= (x + y) - [(x - y) \vee (y - x)] && \text{by Definition G.6 page 200} \\
 &= (x + y) - [(-(y - x)) \vee (-(x - y))] \\
 &= (x + y) + [(y - x) \wedge (x - y)] \\
 &= [(x + y) + (y - x)] \wedge [(x + y) + (x - y)] \\
 &= (2y) \wedge (2x) \\
 &= 2(y \wedge x) \\
 &= 2(x \wedge y) && \text{by Theorem G.4 page 198} \\
 |x - y| &= \frac{1}{2}(x + y + |x - y|) - \frac{1}{2}(x + y - |x - y|) \\
 &= (x \vee y) - (x \wedge y) && \text{by 1 and 2} \\
 |x + y| + |x - y| &= \frac{1}{2}(\emptyset + |2x + 2y|) + |x - y| \\
 &= \frac{1}{2}[(x + y) + (-x - y) + |(x + y) - (-x - y)|] + |x - y| \\
 &= [(x + y) \vee (-x - y)] + |x - y| && \text{by 1} \\
 &= [(x + y) + |x - y|] \vee [(-x - y) + |x - y|] && \text{by Theorem G.4 page 198} \\
 &= 2(x \vee y) \vee 2[(-y) + (-x) + |(-y) - (-x)|] \\
 &= 2(x \vee y) \vee 2[(-y) \vee (-x)] \\
 &= 2([x \vee (-x)] \vee (y \vee (-y))) \\
 &= 2(|x| \vee |y|) && \text{by Definition G.6 page 200} \\
 ||x + y| - |x - y|| &= 2(|x + y| \vee |x - y|) - (|x + y| + |x - y|) \\
 &= (|x + y + x - y| + |x + y - x + y|) - 2(|x| \vee |y|) && \text{by 1} \\
 &= 2(|x| + |y|) - 2(|x| \vee |y|) \\
 &= 2(|x| \vee |y|) && \text{by Theorem G.4 page 198}
 \end{aligned}$$

Definition G.7. ²⁰ Let $(X, \vee, \wedge; \leq)$ be a RIESZ SPACE (Definition G.5 page 198). Let x^+ the POSITIVE PART of $x \in X$, x^- the NEGATIVE PART of $x \in X$, and $|x|$ the ABSOLUTE VALUE (Definition G.6 page 200) of $x \in X$.

D
E
F

x and y are disjoint, denoted by $x \perp y$, if

$$|x| \wedge |y| = \emptyset.$$

Two subsets U and V of X are disjoint, denoted by $U \perp V$ if

$$x \perp y \quad \forall x \in U \text{ and } y \in V$$

¹⁹ Aliprantis and Burkinshaw (2006) page 5 (Theorem 1.4)

²⁰ Aliprantis and Burkinshaw (2006) page 5

Definition G.8. ²¹ Let $(X, \vee, \wedge; \leq)$ be a RIESZ SPACE (Definition G.5 page 198). Let x^+ the POSITIVE PART of $x \in X$, x^- the NEGATIVE PART of $x \in X$, and $|x|$ the ABSOLUTE VALUE (Definition G.6 page 200) of $x \in X$. Let Y be a subset of X .

D E F Y^d is the **disjoint complement** of Y if $Y^d \triangleq \{x \in X | x \perp y \quad \forall y \in Y\}$.
The quantity Y^{dd} is defined as $(Y^d)^d$.

Definition G.9. ²² Let $(X, \vee, \wedge; \leq)$ be a RIESZ SPACE (Definition G.5 page 198). Let x^+ the POSITIVE PART of $x \in X$, x^- the NEGATIVE PART of $x \in X$, and $|x|$ the ABSOLUTE VALUE (Definition G.6 page 200) of $x \in X$.

D E F	$ A \triangleq \{ a a \in A\}$ $A^+ \triangleq \{a^+ a \in A\}$ $A^- \triangleq \{a^- a \in A\}$ $A \vee B \triangleq \{a \vee b a \in A \text{ and } b \in B\}$ $A \wedge B \triangleq \{a \wedge b a \in A \text{ and } b \in B\}$ $x \vee A \triangleq \{x \vee a a \in A\}$ $x \wedge A \triangleq \{x \wedge a a \in A\}$
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²¹  Aliprantis and Burkinshaw (2006) page 5

²²  Aliprantis and Burkinshaw (2006) page 7



APPENDIX H

LINEAR COMBINATIONS

H.1 Linear combinations in linear spaces

A *linear space* (Definition G.1 page 193) in general is not equipped with a *topology*. Without a topology, it is not possible to determine whether an *infinite sum* of vectors converges. Therefore in this section (dealing with linear spaces), all definitions related to sums of vectors will be valid for *finite sums* (Definition N.1 page 289) only (finite “ N ”).

Definition H.1. ¹ Let $\{x_n \in X \mid n=1,2,\dots,N\}$ be a set of vectors in a LINEAR SPACE $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$.

D E F A vector $x \in X$ is a **linear combination** of the vectors in $\{x_n\}$ if

there exists $\{\alpha_n \in \mathbb{F} \mid n=1,2,\dots,N\}$ such that
$$x = \sum_{n=1}^N \alpha_n x_n.$$

Definition H.2. ² Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ be a linear space and Y be a subset of X .

D E F The **linear span** of Y is defined as $\text{span}Y \triangleq \left\{ \sum_{\gamma \in \Gamma} \alpha_\gamma y_\gamma \mid \alpha_\gamma \in \mathbb{F}, y_\gamma \in Y \right\}.$

The set Y **spans** a set A if $A \subseteq \text{span}Y.$

Proposition H.1. ³ Let $\{x_n \in X \mid n=1,2,\dots,N\}$ be a set of vectors in a LINEAR SPACE $L \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times})).$

- P R P**
1. $\text{span}\{x_n\}$ is a LINEAR SPACE (Definition G.1 page 193) and
 2. $\text{span}\{x_n\}$ is a LINEAR SUBSPACE of L (Definition G.2 page 194).

Definition H.3. ⁴ Let $L \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ be a LINEAR SPACE.

D E F The set $Y \triangleq \{x_n \in X \mid n=1,2,\dots,N\}$ is **linearly independent** in L if
$$\left\{ \sum_{n=1}^N \alpha_n x_n = 0 \right\} \implies \{\alpha_1 = \alpha_2 = \dots = \alpha_N = 0\}.$$

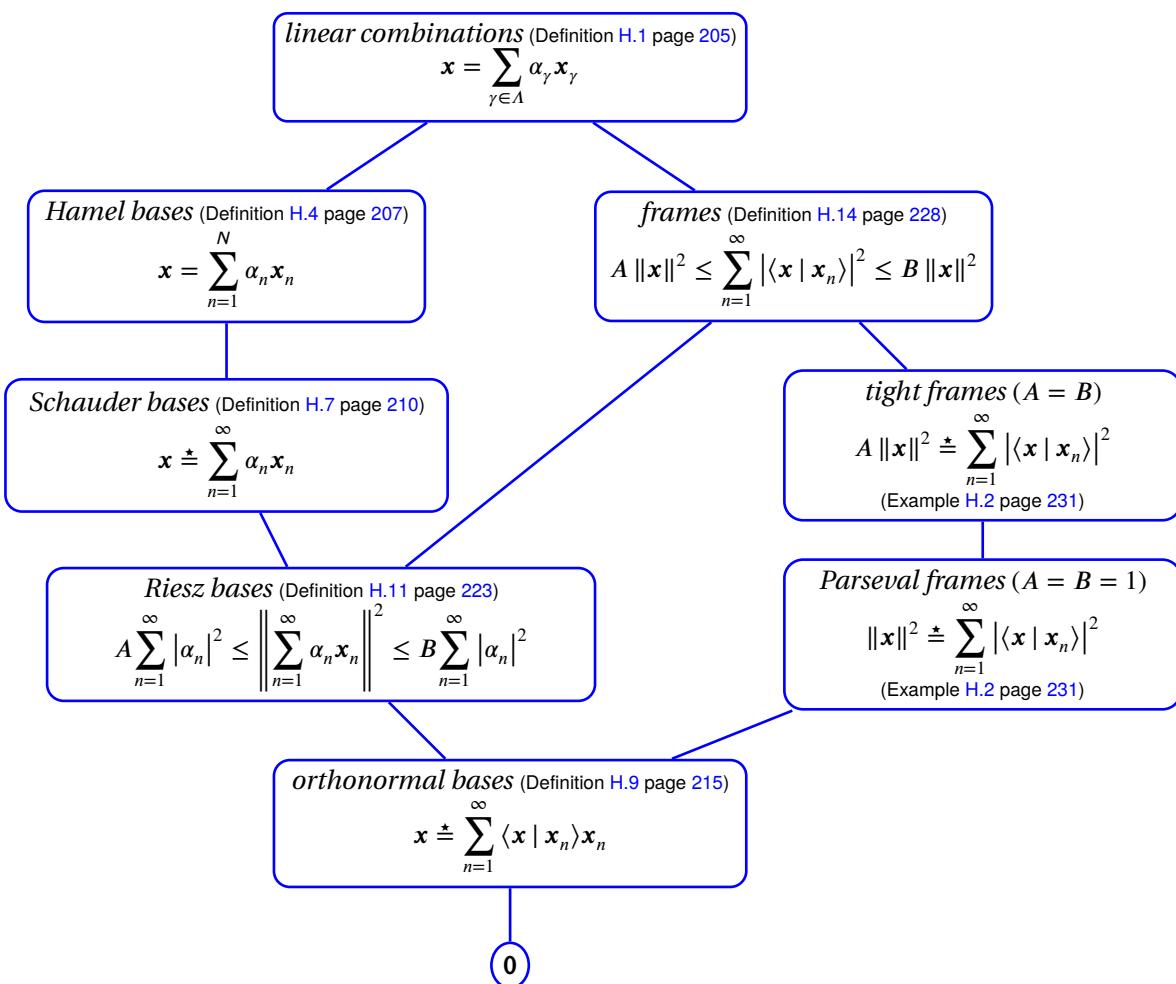
The set Y is **linearly dependent** in L if Y is not linearly independent in L .

¹ Berberian (1961) page 11 (Definition I.4.1), Kubrusly (2001) page 46

² Michel and Herget (1993) page 86 (3.3.7 Definition), Kurdila and Zabarankin (2005) page 44, Searcoid (2002) page 71 (Definition 3.2.5—more general definition)

³ Kubrusly (2001) page 46

⁴ Bachman and Narici (1966) pages 3–4, Christensen (2003) page 2, Heil (2011) page 156 (Definition 5.7)

Figure H.1: Lattice of *linear combinations*

Definition H.4. ⁵ Let $\{x_n \in X | n=1,2,\dots,N\}$ be a set of vectors in a LINEAR SPACE $L \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$.

D E F The set $\{x_n\}$ is a **Hamel basis** for L if

1. $\{x_n\}$ SPANS L (Definition H.2 page 205) and
2. $\{x_n\}$ is LINEARLY INDEPENDENT in L (Definition H.1 page 205) .

A HAMEL BASIS is also called a **linear basis**.

Definition H.5. ⁶ Let $L \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ be a LINEAR SPACE. Let x be a VECTOR in L and $Y \triangleq \{x_n \in X | n=1,2,\dots,N\}$ be a set of vectors in L .

D E F The expression $\sum_{n=1}^N \alpha_n x_n$ is the **expansion** of x on Y in L if $x = \sum_{n=1}^N \alpha_n x_n$.

In this case, the sequence $(\alpha_n)_{n=1}^N$ is the **coordinates** of x with respect to Y in L . If $\alpha_N \neq 0$, then N is the **dimension** $\dim L$ of L .

Theorem H.1. ⁷ Let $\{x_n | n=1,2,\dots,N\}$ be a HAMEL BASIS (Definition H.4 page 207) for a LINEAR SPACE $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$.

T H M
$$\left\{ x = \sum_{n=1}^N \alpha_n x_n = \sum_{n=1}^N \beta_n x_n \right\} \implies \underbrace{\alpha_n = \beta_n}_{\text{coordinates of } x \text{ are UNIQUE}} \quad \forall x \in X$$

PROOF:

$$0 = x - x$$

$$= \sum_{n=1}^N \alpha_n x_n - \sum_{n=1}^N \beta_n x_n$$

$$= \sum_{n=1}^N (\alpha_n - \beta_n) x_n$$

$\implies \{x_n\}$ is linearly dependent if $(\alpha_n - \beta_n) \neq 0 \quad \forall n = 1, 2, \dots, N$

$\implies (\alpha_n - \beta_n) = 0 \quad \forall n = 1, 2, \dots, N$ (because $\{x_n\}$ is a basis and therefore must be linearly independent)

$\implies \alpha_n = \beta_n$ for $n = 1, 2, \dots, N$

Theorem H.2. ⁸ Let $L \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ be a LINEAR SPACE.

T H M
$$\begin{aligned} & \left\{ \begin{array}{l} 1. \{x_n \in X | n=1,2,\dots,N\} \text{ is a HAMEL BASIS for } L \\ 2. \{y_n \in X | n=1,2,\dots,M\} \text{ is a set of LINEARLY INDEPENDENT vectors in } L \end{array} \right. \text{ and } \\ & \implies \left\{ \begin{array}{l} 1. M \leq N \\ 2. M = N \implies \{y_n | n=1,2,\dots,M\} \text{ is a BASIS for } L \\ 3. M \neq N \implies \{y_n | n=1,2,\dots,M\} \text{ is NOT a basis for } L \end{array} \right. \text{ and } \end{aligned}$$

PROOF:

⁵ Hamel (1905), Bachman and Narici (1966) page 4, Kubrusly (2001) pages 48–49 (Section 2.4), Young (2001) page 1, Carothers (2005) page 25, Heil (2011) page 125 (Definition 4.1)

⁶ Hamel (1905), Bachman and Narici (1966) page 4, Kubrusly (2001) pages 48–49 (Section 2.4), Young (2001) page 1, Carothers (2005) page 25, Heil (2011) page 125 (Definition 4.1)

⁷ Michel and Herget (1993) pages 89–90 (Theorem 3.3.25)

⁸ Michel and Herget (1993) pages 90–91 (Theorem 3.3.26)

1. Proof that $\{y_1, x_1, \dots, x_{N-1}\}$ is a *basis* for L :

(a) Proof that $\{y_1, x_1, \dots, x_{N-1}\}$ spans L :

i. Because $\{x_n|_{n=1,2,\dots,N}\}$ is a *basis* for L , there exists $\beta \in \mathbb{F}$ and $\{\alpha_n \in \mathbb{F}|_{n=1,2,\dots,N}\}$ such that

$$\beta y_1 + \sum_{n=1}^N \alpha_n x_n = 0.$$

ii. Select an n such that $\alpha_n \neq 0$ and renumber (if necessary) the above indices such that

$$x_n = -\frac{\beta}{\alpha_n} y_1 + \sum_{n=1}^{N-1} \frac{\alpha_n}{\alpha_n} x_n.$$

iii. Then, for any $y \in X$, we can write

$$\begin{aligned} y &= \sum_{n=1}^N \gamma_{n \in \mathbb{Z}} x_n \\ &= \left(\sum_{n=1}^{N-1} \gamma_{n \in \mathbb{Z}} x_n \right) + \gamma_{n \in \mathbb{Z}} \left(-\frac{\beta}{\alpha_n} y_1 - \sum_{n=1}^{N-1} \frac{\alpha_n}{\alpha_n} x_n \right) \\ &= -\frac{\beta \gamma_n}{\alpha_n} y_1 + \sum_{n=1}^{N-1} \left(\gamma_n - \frac{\alpha_n \gamma_n}{\alpha_n} \right) x_n \\ &= \delta y_1 + \sum_{n=1}^{N-1} \delta_{n \in \mathbb{Z}} x_n \end{aligned}$$

iv. This implies that $\{y_1, x_1, \dots, x_{N-1}\}$ spans L :

(b) Proof that $\{y_1, x_1, \dots, x_{N-1}\}$ is *linearly independent*:

i. If $\{y_1, x_1, \dots, x_{N-1}\}$ is *linearly dependent*, then there exists $\{\epsilon, \epsilon_1, \dots, \epsilon_{N-1}\}$ such that

$$\epsilon y_1 + \left(\sum_{n=1}^{N-1} \epsilon_{n \in \mathbb{Z}} x_n \right) + 0 x_n = 0.$$

ii. item (1(b)i) implies that the coordinate of y_1 associated with x_n is 0.

$$y_1 = -\left(\sum_{n=1}^{N-1} \frac{\epsilon_n}{\epsilon} x_n \right) + 0 x_n = 0.$$

iii. item (1(a)i) implies that the coordinate of y_1 associated with x_n is *not* 0.

$$y_1 = -\sum_{n=1}^N \frac{\alpha_n}{\beta} x_n.$$

iv. This implies that item (1(b)i) (that the set is linearly dependent) is *false* because item (1(b)ii) and item (1(b)iii) contradict each other.

v. This implies $\{y_1, x_1, \dots, x_{N-1}\}$ is *linearly independent*.

2. Proof that $\{y_1, y_2, x_1, \dots, x_{N-2}\}$ is a *basis*: Repeat item (1).

3. Suppose $m = n$. Proof that $\{y_1, y_2, \dots, y_M\}$ is a *basis*: Repeat item (1) $M - 1$ times.

4. Proof that $M \not> N$:

(a) Suppose that $M = N + 1$.

(b) Then because $\{y_n|_{n=1,2,\dots,N}\}$ is a *basis*, there exists $\{\zeta_n|_{n=1,2,\dots,N+1}\}$ such that

$$\sum_{n=1}^{N+1} \zeta_{n \in \mathbb{Z}} y_{n \in \mathbb{Z}} = 0.$$

(c) This implies that $\{y_n|_{n=1,2,\dots,N+1}\}$ is *linearly dependent*.



(d) This implies that $\{y_n | n=1,2,\dots,N+1\}$ is *not* a basis.

(e) This implies that $M > N$.

5. Proof that $M \neq N \implies \{y_n | n=1,2,\dots,M\}$ is *not* a basis for L :

(a) Proof that $M > N \implies \{y_n | n=1,2,\dots,M\}$ is *not* a basis for L : same as in item (4).

(b) Proof that $M < N \implies \{y_n | n=1,2,\dots,M\}$ is *not* a basis for L :

i. Suppose $M = N - 1$.

ii. Then $\{y_n | n=1,2,\dots,N-1\}$ is a *basis* and there exists λ such that

$$\sum_{n=1}^N \lambda_{n \in \mathbb{Z}} y_{n \in \mathbb{Z}} = 0.$$

iii. This implies that $\{y_n | n=1,2,\dots,N\}$ is *linearly dependent* and is *not* a basis.

iv. But this contradicts item (3), therefore $M \neq N - 1$.

v. Because $M = N$ yields a basis but $M = N - 1$ does not, $M < N - 1$ also does not yield a basis.



Corollary H.1. ⁹ Let $L \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ be a linear space.

COR
$$\left\{ \begin{array}{l} 1. \quad \{x_n \in X | n=1,2,\dots,N\} \text{ is a HAMEL BASIS for } L \text{ and} \\ 2. \quad \{y_n \in X | n=1,2,\dots,M\} \text{ is a HAMEL BASIS for } L \end{array} \right\} \implies \{N = M\}$$

(all Hamel bases for L have the same number of vectors)



PROOF: This follows from Theorem H.2 (page 207).

H.2 Bases in topological linear spaces

A linear space supports the concept of the *span* of a set of vectors (Definition H.2 page 205). In a topological linear space $\Omega \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), T)$, a set A is said to be *total* in Ω if the span of A is *dense* in Ω . In this case, A is said to be a *total set* or a *complete set*. However, this use of “complete” in a “complete set” is not equivalent to the use of “complete” in a “complete metric space”. ¹⁰ In this text, except for these comments and Definition H.6, “complete” refers to the metric space definition only.

If a set is both *total* and *linearly independent* (Definition H.3 page 205) in Ω , then that set is a *Hamel basis* (Definition H.4 page 207) for Ω .

Definition H.6. ¹¹ Let A^- be the CLOSURE of A in a TOPOLOGICAL LINEAR SPACE $\Omega \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), T)$. Let $\text{span } A$ be the SPAN (Definition H.2 page 205) of a set A .

DEF A set of vectors A is **total** (or **complete** or **fundamental**) in Ω if
 $(\text{span } A)^- = \Omega$ (SPAN of A is DENSE in Ω).

⁹ Kubrusly (2001) page 52 (Theorem 2.7), Michel and Herget (1993) page 91 (Theorem 3.3.31)

¹⁰ Haaser and Sullivan (1991) pages 296–297 (6-Orthogonal Bases), Rynne and Youngson (2008) page 78 (Remark 3.50), Heil (2011) page 21 (Remark 1.26)

¹¹ Young (2001) page 19 (Definition 1.5.1), Sohrab (2003) page 362 (Definition 9.2.3), Gupta (1998) page 134 (Definition 2.4), Bachman and Narici (1966) pages 149–153 (Definition 9.3, Theorems 9.9 and 9.10)

H.3 Schauder bases in Banach spaces

Definition H.7. ¹² Let $\mathbf{B} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$ be a BANACH SPACE. Let \doteq represent STRONG CONVERGENCE in \mathbf{B} .

The countable set $\{x_n \in X \mid n \in \mathbb{N}\}$ is a **Schauder basis** for \mathbf{B} if for each $x \in X$

$$1. \quad \exists (\alpha_n \in \mathbb{F})_{n \in \mathbb{N}} \quad \text{such that} \quad x \doteq \sum_{n=1}^{\infty} \alpha_n x_n \quad (\text{STRONG CONVERGENCE in } \mathbf{B} \text{ and})$$

$$2. \quad \left\{ \sum_{n=1}^{\infty} \alpha_n x_n \doteq \sum_{n=1}^{\infty} \beta_n x_n \right\} \implies \{(\alpha_n) = (\beta_n)\} \quad (\text{COEFFICIENT FUNCTIONALS are UNIQUE})$$

DEF

In this case, $\sum_{n=1}^{\infty} \alpha_n x_n$ is the **expansion** of x on $\{x_n \mid n \in \mathbb{N}\}$ and

the elements of (α_n) are the **coefficient functionals** associated with the basis $\{x_n\}$. Coefficient functionals are also called **coordinate functionals**.

In a Banach space, the existence of a Schauder basis implies that the space is *separable* (Theorem H.3 page 210). The question of whether the converse is also true was posed by Banach himself in 1932,¹³ and became known as “*The basis problem*”. This remained an open question for many years. The question was finally answered some 41 years later in 1973 by Per Enflo (University of California at Berkley), with the answer being “no”. Enflo constructed a counterexample in which a separable Banach space does *not* have a Schauder basis.¹⁴ Life is simpler in Hilbert spaces where the converse is true: a Hilbert space has a Schauder basis *if and only if* it is separable (Theorem H.11 page 222).

Theorem H.3. ¹⁵ Let $\mathbf{B} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$ be a BANACH SPACE. Let \mathbb{Q} be the field of rational numbers.

$$\begin{array}{c} \text{T} \\ \text{H} \\ \text{M} \end{array} \quad \left\{ \begin{array}{l} 1. \quad \mathbf{B} \text{ has a SCHAUDER BASIS and} \\ 2. \quad \mathbb{Q} \text{ is DENSE in } \mathbb{F}. \end{array} \right\} \implies \{ \mathbf{B} \text{ is SEPARABLE} \}$$

PROOF:

1. lemma:

$$\begin{aligned} \left| \left\{ x \mid \exists (\alpha_n \in \mathbb{Q})_{n \in \mathbb{N}} \text{ such that } \lim_{N \rightarrow \infty} \left\| x - \sum_{n=1}^N \alpha_n x_n \right\| = 0 \right\} \right| &= |\mathbb{Q} \times \mathbb{N}| \\ &= |\mathbb{Z} \times \mathbb{Z}| \\ &= |\mathbb{Z}| \\ &= \text{countably infinite} \end{aligned}$$

¹² Carothers (2005) pages 24–25, Christensen (2003) pages 46–49 (Definition 3.1.1 and page 49), Young (2001) page 19 (Section 6), Singer (1970), page 17, Schauder (1927), Schauder (1928)

¹³ Banach (1932a), page 111

¹⁴ Enflo (1973), Lindenstrauss and Tzafriri (1977) pages 84–95 (Section 2.d)

¹⁵ Bachman et al. (2000) page 112 (3.4.8), Giles (2000) page 17, Heil (2011) page 21 (Theorem 1.27)

2. remainder of proof:

\mathcal{B} has a Schauder basis $(\mathbf{x}_n)_{n \in \mathbb{N}}$

\implies for every $\mathbf{x} \in \mathcal{B}$, there exists $(\alpha_n \in \mathbb{F})_{n \in \mathbb{N}}$ such that $\mathbf{x} \doteq \sum_{n=1}^{\infty} \alpha_n \mathbf{x}_n$ by Definition H.7 page 210

\implies for every $\mathbf{x} \in \mathcal{B}$, there exists $(\alpha_n \in \mathbb{F})_{n \in \mathbb{N}}$ such that $\lim_{N \rightarrow \infty} \left\| \mathbf{x} - \sum_{n=1}^N \alpha_n \mathbf{x}_n \right\| = 0$

\implies for every $\mathbf{x} \in \mathcal{B}$, there exists $(\alpha_n \in \mathbb{Q})_{n \in \mathbb{N}}$ such that $\lim_{N \rightarrow \infty} \left\| \mathbf{x} - \sum_{n=1}^N \alpha_n \mathbf{x}_n \right\| = 0$ because $\mathbb{Q}^- = \mathbb{F}$

$\implies \mathcal{B} = \left\{ \mathbf{x} \mid \exists (\alpha_n \in \mathbb{Q})_{n \in \mathbb{N}} \text{ such that } \lim_{N \rightarrow \infty} \left\| \mathbf{x} - \sum_{n=1}^N \alpha_n \mathbf{x}_n \right\| = 0 \right\}$

$\implies \mathcal{B} = \left\{ \mathbf{x} \mid \exists (\alpha_n \in \mathbb{Q})_{n \in \mathbb{N}} \text{ such that } \mathbf{x} = \lim_{N \rightarrow \infty} \sum_{n=1}^N \alpha_n \mathbf{x}_n \right\}$

$\implies \mathcal{B}$ is separable by (1) lemma page 210



Definition H.8. ¹⁶ Let $\{\mathbf{x}_n | n \in \mathbb{N}\}$ and $\{\mathbf{y}_n | n \in \mathbb{N}\}$ be SCHAUDER BASES of a BANACH SPACE $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$.

D E F $\{\mathbf{x}_n\}$ is equivalent to $\{\mathbf{y}_n\}$
if there exists a BOUNDED INVERTIBLE operator \mathbf{R} in X^X such that $\mathbf{R}\mathbf{x}_n = \mathbf{y}_n \quad \forall n \in \mathbb{Z}$

Theorem H.4. ¹⁷ Let $\{\mathbf{x}_n | n \in \mathbb{N}\}$ and $\{\mathbf{y}_n | n \in \mathbb{N}\}$ be SCHAUDER BASES of a BANACH SPACE $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$.

T H M $\{\{\mathbf{x}_n\} \text{ is EQUIVALENT to } \{\mathbf{y}_n\}\}$
 $\iff \left\{ \sum_{n=1}^{\infty} \alpha_n \mathbf{x}_n \text{ is CONVERGENT} \iff \sum_{n=1}^{\infty} \alpha_n \mathbf{y}_n \text{ is CONVERGENT} \right\}$

Lemma H.1. ¹⁸ Let $\Omega \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), T)$ be a topological linear space. Let $\text{span } A$ be the SPAN of a set A (Definition H.2 page 205). Let $\tilde{f}(\omega)$ and $\tilde{g}(\omega)$ be the FOURIER TRANSFORMS (Definition P.2 page 333) of the functions $f(x)$ and $g(x)$, respectively, in $L^2_{\mathbb{R}}$ (Definition ?? page ??). Let $\check{a}(\omega)$ be the DTFT (Definition Q.1 page 343) of a sequence $(a_n)_{n \in \mathbb{Z}}$ in $\ell^2_{\mathbb{R}}$ (Definition R.2 page 353).

L E M $\left\{ \begin{array}{l} (1). \quad \left\{ \mathbf{T}^n f | n \in \mathbb{Z} \right\} \text{ is a SCHAUDER BASIS for } \Omega \quad \text{and} \\ (2). \quad \left\{ \mathbf{T}^n g | n \in \mathbb{Z} \right\} \text{ is a SCHAUDER BASIS for } \Omega \end{array} \right\} \implies \left\{ \begin{array}{l} \exists (a_n)_{n \in \mathbb{Z}} \text{ such that} \\ \tilde{f}(\omega) = \check{a}(\omega) \tilde{g}(\omega) \end{array} \right\}$

PROOF: Let V'_0 be the space spanned by $\{\mathbf{T}^n \phi | n \in \mathbb{Z}\}$.

$$\begin{aligned} \tilde{f}(\omega) &\triangleq \tilde{F}f && \text{by definition of } \tilde{F} \\ &= \tilde{F} \sum_{n \in \mathbb{Z}} a_n Tg && \text{by (2)} \\ &= \sum_{n \in \mathbb{Z}} a_n \tilde{FT}g \end{aligned}$$

¹⁶ Young (2001) page 25 (Definition 1.8.1, Theorem 1.8.7)

¹⁷ Young (2001) page 25 (Definition 1.8.1, Theorem 1.8.7)

¹⁸ Daubechies (1992), page 140

$$\begin{aligned}
 &= \underbrace{\sum_{n \in \mathbb{Z}} a_n e^{-i\omega n} \tilde{\mathbf{F}} \mathbf{g}}_{\check{a}(\omega)} \quad \text{by Corollary ?? page ??} \\
 &= \check{a}(\omega) \tilde{\mathbf{g}}(\omega) \quad \text{by definition of } \check{\mathbf{F}} \text{ and } \tilde{\mathbf{F}} \quad \text{by (Definition Q.1 page 343, Definition P.2 page 333)}
 \end{aligned}$$

$$\begin{aligned}
 V_0 &\triangleq \left\{ f(x) \mid f(x) = \sum_{n \in \mathbb{Z}} b_n T^n g(x) \right\} \\
 &= \left\{ f(x) \mid \tilde{\mathbf{F}} f(x) = \tilde{\mathbf{F}} \sum_{n \in \mathbb{Z}} b_n T^n g(x) \right\} \\
 &= \left\{ f(x) \mid \tilde{f}(\omega) = \tilde{b}(\omega) \tilde{\mathbf{g}}(\omega) \right\} \\
 &= \left\{ f(x) \mid \tilde{f}(\omega) = \tilde{b}(\omega) \check{a}(\omega) \tilde{f}(\omega) \right\} \\
 &= \left\{ f(x) \mid \tilde{f}(\omega) = \tilde{c}(\omega) \tilde{f}(\omega) \right\} \quad \text{where } \tilde{c}(\omega) \triangleq \tilde{b}(\omega) \check{a}(\omega) \\
 &= \left\{ f(x) \mid f(x) = \sum_{n \in \mathbb{Z}} c_n f(x - n) \right\} \\
 &\triangleq V'_0
 \end{aligned}$$



H.4 Linear combinations in inner product spaces

In an *inner product space*, *orthogonality* is a special case of *linear independence*; or alternatively, linear independence is a generalization of orthogonality (next theorem).

Theorem H.5. ¹⁹ Let $\{x_n \in X \mid n=1,2,\dots,N\}$ be a set of vectors in an INNER PRODUCT SPACE (Definition K.1 page 255) $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), (\Delta \mid \nabla))$.

T H M	$\left\{ \begin{array}{l} \{x_n\} \text{ is ORTHOGONAL} \\ (\text{Definition K.4 page 267}) \end{array} \right\} \implies \left\{ \begin{array}{l} \{x_n\} \text{ is LINEARLY INDEPENDENT} \\ (\text{Definition H.1 page 205}) \end{array} \right\}$
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PROOF:

1. Proof using *Pythagorean theorem* (Theorem K.10 page 269):

Let $(\alpha_n)_{n \in \mathbb{N}}$ be a sequence with at least one nonzero element.

$$\begin{aligned}
 \left\| \sum_{n=1}^N \alpha_n x_n \right\|^2 &= \sum_{n=1}^N \|\alpha_n x_n\|^2 \quad \text{by left hypoth. and Pythagorean Theorem (Theorem K.10 page 269)} \\
 &= \sum_{n=1}^N |\alpha_n|^2 \|x_n\|^2 \quad \text{by definition of } \|\cdot\| \quad (\text{Definition L.1 page 271}) \\
 &> 0 \\
 \implies \sum_{n=1}^N \alpha_n x_n &\neq 0 \\
 \implies (\alpha_n)_{n \in \mathbb{N}} \text{ is linearly independent} &\quad \text{by definition of linear independence} \quad (\text{Definition H.3 page 205})
 \end{aligned}$$

¹⁹ Aliprantis and Burkinshaw (1998) page 283 (Corollary 32.8), Kubrusly (2001) page 352 (Proposition 5.34)

2. Alternative proof:

$$\begin{aligned}
 \sum_{n=1}^N \alpha_n \mathbf{x}_n = \mathbf{0} &\implies \left\langle \sum_{n=1}^N \alpha_n \mathbf{x}_n \mid \mathbf{x}_m \right\rangle = \langle \mathbf{0} \mid \mathbf{x}_m \rangle \\
 &\implies \sum_{n=1}^N \alpha_n \langle \mathbf{x}_n \mid \mathbf{x}_m \rangle = 0 \\
 &\implies \sum_{n=1}^N \alpha_n \bar{\delta}(k-m) = 0 \\
 &\implies \alpha_m = 0 \quad \text{for } m = 1, 2, \dots, N
 \end{aligned}$$

⇒

Theorem H.6 (Bessel's Equality). ²⁰ Let $\{\mathbf{x}_n \in X \mid n=1, 2, \dots, N\}$ be a set of vectors in an INNER PRODUCT SPACE (Definition K.1 page 255) $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), (\triangle \mid \nabla))$ and with $\|\mathbf{x}\| \triangleq \sqrt{\langle \mathbf{x} \mid \mathbf{x} \rangle}$ (Definition K.2 page 261).

T H M	$\left\{ \begin{array}{l} \{\mathbf{x}_n\} \text{ is ORTHONORMAL} \\ (\text{Definition K.4 page 267}) \end{array} \right\} \implies \left\{ \underbrace{\left\ \mathbf{x} - \sum_{n=1}^N \langle \mathbf{x} \mid \mathbf{x}_n \rangle \mathbf{x}_n \right\ ^2}_{\text{approximation error}} = \ \mathbf{x}\ ^2 - \sum_{n=1}^N \langle \mathbf{x} \mid \mathbf{x}_n \rangle ^2 \quad \forall \mathbf{x} \in X \right\}$
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PROOF:

$$\begin{aligned}
 &\left\| \mathbf{x} - \sum_{n=1}^N \langle \mathbf{x} \mid \mathbf{x}_n \rangle \mathbf{x}_n \right\|^2 \\
 &= \|\mathbf{x}\|^2 + \left\| \sum_{n=1}^N \langle \mathbf{x} \mid \mathbf{x}_n \rangle \mathbf{x}_n \right\|^2 - 2\Re \left\langle \mathbf{x} \mid \sum_{n=1}^N \langle \mathbf{x} \mid \mathbf{x}_n \rangle \mathbf{x}_n \right\rangle \quad \text{by polar identity} \quad (\text{Lemma K.1 page 259}) \\
 &= \|\mathbf{x}\|^2 + \left\| \sum_{n=1}^N \langle \mathbf{x} \mid \mathbf{x}_n \rangle \mathbf{x}_n \right\|^2 - 2\Re \left[\left(\sum_{n=1}^N \langle \mathbf{x} \mid \mathbf{x}_n \rangle \right)^* \langle \mathbf{x} \mid \mathbf{x}_n \rangle \right] \quad \text{by property of } (\triangle \mid \nabla) \quad (\text{Definition K.1 page 255}) \\
 &= \|\mathbf{x}\|^2 + \sum_{n=1}^N \|\langle \mathbf{x} \mid \mathbf{x}_n \rangle \mathbf{x}_n\|^2 - 2\Re \left[\left(\sum_{n=1}^N \langle \mathbf{x} \mid \mathbf{x}_n \rangle \right)^* \langle \mathbf{x} \mid \mathbf{x}_n \rangle \right] \quad \text{by Pythagorean Theorem} \quad (\text{Theorem K.10 page 269}) \\
 &= \|\mathbf{x}\|^2 + \sum_{n=1}^N \|\langle \mathbf{x} \mid \mathbf{x}_n \rangle \mathbf{x}_n\|^2 - 2\Re \left(\sum_{n=1}^N \langle \mathbf{x} \mid \mathbf{x}_n \rangle^* \langle \mathbf{x} \mid \mathbf{x}_n \rangle \right) \\
 &= \|\mathbf{x}\|^2 + \sum_{n=1}^N |\langle \mathbf{x} \mid \mathbf{x}_n \rangle|^2 \underbrace{\|\mathbf{x}_n\|^2}_1 - 2\Re \left(\sum_{n=1}^N \langle \mathbf{x} \mid \mathbf{x}_n \rangle^* \langle \mathbf{x} \mid \mathbf{x}_n \rangle \right) \quad \text{by property of } \|\cdot\| \quad (\text{Definition L.1 page 271}) \\
 &= \|\mathbf{x}\|^2 + \sum_{n=1}^N |\langle \mathbf{x} \mid \mathbf{x}_n \rangle|^2 \cdot 1 - 2\Re \left(\sum_{n=1}^N \langle \mathbf{x} \mid \mathbf{x}_n \rangle^* \langle \mathbf{x} \mid \mathbf{x}_n \rangle \right) \quad \text{by def. of orthonormality} \quad (\text{Definition K.4 page 267}) \\
 &= \|\mathbf{x}\|^2 + \sum_{n=1}^N |\langle \mathbf{x} \mid \mathbf{x}_n \rangle|^2 - 2\Re \sum_{n=1}^N |\langle \mathbf{x} \mid \mathbf{x}_n \rangle|^2 \\
 &= \|\mathbf{x}\|^2 + \sum_{n=1}^N |\langle \mathbf{x} \mid \mathbf{x}_n \rangle|^2 - 2 \sum_{n=1}^N |\langle \mathbf{x} \mid \mathbf{x}_n \rangle|^2 \quad \text{because } |\cdot| \text{ is real}
 \end{aligned}$$

²⁰ Bachman et al. (2000) page 103, Pedersen (2000) pages 38–39

$$= \|\mathbf{x}\|^2 - \sum_{n=1}^N |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2$$

⇒

Theorem H.7 (Bessel's inequality). ²¹ Let $\{\mathbf{x}_n \in X \mid n=1,2,\dots,N\}$ be a set of vectors in an INNER PRODUCT SPACE (Definition K.1 page 255) ($X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \Delta | \nabla \rangle$) and with $\|\mathbf{x}\| \triangleq \sqrt{\langle \mathbf{x} | \mathbf{x} \rangle}$ (Definition K.2 page 261).

T H M	$\left\{ \begin{array}{l} \{\mathbf{x}_n\} \text{ is ORTHONORMAL} \\ (\text{Definition K.4 page 267}) \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} \sum_{n=1}^N \langle \mathbf{x} \mathbf{x}_n \rangle ^2 \leq \ \mathbf{x}\ ^2 \quad \forall \mathbf{x} \in X \end{array} \right\}$
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PROOF:

$$\begin{aligned} 0 &\leq \left\| \mathbf{x} - \sum_{n=1}^N \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n \right\|^2 && \text{by definition of } \|\cdot\| && (\text{Definition L.1 page 271}) \\ &= \|\mathbf{x}\|^2 - \sum_{n=1}^N |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 && \text{by Bessel's Equality} && (\text{Theorem H.6 page 213}) \end{aligned}$$

⇒

The *Best Approximation Theorem* (next) shows that

- ➊ the best sequence for representing a vector is the sequence of projections of the vector onto the sequence of basis functions
- ➋ the error of the projection is orthogonal to the projection.

Theorem H.8 (Best Approximation Theorem). ²² Let $\{\mathbf{x}_n \in X \mid n=1,2,\dots,N\}$ be a set of vectors in an INNER PRODUCT SPACE (Definition K.1 page 255) ($X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \Delta | \nabla \rangle$) and with $\|\mathbf{x}\| \triangleq \sqrt{\langle \mathbf{x} | \mathbf{x} \rangle}$ (Definition K.2 page 261).

T H M	$\left\{ \begin{array}{l} \{\mathbf{x}_n\} \text{ is} \\ \text{ORTHONORMAL} \\ (\text{Definition K.4 page 267}) \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} 1. \arg \min_{(\alpha_n)_{n=1}^N} \left\ \mathbf{x} - \sum_{n=1}^N \alpha_n \mathbf{x}_n \right\ = \underbrace{(\langle \mathbf{x} \mathbf{x}_n \rangle)_{n=1}^N}_{\text{best } \alpha_n = \langle \mathbf{x} \mathbf{x}_n \rangle} \quad \forall \mathbf{x} \in X \quad \text{and} \\ 2. \underbrace{\left(\sum_{n=1}^N \langle \mathbf{x} \mathbf{x}_n \rangle \mathbf{x}_n \right)}_{\text{approximation}} \perp \underbrace{\left(\mathbf{x} - \sum_{n=1}^N \langle \mathbf{x} \mathbf{x}_n \rangle \mathbf{x}_n \right)}_{\text{approximation error}} \quad \forall \mathbf{x} \in X \end{array} \right\}$
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PROOF:

²¹  Giles (2000) pages 54–55 (3.13 Bessel's inequality),  Bollobás (1999) page 147,  Aliprantis and Burkinshaw (1998) page 284

²²  Walter and Shen (2001), pages 3–4,  Pedersen (2000), page 39,  Edwards (1995), pages 94–100,  Weyl (1940)

1. Proof that $(\langle \mathbf{x} | \mathbf{x}_n \rangle)$ is the best sequence:

$$\begin{aligned}
 & \left\| \mathbf{x} - \sum_{n=1}^N \alpha_n \mathbf{x}_n \right\|^2 \\
 &= \| \mathbf{x} \|^2 - 2 \Re \left\langle \mathbf{x} \mid \sum_{n=1}^N \alpha_n \mathbf{x}_n \right\rangle + \left\| \sum_{n=1}^N \alpha_n \mathbf{x}_n \right\|^2 \\
 &= \| \mathbf{x} \|^2 - 2 \Re \left(\sum_{n=1}^N \alpha_n^* \langle \mathbf{x} | \mathbf{x}_n \rangle \right) + \sum_{n=1}^N \| \alpha_n \mathbf{x}_n \|^2 \quad \text{by Pythagorean Theorem} \quad (\text{Theorem K.10 page 269}) \\
 &= \| \mathbf{x} \|^2 - 2 \Re \left(\sum_{n=1}^N \alpha_n^* \langle \mathbf{x} | \mathbf{x}_n \rangle \right) + \sum_{n=1}^N | \alpha_n |^2 + \underbrace{\left[\sum_{n=1}^N | \langle \mathbf{x} | \mathbf{x}_n \rangle |^2 - \sum_{n=1}^N | \langle \mathbf{x} | \mathbf{x}_n \rangle |^2 \right]}_0 \\
 &= \left[\| \mathbf{x} \|^2 - \sum_{n=1}^N | \langle \mathbf{x} | \mathbf{x}_n \rangle |^2 \right] + \sum_{n=1}^N \left[| \langle \mathbf{x} | \mathbf{x}_n \rangle |^2 - 2 \Re_e [\alpha_n^* \langle \mathbf{x} | \mathbf{x}_n \rangle] + | \alpha_n |^2 \right] \\
 &= \left[\| \mathbf{x} \|^2 - \sum_{n=1}^N | \langle \mathbf{x} | \mathbf{x}_n \rangle |^2 \right] + \sum_{n=1}^N [| \langle \mathbf{x} | \mathbf{x}_n \rangle |^2 - \alpha_n^* \langle \mathbf{x} | \mathbf{x}_n \rangle - \alpha_n \langle \mathbf{x} | \mathbf{x}_n \rangle^* + | \alpha_n |^2] \\
 &= \left\| \mathbf{x} - \sum_{n=1}^N \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n \right\|^2 + \sum_{n=1}^N | \langle \mathbf{x} | \mathbf{x}_n \rangle - \alpha_n |^2 \quad \text{by Bessel's Equality} \quad (\text{Theorem H.6 page 213}) \\
 &\geq \left\| \mathbf{x} - \sum_{n=1}^N \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n \right\|^2
 \end{aligned}$$

2. Proof that the approximation and approximation error are orthogonal:

$$\begin{aligned}
 \left\langle \sum_{n=1}^N \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n \mid \mathbf{x} - \sum_{n=1}^N \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n \right\rangle &= \left\langle \sum_{n=1}^N \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n \mid \mathbf{x} \right\rangle - \left\langle \sum_{n=1}^N \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n \mid \sum_{n=1}^N \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n \right\rangle \\
 &= \sum_{n=1}^N \langle \mathbf{x} | \mathbf{x}_n \rangle^* \langle \mathbf{x} | \mathbf{x}_n \rangle - \sum_{n=1}^N \sum_{m=1}^N \langle \mathbf{x} | \mathbf{x}_n \rangle \langle \mathbf{x} | \mathbf{x}_m \rangle^* \langle \mathbf{x}_n | \mathbf{x}_m \rangle \\
 &= \sum_{n=1}^N | \langle \mathbf{x} | \mathbf{x}_n \rangle |^2 - \sum_{n=1}^N \sum_{m=1}^N \langle \mathbf{x} | \mathbf{x}_n \rangle \langle \mathbf{x} | \mathbf{x}_m \rangle^* \bar{\delta}_{nm} \\
 &= \sum_{n=1}^N | \langle \mathbf{x} | \mathbf{x}_n \rangle |^2 - \sum_{n=1}^N | \langle \mathbf{x} | \mathbf{x}_n \rangle |^2 \\
 &= 0
 \end{aligned}$$

⇒

H.5 Orthonormal bases in Hilbert spaces

Definition H.9. Let $\{ \mathbf{x}_n \in X \mid n=1,2,\dots,N \}$ be a set of vectors in an INNER PRODUCT SPACE (Definition K.1 page 255) $\Omega \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \triangledown \rangle)$.

D E F The set $\{x_n\}$ is an **orthogonal basis** for Ω if $\{x_n\}$ is ORTHOGONAL and is a SCHAUDER BASIS for Ω .
The set $\{x_n\}$ is an **orthonormal basis** for Ω if $\{x_n\}$ is ORTHONORMAL and is a SCHAUDER BASIS for Ω .

Definition H.10. ²³ Let $H \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \Delta | \nabla \rangle)$ be a Hilbert space.

D E F Suppose there exists a set $\{x_n \in X \mid n \in \mathbb{N}\}$ such that $x \triangleq \sum_{n=1}^{\infty} \langle x | x_n \rangle x_n$. Then the quantities $\langle x | x_n \rangle$ are called the **Fourier coefficients** of x and the sum $\sum_{n=1}^{\infty} \langle x | x_n \rangle x_n$ is called the **Fourier expansion** of x or the **Fourier series** for x .

Lemma H.2 (Perfect reconstruction). Let $\{x_n \in X \mid n \in \mathbb{N}\}$ be a set of vectors in a HILBERT SPACE $H \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \Delta | \nabla \rangle)$.

L E M $\left\{ \begin{array}{l} (1). \quad \{x_n\} \text{ is a BASIS for } H \\ (2). \quad \{x_n\} \text{ is ORTHONORMAL} \end{array} \right. \text{ and } \Rightarrow x \triangleq \underbrace{\sum_{n=1}^{\infty} \underbrace{\langle x | x_n \rangle}_{\text{Fourier coefficient}} x_n}_{\text{Fourier expansion}} \quad \forall x \in X$

PROOF:

$$\begin{aligned} \langle x | x_n \rangle &= \left\langle \sum_{m \in \mathbb{Z}} \alpha_m x_m | x_n \right\rangle && \text{by left hypothesis (1)} \\ &= \sum_{m \in \mathbb{Z}} \alpha_m \langle x_m | x_n \rangle && \text{by homogeneous property of } \langle \Delta | \nabla \rangle \quad (\text{Definition K.1 page 255}) \\ &= \sum_{m \in \mathbb{Z}} \alpha_m \delta_{n-m} && \text{by left hypothesis (2)} \quad (\text{Definition K.4 page 267}) \\ &= \alpha_n \end{aligned}$$



Proposition H.2. ²⁴ Let $\{x_n \in X \mid n \in \mathbb{N}\}$ be a set of vectors in a HILBERT SPACE $H \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \Delta | \nabla \rangle)$.

P R P $\|x\|^2 \triangleq \underbrace{\sum_{n=1}^{\infty} |\langle x | x_n \rangle|^2}_{\text{PARSEVAL FRAME}} \iff x \triangleq \underbrace{\sum_{n=1}^{\infty} \langle x | x_n \rangle x_n}_{\text{FOURIER EXPANSION (Definition H.10 page 216)}} \quad \forall x \in X$

PROOF:

²³ Fabian et al. (2010) page 27 (Theorem 1.55), Young (2001) page 6, Young (1980) page 6

²⁴ Han et al. (2007) pages 93–94 (Proposition 3.11)

1. Proof that *Parseval frame* \iff *Fourier expansion*

$$\begin{aligned}
 \|x\|^2 &\triangleq \langle x | x \rangle && \text{by definition of } \|\cdot\| && (\text{Definition L.1 page 271}) \\
 &= \left\langle \sum_{n=1}^{\infty} \langle x | x_n \rangle x | x_n \right\rangle && \text{by right hypothesis} \\
 &\stackrel{*}{=} \sum_{n=1}^{\infty} \langle x | x_n \rangle \langle x | x_n \rangle && \text{by property of } \langle \Delta | \nabla \rangle && (\text{Definition K.1 page 255}) \\
 &\stackrel{*}{=} \sum_{n=1}^{\infty} \langle x | x_n \rangle \langle x | x_n \rangle^* && \text{by property of } \langle \Delta | \nabla \rangle && (\text{Definition K.1 page 255}) \\
 &\stackrel{*}{=} \sum_{n=1}^{\infty} |\langle x | x_n \rangle|^2 && \text{by property of } \mathbb{C} && (\text{Definition J.7 page 253})
 \end{aligned}$$

2. Proof that *Parseval frame* \implies *Fourier expansion*

(a) Let $(e_n)_{n \in \mathbb{N}}$ be the *standard orthonormal basis* such that the n th element of e_n is 1 and all other elements are 0.

(b) Let M be an operator in H such that $Mx \triangleq \sum_{n=1}^{\infty} \langle x | x_n \rangle e_n$.

(c) lemma: M is *isometric*. Proof:

$$\begin{aligned}
 \|Mx\|^2 &= \left\| \sum_{n=1}^{\infty} \langle x | x_n \rangle e_n \right\|^2 && \text{by definition of } M && (\text{item (2b) page 217}) \\
 &= \sum_{n=1}^{\infty} \|\langle x | x_n \rangle e_n\|^2 && \text{by Pythagorean Theorem} && (\text{Theorem K.10 page 269}) \\
 &= \sum_{n=1}^{\infty} |\langle x | x_n \rangle|^2 \|e_n\|^2 && \text{by homogeneous property of } \|\cdot\| && (\text{Definition L.1 page 271}) \\
 &= \sum_{n=1}^{\infty} |\langle x | x_n \rangle|^2 && \text{by definition of orthonormal} && (\text{Definition K.4 page 267}) \\
 &= \|x\|^2 && \text{by Parseval frame hypothesis} \\
 \implies M &\text{ is isometric} && \text{by definition of isometric} && (\text{Definition O.10 page 323})
 \end{aligned}$$

(d) Let $(u_n)_{n \in \mathbb{N}}$ be an *orthonormal basis* for H .

(e) Proof for *Fourier expansion*:

$$\begin{aligned}
 x &= \sum_{n=1}^{\infty} \langle x | u_n \rangle u_n && \text{by Fourier expansion (Proposition H.3 page 220)} \\
 &= \sum_{n=1}^{\infty} \langle Mx | Mu_n \rangle u_n && \text{by (2c) lemma page 217 and Theorem O.23 page 324} \\
 &= \sum_{n=1}^{\infty} \left\langle \sum_{m=1}^{\infty} \langle x | x_m \rangle e_m | \sum_{k=1}^{\infty} \langle u_n | x_k \rangle e_k \right\rangle u_n && \text{by item (2b) page 217} \\
 &= \sum_{n=1}^{\infty} \sum_{m=1}^{\infty} \langle x | x_m \rangle \sum_{k=1}^{\infty} \langle u_n | x_k \rangle^* \langle e_m | e_k \rangle u_n && \text{by Definition K.1 page 255} \\
 &= \sum_{n=1}^{\infty} \sum_{m=1}^{\infty} \langle x | x_m \rangle \langle u_n | x_m \rangle^* u_n && \text{by item (2a) page 217 and Definition K.4 page 267}
 \end{aligned}$$

$$\begin{aligned}
 &= \sum_{n=1}^{\infty} \sum_{m=1}^{\infty} \langle \mathbf{x} | \mathbf{x}_m \rangle \langle \mathbf{x}_m | \mathbf{u}_n \rangle \mathbf{u}_n && \text{by Definition K.1 page 255} \\
 &= \sum_{m=1}^{\infty} \langle \mathbf{x} | \mathbf{x}_m \rangle \sum_{n=1}^{\infty} \langle \mathbf{x}_m | \mathbf{u}_n \rangle \mathbf{u}_n \\
 &= \sum_{m=1}^{\infty} \langle \mathbf{x} | \mathbf{x}_m \rangle \mathbf{x}_m && \text{by item (2d) page 217}
 \end{aligned}$$

⇒

When is a set of orthonormal vectors in a Hilbert space \mathbf{H} *total*? Theorem H.9 (next) offers some help.

Theorem H.9 (The Fourier Series Theorem). ²⁵ Let $\{\mathbf{x}_n \in X \mid n \in \mathbb{N}\}$ be a set of vectors in a HILBERT SPACE $\mathbf{H} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), (\triangle | \nabla))$ and let $\|\mathbf{x}\| \triangleq \sqrt{\langle \mathbf{x} | \mathbf{x} \rangle}$ (Definition K.2 page 261).

THM	$(A) \{\mathbf{x}_n\}$ is ORTHONORMAL in $\mathbf{H} \implies$ $\left(\begin{array}{l} (1). \quad (\text{span}\{\mathbf{x}_n\})^\perp = \mathbf{H} \\ \iff (2). \quad \langle \mathbf{x} \mathbf{y} \rangle \triangleq \sum_{n=1}^{\infty} \langle \mathbf{x} \mathbf{x}_n \rangle \langle \mathbf{y} \mathbf{x}_n \rangle^* \quad \forall \mathbf{x}, \mathbf{y} \in X \quad (\text{GENERALIZED PARSEVAL'S IDENTITY}) \\ \iff (3). \quad \ \mathbf{x}\ ^2 \triangleq \sum_{n=1}^{\infty} \langle \mathbf{x} \mathbf{x}_n \rangle ^2 \quad \forall \mathbf{x} \in X \quad (\text{PARSEVAL'S IDENTITY}) \\ \iff (4). \quad \mathbf{x} \triangleq \sum_{n=1}^{\infty} \langle \mathbf{x} \mathbf{x}_n \rangle \mathbf{x}_n \quad \forall \mathbf{x} \in X \quad (\text{FOURIER SERIES EXPANSION}) \end{array} \right)$
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PROOF:

1. Proof that (1) \implies (2):

$$\begin{aligned}
 \langle \mathbf{x} | \mathbf{y} \rangle &\triangleq \left\langle \sum_{n=1}^{\infty} \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n \mid \sum_{m=1}^{\infty} \langle \mathbf{y} | \mathbf{x}_m \rangle \mathbf{x}_m \right\rangle && \text{by (A) and (1)} \\
 &\triangleq \sum_{n=1}^{\infty} \langle \mathbf{x} | \mathbf{x}_n \rangle \left\langle \mathbf{x}_n \mid \sum_{m=1}^{\infty} \langle \mathbf{y} | \mathbf{x}_m \rangle \mathbf{x}_m \right\rangle && \text{by property of } \langle \cdot | \cdot \rangle \quad (\text{Definition K.1 page 255}) \\
 &\triangleq \sum_{n=1}^{\infty} \langle \mathbf{x} | \mathbf{x}_n \rangle \sum_{m=1}^{\infty} \langle \mathbf{y} | \mathbf{x}_m \rangle^* \langle \mathbf{x}_n | \mathbf{x}_m \rangle && \text{by property of } \langle \cdot | \cdot \rangle \quad (\text{Definition K.1 page 255}) \\
 &\triangleq \sum_{n=1}^{\infty} \langle \mathbf{x} | \mathbf{x}_n \rangle \sum_{m=1}^{\infty} \langle \mathbf{y} | \mathbf{x}_m \rangle^* \bar{\delta}_{mn} && \text{by (A)} \\
 &\triangleq \sum_{n=1}^{\infty} \langle \mathbf{x} | \mathbf{x}_n \rangle \langle \mathbf{y} | \mathbf{x}_n \rangle^* && \text{by definition of } \bar{\delta}_n \quad (\text{Definition K.3 page 267})
 \end{aligned}$$

²⁵ Bachman and Narici (1966) pages 149–155 (Theorem 9.12), Kubrusly (2001) pages 360–363 (Theorem 5.48), Aliprantis and Burkinshaw (1998) pages 298–299 (Theorem 34.2), Christensen (2003) page 57 (Theorem 3.4.2), Berberian (1961) pages 52–53 (Theorem II§8.3), Heil (2011) pages 34–35 (Theorem 1.50), Bracewell (1978) page 112 (Rayleigh's theorem)



2. Proof that (2) \implies (3):

$$\begin{aligned} \|\mathbf{x}\|^2 &\triangleq \langle \mathbf{x} | \mathbf{x} \rangle && \text{by definition of } \textit{induced norm} && (\text{Theorem K.4 page 260}) \\ &= \sum_{n=1}^{\infty} \langle \mathbf{x} | \mathbf{x}_n \rangle \langle \mathbf{x} | \mathbf{x}_n \rangle^* && \text{by (2)} \\ &= \sum_{n=1}^{\infty} |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 \end{aligned}$$

3. Proof that (3) \iff (4) *not* using (A): by Proposition H.2 page 216

4. Proof that (3) \implies (1) (proof by contradiction):

- (a) Suppose $\{\mathbf{x}_n\}$ is *not total*.
- (b) Then there must exist a vector \mathbf{y} in H such that the set $B \triangleq \{\mathbf{x}_n\} \cup \mathbf{y}$ is *orthonormal*.
- (c) Then $1 = \|\mathbf{y}\|^2 \neq \sum_{n=1}^{\infty} |\langle \mathbf{y} | \mathbf{x}_n \rangle|^2 = 0$.
- (d) But this contradicts (3), and so $\{\mathbf{x}_n\}$ must be *total* and (3) \implies (1).

5. Extraneous proof that (3) \implies (4) (this proof is not really necessary here):

$$\begin{aligned} \left\| \mathbf{x} - \sum_{n=1}^{\infty} \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n \right\|^2 &= \|\mathbf{x}\|^2 - \sum_{n=1}^{\infty} |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 && \text{by Bessel's Equality} && (\text{Theorem H.6 page 213}) \\ &= 0 && \text{by (3)} \\ \implies \mathbf{x} &\stackrel{*}{=} \sum_{n=1}^{\infty} \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n && \text{by definition of } \stackrel{*}{=} \end{aligned}$$

6. Extraneous proof that (A) \implies (4) (this proof is not really necessary here)

- (a) The sequence $\sum_{n=1}^N |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2$ is *monotonically increasing* in n .
- (b) By Bessel's inequality (page 214), the sequence is upper bounded by $\|\mathbf{x}\|^2$:

$$\sum_{n=1}^N |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 \leq \|\mathbf{x}\|^2$$

- (c) Because this sequence is both monotonically increasing and bounded in n , it must equal its bound in the limit as n approaches infinity:

$$\lim_{N \rightarrow \infty} \sum_{n=1}^N |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 = \|\mathbf{x}\|^2 \tag{H.1}$$

- (d) If we combine this result with *Bessel's Equality* (Theorem H.6 page 213) we have

$$\begin{aligned} \lim_{N \rightarrow \infty} \left\| \mathbf{x} - \sum_{n=1}^N \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n \right\|^2 &= \|\mathbf{x}\|^2 - \lim_{N \rightarrow \infty} \sum_{n=1}^N |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 && \text{by Bessel's Equality (Theorem H.6 page 213)} \\ &= \|\mathbf{x}\|^2 - \|\mathbf{x}\|^2 && \text{by equation (H.1) page 219} \\ &= 0 \end{aligned}$$



Proposition H.3 (Fourier expansion). Let $\{x_n \in X | n \in \mathbb{N}\}$ be a set of vectors in a HILBERT SPACE $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$.

P R P	$\underbrace{\{x_n\} \text{ is an ORTHONORMAL BASIS for } H}_{(A)}$ \Rightarrow $\underbrace{x \doteq \sum_{n=1}^{\infty} \alpha_n x_n}_{(1)} \iff \underbrace{\alpha_n = \langle x x_n \rangle}_{(2)}$
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PROOF:

1. Proof that (1) \implies (2): by Lemma H.2 page 216

2. Proof that (1) \Leftarrow (2):

$$\begin{aligned}
 \left\| x - \sum_{n=1}^{\infty} \alpha_n x_n \right\|^2 &= \left\| x - \sum_{n=1}^{\infty} \langle x | x_n \rangle x_n \right\|^2 && \text{by right hypothesis} \\
 &= \|x\|^2 - \sum_{n=1}^{\infty} |\langle x | x_n \rangle|^2 && \text{by Bessel's equality} \quad (\text{Theorem H.6 page 213}) \\
 &= 0 && \text{by Parseval's Identity} \quad (\text{Theorem H.9 page 218}) \\
 \stackrel{\text{def}}{\iff} x &\doteq \sum_{n=1}^{\infty} \langle x | x_n \rangle x_n && \text{by definition of strong convergence}
 \end{aligned}$$

\implies

Proposition H.4 (Riesz-Fischer Theorem). ²⁶ Let $\{x_n \in X | n \in \mathbb{N}\}$ be a set of vectors in a HILBERT SPACE $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$.

P R P	$\underbrace{\{x_n\} \text{ is an ORTHONORMAL BASIS for } H}_{(A)}$ \Rightarrow $\underbrace{\sum_{n=1}^{\infty} \alpha_n ^2 < \infty}_{(1)} \iff \underbrace{\exists x \in H \text{ such that } \alpha_n = \langle x x_n \rangle}_{(2)}$
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PROOF:

1. Proof that (1) \implies (2):

(a) If (1) is true, then let $x \doteq \sum_{n \in \mathbb{N}} \alpha_n x_n$.

(b) Then

$$\begin{aligned}
 \langle x | x_n \rangle &= \left\langle \sum_{m \in \mathbb{N}} \alpha_m x_m | x_n \right\rangle && \text{by definition of } x \\
 &= \sum_{m \in \mathbb{N}} \alpha_m \langle x_m | x_n \rangle && \text{by homogeneous property of } \langle \triangle | \nabla \rangle \quad (\text{Definition K.1 page 255}) \\
 &= \sum_{m \in \mathbb{N}} \alpha_m \bar{\delta}_{mn} && \text{by (A)} \\
 &= \sum_{m \in \mathbb{N}} \alpha_m && \text{by definition of } \bar{\delta} \quad (\text{Definition K.3 page 267})
 \end{aligned}$$

²⁶ Young (2001) page 6



2. Proof that (1) \iff (2):

$$\begin{aligned} \sum_{n \in \mathbb{N}} |\alpha_n|^2 &= \sum_{n \in \mathbb{N}} |\langle x | x_n \rangle|^2 && \text{by (2)} \\ &\leq \|x\|^2 && \text{by Bessel's Inequality} && \text{(Theorem H.7 page 214)} \\ &\leq \infty \end{aligned}$$



Theorem H.10. ²⁷

T H M All SEPARABLE HILBERT SPACES are ISOMORPHIC. That is,

$$\left\{ \begin{array}{l} \mathbf{X} \text{ is a separable} \\ \text{Hilbert space} \\ \mathbf{Y} \text{ is a separable} \\ \text{Hilbert space} \end{array} \right. \text{and} \quad \Rightarrow \quad \left\{ \begin{array}{l} \text{there is a BIJECTIVE operator } \mathbf{M} \in \mathbf{Y}^{\mathbf{X}} \text{ such that} \\ (1). \quad \mathbf{y} = \mathbf{M}\mathbf{x} \quad \forall \mathbf{x} \in \mathbf{X}, \mathbf{y} \in \mathbf{Y} \quad \text{and} \\ (2). \quad \|\mathbf{M}\mathbf{x}\| = \|\mathbf{x}\| \quad \forall \mathbf{x} \in \mathbf{X} \quad \text{and} \\ (3). \quad \langle \mathbf{M}\mathbf{x} | \mathbf{M}\mathbf{y} \rangle = \langle \mathbf{x} | \mathbf{y} \rangle \quad \forall \mathbf{x} \in \mathbf{X}, \mathbf{y} \in \mathbf{Y} \end{array} \right\}$$

PROOF:

1. Let $\mathbf{X} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \triangleright \rangle)$ be a *separable Hilbert space* with *orthonormal basis* $\{x_n|_{n \in \mathbb{N}}\}$. Let $\mathbf{Y} \triangleq (Y, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \triangleright \rangle)$ be a *separable Hilbert space* with *orthonormal basis* $\{y_n|_{n \in \mathbb{N}}\}$.

2. Proof that there exists *bijection* operator \mathbf{M} and its inverse \mathbf{M}^{-1} between $\{x_n\}$ and $\{y_n\}$:

- (a) Let \mathbf{M} be defined such that $y_n \triangleq \mathbf{M}x_n$.
- (b) Thus \mathbf{M} is a *bijection* between $\{x_n\}$ and $\{y_n\}$.
- (c) Because \mathbf{M} is a *bijection* between $\{x_n\}$ and $\{y_n\}$, \mathbf{M} has an inverse operator \mathbf{M}^{-1} between $\{x_n\}$ and $\{y_n\}$ such that $x_n = \mathbf{M}^{-1}y_n$.

3. Proof that \mathbf{M} and \mathbf{M}^{-1} are *bijection* operators between \mathbf{X} and \mathbf{Y} :

- (a) Proof that \mathbf{M} maps \mathbf{X} into \mathbf{Y} :

$$\begin{aligned} \mathbf{x} \in \mathbf{X} &\iff \mathbf{x} \triangleq \sum_{n \in \mathbb{N}} \langle \mathbf{x} | x_n \rangle x_n && \text{by Fourier expansion} && \text{(Theorem H.9 page 218)} \\ &\implies \exists \mathbf{y} \in \mathbf{Y} \quad \text{such that} \quad \langle \mathbf{y} | y_n \rangle = \langle \mathbf{x} | x_n \rangle && \text{by Riesz-Fischer Thm.} && \text{(Proposition H.4 page 220)} \\ &\implies \\ \mathbf{y} &= \sum_{n \in \mathbb{N}} \langle \mathbf{y} | y_n \rangle y_n && \text{by Fourier expansion} && \text{(Theorem H.9 page 218)} \\ &= \sum_{n \in \mathbb{N}} \langle \mathbf{x} | x_n \rangle y_n && \text{by Riesz-Fischer Thm.} && \text{(Proposition H.4 page 220)} \\ &= \sum_{n \in \mathbb{N}} \langle \mathbf{x} | x_n \rangle \mathbf{M}x_n && \text{by definition of } \mathbf{M} && \text{(item (2a) page 221)} \\ &= \mathbf{M} \sum_{n \in \mathbb{N}} \langle \mathbf{x} | x_n \rangle x_n && \text{by prop. of linear ops.} && \text{(Theorem O.1 page 304)} \\ &= \mathbf{M}\mathbf{x} && \text{by definition of } \mathbf{x} && \end{aligned}$$

²⁷ Young (2001) page 6

(b) Proof that \mathbf{M}^{-1} maps \mathbf{Y} into \mathbf{X} :

$$\begin{aligned}
 y \in \mathbf{Y} &\iff y = \sum_{n \in \mathbb{N}} \langle y | y_n \rangle y_n && \text{by Fourier expansion} \quad (\text{Theorem H.9 page 218}) \\
 &\implies \exists x \in \mathbf{X} \text{ such that } \langle x | x_n \rangle = \langle y | y_n \rangle \text{ by Riesz-Fischer Thm.} && (\text{Proposition H.4 page 220}) \\
 &\implies \\
 x &= \sum_{n \in \mathbb{N}} \langle x | x_n \rangle x_n && \text{by Fourier expansion} \quad (\text{Theorem H.9 page 218}) \\
 &= \sum_{n \in \mathbb{N}} \langle y | y_n \rangle x_n && \text{by Riesz-Fischer Thm.} \quad (\text{Proposition H.4 page 220}) \\
 &= \sum_{n \in \mathbb{N}} \langle y | y_n \rangle \mathbf{M}^{-1} y_n && \text{by definition of } \mathbf{M}^{-1} \quad (\text{item (2c) page 221}) \\
 &= \mathbf{M}^{-1} \sum_{n \in \mathbb{N}} \langle y | y_n \rangle y_n && \text{by prop. of linear ops.} \quad (\text{Theorem O.1 page 304}) \\
 &= \mathbf{M}^{-1} y && \text{by definition of } y
 \end{aligned}$$

4. Proof for (2):

$$\begin{aligned}
 \|\mathbf{M}x\|^2 &= \left\| \mathbf{M} \sum_{n \in \mathbb{N}} \langle x | x_n \rangle x_n \right\|^2 && \text{by Fourier expansion} \quad (\text{Theorem H.9 page 218}) \\
 &= \left\| \sum_{n \in \mathbb{N}} \langle x | x_n \rangle \mathbf{M}x_n \right\|^2 && \text{by property of linear operators} \quad (\text{Theorem O.1 page 304}) \\
 &= \left\| \sum_{n \in \mathbb{N}} \langle x | x_n \rangle y_n \right\|^2 && \text{by definition of } \mathbf{M} \quad (\text{item (2a) page 221}) \\
 &= \sum_{n \in \mathbb{N}} |\langle x | x_n \rangle|^2 && \text{by Parseval's Identity} \quad (\text{Proposition H.4 page 220}) \\
 &= \left\| \sum_{n \in \mathbb{N}} \langle x | x_n \rangle x_n \right\|^2 && \text{by Parseval's Identity} \quad (\text{Proposition H.4 page 220}) \\
 &= \|x\|^2 && \text{by Fourier expansion} \quad (\text{Theorem H.9 page 218})
 \end{aligned}$$

5. Proof for (3): by (2) and Theorem O.23 page 324



Theorem H.11.²⁸ Let \mathbf{H} be a HILBERT SPACE.

T	H	M	\mathbf{H} has a SCHAUDER BASIS	\iff	\mathbf{H} is SEPARABLE
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Theorem H.12.²⁹ Let \mathbf{H} be a HILBERT SPACE.

T	H	M	\mathbf{H} has an ORTHONORMAL BASIS	\iff	\mathbf{H} is SEPARABLE
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²⁸ Bachman et al. (2000) page 112 (3.4.8), Berberian (1961) page 53 (Theorem II§8.3)

²⁹ Kubrusly (2001) page 357 (Proposition 5.43)

H.6 Riesz bases in Hilbert spaces

Definition H.11. ³⁰ Let $\{x_n \in X | n \in \mathbb{N}\}$ be a set of vectors in a SEPARABLE HILBERT SPACE $H \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$

DEF $\{x_n\}$ is a **Riesz basis** for H if $\{x_n\}$ is EQUIVALENT (Definition H.8 page 211) to some ORTHONORMAL BASIS (Definition H.9 page 215) in H .

Definition H.12. ³¹ Let $(x_n \in X)_{n \in \mathbb{N}}$ be a sequence of vectors in a SEPARABLE HILBERT SPACE $H \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$.

DEF The sequence (x_n) is a **Riesz sequence** for H if

$$\exists A, B \in \mathbb{R}^+ \text{ such that } A \sum_{n=1}^{\infty} |\alpha_n|^2 \leq \left\| \sum_{n=1}^{\infty} \alpha_n x_n \right\|^2 \leq B \sum_{n=1}^{\infty} |\alpha_n|^2 \quad \forall (\alpha_n) \in \ell_{\mathbb{F}}^2.$$

Definition H.13. Let $X \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ be an INNER PRODUCT SPACE (Definition K.1 page 255).

DEF The sequences $(x_n \in X)_{n \in \mathbb{Z}}$ and $(y_n \in X)_{n \in \mathbb{Z}}$ are **biorthogonal** with respect to each other in X if $\langle x_n | y_m \rangle = \delta_{nm}$

Lemma H.3. ³² Let $\{x_n | n \in \mathbb{N}\}$ be a sequence in a HILBERT SPACE $X \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$. Let $\{y_n | n \in \mathbb{N}\}$ be a sequence in a HILBERT SPACE $Y \triangleq (Y, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$. Let

LEM $\left\{ \begin{array}{l} \text{(i). } \{x_n\} \text{ is TOTAL in } X \\ \text{(ii). } \text{There exists } A > 0 \text{ such that } A \sum_{n \in C} |\alpha_n|^2 \leq \left\| \sum_{n \in C} \alpha_n x_n \right\|^2 \text{ for finite } C \\ \text{(iii). } \text{There exists } B > 0 \text{ such that } \left\| \sum_{n=1}^{\infty} b_n y_n \right\|^2 \leq B \sum_{n=1}^{\infty} |b_n|^2 \quad \forall (b_n)_{n \in \mathbb{N}} \in \ell_{\mathbb{F}}^2 \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} \text{(1). } \mathbf{R}^\circ \text{ is a linear bounded operator that maps from } \text{span}\{x_n\} \text{ to } \text{span}\{y_n\} \\ \text{where } \mathbf{R}^\circ \sum_{n \in C} c_n x_n \triangleq \sum_{n \in C} c_n y_n, \text{ for some sequence } (c_n) \text{ and finite set } C \\ \text{(2). } \mathbf{R} \text{ has a unique extension to a bounded operator } \mathbf{R} \text{ that maps from } X \text{ to } Y \\ \text{(3). } \|\mathbf{R}^\circ\| \leq \frac{B}{A} \\ \text{(4). } \|\mathbf{R}\| \leq \frac{B}{A} \end{array} \right\}$

Theorem H.13. ³³ Let $\{x_n \in X | n \in \mathbb{N}\}$ be a set of vectors in a SEPARABLE HILBERT SPACE $H \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$.

THM $\left\{ \begin{array}{l} \{x_n\} \text{ is a RIESZ BASIS} \\ \text{for } H \end{array} \right\} \iff \left\{ \begin{array}{l} \text{(1). } \{x_n\} \text{ is TOTAL in } H \\ \text{(2). } \exists A, B \in \mathbb{R}^+ \text{ such that } A \sum_{n=1}^{\infty} |\alpha_n|^2 \leq \left\| \sum_{n=1}^{\infty} \alpha_n x_n \right\|^2 \leq B \sum_{n=1}^{\infty} |\alpha_n|^2 \quad \forall (\alpha_n) \in \ell_{\mathbb{F}}^2, \end{array} \right\}$

PROOF:

³⁰ Young (2001) page 27 (Definition 1.8.2), Christensen (2003) page 63 (Definition 3.6.1), Heil (2011) page 196 (Definition 7.9)

³¹ Christensen (2003) pages 66–68 (page 68 and (3.24) on page 66), Wojtaszczyk (1997) page 20 (Definition 2.6)

³² Christensen (2003) pages 65–66 (Lemma 3.6.5)

³³ Young (2001) page 27 (Theorem 1.8.9), Christensen (2003) page 66 (Theorem 3.6.6), Heil (2011) pages 197–198 (Theorem 7.13), Christensen (2008) pages 61–62 (Theorem 3.3.7)

1. Proof for (\implies) case:(a) Proof that *Riesz basis* hypothesis \implies (1): all bases for H are *total* in H .(b) Proof that *Riesz basis* hypothesis \implies (2):i. Let $(\mathbf{u}_n)_{n \in \mathbb{N}}$ be an *orthonormal basis* for H .ii. Let \mathbf{R} be a *bounded bijective* operator such that $\mathbf{x}_n = \mathbf{R}\mathbf{u}_n$.iii. Proof for upper bound B :

$$\begin{aligned}
 \left\| \sum_{n=1}^{\infty} \alpha_n \mathbf{x}_n \right\|^2 &= \left\| \sum_{n=1}^{\infty} \alpha_n \mathbf{R}\mathbf{u}_n \right\|^2 && \text{by definition of } \mathbf{R} && \text{(item (1(b)ii))} \\
 &= \left\| \mathbf{R} \sum_{n=1}^{\infty} \alpha_n \mathbf{u}_n \right\|^2 && \text{by Theorem O.1 page 304} \\
 &\leq \|\mathbf{R}\|^2 \left\| \sum_{n=1}^{\infty} \alpha_n \mathbf{u}_n \right\|^2 && \text{by Theorem O.6 page 310} \\
 &= \|\mathbf{R}\|^2 \sum_{n=1}^{\infty} \|\alpha_n \mathbf{u}_n\|^2 && \text{by Pythagorean Theorem} && \text{(Theorem K.10 page 269)} \\
 &= \|\mathbf{R}\|^2 \sum_{n=1}^{\infty} |\alpha_n|^2 \|\mathbf{u}_n\|^2 && \text{by homogeneous property of norms} && \text{(Definition L.1 page 271)} \\
 &= \underbrace{\|\mathbf{R}\|^2}_{B} \sum_{n=1}^{\infty} |\alpha_n|^2 && \text{by definition of orthonormality} && \text{(Definition K.4 page 267)}
 \end{aligned}$$

iv. Proof for lower bound A :

$$\begin{aligned}
 \left\| \sum_{n=1}^{\infty} \alpha_n \mathbf{x}_n \right\|^2 &= \frac{\|\mathbf{R}^{-1}\|^2}{\|\mathbf{R}^{-1}\|^2} \left\| \sum_{n=1}^{\infty} \alpha_n \mathbf{x}_n \right\|^2 && \text{because } \|\mathbf{R}^{-1}\| > 0 && \text{(Proposition O.1 page 308)} \\
 &\geq \frac{1}{\|\mathbf{R}^{-1}\|^2} \left\| \mathbf{R}^{-1} \sum_{n=1}^{\infty} \alpha_n \mathbf{x}_n \right\|^2 && \text{by Theorem O.6 page 310} \\
 &= \frac{1}{\|\mathbf{R}^{-1}\|^2} \left\| \mathbf{R}^{-1} \sum_{n=1}^{\infty} \alpha_n \mathbf{R}\mathbf{u}_n \right\|^2 && \text{by definition of } \mathbf{R} && \text{(item (1(b)ii) page 224)} \\
 &= \frac{1}{\|\mathbf{R}^{-1}\|^2} \left\| \mathbf{R}^{-1} \mathbf{R} \sum_{n=1}^{\infty} \alpha_n \mathbf{u}_n \right\|^2 && \text{by property of linear operators} && \text{(Theorem O.1 page 304)} \\
 &= \frac{1}{\|\mathbf{R}^{-1}\|^2} \left\| \sum_{n=1}^{\infty} \alpha_n \mathbf{u}_n \right\|^2 && \text{by definition of inverse op.} && \text{(Definition O.2 page 303)} \\
 &= \frac{1}{\|\mathbf{R}^{-1}\|^2} \sum_{n=1}^{\infty} \|\alpha_n \mathbf{u}_n\|^2 && \text{by Pythagorean Theorem} && \text{(Theorem K.10 page 269)} \\
 &= \frac{1}{\|\mathbf{R}^{-1}\|^2} \sum_{n=1}^{\infty} |\alpha_n|^2 \|\mathbf{u}_n\|^2 && \text{by } \|\cdot\| \text{ homogeneous prop.} && \text{(Definition L.1 page 271)} \\
 &= \underbrace{\frac{1}{\|\mathbf{R}^{-1}\|^2} \sum_{n=1}^{\infty} |\alpha_n|^2}_{A} && \text{by def. of orthonormality} && \text{(Definition K.4 page 267)}
 \end{aligned}$$

2. Proof for (\implies) case:

- (a) Let $\{u_n\}_{n \in \mathbb{N}}$ be an *orthonormal basis* for H .
- (b) Using (2) and Lemma H.3 (page 223), construct an bounded extension operator R such that $Ru_n = x_n$ for all $n \in \mathbb{N}$.
- (c) Using (2) and Lemma H.3 (page 223), construct an bounded extension operator S such that $Sx_n = u_n$ for all $n \in \mathbb{N}$.
- (d) Then, $RVx = VRx \implies V = R^{-1}$, and so R is a bounded invertible operator
- (e) and $\{x_n\}$ is a *Riesz sequence*.



Theorem H.14. ³⁴ Let $H \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \Delta | \nabla \rangle)$ be a SEPARABLE HILBERT SPACE.

T H M	$\left\{ \begin{array}{l} (x_n \in H)_{n \in \mathbb{Z}} \text{ is a} \\ \text{RIESZ BASIS for } H \end{array} \right\} \implies \left\{ \begin{array}{l} \text{There exists } (y_n \in H)_{n \in \mathbb{Z}} \text{ such that} \\ (1). \quad (x_n) \text{ and } (y_n) \text{ are BIORTHOGONAL and} \\ (2). \quad (y_n) \text{ is also a RIESZ BASIS for } H \text{ and} \\ (3). \quad \exists B > A > 0 \text{ such that} \\ A \sum_{n=1}^{\infty} a_n ^2 \leq \left\ \sum_{n=1}^{\infty} a_n x_n \right\ ^2 = \left\ \sum_{n=1}^{\infty} a_n y_n \right\ ^2 \leq B \sum_{n=1}^{\infty} a_n ^2 \\ \forall (a_n)_{n \in \mathbb{N}} \in \ell_{\mathbb{F}}^2 \end{array} \right\}$
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PROOF:

1. Proof for (1):

- (a) Let e_n be the *unit vector* in H such that the n th element of e_n is 1 and all other elements are 0.
- (b) Let M be an operator on H such that $Me_n = x_n$.
- (c) Note that M is *isometric*, and as such $\|Mx\| = \|x\| \quad \forall x \in H$.
- (d) Let $y_n \triangleq (M^{-1})^*$.
- (e) Then,

$$\begin{aligned}
 \langle y_n | x_m \rangle &= \left\langle (M^{-1})^* e_n | M e_m \right\rangle \\
 &= \langle e_n | M^{-1} M e_m \rangle \\
 &= \langle e_n | e_m \rangle \\
 &= \bar{\delta}_{nm} \\
 \implies \{x_n\} \text{ and } \{y_n\} \text{ are biorthogonal} &\qquad \text{by Definition K.4 page 267}
 \end{aligned}$$

³⁴ Wojtaszczyk (1997) page 20 (Lemma 2.7(a))

2. Proof for (3):

$$\begin{aligned}
 \left\| \sum_{n \in \mathbb{Z}} \alpha_n y_n \right\| &= \left\| \sum_{n \in \mathbb{Z}} \alpha_n (\mathbf{M}^{-1})^* e_n \right\| && \text{by definition of } y_n && \text{(Proposition 1d page 225)} \\
 &= \left\| (\mathbf{M}^{-1})^* \sum_{n \in \mathbb{Z}} \alpha_n e_n \right\| && \text{by property of linear ops.} \\
 &= \left\| \sum_{n \in \mathbb{Z}} \alpha_n e_n \right\| && \text{because } (\mathbf{M}^{-1})^* \text{ is isometric} && \text{(Definition O.10 page 323)} \\
 &= \left\| \mathbf{M} \sum_{n \in \mathbb{Z}} \alpha_n e_n \right\| && \text{because } \mathbf{M} \text{ is isometric} && \text{(Definition O.10 page 323)} \\
 &= \left\| \sum_{n \in \mathbb{Z}} \alpha_n \mathbf{M} e_n \right\| && \text{by property of linear operators} \\
 &= \left\| \sum_{n \in \mathbb{Z}} \alpha_n x_n \right\| && \text{by definition of } \mathbf{M} \\
 \implies \{y_n\} &\text{ is a Riesz basis} && \text{by left hypothesis}
 \end{aligned}$$

3. Proof for (2): by (3) and definition of *Riesz basis* (Definition H.11 page 223)



Proposition H.5.³⁵ Let $\{x_n | n \in \mathbb{N}\}$ be a set of vectors in a HILBERT SPACE $\mathbf{H} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \triangleright \rangle)$.

P R P	$ \left\{ \begin{array}{l} \{x_n\} \text{ is a RIESZ BASIS for } \mathbf{H} \text{ with} \\ A \sum_{n=1}^{\infty} a_n ^2 \leq \left\ \sum_{n=1}^{\infty} a_n x_n \right\ ^2 \leq B \sum_{n=1}^{\infty} a_n ^2 \\ \forall \{a_n\} \in \ell_{\mathbb{F}}^2 \end{array} \right\} \Rightarrow \underbrace{\left\{ \begin{array}{l} \{x_n\} \text{ is a FRAME for } \mathbf{H} \text{ with} \\ \underbrace{\frac{1}{B} \ x\ ^2 \leq \sum_{n=1}^{\infty} \langle x x_n \rangle ^2 \leq \frac{1}{A} \ x\ ^2}_{\text{STABILITY CONDITION}} \\ \forall x \in \mathbf{H} \end{array} \right\}}_{\text{STABILITY CONDITION}} $
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PROOF:

1. Let $\{y_n | n \in \mathbb{N}\}$ be a *Riesz basis* that is *biorthonormal* to $\{x_n | n \in \mathbb{N}\}$ (Theorem H.14 page 225).

2. Let $x \triangleq \sum_{n=1}^{\infty} a_n y_n$.

3. lemma:

$$\begin{aligned}
 \sum_{n=1}^{\infty} |\langle x | x_n \rangle|^2 &= \sum_{n=1}^{\infty} \left| \left\langle \sum_{m=1}^{\infty} a_m y_m | x_n \right\rangle \right|^2 && \text{by definition of } x && \text{(item (2) page 226)} \\
 &= \sum_{n=1}^{\infty} \left| \sum_{m=1}^{\infty} a_m \langle y_m | x_n \rangle \right|^2 && \text{by homogeneous property of } \langle \triangle | \triangleright \rangle && \text{(Definition K.1 page 255)} \\
 &= \sum_{n=1}^{\infty} \left| \sum_{m=1}^{\infty} a_m \bar{\delta}_{mn} \right|^2 && \text{by definition of biorthonormal} && \text{(Definition H.13 page 223)} \\
 &= \sum_{n=1}^{\infty} |a_n|^2 && \text{by definition of } \bar{\delta} && \text{(Definition K.3 page 267)}
 \end{aligned}$$

³⁵ Igari (1996) page 220 (Lemma 9.8), Wojtaszczyk (1997) pages 20–21 (Lemma 2.7(a))

4. Then

$$\begin{aligned}
 A \sum_{n=1}^{\infty} |a_n|^2 &\leq \left\| \sum_{n=1}^{\infty} a_n \mathbf{x}_n \right\|^2 \leq B \sum_{n=1}^{\infty} |a_n|^2 && \text{by definition of } \{\mathbf{y}_n\} \text{ (item (1) page 226)} \\
 \implies A \sum_{n=1}^{\infty} |a_n|^2 &\leq \left\| \sum_{n=1}^{\infty} a_n \mathbf{y}_n \right\|^2 \leq B \sum_{n=1}^{\infty} |a_n|^2 && \text{by definition of } \{\mathbf{y}_n\} \text{ (item (1) page 226)} \\
 \implies A \sum_{n=1}^{\infty} |a_n|^2 &\leq \|\mathbf{x}\|^2 \leq B \sum_{n=1}^{\infty} |a_n|^2 && \text{by definition of } \mathbf{x} \text{ (item (2) page 226)} \\
 \implies A \sum_{n=1}^{\infty} |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 &\leq \|\mathbf{x}\|^2 \leq B \sum_{n=1}^{\infty} |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 && \text{by (3) lemma} \\
 \implies \frac{1}{B} \|\mathbf{x}\|^2 &\leq \sum_{n=1}^{\infty} |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 \leq \frac{1}{A} \|\mathbf{x}\|^2
 \end{aligned}$$

⇒

Theorem H.15 (Battle-Lemarié orthogonalization). ³⁶ Let $\tilde{f}(\omega)$ be the FOURIER TRANSFORM (Definition P.2 page 333) of a function $f \in L^2_{\mathbb{R}}$.

