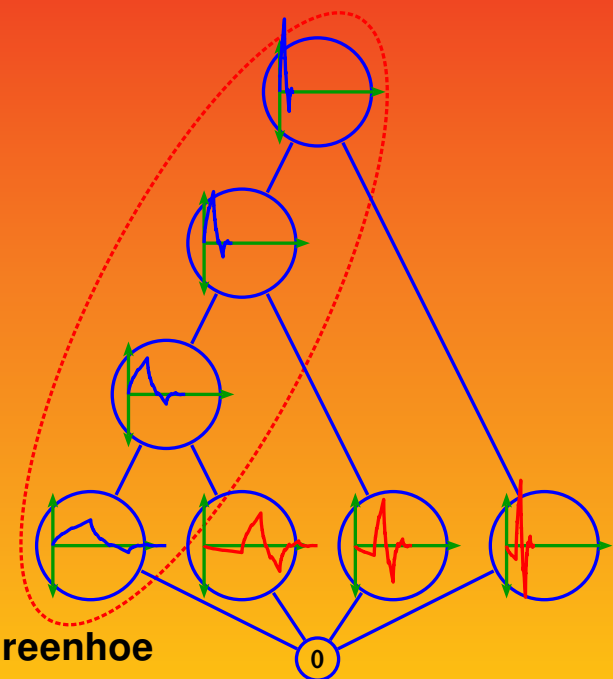
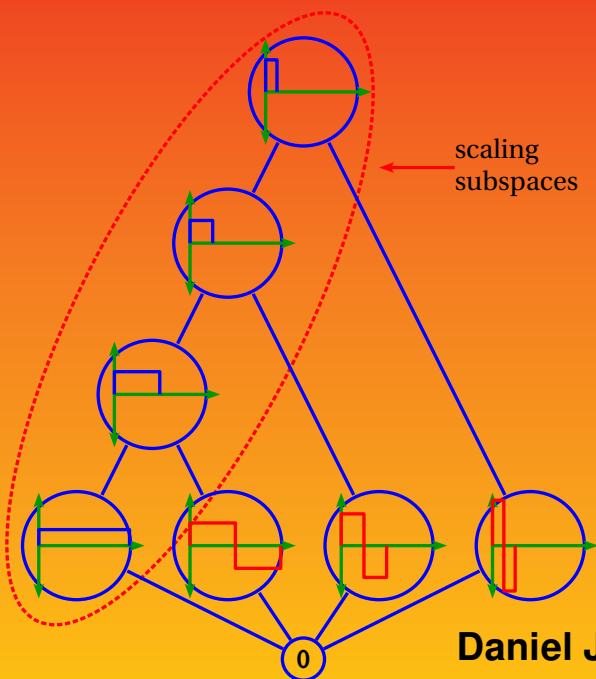
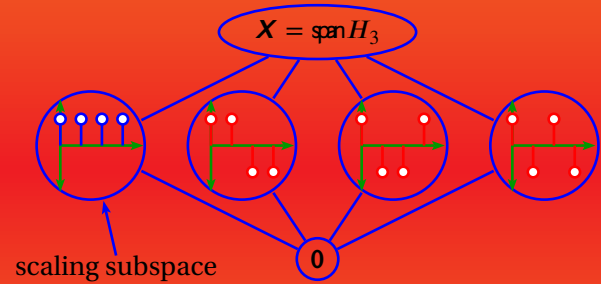
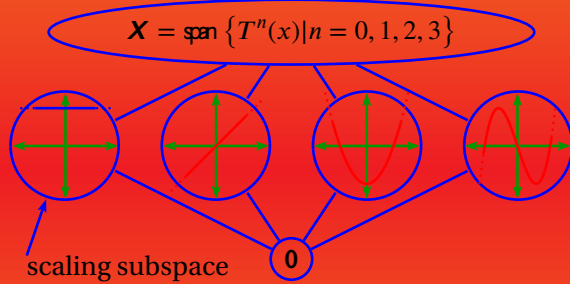
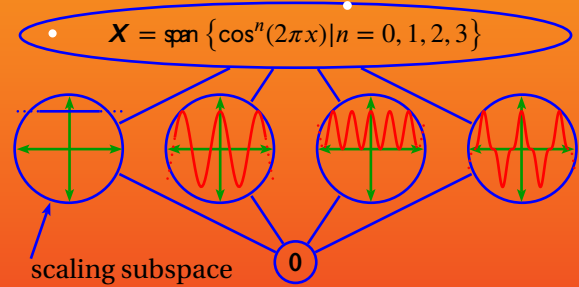
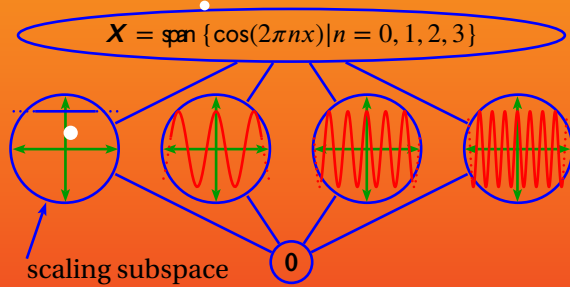


A Book Concerning Transforms

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The ship appearing throughout this text is loosely based on the *Golden Hind*, a sixteenth century English galleon famous for circumnavigating the globe.¹



¹  [Paine \(2000\) page 63](#) ⟨Golden Hind⟩

*“Here, on the level sand,
Between the sea and land,
What shall I build or write
Against the fall of night?”*



*“Tell me of runes to grave
That hold the bursting wave,
Or bastions to design
For longer date than mine.”*

[Alfred Edward Housman](#), English poet (1859–1936) ²



“The uninitiated imagine that one must await inspiration in order to create. That is a mistake. I am far from saying that there is no such thing as inspiration; quite the opposite. It is found as a driving force in every kind of human activity, and is in no wise peculiar to artists. But that force is brought into action by an effort, and that effort is work. Just as appetite comes by eating so work brings inspiration, if inspiration is not discernible at the beginning.”






[Igor Fyodorovich Stravinsky](#) (1882–1971), Russian-born composer ³



“As I think about acts of integrity and grace, I realise that there is nothing in my knowledge to compare with Frege's dedication to truth. His entire life's work was on the verge of completion, much of his work had been ignored to the benefit of men infinitely less capable, his second volume was about to be published, and upon finding that his fundamental assumption was in error, he responded with intellectual pleasure clearly submerging any feelings of personal disappointment. It was almost superhuman and a telling indication of that of which men are capable if their dedication is to creative work and knowledge instead of cruder efforts to dominate and be known.”

[Bertrand Russell](#) (1872–1970), [British mathematician](#), in a 1962 November 23 letter to Dr. van Heijenoort. ⁴



-
- ² quote:  [Housman \(1936\)](#) page 64 <“Smooth Between Sea and Land”>,  [Hardy \(1940\)](#) <section 7>
image: <http://en.wikipedia.org/wiki/Image:Housman.jpg>
- ³ quote:  [Ewen \(1961\)](#) page 408,  [Ewen \(1950\)](#)
image: http://en.wikipedia.org/wiki/Image:Igor_Stravinsky.jpg
- ⁴ quote:  [Heijenoort \(1967\)](#) page 127
image: <http://www-history.mcs.st-andrews.ac.uk/PictDisplay/Russell.html>

“regula XVI. Quae vero praesentem mentis attentionem non requirunt, etiamsi ad conclusionem necessaria sint, illa melius est per brevissimas notas designare quam per integras figuras: ita enim memoria non poterit falli, nec tamen interim cogitatio distrahetur ad haec retinenda, dum aliis deducendis incumbit.”



“Rule XVI. As for things which do not require the immediate attention of the mind, however necessary they may be for the conclusion, it is better to represent them by very concise symbols rather than by complete figures. It will thus be impossible for our memory to go wrong, and our mind will not be distracted by having to retain these while it is taken up with deducing other matters.”

René Descartes (1596–1650), French philosopher and mathematician ⁵



“In signs one observes an advantage in discovery which is greatest when they express the exact nature of a thing briefly and, as it were, picture it; then indeed the labor of thought is wonderfully diminished.”

Gottfried Leibniz (1646–1716), German mathematician, ⁶

Symbol list

symbol	description	
numbers:		
\mathbb{Z}	integers	$\dots, -3, -2, -1, 0, 1, 2, 3, \dots$
\mathbb{W}	whole numbers	$0, 1, 2, 3, \dots$

...continued on next page...

⁵quote: Descartes (1684a) ⟨regula XVI⟩, translation: Descartes (1684b) ⟨rule XVI⟩, image: Frans Hals (circa 1650), <http://en.wikipedia.org/wiki/Descartes>, public domain

⁶quote: Cajori (1993) ⟨paragraph 540⟩, image: http://en.wikipedia.org/wiki/File:Gottfried_Wilhelm_von_Leibniz.jpg, public domain

symbol	description	
\mathbb{N}	natural numbers	$1, 2, 3, \dots$
\mathbb{Z}^+	non-positive integers	$\dots, -3, -2, -1, 0$
\mathbb{Z}^-	negative integers	$\dots, -3, -2, -1$
\mathbb{Z}_o	odd integers	$\dots, -3, -1, 1, 3, \dots$
\mathbb{Z}_e	even integers	$\dots, -4, -2, 0, 2, 4, \dots$
\mathbb{Q}	rational numbers	$\frac{m}{n}$ with $m \in \mathbb{Z}$ and $n \in \mathbb{Z} \setminus 0$
\mathbb{R}	real numbers	completion of \mathbb{Q}
\mathbb{R}^+	non-negative real numbers	$[0, \infty)$
\mathbb{R}^-	non-positive real numbers	$(-\infty, 0]$
\mathbb{R}^+	positive real numbers	$(0, \infty)$
\mathbb{R}^-	negative real numbers	$(-\infty, 0)$
\mathbb{R}^*	extended real numbers	$\mathbb{R}^* \triangleq \mathbb{R} \cup \{-\infty, \infty\}$
\mathbb{C}	complex numbers	
\mathbb{F}	arbitrary field	(often either \mathbb{R} or \mathbb{C})
∞	positive infinity	
$-\infty$	negative infinity	
π	pi	$3.14159265 \dots$
relations:		
\mathbb{R}	relation	
\mathbb{O}	relational and	
$X \times Y$	Cartesian product of X and Y	
(Δ, ∇)	ordered pair	
$ z $	absolute value of a complex number z	
$=$	equality relation	
\triangleq	equality by definition	
\rightarrow	maps to	
\in	is an element of	
\notin	is not an element of	
$\mathcal{D}(\mathbb{R})$	domain of a relation \mathbb{R}	
$\mathcal{I}(\mathbb{R})$	image of a relation \mathbb{R}	
$\mathcal{R}(\mathbb{R})$	range of a relation \mathbb{R}	
$\mathcal{N}(\mathbb{R})$	null space of a relation \mathbb{R}	
set relations:		
\subseteq	subset	
\subsetneq	proper subset	
\supseteq	super set	
\supsetneq	proper superset	
$\not\subseteq$	is not a subset of	
$\not\subsetneq$	is not a proper subset of	
operations on sets:		
$A \cup B$	set union	
$A \cap B$	set intersection	
$A \Delta B$	set symmetric difference	
$A \setminus B$	set difference	
A^c	set complement	
$ \cdot $	set order	
$\mathbb{1}_A(x)$	set indicator function or characteristic function	
logic:		
1	“true” condition	

...continued on next page...

symbol	description	
0	“false” condition	
\neg	logical NOT operation	
\wedge	logical AND operation	
\vee	logical inclusive OR operation	
\oplus	logical exclusive OR operation	
\Rightarrow	“implies”;	“only if”
\Leftarrow	“implied by”;	“if”
\Leftrightarrow	“if and only if”;	“implies and is implied by”
\forall	universal quantifier:	“for each”
\exists	existential quantifier:	“there exists”
order on sets:		
\vee	join or least upper bound	
\wedge	meet or greatest lower bound	
\leq	reflexive ordering relation	“less than or equal to”
\geq	reflexive ordering relation	“greater than or equal to”
$<$	irreflexive ordering relation	“less than”
$>$	irreflexive ordering relation	“greater than”
measures on sets:		
$ X $	order or counting measure of a set X	
distance spaces:		
d	metric or distance function	
linear spaces:		
$\ \cdot\ $	vector norm	
$\ \cdot\ $	operator norm	
$\langle \Delta \nabla \rangle$	inner-product	
$\text{span}(V)$	span of a linear space V	
algebras:		
\Re	real part of an element in a $*$ -algebra	
\Im	imaginary part of an element in a $*$ -algebra	
set structures:		
T	a topology of sets	
R	a ring of sets	
A	an algebra of sets	
\emptyset	empty set	
2^X	power set on a set X	
sets of set structures:		
$\mathcal{T}(X)$	set of topologies on a set X	
$\mathcal{R}(X)$	set of rings of sets on a set X	
$\mathcal{A}(X)$	set of algebras of sets on a set X	
classes of relations/functions/operators:		
2^{XY}	set of <i>relations</i> from X to Y	
Y^X	set of <i>functions</i> from X to Y	
$\mathcal{S}_j(X, Y)$	set of <i>surjective</i> functions from X to Y	
$\mathcal{I}_j(X, Y)$	set of <i>injective</i> functions from X to Y	
$\mathcal{B}_j(X, Y)$	set of <i>bijective</i> functions from X to Y	
$\mathcal{B}(X, Y)$	set of <i>bounded</i> functions/operators from X to Y	
$\mathcal{L}(X, Y)$	set of <i>linear bounded</i> functions/operators from X to Y	
$\mathcal{C}(X, Y)$	set of <i>continuous</i> functions/operators from X to Y	
specific transforms/operators:		

...continued on next page...

symbol	description
$\tilde{\mathbf{F}}$	<i>Fourier Transform operator</i> (Definition 3.2 page 26)
$\hat{\mathbf{F}}$	<i>Fourier Series operator</i> (Definition 7.1 page 53)
$\check{\mathbf{F}}$	<i>Discrete Time Fourier Series operator</i> (Definition 8.1 page 59)
\mathbf{Z}	<i>Z-Transform operator</i> (Definition 9.4 page 70)
$\tilde{f}(\omega)$	<i>Fourier Transform of a function $f(x) \in L^2_{\mathbb{R}}$</i>
$\check{x}(\omega)$	<i>Discrete Time Fourier Transform of a sequence $(x_n \in \mathbb{C})_{n \in \mathbb{Z}}$</i>
$\check{x}(z)$	<i>Z-Transform of a sequence $(x_n \in \mathbb{C})_{n \in \mathbb{Z}}$</i>

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Part I

Continuous to Continuous Transforms

CHAPTER 1

ANALYSES AND TRANSFORMS



“The analytical equations, unknown to the ancient geometers, which Descartes was the first to introduce into the study of curves and surfaces, ...they extend to all general phenomena. There cannot be a language more universal and more simple, more free from errors and from obscurities, ...mathematical analysis is as extensive as nature itself; it defines all perceptible relations, measures times, spaces, forces, temperatures ; this difficult science is formed slowly, but it preserves every principle which it has once acquired; it grows and strengthens itself incessantly in the midst of the many variations and errors of the human mind. Its chief attribute is clearness; it has no marks to express confused notions. It brings together phenomena the most diverse, and discovers the hidden analogies which unite them. ”

Joseph Fourier (1768–1830) ¹

1.1 Abstract spaces

The **abstract space** was introduced by Maurice Fréchet in his 1906 Ph.D. thesis.² An *abstract space* in mathematics does not really have a rigorous definition; but in general it is a set together with some other unifying structure. Examples of spaces include *topological spaces*, *metric spaces*, and *linear spaces* (*vector spaces*).




¹ quote:  Fourier (1878) pages 7–8 (Preliminary Discourse)

image: <http://en.wikipedia.org/wiki/File:Fourier2.jpg>, public domain

²  Fréchet (1906),  Fréchet (1928). “A collection of these abstract elements will be called an abstract set. If to this set there is added some rule of association of these elements, or some relation between them, the set will be called an abstract space.”—Maurice Fréchet

1.2 Lattice of subspaces

An abstract space can be decomposed into one or more *subspaces*. Roughly speaking, a subspace of an abstract space is simply a subset the abstract space that has the same properties of that abstract space. The subspaces can be ordered under the ordering relation \subseteq (subset or equal to relation) to form a *lattice*.