T H M	$ \left\{ \begin{array}{l} 1. \quad \left\{ \mathbf{T}^n f \mid n \in \mathbb{Z} \right\} \text{ is a RIESZ BASIS for } L^2_{\mathbb{R}} \quad \text{and} \\ 2. \quad \tilde{f}(\omega) \triangleq \frac{\tilde{g}(\omega)}{\sqrt{2\pi \sum_{n \in \mathbb{Z}} \tilde{g}(\omega + 2\pi n) ^2}} \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} \left\{ \mathbf{T}^n f \mid n \in \mathbb{Z} \right\} \\ \text{is an ORTHONORMAL BASIS for } L^2_{\mathbb{R}} \end{array} \right\} $
-------------	---

PROOF:

1. Proof that $\{\mathbf{T}^n f \mid n \in \mathbb{Z}\}$ is orthonormal:

$$\begin{aligned}
 \tilde{S}_{\phi\phi}(\omega) &= 2\pi \sum_{n \in \mathbb{Z}} |\tilde{f}(\omega + 2\pi n)|^2 && \text{by Theorem ?? page ??} \\
 &= 2\pi \sum_{n \in \mathbb{Z}} \left| \frac{\tilde{g}(\omega + 2\pi n)}{\sqrt{2\pi \sum_{m \in \mathbb{Z}} |\tilde{g}(\omega + 2\pi(m-n))|^2}} \right|^2 && \text{by left hypothesis} \\
 &= \sum_{n \in \mathbb{Z}} \left| \frac{\tilde{g}(\omega + 2\pi n)}{\sqrt{\sum_{m \in \mathbb{Z}} |\tilde{g}(\omega + 2\pi m)|^2}} \right|^2 \\
 &= \sum_{n \in \mathbb{Z}} \left| \frac{1}{\sqrt{\sum_{m \in \mathbb{Z}} |\tilde{g}(\omega + 2\pi m)|^2}} \right|^2 |\tilde{g}(\omega + 2\pi n)|^2 \\
 &= \frac{1}{\sum_{m \in \mathbb{Z}} |\tilde{g}(\omega + 2\pi m)|^2} \sum_{n \in \mathbb{Z}} |\tilde{g}(\omega + 2\pi n)|^2 \\
 &= 1 \\
 \implies \{f_n \mid n \in \mathbb{Z}\} &\text{ is orthonormal} && \text{by Theorem ?? page ??}
 \end{aligned}$$

³⁶ Wojtaszczyk (1997) page 25 (Remark 2.4), Vidakovic (1999), page 71, Mallat (1989), page 72, Mallat (1999), page 225, Daubechies (1992) page 140 (5.3.3)

2. Proof that $\{T^n f | n \in \mathbb{Z}\}$ is a basis for V_0 : by Lemma H.1 page 211.



H.7 Frames in Hilbert spaces

Definition H.14. ³⁷ Let $\{x_n \in X | n \in \mathbb{N}\}$ be a set of vectors in a HILBERT SPACE $H \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \Delta | \nabla \rangle)$.

The set $\{x_n\}$ is a **frame** for H if (STABILITY CONDITION)

$$\exists A, B \in \mathbb{R}^+ \text{ such that } A \|x\|^2 \leq \sum_{n=1}^{\infty} |\langle x | x_n \rangle|^2 \leq B \|x\|^2 \quad \forall x \in X.$$

The quantities A and B are **frame bounds**.

The quantity A' is the **optimal lower frame bound** if

$$A' = \sup \{A \in \mathbb{R}^+ | A \text{ is a lower frame bound}\}.$$

The quantity B' is the **optimal upper frame bound** if

$$B' = \inf \{B \in \mathbb{R}^+ | B \text{ is an upper frame bound}\}.$$

A frame is a **tight frame** if $A = B$.

A frame is a **normalized tight frame** (or a **Parseval frame**) if $A = B = 1$.

A frame $\{x_n | n \in \mathbb{N}\}$ is an **exact frame** if for some $m \in \mathbb{Z}$, $\{x_n | n \in \mathbb{N}\} \setminus \{x_m\}$ is NOT a frame.

A frame is a *Parseval frame* (Definition H.14) if it satisfies *Parseval's Identity* (Theorem H.9 page 218). All orthonormal bases are Parseval frames (Theorem H.9 page 218); but not all Parseval frames are orthonormal bases.

Definition H.15. Let $\{x_n\}$ be a **frame** (Definition H.14 page 228) for the HILBERT SPACE $H \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \Delta | \nabla \rangle)$. Let S be an OPERATOR on H .

D E F S is a **frame operator** for $\{x_n\}$ if $Sf(x) = \sum_{n \in \mathbb{Z}} \langle f | x_n \rangle x_n \quad \forall f \in H$.

Theorem H.16. ³⁸ Let S be a FRAME OPERATOR (Definition H.15 page 228) of a FRAME $\{x_n\}$ (Definition H.14 page 228) for the HILBERT SPACE $H \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \Delta | \nabla \rangle)$.

T H M

- (1). S is INVERTIBLE.
- (2). $f(x) = \sum_{n \in \mathbb{Z}} \langle f | S^{-1} x_n \rangle x_n = \sum_{n \in \mathbb{Z}} \langle f | x_n \rangle S^{-1} x_n \quad \forall f \in H$

Theorem H.17. ³⁹ Let $\{x_n \in X | n=1,2,\dots,N\}$ be a set of vectors in a HILBERT SPACE $H \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \Delta | \nabla \rangle)$.

T H M $\{x_n\}$ is a FRAME for $\text{span}\{x_n\}$.

PROOF:

³⁷ Young (2001) pages 154–155, Christensen (2003) page 88 (Definitions 5.1.1, 5.1.2), Heil (2011) pages 204–205 (Definition 8.2), Jørgensen et al. (2008) page 267 (Definition 12.22), Duffin and Schaeffer (1952) page 343, Daubechies et al. (1986), page 1272

³⁸ Christensen (2008) pages 100–102 (Theorem 5.1.7)

³⁹ Christensen (2003) page 3



1. Upper bound: Proof that there exists B such that $\sum_{n=1}^N |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 \leq B \|\mathbf{x}\|^2 \quad \forall \mathbf{x} \in \mathcal{H}$:

$$\begin{aligned} \sum_{n=1}^N |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 &\leq \sum_{n=1}^N \langle \mathbf{x}_n | \mathbf{x}_n \rangle \langle \mathbf{x} | \mathbf{x} \rangle \quad \text{by Cauchy-Schwarz inequality (Theorem K.2 page 256)} \\ &= \underbrace{\left\{ \sum_{n=1}^N \|\mathbf{x}_n\|^2 \right\}}_B \|\mathbf{x}\|^2 \end{aligned}$$

2. Lower bound: Proof that there exists A such that $A \|\mathbf{x}\|^2 \leq \sum_{n=1}^N |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 \quad \forall \mathbf{x} \in \mathcal{H}$:

$$\begin{aligned} \sum_{n=1}^N |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 &= \sum_{n=1}^N \left| \left\langle \mathbf{x}_n | \frac{\mathbf{x}}{\|\mathbf{x}\|} \right\rangle \right|^2 \|\mathbf{x}\|^2 \\ &\geq \underbrace{\left(\inf_y \left\{ \sum_{n=1}^N |\langle \mathbf{x}_n | \mathbf{y} \rangle|^2 \mid \|\mathbf{y}\| = 1 \right\} \right)}_A \|\mathbf{x}\|^2 \end{aligned}$$

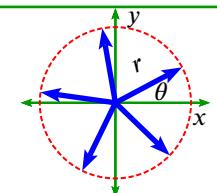
Example H.1. Let $(\mathbb{R}^2, +, \cdot, (\mathbb{R}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ be an inner product space with $\left\langle \begin{bmatrix} x_1 \\ y_1 \end{bmatrix} | \begin{bmatrix} x_2 \\ y_2 \end{bmatrix} \right\rangle \triangleq x_1 x_2 + y_1 y_2$. Let \mathbf{S} be the *frame operator* (Definition H.15 page 228) with *inverse* \mathbf{S}^{-1} .

EX

Let $N \in \{3, 4, 5, \dots\}$, $\theta \in \mathbb{R}$, and $r \in \mathbb{R}^+$ ($r > 0$).

Let $\mathbf{x}_n \triangleq r \begin{bmatrix} \cos(\theta + 2n\pi/N) \\ \sin(\theta + 2n\pi/N) \end{bmatrix} \quad \forall n \in \{0, 1, \dots, N-1\}$.

Then, $(\mathbf{x}_0, \mathbf{x}_1, \dots, \mathbf{x}_{N-1})$ is a **tight frame** for \mathbb{R}^2 with *frame bound* $A = \frac{Nr^2}{2}$.



Moreover, $\mathbf{S} = \frac{Nr^2}{2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$, $\mathbf{S}^{-1} = \frac{2}{Nr^2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$, and $\mathbf{v} = \frac{2}{Nr^2} \sum_{n=0}^{N-1} \langle \mathbf{v} | \mathbf{x}_n \rangle \mathbf{x}_n \quad \forall \mathbf{v} \in \mathbb{R}^2$.

PROOF:

1. Proof that $(\mathbf{x}_0, \mathbf{x}_1, \dots, \mathbf{x}_{N-1})$ is a *tight frame* with *frame bound* $A = \frac{Nr^2}{2}$: Let $\mathbf{v} \triangleq (x, y) \in \mathbb{R}^2$.

$$\begin{aligned} \sum_{n=0}^{N-1} |\langle \mathbf{v} | \mathbf{x}_n \rangle|^2 &\triangleq \sum_{n=0}^{N-1} \left| \mathbf{v}^H \begin{bmatrix} \cos\left(\theta + \frac{2n\pi}{N}\right) \\ \sin\left(\theta + \frac{2n\pi}{N}\right) \end{bmatrix} \right|^2 && \text{by definitions of } \mathbf{v} \text{ of } \langle \mathbf{y} | \mathbf{x} \rangle \\ &\triangleq \sum_{n=0}^{N-1} r^2 \left| x \cos\left(\theta + \frac{2n\pi}{N}\right) + y \sin\left(\theta + \frac{2n\pi}{N}\right) \right|^2 && \text{by definition of } \mathbf{y}^H \mathbf{x} \text{ operation} \\ &= r^2 x^2 \sum_{n=0}^{N-1} \cos^2\left(\theta + \frac{2n\pi}{N}\right) + r^2 y^2 \sum_{n=0}^{N-1} \sin^2\left(\theta + \frac{2n\pi}{N}\right) + r^2 xy \sum_{n=0}^{N-1} \cos\left(\theta + \frac{2n\pi}{N}\right) \sin\left(\theta + \frac{2n\pi}{N}\right) \\ &= r^2 x^2 \frac{N}{2} + r^2 y^2 \frac{N}{2} + r^2 xy 0 && \text{by Corollary ?? page ??} \\ &= (x^2 + y^2) \frac{Nr^2}{2} = \underbrace{\left(\frac{Nr^2}{2} \right)}_A \mathbf{v}^H \mathbf{v} \triangleq \underbrace{\left(\frac{Nr^2}{2} \right)}_A \|\mathbf{v}\|^2 && \text{by definition of } \|\mathbf{v}\| \end{aligned}$$

2. Proof that $\mathbf{S} = \frac{Nr^2}{2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$:

(a) Let $e_1 \triangleq \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and $e_2 \triangleq \begin{bmatrix} 0 \\ 1 \end{bmatrix}$.

(b) lemma: $\mathbf{S}e_1 = \frac{Nr^2}{2}e_1$. Proof:

$$\begin{aligned}\mathbf{S}e_1 &= \sum_{n=0}^{N-1} \langle e_1 | \mathbf{x}_n \rangle \mathbf{x}_n \\ &= \sum_{n=0}^{N-1} r \cos\left(\theta + \frac{2n\pi}{N}\right) r \begin{bmatrix} \cos\left(\theta + \frac{2n\pi}{N}\right) \\ \sin\left(\theta + \frac{2n\pi}{N}\right) \end{bmatrix} = r^2 \sum_{n=0}^{N-1} \begin{bmatrix} \cos^2\left(\theta + \frac{2n\pi}{N}\right) \\ \cos\left(\theta + \frac{2n\pi}{N}\right) \sin\left(\theta + \frac{2n\pi}{N}\right) \end{bmatrix} \\ &= r^2 \begin{bmatrix} N/2 \\ 0 \end{bmatrix} = \frac{Nr^2}{2}e_1 \quad \text{by Summation around unit circle (Corollary ?? page ??)}$$

(c) lemma: $\mathbf{S}e_2 = \frac{Nr^2}{2}e_2$. Proof:

$$\begin{aligned}\mathbf{S}e_2 &= \sum_{n=0}^{N-1} \langle e_2 | \mathbf{x}_n \rangle \mathbf{x}_n \\ &= \sum_{n=0}^{N-1} r \sin\left(\theta + \frac{2n\pi}{N}\right) r \begin{bmatrix} \cos\left(\theta + \frac{2n\pi}{N}\right) \\ \sin\left(\theta + \frac{2n\pi}{N}\right) \end{bmatrix} = r^2 \sum_{n=0}^{N-1} \begin{bmatrix} \sin\left(\theta + \frac{2n\pi}{N}\right) \cos\left(\theta + \frac{2n\pi}{N}\right) \\ \sin^2\left(\theta + \frac{2n\pi}{N}\right) \end{bmatrix} \\ &= r^2 \begin{bmatrix} 0 \\ N/2 \end{bmatrix} = \frac{Nr^2}{2}e_2 \quad \text{by Summation around unit circle (Corollary ?? page ??)}$$

(d) Complete the proof of item (2) using Eigendecomposition $\mathbf{S} = \mathbf{Q}\Lambda\mathbf{Q}^{-1}$:

$$\mathbf{S}e_1 = \frac{Nr^2}{2}e_1 \quad \text{by (2c) lemma}$$

$\Rightarrow e_1$ is an eigenvector of \mathbf{S} with eigenvalue $\frac{Nr^2}{2}$

$$\mathbf{S}e_2 = \frac{Nr^2}{2}e_2 \quad \text{by (2c) lemma}$$

$\Rightarrow e_2$ is an eigenvector of \mathbf{S} with eigenvalue $\frac{Nr^2}{2}$

$$\underbrace{\mathbf{S} = \underbrace{\begin{bmatrix} 1 & 1 \\ e_1 & e_2 \\ 1 & 1 \end{bmatrix}}_{\mathbf{Q}} \underbrace{\begin{bmatrix} \frac{Nr^2}{2} & 0 \\ 0 & \frac{Nr^2}{2} \end{bmatrix}}_{\Lambda} \underbrace{\begin{bmatrix} 1 & 1 \\ e_1 & e_2 \\ 1 & 1 \end{bmatrix}}_{\mathbf{Q}^{-1}}^{-1}}_{\text{Eigendecomposition of } \mathbf{S}} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} \frac{Nr^2}{2} & 0 \\ 0 & \frac{Nr^2}{2} \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}^{-1} = \frac{Nr^2}{2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

3. Proof that $\mathbf{S}^{-1} = \frac{2}{Nr^2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$:

$$\mathbf{S}\mathbf{S}^{-1} = \frac{Nr^2}{2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \frac{2}{Nr^2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \triangleq \mathbf{I}_2 \quad \text{by item (2)}$$

$$\mathbf{S}^{-1}\mathbf{S} = \frac{2}{Nr^2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \frac{Nr^2}{2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \triangleq \mathbf{I}_2 \quad \text{by item (2)}$$

4. Proof that $\mathbf{v} = \frac{2}{Nr^2} \sum_{n=0}^{N-1} (\mathbf{v}^H \mathbf{x}_n) \mathbf{x}_n$:

$$\mathbf{v} = \sum_{n=0}^{N-1} \langle \mathbf{v} | \mathbf{S}^{-1} \mathbf{x}_n \rangle \mathbf{x}_n = \sum_{n=0}^{N-1} \left\langle \mathbf{v} \mid \frac{2}{Nr^2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \mathbf{x}_n \right\rangle \mathbf{x}_n \quad \text{by item (3)}$$

$$= \frac{2}{Nr^2} \sum_{n=0}^{N-1} \langle \mathbf{v} | \mathbf{x}_n \rangle \mathbf{x}_n = \frac{2}{Nr^2} \sum_{n=0}^{N-1} (\mathbf{v}^H \mathbf{x}_n) \mathbf{x}_n \quad \text{by definition of } \langle \mathbf{y} | \mathbf{x} \rangle$$



Example H.2 (Peace Frame/Mercedes Frame). ⁴⁰ Let $(\mathbb{R}^2, +, \cdot, (\mathbb{R}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ be an inner product space with $\langle (x_1, y_1) | (x_2, y_2) \rangle \triangleq x_1y_1 + x_2y_2$. Let \mathbf{S} be the *frame operator* (Definition H.15 page 228) with inverse \mathbf{S}^{-1} .

E X Let $\mathbf{x}_1 \triangleq \frac{1}{2} \begin{bmatrix} 0 \\ 2 \end{bmatrix}$, $\mathbf{x}_2 \triangleq \frac{1}{2} \begin{bmatrix} -\sqrt{3} \\ -1 \end{bmatrix}$, and $\mathbf{x}_3 \triangleq \frac{1}{2} \begin{bmatrix} \sqrt{3} \\ -1 \end{bmatrix}$.

Then, $(\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3)$ is a **tight frame** for \mathbb{R}^2 with *frame bound* $A = \frac{3}{2}$.

Moreover, $\mathbf{S} = \frac{3}{2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$, $\mathbf{S}^{-1} = \frac{2}{3} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$,

and $\mathbf{v} = \frac{2}{3} \sum_{n=1}^3 \langle \mathbf{v} | \mathbf{x}_n \rangle \mathbf{x}_n \triangleq \frac{2}{3} \sum_{n=1}^3 (\mathbf{v}^H \mathbf{x}_n) \mathbf{x}_n \quad \forall \mathbf{v} \in \mathbb{R}^2$.

PROOF:

1. This frame is simply a special case of the frame presented in Example H.1 (page 229) with $r = 1$, $N = 3$, and $\theta = \pi/2$.

2. Let's give it a try! Let $\mathbf{v} \triangleq \begin{bmatrix} 1 \\ 1 \end{bmatrix}$.

$$\begin{aligned}
 \sum_{n=1}^3 \langle \mathbf{v} | \mathbf{S}^{-1} \mathbf{x}_n \rangle \mathbf{x}_n &= \frac{2}{3} \sum_{n=1}^3 (\mathbf{v}^H \mathbf{x}_n) \mathbf{x}_n && \text{by Example H.1 page 229} \\
 &= (\mathbf{v}^H \mathbf{x}_1) \mathbf{x}_1 + (\mathbf{v}^H \mathbf{x}_2) \mathbf{x}_2 + (\mathbf{v}^H \mathbf{x}_3) \mathbf{x}_3 \\
 &= \frac{2}{3} \left(\left(\mathbf{v}^H \frac{1}{2} \begin{bmatrix} 0 \\ 2 \end{bmatrix} \right) \mathbf{x}_1 + \left(\mathbf{v}^H \frac{1}{2} \begin{bmatrix} -\sqrt{3} \\ -1 \end{bmatrix} \right) \mathbf{x}_2 + \left(\mathbf{v}^H \frac{1}{2} \begin{bmatrix} \sqrt{3} \\ -1 \end{bmatrix} \right) \mathbf{x}_3 \right) \\
 &= \frac{2}{3} \cdot \frac{1}{2} \left(\left(\mathbf{v}^H \begin{bmatrix} 0 \\ 2 \end{bmatrix} \right) \mathbf{x}_1 + \left(\mathbf{v}^H \begin{bmatrix} -\sqrt{3} \\ -1 \end{bmatrix} \right) \mathbf{x}_2 + \left(\mathbf{v}^H \begin{bmatrix} \sqrt{3} \\ -1 \end{bmatrix} \right) \mathbf{x}_3 \right) \\
 &= \frac{1}{3} \left((2) \frac{1}{2} \begin{bmatrix} 0 \\ 2 \end{bmatrix} + (-\sqrt{3}-1) \frac{1}{2} \begin{bmatrix} -\sqrt{3} \\ -1 \end{bmatrix} + (\sqrt{3}-1) \frac{1}{2} \begin{bmatrix} \sqrt{3} \\ -1 \end{bmatrix} \right) \\
 &= \frac{1}{6} \left[\begin{array}{lcl} 2(0) & + & (-\sqrt{3}-1)(-\sqrt{3}) & + & (\sqrt{3}-1)(\sqrt{3}) \\ 2(2) & + & (-\sqrt{3}-1)(-1) & + & (\sqrt{3}-1)(-1) \end{array} \right] \\
 &= \frac{1}{6} \left[\begin{array}{lcl} 0 & + & (3+\sqrt{3}) & + & (3-\sqrt{3}) \\ 4 & + & (1+\sqrt{3}) & + & (1-\sqrt{3}) \end{array} \right] = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \triangleq \mathbf{v}
 \end{aligned}$$



In Example H.1 (page 229) and Example H.2 (page 231), the frame operator \mathbf{S} and its inverse \mathbf{S}^{-1} were computed. In general however, it is not always necessary or even possible to compute these, as illustrated in Example H.3 (next).

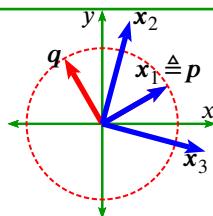
Example H.3. ⁴¹ Let $(\mathbb{R}^2, +, \cdot, (\mathbb{R}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ be an inner product space with $\langle (x_1, y_1) | (x_2, y_2) \rangle \triangleq x_1y_1 + x_2y_2$. Let \mathbf{S} be the *frame operator* (Definition H.15 page 228) with inverse \mathbf{S}^{-1} .

⁴⁰ Heil (2011) pages 204–205 ($r = 1$ case), Byrne (2005) page 80 ($r = 1$ case), Han et al. (2007) page 91 (Example 3.9, $r = \sqrt{2}/3$ case)

⁴¹ Christensen (2003) pages 7–8 (?)

**E
X**

Let p and q be orthonormal vectors in $\mathbf{X} \triangleq \text{span}\{p, q\}$.
 Let $x_1 \triangleq p$, $x_2 \triangleq p + q$, and $x_3 \triangleq p - q$.
 Then, $\{x_1, x_2, x_3\}$ is a frame for \mathbf{X} with frame bounds $A = 0$ and $B = 5$.



Moreover,
 $S^{-1}x_1 = \frac{1}{3}p$ and
 $S^{-1}x_2 = \frac{1}{3}p + \frac{1}{2}q$ and
 $S^{-1}x_3 = \frac{1}{3}p - \frac{1}{2}q$.

PROOF:

1. Proof that (x_1, x_2, x_3) is a frame with frame bounds $A = 0$ and $B = 5$:

$$\begin{aligned} \sum_{n=1}^3 |\langle v | x_n \rangle|^2 &\triangleq |\langle v | p \rangle|^2 + |\langle v | p + q \rangle|^2 + |\langle v | p - q \rangle|^2 && \text{by definitions of } x_1, x_2, \text{ and } x_3 \\ &= |\langle v | p \rangle|^2 + |\langle v | p \rangle + \langle v | q \rangle|^2 + |\langle v | p \rangle - \langle v | q \rangle|^2 && \text{by additivity of } \langle \Delta | \nabla \rangle \text{ (Definition K.1 page 255)} \\ &= |\langle v | p \rangle|^2 + (|\langle v | p \rangle|^2 + |\langle v | q \rangle|^2 + \langle v | p \rangle \langle v | q \rangle^* + \langle v | q \rangle \langle v | p \rangle^*) \\ &\quad + (|\langle v | p \rangle|^2 + |\langle v | q \rangle|^2 - \langle v | p \rangle \langle v | q \rangle^* - \langle v | q \rangle \langle v | p \rangle^*) \\ &= 3|\langle v | p \rangle|^2 + 2|\langle v | q \rangle|^2 \\ &\leq 3\|v\| \|p\| + 2\|v\| \|q\| && \text{by CS Inequality (Theorem K.2 page 256)} \\ &= \|v\| (3\|p\| + 2\|q\|) \\ &= \boxed{5\|v\|} && \text{by orthonormality of } p \text{ and } q \end{aligned}$$

2. lemma: $Sp = 3p$, $Sq = 2q$, $S^{-1}p = \frac{1}{3}p$, and $S^{-1}q = \frac{1}{2}q$. Proof:

$$\begin{aligned} Sp &\triangleq \sum_{n=1}^3 \langle p | x_n \rangle x_n \\ &= \langle p | p \rangle p + \langle p | p + q \rangle (p + q) + \langle p | p - q \rangle (p - q) \\ &= (1)p + (1+0)(p+q) + (1-0)(p-q) \\ &= 3p \\ \implies S^{-1}p &= \frac{1}{3}p \\ Sq &\triangleq \sum_{n=1}^3 \langle q | x_n \rangle x_n \\ &= \langle q | p \rangle p + \langle q | p + q \rangle (p + q) + \langle q | p - q \rangle (p - q) \\ &= (0)q + (0+1)(p+q) + (0-1)(p-q) \\ &= 2q \\ \implies S^{-1}q &= \frac{1}{2}q \end{aligned}$$

3. Remark: Without knowing p and q , from (2) lemma it follows that it is not possible to compute S or S^{-1} explicitly.

4. Proof that $S^{-1}x_1 = \frac{1}{3}p$, $S^{-1}x_2 = \frac{1}{3}p + \frac{1}{2}q$ and $S^{-1}x_3 = \frac{1}{3}p - \frac{1}{2}q$:

$$\begin{aligned} S^{-1}x_1 &\triangleq S^{-1}p && \text{by definition of } x_1 \\ &= \frac{1}{3}p && \text{by (2) lemma} \\ S^{-1}x_2 &\triangleq S^{-1}(p + q) && \text{by definition of } x_2 \\ &= \frac{1}{3}p + \frac{1}{2}q && \text{by (2) lemma} \end{aligned}$$



$$\begin{aligned} \mathbf{S}^{-1}\mathbf{x}_3 &\triangleq \mathbf{S}^{-1}(\mathbf{p} - \mathbf{q}) && \text{by definition of } \mathbf{x}_2 \\ &= \frac{1}{3}\mathbf{p} - \frac{1}{2}\mathbf{q} && \text{by (2) lemma} \end{aligned}$$

5. Check that $\mathbf{v} = \sum_n \langle \mathbf{v} | \mathbf{x}_n \rangle \mathbf{x}_n = \langle \mathbf{v} | \mathbf{p} \rangle \mathbf{p} + \langle \mathbf{v} | \mathbf{q} \rangle \mathbf{q}$:

$$\begin{aligned} \mathbf{v} &= \sum_{n=1}^3 \langle \mathbf{v} | \mathbf{S}^{-1}\mathbf{x}_n \rangle \mathbf{x}_n \\ &= \langle \mathbf{v} | \mathbf{S}^{-1}\mathbf{p} \rangle \mathbf{p} + \langle \mathbf{v} | \mathbf{S}^{-1}(\mathbf{p} + \mathbf{q}) \rangle (\mathbf{p} + \mathbf{q}) + \langle \mathbf{v} | \mathbf{S}^{-1}(\mathbf{p} - \mathbf{q}) \rangle (\mathbf{p} - \mathbf{q}) \\ &= \left\langle \mathbf{v} \mid \frac{1}{3}\mathbf{p} \right\rangle \mathbf{p} + \left\langle \mathbf{v} \mid \frac{1}{3}\mathbf{p} + \frac{1}{2}\mathbf{q} \right\rangle (\mathbf{p} + \mathbf{q}) + \left\langle \mathbf{v} \mid \frac{1}{3}\mathbf{p} - \frac{1}{2}\mathbf{q} \right\rangle (\mathbf{p} - \mathbf{q}) \\ &= \left(\frac{1}{3} + \frac{1}{3} + \frac{1}{3} \right) \langle \mathbf{v} | \mathbf{p} \rangle \mathbf{p} + \left(\frac{1}{3} - \frac{1}{3} \right) \langle \mathbf{v} | \mathbf{p} \rangle \mathbf{q} + \left(\frac{1}{2} - \frac{1}{2} \right) \langle \mathbf{v} | \mathbf{q} \rangle \mathbf{p} + \left(\frac{1}{2} + \frac{1}{2} \right) \langle \mathbf{v} | \mathbf{q} \rangle \mathbf{q} \\ &= \langle \mathbf{v} | \mathbf{p} \rangle \mathbf{p} + \langle \mathbf{v} | \mathbf{q} \rangle \mathbf{q} \end{aligned}$$



I.1 Subspaces of a linear space

Linear spaces (Definition G.1 page 193) can be decomposed into a collection of *linear subspaces* (Definition I.1 page 236). Often such a collection along with an *order relation* forms a *lattice*.

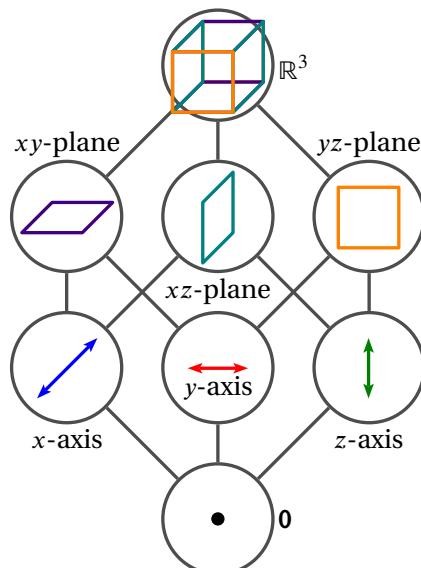
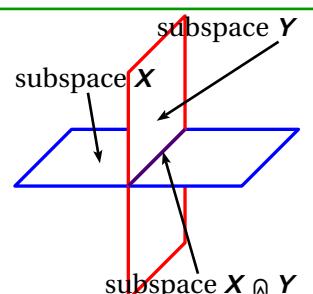


Figure I.1: lattice of subspaces of \mathbb{R}^3 (Example I.1 page 235)

EX

Example I.1. The 3-dimensional Euclidean space \mathbb{R}^3 contains the 2-dimensional xy -plane and xz -plane subspaces, which in turn both contain the 1-dimensional x -axis subspace. These subspaces are illustrated in the figure to the right and in Figure I.1 (page 235).



Definition I.1. ¹ Let $\Omega \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ be a LINEAR SPACE (Definition G.1 page 193).

D E F A ttuple $(Y, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ is a **linear subspace** of Ω if

1. $Y \neq \emptyset$ (Y must contain at least one element) and
2. $Y \subseteq X$ (Y is a subset of X) and
3. $x, y \in Y \implies x + y \in Y$ (closed under vector addition) and
4. $x \in Y$ and $\alpha \in \mathbb{F} \implies \alpha x \in Y$ (closed under scalar-vector multiplication).

A linear subspace is also called a **linear manifold**.

Every *linear space* (Definition G.1 page 193) X has at least two *linear subspaces*—itself and $\mathbf{0}$ (Proposition I.1 page 236), called the *trivial linear space*. The *linear span* (Definition H.2 page 205) of every subset of a linear linear space is a subspace (Proposition I.2 page 237). Every *linear subspace* contains the “zero” vector $\mathbf{0}$, and is *convex* (Definition M.6 page 282, Proposition I.3 page 237).

Proposition I.1. ² Let $X \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ and $\mathbf{0} \triangleq (\{\mathbf{0}\}, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$.

P R P $\left\{ \begin{array}{l} X \text{ is a LINEAR SPACE} \\ (\text{Definition G.1 page 193}) \end{array} \right\} \implies \left\{ \begin{array}{l} 1. \mathbf{0} \text{ is a LINEAR SUBSPACE of } X \text{ and} \\ 2. X \text{ is a LINEAR SUBSPACE of } X \end{array} \right\}$

PROOF: For a structure to be a linear subspace of X , it must satisfy the requirements of Definition I.1 (page 236).

1. Proof that $\{\mathbf{0}\}$ is a linear subspace:

(a) Note that $\{\mathbf{0}\} \neq \emptyset$.

(b) Proof that $x, y \in \{\mathbf{0}\} \implies x + y \in \{\mathbf{0}\}$:

$$\begin{aligned} x + y &= \mathbf{0} + \mathbf{0} && \text{by } x, y \in \{\mathbf{0}\} \text{ hypothesis} \\ &= \mathbf{0} \\ &\in \{\mathbf{0}\} \end{aligned}$$

(c) Proof that $x \in \{\mathbf{0}\}, \alpha \in \mathbb{F} \implies \alpha x \in \{\mathbf{0}\}$:

$$\begin{aligned} \alpha x &= \alpha \mathbf{0} && \text{by } x \in \{\mathbf{0}\} \text{ hypothesis} \\ &= \mathbf{0} && \text{by definition of } \mathbf{0} \\ &\in \{\mathbf{0}\} \end{aligned}$$

2. Proof that Ω is a linear subspace of itself:

(a) Proof that $X \neq \emptyset$:

$$X \neq \emptyset$$

(b) Proof that $x, y \in X \implies x + y \in X$:

$$x + y \in \{\mathbf{0}\} \quad \text{because } + : X \times X \rightarrow X \text{ (} X \text{ is closed under vector addition)}$$

(c) Proof that $x \in X, \alpha \in \mathbb{F} \implies \alpha x \in X$:

$$\alpha x \in X \quad \text{because } \cdot : \mathbb{F} \times X \rightarrow X \text{ (} X \text{ is closed under scalar-vector multiplication)}$$

¹ Michel and Herget (1993) page 81 (Definition 3.2.1), Berberian (1961) page 13 (Definition I.5.1), Halmos (1958), page 16

² Michel and Herget (1993) pages 81–83, Haaser and Sullivan (1991) page 43





Proposition I.2. ³ Let $\mathbf{X} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ be a LINEAR SPACE (Definition G.1 page 193). Let span be the LINEAR SPAN of a set Y in \mathbf{X} .

P R P	$\left\{ \begin{array}{l} Y \text{ is a SUBSET of the set } X \\ (Y \subseteq X) \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} \text{span}Y \text{ is a LINEAR SUBSPACE of } \mathbf{X}. \end{array} \right\}$
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Proposition I.3. ⁴ Let $\mathbf{X} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ be a LINEAR SPACE and $\mathbf{0}$ the zero vector of \mathbf{X} .

P R P	$\left\{ \begin{array}{l} Y \text{ is a LINEAR SUBSPACE of } \mathbf{X} \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} 1. \quad \mathbf{0} \in Y \\ 2. \quad Y \text{ is CONVEX in } \mathbf{X} \end{array} \right. \text{ and } \right\}$
-------------	---

PROOF:

$$\begin{aligned} Y \text{ is a subspace} &\implies \exists(\alpha y) \in Y \quad \forall \alpha \in \mathbb{F} && \text{by Definition I.1 page 236} \\ &\implies \exists 0 \in Y && \text{because } \alpha = 0 \in \mathbb{F} \end{aligned}$$

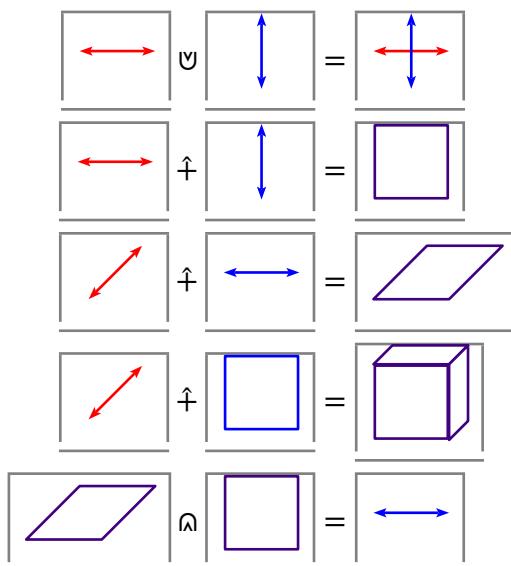
$$\begin{aligned} Y \text{ is a linear subspace} &\implies x + y \in Y \quad \forall x, y \in Y \\ &\implies \lambda x + (1 - \lambda)y \in Y \quad \forall x, y \in Y \\ &\implies Y \text{ is convex} \end{aligned}$$



Definition I.2. ⁵ Let $\mathbf{X} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ and $\mathbf{Y} \triangleq (Y, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ be LINEAR SUBSPACES (Definition I.1 page 236) of a LINEAR SPACE (Definition G.1 page 193) $\Omega \triangleq (\Omega, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$.

DEF	$X \hat{+} Y \triangleq (\{x + y x \in X \text{ and } y \in Y\}, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ (Minkowski addition)
	$X \uplus Y \triangleq (X \cup Y, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ (subspace union)
	$X \Cap Y \triangleq (X \cap Y, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ (subspace intersection)

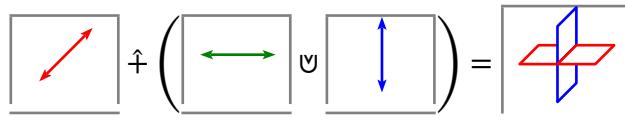
Example I.2. Some examples of operations on subspaces in \mathbb{R}^3 are illustrated next:



³ Michel and Herget (1993) page 86

⁴ Michel and Herget (1993) page 81

⁵ Wedderburn (1907) page 79

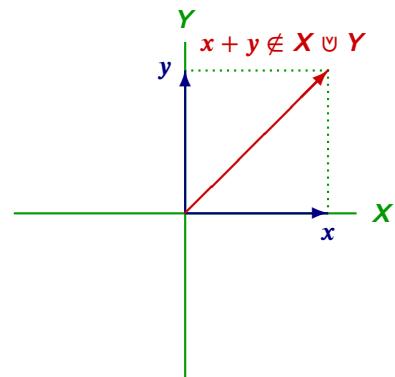


Remark I.1.

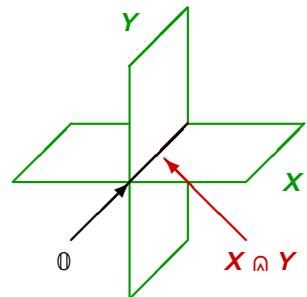
Notice the similarities between the properties of linear subspaces in a linear space (Proposition I.4 page 238) and the properties of closed sets in a topological space:

linear subspaces	closed sets
\emptyset	\emptyset
Ω	Ω
$X \hat{+} Y$	$X \cup Y$
$\bigcap_{n=1}^N X_n$	$\bigcap_{\gamma \in \Gamma} X_\gamma$

One key difference is that the union of two linear subspaces is not in general a linear subspace. For example, if x is the vector $[1 0]$ in the x direction linear subspace of \mathbb{R}^2 and y is the vector $[0 1]$ in the y direction linear subspace, then $x + y$ is not in the union of the two linear subspaces (it is not on the x axis or y axis but rather at $(1, 1)$).⁶



In general, the set of all linear subspaces of a linear space Ω is *not* closed under the subspace union (\cup) operation; that is, the union of two linear subspaces is *not* necessarily a linear subspace. However the set is closed under Minkowski sum ($\hat{+}$) and subspace intersection (\cap). Proposition I.4 (next) shows four useful objects are always subspaces. Some of these in Euclidean space \mathbb{R}^3 are illustrated to the right.



Proposition I.4. ⁷ Let X be a LINEAR SPACE (Definition G.1 page 193).

P R P	$\left\{ X_n \mid n=1,2,\dots,N \right\}$ are LINEAR SUBSPACES of X $\right\} \Rightarrow \left\{ \begin{array}{l} 1. X_1 \hat{+} X_2 \hat{+} \dots \hat{+} X_N \text{ is a LINEAR SUBSPACE of } X \\ \text{and} \\ 2. X_1 \cap X_2 \cap \dots \cap X_N \text{ is a LINEAR SUBSPACE of } X \end{array} \right.$
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PROOF: For a structure to be a linear subspace of X , it must satisfy the requirements of Definition I.1 (page 236).

1. Proof that $X_1 \hat{+} X_2 \hat{+} \dots \hat{+} X_N$ is a *linear subspace* (proof by induction):

- (a) proof for $N = 1$ case: by left hypothesis.
- (b) proof for $N = 2$ case:

⁶ Michel and Herget (1993) page 82

⁷ Michel and Herget (1993) pages 81–83

i. proof that $\mathbf{X}_1 \hat{+} \mathbf{X}_2 \neq \emptyset$:

$$\begin{aligned}\mathbf{X}_1 \hat{+} \mathbf{X}_2 &= \{\mathbf{v} + \mathbf{w} \mid \mathbf{v} \in \mathbf{X}_1 \text{ and } \mathbf{w} \in \mathbf{Y}\} && \text{by Definition I.2 page 237} \\ &\supseteq \{\mathbf{v} + \mathbf{w} \mid \mathbf{v} \in \{\mathbf{0}\} \subseteq \mathbf{X}_1 \text{ and } \mathbf{w} \in \{\mathbf{0}\} \subseteq \mathbf{Y}\} \\ &= \{\mathbf{0} + \mathbf{0}\} \\ &= \{\mathbf{0}\} \\ &\neq \emptyset\end{aligned}$$

ii. proof that $\mathbf{x}, \mathbf{y} \in \mathbf{X}_1 \hat{+} \mathbf{X}_2 \implies \mathbf{x} + \mathbf{y} \in \mathbf{X}_1 \hat{+} \mathbf{X}_2$:

$$\begin{aligned}\mathbf{x} + \mathbf{y} &= (\mathbf{v}_1 + \mathbf{w}_1) + (\mathbf{v}_2 + \mathbf{w}_2) && \text{by } \mathbf{x}, \mathbf{y} \in \mathbf{X}_1 \hat{+} \mathbf{X}_2 \text{ hypothesis} \\ &= \underbrace{(\mathbf{v}_1 + \mathbf{v}_2)}_{\text{in } \mathbf{X}_1} + \underbrace{(\mathbf{w}_1 + \mathbf{w}_2)}_{\text{in } \mathbf{X}_2 \text{ because } \mathbf{X}_2 \text{ is a linear subspace}} && \text{by Definition G.1 page 193} \\ &\in \{\mathbf{v} + \mathbf{w} \mid \mathbf{v} \in \mathbf{X}_1 \text{ and } \mathbf{w} \in \mathbf{Y}\} \\ &= \mathbf{X}_1 \hat{+} \mathbf{X}_2 && \text{by Definition I.2 page 237}\end{aligned}$$

iii. proof that $\mathbf{v} \in \mathbf{X}_1 \hat{+} \mathbf{X}_2, \alpha \in F \implies \alpha\mathbf{v} \in \mathbf{X}_1 \hat{+} \mathbf{X}_2$:

$$\begin{aligned}\alpha\mathbf{x} &= \alpha(\mathbf{v}_1 + \mathbf{w}_1) && \text{by } \mathbf{x} \in \mathbf{X}_1 \hat{+} \mathbf{X}_2 \text{ hypothesis} \\ &= \underbrace{\alpha\mathbf{v}_1}_{\text{in } \mathbf{X}_1} + \underbrace{\alpha\mathbf{w}_1}_{\text{in } \mathbf{X}_2 \text{ because } \mathbf{X}_2 \text{ is a linear subspace}} && \text{by Definition G.1 page 193} \\ &\in \{\mathbf{v} + \mathbf{w} \mid \mathbf{v} \in \mathbf{X}_1 \text{ and } \mathbf{w} \in \mathbf{Y}\} \\ &= \mathbf{X}_1 \hat{+} \mathbf{X}_2 && \text{by Definition I.2 page 237}\end{aligned}$$

(c) Proof that [N case] \implies [N + 1 case]:

$$\begin{aligned}\mathbf{X}_1 \hat{+} \mathbf{X}_2 \hat{+} \cdots \hat{+} \mathbf{X}_{N+1} &= \underbrace{(\mathbf{X}_1 \hat{+} \mathbf{X}_2 \hat{+} \cdots \hat{+} \mathbf{X}_N)}_{\text{linear subspace by } N \text{ case hypothesis}} \hat{+} \mathbf{X}_{N+1} \\ &\implies \text{linear subspace by } N = 2 \text{ case (item (1b) page 238)}\end{aligned}$$

2. Proof that $\mathbf{X}_1 \wedge \mathbf{X}_2 \wedge \cdots \wedge \mathbf{X}_N$ is a *linear subspace* (proof by induction):

(a) proof for $N = 1$ case: \mathbf{X}_1 is a linear subspace by left hypothesis.

(b) Proof for $N = 2$ case:

i. proof that $\mathbf{X} \wedge \mathbf{Y} \neq \emptyset$:

$$\begin{aligned}\mathbf{X} \wedge \mathbf{Y} &= \{\mathbf{x} \in X \mid \mathbf{x} \in \mathbf{X} \text{ and } \mathbf{w} \in \mathbf{Y}\} \\ &\supseteq \{\mathbf{x} \in X \mid \mathbf{x} \in \{\mathbf{0}\} \subseteq \mathbf{X} \text{ and } \mathbf{w} \in \{\mathbf{0}\} \subseteq \mathbf{Y}\} \\ &= \{\mathbf{0} + \mathbf{0}\} \\ &= \{\mathbf{0}\} \\ &\neq \emptyset\end{aligned}$$

ii. proof that $\mathbf{x}, \mathbf{y} \in \mathbf{X} \wedge \mathbf{Y} \implies \mathbf{x} + \mathbf{y} \in \mathbf{X} \wedge \mathbf{Y}$:

$$\begin{aligned}\mathbf{x}, \mathbf{y} \in \mathbf{X} \wedge \mathbf{Y} &\implies \mathbf{x}, \mathbf{y} \in \mathbf{X} \text{ and } \mathbf{x}, \mathbf{y} \in \mathbf{Y} \\ &\implies \mathbf{x} + \mathbf{y} \in \mathbf{X} \text{ and } \mathbf{x} + \mathbf{y} \in \mathbf{Y} \quad \text{because } \mathbf{X} \text{ and } \mathbf{Y} \text{ are linear subspaces} \\ &\implies \mathbf{x} + \mathbf{y} \in \mathbf{X} \wedge \mathbf{Y}\end{aligned}$$

iii. proof that $\mathbf{v} \in \mathbf{X} \wedge \mathbf{Y}, \alpha \in F \implies \alpha\mathbf{v} \in \mathbf{X} \wedge \mathbf{Y}$:

$$\begin{aligned}\mathbf{x} \in \mathbf{X} \wedge \mathbf{Y} &\implies \mathbf{x} \in \mathbf{X} \text{ and } \mathbf{x} \in \mathbf{Y} \\ &\implies \alpha\mathbf{x} \in \mathbf{X} \text{ and } \alpha\mathbf{x} \in \mathbf{Y} \quad \text{because } \mathbf{X} \text{ and } \mathbf{Y} \text{ are linear subspaces} \\ &\implies \alpha\mathbf{x} \in \mathbf{X} \wedge \mathbf{Y}\end{aligned}$$

(c) Proof that [N case] \implies [$N + 1$ case]:

$$\begin{aligned} \mathbf{X}_1 \wedge \mathbf{X}_2 \wedge \cdots \wedge \mathbf{X}_{N+1} &= \underbrace{(\mathbf{X}_1 \wedge \mathbf{X}_2 \wedge \cdots \wedge \mathbf{X}_N)}_{\text{linear subspace by } N \text{ case hypothesis}} \wedge \mathbf{X}_{N+1} \\ &\implies \text{linear subspace by } N = 2 \text{ case (item (2b) page 239)} \end{aligned}$$

⇒

Every linear subspace contains the zero vector $\mathbb{0}$ (Proposition I.3 page 237). But if a pair of linear subspaces of a linear space \mathbf{X} *only* have $\mathbb{0}$ in common, then any vector in \mathbf{X} can be *uniquely* represented by a single vector from each of the two subspaces (next).

Theorem I.1.⁸ Let $\mathbf{X} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ and $\mathbf{Y} \triangleq (Y, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ be LINEAR SUBSPACES (Definition I.1 page 236) of a LINEAR SPACE (Definition G.1 page 193) $\Omega \triangleq (\Omega, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$.

T H M	$X \cap Y = \{\mathbb{0}\} \iff \left\{ \begin{array}{l} \text{for every } u \in X \hat{+} Y \text{ there exist } x \in X \text{ and } y \in Y \text{ such that} \\ \quad \text{1. } u = x + y \quad \text{and} \\ \quad \text{2. } x \text{ and } y \text{ are UNIQUE.} \end{array} \right\}$
-------------	--

PROOF:

1. Proof that $X \cap Y = \{\mathbb{0}\} \implies \text{unique } x, y$:

Suppose that x and y are not unique, but rather $u = x_1 + y_1 = x_2 + y_2$ where $x_1, x_2 \in X$ and $y_1, y_2 \in Y$.

$$\begin{aligned} u = x_1 + y_1 = x_2 + y_2 &\implies \underbrace{x_1 - x_2}_{\in X} = \underbrace{y_2 - y_1}_{\in Y} \\ &\implies x_1 - x_2, y_2 - y_1 \in X \cap Y \\ &\implies x_1 - x_2 = y_2 - y_1 = \mathbb{0} \quad \text{by left hypothesis} \\ &\implies x_1 = x_2 \quad \text{and} \quad y_2 = y_1 \\ &\implies x \text{ and } y \text{ are unique} \end{aligned}$$

2. Proof that $X \cap Y = \{\mathbb{0}\} \iff \text{unique } x, y$:

$$\begin{aligned} u &= x + y \\ &= x + y + y - y && \text{for some vector } y \in X \cap Y \\ &= \underbrace{(x + y)}_{\in X} + \underbrace{(y - y)}_{\in Y} && \text{because } x \in X \text{ and } y \in X \cap Y \dots \\ &\implies x \text{ and } y \text{ are not unique if } y \neq \mathbb{0} \\ &\implies y = \mathbb{0} && \text{by right hypothesis} \\ &\implies X \cap Y = \{\mathbb{0}\} \end{aligned}$$

⇒

Theorem I.2.⁹ Let Ω be a linear subspace and \mathcal{Z}^Ω the set of closed linear subspaces of Ω .

T H M	$(\mathcal{Z}^\Omega, \hat{+}, \wedge, \mathbb{0}, \Omega; \subseteq)$ is a LATTICE. In particular
	$\begin{array}{lll} X \hat{+} X &= X & X \wedge X = X \quad \forall X \in \mathcal{Z}^\Omega \\ X \hat{+} Y &= Y \hat{+} X & X \wedge Y = Y \wedge X \quad \forall X, Y \in \mathcal{Z}^\Omega \\ (X \hat{+} Y) \hat{+} Z &= X \hat{+} (Y \hat{+} Z) & (X \wedge Y) \wedge Z = X \wedge (Y \wedge Z) \quad \forall X, Y, Z \in \mathcal{Z}^\Omega \\ X \hat{+} (X \wedge Y) &= X & X \wedge (X \hat{+} Y) = X \quad \forall X, Y \in \mathcal{Z}^\Omega \end{array}$

PROOF: These results follow directly from the properties of lattices.

⇒

⁸ Michel and Herget (1993) page 83 (Theorem 3.2.12), Kubrusly (2001) page 67 (Theorem 2.14)

⁹ Iturrioz (1985) pages 56–57



I.2 Subspaces of an inner product space

Definition I.3. ¹⁰ Let $\Omega \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ be an INNER PRODUCT SPACE (Definition K.1 page 255).

DEF

The **orthogonal complement** A^\perp in Ω of a set $A \subseteq X$ is

$$A^\perp \triangleq \{x \in X \mid \langle x | y \rangle = 0 \quad \forall y \in A\}.$$

The expression $A^{\perp\perp}$ is defined as $(A^\perp)^\perp$.

Proposition I.5. ¹¹ Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ be an INNER PRODUCT SPACE (Definition K.1 page 255).

PRP

$$A \subseteq B \implies B^\perp \subseteq A^\perp \quad \forall A, B \in 2^X \quad (\text{ANTITONE})$$

PROOF:

$$\begin{aligned} B^\perp &\triangleq \{x \in X \mid \langle x | y \rangle = 0 \quad \forall y \in B\} && \text{by definition of } B^\perp \text{ (Definition I.3 page 241)} \\ &\subseteq \{x \in X \mid \langle x | y \rangle = 0 \quad \forall y \in A\} && \text{by } A \subseteq B \text{ hypothesis} \\ &= A^\perp && \text{by definition of } A^\perp \text{ (Definition I.3 page 241)} \end{aligned}$$



Every *linear space* X contains $\mathbf{0}$ and X as *linear subspaces* (Proposition I.1 page 236). If X is also an *inner product space*, then $\mathbf{0}$ and X are *orthogonal complements* of each other (next proposition).

Proposition I.6. ¹² Let $\Omega \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ be an INNER PRODUCT SPACE (Definition K.1 page 255) and $\mathbf{0}$ the VECTOR ADDITIVE IDENTITY ELEMENT (Definition G.1 page 193) in Ω .

PRP

$$\begin{aligned} 1. \quad \{\mathbf{0}\}^\perp &= X \\ 2. \quad X^\perp &= \{\mathbf{0}\} \end{aligned}$$

PROOF:

$$\begin{aligned} \{\mathbf{0}\}^\perp &= \{x \in X \mid \langle x | y \rangle = 0 \quad \forall y \in \{\mathbf{0}\}\} && \text{by definition of } \perp \text{ (Definition I.3 page 241)} \\ &= \{x \in X \mid \langle x | \mathbf{0} \rangle = 0\} \\ &= X \\ X^\perp &= \{x \in X \mid \langle x | y \rangle = 0 \quad \forall y \in X\} && \text{by definition of } \perp \text{ (Definition I.3 page 241)} \\ &= \{x \in X \mid \langle x | x \rangle = 0\} \\ &= \{\mathbf{0}\} \end{aligned}$$



For any set A contained in a linear space X , $A^{\perp\perp}$ is a *linear subspace*, and it is the smallest linear subspace containing the set A ($A^{\perp\perp} = \text{span}A$, next theorem). In the case that A is a *linear subspace* rather than just a subset, results simplify significantly (next corollary).

¹⁰ Berberian (1961) page 59 (Definition III.2.1), Michel and Herget (1993) page 382, Kubrusly (2001) page 328

¹¹ Berberian (1961) page 60 (Theorem III.2.2), Kubrusly (2011) page 326

¹² Kubrusly (2011) page 326, Michel and Herget (1993) page 383

Theorem I.3. ¹³ Let $\Omega \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ be an INNER PRODUCT SPACE (Definition K.1 page 255). Let $\text{span}A$ be the span of a set A (Definition H.2 page 205).

THEM

$$\left\{ \begin{array}{l} A \text{ is a subset of } X \\ (A \subseteq X) \end{array} \right\} \implies \left\{ \begin{array}{l} 1. \quad A \cap A^\perp = \begin{cases} \{\emptyset\} & \text{if } \emptyset \in A \\ \emptyset & \text{if } \emptyset \notin A \end{cases} \text{ and} \\ 2. \quad A \subseteq A^{\perp\perp} = \text{span}A \text{ and} \\ 3. \quad A^\perp = A^{\perp\perp\perp} = A^{\perp^-} = A^{-\perp} = (\text{span}A)^\perp \text{ and} \\ 4. \quad A^\perp \text{ is a subspace of } \Omega \end{array} \right\}$$

PROOF:

1. Proof that $A \cap A^\perp = \dots$:

$$\begin{aligned} A \cap A^\perp &= \{x \in X | x \in A\} \cap \{x \in X | \langle x | y \rangle \quad \forall y \in A\} && \text{by definition of } A^\perp \\ &= \{x \in X | x \in A \text{ and } \langle x | y \rangle \quad \forall y \in A\} \\ &= \begin{cases} \{\emptyset\} & \text{if } \emptyset \in A \\ \emptyset & \text{if } \emptyset \notin A \end{cases} \end{aligned}$$

2. Proof that $A \subseteq A^{\perp\perp} = \text{span}A$:

$$\begin{aligned} x \in A &\implies \{x\}^{\perp\perp} \subseteq A^{\perp\perp} \\ &\implies x \in \{x\}^{\perp\perp} \subseteq A^{\perp\perp} \\ &\implies x \in A^{\perp\perp} \end{aligned}$$

but

$$x \in A^{\perp\perp} \not\implies x \in A$$

Here is an example for the $\not\implies$ part using the linear space \mathbb{R}^3 :

- (a) Let $A \triangleq \{i\}$, where i is the unit vector on the x-axis.
- (b) Then $A^\perp = \{x \in X | x \in \text{yz plane}\}$.
- (c) Then $A^{\perp\perp} = \{x \in X | x \in \text{x axis}\}$.
- (d) Therefore, $A \subsetneq A^{\perp\perp}$

3. Proof for A^\perp equivalent expressions:

- (a) Proof that $A^\perp = A^{\perp\perp\perp}$:

$$\begin{aligned} A^\perp &\subseteq (A^\perp)^{\perp\perp} && \text{by item (2)} \\ &= (A^{\perp\perp})^\perp \\ &= A^{\perp\perp\perp} && \text{by Definition I.3 page 241} \\ A^{\perp\perp\perp} &= (A^{\perp\perp})^\perp && \text{by Definition I.3 page 241} \\ &\subseteq A^\perp && \text{by item (2) and Proposition I.5 (page 241)} \end{aligned}$$

- (b) Proof that $A^{\perp\perp\perp} = (\text{span}A)^\perp$: follows directly from item (2) ($A^\perp = \text{span}A$).

- (c) Proof that $A^\perp = A^{\perp^-}$:

- i. Let (x_n) be an A^\perp -valued sequence that converges to the limit x in X .

¹³ Michel and Herget (1993) page 383, Kubrusly (2011) page 326

ii. The limit point x must be in A^\perp because for all $y \in A$

$$\begin{aligned}\langle x | y \rangle &= \langle \lim x_n | y \rangle && \text{by definition of the sequence } (\mathbf{x}_n) \\ &= \lim \langle x_n | y \rangle \\ &= 0 && \text{because } (\mathbf{x}_n) \text{ is } A^\perp\text{-valued}\end{aligned}$$

iii. Because $\langle x | y \rangle = 0 \quad \forall y \in A$, x is in A^\perp .

iv. Because A^\perp contains all its limit points, and by the *Closed Set Theorem* (Theorem ?? page ??), it must be *closed* ($A^\perp = A^{\perp^-}$)

(d) Proof that $A^\perp = A^{-\perp}$:

i. Let $x \in A^\perp$ and $y \in A^-$.

ii. Let (y_n) be an A^\perp -valued sequence that converges in X to y .

iii. Thus $A^\perp \perp A^-$ because

$$\begin{aligned}\langle y | x \rangle &= \langle \lim y_n | x \rangle && \text{by definition of } (y_n) \\ &= \lim \langle y_n | x \rangle \\ &= 0 && \text{because } (y_n) \text{ is } A^\perp\text{-valued}\end{aligned}$$

iv. Because $A^\perp \perp A^-$, so $A^\perp \subseteq A^{\perp^-}$.

v. But $A^{\perp^-} \subseteq A^\perp$ because

$$A \subseteq A^- \implies A^{\perp^-} \subseteq A^\perp \quad \text{by } \textit{antitone} \text{ property (Proposition I.5 page 241)}$$

vi. And so $A^\perp = A^{\perp^-}$.

4. Proof that A^\perp is a **subspace** of Ω (must satisfy the conditions of Definition I.1 page 236):

(a) Proof that $A^\perp \neq \emptyset$: A^\perp has at least one element, the element 0 ...

$$\begin{aligned}\langle 0 | y \rangle &= 0 \quad \forall y \in A && \text{by definition of } 0 \\ \implies 0 &\in A^\perp && \text{by definition of } A^\perp \text{ (Definition I.3 page 241)}\end{aligned}$$

(b) Proof that $A^\perp \subseteq X$:

$$\begin{aligned}u \in A^\perp &\implies u \in \{x \in X \mid \langle x | y \rangle = 0 \quad \forall y \in A\} && \text{by definition of } A^\perp \text{ (Definition I.3 page 241)} \\ &\implies u \in X && \text{by definition of sets}\end{aligned}$$

(c) Proof that $u, v \in A^\perp \implies (u + v) \in A^\perp$:

$$\begin{aligned}u, v \in A^\perp &\implies \langle u | y \rangle = \langle v | y \rangle = 0 \quad \forall y \in A && \text{by definition of } A^\perp \text{ (Definition I.3 page 241)} \\ &\implies \langle u | y \rangle + \langle v | y \rangle = 0 \quad \forall y \in A \\ &\implies \langle u + v | y \rangle = 0 \quad \forall y \in A && \text{by } \textit{additive} \text{ property of } \langle \triangle | \nabla \rangle \text{ (Definition K.1 page 255)} \\ &\implies u + v \in A^\perp && \text{by definition of } A^\perp \text{ (Definition I.3 page 241)}\end{aligned}$$

(d) Proof that $v \in \Omega \implies \alpha v \in A^\perp$:

$$\begin{aligned}v \in A^\perp &\implies \langle v | y \rangle = 0 \quad \forall y \in A && \text{by definition of } A^\perp \text{ (Definition I.3 page 241)} \\ &\implies \alpha \langle v | y \rangle = \alpha \cdot 0 \quad \forall y \in A \\ &\implies \langle \alpha v | y \rangle = 0 \quad \forall y \in A && \text{by } \textit{homogeneous} \text{ property of } \langle \triangle | \nabla \rangle \text{ (Definition K.1 page 255)} \\ &\implies \alpha v \in A^\perp && \text{by definition of } A^\perp \text{ (Definition I.3 page 241)}\end{aligned}$$



Corollary I.1. Let $\mathbf{X} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ and $\mathbf{Y} \triangleq (Y, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ be INNER PRODUCT SPACES. Let $\text{span } Y$ be the span of the set Y (Definition H.2 page 205).

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$$\left\{ \begin{array}{l} \mathbf{Y} \text{ is a linear subspace of } \mathbf{X} \end{array} \right\} \implies \left\{ \begin{array}{ll} 1. & Y \cap Y^\perp = \{\mathbb{0}\} \\ 2. & Y = Y^{\perp\perp} = \text{span } Y \\ 3. & Y^\perp = Y^{\perp\perp\perp} \\ 4. & Y^\perp \text{ is a subspace of } \mathbf{X} \end{array} \right. \text{ and}$$

PROOF:

1. Proof that $Y \cap Y^\perp = \{\mathbb{0}\}$: This follows from Theorem I.3 (page 242) and the fact that all subspaces contain the zero vector $\mathbb{0}$ (Proposition I.3 page 237).
2. Proof that $Y = Y^{\perp\perp} = \text{span } Y$: This follows directly from Theorem I.3 (page 242).
3. Proof that $Y^\perp = Y^{\perp\perp\perp}$: This follows directly from Theorem I.3 (page 242).
4. Proof that Y^\perp is a **subspace** of \mathbf{X} : This follows directly from Theorem I.3 (page 242).

⇒

Theorem I.4. ¹⁴ Let $\mathbf{Y} \triangleq (Y, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ and $\mathbf{Z} \triangleq (Z, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ be LINEAR SUBSPACES of an INNER PRODUCT SPACE $\mathbf{Q} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$.

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$$Y \perp Z \implies Y \cap Z = \{\mathbb{0}\}$$

⇒

Theorem I.5. ¹⁵ Let $\mathbf{Y} \triangleq (Y, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ and $\mathbf{Z} \triangleq (Z, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ be linear subspaces of an INNER PRODUCT SPACE $\mathbf{Q} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$.

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$$\left\{ \begin{array}{l} 1. \quad Y \perp Z \text{ and} \\ 2. \quad x \in Y \hat{+} Z \end{array} \right\} \implies \left\{ \begin{array}{l} 1. \quad \text{There exists } y \in Y \text{ and } z \in Z \text{ such that } x = y + z \text{ and} \\ 2. \quad y \text{ and } z \text{ are UNIQUE.} \end{array} \right\}$$

PROOF:

1. Proof that y and z exist: by definition of Minkowski addition operator $\hat{+}$ (Definition I.2 page 237).
2. Proof that y and z are *unique*:

(a) Suppose $x = y_1 + z_1 = y_2 + z_2$ for $y_1, y_2 \in Y$ and $z_1, z_2 \in Z$.

¹⁴ Kubrusly (2001) page 324

¹⁵ Berberian (1961) page 61 (Theorem III.2.3)

(b) This implies

$$\begin{aligned} \mathbb{0} &= \mathbf{x} - \mathbf{x} \\ &= (\mathbf{y}_1 + \mathbf{z}_1) - (\mathbf{y}_1 + \mathbf{z}_2) \\ &= \underbrace{(\mathbf{y}_1 - \mathbf{y}_2)}_{\text{in } Y} + \underbrace{(\mathbf{z}_1 - \mathbf{z}_2)}_{\text{in } Z} \end{aligned}$$

- (c) Because $\mathbf{y}_1 - \mathbf{y}_2 \in Y$, $\mathbf{z}_1 - \mathbf{z}_2 \in Z$, $(\mathbf{y}_1 - \mathbf{y}_2) + (\mathbf{z}_1 - \mathbf{z}_2) = \mathbb{0}$, and $\langle \mathbf{y}_1 - \mathbf{y}_2 | \mathbf{z}_1 - \mathbf{z}_2 \rangle = 0$, then by Theorem K.9 (page 268), $\mathbf{y}_1 - \mathbf{y}_2 = \mathbb{0}$ and $\mathbf{z}_1 - \mathbf{z}_2 = \mathbb{0}$.
- (d) This implies $\mathbf{y}_1 = \mathbf{y}_2$ and $\mathbf{z}_1 = \mathbf{z}_2$.
- (e) This implies \mathbf{y} and \mathbf{z} are *unique*.



I.3 Subspaces of a Hilbert Space

Theorem I.6. ¹⁶ Let $H \triangleq (X, +, \cdot, (\mathbb{F}, +, \times), \langle \Delta | \nabla \rangle)$ be a HILBERT SPACE (Definition ?? page ??). Let Y be a SUBSET of X , and let $d(x, Y) \triangleq \inf_{y \in Y} \|x - y\|$.

T H M	$\left\{ \begin{array}{l} 1. \quad Y \neq \emptyset \\ 2. \quad Y \text{ is CLOSED} \\ 3. \quad Y \text{ is CONVEX} \end{array} \right. \quad \begin{array}{l} \text{and} \\ \text{and} \end{array} \quad \left(\text{Definition M.6 page 282} \right)$	\Rightarrow	$\left\{ \begin{array}{l} \text{There exists } p \in Y \text{ such that} \\ 1. \quad d(x, Y) = \ x - p\ \quad \text{and} \\ 2. \quad p \text{ is UNIQUE.} \end{array} \right.$
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PROOF:

1. Let $\delta \triangleq \inf \{x - y | y \in Y\}$.
2. Let $(\mathbf{y}_n)_{n \in \mathbb{Z}}$ be a sequence such that $\|\mathbf{x} - \mathbf{y}_n\| \rightarrow \delta$.
3. Proof that (\mathbf{y}_n) is *Cauchy*:

$$\begin{aligned} &\lim_{m,n \rightarrow \infty} \|\mathbf{y}_n - \mathbf{y}_m\|^2 \\ &= \lim_{m,n \rightarrow \infty} \|(\mathbf{y}_n - \mathbf{x}) + (\mathbf{x} - \mathbf{y}_m)\|^2 \\ &= \lim_{m,n \rightarrow \infty} \left\{ -\|(\mathbf{y}_n - \mathbf{x}) - (\mathbf{x} - \mathbf{y}_m)\|^2 + 2\|\mathbf{y}_n - \mathbf{x}\|^2 + 2\|\mathbf{x} - \mathbf{y}_m\|^2 \right\} \quad \text{by parallelogram law (page 263)} \\ &= \lim_{m,n \rightarrow \infty} \left\{ -4 \left\| \underbrace{\left(\frac{1}{2}\mathbf{y}_n + \frac{1}{2}\mathbf{y}_m \right)}_{\text{in } Y \text{ by convexity}} - \mathbf{x} \right\|^2 + 2\|\mathbf{y}_n - \mathbf{x}\|^2 + 2\|\mathbf{x} - \mathbf{y}_m\|^2 \right\} \\ &\leq \lim_{m,n \rightarrow \infty} \left\{ -4\delta^2 + 2\|\mathbf{y}_n - \mathbf{x}\|^2 + 2\|\mathbf{x} - \mathbf{y}_m\|^2 \right\} \quad \text{by definition of } \delta \text{ (item (1))} \\ &= -4\delta^2 + \lim_{m,n \rightarrow \infty} \left\{ 2\|\mathbf{y}_n - \mathbf{x}\|^2 \right\} + \lim_{m,n \rightarrow \infty} \left\{ 2\|\mathbf{x} - \mathbf{y}_m\|^2 \right\} \\ &= -4\delta^2 + 2\delta^2 + 2\delta^2 \quad \text{by definition of } \delta \text{ (item (1))} \\ &= 0 \end{aligned}$$

¹⁶ Kubrusly (2001) page 330 (Theorem 5.13), Aliprantis and Burkinshaw (1998) page 290 (Theorem 33.6), Berberian (1961) page 68 (Theorem III.5.1)

4. Proof that $d(x, Y) = \|x - y\|$: because (y_n) is *Cauchy* (item (1)) and by the *closed* hypothesis.
5. Proof that y is *unique*: Because in a metric space, the limit of a convergent sequence is *unique*.

⇒

Theorem I.7. ¹⁷ Let $H \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ be a HILBERT SPACE (Definition ?? page ??). Let $d(x, Y) \triangleq \inf_{y \in Y} \|x - y\|$. Let $Y \triangleq (Y, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ and Y^\perp the ORTHOGONAL COMPLEMENT of Y .

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$$\{ Y \text{ is a SUBSPACE of } H \} \implies \left\{ \begin{array}{l} \text{There exists } p \in Y \text{ such that} \\ \begin{array}{ll} 1. & d(x, Y) = \|x - p\| \text{ and} \\ 2. & p \text{ is UNIQUE} \text{ and} \\ 3. & x - p \in Y^\perp. \end{array} \end{array} \right\}$$

Theorem I.8 (Projection Theorem). ¹⁸ Let $H \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ be a Hilbert space.

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$$\{ Y \text{ is a SUBSPACE of } H \} \implies \{ Y \dagger Y^\perp = H \}$$

PROOF:

$$\begin{aligned} Y \dagger Y^\perp &= [Y \dagger Y^\perp]^\perp && \text{by Corollary I.1 page 244} \\ &= [Y^\perp \wedge Y^{\perp\perp}]^\perp && \text{by Proposition I.5 (page 241)} \\ &= \{\emptyset\}^\perp && \text{by Corollary I.1 page 244} \\ &= H && \text{by Proposition I.6 page 241} \end{aligned}$$

⇒

The inclusion relation \subseteq is an order relation on the set of subspaces of a linear space Ω .

Proposition I.7. Let S be the set of subspaces of a linear space Ω . Let \subseteq be the inclusion relation.

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(S, \subseteq) is an ordered set

PROOF: (S, \subseteq) is an *ordered set* and because

- | | | | | | | |
|----|--|-------------------------|------------------|--|-----|--------------------------|
| 1. | $X \subseteq X$ | $\forall X \in S$ | (reflexive) | | | $\boxed{\quad}$ preorder |
| 2. | $X \subseteq Y$ and $Y \subseteq Z \implies X \subseteq Z$ | $\forall X, Y, Z \in S$ | (transitive) | | and | ⇒ |
| 3. | $X \subseteq Y$ and $Y \subseteq X \implies X = Y$ | $\forall X, Y \in S$ | (anti-symmetric) | | | |

Theorem I.9. ¹⁹ Let H be a Hilbert space and 2^H the set of closed linear subspaces of H .

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$(2^H, \dagger, \wedge, \mathbf{0}, H; \subseteq)$ is an ORTHOMODULAR LATTICE. In particular

- | | | | | |
|----|--|----------------------|-------------------------|--|
| 1. | $X \dagger X^\perp = H$ | $\forall X \in H$ | (COMPLEMENTED) | |
| 2. | $X \wedge X^\perp = \mathbf{0}$ | $\forall X \in H$ | (COMPLEMENTED) | |
| 3. | $(X^\perp)^\perp = X$ | $\forall X \in H$ | (INVOLUTORY) | |
| 4. | $X \leq Y \implies Y^\perp \leq X^\perp$ | $\forall X, Y \in H$ | (ANTITONE) | |
| 5. | $X \leq Y \implies X \dagger (X^\perp \wedge Y) = Y$ | $\forall X, Y \in H$ | (ORTHOMODULAR IDENTITY) | |

¹⁷ ↗ Kubrusly (2001) page 330 (Theorem 5.13)

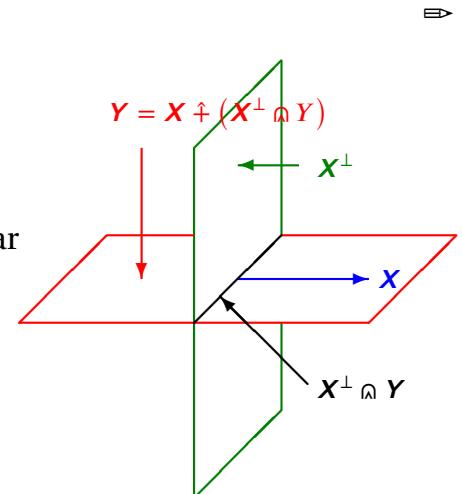
¹⁸ ↗ Bachman and Narici (1966) page 172 (Theorem 10.8), ↗ Kubrusly (2001) page 339 (Theorem 5.20)

¹⁹ ↗ Iturrioz (1985) pages 56–57



PROOF:

1. Proof for *complemented* (1) property: by *Projection Theorem* (Theorem I.8 page 246).
2. Proof for *complemented* (2) property: by Corollary I.1 (page 244).
3. Proof for *involutory* property: by Corollary I.1 (page 244).
4. Proof for *antitone* property: by Proposition I.5 (page 241).
5. Proof for *orthomodular identity* property:
6. Proof that lattice is *orthomodular*: by 5 properties and definition of *orthomodular lattice*.



This concept is illustrated to the right where $X, Y \in 2^H$ are linear subspaces of the linear space H and

$$X \subseteq Y \implies Y = X + (X^\perp \cap Y).$$

Corollary I.2. Let H be a Hilbert space with orthogonality operation \perp . Let $(2^H, \hat{+}, \wedge, 0, H; \subseteq)$ be the lattice of subspaces of H .

C O R	$(X \hat{+} Y)^\perp = X^\perp \wedge Y^\perp \quad \forall X, Y \in 2^H \quad (\text{DE MORGAN}) \quad \text{and}$
	$(X \wedge Y)^\perp = X^\perp \hat{+} Y^\perp \quad \forall X, Y \in 2^H \quad (\text{DE MORGAN})$

PROOF: By properties of *orthocomplemented lattices*.

I.4 Subspace Metrics

Definition I.4 (Hilbert space gap metric). ²⁰ Let X be a **Hilbert space** and S the set of subspaces of X . Then we define the following metric between subspaces of X .

D E F	$d(V, W) \triangleq \ P - Q\ \quad \forall V, W \in S$ (the distance between subspaces V and W is the size of the difference of their projection operators) $where V \triangleq PX$ (P is the projection operator that generates the subspace V) $and W \triangleq QX$ (Q is the projection operator that generates the subspace W).
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Definition I.5 (Banach space gap metric). ²¹ Let X be a **Banach space** and S the set of subspaces of X . Then we define the following metric between subspaces of X .

D E F	$d(V, W) \triangleq \max \left\{ \sup_{v \in V, \ v\ =1} p(v, W), \sup_{w \in W, \ w\ =1} p(w, V) \right\} \quad \forall V, W \in S$ $where p(v, W) \triangleq \inf_{w \in W} \ v - w\ $ (metric from the point v to the subspace W)
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²⁰ Deza and Deza (2006), page 235, Akhiezer and Glazman (1993), page 69, Berkson (1963), page 8, Krein and Krasnoselski (1947)

²¹ Akhiezer and Glazman (1993), page 70, Berkson (1963), page 8, Krein et al. (1948)

Definition I.6 (Schäffer's metric). ²²

DEF	$d(V, W) = \log(1 + \max\{r(V, W), r(W, V)\}) \quad \text{where}$ $r(V, W) \triangleq \begin{cases} \inf\{\ A - I\ \mid AV = W\} & \text{if } A \text{ and } A^{-1} \text{ both exist} \\ 1 & \text{otherwise} \end{cases}$
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I.5 Literature

Literature survey:

1. Lattice of subspaces
 - 📘 Birkhoff and Neumann (1936)
 - 📘 Husimi (1937)
 - 📘 Sasaki (1954)
 - 📘 Loomis (1955)
 - 📘 von Neumann (1960)
 - 📘 Holland (1970)
 - 📘 Halmos (1998b)
 - 📘 Amemiya and Araki (1966)
 - 📘 Gudder (1979)
 - 📘 Gudder (2005)
2. Characterizations of lattice of Hilbert subspaces (cf 📕 Iturrioz (1985) page 60):
 - 📘 Kakutani and Mackey (1946) ⟨using Banach spaces⟩
 - 📘 Piron (1964a) ⟨using pre-Hilbert spaces⟩
 - 📘 Piron (1964b) ⟨using pre-Hilbert spaces⟩
 - 📘 Amemiya and Araki (1966) ⟨using pre-Hilbert spaces⟩
 - 📘 Wilbur (1975) ⟨using locally convex spaces⟩
3. Metrics on subspaces:
 - 📘 Burago et al. (2001)



²²📘 Massera and Schäffer (1958), pages 562–563, 📕 Berkson (1963), pages 7–8



APPENDIX J

NORMED ALGEBRAS

J.1 Algebras

All *linear spaces* (Definition G.1 page 193) are equipped with an operation by which vectors in the spaces can be added together. Linear spaces also have an operation that allows a scalar and a vector to be “multiplied” together. But linear spaces in general have no operation that allows two vectors to be multiplied together. A linear space together with such an operator is an **algebra**.¹

There are many many possible algebras—many more than one can shake a stick at, as indicated by Michiel Hazewinkel in his book, *Handbook of Algebras*: “Algebra, as we know it today (2005), consists of many different ideas, concepts and results. A reasonable estimate of the number of these different items would be somewhere between 50,000 and 200,000. Many of these have been named and many more could (and perhaps should) have a “name” or other convenient designation.”²

Definition J.1. ³ Let \mathbf{A} be an ALGEBRA.

D E F An algebra \mathbf{A} is **unital** if $\exists u \in \mathbf{A}$ such that $ux = xu = x \quad \forall x \in \mathbf{A}$

Definition J.2. ⁴ Let \mathbf{A} be an UNITAL ALGEBRA (Definition J.1 page 249) with unit e .

D E F The **spectrum** of $x \in \mathbf{A}$ is $\sigma(x) \triangleq \{\lambda \in \mathbb{C} \mid \lambda e - x \text{ is not invertible}\}$.
The **resolvent** of $x \in \mathbf{A}$ is $\rho_x(\lambda) \triangleq (\lambda e - x)^{-1} \quad \forall \lambda \notin \sigma(x)$.
The **spectral radius** of $x \in \mathbf{A}$ is $r(x) \triangleq \sup \{|\lambda| \mid \lambda \in \sigma(x)\}$.

¹ Fuchs (1995) page 2

² Hazewinkel (2000) page v

³ Folland (1995) page 1

⁴ Folland (1995) pages 3–4

J.2 Star-Algebras

Definition J.3. ⁵ Let A be an ALGEBRA.

The pair $(A, *)$ is a ***-algebra**, or **star-algebra**, if

- D E F
1. $(x + y)^* = x^* + y^* \quad \forall x, y \in A$ (DISTRIBUTIVE) and
 2. $(\alpha x)^* = \bar{\alpha} x^* \quad \forall x \in A, \alpha \in \mathbb{C}$ (CONJUGATE LINEAR) and
 3. $(xy)^* = y^* x^* \quad \forall x, y \in A$ (ANTIAUTOMORPHIC) and
 4. $x^{**} = x \quad \forall x \in A$ (INVOLUTORY)

The operator $*$ is called an **involution** on the algebra A .

Proposition J.1. ⁶ Let $(A, *)$ be an UNITAL *-ALGEBRA.

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$$x \text{ is invertible} \implies \begin{cases} 1. \quad x^* \text{ is INVERTIBLE} \quad \forall x \in A \text{ and} \\ 2. \quad (x^*)^{-1} = (x^{-1})^* \quad \forall x \in A \end{cases}$$

PROOF: Let e be the unit element of $(A, *)$.

1. Proof that $e^* = e$:

$$\begin{aligned} x e^* &= (x e^*)^{**} && \text{by involutory property of } * && (\text{Definition J.3 page 250}) \\ &= (x^* e^{**})^* && \text{by antiautomorphic property of } * && (\text{Definition J.3 page 250}) \\ &= (x^* e)^* && \text{by involutory property of } * && (\text{Definition J.3 page 250}) \\ &= (x^*)^* && \text{by definition of } e && \\ &= x && \text{by involutory property of } * && (\text{Definition J.3 page 250}) \\ e^* x &= (e^* x)^{**} && \text{by involutory property of } * && (\text{Definition J.3 page 250}) \\ &= (e^{**} x^*)^* && \text{by antiautomorphic property of } * && (\text{Definition J.3 page 250}) \\ &= (e x^*)^* && \text{by involutory property of } * && (\text{Definition J.3 page 250}) \\ &= (x^*)^* && \text{by definition of } e && \\ &= x && \text{by involutory property of } * && (\text{Definition J.3 page 250}) \end{aligned}$$

2. Proof that $(x^*)^{-1} = (x^{-1})^*$:

$$\begin{aligned} (x^{-1})^* (x^*) &= [x (x^{-1})]^* && \text{by antiautomorphic and involution properties of } * && (\text{Definition J.3 page 250}) \\ &= e^* \\ &= e && \text{by item (1) page 250} \\ (x^*) (x^{-1})^* &= [x^{-1} x]^* && \text{by antiautomorphic and involution properties of } * && (\text{Definition J.3 page 250}) \\ &= e^* \\ &= e && \text{by item (1) page 250} \end{aligned}$$

Definition J.4. ⁷ Let $(A, \|\cdot\|)$ be a *-ALGEBRA (Definition J.3 page 250).

D E F

- An element $x \in A$ is **hermitian** or **self-adjoint** if $x^* = x$.

- An element $x \in A$ is **normal** if $xx^* = x^*x$.

- An element $x \in A$ is a **projection** if $xx = x$ (INVOLUTORY) and $x^* = x$ (HERMITIAN).

⁵ Rickart (1960), page 178, Gelfand and Naimark (1964), page 241

⁶ Folland (1995) page 5

⁷ Rickart (1960), page 178, Gelfand and Naimark (1964), page 242

Theorem J.1. ⁸ Let $(A, \|\cdot\|)$ be a $*$ -ALGEBRA (Definition J.3 page 250).

T H M	$\underbrace{x = x^* \text{ and } y = y^*}_{x \text{ and } y \text{ are HERMITIAN}} \implies \begin{cases} x + y = (x + y)^* & (x + y \text{ is selfadjoint}) \\ x^* = (x^*)^* & (x^* \text{ is selfadjoint}) \\ \underbrace{xy = (xy)^*}_{(xy) \text{ is HERMITIAN}} \iff \underbrace{xy = yx}_{\text{commutative}} & \end{cases}$
----------------------	---

PROOF:

$$(x + y)^* = x^* + y^* \quad \begin{matrix} \text{by distributive property of } * \\ \text{by left hypothesis} \end{matrix} \quad (\text{Definition J.3 page 250})$$

$$(x^*)^* = x \quad \begin{matrix} \text{by involutory property of } * \\ \text{by Definition J.3 page 250} \end{matrix}$$

Proof that $xy = (xy)^* \implies xy = yx$

$$\begin{aligned} xy &= (xy)^* && \text{by left hypothesis} \\ &= y^* x^* && \text{by antiautomorphic property of } * \\ &= yx && \text{by left hypothesis} \end{aligned} \quad (\text{Definition J.3 page 250})$$

Proof that $xy = (xy)^* \iff xy = yx$

$$\begin{aligned} (xy)^* &= (yx)^* && \text{by left hypothesis} \\ &= x^* y^* && \text{by antiautomorphic property of } * \\ &= xy && \text{by left hypothesis} \end{aligned} \quad (\text{Definition J.3 page 250})$$

Definition J.5 (Hermitian components). ⁹ Let $(A, \|\cdot\|)$ be a $*$ -ALGEBRA (Definition J.3 page 250).

D E F	$\mathbf{R}_e x \triangleq \frac{1}{2}(x + x^*)$ $\mathbf{I}_m x \triangleq \frac{1}{2i}(x - x^*)$
----------------------	---

Theorem J.2. ¹⁰ Let $(A, *)$ be a $*$ -ALGEBRA (Definition J.3 page 250).

T H M	$\mathbf{R}_e x = (\mathbf{R}_e x)^* \quad \forall x \in A \quad (\mathbf{R}_e x \text{ is HERMITIAN})$ $\mathbf{I}_m x = (\mathbf{I}_m x)^* \quad \forall x \in A \quad (\mathbf{I}_m x \text{ is HERMITIAN})$
----------------------	--

PROOF:

$$\begin{aligned} (\mathbf{R}_e x)^* &= \left(\frac{1}{2}(x + x^*)\right)^* && \text{by definition of } \mathfrak{R} \\ &= \frac{1}{2}(x^* + x^{**}) && \text{by distributive property of } * \\ &= \frac{1}{2}(x^* + x) && \text{by involutory property of } * \\ &= \mathbf{R}_e x && \text{by definition of } \mathfrak{R} \\ (\mathbf{I}_m x)^* &= \left(\frac{1}{2i}(x - x^*)\right)^* && \text{by definition of } \mathfrak{I} \end{aligned} \quad (\text{Definition J.5 page 251})$$

⁸ Michel and Herget (1993) page 429

⁹ Michel and Herget (1993) page 430, Rickart (1960), page 179, Gelfand and Naimark (1964), page 242

¹⁰ Michel and Herget (1993) page 430, Halmos (1998a) page 42

$$\begin{aligned}
 &= \frac{1}{2i}(x^* - x^{**}) && \text{by } \textit{distributive} \text{ property of } * && (\text{Definition J.3 page 250}) \\
 &= \frac{1}{2i}(x^* - x) && \text{by } \textit{involutory} \text{ property of } * && (\text{Definition J.3 page 250}) \\
 &= \mathbf{I}_m x && \text{by definition of } \mathfrak{I} && (\text{Definition J.5 page 251})
 \end{aligned}$$

⇒

Theorem J.3 (Hermitian representation). ¹¹ Let $(A, *)$ be a $*$ -ALGEBRA (Definition J.3 page 250).

T	H	M	$a = x + iy \iff x = \mathbf{R}_e a \text{ and } y = \mathbf{I}_m a$
---	---	---	--

PROOF:

Proof that $a = x + iy \implies x = \mathbf{R}_e a \text{ and } y = \mathbf{I}_m a$:

$$\begin{aligned}
 &a = x + iy && \text{by left hypothesis} \\
 \implies &a^* = (x + iy)^* && \text{by definition of } \textit{adjoint} && (\text{Definition J.4 page 250}) \\
 &= x^* - iy^* && \text{by } \textit{distributive} \text{ property of } * && (\text{Definition J.3 page 250}) \\
 &= x - iy && \text{by Theorem J.2 page 251} \\
 \implies &x = a - iy && \text{by solving for } x \text{ in } a = x + iy \text{ equation} \\
 &x = a^* + iy && \text{by solving for } x \text{ in } a^* = x - iy \text{ equation} \\
 \implies &x + x = a + a^* && \text{by adding previous 2 equations} \\
 \implies &2x = a + a^* && \text{by solving for } x \text{ in previous equation} \\
 \implies &x = \frac{1}{2}(a + a^*) && \\
 &= \mathbf{R}_e a && \text{by definition of } \mathfrak{R} && (\text{Definition J.5 page 251}) \\
 \\
 &iy = a - x && \text{by solving for } iy \text{ in } a = x + iy \text{ equation} \\
 &iy = -a^* + x && \text{by solving for } iy \text{ in } a = x + iy \text{ equation} \\
 \implies &iy + iy = a - a^* && \text{by adding previous 2 equations} \\
 \implies &y = \frac{1}{2i}(a - a^*) && \text{by solving for } iy \text{ in previous equations} \\
 &= \mathbf{I}_m a && \text{by definition of } \mathfrak{I} && (\text{Definition J.5 page 251})
 \end{aligned}$$

Proof that $a = x + iy \iff x = \mathbf{R}_e a \text{ and } y = \mathbf{I}_m a$:

$$\begin{aligned}
 x + iy &= \mathbf{R}_e a + i \mathbf{I}_m a && \text{by right hypothesis} \\
 &= \underbrace{\frac{1}{2}(a + a^*)}_{\mathbf{R}_e a} + i \underbrace{\frac{1}{2i}(a - a^*)}_{\mathbf{I}_m a} && \text{by definition of } \mathfrak{R} \text{ and } \mathfrak{I} && (\text{Definition J.5 page 251}) \\
 &= \left(\frac{1}{2}a + \frac{1}{2}a\right) + \left(\frac{1}{2}a^* - \frac{1}{2}a^*\right) \xrightarrow{0} 0 \\
 &= a
 \end{aligned}$$

⇒

¹¹ Michel and Herget (1993) page 430, Rickart (1960), page 179, Gelfand and Neumark (1943b), page 7



J.3 Normed Algebras

Definition J.6. ¹² Let \mathbf{A} be an algebra.

**D
E
F**

The pair $(\mathbf{A}, \|\cdot\|)$ is a **normed algebra** if

$$\|xy\| \leq \|x\| \|y\| \quad \forall x, y \in \mathbf{A} \quad (\text{multiplicative condition})$$

A normed algebra $(\mathbf{A}, \|\cdot\|)$ is a **Banach algebra** if $(\mathbf{A}, \|\cdot\|)$ is also a Banach space.

Proposition J.2.