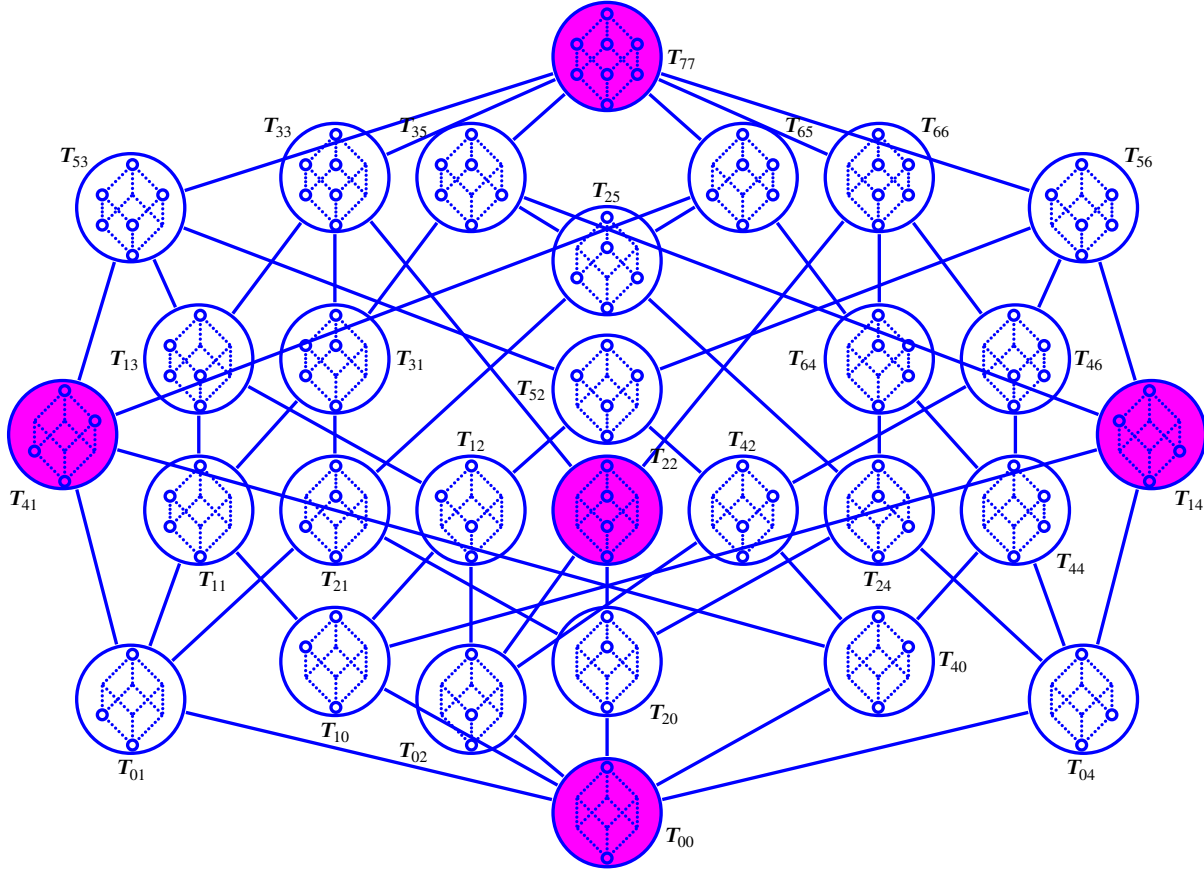
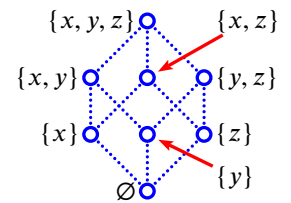


Figure 1.1: lattice of topologies on $X \triangleq \{x, y, z\}$ (Example 1.1 page 4)

Example 1.1. ³The power set 2^X is a *topology* on the set X . But there are also 28 other topologies on $\{x, y, z\}$, and these are all *subspaces* of $2^{\{x,y,z\}}$. Let a given topology in $\mathcal{T}(\{x, y, z\})$ be represented by a Hasse diagram as illustrated to the right, where a circle present means the indicated set is in the topology, and a circle absent means the indicated set is not in the topology. ⁴The lattice of the 29 topologies $(\mathcal{T}(\{x, y, z\}), \cup, \cap; \subseteq)$ is illustrated in Figure 1.1 (page 4). The lattice of these 29 topologies is *non-distributive* (it contains the *N5 lattice*). The five topologies illustrated by red shaded nodes are also *algebras of sets*.



Example 1.2. The power set 2^X is an *algebra of sets* on the set X . But there are also 14 other algebras of sets on $\{w, x, y, z\}$, and these are all *subspaces* of $2^{\{w,x,y,z\}}$. The *lattice of algebras of sets* on $\{w, x, y, z\}$ is illustrated in Figure 1.2 (page 5).

A *linear subspace* is a subspace of a *linear space* (*vector space*). Linear subspaces have some special properties: Every linear subspace contains the additive identity zero vector, and every linear subspace is *convex*.

⁴ [Isham \(1999\)](#) page 44, [Isham \(1989\)](#) page 1516, [Steiner \(1966\)](#) page 386

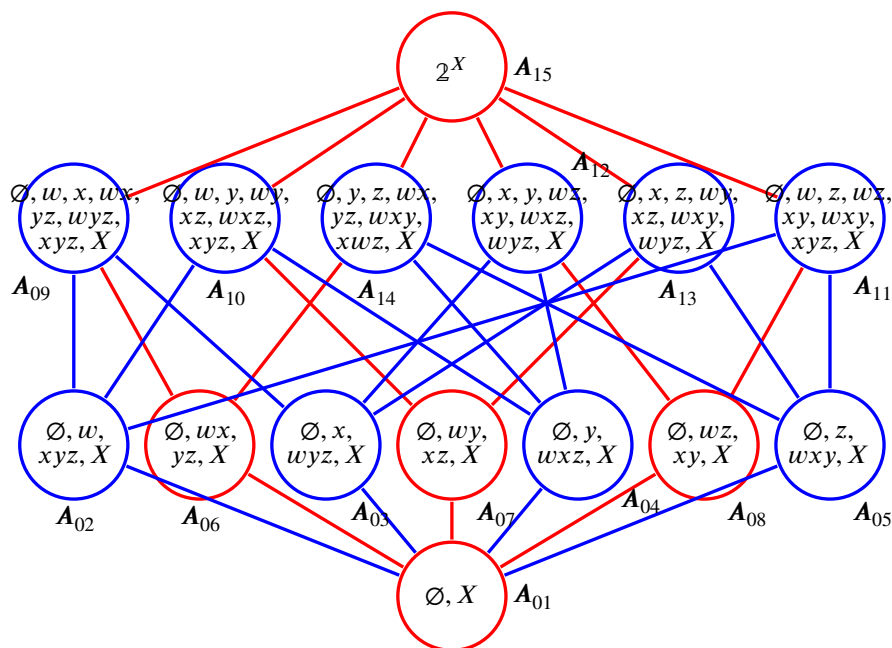
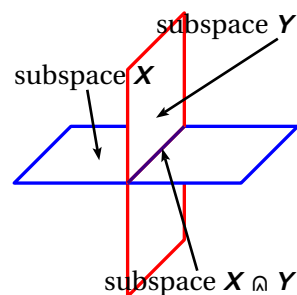


Figure 1.2: lattice of *algebras of sets* on $\{w, x, y, z\}$ (Example 1.2 page 4)

Example 1.3. The 3-dimensional Euclidean space \mathbb{R}^3 contains the 2-dimensional xy -plane and xz -plane subspaces, which in turn both contain the 1-dimensional x -axis subspace. These subspaces are illustrated in the figure to the right and in Figure 1.3 (page 6).



1.3 Analyses

An **analysis** of a space \mathbf{X} is any lattice of subspaces of \mathbf{X} . The partial or complete reconstruction of \mathbf{X} from this set is a **synthesis**.⁵

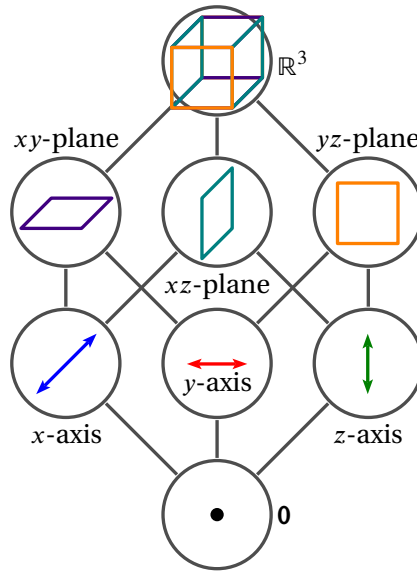
Example 1.4. The lattices of subspaces illustrated in Figure 1.4 (page 6) are all *analyses* of \mathbb{R}^3 .

1.4 Transform

Definition 1.1. A **transform** on a space \mathbf{X} is a sequence of projection operators that induces an ANALYSIS on \mathbf{X} .

Section 1.3 defined an **analysis** of a space \mathbf{X} as is any lattice of subspaces of \mathbf{X} . In like manner, an **analysis** of a function $f(x)$ with respect to a transform \mathbf{T} is simply the transform \mathbf{T} of f ($\mathbf{T}f$). Such

⁵The word *analysis* comes from the Greek word ἀνάλυσις, meaning “dissolution” (Perschbacher (1990) page 23 (entry 359)), which in turn means “the resolution or separation into component parts” (Black et al. (2009), <http://dictionary.reference.com/browse/dissolution>)

Figure 1.3: lattice of subspaces of \mathbb{R}^3 (Example 1.3 page 5)linearly ordered analysis of \mathbb{R}^3 M-3 analysis of \mathbb{R}^3 wavelet-like analysis of \mathbb{R}^3 Figure 1.4: some analyses of \mathbb{R}^3 (Example 1.4 page 5)

an analysis or transform is often represented as the sequence of coefficients (λ_n) multiplying the basis vectors $(\psi_n(x))$ such that

$$f(x) = \mathbf{T}f(x) = \sum_{n \in \mathbb{Z}} \lambda_n \psi_n(x)$$

Example 1.5. A *Fourier analysis* is a sequence of subspaces with sinusoidal bases. Examples of subspaces in a Fourier analysis include $V_1 = \text{span}\{e^{ix}\}$, $V_{2.3} = \text{span}\{e^{i2.3x}\}$, $V_{\sqrt{2}} = \text{span}\{e^{i\sqrt{2}x}\}$, etc. A **transform** is a set of *projection operators* that maps a family of functions (e.g. $L^2_{\mathbb{R}}$) into an analysis. The *Fourier transform* for Fourier Analysis is (Definition 3.2 page 26)

$$[\tilde{f}](\omega) \triangleq \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x) e^{-i\omega x} dx$$

1.5 Properties of subspace order structures

The ordered set of all linear subspaces of a *Hilbert space* is an *orthomodular lattice*. Orthomodular lattices (and hence Hilbert subspaces) have some special properties (next theorem). One is that they satisfy *de Morgan's law*.

Theorem 1.1. ⁶ Let $L \triangleq (X, \vee, \wedge, 0, 1; \leq)$ be an algebraic structure.

T H M	$L \text{ is an ORTHOMODULAR LATTICE} \} \Rightarrow$	1.	$(x \vee y)^\perp = x^\perp \wedge y^\perp$	$\forall x, y \in X$	(DE MORGAN)	and
		2.	$(x \wedge y)^\perp = x^\perp \vee y^\perp$	$\forall x, y \in X$	(DE MORGAN)	and
		3.	$(z^\perp \wedge y^\perp)^\perp \vee x = (x \vee y) \vee z$	$\forall x, y, z \in X$		and
		4.	$x \wedge (x \vee y) = x$	$\forall x, y \in X$		and
		5.	$x \vee (y \wedge y^\perp) = x$	$\forall x, y \in X$		

⁶ Beran (1985) pages 30–33, Birkhoff and Neumann (1936) page 830 (L74), Beran (1976) pages 251–252

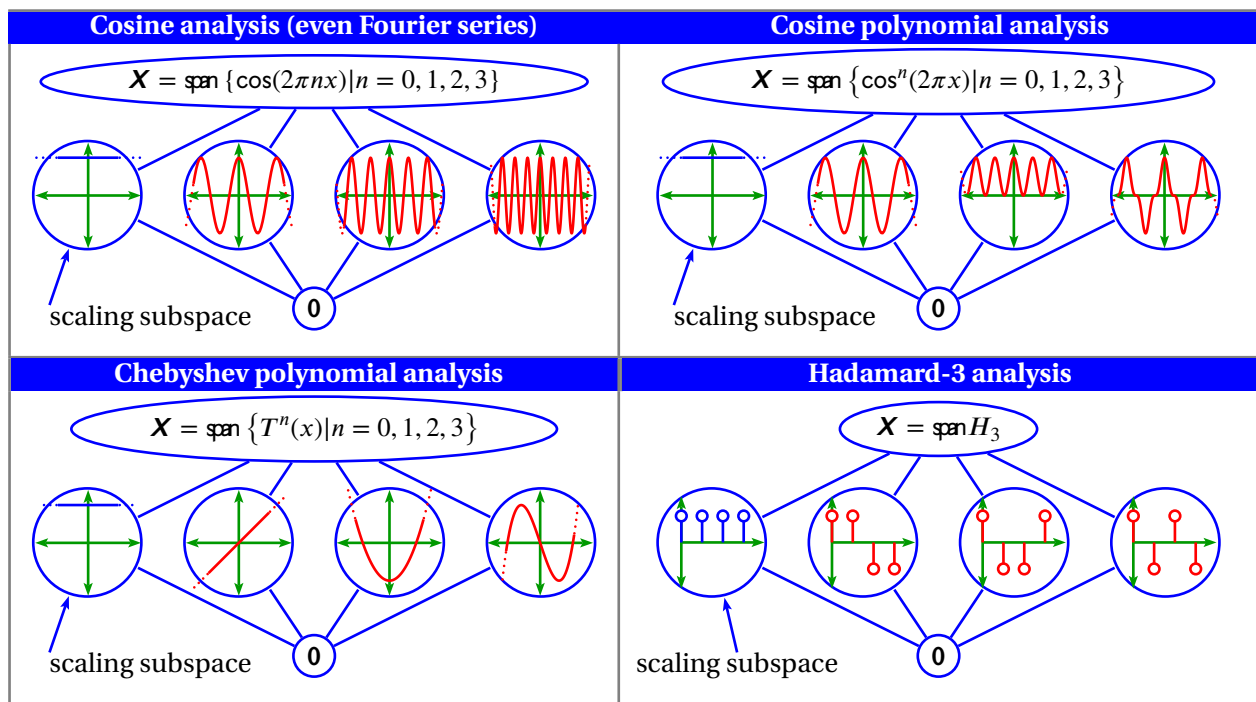
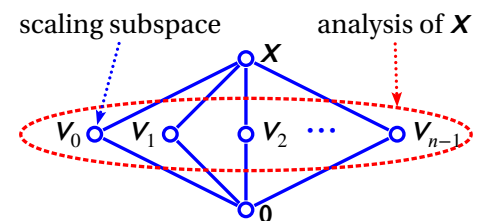
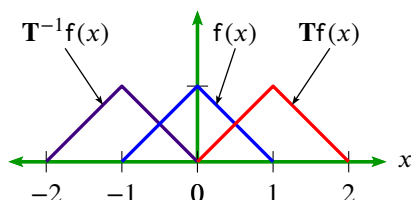


Figure 1.5: some common transforms

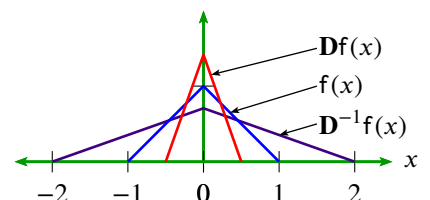
Most transforms have a very simple M - n order structure, as illustrated to the right and in Figure 1.5 page 7. The M - n lattices for $n \geq 3$ are *modular* but not *distributive*. Analyses typically have one subspace that is a *scaling* subspace; and this subspace is often simply a family of constants (as is the case with *Fourier Analysis*). There is one notable exception to this—MRA induced *wavelet analysis*.



1.6 Operator inducing analyses



An *analysis* is often defined in terms of a small number (e.g. 2) operators. Two such operators are the *translation operator* and the *dilation operator* (Definition J.3 page 222).



Example 1.6. In *Fourier analysis*, continuous dilations (Definition J.3 page 222) of the *complex exponential* form a *basis* (Definition H.7 page 188) for the *space of square integrable functions* $\mathcal{L}^2_{\mathbb{R}}$ (Definition B.1 page 99) such that $\mathcal{L}^2_{\mathbb{R}} = \text{span} \{ \mathbf{D}_{\omega} e^{ix} \mid \omega \in \mathbb{R} \}$.

Example 1.7. In *Fourier series analysis* (Theorem 7.1 page 54), discrete dilations of the complex exponential form a basis for $\mathcal{L}^2_{\mathbb{R}}(0 : 2\pi)$ such that $\mathcal{L}^2_{\mathbb{R}}(0 : 2\pi) = \text{span} \{ \mathbf{D}_j e^{ix} \mid j \in \mathbb{Z} \}$.

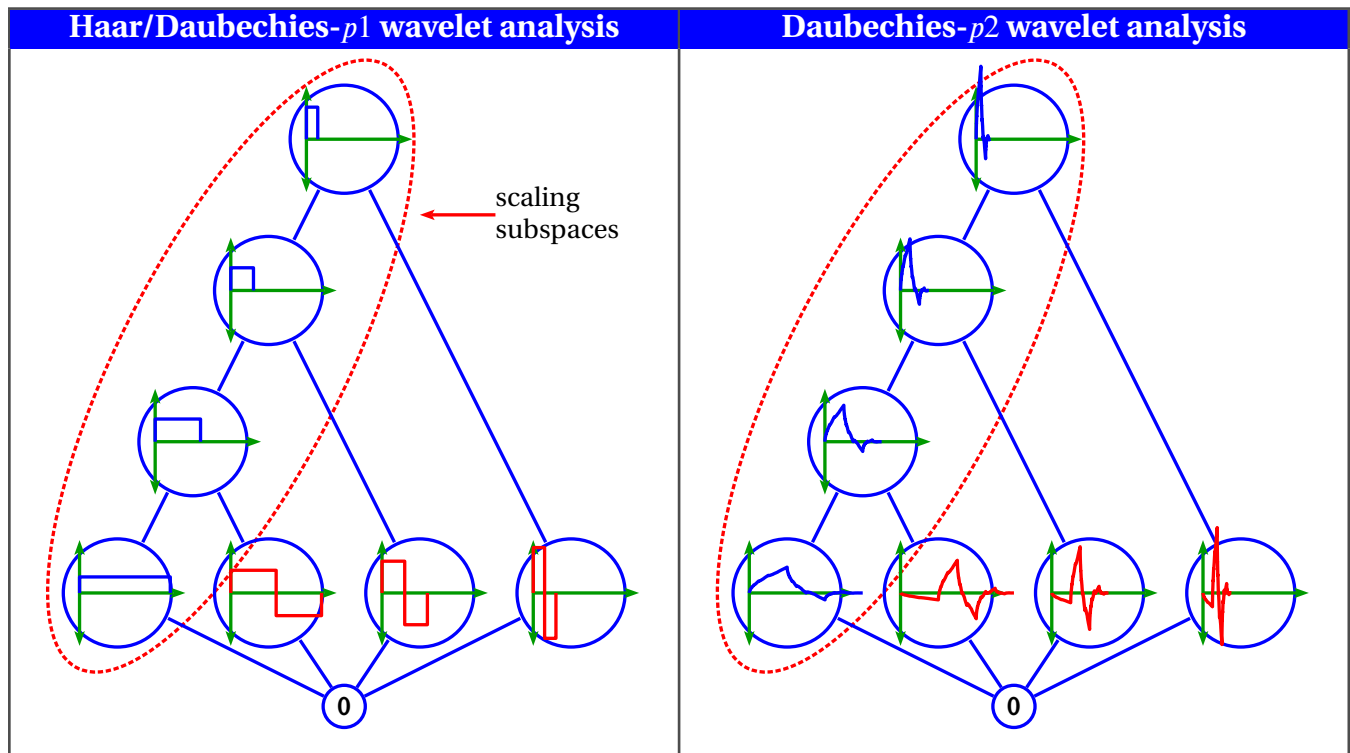
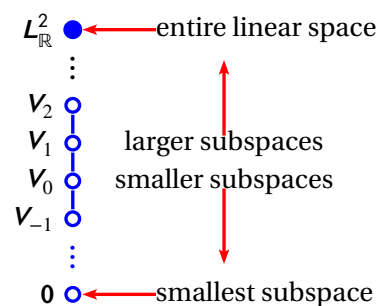


Figure 1.6: some wavelet transforms

1.7 Wavelet analyses

The term “wavelet” comes from the French word “*ondelette*”, meaning “small wave”. And in essence, wavelets are “small waves” (as opposed to the “long waves” of Fourier analysis) that form a basis for the Hilbert space $L^2_{\mathbb{R}}$.⁸

A **special characteristic** of wavelet analysis is that there is not just one scaling subspace, (as is with the case of Fourier and several other analyses), but an entire sequence of scaling subspaces (Figure 1.6 page 8). These scaling subspaces are *linearly ordered* with respect to the ordering relation \subseteq . In wavelet theory, this structure is called a *multiresolution analysis*, or *MRA*. The MRA was introduced by Stéphane G. Mallat in 1989. The concept of a scaling space was perhaps first introduced by Taizo Iijima in 1959 in Japan, and later as the *Gaussian Pyramid* by Burt and Adelson in the 1980s in the West.⁹



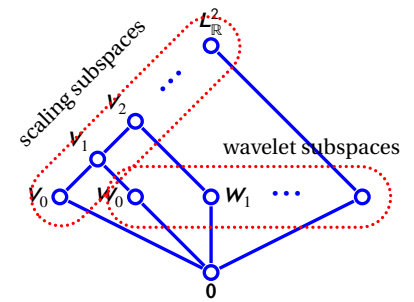
The MRA has become the dominate wavelet construction method. Moreover, P.G. Lemarié has proved that all wavelets with *compact support* are generated by an MRA.¹¹

⁸ Strang and Nguyen (1996) page ix / Atkinson and Han (2009) page 191

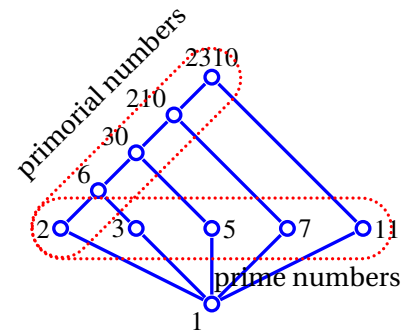
¹⁰ Mallat (1989) page 70, Iijima (1959), Burt and Adelson (1983), Adelson and Burt (1981), Lindeberg (1993), Alvarez et al. (1993), Guichard et al. (2012) pages 23–24 (§3.2.1 Scale-Space Extrema), Guichard et al. (20xx) pages 77–78 (§5.2.1 Scale-Space Extrema), Weickert (1999) (historical survey)

¹¹ Lemarié (1990), Mallat (1999) page 240

A **second special characteristic** of wavelet analysis is that its order structure with respect to the \subseteq relation is not a simple M - n lattice (as is with the case of Fourier and several other analyses). Rather, it is a lattice of the form illustrated to the right and in Figure 1.6 (page 8). This lattice is *non-complemented*, *non-distributive*, *non-modular*, and *non-Boolean* (Proposition ?? page ??).¹²



In the world of mathematical structures, the order structure of wavelet analyses is quite rare, but not completely unique. One example of a system with similar structure is the set of *Primorial numbers* together with the $|$ (“divides”) ordering relation¹³ as illustrated to the right.



The basis sequence of most transform are fixed with no design freedom For example, the Fourier Transform uses the complex exponential, Taylor Expansion uses monomials of the form $(x - a)^n$. However, there are an infinite number of wavelet basis sequences—lots and lots of design freedom. For information regarding designing wavelet basis sequences, see Greenhoe (2013).

However, one arguable disadvantage is that wavelets do not support a **convolution theorem**—a theorem enjoyed by the Fourier transforms, Laplace Transform, and Z Transform. These other transforms induce a convolution theorem because they are defined in terms of an exponential (e.g. $e^{-i\omega t}$, $e^{-i\omega n}$, e^{-st} , z^{-n}), and exponentials sport the property $a^{x+y} = a^x a^y$.

¹² Greenhoe (2013) page 72 (Section 2.4.3 Order structure)

¹⁴ Sloane (2014) (<http://oeis.org/A002110>), Greenhoe (2013) page 30

CHAPTER 2

LAPLACE TRANSFORM

“La langue de l’analyse, la plus parfaite de toutes les langues, tant par elle-même un puissant instrument de découvertes; ses notations, lorsqu’elles sont nécessaires et heureusement imaginées, sont des germes de nouveaux calculs.”

Pierre-Simon Laplace¹

“The language of analysis, most perfect of all, being in itself a powerful instrument of discoveries, its notations, especially when they are necessary and happily imagined, are the seeds of new calculi.”

2.1 Operator Definition

Definition 2.1. ² Let $L^2_{(\mathbb{R}, \mathcal{B}, \mu)}$ be the space of all LEBESGUE SQUARE-INTEGRABLE FUNCTIONS.

DEF The **Laplace Transform** operator \mathbf{L} is here defined as

$$[\mathbf{L}f](s) \triangleq \int_{x \in \mathbb{R}} f(x) e^{-sx} dx \quad \forall f \in L^2_{(\mathbb{R}, \mathcal{B}, \mu)}$$

Such integrals may *converge* for certain values of s and *diverge* for others.

Definition 2.2. Let $\mathbf{L}[g(x)]$ be the LAPLACE TRANSFORM (Definition 2.1 page 11) of a function $g(x)$.

DEF The set $\mathbf{RocL}[g(x)]$ of all s for which $\mathbf{L}[g(x)]$ CONVERGES is the **Region of Convergence** of $\mathbf{L}[g(x)]$.

In this text, the region of convergence may in places be specified using the *open interval* $(A : B)$ and *closed interval* $[A : B]$.

¹ Laplace (1814) page xxxi (Introduction), Laplace (1812), Laplace (1902) pages 48–49, Moritz (1914) page 200 (Quote 1222., but “conceived” not “imagined”, and “are so many germs” not “are the seeds”), https://todayinsci.com/L/Laplace_Pierre/LaplacePierre-Analysis-Quotations.htm, <https://translate.google.com/>,

² Bracewell (1978) page 219 (Chapter 11 The Laplace transform), van der Pol and Bremmer (1959) page 13 (5. Strip of convergence of the Laplace integral), Levy (1958) page 2 (“two-sided transformation”), Betten (2008b) page 295 (B.1)

Remark 2.1. A scaling factor $\frac{1}{\sqrt{2\pi}}$ in front of $\int_{\mathbb{R}}$ in Definition 2.1 is not typically found in references offering definitions of the Laplace Transform, and is not included here either. That is not to say, however, that it's not a good idea. Including it would make the operator \mathbf{L} more directly compatible with the *Unitary Fourier Transform* operator $\tilde{\mathbf{F}}$ (Definition 3.2 page 26). Note also that a $\frac{1}{2\pi}$ scaling factor is included in [Bachman et al. (2002) page 268] in their definition of *convolution* (Definition C.1 page 103, Section 2.8 page 23).

2.2 Operator Inverse

Theorem 2.1. ³

$$\mathbf{L}^{-1}[\mathbf{G}(s)] \triangleq \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} \mathbf{G}(s) e^{sx} ds \quad \text{for some } c \in \mathbb{R}^+$$

2.3 Transversal properties

Theorem 2.2. ⁴ Let $\mathbf{L}[g(x)]$ be the LAPLACE TRANSFORM (Definition 2.1 page 11) of a function $g(x)$. Let the REGION OF CONVERGENCE of $\mathbf{L}[g(x)](s)$ be $A \leq \mathbf{R}_e(s) \leq B$ with $(A, B) \in \mathbb{R}^2$.

	Mapping	Region of Convergence	Domain	Property
$\mathbf{L}[g(x - \alpha)]$	$= e^{-\alpha s} \mathbf{L}[g(x)](s)$	for $\mathbf{R}_e(s) \in [A : B]$	$\forall x, \alpha \in \mathbb{C}$	(TRANSLATION)
$\mathbf{L}[g(\alpha x)]$	$= \frac{1}{ \alpha } \mathbf{L}[g(x)]\left(\frac{s}{\alpha}\right)$	for $\mathbf{R}_e\left(\frac{s}{\alpha}\right) \in [A : B]$	$\forall x, \alpha \in \mathbb{C}$	(DILATION)

PROOF:

$$\begin{aligned}
 \mathbf{L}[g(x - \alpha)] &\triangleq \int_{x=-\infty}^{x=\infty} g(x - \alpha) e^{-sx} dx && \text{by definition of } \mathbf{L} && \text{(Definition 2.1 page 11)} \\
 &= \int_{u+\alpha=-\infty}^{u+\alpha=\infty} g(u) e^{-s(\alpha+u)} du && \text{where } u \triangleq x - \alpha && \implies x = \alpha + u \\
 &= e^{-\alpha s} \int_{u=-\infty}^{u=\infty} g(u) e^{-su} du && \forall A \leq \mathbf{R}_e(s) \leq B && \text{by property of exponents} && b^{x+\alpha} = b^x b^\alpha \\
 &\triangleq e^{-\alpha s} \int_{x=-\infty}^{x=\infty} g(x) e^{-sx} dx && \forall A \leq \mathbf{R}_e(s) \leq B && \text{by change of variable} && u \rightarrow x \\
 &\triangleq e^{-\alpha s} [\mathbf{L}g(x)] && \forall A \leq \mathbf{R}_e(s) \leq B && \text{by definition of } \mathbf{L} && \text{(Definition 2.1 page 11)}
 \end{aligned}$$

$$\begin{aligned}
 \mathbf{L}[g(\alpha x)] &\triangleq \int_{x=-\infty}^{x=\infty} g(\alpha x) e^{-sx} dx && \text{by definition of } \mathbf{L} && \text{(Definition 2.1 page 11)} \\
 &= \int_{u/\alpha=-\infty}^{u/\alpha=\infty} g(u) e^{-s(u/\alpha)} \frac{1}{\alpha} du && \text{where } u \triangleq \alpha x && \implies x = \frac{u}{\alpha} \\
 &= \frac{1}{\alpha} \int_{u=-\infty}^{u=\infty} g(u) e^{-(s/\alpha)u} du
 \end{aligned}$$

³ [Bracewell (1978) page 220] (Chapter 11 The Laplace transform)

⁴ [Bracewell (1978) page 224] (Table 11.1: "Shift" and "Similarity" entries), [Levy (1958) page 15] (Equation 0.8)

$$\begin{aligned}
&= \begin{cases} \frac{1}{\alpha} \int_{u=-\infty}^{u=\infty} g(u) e^{-(s/\alpha)u} du & \text{if } \alpha \geq 0 \\ \frac{1}{\alpha} \int_{u=\infty}^{u=-\infty} g(u) e^{-(s/\alpha)u} du & \text{otherwise} \end{cases} \quad \forall A \leq \mathbf{R}_e\left(\frac{s}{\alpha}\right) \leq B \\
&= \begin{cases} \frac{1}{\alpha} \int_{u=-\infty}^{u=\infty} g(u) e^{-(s/\alpha)u} du & \text{if } \alpha \geq 0 \\ -\frac{1}{\alpha} \int_{u=-\infty}^{u=\infty} g(u) e^{-(s/\alpha)u} du & \text{otherwise} \end{cases} \quad \forall A \leq \mathbf{R}_e\left(\frac{s}{\alpha}\right) \leq B \\
&= \frac{1}{|\alpha|} \int_{x \in \mathbb{R}} g(x) e^{-(s/\alpha)x} dx \quad \forall A \leq \mathbf{R}_e\left(\frac{s}{\alpha}\right) \leq B \quad \text{by change of variable} \quad u \rightarrow x \\
&\triangleq \frac{1}{|\alpha|} [\mathbf{L}g(x)]\left(\frac{s}{\alpha}\right) \quad \forall A \leq \mathbf{R}_e\left(\frac{s}{\alpha}\right) \leq B \quad \text{by definition of } \mathbf{L} \quad (\text{Definition 2.1 page 11})
\end{aligned}$$

⇒

Corollary 2.1. ⁵ Let \mathbf{L} , $G(s)$, A , and B be defined as in Theorem 2.2 (page 12).

COR	Mapping	Region of Convergence	Domain	Property
	$\mathbf{L}[g(-x)] = G(-s)$	for $\mathbf{R}_e(s) \in [-B : -A]$	$\forall x, \alpha \in \mathbb{C}$	(REVERSAL)

PROOF:

$$\begin{aligned}
\mathbf{L}[g(-x)] &= \mathbf{L}[g([-1]x)] & \mathbf{R}_e(s) &\in [A : B] & \text{by definition of unary operator } - \\
&= \mathbf{L}\left[\frac{1}{|-1|} g\left(\frac{x}{-1}\right)\right] & \mathbf{R}_e\left(\frac{s}{-1}\right) &\in [A : B] & \text{by dilation property (Theorem 2.2 page 12)} \\
&= G(-s) & \mathbf{R}_e(s) &\in [-B : -A]
\end{aligned}$$

⇒

2.4 Linear properties

Theorem 2.3. ⁶ Let \mathbf{L} be the LAPLACE TRANSFORM operator (Definition 2.1 page 11). Let $G(s) \triangleq [\mathbf{L}g(x)]$ and $F(s) \triangleq [\mathbf{L}f(x)]$. Let the REGION OF CONVERGENCE of $G(s)$ be $A \leq \mathbf{R}_e(s) \leq B$ and the REGION OF CONVERGENCE of $F(s)$ be $C \leq \mathbf{R}_e(s) \leq D$.

THM	Mapping	Region of Convergence	Domain	Property
	$\mathbf{L}[f(x) + g(x)] = F(s) + G(s)$	for $\mathbf{R}_e(s) \in [A : B] \cap [C : D]$	$\forall x, \alpha \in \mathbb{C}$	(ADDITIVE)
	$\mathbf{L}[\alpha g(x)] = \alpha G(s)$	for $\mathbf{R}_e(s) \in [A : B]$	$\forall x, \alpha \in \mathbb{C}$	(HOMOGENEOUS)

Corollary 2.2 (Linear Properties). Let \mathbf{L} be the LAPLACE TRANSFORM operator (Definition 2.1 page 11). Let A and B be real numbers such that $[A : B]$ is the REGION OF CONVERGENCE of $\mathbf{L}[g(x)]$. Let C and D be real numbers such that $[C : D]$ is the REGION OF CONVERGENCE of $\mathbf{L}[f(x)]$. Let A_n and B_n be real numbers such that $[A_n : B_n]$ is the REGION OF CONVERGENCE of $\mathbf{L}[g_n(x)]$.

⁵ Bracewell (1978) page 224 (Table 11.1 Theorems for the Laplace Transform)

⁶ Bracewell (1978) page 224 (Table 11.1 Theorems for the Laplace Transform), Betten (2008a) page 296 ((B.6)), Levy (1958) page 13 (Equation 0.2), van der Pol and Bremmer (1959) page 22 (Introduction), Shafii-Mousavi (2015) page 7 (Theorem 1.4)

C O R	Mapping		Region of Convergence	Domain
	$\mathbf{L}[0]$	$= 0$	for $\mathbf{R}_e(s) \in [A : B]$	$\forall x \in \mathbb{C}$
	$\mathbf{L}[-g(x)]$	$= -\mathbf{L}[g(x)]$	for $\mathbf{R}_e(s) \in [A : B]$	$\forall x \in \mathbb{C}$
	$\mathbf{L}[f(x) - g(x)]$	$= \mathbf{L}[g(x)] - \mathbf{L}[f(x)]$	for $\mathbf{R}_e(s) \in [A : B] \cap [C : D]$	$\forall x \in \mathbb{C}$
	$\mathbf{L}\left[\sum_{n=1}^N \alpha_n g_n(x)\right]$	$= \sum_{n=1}^N \alpha_n \mathbf{L}[g_n(x)]$	for $\mathbf{R}_e(s) \in \bigcap_{n=1}^N [A_n : B_n]$	$\forall x, \alpha_n \in \mathbb{C}$

✎ PROOF:

1. By Theorem 2.3 (page 13), the operator *Laplace Transform* operator \mathbf{L} is *additive* and *homogeneous*.
2. By item (1) and Definition G.4 (page 155), \mathbf{L} is *linear*.
3. By item (2) and Theorem G.1 (page 155), the four properties listed follow.