**P
R
P**

$(\mathbf{A}, \|\cdot\|)$ is a normed algebra \implies multiplication is **continuous** in $(\mathbf{A}, \|\cdot\|)$

PROOF:

1. Define $f(x) \triangleq zx$. That is, the function f represents multiplication of x times some arbitrary value z .
2. Let $\delta \triangleq \|x - y\|$ and $\epsilon \triangleq \|f(x) - f(y)\|$.
3. To prove that multiplication (f) is *continuous* with respect to the metric generated by $\|\cdot\|$, we have to show that we can always make ϵ arbitrarily small for some $\delta > 0$.
4. And here is the proof that multiplication is indeed continuous in $(\mathbf{A}, \|\cdot\|)$:

$$\begin{aligned} \|f(x) - f(y)\| &\triangleq \|zx - zy\| && \text{by definition of } f && \text{(item (1) page 253)} \\ &= \|z(x - y)\| \\ &\leq \|z\| \|x - y\| && \text{by definition of normed algebra} && \text{(Definition J.6 page 253)} \\ &\triangleq \|z\| \delta && \text{by definition of } \delta && \text{(item (2) page 253)} \\ &\leq \epsilon && \text{for some value of } \delta > 0 \end{aligned}$$



Theorem J.4 (Gelfand-Mazur Theorem). ¹³ Let \mathbb{C} be the field of complex numbers.

**T
H
M**

$(\mathbf{A}, \|\cdot\|)$ is a Banach algebra
every nonzero $x \in \mathbf{A}$ is invertible } $\implies \mathbf{A} \cong \mathbb{C}$ (\mathbf{A} is isomorphic to \mathbb{C})

J.4 C* Algebras

Definition J.7. ¹⁴

**D
E
F**

The triple $(\mathbf{A}, \|\cdot\|, *)$ is a **C* algebra** if

1. $(\mathbf{A}, \|\cdot\|)$ is a Banach algebra and
2. $(\mathbf{A}, *)$ is a $*$ -algebra and
3. $\|x^* x\| = \|x\|^2 \quad \forall x \in \mathbf{A}$.

A **C* algebra** $(\mathbf{A}, \|\cdot\|, *)$ is also called a **C star algebra**.

¹² Rickart (1960), page 2, Berberian (1961) page 103 (Theorem IV.9.2)

¹³ Folland (1995) page 4, Mazur (1938) ((statement)), Gelfand (1941) ((proof))

¹⁴ Folland (1995) page 1, Gelfand and Naimark (1964), page 241, Gelfand and Neumark (1943a), Gelfand and Neumark (1943b)

Theorem J.5. ¹⁵ Let A be an algebra.

T
H
M

$(A, \|\cdot\|, *)$ is a C^* algebra $\implies \|x^*\| = \|x\|$

PROOF:

$$\begin{aligned}
 \|x\| &= \frac{1}{\|x\|} \|x\|^2 \\
 &= \frac{1}{\|x\|} \|x^* x\| && \text{by definition of } C^* \text{-algebra} && (\text{Definition J.7 page 253}) \\
 &\leq \frac{1}{\|x\|} \|x^*\| \|x\| && \text{by definition of normed algebra} && (\text{Definition J.6 page 253}) \\
 &= \|x^*\| \\
 \|x^*\| &\leq \|x^{**}\| && \text{by previous result} \\
 &= \|x\| && \text{by involution property of } * && (\text{Definition J.3 page 250})
 \end{aligned}$$

⇒

¹⁵  Folland (1995) page 1,  Gelfand and Neumark (1943b), page 4,  Gelfand and Neumark (1943a)

APPENDIX K

INNER PRODUCT SPACES

K.1 Definition and basic results

Definition K.1. ¹ Let $\Omega \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ be a LINEAR SPACE (Definition G.1 page 193).

A FUNCTIONAL $\langle \Delta | \nabla \rangle \in \mathbb{F}^{X \times X}$ is an **inner product** on Ω if

- | | | | | |
|-----|--|---|-----------------------|-----|
| DEF | 1. $\langle \alpha x y \rangle = \alpha \langle x y \rangle$ | $\forall x, y \in X, \forall \alpha \in \mathbb{C}$ | (HOMOGENEOUS) | and |
| | 2. $\langle x + y u \rangle = \langle x u \rangle + \langle y u \rangle$ | $\forall x, y, u \in X$ | (ADDITIVE) | and |
| | 3. $\langle x y \rangle = \langle y x \rangle^*$ | $\forall x, y \in X$ | (CONJUGATE SYMMETRIC) | and |
| | 4. $\langle x x \rangle \geq 0$ | $\forall x \in X$ | (NON-NEGATIVE) | and |
| | 5. $\langle x x \rangle = 0 \iff x = \emptyset$ | $\forall x \in X$ | (NON-ISOTROPIC) | |

An inner product is also called a **scalar product**.

The tuple $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \Delta | \nabla \rangle)$ is called an **inner product space**.

Theorem K.1. ² Let $\Omega \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \Delta | \nabla \rangle)$ be a LINEAR SPACE (Definition G.1 page 193).

- | | | |
|-----|--|---|
| THM | 1. $\langle x y + z \rangle = \langle x y \rangle + \langle x z \rangle$ | $\forall x, y, z \in X$ |
| | 2. $\langle x \alpha y \rangle = \alpha^* \langle x y \rangle$ | $\forall x, y \in X, \alpha \in \mathbb{F}$ |
| | 3. $\langle x \emptyset \rangle = \langle \emptyset x \rangle = 0$ | $\forall x \in X$ |
| | 4. $\langle x - y z \rangle = \langle x z \rangle - \langle y z \rangle$ | $\forall x, y, z \in X$ |
| | 5. $\langle x y - z \rangle = \langle x y \rangle - \langle x z \rangle$ | $\forall x, y, z \in X$ |
| | 6. $\langle x z \rangle = \langle y z \rangle$ | $\forall z \in X \neq \{0\} \iff x = y$ |
| | 7. $\langle x y \rangle = 0$ | $\forall x \in X \iff y = \emptyset$ |

PROOF:

$$\begin{aligned}
 \langle x | y + z \rangle &= \langle y + z | x \rangle^* && \text{by conjugate symmetric property of } \langle \Delta | \nabla \rangle && \text{(Definition K.1 page 255)} \\
 &= ((y | x) + (z | x))^* && \text{by additive property of } \langle \Delta | \nabla \rangle && \text{(Definition K.1 page 255)} \\
 &= \langle y | x \rangle^* + \langle z | x \rangle^* && \text{by distributive property of } * && \text{(Definition J.3 page 250)} \\
 &= \langle x | y \rangle + \langle x | z \rangle && \text{by conjugate symmetric property of } \langle \Delta | \nabla \rangle && \text{(Definition K.1 page 255)} \\
 \langle x | \alpha y \rangle &= \langle \alpha y | x \rangle^* && \text{by conjugate symmetric property of } \langle \Delta | \nabla \rangle && \text{(Definition K.1 page 255)}
 \end{aligned}$$

¹ Istrătescu (1987) page 111 (Definition 4.1.1), Bollobás (1999) pages 130–131, Haaser and Sullivan (1991) page 277, Aliprantis and Burkinshaw (1998), page 276, Peano (1888b) page 72

² Berberian (1961) page 27, Haaser and Sullivan (1991) page 277

$= (\alpha \langle y x \rangle)^*$	by <i>homogeneous</i> property of $\langle \triangle \nabla \rangle$	(Definition K.1 page 255)
$= \alpha^* \langle y x \rangle^*$	by <i>antiautomorphic</i> property of $*$	(Definition J.3 page 250)
$= \alpha^* \langle x y \rangle$	by <i>conjugate symmetric</i> property of $\langle \triangle \nabla \rangle$	(Definition K.1 page 255)
$\langle x 0 \rangle = \langle 0 x \rangle^*$	by <i>conjugate symmetric</i> property of $\langle \triangle \nabla \rangle$	(Definition K.1 page 255)
$= \langle 0 \cdot y x \rangle^*$		
$= (0 \cdot \langle y x \rangle)^*$	by <i>homogeneous</i> property of $\langle \triangle \nabla \rangle$	(Definition K.1 page 255)
$= 0$		
$\langle 0 x \rangle = \langle 0 \cdot y x \rangle$		
$= (0 \cdot \langle y x \rangle)$	by <i>homogeneous</i> property of $\langle \triangle \nabla \rangle$	(Definition K.1 page 255)
$= 0$		
$\langle x - y z \rangle = \langle x + (-y) z \rangle$	by definition of $+$	
$= \langle x z \rangle + \langle -y z \rangle$	by <i>additive</i> property of $\langle \triangle \nabla \rangle$	(Definition K.1 page 255)
$= \langle x z \rangle - \langle y z \rangle$	by <i>homogeneous</i> property of $\langle \triangle \nabla \rangle$	(Definition K.1 page 255)
$\langle x y - z \rangle = \langle y - z x \rangle^*$	by <i>conjugate symmetric</i> property of $\langle \triangle \nabla \rangle$	(Definition K.1 page 255)
$= (\langle y x \rangle - \langle z x \rangle)^*$	by 4.	
$= \langle y x \rangle^* - \langle z x \rangle^*$	by <i>distributive</i> property of $*$	(Definition J.3 page 250)
$= \langle x y \rangle - \langle x z \rangle$	by <i>conjugate symmetric</i> property of $\langle \triangle \nabla \rangle$	(Definition K.1 page 255)

$$\begin{aligned} & \langle x | z \rangle = \langle y | z \rangle && \forall z \\ \iff & \langle x | z \rangle - \langle y | z \rangle = 0 && \forall z \quad \text{by property of complex numbers} \\ \iff & \langle x - y | z \rangle = 0 && \forall z \quad \text{by 4.} \\ \iff & x - y = 0 && \forall z \quad \text{by } \textit{non-isotropic} \text{ property of } \langle \triangle | \nabla \rangle \text{ (Definition K.1 page 255)} \end{aligned}$$

Proof that $\langle x | y \rangle = 0 \implies y = 0$:

1. Suppose $y \neq 0$;
2. Then $\langle y | y \rangle \neq 0$ by the *non-isotropic* property of $\langle \triangle | \nabla \rangle$ (Definition K.1 page 255)
3. But because $y \in X$, the left hypothesis implies that $\langle y | y \rangle = 0$.
4. This is a *contradiction*.
5. Therefore $y \neq 0$ must be incorrect and $y = 0$ must be correct.

Proof that $\langle x | y \rangle = 0 \iff y = 0$:

$$\begin{aligned} \langle x | y \rangle &= \langle x | 0 \rangle && \text{by right hypothesis} \\ &= 0 && \text{by Theorem K.1 page 255} \end{aligned}$$

⇒

One of the most useful and widely used inequalities in analysis is the *Cauchy-Schwarz Inequality* (sometimes also called the *Cauchy-Bunyakovsky-Schwarz Inequality*). In fact, we will use this inequality shortly to prove that every inner product space *has* a norm and therefore every inner product space *is* a normed linear space.

Theorem K.2 (Cauchy-Schwarz Inequality). ³ Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ be an INNER PRODUCT SPACE and $|\cdot| \in \mathbb{R}^{\mathbb{C}}$ an ABSOLUTE VALUE function (Definition F.4 page 192). Let $\|\cdot\|$ be a function in $\mathbb{R}^{\mathbb{F}}$ such

³ Haaser and Sullivan (1991) page 278, Aliprantis and Burkinshaw (1998), page 278, Cauchy (1821) page 455, Bunyakovsky (1859) page 6, Schwarz (1885)



that $\|x\| \triangleq \sqrt{\langle x | x \rangle}$.⁴

T H M	$ \langle x y \rangle ^2 \leq \langle x x \rangle \langle y y \rangle \quad \forall x, y \in X$ $ \langle x y \rangle ^2 = \langle x x \rangle \langle y y \rangle \iff \exists \alpha \in \mathbb{F} \text{ such that } y = \alpha x \quad \forall x, y \in X$ $ \langle x y \rangle \leq \ x\ \ y\ \quad \forall x, y \in X$ $ \langle x y \rangle = \ x\ \ y\ \iff \exists \alpha \in \mathbb{F} \text{ such that } y = \alpha x \quad \forall x, y \in X$
----------------------	--

PROOF:

1. Proof that $|\langle x | y \rangle| \leq \|x\| \|y\|$:⁵

(a) $y = \emptyset$ case:

$$\begin{aligned}
 |\langle x | y \rangle|^2 &= |\langle x | \emptyset \rangle|^2 && \text{by } y = \emptyset \text{ hypothesis} \\
 &= |\langle \emptyset | x \rangle|^2 && \text{by Definition K.1 page 255} \\
 &= |\langle \emptyset \emptyset | x \rangle|^2 && \text{by Definition G.1 page 193} \\
 &= |0 \langle \emptyset | x \rangle|^2 && \text{by Definition K.1 page 255} \\
 &= 0 \\
 &= \langle x | x \rangle \langle \emptyset | \emptyset \rangle \\
 &= \langle x | x \rangle \langle y | y \rangle && \text{by } y = \emptyset \text{ hypothesis}
 \end{aligned}$$

(b) $y \neq \emptyset$ case: Let $\lambda \triangleq \frac{\langle x | y \rangle}{\langle y | y \rangle}$.

$$\begin{aligned}
 0 &\leq \langle x - \lambda y | x - \lambda y \rangle && \text{by Definition K.1} \\
 &= \langle x | x - \lambda y \rangle + \langle -\lambda y | x - \lambda y \rangle && \text{by Definition K.1} \\
 &= \langle x - \lambda y | x \rangle^* - \lambda \langle y | x - \lambda y \rangle && \text{by Definition K.1} \\
 &= \langle x | x \rangle^* + \langle -\lambda y | x \rangle^* - \lambda \langle x - \lambda y | y \rangle^* && \text{by Definition K.1} \\
 &= \langle x | x \rangle^* - \lambda^* \langle y | x \rangle^* - \lambda \langle x | y \rangle^* - \lambda \langle -\lambda y | y \rangle^* && \text{by Definition K.1} \\
 &= \langle x | x \rangle - \lambda^* \langle x | y \rangle - \lambda \langle x | y \rangle^* + \lambda \lambda^* \langle y | y \rangle^* && \text{by Definition K.1} \\
 &= \langle x | x \rangle + \left[\frac{\langle x | y \rangle}{\langle y | y \rangle} \lambda^* \langle y | y \rangle - \lambda^* \langle x | y \rangle \right] - \frac{\langle x | y \rangle}{\langle y | y \rangle} \langle x | y \rangle^* && \text{by definition of } \lambda \\
 &= \langle x | x \rangle - \frac{1}{\langle y | y \rangle} |\langle x | y \rangle|^2 \\
 \implies |\langle x | y \rangle|^2 &\leq \langle x | x \rangle \langle y | y \rangle
 \end{aligned}$$

2. Proof that $|\langle x | y \rangle|^2 = \langle x | x \rangle \langle y | y \rangle \iff y = ax$:

Let $\frac{1}{a} \triangleq \lambda \triangleq \frac{\langle x | y \rangle}{\langle y | y \rangle}$. Then...

$$\begin{aligned}
 y &= ax \\
 \iff x &= \lambda y \\
 \iff x - \lambda y &= \emptyset \\
 \iff 0 &= \langle x - \lambda y | x - \lambda y \rangle && \text{by Definition K.1 page 255} \\
 &= \langle x | x - \lambda y \rangle + \langle -\lambda y | x - \lambda y \rangle && \text{by Definition K.1 page 255} \\
 &= \langle x - \lambda y | x \rangle^* - \lambda \langle y | x - \lambda y \rangle && \text{by Definition K.1 page 255} \\
 &\vdots && \text{(same steps as in 1(b))}
 \end{aligned}$$

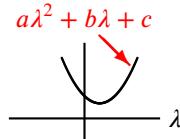
⁴The function $\|\cdot\|$ is a *norm* (Theorem K.4 page 260) and is called the *norm induced by the inner product* $\langle \Delta | \nabla \rangle$ (Definition K.2 page 261).

⁵ Haaser and Sullivan (1991), page 278

$$\iff |\langle \mathbf{x} | \mathbf{y} \rangle|^2 = \langle \mathbf{x} | \mathbf{x} \rangle \langle \mathbf{y} | \mathbf{y} \rangle - \frac{1}{\langle \mathbf{y} | \mathbf{y} \rangle} |\langle \mathbf{x} | \mathbf{y} \rangle|^2$$

3. Alternate proof for $|\langle \mathbf{x} | \mathbf{y} \rangle| \leq \|\mathbf{x}\| \|\mathbf{y}\|$: (Note: This is essentially the same proof as used by Schwarz).⁶

- (a) Proof that $\{a\lambda^2 + b\lambda + c \geq 0 \quad \forall \lambda \in \mathbb{R}\} \implies \{b^2 \leq 4ac\}$ (quadratic discriminant inequality):



Let $k \in (0, \infty)$, and $r_1, r_2 \in \mathbb{C}$ be the roots of $a\lambda^2 + b\lambda + c = 0$. Then

$$\begin{aligned} 0 &\leq a\lambda^2 + b\lambda + c && \text{by left hypothesis} \\ &= k(\lambda - r_1)(\lambda - r_2) && \text{by definition of } r_1 \text{ and } r_2 \\ &= k(\lambda^2 - r_1\lambda - r_2\lambda + r_1r_2) \\ \implies \lambda^2 - r_1\lambda - r_2\lambda + r_1r_2 &\geq 0 \\ \implies r_1 &= r_2^* && \text{because } r_1r_2 \geq 0 \text{ for } \lambda = 0 \end{aligned}$$

The *quadratic equation* places another constraint on r_1 and r_2 :

$$\begin{aligned} \frac{b^2 + \sqrt{b^2 - 4ac}}{2a} &= r_1 && \text{by quadratic equation} \\ &= r_2^* && \text{by previous result} \\ &= \left(\frac{b^2 - \sqrt{b^2 - 4ac}}{2a} \right)^* && \text{by quadratic equation} \end{aligned}$$

The only way for this to be true is if $b^2 \leq 4ac$ (the **discriminate** is non-positive).

- (b) Proof that $\langle \mathbf{y} | \mathbf{y} \rangle \lambda^2 + 2|\langle \mathbf{x} | \mathbf{y} \rangle| \lambda + \langle \mathbf{x} | \mathbf{x} \rangle \geq 0 \quad \forall \lambda \in \mathbb{R}$:

$$\begin{aligned} 0 &\leq \langle \mathbf{x} + \alpha \mathbf{y} | \mathbf{x} + \alpha \mathbf{y} \rangle && \text{by Definition K.1 page 255} \\ &= \langle \mathbf{x} | \mathbf{x} + \alpha \mathbf{y} \rangle + \langle \alpha \mathbf{y} | \mathbf{x} + \alpha \mathbf{y} \rangle && \text{by Definition K.1 page 255} \\ &= \langle \mathbf{x} | \mathbf{x} + \alpha \mathbf{y} \rangle + \alpha \langle \mathbf{y} | \mathbf{x} + \alpha \mathbf{y} \rangle && \text{by Definition K.1 page 255} \\ &= \langle \mathbf{x} + \alpha \mathbf{y} | \mathbf{x} \rangle^* + \alpha \langle \mathbf{x} + \alpha \mathbf{y} | \mathbf{y} \rangle^* && \text{by Definition K.1 page 255} \\ &= \langle \mathbf{x} | \mathbf{x} \rangle^* + \langle \alpha \mathbf{y} | \mathbf{x} \rangle^* + \alpha \langle \mathbf{x} | \mathbf{y} \rangle^* + \alpha \langle \alpha \mathbf{y} | \mathbf{y} \rangle^* && \text{by Definition K.1 page 255} \\ &= \langle \mathbf{x} | \mathbf{x} \rangle^* + \alpha^* \langle \mathbf{y} | \mathbf{x} \rangle^* + \alpha \langle \mathbf{x} | \mathbf{y} \rangle^* + \alpha \alpha^* \langle \mathbf{y} | \mathbf{y} \rangle^* && \text{by Definition K.1 page 255} \\ &= \langle \mathbf{x} | \mathbf{x} \rangle + \alpha^* \langle \mathbf{x} | \mathbf{y} \rangle + (\alpha^* \langle \mathbf{x} | \mathbf{y} \rangle)^* + |\alpha|^2 \langle \mathbf{y} | \mathbf{y} \rangle && \text{by Definition K.1 page 255} \\ &= \langle \mathbf{x} | \mathbf{x} \rangle + 2\Re(\alpha^* \langle \mathbf{x} | \mathbf{y} \rangle) + |\alpha|^2 \langle \mathbf{y} | \mathbf{y} \rangle && \text{by Definition K.1 page 255} \\ &\leq \langle \mathbf{x} | \mathbf{x} \rangle + 2|\alpha^* \langle \mathbf{x} | \mathbf{y} \rangle| + |\alpha|^2 \langle \mathbf{y} | \mathbf{y} \rangle && \text{by Definition K.1 page 255} \\ &= \langle \mathbf{x} | \mathbf{x} \rangle + 2|\langle \mathbf{x} | \mathbf{y} \rangle||\alpha| + \langle \mathbf{y} | \mathbf{y} \rangle |\alpha|^2 && \text{by Definition K.1 page 255} \\ &= \langle \mathbf{y} | \mathbf{y} \rangle |\alpha|^2 + 2|\langle \mathbf{x} | \mathbf{y} \rangle| |\alpha| + \langle \mathbf{x} | \mathbf{x} \rangle && \text{by Definition K.1 page 255} \\ &= \underbrace{\langle \mathbf{y} | \mathbf{y} \rangle}_{a} \lambda^2 + \underbrace{2|\langle \mathbf{x} | \mathbf{y} \rangle|}_{b} \lambda + \underbrace{\langle \mathbf{x} | \mathbf{x} \rangle}_{c} && \text{because } \lambda \triangleq |\alpha| \in \mathbb{R} \end{aligned}$$

⁶ Aliprantis and Burkinshaw (1998), page 278, Steele (2004), page 11

(c) The above equation is in the quadratic form used in the lemma of part (a).

$$\begin{aligned} \underbrace{\left(2|\langle x | y \rangle|\right)^2}_{b} &\leq 4 \underbrace{\langle y | y \rangle}_{a} \underbrace{\langle x | x \rangle}_{c} \quad \text{by the results of parts (a) and (b)} \\ \implies |\langle x | y \rangle|^2 &\leq \langle x | x \rangle \langle y | y \rangle \end{aligned}$$

4. Proof that $|\langle x | y \rangle| \leq \|x\| \|y\|$:

This follows directly from the definition $\|x\| \triangleq \sqrt{\langle x | x \rangle}$.

5. Proof that $|\langle x | y \rangle| = \|x\| \|y\| \iff \exists \alpha \in \mathbb{C} \text{ such that } y = \alpha x$:

This follows directly from the definition $\|x\| \triangleq \sqrt{\langle x | x \rangle}$.



Corollary K.1. ⁷ Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ be an INNER PRODUCT SPACE.

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$\langle x | y \rangle$ is CONTINUOUS in both x and y .

PROOF: Let $\|x\| \triangleq \sqrt{\langle x | x \rangle}$.

$$\begin{aligned} |\langle x + \epsilon | y \rangle - \langle x | y \rangle|^2 &= |\langle x + \epsilon - x | y \rangle|^2 \quad \text{by additivity of } \langle \triangle | \nabla \rangle \quad (\text{Definition K.1 page 255}) \\ &= |\langle \epsilon | y \rangle|^2 \\ &\leq \|\epsilon\|^2 \|y\|^2 \quad \text{by Cauchy-Schwarz Inequality} \quad (\text{Theorem K.2 page 256}) \end{aligned}$$



K.2 Relationship between norms and inner products

K.2.1 Norms induced by inner products

Lemma K.1 (Polar Identity). ⁸ Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ be an INNER PRODUCT SPACE (Definition K.1 page 255). Let $\Re z$ represent the real part of $z \in \mathbb{C}$. Let $\|\cdot\|$ be a function in $\mathbb{R}^{\mathbb{F}}$ such that $\|x\| \triangleq \sqrt{\langle x | x \rangle}$.⁹

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$$\|x + y\|^2 = \|x\|^2 + 2\Re_e [\langle x | y \rangle] + \|y\|^2 \quad \forall x, y \in X$$

⁷ Bollobás (1999) page 132, Aliprantis and Burkinshaw (1998) page 279 (Lemma 32.4)

⁸ Conway (1990) page 4, Heil (2011) page 27 (Lemma 1.36(a))

⁹The function $\|\cdot\|$ is a norm (Theorem K.4 page 260) and is called the norm induced by the inner product $\langle \triangle | \nabla \rangle$ (Definition K.2 page 261).

PROOF:

$$\begin{aligned}
 \|x + y\|^2 &= \langle x + y | x + y \rangle && \text{by definition of } \textit{induced norm} && (\text{Theorem K.4 page 260}) \\
 &= \langle x | x + y \rangle + \langle y | x + y \rangle && \text{by Definition K.1 page 255} \\
 &= \langle x + y | x \rangle^* + \langle x + y | y \rangle^* && \text{by Definition K.1 page 255} \\
 &= \langle x | x \rangle^* + \langle y | x \rangle^* + \langle x | y \rangle^* + \langle y | y \rangle^* && \text{by Definition K.1 page 255} \\
 &= \langle x | x \rangle + \langle x | y \rangle + \langle x | y \rangle^* + \langle y | y \rangle && \text{by definition of } \textit{inner product} && (\text{Definition K.1 page 255}) \\
 &= \|x\|^2 + 2\Re \langle x | y \rangle + \|y\|^2 && \text{by definition of } \textit{induced norm} && (\text{Theorem K.4 page 260})
 \end{aligned}$$

⇒

Theorem K.3 (Minkowski's Inequality). ¹⁰ Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ be an INNER PRODUCT SPACE. Let $\|\cdot\|$ be a function in $\mathbb{R}^{\mathbb{F}}$ such that $\|x\| \triangleq \sqrt{\langle x | x \rangle}$.¹¹

T H M $\|x + y\| \leq \|x\| + \|y\| \quad \forall x, y \in X$

PROOF:

$$\begin{aligned}
 \|x + y\|^2 &= \|x\|^2 + 2\Re \langle x | y \rangle + \|y\|^2 && \text{by } \textit{Polar Identity} && (\text{Lemma K.1 page 259}) \\
 &\leq \|x\|^2 + 2|\langle x | y \rangle| + \|y\|^2 \\
 &\leq \|x\|^2 + 2\sqrt{\langle x | x \rangle}\sqrt{\langle y | y \rangle} + \|y\|^2 && \text{by } \textit{Cauchy-Schwarz Inequality} && (\text{Theorem K.2 page 256}) \\
 &= (\|x\| + \|y\|)^2
 \end{aligned}$$

⇒

Theorem K.4 (induced norm). ¹² Let $\Omega \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ be an INNER PRODUCT SPACE (Definition K.1 page 255).

T H M $\|x\| \triangleq \sqrt{\langle x | x \rangle} \implies \|\cdot\| \text{ is a NORM}$

PROOF: For a function to be a norm, it must satisfy the four properties listed in Definition L.1 (page 271).

1. Proof that $\|\cdot\|$ is a norm:

- (a) Proof that $\|x\| > 0$ for $x \neq 0$ (non-negative):
By Definition K.1 page 255, all inner products have this property.
- (b) Proof that $\|x\| = 0 \iff x = 0$ (non-isometric):
By Definition K.1, all inner products have this property.
- (c) Prove $\|ax\| = |a| \|x\|$ (homogeneous):

$$\|ax\| \triangleq \sqrt{\langle ax | ax \rangle} = \sqrt{aa^* \langle x | x \rangle} = \sqrt{|a|^2 \langle x | x \rangle} = |a| \|x\|$$

- (d) Proof that $\|x + y\| \leq \|x\| + \|y\|$ (subadditive): This is true by Minkowski's inequality page ??

¹⁰  Aliprantis and Burkinshaw (1998) pages 278–279 (Theorem 32.3),  Maligranda (1995),  Minkowski (1910) page 115

¹¹ The function $\|\cdot\|$ is a *norm* (Theorem K.4 page 260) and is called the *normed induced by the inner product* $\langle \triangle | \nabla \rangle$ (Definition K.2 page 261).

¹²  Aliprantis and Burkinshaw (1998), pages 278–279,  Haaser and Sullivan (1991) page 278



2. Proof that every inner product space is a normed linear space:

Since every inner product induces a norm, so every inner product space has a norm (the norm induced by the inner product) and is therefore a normed linear space.



Theorem K.4 (previous theorem) demonstrates that in any inner product space $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \triangleright \rangle)$, the function $\|x\| \triangleq \sqrt{\langle x | x \rangle}$ is a norm. That is, $\|x\|$ is the *norm induced by the inner product*. This norm is formally defined next.

Definition K.2. Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \triangleright \rangle)$ be an INNER PRODUCT SPACE (Definition K.1 page 255).

D E F The norm induced by the inner product $\langle \triangle | \triangleright \rangle$ is defined as

$$\|x\| \triangleq \sqrt{\langle x | x \rangle}$$

K.2.2 Inner products induced by norms

Theorem K.4 (page 260) demonstrates that if a *linear space* (Definition G.1 page 193) has an *inner product* (Definition K.1 page 255), then that inner product always induces a *norm* (Definition L.1 page 271), and the relationship between the two is simply $\|x\| = \sqrt{\langle x | x \rangle}$ (Definition K.2 page 261). But what about the converse? What if a linear space has a norm—can that norm also induce an inner product? The answer in general is “no”: Not all norms can induce an inner product. But a less harsh answer is “sometimes”: Some norms **can** induce inner products. This leads to some important and interesting questions:

1. How many different inner products can be induced from a single norm? The answer turns out to be **at most** one, but maybe none (Theorem K.5 page 261).
2. When a norm *can* induce an inner product, what is that (unique) inner product? The inner product expressed in terms of the norm is given by the *Polarization Identity* (Theorem K.6 page 262).
3. Which norms can induce an inner product and which ones cannot? The answer is that norms that satisfy the *parallelogram law* (Theorem K.7 page 263) **can** induce an inner product; and the ones that don't, cannot (Theorem K.7 page 263).

Theorem K.5.¹³ Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$ be a NORMED LINEAR SPACE (Definition L.1 page 271).

T H M
$$\underbrace{\exists \langle \triangle | \triangleright \rangle \text{ and } (\cdot | \cdot) \text{ such that } \|x\|^2 = \langle x | x \rangle = (x | x) \quad \forall x \in X}_{\text{If a norm is induced by two inner products...}} \Rightarrow \underbrace{\langle x | y \rangle = (x | y)}_{\dots \text{then those two inner products are equivalent.}} \quad \forall x, y \in X$$

¹³ Aliprantis and Burkinshaw (1998), page 280, Bollobás (1999), page 132, Jordan and von Neumann (1935) page 721

PROOF:

$$\begin{aligned}
 2 \langle x | y \rangle &= [\langle x | y \rangle + \langle y | x \rangle] + [\langle x | y \rangle - \langle y | x \rangle] \\
 &= [\langle x | y \rangle + \langle y | x \rangle] + i [-i \langle x | y \rangle + i \langle y | x \rangle] \\
 &= [\langle x | y \rangle + \langle y | x \rangle] + i [-\langle ix | y \rangle - \langle y | ix \rangle] \\
 &= \left(\underbrace{[\langle x | y \rangle + \langle y | x \rangle + \langle x | x \rangle + \langle y | y \rangle]}_{\langle x+y | x+y \rangle} - \underbrace{[\langle x | x \rangle + \langle y | y \rangle]}_{\text{residue}} \right) \\
 &\quad - i \left(\underbrace{[\langle ix | y \rangle + \langle y | ix \rangle + \langle ix | ix \rangle + \langle y | y \rangle]}_{\langle ix+y | ix+y \rangle} - \underbrace{[\langle ix | ix \rangle + \langle y | y \rangle]}_{\text{residue}} \right) \\
 &= ([\langle x+y | x+y \rangle] - [\langle x | x \rangle + \langle y | y \rangle]) - i ([\langle ix+y | ix+y \rangle] - [\langle ix | ix \rangle + \langle y | y \rangle]) \\
 &= ([\langle x+y | x+y \rangle] - [\langle x | x \rangle + \langle y | y \rangle]) - i ([\langle ix+y | ix+y \rangle] - [\langle ix | ix \rangle + \langle y | y \rangle]) \\
 &= \left(\underbrace{[\langle x | y \rangle + \langle y | x \rangle + \langle x | x \rangle + \langle y | y \rangle]}_{\langle x+y | x+y \rangle} - \underbrace{[\langle x | x \rangle + \langle y | y \rangle]}_{\text{residue}} \right) \\
 &\quad - i \left(\underbrace{[\langle ix | y \rangle + \langle y | ix \rangle + \langle ix | ix \rangle + \langle y | y \rangle]}_{\langle ix+y | ix+y \rangle} - \underbrace{[\langle ix | ix \rangle + \langle y | y \rangle]}_{\text{residue}} \right) \\
 &= [\langle x | y \rangle + \langle y | x \rangle] + i [-\langle ix | y \rangle - \langle y | ix \rangle] \\
 &= [\langle x | y \rangle + \langle y | x \rangle] + i [-i \langle x | y \rangle + i \langle y | x \rangle] \\
 &= [\langle x | y \rangle + \langle y | x \rangle] + [\langle x | y \rangle - \langle y | x \rangle] \\
 &= 2 \langle x | y \rangle
 \end{aligned}$$



Theorem K.6 (Polarization Identities). ¹⁴ Let $\Omega \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ be a linear space, $\langle \Delta | \nabla \rangle \in \mathbb{F}^{X \times X}$ a function, and $\|x\| \triangleq \sqrt{\langle x | x \rangle}$.

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$(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \Delta | \nabla \rangle)$ is an inner product space \implies

$$4 \langle x | y \rangle = \underbrace{\begin{cases} \|x+y\|^2 - \|x-y\|^2 + i \|x+iy\|^2 - i \|x-iy\|^2 & \text{for } \mathbb{F} = \mathbb{C} \quad \forall x, y \in X \\ \|x+y\|^2 - \|x-y\|^2 & \text{for } \mathbb{F} = \mathbb{R} \quad \forall x, y \in X \end{cases}}_{\text{inner product induced by norm}}$$

PROOF:

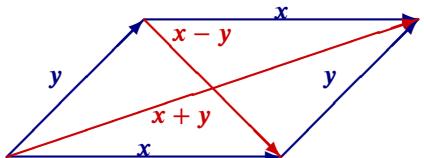
- These follow directly from properties of *bilinear functionals* (Theorem ?? page ??).

¹⁴ Berberian (1961) pages 29–30 (Theorem II.3.3), Istrățescu (1987) page 110 (Proposition 4.1.5), Bollobás (1999), page 132, Jordan and von Neumann (1935) page 721

2. Alternative proof for $\mathbb{F} = \mathbb{C}$ case:

$$\begin{aligned}
& \|x + y\|^2 - \|x - y\|^2 + i \|x + iy\|^2 - i \|x - iy\|^2 \\
&= \underbrace{\|x\|^2 + \|y\|^2 + 2\Re \langle x | y \rangle}_{\langle x + y | x + y \rangle} - \underbrace{(\|x\|^2 + \|y\|^2 + 2\Re \langle x | -y \rangle)}_{\langle x - y | x - y \rangle} \\
&\quad + i \underbrace{(\|x\|^2 + \|y\|^2 + 2\Re \langle x | iy \rangle)}_{i \langle x + iy | x + iy \rangle} - i \underbrace{(\|x\|^2 + \|y\|^2 + 2\Re \langle x | -iy \rangle)}_{i \langle x - iy | x - iy \rangle} \quad \text{by Lemma K.1 page 259} \\
&= \underbrace{\|x\|^2 + \|y\|^2 + 2\Re \langle x | y \rangle}_{\langle x + y | x + y \rangle} - \underbrace{(\|x\|^2 + \|y\|^2 - 2\Re \langle x | y \rangle)}_{\langle x - y | x - y \rangle} \\
&\quad + i \underbrace{(\|x\|^2 + \|y\|^2 + 2\Re \langle x | iy \rangle)}_{i \langle x + iy | x + iy \rangle} - i \underbrace{(\|x\|^2 + \|y\|^2 - 2\Re \langle x | iy \rangle)}_{i \langle x - iy | x - iy \rangle} \quad \text{by Definition K.1 page 255} \\
&= 4\Re \langle x | y \rangle + 4i\Re \langle x | iy \rangle \\
&= 2 \underbrace{(\langle x | y \rangle + \langle x | y \rangle^*)}_{4\Re \langle x | y \rangle} + 2i \underbrace{(\langle x | iy \rangle + \langle x | iy \rangle^*)}_{4i\Re \langle x | iy \rangle} \\
&= 2 (\langle x | y \rangle + \langle x | y \rangle^*) + 2i (i^* \langle x | y \rangle + (i^{**}) \langle x | y \rangle^*) \\
&= 2 (\langle x | y \rangle + \langle x | y \rangle^*) + 2i (-i \langle x | y \rangle + i \langle x | y \rangle^*) \quad \text{by Definition K.1 page 255} \\
&= 2 \langle x | y \rangle + 2 \langle x | y \rangle^* + 2 \langle x | y \rangle - 2 \langle x | y \rangle^* \\
&= 4 \langle x | y \rangle
\end{aligned}$$

⇒



In plane geometry (\mathbb{R}^2), the *parallelogram law* states that the sum of the squares of the lengths of the sides of a parallelogram is equal to the sum of the squares of the lengths of its diagonals. This is illustrated in the figure to the left.

Actually, the parallelogram law can be generalized to *any inner product space* (not just in the plane). And if the parallelogram law happens to hold true in a normed linear space, then that normed linear space is actually an *inner product space*. The parallelogram law and its relation to inner product spaces is stated in the next theorem.

Theorem K.7 (Parallelogram law). ¹⁵ Let $\Omega \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ and $\|x\| \triangleq \sqrt{\langle x | x \rangle}$.

T H M	Ω is an inner product space	\iff	$\underbrace{2\ x\ ^2 + 2\ y\ ^2}_{\text{PARALLELOGRAM LAW / VON NEUMANN-JORDAN CONDITION}} = \ x + y\ ^2 + \ x - y\ ^2$	$\forall x, y \in \Omega$
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PROOF:

1. Proof that $[\exists \langle x | y \rangle \text{ such that } \|x\|^2 = \langle x | x \rangle] \implies [\text{parallelogram law is true}]$:

$$\begin{aligned}
\|x + y\|^2 + \|x - y\|^2 &= [\|x\|^2 + \|y\|^2 + 2\Re_e [2\langle x | y \rangle]] + [\|x\|^2 + \|y\|^2 + 2\Re_e [2\langle x | -y \rangle]] \\
&\quad \text{by Lemma K.1 page 259} \\
&= [\|x\|^2 + \|y\|^2 + 2\Re_e [2\langle x | y \rangle]] + [\|x\|^2 + \|y\|^2 - 2\Re_e [2\langle x | y \rangle]] \\
&= 2\|x\|^2 + 2\|y\|^2
\end{aligned}$$

¹⁵ Amir (1986), page 8, Istrățescu (1987) page 110, Day (1973), page 151, Halmos (1998a), page 14, Aliprantis and Burkinshaw (1998) pages 280–281 (Theorem 32.6), Riesz (1934) page 36?, Jordan and von Neumann (1935) pages 721–722

2. Proof that $[\exists \langle x | y \rangle \text{ such that } \|x\|^2 = \langle x | x \rangle] \iff [\text{parallelogram law is true}]$:

Note that if an inner product exists in the norm linear space $(\Omega, \|\cdot\|)$, then that norm linear space is actually an inner product space $(X, +, \cdot, (\mathbb{F}, +, \dot{\times}), \langle \triangle | \nabla \rangle)$. And if it is an inner product space, then by Theorem K.6 page 262 that inner product must be given by the **Polarization Identity**

$$\langle x | y \rangle = \|ax + y\|^2 - \|ax - y\|^2 + i \|ax + iy\|^2 - i \|ax - iy\|^2.$$

Therefore, here we must use the parallelogram law to show that the bilinear function $f(x, y) \triangleq \langle x | y \rangle$ given on the left hand side of the “=” relation is indeed an inner product—that is, that it satisfies the requirements of Definition K.1 page 255.

(a) Proof that $\langle x | x \rangle \geq 0$ (non-negative):

$$\begin{aligned} 4 \langle x | x \rangle &\triangleq \|x + x\|^2 - \cancel{\|x - x\|^2}^0 + i \|x + ix\|^2 - i \|x - ix\|^2 && \text{by Polarization Identity} \\ &= \|2x\|^2 - 0 + i (\|x + ix\|^2 - \|x - ix\|^2) && \text{by Definition L.1 page 271} \\ &= |2|^2 \|x\|^2 + i (\|x + ix\|^2 - |i| \|x - ix\|^2) \\ &= 4 \|x\|^2 + i (\|x + ix\|^2 - \|ix + x\|^2) && \text{by Definition L.1 page 271} \\ &= 4 \|x\|^2 && \cancel{\|ix + x\|^2}^0 \\ &\geq 0 && \text{by Definition L.1 page 271} \end{aligned}$$

(b) Proof that $\langle x | x \rangle = 0 \iff x = 0$ (non-isotropic):

$$\begin{aligned} 4 \langle x | x \rangle &= 4 \|x\|^2 && \text{by result of part (a)} \\ &= 0 \iff x = 0 && \text{by Definition L.1 page 271} \end{aligned}$$

(c) Proof that $\langle x + u | y \rangle = \langle x | y \rangle + \langle u | y \rangle$ (additive):¹⁶

$$\begin{aligned} 4 \langle x + y | z \rangle &= 8 \left\langle \frac{x+y}{2} | z \right\rangle && \text{by Definition K.1 page 255} \\ &= 2 \left\| \frac{x+y}{2} + z \right\|^2 - 2 \left\| \frac{x+y}{2} - z \right\|^2 \\ &\quad + 2i \left\| \frac{x+y}{2} + z \right\|^2 - 2i \left\| \frac{x+y}{2} - iz \right\|^2 && \text{by Polarization Identity} \\ &= \left(2 \left\| \frac{x+y}{2} + z \right\|^2 + 2 \left\| \frac{x-y}{2} \right\|^2 \right) \\ &\quad - \left(2 \left\| \frac{x+y}{2} - z \right\|^2 + 2 \left\| \frac{x-y}{2} \right\|^2 \right) \\ &\quad + \left(2i \left\| \frac{x+y}{2} + z \right\|^2 + 2i \left\| \frac{x-y}{2} \right\|^2 \right) \\ &\quad - \left(2i \left\| \frac{x+y}{2} - iz \right\|^2 + 2i \left\| \frac{x-y}{2} \right\|^2 \right) \\ &= (\|x+z\|^2 + \|y+z\|^2) - (\|x-z\|^2 + \|y-z\|^2) \\ &\quad + (i \|x+z\|^2 + i \|y+z\|^2) - (i \|x-iz\|^2 + i \|y-iz\|^2) && \text{by parallelogram law} \\ &= (\|x+z\|^2 - \|x-z\|^2 + i \|x+z\|^2 - i \|x-iz\|^2) \\ &\quad + (\|y+z\|^2 - \|y-z\|^2 + i \|y+z\|^2 - i \|y-iz\|^2) \\ &= 4 \langle x | z \rangle + 4 \langle y | z \rangle && \text{by Polarization Identity} \end{aligned}$$

¹⁶ Aliprantis and Burkinshaw (1998), page 281



(d) Proof that $\langle \mathbf{x} | \mathbf{y} \rangle = \langle \mathbf{y} | \mathbf{y} \rangle^*$ (*conjugate symmetric*):

$$\begin{aligned}
 4 \langle \mathbf{x} | \mathbf{y} \rangle &\triangleq \|\mathbf{x} + \mathbf{y}\|^2 - \|\mathbf{x} - \mathbf{y}\|^2 + i \|\mathbf{x} + i\mathbf{y}\|^2 - i \|\mathbf{x} - i\mathbf{y}\|^2 && \text{by Polarization Identity} \\
 &= \|\mathbf{y} + \mathbf{x}\|^2 - \|\mathbf{y} - \mathbf{x}\|^2 + i \|i(\mathbf{y} - i\mathbf{x})\|^2 - i \|-i(\mathbf{y} + i\mathbf{x})\|^2 && \text{by Definition G.1 page 193} \\
 &= \|\mathbf{y} + \mathbf{x}\|^2 - \|\mathbf{y} - \mathbf{x}\|^2 + i \|\mathbf{y} - i\mathbf{x}\|^2 - i \|\mathbf{y} + i\mathbf{x}\|^2 && \text{by Definition L.1 page 271} \\
 &= (\|\mathbf{y} + \mathbf{x}\|^2 - \|\mathbf{y} - \mathbf{x}\|^2 - i \|\mathbf{y} - i\mathbf{x}\|^2 + i \|\mathbf{y} + i\mathbf{x}\|^2)^* \\
 &= (\|\mathbf{y} + \mathbf{x}\|^2 - \|\mathbf{y} - \mathbf{x}\|^2 + i \|\mathbf{y} + i\mathbf{x}\|^2 - i \|\mathbf{y} - i\mathbf{x}\|^2)^* \\
 &\triangleq 4 \langle \mathbf{y} | \mathbf{x} \rangle^* && \text{by } \textit{Polarization Identity}
 \end{aligned}$$

(e) Proof that $\langle \alpha \mathbf{x} | \mathbf{y} \rangle = \alpha \langle \mathbf{x} | \mathbf{y} \rangle$ (*homogeneous*):¹⁷

i. Proof that $\langle \alpha \mathbf{x} | \mathbf{y} \rangle$ is linear in α :

$$\begin{aligned}
 0 &\leq \|\alpha \mathbf{x} + \mathbf{y}\| - \|\beta \mathbf{x} + \mathbf{y}\| && \text{by Definition F.4 page 192} \\
 &\leq \|(\alpha \mathbf{x} + \mathbf{y}) - (\beta \mathbf{x} + \mathbf{y})\| && \text{by Theorem L.2 page 272} \\
 &\leq \|(\alpha - \beta)\mathbf{x}\|
 \end{aligned}$$

This implies that as $\alpha \rightarrow \beta$, $\|\alpha \mathbf{x} + \mathbf{y}\| \rightarrow \|\beta \mathbf{x} + \mathbf{y}\|$, which by definition implies that $\|\alpha \mathbf{x} + \mathbf{y}\|$ linear in α . And by the parallelogram law, $\langle \alpha \mathbf{x} | \mathbf{y} \rangle$ is also linear in α .

ii. Proof that $\langle n \mathbf{x} | \mathbf{y} \rangle = n \langle \mathbf{x} | \mathbf{y} \rangle$ for $n \in \mathbb{Z}$ (integer case):

A. Proof for $n = \pm 1$:

$$\begin{aligned}
 \langle n \mathbf{x} | \mathbf{y} \rangle &= \langle \pm 1 \mathbf{x} | \mathbf{y} \rangle && \text{by } n = \pm 1 \text{ hypothesis} \\
 &= \pm 1 \langle \mathbf{x} | \mathbf{y} \rangle && \text{by definition of inner product} && \text{(Definition K.1 page 255)} \\
 &= n \langle \mathbf{x} | \mathbf{y} \rangle && \text{by } n = \pm 1 \text{ hypothesis}
 \end{aligned}$$

B. Proof for $n = 0$:

$$\begin{aligned}
 \langle n \mathbf{x} | \mathbf{y} \rangle &= \langle 0 \mathbf{x} | \mathbf{y} \rangle && \text{by } n = 0 \text{ hypothesis} \\
 &= \langle \mathbf{x} - \mathbf{x} | \mathbf{y} \rangle \\
 &= \langle \mathbf{x} | \mathbf{y} \rangle + \langle -1 \mathbf{x} | \mathbf{y} \rangle \\
 &= \langle \mathbf{x} | \mathbf{y} \rangle - 1 \langle \mathbf{x} | \mathbf{y} \rangle \\
 &= \langle \mathbf{x} | \mathbf{y} \rangle - \langle \mathbf{x} | \mathbf{y} \rangle \\
 &= 0 \langle \mathbf{x} | \mathbf{y} \rangle \\
 &= n \langle \mathbf{x} | \mathbf{y} \rangle && \text{by } n = 0 \text{ hypothesis}
 \end{aligned}$$

C. Proof for $n = \pm 2$:

$$\begin{aligned}
 \langle n \mathbf{x} | \mathbf{y} \rangle &= \langle \pm 2 \mathbf{x} | \mathbf{y} \rangle && \text{by } n = \pm 1 \text{ hypothesis} \\
 &= \langle \pm(\mathbf{x} + \mathbf{x}) | \mathbf{y} \rangle \\
 &= \pm \langle \mathbf{x} + \mathbf{x} | \mathbf{y} \rangle && \text{by definition of inner product} && \text{(Definition K.1 page 255)} \\
 &= \pm (\langle \mathbf{x} | \mathbf{y} \rangle + \langle \mathbf{x} | \mathbf{y} \rangle) && \text{by additive property} \\
 &= \pm 2 \langle \mathbf{x} | \mathbf{y} \rangle \\
 &= n \langle \mathbf{x} | \mathbf{y} \rangle && \text{by } n = \pm 2 \text{ hypothesis}
 \end{aligned}$$

D. Proof that $[n \text{ case}] \implies [n \pm 1 \text{ case}]$:

$$\begin{aligned}
 \langle (n \pm 1) \mathbf{x} | \mathbf{y} \rangle &= \langle n \mathbf{x} \pm 1 \mathbf{x} | \mathbf{y} \rangle \\
 &= \langle n \mathbf{x} | \mathbf{y} \rangle + \langle \pm 1 \mathbf{x} | \mathbf{y} \rangle && \text{by additive property} \\
 &= n \langle \mathbf{x} | \mathbf{y} \rangle \pm 1 \langle \mathbf{x} | \mathbf{y} \rangle && \text{by left hypothesis} \\
 &= (n \pm 1) \langle \mathbf{x} | \mathbf{y} \rangle
 \end{aligned}$$

¹⁷  Aliprantis and Burkinshaw (1998), page 138

iii. Proof that $\langle qx | y \rangle = q \langle x | y \rangle$ for $q \in \mathbb{Q}$ (rational number case):

$$\begin{aligned} \frac{n}{m} \langle x | y \rangle &= \frac{n}{m} \left\langle \frac{m}{m} x | y \right\rangle && \text{where } n, m \in \mathbb{Z} \text{ and } m \neq 0 \\ &= \frac{nm}{m} \left\langle \frac{1}{m} x | y \right\rangle && \text{by previous result} \\ &= \frac{m}{m} \left\langle \frac{n}{m} x | y \right\rangle && \text{by previous result} \\ &= \left\langle \frac{n}{m} x | y \right\rangle \end{aligned}$$

iv. Proof that $\langle rx | y \rangle = r \langle x | y \rangle$ for all $r \in \mathbb{R}$ (real number case):

Because \mathbb{Q} is dense in \mathbb{R} and because $\|ax + y\|$ is continuous in a , so $\langle ax | y \rangle = a \langle x | y \rangle$ for all $a \in \mathbb{R}$.

v. Proof that $\langle cx | y \rangle = c \langle x | y \rangle$ for all $c \in \mathbb{C}$ (complex number case):

No proof at this time.



Remark K.1. ¹⁸ The inner product has already been defined in Definition K.1 (page 255) as a bilinear function that is *non-negative*, *non-isotropic*, *homogeneous*, *additive*, and *conjugate symmetric*. However, given a normed linear space, we could alternatively define the inner product using the *parallelogram law* (Theorem K.7 page 263) together with the *Polarization Identity* (Theorem K.6 page 262). Under this new definition, an inner product *exists* if the parallelogram law is satisfied, and is *specified*, in terms of the norm, by the Polarization Identity.

Of the uncountably infinite number of ℓ_F^p norms, only the norm for $p = 2$ induces an inner product (Proposition K.1, next).

Proposition K.1. ¹⁹ Let $\|(x_n)_{n \in \mathbb{Z}}\|_p$ be the ℓ_F^p norm of the sequence (x_n) in the space ℓ_F^p .

P R P	$\ (x_n)\ _p$ induces an inner product $\iff p = 2$
-------------	---

PROOF:

1. Proof that $\|\cdot\|_p$ induces an inner product $\iff p = 2$ (using the *Parallelogram law* page 263):

$$\begin{aligned} &\|x + y\|_p^2 + \|x - y\|_p^2 \\ &= \|x + y\|_2^2 + \|x - y\|_2^2 && \text{by right hypothesis} \\ &= \left(\sum_{n \in \mathbb{Z}} |x_n + y_n|^2 \right)^{\frac{2}{2}} + \left(\sum_{n \in \mathbb{Z}} |x_n - y_n|^2 \right)^{\frac{2}{2}} && \text{by definition of } \|\cdot\|_p \\ &= \sum_{n \in \mathbb{Z}} (x_n + y_n)(x_n + y_n)^* + \sum_{n \in \mathbb{Z}} (x_n - y_n)(x_n - y_n)^* \\ &= \sum_{n \in \mathbb{Z}} \left(|x_n|^2 + |y_n|^2 + 2\Re(x_n y_n) \right) + \sum_{n \in \mathbb{Z}} \left(|x_n|^2 + |y_n|^2 - 2\Re(x_n y_n) \right) \\ &= 2 \sum_{n \in \mathbb{Z}} |x_n|^2 + 2 \sum_{n \in \mathbb{Z}} |y_n|^2 \\ &= 2 \|x\|_2^2 + 2 \|y\|_2^2 && \text{by definition of } \|\cdot\|_p \\ &= 2 \|x\|_p^2 + 2 \|y\|_p^2 && \text{by right hypothesis} \\ &\implies \|\cdot\|_2 \text{ induces an inner product} && \text{by Theorem K.7 page 263} \end{aligned}$$

¹⁸ Loomis (1953), pages 23–24, Kubrusly (2001) page 317

¹⁹ Kubrusly (2001) pages 318–319 (Example 5B)



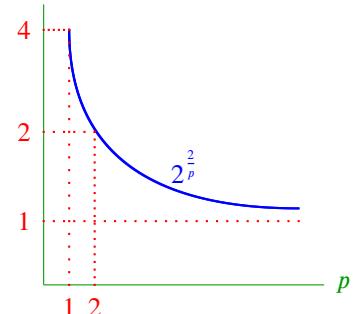
2. Proof that $\|\cdot\|_p$ induces an inner product $\implies p = 2$:

(a) Let $x \triangleq (1, 0)$ and $y \triangleq (0, 1)$. Then ²⁰

$$\begin{aligned}
 \|x + y\|_p^2 + \|x - y\|_p^2 &= \left(\sum_{n \in \mathbb{Z}} |x_n + y_n|^p \right)^{\frac{2}{p}} + \left(\sum_{n \in \mathbb{Z}} |x_n - y_n|^p \right)^{\frac{2}{p}} && \text{by definition of } \|\cdot\|_p \\
 &= (|1+0|^p + |0+1|^p)^{\frac{2}{p}} + (|1-0|^p + |0-1|^p)^{\frac{2}{p}} && \text{by definitions of } x \text{ and } y \\
 &= 2^{\frac{2}{p}} + 2^{\frac{2}{p}} \\
 &= 2 \cdot 2^{\frac{2}{p}} \\
 2 \|x\|_p^2 + 2 \|y\|_p^2 &= 2 \left(\sum_{n \in \mathbb{Z}} |x_n|^p \right)^{\frac{2}{p}} + 2 \left(\sum_{n \in \mathbb{Z}} |y_n|^p \right)^{\frac{2}{p}} && \text{by definition of } \|\cdot\|_p \\
 &= 2(|1|^p + |0|^p)^{\frac{2}{p}} + 2(|1|^p + |0|^p)^{\frac{2}{p}} && \text{by definitions of } x \text{ and } y \\
 &= 2 + 2 \\
 &= 4 \\
 2 \cdot 2^{\frac{2}{p}} = 4 &\iff 2^{\frac{2}{p}} = 2 \\
 &\implies p = 2
 \end{aligned}$$

(b) Proof that $2^{2/p}$ is monotonic decreasing in p (and so $p = 2$ is the only solution):

$$\begin{aligned}
 \frac{d}{dp} 2^{\frac{2}{p}} &= \frac{d}{dp} e^{\ln 2^{\frac{2}{p}}} \\
 &= \left(e^{\ln 2^{\frac{2}{p}}} \right) \frac{d}{dp} \ln 2^{\frac{2}{p}} \\
 &= \left(2^{\frac{2}{p}} \right) \frac{d}{dp} (2 \ln 2) \frac{1}{p} \\
 &= \left(2^{\frac{2}{p}} \right) 2 \ln 2 \left(-\frac{1}{p^2} \right) \\
 &< 0 \quad \forall p \in (0, \infty)
 \end{aligned}$$



K.3 Orthogonality

Definition K.3.

D E F The **Kronecker delta function** $\bar{\delta}_n$ is defined as $\bar{\delta}_n \triangleq \begin{cases} 1 & \text{for } n = 0 \\ 0 & \text{for } n \neq 0 \end{cases}$ $\forall n \in \mathbb{Z}$

Definition K.4. Let $(X, +, \cdot, (\mathbb{F}, +, \times), \langle \triangle | \triangleright \rangle)$ be an INNER PRODUCT SPACE (Definition K.1 page 255).

²⁰ <http://groups.google.com/group/sci.math/msg/531b1173f08871e9>

Two vectors x and y in X are **orthogonal** if

$$\langle x | y \rangle = \begin{cases} 0 & \text{for } x \neq y \\ c \in \mathbb{F} \setminus 0 & \text{for } x = y \end{cases}$$

The notation $x \perp y$ implies x and y are **ORTHOGONAL**.

A set $Y \in 2^X$ is **orthogonal** if $x \perp y \quad \forall x, y \in Y$.

A set Y is **orthonormal** if it is ORTHOGONAL and $\langle y | y \rangle = 1 \quad \forall y \in Y$.

A sequence $(x_n \in X)_{n \in \mathbb{Z}}$ is **orthogonal** if $\langle x_n | x_m \rangle = c \delta_{nm}$ for some $c \in \mathbb{R} \setminus 0$.

A sequence $(x_n \in X)_{n \in \mathbb{Z}}$ is **orthonormal** if $\langle x_n | x_m \rangle = \delta_{nm}$.

The definition of the orthogonality relation \perp has several immediate consequences (next theorem):

Theorem K.8. ²¹ Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \triangledown \rangle)$ be an INNER PRODUCT SPACE.

T H M	<ol style="list-style-type: none"> 1. $x \perp x \iff x = 0 \quad \forall x \in X$ 2. $x \perp y \implies \alpha x \perp y \quad \forall \alpha \in \mathbb{R}, x, y \in X \quad (\text{HOMOGENEOUS})$ 3. $x \perp y \iff y \perp x \quad \forall x, y \in X \quad (\text{SYMMETRY})$ 4. $x \perp y \text{ and } y \perp z \implies x \perp (y + z) \quad \forall x, y, z \in X \quad (\text{ADDITIVE})$ 5. $\exists \beta \in \mathbb{R} \text{ such that } x \perp (\beta x + y) \quad \forall x \in X \setminus 0, y \in X$
-------------	--

Theorem K.9. Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \triangledown \rangle)$ be an INNER PRODUCT SPACE.

T H M	$\left. \begin{array}{l} 1. \langle x y \rangle = 0 \text{ and} \\ 2. x + y = 0 \end{array} \right\} \iff \left\{ \begin{array}{l} 1. x = 0 \text{ and} \\ 2. y = 0 \end{array} \right. \quad \forall x, y \in X$
-------------	---

PROOF:

1. Proof that $x = y = 0$:

$$\begin{aligned}
 0 &= \langle 0 | 0 \rangle && \text{by non-isotropic property of } \langle \triangle | \triangledown \rangle \text{ (Definition K.1 page 255)} \\
 &= \langle x + y | x + y \rangle && \text{by left hypothesis 2} \\
 &= \langle x | x + y \rangle + \langle y | x + y \rangle && \text{by additive property of } \langle \triangle | \triangledown \rangle \text{ (Definition K.1 page 255)} \\
 &= \langle x | x \rangle + \langle x | y \rangle + \langle x | y \rangle^* + \langle y | y \rangle && \text{by conjugate symmetric and additive properties of } \langle \triangle | \triangledown \rangle \\
 &= \underbrace{\langle x | x \rangle}_{\geq 0} + 0 + 0 + \underbrace{\langle y | y \rangle}_{\geq 0} && \text{by left hypothesis 1} \\
 &\implies x = 0 \text{ and } y = 0 && \text{by non-negative and non-isotropic properties of } \langle \triangle | \triangledown \rangle
 \end{aligned}$$

2. Proof that $\langle x | y \rangle = 0$:

$$\begin{aligned}
 \langle x | y \rangle &= \langle 0 | 0 \rangle && \text{by right hypotheses} \\
 &= 0 && \text{by non-isotropic property of } \langle \triangle | \triangledown \rangle \text{ (Definition K.1 page 255)}
 \end{aligned}$$

3. Proof that $x + y = 0$:

$$\begin{aligned}
 x + y &= 0 + 0 && \text{by right hypotheses} \\
 &= 0
 \end{aligned}$$



The *triangle inequality* for vectors in a normed linear space (Theorem L.1 page 271) demonstrates that

$\left\| \sum_{n=1}^N x_n \right\| \leq \sum_{n=1}^N \|x_n\|$. The *Pythagorean Theorem* (next) demonstrates that this *inequality* becomes *equality* when the set $\{x_n\}$ is *orthogonal*.

²¹ James (1945), page 292, Drljević (1989) page 232

Theorem K.10 (Pythagorean Theorem). ²² Let $\{x_n \in X \mid n=1,2,\dots,N\}$ be a set of vectors in an INNER PRODUCT SPACE (Definition K.1 page 255) $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ and let $\|x\| \triangleq \sqrt{\langle x | x \rangle}$ (Definition K.2 page 261).

T
H
M

$$\{x_n\} \text{ is ORTHOGONAL} \iff \left\| \sum_{n=1}^N x_n \right\|^2 = \sum_{n=1}^N \|x_n\|^2 \quad \forall N \in \mathbb{N}$$

PROOF: 1. Proof for (\implies) case:

$$\begin{aligned} \left\| \sum_{n=1}^N x_n \right\|^2 &= \left\langle \sum_{n=1}^N x_n \mid \sum_{m=1}^N x_m \right\rangle && \text{by def. of } \|\cdot\| && \text{(Definition L.1 page 271)} \\ &= \sum_{n=1}^N \sum_{m=1}^N \langle x_n \mid x_m \rangle && \text{by def. of } \langle \triangle | \nabla \rangle && \text{(Definition K.1 page 255)} \\ &= \sum_{n=1}^N \sum_{m=1}^N \langle x_n \mid x_m \rangle \bar{\delta}_{n-m} && \text{by left hypothesis} \\ &= \sum_{n=1}^N \langle x_n \mid x_n \rangle && \text{by def. of } \bar{\delta} && \text{(Definition K.3 page 267)} \\ &= \sum_{n=1}^N \|x_n\|^2 && \text{by def. of } \|\cdot\| && \text{(Definition L.1 page 271)} \end{aligned}$$

2. Proof for (\impliedby) case:

$$\begin{aligned} 4 \langle x \mid y \rangle &= \|x + y\|^2 - \|x - y\|^2 + i \|x + iy\|^2 - i \|x - iy\|^2 && \text{by polarization identity (Theorem K.6 page 262)} \\ &= (\|x\|^2 + \|y\|^2) - (\|x\|^2 + \|y\|^2) + i (\|x\|^2 + \|y\|^2) - i (\|x\|^2 + \|y\|^2) && \text{by right hypothesis} \\ &= (\|x\|^2 + \|y\|^2) - (\|x\|^2 + | -1 |^2 \|y\|^2) + i (\|x\|^2 + |i|^2 \|y\|^2) - i (\|x\|^2 + | -i |^2 \|y\|^2) && \text{by definition of } \|\cdot\| \\ &= (\|x\|^2 + \|y\|^2) - (\|x\|^2 + \|y\|^2) + i (\|x\|^2 + \|y\|^2) - i (\|x\|^2 + \|y\|^2) && \text{by def. of } |\cdot| \text{ (Definition F.4 page 192)} \\ &= 0 \end{aligned}$$



²² Aliprantis and Burkinshaw (1998) pages 282–283 (Theorem 32.7), Kubrusly (2001) page 324 (Proposition 5.8), Bollobás (1999) pages 132–133 (Theorem 3)



APPENDIX L

NORMED LINEAR SPACES

L.1 Definition and basic results

Definition L.1. ¹ Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ be a LINEAR SPACE (Definition G.1 page 193) and $|\cdot| \in \mathbb{R}^{\mathbb{F}}$ the ABSOLUTE VALUE function (Definition F.4 page 192).

A functional $\|\cdot\|$ in \mathbb{R}^X is a **norm** if

- | | | | | |
|-----|------------------------------------|--|------------------------------------|-----|
| DEF | 1. $\ x\ \geq 0$ | $\forall x \in X$ | (STRICTLY POSITIVE) | and |
| | 2. $\ x\ = 0 \iff x = 0$ | $\forall x \in X$ | (NONDEGENERATE) | and |
| | 3. $\ \alpha x\ = \alpha \ x\ $ | $\forall x \in X, \alpha \in \mathbb{C}$ | (HOMOGENEOUS) | and |
| | 4. $\ x + y\ \leq \ x\ + \ y\ $ | $\forall x, y \in X$ | (SUBADDITIVE/TRIANGLE INEQUALITY). | |

A normed linear space is the tuple $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$.

The definition of the *norm* (Definition L.1 page 271) requires that any two vectors in a norm space be *subadditive* (they satisfy the *triangle inequality* property) such that $\|x_1 + x_2\| \leq \|x_1\| + \|x_2\|$. Actually, in **any** normed linear space, this property holds true for **any** finite number of vectors—not just two—such that $\|x_1 + x_2 + \dots + x_N\| \leq \|x_1\| + \|x_2\| + \dots + \|x_N\|$ (next theorem).

Theorem L.1 (triangle inequality). ² Let $(x_n \in X)_1^N$ be an N-TUPLE (Definition R.1 page 353) of vectors in a NORMED LINEAR SPACE $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$.

THM	$\left\ \sum_{n=1}^N x_n \right\ \leq \sum_{n=1}^N \ x_n\ \quad \forall N \in \mathbb{N}, x_n \in V$
-----	---

PROOF: Proof is by induction:

¹ Aliprantis and Burkinshaw (1998), pages 217–218, Banach (1932a), page 53, Banach (1932b), page 33, Banach (1922) page 135

² Michel and Herget (1993), page 344, Euclid (circa 300BC) (Book I Proposition 20)

1. Proof for the $N = 1$ case:

$$\begin{aligned} \left\| \sum_{n=1}^1 \mathbf{x}_n \right\| &= \|\mathbf{x}_1\| \\ &= \sum_{n=1}^1 \|\mathbf{x}_1\| \end{aligned}$$

2. Proof for the $N = 2$ case:

$$\begin{aligned} \left\| \sum_{n=1}^2 \mathbf{x}_n \right\| &= \left\| \sum_{n=1}^2 \mathbf{x}_n \right\| \\ &= \|\mathbf{x}_1 + \mathbf{x}_2\| \\ &\leq \|\mathbf{x}_1\| + \|\mathbf{x}_2\| && \text{by Definition L.1 page 271 (triangle inequality)} \\ &= \sum_{n=1}^2 \|\mathbf{x}_n\| \end{aligned}$$

3. Proof that [N case] \implies [$N + 1$ case]:

$$\begin{aligned} \left\| \sum_{n=1}^{N+1} \mathbf{x}_n \right\| &= \left\| \sum_{n=1}^N \mathbf{x}_n + \mathbf{x}_{N+1} \right\| \\ &\leq \left\| \sum_{n=1}^N \mathbf{x}_n \right\| + \|\mathbf{x}_{N+1}\| && \text{by Definition L.1 page 271 (triangle inequality)} \\ &\leq \sum_{n=1}^N \|\mathbf{x}_n\| + \|\mathbf{x}_{N+1}\| && \text{by left hypothesis} \\ &= \sum_{n=1}^{N+1} \|\mathbf{x}_n\| \end{aligned}$$



Theorem L.2 (Reverse Triangle Inequality). ³ Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$ be a NORMED LINEAR SPACE (Definition L.1 page 271).

T	$\underbrace{\ \ \mathbf{x}\ - \ \mathbf{y}\ \ }_{\text{REVERSE TRIANGLE INEQUALITY}} \leq \ \mathbf{x} - \mathbf{y}\ \quad \forall \mathbf{x}, \mathbf{y} \in X$	H M
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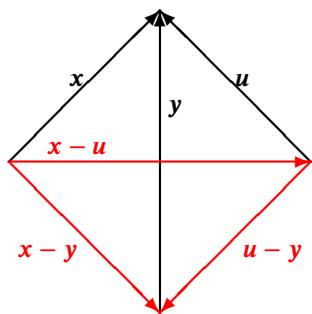
PROOF:

$$\begin{aligned} \|\|\mathbf{x}\| - \|\mathbf{y}\|\| &= \|(\|\mathbf{x}\| - \|\mathbf{y}\|) + \|\mathbf{y}\| - \|\mathbf{y}\| \| \\ &\leq \|\|\mathbf{x}\| - \|\mathbf{y}\|\| + \|\|\mathbf{y}\| - \|\mathbf{y}\|\| && \text{by Definition L.1 page 271} \\ &= \|\|\mathbf{x}\| - \|\mathbf{y}\|\| \\ &= \|\mathbf{x} - \mathbf{y}\| && \text{by Definition L.1 page 271} \end{aligned}$$

$$\begin{aligned} \|\mathbf{x} - \mathbf{y}\| &\leq \|\mathbf{x} - \mathbf{0}\| + \|\mathbf{0} - \mathbf{y}\| \\ &= \|\mathbf{x}\| + |-1| \|\mathbf{y}\| && \text{by previous result with } u = 0 \\ &= \|\mathbf{x}\| + \|\mathbf{y}\| && \text{by Definition L.1 page 271} \end{aligned}$$



³ Aliprantis and Burkinshaw (1998), page 218, Giles (2000) page 2, Banach (1922) page 136



The shortest distance between two vectors is always the difference of the vectors. This is proven in next and illustrated to the left in the Euclidean space \mathbb{R}^2 (the plane)

Proposition L.1. ⁴ Let $(X, +, \cdot, (\mathbb{F}, +, \dot{\times}), \|\cdot\|)$ be a NORMED LINEAR SPACE (Definition L.1 page 271).

P **R** **P**
$$\|x - y\| \leq \|x - u\| + \|u - y\| \quad \forall x, y, u \in X$$

PROOF:

$$\begin{aligned} \|x - y\| &= \|(x - u) + (u - y)\| \\ &\leq \|x - u\| + \|u - y\| \end{aligned} \quad \text{by Definition L.1 page 271}$$

Example L.1 (The usual norm). ⁵ Let $\mathbb{R}^\mathbb{R}$ be the set of all functions with domain and range the set of *real numbers* \mathbb{R} .

E **X** The absolute value (Definition F.4 page 192) $|\cdot| \in \mathbb{R}^\mathbb{R}$ is a norm.

Example L.2 (l_p norms). Let $(x_n)_{n \in \mathbb{Z}}$ be a sequence (Definition R.1 page 353) of real numbers. An uncountably infinite number of norms is provided by the $\ell_p^{\mathbb{F}}$ norms $\|(x_n)\|_p$:

E **X**
$$\|(x_n)\|_p \triangleq \left(\sum_{n \in \mathbb{Z}} |x_n|^p \right)^{\frac{1}{p}}$$
 is a norm for $p \in [1 : \infty]$

L.2 Relationship between metrics and norms

L.2.1 Metrics generated by norms

The concept of *length* is very closely related to the concept of *distance*. Thus it is not surprising that a *norm* (a “length” function) can be used to define a *metric* (a “distance” function) on any *metric linear space* (Definition ?? page ??). Another way to say this is that the norm of a normed linear space *induces* a metric on this space. And so every normed linear space also has a metric. And because every normed linear space has a metric, **every normed linear space is also a metric space**. Actually this can be generalized one step further in that every metric space is also a *topological space*. And so **every normed linear space is also a topological space**. In symbols,

$$\text{normed linear space} \implies \text{metric space} \implies \text{topological space}.$$

⁴ Aliprantis and Burkinshaw (1998), page 218

⁵ Giles (1987), page 3

Theorem L.3. ⁶ Let $d \in \mathbb{R}^{X \times X}$ be a function on a REAL normed linear space $(X, +, \cdot, (\mathbb{R}, \dot{+}, \dot{\times}), \|\cdot\|)$. Let $B(x, r) \triangleq \{y \in X \mid \|y - x\| < r\}$ be the OPEN BALL of radius r centered at a point x .

T H M $d(x, y) \triangleq \|x - y\|$ is a metric on X

PROOF: The proof follows directly from the definition of a metric (not included in this text) the definition of *norm* (Definition L.1 page 271). \Rightarrow

The previous theorem defined a metric $d(x, y)$ induced by the norm $\|x\|$. The next definition defines this metric formally.

Definition L.2. ⁷ Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$ be a NORMED LINEAR SPACE (Definition L.1 page 271).

D E F The metric induced by the norm $\|\cdot\|$ is the function $d \in \mathbb{R}^X$ such that

$$d(x, y) \triangleq \|x - y\| \quad \forall x, y \in X$$

Due to its algebraic structure, every norm is *continuous* (Corollary L.1 page 274). This makes norm spaces very useful in analysis. For a function f to be *continuous*, for every $\epsilon > 0$ there must exist a $\delta > 0$ such that $|f(x + \delta) - f(x)| < \epsilon$. The *Reverse Triangle Inequality* (Theorem L.2 page 272) shows this to be true when $f(\cdot) \triangleq \|\cdot\|$.

Corollary L.1. ⁸ Let $\Omega \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$ be a NORMED LINEAR SPACE (Definition L.1 page 271).

C O R The norm $\|\cdot\|$ is CONTINUOUS in Ω .

PROOF: This follows from these concepts:

1. The fact that $d(x, y) \triangleq \|x - y\|$ is a *metric* (Theorem L.3 page 274).
2. *Continuity* in a metric space.
3. The *Reverse Triangle Inequality* (Theorem L.2 page 272).

Theorem L.4 (next) demonstrates that **all open or closed balls** in **any normed linear space** are *convex*. However, the converse is not true—that is, a metric not generated by a norm may still produce a ball that is convex.

Theorem L.4. ⁹ Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), d)$ be a METRIC LINEAR SPACE (Definition ?? page ??). Let B be the OPEN BALL $B(p, r) \triangleq \{x \in X \mid d(p, x) < r\}$ (open ball with respect to metric d centered at point p and with radius r).

T H M
$$\left. \begin{array}{l} \exists \|\cdot\| \in \mathbb{R}^X \text{ such that} \\ d(x, y) = \|y - x\| \\ d \text{ is generated by a norm} \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} 1. \quad B(x, r) = x + B(0, r) \\ 2. \quad B(0, r) = r B(0, 1) \\ 3. \quad B(x, r) \text{ is CONVEX} \\ 4. \quad x \in B(0, r) \iff -x \in B(0, r) \quad (\text{SYMMETRIC}) \end{array} \right.$$

⁶ Michel and Herget (1993), page 344, Banach (1932a) page 53

⁷ Giles (2000) page 1 (1.1 Definition)

⁸ Giles (2000) page 2

⁹ Giles (2000) page 2 (1.2 Remarks), Giles (1987) pages 22–26 (2.4 Theorem, 2.11 Theorem)

PROOF:

1. Proof that $d(x + z, y + vz) = d(x, y)$ (invariant):

$$\begin{aligned} d(x + z, y + vz) &= \|(y + vz) - (x + z)\| && \text{by left hypothesis} \\ &= \|y - x\| \\ &= d(x, y) && \text{by left hypothesis} \end{aligned}$$

2. Proof that $B(x, r) = x + B(0, r)$:

$$\begin{aligned} B(x, r) &= \{y \in X | d(x, y) < r\} && \text{by definition of open ball } B \\ &= \{y \in X | d(y - x, y - x) < r\} && \text{by right result 1.} \\ &= \{y \in X | d(0, y - x) < r\} \\ &= \{u + x \in X | d(0, u) < r\} && \text{let } u \triangleq y - x \\ &= x + \{u \in X | d(0, u) < r\} \\ &= x + B(0, r) && \text{by definition of open ball } B \end{aligned}$$

3. Proof that $B(0, r) = r B(0, 1)$:

$$\begin{aligned} B(0, r) &= \{y \in X | d(0, y) < r\} && \text{by definition of open ball } B \\ &= \left\{ y \in X | \frac{1}{r} d(0, y) < 1 \right\} \\ &= \left\{ y \in X | \frac{1}{r} \|y - 0\| < 1 \right\} && \text{by left hypothesis} \\ &= \left\{ y \in X | \left\| \frac{1}{r} y - \frac{1}{r} 0 \right\| < 1 \right\} && \text{by homogeneous property of } \|\cdot\| \text{ page 271} \\ &= \left\{ y \in X | d\left(\frac{1}{r} 0, \frac{1}{r} y\right) < 1 \right\} && \text{by left hypothesis} \\ &= \{ru \in X | d(0, u) < 1\} && \text{let } u \triangleq \frac{1}{r} y \\ &= r \{u \in X | d(0, u) < 1\} \\ &= r B(0, 1) && \text{by definition of open ball } B \end{aligned}$$

4. Proof that $B(p, r)$ is convex:

We must prove that for any pair of points x and y in the open ball $B(p, r)$, any point $\lambda x + (1 - \lambda)y$ is also in the open ball. That is, the distance from any point $\lambda x + (1 - \lambda)y$ to the ball's center p must be less than r .

$$\begin{aligned} d(p, \lambda x + (1 - \lambda)y) &= \|p - \lambda x - (1 - \lambda)y\| && \text{by left hypothesis} \\ &= \left\| \underbrace{\lambda p + (1 - \lambda)p - \lambda x - (1 - \lambda)y}_{p} \right\| \\ &= \|\lambda p - \lambda x + (1 - \lambda)p - (1 - \lambda)y\| \\ &\leq \|\lambda p - \lambda x\| + \|(1 - \lambda)p - (1 - \lambda)y\| && \text{by subadditivity property of } \|\cdot\| \text{ page 271} \\ &= |\lambda| \|p - x\| + |1 - \lambda| \|p - y\| && \text{by homogeneous property of } \|\cdot\| \text{ page 271} \\ &= \lambda \|p - x\| + (1 - \lambda) \|p - y\| && \text{because } 0 \leq \lambda \leq 1 \\ &\leq \lambda r + (1 - \lambda)r && \text{because } x, y \text{ are in the ball } B(p, r) \\ &= r \end{aligned}$$

5. Proof that $x \in B(\mathbf{0}, r) \iff -x \in B(\mathbf{0}, r)$ (symmetric):

$$\begin{aligned}
 x \in B(\mathbf{0}, r) &\iff x \in \{y \in X \mid d(\mathbf{0}, y) < r\} && \text{by definition of open ball } B \\
 &\iff x \in \{y \in X \mid \|y - \mathbf{0}\| < r\} && \text{by left hypothesis} \\
 &\iff x \in \{y \in X \mid \|y\| < r\} \\
 &\iff x \in \{y \in X \mid \|(-1)(-y)\| < r\} \\
 &\iff x \in \{y \in X \mid \| -1 \| \| -y \| < r\} && \text{by homogeneous property of } \|\cdot\| \text{ page 271} \\
 &\iff x \in \{y \in X \mid \| -y - \mathbf{0} \| < r\} \\
 &\iff x \in \{y \in X \mid d(\mathbf{0}, -y) < r\} && \text{by left hypothesis} \\
 &\iff x \in \{-u \in X \mid d(\mathbf{0}, u) < r\} && \text{let } u \triangleq -y \\
 &\iff x \in (-\{u \in X \mid d(\mathbf{0}, u) < r\}) \\
 &\iff x \in (-B(\mathbf{0}, r)) \\
 &\iff -x \in B(\mathbf{0}, r)
 \end{aligned}$$

⇒

Theorem L.4 (page 274) demonstrates that if a metric d in a metric space $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), d)$ is generated by a norm, then the ball $B(x, r)$ in that metric linear space is *convex*. However, the converse is not true. That is, it is possible for the balls in a metric space (Y, p) to be *convex*, but yet the metric p not be generated by a norm.

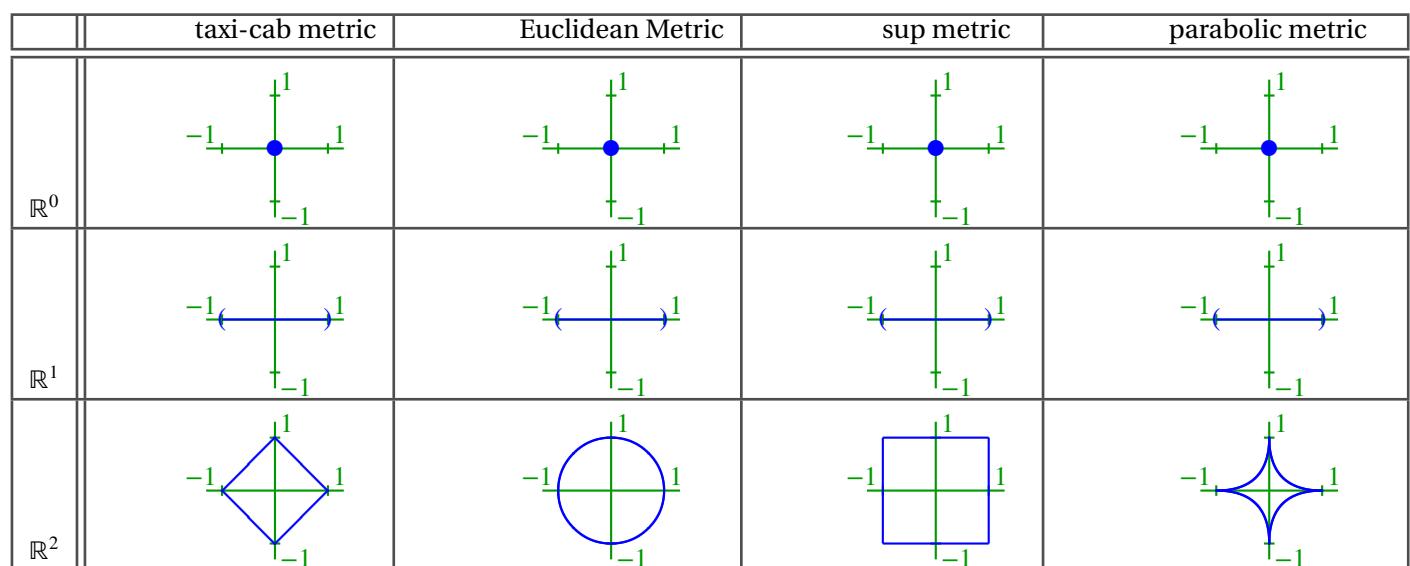


Figure L.1: Open balls in (\mathbb{R}^0, d_n) , (\mathbb{R}, d_n) , (\mathbb{R}^2, d_n) , and (\mathbb{R}^3, d_n) .

L.2.2 Norms generated by metrics

Every normed linear space is also a metric linear space (Theorem L.3 page 274). That is, a metric linear space generates a *normed linear space*. However, the converse is not true—not every metric linear space is a *normed linear space*. A characterization of metric linear spaces that *are* normed linear spaces is given by Theorem L.5 page 277.

Lemma L.1.¹⁰ Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), d)$ be a METRIC LINEAR SPACE. Let $\|x\| \triangleq d(x, \mathbf{0}) \forall x \in X$.

¹⁰ Oikhberg and Rosenthal (2007), page 599

L E M

$$\underbrace{d(x+z, y+z) = d(x, y) \quad \forall x, y, z \in X}_{\text{TRANSLATION INVARIANT}} \implies \begin{cases} 1. \quad \|x\| = \|-x\| & \forall x \in X \quad \text{and} \\ 2. \quad \|x\| = 0 \iff x = 0 & \forall x \in X \quad \text{and} \\ 3. \quad \|x+y\| \leq \|x\| + \|y\| & \forall x, y \in X \end{cases}$$

PROOF:

1. Proof that $\|x\| = \|-x\|$:

$$\begin{aligned} \|x\| &= d(x, 0) && \text{by definition of } \|\cdot\| \\ &= d(x - x, 0 - x) && \text{by translation invariance hypothesis} \\ &= d(0, -x) \\ &= \|-x\| && \text{by definition of } \|\cdot\| \end{aligned}$$

2a. Proof that $\|x\| = 0 \implies x = 0$:

$$\begin{aligned} 0 &= \|x\| && \text{by left hypothesis} \\ &= d(x, 0) && \text{by definition of } \|\cdot\| \\ &= d(x, 0) && \text{by definition of } \|\cdot\| \\ &\implies x = 0 && \text{by property of metrics} \end{aligned}$$

2b. Proof that $\|x\| = 0 \iff x = 0$:

$$\begin{aligned} \|x\| &= d(x, 0) && \text{by definition of } \|\cdot\| \\ &= d(0, 0) && \text{by right hypothesis} \\ &= 0 && \text{by property of metrics} \end{aligned}$$

3. Proof that $\|x+y\| \leq \|x\| + \|y\|$:

$$\begin{aligned} \|x+y\| &= d(x+y, 0) && \text{by definition of } \|\cdot\| \\ &= d(x+y - y, 0 - y) && \text{by translation invariance hypothesis} \\ &= d(x, -y) \\ &\leq d(x, 0) + d(0, y) && \text{by property of metrics} \\ &= d(x, 0) + d(y, 0) && \text{by property of metrics} \\ &= \|x\| + \|y\| && \text{by definition of } \|\cdot\| \end{aligned}$$



Theorem L.5. ¹¹ Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ be a LINEAR SPACE. Let $d(x, y) \triangleq \|x - y\| \forall x, y \in X$.

T H M

$$\left. \begin{array}{l} 1. \quad d(x+z, y+z) = d(x, y) \quad \forall x, y, z \in X \quad (\text{TRANSLATION INVARIANT}) \\ 2. \quad d(\alpha x, \alpha y) = |\alpha| d(x, y) \quad \forall x, y \in X, \alpha \in \mathbb{F} \quad (\text{HOMOGENEOUS}) \end{array} \right\} \iff \|\cdot\| \text{ is a NORM}$$

PROOF:

1. Proof of \implies assertion:

- (a) Proof that $\|\cdot\|$ is *strictly positive*: This follows directly from the definition of d .
- (b) Proof that $\|\cdot\|$ is *nondegenerate*: This follows directly from Lemma L.1 (page 276).
- (c) Proof that $\|\cdot\|$ is *homogeneous*: This follows from the second left hypothesis.

¹¹ Bollobás (1999), page 21

(d) Proof that $\|\cdot\|$ satisfies the *triangle-inequality*: This follows directly from Lemma L.1 (page 276).

2. Proof of \Leftarrow assertion:

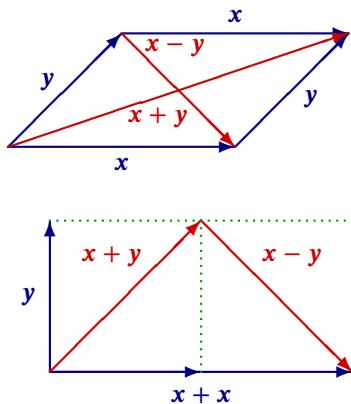
$$\begin{aligned}
 d(x+z, y+z) &= \|(x+z) - (y+z)\| && \text{by definition of } d \\
 &= \|x - y\| \\
 &= d(x, y) && \text{by definition of } d \\
 d(\alpha x, \alpha y) &= \|(\alpha x) - (\alpha y)\| && \text{by definition of } d \\
 &= \|\alpha(x - y)\| \\
 &= |\alpha| \|x - y\| && \text{by definition of } \|\cdot\| \text{ page 271} \\
 &= |\alpha| d(x, y) && \text{by definition of } d
 \end{aligned}$$

⇒

L.3 Orthogonality on normed linear spaces

Traditionally, *orthogonality* (Definition K.4 page 267) is a property defined in *inner product spaces* (Definition K.1 page 255). However, the concept of orthogonality can be extended to *normed linear spaces* (Definition L.1 page 271). Here are some examples:

- ① *Isosceles orthogonality*: Definition L.3 page 278
- ② *Pythagorean orthogonality*: Definition L.4 page 280
- ③ *Birkhoff orthogonality*: Definition L.5 page 280



Isosceles orthogonality (Definition L.3 page 278) can be illustrated using a *parallelogram*, as illustrated in the figure to the upper left. In this case, orthogonality implies that the parallelogram is a rectangle, which in turn implies that the lengths of the two diagonals are equal ($\|x + y\| = \|x - y\|$). Isosceles orthogonality can also be illustrated with a triangle where the sides are of lengths $\|x + y\|$ and $\|x - y\|$ and base of length $\|x + x\|$. In this case if x and y are orthogonal, then the triangle is *isosceles*. This is illustrated in figure to the lower left. Isosceles orthogonality is formally defined next.

Definition L.3. ¹² Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$ be a NORMED LINEAR SPACE (Definition L.1 page 271).

D E F Two vectors x and y are **orthogonal in the sense of James** if

$$\|x + y\| = \|x - y\|.$$

This property is also called **isosceles orthogonality** or **James orthogonality**.