⇒

2.5 Modulation properties

Theorem 2.4.⁷ Let \mathbf{L} be the LAPLACE TRANSFORM operator (Definition 2.1 page 11). Let $G(s) \triangleq [\mathbf{L}g(x)]$. Let the REGION OF CONVERGENCE of $G(s)$ be $A \leq \mathbf{R}_e(s) \leq B$.

T H M	Mapping	Region of Convergence	Domain	Property
	$\mathbf{L}[e^{-\alpha x} g(x)] = G(s + \alpha)$	for $A - \mathbf{R}_e(\alpha) \leq \mathbf{R}_e(s) \leq B - \mathbf{R}_e(\alpha)$	$\forall x, \alpha \in \mathbb{C}$	(MODULATION)

✎ PROOF:

$$\begin{aligned}
 \mathbf{L}[e^{-\alpha x} g(x)] &\triangleq \int_{x \in \mathbb{R}} e^{-\alpha x} g(x) e^{-sx} dx && \text{by definition of } \mathbf{L} && \text{(Definition 2.1 page 11)} \\
 &= \int_{x \in \mathbb{R}} g(x) e^{-(s+\alpha)x} dx && A \leq \mathbf{R}_e(s + \alpha) \leq B && b^{x+y} = b^x b^y \\
 &\triangleq [\mathbf{L}g(x)](s + \alpha) && A - \mathbf{R}_e(\alpha) \leq \mathbf{R}_e(s) \leq B - \mathbf{R}_e(\alpha) && \text{(Definition 2.1 page 11)} \\
 &\triangleq G(s + \alpha) && A - \mathbf{R}_e(\alpha) \leq \mathbf{R}_e(s) \leq B - \mathbf{R}_e(\alpha) && \text{by definition of } G(s)
 \end{aligned}$$

⇒

Corollary 2.3.⁸ Let \mathbf{L} be the LAPLACE TRANSFORM operator (Definition 2.1 page 11). Let $G(s) \triangleq [\mathbf{L}g(x)]$. Let the REGION OF CONVERGENCE of $G(s)$ be $A \leq \mathbf{R}_e(s) \leq B$.

C O R	Mapping		Region of Convergence	Domain
	$\mathbf{L}[\cos(\omega_o x) g(x)]$	$= \frac{1}{2} G(s - i\omega_o) + \frac{1}{2} G(s + i\omega_o)$	for $\mathbf{R}_e(s) \in [A : B]$	$\forall x, \omega_o \in \mathbb{C}$
	$\mathbf{L}[\sin(\omega_o x) g(x)]$	$= -\frac{i}{2} G(s - i\omega_o) + \frac{i}{2} G(s + i\omega_o)$	for $\mathbf{R}_e(s) \in [A : B]$	$\forall x, \omega_o \in \mathbb{C}$
	$\mathbf{L}[\cosh(\omega_o x) g(x)]$	$= \frac{1}{2} G(s - \omega_o) + \frac{1}{2} G(s + \omega_o)$	for $\mathbf{R}_e(s) \in [A + \mathbf{R}_e(\omega_o) : B - \mathbf{R}_e(\omega_o)]$	$\forall x, \omega_o \in \mathbb{C}$
	$\mathbf{L}[\sinh(\omega_o x) g(x)]$	$= \frac{1}{2} G(s - \omega_o) - \frac{1}{2} G(s + \omega_o)$	for $\mathbf{R}_e(s) \in [A + \mathbf{R}_e(\omega_o) : B - \mathbf{R}_e(\omega_o)]$	$\forall x, \omega_o \in \mathbb{C}$

⁷ [Bracewell \(1978\) page 224](#) (Table 11.1: “Modulation” entry), [Levy \(1958\) page 19](#) (Equation 1.2)

⁸ [Bracewell \(1978\) page 224](#) (Table 11.1 Theorems for the Laplace Transform)

 PROOF:

1. Mappings:

$$\begin{aligned}
 \mathbf{L}[\cosh(\omega_o x)g(x)] &= \mathbf{L}\left[\left(\frac{e^{\omega_o x} + e^{-\omega_o x}}{2}\right)g(x)\right] && \text{by definition of } \cosh(x) && (\text{Definition D.5 page 120}) \\
 &= \frac{1}{2}\mathbf{L}[e^{\omega_o x}g(x)](s) + \frac{1}{2}\mathbf{L}[e^{-\omega_o x}g(x)](s) && \text{by additive property} && (\text{Theorem 2.3 page 13}) \\
 &= \frac{1}{2}\mathbf{L}[g(x)](s - \omega) + \frac{1}{2}\mathbf{L}[g(x)](s + \omega) && \text{by modulation prop.} && (\text{Theorem 2.4 page 14}) \\
 &= \frac{1}{2}\mathbf{G}(s - \omega_o) + \frac{1}{2}\mathbf{G}(s + \omega_o) && \text{by definition of } \mathbf{G}(s)
 \end{aligned}$$

$$\begin{aligned}
 \mathbf{L}[\sinh(\omega_o x)g(x)] &= \mathbf{L}\left[\left(\frac{e^{\omega_o x} - e^{-\omega_o x}}{2}\right)g(x)\right] && \text{by definition of } \sinh(x) && (\text{Definition D.5 page 120}) \\
 &= \frac{1}{2}\mathbf{L}[e^{\omega_o x}g(x)](s) - \frac{1}{2}\mathbf{L}[e^{-\omega_o x}g(x)](s) && \text{by additive property} && (\text{Theorem 2.3 page 13}) \\
 &= \frac{1}{2}\mathbf{L}[g(x)](s - \omega) - \frac{1}{2}\mathbf{L}[g(x)](s + \omega) && \text{by modulation prop.} && (\text{Theorem 2.4 page 14}) \\
 &= \frac{1}{2}\mathbf{G}(s - \omega_o) - \frac{1}{2}\mathbf{G}(s + \omega_o) && \text{by definition of } \mathbf{G}(s)
 \end{aligned}$$

$$\begin{aligned}
 \mathbf{L}[\cos(\omega_o x)g(x)] &= \mathbf{L}[\cosh(i\omega_o x)g(x)] && \text{by Theorem D.12 page 121} \\
 &= \frac{1}{2}\mathbf{G}(s - i\omega_o) + \frac{1}{2}\mathbf{G}(s + i\omega_o) && \text{by } \mathbf{L}[\cos(\omega_o x)g(x)] \text{ result}
 \end{aligned}$$

$$\begin{aligned}
 \mathbf{L}[\sin(\omega_o x)g(x)] &= \mathbf{L}[-i^2 \sin(\omega_o x)g(x)] \\
 &= -i\mathbf{L}[i \sin(\omega_o x)g(x)] && \text{by homogeneous property} && (\text{Theorem 2.3 page 13}) \\
 &= -i\mathbf{L}[\sinh(i\omega_o x)g(x)] && \text{by Theorem D.12 page 121} \\
 &= -\frac{i}{2}\mathbf{G}(s - i\omega_o) + \frac{i}{2}\mathbf{G}(s + i\omega_o) && \text{by } \mathbf{L}[\sin(\omega_o x)g(x)] \text{ result}
 \end{aligned}$$

2. Region of Convergence of $\mathbf{L}[\cos(\omega_o x)g(x)]$ and $\mathbf{L}[\sin(\omega_o x)g(x)]$:

$$\begin{aligned}
 \mathbf{RocL}[\cos/\sin(\omega_o x)g(x)] &= \mathbf{RocL}\left[\left(\frac{e^{i\omega_o x} \pm e^{-i\omega_o x}}{2}\right)g(x)\right] && \text{by Euler's Identity} && (\text{Theorem D.5 page 112}) \\
 &= \mathbf{Roc}\left(\mathbf{L}\left[\frac{e^{i\omega_o x}}{2}g(x)\right] \pm \mathbf{L}\left[\frac{e^{-i\omega_o x}}{2}g(x)\right]\right) && \text{by additive property} && (\text{Theorem 2.3 page 13}) \\
 &= \mathbf{RocL}\left[\left(\frac{e^{-i\omega_o x}}{2}\right)g(x)\right] \cap \mathbf{RocL}\left[\left(\frac{e^{i\omega_o x}}{2}\right)g(x)\right] \\
 &= [A - \mathbf{R}_e(i\omega) : B - \mathbf{R}_e(i\omega)] \cap [A - \mathbf{R}_e(-i\omega) : B - \mathbf{R}_e(-i\omega)] \\
 &= [A - 0 : B - 0] \cap [A - 0 : B - 0] \\
 &= [A : B]
 \end{aligned}$$

3. Region of Convergence of $\mathbf{L}[\cosh(\omega_o x)g(x)]$ and $\mathbf{L}[\sinh(\omega_o x)g(x)]$:

$$\begin{aligned}
 \mathbf{RocL}[\cosh/\sinh(\omega_o x)g(x)] &= \mathbf{RocL}\left[\left(\frac{e^{\omega_o x} \pm e^{-\omega_o x}}{2}\right)g(x)\right] && \text{by def. } \cosh(x), \sinh(x) && (\text{Definition D.5 page 120})
 \end{aligned}$$

$$\begin{aligned}
&= \mathbf{Roc} \left(\mathbf{L} \left[\frac{e^{\omega_o x}}{2} g(x) \right] \pm \mathbf{L} \left[\frac{e^{-\omega_o x}}{2} g(x) \right] \right) && \text{by additive property} && (\text{Theorem 2.3 page 13}) \\
&= \mathbf{RocL} \left[\left(\frac{e^{-\omega_o x}}{2} \right) g(x) \right] \cap \mathbf{RocL} \left[\left(\frac{e^{\omega_o x}}{2} \right) g(x) \right] \\
&= [A - \mathbf{R}_e(\omega_o) : B - \mathbf{R}_e(\omega_o)] \cap [A - \mathbf{R}_e(-\omega_o) : B - \mathbf{R}_e(-\omega_o)] \\
&= \begin{cases} [A + \mathbf{R}_e(\omega_o) : B - \mathbf{R}_e(\omega_o)] & \text{for } \omega \geq 0 \\ [A - \mathbf{R}_e(\omega_o) : B + \mathbf{R}_e(\omega_o)] & \text{otherwise} \end{cases} \\
&= [A + |\mathbf{R}_e(\omega_o)| : B - |\mathbf{R}_e(\omega_o)|] && \text{by definition of } |x|
\end{aligned}$$



2.6 Causality properties

Definition 2.3.⁹ The *Heaviside step function* $\mu(x)$ or *unit step function* is defined as

DEF $\mu(x) \triangleq \begin{cases} 1 & \forall x \geq 0 \\ 0 & \text{otherwise} \end{cases}$

Theorem 2.5.¹⁰ Let \mathbf{L} be the LAPLACE TRANSFORM operator (Definition 2.1 page 11) and $\mu(x)$ the UNIT STEP function (Definition 2.3 page 16).

	Mapping	Region of Convergence	Domain
THM	(1). $\mathbf{L}[\mu(x)] = \frac{1}{s}$	for $\mathbf{R}_e(s) > 0$	$\forall x \in \mathbb{R}$
	(2). $\mathbf{L}[\mu(-x)] = -\frac{1}{s}$	for $\mathbf{R}_e(s) < 0$	$\forall x \in \mathbb{R}$

PROOF:

$$\begin{aligned}
\mathbf{L}[\mu(x)] &\triangleq \int_{\mathbb{R}} \mu(x) e^{-sx} dx && \text{by definition of } \mathbf{L} && (\text{Definition 2.1 page 11}) \\
&= \int_0^{\infty} e^{-sx} dx && \text{by definition of } \mu(x) && (\text{Definition 2.3 page 16}) \\
&= \frac{e^{-sx}}{-s} \Big|_0^{\infty} && \text{by Fundamental Theorem of Calculus} \\
&= \lim_{x \rightarrow \infty} \left[\frac{e^{-sx}}{-s} \right] - \left(\frac{e^0}{-s} \right) \\
&= 0 + \frac{1}{s} && \forall \mathbf{R}_e(s) > 0 \\
&= \frac{1}{s} && \forall \mathbf{R}_e(s) > 0 \\
\mathbf{L}[\mu(-x)] &= \mathbf{L}[\mu(x)](-s) && \mathbf{R}_e(s) < 0 && \text{by reversal property} && (\text{Corollary 2.1 page 13}) \\
&= \frac{-1}{s} && \mathbf{R}_e(s) < 0 && \text{by (1)}
\end{aligned}$$



⁹ Betten (2008a) page 285

¹⁰ Bracewell (1978) page 227 (Table 11.2 Some Laplace transforms)

Corollary 2.4. ¹¹ Let \mathbf{L} be the LAPLACE TRANSFORM operator (Definition 2.1 page 11) and $\mu(x)$ the UNIT STEP function.

Mapping	Region of Convergence	Domain
$\mathbf{L}[e^{-\alpha x}\mu(x)] = \frac{1}{s+\alpha}$	for $\mathbf{R}_e(s) > -\mathbf{R}_e(\alpha)$	$\forall x \in \mathbb{R}; \alpha \in \mathbb{C}$
$\mathbf{L}[e^{-\alpha x}\mu(-x)] = \frac{1}{s+\alpha}$	for $\mathbf{R}_e(s) < \mathbf{R}_e(\alpha)$	$\forall x \in \mathbb{R}; \alpha \in \mathbb{C}$

✎ PROOF:

$$\begin{aligned} \mathbf{L}[e^{-\alpha x}\mu(x)](s) &= \mathbf{L}[\mu(x)](s+\alpha) && \text{by modulation} && (\text{Theorem 2.4 page 14}) \\ &= \frac{1}{s+\alpha} && \forall \mathbf{R}_e(s) \in (0 - \mathbf{R}_e(\alpha) : \infty - \mathbf{R}_e(\alpha)) \text{ by Theorem 2.5 page 16} \\ &= \frac{1}{s+\alpha} && \forall \mathbf{R}_e(s) > -\mathbf{R}_e(\alpha) \end{aligned}$$

$$\begin{aligned} \mathbf{L}[e^{-\alpha x}\mu(-x)](s) &= \mathbf{L}[\mu(-x)](s+\alpha) && \text{by modulation} && (\text{Theorem 2.4 page 14}) \\ &= \frac{-1}{s+\alpha} && \forall \mathbf{R}_e(s) \in (-\infty - \mathbf{R}_e(\alpha) : 0 - (-\mathbf{R}_e(\alpha))) \text{ by Theorem 2.5 page 16} \\ &= \frac{-1}{s+\alpha} && \forall \mathbf{R}_e(s) < \mathbf{R}_e(\alpha) && \text{by anti-causality} && (\text{Theorem 2.5 page 16}) \end{aligned}$$

⇒

Corollary 2.5. ¹² Let \mathbf{L} be the LAPLACE TRANSFORM operator (Definition 2.1 page 11) and $\mu(x)$ the UNIT STEP function.

Mapping	Region of Convergence	Domain
(1). $\mathbf{L}[\cos(\omega_o x)\mu(x)] = \frac{s}{s^2 + \omega_o^2}$	for $\mathbf{R}_e(s) > 0$	$x, \omega_o \in \mathbb{R}$
(2). $\mathbf{L}[\sin(\omega_o x)\mu(x)] = \frac{\omega_o}{s^2 + \omega_o^2}$	for $\mathbf{R}_e(s) > 0$	$x, \omega_o \in \mathbb{R}$
(3). $\mathbf{L}[\cos(\omega_o x)\mu(-x)] = \frac{-s}{s^2 + \omega_o^2}$	for $\mathbf{R}_e(s) < 0$	$x, \omega_o \in \mathbb{R}$
(4). $\mathbf{L}[\sin(\omega_o x)\mu(-x)] = \frac{-\omega_o}{s^2 + \omega_o^2}$	for $\mathbf{R}_e(s) < 0$	$x, \omega_o \in \mathbb{R}$

✎ PROOF:

$$\begin{aligned} \mathbf{L}[\cos(\omega_o x)\mu(x)](s) &= \frac{1}{2}\mathbf{L}[\mu(x)](s - i\omega_o) + \frac{1}{2}\mathbf{L}[\mu(x)](s + i\omega_o) && \text{by modulation} && (\text{Corollary 2.3 page 14}) \\ &= \frac{1}{2}\left[\frac{1}{s - i\omega_o}\right] + \frac{1}{2}\left[\frac{1}{s + i\omega_o}\right] && \mathbf{R}_e(s) > 0 \text{ by causal prop.} && (\text{Theorem 2.5 page 16}) \\ &= \frac{1}{2}\left[\frac{1}{s - i\omega_o}\right]\left[\frac{s + i\omega_o}{s + i\omega_o}\right] + \frac{1}{2}\left[\frac{1}{s + i\omega_o}\right]\left[\frac{s - i\omega_o}{s - i\omega_o}\right] && (\text{Rationalizing the Denominator}) \\ &= \frac{1}{2}\left[\frac{(s + i\omega_o) + (s - i\omega_o)}{s^2 + \omega_o^2}\right] && \mathbf{R}_e(s) > 0 \\ &= \frac{s}{s^2 + \omega_o^2} && \mathbf{R}_e(s) > 0 \end{aligned}$$

¹¹ van der Pol and Bremmer (1959) page 22 (Introduction), Shafii-Mousavi (2015) page 3 (Table 1, using One-Sided Laplace Transform), van der Pol and Bremmer (1959) page 26 (8) seems to have an error: $\frac{s}{s+\alpha}$

¹² Bracewell (1978) page 227 (Table 11.2 Some Laplace transforms), Shafii-Mousavi (2015) page 3 (Table 1, using One-Sided Laplace Transform)

$$\begin{aligned}
\mathbf{L}[\sin(\omega_o x)\mu(x)](s) &= -\frac{i}{2}\mathbf{L}[\mu(x)](s - i\omega_o) + \frac{i}{2}\mathbf{L}[\mu(x)](s + i\omega_o) && \text{by modulation} \quad (\text{Corollary 2.3 page 14}) \\
&= -\frac{i}{2}\left[\frac{1}{s - i\omega_o}\right] + \frac{i}{2}\left[\frac{1}{s + i\omega_o}\right] && \mathbf{R}_e(s) > 0 \quad \text{by causal prop.} \quad (\text{Theorem 2.5 page 16}) \\
&= -\frac{i}{2}\left[\frac{1}{s - i\omega_o}\right]\left[\frac{s + i\omega_o}{s + i\omega_o}\right] + \frac{i}{2}\left[\frac{1}{s + i\omega_o}\right]\left[\frac{s - i\omega_o}{s - i\omega_o}\right] && (\text{Rationalizing the Denominator}) \\
&= \frac{i}{2}\left[\frac{-(s + i\omega_o) + (s - i\omega_o)}{s^2 + \omega_o^2}\right] && \mathbf{R}_e(s) > 0 \\
&= \frac{\omega_o}{s^2 + \omega_o^2} && \mathbf{R}_e(s) > 0
\end{aligned}$$

$$\begin{aligned}
\mathbf{L}[\mu(-x)\cos(\omega_o x)](s) &= \mathbf{L}[\mu(-x)\cos(\omega_o(-x))](s) && \text{by even property of } \cos(x) \quad (\text{Theorem D.2 page 109}) \\
&= \mathbf{L}[\mu(x)\cos(\omega_o x)](-s) && \text{by reversal property} \quad (\text{Corollary 2.1 page 13}) \\
&= \frac{(-s)}{(-s)^2 + \omega_o^2} && \mathbf{R}_e(s) < 0 \quad \text{by (1)} \\
&= \frac{-s}{s^2 + \omega_o^2} && \mathbf{R}_e(s) < 0 \\
\mathbf{L}[\sin(\omega_o x)\mu(-x)](s) &= \mathbf{L}[-\sin(\omega_o(-x))\mu(-x)](s) && \text{by odd property of } \sin(x) \quad (\text{Theorem D.2 page 109}) \\
&= -\mathbf{L}[\sin(\omega_o(-x))\mu(-x)](s) && \text{by homogeneous property} \quad (\text{Theorem 2.3 page 13}) \\
&= -\mathbf{L}[\sin(\omega_o x)\mu(x)](-s) && \text{by reversal property} \quad (\text{Corollary 2.1 page 13}) \\
&= -\left[\frac{\omega_o}{(-s)^2 + \omega_o^2}\right] && \mathbf{R}_e(s) < 0 \quad \text{by (2)} \\
&= \frac{-\omega_o}{s^2 + \omega_o^2} && \mathbf{R}_e(s) < 0
\end{aligned}$$

⇒


Corollary 2.6. ¹³ Let \mathbf{L} be the LAPLACE TRANSFORM operator (Definition 2.1 page 11) and $\mu(x)$ the UNIT STEP function.

	Mapping	Region of Convergence	Domain
(1).	$\mathbf{L}[\cosh(\omega_o x)\mu(x)] = \frac{s}{s^2 - \omega_o^2}$	for $\mathbf{R}_e(s) > \omega_o $	$x, \omega_o \in \mathbb{R}$
(2).	$\mathbf{L}[\sinh(\omega_o x)\mu(x)] = \frac{\omega_o}{s^2 - \omega_o^2}$	for $\mathbf{R}_e(s) > \omega_o $	$x, \omega_o \in \mathbb{R}$
(3).	$\mathbf{L}[\sinh(\omega_o x)\mu(-x)] = \frac{-s}{s^2 - \omega_o^2}$	for $\mathbf{R}_e(s) < \omega_o $	$x, \omega_o \in \mathbb{R}$
(4).	$\mathbf{L}[\sinh(\omega_o x)\mu(-x)] = \frac{-\omega_o}{s^2 - \omega_o^2}$	for $\mathbf{R}_e(s) < \omega_o $	$x, \omega_o \in \mathbb{R}$

PROOF:

1. Mappings for $\mathbf{L}[\cosh(\omega_o x)\mu(x)]$ and $\mathbf{L}[\sinh(\omega_o x)\mu(x)]$:

$$\begin{aligned}
\mathbf{L}[\cosh(\omega_o x)\mu(x)](s) &= \frac{1}{2}\mathbf{L}[\mu(x)](s - \omega_o) + \frac{1}{2}\mathbf{L}[\mu(x)](s + \omega_o) && \text{by modulation} \quad (\text{Corollary 2.3 page 14}) \\
&= \frac{1}{2}\left[\frac{1}{s - \omega_o}\right] + \frac{1}{2}\left[\frac{1}{s + \omega_o}\right] && \text{by causal property} \quad (\text{Theorem 2.5 page 16})
\end{aligned}$$

¹³  Shafii-Mousavi (2015) page 3 (Table 1, using One-Sided Laplace Transform)

$$\begin{aligned}
&= \frac{1}{2} \left[\frac{1}{s - \omega_o} \right] \left[\frac{s + \omega_o}{s + \omega_o} \right] + \frac{1}{2} \left[\frac{1}{s + \omega_o} \right] \left[\frac{s - \omega_o}{s - \omega_o} \right] \\
&= \frac{1}{2} \left[\frac{(s + \omega_o) + (s - \omega_o)}{s^2 - \omega_o^2} \right] \\
&= \frac{s}{s^2 - \omega_o^2}
\end{aligned}$$

$$\begin{aligned}
\mathbf{L}[\sinh(\omega_o x)\mu(x)](s) &= \frac{1}{2}\mathbf{L}[\mu(x)](s - \omega_o) - \frac{1}{2}\mathbf{L}[\mu(x)](s + \omega_o) \quad \text{by modulation} \quad (\text{Corollary 2.3 page 14}) \\
&= \frac{1}{2} \left[\frac{1}{s - \omega_o} \right] - \frac{1}{2} \left[\frac{1}{s + \omega_o} \right] \quad \text{by causal property} \quad (\text{Theorem 2.5 page 16}) \\
&= \frac{1}{2} \left[\frac{1}{s - \omega_o} \right] \left[\frac{s + \omega_o}{s + \omega_o} \right] - \frac{1}{2} \left[\frac{1}{s + \omega_o} \right] \left[\frac{s - \omega_o}{s - \omega_o} \right] \\
&= \frac{1}{2} \left[\frac{(s + \omega_o) - (s - \omega_o)}{s^2 - \omega_o^2} \right] \\
&= \frac{\omega_o}{s^2 - \omega_o^2}
\end{aligned}$$

2. Region of Convergence of $\mathbf{L}[\cosh(\omega_o x)\mu(x)]$ and $\mathbf{L}[\sinh(\omega_o x)\mu(x)]$:

$$\begin{aligned}
\mathbf{RocL}[\cosh(\omega_o x)\mu(x)] &= [A + |\mathbf{R}_e(\omega_o)| : B - |\mathbf{R}_e(\omega_o)|] \quad \text{by Corollary 2.3 page 14} \\
&= (0 + |\mathbf{R}_e(\omega_o)| : \infty - |\mathbf{R}_e(\omega_o)|) \quad \text{by Theorem 2.5 page 16} \\
&= (|\mathbf{R}_e(\omega_o)| : \infty) \\
&\implies \mathbf{RocL}[\cosh(\omega_o x)\mu(x)] > |\mathbf{R}_e(\omega_o)|
\end{aligned}$$

3. Mappings for $\mathbf{L}[\cosh(\omega_o x)\mu(-x)]$ and $\mathbf{L}[\sinh(\omega_o x)\mu(-x)]$:

$$\begin{aligned}
\mathbf{L}[\cosh(\omega_o x)\mu(-x)](s) &= \mathbf{L}[\cosh(\omega_o(-x))\mu(-x)](s) \\
&= \mathbf{L}[\cosh(\omega_o x)\mu(x)](-s) \quad \text{by reversal property} \quad (\text{Corollary 2.1 page 13}) \\
&= \frac{(-s)}{(-s)^2 - \omega_o^2} \quad \text{by previous result} \\
&= \frac{-s}{s^2 - \omega_o^2}
\end{aligned}$$

$$\begin{aligned}
\mathbf{L}[\sinh(\omega_o x)\mu(-x)](s) &= \mathbf{L}[-\sinh(\omega_o(-x))\mu(-x)](s) \\
&= -\mathbf{L}[\sinh(\omega_o(-x))\mu(-x)](s) \quad \text{by homogeneous property} \quad (\text{Theorem 2.3 page 13}) \\
&= -\mathbf{L}[\sinh(\omega_o x)\mu(x)](-s) \quad \text{by reversal property} \quad (\text{Corollary 2.1 page 13}) \\
&= \frac{-\omega_o}{(-s)^2 - \omega_o^2} \quad \text{by previous result} \\
&= \frac{-\omega_o}{s^2 - \omega_o^2}
\end{aligned}$$

4. Region of Convergence of $\mathbf{L}[\cosh(\omega_o x)\mu(-x)]$ and $\mathbf{L}[\sinh(\omega_o x)\mu(-x)]$:

$$\begin{aligned}
\mathbf{RocL}[\cosh(\omega_o x)\mu(-x)] &= [A + |\mathbf{R}_e(\omega_o)| : B - |\mathbf{R}_e(\omega_o)|] \quad \text{by Corollary 2.3 page 14} \\
&= (-\infty + |\mathbf{R}_e(\omega_o)| : 0 - |\mathbf{R}_e(\omega_o)|) \quad \text{by Theorem 2.5 page 16} \\
&= (-\infty : |\mathbf{R}_e(\omega_o)|) \\
&\implies \mathbf{RocL}[\cosh(\omega_o x)\mu(-x)] < |\mathbf{R}_e(\omega_o)|
\end{aligned}$$

Corollary 2.7. ¹⁴ Let \mathbf{L} be the LAPLACE TRANSFORM operator (Definition 2.1 page 11) and $\mu(x)$ the UNIT STEP function.

	Mapping	Region of Convergence	Domain
C O R	(1). $\mathbf{L}[\cos(\omega_o x)e^{-\alpha x}\mu(x)]$	$= \frac{s + \alpha}{(s + \alpha)^2 + \omega_o^2}$	for $\mathbf{R}_e(s) > -\mathbf{R}_e(\alpha)$ $x, \omega_o \in \mathbb{R}; \alpha \in \mathbb{C}$
	(2). $\mathbf{L}[\sin(\omega_o x)e^{-\alpha x}\mu(x)]$	$= \frac{\omega_o}{(s + \alpha)^2 + \omega_o^2}$	for $\mathbf{R}_e(s) > -\mathbf{R}_e(\alpha)$ $x, \omega_o \in \mathbb{R}; \alpha \in \mathbb{C}$
	(3). $\mathbf{L}[\cos(\omega_o x)e^{\alpha x}\mu(-x)]$	$= \frac{-s + \alpha}{(s - \alpha)^2 + \omega_o^2}$	for $\mathbf{R}_e(s) > -\mathbf{R}_e(\alpha)$ $x, \omega_o \in \mathbb{R}; \alpha \in \mathbb{C}$
	(4). $\mathbf{L}[\sin(\omega_o x)e^{\alpha x}\mu(-x)]$	$= \frac{-\omega_o}{(s - \alpha)^2 + \omega_o^2}$	for $\mathbf{R}_e(s) > -\mathbf{R}_e(\alpha)$ $x, \omega_o \in \mathbb{R}; \alpha \in \mathbb{C}$

PROOF:

$$\begin{aligned}
 \mathbf{L}[\cos(\omega_o x)e^{-\alpha x}\mu(x)](s) &= \mathbf{L}[\mu(x)\cos(\omega_o x)](s + \alpha) && \text{by modulation property} && (\text{Theorem 2.4 page 14}) \\
 &= \frac{s + \alpha}{(s + \alpha)^2 + \omega_o^2} && \forall \mathbf{R}_e(s) \in (0 - \mathbf{R}_e(\alpha) : \infty - \mathbf{R}_e(\alpha)) && \text{by Corollary 2.5} \\
 &= \frac{s + \alpha}{(s + \alpha)^2 + \omega_o^2} && \forall \mathbf{R}_e(s) > -\mathbf{R}_e(\alpha) && \\
 \mathbf{L}[\sin(\omega_o x)e^{-\alpha x}\mu(x)](s) &= \mathbf{L}[\mu(x)\sin(\omega_o x)](s + \alpha) && \text{by modulation property} && (\text{Theorem 2.4 page 14}) \\
 &= \frac{\omega_o}{(s + \alpha)^2 + \omega_o^2} && \forall \mathbf{R}_e(s) \in (0 - \mathbf{R}_e(\alpha) : \infty - \mathbf{R}_e(\alpha)) && \text{by Corollary 2.5} \\
 &= \frac{\omega_o}{(s + \alpha)^2 + \omega_o^2} && \forall \mathbf{R}_e(s) > -\mathbf{R}_e(\alpha) && \\
 \mathbf{L}[\cos(\omega_o x)e^{\alpha x}\mu(-x)](s) &= \mathbf{L}[\mu(-x)\cos(\omega_o x)](s - \alpha) && \text{by modulation property} && (\text{Theorem 2.4 page 14}) \\
 &= \frac{-(s - \alpha)}{(s - \alpha)^2 + \omega_o^2} && \forall \mathbf{R}_e(s) \in (0 - \mathbf{R}_e(\alpha) : \infty - \mathbf{R}_e(\alpha)) && \text{by Corollary 2.5} \\
 &= \frac{-s + \alpha}{(s - \alpha)^2 + \omega_o^2} && \forall \mathbf{R}_e(s) > -\mathbf{R}_e(\alpha) && \\
 \mathbf{L}[\sin(\omega_o x)e^{\alpha x}\mu(-x)](s) &= \mathbf{L}[\mu(-x)\sin(\omega_o x)](s - \alpha) && \text{by modulation property} && (\text{Theorem 2.4 page 14}) \\
 &= \frac{-\omega_o}{(s - \alpha)^2 + \omega_o^2} && \forall \mathbf{R}_e(s) \in (0 - \mathbf{R}_e(\alpha) : \infty - \mathbf{R}_e(\alpha)) && \text{by Corollary 2.5} \\
 &= \frac{-\omega_o}{(s - \alpha)^2 + \omega_o^2} && \forall \mathbf{R}_e(s) > -\mathbf{R}_e(\alpha) &&
 \end{aligned}$$

⇒

Corollary 2.8. Let \mathbf{L} be the LAPLACE TRANSFORM operator (Definition 2.1 page 11).

C O R	$\mathbf{L}[\cos(\omega_o x)]$	is divergent	$\forall s \in \mathbb{C}$	$\forall x, \omega_o \in \mathbb{R}$
	$\mathbf{L}[\sin(\omega_o x)]$	is divergent	$\forall s \in \mathbb{C}$	$\forall x, \omega_o \in \mathbb{R} \setminus \{0\}$

PROOF:

$$\begin{aligned}
 \mathbf{L}[\cos(\omega_o x)] &= \underbrace{\mathbf{L}[\mu(x)\cos(\omega_o x)]}_{\forall \mathbf{R}_e(s) > 0} + \underbrace{\mathbf{L}[\mu(-x)\cos(\omega_o x)]}_{\forall \mathbf{R}_e(s) < 0} && \text{by Corollary 2.5 page 17} \\
 &= \underbrace{\frac{s}{s^2 + \omega_o^2}}_{\forall \mathbf{R}_e(s) > 0} + \underbrace{\frac{-s}{s^2 + \omega_o^2}}_{\forall \mathbf{R}_e(s) < 0} && \text{by Corollary 2.5 page 17}
 \end{aligned}$$

¹⁴ Bracewell (1978) page 227 (Table 11.2 Some Laplace transforms)

$$\begin{aligned}
&= \begin{cases} 0 & \forall \mathbf{R}_e(s) \in (-\infty : 0) \cap (0 : \infty) = \emptyset \\ \infty & \forall s \in \mathbb{C} \end{cases} \\
&\Rightarrow \mathbf{L}[\cos(\omega_o x)] \text{ is } \mathbf{divergent} \forall s \in \mathbb{C} \\
\mathbf{L}[\sin(\omega_o x)] &= \underbrace{\mathbf{L}[\mu(x)\sin(\omega_o x)]}_{\forall \mathbf{R}_e(s) > 0} + \underbrace{\mathbf{L}[\mu(-x)\sin(\omega_o x)]}_{\forall \mathbf{R}_e(s) < 0} && \text{by Corollary 2.5 page 17} \\
&= \underbrace{\frac{\omega_o}{s^2 + \omega_o^2}}_{\forall \mathbf{R}_e(s) > 0} + \underbrace{\frac{-\omega_o}{s^2 + \omega_o^2}}_{\forall \mathbf{R}_e(s) < 0} && \text{by Corollary 2.5 page 17} \\
&= \begin{cases} 0 & \forall \mathbf{R}_e(s) \in (-\infty : 0) \cap (0 : \infty) = \emptyset \\ \infty & \forall s \in \mathbb{C} \end{cases} \\
&\Rightarrow \mathbf{L}[\sin(\omega_o x)] \text{ is } \mathbf{divergent} \forall s \in \mathbb{C}
\end{aligned}$$

⇒

2.7 Exponential decay properties

Corollary 2.9. ¹⁵ Let \mathbf{L} be the LAPLACE TRANSFORM operator (Definition 2.1 page 11) and $\mu(x)$ the UNIT STEP function. Let $A \triangleq \mathbf{R}_e(\alpha)$.