Theorem L.6. Let $(X, +, \cdot, (\mathbb{R}, \dot{+}, \dot{\times}), \langle \Delta | \nabla \rangle)$ be an INNER-PRODUCT SPACE (Definition K.1 page 255) with induced norm $\|x\| \triangleq \sqrt{\langle x | x \rangle}$, ISOSCELES ORTHOGONALITY (Definition L.3 page 278) relation \oplus , and inner-product relation ORTHOGONALITY (Definition K.4 page 267) relation \perp .

T H M	$\underbrace{x \oplus y}_{\text{orthogonal in the sense of James}}$	\iff	$\underbrace{x \perp y}_{\text{orthogonal in the sense of inner-product space}}$
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¹² James (1945) page 292 (DEFINITION 2.1), Amir (1986) page 24, Dunford and Schwartz (1957), page 93

PROOF:

1. Proof that $x \odot y \implies x \perp y$:

$$\begin{aligned}
 & 4 \langle x | y \rangle \\
 &= \underbrace{\|x + y\|^2 - \|x - y\|^2}_{0 \text{ by } x \odot y \text{ hypothesis}} + i \|x + iy\|^2 - i \|x - iy\|^2 \quad \text{by polarization identity (Theorem K.6 page 262)} \\
 &= 0 + i \|x + iy\|^2 - i \|x - iy\|^2 \quad \text{by } x \odot y \text{ hypothesis} \\
 &= i [\|x\|^2 + \|y\|^2 + 2\Re \langle x | iy \rangle] \\
 &\quad - i [\|x\|^2 + \|y\|^2 + 2\Re \langle x | -iy \rangle] \quad \text{by Polar Identity (Lemma K.1 page 259)} \\
 &= i [\|x\|^2 + \|y\|^2 + 2\Re \langle x | iy \rangle] \\
 &\quad - i [\|x\|^2 + \|y\|^2 + 2\Re \langle x | -iy \rangle] \quad \text{by Definition L.1 page 271 and Definition K.1 page 255} \\
 &= 4i\Re \langle x | iy \rangle \\
 &= 4i\Re [i^* \langle x | y \rangle] \\
 &= 0 \quad \text{because inner-product space is real } (\mathbb{F} = \mathbb{R})
 \end{aligned}$$

2. Proof that $x \odot y \iff x \perp y$:

$$\begin{aligned}
 \|x + y\|^2 &= \|x\|^2 + \|y\|^2 + 2\Re \langle x | y \rangle \quad \text{by Polar Identity (Lemma K.1 page 259)} \\
 &= \|x\|^2 + \|y\|^2 + 0 \quad \text{by } x \perp y \text{ hypothesis} \\
 &= \|x\|^2 + \|y\|^2 - 2\Re \langle x | y \rangle \quad \text{0 when } x \perp y \quad \text{by } x \perp y \text{ hypothesis} \\
 &= \|x\|^2 + \|y\|^2 + 2\Re \langle x | -y \rangle \\
 &= \|x - y\|^2 \quad \text{by Polar Identity (Lemma K.1 page 259)}
 \end{aligned}$$



Theorem L.7. ¹³ Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$ be a normed linear space and with ISOSCELES ORTHOGONALITY (Definition L.3 page 278) relation \odot .

T H M	$x \odot y \iff y \odot x \iff \alpha x \odot \alpha y \quad \forall \alpha \in \mathbb{F}$
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PROOF:

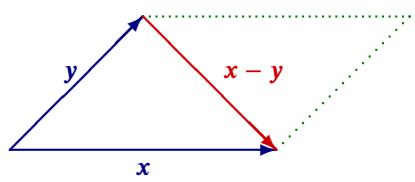
$$\begin{aligned}
 x \odot y \implies & \|x + y\| = \|x - y\| \quad \text{by Definition L.3 page 278} \\
 \implies & \|x + y\| = |-1| \|x - y\| \\
 \implies & \|x + y\| = \|(x - y)\| \quad \text{by Definition L.1 page 271} \\
 \implies & \|y + x\| = \|y - x\| \quad \text{by Definition G.1 page 193} \\
 \implies & y \odot x \quad \text{by Definition L.3 page 278}
 \end{aligned}$$

$$\begin{aligned}
 y \odot x \implies & \|y + x\| = \|y - x\| \quad \text{by Definition L.3 page 278} \\
 \implies & |\alpha| \|y + x\| = |\alpha| \|y - x\| \\
 \implies & \|\alpha(y + x)\| = \|\alpha(y - x)\| \quad \text{by Definition L.1 page 271} \\
 \implies & \|\alpha y + \alpha x\| = \|\alpha y - \alpha x\| \\
 \implies & \|\alpha x + \alpha y\| = \|-(\alpha x - \alpha y)\| \quad \text{by Definition G.1 page 193}
 \end{aligned}$$

¹³ Amir (1986) page 24

$$\begin{aligned} \Rightarrow \| \alpha x + \alpha y \| &= | -1 | \| \alpha x - \alpha y \| \\ \Rightarrow \| \alpha x + \alpha y \| &= \| \alpha x - \alpha y \| \\ \Rightarrow \alpha x \oplus \alpha y & \end{aligned} \quad \begin{array}{l} \text{by Definition L.1 page 271} \\ \text{by Definition F.4 page 192} \\ \text{by Definition L.3 page 278} \end{array}$$

$$\begin{aligned} \alpha x \oplus \alpha y \Rightarrow \| \alpha x + \alpha y \| &= \| \alpha x - \alpha y \| \\ \Rightarrow \| \alpha(x + y) \| &= \| \alpha(x - y) \| \\ \Rightarrow | \alpha | \| x + y \| &= | \alpha | \| x - y \| \\ \Rightarrow \| x + y \| &= \| x - y \| \\ \Rightarrow x \oplus y & \end{aligned} \quad \begin{array}{l} \text{by Definition L.3 page 278} \\ \text{by Definition G.1 page 193} \\ \text{by Definition L.1 page 271} \\ \text{by Definition L.1 page 271} \\ \text{by Definition L.3 page 278} \end{array}$$



If a triangle in a plane has two perpendicular sides of lengths a and b and a hypotenuse of length c , then by the *Pythagorean Theorem* (Theorem K.10 page 269), $a^2 + b^2 = c^2$. This concept of orthogonality can be generalized to normed linear spaces. Two vectors x and y (with lengths $\|x\|$ and $\|y\|$) are orthogonal when $\|x\|^2 + \|y\|^2 = \|x - y\|^2$ ($x - y$ is a kind of “hypotenuse”). This kind of orthogonality is defined next and illustrated in the figure to the left.

Definition L.4. ¹⁴ Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$ be a NORMED LINEAR SPACE (Definition L.1 page 271).

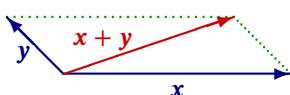
D E F Two vectors x and y are **orthogonal in the Pythagorean sense** if

$$\|x - y\|^2 = \|x\|^2 + \|y\|^2.$$

This relationship is also called **Pythagorean orthogonality**.

Theorem L.8. ¹⁵ Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ be an INNER-PRODUCT SPACE (Definition K.1 page 255) with induced norm $\|x\| \triangleq \sqrt{\langle x | x \rangle}$, PYTHAGOREAN ORTHOGONALITY (Definition L.4 page 280) relation \oplus , and inner-product relation ORTHOGONALITY (Definition K.4 page 267) relation \perp .

T H M	$\underbrace{x \oplus y}_{\text{orthogonal in the Pythagorean sense}}$	\iff	$\underbrace{x \perp y}_{\text{orthogonal in the sense of inner-product space}}$
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Besides *isosceles orthogonality* (Definition L.3 page 278), orthogonality in normed linear spaces can be defined using *Birkhoff orthogonality*, as defined in Definition L.5 (next) and illustrated to the left.

Definition L.5. ¹⁶ Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$ be a NORMED LINEAR SPACE (Definition L.1 page 271).

D E F Two vectors x and y are **orthogonal in the sense of Birkhoff** if

$$\|x\| \leq \|x + \alpha y\| \quad \forall \alpha \in \mathbb{F}.$$

This relationship is also called **Birkhoff orthogonality**.

Theorem L.9. Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ be an INNER-PRODUCT SPACE (Definition K.1 page 255) with induced norm $\|x\| \triangleq \sqrt{\langle x | x \rangle}$, BIRKHOFF ORTHOGONALITY relation \oplus (Definition L.5 page 280), and inner-product relation ORTHOGONALITY relation \perp (Definition K.4 page 267).

T H M	$\underbrace{x \oplus y}_{\text{orthogonal in the sense of Birkhoff}}$	\iff	$\underbrace{x \perp y}_{\text{orthogonal in the sense of inner-product space}}$
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¹⁴ James (1945) page 292 (DEFINITION 2.2), Amir (1986) page 57, Drljević (1989) page 232

¹⁵ Amir (1986) page 57

¹⁶ Amir (1986) page 33, Dunford and Schwartz (1957), page 93, James (1947) page 265

APPENDIX M

INTERVALS AND CONVEXITY

M.1 Intervals

In the real number system, for $a \leq b$, the *interval* $[a : b]$ is the set a and b and all the numbers inbetween, as in $[a : b] \triangleq \{x \in \mathbb{R} | a \leq x \leq b\}$. This concept can be easily generalized:

- In an **ordered set**, if two elements x and y are *comparable* and $x \leq y$, then we say that x and y and all the elements inbetween, as determined by the ordering relation \leq , are the interval $[a : b]$.
- In a **lattice**, the concept of the *interval* can be generalized even further. In an arbitrary ordered set, the interval $[x : y]$ of item (M.1) is restricted to the case in which x and y are *comparable*. This restriction can be lifted (Definition M.2 page 281) with the additional structure of upper and lower bounds provided by lattices.
- A **metric space** in general has no *order relation* \leq . But intervals can still be defined (Definition M.4 page 282) in a metric space in terms of the *triangle inequality*.
- A **linear space** (Definition G.1 page 193) over a real or complex field in general has no *order relation* that compares *vectors* in the space, but the standard order relation \leq for real numbers \mathbb{R} can still be used (Definition M.5 page 282) to define an interval in a linear space.

Definition M.1 (intervals on ordered sets). ¹ Let (X, \leq) be an ORDERED SET.

DEF	The set $[x : y] \triangleq \{z \in X x \leq z \leq y\}$ is called a closed interval and
	The set $(x : y] \triangleq \{z \in X x < z \leq y\}$ is called a half-open interval and
	The set $[x : y) \triangleq \{z \in X x \leq z < y\}$ is called a half-open interval and
	The set $(x : y) \triangleq \{z \in X x < z < y\}$ is called an open interval .

Definition M.2 (intervals on lattices). ² Let $(X, \vee, \wedge; \leq)$ be a LATTICE.

DEF	The set $[x : y] \triangleq \{z \in X x \wedge y \leq z \leq x \vee y\}$ is called a closed interval .
	The set $(x : y] \triangleq \{z \in X x \wedge y < z \leq x \vee y\}$ is called a half-open interval .
	The set $[x : y) \triangleq \{z \in X x \wedge y \leq z < x \vee y\}$ is called a half-open interval .
	The set $(x : y) \triangleq \{z \in X x \wedge y < z < x \vee y\}$ is called an open interval .

When x and y are comparable and $x \leq y$, then Definition M.2 (previous) simplifies to item (M.1)

¹ Apostol (1975) page 4, Ore (1935) page 409

² Duthie (1942) page 2, Ore (1935) page 425 (*quotient structures*)

(page 281).

Definition M.3.³ Let $L \triangleq (X, \vee, \wedge; \leq)$ be a LATTICE with dual L^* . Let $[x : y]$ be a CLOSED INTERVAL (Definition M.2 page 281) on set X . The sublattices $L[x : y]$ and $L^*[x : y]$ are defined as follows:

DEF	$L[x : y] \triangleq \{z \in L z \in [x : y]\} \quad \forall x, y \in X$
DEF	$L^*[x : y] \triangleq \{z \in L^* z \in [x : y]\} \quad \forall x, y \in X$

Definition M.4.⁴

DEF	In a METRIC SPACE (X, d) , the set $[a : b]$ is the closed interval from x to y and is defined as $[x : y] \triangleq \{z \in X d(x, z) + d(z, y) = d(x, y)\}.$ An element $z \in X$ is geodesically between x and y if $z \in [x : y]$.
-----	--

Definition M.5.⁵

DEF	In a LINEAR SPACE $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ (Definition G.1 page 193), $[x : y] \triangleq \{\lambda x + (1 - \lambda)y = z 0 \leq \lambda \leq 1\}$ is called a closed interval and $(x : y] \triangleq \{\lambda x + (1 - \lambda)y = z 0 < \lambda \leq 1\}$ is called a half-open interval and $[x : y) \triangleq \{\lambda x + (1 - \lambda)y = z 0 \leq \lambda < 1\}$ is called a half-open interval and $(x : y) \triangleq \{\lambda x + (1 - \lambda)y = z 0 < \lambda < 1\}$ is called an open interval .
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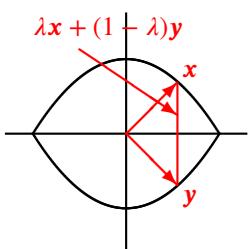
M.2 Convex sets

Using the concept of the *interval* (previous section), we can define the *convex set* (next definition).

Definition M.6.⁶ Let X be a SET in an ORDERED SET (X, \leq) , a LATTICE $(X, \vee, \wedge; \leq)$, a METRIC SPACE (X, d) , or a LINEAR SPACE $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$.

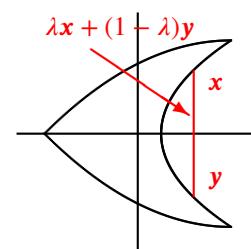
DEF	A subset $D \subseteq X$ is a convex set in X if $x, y \in D \implies [x : y] \subseteq D.$ A set that is not convex is concave .
-----	--

Example M.1. Consider the Euclidean space \mathbb{R}^2 (a special case of a linear space).



$\Leftarrow \begin{cases} \text{The figure to the left is a} \\ \text{convex set in } \mathbb{R}^2. \end{cases}$

$\Rightarrow \begin{cases} \text{The figure to the right is a} \\ \text{concave set in } \mathbb{R}^2. \end{cases}$



Example M.2. In a metric space, examples of *convex sets* are *convex balls*. Examples include those balls generated by the following metrics:

- Taxi-cab metric
- Euclidean metric
- Sup metric
- Tangential metric

³ Maeda and Maeda (1970), page 1

⁴ van de Vel (1993) page 8

⁵ Barvinok (2002) page 2

⁶ Barvinok (2002) page 5

Examples of metrics generating balls which are *not* convex include the following:

- ➊ Parabolic metric
- ➋ Exponential metric

M.3 Convex functions

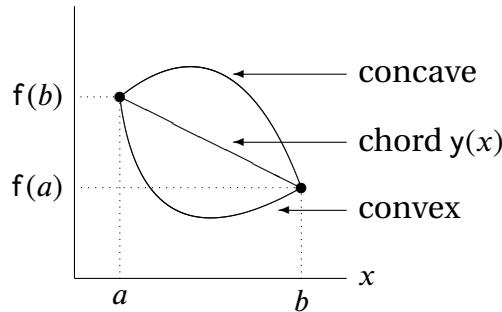


Figure M.1: Convex and concave functions

Definition M.7. ⁷ Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ be a LINEAR SPACE (Definition G.1 page 193) and D a CONVEX SET (Definition M.6 page 282) in X .

A function $f \in F^D$ is **convex** if

$$f(\lambda x + [1 - \lambda]y) \leq \lambda f(x) + (1 - \lambda) f(y) \quad \forall x, y \in D \text{ and } \forall \lambda \in (0, 1)$$

A function $g \in F^D$ is **strictly convex** if

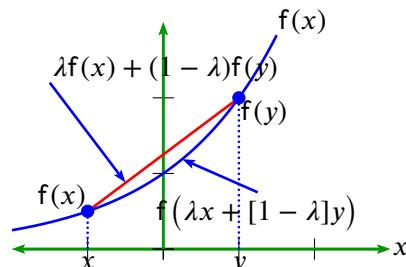
$$g(\lambda x + [1 - \lambda]y) = \lambda g(x) + (1 - \lambda) g(y) \quad \forall x, y \in D, x \neq y, \text{ and } \forall \lambda \in (0, 1)$$

A function $f \in F^D$ is **concave** if $-f$ is CONVEX.

A function $f \in F^D$ is **affine** iff is CONVEX and CONCAVE.

DEF

Example M.3. The function $f(x) = 2^x$ is a **convex function** (Definition M.7 page 283), as illustrated to the right.



Definition M.8. ⁸ Let $(X, +, \cdot, (\mathbb{R}, \dot{+}, \dot{\times}))$ be a LINEAR SPACE (Definition G.1 page 193).

The **epigraph** $\text{epi}(f)$ and **hypograph** $\text{hyp}(f)$ of a functional $f \in \mathbb{R}^X$ are defined as

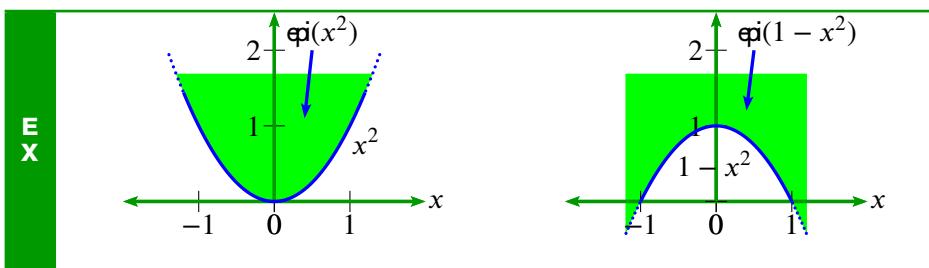
$$\text{epi}(f) \triangleq \{(x, y) \in X \times \mathbb{R} | y \geq f(x)\}$$

$$\text{hyp}(f) \triangleq \{(x, y) \in X \times \mathbb{R} | y \leq f(x)\}$$

Example M.4.

⁷ Simon (2011) page 2, Barvinok (2002) page 2, Bollobás (1999), page 3, Jensen (1906), page 176, Clarkson (1936) (strictly convex)

⁸ Beer (1993) page 13 (§1.3), Aubin and Frankowska (2009) page 222, Aubin (2011) page 223



Proposition M.1.⁹ Let $(X, +, \cdot, (\mathbb{R}, \dot{+}, \dot{\times}))$ be a LINEAR SPACE (Definition G.1 page 193). Let f be a FUNCTIONAL in \mathbb{R}^X .

P R P	$\left\{ \begin{array}{l} f \text{ is a} \\ \text{CONVEX FUNCTION} \end{array} \right\} \Leftrightarrow \left\{ \begin{array}{l} \text{epi}(f) \text{ is a} \\ \text{CONVEX SET} \end{array} \right\}$
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Often a function can be proven to be *convex* or *concave*. *Convex* and *concave* functions are defined in Definition M.9 (page 284) (next) and illustrated in Figure M.1 (page 283).

Definition M.9. Let

$$y(x) = \frac{f(b) - f(a)}{b - a}(x - a) + f(a).$$

A function $f : \mathbb{R} \rightarrow \mathbb{R}$ is

D E F	(1). convex in $(a : b)$ if $f(x) \leq y(x)$ for $x \in (a : b)$ (2). concave in $(a : b)$ if $f(x) \geq y(x)$ for $x \in (a : b)$ (3). strictly convex in $(a : b)$ if $f(x) < y(x)$ for $x \in (a : b)$ (4). strictly concave in $(a : b)$ if $f(x) > y(x)$ for $x \in (a : b)$
-------------	--

Theorem M.1 (Jensen's Inequality).¹⁰ Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ be a LINEAR SPACE (Definition G.1 page 193), D a subset of X , and f a functional in \mathbb{F}^D . Let \sum be the SUMMATION OPERATOR (Definition N.1 page 289).

T H M	$\left\{ \begin{array}{ll} 1. & D \text{ is CONVEX} \quad \text{and} \\ 2. & f \text{ is CONVEX} \quad \text{and} \\ 3. & \sum_{n=1}^N \lambda_n = 1 \quad (\text{WEIGHTS}) \end{array} \right\} \implies f\left(\sum_{n=1}^N \lambda_n x_n\right) \leq \sum_{n=1}^N \lambda_n f(x_n) \quad \forall x_n \in D, N \in \mathbb{N}$
-------------	--

PROOF: Proof is by induction:

1. Proof that statement is true for $N = 1$:

$$\begin{aligned} f\left(\sum_{n=1}^{N=1} \lambda_n x_n\right) &= f(\lambda_1 x_1) \\ &\leq f(\lambda_1 x_1) \\ &= \sum_{n=1}^{N=1} \lambda_n f(x_n) \end{aligned}$$

⁹ Udriste (1994) page 63, Kurdila and Zabarankin (2005) page 178 (Proposition 6.1.1), Rockafellar (1970) page 23 (Section 4 Convex Functions), Çinlar and Vanderbei (2013) page 86 (5.4 Theorem)

¹⁰ Mitrovic et al. (2010) page 6, Bollobás (1999) page 3, Lay (1982) page 7, Jensen (1906), pages 179–180



2. Proof that statement is true for $N = 2$:

$$\begin{aligned}
 f\left(\sum_{n=1}^{N=2} \lambda_n x_n\right) &= f(\lambda_1 x_1 + \lambda_2 x_2) \\
 &\leq \lambda_1 f(x_1) + \lambda_2 f(x_2) && \text{by convexity hypothesis} \\
 &= \sum_{n=1}^{N=2} \lambda_n f(x_n)
 \end{aligned}$$

3. Proof that if the statement is true for N , then it is also true for $N + 1$:

$$\begin{aligned}
 f\left(\sum_{n=1}^{N+1} \lambda_n x_n\right) &= f\left(\sum_{n=1}^N \lambda_n x_n + \lambda_{N+1} x_{N+1}\right) \\
 &= f\left([1 - \lambda_{N+1}] \sum_{n=1}^N \frac{\lambda_n}{1 - \lambda_{N+1}} x_n + \lambda_{N+1} x_{N+1}\right) \\
 &\leq [1 - \lambda_{N+1}] f\left(\sum_{n=1}^N \frac{\lambda_n}{1 - \lambda_{N+1}} x_n\right) + \lambda_{N+1} f(x_{N+1}) && \text{by convexity hypothesis} \\
 &\leq [1 - \lambda_{N+1}] \sum_{n=1}^N \frac{\lambda_n}{1 - \lambda_{N+1}} f(x_n) + \lambda_{N+1} f(x_{N+1}) && \text{by "true for } N\text{" hypothesis} \\
 &= \sum_{n=1}^N \lambda_n f(x_n) + \lambda_{N+1} f(x_{N+1}) \\
 &= \sum_{n=1}^{N+1} \lambda_n f(x_n)
 \end{aligned}$$

4. Since the statement is true for $N = 1$, $N = 2$, and true for $N \implies$ true for $N + 1$, then it is true for $N = 1, 2, 3, 4, \dots$



The next theorem gives another form of convex functions that is a little less intuitive but provides powerful analytic results.

Theorem M.2. Let $f : \mathbb{R} \rightarrow \mathbb{R}$. For every $x_1, x_2 \in (a, b)$ and $\lambda \in [0, 1]$

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f is convex in $(a, b) \iff f(\lambda x_1 + (1 - \lambda)x_2) \leq \lambda f(x_1) + (1 - \lambda)f(x_2)$

PROOF:

1. prove f is convex $\implies f(\lambda x_1 + (1 - \lambda)x_2) \leq \lambda f(x_1) + (1 - \lambda)f(x_2)$:

$$\begin{aligned}
 f(\lambda x_1 + (1 - \lambda)x_2) &\leq \frac{f(b) - f(a)}{b - a} [\lambda x_1 + (1 - \lambda)x_2 - a] + f(a) \\
 &= \frac{f(x_2) - f(x_1)}{x_2 - x_1} [\lambda x_1 + (1 - \lambda)x_2 - x_1] + f(x_1) \\
 &= \frac{f(x_2) - f(x_1)}{x_2 - x_1} [(x_2 - x_1)(1 - \lambda)] + f(x_1) \\
 &= (1 - \lambda)f(x_2) - (1 - \lambda)f(x_1) + f(x_1) \\
 &= \lambda f(x_1) + (1 - \lambda)f(x_2)
 \end{aligned}$$

2. prove f is convex $\iff f(\lambda x_1 + (1 - \lambda)x_2) \leq \lambda f(x_1) + (1 - \lambda)f(x_2)$:

Let $x = \lambda(b - a) + a$ Notice that as λ varies from 0 to 1, x varies from b to a . So free variable λ works as a change of variable for free variable x .

$$\begin{aligned}\lambda &= \frac{x - a}{b - a} \\ f(x) &= f(\lambda(b - a) + a) \\ &\leq \lambda f(b) + (1 - \lambda)f(a) \\ &= \lambda[f(b) - f(a)] + f(a) \\ &= \frac{f(b) - f(a)}{b - a}(x - a) + f(a)\end{aligned}$$

⇒

Taking the second derivative of a function provides a convenient test for whether that function is convex.

Theorem M.3. ¹¹

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$f''(x) > 0 \implies f$ is convex

PROOF:

$$\begin{aligned}f(x) &= f(x_0) + f'(x_0)(x - x_0) + f''(c)(x - x_0)^2 \\ &\geq f(x_0) + f'(x_0)(x - x_0) \\ &= f(x_0) + f'(x_0)(x - \lambda x_1 - (1 - \lambda)x_2)\end{aligned}$$

$$\begin{aligned}f(x_1) &\geq f(x_0) + f'(x_0)(x_1 - \lambda x_1 - (1 - \lambda)x_2) \\ &= f(x_0) + f'(x_0)(1 - \lambda)(x_1 - x_2) \\ &= f(x_0) - f'(x_0)(1 - \lambda)(x_2 - x_1)\end{aligned}$$

$$\begin{aligned}f(x_2) &\geq f(x_0) + f'(x_0)(x_2 - \lambda x_1 - (1 - \lambda)x_2) \\ &= f(x_0) + f'(x_0)\lambda(x_2 - x_1)\end{aligned}$$

$$\begin{aligned}\lambda f(x_1) + (1 - \lambda)f(x_2) &\geq \lambda [f(x_0) - f'(x_0)(1 - \lambda)(x_2 - x_1)] + (1 - \lambda) [f(x_0) + f'(x_0)\lambda(x_2 - x_1)] \\ &= \lambda [f(x_0) - f'(x_0)(1 - \lambda)(x_2 - x_1)] + [f(x_0) + f'(x_0)\lambda(x_2 - x_1)] - \lambda [f(x_0) + f'(x_0)\lambda(x_2 - x_1)] \\ &= f(x_0) \\ &= f(\lambda x_1 + (1 - \lambda)x_2)\end{aligned}$$

By Theorem M.2 (page 285), $f(x)$ is convex.

⇒

M.4 Literature

 **Literature survey:**

¹¹  Cover and Thomas (1991), pages 24–25



1. Abstract convexity:

- ☞ [Edelman and Jamison \(1985\)](#)
- ☞ [van de Vel \(1993\)](#)
- ☞ [Hörmander \(1994\)](#)

2. Order convexity (lattice theory):

- ☞ [Edelman \(1986\)](#)

3. Metric convexity:

- ☞ [Menger \(1928\)](#)
- ☞ [Blumenthal \(1970\) page 41 \(?\)](#)
- ☞ [Khamsi and Kirk \(2001\) pages 35–38](#)



APPENDIX N

FINITE SUMS



“I think that it was Harald Bohr who remarked to me that “all analysts spend half their time hunting through the literature for inequalities which they want to use and cannot prove.””¹

G.H. Hardy (1877–1947) in his “Presidential Address” to the London Mathematical Society on November 8, 1928, about a remark that he suggested was from Harald Bohr (1887–1951), Danish mathematician pictured to the left.¹

N.1 Summation

Definition N.1. ² Let $+$ be an addition operator on a tuple $(x_n)_m^N$.

The **summation** of (x_n) from index m to index N with respect to $+$ is

$$\sum_{n=m}^N x_n \triangleq \begin{cases} 0 & \text{for } N < m \\ \left(\sum_{n=m}^{N-1} x_n \right) + x_N & \text{for } N \geq m \end{cases}$$

Theorem N.1 (Generalized associative property). ³ Let $+$ be an addition operator on a tuple $(x_n)_m^N$.

$$\begin{aligned} + \text{ is ASSOCIATIVE} \implies & \sum_{n=m}^L x_n + \left(\sum_{n=L+1}^M x_n + \sum_{n=M+1}^N x_n \right) = \left(\sum_{n=m}^L x_n + \sum_{n=L+1}^M x_n \right) + \sum_{n=M+1}^N x_n \quad \text{for } m < L < M \leq N \\ & \underbrace{\sum_{n=m}^N x_n}_{\text{is ASSOCIATIVE}} \end{aligned}$$

PROOF:

¹ quote: [Hardy \(1929\)](#), page 64

image: http://www-history.mcs.st-andrews.ac.uk/PictDisplay/Bohr_Harald.html

² reference: [Berberian \(1961\) page 8](#) (Definition I.3.1)

“ Σ ” notation: [Fourier \(1820\)](#) page 280

³ [Berberian \(1961\)](#) pages 9–10 (Theorem I.3.1)

1. Proof for $N < m$ case: $\sum_{n=m}^N x_n = 0$.

2. Proof for $N = m$ case: $\sum_{n=m}^m x_n = \left(\sum_{n=m}^{m-1} x_n \right) + x_m = 0 + x_m = x_m$.

3. Proof for $N = m + 1$ case: $\sum_{n=m}^{m+1} x_n = \left(\sum_{n=m}^m x_n \right) + x_{m+1} = x_m + x_{m+1}$

4. Proof for $N = m + 2$ case:

$$\begin{aligned} \sum_{n=m}^{m+2} x_n &= \left(\sum_{n=m}^{m+1} x_n \right) + x_{m+2} && \text{by Definition N.1 page 289} \\ &= (x_m + x_{m+1}) + x_{m+2} && \text{by item (3)} \\ &= x_m + (x_{m+1} + x_{m+2}) && \text{by left hypothesis} \end{aligned}$$

5. Proof that N case $\implies N + 1$ case:

$$\begin{aligned} \sum_{n=m}^{N+1} x_n &= \underbrace{\left(\sum_{n=m}^N x_n \right)}_{\text{associative}} + x_{N+1} && \text{by Definition N.1 page 289} \\ &= \left(\sum_{n=m}^L x_n + \left(\sum_{n=L+1}^M x_n + \sum_{n=M+1}^N x_n \right) \right) + x_{N+1} && = \left(\left(\sum_{n=m}^L x_n + \sum_{n=L+1}^M x_n \right) + \sum_{n=M+1}^N x_n \right) + x_{N+1} \\ &= \left(\sum_{n=m}^L x_n + \sum_{n=L+1}^M x_n \right) + \left(\sum_{n=M+1}^N x_n + x_{N+1} \right) && = \left(\sum_{n=m}^L x_n + \sum_{n=L+1}^M x_n \right) + \left(\sum_{n=M+1}^{N+1} x_n \right) \end{aligned}$$

\iff

N.2 Means

N.2.1 Weighted ϕ -means

Definition N.2.⁴

The $(\lambda_n)_1^N$ weighted ϕ -mean of a tuple $(x_n)_1^N$ is defined as

$$M_\phi((x_n)) \triangleq \phi^{-1} \left(\sum_{n=1}^N \lambda_n \phi(x_n) \right)$$

where ϕ is a CONTINUOUS and STRICTLY MONOTONIC function in $\mathbb{R}^{\mathbb{R}^+}$

and $(\lambda_n)_{n=1}^N$ is a sequence of weights for which $\sum_{n=1}^N \lambda_n = 1$.

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⁴  Bollobás (1999) page 5



Lemma N.1. ⁵ Let $M_\phi(\langle x_n \rangle)$ be the $(\lambda_n)_1^N$ weighted ϕ -mean of a tuple $\langle x_n \rangle_1^N$. Let the property CONVEX be defined as in Definition M.7 (page 283).

LEM

$\phi\psi^{-1}$ is CONVEX and ϕ is INCREASING	$\implies M_\phi(\langle x_n \rangle) \geq M_\psi(\langle x_n \rangle)$
$\phi\psi^{-1}$ is CONVEX and ϕ is DECREASING	$\implies M_\phi(\langle x_n \rangle) \leq M_\psi(\langle x_n \rangle)$
$\phi\psi^{-1}$ is CONCAVE and ϕ is INCREASING	$\implies M_\phi(\langle x_n \rangle) \leq M_\psi(\langle x_n \rangle)$
$\phi\psi^{-1}$ is CONCAVE and ϕ is DECREASING	$\implies M_\phi(\langle x_n \rangle) \geq M_\psi(\langle x_n \rangle)$

PROOF:

1. Case where $\phi\psi^{-1}$ is *convex* and ϕ is *increasing*:

$$\begin{aligned}
 M_\phi(\langle x_n \rangle) &\triangleq \phi^{-1}\left(\sum_{n=1}^N \lambda_n \phi(x_n)\right) && \text{by definition of } M_\phi && (\text{Definition N.2 page 290}) \\
 &= \phi^{-1}\left(\sum_{n=1}^N \lambda_n \phi\psi^{-1}\psi(x_n)\right) && \text{by definition of } \psi^{-1} \\
 &\geq \phi^{-1}\left(\phi\psi^{-1} \sum_{n=1}^N \lambda_n \psi(x_n)\right) && \text{by Jensen's Inequality} && (\text{Theorem M.1 page 284}) \\
 &= \left(\psi^{-1} \sum_{n=1}^N \lambda_n \psi(x_n)\right) && \text{by definition of } \psi^{-1} \\
 &\triangleq M_\psi(\langle x_n \rangle) && \text{by definition of } M_\psi && (\text{Definition N.2 page 290})
 \end{aligned}$$

2. Case where $\phi\psi^{-1}$ is *convex* and ϕ is *decreasing*:

$$\begin{aligned}
 M_\phi(\langle x_n \rangle) &\triangleq \phi^{-1}\left(\sum_{n=1}^N \lambda_n \phi(x_n)\right) && \text{by definition of } M_\phi && (\text{Definition N.2 page 290}) \\
 &= \phi^{-1}\left(\sum_{n=1}^N \lambda_n \phi\psi^{-1}\psi(x_n)\right) && \text{by definition of } \psi^{-1} \\
 &\leq \phi^{-1}\left(\phi\psi^{-1} \sum_{n=1}^N \lambda_n \psi(x_n)\right) && \text{by Jensen's Inequality} && (\text{Theorem M.1 page 284}) \\
 &&& \text{and because } \phi^{-1} \text{ is decreasing} && (\text{by hypothesis}) \\
 &= \left(\psi^{-1} \sum_{n=1}^N \lambda_n \psi(x_n)\right) && \text{by definition of } \psi^{-1} \\
 &\triangleq M_\psi(\langle x_n \rangle) && \text{by definition of } M_\psi && (\text{Definition N.2 page 290})
 \end{aligned}$$



One of the most well known inequalities in mathematics is *Minkowski's Inequality* (1910, Theorem N.5 page 297). In 1946, H.P. Mulholland submitted a result⁶ that generalizes Minkowski's Inequality to an equal weighted ϕ -mean. And Milovanović and Milovanović (1979) generalized this even further to a *weighted* ϕ -mean (Theorem N.2, next).

Theorem N.2.

⁵ Pečarić et al. (1992) page 107, Bollobás (1999) page 5, Hardy et al. (1952) page 75

⁶ Mulholland (1950)

⁷ Milovanović and Milovanović (1979), Bullen (2003) page 306 (Theorem 9)

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$$\left\{ \begin{array}{l} (1). \phi \text{ is CONVEX} \\ (2). \phi \text{ is STRICTLY MONOTONIC} \end{array} \right. \text{ and } \left\{ \begin{array}{l} (3). \phi(0) = 0 \\ (4). \log \circ \phi \circ \exp \text{ is CONVEX} \end{array} \right. \text{ and } \left\{ \begin{array}{l} \left\{ \phi^{-1} \left(\sum_{n=1}^N \lambda_n \phi(x_n + y_n) \right) \leq \phi^{-1} \left(\sum_{n=1}^N \lambda_n \phi(x_n) \right) + \phi^{-1} \left(\sum_{n=1}^N \lambda_n \phi(y_n) \right) \right\} \end{array} \right\} \Rightarrow$$

N.2.2 Power means

Definition N.3.⁸ Let $M_{\phi(x;r)}(\{x_n\})$ be the $(\lambda_n)_1^N$ weighted ϕ -mean of a NON-NEGATIVE tuple $(x_n)_1^N$ (Definition N.2 page 290).

D E F A mean $M_{\phi(x;r)}(\{x_n\})$ is a **power mean** with parameter r if $\phi(x) \triangleq x^r$. That is,

$$M_{\phi(x;r)}(\{x_n\}) = \left(\sum_{n=1}^N \lambda_n (x_n)^r \right)^{\frac{1}{r}}$$

Theorem N.3.⁹ Let $M_{\phi(x;r)}(\{x_n\})$ be POWER MEAN with parameter r of an N -tuple $(x_n)_1^N$. Let \mathbb{R}^* be the set of extended real numbers ($\mathbb{R}^* \triangleq \mathbb{R} \cup \{-\infty, \infty\}$).¹⁰

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$$M_{\phi(x;r)}(\{x_n\}) \triangleq \left(\sum_{n=1}^N \lambda_n (x_n)^r \right)^{\frac{1}{r}} \text{ is CONTINUOUS and STRICTLY INCREASING in } \mathbb{R}^*.$$

$$M_{\phi(x;r)}(\{x_n\}) = \begin{cases} \min_{n=1,2,\dots,N} \{x_n\} & \text{for } r = -\infty \\ \prod_{n=1}^N x_n^{\lambda_n} & \text{for } r = 0 \\ \max_{n=1,2,\dots,N} \{x_n\} & \text{for } r = +\infty \end{cases}$$

PROOF:

1. Proof that $M_{\phi(x;r)}$ is strictly increasing in r :

- (a) Let r and s be such that $-\infty < r < s < \infty$.
- (b) Let $\phi_r \triangleq x^r$ and $\phi_s \triangleq x^s$. Then $\phi_r \phi_s^{-1} = x^{\frac{r}{s}}$.
- (c) The composite function $\phi_r \phi_s^{-1}$ is convex or concave depending on the values of r and s :

$r < 0$ (ϕ_r decreasing)	$r > 0$ (ϕ_r increasing)
--------------------------------	--------------------------------

$s < 0$	convex	(not possible)
$s > 0$	convex	concave

(d) Therefore by Lemma N.1 (page 291),
 $-\infty < r < s < \infty \implies M_{\phi(x;r)}(\{x_n\}) < M_{\phi(x;s)}(\{x_n\}).$

2. Proof that $M_{\phi(x;r)}$ is continuous in r for $r \in \mathbb{R} \setminus 0$: The sum of continuous functions is continuous. For the cases of $r \in \{-\infty, 0, \infty\}$, see the items that follow.

⁸ Bullen (2003) page 175, Bollobás (1999) page 6

⁹ Bullen (2003) pages 175–177 (see also page 203), Bollobás (1999) pages 6–8, Besso (1879), Bienaymé (1840) page 68

¹⁰ Rana (2002) pages 385–388 (Appendix A)

3. Lemma: $M_{\phi(x;-r)}(\langle x_n \rangle) = \{M_{\phi(x;r)}(\langle x_n^{-1} \rangle)\}^{-1}$. Proof:

$$\begin{aligned} \{M_{\phi(x;r)}(\langle x_n^{-1} \rangle)\}^{-1} &= \left\{ \left(\sum_{n=1}^N \lambda_n (x_n^{-1})^r \right)^{\frac{1}{r}} \right\}^{-1} && \text{by definition of } M_\phi \\ &= \left(\sum_{n=1}^N \lambda_n (x_n)^{-r} \right)^{\frac{1}{-r}} \\ &= M_{\phi(x;-r)}(\langle x_n \rangle) && \text{by definition of } M_\phi \end{aligned}$$

4. Proof that $\lim_{r \rightarrow \infty} M_\phi(\langle x_n \rangle) = \max_{n \in \mathbb{Z}} \langle x_n \rangle$:

(a) Let $x_m \triangleq \max_{n \in \mathbb{Z}} \langle x_n \rangle$

(b) Note that $\lim_{r \rightarrow \infty} M_\phi \leq \max_{n \in \mathbb{Z}} \langle x_n \rangle$ because

$$\begin{aligned} \lim_{r \rightarrow \infty} M_\phi(\langle x_n \rangle) &= \lim_{r \rightarrow \infty} \left(\sum_{n=1}^N \lambda_n x_n^r \right)^{\frac{1}{r}} && \text{by definition of } M_\phi \\ &\leq \lim_{r \rightarrow \infty} \left(\sum_{n=1}^N \lambda_n x_m^r \right)^{\frac{1}{r}} && \text{by definition of } x_m \text{ in item (4a) and because } \\ &&& \phi(x) \triangleq x^r \text{ and } \phi^{-1} \text{ are both increasing or both decreasing} \\ &= \lim_{r \rightarrow \infty} \left(x_m^r \underbrace{\sum_{n=1}^N \lambda_n}_1 \right)^{\frac{1}{r}} && \text{because } x_m \text{ is a constant} \\ &= \lim_{r \rightarrow \infty} (x_m^r \cdot 1)^{\frac{1}{r}} \\ &= x_m \\ &= \max_{n \in \mathbb{Z}} \langle x_n \rangle && \text{by definition of } x_m \text{ in item (4a)} \end{aligned}$$

(c) But also note that $\lim_{r \rightarrow \infty} M_\phi \geq \max_{n \in \mathbb{Z}} \langle x_n \rangle$ because

$$\begin{aligned} \lim_{r \rightarrow \infty} M_\phi(\langle x_n \rangle) &= \lim_{r \rightarrow \infty} \left(\sum_{n=1}^N \lambda_n x_n^r \right)^{\frac{1}{r}} && \text{by definition of } M_\phi \\ &\geq \lim_{r \rightarrow \infty} (w_m x_m^r)^{\frac{1}{r}} && \text{by definition of } x_m \text{ in item (4a) and because } \\ &&& \phi(x) \triangleq x^r \text{ and } \phi^{-1} \text{ are both increasing or both decreasing} \\ &= \lim_{r \rightarrow \infty} w_m^{\frac{1}{r}} x_m^r \\ &= x_m \\ &= \max_{n \in \mathbb{Z}} \langle x_n \rangle && \text{by definition of } x_m \text{ in item (4a)} \end{aligned}$$

(d) Combining items (b) and (c) we have $\lim_{r \rightarrow \infty} M_\phi = \max_{n \in \mathbb{Z}} \langle x_n \rangle$.

5. Proof that $\lim_{r \rightarrow -\infty} M_\phi(\langle x_n \rangle) = \min_{n \in \mathbb{Z}} \langle x_n \rangle$:

$$\begin{aligned}
 \lim_{r \rightarrow -\infty} M_{\phi(x;r)}(\langle x_n \rangle) &= \lim_{r \rightarrow \infty} M_{\phi(x;-r)}(\langle x_n \rangle) && \text{by change of variable } r \\
 &= \lim_{r \rightarrow \infty} \{M_{\phi(x;r)}(\langle x_n^{-1} \rangle)\}^{-1} && \text{by Lemma in item (3) page 293} \\
 &= \lim_{r \rightarrow \infty} \frac{1}{M_{\phi(x;r)}(\langle x_n^{-1} \rangle)} && \\
 &= \frac{\lim_{r \rightarrow \infty} 1}{\lim_{r \rightarrow \infty} M_{\phi(x;r)}(\langle x_n^{-1} \rangle)} && \text{by property of lim } ^{11} \\
 &= \frac{1}{\max_{n \in \mathbb{Z}} \langle x_n^{-1} \rangle} && \text{by item (4)} \\
 &= \frac{1}{\left(\min_{n \in \mathbb{Z}} \langle x_n \rangle \right)^{-1}} \\
 &= \min_{n \in \mathbb{Z}} \langle x_n \rangle
 \end{aligned}$$

6. Proof that $\lim_{r \rightarrow 0} M_\phi(\langle x_n \rangle) = \prod_{n=1}^N x_n^{\lambda_n}$:

$$\begin{aligned}
 \lim_{r \rightarrow 0} M_\phi(\langle x_n \rangle) &= \lim_{r \rightarrow 0} \exp \{ \ln \{ M_\phi(\langle x_n \rangle) \} \} \\
 &= \lim_{r \rightarrow 0} \exp \left\{ \ln \left\{ \left(\sum_{n=1}^N \lambda_n (x_n^r) \right)^{\frac{1}{r}} \right\} \right\} && \text{by definition of } M_\phi \\
 &= \exp \left\{ \frac{\frac{\partial}{\partial r} \ln \left(\sum_{n=1}^N \lambda_n (x_n^r) \right)}{\frac{\partial}{\partial r} r} \right\}_{r=0} && \text{by l'Hôpital's rule}^{12} \\
 &= \exp \left\{ \frac{\sum_{n=1}^N \lambda_n \frac{\partial}{\partial r} (x_n^r)}{\sum_{n=1}^N \lambda_n (x_n^r)} \right\}_{r=0} \\
 &= \exp \left\{ \frac{\sum_{n=1}^N \lambda_n \frac{\partial}{\partial r} \exp(r \ln(x_n))}{1} \right\}_{r=0} \\
 &= \exp \left\{ \sum_{n=1}^N \lambda_n \exp \{ r \ln(x_n) \} \ln(x_n) \right\}_{r=0} \\
 &= \exp \left\{ \sum_{n=1}^N \lambda_n \ln(x_n) \right\} \\
 &= \exp \left\{ \ln \prod_{n=1}^N x_n^{\lambda_n} \right\} = \prod_{n=1}^N x_n^{\lambda_n}
 \end{aligned}$$

¹¹  Rudin (1976) page 85 (4.4 Theorem)

¹²  Rudin (1976) page 109 (5.13 Theorem)



Definition N.4. Let $(x_n)_1^N$ be a tuple. Let $(\lambda_n)_1^N$ be a tuple of weighting values.

DEF

The **harmonic mean** of (x_n) is defined as $\mu_h \triangleq \left(\sum_{n=1}^N \lambda_n \frac{1}{x_n} \right)^{-1}$ where $\sum_{n=1}^N \lambda_n = 1$

The **geometric mean** of (x_n) is defined as $\mu_g \triangleq \prod_{n=1}^N x_n^{\lambda_n}$ where $\sum_{n=1}^N \lambda_n = 1$

The **arithmetic mean** of (x_n) is defined as $\mu_a \triangleq \sum_{n=1}^N \lambda_n x_n$ where $\sum_{n=1}^N \lambda_n = 1$

The **average** of (x_n) is defined as $\mu_a \triangleq \frac{1}{N} \sum_{n=1}^N x_n$

N.3 Inequalities on power means

Corollary N.1. ¹³ Let $(x_n)_1^N$ be a tuple. Let $(\lambda_n)_1^N$ be a tuple of weighting values.

COR

$$\min(x_n) \leq \underbrace{\left(\sum_{n=1}^N \lambda_n \frac{1}{x_n} \right)^{-1}}_{\text{harmonic mean}} \leq \underbrace{\prod_{n=1}^N x_n^{\lambda_n}}_{\text{geometric mean}} \leq \underbrace{\sum_{n=1}^N \lambda_n x_n}_{\text{arithmetic mean}} \leq \max(x_n) \quad \text{where } \sum_{n=1}^N \lambda_n = 1$$

PROOF:

- These five means are all special cases of the *power mean* $M_{\phi(x:r)}$ (Definition N.3 page 292):

$$\begin{aligned} r = \infty: & \max(x_n) \\ r = 1: & \text{arithmetic mean} \\ r = 0: & \text{geometric mean} \\ r = -1: & \text{harmonic mean} \\ r = -\infty: & \min(x_n) \end{aligned}$$

- The inequalities follow directly from Theorem N.3 (page 292).
- Generalized AM-GM inequality: If one is only concerned with the arithmetic mean and geometric mean, their relationship can be established directly using *Jensen's Inequality*:

$$\begin{aligned} \sum_{n=1}^N \lambda_n x_n &= b^{\log_b(\sum_{n=1}^N \lambda_n x_n)} \geq b^{(\sum_{n=1}^N \lambda_n \log_b x_n)} \quad \text{by Jensen's Inequality (Theorem M.1 page 284)} \\ &= \prod_{n=1}^N b^{(\lambda_n \log_b x_n)} = \prod_{n=1}^N b^{(\log_b x_n) \lambda_n} = \prod_{n=1}^N x_n^{\lambda_n} \end{aligned}$$



¹³ Bullen (2003) page 71, Bollobás (1999) page 5, Cauchy (1821), pages 457–459 (Note II, theorem 17), Jensen (1906) page 183

Lemma N.2 (Young's Inequality). ¹⁴

LEM	$xy < \frac{x^p}{p} + \frac{y^q}{q} \quad \text{with } \frac{1}{p} + \frac{1}{q} = 1 \quad \forall 1 < p < \infty, x, y \geq 0, \quad \text{but } y \neq x^{p-1}$ $xy = \frac{x^p}{p} + \frac{y^q}{q} \quad \text{with } \frac{1}{p} + \frac{1}{q} = 1 \quad \forall 1 < p < \infty, x, y \geq 0, \quad \text{and } y = x^{p-1}$
-----	--

PROOF:

1. Proof that $\frac{1}{p-1} = q - 1$:

$$\begin{aligned} \frac{1}{p} + \frac{1}{q} = 1 &\iff \frac{q}{q} + \frac{q}{p} = q \\ &\iff q\left(1 - \frac{1}{p}\right) = 1 \\ &\iff q = \frac{1}{1 - \frac{1}{p}} \\ &\iff q = \frac{p}{p-1} \\ &\iff q - 1 = \frac{p}{p-1} - \frac{p-1}{p-1} \\ &\iff q - 1 = \frac{p - (p-1)}{p-1} \\ &\iff q - 1 = \frac{1}{p-1} \end{aligned}$$

2. Proof that $v = u^{p-1} \iff u = v^{q-1}$:

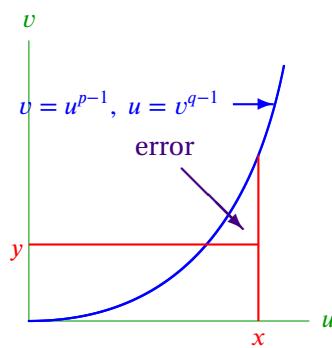
$$\begin{aligned} u &= v^{\frac{1}{p-1}} && \text{by left hypothesis} \\ &= v^{q-1} && \text{by item (1)} \end{aligned}$$

3. Proof that $v = u^{p-1}$ is propemonotonically increasing in u and $u = v^{q-1}$ is propemonotonically increasing in v :

$$\begin{aligned} \frac{dv}{du} &= \frac{d}{du} u^{p-1} && = (p-1)u^{p-2} && > 0 \\ \frac{du}{dv} &= \frac{d}{dv} v^{q-1} && = (q-1)v^{q-2} && > 0 \end{aligned}$$

4. Proof that $xy \leq \frac{x^p}{p} + \frac{y^q}{q}$:

$$\begin{aligned} xy &\leq \int_0^x u^{p-1} du + \int_0^y v^{q-1} dv \\ &= \frac{u^p}{p} \Big|_0^x + \frac{v^q}{q} \Big|_0^y \\ &= \frac{x^p}{p} + \frac{y^q}{q} \end{aligned}$$



¹⁴ Carothers (2000), page 43, Tolsted (1964), page 5, Maligranda (1995), page 257, Hardy et al. (1952) (Theorem 24), Young (1912) page 226



Theorem N.4 (Hölder's Inequality). ¹⁵ Let $\langle x_n \rangle \in \mathbb{C} \rangle_1^N$ and $\langle y_n \rangle \in \mathbb{C} \rangle_1^N$ be complex N -tuples.

T H M	$\underbrace{\sum_{n=1}^N x_n y_n }_{\ \mathbf{x} \cdot \mathbf{y}\ _1} \leq \underbrace{\left(\sum_{n=1}^N x_n ^p \right)^{\frac{1}{p}}}_{\ \mathbf{x}\ _p} \underbrace{\left(\sum_{n=1}^N y_n ^q \right)^{\frac{1}{q}}}_{\ \mathbf{y}\ _q}$	<i>with</i> $\frac{1}{p} + \frac{1}{q} = 1 \quad \forall 1 < p < \infty$
-------------	--	--

PROOF: Let $\|x_n\|_p \triangleq \left(\sum_{n=1}^N |x_n|^p \right)^{\frac{1}{p}}$.

$$\begin{aligned}
 \sum_{n=1}^N |x_n y_n| &= \|(\langle x_n \rangle\|_p \|(\langle y_n \rangle\|_q \sum_{n=1}^N \frac{|x_n y_n|}{\|(\langle x_n \rangle\|_p \|(\langle y_n \rangle\|_q} \\
 &= \|(\langle x_n \rangle\|_p \|(\langle y_n \rangle\|_q \sum_{n=1}^N \frac{|x_n|}{\|(\langle x_n \rangle\|_p} \frac{|y_n|}{\|(\langle y_n \rangle\|_q} \\
 &\leq \|(\langle x_n \rangle\|_p \|(\langle y_n \rangle\|_q \sum_{n=1}^N \left(\frac{1}{p} \frac{|x_n|^p}{\|(\langle x_n \rangle\|_p^p} + \frac{1}{q} \frac{|y_n|^q}{\|(\langle y_n \rangle\|_q^q} \right) \quad \text{by Young's Inequality} \quad (\text{Lemma N.2 page 296}) \\
 &= \|(\langle x_n \rangle\|_p \|(\langle y_n \rangle\|_q \left(\frac{1}{p} \cdot \frac{\sum |x_n|^p}{\|(\langle x_n \rangle\|_p^p} + \frac{1}{q} \cdot \frac{\sum |y_n|^q}{\|(\langle y_n \rangle\|_q^q} \right) \\
 &= \|(\langle x_n \rangle\|_p \|(\langle y_n \rangle\|_q \left(\frac{1}{p} \frac{\|(\langle x_n \rangle\|_p^p}{\|(\langle x_n \rangle\|_p^p} + \frac{1}{q} \frac{\|(\langle y_n \rangle\|_q^q}{\|(\langle y_n \rangle\|_q^q} \right) \quad \text{by definition of } \|\cdot\| \\
 &= \|(\langle x_n \rangle\|_p \|(\langle y_n \rangle\|_q \underbrace{\left(\frac{1}{p} + \frac{1}{q} \right)}_1 \\
 &= \|(\langle x_n \rangle\|_p \|(\langle y_n \rangle\|_q \quad \text{by } \frac{1}{p} + \frac{1}{q} = 1 \text{ constraint}
 \end{aligned}$$



Theorem N.5 (Minkowski's Inequality for sequences). ¹⁶ Let $\langle x_n \rangle \in \mathbb{C} \rangle_1^N$ and $\langle y_n \rangle \in \mathbb{C} \rangle_1^N$ be complex N -tuples.

T H M	$\left(\sum_{n=1}^N x_n + y_n ^p \right)^{\frac{1}{p}} \leq \left(\sum_{n=1}^N x_n ^p \right)^{\frac{1}{p}} + \left(\sum_{n=1}^N y_n ^p \right)^{\frac{1}{p}} \quad \forall 1 < p < \infty$
-------------	---

PROOF:

1. Define $q \triangleq \frac{p}{p-1}$

¹⁵ Bullen (2003) page 178 (2.1), Carothers (2000), page 44, Tolsted (1964), page 6, Maligranda (1995), page 257, Hardy et al. (1952) (Theorem 11), Hölder (1889)

¹⁶ Bullen (2003) page 179, Carothers (2000), page 44, Tolsted (1964), page 7, Maligranda (1995), page 258, Hardy et al. (1952) (Theorem 24), Minkowski (1910) page 115

2. Define $\|x\|_p \triangleq \left(\sum_{n=1}^N |x_n|^p \right)^{\frac{1}{p}}$.

3. Proof that $\|x_n + y_n\|_p \leq \|x_n\|_p + \|y_n\|_p$:

$$\|x_n + y_n\|_p^p$$

$$= \sum_{n=1}^N |x_n + y_n|^p$$

by definition of $\|\cdot\|_p$ (definition 2 page 298)

$$= \sum_{n=1}^N |x_n + y_n| |x_n + y_n|^{p-1}$$

by homogeneous property of $|\cdot|$

$$\leq \sum_{n=1}^N |x_n| |x_n + y_n|^{p-1} + \sum_{n=1}^N |y_n| |x_n + y_n|^{p-1}$$

by subadditive property of $|\cdot|$

$$= \sum_{n=1}^N |x_n(x_n + y_n)^{p-1}| + \sum_{n=1}^N |y_n(x_n + y_n)^{p-1}|$$

by homogeneous property of $|\cdot|$

$$\leq \|x_n\|_p \|(x_n + y_n)^{p-1}\|_q + \|y_n\|_p \|(x_n + y_n)^{p-1}\|_q$$

by Hölder's Inequality (Theorem N.4 page 297)

$$= (\|x_n\|_p + \|y_n\|_p) \|(x_n + y_n)^{p-1}\|_q$$

$$= (\|x_n\|_p + \|y_n\|_p) \left(\sum_{n=1}^N |(x_n + y_n)^{p-1}|^q \right)^{\frac{1}{q}}$$

by definition of $\|\cdot\|_p$ (definition 2 page 298)

$$= (\|x_n\|_p + \|y_n\|_p) \left(\sum_{n=1}^N |(x_n + y_n)^{p-1}|^{\frac{p}{p-1}} \right)^{\frac{p-1}{p}}$$

by definition 1

$$= (\|x_n\|_p + \|y_n\|_p) \left(\sum_{n=1}^N |(x_n + y_n)|^p \right)^{\frac{p-1}{p}}$$

by definition of $\|\cdot\|_p$ (definition 2 page 298)

$$= (\|x_n\|_p + \|y_n\|_p) \|x_n + y_n\|_p^{p-1}$$

$$\Rightarrow \|x_n + y_n\|_p \leq \|x_n\|_p + \|y_n\|_p$$



“Cauchy is the only one occupied with pure mathematics: Poisson, Fourier, Ampere, etc., busy themselves exclusively with magnetism and other physical subjects. Mr. Laplace writes nothing now, I believe.”

Niels Henrik Abel in an 1826 letter ¹⁷

⇒

Theorem N.6 (Cauchy-Schwarz Inequality for sequences). ¹⁸ Let $\{x_n \in \mathbb{C}\}_1^N$ and $\{y_n \in \mathbb{C}\}_1^N$ be complex N -tuples.

¹⁷ quote: Bell (1986) page 318 (Chapter 17. “GENIUS AND POVERTY” “ABEL (1802–1829)”), Boyer and Merzbach (2011) page 462 (without “Mr. Laplace...” portion). image: http://en.wikipedia.org/wiki/File:Augustin-Louis_Cauchy_1901.jpg, public domain

¹⁸ Aliprantis and Burkinshaw (1998), page 278, Scharz (1885), Bouniakowsky (1859), Hardy et al. (1952) page 25 (Theorem 11), Cauchy (1821), page 455 (???)



T H M

$$\begin{aligned} \left| \sum_{n=1}^N x_n y_n^* \right|^2 &\leq \left(\sum_{n=1}^N |x_n|^2 \right) \left(\sum_{n=1}^N |y_n|^2 \right) & \forall x, y \in X \\ \left| \sum_{n=1}^N x_n y_n^* \right|^2 &= \left(\sum_{n=1}^N |x_n|^2 \right) \left(\sum_{n=1}^N |y_n|^2 \right) & \Leftrightarrow \exists a \in \mathbb{C} \text{ such that } y = ax & \forall x, y \in X \end{aligned}$$

PROOF:

1. The *Cauchy-Schwarz Inequality for sequences* is a special case of the *Hölder inequality* (Theorem N.4 page 297) for $p = q = 2$.
2. Alternatively, the *Cauchy-Schwarz inequality for sequences* is a special case of the *Cauchy-Schwarz inequality for inner-product spaces*:
 - (a) $\langle x_n | y_n \rangle \triangleq \sum_{n=1}^N x_n y_n$ is an inner-product and $(\|x_n\|, \langle \cdot | \cdot \rangle)$ is an inner-product space.
 - (b) By the more general *Cauchy-Schwarz Inequality for inner-product spaces*,

$$\begin{aligned} \left(\sum_{n=1}^N a_n \lambda_n \right)^2 &\triangleq \langle a_n | \lambda_n \rangle^2 && \text{by definition of } \langle x_n | y_n \rangle \\ &\leq \|x_n\|^2 \|y_n\|^2 && \text{by Cauchy-Schwarz Inequality for inner-product spaces} \\ &\triangleq \left(\sum_{n=1}^N x_n^2 \right) \left(\sum_{n=1}^N y_n^2 \right) && \text{by definition of } \|\cdot\| \end{aligned}$$

3. Not only does the *Hölder inequality* imply the *Cauchy-Schwarz inequality*, but somewhat surprisingly, the converse is also true: The Cauchy-Schwarz inequality implies the Hölder inequality.¹⁹



Proposition N.1. ²⁰

P R P

$$(x + y)^p \leq 2^p(x^p + y^p) \quad \forall x, y \geq 0, 1 < p < \infty$$

PROOF:

$$\begin{aligned} (x + y)^p &\leq (2 \max \{x, y\})^p \\ &= 2^p(\max \{x, y\})^p \\ &= 2^p(\max \{x^p, y^p\}) \\ &\leq 2^p(x^p + y^p) \end{aligned}$$



¹⁹ Bullen (2003) pages 183–185 (Theorem 5)

²⁰ Carothers (2000), page 43

N.4 Power Sums

Theorem N.7 (Geometric Series). ²¹

T H M
$$\sum_{k=0}^{n-1} r^k = \frac{1 - r^n}{1 - r} \quad \forall r \in \mathbb{C} \setminus \{0\}$$

PROOF:

$$\begin{aligned} \left[\sum_{k=0}^{n-1} r^k \right] &= \left(\frac{1}{1-r} \right) \left[(1-r) \sum_{k=0}^{n-1} r^k \right] = \left(\frac{1}{1-r} \right) \left[\sum_{k=0}^{n-1} r^k - r \sum_{k=0}^{n-1} r^k \right] = \left(\frac{1}{1-r} \right) \left[\sum_{k=0}^{n-1} r^k - \left(\sum_{k=0}^{n-1} r^k - 1 + r^n \right) \right] \\ &= \left(\frac{1}{1-r} \right) [1 - r^n] = \boxed{\frac{1 - r^n}{1 - r}} \end{aligned}$$

⇒

Lemma N.3. Let $f(x)$ be a function.

L E M $S(x) \triangleq \sum_{n \in \mathbb{Z}} f(x + n\tau) = S(x + \tau) \quad (S(x) \text{ is PERIODIC with period } \tau)$

PROOF:

$$\begin{aligned} S(x + \tau) &\triangleq \sum_{n \in \mathbb{Z}} f(x + \tau + n\tau) = \sum_{n \in \mathbb{Z}} f(x + (n+1)\tau) = \sum_{m \in \mathbb{Z}} f(x + m\tau) \quad (\text{where } m \triangleq n+1) \\ &\triangleq S(x) \end{aligned}$$

⇒

Proposition N.2 (Power Sums). ²²

P R P
$$\begin{aligned} \sum_{k=1}^n k &= \frac{n(n+1)}{2} \quad \forall n \in \mathbb{N} & \sum_{k=1}^n k^3 &= \frac{n^2(n+1)^2}{4} \quad \forall n \in \mathbb{N} \\ \sum_{k=1}^n k^2 &= \frac{n(n+1)(2n+1)}{6} \quad \forall n \in \mathbb{N} & \sum_{k=1}^n k^4 &= \frac{n(n+1)(2n+1)(3n^2+3n-1)}{30} \quad \forall n \in \mathbb{N} \end{aligned}$$

PROOF:

1. Proof that $\sum_{k=1}^n k = \frac{n(n+1)}{2}$: (proof by induction)

$$\begin{aligned} \sum_{k=1}^{n+1} k &= 1 + \frac{1(1+1)}{2} = \frac{n(n+1)}{2} \Big|_{n=1} \\ \sum_{k=1}^{n+1} k &= \left(\sum_{k=1}^n k \right) + (n+1) = \underbrace{\left(\frac{n(n+1)}{2} \right)}_{\text{by left hypothesis}} + (n+1) = (n+1) \left(\frac{n}{2} + 1 \right) \\ &= (n+1) \left(\frac{n+2}{2} \right) = \frac{(n+1)(n+2)}{2} \end{aligned}$$

²¹  Hall and Knight (1894), page 39 (article 55)

²²  Amann and Escher (2008) pages 51–57,  Menini and Oystaeyen (2004) page 91 (Exercises 5.36–5.39)

2. Proof that $\sum_{k=1}^n k^2 = \frac{n(n+1)(2n+1)}{6}$: (proof by induction)

$$\begin{aligned}\sum_{k=1}^{n=1} k^2 &= 1 = \frac{1(1+1)(2+1)}{6} = \frac{n(n+1)(2n+1)}{6} \Big|_{n=1} \\ \sum_{k=1}^{n+1} k^2 &= \left(\sum_{k=1}^n k^2 \right) + (n+1)^2 = \underbrace{\left(\frac{n(n+1)(2n+1)}{6} \right)}_{\text{by left hypothesis}} + (n+1)^2 = (n+1) \left(\frac{n(2n+1) + 6(n+1)}{6} \right) \\ &= (n+1) \left(\frac{2n^2 + 7n + 6}{6} \right) = (n+1) \left(\frac{(n+2)(2n+3)}{6} \right) = \frac{(n+1)[(n+1)+1][2(n+1)+1]}{6}\end{aligned}$$





APPENDIX O

OPERATORS ON LINEAR SPACES



“And I am not afraid to say that there is a way to advance algebra as far beyond what Vieta and Descartes have left us as Vieta and Descartes carried it beyond the ancients....we need still another analysis which is distinctly geometrical or linear, and which will express situation directly as algebra expresses magnitude directly.”

Gottfried Leibniz (1646–1716), German mathematician, in a September 8, 1679 letter to Christian Huygens.¹

O.1 Operators on linear spaces

O.1.1 Operator Algebra

An operator is simply a function that maps from a linear space to another linear space (or to the same linear space).

Definition O.1. ²

D E F A function A in Y^X is an **operator** in Y^X if
 X and Y are both LINEAR SPACES (Definition G.1 page 193).

Two operators A and B in Y^X are **equal** if $Ax = Bx$ for all $x \in X$. The inverse relation of an operator A in Y^X always exists as a *relation* in 2^{XY} , but may not always be a *function* (may not always be an operator) in Y^X .

The operator $I \in X^X$ is the *identity* operator if $Ix = I$ for all $x \in X$.

Definition O.2. ³ Let X^X be the set of all operators with from a LINEAR SPACE X to X . Let I be an operator in X^X . Let $\mathbb{I}(X)$ be the IDENTITY ELEMENT in X^X .

¹ quote: Leibniz (1679) pages 248–249

image: http://en.wikipedia.org/wiki/File:Gottfried_Wilhelm_von_Leibniz.jpg, public domain

² Heil (2011) page 42

³ Michel and Herget (1993) page 411

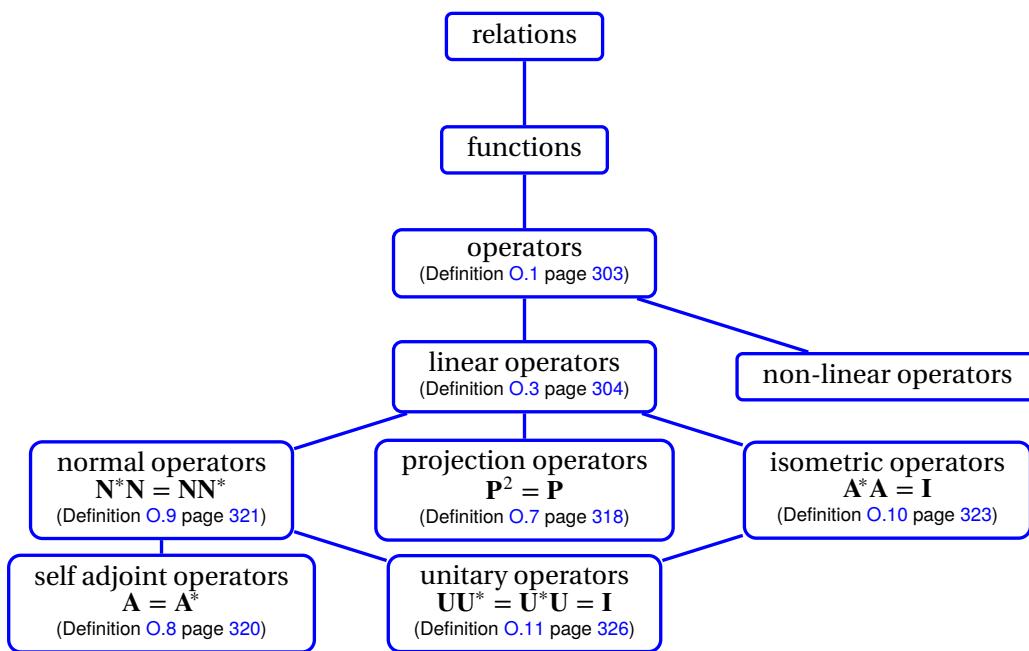


Figure O.1: Some operator types

DEF

I is the **identity operator** in $\mathbf{X}^{\mathbf{X}}$ if $\mathbf{I} = \mathbb{I}(\mathbf{X})$.

O.1.2 Linear operators

Definition O.3. ⁴ Let $\mathbf{X} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ and $\mathbf{Y} \triangleq (Y, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ be linear spaces.

DEF

An operator $\mathbf{L} \in \mathbf{Y}^{\mathbf{X}}$ is **linear** if

1. $\mathbf{L}(x + y) = \mathbf{L}x + \mathbf{L}y \quad \forall x, y \in \mathbf{X}$ (ADDITIVE) and
2. $\mathbf{L}(\alpha x) = \alpha \mathbf{L}x \quad \forall x \in \mathbf{X}, \alpha \in \mathbb{F}$ (HOMOGENEOUS).

The set of all linear operators from \mathbf{X} to \mathbf{Y} is denoted $\mathcal{L}(\mathbf{X}, \mathbf{Y})$ such that $\mathcal{L}(\mathbf{X}, \mathbf{Y}) \triangleq \{\mathbf{L} \in \mathbf{Y}^{\mathbf{X}} | \mathbf{L} \text{ is linear}\}$.

Theorem O.1. ⁵ Let \mathbf{L} be an operator from a linear space \mathbf{X} to a linear space \mathbf{Y} , both over a field \mathbb{F} .

THM

$$\{\mathbf{L} \text{ is LINEAR}\} \implies \left\{ \begin{array}{lcl} 1. \mathbf{L}\emptyset & = & \emptyset \\ 2. \mathbf{L}(-x) & = & -(\mathbf{L}x) \quad \forall x \in \mathbf{X} \\ 3. \mathbf{L}(x - y) & = & \mathbf{L}x - \mathbf{L}y \quad \forall x, y \in \mathbf{X} \\ 4. \mathbf{L}\left(\sum_{n=1}^N \alpha_n x_n\right) & = & \sum_{n=1}^N \alpha_n (\mathbf{L}x_n) \quad x_n \in \mathbf{X}, \alpha_n \in \mathbb{F} \end{array} \right\}$$

PROOF:

⁴ Kubrusly (2001) page 55, Aliprantis and Burkinshaw (1998) page 224, Hilbert et al. (1927) page 6, Stone (1932) page 33

⁵ Berberian (1961) page 79 (Theorem IV.1.1)

1. Proof that $\mathbf{L}\mathbf{0} = \mathbf{0}$:

$$\begin{aligned}\mathbf{L}\mathbf{0} &= \mathbf{L}(0 \cdot \mathbf{0}) && \text{by additive identity property} && (\text{Theorem G.1 page 195}) \\ &= 0 \cdot (\mathbf{L}\mathbf{0}) && \text{by } \textit{homogeneous} \text{ property of } \mathbf{L} && (\text{Definition O.3 page 304}) \\ &= \mathbf{0} && \text{by } \textit{additive identity} \text{ property} && (\text{Theorem G.1 page 195})\end{aligned}$$

2. Proof that $\mathbf{L}(-\mathbf{x}) = -(\mathbf{Lx})$:

$$\begin{aligned}\mathbf{L}(-\mathbf{x}) &= \mathbf{L}(-1 \cdot \mathbf{x}) && \text{by } \textit{additive inverse} \text{ property} && (\text{Theorem G.2 page 196}) \\ &= -1 \cdot (\mathbf{Lx}) && \text{by } \textit{homogeneous} \text{ property of } \mathbf{L} && (\text{Definition O.3 page 304}) \\ &= -(\mathbf{Lx}) && \text{by } \textit{additive inverse} \text{ property} && (\text{Theorem G.2 page 196})\end{aligned}$$

3. Proof that $\mathbf{L}(\mathbf{x} - \mathbf{y}) = \mathbf{Lx} - \mathbf{Ly}$:

$$\begin{aligned}\mathbf{L}(\mathbf{x} - \mathbf{y}) &= \mathbf{L}(\mathbf{x} + (-\mathbf{y})) && \text{by } \textit{additive inverse} \text{ property} && (\text{Theorem G.2 page 196}) \\ &= \mathbf{L}(\mathbf{x}) + \mathbf{L}(-\mathbf{y}) && \text{by } \textit{linearity} \text{ property of } \mathbf{L} && (\text{Definition O.3 page 304}) \\ &= \mathbf{Lx} - \mathbf{Ly} && \text{by item (2)} &&\end{aligned}$$

4. Proof that $\mathbf{L}\left(\sum_{n=1}^N \alpha_n \mathbf{x}_n\right) = \sum_{n=1}^N \alpha_n (\mathbf{Lx}_n)$:

(a) Proof for $N = 1$:

$$\begin{aligned}\mathbf{L}\left(\sum_{n=1}^N \alpha_n \mathbf{x}_n\right) &= \mathbf{L}(\alpha_1 \mathbf{x}_1) && \text{by } N = 1 \text{ hypothesis} \\ &= \alpha_1 (\mathbf{Lx}_1) && \text{by } \textit{homogeneous} \text{ property of } \mathbf{L} && (\text{Definition O.3 page 304})\end{aligned}$$

(b) Proof that N case $\implies N + 1$ case:

$$\begin{aligned}\mathbf{L}\left(\sum_{n=1}^{N+1} \alpha_n \mathbf{x}_n\right) &= \mathbf{L}\left(\alpha_{N+1} \mathbf{x}_{N+1} + \sum_{n=1}^N \alpha_n \mathbf{x}_n\right) \\ &= \mathbf{L}(\alpha_{N+1} \mathbf{x}_{N+1}) + \mathbf{L}\left(\sum_{n=1}^N \alpha_n \mathbf{x}_n\right) && \text{by } \textit{linearity} \text{ property of } \mathbf{L} && (\text{Definition O.3 page 304}) \\ &= \alpha_{N+1} \mathbf{L}(\mathbf{x}_{N+1}) + \sum_{n=1}^N \mathbf{L}(\alpha_n \mathbf{x}_n) && \text{by left } N + 1 \text{ hypothesis} \\ &= \sum_{n=1}^{N+1} \mathbf{L}(\alpha_n \mathbf{x}_n)\end{aligned}$$



Theorem O.2.⁶ Let $\mathcal{L}(\mathbf{X}, \mathbf{Y})$ be the set of all linear operators from a linear space \mathbf{X} to a linear space \mathbf{Y} . Let $\mathcal{N}(\mathbf{L})$ be the NULL SPACE of an operator \mathbf{L} in $\mathbf{Y}^\mathbf{X}$ and $\mathcal{I}(\mathbf{L})$ the IMAGE SET of \mathbf{L} in $\mathbf{Y}^\mathbf{X}$.

T H M	$\mathcal{L}(\mathbf{X}, \mathbf{Y})$ is a linear space $\mathcal{N}(\mathbf{L})$ is a linear subspace of \mathbf{X} $\mathcal{I}(\mathbf{L})$ is a linear subspace of \mathbf{Y}	(space of linear transforms) $\forall \mathbf{L} \in \mathbf{Y}^\mathbf{X}$ $\forall \mathbf{L} \in \mathbf{Y}^\mathbf{X}$
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PROOF:

⁶ Michel and Herget (1993) pages 98–104, Berberian (1961) pages 80–85 (Theorem IV.1.4 and Theorem IV.3.1)

1. Proof that $\mathcal{N}(\mathbf{L})$ is a linear subspace of \mathbf{X} :

- (a) $0 \in \mathcal{N}(\mathbf{L}) \implies \mathcal{N}(\mathbf{L}) \neq \emptyset$
- (b) $\mathcal{N}(\mathbf{L}) \triangleq \{x \in \mathbf{X} | \mathbf{L}x = 0\} \subseteq \mathbf{X}$
- (c) $x + y \in \mathcal{N}(\mathbf{L}) \implies 0 = \mathbf{L}(x + y) = \mathbf{L}(y + x) \implies y + x \in \mathcal{N}(\mathbf{L})$
- (d) $\alpha \in \mathbb{F}, x \in \mathbf{X} \implies 0 = \mathbf{L}x \implies 0 = \alpha \mathbf{L}x \implies 0 = \mathbf{L}(\alpha x) \implies \alpha x \in \mathcal{N}(\mathbf{L})$

2. Proof that $\mathcal{I}(\mathbf{L})$ is a linear subspace of \mathbf{Y} :

- (a) $0 \in \mathcal{I}(\mathbf{L}) \implies \mathcal{I}(\mathbf{L}) \neq \emptyset$
- (b) $\mathcal{I}(\mathbf{L}) \triangleq \{y \in \mathbf{Y} | \exists x \in \mathbf{X} \text{ such that } y = \mathbf{L}x\} \subseteq \mathbf{Y}$
- (c) $x + y \in \mathcal{I}(\mathbf{L}) \implies \exists v \in \mathbf{X} \text{ such that } \mathbf{L}v = x + y = y + x \implies y + x \in \mathcal{I}(\mathbf{L})$
- (d) $\alpha \in \mathbb{F}, x \in \mathcal{I}(\mathbf{L}) \implies \exists x \in \mathbf{X} \text{ such that } y = \mathbf{L}x \implies \alpha y = \alpha \mathbf{L}x = \mathbf{L}(\alpha x) \implies \alpha x \in \mathcal{I}(\mathbf{L})$

⇒

Example O.1. ⁷ Let $C([a : b], \mathbb{R})$ be the set of all *continuous* functions from the closed real interval $[a : b]$ to \mathbb{R} .

E **X** $C([a : b], \mathbb{R})$ is a linear space.

Theorem O.3. ⁸ Let $\mathcal{L}(\mathbf{X}, \mathbf{Y})$ be the set of linear operators from a linear space \mathbf{X} to a linear space \mathbf{Y} . Let $\mathcal{N}(\mathbf{L})$ be the NULL SPACE of a linear operator $\mathbf{L} \in \mathcal{L}(\mathbf{X}, \mathbf{Y})$.

T	$\mathbf{L}x = \mathbf{Ly} \iff x - y \in \mathcal{N}(\mathbf{L})$
H	\mathbf{L} is INJECTIVE $\iff \mathcal{N}(\mathbf{L}) = \{0\}$

PROOF:

1. Proof that $\mathbf{L}x = \mathbf{Ly} \implies x - y \in \mathcal{N}(\mathbf{L})$:

$$\begin{aligned} \mathbf{L}(x - y) &= \mathbf{L}x - \mathbf{Ly} && \text{by Theorem O.1 page 304} \\ &= 0 && \text{by left hypothesis} \\ &\implies x - y \in \mathcal{N}(\mathbf{L}) && \text{by definition of null space} \end{aligned}$$

2. Proof that $\mathbf{L}x = \mathbf{Ly} \iff x - y \in \mathcal{N}(\mathbf{L})$:

$$\begin{aligned} \mathbf{Ly} &= \mathbf{Ly} + 0 && \text{by definition of linear space (Definition G.1 page 193)} \\ &= \mathbf{Ly} + \mathbf{L}(x - y) && \text{by right hypothesis} \\ &= \mathbf{Ly} + (\mathbf{L}x - \mathbf{Ly}) && \text{by Theorem O.1 page 304} \\ &= (\mathbf{Ly} - \mathbf{Ly}) + \mathbf{L}x && \text{by associative and commutative properties (Definition G.1 page 193)} \\ &= \mathbf{L}x \end{aligned}$$

3. Proof that \mathbf{L} is *injective* $\iff \mathcal{N}(\mathbf{L}) = \{0\}$:

$$\begin{aligned} \mathbf{L} \text{ is injective} &\iff \{(\mathbf{L}x = \mathbf{Ly} \iff x = y) \quad \forall x, y \in \mathbf{X}\} \\ &\iff \{[\mathbf{L}x - \mathbf{Ly} = 0 \iff (x - y) = 0] \quad \forall x, y \in \mathbf{X}\} \\ &\iff \{[\mathbf{L}(x - y) = 0 \iff (x - y) = 0] \quad \forall x, y \in \mathbf{X}\} \\ &\iff \mathcal{N}(\mathbf{L}) = \{0\} \end{aligned}$$

⁷ Eidelman et al. (2004) page 3

⁸ Berberian (1961) page 88 (Theorem IV.1.4)



Theorem O.4.⁹ Let \mathcal{W} , \mathcal{X} , \mathcal{Y} , and \mathcal{Z} be linear spaces over a field \mathbb{F} .

T H M	1. $L(MN) = (LM)N$ 2. $L(M \dotplus N) = (LM) \dotplus (LN)$ 3. $(L \dotplus M)N = (LN) \dotplus (MN)$ 4. $\alpha(LM) = (\alpha L)M = L(\alpha M)$	$\forall L \in \mathcal{L}(\mathcal{Z}, \mathcal{W}), M \in \mathcal{L}(\mathcal{Y}, \mathcal{Z}), N \in \mathcal{L}(\mathcal{X}, \mathcal{Y})$ $\forall L \in \mathcal{L}(\mathcal{Y}, \mathcal{Z}), M \in \mathcal{L}(\mathcal{X}, \mathcal{Y}), N \in \mathcal{L}(\mathcal{X}, \mathcal{Y})$ $\forall L \in \mathcal{L}(\mathcal{Y}, \mathcal{Z}), M \in \mathcal{L}(\mathcal{Y}, \mathcal{Z}), N \in \mathcal{L}(\mathcal{X}, \mathcal{Y})$ $\forall L \in \mathcal{L}(\mathcal{Y}, \mathcal{Z}), M \in \mathcal{L}(\mathcal{X}, \mathcal{Y}), \alpha \in \mathbb{F}$	(ASSOCIATIVE) (LEFT DISTRIBUTIVE) (RIGHT DISTRIBUTIVE) (HOMOGENEOUS)
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PROOF:

1. Proof that $L(MN) = (LM)N$: Follows directly from property of *associative* operators.

2. Proof that $L(M \dotplus N) = (LM) \dotplus (LN)$:

$$\begin{aligned}
 [L(M \dotplus N)]x &= L[(M \dotplus N)x] \\
 &= L[(Mx) \dotplus (Nx)] \\
 &= [L(Mx)] \dotplus [L(Nx)] \quad \text{by } \textit{additive} \text{ property Definition O.3 page 304} \\
 &= [(LM)x] \dotplus [(LN)x]
 \end{aligned}$$

3. Proof that $(L \dotplus M)N = (LN) \dotplus (MN)$: Follows directly from property of *associative* operators.

4. Proof that $\alpha(LM) = (\alpha L)M$: Follows directly from *associative* property of linear operators.

5. Proof that $\alpha(LM) = L(\alpha M)$:

$$\begin{aligned}
 [\alpha(LM)]x &= \alpha[(LM)x] \\
 &= L[\alpha(Mx)] \quad \text{by } \textit{homogeneous} \text{ property Definition O.3 page 304} \\
 &= L[(\alpha M)x] \\
 &= [L(\alpha M)]x
 \end{aligned}$$



Theorem O.5 (Fundamental theorem of linear equations). Michel and Herget (1993) page 99 Let $\mathcal{Y}^{\mathcal{X}}$ be the set of all operators from a linear space \mathcal{X} to a linear space \mathcal{Y} . Let $\mathcal{N}(L)$ be the NULL SPACE of an operator L in $\mathcal{Y}^{\mathcal{X}}$ and $\mathcal{I}(L)$ the IMAGE SET of L in $\mathcal{Y}^{\mathcal{X}}$ (Definition ?? page ??).

T H M	$\dim \mathcal{I}(L) + \dim \mathcal{N}(L) = \dim \mathcal{X}$ $\forall L \in \mathcal{Y}^{\mathcal{X}}$
----------------------	--

PROOF: Let $\{\psi_k | k = 1, 2, \dots, p\}$ be a basis for \mathcal{X} constructed such that $\{\psi_{p-n+1}, \psi_{p-n+2}, \dots, \psi_p\}$ is a basis for

⁹ Berberian (1961) page 88 (Theorem IV.5.1)

$\mathcal{N}(\mathbf{L})$.

Let $p \triangleq \dim \mathbf{X}$.

Let $n \triangleq \dim \mathcal{N}(\mathbf{L})$.

$$\begin{aligned}
 \dim \mathcal{I}(\mathbf{L}) &= \dim \{y \in \mathbf{Y} \mid \exists x \in \mathbf{X} \text{ such that } y = \mathbf{L}x\} \\
 &= \dim \left\{ y \in \mathbf{Y} \mid \exists (\alpha_1, \alpha_2, \dots, \alpha_p) \text{ such that } y = \mathbf{L} \sum_{k=1}^p \alpha_k \psi_k \right\} \\
 &= \dim \left\{ y \in \mathbf{Y} \mid \exists (\alpha_1, \alpha_2, \dots, \alpha_p) \text{ such that } y = \sum_{k=1}^p \alpha_k \mathbf{L}\psi_k \right\} \\
 &= \dim \left\{ y \in \mathbf{Y} \mid \exists (\alpha_1, \alpha_2, \dots, \alpha_p) \text{ such that } y = \sum_{k=1}^{p-n} \alpha_k \mathbf{L}\psi_k + \sum_{k=1}^n \alpha_k \mathbf{L}\psi_k \right\} \\
 &= \dim \left\{ y \in \mathbf{Y} \mid \exists (\alpha_1, \alpha_2, \dots, \alpha_p) \text{ such that } y = \sum_{k=1}^{p-n} \alpha_k \mathbf{L}\psi_k + \mathbb{0} \right\} \\
 &= p - n \\
 &= \dim \mathbf{X} - \dim \mathcal{N}(\mathbf{L})
 \end{aligned}$$

Note: This “proof” may be missing some necessary detail.



O.2 Operators on Normed linear spaces

O.2.1 Operator norm

Definition O.4. ¹⁰ Let $\mathcal{L}(\mathbf{X}, \mathbf{Y})$ be the space of linear operators over normed linear spaces \mathbf{X} and \mathbf{Y} .
¹¹

D E F The **operator norm** $\|\cdot\|$ is defined as

$$\|\mathbf{A}\| \triangleq \sup_{x \in \mathbf{X}} \{\|\mathbf{Ax}\| \mid \|x\| \leq 1\} \quad \forall \mathbf{A} \in \mathcal{L}(\mathbf{X}, \mathbf{Y})$$

The pair $(\mathcal{L}(\mathbf{X}, \mathbf{Y}), \|\cdot\|)$ is the **normed space of linear operators** on (\mathbf{X}, \mathbf{Y}) .

Proposition O.1 (next) shows that the functional defined in Definition O.4 (previous) is a **norm** (Definition L.1 page 271).

Proposition O.1. ¹² Let $(\mathcal{L}(\mathbf{X}, \mathbf{Y}), \|\cdot\|)$ be the normed space of linear operators over the normed linear spaces $\mathbf{X} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$ and $\mathbf{Y} \triangleq (Y, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$.

P R P The functional $\|\cdot\|$ is a **norm** on $\mathcal{L}(\mathbf{X}, \mathbf{Y})$. In particular,

1. $\|\mathbf{A}\| \geq 0 \quad \forall \mathbf{A} \in \mathcal{L}(\mathbf{X}, \mathbf{Y}) \quad (\text{NON-NEGATIVE}) \quad \text{and}$
2. $\|\mathbf{A}\| = 0 \iff \mathbf{A} \stackrel{\circ}{=} \mathbb{0} \quad \forall \mathbf{A} \in \mathcal{L}(\mathbf{X}, \mathbf{Y}) \quad (\text{NONDEGENERATE}) \quad \text{and}$
3. $\|\alpha \mathbf{A}\| = |\alpha| \|\mathbf{A}\| \quad \forall \mathbf{A} \in \mathcal{L}(\mathbf{X}, \mathbf{Y}), \alpha \in \mathbb{F} \quad (\text{HOMOGENEOUS}) \quad \text{and}$
4. $\|\mathbf{A} \dot{+} \mathbf{B}\| \leq \|\mathbf{A}\| + \|\mathbf{B}\| \quad \forall \mathbf{A} \in \mathcal{L}(\mathbf{X}, \mathbf{Y}) \quad (\text{SUBADDITIVE}).$

Moreover, $(\mathcal{L}(\mathbf{X}, \mathbf{Y}), \|\cdot\|)$ is a **normed linear space**.