C O R	Mapping	Region of Convergence	Domain
	$\mathbf{L}[e^{-\alpha x }] = \frac{2\alpha}{\alpha^2 - s^2}$	for $\mathbf{R}_e(s) \in (-A : A)$	$x, \alpha \in \mathbb{C}$

PROOF:

$$\begin{aligned}
\mathbf{L}[e^{-\alpha|x|}] &= \mathbf{L}[e^{-\alpha|x|}\mu(x) + e^{-\alpha|x|}\mu(-x)] && \text{by definition of } \mu(x) && \text{(Definition 2.3 page 16)} \\
&= \mathbf{L}[e^{-\alpha|x|}\mu(x)] + \mathbf{L}[e^{-\alpha|x|}\mu(-x)] && \text{by homogeneous property} && \text{(Theorem 2.3 page 13)} \\
&= \underbrace{\mathbf{L}[e^{-\alpha x}\mu(x)]}_{\mathbf{R}_e(s) > -\mathbf{R}_e(\alpha)} + \underbrace{\mathbf{L}[e^{\alpha x}\mu(-x)]}_{\mathbf{R}_e(s) < \mathbf{R}_e(\alpha)} && \text{by Definition 2.3 page 16} && \text{and Corollary 2.4 page 17} \\
&= \left[\frac{1}{s + \alpha} \right] + \left[\frac{-1}{s - \alpha} \right] && \forall \mathbf{R}_e(s) \in (-\mathbf{R}_e(\alpha) : \mathbf{R}_e(\alpha)) && \text{by Corollary 2.4 page 17} \\
&= \frac{(s - \alpha) - (s + \alpha)}{(s + \alpha)(s - \alpha)} && \forall \mathbf{R}_e(s) \in (-\mathbf{R}_e(\alpha) : \mathbf{R}_e(\alpha)) \\
&= \frac{2\alpha}{\alpha^2 - s^2} && \forall \mathbf{R}_e(s) \in (-\mathbf{R}_e(\alpha) : \mathbf{R}_e(\alpha))
\end{aligned}$$

⇒

Corollary 2.10. ¹⁶ Let \mathbf{L} be the LAPLACE TRANSFORM operator (Definition 2.1 page 11) and $\mu(x)$ the UNIT STEP function. Let $A \triangleq \mathbf{R}_e(\alpha)$.

C O R	Mapping	Region of Convergence	Domain
	(1). $\mathbf{L}[\cos(\omega_o x)e^{-\alpha x }\mu(x)] = \frac{s + \alpha}{(s + \alpha)^2 + \omega_o^2}$	for $\mathbf{R}_e(s) \in (-A : A)$	$x, \alpha \in \mathbb{R}$
	(2). $\mathbf{L}[\cos(\omega_o x)e^{-\alpha x }\mu(-x)] = \frac{-s + \alpha}{(s - \alpha)^2 + \omega_o^2}$	for $\mathbf{R}_e(s) \in (-A : A)$	$x, \alpha \in \mathbb{R}$
	(3). $\mathbf{L}[\cos(\omega_o x)e^{-\alpha x }] = \frac{s + \alpha}{(s + \alpha)^2 + \omega_o^2} + \frac{-s + \alpha}{(s - \alpha)^2 + \omega_o^2}$	for $\mathbf{R}_e(s) \in (-A : A)$	$x, \alpha \in \mathbb{R}$

¹⁵ Bracewell (1978) page 227 (Table 11.2 Some Laplace transforms),

¹⁶ Bracewell (1978) page 227 (Table 11.2 Some Laplace transforms), Levy (1958) page 19 (with $\psi = 0$, $\alpha_0 = \alpha$, and $\alpha_1 = 1$), http://ece-research.unm.edu/bsanthan/ece541/table_ME.pdf

✎ PROOF:

1. Proof for (1):

$$\begin{aligned}
 & \mathbf{L}[\cos(\omega_o x) e^{-\alpha|x|} \mu(x)](s) \\
 &= \mathbf{L}[\cos(\omega_o x) e^{-\alpha x} \mu(x)](s) && \text{by definition of } \mu(x) \quad (\text{Definition 2.3 page 16}) \\
 &= \mathbf{L}[\cos(\omega_o x) \mu(x)](s + \alpha) \quad \forall \mathbf{R}_e(s) \in (0 - \mathbf{R}_e(\alpha) : \infty - \mathbf{R}_e(\alpha)) && \text{by modulation prop.} \quad (\text{Theorem 2.4 page 14}) \\
 &= \frac{s + \alpha}{(s + \alpha)^2 + \omega_o^2} \quad \forall \mathbf{R}_e(s) \in (-\mathbf{R}_e(\alpha) : \mathbf{R}_e(\alpha)) && \text{by Corollary 2.5 page 17}
 \end{aligned}$$

2. Proof for (2):

$$\begin{aligned}
 & \mathbf{L}[\cos(\omega_o x) e^{-\alpha|x|} \mu(-x)] \\
 &= \mathbf{L}[\cos(\omega_o x) e^{\alpha x} \mu(-x)] && \text{by definition of } \mu(x) \quad (\text{Definition 2.3 page 16}) \\
 &= \mathbf{L}[\cos(-\omega_o x) e^{\alpha x} \mu(-x)] && \text{by even property of } \cos(x) \quad (\text{Theorem D.2 page 109}) \\
 &= \mathbf{L}[e^{\alpha x} \cos(\omega_o(-x)) \mu(-x)] \\
 &= \underbrace{\mathbf{L}[\cos(\omega_o(-x)) \mu(-x)]}_{g(x)}(s - \alpha) && \text{by modulation property} \quad (\text{Theorem 2.4 page 14}) \\
 &= \underbrace{\mathbf{L}[\cos(\omega_o(-x)) \mu(-x)]}_{g(x)}(s - \alpha) && \text{by modulation property} \quad (\text{Theorem 2.4 page 14}) \\
 &= \frac{-s + \alpha}{(s - \alpha)^2 + \omega_o^2} \quad \forall \mathbf{R}_e(s) \in (-\mathbf{R}_e(\alpha) : \mathbf{R}_e(\alpha)) && \text{by Corollary 2.5 and Theorem 2.4 page 14}
 \end{aligned}$$

3. Proof for (3):

$$\begin{aligned}
 \mathbf{L}[\cos(\omega_o x) e^{-\alpha|x|}] &= \mathbf{L}[\cos(\omega_o x) e^{-\alpha|x|} \mu(x)] + \mathbf{L}[\cos(\omega_o x) e^{-\alpha|x|} \mu(-x)] \\
 &= \mathbf{L}[\cos(\omega_o x) e^{-\alpha x} \mu(x)] + \mathbf{L}[\cos(-\omega_o x) e^{\alpha x} \mu(-x)] \\
 &= \frac{s + \alpha}{(s + \alpha)^2 + \omega_o^2} + \frac{-s + \alpha}{(s - \alpha)^2 + \omega_o^2} \quad \forall \mathbf{R}_e(s) \in (-\mathbf{R}_e(\alpha) : \mathbf{R}_e(\alpha))
 \end{aligned}$$

⇒

Corollary 2.11. ¹⁷ Let \mathbf{L} be the LAPLACE TRANSFORM operator (Definition 2.1 page 11) and $\mu(x)$ the UNIT STEP function. Let $A \triangleq \mathbf{R}_e(\alpha)$.

	Mapping	Region of Convergence	Domain
(1). $\mathbf{L}[\sin(\omega_o x) e^{-\alpha x } \mu(x)]$	$= \frac{\omega_o}{(s + \alpha)^2 + \omega_o^2}$	for $\mathbf{R}_e(s) \in (-A : A)$	$x, \alpha \in \mathbb{R}$
(2). $\mathbf{L}[\sin(\omega_o x) e^{-\alpha x } \mu(-x)]$	$= \frac{-\omega_o}{(s - \alpha)^2 + \omega_o^2}$	for $\mathbf{R}_e(s) \in (-A : A)$	$x, \alpha \in \mathbb{R}$
(3). $\mathbf{L}[\sin(\omega_o x) e^{-\alpha x }]$	$= \frac{\omega_o}{(s + \alpha)^2 + \omega_o^2} + \frac{-\omega_o}{(s - \alpha)^2 + \omega_o^2}$	for $\mathbf{R}_e(s) \in (-A : A)$	$x, \alpha \in \mathbb{R}$

✎ PROOF:

1. Proof for (1):

$$\begin{aligned}
 & \mathbf{L}[\sin(\omega_o x) e^{-\alpha|x|} \mu(x)] \\
 &= \mathbf{L}[\sin(\omega_o x) e^{-\alpha x} \mu(x)] && \text{by definition of } \mu(x) \quad (\text{Definition 2.3 page 16}) \\
 &= \frac{s + \alpha}{(\omega_o)^2 + \omega_o^2} \quad \forall \mathbf{R}_e(s) \in (-\mathbf{R}_e(\alpha) : \mathbf{R}_e(\alpha)) && \text{by Corollary 2.5 page 17 and Theorem 2.4 page 14}
 \end{aligned}$$

¹⁷ Bracewell (1978) page 227 (Table 11.2 Some Laplace transforms), Levy (1958) page 19 (with $\psi = 0$, $\alpha_0 = \alpha$, and $\alpha_1 = 1$), http://ece-research.unm.edu/bsanthan/ece541/table_ME.pdf

2. Proof for (2):

$$\begin{aligned}
 & \mathbf{L}[\sin(\omega_o x) e^{-\alpha|x|} \mu(-x)] \\
 &= \mathbf{L}[\sin(-\omega_o x) e^{\alpha x} \mu(-x)] && \text{by definition of } \mu(x) && (\text{Definition 2.3 page 16}) \\
 &= \mathbf{L}[-\sin(\omega_o x) e^{\alpha x} \mu(-x)] && \text{by odd property of } \sin(x) && (\text{Theorem D.2 page 109}) \\
 &= -\mathbf{L}[\sin(\omega_o x) e^{\alpha x} \mu(-x)] && \text{by homogeneous property} && (\text{Theorem 2.3 page 13}) \\
 &= \frac{-\omega_o}{(s - \alpha)^2 + \omega_o^2} && \forall \mathbf{R}_e(s) \in (-\mathbf{R}_e(\alpha) : \mathbf{R}_e(\alpha)) && \text{by Theorem 2.4 page 14 and Corollary 2.5}
 \end{aligned}$$

3. Proof for (3):

$$\begin{aligned}
 \mathbf{L}[\sin(\omega_o x) e^{-\alpha|x|}] &= \mathbf{L}[\sin(\omega_o x) e^{-\alpha|x|} \mu(x)] + \mathbf{L}[\sin(\omega_o x) e^{-\alpha|x|} \mu(-x)] \\
 &= \mathbf{L}[\sin(\omega_o x) e^{-\alpha x} \mu(x)] + \mathbf{L}[\sin(-\omega_o x) e^{\alpha x} \mu(-x)] \\
 &= \frac{\omega_o}{(s + \alpha)^2 + \omega_o^2} + \frac{-\omega_o}{(s - \alpha)^2 + \omega_o^2} && \forall \mathbf{R}_e(s) \in (-\mathbf{R}_e(\alpha) : \mathbf{R}_e(\alpha))
 \end{aligned}$$

⇒

2.8 Product properties

Theorem 2.6 (next) demonstrates that multiplication in the “time domain” is equivalent to convolution in the “s domain” and vice-versa.

Theorem 2.6 (convolution theorem).¹⁸ *Let \mathbf{L} be the LAPLACE TRANSFORM operator (Definition 2.1 page 11) and \star the convolution operator (Definition C.1 page 103). Let A , B , C , and D be defined as in Corollary 2.2 (page 13).*

T H M	$ \begin{aligned} \mathbf{L}[f(x) \star g(x)](s) &= [\mathbf{L}f](s) [\mathbf{L}g](s) && \forall \mathbf{R}_e(s) \in [A : B] \cap [C : D] && \forall f, g \in L^2_{(\mathbb{R}, \mathcal{B}, \mu)} \\ \mathbf{L}[f(x)g(x)](s) &= [\mathbf{L}f](s) \star [\mathbf{L}g](s) && \forall \mathbf{R}_e(s) \in [A + C : B + D], c \in (A : B) && \forall f, g \in L^2_{(\mathbb{R}, \mathcal{B}, \mu)}. \end{aligned} $
----------------------	---

✎ PROOF:

$$\begin{aligned}
 \mathbf{L}[f(x) \star g(x)](s) &= \mathbf{L}\left[\int_{u \in \mathbb{R}} f(u)g(x-u) du\right](s) && \text{by definition of } \star && (\text{Definition C.1 page 103}) \\
 &= \int_{u \in \mathbb{R}} f(u) [\mathbf{L}g(x-u)](s) du \\
 &= \int_{u \in \mathbb{R}} f(u) e^{-su} [\mathbf{L}g(x)](s) du && \text{by translation property} && (\text{Theorem 2.2 page 12}) \\
 &= \underbrace{\left(\int_{u \in \mathbb{R}} f(u) e^{-su} du\right)}_{[\mathbf{L}f](s)} [\mathbf{L}g](s) \\
 &= [\mathbf{L}f](s) [\mathbf{L}g](s) && \mathbf{R}_e(s) \in [A : B] \cap [C : D] && \text{by definition of } \mathbf{L}
 \end{aligned}$$

$$\begin{aligned}
 \mathbf{L}[f(x)g(x)](s) &= \mathbf{L}[(\mathbf{L}^{-1} \mathbf{L}f(x)) g(x)](s) && \text{by def. of operator inverse} && (\text{Definition G.3 page 154}) \\
 &= \mathbf{L}\left[\left(\int_{v \in \mathbb{R}} [\mathbf{L}f(x)](v) e^{sv} dv\right) g(x)\right](s) && \text{by Theorem 2.1 page 12}
 \end{aligned}$$

¹⁸ Bracewell (1978) page 224, Bachman et al. (2002) pages 268–270, Bachman (1964) page 8

$$\begin{aligned}
&= \int_{v \in \mathbb{R}} [\mathbf{L}f(x)](v) [\mathbf{L}(e^{sxv} g(x))](s, v) dv \\
&= \int_{v \in \mathbb{R}} [\mathbf{L}f(x)](v) [\mathbf{L}g(x)](s - v) dv && \text{by Theorem 2.2 page 12} \\
&= [\mathbf{L}f](s) \star [\mathbf{L}g](s) && \text{by definition of } \star \quad (\text{Definition C.1 page 103})
\end{aligned}$$

⇒

2.9 Calculus properties

Theorem 2.7. ¹⁹ Let \mathbf{L} be the LAPLACE TRANSFORM operator (Definition 2.1 page 11).

T H M

$$\begin{aligned}
\left\{ \lim_{x \rightarrow -\infty} g(x) = 0 \right\} &\implies \left\{ \mathbf{L} \left[\frac{d}{dx} g(x) \right] \right\} = s [\mathbf{L}g](s) \\
&\mathbf{L} \int_{u=-\infty}^{u=x} g(u) du = \frac{1}{s} [\mathbf{L}g](s)
\end{aligned}$$

PROOF:

$$\begin{aligned}
\mathbf{L} \left[\frac{d}{dx} g(x) \right] &\triangleq \int_{x \in \mathbb{R}} \underbrace{\left[\frac{d}{dx} g(x) \right]}_{dv} \underbrace{e^{-sx}}_u dx && \text{by definition of } \mathbf{L} \\
&= \underbrace{e^{-sx}}_u \underbrace{g(x)}_v \Big|_{x=-\infty}^{x=+\infty} - \int_{x \in \mathbb{R}} \underbrace{g(x)}_v \underbrace{(-s)e^{-sx}}_{du} dx && \text{by Integration by Parts} \\
&= \cancel{e^{-s\infty}} \cancel{0} - \cancel{e^{s\infty}} \cancel{g(-\infty)} \cancel{0} (-s) \int_{x \in \mathbb{R}} g(x) e^{-sx} dx && \text{by left hypothesis} \\
&\triangleq s [\mathbf{L}g](s) && \text{by definition of } \mathbf{L} \quad (\text{Definition 2.1 page 11})
\end{aligned}$$

$$\begin{aligned}
\mathbf{L} \int_{u=-\infty}^{u=x} g(u) du &\triangleq \int_{x=-\infty}^{x=+\infty} \left[\int_{u=-\infty}^{u=x} g(u) du \right] e^{-sx} dx && \text{by definition of } \mathbf{L} \\
&= \int_{x=-\infty}^{x=+\infty} \left[\int_{u=-\infty}^{u=+\infty} g(u) \mu(x-u) du \right] e^{-sx} dx \\
&= \int_{v=-\infty}^{v=+\infty} \int_{u=-\infty}^{u=+\infty} g(u) h(v) e^{-s(u+v)} du dv && \left(\begin{array}{l} \text{where } v \triangleq x - u \\ \implies x = u + v \end{array} \right) \\
&= \left[\int_{v=-\infty}^{v=+\infty} \mu(v) e^{-sv} dv \right] \underbrace{\left[\int_{u=-\infty}^{u=+\infty} g(u) e^{-su} du \right]}_{\text{Laplace Transform of } g(x)} \\
&= \left[\int_{v=0}^{v=\infty} e^{-sv} dv \right] [\mathbf{L}g](s) \\
&= \frac{1}{-s} e^{-sv} \Big|_{v=0}^{v=\infty} [\mathbf{L}g](s) && \text{by Fundamental Theorem of Calculus} \\
&= \frac{1}{s} [\mathbf{L}g](s) && \text{by definition of } \mathbf{L} \quad (\text{Definition 2.1 page 11})
\end{aligned}$$

⇒

¹⁹ Betten (2008b) page 301 (B.27), Levy (1958) page 15 (Equation 0.7)

CHAPTER 3

FOURIER TRANSFORM



“Up to this point we have supposed that the function whose development is required in a series of sines of multiple arcs can be developed in a series arranged according to powers of the variable x We can extend the same results to any functions, even to those which are discontinuous and entirely arbitrary. ... even entirely arbitrary functions may be developed in series of sines of multiple arcs.”