¹⁰ Rudin (1991) page 92, Aliprantis and Burkinshaw (1998) page 225

¹¹ The operator norm notation $\|\cdot\|$ is introduced (as a Matrix norm) in

Horn and Johnson (1990), page 290

¹² Rudin (1991) page 93



PROOF:

1. Proof that $\|\mathbf{A}\| > 0$ for $\mathbf{A} \neq \mathbb{0}$:

$$\begin{aligned} \|\mathbf{A}\| &\triangleq \sup_{\mathbf{x} \in X} \{\|\mathbf{Ax}\| \mid \|\mathbf{x}\| \leq 1\} \\ &> 0 \end{aligned} \quad \text{by definition of } \|\cdot\| \text{ (Definition O.4 page 308)}$$

2. Proof that $\|\mathbf{A}\| = 0$ for $\mathbf{A} \stackrel{\circ}{=} \mathbb{0}$:

$$\begin{aligned} \|\mathbf{A}\| &\triangleq \sup_{\mathbf{x} \in X} \{\|\mathbf{Ax}\| \mid \|\mathbf{x}\| \leq 1\} \\ &= \sup_{\mathbf{x} \in X} \{\|\mathbf{0x}\| \mid \|\mathbf{x}\| \leq 1\} \\ &= 0 \end{aligned} \quad \text{by definition of } \|\cdot\| \text{ (Definition O.4 page 308)}$$

3. Proof that $\|\alpha\mathbf{A}\| = |\alpha| \|\mathbf{A}\|$:

$$\begin{aligned} \|\alpha\mathbf{A}\| &\triangleq \sup_{\mathbf{x} \in X} \{\|\alpha\mathbf{Ax}\| \mid \|\mathbf{x}\| \leq 1\} \\ &= \sup_{\mathbf{x} \in X} \{|\alpha| \|\mathbf{Ax}\| \mid \|\mathbf{x}\| \leq 1\} \\ &= |\alpha| \sup_{\mathbf{x} \in X} \{\|\mathbf{Ax}\| \mid \|\mathbf{x}\| \leq 1\} \\ &= |\alpha| \|\mathbf{A}\| \end{aligned} \quad \begin{array}{l} \text{by definition of } \|\cdot\| \text{ (Definition O.4 page 308)} \\ \text{by definition of } \|\cdot\| \text{ (Definition O.4 page 308)} \\ \text{by definition of sup} \\ \text{by definition of } \|\cdot\| \text{ (Definition O.4 page 308)} \end{array}$$

4. Proof that $\|\mathbf{A} + \mathbf{B}\| \leq \|\mathbf{A}\| + \|\mathbf{B}\|$:

$$\begin{aligned} \|\mathbf{A} + \mathbf{B}\| &\triangleq \sup_{\mathbf{x} \in X} \{\|(A + B)x\| \mid \|\mathbf{x}\| \leq 1\} \\ &= \sup_{\mathbf{x} \in X} \{\|\mathbf{Ax} + \mathbf{Bx}\| \mid \|\mathbf{x}\| \leq 1\} \\ &\leq \sup_{\mathbf{x} \in X} \{\|\mathbf{Ax}\| + \|\mathbf{Bx}\| \mid \|\mathbf{x}\| \leq 1\} \\ &\leq \sup_{\mathbf{x} \in X} \{\|\mathbf{Ax}\| \mid \|\mathbf{x}\| \leq 1\} + \sup_{\mathbf{x} \in X} \{\|\mathbf{Bx}\| \mid \|\mathbf{x}\| \leq 1\} \\ &\triangleq \|\mathbf{A}\| + \|\mathbf{B}\| \end{aligned} \quad \begin{array}{l} \text{by definition of } \|\cdot\| \text{ (Definition O.4 page 308)} \\ \text{by definition of } \|\cdot\| \text{ (Definition O.4 page 308)} \\ \text{by definition of } \|\cdot\| \text{ (Definition O.4 page 308)} \\ \text{by definition of } \|\cdot\| \text{ (Definition O.4 page 308)} \end{array}$$

Lemma O.1. Let $(\mathcal{L}(X, Y), \|\cdot\|)$ be the normed space of linear operators over normed linear spaces $X \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$ and $Y \triangleq (Y, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$.

L
E
M

$$\|\mathbf{L}\| = \sup_x \{\|\mathbf{Lx}\| \mid \|x\| = 1\} \quad \forall x \in \mathcal{L}(X, Y)$$

PROOF: 13

1. Proof that $\sup_x \{\|\mathbf{Lx}\| \mid \|x\| \leq 1\} \geq \sup_x \{\|\mathbf{Lx}\| \mid \|x\| = 1\}$:

$$\sup_x \{\|\mathbf{Lx}\| \mid \|x\| \leq 1\} \geq \sup_x \{\|\mathbf{Lx}\| \mid \|x\| = 1\} \quad \text{because } A \subseteq B \implies \sup A \leq \sup B$$

13



Many many thanks to former NCTU Ph.D. student Chien Yao (Chinese: 姚建; PinYin: Yáo Jiàn) for his brilliant help with this proof. (If you are viewing this text as a pdf file, zoom in on the figure to the left to see text from Chien Yao's 2007 April 16 email.)

2. Let the subset $Y \subsetneq X$ be defined as

$$Y \triangleq \left\{ y \in X \mid \begin{array}{l} 1. \quad \|Ly\| = \sup_{x \in X} \{\|Lx\| \mid \|x\| \leq 1\} \text{ and} \\ 2. \quad 0 < \|y\| \leq 1 \end{array} \right\}$$

3. Proof that $\sup_x \{\|Lx\| \mid \|x\| \leq 1\} \leq \sup_x \{\|Lx\| \mid \|x\| = 1\}$:

$$\begin{aligned} \sup_{x \in X} \{\|Lx\| \mid \|x\| \leq 1\} &= \|Ly\| && \text{by definition of set } Y \\ &= \frac{\|y\|}{\|y\|} \|Ly\| \\ &= \|y\| \left\| \frac{1}{\|y\|} Ly \right\| && \text{by homogeneous property (page 271)} \\ &= \|y\| \left\| L \frac{y}{\|y\|} \right\| && \text{by homogeneous property (page 304)} \\ &\leq \|y\| \sup_{y \in Y} \left\{ \left\| L \frac{y}{\|y\|} \right\| \right\} && \text{by definition of supremum} \\ &= \|y\| \sup_{y \in Y} \left\{ \left\| L \frac{y}{\|y\|} \right\| \mid \left\| \frac{y}{\|y\|} \right\| = 1 \right\} && \text{because } \left\| \frac{y}{\|y\|} \right\| = 1 \text{ for all } y \in Y \\ &\leq \sup_{y \in Y} \left\{ \left\| L \frac{y}{\|y\|} \right\| \mid \left\| \frac{y}{\|y\|} \right\| = 1 \right\} && \text{because } 0 < \|y\| \leq 1 \\ &\leq \sup_{x \in X} \{\|Lx\| \mid \|x\| = 1\} && \text{because } \frac{y}{\|y\|} \in X \quad \forall y \in Y \end{aligned}$$

4. By (1) and (3),

$$\sup_{x \in X} \{\|Lx\| \mid \|x\| \leq 1\} = \sup_{x \in X} \{\|Lx\| \mid \|x\| = 1\}$$



Proposition O.2. ¹⁴ Let \mathbf{I} be the identity operator in the normed space of linear operators $(\mathcal{L}(X, X), \|\cdot\|)$.

P R P	$\ \mathbf{I}\ = 1$
-------------	----------------------

PROOF:

$$\begin{aligned} \|\mathbf{I}\| &\triangleq \sup \{\|\mathbf{Ix}\| \mid \|x\| \leq 1\} && \text{by definition of } \|\cdot\| \text{ (Definition O.4 page 308)} \\ &= \sup \{\|x\| \mid \|x\| \leq 1\} && \text{by definition of } \mathbf{I} \text{ (Definition O.2 page 303)} \\ &= 1 \end{aligned}$$



Theorem O.6. ¹⁵ Let $(\mathcal{L}(X, Y), \|\cdot\|)$ be the normed space of linear operators over normed linear spaces X and Y .

T H M	$\ Lx\ \leq \ \mathbf{L}\ \ x\ \quad \forall L \in \mathcal{L}(X, Y), x \in X$
	$\ \mathbf{KL}\ \leq \ \mathbf{K}\ \ \mathbf{L}\ \quad \forall K, L \in \mathcal{L}(X, Y)$

¹⁴ Michel and Herget (1993) page 410

¹⁵ Rudin (1991) page 103, Aliprantis and Burkinshaw (1998) page 225

PROOF:

1. Proof that $\|Lx\| \leq \|L\| \|x\|$:

$$\begin{aligned}
 \|Lx\| &= \frac{\|x\|}{\|x\|} \|Lx\| \\
 &= \|x\| \left\| \frac{1}{\|x\|} Lx \right\| \\
 &= \|x\| \left\| L \frac{x}{\|x\|} \right\| \\
 &\triangleq \|x\| \|Ly\| \\
 &\leq \|x\| \sup_y \|Ly\| \\
 &= \|x\| \sup_y \{ \|Ly\| \mid \|y\| = 1 \} \\
 &\triangleq \|x\| \|L\|
 \end{aligned}$$

by property of norms
by property of linear operators
where $y \triangleq \frac{x}{\|x\|}$
by definition of supremum
because $\|y\| = \left\| \frac{x}{\|x\|} \right\| = \frac{\|x\|}{\|x\|} = 1$
by definition of operator norm

2. Proof that $\|KL\| \leq \|K\| \|L\|$:

$$\begin{aligned}
 \|KL\| &\triangleq \sup_{x \in X} \{ \|(KL)x\| \mid \|x\| \leq 1 \} \\
 &= \sup_{x \in X} \{ \|K(Lx)\| \mid \|x\| \leq 1 \} \\
 &\leq \sup_{x \in X} \{ \|K\| \|Lx\| \mid \|x\| \leq 1 \} \\
 &\leq \sup_{x \in X} \{ \|K\| \|L\| \|x\| \mid \|x\| \leq 1 \} \\
 &= \sup_{x \in X} \{ \|K\| \|L\| 1 \mid \|x\| \leq 1 \} \\
 &= \|K\| \|L\|
 \end{aligned}$$

by Definition O.4 page 308 ($\|\cdot\|$)
by 1.
by 1.
by definition of sup
by definition of sup

O.2.2 Bounded linear operators

Definition O.5. ¹⁶ Let $(\mathcal{L}(X, Y), \|\cdot\|)$ be a normed space of linear operators.

D E F An operator B is **bounded** if $\|B\| < \infty$.

The quantity $B(X, Y)$ is the set of all **bounded linear operators** on (X, Y) such that $B(X, Y) \triangleq \{L \in \mathcal{L}(X, Y) \mid \|L\| < \infty\}$.

Theorem O.7. ¹⁷ Let $(\mathcal{L}(X, Y), \|\cdot\|)$ be the set of linear operators over normed linear spaces $X \triangleq (X, +, \cdot, (\mathbb{F}, +, \times), \|\cdot\|)$ and $Y \triangleq (Y, +, \cdot, (\mathbb{F}, +, \times), \|\cdot\|)$.

The following conditions are all EQUIVALENT:

- | | |
|--|--------|
| 1. L is continuous at A SINGLE POINT $x_0 \in X$ $\forall L \in \mathcal{L}(X, Y)$ | \iff |
| 2. L is CONTINUOUS (at every point $x \in X$) $\forall L \in \mathcal{L}(X, Y)$ | \iff |
| 3. $\ L\ < \infty$ (L is BOUNDED) $\forall L \in \mathcal{L}(X, Y)$ | \iff |
| 4. $\exists M \in \mathbb{R}$ such that $\ Lx\ \leq M \ x\ $ $\forall L \in \mathcal{L}(X, Y), x \in X$ | \iff |

¹⁶ Rudin (1991) pages 92–93

¹⁷ Aliprantis and Burkinshaw (1998) page 227

PROOF:

1. Proof that 1 \implies 2:

$$\begin{aligned}
 \epsilon &> \|Lx - Lx_0\| && \text{by hypothesis 1} \\
 &= \|L(x - x_0)\| && \text{by linearity (Definition O.3 page 304)} \\
 &= \|L(x + y - x_0 - y)\| \\
 &= \|L(x + y) - L(x_0 + y)\| && \text{by linearity (Definition O.3 page 304)} \\
 \implies L &\text{ is continuous at point } x + y \\
 \implies L &\text{ is continuous at every point in } X && \text{(hypothesis 2)}
 \end{aligned}$$

2. Proof that 2 \implies 1: obvious:

3. Proof that 4 \implies 2:¹⁸

$$\begin{aligned}
 \|Lx\| \leq M \|x\| &\implies \|L(x - y)\| \leq M \|x - y\| && \text{by hypothesis 4} \\
 &\implies \|Lx - Ly\| \leq M \|x - y\| && \text{by linearity of } L \text{ (Definition O.3 page 304)} \\
 &\implies \|Lx - Ly\| \leq \epsilon \text{ whenever } M \|x - y\| < \epsilon \\
 &\implies \|Lx - Ly\| \leq \epsilon \text{ whenever } \|x - y\| < \frac{\epsilon}{M} && \text{(hypothesis 2)}
 \end{aligned}$$

4. Proof that 3 \implies 4:

$$\begin{aligned}
 \|Lx\| &\leq \underbrace{\|L\|}_M \|x\| && \text{by Theorem O.6 page 310} \\
 &= M \|x\| && \text{where } M \triangleq \|L\| < \infty \text{ (by hypothesis 1)}
 \end{aligned}$$

5. Proof that 1 \implies 3:¹⁹

$$\begin{aligned}
 \|L\| = \infty &\implies \{\|Lx\| \mid \|x\| \leq 1\} = \infty \\
 &\implies \exists (x_n) \text{ such that } \|x_n\| = 1 \text{ and } \|L\| = \{\|Lx_n\| \mid \|x_n\| \leq 1\} = \infty \\
 &\implies \|x_n\| = 1 \text{ and } \infty = \|L\| = \|Lx_n\| \\
 &\implies \|x_n\| = 1 \text{ and } \|Lx_n\| \geq n \\
 &\implies \frac{1}{n} \|x_n\| = \frac{1}{n} \text{ and } \frac{1}{n} \|Lx_n\| \geq 1 \\
 &\implies \left\| \frac{x_n}{n} \right\| = \frac{1}{n} \text{ and } \left\| L \frac{x_n}{n} \right\| \geq 1 \\
 &\implies \lim_{n \rightarrow \infty} \left\| \frac{x_n}{n} \right\| = 0 \text{ and } \lim_{n \rightarrow \infty} \left\| L \frac{x_n}{n} \right\| \geq 1 \\
 &\implies L \text{ is not continuous at } 0
 \end{aligned}$$

But by hypothesis, L is continuous. So the statement $\|L\| = \infty$ must be *false* and thus $\|L\| < \infty$ (L is *bounded*).

¹⁸ Bollobás (1999), page 29

¹⁹ Aliprantis and Burkinshaw (1998), page 227

O.2.3 Adjoint on normed linear spaces

Definition O.6. Let $\mathcal{B}(X, Y)$ be the space of BOUNDED LINEAR OPERATORS on normed linear spaces X and Y . Let X^* be the TOPOLOGICAL DUAL SPACE of X .

DEF B^* is the **adjoint** of an operator $B \in \mathcal{B}(X, Y)$ if
 $f(Bx) = [B^*f](x) \quad \forall f \in X^*, x \in X$

Theorem O.8. ²⁰ Let $\mathcal{B}(X, Y)$ be the space of BOUNDED LINEAR OPERATORS on NORMED LINEAR SPACES X and Y .

THM
$$\begin{aligned} (A + B)^* &= A^* + B^* && \forall A, B \in \mathcal{B}(X, Y) \\ (\lambda A)^* &= \lambda A^* && \forall A, B \in \mathcal{B}(X, Y) \\ (AB)^* &= B^*A^* && \forall A, B \in \mathcal{B}(X, Y) \end{aligned}$$

PROOF:

$$[A + B]^*f(x) = f([A + B]x) \quad \text{by definition of adjoint} \quad (\text{Definition O.6 page 313})$$

$$= f(Ax + Bx) \quad \text{by definition of linear operators} \quad (\text{Definition O.3 page 304})$$

$$= f(Ax) + f(Bx) \quad \text{by definition of linear functional}$$

$$= A^*f(x) + B^*f(x) \quad \text{by definition of adjoint} \quad (\text{Definition O.6 page 313})$$

$$= [A^* + B^*]f(x) \quad \text{by definition of linear functional}$$

$$[\lambda A]^*f(x) = f([\lambda A]x) \quad \text{by definition of adjoint} \quad (\text{Definition O.6 page 313})$$

$$= \lambda f(Ax) \quad \text{by definition of linear functional}$$

$$= [\lambda A^*]f(x) \quad \text{by definition of adjoint}$$

$$[AB]^*f(x) = f([AB]x) \quad \text{by definition of adjoint} \quad (\text{Definition O.6 page 313})$$

$$= f(A[Bx]) \quad \text{by definition of linear operators} \quad (\text{Definition O.3 page 304})$$

$$= [A^*f](Bx) \quad \text{by definition of adjoint} \quad (\text{Definition O.6 page 313})$$

$$= B^*[A^*f](x) \quad \text{by definition of adjoint} \quad (\text{Definition O.6 page 313})$$

$$= [B^*A^*]f(x) \quad \text{by definition of adjoint} \quad (\text{Definition O.6 page 313})$$

Theorem O.9. ²¹ Let $\mathcal{B}(X, Y)$ be the space of BOUNDED LINEAR OPERATORS on normed linear spaces X and Y . Let B^* be the adjoint of an operator B .

THM $\|B\| = \|B^*\| \quad \forall B \in \mathcal{B}(X, Y)$

PROOF:

$$\|B\| \triangleq \sup \{\|Bx\| \mid \|x\| \leq 1\} \quad \text{by Definition O.4 page 308}$$

$$\triangleq \sup \{|g(Bx; y^*)| \mid \|x\| \leq 1, \|y^*\| \leq 1\}$$

$$\triangleq \sup \{|f(x; B^*y^*)| \mid \|x\| \leq 1, \|y^*\| \leq 1\}$$

$$\triangleq \sup \{\|B^*y^*\| \mid \|x\| \leq 1, \|y^*\| \leq 1\}$$

$$\triangleq \sup \{\|B^*y^*\| \mid \|y^*\| \leq 1\}$$

$$\triangleq \|B^*\| \quad \text{by Definition O.4 page 308}$$

²⁰ Bollobás (1999), page 156

²¹ Rudin (1991) page 98

O.2.4 More properties



“Beginning with the third year of studies, most of my mathematical work was really started in conversations with Mazur and Banach. And according to Banach some of my own contributions were characterized by a certain “strangeness” in the formulation of problems and in the outline of possible proofs. As he told me once some years later, he was surprised how often these “strange” approaches really worked.”²²

Stanislaus M. Ulam (1909–1984), Polish mathematician ²²

Theorem O.10 (Mazur-Ulam theorem). ²³ Let $\phi \in \mathcal{L}(\mathbf{X}, \mathbf{Y})$ be a function on normed linear spaces $(\mathbf{X}, \|\cdot\|_{\mathbf{X}})$ and $(\mathbf{Y}, \|\cdot\|_{\mathbf{Y}})$. Let $\mathbf{I} \in \mathcal{L}(\mathbf{X}, \mathbf{X})$ be the identity operator on $(\mathbf{X}, \|\cdot\|_{\mathbf{X}})$.

T H M	$\left. \begin{array}{l} 1. \underbrace{\phi^{-1}\phi = \phi\phi^{-1} = \mathbf{I}}_{\text{bijective}} \\ 2. \underbrace{\ \phi\mathbf{x} - \phi\mathbf{y}\ _{\mathbf{Y}} = \ \mathbf{x} - \mathbf{y}\ _{\mathbf{X}}}_{\text{isometric}} \end{array} \right\} \text{and} \quad \Rightarrow \underbrace{\phi([1 - \lambda]\mathbf{x} + \lambda\mathbf{y}) = [1 - \lambda]\phi\mathbf{x} + \lambda\phi\mathbf{y} \forall \lambda \in \mathbb{R}}_{\text{affine}}$
-------------	---

PROOF: Proof not yet complete.

1. Let ψ be the reflection of \mathbf{z} in \mathbf{X} such that $\psi\mathbf{x} = 2\mathbf{z} - \mathbf{x}$

$$(a) \|\psi\mathbf{x} - \mathbf{z}\| = \|\mathbf{x} - \mathbf{z}\|$$

2. Let $\lambda \triangleq \sup_g \{\|g\mathbf{z} - \mathbf{z}\|\}$

3. Proof that $g \in W \implies g^{-1} \in W$:

Let $\hat{\mathbf{x}} \triangleq g^{-1}\mathbf{x}$ and $\hat{\mathbf{y}} \triangleq g^{-1}\mathbf{y}$.

$$\begin{aligned} \|g^{-1}\mathbf{x} - g^{-1}\mathbf{y}\| &= \|\hat{\mathbf{x}} - \hat{\mathbf{y}}\| && \text{by definition of } \hat{\mathbf{x}} \text{ and } \hat{\mathbf{y}} \\ &= \|g\hat{\mathbf{x}} - g\hat{\mathbf{y}}\| && \text{by left hypothesis} \\ &= \|gg^{-1}\mathbf{x} - gg^{-1}\mathbf{y}\| && \text{by definition of } \hat{\mathbf{x}} \text{ and } \hat{\mathbf{y}} \\ &= \|\mathbf{x} - \mathbf{y}\| && \text{by definition of } g^{-1} \end{aligned}$$

²² quote: [Ulam \(1991\)](#), page 33

image: <http://www-history.mcs.st-andrews.ac.uk/Biographies/Ulam.html>

²³ [Oikhberg and Rosenthal \(2007\)](#), page 598, [Väisälä \(2003\)](#), page 634, [Giles \(2000\)](#), page 11, [Dunford and Schwartz \(1957\)](#), page 91, [Mazur and Ulam \(1932\)](#)



4. Proof that $gz = z$:

$$\begin{aligned}
 2\lambda &= 2 \sup \{ \|gz - z\| \} && \text{by definition of } \lambda \text{ item (2)} \\
 &\leq 2 \|gz - z\| && \text{by definition of sup} \\
 &= \|2z - 2gz\| && \\
 &= \|\psi gz - gz\| && \text{by definition of } \psi \text{ item (1)} \\
 &= \|g^{-1}\psi gz - g^{-1}gz\| && \text{by item (3)} \\
 &= \|g^{-1}\psi gz - z\| && \text{by definition of } g^{-1} \\
 &= \|\psi g^{-1}\psi gz - z\| && \\
 &= \|g^*z - z\| && \\
 &\leq \lambda && \text{by definition of } \lambda \text{ item (2)} \\
 &\implies 2\lambda \leq \lambda && \\
 &\implies \lambda = 0 && \\
 &\implies gz = z &&
 \end{aligned}$$

5. Proof that $\phi\left(\frac{1}{2}\mathbf{x} + \frac{1}{2}\mathbf{y}\right) = \frac{1}{2}\phi\mathbf{x} + \frac{1}{2}\phi\mathbf{y}$:

$$\begin{aligned}
 \phi\left(\frac{1}{2}\mathbf{x} + \frac{1}{2}\mathbf{y}\right) &= \\
 &= \frac{1}{2}\phi\mathbf{x} + \frac{1}{2}\phi\mathbf{y}
 \end{aligned}$$

6. Proof that $\phi([1 - \lambda]\mathbf{x} + \lambda\mathbf{y}) = [1 - \lambda]\phi\mathbf{x} + \lambda\phi\mathbf{y}$:

$$\begin{aligned}
 \phi([1 - \lambda]\mathbf{x} + \lambda\mathbf{y}) &= \\
 &= [1 - \lambda]\phi\mathbf{x} + \lambda\phi\mathbf{y}
 \end{aligned}$$



Theorem O.11 (Neumann Expansion Theorem). ²⁴ Let $\mathbf{A} \in \mathbf{X}^\mathbf{X}$ be an operator on a linear space \mathbf{X} . Let $\mathbf{A}^0 \triangleq \mathbf{I}$.

T H M	$ \left. \begin{array}{l} 1. \quad \mathbf{A} \in \mathcal{B}(\mathbf{X}, \mathbf{X}) \quad (\mathbf{A} \text{ is bounded}) \\ 2. \quad \ \mathbf{A}\ < 1 \end{array} \right\} \implies \left\{ \begin{array}{ll} 1. & (\mathbf{I} - \mathbf{A})^{-1} \quad \text{exists} \\ 2. & \ (\mathbf{I} - \mathbf{A})^{-1}\ \leq \frac{1}{1 - \ \mathbf{A}\ } \\ 3. & (\mathbf{I} - \mathbf{A})^{-1} = \sum_{n=0}^{\infty} \mathbf{A}^n \\ & \text{with uniform convergence} \end{array} \right. $
-------------	--

O.3 Operators on Inner product spaces

O.3.1 General Results

Theorem O.12. ²⁵ Let $\mathbf{A}, \mathbf{B} \in \mathcal{B}(\mathbf{X}, \mathbf{X})$ be BOUNDED LINEAR OPERATORS on an inner product space $\mathbf{X} \triangleq (X, +, \cdot, (\mathbb{F}, +, \dot{\times}), \langle \triangle | \nabla \rangle)$.

T H M	$ \begin{array}{llll} \langle \mathbf{Bx} x \rangle & = & 0 & \forall x \in X \iff \mathbf{Bx} = \mathbf{0} \quad \forall x \in X \\ \langle \mathbf{Ax} x \rangle & = & \langle \mathbf{Bx} x \rangle & \forall x \in X \iff \mathbf{A} = \mathbf{B} \end{array} $
-------------	--

²⁴ Michel and Herget (1993) page 415

²⁵ Rudin (1991) page 310 (Theorem 12.7, Corollary)

PROOF:

1. Proof that $\langle \mathbf{Bx} | x \rangle = 0 \implies \mathbf{Bx} = \mathbb{0}$:

$$\begin{aligned}
 0 &= \langle \mathbf{B}(x + \mathbf{Bx}) | (x + \mathbf{Bx}) \rangle + i \langle \mathbf{B}(x + i\mathbf{Bx}) | (x + i\mathbf{Bx}) \rangle && \text{by left hypothesis} \\
 &= \{\langle \mathbf{Bx} + \mathbf{B}^2 x | x + \mathbf{Bx} \rangle\} + i\{\langle \mathbf{Bx} + i\mathbf{B}^2 x | x + i\mathbf{Bx} \rangle\} && \text{by Definition O.3 page 304} \\
 &= \{\langle \mathbf{Bx} | x \rangle + \langle \mathbf{Bx} | \mathbf{Bx} \rangle + \langle \mathbf{B}^2 x | x \rangle + \langle \mathbf{B}^2 x | \mathbf{Bx} \rangle\} && \text{by Definition K.1 page 255} \\
 &\quad + i\{\langle \mathbf{Bx} | x \rangle - i\langle \mathbf{Bx} | \mathbf{Bx} \rangle + i\langle \mathbf{B}^2 x | x \rangle - i^2\langle \mathbf{B}^2 x | \mathbf{Bx} \rangle\} \\
 &= \{0 + \langle \mathbf{Bx} | \mathbf{Bx} \rangle + \langle \mathbf{B}^2 x | x \rangle + 0\} + i\{0 - i\langle \mathbf{Bx} | \mathbf{Bx} \rangle + i\langle \mathbf{B}^2 x | x \rangle - i^2 0\} && \text{by left hypothesis} \\
 &= \{\langle \mathbf{Bx} | \mathbf{Bx} \rangle + \langle \mathbf{B}^2 x | x \rangle\} + \{\langle \mathbf{Bx} | \mathbf{Bx} \rangle - \langle \mathbf{B}^2 x | x \rangle\} \\
 &= 2\langle \mathbf{Bx} | \mathbf{Bx} \rangle \\
 &= 2\|\mathbf{Bx}\|^2 \\
 \implies \mathbf{Bx} &= \mathbb{0} && \text{by Definition L.1 page 271}
 \end{aligned}$$

2. Proof that $\langle \mathbf{Bx} | x \rangle = 0 \iff \mathbf{Bx} = \mathbb{0}$: by property of inner products (Theorem K.1 page 255).

3. Proof that $\langle \mathbf{Ax} | x \rangle = \langle \mathbf{Bx} | x \rangle \implies \mathbf{A} \doteq \mathbf{B}$:

$$\begin{aligned}
 0 &= \langle \mathbf{Ax} | x \rangle - \langle \mathbf{Bx} | x \rangle && \text{by left hypothesis} \\
 &= \langle \mathbf{Ax} - \mathbf{Bx} | x \rangle && \text{by } \textit{additivity} \text{ property of } \langle \triangle | \nabla \rangle \text{ (Definition K.1 page 255)} \\
 &= \langle (\mathbf{A} - \mathbf{B})x | x \rangle && \text{by definition of operator addition} \\
 \implies (\mathbf{A} - \mathbf{B})x &= \mathbb{0} && \text{by item 1} \\
 \implies \mathbf{A} &= \mathbf{B} && \text{by definition of operator subtraction}
 \end{aligned}$$

4. Proof that $\langle \mathbf{Ax} | x \rangle = \langle \mathbf{Bx} | x \rangle \iff \mathbf{A} \doteq \mathbf{B}$:

$$\langle \mathbf{Ax} | x \rangle = \langle \mathbf{Bx} | x \rangle \quad \text{by } \mathbf{A} \doteq \mathbf{B} \text{ hypothesis}$$

⇒

O.3.2 Operator adjoint

A fundamental concept of operators on inner product spaces is the *operator adjoint* (Proposition O.3 page 316). The adjoint of an operator is a kind of generalization of the conjugate of a complex number in that

- Both are *star-algebras* (Theorem O.13 page 317).
- Both support decomposition into “real” and “imaginary” parts (Theorem J.3 page 252).

Structurally, the operator adjoint provides a convenient symmetric relationship between the *range space* and *null space* of an operator (Theorem O.14 page 318).

Proposition O.3. ²⁶ Let $\mathcal{B}(\mathbf{H}, \mathbf{H})$ be the space of BOUNDED LINEAR OPERATORS (Definition O.5 page 311) on a HILBERT SPACE \mathbf{H} .

P An operator \mathbf{B}^* is the **adjoint** of $\mathbf{B} \in \mathcal{B}(\mathbf{H}, \mathbf{H})$ if
R $\langle \mathbf{Bx} | y \rangle = \langle x | \mathbf{B}^* y \rangle \quad \forall x, y \in \mathbf{H}$.

²⁶ Michel and Herget (1993) page 220, Rudin (1991) page 311, Giles (2000), page 182, von Neumann (1929) page 49, Stone (1932) page 41



PROOF:

1. For fixed y , $f(x) \triangleq \langle x | y \rangle$ is a *functional* in \mathbb{F}^X .

2. \mathbf{B}^* is the *adjoint* of \mathbf{B} because

$$\begin{aligned} \langle \mathbf{B}x | y \rangle &\triangleq f(\mathbf{B}x) \\ &\triangleq \mathbf{B}^*f(x) \quad \text{by definition of operator adjoint} \\ &= \langle x | \mathbf{B}^*y \rangle \end{aligned} \quad (\text{Definition O.6 page 313})$$



Example O.2.

E
X

In matrix algebra (“linear algebra”)

- The inner product operation $\langle x | y \rangle$ is represented by $y^H x$.
- The linear operator is represented as a matrix A .
- The operation of A on a vector x is represented as Ax .
- The adjoint of matrix A is the Hermitian matrix A^H .



Structures that satisfy the four conditions of the next theorem are known as **-algebras* (“star-algebras” (Definition J.3 page 250)). Other structures which are *-algebras include the *field of complex numbers* \mathbb{C} and any *ring of complex square $n \times n$ matrices*.²⁷

Theorem O.13 (operator star-algebra). ²⁸ Let H be a HILBERT SPACE with operators $A, B \in \mathcal{B}(H, H)$ and with adjoints $A^*, B^* \in \mathcal{B}(H, H)$. Let $\bar{\alpha}$ be the complex conjugate of some $\alpha \in \mathbb{C}$.

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The pair $(H, *)$ is a *-ALGEBRA (STAR-ALGEBRA). In particular,

1. $(A + B)^* = A^* + B^*$ $\forall A, B \in H$ (DISTRIBUTIVE) and
2. $(\alpha A)^* = \bar{\alpha} A^*$ $\forall A, B \in H$ (CONJUGATE LINEAR) and
3. $(AB)^* = B^* A^*$ $\forall A, B \in H$ (ANTIAUTOMORPHIC) and
4. $A^{**} = A$ $\forall A, B \in H$ (INVOLUTARY)

PROOF:

$$\begin{aligned} \langle x | (A + B)^* y \rangle &= \langle (A + B)x | y \rangle \quad \text{by definition of adjoint} \\ &= \langle Ax | y \rangle + \langle Bx | y \rangle \quad \text{by definition of inner product} \\ &= \langle x | A^* y \rangle + \langle x | B^* y \rangle \quad \text{by definition of operator addition} \\ &= \langle x | A^* y + B^* y \rangle \quad \text{by definition of inner product} \\ &= \langle x | (A^* + B^*) y \rangle \quad \text{by definition of operator addition} \end{aligned} \quad (\text{Proposition O.3 page 316})$$

$$\begin{aligned} \langle x | (\alpha A)^* y \rangle &= \langle (\alpha A)x | y \rangle \quad \text{by definition of adjoint} \\ &= \langle \alpha(Ax) | y \rangle \quad \text{by definition of scalar multiplication} \\ &= \alpha \langle Ax | y \rangle \quad \text{by definition of inner product} \end{aligned} \quad (\text{Proposition O.3 page 316})$$

²⁷ Sakai (1998) page 1

²⁸ Halmos (1998a), pages 39–40, Rudin (1991) page 311

$$\begin{aligned} &= \alpha \langle x | A^* y \rangle && \text{by definition of adjoint} && (\text{Proposition O.3 page 316}) \\ &= \langle x | \alpha^* A^* y \rangle && \text{by definition of inner product} && (\text{Definition K.1 page 255}) \end{aligned}$$

$$\begin{aligned} \langle x | (AB)^* y \rangle &= \langle (AB)x | y \rangle && \text{by definition of adjoint} && (\text{Proposition O.3 page 316}) \\ &= \langle Ax | By \rangle && \text{by definition of operator multiplication} && \\ &= \langle Bx | A^* y \rangle && \text{by definition of adjoint} && (\text{Proposition O.3 page 316}) \\ &= \langle x | B^* A^* y \rangle && \text{by definition of adjoint} && (\text{Proposition O.3 page 316}) \end{aligned}$$

$$\begin{aligned} \langle x | A^{**} y \rangle &= \langle A^* x | y \rangle && \text{by definition of adjoint} && (\text{Proposition O.3 page 316}) \\ &= \langle y | A^* x \rangle^* && \text{by definition of inner product} && (\text{Definition K.1 page 255}) \\ &= \langle Ay | x \rangle^* && \text{by definition of adjoint} && (\text{Proposition O.3 page 316}) \\ &= \langle x | Ay \rangle && \text{by definition of inner product} && (\text{Definition K.1 page 255}) \end{aligned}$$

⇒

Theorem O.14. ²⁹ Let Y^X be the set of all operators from a linear space X to a linear space Y . Let $\mathcal{N}(L)$ be the NULL SPACE of an operator L in Y^X and $I(L)$ the IMAGE SET of L in Y^X .

T	$\mathcal{N}(A) = I(A^*)^\perp$
H	
M	$\mathcal{N}(A^*) = I(A)^\perp$

PROOF:

$$\begin{aligned} I(A^*)^\perp &= \{y \in H \mid \langle y | u \rangle = 0 \quad \forall u \in I(A^*)\} \\ &= \{y \in H \mid \langle y | A^* x \rangle = 0 \quad \forall x \in H\} \\ &= \{y \in H \mid \langle Ay | x \rangle = 0 \quad \forall x \in H\} && \text{by definition of } A^* && (\text{Proposition O.3 page 316}) \\ &= \{y \in H \mid Ay = 0\} \\ &= \mathcal{N}(A) && \text{by definition of } \mathcal{N}(A) \end{aligned}$$

$$\begin{aligned} I(A)^\perp &= \{y \in H \mid \langle y | u \rangle = 0 \quad \forall u \in I(A)\} \\ &= \{y \in H \mid \langle y | Ax \rangle = 0 \quad \forall x \in H\} && \text{by definition of } I \\ &= \{y \in H \mid \langle A^* y | x \rangle = 0 \quad \forall x \in H\} && \text{by definition of } A^* && (\text{Proposition O.3 page 316}) \\ &= \{y \in H \mid A^* y = 0\} \\ &= \mathcal{N}(A^*) && \text{by definition of } \mathcal{N}(A) \end{aligned}$$

⇒

O.4 Special Classes of Operators

O.4.1 Projection operators

Definition O.7. ³⁰ Let $B(X, Y)$ be the space of BOUNDED LINEAR OPERATORS on normed linear spaces X and Y . Let P be a bounded linear operator in $B(X, Y)$.

²⁹ Rudin (1991) page 312

³⁰ Rudin (1991) page 133 (5.15 Projections), Kubrusly (2001) page 70, Bachman and Narici (1966) page 6, Halmos (1958) page 73 (§41. Projections)



**D
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F**

P is a **projection operator** if $\mathbf{P}^2 = \mathbf{P}$.

Theorem O.15. ³¹ Let $\mathcal{B}(X, Y)$ be the space of BOUNDED LINEAR OPERATORS on normed linear spaces X and Y . Let \mathbf{P} be a bounded linear operator in $\mathcal{B}(X, Y)$ with NULL SPACE $\mathcal{N}(\mathbf{P})$ and IMAGE SET $\mathcal{I}(\mathbf{P})$.

**T
H
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$$\left. \begin{array}{ll} 1. \quad \mathbf{P}^2 = \mathbf{P} & (\mathbf{P} \text{ is a projection operator}) \\ 2. \quad \Omega = X \hat{+} Y & (Y \text{ complements } X \text{ in } \Omega) \\ 3. \quad \mathbf{P}\Omega = X & (\mathbf{P} \text{ projects onto } X) \end{array} \right\} \Rightarrow \left\{ \begin{array}{ll} 1. \quad \mathcal{I}(\mathbf{P}) = X & \text{and} \\ 2. \quad \mathcal{N}(\mathbf{P}) = Y & \text{and} \\ 3. \quad \Omega = \mathcal{I}(\mathbf{P}) \hat{+} \mathcal{N}(\mathbf{P}) \end{array} \right.$$

PROOF:

$$\begin{aligned} \mathcal{I}(\mathbf{P}) &= \mathbf{P}\Omega \\ &= \mathbf{P}(\Omega_1 + \Omega_2) \\ &= \mathbf{P}\Omega_1 + \mathbf{P}\Omega_2 \\ &= \Omega_1 + \{\mathbf{0}\} \\ &= \Omega_1 \end{aligned}$$

$$\begin{aligned} \mathcal{N}(\mathbf{P}) &= \{x \in \Omega \mid \mathbf{P}x = \mathbf{0}\} \\ &= \{x \in (\Omega_1 + \Omega_2) \mid \mathbf{P}x = \mathbf{0}\} \\ &= \{x \in \Omega_1 \mid \mathbf{P}x = \mathbf{0}\} + \{x \in \Omega_2 \mid \mathbf{P}x = \mathbf{0}\} \\ &= \{\mathbf{0}\} + \Omega_2 \\ &= \Omega_2 \end{aligned}$$

⇒

Theorem O.16. ³² Let $\mathcal{B}(X, Y)$ be the space of BOUNDED LINEAR OPERATORS on normed linear spaces X and Y . Let \mathbf{P} be a bounded linear operator in $\mathcal{B}(X, Y)$.

**T
H
M**

$$\underbrace{\mathbf{P}^2 = \mathbf{P}}_{\mathbf{P} \text{ is a projection operator}} \iff \underbrace{(\mathbf{I} - \mathbf{P})^2 = (\mathbf{I} - \mathbf{P})}_{(\mathbf{I} - \mathbf{P}) \text{ is a projection operator}}$$

PROOF:

Proof that $\mathbf{P}^2 = \mathbf{P} \implies (\mathbf{I} - \mathbf{P})^2 = (\mathbf{I} - \mathbf{P})$:

$$\begin{aligned} (\mathbf{I} - \mathbf{P})^2 &= (\mathbf{I} - \mathbf{P})(\mathbf{I} - \mathbf{P}) \\ &= \mathbf{I}(\mathbf{I} - \mathbf{P}) + (-\mathbf{P})(\mathbf{I} - \mathbf{P}) \\ &= \mathbf{I} - \mathbf{P} - \mathbf{P}\mathbf{I} + \mathbf{P}^2 \\ &= \mathbf{I} - \mathbf{P} - \mathbf{P} + \mathbf{P} && \text{by left hypothesis} \\ &= \mathbf{I} - \mathbf{P} \end{aligned}$$

Proof that $\mathbf{P}^2 = \mathbf{P} \iff (\mathbf{I} - \mathbf{P})^2 = (\mathbf{I} - \mathbf{P})$:

$$\begin{aligned} \mathbf{P}^2 &= \underbrace{\mathbf{I} - \mathbf{P} - \mathbf{P} + \mathbf{P}^2}_{(\mathbf{I} - \mathbf{P})^2} - (\mathbf{I} - \mathbf{P} - \mathbf{P}) \\ &= (\mathbf{I} - \mathbf{P})^2 - (\mathbf{I} - \mathbf{P} - \mathbf{P}) \\ &= (\mathbf{I} - \mathbf{P}) - (\mathbf{I} - \mathbf{P} - \mathbf{P}) && \text{by right hypothesis} \\ &= \mathbf{P} \end{aligned}$$

⇒

³¹ Michel and Herget (1993) pages 120–121

³² Michel and Herget (1993) page 121

Theorem O.17. ³³ Let \mathbf{H} be a HILBERT SPACE and \mathbf{P} an operator in $\mathcal{B}(\mathbf{H})$ with adjoint \mathbf{P}^* , NULL SPACE $\mathcal{N}(\mathbf{P})$, and IMAGE SET $\mathcal{I}(\mathbf{P})$.

If \mathbf{P} is a PROJECTION OPERATOR, then the following are equivalent:

- | | | | |
|-------------|---|--|--------|
| T
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M | 1. $\mathbf{P}^* = \mathbf{P}$ | <small>(\mathbf{P} is SELF-ADJOINT)</small> | \iff |
| | 2. $\mathbf{P}^*\mathbf{P} = \mathbf{P}\mathbf{P}^*$ | <small>(\mathbf{P} is NORMAL)</small> | \iff |
| | 3. $\mathcal{I}(\mathbf{P}) = \mathcal{N}(\mathbf{P})^\perp$ | | \iff |
| | 4. $\langle \mathbf{P}\mathbf{x} \mathbf{x} \rangle = \ \mathbf{P}\mathbf{x}\ ^2 \quad \forall \mathbf{x} \in \mathbf{X}$ | | |

PROOF: This proof is incomplete at this time.

Proof that (1) \implies (2):

$$\begin{aligned} \mathbf{P}^*\mathbf{P} &= \mathbf{P}^*\mathbf{P}^* && \text{by (1)} \\ &= \mathbf{P}\mathbf{P}^* && \text{by Theorem O.13 page 317} \end{aligned}$$

Proof that (1) \implies (3):

$$\begin{aligned} \mathcal{I}(\mathbf{P}) &= \mathcal{N}(\mathbf{P}^*)^\perp && \text{by Theorem O.14 page 318} \\ &= \mathcal{N}(\mathbf{P})^\perp && \text{by (1)} \end{aligned}$$

Proof that (3) \implies (4):

Proof that (4) \implies (1):



O.4.2 Self Adjoint Operators

Definition O.8. ³⁴ Let $\mathbf{B} \in \mathcal{B}(\mathbf{H}, \mathbf{H})$ be a BOUNDED operator with adjoint \mathbf{B}^* on a HILBERT SPACE \mathbf{H} .

D E F The operator \mathbf{B} is said to be **self-adjoint** or **hermitian** if $\mathbf{B} = \mathbf{B}^*$.

Example O.3 (Autocorrelation operator). Let $\mathbf{x}(t)$ be a random process with autocorrelation

$$R_{xx}(t, u) \triangleq \underbrace{\mathbb{E}[x(t)x^*(u)]}_{\text{expectation}}$$

Let an autocorrelation operator \mathbf{R} be defined as $[\mathbf{R}\mathbf{f}](t) \triangleq \int_{\mathbb{R}} R_{xx}(t, u)\mathbf{f}(u) du$.

E X $\mathbf{R} = \mathbf{R}^*$ (The auto-correlation operator \mathbf{R} is *self-adjoint*)

Theorem O.18. ³⁵ Let $\mathbf{S} : \mathbf{H} \rightarrow \mathbf{H}$ be an operator over a HILBERT SPACE \mathbf{H} with eigenvalues $\{\lambda_n\}$ and eigenfunctions $\{\psi_n\}$ such that $\mathbf{S}\psi_n = \lambda_n\psi_n$ and let $\|\mathbf{x}\| \triangleq \sqrt{\langle \mathbf{x} | \mathbf{x} \rangle}$.

T H M $\left\{ \begin{array}{l} \mathbf{S} = \mathbf{S}^* \\ \mathbf{S} \text{ is selfadjoint} \end{array} \right\} \implies \left\{ \begin{array}{ll} 1. \langle \mathbf{S}\mathbf{x} | \mathbf{x} \rangle \in \mathbb{R} & (\text{the hermitian quadratic form of } \mathbf{S} \text{ is REAL-VALUED}) \\ 2. \lambda_n \in \mathbb{R} & (\text{eigenvalues of } \mathbf{S} \text{ are REAL-VALUED}) \\ 3. \lambda_n \neq \lambda_m \implies \langle \psi_n | \psi_m \rangle = 0 & (\text{eigenvectors are ORTHOGONAL}) \end{array} \right\}$

³³ Rudin (1991) page 314

³⁴ Historical works regarding self-adjoint operators: von Neumann (1929), page 49, "linearer Operator R selbstdjugiert oder Hermitesch", Stone (1932), page 50 ('self-adjoint transformations')

³⁵ Lax (2002), pages 315–316, Keener (1988), pages 114–119, Bachman and Narici (1966) page 24 (Theorem 2.1), Bertero and Boccacci (1998) page 225 (§“9.2 SVD of a matrix ...If all eigenvectors are normalized...”)

PROOF:

1. Proof that $S = S^* \implies \langle Sx | x \rangle \in \mathbb{R}$:

$$\begin{aligned} \langle x | Sx \rangle &= \langle Sx | x \rangle && \text{by left hypothesis} \\ &= \langle x | Sx \rangle^* && \text{by definition of } \langle \cdot | \cdot \rangle \text{ Definition K.1 page 255} \end{aligned}$$

2. Proof that $S = S^* \implies \lambda_n \in \mathbb{R}$:

$$\begin{aligned} \lambda_n \|\psi_n\|^2 &= \lambda_n \langle \psi_n | \psi_n \rangle && \text{by definition} \\ &= \langle \lambda_n \psi_n | \psi_n \rangle && \text{by definition of } \langle \cdot | \cdot \rangle \text{ Definition K.1 page 255} \\ &= \langle S\psi_n | \psi_n \rangle && \text{by definition of eigenpairs} \\ &= \langle \psi_n | S\psi_n \rangle && \text{by left hypothesis} \\ &= \langle \psi_n | \lambda_n \psi_n \rangle && \text{by definition of eigenpairs} \\ &= \lambda_n^* \langle \psi_n | \psi_n \rangle && \text{by definition of } \langle \cdot | \cdot \rangle \text{ Definition K.1 page 255} \\ &= \lambda_n^* \|\psi_n\|^2 && \text{by definition} \end{aligned}$$

3. Proof that $S = S^* \implies [\lambda_n \neq \lambda_m \implies \langle \psi_n | \psi_m \rangle = 0]$:

$$\begin{aligned} \lambda_n \langle \psi_n | \psi_m \rangle &= \langle \lambda_n \psi_n | \psi_m \rangle && \text{by definition of } \langle \cdot | \cdot \rangle \text{ Definition K.1 page 255} \\ &= \langle S\psi_n | \psi_m \rangle && \text{by definition of eigenpairs} \\ &= \langle \psi_n | S\psi_m \rangle && \text{by left hypothesis} \\ &= \langle \psi_n | \lambda_m \psi_m \rangle && \text{by definition of eigenpairs} \\ &= \lambda_m^* \langle \psi_n | \psi_m \rangle && \text{by definition of } \langle \cdot | \cdot \rangle \text{ Definition K.1 page 255} \\ &= \lambda_m \langle \psi_n | \psi_m \rangle && \text{because } \lambda_m \text{ is real} \end{aligned}$$

This implies for $\lambda_n \neq \lambda_m \neq 0$, $\langle \psi_n | \psi_m \rangle = 0$.



O.4.3 Normal Operators

Definition O.9. ³⁶ Let $\mathcal{B}(X, Y)$ be the space of BOUNDED LINEAR OPERATORS on normed linear spaces X and Y . Let N^* be the adjoint of an operator $N \in \mathcal{B}(X, Y)$.

D E F N is **normal** if $N^*N = NN^*$.

Theorem O.19. ³⁷ Let $\mathcal{B}(H, H)$ be the space of BOUNDED LINEAR OPERATORS on a HILBERT SPACE H . Let $\mathcal{N}(N)$ be the NULL SPACE of an operator N in $\mathcal{B}(H, H)$ and $\mathcal{I}(N)$ the IMAGE SET of N in $\mathcal{B}(H, H)$.

T H M	$\underbrace{N^*N = NN^*}_{N \text{ is normal}}$	\iff	$\ N^*x\ = \ Nx\ \quad \forall x \in H$
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³⁶ Rudin (1991) page 312, Michel and Herget (1993) page 431, Dieudonné (1969), page 167, Frobenius (1878), Frobenius (1968), page 391

³⁷ Rudin (1991) pages 312–313

PROOF:

1. Proof that $\mathbf{N}^*\mathbf{N} = \mathbf{N}\mathbf{N}^* \implies \|\mathbf{N}^*\mathbf{x}\| = \|\mathbf{N}\mathbf{x}\|$:

$$\begin{aligned}
 \|\mathbf{N}\mathbf{x}\|^2 &= \langle \mathbf{N}\mathbf{x} | \mathbf{N}\mathbf{x} \rangle && \text{by definition} \\
 &= \langle \mathbf{x} | \mathbf{N}^*\mathbf{N}\mathbf{x} \rangle && \text{by Proposition O.3 page 316 (definition of } \mathbf{N}^*) \\
 &= \langle \mathbf{x} | \mathbf{N}\mathbf{N}^*\mathbf{x} \rangle && \text{by left hypothesis (N is normal)} \\
 &= \langle \mathbf{N}\mathbf{x} | \mathbf{N}^*\mathbf{x} \rangle && \text{by Proposition O.3 page 316 (definition of } \mathbf{N}^*) \\
 &= \|\mathbf{N}^*\mathbf{x}\|^2 && \text{by definition}
 \end{aligned}$$

2. Proof that $\mathbf{N}^*\mathbf{N} = \mathbf{N}\mathbf{N}^* \iff \|\mathbf{N}^*\mathbf{x}\| = \|\mathbf{N}\mathbf{x}\|$:

$$\begin{aligned}
 \langle \mathbf{N}^*\mathbf{N}\mathbf{x} | \mathbf{x} \rangle &= \langle \mathbf{N}\mathbf{x} | \mathbf{N}^*\mathbf{x} \rangle && \text{by Proposition O.3 page 316 (definition of } \mathbf{N}^*) \\
 &= \langle \mathbf{N}\mathbf{x} | \mathbf{N}\mathbf{x} \rangle && \text{by Theorem O.13 page 317 (property of adjoint)} \\
 &= \|\mathbf{N}\mathbf{x}\|^2 && \text{by definition} \\
 &= \|\mathbf{N}^*\mathbf{x}\|^2 && \text{by right hypothesis (\|N}^*\mathbf{x}\| = \|\mathbf{N}\mathbf{x}\|)} \\
 &= \langle \mathbf{N}^*\mathbf{x} | \mathbf{N}^*\mathbf{x} \rangle && \text{by definition} \\
 &= \langle \mathbf{N}\mathbf{N}^*\mathbf{x} | \mathbf{x} \rangle && \text{by Proposition O.3 page 316 (definition of } \mathbf{N}^*)
 \end{aligned}$$

⇒

Theorem O.20.³⁸ Let $\mathcal{B}(\mathbf{H}, \mathbf{H})$ be the space of BOUNDED LINEAR OPERATORS on a HILBERT SPACE \mathbf{H} . Let $\mathcal{N}(\mathbf{N})$ be the NULL SPACE of an operator \mathbf{N} in $\mathcal{B}(\mathbf{H}, \mathbf{H})$ and $\mathcal{I}(\mathbf{N})$ the IMAGE SET of \mathbf{N} in $\mathcal{B}(\mathbf{H}, \mathbf{H})$.

T H M	$\underbrace{\mathbf{N}^*\mathbf{N} = \mathbf{N}\mathbf{N}^*}_{\mathbf{N} \text{ is normal}}$	\implies	$\underbrace{\mathcal{N}(\mathbf{N}^*) = \mathcal{N}(\mathbf{N})}_{\mathbf{N} \text{ and } \mathbf{N}^* \text{ have the same null space}}$
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PROOF:

$$\begin{aligned}
 \mathcal{N}(\mathbf{N}^*) &= \{ \mathbf{x} | \mathbf{N}^*\mathbf{x} = 0 \quad \forall \mathbf{x} \in \mathbf{X} \} && \text{(definition of } \mathcal{N}^*) \\
 &= \{ \mathbf{x} | \| \mathbf{N}^*\mathbf{x} \| = 0 \quad \forall \mathbf{x} \in \mathbf{X} \} && \text{by definition of } \| \cdot \| \text{ (Definition L.1 page 271)} \\
 &= \{ \mathbf{x} | \| \mathbf{N}\mathbf{x} \| = 0 \quad \forall \mathbf{x} \in \mathbf{X} \} && \text{by definition of } \| \cdot \| \text{ (Definition L.1 page 271)} \\
 &= \{ \mathbf{x} | \mathbf{N}\mathbf{x} = 0 \quad \forall \mathbf{x} \in \mathbf{X} \} && \text{(definition of } \mathcal{N})
 \end{aligned}$$

⇒

Theorem O.21.³⁹ Let $\mathcal{B}(\mathbf{H}, \mathbf{H})$ be the space of BOUNDED LINEAR OPERATORS on a HILBERT SPACE \mathbf{H} . Let $\mathcal{N}(\mathbf{N})$ be the NULL SPACE of an operator \mathbf{N} in $\mathcal{B}(\mathbf{H}, \mathbf{H})$ and $\mathcal{I}(\mathbf{N})$ the IMAGE SET of \mathbf{N} in $\mathcal{B}(\mathbf{H}, \mathbf{H})$.

T H M	$\left\{ \underbrace{\mathbf{N}^*\mathbf{N} = \mathbf{N}\mathbf{N}^*}_{\mathbf{N} \text{ is normal}} \right\}$	\implies	$\left\{ \underbrace{\lambda_n \neq \lambda_m \implies \langle \psi_n \psi_m \rangle = 0}_{\text{eigenfunctions associated with distinct eigenvalues are orthogonal}} \right\}$
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PROOF: The proof in (1) is flawed. This implies that (2) is also flawed. [Rudin] claims both to be true. (Rudin, 1991)313

³⁸ Rudin (1991) pages 312–313

³⁹ Rudin (1991) pages 312–313

1. Proof that $\mathbf{N}^* \mathbf{N} = \mathbf{N} \mathbf{N}^* \implies \mathbf{N}^* \psi = \lambda^* \psi$:

$$\begin{aligned}
 \mathbf{N}\psi &= \lambda\psi \\
 \iff 0 &= \mathcal{N}(\mathbf{N} - \lambda\mathbf{I}) \\
 &= \mathcal{N}([\mathbf{N} - \lambda\mathbf{I}]^*) && \text{by } \mathcal{N}(\mathbf{N}) = \mathcal{N}(\mathbf{N}^*) \\
 &= \mathcal{N}(\mathbf{N}^* - [\lambda\mathbf{I}]^*) && \text{by Theorem O.13 page 317} \\
 &= \mathcal{N}(\mathbf{N}^* - \lambda^*\mathbf{I}^*) && \text{by Theorem O.13 page 317} \\
 &= \mathcal{N}(\mathbf{N}^* - \lambda^*\mathbf{I}) \\
 \implies (\mathbf{N}^* - \lambda^*\mathbf{I})\psi &= 0 \\
 \iff \mathbf{N}^*\psi &= \lambda^*\psi
 \end{aligned}$$

2. Proof that $\mathbf{N}^* \mathbf{N} = \mathbf{N} \mathbf{N}^* \implies [\lambda_n \neq \lambda_m \implies \langle \psi_n | \psi_m \rangle = 0]$:

$$\begin{aligned}
 \lambda_n \langle \psi_n | \psi_m \rangle &= \langle \lambda_n \psi_n | \psi_m \rangle && \text{by definition of } \langle \triangle | \triangleright \rangle \text{ Definition K.1 page 255} \\
 &= \langle \mathbf{N}\psi_n | \psi_m \rangle && \text{by definition of eigenpairs} \\
 &= \langle \psi_n | \mathbf{N}^*\psi_m \rangle && \text{by Proposition O.3 page 316 (definition of adjoint)} \\
 &= \langle \psi_n | \lambda_m^* \psi_m \rangle && \text{by (4.)} \\
 &= \lambda_m \langle \psi_n | \psi_m \rangle && \text{by definition of } \langle \triangle | \triangleright \rangle \text{ Definition K.1 page 255}
 \end{aligned}$$

This implies for $\lambda_n \neq \lambda_m \neq 0$, $\langle \psi_n | \psi_m \rangle = 0$.



O.4.4 Isometric operators

An operator on a pair of normed linear spaces is *isometric* (next definition) if it is an *isometry*.

Definition O.10. Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$ and $(Y, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$ be NORMED LINEAR SPACES (Definition L.1 page 271).

D E F An operator $\mathbf{M} \in \mathcal{L}(X, Y)$ is **isometric** if $\|\mathbf{M}\mathbf{x}\| = \|\mathbf{x}\| \quad \forall \mathbf{x} \in X$.

Theorem O.22. ⁴⁰ Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$ and $(Y, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$ be NORMED LINEAR SPACES. Let \mathbf{M} be a linear operator in $\mathcal{L}(X, Y)$.

T H M	$\underbrace{\ \mathbf{M}\mathbf{x}\ = \ \mathbf{x}\ }_{\text{isometric in length}} \quad \iff \quad \underbrace{\ \mathbf{M}\mathbf{x} - \mathbf{M}\mathbf{y}\ = \ \mathbf{x} - \mathbf{y}\ }_{\text{isometric in distance}} \quad \forall \mathbf{x}, \mathbf{y} \in X$
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PROOF:

1. Proof that $\|\mathbf{M}\mathbf{x}\| = \|\mathbf{x}\| \implies \|\mathbf{M}\mathbf{x} - \mathbf{M}\mathbf{y}\| = \|\mathbf{x} - \mathbf{y}\|$:

$$\begin{aligned}
 \|\mathbf{M}\mathbf{x} - \mathbf{M}\mathbf{y}\| &= \|\mathbf{M}(\mathbf{x} - \mathbf{y})\| && \text{by definition of linear operators (Definition O.3 page 304)} \\
 &= \|\mathbf{M}\mathbf{u}\| && \text{let } \mathbf{u} \triangleq \mathbf{x} - \mathbf{y} \\
 &= \|\mathbf{x} - \mathbf{y}\| && \text{by left hypothesis}
 \end{aligned}$$

⁴⁰ Kubrusly (2001) page 239 (Proposition 4.37), Berberian (1961) page 27 (Theorem IV.7.5)

2. Proof that $\|\mathbf{M}\mathbf{x}\| = \|\mathbf{x}\| \iff \|\mathbf{M}\mathbf{x} - \mathbf{M}\mathbf{y}\| = \|\mathbf{x} - \mathbf{y}\|$:

$$\begin{aligned}\|\mathbf{M}\mathbf{x}\| &= \|\mathbf{M}(\mathbf{x} - \mathbf{0})\| \\ &= \|\mathbf{M}\mathbf{x} - \mathbf{M}\mathbf{0}\| && \text{by definition of linear operators (Definition O.3 page 304)} \\ &= \|\mathbf{x} - \mathbf{0}\| && \text{by right hypothesis} \\ &= \|\mathbf{x}\|\end{aligned}$$



Isometric operators have already been defined (Definition O.10 page 323) in the more general normed linear spaces, while Theorem O.22 (page 323) demonstrated that in a normed linear space \mathbf{X} , $\|\mathbf{M}\mathbf{x}\| = \|\mathbf{x}\| \iff \|\mathbf{M}\mathbf{x} - \mathbf{M}\mathbf{y}\| = \|\mathbf{x} - \mathbf{y}\|$ for all $\mathbf{x}, \mathbf{y} \in \mathbf{X}$. Here in the more specialized inner product spaces, Theorem O.23 (next) demonstrates two additional equivalent properties.

Theorem O.23.⁴¹ Let $\mathcal{B}(\mathbf{X}, \mathbf{X})$ be the space of BOUNDED LINEAR OPERATORS on a normed linear space $\mathbf{X} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$. Let \mathbf{N} be a bounded linear operator in $\mathcal{L}(\mathbf{X}, \mathbf{X})$, and \mathbf{I} the identity operator in $\mathcal{L}(\mathbf{X}, \mathbf{X})$. Let $\|\mathbf{x}\| \triangleq \sqrt{\langle \mathbf{x} | \mathbf{x} \rangle}$.

The following conditions are all equivalent:

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- | | | |
|----|---|--------|
| 1. | $\mathbf{M}^*\mathbf{M} = \mathbf{I}$ | \iff |
| 2. | $\langle \mathbf{M}\mathbf{x} \mathbf{M}\mathbf{y} \rangle = \langle \mathbf{x} \mathbf{y} \rangle \quad \forall \mathbf{x}, \mathbf{y} \in X \quad (\mathbf{M} \text{ is surjective})$ | \iff |
| 3. | $\ \mathbf{M}\mathbf{x} - \mathbf{M}\mathbf{y}\ = \ \mathbf{x} - \mathbf{y}\ \quad \forall \mathbf{x}, \mathbf{y} \in X \quad (\text{isometric in distance})$ | \iff |
| 4. | $\ \mathbf{M}\mathbf{x}\ = \ \mathbf{x}\ \quad \forall \mathbf{x} \in X \quad (\text{isometric in length})$ | \iff |

PROOF:

1. Proof that (1) \implies (2):

$$\begin{aligned}\langle \mathbf{M}\mathbf{x} | \mathbf{M}\mathbf{y} \rangle &= \langle \mathbf{x} | \mathbf{M}^*\mathbf{M}\mathbf{y} \rangle && \text{by Proposition O.3 page 316 (definition of adjoint)} \\ &= \langle \mathbf{x} | \mathbf{I}\mathbf{y} \rangle && \text{by (1)} \\ &= \langle \mathbf{x} | \mathbf{y} \rangle && \text{by Definition O.2 page 303 (definition of I)}$$

2. Proof that (2) \implies (4):

$$\begin{aligned}\|\mathbf{M}\mathbf{x}\| &= \sqrt{\langle \mathbf{M}\mathbf{x} | \mathbf{M}\mathbf{x} \rangle} && \text{by definition of } \|\cdot\| \\ &= \sqrt{\langle \mathbf{x} | \mathbf{x} \rangle} && \text{by right hypothesis} \\ &= \|\mathbf{x}\| && \text{by definition of } \|\cdot\|\end{aligned}$$

3. Proof that (2) \iff (4):

$$\begin{aligned}4 \langle \mathbf{M}\mathbf{x} | \mathbf{M}\mathbf{y} \rangle &= \|\mathbf{M}\mathbf{x} + \mathbf{M}\mathbf{y}\|^2 - \|\mathbf{M}\mathbf{x} - \mathbf{M}\mathbf{y}\|^2 + i \|\mathbf{M}\mathbf{x} + i\mathbf{M}\mathbf{y}\|^2 - i \|\mathbf{M}\mathbf{x} - i\mathbf{M}\mathbf{y}\|^2 && \text{by polarization id.} \\ &= \|\mathbf{M}(\mathbf{x} + \mathbf{y})\|^2 - \|\mathbf{M}(\mathbf{x} - \mathbf{y})\|^2 + i \|\mathbf{M}(\mathbf{x} + i\mathbf{y})\|^2 - i \|\mathbf{M}(\mathbf{x} - i\mathbf{y})\|^2 && \text{by Definition O.3} \\ &= \|\mathbf{x} + \mathbf{y}\|^2 - \|\mathbf{x} - \mathbf{y}\|^2 + i \|\mathbf{x} + i\mathbf{y}\|^2 - i \|\mathbf{x} - i\mathbf{y}\|^2 && \text{by left hypothesis}\end{aligned}$$

4. Proof that (3) \iff (4): by Theorem O.22 page 323

⁴¹ Michel and Herget (1993) page 432 (Theorem 7.5.8), Kubrusly (2001) page 391 (Proposition 5.72)

5. Proof that (4) \implies (1):

$$\begin{aligned}
 \langle \mathbf{M}^* \mathbf{M} \mathbf{x} | \mathbf{x} \rangle &= \langle \mathbf{M} \mathbf{x} | \mathbf{M}^* \mathbf{x} \rangle && \text{by Proposition O.3 page 316 (definition of adjoint)} \\
 &= \langle \mathbf{M} \mathbf{x} | \mathbf{M} \mathbf{x} \rangle && \text{by Theorem O.13 page 317 (property of adjoint)} \\
 &= \|\mathbf{M} \mathbf{x}\|^2 && \text{by definition} \\
 &= \|\mathbf{x}\|^2 && \text{by left hypothesis with } y = 0 \\
 &= \langle \mathbf{x} | \mathbf{x} \rangle && \text{by definition} \\
 &= \langle \mathbf{I} \mathbf{x} | \mathbf{x} \rangle && \text{by Definition O.2 page 303 (definition of I)} \\
 \implies \mathbf{M}^* \mathbf{M} &= \mathbf{I} && \forall \mathbf{x} \in X
 \end{aligned}$$



Theorem O.24.⁴² Let $\mathcal{B}(\mathbf{X}, \mathbf{Y})$ be the space of BOUNDED LINEAR OPERATORS on normed linear spaces \mathbf{X} and \mathbf{Y} . Let \mathbf{M} be a bounded linear operator in $\mathcal{B}(\mathbf{X}, \mathbf{Y})$, and \mathbf{I} the identity operator in $\mathcal{L}(\mathbf{X}, \mathbf{X})$. Let Λ be the set of eigenvalues of \mathbf{M} . Let $\|\mathbf{x}\| \triangleq \sqrt{\langle \mathbf{x} | \mathbf{x} \rangle}$.

THM	$\underbrace{\mathbf{M}^* \mathbf{M} = \mathbf{I}}_{\mathbf{M} \text{ is isometric}}$ $\implies \left\{ \begin{array}{l} \ \mathbf{M}\ = 1 \quad (\text{UNIT LENGTH}) \\ \lambda = 1 \quad \forall \lambda \in \Lambda \end{array} \right.$
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PROOF:

1. Proof that $\mathbf{M}^* \mathbf{M} = \mathbf{I} \implies \|\mathbf{M}\| = 1$:

$$\begin{aligned}
 \|\mathbf{M}\| &= \sup_{\mathbf{x} \in \mathbf{X}} \{ \|\mathbf{M} \mathbf{x}\| \mid \|\mathbf{x}\| = 1 \} && \text{by Definition O.4 page 308} \\
 &= \sup_{\mathbf{x} \in \mathbf{X}} \{ \|\mathbf{x}\| \mid \|\mathbf{x}\| = 1 \} && \text{by Theorem O.23 page 324} \\
 &= \sup_{\mathbf{x} \in \mathbf{X}} \{ 1 \} \\
 &= 1
 \end{aligned}$$

2. Proof that $|\lambda| = 1$: Let (\mathbf{x}, λ) be an eigenvector-eigenvalue pair.

$$\begin{aligned}
 1 &= \frac{1}{\|\mathbf{x}\|} \|\mathbf{x}\| \\
 &= \frac{1}{\|\mathbf{x}\|} \|\mathbf{M} \mathbf{x}\| && \text{by Theorem O.23 page 324} \\
 &= \frac{1}{\|\mathbf{x}\|} \|\lambda \mathbf{x}\| && \text{by definition of } \lambda \\
 &= \frac{1}{\|\mathbf{x}\|} |\lambda| \|\mathbf{x}\| && \text{by homogeneous property of } \|\cdot\| \\
 &= |\lambda|
 \end{aligned}$$



*Example O.4 (One sided shift operator).*⁴³ Let \mathbf{X} be the set of all sequences with range $\mathbb{W}(0, 1, 2, \dots)$ and shift operators defined as

1. $\mathbf{S}_r((x_0, x_1, x_2, \dots)) \triangleq (0, x_0, x_1, x_2, \dots)$ (right shift operator)
2. $\mathbf{S}_l((x_0, x_1, x_2, \dots)) \triangleq (x_1, x_2, x_3, \dots)$ (left shift operator)

EX	1. \mathbf{S}_r is an isometric operator. 2. $\mathbf{S}_r^* = \mathbf{S}_l$
----	---

⁴² Michel and Herget (1993) page 432

⁴³ Michel and Herget (1993) page 441

PROOF:

1. Proof that $\mathbf{S}_r^* = \mathbf{S}_l$:

$$\begin{aligned}
 \langle \mathbf{S}_r(x_0, x_1, x_2, \dots) | (y_0, y_1, y_2, \dots) \rangle &= \langle (0, x_0, x_1, x_2, \dots) | (y_0, y_1, y_2, \dots) \rangle \\
 &= \sum_{n=1}^{\infty} x_{n-1} y_n^* \\
 &= \sum_{n=0}^{\infty} x_n y_{n+1}^* \\
 &= \sum_{n=0}^{\infty} x_n y_{n+1}^* \\
 &= \langle (x_0, x_1, x_2, \dots) | (y_1, y_2, y_3, \dots) \rangle \\
 &= \left\langle (x_0, x_1, x_2, \dots) | \underbrace{\mathbf{S}_l}_{\mathbf{S}_r^*} (y_0, y_1, y_2, \dots) \right\rangle
 \end{aligned}$$

2. Proof that \mathbf{S}_r is isometric ($\mathbf{S}_r^* \mathbf{S}_r = \mathbf{I}$):

$$\begin{aligned}
 \mathbf{S}_r^* \mathbf{S}_r &= \mathbf{S}_l \mathbf{S}_r \\
 &= \mathbf{I}
 \end{aligned}
 \quad \text{by 1.}$$

⇒

O.4.5 Unitary operators

Definition O.11. ⁴⁴ Let $\mathcal{B}(X, Y)$ be the space of BOUNDED LINEAR OPERATORS on normed linear spaces X and Y . Let \mathbf{U} be a bounded linear operator in $\mathcal{B}(X, Y)$, and \mathbf{I} the identity operator in $\mathcal{B}(X, X)$.

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The operator \mathbf{U} is **unitary** if $\mathbf{U}^* \mathbf{U} = \mathbf{U} \mathbf{U}^* = \mathbf{I}$.

Proposition O.4. Let $\mathcal{B}(X, Y)$ be the space of BOUNDED LINEAR OPERATORS on normed linear spaces X and Y . Let \mathbf{U} and \mathbf{V} be BOUNDED LINEAR OPERATORS in $\mathcal{B}(X, Y)$.

P \mathbf{U} is UNITARY and $\left. \begin{array}{l} \mathbf{V} \text{ is UNITARY} \\ \mathbf{V} \text{ is UNITARY} \end{array} \right\} \Rightarrow (\mathbf{UV}) \text{ is UNITARY.}$

PROOF:

$$\begin{aligned}
 (\mathbf{UV})(\mathbf{UV})^* &= (\mathbf{UV})(\mathbf{V}^* \mathbf{U}^*) && \text{by Theorem O.8 page 313} \\
 &= \mathbf{U}(\mathbf{V} \mathbf{V}^*) \mathbf{U}^* && \text{by associative property} \\
 &= \mathbf{U} \mathbf{I} \mathbf{U}^* && \text{by definition of unitary operators} && \text{(Definition O.11 page 326)} \\
 &= \mathbf{I} && \text{by definition of unitary operators} && \text{(Definition O.11 page 326)}
 \end{aligned}$$

$$\begin{aligned}
 (\mathbf{UV})^*(\mathbf{UV}) &= (\mathbf{V}^* \mathbf{U}^*)(\mathbf{UV}) && \text{by Theorem O.8 page 313} \\
 &= \mathbf{V}^* (\mathbf{U}^* \mathbf{U}) \mathbf{V} && \text{by associative property} \\
 &= \mathbf{V}^* \mathbf{I} \mathbf{V} && \text{by definition of unitary operators} && \text{(Definition O.11 page 326)} \\
 &= \mathbf{I} && \text{by definition of unitary operators} && \text{(Definition O.11 page 326)}
 \end{aligned}$$

⁴⁴ Rudin (1991) page 312, Michel and Herget (1993) page 431, Autonne (1901) page 209, Autonne (1902), Schur (1909), Steen (1973)





Theorem O.25. ⁴⁵ Let $\mathcal{B}(\mathbf{H}, \mathbf{H})$ be the space of BOUNDED LINEAR OPERATORS on a HILBERT SPACE \mathbf{H} . Let $\mathcal{I}(\mathbf{U})$ be the IMAGE SET of \mathbf{U} .

If \mathbf{U} is a **bounded linear operator** ($\mathbf{U} \in \mathcal{B}(\mathbf{H}, \mathbf{H})$), then the following conditions are **equivalent**:

- | | |
|---|---|
| 1. $\mathbf{U}\mathbf{U}^* = \mathbf{U}^*\mathbf{U} = \mathbf{I}$
2. $\langle \mathbf{U}\mathbf{x} \mathbf{U}\mathbf{y} \rangle = \langle \mathbf{U}^*\mathbf{x} \mathbf{U}^*\mathbf{y} \rangle = \langle \mathbf{x} \mathbf{y} \rangle$ and $\mathcal{I}(\mathbf{U}) = X$
3. $\ \mathbf{U}\mathbf{x} - \mathbf{U}\mathbf{y}\ = \ \mathbf{U}^*\mathbf{x} - \mathbf{U}^*\mathbf{y}\ = \ \mathbf{x} - \mathbf{y}\ $ and $\mathcal{I}(\mathbf{U}) = X$
4. $\ \mathbf{U}\mathbf{x}\ = \ \mathbf{x}\ $ and $\mathcal{I}(\mathbf{U}) = X$ | (UNITARY) \iff
(SURJECTIVE) \iff
(ISOMETRIC IN DISTANCE) \iff
(ISOMETRIC IN LENGTH) \iff |
|---|---|

PROOF:

1. Proof that (1) \implies (2):

$$(a) \langle \mathbf{U}\mathbf{x} | \mathbf{U}\mathbf{y} \rangle = \langle \mathbf{U}^*\mathbf{x} | \mathbf{U}^*\mathbf{y} \rangle = \langle \mathbf{x} | \mathbf{y} \rangle \text{ by Theorem O.23 (page 324).}$$

(b) Proof that $\mathcal{I}(\mathbf{U}) = X$:

$$\begin{aligned} X &\supseteq \mathcal{I}(\mathbf{U}) && \text{because } \mathbf{U} \in X^X \\ &\supseteq \mathcal{I}(\mathbf{U}\mathbf{U}^*) \\ &= \mathcal{I}(\mathbf{I}) && \text{by left hypothesis } (\mathbf{U}^*\mathbf{U} = \mathbf{U}\mathbf{U}^* = \mathbf{I}) \\ &= X && \text{by Definition O.2 page 303 (definition of } \mathbf{I} \text{)} \end{aligned}$$

2. Proof that (2) \iff (3) \iff (4): by Theorem O.23 page 324.

3. Proof that (3) \implies (1):

(a) Proof that $\|\mathbf{U}\mathbf{x} - \mathbf{U}\mathbf{y}\| = \|\mathbf{x} - \mathbf{y}\| \implies \mathbf{U}^*\mathbf{U} = \mathbf{I}$: by Theorem O.23 page 324

(b) Proof that $\|\mathbf{U}^*\mathbf{x} - \mathbf{U}^*\mathbf{y}\| = \|\mathbf{x} - \mathbf{y}\| \implies \mathbf{U}\mathbf{U}^* = \mathbf{I}$:

$$\begin{aligned} \|\mathbf{U}^*\mathbf{x} - \mathbf{U}^*\mathbf{y}\| = \|\mathbf{x} - \mathbf{y}\| \implies \mathbf{U}^{**}\mathbf{U}^* = \mathbf{I} && \text{by Theorem O.23 page 324} \\ \mathbf{U}\mathbf{U}^* = \mathbf{I} && \text{by Theorem O.13 page 317} \end{aligned}$$



Theorem O.26. Let $\mathcal{B}(\mathbf{H}, \mathbf{H})$ be the space of BOUNDED LINEAR OPERATORS on a HILBERT SPACE \mathbf{H} . Let \mathbf{U} be a bounded linear operator in $\mathcal{B}(\mathbf{H}, \mathbf{H})$, $\mathcal{N}(\mathbf{U})$ the NULL SPACE of \mathbf{U} , and $\mathcal{I}(\mathbf{U})$ the IMAGE SET of \mathbf{U} .

T H M $\underbrace{\mathbf{U}\mathbf{U}^* = \mathbf{U}^*\mathbf{U} = \mathbf{I}}_{\mathbf{U} \text{ is unitary}}$	$\left\{ \begin{array}{lcl} \mathbf{U}^{-1} & = & \mathbf{U}^* & \text{and} \\ \mathcal{I}(\mathbf{U}) & = & \mathcal{I}(\mathbf{U}^*) & = & X & \text{and} \\ \mathcal{N}(\mathbf{U}) & = & \mathcal{N}(\mathbf{U}^*) & = & \{\mathbf{0}\} & \text{and} \\ \ \mathbf{U}\ & = & \ \mathbf{U}^*\ & = & 1 & \text{(UNIT LENGTH)} \end{array} \right\}$
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PROOF:

1. Note that \mathbf{U} , \mathbf{U}^* , and \mathbf{U}^{-1} are all both *isometric* and *normal*:

$$\begin{aligned} \mathbf{U}^*\mathbf{U} &= \mathbf{I} \implies \mathbf{U} \text{ is isometric} \\ \mathbf{U}\mathbf{U}^* &= \mathbf{U}^*\mathbf{U} = \mathbf{I} \implies \mathbf{U}^* \text{ is isometric} \\ \mathbf{U}^{-1} &= \mathbf{U}^* \implies \mathbf{U}^{-1} \text{ is isometric} \end{aligned}$$

$$\begin{aligned} \mathbf{U}^*\mathbf{U} &= \mathbf{U}\mathbf{U}^* = \mathbf{I} \implies \mathbf{U} \text{ is normal} \\ \mathbf{U}\mathbf{U}^* &= \mathbf{U}^*\mathbf{U} = \mathbf{I} \implies \mathbf{U}^* \text{ is normal} \\ \mathbf{U}^{-1} &= \mathbf{U}^* \implies \mathbf{U}^{-1} \text{ is normal} \end{aligned}$$

⁴⁵ Rudin (1991) pages 313–314 (Theorem 12.13), Knapp (2005a) page 45 (Proposition 2.6)

2. Proof that $\mathbf{U}^*\mathbf{U} = \mathbf{U}\mathbf{U}^* = \mathbf{I} \implies \mathcal{I}(\mathbf{U}) = \mathcal{I}(\mathbf{U}^*) = \mathbf{H}$: by Theorem O.25 page 327.

3. Proof that $\mathbf{U}^*\mathbf{U} = \mathbf{U}\mathbf{U}^* = \mathbf{I} \implies \mathcal{N}(\mathbf{U}) = \mathcal{N}(\mathbf{U}^*) = \mathcal{N}(\mathbf{U}^{-1})$:

$$\begin{aligned}\mathcal{N}(\mathbf{U}^*) &= \mathcal{N}(\mathbf{U}) && \text{because } \mathbf{U} \text{ and } \mathbf{U}^* \text{ are both } \textit{normal} \text{ and by Theorem O.21 page 322} \\ &= \mathcal{I}(\mathbf{U})^\perp && \text{by Theorem O.14 page 318} \\ &= X^\perp && \text{by above result} \\ &= \{\emptyset\} && \text{by Proposition I.6 page 241}\end{aligned}$$

4. Proof that $\mathbf{U}^*\mathbf{U} = \mathbf{U}\mathbf{U}^* = \mathbf{I} \implies \|\mathbf{U}^{-1}\| = \|\mathbf{U}^*\| = \|\mathbf{U}\| = 1$:

Because \mathbf{U} , \mathbf{U}^* , and \mathbf{U}^{-1} are all isometric and by Theorem O.24 page 325.



Example O.5 (Rotation matrix). ⁴⁶

E X	$\left\{ \mathbf{R}_\theta \triangleq \underbrace{\begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix}}_{\text{rotation matrix } \mathbf{R}_\theta : \mathbb{R}^2 \rightarrow \mathbb{R}^2} \right\}$	\implies	$\left\{ \begin{array}{l} (1). \quad \mathbf{R}_{-\theta}^{-1} = \mathbf{R}_{-\theta} \quad \text{and} \\ (2). \quad \mathbf{R}_\theta^* = \mathbf{R}_{-\theta}^{-1} \quad (\mathbf{R} \text{ is unitary}) \end{array} \right\}$
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PROOF:

$$\begin{aligned}\mathbf{R}^* &= \mathbf{R}^H \\ &= \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix}^H && \text{by definition of } \mathbf{R} \\ &= \begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix} && \text{by definition of } \textit{Hermitian transpose operator } H \\ &= \begin{bmatrix} \cos(-\theta) & -\sin(-\theta) \\ \sin(-\theta) & \cos(-\theta) \end{bmatrix} && \text{by Theorem ?? page ??} \\ &= \mathbf{R}_{-\theta} && \text{by definition of } \mathbf{R} \\ &= \mathbf{R}^{-1} && \text{by 1.}\end{aligned}$$



Example O.6. ⁴⁷ Let \mathbf{A} and \mathbf{B} be matrix operators.

E X	$\mathbf{A} \triangleq \begin{bmatrix} \cos\phi & -\sin\phi & 0 \\ \sin\phi & \cos\phi & 0 \\ 0 & 0 & 1 \end{bmatrix}$	$\mathbf{B} \triangleq \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$
\mathbf{A} is a <i>rotation operator</i> . \mathbf{B} is a <i>reflection operator</i> .		
\mathbf{A} and \mathbf{B} are unitary .		

Example O.7. Examples of *Fredholm integral operators* include

E X	1. Fourier Transform $[\tilde{\mathbf{F}}\mathbf{x}](f) = \int_{t \in \mathbb{R}} x(t)e^{-i2\pi ft} dt$ $\kappa(t, f) = e^{-i2\pi ft}$ 2. Inverse Fourier Transform $[\tilde{\mathbf{F}}^{-1}\tilde{\mathbf{x}}](t) = \int_{f \in \mathbb{R}} \tilde{\mathbf{x}}(f)e^{i2\pi ft} df$ $\kappa(f, t) = e^{i2\pi ft}$ 3. Laplace operator $[\mathbf{L}\mathbf{x}](s) = \int_{t \in \mathbb{R}} x(t)e^{-st} dt$ $\kappa(t, s) = e^{-st}$
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Example O.8 (Translation operator). Let $\mathbf{T} = L_{\mathbb{R}}^2$ and $\mathbf{T} \in \mathbf{X}^{\mathbf{X}}$ be defined as

$$\mathbf{T}\mathbf{f}(x) \triangleq \mathbf{f}(x - 1) \quad \forall \mathbf{f} \in L_{\mathbb{R}}^2 \quad (\text{translation operator})$$

⁴⁶ Noble and Daniel (1988) page 311

⁴⁷ Gel'fand (1963), page 4, Gelfand et al. (2018) page 4

E	1. $\mathbf{T}^{-1}\mathbf{f}(x) = \mathbf{f}(x+1)$ $\forall \mathbf{f} \in L^2_{\mathbb{R}}$	(inverse translation operator)
X	2. $\mathbf{T}^* = \mathbf{T}^{-1}$	(\mathbf{T} is invertible)
X	3. $\mathbf{T}^*\mathbf{T} = \mathbf{T}\mathbf{T}^* = \mathbf{I}$	(\mathbf{T} is unitary)

PROOF:

1. Proof that $\mathbf{T}^{-1}\mathbf{f}(x) = \mathbf{f}(x+1)$:

$$\begin{aligned}\mathbf{T}^{-1}\mathbf{T} &= \mathbf{I} \\ \mathbf{T}\mathbf{T}^{-1} &= \mathbf{I}\end{aligned}$$

2. Proof that \mathbf{T} is unitary:

$$\begin{aligned}\langle \mathbf{T}\mathbf{f}(x) | \mathbf{g}(x) \rangle &= \langle \mathbf{f}(x-1) | \mathbf{g}(x) \rangle && \text{by definition of } \mathbf{T} \\ &= \int_x \mathbf{f}(x-1)\mathbf{g}^*(x) dx \\ &= \int_x \mathbf{f}(x)\mathbf{g}^*(x+1) dx \\ &= \langle \mathbf{f}(x) | \mathbf{g}(x+1) \rangle \\ &= \left\langle \mathbf{f}(x) | \underbrace{\mathbf{T}^{-1}\mathbf{g}(x)}_{\mathbf{T}^*} \right\rangle && \text{by 1.}\end{aligned}$$



Example O.9 (Dilation operator). Let $\mathbf{X} = L^2_{\mathbb{R}}$ and $\mathbf{T} \in \mathbf{X}^{\mathbf{X}}$ be defined as

$$\mathbf{D}\mathbf{f}(x) \triangleq \sqrt{2}\mathbf{f}(2x) \quad \forall \mathbf{f} \in L^2_{\mathbb{R}} \quad (\text{dilation operator})$$

E	1. $\mathbf{D}^{-1}\mathbf{f}(x) = \frac{1}{\sqrt{2}}\mathbf{f}\left(\frac{1}{2}x\right)$ $\forall \mathbf{f} \in L^2_{\mathbb{R}}$	(inverse dilation operator)
X	2. $\mathbf{D}^* = \mathbf{D}^{-1}$	(\mathbf{D} is invertible)
X	3. $\mathbf{D}^*\mathbf{D} = \mathbf{D}\mathbf{D}^* = \mathbf{I}$	(\mathbf{D} is unitary)

PROOF:

1. Proof that $\mathbf{D}^{-1}\mathbf{f}(x) = \frac{1}{\sqrt{2}}\mathbf{f}\left(\frac{1}{2}x\right)$:

$$\begin{aligned}\mathbf{D}^{-1}\mathbf{D} &= \mathbf{I} \\ \mathbf{D}\mathbf{D}^{-1} &= \mathbf{I}\end{aligned}$$

2. Proof that \mathbf{D} is unitary:

$$\begin{aligned}\langle \mathbf{D}\mathbf{f}(x) | \mathbf{g}(x) \rangle &= \left\langle \sqrt{2}\mathbf{f}(2x) | \mathbf{g}(x) \right\rangle && \text{by definition of } \mathbf{D} \\ &= \int_x \sqrt{2}\mathbf{f}(2x)\mathbf{g}^*(x) dx \\ &= \int_{u \in \mathbb{R}} \sqrt{2}\mathbf{f}(u)\mathbf{g}^*\left(\frac{1}{2}u\right) \frac{1}{2} du && \text{let } u \triangleq 2x \implies dx = \frac{1}{2} du \\ &= \int_{u \in \mathbb{R}} \mathbf{f}(u) \left[\frac{1}{\sqrt{2}}\mathbf{g}\left(\frac{1}{2}u\right) \right]^* du \\ &= \left\langle \mathbf{f}(x) | \underbrace{\frac{1}{\sqrt{2}}\mathbf{g}\left(\frac{1}{2}x\right)}_{\mathbf{D}^*} \right\rangle \\ &= \left\langle \mathbf{f}(x) | \underbrace{\mathbf{D}^{-1}\mathbf{g}(x)}_{\mathbf{D}^*} \right\rangle && \text{by 1.}\end{aligned}$$



Example O.10 (Delay operator). Let \mathbf{X} be the set of all sequences and $\mathbf{D} \in \mathbf{X}^{\mathbf{X}}$ be a delay operator.

E X The delay operator $\mathbf{D}((x_n)_{n \in \mathbb{Z}}) \triangleq ((x_{n-1})_{n \in \mathbb{Z}})$ is unitary.

PROOF: The inverse \mathbf{D}^{-1} of the delay operator \mathbf{D} is

$$\mathbf{D}^{-1}((x_n)_{n \in \mathbb{Z}}) \triangleq ((x_{n+1})_{n \in \mathbb{Z}}).$$

$$\begin{aligned} \langle \mathbf{D}((x_n)) | (y_n) \rangle &= \langle ((x_{n-1})) | (y_n) \rangle && \text{by definition of } \mathbf{D} \\ &= \sum_n x_{n-1} y_n^* \\ &= \sum_n x_n y_{n+1}^* \\ &= \langle ((x_n)) | ((y_{n+1})) \rangle \\ &= \left\langle ((x_n)) | \underbrace{\mathbf{D}^{-1}((y_n))}_{\mathbf{D}^*} \right\rangle \end{aligned}$$

Therefore, $\mathbf{D}^* = \mathbf{D}^{-1}$. This implies that $\mathbf{D}\mathbf{D}^* = \mathbf{D}^*\mathbf{D} = \mathbf{I}$ which implies that \mathbf{D} is unitary. ⇒

Example O.11 (Fourier transform). Let $\tilde{\mathbf{F}}$ be the *Fourier Transform* and $\tilde{\mathbf{F}}^{-1}$ the *inverse Fourier Transform* operator

$$[\tilde{\mathbf{F}}\mathbf{x}](f) \triangleq \int_t \mathbf{x}(t) e^{-i2\pi f t} dt \quad [\tilde{\mathbf{F}}^{-1}\tilde{\mathbf{x}}](t) \triangleq \int_f \tilde{\mathbf{x}}(f) e^{i2\pi f t} df.$$

E X $\tilde{\mathbf{F}}^* = \tilde{\mathbf{F}}^{-1}$ (the Fourier Transform operator $\tilde{\mathbf{F}}$ is unitary)

PROOF:

$$\begin{aligned} \langle \tilde{\mathbf{F}}\mathbf{x} | \tilde{\mathbf{y}} \rangle &= \left\langle \int_t \mathbf{x}(t) e^{-i2\pi f t} dt | \tilde{\mathbf{y}}(f) \right\rangle \\ &= \int_t \mathbf{x}(t) \left\langle e^{-i2\pi f t} | \tilde{\mathbf{y}}(f) \right\rangle dt \\ &= \int_t \mathbf{x}(t) \int_f e^{-i2\pi f t} \tilde{\mathbf{y}}^*(f) df dt \\ &= \int_t \mathbf{x}(t) \left[\int_f e^{i2\pi f t} \tilde{\mathbf{y}}(f) df \right]^* dt \\ &= \left\langle \mathbf{x}(t) | \int_f \tilde{\mathbf{y}}(f) e^{i2\pi f t} df \right\rangle \\ &= \left\langle \mathbf{x} | \underbrace{\tilde{\mathbf{F}}^{-1}\tilde{\mathbf{y}}}_{\tilde{\mathbf{F}}^*} \right\rangle \end{aligned}$$

This implies that $\tilde{\mathbf{F}}$ is unitary ($\tilde{\mathbf{F}}^* = \tilde{\mathbf{F}}^{-1}$). ⇒



O.5 Operator order

Definition O.12. ⁴⁸ Let $P \in Y^X$ be an operator.

D E F P is **positive** if $\langle Px | x \rangle \geq 0 \forall x \in X$.
This condition is denoted $P \geq 0$.

Theorem O.27. ⁴⁹

T H M $\underbrace{P \geq 0 \text{ and } Q \geq 0}_{P \text{ and } Q \text{ are both positive}}$	\implies	$\begin{cases} (P + Q) \geq 0 & (\text{$(P + Q)$ is positive}) \\ A^*PA \geq 0 & (\text{A^*PA is positive}) \\ A^*A \geq 0 & (\text{A^*A is positive}) \end{cases}$
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PROOF:

$$\begin{aligned}
 \langle (P + Q)x | x \rangle &= \langle Px | x \rangle + \langle Qx | x \rangle && \text{by additive property of } \langle \triangle | \nabla \rangle \text{ (Definition K.1 page 255)} \\
 &\geq \langle Px | x \rangle && \text{by left hypothesis} \\
 &\geq 0 && \text{by left hypothesis} \\
 \langle A^*PAx | x \rangle &= \langle PAx | Ax \rangle && \text{by definition of adjoint (Proposition O.3 page 316)} \\
 &= \langle Py | y \rangle && \text{where } y \triangleq Ax \\
 &\geq 0 && \text{by left hypothesis} \\
 \langle Ix | x \rangle &= \langle x | x \rangle && \text{by definition of } I \text{ (Definition O.2 page 303)} \\
 &\geq 0 && \text{by non-negative property of } \langle \triangle | \nabla \rangle \text{ (Definition K.1 page 255)} \\
 &\implies I \text{ is positive} && \\
 \langle A^*Ax | x \rangle &= \langle A^*IAx | x \rangle && \text{by definition of } I \text{ (Definition O.2 page 303)} \\
 &\geq 0 && \text{by two previous results}
 \end{aligned}$$



Definition O.13. ⁵⁰ Let $A, B \in \mathcal{B}(X, Y)$ be BOUNDED operators.

D E F $A \geq B$ ("A is greater than or equal to B") if
 $A - B \geq 0$ ("($A - B$) is positive")

⁴⁸ Michel and Herget (1993) page 429 (Definition 7.4.12)

⁴⁹ Michel and Herget (1993) page 429

⁵⁰ Michel and Herget (1993) page 429

APPENDIX P

FOURIER TRANSFORM



“The analytical equations ... extend to all general phenomena. There cannot be a language more universal and more simple, more free from errors and from obscurities, ... mathematical analysis is as extensive as nature itself; ... it preserves every principle which it has once acquired; it grows and strengthens itself incessantly in the midst of the many variations and errors of the human mind. Its chief attribute is clearness; it has no marks to express confused notions. It brings together phenomena the most diverse, and discovers the hidden analogies which unite them.”

Joseph Fourier (1768–1830)¹

P.1 Definitions

This chapter deals with the *Fourier Transform* in the space of *Lebesgue square-integrable functions* $L^2_{(\mathbb{R}, \mathcal{B}, \mu)}$, where \mathbb{R} is the set of real numbers, \mathcal{B} is the set of *Borel sets* on \mathbb{R} , μ is the standard *Borel measure* on \mathbb{R} , and

$$L^2_{(\mathbb{R}, \mathcal{B}, \mu)} \triangleq \left\{ f \in \mathbb{R}^{\mathbb{R}} \mid \int_{\mathbb{R}} |f|^2 d\mu < \infty \right\}.$$

Furthermore, $\langle \Delta | \nabla \rangle$ is the *inner product* induced by the operator $\int_{\mathbb{R}} d\mu$ such that

$$\langle f | g \rangle \triangleq \int_{\mathbb{R}} f(x)g^*(x) dx,$$

and $(L^2_{(\mathbb{R}, \mathcal{B}, \mu)}, \langle \Delta | \nabla \rangle)$ is a *Hilbert space*.

Definition P.1. Let κ be a FUNCTION in $\mathbb{C}^{\mathbb{R}^2}$.

D E F The function κ is the **Fourier kernel** if $\kappa(x, \omega) \triangleq e^{i\omega x} \quad \forall x, \omega \in \mathbb{R}$

Definition P.2. ² Let $L^2_{(\mathbb{R}, \mathcal{B}, \mu)}$ be the space of all LEBESGUE SQUARE-INTEGRABLE FUNCTIONS.

¹ quote: [Fourier \(1878\)](#), pages 7–8 (Preliminary Discourse)

image: <http://en.wikipedia.org/wiki/File:Fourier2.jpg>, public domain

² [Bachman et al. \(2000\)](#) page 363, [Chorin and Hald \(2009\)](#) page 13, [Loomis and Bolker \(1965\)](#), page 144, [Knapp \(2005b\)](#) pages 374–375, [Fourier \(1822\)](#), [Fourier \(1878\)](#) page 336?

D E F The Fourier Transform operator \tilde{F} is defined as

$$[\tilde{F}f](\omega) \triangleq \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x) e^{-i\omega x} dx \quad \forall f \in L^2_{(\mathbb{R}, \mathcal{B}, \mu)}$$

This definition of the Fourier Transform is also called the **unitary Fourier Transform**.

Remark P.1 (Fourier transform scaling factor). ³ If the Fourier transform operator \tilde{F} and inverse Fourier transform operator \tilde{F}^{-1} are defined as

$$\tilde{F}f(x) \triangleq F(\omega) \triangleq A \int_{\mathbb{R}} f(x) e^{-i\omega x} dx \quad \text{and} \quad \tilde{F}^{-1}\tilde{f}(\omega) \triangleq B \int_{\mathbb{R}} F(\omega) e^{i\omega x} d\omega$$

then A and B can be any constants as long as $AB = \frac{1}{2\pi}$. The Fourier transform is often defined with the scaling factor A set equal to 1 such that $[\tilde{F}f(x)](\omega) \triangleq \int_{\mathbb{R}} f(x) e^{-i\omega x} dx$. In this case, the inverse Fourier transform operator \tilde{F}^{-1} is either defined as

- $[\tilde{F}^{-1}f(x)](f) \triangleq \int_{\mathbb{R}} f(x) e^{i2\pi f x} dx$ (using oscillatory frequency free variable f) or
- $[\tilde{F}^{-1}f(x)](\omega) \triangleq \frac{1}{2\pi} \int_{\mathbb{R}} f(x) e^{i\omega x} dx$ (using angular frequency free variable ω).

In short, the 2π has to show up somewhere, either in the argument of the exponential ($e^{-i2\pi f t}$) or in front of the integral ($\frac{1}{2\pi} \int \dots$). One could argue that it is unnecessary to burden the exponential argument with the 2π factor ($e^{-i2\pi f t}$), and thus could further argue in favor of using the angular frequency variable ω thus giving the inverse operator definition $[\tilde{F}^{-1}f(x)](\omega) \triangleq \frac{1}{2\pi} \int_{\mathbb{R}} f(x) e^{-i\omega x} dx$. But this causes a new problem. In this case, the Fourier operator \tilde{F} is not *unitary* (see Theorem P.2 page 334)—in particular, $\tilde{F}\tilde{F}^* \neq I$, where \tilde{F}^* is the *adjoint* of \tilde{F} ; but rather, $\tilde{F} \left(\frac{1}{2\pi} \tilde{F}^* \right) = \left(\frac{1}{2\pi} \tilde{F}^* \right) \tilde{F} = I$. But if we define the operators \tilde{F} and \tilde{F}^{-1} to both have the scaling factor $\frac{1}{\sqrt{2\pi}}$, then \tilde{F} and \tilde{F}^{-1} are inverses and \tilde{F} is *unitary*—that is, $\tilde{F}\tilde{F}^* = \tilde{F}^*\tilde{F} = I$.

P.2 Operator properties

Theorem P.1 (Inverse Fourier transform). ⁴ Let \tilde{F} be the Fourier Transform operator (Definition P.2 page 333). The inverse \tilde{F}^{-1} of \tilde{F} is

T H M $[\tilde{F}^{-1}\tilde{f}](x) = \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} \tilde{f}(\omega) e^{i\omega x} d\omega \quad \forall \tilde{f} \in L^2_{(\mathbb{R}, \mathcal{B}, \mu)}$

Theorem P.2. Let \tilde{F} be the Fourier Transform operator with inverse \tilde{F}^{-1} and adjoint \tilde{F}^* .

T H M $\tilde{F}^* = \tilde{F}^{-1}$

PROOF:

$$\begin{aligned} \langle \tilde{F}f | g \rangle &= \left\langle \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x) e^{-i\omega x} dx | g(\omega) \right\rangle && \text{by definition of } \tilde{F} \text{ page 333} \\ &= \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x) \langle e^{-i\omega x} | g(\omega) \rangle dx && \text{by additive property of } \langle \cdot | \cdot \rangle \text{ page 255} \\ &= \int_{\mathbb{R}} f(x) \frac{1}{\sqrt{2\pi}} \langle g(\omega) | e^{-i\omega x} \rangle^* dx && \text{by conjugate symmetric property of } \langle \cdot | \cdot \rangle \text{ page 255} \end{aligned}$$

³ Chorin and Hald (2009) page 13, Jeffrey and Dai (2008) pages xxxi–xxxii, Knapp (2005b) pages 374–375

⁴ Chorin and Hald (2009) page 13

$$\begin{aligned}
 &= \left\langle f(x) \mid \frac{1}{\sqrt{2\pi}} \langle g(\omega) \mid e^{-i\omega x} \rangle \right\rangle && \text{by definition of } \langle \triangle \mid \nabla \rangle \\
 &= \left\langle f \mid \underbrace{\tilde{F}^{-1}g}_{\tilde{F}^*} \right\rangle && \text{by Theorem P.1 page 334}
 \end{aligned}$$



The Fourier Transform operator has several nice properties:

- ▣ \tilde{F} is *unitary*⁵ (Corollary P.1—next corollary).
- ▣ Because \tilde{F} is unitary, it automatically has several other nice properties (Theorem P.3 page 335).

Corollary P.1. Let \mathbf{I} be the identity operator and let \tilde{F} be the Fourier Transform operator with adjoint \tilde{F}^* and inverse \tilde{F}^{-1} .

C O R	$\tilde{F}\tilde{F}^* = \tilde{F}^*\tilde{F} = \mathbf{I}$ (\tilde{F} is unitary)
	$\tilde{F}^* = \tilde{F}^{-1}$



PROOF: This follows directly from the fact that $\tilde{F}^* = \tilde{F}^{-1}$ (Theorem P.2 page 334). ⇒

Theorem P.3. Let \tilde{F} be the Fourier transform operator with adjoint \tilde{F}^* and inverse \tilde{F} . Let $\|\cdot\|$ be the operator norm with respect to the vector norm $\|\cdot\|$ with respect to the Hilbert space $(\mathbb{C}^{\mathbb{R}}, \langle \triangle \mid \nabla \rangle)$. Let $\mathcal{R}(A)$ be the range of an operator A .

T H M	$ \begin{aligned} \mathcal{R}(F\tau) &= \mathcal{R}(\tilde{F}^{-1}) &= L^2_{\mathbb{R}} \\ \ \tilde{F}\ &= \ \tilde{F}^{-1}\ &= 1 & \text{(UNITARY)} \\ \langle \tilde{F}f \mid \tilde{F}g \rangle &= \langle \tilde{F}^{-1}f \mid \tilde{F}^{-1}g \rangle &= \langle f \mid g \rangle & \text{(PARSEVAL'S EQUATION)} \\ \ \tilde{F}f\ &= \ \tilde{F}^{-1}f\ &= \ f\ & \text{(PLANCHEREL'S FORMULA)} \\ \ \tilde{F}f - \tilde{F}g\ &= \ \tilde{F}^{-1}f - \tilde{F}^{-1}g\ &= \ f - g\ & \text{(ISOMETRIC)} \end{aligned} $
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PROOF: These results follow directly from the fact that \tilde{F} is unitary (Corollary P.1 page 335) and from the properties of unitary operators (Theorem O.26 page 327). ⇒

Theorem P.4 (Shift relations). Let \tilde{F} be the Fourier transform operator.

T H M	$ \begin{aligned} \tilde{F}[f(x-u)](\omega) &= e^{-i\omega u} [\tilde{F}f](\omega) \\ [\tilde{F}(e^{ivx}g(x))](\omega) &= [\tilde{F}g](\omega - v) \end{aligned} $
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PROOF:

$$\begin{aligned}
 \tilde{F}[f(x-u)](\omega) &= \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x-u)e^{-i\omega x} dx && \text{by definition of } \tilde{F} && (\text{Definition P.2 page 333}) \\
 &= \frac{1}{\sqrt{2\pi}} \int_{v \in \mathbb{R}} f(v)e^{-i\omega(u+v)} dv && \text{where } v \triangleq x - u \implies t = u + v \\
 &= e^{-i\omega u} \frac{1}{\sqrt{2\pi}} \int_{v \in \mathbb{R}} f(v)e^{-i\omega v} dv \\
 &= e^{-i\omega u} \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x)e^{-i\omega x} dx && \text{by change of variable } t = v \\
 &= e^{-i\omega u} [\tilde{F}f](\omega) && \text{by definition of } \tilde{F} && (\text{Definition P.2 page 333}) \\
 [\tilde{F}(e^{ivx}g(x))](\omega) &= \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} e^{ivx}g(x)e^{-i\omega x} dx && \text{by definition of } \tilde{F} && (\text{Definition P.2 page 333})
 \end{aligned}$$

⁵ unitary operators: Definition O.11 page 326

$$\begin{aligned}
 &= \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} g(x) e^{-i(\omega-v)x} dx \\
 &= [\tilde{\mathbf{F}}g(x)](\omega - v) \quad \text{by definition of } \tilde{\mathbf{F}} \quad (\text{Definition P.2 page 333})
 \end{aligned}$$

⇒

Theorem P.5 (Complex conjugate). *Let $\tilde{\mathbf{F}}$ be the Fourier Transform operator and $*$ represent the complex conjugate operation on the set of complex numbers.*

T H M	$\tilde{\mathbf{F}}f^*(-x) = -[\tilde{\mathbf{F}}f(x)]^* \quad \forall f \in L^2_{(\mathbb{R}, \mathcal{B}, \mu)}$ $f \text{ is real} \implies \tilde{f}(-\omega) = [\tilde{f}(\omega)]^* \quad \forall \omega \in \mathbb{R}$ REALITY CONDITION
-------------	--

PROOF:

$$\begin{aligned}
 [\tilde{\mathbf{F}}f^*(-x)](\omega) &\triangleq \frac{1}{\sqrt{2\pi}} \int f^*(-x) e^{-i\omega x} dx \quad \text{by definition of } \tilde{\mathbf{F}} \quad (\text{Definition P.2 page 333}) \\
 &= \frac{1}{\sqrt{2\pi}} \int f^*(u) e^{i\omega u} (-1) du \quad \text{where } u \triangleq -x \implies dx = -du \\
 &= - \left[\frac{1}{\sqrt{2\pi}} \int f(u) e^{-i\omega u} du \right]^* \\
 &\triangleq -[\tilde{\mathbf{F}}f(x)]^* \quad \text{by definition of } \tilde{\mathbf{F}} \quad (\text{Definition P.2 page 333}) \\
 \tilde{f}(-\omega) &\triangleq \frac{1}{\sqrt{2\pi}} \int f(x) e^{-i(-\omega)x} dx \quad \text{by definition of } \tilde{\mathbf{F}} \quad (\text{Definition P.2 page 333}) \\
 &= \left[\frac{1}{\sqrt{2\pi}} \int f^*(x) e^{-i\omega x} dx \right]^* \\
 &= \left[\frac{1}{\sqrt{2\pi}} \int f(x) e^{-i\omega x} dx \right]^* \quad \text{by } f \text{ is real hypothesis} \\
 &\triangleq \tilde{f}^*(\omega) \quad \text{by definition of } \tilde{\mathbf{F}} \quad (\text{Definition P.2 page 333})
 \end{aligned}$$

⇒

P.3 Convolution

Definition P.3. ⁶

D E F *The convolution operation is defined as*

D E F	$[f \star g](x) \triangleq f(x) \star g(x) \triangleq \int_{u \in \mathbb{R}} f(u)g(x-u) du \quad \forall f, g \in L^2_{(\mathbb{R}, \mathcal{B}, \mu)}$
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Theorem R.2 (next) demonstrates that multiplication in the “time domain” is equivalent to convolution in the “frequency domain” and vice-versa.

Theorem P.6 (convolution theorem). ⁷ *Let $\tilde{\mathbf{F}}$ be the Fourier Transform operator and \star the convolution operator.*

⁶ Bachman (1964), page 6, Bracewell (1978) page 108 (Convolution theorem)

⁷ Bracewell (1978) page 110

T H M

$\underbrace{\tilde{F}[f(x) \star g(x)](\omega)}_{\text{convolution in "time domain"}}$	$=$	$\underbrace{\sqrt{2\pi} [\tilde{F}f](\omega) [\tilde{F}g](\omega)}_{\text{multiplication in "frequency domain"}}$ $\forall f, g \in L^2_{(\mathbb{R}, \mathcal{B}, \mu)}$
$\underbrace{F[f(x)g(x)](\omega)}_{\text{multiplication in "time domain"}}$	$=$	$\frac{1}{\sqrt{2\pi}} [\tilde{F}f](\omega) \star [\tilde{F}g](\omega)$ $\underbrace{\quad\quad\quad}_{\text{convolution in "frequency domain"}}$ $\forall f, g \in L^2_{(\mathbb{R}, \mathcal{B}, \mu)}.$

PROOF:

$$\begin{aligned}
 \tilde{F}[f(x) \star g(x)](\omega) &= \tilde{F}\left[\int_{u \in \mathbb{R}} f(u)g(x-u) du\right](\omega) && \text{by definition of } \star \text{ (Definition P.3 page 336)} \\
 &= \int_{u \in \mathbb{R}} f(u)[\tilde{F}g(x-u)](\omega) du \\
 &= \int_{u \in \mathbb{R}} f(u)e^{-i\omega u} [\tilde{F}g(x)](\omega) du && \text{by Theorem P.4 page 335} \\
 &= \sqrt{2\pi} \left(\underbrace{\frac{1}{\sqrt{2\pi}} \int_{u \in \mathbb{R}} f(u)e^{-i\omega u} du}_{[\tilde{F}f](\omega)} \right) [\tilde{F}g](\omega) \\
 &= \sqrt{2\pi} [\tilde{F}f](\omega) [\tilde{F}g](\omega) && \text{by definition of } \tilde{F} \text{ (Definition P.2 page 333)} \\
 \tilde{F}[f(x)g(x)](\omega) &= \tilde{F}[(\tilde{F}^{-1}\tilde{F}f(x))g(x)](\omega) && \text{by definition of operator inverse (page 303)} \\
 &= \tilde{F}\left[\left(\frac{1}{\sqrt{2\pi}} \int_{v \in \mathbb{R}} [\tilde{F}f(x)](v)e^{ivx} dv\right) g(x)\right](\omega) && \text{by Theorem P.1 page 334} \\
 &= \frac{1}{\sqrt{2\pi}} \int_{v \in \mathbb{R}} [\tilde{F}f(x)](v) [\tilde{F}(e^{ivx} g(x))](\omega, v) dv \\
 &= \frac{1}{\sqrt{2\pi}} \int_{v \in \mathbb{R}} [\tilde{F}f(x)](v) [\tilde{F}g(x)](\omega - v) dv && \text{by Theorem P.4 page 335} \\
 &= \frac{1}{\sqrt{2\pi}} [\tilde{F}f](\omega) \star [\tilde{F}g](\omega) && \text{by definition of } \star \text{ (Definition P.3 page 336)}
 \end{aligned}$$



P.4 Real valued functions

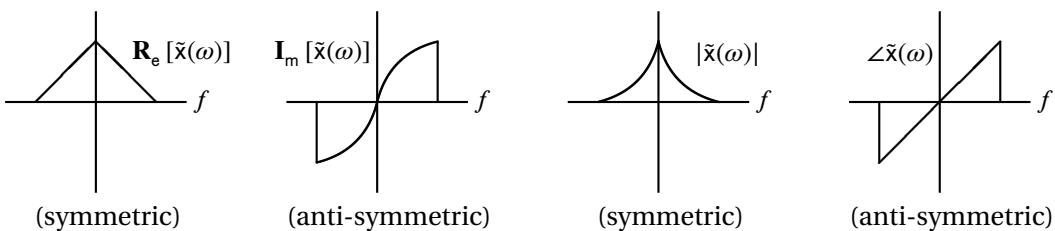


Figure P.1: Fourier transform components of real-valued signal

Theorem P.7. Let $f(x)$ be a function in $L^2_{\mathbb{R}}$ and $\tilde{f}(\omega)$ the FOURIER TRANSFORM of $f(x)$.

T H M

$\left\{ \begin{array}{l} f(x) \text{ is REAL-VALUED} \\ (f \in \mathbb{R}^{\mathbb{R}}) \end{array} \right\}$	\Rightarrow	$\left\{ \begin{array}{lcl} \tilde{f}(\omega) & = & \tilde{f}^*(-\omega) & (\text{HERMITIAN SYMMETRIC}) \\ \mathbf{R}_e[\tilde{f}(\omega)] & = & \mathbf{R}_e[\tilde{f}(-\omega)] & (\text{SYMMETRIC}) \\ \mathbf{I}_m[\tilde{f}(\omega)] & = & -\mathbf{I}_m[\tilde{f}(-\omega)] & (\text{ANTI-SYMMETRIC}) \\ \tilde{f}(\omega) & = & \tilde{f}(-\omega) & (\text{SYMMETRIC}) \\ \angle \tilde{f}(\omega) & = & \angle \tilde{f}(-\omega) & (\text{ANTI-SYMMETRIC}). \end{array} \right\}$
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PROOF:

$$\begin{aligned}
 \tilde{f}(\omega) &\triangleq [\tilde{\mathbf{F}}f(x)](\omega) \triangleq \langle f(x) | e^{i\omega x} \rangle = \langle f(x) | e^{i(-\omega)x} \rangle^* \triangleq \tilde{f}^*(-\omega) \\
 \mathbf{R}_e[\tilde{f}(\omega)] &= \mathbf{R}_e[\tilde{f}^*(-\omega)] = \mathbf{R}_e[\tilde{f}(-\omega)] \\
 \mathbf{I}_m[\tilde{f}(\omega)] &= \mathbf{I}_m[\tilde{f}^*(-\omega)] = -\mathbf{I}_m[\tilde{f}(-\omega)] \\
 |\tilde{f}(\omega)| &= |\tilde{f}^*(-\omega)| = |\tilde{f}(-\omega)| \\
 \angle\tilde{f}(\omega) &= \angle\tilde{f}^*(-\omega) = -\angle\tilde{f}(-\omega)
 \end{aligned}$$

⇒

P.5 Moment properties

Definition P.4.⁸

DEF

The quantity M_n is the ***n*th moment** of a function $f(x) \in L^2_{\mathbb{R}}$ if

$$M_n \triangleq \int_{\mathbb{R}} x^n f(x) dx \quad \text{for } n \in \mathbb{W}.$$

Lemma P.1.⁹ Let M_n be the ***n*th moment** (Definition P.4 page 338) and $\tilde{f}(\omega) \triangleq [\tilde{\mathbf{F}}f](\omega)$ the Fourier transform (Definition P.2 page 333) of a function $f(x)$ in $L^2_{\mathbb{R}}$ (Definition ?? page ??).

LEM

$$M_n = \sqrt{2\pi}(i)^n \left[\frac{d}{d\omega} \right]^n \tilde{f}(\omega) \Big|_{\omega=0} \quad \forall n \in \mathbb{W}, f \in L^2_{\mathbb{R}}$$

$$\left[\frac{d}{d\omega} \right]^n \tilde{f}(\omega) \Big|_{\omega=0} = \frac{1}{\sqrt{2\pi}} (-i)^n M_n \quad \forall n \in \mathbb{W}, f \in L^2_{\mathbb{R}}$$

PROOF:

$$\begin{aligned}
 \sqrt{2\pi}(i)^n \left[\left[\frac{d}{d\omega} \right]^n \tilde{f}(\omega) \right]_{\omega=0} &= \sqrt{2\pi}(i)^n \left[\left[\frac{d}{d\omega} \right]^n \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x) e^{-i\omega x} dx \right]_{\omega=0} \quad \text{by definition of } \tilde{\mathbf{F}} \text{ (Definition P.2 page 333)} \\
 &= (i)^n \int_{\mathbb{R}} f(x) \left[\left[\frac{d}{d\omega} \right]^n e^{-i\omega x} \right] dx \Big|_{\omega=0} \\
 &= (i)^n \int_{\mathbb{R}} f(x) [(-i)^n x^n e^{-i\omega x}] dx \Big|_{\omega=0} \\
 &= (-i^2)^n \int_{\mathbb{R}} f(x) x^n dx \\
 &= \int_{\mathbb{R}} f(x) x^n dx \\
 &\triangleq M_n \quad \text{by definition of } M_n \text{ (Definition P.4 page 338)}
 \end{aligned}$$

⇒

Lemma P.2.¹⁰ Let M_n be the ***n*th moment** (Definition P.4 page 338) and $\tilde{f}(\omega) \triangleq [\tilde{\mathbf{F}}f](\omega)$ the Fourier transform (Definition P.2 page 333) of a function $f(x)$ in $L^2_{\mathbb{R}}$ (Definition ?? page ??).

LEM

$$M_n = 0 \iff \left[\frac{d}{d\omega} \right]^n \tilde{f}(\omega) \Big|_{\omega=0} = 0 \quad \forall n \in \mathbb{W}$$

PROOF:

⁸ Jawerth and Sweldens (1994), pages 16–17, Sweldens and Piessens (1993), page 2, Vidakovic (1999), page 83

⁹ Goswami and Chan (1999), pages 38–39

¹⁰ Vidakovic (1999), pages 82–83, Mallat (1999), pages 241–242

1. Proof for (\implies) case:

$$\begin{aligned} 0 &= \langle f(x) | x^n \rangle && \text{by left hypothesis} \\ &= \sqrt{2\pi}(-i)^{-n} \left[\frac{d}{d\omega} \right]^n \tilde{f}(\omega) \Big|_{\omega=0} && \text{by Lemma P.1 page 338} \\ &\implies \left[\frac{d}{d\omega} \right]^n \tilde{f}(\omega) \Big|_{\omega=0} = 0 \end{aligned}$$

2. Proof for (\Leftarrow) case:

$$\begin{aligned} 0 &= \left[\frac{d}{d\omega} \right]^n \tilde{f}(\omega) \Big|_{\omega=0} && \text{by right hypothesis} \\ &= \left[\frac{d}{d\omega} \right]^n \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x) e^{-i\omega x} dx \Big|_{\omega=0} && \text{by definition of } \tilde{f}(\omega) \\ &= \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x) \left[\frac{d}{d\omega} \right]^n e^{-i\omega x} dx \Big|_{\omega=0} \\ &= \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x) [(-i)^n x^n e^{-i\omega x}] dx \Big|_{\omega=0} \\ &= (-i)^n \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x) x^n dx \\ &= (-i)^n \frac{1}{\sqrt{2\pi}} \langle f(x) | x^n \rangle && \text{by definition of } \langle \cdot | \cdot \rangle \text{ in } L^2_{\mathbb{R}} \text{ (Definition ?? page ??)} \end{aligned}$$



Lemma P.3 (Strang-Fix condition). ¹¹ Let $f(x)$ be a function in $L^2_{\mathbb{R}}$ and M_n the n TH MOMENT (Definition P.4 page 338) off $f(x)$. Let T be the TRANSLATION OPERATOR (Definition ?? page ??).

L E M	$\sum_{k \in \mathbb{Z}} \underbrace{T^k x^n f(x)}_{\text{STRANG-FIX CONDITION in "time"}} = M_n \iff \underbrace{\left[\frac{d}{d\omega} \right]^n \tilde{f}(\omega) \Big _{\omega=2\pi k} = \frac{1}{\sqrt{2\pi}} (-i)^n \bar{\delta}_k M_n}_{\text{STRANG-FIX CONDITION in "frequency"}}$
----------------------------------	---

PROOF:

1. Proof for (\implies) case:

$$\begin{aligned} \left[\left[\frac{d}{d\omega} \right]^n \tilde{f}(\omega) \right]_{\omega=2\pi k} &= \sum_{k \in \mathbb{Z}} \left[\left[\frac{d}{d\omega} \right]^n \tilde{f}(\omega) \right]_{\omega=2\pi k} e^{i2\pi kx} \bar{\delta}_k \\ &= \frac{1}{\sqrt{2\pi}} \sum_{k \in \mathbb{Z}} \left[\left[\frac{d}{d\omega} \right]^n \int_{\mathbb{R}} f(x) e^{-i\omega x} dx \right]_{\omega=2\pi k} e^{i2\pi kx} \bar{\delta}_k && \text{by Definition P.2 page 333} \\ &= \frac{1}{\sqrt{2\pi}} \sum_{k \in \mathbb{Z}} \left[\int_{\mathbb{R}} f(x) (-ix)^n e^{-i\omega x} dx \right]_{\omega=2\pi k} e^{i2\pi kx} \bar{\delta}_k \\ &= (-i)^n \frac{1}{\sqrt{2\pi}} \sum_{k \in \mathbb{Z}} \left[\int_{\mathbb{R}} x^n f(x) e^{-i\omega x} dx \right]_{\omega=2\pi k} e^{i2\pi kx} \bar{\delta}_k \\ &= (-i)^n \frac{1}{\sqrt{2\pi}} \sum_{k \in \mathbb{Z}} (x - k)^n f(x - k) \bar{\delta}_k && \text{by PSF (Theorem ?? page ??)} \\ &= \frac{1}{\sqrt{2\pi}} (-i)^n \bar{\delta}_k M_n && \text{by left hypothesis} \end{aligned}$$

¹¹ Jawerth and Sweldens (1994), pages 16–17, Sweldens and Piessens (1993), page 2, Vidakovic (1999), page 83, Mallat (1999), pages 241–243, Fix and Strang (1969)

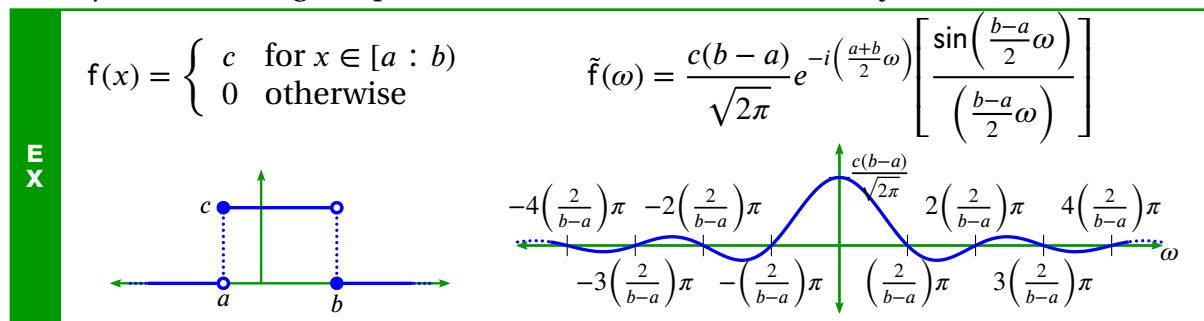
2. Proof for (\Leftarrow) case:

$$\begin{aligned}
 \frac{1}{\sqrt{2\pi}}(-i)^n \mathbf{M}_n &= \frac{1}{\sqrt{2\pi}} \sum_{k \in \mathbb{Z}} [(-i)^n \bar{\delta}_k \mathbf{M}_n] e^{-i2\pi kx} && \text{by definition of } \bar{\delta} \quad (\text{Definition K.3 page 267}) \\
 &= \sum_{k \in \mathbb{Z}} \left[\left[\frac{d}{d\omega} \right]^n \tilde{f}(\omega) \right] \Big|_{\omega=2\pi k} e^{-i2\pi kx} && \text{by right hypothesis} \\
 &= \sum_{k \in \mathbb{Z}} \left[\left[\frac{d}{d\omega} \right]^n \int_{\mathbb{R}} f(x) e^{-i\omega x} dx \right] \Big|_{\omega=2\pi k} e^{-i2\pi kx} \\
 &= \sum_{k \in \mathbb{Z}} \left[\int_{\mathbb{R}} f(x) (-ix)^n e^{-i\omega x} dx \right] \Big|_{\omega=2\pi k} e^{-i2\pi kx} \\
 &= (-i)^n \sum_{k \in \mathbb{Z}} \left[\int_{\mathbb{R}} x^n f(x) e^{-i\omega x} dx \right] \Big|_{\omega=2\pi k} e^{-i2\pi kx} \\
 &= (-i)^n \sum_{k \in \mathbb{Z}} (x - k)^n f(x - k) && \text{by PSF} \quad (\text{Theorem ?? page ??})
 \end{aligned}$$

⇒

P.6 Examples

Example P.1 (rectangular pulse). Let $\tilde{f}(\omega)$ be the Fourier transform of a function $f(x) \in L^2_{\mathbb{R}}$.



PROOF:

$$\begin{aligned}
 \tilde{f}(\omega) &= \tilde{F}[f(x)](\omega) && \text{by definition of } \tilde{f}(\omega) \\
 &= e^{-i\left(\frac{a+b}{2}\right)\omega} \tilde{F}\left[f\left(x - \frac{a+b}{2}\right)\right](\omega) && \text{by shift relation} \quad (\text{Theorem P.4 page 335}) \\
 &= e^{-i\left(\frac{a+b}{2}\right)\omega} \tilde{F}\left[c \mathbb{1}_{[a:b]} \left(x - \frac{a+b}{2}\right)\right](\omega) && \text{by definition of } f(x) \\
 &= e^{-i\left(\frac{a+b}{2}\right)\omega} \tilde{F}\left[c \mathbb{1}_{\left[-\frac{b-a}{2} : \frac{b-a}{2}\right]}(x)\right](\omega) && \text{by definition of } \mathbb{1} \quad (\text{Definition ?? page ??}) \\
 &= \frac{1}{\sqrt{2\pi}} e^{-i\left(\frac{a+b}{2}\right)\omega} \int_{\mathbb{R}} c \mathbb{1}_{\left[-\frac{b-a}{2} : \frac{b-a}{2}\right]}(x) e^{-i\omega x} dx && \text{by definition of } \tilde{F} \quad (\text{Definition P.2 page 333}) \\
 &= \frac{1}{\sqrt{2\pi}} e^{-i\left(\frac{a+b}{2}\right)\omega} \int_{-\frac{b-a}{2}}^{\frac{b-a}{2}} c e^{-i\omega x} dx && \text{by definition of } \mathbb{1} \quad (\text{Definition ?? page ??}) \\
 &= \frac{c}{\sqrt{2\pi}} e^{-i\left(\frac{a+b}{2}\right)\omega} \frac{1}{-i\omega} e^{-i\omega x} \Big|_{-\frac{b-a}{2}}^{\frac{b-a}{2}} \\
 &= \frac{2c}{\sqrt{2\pi}\omega} e^{-i\left(\frac{a+b}{2}\right)\omega} \left[\frac{e^{i\left(\frac{b-a}{2}\omega\right)} - e^{-i\left(\frac{b-a}{2}\omega\right)}}{2i} \right]
 \end{aligned}$$

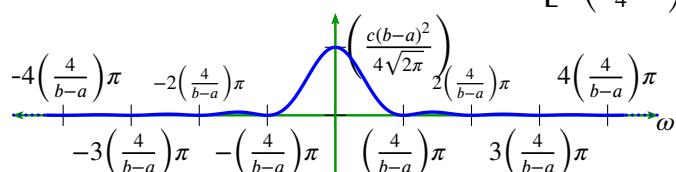
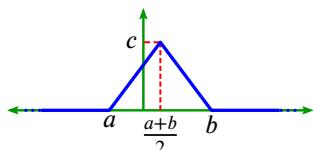
$$= \frac{c(b-a)}{\sqrt{2\pi}} e^{-i(\frac{a+b}{2}\omega)} \left[\frac{\sin\left(\frac{b-a}{2}\omega\right)}{\left(\frac{b-a}{2}\omega\right)} \right]$$

by Euler formulas

(Corollary ?? page ??)

Example P.2 (triangle). Let $\tilde{f}(\omega)$ be the Fourier transform of a function $f(x) \in L^2_{\mathbb{R}}$.

$f(x) = \begin{cases} c \left[1 - \frac{ 2x-b-a }{b-a} \right] & \text{for } x \in [a : b) \\ 0 & \text{otherwise} \end{cases}$	$\tilde{f}(\omega) = \frac{c(b-a)^2}{4\sqrt{2\pi}} e^{-i(\frac{a+b}{2}\omega)} \left[\frac{\sin\left(\frac{b-a}{4}\omega\right)}{\left(\frac{b-a}{4}\omega\right)} \right]^2$
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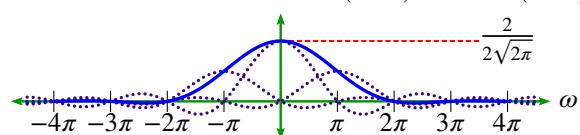
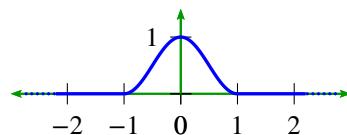
**E
X**

PROOF:

$$\begin{aligned}
 \tilde{f}(\omega) &= \tilde{F}[f(x)](\omega) && \text{by definition of } \tilde{f}(\omega) \\
 &= e^{-i(\frac{a+b}{2})\omega} \tilde{F}\left[f\left(x - \frac{a+b}{2}\right)\right](\omega) && \text{by shift relation} \quad (\text{Theorem P.4 page 335}) \\
 &= \tilde{F}\left[c\left(1 - \frac{|2x-b-a|}{b-a}\right) \mathbb{1}_{[a:b)}(x)\right](\omega) && \text{by definition of } f(x) \\
 &= c \tilde{F}\left[\mathbb{1}_{[\frac{a}{2}:\frac{b}{2}]}(x) \star \mathbb{1}_{[\frac{a}{2}:\frac{b}{2}]}(x)\right](\omega) \\
 &= c \sqrt{2\pi} \tilde{F}\left[\mathbb{1}_{[\frac{a}{2}:\frac{b}{2}]}\right] \tilde{F}\left[\mathbb{1}_{[\frac{a}{2}:\frac{b}{2}]}\right] && \text{by convolution theorem} \quad (\text{Theorem R.2 page 356}) \\
 &= c \sqrt{2\pi} \left(\tilde{F}\left[\mathbb{1}_{[\frac{a}{2}:\frac{b}{2}]}\right] \right)^2 \\
 &= c \sqrt{2\pi} \left(\frac{\left(\frac{b}{2} - \frac{a}{2}\right)}{\sqrt{2\pi}} e^{-i(\frac{a+b}{4}\omega)} \left[\frac{\sin\left(\frac{b-a}{4}\omega\right)}{\left(\frac{b-a}{4}\omega\right)} \right] \right)^2 && \text{by Rectangular pulse ex.} \quad \text{Example P.1 page 340} \\
 &= \frac{c(b-a)^2}{4\sqrt{2\pi}} e^{-i(\frac{a+b}{2}\omega)} \left[\frac{\sin\left(\frac{b-a}{4}\omega\right)}{\left(\frac{b-a}{4}\omega\right)} \right]^2
 \end{aligned}$$

Example P.3. Let a function f be defined in terms of the cosine function (Definition ?? page ??) as follows:

$f(x) \triangleq \begin{cases} \cos^2\left(\frac{\pi}{2}x\right) & \text{for } x \leq 1 \\ 0 & \text{otherwise} \end{cases}$	$\tilde{f}(\omega) = \frac{1}{2\sqrt{2\pi}} \left[\underbrace{\frac{2\sin\omega}{\omega}}_{2\operatorname{sinc}(\omega)} + \underbrace{\frac{\sin(\omega+\pi)}{(\omega+\pi)}}_{\operatorname{sinc}(\omega+\pi)} + \underbrace{\frac{\sin(\omega-\pi)}{(\omega-\pi)}}_{\operatorname{sinc}(\omega-\pi)} \right]$
--	--

**E
X**

PROOF: Let $\mathbb{1}_A(x)$ be the *set indicator function* (Definition ?? page ??) on a set A .

$$\begin{aligned}
 \tilde{f}(\omega) &\triangleq \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x)e^{-i\omega x} dx && \text{by definition of } \tilde{f}(\omega) \text{ (Definition P.2)} \\
 &= \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} \cos^2\left(\frac{\pi}{2}x\right) \mathbb{1}_{[-1:1]}(x) e^{-i\omega x} dx && \text{by definition of } f(x) \\
 &= \frac{1}{\sqrt{2\pi}} \int_{-1}^1 \cos^2\left(\frac{\pi}{2}x\right) e^{-i\omega x} dx && \text{by definition of } \mathbb{1} \text{ (Definition ??)} \\
 &= \frac{1}{\sqrt{2\pi}} \int_{-1}^1 \left[\frac{e^{i\frac{\pi}{2}x} + e^{-i\frac{\pi}{2}x}}{2} \right]^2 e^{-i\omega x} dx && \text{by Corollary ?? page ??} \\
 &= \frac{1}{4\sqrt{2\pi}} \int_{-1}^1 [2 + e^{i\pi x} + e^{-i\pi x}] e^{-i\omega x} dx \\
 &= \frac{1}{4\sqrt{2\pi}} \int_{-1}^1 2e^{-i\omega x} + e^{-i(\omega+\pi)x} + e^{-i(\omega-\pi)x} dx \\
 &= \frac{1}{4\sqrt{2\pi}} \left[2 \frac{e^{-i\omega x}}{-i\omega} + \frac{e^{-i(\omega+\pi)x}}{-i(\omega+\pi)} + \frac{e^{-i(\omega-\pi)x}}{-i(\omega-\pi)} \right]_{-1}^1 \\
 &= \frac{1}{2\sqrt{2\pi}} \left[2 \frac{e^{-i\omega} - e^{+i\omega}}{-2i\omega} + \frac{e^{-i(\omega+\pi)} - e^{+i(\omega+\pi)}}{-2i(\omega+\pi)} + \frac{e^{-i(\omega-\pi)} - e^{+i(\omega-\pi)}}{-2i(\omega-\pi)} \right]_{-1}^1 \\
 &= \frac{1}{2\sqrt{2\pi}} \left[\underbrace{\frac{2\sin\omega}{\omega}}_{2\operatorname{sinc}(\omega)} + \underbrace{\frac{\sin(\omega+\pi)}{(\omega+\pi)}}_{\operatorname{sinc}(\omega+\pi)} + \underbrace{\frac{\sin(\omega-\pi)}{(\omega-\pi)}}_{\operatorname{sinc}(\omega-\pi)} \right]
 \end{aligned}$$

⇒

APPENDIX Q

DISCRETE TIME FOURIER TRANSFORM

Q.1 Definition

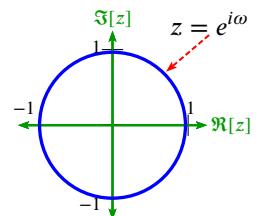
Definition Q.1.

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The **discrete-time Fourier transform** \check{F} of $(x_n)_{n \in \mathbb{Z}}$ is defined as

$$[\check{F}(x_n)](\omega) \triangleq \sum_{n \in \mathbb{Z}} x_n e^{-i\omega n} \quad \forall (x_n)_{n \in \mathbb{Z}} \in \ell^2_{\mathbb{R}}$$

If we compare the definition of the *Discrete Time Fourier Transform* (Definition Q.1 page 343) to the definition of the Z-transform (Definition R.4 page 354), we see that the DTFT is just a special case of the more general Z-Transform, with $z = e^{i\omega}$. If we imagine $z \in \mathbb{C}$ as a complex plane, then $e^{i\omega}$ is a unit circle in this plane. The “frequency” ω in the DTFT is the unit circle in the much larger z-plane, as illustrated to the right.



Q.2 Properties

Proposition Q.1 (DTFT periodicity). Let $\check{x}(\omega) \triangleq \check{F}[(x_n)](\omega)$ be the DISCRETE-TIME FOURIER TRANSFORM (Definition Q.1 page 343) of a sequence $(x_n)_{n \in \mathbb{Z}}$ in $\ell^2_{\mathbb{R}}$.

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$$\underbrace{\check{x}(\omega)}_{\text{PERIODIC with period } 2\pi} = \check{x}(\omega + 2\pi n) \quad \forall n \in \mathbb{Z}$$

PROOF:

$$\begin{aligned} \check{x}(\omega + 2\pi n) &= \sum_{m \in \mathbb{Z}} x_m e^{-i(\omega+2\pi n)m} \\ &= \sum_{m \in \mathbb{Z}} x_m e^{-i\omega m} e^{-i2\pi nm} \\ &= \check{x}(\omega) \end{aligned}$$

Theorem Q.1. Let $\tilde{x}(\omega) \triangleq \check{F}[(x[n])](\omega)$ be the DISCRETE-TIME FOURIER TRANSFORM (Definition Q.1 page 343) of a sequence $(x_n)_{n \in \mathbb{Z}}$ in $\ell^2_{\mathbb{R}}$.

T H M	$\left\{ \begin{array}{l} \tilde{x}(\omega) \triangleq \check{F}(x[n]) \\ \end{array} \right\}$	\implies	$\left\{ \begin{array}{l} (1). \quad \check{F}(x[-n]) = \tilde{x}(-\omega) \quad \text{and} \\ (2). \quad \check{F}(x^*[n]) = \tilde{x}^*(-\omega) \quad \text{and} \\ (3). \quad \check{F}(x^*[-n]) = \tilde{x}^*(\omega) \end{array} \right\}$
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PROOF:

$$\begin{aligned} \check{F}(x[-n]) &\triangleq \sum_{n \in \mathbb{Z}} x[-n]e^{-i\omega n} && \text{by definition of DTFT} && (\text{Definition Q.1 page 343}) \\ &= \sum_{m \in \mathbb{Z}} x[m]e^{i\omega m} && \text{where } m \triangleq -n \implies n = -m \\ &= \sum_{m \in \mathbb{Z}} x[m]e^{-i(-\omega)m} \\ &\triangleq \tilde{x}(-\omega) && \text{by left hypothesis} \end{aligned}$$

$$\begin{aligned} \check{F}(x^*[n]) &\triangleq \sum_{n \in \mathbb{Z}} x^*[n]e^{-i\omega n} && \text{by definition of DTFT} && (\text{Definition Q.1 page 343}) \\ &= \left(\sum_{n \in \mathbb{Z}} x[n]e^{i\omega n} \right)^* && \text{by distributive property of } *-\text{algebras} && (\text{Definition J.3 page 250}) \\ &= \left(\sum_{n \in \mathbb{Z}} x[n]e^{-i(-\omega)n} \right)^* \\ &\triangleq \tilde{x}^*(-\omega) && \text{by left hypothesis} \end{aligned}$$

$$\begin{aligned} \check{F}(x^*[-n]) &\triangleq \sum_{n \in \mathbb{Z}} x^*[-n]e^{-i\omega n} && \text{by definition of DTFT} && (\text{Definition Q.1 page 343}) \\ &= \left(\sum_{n \in \mathbb{Z}} x[-n]e^{i\omega n} \right)^* && \text{by distributive property of } *-\text{algebras} && (\text{Definition J.3 page 250}) \\ &= \left(\sum_{m \in \mathbb{Z}} x[m]e^{-i\omega m} \right)^* && \text{where } m \triangleq -n \implies n = -m \\ &\triangleq \tilde{x}^*(\omega) && \text{by left hypothesis} \end{aligned}$$

⇒

Theorem Q.2. Let $\tilde{x}(\omega) \triangleq \check{F}[(x[n])](\omega)$ be the DISCRETE-TIME FOURIER TRANSFORM (Definition Q.1 page 343) of a sequence $(x[n])_{n \in \mathbb{Z}}$ in $\ell^2_{\mathbb{R}}$.

T H M	$\left\{ \begin{array}{l} (1). \quad \tilde{x}(\omega) \triangleq \check{F}(x[n]) \\ (2). \quad (x[n]) \text{ is REAL-VALUED} \end{array} \right\}$	\implies	$\left\{ \begin{array}{l} (1). \quad \check{F}(x[-n]) = \tilde{x}(-\omega) \quad \text{and} \\ (2). \quad \check{F}(x^*[n]) = \tilde{x}^*(-\omega) = \tilde{x}(\omega) \quad \text{and} \\ (3). \quad \check{F}(x^*[-n]) = \tilde{x}^*(\omega) = \tilde{x}(-\omega) \end{array} \right\}$
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PROOF:

$$\begin{aligned} \check{F}(x[-n]) &\triangleq \sum_{n \in \mathbb{Z}} x[-n]e^{-i\omega n} && \text{by definition of DTFT} && (\text{Definition Q.1 page 343}) \\ &= \sum_{m \in \mathbb{Z}} x[m]e^{i\omega m} && \text{where } m \triangleq -n \implies n = -m \\ &= \sum_{m \in \mathbb{Z}} x[m]e^{-i(-\omega)m} \end{aligned}$$

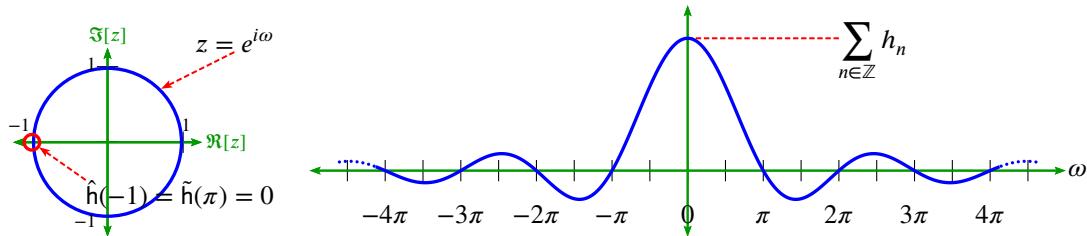


$$\triangleq \check{x}(-\omega) \quad \text{by left hypothesis}$$

$$\begin{aligned} \check{x}^*(-\omega) &= \check{\mathbf{F}}(\mathbf{x}^*[n]) && \text{by Theorem Q.1 page 344} \\ &= \check{\mathbf{F}}(\mathbf{x}[n]) && \text{by real-valued hypothesis} \\ &= [\check{x}(\omega)] && \text{by definition of } \check{x}(\omega) \quad (\text{Definition Q.1 page 343}) \end{aligned}$$

$$\begin{aligned} \check{x}^*(\omega) &= \check{\mathbf{F}}(\mathbf{x}^*[-n]) && \text{by Theorem Q.1 page 344} \\ &= \check{\mathbf{F}}(\mathbf{x}[-n]) && \text{by real-valued hypothesis} \\ &= [\check{x}(-\omega)] && \text{by result (1)} \end{aligned}$$

⇒



Proposition Q.2. Let $\check{x}(z)$ be the Z-TRANSFORM (Definition R.4 page 354) and $\check{x}(\omega)$ the DISCRETE-TIME FOURIER TRANSFORM (Definition Q.1 page 343) of (x_n) .

P R P	$\underbrace{\left\{ \sum_{n \in \mathbb{Z}} x_n = c \right\}}_{(1) \text{ time domain}} \iff \underbrace{\left\{ \check{x}(z) \Big _{z=1} = c \right\}}_{(2) z \text{ domain}} \iff \underbrace{\left\{ \check{x}(\omega) \Big _{\omega=0} = c \right\}}_{(3) \text{ frequency domain}} \quad \forall (x_n)_{n \in \mathbb{Z}} \in \ell^2_{\mathbb{R}}, c \in \mathbb{R}$
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PROOF:

1. Proof that (1) \implies (2):

$$\begin{aligned} \check{x}(z) \Big|_{z=1} &= \sum_{n \in \mathbb{Z}} x_n z^{-n} \Big|_{z=1} && \text{by definition of } \check{x}(z) \text{ (Definition R.4 page 354)} \\ &= \sum_{n \in \mathbb{Z}} x_n && \text{because } z^n = 1 \text{ for all } n \in \mathbb{Z} \\ &= c && \text{by hypothesis (1)} \end{aligned}$$

2. Proof that (2) \implies (3):

$$\begin{aligned} \check{x}(\omega) \Big|_{\omega=0} &= \sum_{n \in \mathbb{Z}} x_n e^{-i\omega n} \Big|_{\omega=0} && \text{by definition of } \check{x}(\omega) \quad (\text{Definition Q.1 page 343}) \\ &= \sum_{n \in \mathbb{Z}} x_n z^{-n} \Big|_{z=1} \\ &= \check{x}(z) \Big|_{z=1} && \text{by definition of } \check{x}(z) \quad (\text{Definition R.4 page 354}) \\ &= c && \text{by hypothesis (2)} \end{aligned}$$

3. Proof that (3) \implies (1):

$$\begin{aligned} \sum_{n \in \mathbb{Z}} x_n &= \sum_{n \in \mathbb{Z}} x_n e^{-i\omega n} \Big|_{\omega=0} \\ &= \check{x}(\omega) && \text{by definition of } \check{x}(\omega) && (\text{Definition Q.1 page 343}) \\ &= c && \text{by hypothesis (3)} \end{aligned}$$



Proposition Q.3. *If the coefficients are real, then the magnitude response (MR) is symmetric.*

PROOF:

$$\begin{aligned} |\tilde{h}(-\omega)| &\triangleq |\check{h}(z)|_{z=e^{-i\omega}} \\ &= \left| \sum_{m \in \mathbb{Z}} x[m] e^{i\omega m} \right| \\ &= \left| \underbrace{\left(\sum_{m \in \mathbb{Z}} x[m] e^{-i\omega m} \right)^*}_{\text{if } x[m] \text{ is real}} \right| \\ &\triangleq |\check{h}(z)|_{z=e^{-i\omega}} && \triangleq |\tilde{h}(\omega)| \end{aligned}$$

$$\begin{aligned} &\triangleq \left| \sum_{m \in \mathbb{Z}} x[m] z^{-m} \right|_{z=e^{-i\omega}} \\ &= \left| \left(\sum_{m \in \mathbb{Z}} x^*[m] e^{-i\omega m} \right)^* \right| \\ &= \left| \sum_{m \in \mathbb{Z}} x[m] e^{-i\omega m} \right| \end{aligned}$$



Proposition Q.4.¹

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$$\begin{aligned} \underbrace{\sum_{n \in \mathbb{Z}} (-1)^n x_n = c}_{(1) \text{ in "time"}} &\iff \underbrace{\check{x}(z)|_{z=-1} = c}_{(2) \text{ in "z domain"}} \iff \underbrace{\check{x}(\omega)|_{\omega=\pi} = c}_{(3) \text{ in "frequency"}} \\ &\iff \underbrace{\left(\sum_{n \in \mathbb{Z}} h_{2n}, \sum_{n \in \mathbb{Z}} h_{2n+1} \right)}_{(4) \text{ sum of even, sum of odd}} = \left(\frac{1}{2} \left(\sum_{n \in \mathbb{Z}} h_n + c \right), \frac{1}{2} \left(\sum_{n \in \mathbb{Z}} h_n - c \right) \right) \\ &\forall c \in \mathbb{R}, (x_n)_{n \in \mathbb{Z}}, (y_n)_{n \in \mathbb{Z}} \in \ell^2_{\mathbb{R}} \end{aligned}$$

PROOF:

1. Proof that (1) \implies (2):

$$\begin{aligned} \check{x}(z)|_{z=-1} &= \sum_{n \in \mathbb{Z}} x_n z^{-n} \Big|_{z=-1} \\ &= \sum_{n \in \mathbb{Z}} (-1)^n x_n \\ &= c && \text{by (1)} \end{aligned}$$

¹ Chui (1992) page 123



2. Proof that (2) \implies (3):

$$\begin{aligned} \sum_{n \in \mathbb{Z}} x_n e^{-i\omega n} \Big|_{\omega=\pi} &= \sum_{n \in \mathbb{Z}} (-1)^n x_n \\ &= \sum_{n \in \mathbb{Z}} (-1)^{-n} x_n && = \sum_{n \in \mathbb{Z}} z^{-n} x_n \Big|_{z=-1} \\ &= c && \text{by (2)} \end{aligned}$$

3. Proof that (3) \implies (1):

$$\begin{aligned} \sum_{n \in \mathbb{Z}} (-1)^n x_n &= \sum_{n \in \mathbb{Z}} (-1)^{-n} x_n \\ &= \sum_{n \in \mathbb{Z}} e^{-i\omega n} x_n \Big|_{\omega=\pi} \\ &= c && \text{by (3)} \end{aligned}$$

4. Proof that (2) \implies (4):

$$(a) \text{ Define } A \triangleq \sum_{n \in \mathbb{Z}} h_{2n} \quad B \triangleq \sum_{n \in \mathbb{Z}} h_{2n+1}.$$

(b) Proof that $A - B = c$:

$$\begin{aligned} c &= \sum_{n \in \mathbb{Z}} (-1)^n x_n && \text{by (2)} \\ &= \underbrace{\sum_{n \in \mathbb{Z}_e} (-1)^n x_n}_{\text{even terms}} + \underbrace{\sum_{n \in \mathbb{Z}_o} (-1)^n x_n}_{\text{odd terms}} \\ &= \sum_{n \in \mathbb{Z}} (-1)^{2n} x_{2n} + \sum_{n \in \mathbb{Z}} (-1)^{2n+1} x_{2n+1} \\ &= \underbrace{\sum_{n \in \mathbb{Z}} x_{2n}}_A - \underbrace{\sum_{n \in \mathbb{Z}} x_{2n+1}}_B \\ &\triangleq A - B && \text{by definitions of } A \text{ and } B \end{aligned}$$

(c) Proof that $A + B = \sum_{n \in \mathbb{Z}} x_n$:

$$\begin{aligned} \sum_{n \in \mathbb{Z}} x_n &= \sum_{n \text{ even}} x_n + \sum_{n \text{ odd}} x_n \\ &= \underbrace{\sum_{n \in \mathbb{Z}} x_{2n}}_A + \underbrace{\sum_{n \in \mathbb{Z}} x_{2n+1}}_B \\ &= A + B && \text{by definitions of } A \text{ and } B \end{aligned}$$

(d) This gives two simultaneous equations:

$$A - B = c$$

$$A + B = \sum_{n \in \mathbb{Z}} x_n$$

(e) Solutions to these equations give

$$\begin{aligned}\sum_{n \in \mathbb{Z}} x_{2n} &\triangleq A \\ \sum_{n \in \mathbb{Z}} x_{2n+1} &\triangleq B\end{aligned}\begin{aligned}&= \frac{1}{2} \left(\sum_{n \in \mathbb{Z}} x_n + c \right) \\ &= \frac{1}{2} \left(\sum_{n \in \mathbb{Z}} x_n - c \right)\end{aligned}$$

5. Proof that (2) \Leftarrow (4):

$$\begin{aligned}\sum_{n \in \mathbb{Z}} (-1)^n x_n &= \underbrace{\sum_{n \in \mathbb{Z}_e} (-1)^n x_n}_{\text{even terms}} + \underbrace{\sum_{n \in \mathbb{Z}_o} (-1)^n x_n}_{\text{odd terms}} \\ &= \sum_{n \in \mathbb{Z}} (-1)^{2n} x_{2n} + \sum_{n \in \mathbb{Z}} (-1)^{2n+1} x_{2n+1} \\ &= \sum_{n \in \mathbb{Z}} x_{2n} - \sum_{n \in \mathbb{Z}} x_{2n+1} \\ &= \frac{1}{2} \left(\sum_{n \in \mathbb{Z}} x_n + c \right) - \frac{1}{2} \left(\sum_{n \in \mathbb{Z}} x_n - c \right) \quad \text{by (3)} \\ &= c\end{aligned}$$

\Rightarrow

Lemma Q.1. Let $\tilde{f}(\omega)$ be the DTFT (Definition Q.1 page 343) of a sequence $(x_n)_{n \in \mathbb{Z}}$.

L E M	$\underbrace{(x_n \in \mathbb{R})_{n \in \mathbb{Z}}}_{\text{REAL-VALUED sequence}}$	\Rightarrow	$\underbrace{ \check{x}(\omega) ^2 = \check{x}(-\omega) ^2}_{\text{EVEN}}$	$\forall (x_n)_{n \in \mathbb{Z}} \in \ell^2_{\mathbb{R}}$
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PROOF:

$$\begin{aligned}|\check{x}(\omega)|^2 &= |\check{x}(z)|^2 \Big|_{z=e^{i\omega}} \\ &= \check{x}(z)\check{x}^*(z) \Big|_{z=e^{i\omega}} \\ &= \left[\sum_{n \in \mathbb{Z}} x_n z^{-n} \right] \left[\sum_{m \in \mathbb{Z}} x_m z^{-m} \right]^* \Big|_{z=e^{i\omega}} \\ &= \left[\sum_{n \in \mathbb{Z}} x_n z^{-n} \right] \left[\sum_{m \in \mathbb{Z}} x_m^* (z^*)^{-m} \right] \Big|_{z=e^{i\omega}} \\ &= \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} x_n x_m^* z^{-n} (z^*)^{-m} \Big|_{z=e^{i\omega}} \\ &= \sum_{n \in \mathbb{Z}} \left[|x_n|^2 + \sum_{m>n} x_n x_m^* z^{-n} (z^*)^{-m} + \sum_{m<n} x_n x_m^* z^{-n} (z^*)^{-m} \right] \Big|_{z=e^{i\omega}} \\ &= \sum_{n \in \mathbb{Z}} \left[|x_n|^2 + \sum_{m>n} x_n x_m e^{i\omega(m-n)} + \sum_{m<n} x_n x_m e^{i\omega(m-n)} \right] \\ &= \sum_{n \in \mathbb{Z}} \left[|x_n|^2 + \sum_{m>n} x_n x_m e^{i\omega(m-n)} + \sum_{m>n} x_n x_m e^{-i\omega(m-n)} \right] \\ &= \sum_{n \in \mathbb{Z}} \left[|x_n|^2 + \sum_{m>n} x_n x_m (e^{i\omega(m-n)} + e^{-i\omega(m-n)}) \right]\end{aligned}$$



$$\begin{aligned}
 &= \sum_{n \in \mathbb{Z}} \left[|x_n|^2 + \sum_{m>n} x_n x_m 2\cos[\omega(m-n)] \right] \\
 &= \sum_{n \in \mathbb{Z}} |x_n|^2 + 2 \sum_{n \in \mathbb{Z}} \sum_{m>n} x_n x_m \cos[\omega(m-n)]
 \end{aligned}$$

Since \cos is real and even, then $|\check{x}(\omega)|^2$ must also be real and even. \Rightarrow

Theorem Q.3 (inverse DTFT). ² Let $\check{x}(\omega)$ be the DISCRETE-TIME FOURIER TRANSFORM (Definition Q.1 page 343) of a sequence $(x_n)_{n \in \mathbb{Z}} \in \ell^2_{\mathbb{R}}$. Let \check{x}^{-1} be the inverse of \check{x} .

T H M	$\underbrace{\left\{ \check{x}(\omega) \triangleq \sum_{n \in \mathbb{Z}} x_n e^{-i\omega n} \right\}}_{\check{x}(\omega) \triangleq \check{F}(x_n)} \quad \Rightarrow \quad \underbrace{\left\{ x_n = \frac{1}{2\pi} \int_{-\pi}^{\pi} \check{x}(\omega) e^{i\omega n} d\omega \quad \forall \omega \in \mathbb{R} \right\}}_{(x_n) = \check{F}^{-1}(\check{x}(\omega))} \quad \forall (x_n)_{n \in \mathbb{Z}} \in \ell^2_{\mathbb{R}}$
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\Leftarrow PROOF:

$$\begin{aligned}
 \frac{1}{2\pi} \int_{-\pi}^{\pi} \check{x}(\omega) e^{i\omega n} d\omega &= \frac{1}{2\pi} \int_{-\pi}^{\pi} \underbrace{\left[\sum_{m \in \mathbb{Z}} x_m e^{-i\omega m} \right]}_{\check{x}(\omega)} e^{i\omega n} d\omega && \text{by definition of } \check{x}(\omega) \\
 &= \frac{1}{2\pi} \int_{-\pi}^{\pi} \sum_{m \in \mathbb{Z}} x_m e^{-i\omega(m-n)} d\omega \\
 &= \frac{1}{2\pi} \sum_{m \in \mathbb{Z}} x_m \int_{-\pi}^{\pi} e^{-i\omega(m-n)} d\omega \\
 &= \frac{1}{2\pi} \sum_{m \in \mathbb{Z}} x_m [2\pi \delta_{m-n}] \\
 &= x_n
 \end{aligned}$$

Theorem Q.4 (orthonormal quadrature conditions). ³ Let $\check{x}(\omega)$ be the DISCRETE-TIME FOURIER TRANSFORM (Definition Q.1 page 343) of a sequence $(x_n)_{n \in \mathbb{Z}} \in \ell^2_{\mathbb{R}}$. Let $\bar{\delta}_n$ be the KRONECKER DELTA FUNCTION at n (Definition K.3 page 267).

T H M	$ \begin{aligned} \sum_{m \in \mathbb{Z}} x_m y_{m-2n}^* &= 0 \iff \check{x}(\omega) \check{y}^*(\omega) + \check{x}(\omega + \pi) \check{y}^*(\omega + \pi) = 0 && \forall n \in \mathbb{Z}, \forall (x_n), (y_n) \in \ell^2_{\mathbb{R}} \\ \sum_{m \in \mathbb{Z}} x_m x_{m-2n}^* &= \bar{\delta}_n \iff \check{x}(\omega) ^2 + \check{x}(\omega + \pi) ^2 = 2 && \forall n \in \mathbb{Z}, \forall (x_n), (y_n) \in \ell^2_{\mathbb{R}} \end{aligned} $
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\Leftarrow PROOF: Let $z \triangleq e^{i\omega}$.

²  J.S.Chitode (2009a) page 3-95 ⟨(3.6.2)⟩

³  Daubechies (1992) pages 132–137 ⟨(5.1.20),(5.1.39)⟩

1. Proof that $2 \sum_{n \in \mathbb{Z}} \left[\sum_{k \in \mathbb{Z}} x_k y_{k-2n}^* \right] e^{-i2\omega n} = \check{x}(\omega) \check{y}^*(\omega) + \check{x}(\omega + \pi) \check{y}^*(\omega + \pi)$:

$$\begin{aligned}
 & 2 \sum_{n \in \mathbb{Z}} \left[\sum_{k \in \mathbb{Z}} x_k y_{k-2n}^* \right] e^{-i2\omega n} \\
 &= 2 \sum_{k \in \mathbb{Z}} x_k \sum_{n \in \mathbb{Z}} y_{k-2n}^* z^{-2n} \\
 &= 2 \sum_{k \in \mathbb{Z}} x_k \sum_{n \text{ even}} y_{k-n}^* z^{-n} \\
 &= \sum_{k \in \mathbb{Z}} x_k \sum_{n \in \mathbb{Z}} y_{k-n}^* z^{-n} (1 + e^{i\pi n}) \\
 &= \sum_{k \in \mathbb{Z}} x_k \sum_{n \in \mathbb{Z}} y_{k-n}^* z^{-n} + \sum_{k \in \mathbb{Z}} x_k \sum_{n \in \mathbb{Z}} y_{k-n}^* z^{-n} e^{i\pi n} \\
 &= \sum_{k \in \mathbb{Z}} x_k \sum_{m \in \mathbb{Z}} y_m^* z^{-(k-m)} + \sum_{k \in \mathbb{Z}} x_k \sum_{m \in \mathbb{Z}} y_m^* e^{-i(\omega+\pi)(k-m)} \quad \text{where } m \triangleq k - n \\
 &= \sum_{k \in \mathbb{Z}} x_k z^{-k} \sum_{m \in \mathbb{Z}} y_m^* z^m + \sum_{k \in \mathbb{Z}} x_k e^{-i(\omega+\pi)k} \sum_{m \in \mathbb{Z}} y_m^* e^{+i(\omega+\pi)m} \\
 &= \sum_{k \in \mathbb{Z}} x_k e^{-i\omega k} \left[\sum_{m \in \mathbb{Z}} y_m^* e^{-i\omega m} \right]^* + \sum_{k \in \mathbb{Z}} x_k e^{-i(\omega+\pi)k} \left[\sum_{m \in \mathbb{Z}} y_m^* e^{-i(\omega+\pi)m} \right]^* \\
 &\triangleq \check{x}(\omega) \check{y}^*(\omega) + \check{x}(\omega + \pi) \check{y}^*(\omega + \pi)
 \end{aligned}$$

2. Proof that $\sum_{m \in \mathbb{Z}} x_m y_{m-2n}^* = 0 \implies \check{x}(\omega) \check{y}^*(\omega) + \check{x}(\omega + \pi) \check{y}^*(\omega + \pi) = 0$:

$$\begin{aligned}
 0 &= 2 \sum_{n \in \mathbb{Z}} \left[\sum_{k \in \mathbb{Z}} x_k y_{k-2n}^* \right] e^{-i2\omega n} && \text{by left hypothesis} \\
 &= \check{x}(\omega) \check{y}^*(\omega) + \check{x}(\omega + \pi) \check{y}^*(\omega + \pi) && \text{by item (1)}
 \end{aligned}$$

3. Proof that $\sum_{m \in \mathbb{Z}} x_m y_{m-2n}^* = 0 \iff \check{x}(\omega) \check{y}^*(\omega) + \check{x}(\omega + \pi) \check{y}^*(\omega + \pi) = 0$:

$$\begin{aligned}
 2 \sum_{n \in \mathbb{Z}} \left[\sum_{k \in \mathbb{Z}} x_k y_{k-2n}^* \right] e^{-i2\omega n} &= \check{x}(\omega) \check{y}^*(\omega) + \check{x}(\omega + \pi) \check{y}^*(\omega + \pi) && \text{by item (1)} \\
 &= 0 && \text{by right hypothesis}
 \end{aligned}$$

Thus by the above equation, $\sum_{n \in \mathbb{Z}} \left[\sum_{k \in \mathbb{Z}} x_k y_{k-2n}^* \right] e^{-i2\omega n} = 0$. The only way for this to be true is if $\sum_{k \in \mathbb{Z}} x_k y_{k-2n}^* = 0$.

4. Proof that $\sum_{m \in \mathbb{Z}} x_m x_{m-2n}^* = \bar{\delta}_n \implies |\check{x}(\omega)|^2 + |\check{x}(\omega + \pi)|^2 = 2$:
Let $g_n \triangleq x_n$.

$$\begin{aligned}
 2 &= 2 \sum_{n \in \mathbb{Z}} \bar{\delta}_n e^{-i2\omega n} \\
 &= 2 \sum_{n \in \mathbb{Z}} \left[\sum_{k \in \mathbb{Z}} x_k y_{k-2n}^* \right] e^{-i2\omega n} && \text{by left hypothesis} \\
 &= \check{x}(\omega) \check{y}^*(\omega) + \check{x}(\omega + \pi) \check{y}^*(\omega + \pi) && \text{by item (1)}
 \end{aligned}$$

5. Proof that $\sum_{m \in \mathbb{Z}} x_m x_{m-2n}^* = \bar{\delta}_n \iff |\check{x}(\omega)|^2 + |\check{x}(\omega + \pi)|^2 = 2$:
Let $g_n \triangleq x_n$.

$$\begin{aligned}
 2 \sum_{n \in \mathbb{Z}} \left[\sum_{k \in \mathbb{Z}} x_k y_{k-2n}^* \right] e^{-i2\omega n} &= \check{x}(\omega) \check{y}^*(\omega) + \check{x}(\omega + \pi) \check{y}^*(\omega + \pi) && \text{by item (1)} \\
 &= 2 && \text{by right hypothesis}
 \end{aligned}$$



Thus by the above equation, $\sum_{n \in \mathbb{Z}} [\sum_{k \in \mathbb{Z}} x_k y_{k-2n}^*] e^{-i2\omega n} = 1$. The only way for this to be true is if $\sum_{k \in \mathbb{Z}} x_k y_{k-2n}^* = \delta_n$.



Q.3 Derivatives

Theorem Q.5.⁴ Let $\check{x}(\omega)$ be the DTFT (Definition Q.1 page 343) of a sequence $(x_n)_{n \in \mathbb{Z}}$.

T H M	$(A) \quad \left[\frac{d}{d\omega} \right]^n \check{x}(\omega) \Big _{\omega=0} = 0 \iff \sum_{k \in \mathbb{Z}} k^n x_k = 0 \quad (B) \quad \forall n \in \mathbb{W}$ $(C) \quad \left[\frac{d}{d\omega} \right]^n \check{x}(\omega) \Big _{\omega=\pi} = 0 \iff \sum_{k \in \mathbb{Z}} (-1)^k k^n x_k = 0 \quad (D) \quad \forall n \in \mathbb{W}$
-------------	--

PROOF:

1. Proof that (A) \implies (B):

$$\begin{aligned}
 0 &= \left[\frac{d}{d\omega} \right]^n \check{x}(\omega) \Big|_{\omega=0} && \text{by hypothesis (A)} \\
 &= \left[\frac{d}{d\omega} \right]^n \sum_{k \in \mathbb{Z}} x_k e^{-i\omega k} \Big|_{\omega=0} && \text{by definition of } \check{x}(\omega) \text{ (Definition Q.1 page 343)} \\
 &= \sum_{k \in \mathbb{Z}} x_k \left[\frac{d}{d\omega} \right]^n e^{-i\omega k} \Big|_{\omega=0} \\
 &= \sum_{k \in \mathbb{Z}} x_k \left[(-i)^n k^n e^{-i\omega k} \right] \Big|_{\omega=0} \\
 &= (-i)^n \sum_{k \in \mathbb{Z}} k^n x_k
 \end{aligned}$$

2. Proof that (A) \iff (B):

$$\begin{aligned}
 \left[\frac{d}{d\omega} \right]^n \check{x}(\omega) \Big|_{\omega=0} &= \left[\frac{d}{d\omega} \right]^n \sum_{k \in \mathbb{Z}} x_k e^{-i\omega k} \Big|_{\omega=0} && \text{by definition of } \check{x}(\omega) \\
 &= \sum_{k \in \mathbb{Z}} x_k \left[\left[\frac{d}{d\omega} \right]^n e^{-i\omega k} \right] \Big|_{\omega=0} \\
 &= \sum_{k \in \mathbb{Z}} x_k \left[(-i)^n k^n e^{-i\omega k} \right] \Big|_{\omega=0} \\
 &= (-i)^n \sum_{k \in \mathbb{Z}} k^n x_k \\
 &= 0 && \text{by hypothesis (B)}
 \end{aligned}$$

⁴ Vidakovic (1999), pages 82–83, Mallat (1999), pages 241–242

3. Proof that (C) \implies (D):

$$\begin{aligned}
 0 &= \left[\frac{d}{d\omega} \right]^n \check{x}(\omega) \Big|_{\omega=\pi} && \text{by hypothesis (C)} \\
 &= \left[\frac{d}{d\omega} \right]^n \sum_{k \in \mathbb{Z}} x_k e^{-i\omega k} \Big|_{\omega=\pi} && \text{by definition of } \check{x} \text{ (Definition Q.1 page 343)} \\
 &= \sum_{k \in \mathbb{Z}} x_k \left[\frac{d}{d\omega} \right]^n e^{-i\omega k} \Big|_{\omega=\pi} \\
 &= \sum_{k \in \mathbb{Z}} x_k \left[(-i)^n k^n e^{-i\omega k} \right] \Big|_{\omega=\pi} \\
 &= \sum_{k \in \mathbb{Z}} x_k \left[(-i)^n k^n (-1)^k \right] \\
 &= (-i)^n \sum_{k \in \mathbb{Z}} (-1)^k k^n x_k
 \end{aligned}$$

4. Proof that (C) \iff (D):

$$\begin{aligned}
 \left[\frac{d}{d\omega} \right]^n \check{x}(\omega) \Big|_{\omega=\pi} &= \left[\frac{d}{d\omega} \right]^n \sum_{k \in \mathbb{Z}} x_k e^{-i\omega k} \Big|_{\omega=\pi} && \text{by definition of } \check{x} \text{ (Definition Q.1 page 343)} \\
 &= \sum_{k \in \mathbb{Z}} x_k \left[\frac{d}{d\omega} \right]^n e^{-i\omega k} \Big|_{\omega=\pi} \\
 &= \sum_{k \in \mathbb{Z}} x_k \left[(-i)^n k^n e^{-i\omega k} \right] \Big|_{\omega=\pi} \\
 &= \sum_{k \in \mathbb{Z}} x_k \left[(-i)^n k^n (-1)^k \right] \\
 &= (-i)^n \sum_{k \in \mathbb{Z}} (-1)^k k^n x_k \\
 &= 0 && \text{by hypothesis (D)}
 \end{aligned}$$



APPENDIX R

OPERATIONS ON SEQUENCES

R.1 Convolution operator

Definition R.1. ¹ Let X^Y be the set of all functions from a set Y to a set X . Let \mathbb{Z} be the set of integers.

D E F A function f in X^Y is a **sequence** over X if $Y = \mathbb{Z}$.

A sequence may be denoted in the form $(x_n)_{n \in \mathbb{Z}}$ or simply as (x_n) .

Definition R.2. ² Let $(\mathbb{F}, +, \cdot, 0, 1)$ be a FIELD (Definition F.5 page 192).

The space of all absolutely square summable sequences $\ell_{\mathbb{F}}^2$ over \mathbb{F} is defined as

$$\ell_{\mathbb{F}}^2 \triangleq \left\{ (x_n)_{n \in \mathbb{Z}} \mid \sum_{n \in \mathbb{Z}} |x_n|^2 < \infty \right\}$$

The space $\ell_{\mathbb{R}}^2$ is an example of a *separable Hilbert space*. In fact, $\ell_{\mathbb{R}}^2$ is the *only* separable Hilbert space in the sense that all separable Hilbert spaces are isomorphically equivalent. For example, $\ell_{\mathbb{R}}^2$ is isomorphic to $L_{\mathbb{R}}^2$, the space of all absolutely square Lebesgue integrable functions.

Definition R.3.

The **convolution operation** \star is defined as

$$(x_n) \star (y_n) \triangleq \left(\left(\sum_{m \in \mathbb{Z}} x_m y_{n-m} \right) \right)_{n \in \mathbb{Z}} \quad \forall (x_n)_{n \in \mathbb{Z}}, (y_n)_{n \in \mathbb{Z}} \in \ell_{\mathbb{R}}^2$$

Proposition R.1. Let \star be the CONVOLUTION OPERATOR (Definition R.3 page 353).

P R P $(x_n) \star (y_n) = (y_n) \star (x_n) \quad \forall (x_n)_{n \in \mathbb{Z}}, (y_n)_{n \in \mathbb{Z}} \in \ell_{\mathbb{R}}^2 \quad (\star \text{ is COMMUTATIVE})$

¹ Bromwich (1908), page 1, Thomson et al. (2008) page 23 (Definition 2.1), Joshi (1997) page 31

² Kubrusly (2011) page 347 (Example 5.K)

PROOF:

$$\begin{aligned}
 [x \star y](n) &\triangleq \sum_{m \in \mathbb{Z}} x_m y_{n-m} && \text{by Definition R.3 page 353} \\
 &= \sum_{k \in \mathbb{Z}} x_{n-k} y(k) && \text{where } k \triangleq n - m \implies m = n - k \\
 &= \sum_{k \in \mathbb{Z}} x_{n-k} y(k) && \text{by commutativity of addition} \\
 &= \sum_{m \in \mathbb{Z}} x_{n-m} y_m && \text{by change of variables} \\
 &= \sum_{m \in \mathbb{Z}} y_m x_{n-m} && \text{by commutative property of the field over } \mathbb{C} \\
 &\triangleq (y \star x)_n && \text{by Definition R.3 page 353}
 \end{aligned}$$

⇒

Proposition R.2. Let \star be the CONVOLUTION OPERATOR (Definition R.3 page 353). Let $\ell^2_{\mathbb{R}}$ be the set of ABSOLUTELY SUMMABLE sequences (Definition R.2 page 353).

$$\boxed{\begin{array}{l} \textbf{P} \\ \textbf{R} \\ \textbf{P} \end{array} \left\{ \begin{array}{l} (A). \quad x(n) \in \ell^2_{\mathbb{R}} \text{ and} \\ (B). \quad y(n) \in \ell^2_{\mathbb{R}} \end{array} \right\} \Rightarrow \left\{ \sum_{k \in \mathbb{Z}} x[k]y[n+k] = x[-n] \star y(n) \right\}}$$

PROOF:

$$\begin{aligned}
 \sum_{k \in \mathbb{Z}} x[k]y[n+k] &= \sum_{-p \in \mathbb{Z}} x[-p]y[n-p] && \text{where } p \triangleq -k && \implies k = -p \\
 &= \sum_{p \in \mathbb{Z}} x[-p]y[n-p] && \text{by absolutely summable hypothesis} && (\text{Definition R.2 page 353}) \\
 &= \sum_{p \in \mathbb{Z}} x'[p]y[n-p] && \text{where } x'[n] \triangleq x[-n] && \implies x[-n] = x'[n] \\
 &\triangleq x'[n] \star y[n] && \text{by definition of convolution } \star && (\text{Definition R.3 page 353}) \\
 &\triangleq x[-n] \star y[n] && \text{by definition of } x'[n]
 \end{aligned}$$

⇒

R.2 Z-transform

Definition R.4.³

$$\boxed{\begin{array}{l} \textbf{D} \\ \textbf{E} \\ \textbf{F} \end{array} \text{The } z\text{-transform } \mathbf{Z} \text{ of } (x_n)_{n \in \mathbb{Z}} \text{ is defined as} \\
 [\mathbf{Z}(x_n)](z) \triangleq \underbrace{\sum_{n \in \mathbb{Z}} x_n z^{-n}}_{\text{Laurent series}} \quad \forall (x_n) \in \ell^2_{\mathbb{R}}}$$

Theorem R.1. Let $X(z) \triangleq \mathbf{Z}x[n]$ be the Z-TRANSFORM of $x[n]$.

$$\boxed{\begin{array}{l} \textbf{T} \\ \textbf{H} \\ \textbf{M} \end{array} \left\{ \check{x}(z) \triangleq \mathbf{Z}(x[n]) \right\} \implies \left\{ \begin{array}{l} (1). \quad \mathbf{Z}(\alpha x[n]) = \alpha \check{x}(z) \quad \forall (x_n) \in \ell^2_{\mathbb{R}} \text{ and} \\ (2). \quad \mathbf{Z}(x[n-k]) = z^{-k} \check{x}(z) \quad \forall (x_n) \in \ell^2_{\mathbb{R}} \text{ and} \\ (3). \quad \mathbf{Z}(x[-n]) = \check{x}\left(\frac{1}{z}\right) \quad \forall (x_n) \in \ell^2_{\mathbb{R}} \text{ and} \\ (4). \quad \mathbf{Z}(x^*[n]) = \check{x}^*\left(z^*\right) \quad \forall (x_n) \in \ell^2_{\mathbb{R}} \text{ and} \\ (5). \quad \mathbf{Z}(x^*[-n]) = \check{x}^*\left(\frac{1}{z^*}\right) \quad \forall (x_n) \in \ell^2_{\mathbb{R}} \end{array} \right\}}$$

³Laurent series: [Abramovich and Aliprantis \(2002\) page 49](#)

PROOF:

$$\begin{aligned}
 \alpha \mathbb{Z} \check{x}(z) &\triangleq \alpha \mathbb{Z}(\check{x}[n]) && \text{by definition of } \check{x}(z) \\
 &\triangleq \alpha \sum_{n \in \mathbb{Z}} x[n] z^{-n} && \text{by definition of } \mathbb{Z} \text{ operator} \\
 &\triangleq \sum_{n \in \mathbb{Z}} (\alpha x[n]) z^{-n} && \text{by distributive property} \\
 &\triangleq \mathbb{Z}(\alpha x[n]) && \text{by definition of } \mathbb{Z} \text{ operator} \\
 z^{-k} \check{x}(z) &= z^{-k} \mathbb{Z}(x[n]) && \text{by definition of } \check{x}(z) \quad (\text{left hypothesis}) \\
 &\triangleq z^{-k} \sum_{n=-\infty}^{n=+\infty} x[n] z^{-n} && \text{by definition of } \mathbb{Z} \\
 &= \sum_{n=-\infty}^{n=+\infty} x[n] z^{-n-k} && (\text{Definition R.4 page 354}) \\
 &= \sum_{m=k-\infty}^{m=+\infty} x[m-k] z^{-m} && \text{where } m \triangleq n+k \quad \implies n = m - k \\
 &= \sum_{m=-\infty}^{m=+\infty} x[m-k] z^{-m} \\
 &= \sum_{n=-\infty}^{n=+\infty} x[n-k] z^{-n} && \text{where } n \triangleq m \\
 &\triangleq \mathbb{Z}(x[n-k]) && \text{by definition of } \mathbb{Z} \quad (\text{Definition R.4 page 354}) \\
 \mathbb{Z}(x^*[n]) &\triangleq \sum_{n \in \mathbb{Z}} x^*[n] z^{-n} && \text{by definition of } \mathbb{Z} \quad (\text{Definition R.4 page 354}) \\
 &\triangleq \left(\sum_{n \in \mathbb{Z}} x[n] (z^*)^{-n} \right)^* && \text{by definition of } \mathbb{Z} \quad (\text{Definition R.4 page 354}) \\
 &\triangleq \check{x}^*(z^*) && \text{by definition of } \mathbb{Z} \quad (\text{Definition R.4 page 354}) \\
 \mathbb{Z}(x[-n]) &\triangleq \sum_{n \in \mathbb{Z}} x[-n] z^{-n} && \text{by definition of } \mathbb{Z} \quad (\text{Definition R.4 page 354}) \\
 &= \sum_{-m \in \mathbb{Z}} x[m] z^m && \text{where } m \triangleq -n \quad \implies n = -m \\
 &= \sum_{m \in \mathbb{Z}} x[m] z^m && \text{by absolutely summable property} \quad (\text{Definition R.2 page 353}) \\
 &= \sum_{m \in \mathbb{Z}} x[m] \left(\frac{1}{z} \right)^{-m} && \text{by absolutely summable property} \quad (\text{Definition R.2 page 353}) \\
 &\triangleq \check{x}\left(\frac{1}{z}\right) && \text{by definition of } \mathbb{Z} \quad (\text{Definition R.4 page 354}) \\
 \mathbb{Z}(x^*[-n]) &\triangleq \sum_{n \in \mathbb{Z}} x^*[-n] z^{-n} && \text{by definition of } \mathbb{Z} \quad (\text{Definition R.4 page 354}) \\
 &= \sum_{-m \in \mathbb{Z}} x^*[m] z^m && \text{where } m \triangleq -n \quad \implies n = -m \\
 &= \sum_{m \in \mathbb{Z}} x^*[m] z^m && \text{by absolutely summable property} \quad (\text{Definition R.2 page 353}) \\
 &= \sum_{m \in \mathbb{Z}} x^*[m] \left(\frac{1}{z} \right)^{-m} && \text{by absolutely summable property} \quad (\text{Definition R.2 page 353}) \\
 &= \left(\sum_{m \in \mathbb{Z}} x[m] \left(\frac{1}{z^*} \right)^{-m} \right)^* && \text{by absolutely summable property} \quad (\text{Definition R.2 page 353})
 \end{aligned}$$

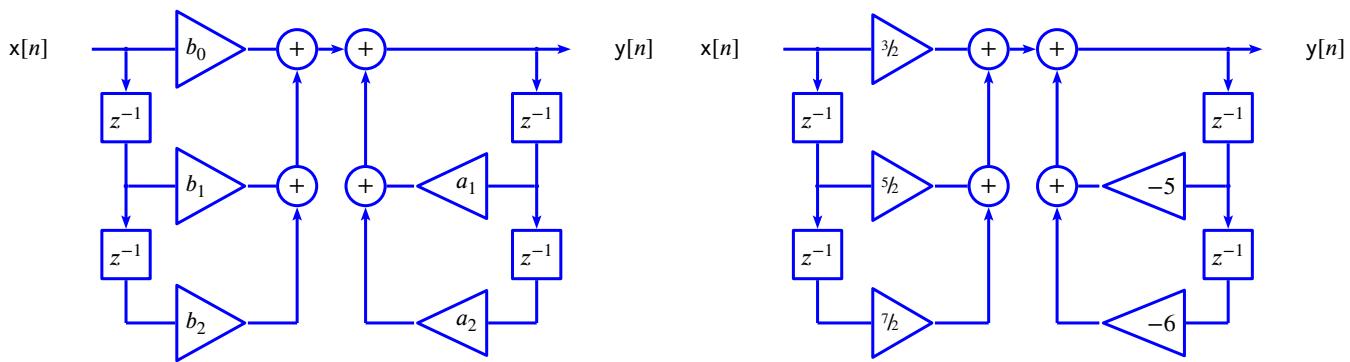


Figure R.1: Direct form 1 order 2 IIR filters

$$\triangleq \check{x}^* \left(\frac{1}{z^*} \right) \quad \text{by definition of } \mathbf{Z} \quad (\text{Definition R.4 page 354})$$

⇒

Theorem R.2 (convolution theorem). Let \star be the convolution operator (Definition R.3 page 353).