Joseph Fourier (1768–1830) ¹

3.1 Introduction

Historically, before the Fourier Transform was the Taylor Expansion (transform). The Taylor Expansion demonstrates that for **analytic** functions, knowledge of the derivatives of a function at a location $x = a$ allows you to determine (predict) arbitrarily closely all the points $f(x)$ in the vicinity of $x = a$ (CHAPTER 6 page 51). But analytic functions are by definition functions for which all their derivatives exist. Thus, if a function is *discontinuous*, it is simply not a candidate for the Taylor Expansion. And some 300 years ago, mathematician giants of the day were fairly content with this.

But then in came an engineer named Joseph Fourier whose day job was working as a governor of lower Egypt under Napoleon. He claimed that, rather than expansion based on derivatives, one could expand based on integrals over sinusoids, and that this would work not just for analytic functions, but for **discontinuous** ones as well!²

Needless to say, this did not go over too well initially in the mathematical community. But over time (on the order of 200 or so years), the Fourier Transform has in many ways won the day.



3



¹ quote:  Fourier (1878) page 184,186 (§219,220)

image: <http://en.wikipedia.org/wiki/File:Fourier2.jpg>, public domain

²  Robinson (1982) page 886

³ Caricature of Legendre (left) and Fourier (right), 1820, by Julien-Léopold Boilly (1796–1874). “Album de 73

3.2 Definitions

This chapter deals with the *Fourier Transform* in the space of *Lebesgue square-integrable functions* $L^2_{(\mathbb{R}, \mathcal{B}, \mu)}$, where \mathbb{R} is the set of real numbers, \mathcal{B} is the set of *Borel sets* on \mathbb{R} , μ is the standard *Borel measure* on \mathcal{B} , and

$$L^2_{(\mathbb{R}, \mathcal{B}, \mu)} \triangleq \left\{ f \in \mathbb{R}^{\mathbb{R}} \mid \int_{\mathbb{R}} |f|^2 d\mu < \infty \right\}.$$

Furthermore, $\langle \triangle | \nabla \rangle$ is the *inner product* induced by the operator $\int_{\mathbb{R}} d\mu$ such that

$$\langle f | g \rangle \triangleq \int_{\mathbb{R}} f(x)g^*(x) dx,$$

and $(L^2_{(\mathbb{R}, \mathcal{B}, \mu)}, \langle \triangle | \nabla \rangle)$ is a *Hilbert space*.

Definition 3.1. Let κ be a FUNCTION in $\mathbb{C}^{\mathbb{R}^2}$.

DEF

The function κ is the **Fourier kernel** if $\kappa(x, \omega) \triangleq e^{i\omega x} \quad \forall x, \omega \in \mathbb{R}$

Definition 3.2. ⁴ Let $L^2_{(\mathbb{R}, \mathcal{B}, \mu)}$ be the space of all LEBESGUE SQUARE-INTEGRABLE FUNCTIONS.

DEF

The **Fourier Transform** operator $\tilde{\mathbf{F}}$ is defined as

$$[\tilde{\mathbf{F}}f](\omega) \triangleq \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x) e^{-i\omega x} dx \quad \forall f \in L^2_{(\mathbb{R}, \mathcal{B}, \mu)}$$

This definition of the Fourier Transform is also called the **unitary Fourier Transform**.

Remark 3.1 (Fourier transform scaling factor). ⁵ If the Fourier transform operator $\tilde{\mathbf{F}}$ and inverse Fourier transform operator $\tilde{\mathbf{F}}^{-1}$ are defined as

$$\tilde{\mathbf{F}}f(x) \triangleq F(\omega) \triangleq A \int_{\mathbb{R}} f(x) e^{-i\omega x} dx \quad \text{and} \quad \tilde{\mathbf{F}}^{-1}\tilde{f}(\omega) \triangleq B \int_{\mathbb{R}} F(\omega) e^{i\omega x} d\omega$$

then A and B can be any constants as long as $AB = \frac{1}{2\pi}$. The Fourier transform is often defined with the scaling factor A set equal to 1 such that $[\tilde{\mathbf{F}}f(x)](\omega) \triangleq \int_{\mathbb{R}} f(x) e^{-i\omega x} dx$. In this case, the inverse Fourier transform operator $\tilde{\mathbf{F}}^{-1}$ is either defined as

$$\begin{aligned} \tilde{\mathbf{F}}^{-1}f(x) &\triangleq \int_{\mathbb{R}} f(x) e^{i2\pi f x} dx \quad (\text{using oscillatory frequency free variable } f) \text{ or} \\ \tilde{\mathbf{F}}^{-1}f(x) &\triangleq \frac{1}{2\pi} \int_{\mathbb{R}} f(x) e^{i\omega x} dx \quad (\text{using angular frequency free variable } \omega). \end{aligned}$$

In short, the 2π has to show up somewhere, either in the argument of the exponential ($e^{-i2\pi f t}$) or in front of the integral ($\frac{1}{2\pi} \int \dots$). One could argue that it is unnecessary to burden the exponential argument with the 2π factor ($e^{-i2\pi f t}$), and thus could further argue in favor of using the angular frequency variable ω thus giving the inverse operator definition $[\tilde{\mathbf{F}}^{-1}f(x)](\omega) \triangleq \frac{1}{2\pi} \int_{\mathbb{R}} f(x) e^{-i\omega x} dx$. But this causes a new problem. In this case, the Fourier operator $\tilde{\mathbf{F}}$ is not *unitary* (see Theorem 3.2 page 27)—in particular, $\tilde{\mathbf{F}}\tilde{\mathbf{F}}^* \neq \mathbf{I}$, where $\tilde{\mathbf{F}}^*$ is the *adjoint* of $\tilde{\mathbf{F}}$; but rather, $\tilde{\mathbf{F}}\left(\frac{1}{2\pi}\tilde{\mathbf{F}}^*\right) = \left(\frac{1}{2\pi}\tilde{\mathbf{F}}^*\right)\tilde{\mathbf{F}} = \mathbf{I}$. But if we define the operators $\tilde{\mathbf{F}}$ and $\tilde{\mathbf{F}}^{-1}$ to both have the scaling factor $\frac{1}{\sqrt{2\pi}}$, then $\tilde{\mathbf{F}}$ and $\tilde{\mathbf{F}}^{-1}$ are inverses and $\tilde{\mathbf{F}}$ is *unitary*—that is, $\tilde{\mathbf{F}}\tilde{\mathbf{F}}^* = \tilde{\mathbf{F}}^*\tilde{\mathbf{F}} = \mathbf{I}$.

Portraits-Charge Aquarelle's des Membres de l'Institute (watercolor portrait #29). Biliotheque de l'Institut de France." Public domain. [https://en.wikipedia.org/wiki/File:Legendre_and_Fourier_\(1820\).jpg](https://en.wikipedia.org/wiki/File:Legendre_and_Fourier_(1820).jpg)

⁴ [Bachman et al. \(2002\) page 363](#), [Chorin and Hald \(2009\) page 13](#), [Loomis and Bolker \(1965\) page 144](#), [Knapp \(2005b\) pages 374–375](#), [Fourier \(1822\)](#), [Fourier \(1878\) page 336?](#)

⁵ [Chorin and Hald \(2009\) page 13](#), [Jeffrey and Dai \(2008\) pages xxxi–xxxii](#), [Knapp \(2005b\) pages 374–375](#)



3.3 Operator properties

Theorem 3.1 (Inverse Fourier transform).⁶ Let $\tilde{\mathbf{F}}$ be the Fourier Transform operator (Definition 3.2 page 26). The inverse $\tilde{\mathbf{F}}^{-1}$ of $\tilde{\mathbf{F}}$ is

$$\boxed{\text{T H M} \quad [\tilde{\mathbf{F}}^{-1}\tilde{f}](x) = \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} \tilde{f}(\omega) e^{i\omega x} d\omega \quad \forall \tilde{f} \in L^2_{(\mathbb{R}, \mathcal{B}, \mu)}}$$

Theorem 3.2. Let $\tilde{\mathbf{F}}$ be the Fourier Transform operator with inverse $\tilde{\mathbf{F}}^{-1}$ and adjoint $\tilde{\mathbf{F}}^*$.

$$\boxed{\text{T H M} \quad \tilde{\mathbf{F}}^* = \tilde{\mathbf{F}}^{-1}}$$

PROOF:

$$\begin{aligned} \langle \tilde{\mathbf{F}}f | g \rangle &= \left\langle \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x) e^{-i\omega x} dx | g(\omega) \right\rangle && \text{by definition of } \tilde{\mathbf{F}} \text{ page 26} \\ &= \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x) \langle e^{-i\omega x} | g(\omega) \rangle dx && \text{by additive property of } \langle \Delta | \nabla \rangle \\ &= \int_{\mathbb{R}} f(x) \frac{1}{\sqrt{2\pi}} \langle g(\omega) | e^{-i\omega x} \rangle^* dx && \text{by conjugate symmetric property of } \langle \Delta | \nabla \rangle \\ &= \left\langle f(x) | \frac{1}{\sqrt{2\pi}} \langle g(\omega) | e^{-i\omega x} \rangle \right\rangle && \text{by definition of } \langle \Delta | \nabla \rangle \\ &= \left\langle f | \underbrace{\tilde{\mathbf{F}}^{-1}}_{\tilde{\mathbf{F}}^*} g \right\rangle && \text{by Theorem 3.1 page 27} \end{aligned}$$

⇒

The Fourier Transform operator has several nice properties:

🔥 $\tilde{\mathbf{F}}$ is unitary⁷ (Corollary 3.1—next corollary).

🔥 Because $\tilde{\mathbf{F}}$ is unitary, it automatically has several other nice properties (Theorem 3.3 page 27).

Corollary 3.1. Let \mathbf{I} be the identity operator and let $\tilde{\mathbf{F}}$ be the Fourier Transform operator with adjoint $\tilde{\mathbf{F}}^*$ and inverse $\tilde{\mathbf{F}}^{-1}$.

$$\boxed{\text{C O R} \quad \underbrace{\tilde{\mathbf{F}}\tilde{\mathbf{F}}^* = \tilde{\mathbf{F}}^*\tilde{\mathbf{F}}}_{\tilde{\mathbf{F}}^* = \tilde{\mathbf{F}}^{-1}} = \mathbf{I} \quad (\tilde{\mathbf{F}} \text{ is unitary})}$$

PROOF: This follows directly from the fact that $\tilde{\mathbf{F}}^* = \tilde{\mathbf{F}}^{-1}$ (Theorem 3.2 page 27).

⇒

Theorem 3.3. Let $\tilde{\mathbf{F}}$ be the Fourier transform operator with adjoint $\tilde{\mathbf{F}}^*$ and inverse $\tilde{\mathbf{F}}^{-1}$. Let $\|\cdot\|$ be the operator norm with respect to the vector norm $\|\cdot\|$ with respect to the Hilbert space $(\mathbb{C}^{\mathbb{R}}, \langle \Delta | \nabla \rangle)$. Let $\mathcal{R}(\mathbf{A})$ be the range of an operator \mathbf{A} .

$$\boxed{\text{T H M} \quad \begin{aligned} \mathcal{R}(\tilde{\mathbf{F}}) &= \mathcal{R}(\tilde{\mathbf{F}}^{-1}) &&= \mathcal{L}^2_{\mathbb{R}} \\ \|\tilde{\mathbf{F}}\| &= \|\tilde{\mathbf{F}}^{-1}\| &&= 1 && \text{(UNITARY)} \\ \langle \tilde{\mathbf{F}}f | \tilde{\mathbf{F}}g \rangle &= \langle \tilde{\mathbf{F}}^{-1}f | \tilde{\mathbf{F}}^{-1}g \rangle &&= \langle f | g \rangle && \text{(PARSEVAL'S EQUATION)} \\ \|\tilde{\mathbf{F}}f\| &= \|\tilde{\mathbf{F}}^{-1}f\| &&= \|f\| && \text{(PLANCHEREL'S FORMULA)} \\ \|\tilde{\mathbf{F}}f - \tilde{\mathbf{F}}g\| &= \|\tilde{\mathbf{F}}^{-1}f - \tilde{\mathbf{F}}^{-1}g\| &&= \|f - g\| && \text{(ISOMETRIC)} \end{aligned}}$$

PROOF: These results follow directly from the fact that $\tilde{\mathbf{F}}$ is unitary (Corollary 3.1 page 27) and from the properties of unitary operators (Theorem G.26 page 178).

⇒


⁶ 🔥 Chorin and Hald (2009) page 13

⁷ unitary operators: Definition G.14 page 177

3.4 Transversal properties

Theorem 3.4 (Shift relations). *Let $\tilde{\mathbf{F}}$ be the Fourier Transform operator (Definition 3.2 page 26).*

$$\begin{aligned} \tilde{\mathbf{F}}[f(x-y)](\omega) &= e^{-i\omega y} [\tilde{\mathbf{F}}f(x)](\omega) \\ [\tilde{\mathbf{F}}(e^{irx}g(x))](\omega) &= [\tilde{\mathbf{F}}g(x)](\omega-r) \end{aligned}$$

 **PROOF:** Let \mathbf{L} be the Laplace Transform operator (Definition 2.1 page 11).

$$\begin{aligned} \tilde{\mathbf{F}}[f(x-y)](\omega) &= \mathbf{L}[f(x-y)](s)|_{s=i\omega} && \text{by definition of } \mathbf{L} && (\text{Definition 2.1 page 11}) \\ &= e^{-sy} [\mathbf{L}f(x)](s)|_{s=i\omega} && \text{by Laplace translation property} && (\text{Theorem 2.2 page 12}) \\ &= e^{-i\omega y} [\tilde{\mathbf{F}}f(x)](\omega) && \text{by definition of } \tilde{\mathbf{F}} && (\text{Definition 3.2 page 26}) \\ [\tilde{\mathbf{F}}(e^{irx}g(x))](\omega) &= [\mathbf{L}(e^{irx}g(x))](s)|_{s=i\omega} && \text{by definition of } \mathbf{L} && (\text{Definition 2.1 page 11}) \\ &= [[\mathbf{L}g(x)](s-r)]|_{s=i\omega} && \text{by Laplace dilation property} && (\text{Theorem 2.2 page 12}) \\ &= [\tilde{\mathbf{F}}g(x)](\omega-r) && \text{by definition of } \tilde{\mathbf{F}} && (\text{Definition 3.2 page 26}) \end{aligned}$$



Theorem 3.5 (Complex conjugate). *Let $\tilde{\mathbf{F}}$ be the Fourier Transform operator and $*$ represent the complex conjugate operation on the set of complex numbers.*

$$\tilde{\mathbf{F}}f^*(-x) = -[\tilde{\mathbf{F}}f(x)]^* \quad \forall f \in L^2_{(\mathbb{R}, \mathcal{B}, \mu)}$$

 **PROOF:**




$$\begin{aligned} [\tilde{\mathbf{F}}f^*(-x)](\omega) &\triangleq \frac{1}{\sqrt{2\pi}} \int f^*(-x)e^{-i\omega x} dx && \text{by definition of } \tilde{\mathbf{F}} && (\text{Definition 3.2 page 26}) \\ &= \frac{1}{\sqrt{2\pi}} \int f^*(u)e^{i\omega u}(-1) du && \text{where } u \triangleq -x \implies dx = -du \\ &= -\left[\frac{1}{\sqrt{2\pi}} \int f(u)e^{-i\omega u} du \right]^* \\ &\triangleq -[\tilde{\mathbf{F}}f(x)]^* && \text{by definition of } \tilde{\mathbf{F}} && (\text{Definition 3.2 page 26}) \end{aligned}$$



3.5 Convolution relations

Theorem 9.2 (next) demonstrates that multiplication in the “time domain” is equivalent to convolution in the “frequency domain” and vice-versa.