T H M	$\mathbf{Z} \underbrace{\left(\langle x_n \rangle \star \langle y_n \rangle \right)}_{\text{sequence convolution}} = \underbrace{\left(\mathbf{Z} \langle x_n \rangle \right) \left(\mathbf{Z} \langle y_n \rangle \right)}_{\text{series multiplication}}$	$\forall \langle x_n \rangle_{n \in \mathbb{Z}}, \langle y_n \rangle_{n \in \mathbb{Z}} \in \ell^2_{\mathbb{R}}$
-------------	--	--

PROOF:

$$\begin{aligned}
 [\mathbf{Z}(x \star y)](z) &\triangleq \mathbf{Z} \left(\sum_{m \in \mathbb{Z}} x_m y_{n-m} \right) && \text{by Definition R.3 page 353} \\
 &\triangleq \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} x_m y_{n-m} z^{-n} && \text{by Definition R.4 page 354} \\
 &= \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} x_m y_{n-m} z^{-n} \\
 &= \sum_{m \in \mathbb{Z}} \sum_{n \in \mathbb{Z}} x_m y_{n-m} z^{-n} \\
 &= \sum_{m \in \mathbb{Z}} \sum_{k \in \mathbb{Z}} x_m y_k z^{-(m+k)} && \text{where } k = n - m \iff n = m + k \\
 &= \left[\sum_{m \in \mathbb{Z}} x_m z^{-m} \right] \left[\sum_{k \in \mathbb{Z}} y_k z^{-k} \right] \\
 &\triangleq (\mathbf{Z} \langle x_n \rangle) (\mathbf{Z} \langle y_n \rangle) && \text{by Definition R.4 page 354}
 \end{aligned}$$

⇒

R.3 From z-domain back to time-domain

$$\check{y}(z) = b_0 X(z) + b_1 z^{-1} X(z) + b_2 z^{-2} X(z) - a_1 z^{-1} Y(z) + a_2 z^{-2} Y(z)$$

$$y[n] = b_0 x[n] + b_1 x[n-1] + b_2 x[n-2] - a_1 y[n-1] - a_2 y[n-2]$$

Example R.1. See Figure R.1 (page 356)

$$\frac{3z^2 + 5z + 7}{2z^2 + 10z + 12} = \frac{3z^2 + 5z + 7}{2(z^2 + 5z + 6)} = \frac{(3z^2 + 5z + 7)z^{-2}}{z^2 + 5z + 6} = \frac{(3z^2 + 5z + 7)z^{-2}}{1 + 5z^{-1} + 6z^{-2}}$$

R.4 Zero locations

The system property of *minimum phase* is defined in Definition R.5 (next) and illustrated in Figure R.2 (page 357).

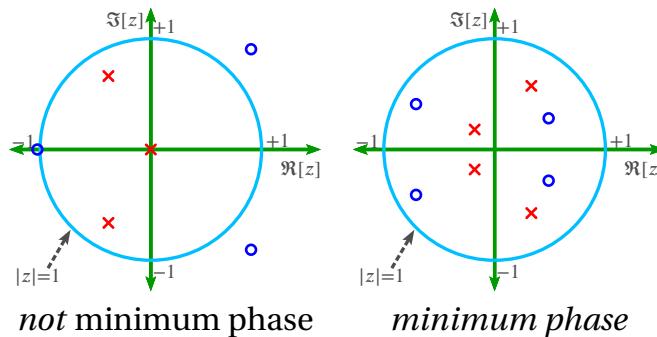


Figure R.2: Minimum Phase filter

Definition R.5. ⁴ Let $\check{x}(z) \triangleq \mathbf{Z}(x_n)$ be the Z TRANSFORM (Definition R.4 page 354) of a sequence $(x_n)_{n \in \mathbb{Z}}$ in $\ell_{\mathbb{R}}^2$. Let $(z_n)_{n \in \mathbb{Z}}$ be the ZEROS of $\check{x}(z)$.

DEF The sequence (x_n) is **minimum phase** if

$$\underbrace{|z_n| < 1}_{\check{x}(z) \text{ has all its ZEROS inside the unit circle}} \quad \forall n \in \mathbb{Z}$$

The impulse response of a minimum phase filter has most of its energy concentrated near the beginning of its support, as demonstrated next.

Theorem R.3 (Robinson's Energy Delay Theorem). ⁵ Let $p(z) \triangleq \sum_{n=0}^N a_n z^{-n}$ and $q(z) \triangleq \sum_{n=0}^N b_n z^{-n}$ be polynomials.

THM $\left\{ \begin{array}{l} p \text{ is MINIMUM PHASE} \\ q \text{ is NOT minimum phase} \end{array} \right. \text{ and } \Rightarrow \sum_{n=0}^{m-1} |a_n|^2 \geq \sum_{n=0}^{m-1} |b_n|^2 \quad \forall 0 \leq m \leq N$

$$\underbrace{\text{"energy" of the first } m \text{ coefficients of } p(z)}_{\text{of }} \geq \underbrace{\text{"energy" of the first } m \text{ coefficients of } q(z)}_{\text{of }}$$

But for more *symmetry*, put some zeros inside and some outside the unit circle (Figure R.3 page 358).

Example R.2. An example of a minimum phase polynomial is the Daubechies-4 scaling function. The minimum phase polynomial causes most of the energy to be concentrated near the origin, making it very *asymmetric*. In contrast, the Symlet-4 has a design very similar to that of Daubechies-4, but the selected zeros are not all within the unit circle in the complex z plane. This results in a

⁴ Farina and Rinaldi (2000) page 91, Dumitrescu (2007) page 36

⁵ Dumitrescu (2007) page 36, Robinson (1962), Robinson (1966) (???), Claerbout (1976), pages 52–53

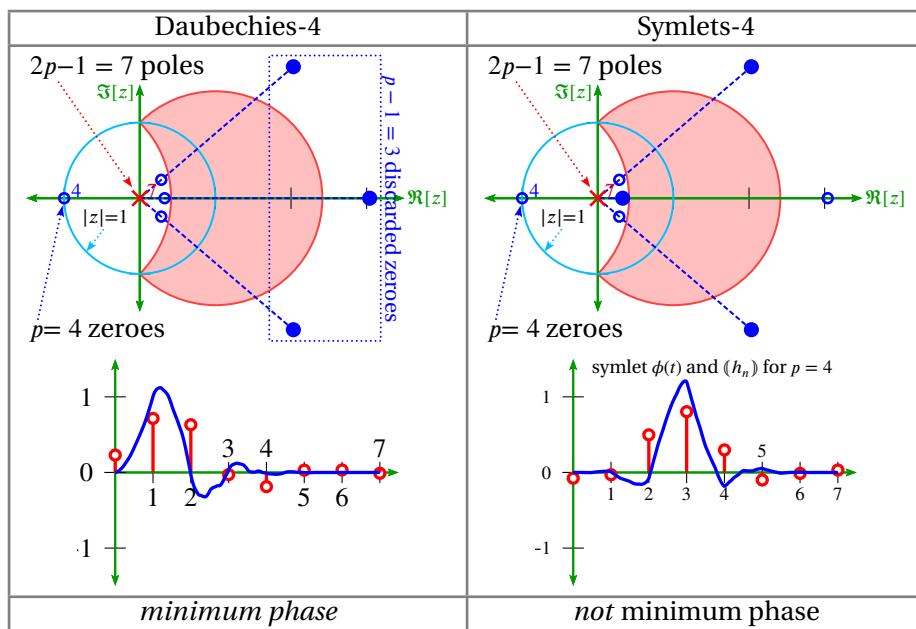


Figure R.3: Daubechies-4 and Symlet-4 scaling functions pole-zero plots

scaling function that is more symmetric and less contracted near the origin. Both scaling functions are illustrated in Figure R.3 (page 358).

R.5 Pole locations

Definition R.6.

D E F A filter (or system or operator) \mathbf{H} is **causal** if its current output does not depend on future inputs.

Definition R.7.

D E F A filter (or system or operator) \mathbf{H} is **time-invariant** if the mapping it performs does not change with time.

Definition R.8.

D E F An operation \mathbf{H} is **linear** if any output y_n can be described as a linear combination of inputs x_n as in

$$y_n = \sum_{m \in \mathbb{Z}} h(m)x(n-m).$$

For a filter to be *stable*, place all the poles *inside* the unit circle.

Theorem R.4. A causal LTI filter is **stable** if all of its poles are **inside** the unit circle.

Example R.3. Stable/unstable filters are illustrated in Figure R.4 (page 359).

True or False? This filter has no poles:



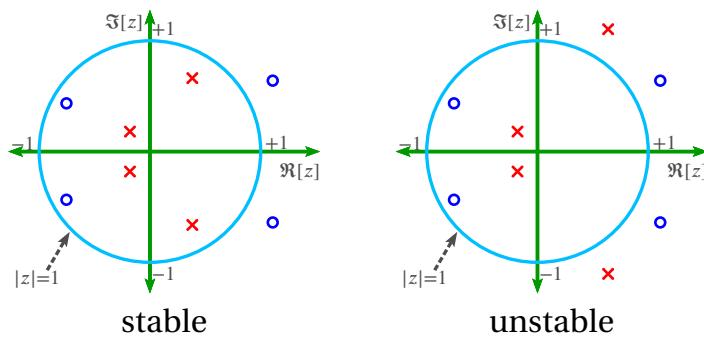
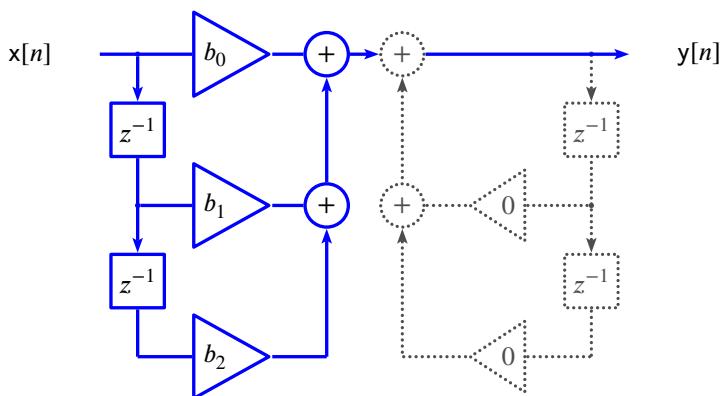
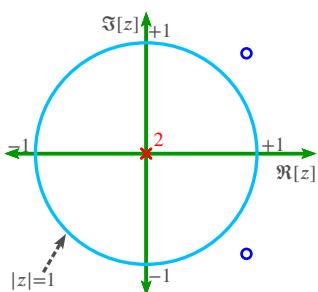


Figure R.4: Pole-zero plot stable/unstable causal LTI filters (Example R.3 page 358)

$$H(z) = b_0 + b_1 z^{-1} + b_2 z^{-2}$$



$$H(z) = b_0 + b_1 z^{-1} + b_2 z^{-2} = \frac{z^2}{z^2} \times \frac{b_0 + b_1 z^{-1} + b_2 z^{-2}}{1} = \frac{b_0 z^2 + b_1 z^1 + b_2}{z^2}$$



R.6 Mirroring for real coefficients

If you want real coefficients, choose poles and zeros in conjugate pairs (next).

Proposition R.3.

P R P	$\left\{ \begin{array}{l} \text{ZEROS and POLES} \\ \text{occur in CONJUGATE PAIRS} \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} \text{COEFFICIENTS} \\ \text{are REAL.} \end{array} \right\}$
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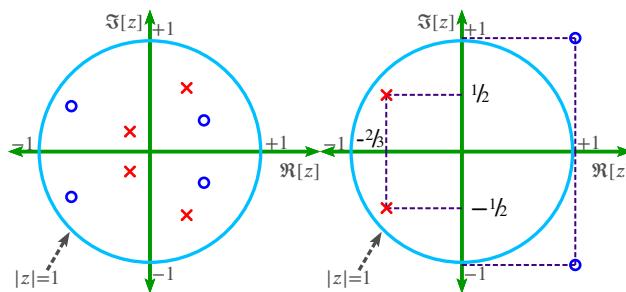


Figure R.5: Conjugate pair structure yielding real coefficients

PROOF:

$$\begin{aligned}(z - p_1)(z - p_1^*) &= [z - (a + ib)][z - (a - ib)] \\&= z^2 + [-a + ib - ib - a]z - [ib]^2 \\&= z^2 - 2az + b^2\end{aligned}$$

⇒

Example R.4. See Figure R.5 (page 360).

$$\begin{aligned}H(z) &= G \frac{[z - z_1][z - z_2]}{[z - p_1][z - p_2]} = G \frac{[z - (1+i)][z - (1-i)]}{[z - (-^{2/3} + i^{1/2})][z - (-^{2/3} - i^{1/2})]} \\&= G \frac{z^2 - z[(1-i) + (1+i)] + (1-i)(1+i)}{z^2 - z[(-^{2/3} + i^{1/2}) + (-^{2/3} - i^{1/2})] + (-^{2/3} + i^{1/2})(-^{2/3} - i^{1/2})} \\&= G \frac{z^2 - 2z + 2}{z^2 - \frac{4}{3}z + (\frac{1}{3} + \frac{1}{4})} = G \frac{z^2 - 2z + 2}{z^2 - \frac{4}{3}z + \frac{19}{12}}\end{aligned}$$

R.7 Rational polynomial operators

A digital filter is simply an operator on $\ell_{\mathbb{R}}^2$. If the digital filter is a causal LTI system, then it can be expressed as a rational polynomial in z as shown next.

Lemma R.1. A causal LTI operator H can be expressed as a rational expression $\check{h}(z)$.

$$\begin{aligned}\check{h}(z) &= \frac{b_0 + b_1 z^{-1} + b_2 z^{-2} + \dots + b_N z^{-N}}{1 + a_1 z^{-1} + a_2 z^{-2} + \dots + a_N z^{-N}} \\&= \frac{\sum_{n=0}^N b_n z^{-n}}{1 + \sum_{n=1}^N a_n z^{-n}}\end{aligned}$$

A filter operation $\check{h}(z)$ can be expressed as a product of its roots (poles and zeros).

$$\begin{aligned}\check{h}(z) &= \frac{b_0 + b_1 z^{-1} + b_2 z^{-2} + \dots + b_N z^{-N}}{1 + a_1 z^{-1} + a_2 z^{-2} + \dots + a_N z^{-N}} \\&= \alpha \frac{(z - z_1)(z - z_2) \dots (z - z_N)}{(z - p_1)(z - p_2) \dots (z - p_N)}\end{aligned}$$

where α is a constant, z_i are the zeros, and p_i are the poles. The poles and zeros of such a rational expression are often plotted in the z-plane with a unit circle about the origin (representing $z = e^{i\omega}$). Poles are marked with \times and zeros with \circ . An example is shown in Figure R.6 page 361. Notice that in this figure the zeros and poles are either real or occur in complex conjugate pairs.

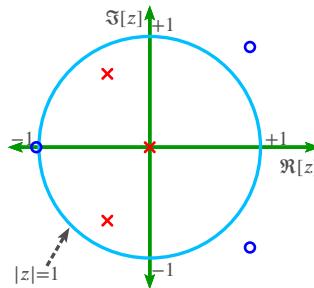


Figure R.6: Pole-zero plot for rational expression with real coefficients

R.8 Filter Banks

Conjugate quadrature filters (next definition) are used in *filter banks*. If $\check{x}(z)$ is a *low-pass filter*, then the conjugate quadrature filter of $\check{y}(z)$ is a *high-pass filter*.

Definition R.9.⁶ Let $(x_n)_{n \in \mathbb{Z}}$ and $(y_n)_{n \in \mathbb{Z}}$ be SEQUENCES (Definition R.1 page 353) in $\ell^2_{\mathbb{R}}$ (Definition R.2 page 353).

The sequence (y_n) is a **conjugate quadrature filter** with shift N with respect to (x_n) if

$$y_n = \pm(-1)^n x_{N-n}^*$$

A CONJUGATE QUADRATURE FILTER is also called a **CQF** or a **Smith-Barnwell filter**.

Any triple $((x_n), (y_n), N)$ in this form is said to satisfy the

conjugate quadrature filter condition or the **CQF condition**.

Theorem R.5 (CQF theorem).⁷ Let $\check{y}(\omega)$ and $\check{x}(\omega)$ be the DTFTs (Definition Q.1 page 343) of the sequences $(y_n)_{n \in \mathbb{Z}}$ and $(x_n)_{n \in \mathbb{Z}}$, respectively, in $\ell^2_{\mathbb{R}}$ (Definition R.2 page 353).

T H M	$\underbrace{y_n = \pm(-1)^n x_{N-n}^*}_{(1) \text{ CQF in "time"} \quad \text{iff}} \quad \Leftrightarrow \quad \check{y}(z) = \pm(-1)^N z^{-N} \check{x}^*\left(\frac{-1}{z^*}\right) \quad (2) \quad \text{CQF in "z-domain"}$ $\Leftrightarrow \check{y}(\omega) = \pm(-1)^N e^{-i\omega N} \check{x}^*(\omega + \pi) \quad (3) \quad \text{CQF in "frequency"}$ $\Leftrightarrow x_n = \pm(-1)^N (-1)^n y_{N-n}^* \quad (4) \quad \text{"reversed" CQF in "time"}$ $\Leftrightarrow \check{x}(z) = \pm z^{-N} \check{y}^*\left(\frac{-1}{z^*}\right) \quad (5) \quad \text{"reversed" CQF in "z-domain"}$ $\Leftrightarrow \check{x}(\omega) = \pm e^{-i\omega N} \check{y}^*(\omega + \pi) \quad (6) \quad \text{"reversed" CQF in "frequency"}$
-------------	--

$$\forall n \in \mathbb{Z}$$

PROOF:

⁶ Strang and Nguyen (1996) page 109, Haddad and Akansu (1992) pages 256–259 (section 4.5), Vaidyanathan (1993) page 342 ((7.2.7), (7.2.8)), Smith and Barnwell (1984a), Smith and Barnwell (1984b), Mintzer (1985)

⁷ Strang and Nguyen (1996) page 109, Mallat (1999) pages 236–238 ((7.58),(7.73)), Haddad and Akansu (1992) pages 256–259 (section 4.5), Vaidyanathan (1993) page 342 ((7.2.7), (7.2.8))

1. Proof that (1) \implies (2):

$$\begin{aligned}
 \check{y}(z) &= \sum_{n \in \mathbb{Z}} y_n z^{-n} && \text{by definition of } z\text{-transform} && (\text{Definition R.4 page 354}) \\
 &= \sum_{n \in \mathbb{Z}} (\pm)(-1)^n x_{N-n}^* z^{-n} && \text{by (1)} \\
 &= \pm \sum_{m \in \mathbb{Z}} (-1)^{N-m} x_m^* z^{-(N-m)} && \text{where } m \triangleq N - n \implies && n = N - m \\
 &= \pm(-1)^N z^{-N} \sum_{m \in \mathbb{Z}} (-1)^{-m} x_m^* (z^{-1})^{-m} \\
 &= \pm(-1)^N z^{-N} \sum_{m \in \mathbb{Z}} x_m^* \left(-\frac{1}{z}\right)^{-m} \\
 &= \pm(-1)^N z^{-N} \left[\sum_{m \in \mathbb{Z}} x_m \left(-\frac{1}{z^*}\right)^{-m} \right]^* \\
 &= \pm(-1)^N z^{-N} \check{x}^* \left(\frac{-1}{z^*}\right)
 \end{aligned}$$

by definition of z -transform (Definition R.4 page 354)

2. Proof that (1) \Leftarrow (2):

$$\begin{aligned}
 \check{y}(z) &= \pm(-1)^N z^{-N} \check{x}^* \left(\frac{-1}{z^*}\right) && \text{by (2)} \\
 &= \pm(-1)^N z^{-N} \left[\sum_{m \in \mathbb{Z}} x_m \left(\frac{-1}{z^*}\right)^{-m} \right]^* && \text{by definition of } z\text{-transform} && (\text{Definition R.4 page 354}) \\
 &= \pm(-1)^N z^{-N} \left[\sum_{m \in \mathbb{Z}} x_m^* (-z^{-1})^{-m} \right] && \text{by definition of } z\text{-transform} && (\text{Definition R.4 page 354}) \\
 &= \sum_{m \in \mathbb{Z}} (\pm)(-1)^{N-m} x_m^* z^{-(N-m)} \\
 &= \sum_{m \in \mathbb{Z}} (\pm)(-1)^n x_{N-n}^* z^{-n} && \text{where } n = N - m \implies && m \triangleq N - n \\
 &\implies x_n = \pm(-1)^n x_{N-n}^*
 \end{aligned}$$

3. Proof that (1) \implies (3):

$$\begin{aligned}
 \check{y}(\omega) &\triangleq \check{y}(z) \Big|_{z=e^{i\omega}} && \text{by definition of DTFT (Definition Q.1 page 343)} \\
 &= \left[\pm(-1)^N z^{-N} \check{x} \left(\frac{-1}{z^*}\right) \right]_{z=e^{i\omega}} && \text{by (2)} \\
 &= \pm(-1)^N e^{-i\omega N} \check{x} (e^{i\pi} e^{i\omega}) \\
 &= \pm(-1)^N e^{-i\omega N} \check{x} (e^{i(\omega+\pi)}) \\
 &= \pm(-1)^N e^{-i\omega N} \check{x}(\omega + \pi)
 \end{aligned}$$

by definition of DTFT (Definition Q.1 page 343)

4. Proof that (1) \implies (6):

$$\begin{aligned}
 \check{x}(\omega) &= \sum_{n \in \mathbb{Z}} y_n e^{-i\omega n} && \text{by definition of DTFT} && (\text{Definition Q.1 page 343}) \\
 &= \sum_{n \in \mathbb{Z}} \underbrace{\pm(-1)^n x_{N-n}^*}_{CQF} e^{-i\omega n} && \text{by (1)} \\
 &= \sum_{m \in \mathbb{Z}} \pm(-1)^{N-m} x_m^* e^{-i\omega(N-m)} && \text{where } m \triangleq N - n \implies && n = N - m \\
 &= \pm(-1)^N e^{-i\omega N} \sum_{m \in \mathbb{Z}} (-1)^m x_m^* e^{i\omega m}
 \end{aligned}$$



$$\begin{aligned}
&= \pm(-1)^N e^{-i\omega N} \sum_{m \in \mathbb{Z}} e^{i\pi m} x_m^* e^{i\omega m} \\
&= \pm(-1)^N e^{-i\omega N} \sum_{m \in \mathbb{Z}} x_m^* e^{i(\omega+\pi)m} \\
&= \pm(-1)^N e^{-i\omega N} \left[\sum_{m \in \mathbb{Z}} x_m e^{-i(\omega+\pi)m} \right]^* \\
&= \pm(-1)^N e^{-i\omega N} \check{x}^*(\omega + \pi) \quad \text{by definition of DTFT} \quad (\text{Definition Q.1 page 343})
\end{aligned}$$

5. Proof that (1) \iff (3):

$$\begin{aligned}
y_n &= \frac{1}{2\pi} \int_{-\pi}^{+\pi} \check{y}(\omega) e^{i\omega n} d\omega && \text{by inverse DTFT} \quad (\text{Theorem Q.3 page 349}) \\
&= \frac{1}{2\pi} \int_{-\pi}^{+\pi} \underbrace{\pm(-1)^N e^{-iN\omega}}_{\text{right hypothesis}} \check{x}^*(\omega + \pi) e^{i\omega n} d\omega && \text{by right hypothesis} \\
&= \pm(-1)^N \frac{1}{2\pi} \int_{-\pi}^{+\pi} \check{x}^*(\omega + \pi) e^{i\omega(n-N)} d\omega && \text{by right hypothesis} \\
&= \pm(-1)^N \frac{1}{2\pi} \int_0^{2\pi} \check{x}^*(v) e^{i(v-\pi)(n-N)} dv && \text{where } v \triangleq \omega + \pi \implies \omega = v - \pi \\
&= \pm(-1)^N e^{-i\pi(n-N)} \frac{1}{2\pi} \int_0^{2\pi} \check{x}^*(v) e^{iv(n-N)} dv \\
&= \pm(-1)^N \underbrace{(-1)^N}_{e^{i\pi N}} \underbrace{(-1)^n}_{e^{-i\pi n}} \left[\frac{1}{2\pi} \int_0^{2\pi} \check{x}(v) e^{iv(N-n)} dv \right]^* \\
&= \pm(-1)^n x_{N-n}^* && \text{by inverse DTFT} \quad (\text{Theorem Q.3 page 349})
\end{aligned}$$

6. Proof that (1) \iff (4):

$$\begin{aligned}
y_n = \pm(-1)^n x_{N-n}^* &\iff (\pm)(-1)^n y_n = (\pm)(\pm)(-1)^n (-1)^n x_{N-n}^* \\
&\iff \pm(-1)^n y_n = x_{N-n}^* \\
&\iff (\pm(-1)^n y_n)^* = (x_{N-n}^*)^* \\
&\iff \pm(-1)^n y_n^* = x_{N-n} \\
&\iff x_{N-n} = \pm(-1)^n y_n^* \\
&\iff x_m = \pm(-1)^{N-m} y_{N-m}^* && \text{where } m \triangleq N - n \implies n = N - m \\
&\iff x_m = \pm(-1)^{N-m} y_{N-m}^* \\
&\iff x_m = \pm(-1)^N (-1)^m y_{N-m}^* \\
&\iff x_n = \pm(-1)^N (-1)^n y_{N-n}^* && \text{by change of free variables}
\end{aligned}$$

7. Proofs for (5) and (6): not included. See proofs for (2) and (3).



Theorem R.6.⁸ Let $\check{y}(\omega)$ and $\check{x}(\omega)$ be the DTFTs (Definition Q.1 page 343) of the sequences $(y_n)_{n \in \mathbb{Z}}$ and $(x_n)_{n \in \mathbb{Z}}$, respectively, in $\ell^2_{\mathbb{R}}$ (Definition R.2 page 353).

T H M

Let $y_n = \pm(-1)^n x_{N-n}^*$ (CQF CONDITION, Definition R.9 page 361). Then

$$\left\{
\begin{aligned}
(A) \quad \left[\frac{d}{d\omega} \right]^n \check{y}(\omega) \Big|_{\omega=0} &= 0 \iff \left[\frac{d}{d\omega} \right]^n \check{x}(\omega) \Big|_{\omega=\pi} &= 0 & (B) \\
&\iff \sum_{k \in \mathbb{Z}} (-1)^k k^n x_k &= 0 & (C) \\
&\iff \sum_{k \in \mathbb{Z}} k^n y_k &= 0 & (D)
\end{aligned}
\right\} \forall n \in \mathbb{W}$$

⁸ Vidakovic (1999), pages 82–83, Mallat (1999), pages 241–242

PROOF:

1. Proof that (A) \implies (B):

$$\begin{aligned}
 0 &= \left[\frac{d}{d\omega} \right]^n \check{y}(\omega) \Big|_{\omega=0} && \text{by (A)} \\
 &= \left[\frac{d}{d\omega} \right]^n (\pm)(-1)^N e^{-i\omega N} \check{x}^*(\omega + \pi) \Big|_{\omega=0} && \text{by CQF theorem (Theorem R.5 page 361)} \\
 &= (\pm)(-1)^N \sum_{\ell=0}^n \binom{n}{\ell} \left[\frac{d}{d\omega} \right]^\ell [e^{-i\omega N}] \cdot \left[\frac{d}{d\omega} \right]^{n-\ell} [\check{x}^*(\omega + \pi)] \Big|_{\omega=0} && \text{by Leibnitz GPR (Lemma ?? page ??)} \\
 &= (\pm)(-1)^N \sum_{\ell=0}^n \binom{n}{\ell} -iN^\ell e^{-i\omega N} \left[\frac{d}{d\omega} \right]^{n-\ell} [\check{x}^*(\omega + \pi)] \Big|_{\omega=0} \\
 &= (\pm)(-1)^N e^{-i0N} \sum_{\ell=0}^n \binom{n}{\ell} -iN^\ell \left[\frac{d}{d\omega} \right]^{n-\ell} [\check{x}^*(\omega + \pi)] \Big|_{\omega=0} \\
 &\implies \check{x}^{(0)}(\pi) = 0 \\
 &\implies \check{x}^{(1)}(\pi) = 0 \\
 &\implies \check{x}^{(2)}(\pi) = 0 \\
 &\implies \check{x}^{(3)}(\pi) = 0 \\
 &\implies \check{x}^{(4)}(\pi) = 0 \\
 &\vdots \quad \vdots \\
 &\implies \check{x}^{(n)}(\pi) = 0 \quad \text{for } n = 0, 1, 2, \dots
 \end{aligned}$$

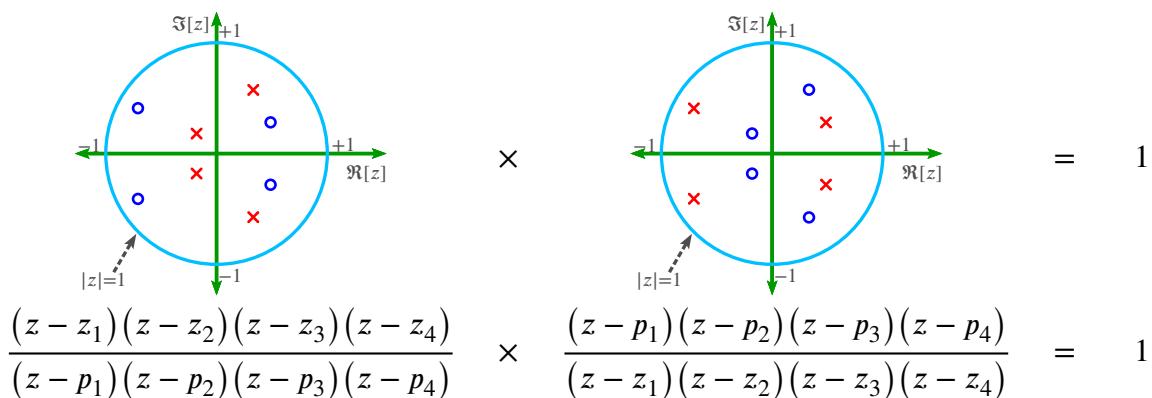
2. Proof that (A) \iff (B):

$$\begin{aligned}
 0 &= \left[\frac{d}{d\omega} \right]^n \check{x}(\omega) \Big|_{\omega=\pi} && \text{by (B)} \\
 &= \left[\frac{d}{d\omega} \right]^n (\pm) e^{-i\omega N} \check{y}^*(\omega + \pi) \Big|_{\omega=\pi} && \text{by CQF theorem (Theorem R.5 page 361)} \\
 &= (\pm) \sum_{\ell=0}^n \binom{n}{\ell} \left[\frac{d}{d\omega} \right]^\ell [e^{-i\omega N}] \cdot \left[\frac{d}{d\omega} \right]^{n-\ell} [\check{y}^*(\omega + \pi)] \Big|_{\omega=\pi} && \text{by Leibnitz GPR (Lemma ?? page ??)} \\
 &= (\pm) \sum_{\ell=0}^n \binom{n}{\ell} (-iN)^\ell e^{-i\omega N} \left[\frac{d}{d\omega} \right]^{n-\ell} [\check{y}^*(\omega + \pi)] \Big|_{\omega=\pi} \\
 &= (\pm) e^{-i\pi N} \sum_{\ell=0}^n \binom{n}{\ell} -iN^\ell \left[\frac{d}{d\omega} \right]^{n-\ell} [\check{y}^*(\omega + \pi)] \Big|_{\omega=\pi} \\
 &= (\pm)(-1)^N \sum_{\ell=0}^n \binom{n}{\ell} -iN^\ell \left[\frac{d}{d\omega} \right]^{n-\ell} [\check{y}^*(\omega + \pi)] \Big|_{\omega=\pi} \\
 &\implies \check{y}^{(0)}(0) = 0 \\
 &\implies \check{y}^{(1)}(0) = 0 \\
 &\implies \check{y}^{(2)}(0) = 0 \\
 &\implies \check{y}^{(3)}(0) = 0 \\
 &\implies \check{y}^{(4)}(0) = 0 \\
 &\vdots \quad \vdots \\
 &\implies \check{y}^{(n)}(0) = 0 \quad \text{for } n = 0, 1, 2, \dots
 \end{aligned}$$

3. Proof that (B) \iff (C): by Theorem Q.5 page 351

4. Proof that (A) \iff (D): by Theorem Q.5 page 351



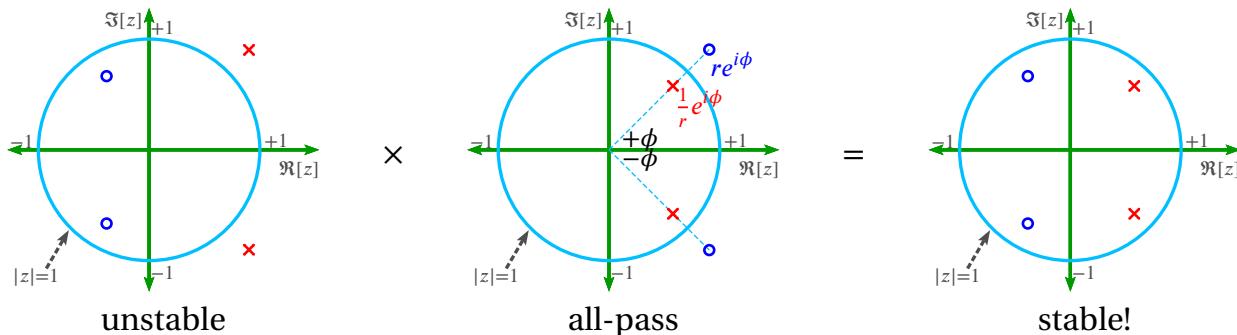


5. Proof that (CQF) \Leftrightarrow (A): Here is a counterexample: $\check{y}(\omega) = 0$.



R.9 Inverting non-minimum phase filters

Minimum phase filters are easy to invert: each *zero* becomes a *pole* and each *pole* becomes a *zero*.



$$\begin{aligned}
 |A(z)|_{z=e^{i\omega}} &= \frac{1}{r} \left| \frac{z - re^{i\phi}}{z - \frac{1}{r}e^{i\phi}} \right|_{z=e^{i\omega}} \\
 &= \left| e^{i\phi} \left(\frac{e^{-i\phi}z - r}{rz - e^{i\phi}} \right) \right|_{z=e^{i\omega}} \\
 &= \left| -z \left(\frac{rz^{-1} - e^{-i\phi}}{rz - e^{i\phi}} \right) \right|_{z=e^{i\omega}} \\
 &= \left| \frac{1}{e^{-iv}} \left(\frac{re^{-i\omega} - e^{-i\phi}}{(re^{i\omega} - e^{i\phi})^*} \right) \right| \\
 &= 1
 \end{aligned}
 \quad
 \begin{aligned}
 &= \left| \frac{z - re^{i\phi}}{rz - e^{i\phi}} \right|_{z=e^{i\omega}} \\
 &= \left| z \left(\frac{e^{-i\phi} - rz^{-1}}{rz - e^{i\phi}} \right) \right|_{z=e^{i\omega}} \\
 &= \left| e^{i\pi} e^{i\omega} \left(\frac{re^{-i\omega} - e^{-i\phi}}{re^{i\omega} - e^{i\phi}} \right) \right| \\
 &= \left| \frac{re^{-i\omega} - e^{-i\phi}}{re^{-i\omega} - e^{-i\phi}} \right|
 \end{aligned}$$

APPENDIX S

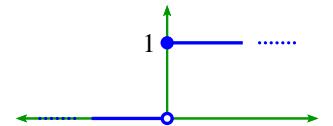
B-SPLINES

S.1 Definitions

Definition S.1. Let X be a set.

D E F The **step function** $\sigma \in \mathbb{R}^{\mathbb{R}}$ is defined as

$$\sigma(x) \triangleq \mathbb{1}_{[0:\infty)}(x) \quad \forall x \in \mathbb{R}.$$



Lemma S.1. Let $\sigma(x)$ be the STEP FUNCTION (Definition S.1 page 367).

L E M $\{g(x) > 0\} \implies \{\sigma[g(x)f(x)] = \sigma[f(x)]\} \quad \forall f, g \in \mathbb{R}^{\mathbb{R}}$

PROOF:

$$\begin{aligned}
 \sigma[g(x)f(x)] &\triangleq \mathbb{1}_{[0:\infty)}[g(x)f(x)] && \text{by definition of } \sigma(x) && (\text{Definition S.1 page 367}) \\
 &\triangleq \begin{cases} 1 & \text{for } g(x)f(x) \geq 0 \\ 0 & \text{otherwise} \end{cases} && \text{by definition of } \mathbb{1}_A(x) && (\text{Definition ?? page ??}) \\
 &= \begin{cases} 1 & \text{for } f(x) \geq 0 \\ 0 & \text{otherwise} \end{cases} && \text{by } g(x) > 0 \text{ hypothesis} && \\
 &\triangleq \mathbb{1}_{[0:\infty)}[f(x)] && \text{by definition of } \mathbb{1}_A(x) && (\text{Definition ?? page ??}) \\
 &\triangleq \sigma[f(x)] && \text{by definition of } \sigma(x) && (\text{Definition S.1 page 367})
 \end{aligned}$$

Definition S.2.¹ Let $\mathbb{1}$ be the SET INDICATOR function (Definition ?? page ??). Let $f(x) \star g(x)$ represent the CONVOLUTION operation (Definition P.3 page 336).

D E F The **n th order cardinal B-spline** $N_n(x)$ for $n \in \mathbb{W}$ is defined as

$$N_n(x) \triangleq \begin{cases} \mathbb{1}_{[0:1)}(x) & \text{for } n = 0 \\ N_{n-1}(x) \star N_0(x) & \text{for } n \in \mathbb{W} \setminus 0 \end{cases} \quad \forall x \in \mathbb{R}$$

Lemma S.2.²

¹ Chui (1992) page 85 ((4.2.1)), Christensen (2008) page 140, Chui (1988) page 1

² Christensen (2008) page 140, Chui (1992) page 85 ((4.2.1)), Chui (1988) page 1, Prasad and Iyengar (1997) page 145

L E M $N_n(x) = \int_{\tau=0}^{\tau=1} N_{n-1}(x - \tau) d\tau \quad \forall n \in \{1, 2, 3, \dots\}$

PROOF:

$$\begin{aligned}
 N_n(x) &\triangleq N_{n-1}(x) \star N_0(x) && \text{by definition of } N_n(x) && (\text{Definition S.2 page 367}) \\
 &\triangleq \int_{\mathbb{R}} N_{n-1}(x - \tau) N_0(\tau) d\tau && \text{by definition of convolution operation } \star && (\text{Definition P.3 page 336}) \\
 &\triangleq \int_{\mathbb{R}} N_{n-1}(x - \tau) \mathbb{1}_{[0:1]}(\tau) d\tau && \text{by definition of } N_0(x) && (\text{Definition S.2 page 367}) \\
 &= \int_{[0:1]} N_{n-1}(x - \tau) d\tau && \text{by definition of } \mathbb{1}_A(x) && (\text{Definition ?? page ??}) \\
 &= \int_{[0:1]} N_{n-1}(x - \tau) d\tau \\
 &\triangleq \int_0^1 N_{n-1}(x - \tau) d\tau
 \end{aligned}$$

⇒

Lemma S.3. Let $f(x)$ be a FUNCTION in $\mathbb{R}^{\mathbb{R}}$. Let $F(x)$ be the ANTI-DERIVATIVE of $f(x)$.

Let $\sigma(x)$ be the STEP FUNCTION (Definition S.1 page 367).

L E M

$$\begin{aligned}
 &\int_{y=a}^{y=b} f(x - y) \sigma(x - y) dy \\
 &= \left\{ \begin{array}{ll} - \int_{y=x-a}^{y=x-b} f(y) dy & \text{for } x \geq b \\ - \int_{y=x-a}^{y=0} f(y) dy & \text{for } a \leq x \leq b \\ 0 & \text{for } x \leq a \end{array} \right\} = \left\{ \begin{array}{ll} F(x - a) - F(x - b) & \text{for } x \geq b \\ F(x - a) - F(0) & \text{for } a \leq x \leq b \\ 0 & \text{for } x \leq a \end{array} \right\} \\
 &= [F(x - a) - F(0)]\sigma(x - a) + [F(0) - F(x - b)]\sigma(x - b)
 \end{aligned}$$

PROOF:

$$\begin{aligned}
 \int_{y=a}^{y=b} f(x - y) \sigma(x - y) dy &= \left\{ \begin{array}{ll} \int_{y=a}^{y=b} f(x - y) dy & \text{for } x \geq b \\ \int_{y=a}^{y=x} f(x - y) dy & \text{for } a \leq x \leq b \\ 0 & \text{for } x \leq a \end{array} \right\} && \text{by definition of } \sigma \text{ (Definition S.1 page 367)} \\
 &= \left\{ \begin{array}{ll} - \int_{u=x-a}^{u=x-b} f(u) du & \text{for } x \geq b \\ - \int_{u=x-a}^{u=0} f(u) du & \text{for } a \leq x \leq b \\ 0 & \text{for } x \leq a \end{array} \right\} && \text{where } u \triangleq x - y \implies y = x - u \\
 &= \left\{ \begin{array}{ll} - \int_{y=x-a}^{y=x-b} f(y) dy & \text{for } x \geq b \\ - \int_{y=x-a}^{y=0} f(y) dy & \text{for } a \leq x \leq b \\ 0 & \text{for } x \leq a \end{array} \right\} && \text{by change of dummy variable } (u \rightarrow y) \\
 &= \left\{ \begin{array}{ll} F(x - a) - F(x - b) & \text{for } x \geq b \\ F(x - a) - F(0) & \text{for } a \leq x \leq b \\ 0 & \text{for } x \leq a \end{array} \right\} && \text{by Fundamental Theorem of Calculus} \\
 &= [F(x - a) - F(x - b)]\sigma(x - b) + [F(x - a) - F(0)][\sigma(x - a) - \sigma(x - b)] \\
 &= [F(x - a) - F(0)]\sigma(x - a) + [F(x - a) - F(x - b) - F(x - a) + F(0)]\sigma(x - b) \\
 &= [F(x - a) - F(0)]\sigma(x - a) + [F(0) - F(x - b)]\sigma(x - b)
 \end{aligned}$$

⇒



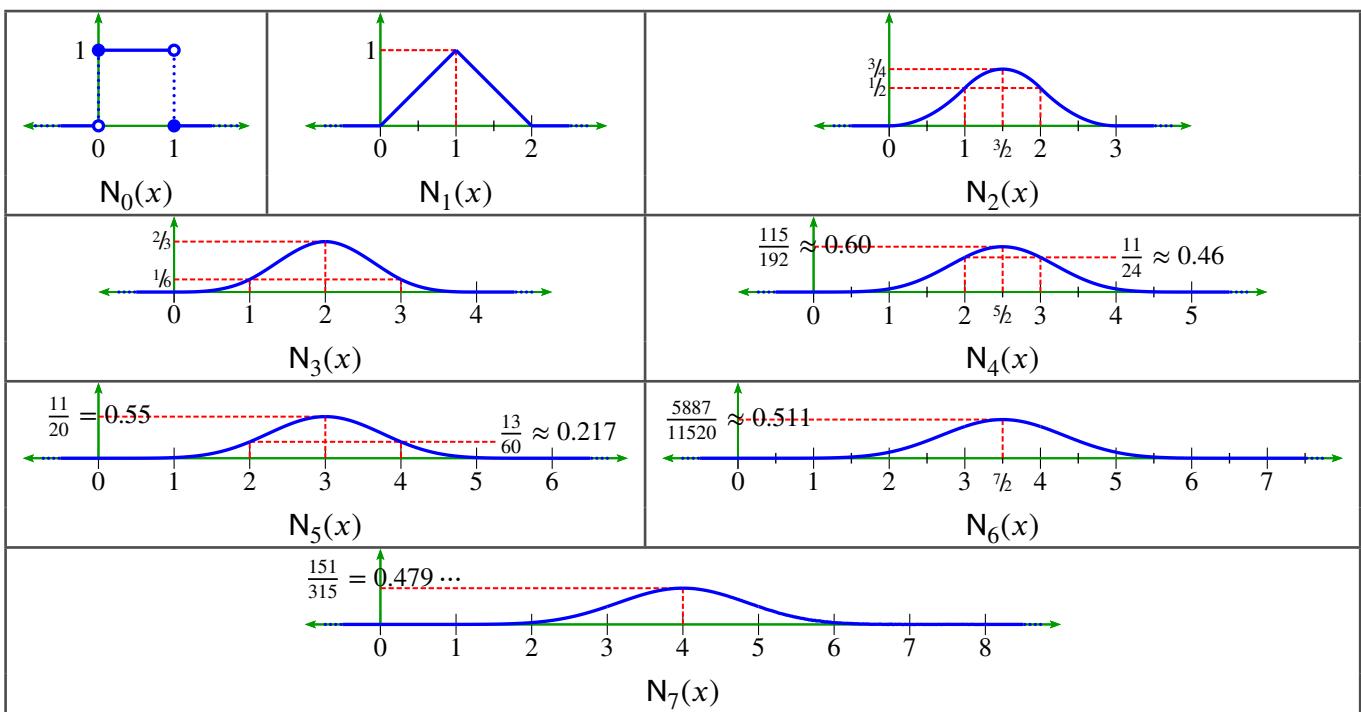


Figure S.1: some low order B-splines (Example S.1 page 369)

Lemma S.4. Let $\sigma(x)$ be the STEP FUNCTION (Definition S.1 page 367).

$$\boxed{\text{LEM}} \quad \int_{\tau=0}^{\tau=1} (x - \tau - k)^n \sigma(x - \tau - k) d\tau = \frac{1}{n+1} [(x - k)^{n+1} \sigma(x - k) - (x - k - 1)^{n+1} \sigma(x - k - 1)]$$

PROOF:

$$\begin{aligned}
 & \int_{\tau=0}^{\tau=1} (x - \tau - k)^n \sigma(x - \tau - k) d\tau \\
 &= \int_{y=k}^{y=k+1} (x - y)^n \sigma(x - y) dy && \text{where } y \triangleq \tau + k \implies \tau = y - k \\
 &= [\mathcal{F}(x - k) - \mathcal{F}(0)] \sigma(x - k) + [\mathcal{F}(0) - \mathcal{F}(x - k - 1)] \sigma(x - k - 1) && \text{by Lemma S.3 (page 368), where } f(x) \triangleq x^n \\
 &= \frac{[(x - k)^{n+1} - 0] \sigma(x - k) + [0 - (x - k - 1)^{n+1}] \sigma(x - k - 1)}{n+1} && \text{because } \mathcal{F}(x) \triangleq \int f(x) dx = \frac{x^{n+1}}{n+1} + c \\
 &= \frac{1}{n+1} [(x - k)^{n+1} \sigma(x - k) - (x - k - 1)^{n+1} \sigma(x - k - 1)]
 \end{aligned}$$

☞

Example S.1.³ Let $\sigma(x)$ be the step function (Definition S.1 page 367). Let $\binom{n}{k}$ be the binomial coefficient (Definition ?? page ??). The 0th order B-spline (Definition S.2 page 367) $N_0(x)$ can be expressed as follows:

$$\boxed{\text{EX}} \quad N_0(x) = \left\{ \begin{array}{ll} 1 & \text{for } x \in [0 : 1) \\ 0 & \text{otherwise} \end{array} \right\} = \left\{ \sum_{k=0}^1 (-1)^k \binom{1}{k} (x - k)^0 \sigma(x - k) \quad \forall x \in \mathbb{R} \right\}$$

The B-spline $N_0(x)$ is illustrated in Figure S.1 (page 369).

³ Schumaker (2007) page 136 (Table 1)

PROOF:

$$\begin{aligned}
 N_0(x) &= \mathbb{1}_{[0:1)}(x) && \text{by definition of } N_0(x) \\
 &= \sigma(x) - \sigma(x-1) && \text{by definition of } \sigma(x) \\
 &= \left[\binom{1}{0} \sigma(x) - \binom{1}{1} \sigma(x-1) \right] && \text{by definition of binomial coefficient } \binom{n}{k} \\
 &= \sum_{k=0}^1 (-1)^k \binom{1}{k} (x-k)^0 \sigma(x-k) && \text{by definition of } \sum \text{ operator}
 \end{aligned}$$

Example S.2. ⁴ Let $\sigma(x)$ be the step function. Let $\binom{n}{k}$ be the binomial coefficient.

The 1st order B-spline $N_1(x)$ can be expressed as follows:

$$\boxed{\mathbf{E} \quad X \quad N_1(x) = \begin{cases} x & \text{for } x \in [0 : 1] \\ -x+2 & \text{for } x \in [1 : 2] \\ 0 & \text{otherwise} \end{cases} = \left\{ \sum_{k=0}^2 (-1)^k \binom{2}{k} (x-k) \sigma(x-k) \quad \forall x \in \mathbb{R} \right\}}$$

The B-spline $N_1(x)$ is illustrated in Figure S.1 (page 369).

PROOF:

$$\begin{aligned}
 N_1(x) &= \int_{\tau=0}^{\tau=1} N_0(x-\tau) d\tau && \text{by Lemma S.2 page 367} \\
 &= \int_{\tau=0}^{\tau=1} \sum_{k=0}^1 (-1)^k \binom{1}{k} (x-\tau-k)^0 \sigma(x-\tau-k) d\tau && \text{by Example S.1 page 369} \\
 &= \sum_{k=0}^1 (-1)^k \binom{1}{k} \int_{\tau=0}^{\tau=1} (x-\tau-k)^0 \sigma(x-\tau-k) d\tau && \text{by linearity of } \int d\tau \text{ operator} \\
 &= \sum_{k=0}^1 (-1)^k \binom{1}{k} \frac{1}{0+1} [(x-k)^{0+1} \sigma(x-k) - (x-k-1)^{0+1} \sigma(x-k-1)] && \text{by Lemma S.4 page 369} \\
 &= \begin{pmatrix} 1\{(x-0)\sigma(x-0) - (x-1)\sigma(x-1)\} \\ -1\{(x-1)\sigma(x-1) - (x-2)\sigma(x-2)\} \end{pmatrix} \\
 &= x\sigma(x) - 2(x-1)\sigma(x-1) + (x-2)\sigma(x-2) \\
 &= \sum_{k=0}^2 (-1)^k \binom{2}{k} (x-k) \sigma(x-k) && \text{by def. of } \binom{n}{k} \text{ (Definition ?? page ??)} \\
 &= \begin{cases} x & \text{for } x \in [0 : 1] \\ -x+2 & \text{for } x \in [1 : 2] \\ 0 & \text{otherwise} \end{cases} && \text{by def. of } \sigma(x) \text{ (Definition S.1 page 367)}
 \end{aligned}$$

Example S.3. ⁵ Let $\sigma(x)$ be the step function. Let $\binom{n}{k}$ be the binomial coefficient.

The 2nd order B-spline $N_2(x)$ can be expressed as follows:

$$\boxed{\mathbf{E} \quad X \quad N_2(x) = \frac{1}{2} \begin{cases} x^2 & \text{for } x \in [0 : 1) \\ -2x^2+6x-3 & \text{for } x \in [1 : 2] \\ x^2-6x+9 & \text{for } x \in [2 : 3] \\ 0 & \text{otherwise} \end{cases} = \left\{ \frac{1}{2} \sum_{k=0}^3 (-1)^k \binom{3}{k} (x-k)^2 \sigma(x-k) \quad \forall x \in \mathbb{R} \right\}}$$

The B-spline $N_2(x)$ is illustrated in Figure S.1 (page 369).

⁴  Christensen (2008) page 148 (Exercise 6.2),  Christensen (2010) page 212 (Exercise 10.2),  Heil (2011) pages 142–143 (Definition 4.22 (The Schauder System)),  Schumaker (2007) page 136 (Table 1),  Stoer and Bulirsch (2002) page 124

⁵  Christensen (2008) page 148 (Exercise 6.2),  Christensen (2010) page 212 (Exercise 10.2),  Schumaker (2007) page 136 (Table 1),  Stoer and Bulirsch (2002) page 124



PROOF:

$$\begin{aligned}
 N_2(x) &= \int_{\tau=0}^{\tau=1} N_1(x - \tau) d\tau && \text{by Lemma S.2 page 367} \\
 &= \int_{\tau=0}^{\tau=1} \sum_{k=0}^2 (-1)^k \binom{2}{k} (x - \tau - k) \sigma(x - \tau - k) d\tau && \text{by Example S.2 page 370} \\
 &= \sum_{k=0}^2 (-1)^k \binom{2}{k} \int_{\tau=0}^{\tau=1} (x - \tau - k) \sigma(x - \tau - k) d\tau && \text{by linearity of } \int d\tau \text{ operator} \\
 &= \sum_{k=0}^2 (-1)^k \binom{2}{k} \frac{1}{1+1} [(x - k)^{1+1} \sigma(x - k) - (x - k - 1)^{1+1} \sigma(x - k - 1)] && \text{by Lemma S.4 page 369} \\
 &= \frac{1}{2} \left(\begin{array}{l} 1 \quad \{(x-0)^2 \sigma(x-0) - (x-1)^2 \sigma(x-1)\} \\ -2 \quad \{(x-1)^2 \sigma(x-1) - (x-2)^2 \sigma(x-2)\} \\ +1 \quad \{(x-2)^2 \sigma(x-2) - (x-3)^2 \sigma(x-3)\} \end{array} \right) \\
 &= \frac{1}{2} [x^2 \sigma(x) - 3(x-1)^2 \sigma(x-1) + 3(x-2)^2 \sigma(x-2) - (x-3)^2 \sigma(x-3)] \\
 &= \frac{1}{2} \sum_{k=0}^3 (-1)^k \binom{3}{k} (x-k)^2 \sigma(x-k) && \text{by def. of } \binom{n}{k} \text{ (Definition ?? page ??)} \\
 &= \frac{1}{2} \left\{ \begin{array}{ll} x^2 & \text{for } x \in [0 : 1] \\ -2x^2 + 6x - 3 & \text{for } x \in [1 : 2] \\ x^2 - 6x + 9 & \text{for } x \in [2 : 3] \\ 0 & \text{otherwise} \end{array} \right\} && \text{by def. of } \sigma(x) \text{ (Definition S.1 page 367)}
 \end{aligned}$$

The final steps of this proof can be calculated “by hand” or by using the free and open source software package *Maxima* along with the script file listed in Section ?? (page ??). \Rightarrow

S.2 Algebraic properties

Theorem S.1 (next) presents a closed form expression for an *n*th order B-spline $N_n(x)$ based on the definition of $N_n(x)$ given in Definition S.2 (page 367). Alternatively, Theorem S.1 could serve as the definition and Definition S.2 as a property.

Theorem S.1.⁶ Let $N_n(x)$ be the *n*th ORDER B-SPLINE (Definition S.2 page 367). Let $\sigma(x)$ be the STEP FUNCTION (Definition S.1 page 367).

T H M	$N_n(x) = \frac{1}{n!} \sum_{k=0}^{n+1} (-1)^k \binom{n+1}{k} (x-k)^n \sigma(x-k) \quad \forall n \in \{0, 1, 2, \dots\} = \mathbb{W}$
-------------	--

PROOF: Proof follows by induction:

1. base case (choose one):
 - Proof for $n = 0$ case: by Example S.1 (page 369).
 - Proof for $n = 1$ case: by Example S.2 (page 370).
 - Proof for $n = 2$ case: by Example S.3 (page 370).

⁶ Christensen (2008) page 142 (Theorem 6.1.3), Chui (1992) page 84 ((4.1.12))

2. inductive step—proof that n case $\implies n + 1$ case:

$$\begin{aligned}
 N_{n+1}(x) &= \int_0^1 N_n(x - \tau) d\tau && \text{by Lemma S.2 page 367} \\
 &= \int_0^1 \frac{1}{n!} \sum_{k=0}^{k=n+1} (-1)^k \binom{n+1}{k} (x - \tau - k)^n \sigma(x - \tau - k) d\tau && \text{by induction hypothesis} \\
 &= \frac{1}{n!} \sum_{k=0}^{k=n+1} (-1)^k \binom{n+1}{k} \int_0^1 (x - \tau - k)^n \sigma(x - \tau - k) d\tau && \text{by linearity of } \int d\tau \text{ operator} \\
 &= \frac{1}{n!} \sum_{k=0}^{k=n+1} (-1)^k \binom{n+1}{k} \frac{1}{n+1} [(x - k)^{n+1} \sigma(x - k) - (x - k - 1)^{n+1} \sigma(x - k - 1)] && \text{by Lemma S.4 page 369} \\
 &= \frac{1}{(n+1)!} \sum_{k=0}^{k=n+1} (-1)^k \binom{n+1}{k} [(x - k)^{n+1} \sigma(x - k) - (x - k - 1)^{n+1} \sigma(x - k - 1)] \\
 &= \frac{1}{(n+1)!} \left[\sum_{k=0}^{k=n+1} (-1)^k \binom{n+1}{k} (x - k)^{n+1} \sigma(x - k) - \sum_{k=0}^{k=n+1} (-1)^k \binom{n+1}{k} (x - k - 1)^{n+1} \sigma(x - k - 1) \right] \\
 &= \frac{1}{(n+1)!} \left[\sum_{k=0}^{k=n+1} (-1)^k \binom{n+1}{k} (x - k)^{n+1} \sigma(x - k) - \sum_{m=1}^{m=n+2} (-1)^{m-1} \binom{n+1}{m-1} (x - m)^{n+1} \sigma(x - m) \right]
 \end{aligned}$$

where $m \triangleq k + 1 \implies k = m - 1$

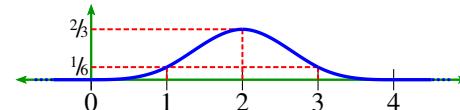
$$\begin{aligned}
 &= \frac{1}{(n+1)!} \left(\sum_{k=0}^{k=n+1} (-1)^k \binom{n+1}{k} (x - k)^{n+1} \sigma(x - k) - \sum_{m=1}^{m=n+2} (-1)^{m-1} \left[\binom{n+2}{m} - \binom{n+1}{m} \right] (x - m)^{n+1} \sigma(x - m) \right) && \text{by Pascal's identity / Stifel formula} \\
 &= \frac{1}{(n+1)!} \left(\sum_{m=1}^{m=n+2} (-1)^m \binom{n+2}{m} (x - m)^{n+1} \sigma(x - m) - \sum_{m=1}^{m=n+2} (-1)^m \binom{n+1}{m} (x - m)^{n+1} \sigma(x - m) + \sum_{k=0}^{k=n+1} (-1)^k \binom{n+1}{k} (x - k)^{n+1} \sigma(x - k) \right) && \text{note } (-1)^{m-1} = -(-1)^m \\
 &= \frac{1}{(n+1)!} \left(\sum_{m=0}^{m=n+2} (-1)^m \binom{n+2}{m} (x - m)^{n+1} \sigma(x - m) - (-1)^0 \binom{n+2}{0} (x - 0)^{n+1} \sigma(x - 0) - \sum_{m=1}^{m=n+1} (-1)^m \binom{n+1}{m} (x - m)^{n+1} \sigma(x - m) - (-1)^{n+2} \binom{n+1}{n+2} (x - n - 2)^{n+1} \sigma(x - n - 2) + \sum_{k=1}^{k=n+1} (-1)^k \binom{n+1}{k} (x - k)^{n+1} \sigma(x - k) + (-1)^0 \binom{n+1}{0} (x - 0)^{n+1} \sigma(x - 0) \right) && \begin{array}{ll} \text{(A)} & \text{desired } n+1 \text{ case} \\ \text{(B)} & \text{cancelled by (F)} \\ \text{(C)} & \text{cancelled by (E)} \\ \text{(D)} & \binom{n+1}{n+2} = 0 \text{ by Proposition ?? page ??} \\ \text{(E)} & \text{cancelled by (C)} \\ \text{(F)} & \binom{n+2}{0} = \binom{n+1}{0} = 1, \text{ so (F) is cancelled by (B)} \end{array} \\
 &= \frac{1}{(n+1)!} \sum_{m=0}^{m=n+2} (-1)^m \binom{n+2}{m} (x - m)^{n+1} \sigma(x - m) && (n+1 \text{ case})
 \end{aligned}$$





Example S.4. ⁷ Let $N_3(x)$ be the 3rd order B-spline (Definition S.2 page 367).⁸

EX
$$N_3(x) = \frac{1}{6} \begin{cases} x^3 & \text{for } 0 \leq x \leq 1 \\ -3x^3 + 12x^2 - 12x + 4 & \text{for } 1 \leq x \leq 2 \\ 3x^3 - 24x^2 + 60x - 44 & \text{for } 2 \leq x \leq 3 \\ -x^3 + 12x^2 - 48x + 64 & \text{for } 3 \leq x \leq 4 \\ 0 & \text{otherwise} \end{cases}$$



PROOF: This expression can be calculated “by hand” using Theorem S.1 (page 371) or by using the free and open source software package *Maxima* along with the script file listed in Section ?? (page ??). \Rightarrow

Example S.5. Let $N_4(x)$ be the 4th order B-spline (Definition S.2 page 367).

EX
$$N_4(x) = \frac{1}{24} \begin{cases} x^4 & \text{for } 0 \leq x \leq 1 \\ -4x^4 + 20x^3 - 30x^2 + 20x - 5 & \text{for } 1 \leq x \leq 2 \\ 6x^4 - 60x^3 + 210x^2 - 300x + 155 & \text{for } 2 \leq x \leq 3 \\ -4x^4 + 60x^3 - 330x^2 + 780x - 655 & \text{for } 3 \leq x \leq 4 \\ x^4 - 20x^3 + 150x^2 - 500x + 625 & \text{for } 4 \leq x \leq 5 \\ 0 & \text{otherwise} \end{cases}$$

PROOF: This expression can be calculated “by hand” using Theorem S.1 (page 371) or by using the free and open source software package *Maxima* along with the script file listed in Section ?? (page ??). \Rightarrow

Example S.6. Let $N_5(x)$ be the 5th order B-spline (Definition S.2 page 367).

EX
$$N_5(x) = \frac{1}{120} \begin{cases} x^5 & \text{for } 0 \leq x \leq 1 \\ -5x^5 + 30x^4 - 60x^3 + 60x^2 - 30x + 6 & \text{for } 1 \leq x \leq 2 \\ 10x^5 - 120x^4 + 540x^3 - 1140x^2 + 1170x - 474 & \text{for } 2 \leq x \leq 3 \\ -10x^5 + 180x^4 - 1260x^3 + 4260x^2 - 6930x + 4386 & \text{for } 3 \leq x \leq 4 \\ 5x^5 - 120x^4 + 1140x^3 - 5340x^2 + 12270x - 10974 & \text{for } 4 \leq x \leq 5 \\ x^5 + 30x^4 - 360x^3 + 2160x^2 - 6480x + 7776 & \text{for } 5 \leq x \leq 6 \\ 0 & \text{otherwise} \end{cases}$$

The 5th order B-spline $N_5(x)$ is illustrated in Figure S.1 (page 369).

PROOF: This expression can be calculated “by hand” using Theorem S.1 (page 371) or by using the free and open source software package *Maxima* along with the script file listed in Section ?? (page ??). \Rightarrow

Example S.7. Let $N_6(x)$ be the 6th order B-spline (Definition S.2 page 367).

EX
$$N_6(x) = \frac{1}{720} \begin{cases} x^6 & \text{for } 0 \leq x \leq 1 \\ -6x^6 + 42x^5 - 105x^4 + 140x^3 - 105x^2 + 42x - 7 & \text{for } 1 \leq x \leq 2 \\ 15x^6 - 210x^5 + 1155x^4 - 3220x^3 + 4935x^2 - 3990x + 1337 & \text{for } 2 \leq x \leq 3 \\ -20x^6 + 420x^5 - 3570x^4 + 15680x^3 - 37590x^2 + 47040x - 24178 & \text{for } 3 \leq x \leq 4 \\ 15x^6 - 420x^5 + 4830x^4 - 29120x^3 + 96810x^2 - 168000x + 119182 & \text{for } 4 \leq x \leq 5 \\ -6x^6 + 210x^5 - 3045x^4 + 23380x^3 - 100065x^2 + 225750x - 208943 & \text{for } 5 \leq x \leq 6 \\ x^6 - 42x^5 + 735x^4 - 6860x^3 + 36015x^2 - 100842x + 117649 & \text{for } 6 \leq x \leq 7 \\ 0 & \text{otherwise} \end{cases}$$

The 6th order B-spline $N_6(x)$ is illustrated in Figure S.1 (page 369).

PROOF: This expression can be calculated “by hand” using Theorem S.1 (page 371) or by using the free and open source software package *Maxima* along with the script file listed in Section ?? (page ??). \Rightarrow

⁷ Schumaker (2007) page 136 (Table 1), Shizgal (2015) page 92 ((2.199)), Szabó and Horváth (2004) page 146 ((4)), Wei and Billings (2006) page 578 (Table 1), Maleknejad et al. (2013) ((9))

⁸For help with plotting B-splines, see APPENDIX T (page 399).

Example S.8. Let $N_7(x)$ be the 7th order B-spline (Definition S.2 page 367).

E X

$$7!N_7(x) = 5040N_7(x) = \begin{cases} x^7 & \text{for } 0 \leq x \leq 1 \\ -7x^7 + 56x^6 - 168x^5 + 280x^4 - 280x^3 + 168x^2 - 56x + 8 & \text{for } 1 \leq x \leq 2 \\ 21x^7 - 336x^6 + 2184x^5 - 7560x^4 + 15400x^3 - 18648x^2 + 12488x - 3576 & \text{for } 2 \leq x \leq 3 \\ -35x^7 + 840x^6 - 8400x^5 + 45360x^4 - 143360x^3 + 267120x^2 - 273280x + 118896 & \text{for } 3 \leq x \leq 4 \\ 35x^7 - 1120x^6 + 15120x^5 - 111440x^4 + 483840x^3 - 1238160x^2 + 1733760x - 1027984 & \text{for } 4 \leq x \leq 5 \\ -21x^7 + 840x^6 - 14280x^5 + 133560x^4 - 741160x^3 + 2436840x^2 - 4391240x + 3347016 & \text{for } 5 \leq x \leq 6 \\ 7x^7 - 336x^6 + 6888x^5 - 78120x^4 + 528920x^3 - 2135448x^2 + 4753336x - 4491192 & \text{for } 6 \leq x \leq 7 \\ -x^7 + 56x^6 - 1344x^5 + 17920x^4 - 143360x^3 + 688128x^2 - 1835008x + 2097152 & \text{for } 7 \leq x \leq 8 \\ 0 & \text{otherwise} \end{cases}$$

The 7th order B-spline $N_7(x)$ is illustrated in Figure S.1 (page 369).

PROOF: This expression can be calculated “by hand” using Theorem S.1 (page 371) or by using the free and open source software package *Maxima* along with the script file listed in Section ?? (page ??). \Rightarrow

*Example S.9.*⁹ The $(n+1)^2$ coefficients of the order $n, n-1, \dots, 0$ monomials of each B-spline $N_n(x)$ multiplied by $n!$ induce an *integer sequence*

$x \triangleq (1, 1, 0, -1, 2, 1, 0, 0, -2, 6, -3, 1, -6, 9, 1, 0, 0, 0, -3, 12, -12, 4, 3, -24, 60, -44, -1, 12, -48, 64, \dots)$ as more fully listed in Table S.1 (page 398). In this sequence $x \triangleq (x_0, x_1, x_2, \dots)$, the coefficients for the order n B-spline $N_n(x)$ begin at the sequence index value

$$p \triangleq \sum_{k=0}^n k^2 = \frac{1}{6}n(n+1)(2n+1) \quad \text{and end at index value } p + (n+1)^2 - 1.$$

For example, the coefficients for $N_3(x)$ begin at index value $p \triangleq 0 + 1 + 4 + 9 = 14$ and end at index value $p + 4^2 - 1 = 29$. Using these coefficients gives the following expression for $N_3(x)$:

$$N_3(x) = \left[\begin{array}{cccc} 1 & 0 & 0 & 0 \\ -3 & 12 & -12 & 4 \\ 3 & -24 & 60 & -44 \\ -1 & 12 & -48 & 64 \end{array} \right] \left[\begin{array}{c} x^3 \\ x^2 \\ x \\ 1 \end{array} \right] = \begin{cases} x^3 & \text{for } 0 \leq x < 1 \\ -3x^3 + 12x^2 - 12x + 4 & \text{for } 1 \leq x < 2 \\ 3x^3 - 24x^2 + 60x - 44 & \text{for } 2 \leq x < 3 \\ -x^3 + 12x^2 - 48x + 64 & \text{for } 3 \leq x < 4 \\ 0 & \text{otherwise} \end{cases}$$

...which agrees with the result presented in Example S.4 (page 373).

PROOF:

1. The coefficients for the sequence x may be computed with assistance from *Maxima* together with the script file listed in Section ?? (page ??).
2. Proof that $\sum_{k=0}^n k^2 = \frac{1}{6}n(n+1)(2n+1)$: The summation is a *power sum*. The relation may be proved using *induction*.¹⁰
 - (a) Base case: $n=0$ case ...

$$\begin{aligned} \sum_{k=0}^{n=0} k^2 &= 0 \\ &= \frac{0(0+1)(2 \cdot 0 + 1)}{6} \\ &= \frac{n(n+1)(2n+1)}{6} \Big|_{n=0} \end{aligned}$$

⁹ Greenhoe (2017b)

¹⁰ Greenhoe (2017a), pages 186–187 (Proposition 11.2 (Power Sums))

(b) Base case: $n=1$ case ...

$$\begin{aligned}\sum_{k=0}^{k=1} k^2 &= 0 + 1 \\ &= \frac{1(1+1)(2 \cdot 1 + 1)}{6} \\ &= \frac{n(n+1)(2n+1)}{6} \Big|_{n=1}\end{aligned}$$

(c) inductive step—proof that n case $\implies n+1$ case:

$$\begin{aligned}\sum_{k=0}^{n+1} k^2 &= \left(\sum_{k=0}^n k^2 \right) + (n+1)^2 \\ &= \left(\frac{n(n+1)(2n+1)}{6} \right) + (n+1)^2 && \text{by } n \text{ case hypothesis} \\ &= (n+1) \left(\frac{n(2n+1) + 6(n+1)}{6} \right) \\ &= (n+1) \left(\frac{2n^2 + 7n + 6}{6} \right) \\ &= (n+1) \left(\frac{(n+2)(2n+3)}{6} \right) \\ &= \frac{(n+1)[(n+1)+1][2(n+1)+1]}{6}\end{aligned}$$



Theorem S.2. ¹¹

T H M	$\frac{d}{dx} N_n(x) = N_{n-1}(x) - N_{n-1}(x-1) \quad \forall n \in \mathbb{N}, \forall x \in \mathbb{R}$
-------------	--

PROOF:

1. Proof using Lemma S.2 (page 367) and the *Fundamental Theorem of Calculus*:

$$\begin{aligned}\frac{d}{dx} N_n(x) &= \frac{d}{dx} \int_0^1 N_{n-1}(x-\tau) d\tau && \text{by Lemma S.2 page 367} \\ &= \frac{d}{dx} \int_{x-u=0}^{x-u=1} N_{n-1}(u)(-1) du && \text{where } u \triangleq x - \tau \implies \tau = x - u \\ &= \frac{d}{dx} \int_{u=x-1}^{u=x} N_{n-1}(u) du \\ &= \left\{ \frac{d}{dx} \int N_{n-1}(u) du \Big|_{u=x} \right\} - \left\{ \frac{d}{dx} \int N_{n-1}(u) du \Big|_{u=x-1} \right\} && \text{by Fundamental Theorem of Calculus}^{12} \\ &= \left\{ N_{n-1}(x) \frac{d}{dx}(x) \right\} - \left\{ N_{n-1}(x-1) \frac{d}{dx}(x-1) \right\} && \text{by Chain Rule}^{13} \\ &= N_{n-1}(x) - N_{n-1}(x-1)\end{aligned}$$

¹¹ Höllig (2003) page 25 (3.2), Schumaker (2007) page 121 (Theorem 4.16)

¹² Hijab (2011) page 163 (Theorem 4.4.3)

¹³ Hijab (2011) pages 73–74 (Theorem 3.1.2)

2. Proof using Lemma S.2 (page 367) and *induction*:

(a) Base case ...proof for $n = 1$ case:

$$\begin{aligned}
 N_0(x) - N_0(x-1) &= \underbrace{\sigma(x) - \sigma(x-1)}_{N_0(x)} - \underbrace{[\sigma(x-1) - \sigma(x-2)]}_{N_0(x-1)} \quad \text{by Example S.1 page 369} \\
 &= \sigma(x) - 2\sigma(x-1) + \sigma(x-2) \\
 &= \sum_{k=0}^2 (-1)^k \binom{2}{k} \sigma(x-k) \\
 &= \frac{d}{dx} \sum_{k=0}^2 (-1)^k \binom{2}{k} (x-k) \sigma(x-k) \\
 &= \frac{d}{dx} N_1(x) \quad \text{by Example S.2 page 370}
 \end{aligned}$$

(b) Base case ...proof for $n = 2$ case:

$$\begin{aligned}
 N_1(x) - N_1(x-1) &= \underbrace{x\sigma(x) - 2(x-1)\sigma(x-1) + (x-2)\sigma(x-2)}_{N_1(x)} \\
 &\quad - \underbrace{[(x-1)\sigma(x-1) - 2(x-2)\sigma(x-2) + (x-3)\sigma(x-3)]}_{N_1(x-1)} \quad \text{by Example S.2 page 370} \\
 &= x\sigma(x) + [-2x + 2 - x + 1]\sigma(x-1) + [x - 2 + 2x - 4]\sigma(x-2) + [-x + 3]\sigma(x-3) \\
 &= x\sigma(x) + [-3x + 3]\sigma(x-1) + [3x - 6]\sigma(x-2) + [-x + 3]\sigma(x-3) \\
 &= \frac{d}{dx} \left\{ \begin{array}{l} \frac{1}{2}x^2\sigma(x) + \left[-\frac{3}{2}x^2 + 3x - \frac{1}{2} \right] \sigma(x-1) + \left[\frac{3}{2}x^2 - 6x + 3 \right] \sigma(x-2) \\ \quad + \left[-\frac{1}{2}x^2 + 3x - \frac{5}{2} \right] \sigma(x-3) \end{array} \right\} \\
 &= \frac{d}{dx} N_2(x) \quad \text{by Example S.3 page 370}
 \end{aligned}$$

(c) Proof that n case $\implies n+1$ case:

$$\begin{aligned}
 \frac{d}{dx} N_{n+1}(x) &= \frac{d}{dx} \int_0^1 N_n(x-\tau) d\tau \quad \text{by Lemma S.2 page 367} \\
 &= \int_0^1 \frac{d}{d\tau} N_n(x-\tau) d\tau \quad \text{by Leibniz Integration Rule (Theorem ?? page ??)} \\
 &= \int_0^1 [N_{n-1}(x-\tau) - N_{n-1}(x-1-\tau)] d\tau \quad \text{by left hypothesis} \\
 &= \int_0^1 N_{n-1}(x-\tau) d\tau - \int_0^1 N_{n-1}(x-1-\tau) d\tau \\
 &= N_n(x) - N_n(x-1) \quad \text{by Lemma S.2 page 367}
 \end{aligned}$$



Theorem S.3 (B-spline recursion). ¹⁴ Let $N_n(x)$ be the n TH ORDER B-SPLINE (Definition S.2 page 367).

T H M	$N_n(x) = \frac{x}{n} N_{n-1}(x) + \frac{n+1-x}{n} N_{n-1}(x-1) \quad \forall n \in \{1, 2, 3, \dots\}, \forall x \in \mathbb{R}$
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¹⁴ Christensen (2008) page 140 (Theorem 6.1.1), Höllig (2003) page 27 (3.4), Schumaker (2007) page 120 (Theorem 4.15), de Boor (2001) page 90 (B-Spline Property (i)), Chui (1988) page 2 (Theorem 1.1), Wojtaszczyk (1997) page 53 (Theorem 3.7), Cox (1972), de Boor (1972)

PROOF:

1. Base case ...proof for $n = 1$ case:

$$\begin{aligned} \frac{x}{1} N_0(x) + \frac{1+1-x}{1} N_0(x-1) &= \underbrace{\frac{x}{1} [\sigma(x) - \sigma(x-1)]}_{N_0(x)} + \underbrace{\frac{1+1-x}{1} [\sigma(x-1) - \sigma(x-2)]}_{N_0(x-1)} \\ &= x\sigma(x) + [-x - x + 2]\sigma(x-1) + [x - 2]\sigma(x-2) \\ &= N_1(x) \quad \text{by Example S.2 page 370} \end{aligned}$$

2. Induction step ...proof that n case $\Rightarrow n+1$ case:

$$\begin{aligned} &\frac{x}{n+1} N_n(x) + \frac{n+2-x}{n+1} N_n(x-1) + c_1 \\ &= \int \frac{d}{dx} \left\{ \frac{x}{n+1} N_n(x) + \frac{n+2-x}{n+1} N_n(x-1) \right\} dx \\ &= \int \underbrace{\frac{1}{n+1} N_n(x) + \frac{x}{n+1} \frac{d}{dx} N_n(x)}_{\frac{d}{dx} \frac{x}{n+1} N_n(x)} + \underbrace{\frac{-1}{n+1} N_n(x-1) + \frac{n+2-x}{n} \frac{d}{dx} N_n(x-1)}_{\frac{d}{dx} \frac{n+2-x}{n+1} N_n(x-1)} dx \\ &\quad \text{by product rule} \\ &= \int \underbrace{\frac{1}{n+1} \left[\frac{x}{n} N_{n-1}(x) + \frac{n+1-x}{n} N_{n-1}(x-1) \right]}_{\text{by } n \text{ hypothesis}} + \underbrace{\frac{x}{n+1} [N_{n-1}(x) - N_{n-1}(x-1)]}_{\text{by Theorem S.2 page 375}} \\ &\quad - \underbrace{\left[\frac{x-1}{n^2+n} N_{n-1}(x-1) + \frac{n-x+2}{n(n+1)} N_{n-1}(x-2) \right]}_{\text{by induction hypothesis}} \\ &\quad + \underbrace{\frac{n+2-x}{n+1} [N_{n-1}(x-1) - N_{n-1}(x-2)]}_{\text{by Theorem S.2 page 375}} dx \\ &= \int \left[\frac{x}{n(n+1)} + \frac{x}{n+1} \right] N_{n-1}(x) + \left[\frac{n-x+1}{n(n+1)} - \frac{x-1}{n(n+1)} + \frac{n+2-2x}{n+1} \right] N_{n-1}(x-1) \\ &\quad + \left[\frac{-n-2+x}{n(n+1)} + \frac{-n-2+x}{n+1} \right] N_{n-1}(x-2) dx \\ &= \int \left[\frac{x+nx}{n(n+1)} \right] N_{n-1}(x) + \left[\frac{n+2-2x+n(n+2-2x)}{n(n+1)} \right] N_{n-1}(x-1) \\ &\quad + \left[\frac{-n-2+x+n(-n-2+x)}{n(n+1)} \right] N_{n-1}(x-2) dx \\ &= \int \left[\frac{x}{n} \right] N_{n-1}(x) + \left[\frac{n+2-2x}{n} \right] N_{n-1}(x-1) + \left[\frac{-n-2+x}{n} \right] N_{n-1}(x-2) dx \\ &= \int \underbrace{\left[\frac{x}{n} \right] N_{n-1}(x)}_{N_n(x)} + \underbrace{\left[\frac{n+1-x}{n} \right] N_{n-1}(x-1)}_{N_{n-1}(x-1)} \\ &\quad - \underbrace{\left[\frac{x-1}{n} \right] N_{n-1}(x-1) - \left[\frac{n+2-x}{n} \right] N_{n-1}(x-2)}_{N_{n-1}(x-1)} dx \\ &= \int N_n(x) - N_n(x-1) dx \quad \text{by } n \text{ hypothesis} \\ &= \int \frac{d}{dx} N_{n+1}(x) dx \quad \text{by Theorem S.2 page 375} \\ &= N_{n+1}(x) + c_2 \end{aligned}$$

Proof that $c_1 = c_2$: By item (2) (page 378), $N_n(x) = 0$ for $x < 0$. Therefore, $c_1 = c_2$.



Theorem S.4 (B-spline general form). ¹⁵ Let $N_n(x)$ be the n TH ORDER B-SPLINE (Definition S.2 page 367). Let supp be the SUPPORT of a function $f \in \mathbb{R}^{\mathbb{R}}$.

T H M	1. $N_n(x) \geq 0 \quad \forall n \in \mathbb{W}, \quad \forall x \in \mathbb{R}$ (NON-NEGATIVE) 2. $\text{supp}N_n(x) = [0 : n + 1] \quad \forall n \in \mathbb{W}$ (CLOSED SUPPORT) 3. $\int_{\mathbb{R}} N_n(x) dx = 1 \quad \forall n \in \mathbb{W}$ (UNIT AREA) 4. $N_n\left(\frac{n+1}{2} - x\right) = N_n\left(\frac{n+1}{2} + x\right) \quad \forall n \in \mathbb{N} \quad \forall x \in \mathbb{R}$ (SYMMETRIC about $x = \frac{n+1}{2}$)
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PROOF:

1. Proof that $N_n(x) \geq 0$ (proof by induction):

(a) base case...proof that $N_0(x) \geq 0$:

$$\begin{aligned} N_0(x) &\triangleq \mathbb{1}_{[0:1]}(x) && \text{by definition of } N_0(x) && (\text{Definition S.2 page 367}) \\ &\geq 0 && \text{by definition of } \mathbb{1}_A(x) && (\text{Definition ?? page ??}) \end{aligned}$$

(b) inductive step—proof that $\{N_n(x) \geq 0\} \implies \{N_{n+1}(x) \geq 0\}$:

$$\begin{aligned} N_{n+1}(x) &= \int_{\tau=0}^{\tau=1} N_n(x - \tau) d\tau && \text{by Lemma S.2 page 367} \\ &\geq 0 && \text{by induction hypothesis } (N_n(x) \geq 0) \end{aligned}$$

2. Proof that $\text{supp}N_n(x) = [0 : n + 1]$ (proof by induction):

(a) Base case ...proof that $\text{supp}N_0 = [0 : 1]$:

$$\begin{aligned} \text{supp}N_0 &\triangleq \text{supp} \mathbb{1}_{[0:1]} && \text{by definition of } N_0(x) && (\text{Definition S.2 page 367}) \\ &= \{[0 : 1]\}^- && \text{by definition of } \text{support} \text{ operator} \\ &= [0 : 1] && \text{by definition of } \text{closure} \text{ operator} \end{aligned}$$

(b) Induction step ...proof that $\{\text{supp}N_n = [0 : n + 1]\} \implies \{\text{supp}N_{n+1} = [0 : n + 2]\}$:

$$\begin{aligned} \text{supp}N_{n+1}(x) &= \text{supp} \int_{\tau=0}^{\tau=1} N_n(x - \tau) d\tau && \text{by Lemma S.2 page 367} \\ &= \text{supp} \int_{[0:1]} N_n(x - \tau) d\tau && \text{by def. of Lebesgue integration} \\ &= \{x \in \mathbb{R} | (x - \tau) \in [0 : n + 1] \text{ for some } \tau \in [0 : 1]\}^- && \text{by induction hypothesis} \\ &= [0 : n + 1] \cup [0 + 1 : n + 1 + 1]^- \\ &= [0 : n + 2]^- \\ &= [0 : n + 2] && \text{by property of } \text{closure} \text{ operator} \end{aligned}$$

3. Proof that $\int_{\mathbb{R}} N_n(x) dx = 1$ (proof by induction):

¹⁵ Christensen (2008) page 140 (Theorem 6.1.1), Höllig (2003) page 27 (3.4), Schumaker (2007) page 120 (Theorem 4.15), de Boor (2001) page 90 (B-Spline Property (i)), Chui (1988) page 2 (Theorem 1.1), Wojtaszczyk (1997) page 53 (Theorem 3.7), Cox (1972), de Boor (1972), Prasad and Iyengar (1997) pages 145–146 (Theorem 6.2)



(a) Base case ...proof that $\int_{\mathbb{R}} N_0(x) dx = 1$:

$$\begin{aligned} \int_{\mathbb{R}} N_0(x) dx &= \int_{\mathbb{R}} \mathbb{1}_{[0:1]} dx && \text{by definition of } N_0(x) && (\text{Definition S.2 page 367}) \\ &= \int_{[0:1)} 1 dx && \text{by definition of } \mathbb{1}_A(x) && (\text{Definition ?? page ??}) \\ &= \int_{[0:1]} 1 dx && \text{by property of Lebesgue integration} \\ &= 1 \end{aligned}$$

(b) Induction step ...proof that $\{\int_{\mathbb{R}} N_n(x) dx = 1\} \implies \{\int_{\mathbb{R}} N_{n+1} dx = 1\}$:

$$\begin{aligned} \int_{\mathbb{R}} N_{n+1}(x) dx &= \int_{\mathbb{R}} \int_0^1 N_n(x - \tau) d\tau dx && \text{by Lemma S.2 page 367} \\ &= \int_0^1 \int_{\mathbb{R}} N_n(x - \tau) dx d\tau \\ &= \int_0^1 \int_{\mathbb{R}} N_n(u) du d\tau && \text{where } u \triangleq x - \tau \implies \tau = x - u \\ &= \int_0^1 1 d\tau && \text{by induction hypothesis} \\ &= 1 \end{aligned}$$

4. Proof that $N_n(x)$ is *symmetric* for $n \in \{1, 2, 3, \dots\}$:

(a) Note that $N_0(x)$ ($n = 0$) is *not symmetric* (in particular it fails at $x = 1/2$) because

$$N_0\left(\frac{0+1}{2} - \frac{1}{2}\right) = N_0(0) = 1 \neq 0 = N_1(1) = N_0\left(\frac{0+1}{2} + \frac{1}{2}\right)$$

(b) Base case ...proof for $n = 1$ case:

$$\begin{aligned} N_1\left(\frac{1+1}{2} - x\right) &= N_1(1-x) \\ &= \begin{cases} (1-x) & \text{for } 1-x \in [0 : 1] \\ -(1-x)+2 & \text{for } 1-x \in [1 : 2] \\ 0 & \text{otherwise} \end{cases} && \text{by Example S.2 page 370} \\ &= \begin{cases} -x+1 & \text{for } -x \in [-1 : 0] \\ x+1 & \text{for } -x \in [0 : 1] \\ 0 & \text{otherwise} \end{cases} \\ &= \begin{cases} x+1 & \text{for } x \in [-1 : 0] \\ -x+1 & \text{for } x \in [0 : 1] \\ 0 & \text{otherwise} \end{cases} \\ &= \begin{cases} (1+x) & \text{for } 1+x \in [0 : 1] \\ -(1+x)+2 & \text{for } 1+x \in [1 : 2] \\ 0 & \text{otherwise} \end{cases} \\ &= N_1(1+x) && \text{by Example S.2 page 370} \\ &= N_1\left(\frac{1+1}{2} + x\right) \end{aligned}$$

(c) Induction step ...proof that $n - 1$ case $\implies n$ case:

$$\begin{aligned}
 & N_n\left(\frac{n+1}{2} + x\right) \\
 &= \frac{\frac{n+1}{2} + x}{n} N_{n-1}\left(\frac{n+1}{2} + x\right) + \frac{n+1 - \left(\frac{n+1}{2} + x\right)}{n} N_{n-1}\left(\frac{n+1}{2} + x - 1\right) \quad \text{by Theorem S.3 page 376} \\
 &= \frac{n+1 - \left(\frac{n+1}{2} - x\right)}{n} N_{n-1}\left(\frac{n}{2} + \left[x + \frac{1}{2}\right]\right) + \frac{\frac{n+1}{2} - x}{n} N_{n-1}\left(\frac{n}{2} + \left[x - \frac{1}{2}\right]\right) \\
 &= \frac{n+1 - \left(\frac{n+1}{2} - x\right)}{n} N_{n-1}\left(\frac{n}{2} - \left[x + \frac{1}{2}\right]\right) + \frac{\frac{n+1}{2} - x}{n} N_{n-1}\left(\frac{n}{2} - \left[x - \frac{1}{2}\right]\right) \quad \text{by induction hypothesis} \\
 &= \frac{n+1 - \left(\frac{n+1}{2} - x\right)}{n} N_{n-1}\left(\left[\frac{n+1}{2} - x\right] - 1\right) + \frac{\frac{n+1}{2} - x}{n} N_{n-1}\left(\frac{n+1}{2} - x\right) \\
 &= N_n\left(\frac{n+1}{2} - x\right) \quad \text{by Theorem S.3 page 376}
 \end{aligned}$$

⇒

S.3 Projection properties

In the case where $(N_n(x - k))_{k \in \mathbb{Z}}$ is to be used as a basis in some subspace of $L^2_{\mathbb{R}}$, one may want to *project* a function $f(x)$ onto a basis function $N_n(x - k)$. This is especially true when $(N_n(x - k))$ is *orthogonal*; but in the case of *B-splines* this is only true when $n = 0$ (Theorem S.8 page 390). Nevertheless, projection of a function onto $N_n(x - k)$, or the projection of $N_n(x)$ onto another basis function (such as the complex exponential in the case of *Fourier analysis* as in Lemma S.5 page 382), is still useful. Projection in an *inner product space* is typically performed using the *inner product* $\langle f(x) | N_n(x - k) \rangle$; and in the space $L^2_{\mathbb{R}}$, this inner product is typically defined as an *integral* such that

$$\langle f(x) | N_n(x - k) \rangle \triangleq \int_{\mathbb{R}} f(x) N_n(x - k) dx.$$

As it turns out, there is a way to compute this inner product that only involves the function $f(x)$ and the order parameter n (next theorem).

Theorem S.5. ¹⁶ Let f be a continuous function in $L^2_{\mathbb{R}}$ and $f^{(n)}$ the n th derivative of $f(x)$.

THEM

$$\begin{aligned}
 (1). \quad \int_{\mathbb{R}} f(x) N_n(x) dx &= \int_{[0:1]^{n+1}} f(x_1 + x_2 + \dots + x_{n+1}) dx_1 dx_2 \dots dx_{n+1} \\
 (2). \quad \int_{\mathbb{R}} f^{(n)}(x) N_n(x) dx &= \sum_{k=0}^{n+1} (-1)^{n-k+1} \binom{n+1}{k} f(k)
 \end{aligned}$$

PROOF:

1. Proof for (1) (proof by induction):

(a) Base case ...proof for $n = 0$ case:

$$\int_{\mathbb{R}} f(x) N_0(x) dx = \int_{[0:1]} f(x) dx \quad \text{by definition of } N_0(x) \quad (\text{Definition S.2 page 367})$$

¹⁶ Chui (1992) page 85 ⟨(4.2.2), (4.2.3)⟩, Christensen (2008) page 140 ⟨Theorem 6.1.1⟩



(b) Inductive step—proof that n case $\implies n + 1$ case:

$$\begin{aligned}
 & \int_{\mathbb{R}} f(x) N_{n+1}(x) dx \\
 &= \int_{\mathbb{R}} \left[\int_0^1 N_n(x - \tau) d\tau \right] f(x) dx && \text{by Lemma S.2 page 367} \\
 &= \int_{[0:1]} \int_{\mathbb{R}} N_n(x - \tau) f(x) dx d\tau \\
 &= \int_{[0:1]} \int_{\mathbb{R}} N_n(u) f(u + \tau) du d\tau && \text{where } u \triangleq x - \tau \implies x = u + \tau \\
 &= \int_{[0:1]} \int_{[0:1]^{n+1}} f(u_1 + u_2 + \dots + u_{n+1} + \tau) du_1 du_2 \dots du_{n+1} d\tau && \text{by induction hypothesis} \\
 &= \int_{[0:1]^{n+2}} f(u_1 + u_2 + \dots + u_{n+1} + u_{n+2}) du_1 du_2 \dots du_{n+2} d\tau \\
 &= \int_{[0:1]^{n+2}} f(x_1 + x_2 + \dots + x_{n+1} + x_{n+2}) dx_1 dx_2 \dots dx_{n+2} && \text{by change of variables } u_k \rightarrow x_k
 \end{aligned}$$

2. Proof for (2):

$$\begin{aligned}
 \int_{\mathbb{R}} f^{(n)}(x) N_n(x) dx &= \int_{[0:1]^{n+1}} f^{(n)} \left(\sum_{k=1}^{n+1} x_k \right) dx_1 dx_2 \dots dx_{n+1} && \text{by (1)} \\
 &= \sum_{k=0}^{n+1} (-1)^{n-k+1} \binom{n+1}{k} f(k) && \text{by Theorem ?? page ??}
 \end{aligned}$$

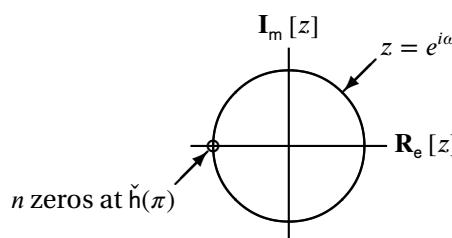


Figure S.2: Zero locations for B-cardinal spline $N_n(x)$ scaling coefficients

S.4 Fourier analysis

Simply put, no matter what new and fancy basis sequences are discovered, the *Fourier transform* never goes out of style. This is largely because the *kernel* of the Fourier transform—the *complex exponential* function—has two properties that makes it extremely special:

- ➊ The complex exponential is an eigenvalue of any *linear time invariant* (LTI) operator (Theorem ?? page ??).
- ➋ The complex exponential generates a *continuous point spectrum* for the *differential operator*.

Thus, we might expect the projection of the *B-spline* function $N_n(x)$ onto the complex exponential (essentially the *Fourier transform* of $N_n(x)$,...next lemma) to be useful. Such a hunch would be confirmed because it is useful for proving that

- ☞ the sequence $(N_n(x - k))_{k \in \mathbb{Z}}$ is a *Riesz basis* (Lemma S.6 page 385, Theorem S.8 page 390) and
- ☞ the sequence $(N_n(x - k))_{k \in \mathbb{Z}}$ is a *multiresolution analysis* (Theorem S.10 page 393).

Lemma S.5. ¹⁷ Let $\tilde{\mathbf{F}}$ be the FOURIER TRANSFORM operator (Definition P.2 page 333).

$$\boxed{\text{LEM}} \quad \tilde{\mathbf{F}} N_n(\omega) = \frac{1}{\sqrt{2\pi}} \left(\frac{1 - e^{-i\omega}}{i\omega} \right)^{n+1} = \frac{1}{\sqrt{2\pi}} e^{-i\frac{(n+1)\omega}{2}} \left(\frac{\sin(\omega/2)}{\omega/2} \right)^{n+1} \triangleq \frac{1}{\sqrt{2\pi}} e^{-i\frac{(n+1)\omega}{2}} \left(\text{sinc} \frac{\omega}{2} \right)^{n+1}$$

☞ PROOF:

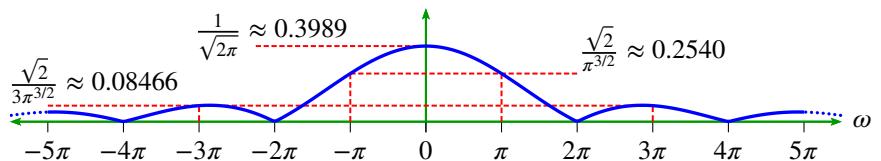
1. Proof using Theorem S.5 page 380:

$$\begin{aligned} \tilde{\mathbf{F}} N_n(\omega) &= \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} N_n(x) e^{-i\omega x} dx && \text{by definition of } \tilde{\mathbf{F}} \quad (\text{Definition P.2 page 333}) \\ &= \frac{1}{\sqrt{2\pi}} \int_{[0:1]^{n+1}} e^{-i\omega(x_1+x_2+\dots+x_{n+1})} dx_1 dx_2 \dots dx_{n+1} && \text{by Theorem S.5} \\ &= \frac{1}{\sqrt{2\pi}} \prod_{k=1}^{n+1} \left(\int_{[0:1]} e^{-i\omega x_k} dx_k \right) && \text{because } e^{x+y} = e^x e^y \\ &= \frac{1}{\sqrt{2\pi}} \left(\int_0^1 e^{-i\omega x} dx \right)^{n+1} = \frac{1}{\sqrt{2\pi}} \left(\left. \frac{e^{-i\omega x}}{-i\omega} \right|_0^1 \right)^{n+1} \\ &= \frac{1}{\sqrt{2\pi}} \left(\frac{1 - e^{-i\omega}}{i\omega} \right)^{n+1} = \frac{1}{\sqrt{2\pi}} \left[e^{-i\frac{\omega}{2}} \left(\frac{e^{i\frac{\omega}{2}} - e^{-i\frac{\omega}{2}}}{i\omega} \right) \right]^{n+1} \\ &= \frac{1}{\sqrt{2\pi}} \left[e^{-i\frac{\omega}{2}} \left(\frac{2i \sin\left(\frac{\omega}{2}\right)}{\frac{2i\omega}{2}} \right) \right]^{n+1} && \text{by Euler formulas} \quad (\text{Corollary ?? page ??}) \\ &= \frac{1}{\sqrt{2\pi}} e^{-i\frac{(n+1)\omega}{2}} \left(\frac{\sin(\omega/2)}{\omega/2} \right)^{n+1} \end{aligned}$$

2. Proof using *rectangular pulse* example (Example P.1 page 340) and *Convolution Theorem* (Theorem R.2 page 356):

$$\begin{aligned} \tilde{\mathbf{F}} N_n(\omega) &= \left[\sqrt{2\pi} \right]^n [\tilde{\mathbf{F}} N_0]^{n+1} && \text{by Convolution Theorem} \quad (\text{Theorem R.2 page 356}) \\ &= \frac{1}{\sqrt{2\pi}} \left[\sqrt{2\pi} \frac{c(b-a)}{\sqrt{2\pi}} e^{-i\left(\frac{a+b}{2}\omega\right)} \left(\frac{\sin\left(\frac{b-a}{2}\omega\right)}{\left(\frac{b-a}{2}\omega\right)} \right) \right]^{n+1} && \text{by rectangular pulse example} \\ &= \frac{1}{\sqrt{2\pi}} \left[\sqrt{2\pi} \frac{1}{\sqrt{2\pi}} e^{-i\left(\frac{\omega}{2}\right)} \left(\frac{\sin\left(\frac{\omega}{2}\right)}{(\omega/2)} \right) \right]^{n+1} && \text{with } a = 0, b = c = 1 \quad (\text{Example P.1 page 340}) \\ &= \frac{1}{\sqrt{2\pi}} e^{-i\left(\frac{(n+1)\omega}{2}\right)} \left(\frac{\sin\left(\frac{\omega}{2}\right)}{(\omega/2)} \right)^{n+1} \end{aligned}$$

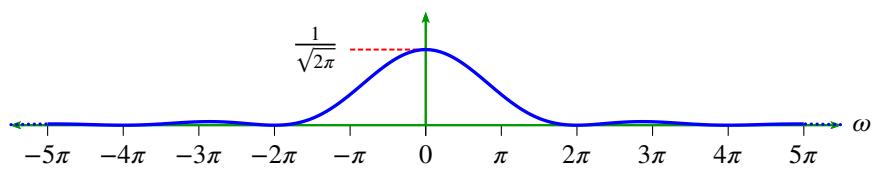
Example S.10. The Fourier transform magnitude $|\tilde{\mathbf{F}} N_0](\omega)|$ of the 0 order B-spline $N_0(x)$ is illustrated to the right.



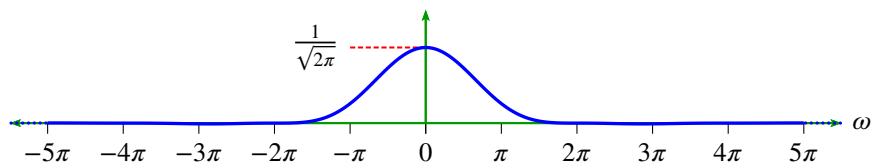
¹⁷ ☝ Christensen (2008) page 142 (Corollary 6.1.2)



Example S.11. The Fourier transform magnitude $|[\tilde{F}N_1](\omega)|$ of the 1st order B-spline $N_1(x)$ is illustrated to the right.



Example S.12. The Fourier transform magnitude $|[\tilde{F}N_2](\omega)|$ of the 2nd order B-spline $N_2(x)$ is illustrated to the right.



S.5 Basis properties

S.5.1 Uniqueness properties

Coefficients of a *basis sequence* are not always *unique*. Take for example a very trivial sequence (α_1, α_2) in which the coefficients are summed. If $f(x) \triangleq \alpha_1 + \alpha_2$ and $g(x) \triangleq \beta_1 + \beta_2$,

$$\begin{aligned} \text{then } \{(\alpha_1, \alpha_2) = (\beta_1, \beta_2)\} &\implies f(x) = g(x) \\ \text{but } f(x) = g(x) &\implies \{(\alpha_1, \alpha_2) = (\beta_1, \beta_2)\}, \end{aligned}$$

because for example if $(\alpha_1, \alpha_2) = (1, 2)$ and $(\beta_1, \beta_2) = (-6, 9)$, then $f(x) = g(x)$, but $(\alpha_1, \alpha_2) \neq (\beta_1, \beta_2)$. This example demonstrates that the “if and only if” condition \iff does not hold and coefficients are not unique in all *basis sequences*. But arguably a minimal requirement for any practical basis sequence is that the coefficients are *unique* (the “if and only if” condition \iff holds). And indeed, in a *B-spline* basis sequence $(N_n(x - k))_{k \in \mathbb{Z}}$, the coefficients $(\alpha_k)_{k \in \mathbb{Z}}$ are *unique*, as demonstrated by Theorem S.6 (next).

Theorem S.6. ¹⁸ Let $N_n(x)$ be the *n*TH-ORDER B-SPLINE (Definition S.2 page 367). Let

$$f(x) \triangleq \sum_{k \in \mathbb{Z}} \alpha_k N_n(x - k) \quad \text{and} \quad g(x) \triangleq \sum_{k \in \mathbb{Z}} \beta_k N_n(x - k).$$

T H M	$\{ f(x) = g(x) \quad \forall x \in \mathbb{R} \} \iff \{ (\alpha_k)_{k \in \mathbb{Z}} = (\beta_k)_{k \in \mathbb{Z}} \}$
coefficients are UNIQUE	

PROOF:

1. Proof that \iff condition holds:

$$\begin{aligned} f(x) &\triangleq \sum_{k \in \mathbb{Z}} \alpha_k N_n(x - k) && \text{by definition of } f(x) \\ &= \sum_{k \in \mathbb{Z}} \beta_k N_n(x - k) && \text{by right hypothesis} \\ &\triangleq g(x) && \text{by definition of } g(x) \end{aligned}$$

2. Proof that \implies condition holds (proof by contradiction):

(a) Suppose it does *not* hold.

¹⁸ Wojtaszczyk (1997) page 55 (Theorem 3.11)

- (b) Then there exists sequences $(\alpha_k)_{k \in \mathbb{Z}}$ and $(\beta_k)_{k \in \mathbb{Z}}$ such that
 $(\alpha_k) - (\beta_k) \triangleq (\alpha_k - \beta_k) \neq (0, 0, 0, \dots)$
but also such that $f(x) - g(x) = 0 \forall x \in \mathbb{R}$.

- (c) If this were possible, then

$$\begin{aligned} 0 &= f(x) - g(x) \\ &= \sum_{m \in \mathbb{Z}} \alpha_m N_n(x-m) - \sum_{m \in \mathbb{Z}} \beta_m N_n(x-m) \\ &= \sum_{m \in \mathbb{Z}} (\alpha_m - \beta_m) N_n(x-m) \\ &= \sum_{m=0}^{m=n} (\alpha_m - \beta_m) \frac{1}{n!} \left[\sum_{k=0}^{n+1} (-1)^k \binom{n+1}{k} (x-k)^n \sigma(x-k) \right] \end{aligned} \quad \text{by Theorem S.1 page 371}$$

- (d) But this is *impossible* because $N(x)$ is *non-negative* (Theorem S.4 page 378).
(e) Therefore, there is a contradiction, and the \Rightarrow condition *does* hold.

⇒

S.5.2 Partition of unity properties

In the case in which a sequence of *B-splines* $(N_n(x-k))_{k \in \mathbb{Z}}$ is to be used as a *basis* for some subspace of $L^2_{\mathbb{R}}$, arguably one of the most important properties for the sequence to have is the *partition of unity* property such that $\sum_{k \in \mathbb{Z}} N_n(x-k) = 1$. This allows for convenient representation of the most basic functions, such as constants.¹⁹ As it turns out, B-splines *do* have this property (next theorem).

Theorem S.7 (B-spline partition of unity). ²⁰ Let $N_n(x)$ be the *n*TH ORDER B-SPLINE (Definition S.2 page 367).

THEOREM	$\sum_{k \in \mathbb{Z}} N_n(x-k) = 1 \quad \forall n \in \mathbb{W}$	(PARTITION OF UNITY)
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PROOF:

1. lemma: $\sum_{k \in \mathbb{Z}} N_0(x-k) = 1$. Proof:

$$\begin{aligned} \sum_{k \in \mathbb{Z}} N_0(x-k) &= \sum_{k \in \mathbb{Z}} \mathbb{1}_{[0:1]}(x-k) && \text{by definition of } N_0(x) && \text{(Definition S.2 page 367)} \\ &= 1 && \text{by definition of } \mathbb{1}_A(x) && \text{(Definition ?? page ??)} \end{aligned}$$

2. Proof for this theorem follows from the $n = 0$ case ((1) lemma page 384), the definition of $N_n(x)$ (Definition S.2 page 367), and Corollary ?? (page ??).

3. Alternatively, this theorem can be proved by *induction*:

- (a) Base case ($n = 0$ case): by (1) lemma.

¹⁹  Jawerth and Sweldens (1994) page 8

²⁰  Christensen (2008) page 140 (Theorem 6.1.1),  Höllig (2003) page 27 (3.4),  Schumaker (2007) page 120 (Theorem 4.15),  de Boor (2001) page 90 (B-Spline Property (i)),  Chui (1988) page 2 (Theorem 1.1),  Wojtaszczyk (1997) page 53 (Theorem 3.7),  Cox (1972),  de Boor (1972)

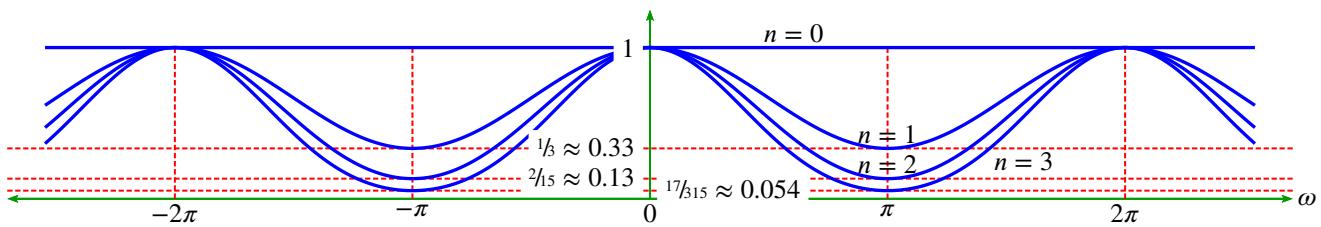


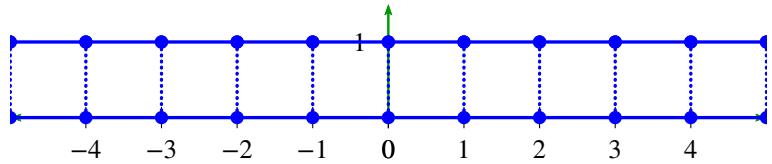
Figure S.3: *auto-power spectrum* $\tilde{S}_n(\omega)$ plots of *B-splines* $N_n(x)$ (Lemma S.6 page 385) For C and L^AT_EX source code to generate such a plot, see Section ?? (page ??).

(b) Inductive step—proof that $\sum_{k \in \mathbb{Z}} N_n(x - k) = 1 \implies \sum_{k \in \mathbb{Z}} N_{n+1}(x - k) = 1$:

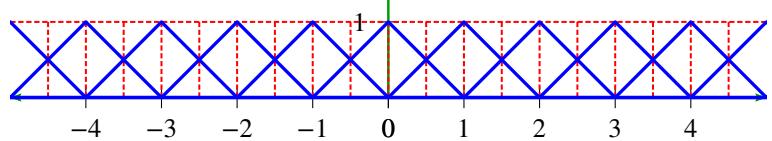
$$\begin{aligned}
 \sum_{k \in \mathbb{Z}} N_{n+1}(x - k) &= \sum_{k \in \mathbb{Z}} \int_{\tau=0}^{\tau=1} N_n(x - k - \tau) d\tau && \text{by Lemma S.2 page 367} \\
 &= \sum_{k \in \mathbb{Z}} \int_{x-u=0}^{x-u=1} N_n(u - k)(-1) du && \text{where } u \triangleq x - \tau \implies \tau = x - u \\
 &= \sum_{k \in \mathbb{Z}} \int_{u=x-1}^{u=x} N_n(u - k) du \\
 &= \int_{u=x-1}^{u=x} \left(\sum_{k \in \mathbb{Z}} N_n(u - k) \right) du \\
 &= \int_{u=x-1}^{u=x} 1 du && \text{by induction hypothesis} \\
 &= 1
 \end{aligned}$$



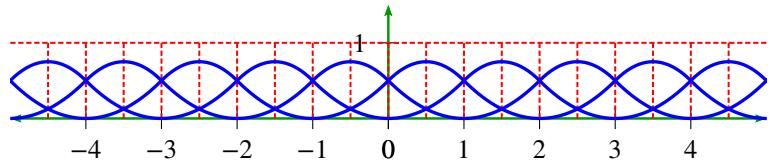
Example S.13. The *partition of unity* property for the *0 order B-spline* $N_0(x)$ (Example S.1 page 369) is illustrated to the right.



Example S.14. The *partition of unity* property for the *1st order B-spline* $N_1(x)$ (Example S.2 page 370) is illustrated to the right.



Example S.15. The *partition of unity* property for the *2nd order B-spline* $N_2(x)$ (Example S.3 page 370) is illustrated to the right.



S.5.3 Riesz basis properties

Lemma S.6. Let $N_n(x)$ be the *n*th ORDER B-SPLINE (Definition S.2 page 367).

Let $\tilde{S}_n(\omega) \triangleq 2\pi \sum_{k \in \mathbb{Z}} |\tilde{F}N_n(\omega - 2\pi k)|^2$ be the AUTO-POWER SPECTRUM (Definition ?? page ??) of $N_n(x)$.

LEM	(1). $0 < \tilde{S}_n(\omega) \leq 1 \quad \forall \omega \in \mathbb{R} \quad , \quad \forall n \in \mathbb{W}$ (2). $\tilde{S}_n(\omega) = 1 \quad \forall \omega \in \mathbb{R} \quad , \quad \text{for } n = 0$	(3). $\tilde{S}_n(0) = 1 \quad \forall n \in \mathbb{W}$ (4). $\tilde{S}_n(\pi) \leq \frac{1}{3} \quad \forall n \in \mathbb{W} \setminus \{0\}$	(Note: see illustration in Figure S.3 page 385.)
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PROOF:

1. lemma: $\tilde{S}_n(\omega) = \sum_{k \in \mathbb{Z}} \left[\frac{\sin\left(\frac{\omega}{2}\right)}{k\pi - \frac{\omega}{2}} \right]^{2(n+1)}$. Proof:

$$\begin{aligned}
 \tilde{S}_n(\omega) &\triangleq 2\pi \sum_{k \in \mathbb{Z}} |\tilde{\mathbf{F}}\mathbf{N}_n(\omega - 2\pi k)|^2 && \text{by Definition ?? page ??} \\
 &= 2\pi \sum_{k \in \mathbb{Z}} \left| \frac{1}{\sqrt{2\pi}} e^{-i\frac{(n+1)(\omega-2\pi k)}{2}} \left(\frac{\sin\left(\frac{\omega-2\pi k}{2}\right)}{\frac{\omega-2\pi k}{2}} \right)^{n+1} \right|^2 && \text{by Lemma S.5 page 382} \\
 &= \sum_{k \in \mathbb{Z}} \left[\frac{\sin\left(\frac{\omega-2\pi k}{2}\right)}{\frac{\omega-2\pi k}{2}} \right]^{2(n+1)} \\
 &= \sum_{k \in \mathbb{Z}} \left[\frac{\sin\left(\frac{\omega}{2} - k\pi\right)}{k\pi - \frac{\omega}{2}} \right]^{2(n+1)} \\
 &= \sum_{k \in \mathbb{Z}} \left[\frac{(-1)^k \sin\left(\frac{\omega}{2}\right)}{k\pi - \frac{\omega}{2}} \right]^{2(n+1)} \\
 &= \sum_{k \in \mathbb{Z}} \left[\frac{\sin\left(\frac{\omega}{2}\right)}{k\pi - \frac{\omega}{2}} \right]^{2(n+1)}
 \end{aligned}$$

2. lemma (one sided series form):

$$\begin{aligned}
 \tilde{S}_n(\omega) &= \sum_{k \in \mathbb{Z}} \left[\frac{\sin\left(\frac{\omega}{2}\right)}{k\pi - \frac{\omega}{2}} \right]^{2(n+1)} && \text{by (1) lemma} \\
 &= \left[\frac{\sin(\omega/2)}{(\omega/2)} \right]^{2(n+1)} + \left[\frac{\sin(\omega/2)}{(\pi/2)} \right]^{2(n+1)} \left(\sum_{k=1}^{\infty} \left[\frac{1}{2k - \frac{\omega}{\pi}} \right]^{2(n+1)} + \sum_{k=1}^{\infty} \left[\frac{1}{2k + \frac{\omega}{\pi}} \right]^{2(n+1)} \right)
 \end{aligned}$$

3. lemma: $\tilde{S}_n(\omega)$ is *continuous* for all $\omega \in \mathbb{R}$.

Proof: $\sin(\omega/2)$ and $\omega/2$ are *continuous*, so $\tilde{S}_n(\omega)$ is *continuous* as well.

4. lemma: $\tilde{S}_n(\omega)$ is *periodic* with period 2π (and so we only need to examine $\tilde{S}_n(\omega)$ for $\omega \in [0 : 2\pi]$). Proof of *periodicity*: This follows directly from Proposition ?? (page ??).

5. lemma: $\tilde{S}_n(-\omega) = \tilde{S}_n(\omega)$ (*symmetric* about 0) and $\tilde{S}_n(\pi - \omega) = \tilde{S}_n(\pi + \omega)$ (*symmetric* about π). Proof: This follows directly from Proposition ?? (page ??).



6. Proof that $\tilde{S}_n(0) = 1$:

$$\begin{aligned}
 \tilde{S}_n(0) &= \lim_{\omega \rightarrow 0} \tilde{S}_n(\omega) && \text{by (3) lemma} \\
 &= \lim_{\omega \rightarrow 0} \left[\left[\frac{\sin(\omega/2)}{(\omega/2)} \right]^{2(n+1)} + \left[\frac{\sin(\omega/2)}{(\pi/2)} \right]^{2(n+1)} \left(\sum_{k=1}^{\infty} \left[\frac{1}{2k - \frac{\omega}{\pi}} \right]^{2(n+1)} + \sum_{k=1}^{\infty} \left[\frac{1}{2k + \frac{\omega}{\pi}} \right]^{2(n+1)} \right) \right] && \text{by (2) lemma} \\
 &= \lim_{\omega \rightarrow 0} \left[\frac{\cos\left(\frac{\omega}{2}\right)}{-\frac{1}{2}} \right]^{2(n+1)} + 0 && \text{by l'Hôpital's rule} \\
 &= (-1)^{2(n+1)} = 1
 \end{aligned}$$

7. Proof that $\tilde{S}_n(\pi)$ converges to some value > 0 :

(a) Proof that $\tilde{S}_n(\pi) > 0$:

$$\begin{aligned}
 \tilde{S}_n(\pi) &= \left[\frac{\sin(\pi/2)}{(\pi/2)} \right]^{2(n+1)} + \left[\frac{\sin(\pi/2)}{(\pi/2)} \right]^{2(n+1)} \left(\sum_{k=1}^{\infty} \left[\frac{1}{2k - \frac{\pi}{\pi}} \right]^{2(n+1)} + \sum_{k=1}^{\infty} \left[\frac{1}{2k + \frac{\pi}{\pi}} \right]^{2(n+1)} \right) && \text{by (2) lemma} \\
 &= \left(\frac{2}{\pi} \right)^{2(n+1)} \left[1 + \left(\frac{1}{1} \right)^{2(n+1)} + \left(\frac{1}{3} \right)^{2(n+1)} + \left(\frac{1}{3} \right)^{2(n+1)} + \left(\frac{1}{5} \right)^{2(n+1)} + \left(\frac{1}{5} \right)^{2(n+1)} + \dots \right] \\
 &= 2 \left(\frac{2}{\pi} \right)^{2(n+1)} \underbrace{\sum_{k=1}^{\infty} \left[\frac{1}{2k-1} \right]^{2(n+1)}}_{\text{Dirichlet Lambda function } \lambda(2n+2)} \\
 &> 0 && \text{because } x^2 > 0 \text{ for all } x \in \mathbb{R} \setminus \{0\}
 \end{aligned}$$

(b) Proof that $\tilde{S}_n(\pi)$ converges:

$$\begin{aligned}
 \tilde{S}_n(\pi) &= 2 \left(\frac{2}{\pi} \right)^{2(n+1)} \sum_{k=1}^{\infty} \left(\frac{1}{2k-1} \right)^{2(n+1)} && \text{by item (7a)} \\
 &\leq 2 \left(\frac{2}{\pi} \right)^{2(n+1)} \sum_{k=1}^{\infty} \left(\frac{1}{k} \right)^{2(n+1)} \\
 &\leq 2 \left(\frac{2}{\pi} \right)^{2(n+1)} \sum_{k=1}^{\infty} \left(\frac{1}{k} \right)^2 \\
 &\implies \text{convergence} && \text{by comparison test}
 \end{aligned}$$

(c) Tighter bounds for $\tilde{S}_n(\pi)$ for certain values of $n \in \{0, 1, 2, 3, 4\}$:

$$\begin{aligned}
 \tilde{S}_n(\pi) &= 2 \left(\frac{2}{\pi} \right)^{2(n+1)} \sum_{k=1}^{\infty} \left(\frac{1}{2k-1} \right)^{2(n+1)} && \text{by item (7a)} \\
 &= 2 \left(\frac{2}{\pi} \right)^{2(n+1)} U_{2(n+1)} && \text{by } \text{Jolley (1961), pages 56–57 ((307))} \\
 &= 2 \left(\frac{2}{\pi} \right)^{2(n+1)} \left[\frac{\pi^{2(n+1)} \alpha_{n+1}}{(4)[(2n+2)!]} \right] && \text{by } \text{Jolley (1961), pages 56–57 ((307))} \\
 &= \frac{2^{2n+1} \alpha_{n+1}}{(2n+2)!}
 \end{aligned}$$

$$\begin{aligned}
 &= \left\{ \begin{array}{ll} \frac{2^1(1)}{2!} & \text{for } n = 0 \quad (\alpha_1 = 1) \\ \frac{2^2(1)}{4!} & \text{for } n = 1 \quad (\alpha_2 = 1) \\ \frac{2^5(3)}{6!} & \text{for } n = 2 \quad (\alpha_3 = 3) \\ \frac{2^7(17)}{8!} & \text{for } n = 3 \quad (\alpha_4 = 17) \\ \frac{2^9(155)}{10!} & \text{for } n = 4 \quad (\alpha_5 = 155) \end{array} \right\} \quad \text{by } \text{Jolley (1961), page 234 (1130)} \\
 &= \left\{ \begin{array}{ll} 1 & \text{for } n = 0 \\ \frac{1}{3} & \text{for } n = 1 \\ \frac{2}{15} & \text{for } n = 2 \\ \frac{17}{315} & \text{for } n = 3 \\ \frac{62}{2835} & \text{for } n = 4 \end{array} \right\} = \left\{ \begin{array}{ll} 1 & \text{for } n = 0 \\ 0.3333333333333333 \dots & \text{for } n = 1 \\ 0.1333333333333333 \dots & \text{for } n = 2 \\ 0.0539682539682 \dots & \text{for } n = 3 \\ 0.0218694885361 \dots & \text{for } n = 4 \end{array} \right\}
 \end{aligned}$$

(d) Being important for the $n = 0$ case, note that²¹

$$\underbrace{\sum_{k=1}^{\infty} \left(\frac{1}{2k-1} \right)^2}_{\text{Dirichlet Lambda function } \lambda(2)} = 1 + \frac{1}{3^2} + \frac{1}{5^2} + \frac{1}{7^2} + \dots = \frac{\pi^2}{8}$$

(e) Proof that $\tilde{S}_n(\pi) \leq \frac{1}{3}$: because $\tilde{S}_n(\pi) = \frac{1}{3}$ for $n = 1$ (item (7c) page 387) and because $\tilde{S}_n(\pi)$ is decreasing for increasing n .

8. lemma: $\tilde{S}_n(\omega)$ converges to some value $> 0 \forall \omega \in \mathbb{R}$. Proof:

(a) For $\omega = 0$, $\tilde{S}_n(\omega) = 1$ by item (6).

(b) Proof that $\tilde{S}_n(\omega) > 0$ for $\omega \in (0 : 2\pi)$:

$$\begin{aligned}
 \tilde{S}_n(\omega) &= \left[\frac{\sin(\omega/2)}{(\omega/2)} \right]^{2(n+1)} + \left[\frac{\sin(\omega/2)}{(\pi/2)} \right]^{2(n+1)} \left(\sum_{k=1}^{\infty} \left[\frac{1}{2k - \frac{\omega}{\pi}} \right]^{2(n+1)} + \sum_{k=1}^{\infty} \left[\frac{1}{2k + \frac{\omega}{\pi}} \right]^{2(n+1)} \right) \quad \text{by (2) lemma} \\
 &> 0
 \end{aligned}$$

(c) Proof that $\tilde{S}_n(\omega)$ converges:

$$\begin{aligned}
 \text{i. lemma: } \sum_{k=1}^{\infty} \left[\frac{1}{2k \pm \frac{\omega}{\pi}} \right]^{2(n+1)} \text{ converges. Proof:} \\
 \lim_{b \rightarrow \infty} \int_1^b \left[\frac{1}{2y \pm \frac{\omega}{\pi}} \right]^{2(n+1)} dy &= \lim_{b \rightarrow \infty} \int_1^b \left[2y \pm \frac{\omega}{\pi} \right]^{-2n-2} dy \\
 &= \lim_{b \rightarrow \infty} \frac{\left[2y \pm \frac{\omega}{\pi} \right]^{-2n-1}}{2(-2n-1)} \Big|_1^b \\
 &= \lim_{b \rightarrow \infty} \left(\frac{-1}{2(2n+1)} \right) \left[\frac{1}{\left[2b \pm \frac{\omega}{\pi} \right]^{2n+1}} - \frac{1}{\left[2 \pm \frac{\omega}{\pi} \right]^{2n+1}} \right] \\
 &= 0 + \frac{1}{2(2n+1) \left[2 \pm \frac{\omega}{\pi} \right]^{2n+1}} \\
 &< \infty \quad \forall \omega \in [0 : 2\pi] \\
 \Rightarrow \sum_{k=1}^{\infty} \left[\frac{1}{2k \pm \frac{\omega}{\pi}} \right]^{2(n+1)} \text{ converges} &\quad \text{by integral test}
 \end{aligned}$$

²¹ [Nahin \(2011\) page 153](#), [Bailey et al. \(2013\) page 334](#) (Catalan's Constant), [Bailey et al. \(2011\) \(15\)](#), [Wells \(1987\) page 36](#) (Dictionary entry for π : pages 31–37), [Heinbockel \(2010\) page 94](#) ((2.27) Dirichlet Lambda function)

ii. completion of proof using (8(c)i) lemma ...

$$\begin{aligned}\tilde{S}_n(\omega) &= \left[\frac{\sin(\omega/2)}{(\omega/2)} \right]^{2(n+1)} + \left[\frac{\sin(\omega/2)}{(\pi/2)} \right]^{2(n+1)} \left(\sum_{k=1}^{\infty} \left[\frac{1}{2k - \frac{\omega}{\pi}} \right]^{2(n+1)} + \sum_{k=1}^{\infty} \left[\frac{1}{2k + \frac{\omega}{\pi}} \right]^{2(n+1)} \right) \text{ by (2) lemma} \\ &\implies \tilde{S}_n(\omega) \text{ converges } \forall \omega \in (0 : 2\pi) \quad \text{by (8(c)i) lemma}\end{aligned}$$

9. lemma (an expression for $\tilde{S}'_n(\omega)$):

$$\begin{aligned}\tilde{S}'_n(\omega) &\triangleq \frac{d}{d\omega} \tilde{S}_n(\omega) \\ &= \frac{d}{d\omega} \sum_{k \in \mathbb{Z}} \left[\frac{\sin\left(\frac{\omega}{2}\right)}{k\pi - \frac{\omega}{2}} \right]^{2(n+1)} \text{ by (1) lemma page 386} \\ &= \sum_{k \in \mathbb{Z}} \frac{d}{d\omega} \left[\frac{\sin\left(\frac{\omega}{2}\right)}{k\pi - \frac{\omega}{2}} \right]^{2(n+1)} \text{ by linearity of } \frac{d}{d\omega} \text{ operator} \\ &= \sum_{k \in \mathbb{Z}} 2(n+1) \left[\frac{\sin\left(\frac{\omega}{2}\right)}{k\pi - \frac{\omega}{2}} \right]^{2n+1} \frac{d}{d\omega} \left[\frac{\sin\left(\frac{\omega}{2}\right)}{k\pi - \frac{\omega}{2}} \right] \text{ by power rule} \\ &= 2(n+1) \sum_{k \in \mathbb{Z}} \left[\frac{\sin\left(\frac{\omega}{2}\right)}{k\pi - \frac{\omega}{2}} \right]^{2n+1} \left[\frac{\frac{1}{2} \cos\left(\frac{\omega}{2}\right) \left(k\pi - \frac{\omega}{2}\right) - \sin\left(\frac{\omega}{2}\right) \left(-\frac{1}{2}\right)}{\left(k\pi - \frac{\omega}{2}\right)^2} \right] \text{ by quotient rule} \\ &= (n+1) \sum_{k \in \mathbb{Z}} \left[\frac{\sin\left(\frac{\omega}{2}\right)}{k\pi - \frac{\omega}{2}} \right]^{2n+1} \left[\frac{\cos\left(\frac{\omega}{2}\right) \left(k\pi - \frac{\omega}{2}\right) + \sin\left(\frac{\omega}{2}\right)}{\left(k\pi - \frac{\omega}{2}\right)^2} \right]\end{aligned}$$

10. lemma: $\tilde{S}'_n(0) = \tilde{S}'_n(\pi) = 0$. Proof: This follows from Proposition ?? (page ??). Here is alternate proof:

$$\begin{aligned}\tilde{S}'_n(0) &= \lim_{\omega \rightarrow 0} \tilde{S}'_n(\omega) \\ &= \lim_{\omega \rightarrow 0} (n+1) \sum_{k \in \mathbb{Z}} \left[\frac{\sin\left(\frac{\omega}{2}\right)}{k\pi - \frac{\omega}{2}} \right]^{2n+1} \left[\frac{\cos\left(\frac{\omega}{2}\right) \left(k\pi - \frac{\omega}{2}\right) + \sin\left(\frac{\omega}{2}\right)}{\left(k\pi - \frac{\omega}{2}\right)^2} \right] \text{ by (9) lemma} \\ &= \lim_{\omega \rightarrow 0} (n+1) \left[\frac{\sin\left(\frac{\omega}{2}\right)}{-\frac{\omega}{2}} \right]^{2n+1} \left[\frac{\cos\left(\frac{\omega}{2}\right) \left(-\frac{\omega}{2}\right) + \sin\left(\frac{\omega}{2}\right)}{\left(-\frac{\omega}{2}\right)^2} \right] \\ &= (n+1) \lim_{\omega \rightarrow 0} \left[\frac{\sin\left(\frac{\omega}{2}\right)}{-\frac{\omega}{2}} \right]^{2n+1} \lim_{\omega \rightarrow 0} \left[\frac{\cos\left(\frac{\omega}{2}\right) \left(-\frac{\omega}{2}\right) + \sin\left(\frac{\omega}{2}\right)}{\left(-\frac{\omega}{2}\right)^2} \right] \\ &= (n+1) [-1]^{2n+1} \lim_{\omega \rightarrow 0} \left[\frac{-\frac{1}{2} \sin\left(\frac{\omega}{2}\right) \left(-\frac{\omega}{2}\right) + \cos\left(\frac{\omega}{2}\right) \left(-\frac{1}{2}\right) + \cos\left(\frac{\omega}{2}\right) \left(\frac{1}{2}\right)}{-\frac{2}{2} \left(-\frac{\omega}{2}\right)} \right] \text{ by l'Hôpital's rule} \\ &= (1)(0) \\ &= 0\end{aligned}$$

$$\begin{aligned}
\tilde{S}'_n(\pi) &= (n+1) \sum_{k \in \mathbb{Z}} \left[\frac{\sin\left(\frac{\pi}{2}\right)}{k\pi - \frac{\pi}{2}} \right]^{2n+1} \left[\frac{\cos\left(\frac{\pi}{2}\right)\left(k\pi - \frac{\pi}{2}\right) + \sin\left(\frac{\pi}{2}\right)}{\left(k\pi - \frac{\pi}{2}\right)^2} \right] \\
&= (n+1) \sum_{k \in \mathbb{Z}} \left[\frac{1}{k\pi - \frac{\pi}{2}} \right]^{2n+1} \left[\frac{0\left(k\pi - \frac{\pi}{2}\right) + 1}{\left(k\pi - \frac{\pi}{2}\right)^2} \right] \\
&= (n+1) \left(\frac{2}{\pi} \right)^{2n+3} \sum_{k \in \mathbb{Z}} \left[\frac{1}{2k-1} \right]^{2n+3} \\
&= (n+1) \left(\frac{2}{\pi} \right)^{2n+3} \left[\left(\frac{1}{1} \right)^{2n+3} + \left(\frac{1}{-1} \right)^{2n+3} + \left(\frac{1}{3} \right)^{2n+3} + \left(\frac{1}{-3} \right)^{2n+3} + \dots \right] \\
&= (n+1) \left(\frac{2}{\pi} \right)^{2n+3} \sum_{k=1}^{\infty} (-1)^{k+1} \alpha_k \quad \text{where } \alpha_k \triangleq \begin{cases} \left(\frac{1}{k} \right)^{2n+3} & \text{for } k \text{ odd} \\ \left(\frac{1}{k-1} \right)^{2n+3} & \text{for } k \text{ even} \end{cases} \\
&= 0 \quad \text{because } \lim_{k \rightarrow \infty} \alpha_k = 0 \text{ and by Alternating Series Test}
\end{aligned}$$

11. lemma: $\tilde{S}_n(\omega)$ is *decreasing* with respect to $\omega \in [0 : \pi]$. Proof:

$$\begin{aligned}
\tilde{S}'_n(\omega) &= (n+1) \sum_{k \in \mathbb{Z}} \left[\frac{\sin\left(\frac{\omega}{2}\right)}{k\pi - \frac{\omega}{2}} \right]^{2n+1} \left[\frac{\cos\left(\frac{\omega}{2}\right)\left(k\pi - \frac{\omega}{2}\right) + \sin\left(\frac{\omega}{2}\right)}{\left(k\pi - \frac{\omega}{2}\right)^2} \right] \quad \text{by (9) lemma page 389} \\
&= (n+1) \underbrace{\left(\sin \frac{\omega}{2} \right)^{2n+1}}_{\geq 0 \text{ for } \omega \in [0 : 2\pi]} \sum_{k \in \mathbb{Z}} \underbrace{\left[\frac{1}{k\pi - \frac{\omega}{2}} \right]^{2n+2}}_{> 0} \left[\underbrace{\left(\cos \frac{\omega}{2} \right)}_{\text{sign change at } \omega = \pi} + \underbrace{\frac{\sin \frac{\omega}{2}}{k\pi - \frac{\omega}{2}}}_{\substack{\text{decreasing w.r.t. } \omega \in \mathbb{R} \\ > 0 \text{ for } \omega \in (0 : 2\pi)}} \right]
\end{aligned}$$

12. lemma: $\tilde{S}_n(\omega)$ is *increasing* with respect to $\omega \in [\pi : 2\pi]$. Proof: This is true because $\tilde{S}_n(\omega)$ is *decreasing* in $[0 : \pi]$ ((11) lemma) and because $\tilde{S}_n(\omega)$ is *symmetric* about $\omega = \pi$ ((5) lemma).

13. Proof that $0 < \tilde{S}_n(\omega) \leq 1$:

- (a) $\tilde{S}_n(\omega) > 0$ by (8) lemma and
- (b) $\tilde{S}_n(0) = 1$ by item (6) and
- (c) $\tilde{S}_n(\omega)$ is *decreasing* from $\omega = 0$ to $\omega = \pi$ by (11) lemma and
- (d) $\tilde{S}_n(\omega)$ is *increasing* from $\omega = \pi$ to $\omega = 2\pi$ by (12) lemma and
- (e) $\tilde{S}_n(2\pi) = 1$ because $\tilde{S}_n(2\pi) = \tilde{S}_n(0)$ by (4) lemma.



Theorem S.8. ²²

T H M	1. $(N_n(x-k))_{k \in \mathbb{Z}}$ is a RIESZ BASIS	<i>for</i> $\text{span}(N_n(x-k))_{k \in \mathbb{Z}}$	$\forall n \in \mathbb{W}$
	2. $(N_n(x-k))_{k \in \mathbb{Z}}$ is an ORTHONORMAL BASIS	<i>for</i> $\text{span}(N_n(x-k))_{k \in \mathbb{Z}}$	$\iff n = 0$

PROOF:

²² Wojaszczyk (1997) page 56 (Proposition 3.12), Prasad and Iyengar (1997) page 148 (Theorem 6.3), Forster and Massopust (2009) page 66 (Theorem 2.25)



1. Proof that $(N_n(x - k))_{k \in \mathbb{Z}}$ is a *Riesz basis* for $\text{span}(N_n(x - k))_{k \in \mathbb{Z}}$:

$$\begin{aligned} 0 < \tilde{S}_n(\omega) &\leq 1 && \text{by Lemma S.6 page 385 (1)} \\ \implies (N_n(x - k))_{k \in \mathbb{Z}} &\text{ is a } Riesz \text{ basis for } \text{span}(N_n(x - k))_{k \in \mathbb{Z}} && \text{by Theorem ?? page ??} \end{aligned}$$

2. Proof that $\{n = 0\} \iff (N_n(x - k))_{k \in \mathbb{Z}}$ is an *orthonormal basis* for $\text{span}(N_n(x - k))_{k \in \mathbb{Z}}$:

$$\begin{aligned} n = 0 \iff \tilde{S}_n(\omega) &= 1 && \text{by Lemma S.6 page 385 (2), (4)} \\ \iff (N_n(x - k))_{k \in \mathbb{Z}} &\text{ is an orthonormal basis for } \text{span}(N_n(x - k)) && \text{by Theorem ?? page ??} \end{aligned}$$



S.6 Mutiresolution properties

S.6.1 Introduction

In 1989, Stéphane G. Mallat introduced the *Mutiresolution Analysis* (MRA) structure (Definition ?? page ??). An MRA is very powerful because it can be used to approximate functions at incrementally increasing “scales” of resolution, and furthermore induces a *wavelet*. In fact, the MRA has become the dominate wavelet construction method. Moreover, P.G. Lemarié has proved that all wavelets with *compact support* are generated by an MRA.²³

S.6.2 B-spline dyadic decomposition

One key feature of an MRA is *dyadic decomposition* such that $N_n(x) = \sum_k \alpha_n N_n(2x - k)$ for some sequence (α_n) . As it turns out, *B-splines* also have this property (next theorem).

Theorem S.9 (*B-spline dyadic decomposition*).²⁴ Let $N_n(x)$ be the n th ORDER B-SPLINE.

T H M	$N_n(x) = \frac{1}{2^n} \sum_{k=0}^{n+1} \binom{n+1}{k} N_n(2x - k) \quad \forall n \in \mathbb{W}, \forall x \in \mathbb{R}$
-------------	---

PROOF:

1. Base case ...proof for $n = 0$ case:

$$\begin{aligned} N_0(x) &= \mathbb{1}_{[0:1]}(x) && \text{by definition of } \mathbb{1}_A(x) \quad (\text{Definition ?? page ??}) \\ &= \mathbb{1}_{[0:\frac{1}{2}]}(x) + \mathbb{1}_{[\frac{1}{2}:1]}(x) \\ &= \mathbb{1}_{[2x:2x+\frac{1}{2}]}(2x) + \mathbb{1}_{[2x+\frac{1}{2}:2x+1]}(2x - 1) \\ &= \mathbb{1}_{[0:1]}(2x) + \mathbb{1}_{[0:1]}(2x - 1) \\ &= \frac{1}{2^0} \sum_{k=0}^{0+1} \binom{0+1}{k} N_0(2x - k) \end{aligned}$$

²³ Mallat (1999) page 240, Definition ?? (page ??)

²⁴ Prasad and Iyengar (1997) pages 151–152 (proof using Fourier transform)

2. Induction step...proof that n case $\implies n + 1$ case:

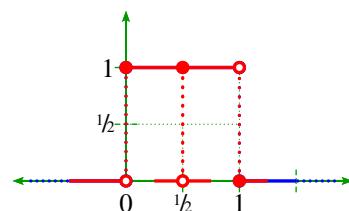
$$\begin{aligned}
 N_{n+1}(x) &= \int_0^1 N_n(x - \tau) d\tau && \text{by Lemma S.2 page 367} \\
 &= \int_0^1 \frac{1}{2^n} \sum_{k=0}^{n+1} \binom{n+1}{k} N_n(2x - 2\tau - k) d\tau && \text{by induction hypothesis} \\
 &= \frac{1}{2^n} \sum_{k=0}^{n+1} \binom{n+1}{k} \int_{\tau=0}^{\tau=1} N_n(2x - 2\tau - k) d\tau && \text{by linearity of } \sum \text{ operator} \\
 &= \frac{1}{2^n} \sum_{k=0}^{n+1} \binom{n+1}{k} \int_{u=0}^{u=2} N_n(2x - u - k) \frac{1}{2} du && \text{where } u \triangleq 2\tau \implies \tau = \frac{1}{2}u \\
 &= \frac{1}{2^{n+1}} \sum_{k=0}^{n+1} \binom{n+1}{k} \left[\int_{u=0}^{u=1} N_n(2x - k - u) du + \int_{u=1}^{u=2} N_n(2x - k - u) du \right] \\
 &= \frac{1}{2^{n+1}} \sum_{k=0}^{n+1} \binom{n+1}{k} \left[\int_{u=0}^{u=1} N_n(2x - k - u) du + \int_{v=0}^{v=1} N_n(2x - k - v - 1) dv \right] && \text{where } v \triangleq u - 1 \implies u = v + 1 \\
 &= \frac{1}{2^{n+1}} \sum_{k=0}^{n+1} \binom{n+1}{k} [N_n(2x - k) + N_n(2x - k - 1)] && \text{by Lemma S.2 page 367} \\
 &= \frac{1}{2^{n+1}} \left[\sum_{k=0}^{n+1} \binom{n+1}{k} N_n(2x - k) + \sum_{m=1}^{n+2} \binom{n+1}{m-1} N_n(2x - m) \right] && \text{where } m \triangleq k + 1 \implies k = m - 1 \\
 &= \frac{1}{2^{n+1}} \left[\underbrace{\sum_{k=1}^{n+1} \left[\binom{n+1}{k} + \binom{n+1}{k-1} \right] N_n(2x - k)}_{\text{common indices of above two summations}} + \underbrace{\binom{n+1}{0} N_n(2x - 0)}_{k=0 \text{ term}} + \underbrace{\binom{n+2}{n+2} N_n(2x - n - 2)}_{m=n+2 \text{ term}} \right] \\
 &= \frac{1}{2^{n+1}} \left[\underbrace{\sum_{k=1}^{n+1} \binom{n+2}{k} N_n(2x - k)}_{\text{by Stifel formula (Theorem ?? page ??)}} + \underbrace{\binom{n+2}{0} N_n(2x - 0)}_{\text{because } \binom{n+1}{0} = 1 = \binom{n+2}{0}} + \underbrace{\binom{n+2}{n+2} N_n(2x - n - 2)}_{\text{ }} \right] \\
 &= \frac{1}{2^{n+1}} \sum_{k=0}^{n+2} \binom{n+2}{k} N_n(2x - k)
 \end{aligned}$$

⇒

Example S.16. ²⁵The 0 order B-spline dyadic decomposition

$$N_0(x) = \frac{1}{1} \sum_{k=0}^{k=1} \binom{1}{k} N_0(2x - k)$$

is illustrated to the right.

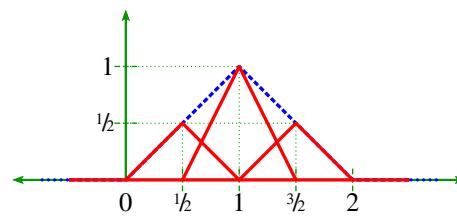


²⁵ Strang (1989) page 615 (Box function), Strang and Nguyen (1996) page 441 (Box function)

Example S.17. ²⁶The 1st order B-spline dyadic decomposition

$$N_1(x) = \frac{1}{2} \sum_{k=0}^{k=2} \binom{2}{k} N_1(2x - k)$$

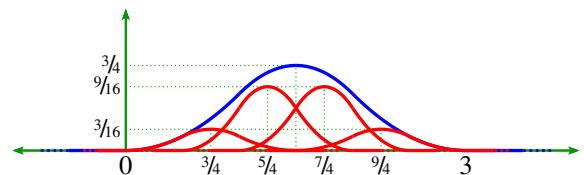
is illustrated to the right.



Example S.18. The 2nd order B-spline dyadic decomposition

$$N_2(x) = \frac{1}{4} \sum_{k=0}^{k=3} \binom{3}{k} N_2(2x - k)$$

is illustrated to the right.



S.6.3 B-spline MRA scaling functions

Theorem S.10. Let $f N_n(x)$ be the n TH ORDER B-SPLINE (Definition S.2 page 367).

Let $V_j \triangleq \text{span}(\{N_n(2^j x - k)\}_{k \in \mathbb{Z}})$.

T H M $(V_j)_{j \in \mathbb{Z}}$ is a MULTIRESOLUTION ANALYSIS on $L^2_{\mathbb{R}}$ with SCALING FUNCTION $\phi(x) \triangleq N_n(x)$

PROOF:

1. lemma: $(N_n(x - k))_{k \in \mathbb{Z}}$ is a *Riesz sequence*. Proof: by Theorem S.8 (page 390).

2. lemma: $\exists (h_k) \text{ such that } N_n(x) = \sum_{k \in \mathbb{Z}} h_k N_n(2x - k)$. Proof: by Theorem S.9 (page 391). In fact, note that $h_k = \frac{1}{2^n \sqrt{2}} \binom{n+1}{k}$

3. lemma: $\tilde{F}N_n(\omega)$ is *continuous* at 0. Proof:

$$\tilde{F}N_n(\omega) = \frac{1}{\sqrt{2\pi}} e^{-i\frac{(n+1)\omega}{2}} \left(\text{sinc} \frac{\omega}{2} \right)^{n+1} \quad \text{by Lemma S.5 page 382}$$

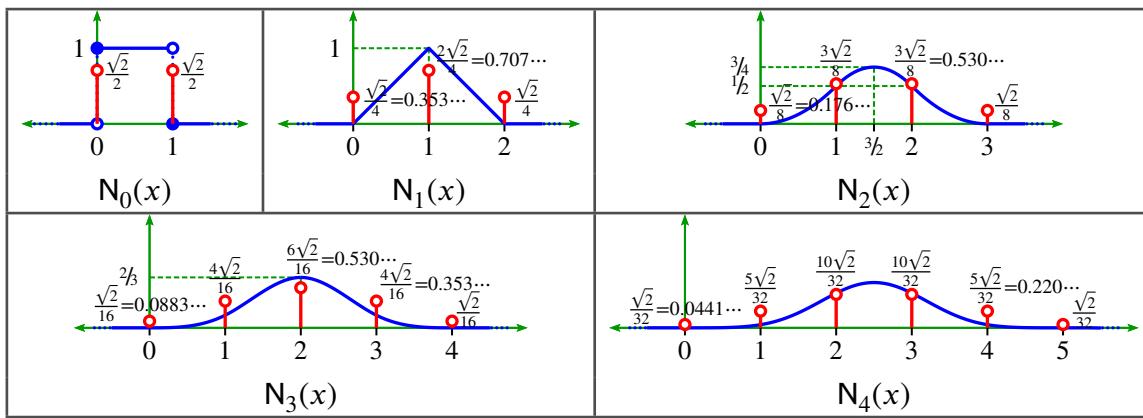
\implies continuous at 0 by known property of sinc function

4. lemma: $\tilde{\phi}(0) \neq 0$. Proof:

$$\begin{aligned} \tilde{F}N_n(0) &= \frac{1}{\sqrt{2\pi}} e^{-i\frac{(n+1)\omega}{2}} \left(\text{sinc} \frac{\omega}{2} \right)^{n+1} \Big|_{\omega=0} && \text{by Lemma S.5 page 382} \\ &= 1 \cdot \frac{1}{1/2} = 2 && \text{by } l'Hôpital's \text{ rule} \\ &\neq 0 \end{aligned}$$

5. The completion of this proof follows directly from (1) lemma, (2) lemma, (3) lemma, (4) lemma, and Theorem ?? (page ??).

²⁶ Strang (1989) page 615 (Hat function), Strang and Nguyen (1996) page 442 (Hat function), Heil (2011) page 380 (Fig. 12.10)

Figure S.4: *dilation equation* demonstrations for selected B-splines (Example S.19 page 394)

S.6.4 B-spline MRA coefficient sequences

Because each *B-spline* $N_n(x)$ is the *scaling function* for an *MRA* (Theorem S.10 page 393), each *B-spline* also satisfies the *dilation equation* (Theorem ?? page ??) such that

$$N_n(x) = \sqrt{2} \sum_{k \in \mathbb{Z}} h_k N(2x - k) \quad \text{where} \quad h_k = \begin{cases} \frac{\sqrt{2}}{2^{n+1}} \binom{n+1}{k} & \text{for } n = 0, 1, \dots, n \\ 0 & \text{otherwise} \end{cases}$$

The resulting sequence $(h_k)_{k \in \mathbb{Z}}$ is the *ordern B-spline MRA coefficient sequence* induced by the *order n B-spline MRA scaling sequence* $\phi(x) \triangleq N_n(x)$.²⁷

Example S.19. See Figure S.4 (page 394) for some *dilation equation* demonstrations of selected B-splines.

Theorem S.11 (*B-spline scaling coefficients*). *Let $(L^2_{\mathbb{R}}, (\mathcal{V}_j), \phi, (h_n))$ be an MRA SYSTEM (Definition ?? page ??). Let $N_n(x)$ be a nTH ORDER B- SPLINE (Definition S.2 page 367).*

T H M	$\underbrace{\phi(x) \triangleq N_n(x)}_{(1) \text{ B-spline scaling function}} \implies (h_k) = \begin{cases} \frac{\sqrt{2}}{2^{n+1}} \binom{n}{k} & \text{for } k = 0, 1, \dots, n \\ 0 & \text{otherwise} \end{cases} \quad (2) \text{ scaling sequence in "time"}$ $\iff \check{h}(z) \Big _{z \triangleq e^{i\omega}} = \frac{\sqrt{2}}{2^n} (1 + z^{-1})^{n+1} \Big _{z \triangleq e^{i\omega}} \quad (3) \text{ scaling sequence in "z domain"}$ $\iff \check{h}(\omega) = 2\sqrt{2} e^{-i\frac{n+1}{2}\omega} \left[\cos\left(\frac{\omega}{2}\right) \right] \quad (4) \text{ scaling sequence in "frequency"}$
-------------	--

PROOF:

1. Proof that (1) \implies (3): By Theorem S.10 page 393 we know that $N_n(x)$ is a *scaling function* (Definition ?? page ??). So then we know that we can use Lemma ?? page ??.

$$\begin{aligned}
 \check{h}(\omega) &= \sqrt{2} \frac{\tilde{\phi}(2\omega)}{\tilde{\phi}(\omega)} && \text{by Lemma ?? page ??} \\
 &= \sqrt{2} \frac{\tilde{N}_n(2\omega)}{\tilde{N}_n(\omega)} && \text{by (1)} \\
 &= \sqrt{2} \frac{\frac{1}{\sqrt{2\pi}} \left(\frac{1-e^{-i2\omega}}{2i\omega} \right)^{n+1}}{\frac{1}{\sqrt{2\pi}} \left(\frac{1-e^{-i\omega}}{i\omega} \right)^{n+1}} && \text{by Lemma S.5 page 382}
 \end{aligned}$$

²⁷For Octave/ MatLab code useful for plotting a function given a sequence of coefficients (h_k) , see Section ?? (page ??).

$$\begin{aligned}
&= \frac{\sqrt{2}}{2^{n+1}} \left(\frac{1 - z^{-2}}{1 - z^{-1}} \right)^{n+1} \Big|_{z=e^{i\omega}} \\
&= \frac{\sqrt{2}}{2^{n+1}} \left[\left(\frac{1 - z^{-2}}{1 - z^{-1}} \right) \left(\frac{1 + z^{-1}}{1 + z^{-1}} \right) \right]^{n+1} \Big|_{z=e^{i\omega}} \\
&= \frac{\sqrt{2}}{2^{n+1}} \left(\frac{(1 - z^{-2})(1 + z^{-1})}{1 - z^{-2}} \right)^{n+1} \Big|_{z=e^{i\omega}} \\
&= \frac{\sqrt{2}}{2^n} (1 + z^{-1})^{n+1} \Big|_{z=e^{i\omega}}
\end{aligned}$$

2. Proof that (3) \iff (2):

$$\begin{aligned}
\check{h}(z) \Big|_{z=e^{i\omega}} &= \frac{\sqrt{2}}{2^n} (1 + z^{-1})^{n+1} \Big|_{z=e^{i\omega}} && \text{by (3)} \\
&= \frac{\sqrt{2}}{2^n} \left(\sum_{k=0}^{n+1} \binom{n}{k} z^{-k} \right) \Big|_{z=e^{i\omega}} && \text{by binomial theorem} \\
\iff h_k &= \frac{\sqrt{2}}{2^{n+1}} \binom{n}{k} && \text{by definition of } Z \text{ transform (Definition R.4 page 354)}
\end{aligned}$$

3. Proof that (3) \implies (4):

$$\begin{aligned}
\tilde{h}(\omega) &= \check{h}(z) \Big|_{z=e^{i\omega}} && \text{by definition of DTFT (Definition Q.1 page 343)} \\
&= \frac{\sqrt{2}}{2^n} (1 + z^{-1})^{n+1} \Big|_{z=e^{i\omega}} && \text{by (3)} \\
&= \frac{\sqrt{2}}{2^n} (1 + e^{-i\omega})^{n+1} && \text{by definition of } z \\
&= \frac{\sqrt{2}}{2^n} \left[e^{-i\frac{1}{2}\omega} \left(e^{i\frac{\omega}{2}} + e^{-i\frac{\omega}{2}} \right) \right]^{n+1} \\
&= \frac{\sqrt{2}}{2^n} e^{-i\frac{n+1}{2}\omega} \left[2\cos\left(\frac{\omega}{2}\right) \right]^{n+1} \\
&= 2\sqrt{2} e^{-i\frac{n+1}{2}\omega} \left[\cos\left(\frac{\omega}{2}\right) \right]^{n+1}
\end{aligned}$$

4. Proof that (3) \iff (4):

$$\begin{aligned}
\check{h}(z) \Big|_{z=e^{i\omega}} &= \check{h}(e^{i\omega}) \\
&= \tilde{h}(\omega) \\
&= 2\sqrt{2} e^{-i\frac{n+1}{2}\omega} \left[\cos\left(\frac{\omega}{2}\right) \right]^{n+1} && \text{by (4)} \\
&= \frac{\sqrt{2}}{2^n} e^{-i\frac{n+1}{2}\omega} \left[2\cos\left(\frac{\omega}{2}\right) \right]^{n+1} \\
&= \frac{\sqrt{2}}{2^n} \left[e^{-i\frac{1}{2}\omega} \left(e^{i\frac{\omega}{2}} + e^{-i\frac{\omega}{2}} \right) \right]^{n+1} \\
&= \frac{\sqrt{2}}{2^n} (1 + e^{-i\omega})^{n+1} \\
&= \frac{\sqrt{2}}{2^n} (1 + z^{-1})^{n+1} \Big|_{z=e^{i\omega}}
\end{aligned}$$



Example S.20 (2 coefficient case). ²⁸ Let $(L^2_{\mathbb{R}}, (\mathcal{V}_j), \phi, (h_n))$ be an MRA system (Definition ?? page ??).

E x	$\left\{ \begin{array}{l} 1. \text{ supp}\phi(x) = [0 : 1] \quad \text{and} \\ 2. (\phi(x - k)) \text{ forms a} \\ \text{partition of unity} \end{array} \right\} \iff h_n = \left\{ \begin{array}{ll} \frac{\sqrt{2}}{2} & \text{for } n = 0 \\ \frac{\sqrt{2}}{2} & \text{for } n = 1 \\ 0 & \text{otherwise} \end{array} \right\} \iff \underbrace{\{\phi(x) = N_0(x)\}}_{(C)}$
----------------------	--

PROOF:

1. Proof that (A) \implies (B):

- (a) lemma: Only h_0 and h_1 are *non-zero*; All other coefficients h_k are 0. Proof: This follows from $\text{supp}\phi(x) = [0 : 1]$ (Definition ?? page ??) and by Theorem ?? page ??.
- (b) lemma (equations for (h_k)): Because (h_k) is a *scaling coefficient sequence* (Definition ?? page ??), it must satisfy the *admissibility equation* (Theorem ?? page ??). And because $(\phi(x - k))$ forms a *partition of unity*, it must satisfy the equations given by Theorem ?? (page ??). (1a) lemma and these two constraints yield two simultaneous equations and two unknowns:

$$\begin{aligned} h_0 + h_1 &= \sqrt{2} && \text{(admissibility condition)} \\ h_0 - h_1 &= 0 && \text{(partition of unity/zero at -1/vanishing 0th moment)} \end{aligned}$$

- (c) lemma: The equations provided by (1b) lemma can be expressed in matrix algebra form as follows...

$$\underbrace{\begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}}_A \begin{bmatrix} h_0 \\ h_1 \end{bmatrix} = \begin{bmatrix} \sqrt{2} \\ 0 \end{bmatrix}$$

- (d) lemma: The *inverse A⁻¹* of A can be expressed as demonstrated below...

$$\begin{aligned} \left[\begin{array}{cc|cc} 1 & 1 & 1 & 0 \\ 1 & -1 & 0 & 1 \end{array} \right] &\rightarrow \left[\begin{array}{cc|cc} 2 & 0 & 1 & 1 \\ 1 & -1 & 0 & 1 \end{array} \right] \rightarrow \left[\begin{array}{cc|cc} 2 & 0 & 1 & 1 \\ 0 & -1 & -\frac{1}{2} & \frac{1}{2} \end{array} \right] \rightarrow \left[\begin{array}{cc|cc} 1 & 0 & \frac{1}{2} & \frac{1}{2} \\ 0 & 1 & \frac{1}{2} & -\frac{1}{2} \end{array} \right] \\ \implies A^{-1} &= \frac{1}{2} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \end{aligned}$$

- (e) Proof for the values of (h_k) (B):

$$\begin{aligned} \begin{bmatrix} h_0 \\ h_1 \end{bmatrix} &= A^{-1} A \begin{bmatrix} h_0 \\ h_1 \end{bmatrix} = A^{-1} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} h_0 \\ h_1 \end{bmatrix} && \text{by (1c) lemma} \\ &= A^{-1} \begin{bmatrix} \sqrt{2} \\ 0 \end{bmatrix} && \text{by (1c) lemma} \\ &= \frac{1}{2} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} \sqrt{2} \\ 0 \end{bmatrix} && \text{by (1d) lemma} \\ &= \frac{\sqrt{2}}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix} \end{aligned}$$

²⁸ Haar (1910), Wojtaszczyk (1997) pages 14–15 (“Sources and comments”)

2. Proof that (B) \implies (C):

$$\begin{aligned}
 (B) \implies \phi(x) &= \sum_{k \in \mathbb{Z}} h_k \sqrt{2} \phi(2x - k) && \text{dilation equation} \\
 &= \sum_{k=0}^{k=1} \left(\frac{\sqrt{2}}{2} \right) \sqrt{2} \phi(2x - k) && \text{by item (1e) page 396} \\
 &= \sum_{k=0}^{k=1} \phi(2x - k) \\
 &= \sum_{k=0}^{k=1} \binom{1}{k} \phi(2x - k) && \text{by definition of } \binom{n}{k} \\
 \implies (D) && \text{by } B\text{-spline dyadic decomposition} & \text{(Theorem S.9 page 391)}
 \end{aligned}$$

3. Proof that (B) \Leftarrow (C):

$$\begin{aligned}
 (C) \implies N_0(x) &= \sum_{k=0}^{k=1} \binom{1}{k} N_0(2x - k) && \text{by } B\text{-spline dyadic decomposition} & \text{(Theorem S.9 page 391)} \\
 &= \sum_{k=0}^{k=1} \left(\frac{\sqrt{2}}{2} \right) \sqrt{2} N_0(2x - k) && \text{by definition of } \binom{n}{k} & \text{(Definition ?? page ??)} \\
 &= \sum_{k \in \mathbb{Z}} h_k \sqrt{2} N_0(2x - k) && \text{by definition of } \binom{n}{k} & \text{(Definition ?? page ??)} \\
 \implies (B) &
 \end{aligned}$$

4. Proof that (A) \Leftarrow (C):

1. Proof that (C) $\implies \text{supp } \phi(x) = [0 : 1]$: by Theorem S.4 (page 378)
2. Proof that (C) $\implies (\phi(x - k))$ forms a *partition of unity*: by Theorem S.7 (page 384)



E X	n=0,	(÷0!)	1;						
	n=1,	(÷1!)	1, 0; -1, 2;						
	n=2,	(÷2!)	1, 0, 0; -2, 6, -3; 1, -6, 9;						
	n=3,	(÷3!)	1, 0, 0, 0; -3, 12, -12, 4; 3, -24, 60, -44; -1, 12, -48, 64;						
	n=4,	(÷4!)	1, 0, 0, 0, 0; -4, 20, -30, 20, -5; 6, -60, 210, -300, 155; -4, 60, -330, 780, -655; 1, -20, 150, -500, 625;						
	n=5,	(÷5!)	1, 0, 0, 0, 0, 0; -5, 30, -60, 60, -30, 6; 10, -120, 540, -1140, 1170, -474; -10, 180, -1260, 4260, -6930, 4386; 5, -120, 1140, -5340, 12270, -10974; -1, 30, -360, 2160, -6480, 7776;						
	n=6,	(÷6!)	1, 0, 0, 0, 0, 0, 0; -6, 42, -105, 140, -105, 42, -7; 15, -210, 1155, -3220, 4935, -3990, 1337; -20, 420, -3570, 15680, -37590, 47040, -24178; 15, -420, 4830, -29120, 96810, -168000, 119182; -6, 210, -3045, 23380, -100065, 225750, -208943; 1, -42, 735, -6860, 36015, -100842, 117649;						
	n=7,	(÷7!)	1, 0, 0, 0, 0, 0, 0, 0; -7, 56, -168, 280, -280, 168, -56, 8; 21, -336, 2184, -7560, 15400, -18648, 12488, -3576; -35, 840, -8400, 45360, -143360, 267120, -273280, 118896; 35, -1120, 15120, -111440, 483840, -1238160, 1733760, -1027984; -21, 840, -14280, 133560, -741160, 2436840, -4391240, 3347016; 7, -336, 6888, -78120, 528920, -2135448, 4753336, -4491192; -1, 56, -1344, 17920, -143360, 688128, -1835008, 2097152;						
	n=8,	(÷8!)	1, 0, 0, 0, 0, 0, 0, 0, 0; -8, 72, -252, 504, -630, 504, -252, 72, -9; 28, -504, 3780, -15624, 39690, -64008, 64260, -36792, 9207; -56, 1512, -17388, 111384, -436590, 1079064, -1650348, 1432872, -541917; 70, -2520, 39060, -340200, 1821330, -6146280, 12800340, -15082200, 7715619; -56, 2520, -49140, 541800, -3691170, 15903720, -42324660, 63667800, -41503131; 28, -1512, 35532, -474264, 3929310, -20674584, 67410252, -124449192, 99584613; -8, 504, -13860, 217224, -2121210, 13208328, -51179940, 112731192, -107948223; 1, -72, 2268, -40824, 459270, -3306744, 14880348, -38263752, 43046721						

Table S.1: Coefficients of the *B-splines* $N_n(x)$ multiplied by $n!$ (Example S.9 page 374)

APPENDIX T

SOURCE CODE

The free and open source software package Maxima has been used to compute some of the algebraic expressions for *B-splines* used in APPENDIX S (page 367):

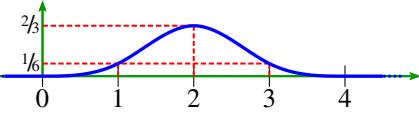
```
1 /*=====
2 * Daniel J. Greenhoe
3 * Maxima script file
4 * To execute this script, start Maxima in a command window
5 * in the subdirectory containing this file (e.g. c:\math\maxima\
6 * and then after the (%i...) prompt enter
7 * batchload("bspline.max")$
8 * Data produced will be written to the file "bsplineout.txt".
9 * reference: http://maxima.sourceforge.net/documentation.html
10 */
11 /*
12 * initialize script
13 */
14 reset();
15 kill(all);
16 load(orthopoly);
17 display2d:false; /* 2-dimensional display */
18 writefile ("bsplineout.txt");
19 /*
20 * n = B-spline order parameter
21 * may be set to any value in {1,2,3,...}
22 */
23 n:2;
24 print("=====");
25 print("Daniel J. Greenhoe");
26 print("Output file for nth order B-spline Nn(x) calculation , n=",n," .");
27 print("Output produced using Maxima running the script file bspline.max");
28 print("=====");
29 Nnx:(1/n!)*sum((-1)^k*binomial(n+1,k)*(x-k)^n*unit_step(x-k),k,0,n+1);
30 print("=====");
31 print("      n+1      k (n+1)      n      ");
32 print("      n! Nn(x) = SUM (-1) ( ) (x-k)  step(x-k) ,n=",n," ");
33 print("      k=0      ( k )      ");
34 print("      ,n+1,"      k (",n+1,")      ,n);
35 print(n,"! Nn(x) = SUM (-1) ( ) (x-k)  step(x-k)");
36 print("      k=0      ( k )");
37 print("      = ",expand(n!*Nnx));
38 print("=====");
39 assume(x<=0);   print(n!,"N(x)= ",expand(n!*Nnx)," for x<=0");   forget(x<=0);
40 for i:0 thru n step 1 do(
41   assume(x>i,x<(i+1)),
42   print(n!,"N(x)= ",expand(n!*Nnx)," for ",i,"<x<",i+1),
43   tex(expand(n!*Nnx),"djh.tex"),/*write output in TeX format to file "djh.tex"*/
44   forget(x>i,x<(i+1))
45 );
46 assume(x>(n+1)); print(n!,"N(x)= ",expand(n!*Nnx)," for x>",n+1); forget(x>(n+1));
```

```

47 print("-----");
48 print(" values at some specific points x:           ");
49 print("-----");
50 y:Nnx,x=(n+1)/2;print("N(",(n+1)/2,")= ",y," (center value)");
51 y:Nnx,x=(n+2)/2;print("N(",(n+2)/2,")= ",y);
52 y:Nnx,x=(n+3)/2;print("N(",(n+3)/2,")= ",y);
53 /*-----*/
54 * close output file
55 *-----*/
56 closefile();

```

Once the polynomial expressions for a *B-spline* have been calculated, they can be plotted within a \LaTeX environment using the [pst-plot package](#) along with a \LaTeX source file such as the following:¹

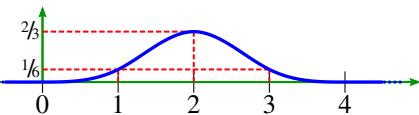


```

1 %=====
2 % Daniel J. Greenhoe
3 % LaTeX file
4 % N_3(x) B-spline
5 % nominal unit = 10mm
6 %=====
7 \begin{pspicture}(-1,-0.5)(5,1)
8 %
9 % parameters
10 %
11 \psset{plotpoints=64,labelsep=1pt}
12 %
13 % axes
14 %
15 \psaxes[linewidth=0.75pt, linecolor=axis ,yAxis=false ,ticks=x, labels=x]{<->}(0,0)(-1,0)(5,1)% x axis
16 \psaxes[linewidth=0.75pt, linecolor=axis ,xAxis=false ,ticks=x, labels=x]{->}(0,0)(-1,0)(5,1)% y axis
17 %
18 % annotation
19 %
20 \psline [linestyle=dashed, linewidth=0.75pt, linecolor=red](2,0)(2,0.667)%
21 \psline [linestyle=dashed, linewidth=0.75pt, linecolor=red](0,0.667)(2,0.667)%
22 \psline [linestyle=dashed, linewidth=0.75pt, linecolor=red](1,0)(1,0.1667)%
23 \psline [linestyle=dashed, linewidth=0.75pt, linecolor=red](3,0)(3,0.1667)%
24 \psline [linestyle=dashed, linewidth=0.75pt, linecolor=red](0,0.1667)(3,0.1667)%
25 \uput[180](0,0.667){$\frac{2}{3}$}%
26 \uput[180](0,0.1667){$\frac{1}{6}$}%
27 %
28 % function plot
29 %
30 \psplot{0}{1}{+1 x 3 exp mul}                                6 div% for 0<=x<=1
31 \psplot{1}{2}{-3 x 3 exp mul +12 x 2 exp mul add -12 x mul add +4 add 6 div}%
32 % for 1<=x<=2
33 \psplot{2}{3}{+3 x 3 exp mul -24 x 2 exp mul add +60 x mul add -44 add 6 div}%
34 % for 2<=x<=3
35 \psplot{3}{4}{-1 x 3 exp mul +12 x 2 exp mul add -48 x mul add +64 add 6 div}%
36 % for 3<=x<=4
37 \psline(0,0)(-0.5,0)\psline[linestyle=dotted](-0.5,0)(-0.75,0)%          % for x<=0
38 \psline(4,0)(4.5,0)\psline[linestyle=dotted](4.5,0)(4.75,0)%          % for x>=4
39 \end{pspicture}

```

Alternatively, one can plot $N_3(x)$ more or less directly from the equation given in Theorem S.1 (page 371) without first calculating the polynomial expressions:



```

1 %=====
2 % Daniel J. Greenhoe
3 % LaTeX file
4 % N_3(x) B-spline
5 % nominal unit = 10mm
6 %=====
7 \begin{pspicture}(-1,-0.5)(5,1)
8 %
9 % parameters
10 %
11 \psset{plotpoints=64,labelsep=1pt}

```

¹For help with PostScript®math operators, see [Adobe \(1999\)](#), pages 508–509 (Arithmetic and Math Operators).

```

12 %
13 % axes
14 %
15 \psaxes[linewidth=0.75pt, linecolor=axis, yAxis=false, ticks=x, labels=x]{<->}(0,0)(-1,0)(5,1)% x axis
16 \psaxes[linewidth=0.75pt, linecolor=axis, xAxis=false, ticks=x, labels=x]{->}(0,0)(-1,0)(5,1)% y axis
17 %
18 % annotation
19 %
20 \psline[linestyle=dashed, linewidth=0.75pt, linecolor=red](2,0)(2,0.667)%
21 \psline[linestyle=dashed, linewidth=0.75pt, linecolor=red](0,0.667)(2,0.667)%
22 \psline[linestyle=dashed, linewidth=0.75pt, linecolor=red](1,0)(1,0.1667)%
23 \psline[linestyle=dashed, linewidth=0.75pt, linecolor=red](3,0)(3,0.1667)%
24 \psline[linestyle=dashed, linewidth=0.75pt, linecolor=red](0,0.1667)(3,0.1667)%
25 \put[180](0,0.667){$ \frac{2}{3} $}%
26 \put[180](0,0.1667){$ \frac{1}{6} $}%
27 %
28 % for n=3
29 % 
$$\frac{1}{n!} \sum_{k=1}^{n+1} (-1)^k \binom{n+1}{k} (x-k)^n s(x-k) = \frac{1}{3!} \sum_{k=1}^4 (-1)^k \binom{4}{k} (x-k)^3 s(x-k)$$

30 % where  $s(x) = 0$  for  $x < 0$  and  $1$  for  $x \geq 0$  (step function)
31 %
32 %
33 \psplot{0}{1}{1 x 0 sub 3 exp mul 6 div}%
34 \psplot{1}{2}{1 x 0 sub 3 exp mul 4 x 1 sub 3 exp mul sub 6 div}%
35 \psplot{2}{3}{1 x 0 sub 3 exp mul 4 x 1 sub 3 exp mul sub 6 x 2 sub 3 exp mul add 6 div}%
36 \psplot{3}{4}{1 x 0 sub 3 exp mul 4 x 1 sub 3 exp mul sub 6 x 2 sub 3 exp mul add 4 x 3 sub
   3 exp mul sub 6 div}%
37 \psplot{4}{4.5}{1 x 0 sub 3 exp mul 4 x 1 sub 3 exp mul sub 6 x 2 sub 3 exp mul add 4 x 3 sub
   3 exp mul sub 1 x 4 sub 3 exp mul add 6 div}%
38 %
39 % 
$$N_3(x) = \frac{[(4 \text{choose} 0)(x-0)^3 - (4 \text{choose} 1)(x-1)^3 + (4 \text{choose} 2)(x-2)^3 - (4 \text{choose} 3)(x-3)^3 + (4 \text{choose} 4)(x-4)^3] / 3!}{6}$$

40 % 
$$= \frac{1 (x-0)^3 - 4 (x-1)^3 + 6 (x-2)^3 - (x-3)^3 + 1 (x-4)^3}{6} / 6$$

41 %
42 \psline(0,0)(-0.5,0)%
43 \psline[linestyle=dotted](-0.5,0)(-0.75,0)%
44 \psline[linestyle=dotted](4.5,0)(4.75,0)%
45 \end{pspicture}%

```



Back Matter



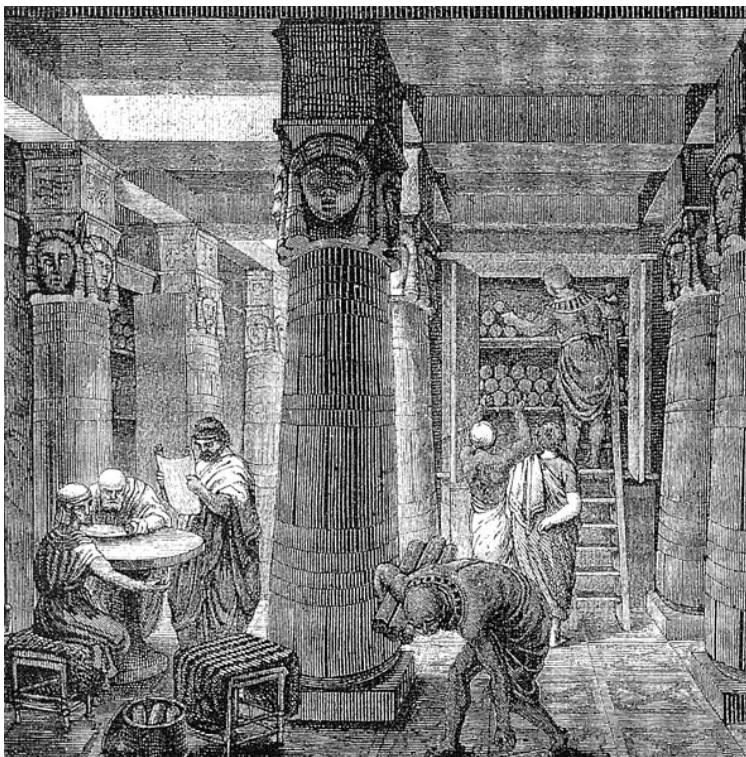
“It appears to me that if one wants to make progress in mathematics, one should study the masters and not the pupils.”

Niels Henrik Abel (1802–1829), Norwegian mathematician ²

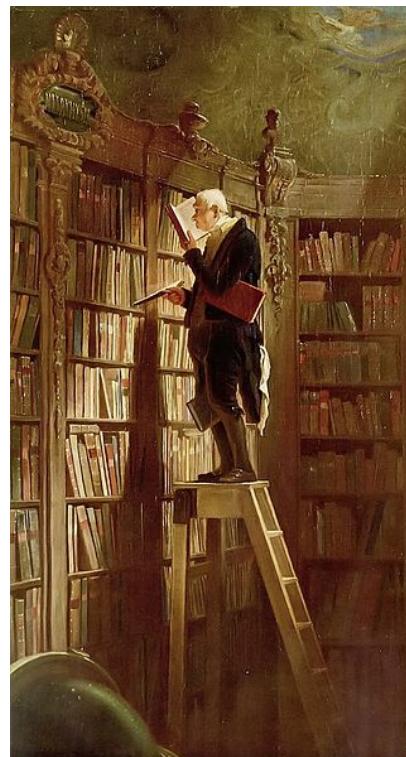


“When evening comes, I return home and go to my study. On the threshold I strip naked, taking off my muddy, sweaty workaday clothes, and put on the robes of court and palace, and in this graver dress I enter the courts of the ancients and am welcomed by them, and there I taste the food that alone is mine, and for which I was born. And there I make bold to speak to them and ask the motives of their actions, and they, in their humanity reply to me. And for the space of four hours I forget the world, remember no vexation, fear poverty no more, tremble no more at death; I pass indeed into their world.”

Niccolò Machiavelli (1469–1527), Italian political philosopher, in a 1513 letter to friend Francesco Vettori. ³



ancient library of Alexandria



The Book Worm by Carl Spitzweg, circa 1850



“To sit alone in the lamplight with a book spread out before you, and hold intimate converse with men of unseen generations—such is a pleasure beyond compare.”

Yoshida Kenko (Urabe Kaneyoshi) (1283? – 1350?), Japanese author and Buddhist monk ⁵

² quote: [Simmons \(2007\)](#), page 187.

image: http://en.wikipedia.org/wiki/Image:Niels_Henrik_Abel.jpg, public domain

³ quote: [Machiavelli \(1961\)](#), page 139?.

image: http://commons.wikimedia.org/wiki/File:Santi_di_Tito_-_Niccolo_Machiavelli%27s_portrait_headcrop.jpg, public domain

⁴ <http://en.wikipedia.org/wiki/File:Ancientlibraryalex.jpg>, public domain http://en.wikipedia.org/wiki/File:Carl_Spitzweg_021.jpg

⁵ quote:  Kenko (circa 1330)
image: https://en.wikipedia.org/wiki/Yoshida_Kenko



A Book Concerning Statistical Signal Processing [VERSION 0.18] 
<https://github.com/dgreenhoe/pdfs/blob/master/abcstat.pdf>

2019 OCTOBER 12 (SATURDAY) 12:33PM UTC
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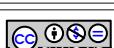
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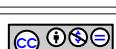
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