Theorem 3.6 (convolution theorem). ⁸ *Let $\tilde{\mathbf{F}}$ be the Fourier Transform operator (Definition 3.2 page 26) and \star the convolution operator (Definition C.1 page 103).*

⁸  Bachman et al. (2002) pages 269–270 (5.2.3 Convolutions to Products),  Bachman (1964) page 8,  Bracewell (1978) page 110

T H M

$$\begin{aligned}
\underbrace{\tilde{\mathbf{F}}[f(x) \star g(x)](\omega)}_{\text{convolution in "time domain"}} &= \underbrace{\sqrt{2\pi} [\tilde{\mathbf{F}}f](\omega) [\tilde{\mathbf{F}}g](\omega)}_{\text{multiplication in "frequency domain"}} & \forall f, g \in L^2_{(\mathbb{R}, \mathcal{B}, \mu)} \\
\underbrace{\tilde{\mathbf{F}}[f(x)g(x)](\omega)}_{\text{multiplication in "time domain"}} &= \underbrace{\frac{1}{\sqrt{2\pi}} [\tilde{\mathbf{F}}f](\omega) \star [\tilde{\mathbf{F}}g](\omega)}_{\text{convolution in "frequency domain"}} & \forall f, g \in L^2_{(\mathbb{R}, \mathcal{B}, \mu)}.
\end{aligned}$$

PROOF: Let \mathbf{L} be the *Laplace Transform* operator (Definition 2.1 page 11).

$$\begin{aligned}
\tilde{\mathbf{F}}[f(x) \star g(x)](\omega) &= \mathbf{L}[f(x) \star g(x)](s) \Big|_{s=i\omega} && \text{by definition of } \mathbf{L} && (\text{Definition 2.1 page 11}) \\
&= \sqrt{2\pi} [\mathbf{L}f](s) [\mathbf{L}g](s) \Big|_{s=i\omega} && \text{by Laplace convolution result} && (\text{Theorem 2.6 page 23}) \\
&= \sqrt{2\pi} [\tilde{\mathbf{F}}f](\omega) [\tilde{\mathbf{F}}g](\omega) \\
\tilde{\mathbf{F}}[f(x)g(x)](\omega) &= \mathbf{L}[f(x)g(x)](s) \Big|_{s=i\omega} \\
&= \frac{1}{\sqrt{2\pi}} [\mathbf{L}f](s) \star [\mathbf{L}g](s) \Big|_{s=i\omega} \\
&= \frac{1}{\sqrt{2\pi}} [\tilde{\mathbf{F}}f](\omega) \star [\tilde{\mathbf{F}}g](\omega)
\end{aligned}$$

⇒

3.6 Calculus relations

Theorem 3.7. Let $\tilde{\mathbf{F}}$ be the *FOURIER TRANSFORM* operator (Definition 3.2 page 26).

$$\left\{ \lim_{t \rightarrow -\infty} x(t) = 0 \right\} \implies \left\{ \tilde{\mathbf{F}} \left[\frac{d}{dt} x(t) \right] = i\omega [\tilde{\mathbf{F}}x](\omega) \right\}$$

PROOF: Let \mathbf{L} be the *Laplace Transform* operator (Definition 2.1 page 11).

$$\begin{aligned}
\tilde{\mathbf{F}} \left[\frac{d}{dt} x(t) \right] &\triangleq \mathbf{L} \left[\frac{d}{dt} x(t) \right](s) \Big|_{s=i\omega} && \text{by definitions of } \mathbf{L} \text{ and } \tilde{\mathbf{F}} && (\text{Definition 2.1 page 11}) \\
&= s [\mathbf{L}x(t)](s) \Big|_{s=i\omega} && \text{by Theorem 2.7 page 24} \\
&= i\omega [\tilde{\mathbf{F}}x](\omega)
\end{aligned}$$

⇒

Theorem 3.8. Let $\tilde{\mathbf{F}}$ be the *FOURIER TRANSFORM* operator (Definition 3.2 page 26).

$$\tilde{\mathbf{F}} \int_{u=-\infty}^{u=t} x(u) du = \frac{1}{i\omega} [\tilde{\mathbf{F}}x](\omega)$$

Let \mathbf{L} be the *Laplace Transform* operator (Definition 2.1 page 11). PROOF:

$$\begin{aligned}
\tilde{\mathbf{F}} \int_{u=-\infty}^{u=t} x(u) du &\triangleq \mathbf{L} \int_{u=-\infty}^{u=t} x(u) du \Big|_{s=i\omega} \\
&= \frac{1}{s} [\mathbf{L}x(t)](s) \Big|_{s=i\omega} && \text{by Theorem 2.7 page 24} \\
&= \frac{1}{i\omega} [\tilde{\mathbf{F}}x](\omega)
\end{aligned}$$

⇒

3.7 Real valued functions

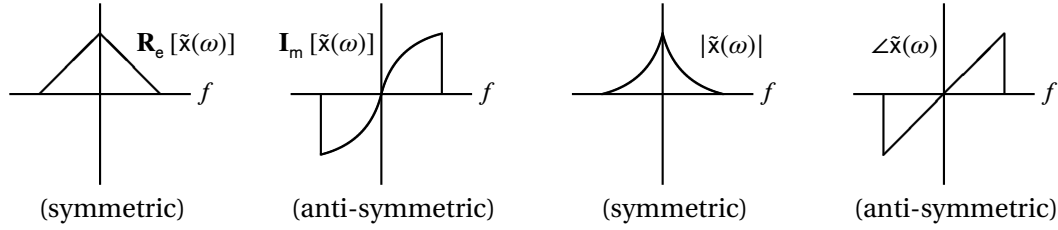


Figure 3.1: Fourier transform components of real-valued signal

Theorem 3.9. Let $f(x)$ be a function in $L^2_{\mathbb{R}}$ and $\tilde{f}(\omega)$ the FOURIER TRANSFORM of $f(x)$.

T H M	$\left\{ \begin{array}{l} f(x) \text{ is REAL-VALUED} \\ (f \in \mathbb{R}^{\mathbb{R}}) \end{array} \right\} \Rightarrow$	$\left\{ \begin{array}{l} \tilde{f}(\omega) = \tilde{f}^*(-\omega) \quad (\text{HERMITIAN SYMMETRIC}) \\ \mathbf{R}_e[\tilde{f}(\omega)] = \mathbf{R}_e[\tilde{f}(-\omega)] \quad (\text{SYMMETRIC}) \\ \mathbf{I}_m[\tilde{f}(\omega)] = -\mathbf{I}_m[\tilde{f}(-\omega)] \quad (\text{ANTI-SYMMETRIC}) \\ \tilde{f}(\omega) = \tilde{f}(-\omega) \quad (\text{SYMMETRIC}) \\ \angle \tilde{f}(\omega) = \angle \tilde{f}(-\omega) \quad (\text{ANTI-SYMMETRIC}). \end{array} \right\}$

PROOF:

$$\begin{aligned}
 \tilde{f}(\omega) &\triangleq [\tilde{\mathbf{F}}f(x)](\omega) \triangleq \langle f(x) | e^{i\omega x} \rangle = \langle f(x) | e^{i(-\omega)x} \rangle^* \triangleq \tilde{f}^*(-\omega) \\
 \mathbf{R}_e[\tilde{f}(\omega)] &= \mathbf{R}_e[\tilde{f}^*(-\omega)] = \mathbf{R}_e[\tilde{f}(-\omega)] \\
 \mathbf{I}_m[\tilde{f}(\omega)] &= \mathbf{I}_m[\tilde{f}^*(-\omega)] = -\mathbf{I}_m[\tilde{f}(-\omega)] \\
 |\tilde{f}(\omega)| &= |\tilde{f}^*(-\omega)| = |\tilde{f}(-\omega)| \\
 \angle \tilde{f}(\omega) &= \angle \tilde{f}^*(-\omega) = -\angle \tilde{f}(-\omega)
 \end{aligned}$$

3.8 Moment properties

Definition 3.3. ⁹

DEF The quantity M_n is the ***n*th moment** of a function $f(x) \in L^2_{\mathbb{R}}$ if

$$M_n \triangleq \int_{\mathbb{R}} x^n f(x) dx \quad \text{for } n \in \mathbb{W}.$$

Lemma 3.1. ¹⁰ Let M_n be the *n*TH MOMENT (Definition 3.3 page 30) and $\tilde{f}(\omega) \triangleq [\tilde{\mathbf{F}}f](\omega)$ the FOURIER TRANSFORM (Definition 3.2 page 26) of a function $f(x)$ in $L^2_{\mathbb{R}}$ (Definition B.1 page 99).

L E M	$M_n \triangleq \int_{\mathbb{R}} x^n f(x) dx = \sqrt{2\pi} (i)^n \left[\frac{d}{d\omega} \right]^n \tilde{f}(\omega) \Big _{\omega=0} \quad \forall n \in \mathbb{W}, f \in L^2_{\mathbb{R}}$

⁹ Jawerth and Sweldens (1994) pages 16–17, Sweldens and Piessens (1993) page 2, Vidakovic (1999) page 83

¹⁰ Goswami and Chan (1999) pages 38–39

✎ PROOF:

$$\begin{aligned}
 \sqrt{2\pi}(i)^n \left[\left[\frac{d}{d\omega} \right]^n \tilde{f}(\omega) \right]_{\omega=0} &= \sqrt{2\pi}(i)^n \left[\left[\frac{d}{d\omega} \right]^n \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x) e^{-i\omega x} dx \right]_{\omega=0} && \text{by definition of } \tilde{F} \quad (\text{Definition 3.2 page 26}) \\
 &= (i)^n \int_{\mathbb{R}} f(x) \left[\left[\frac{d}{d\omega} \right]^n e^{-i\omega x} \right] dx \Big|_{\omega=0} \\
 &= (i)^n \int_{\mathbb{R}} f(x) [(-i)^n x^n e^{-i\omega x}] dx \Big|_{\omega=0} \\
 &= (-i^2)^n \int_{\mathbb{R}} f(x) x^n dx \\
 &= \int_{\mathbb{R}} x^n f(x) dx \\
 &\triangleq M_n && \text{by definition of } M_n \quad (\text{Definition 3.3 page 30})
 \end{aligned}$$

⇒

Lemma 3.2. ¹¹ Let M_n be the n TH MOMENT (Definition 3.3 page 30) and $\tilde{f}(\omega) \triangleq [\tilde{F}f](\omega)$ the FOURIER TRANSFORM (Definition 3.2 page 26) of a function $f(x)$ in $\mathcal{L}_{\mathbb{R}}^2$ (Definition B.1 page 99).

L E M	$M_n = 0 \quad \iff \quad \left[\frac{d}{d\omega} \right]^n \tilde{f}(\omega) \Big _{\omega=0} = 0 \quad \forall n \in \mathbb{W}$
----------------------	---

✎ PROOF:

1. Proof for (\implies) case:

$$\begin{aligned}
 0 &= \langle f(x) | x^n \rangle && \text{by left hypothesis} \\
 &= \sqrt{2\pi}(-i)^{-n} \left[\frac{d}{d\omega} \right]^n \tilde{f}(\omega) \Big|_{\omega=0} && \text{by Lemma 3.1 page 30} \\
 &\implies \left[\frac{d}{d\omega} \right]^n \tilde{f}(\omega) \Big|_{\omega=0} = 0
 \end{aligned}$$

2. Proof for (\impliedby) case:

$$\begin{aligned}
 0 &= \left[\frac{d}{d\omega} \right]^n \tilde{f}(\omega) \Big|_{\omega=0} && \text{by right hypothesis} \\
 &= \left[\frac{d}{d\omega} \right]^n \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x) e^{-i\omega x} dx \Big|_{\omega=0} && \text{by definition of } \tilde{f}(\omega) \\
 &= \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x) \left[\frac{d}{d\omega} \right]^n e^{-i\omega x} dx \Big|_{\omega=0} \\
 &= \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x) [(-i)^n x^n e^{-i\omega x}] dx \Big|_{\omega=0} \\
 &= (-i)^n \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x) x^n dx \\
 &= (-i)^n \frac{1}{\sqrt{2\pi}} \langle f(x) | x^n \rangle && \text{by definition of } \langle \cdot | \cdot \rangle \text{ in } \mathcal{L}_{\mathbb{R}}^2 \quad (\text{Definition B.1 page 99})
 \end{aligned}$$

⇒

¹¹ Vidakovic (1999) pages 82–83, Mallat (1999) pages 241–242

Lemma 3.3 (Strang-Fix condition).¹² Let $f(x)$ be a function in $L^2_{\mathbb{R}}$ and M_n the n TH MOMENT (Definition 3.3 page 30) of $f(x)$. Let T be the TRANSLATION OPERATOR (Definition J.3 page 222).

L
E
M

$$\underbrace{\sum_{k \in \mathbb{Z}} T^k x^n f(x) = M_n}_{\text{STRANG-FIX CONDITION in "time"}} \iff \underbrace{\left[\frac{d}{d\omega} \right]^n \tilde{f}(\omega) \Big|_{\omega=2\pi k} = \frac{1}{\sqrt{2\pi}} (-i)^n \bar{\delta}_k M_n}_{\text{STRANG-FIX CONDITION in "frequency"}}$$

 PROOF:

1. Proof for (\implies) case:

$$\begin{aligned} \left[\left[\frac{d}{d\omega} \right]^n \tilde{f}(\omega) \right]_{\omega=2\pi k} &= \sum_{k \in \mathbb{Z}} \left[\left[\frac{d}{d\omega} \right]^n \tilde{f}(\omega) \right]_{\omega=2\pi k} e^{i2\pi k x} \bar{\delta}_k \\ &= \frac{1}{\sqrt{2\pi}} \sum_{k \in \mathbb{Z}} \left[\left[\frac{d}{d\omega} \right]^n \int_{\mathbb{R}} f(x) e^{-i\omega x} dx \right]_{\omega=2\pi k} e^{i2\pi k x} \bar{\delta}_k \quad \text{by definition of } \tilde{f}(\omega) \quad (\text{Definition 3.2 page 26}) \\ &= \frac{1}{\sqrt{2\pi}} \sum_{k \in \mathbb{Z}} \left[\int_{\mathbb{R}} f(x) (-ix)^n e^{-i\omega x} dx \right]_{\omega=2\pi k} e^{i2\pi k x} \bar{\delta}_k \\ &= (-i)^n \frac{1}{\sqrt{2\pi}} \sum_{k \in \mathbb{Z}} \left[\int_{\mathbb{R}} x^n f(x) e^{-i\omega x} dx \right]_{\omega=2\pi k} e^{i2\pi k x} \bar{\delta}_k \\ &= (-i)^n \frac{1}{\sqrt{2\pi}} \sum_{k \in \mathbb{Z}} (x-k)^n f(x-k) \bar{\delta}_k \quad \text{by PSF} \quad (\text{Theorem J.2 page 230}) \\ &= \frac{1}{\sqrt{2\pi}} (-i)^n \bar{\delta}_k M_n \quad \text{by left hypothesis} \end{aligned}$$

2. Proof for (\impliedby) case:

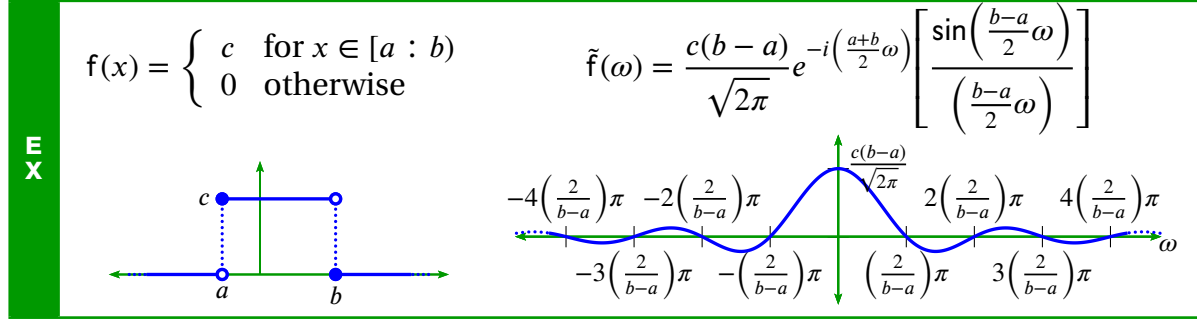
$$\begin{aligned} \frac{1}{\sqrt{2\pi}} (-i)^n M_n &= \frac{1}{\sqrt{2\pi}} \sum_{k \in \mathbb{Z}} [(-i)^n \bar{\delta}_k M_n] e^{-i2\pi k x} \quad \text{by definition of } \bar{\delta} \quad (\text{Definition H.12 page 194}) \\ &= \sum_{k \in \mathbb{Z}} \left[\left[\frac{d}{d\omega} \right]^n \tilde{f}(\omega) \right]_{\omega=2\pi k} e^{-i2\pi k x} \quad \text{by right hypothesis} \\ &= \sum_{k \in \mathbb{Z}} \left[\left[\frac{d}{d\omega} \right]^n \int_{\mathbb{R}} f(x) e^{-i\omega x} dx \right]_{\omega=2\pi k} e^{-i2\pi k x} \\ &= \sum_{k \in \mathbb{Z}} \left[\int_{\mathbb{R}} f(x) (-ix)^n e^{-i\omega x} dx \right]_{\omega=2\pi k} e^{-i2\pi k x} \\ &= (-i)^n \sum_{k \in \mathbb{Z}} \left[\int_{\mathbb{R}} x^n f(x) e^{-i\omega x} dx \right]_{\omega=2\pi k} e^{-i2\pi k x} \\ &= (-i)^n \sum_{k \in \mathbb{Z}} (x-k)^n f(x-k) \quad \text{by PSF} \quad (\text{Theorem J.2 page 230}) \end{aligned}$$



¹²  Jawerth and Sweldens (1994) pages 16–17,  Sweldens and Piessens (1993) page 2,  Vidakovic (1999) page 83,  Mallat (1999) pages 241–243,  Fix and Strang (1969)

3.9 Examples

Example 3.1 (rectangular pulse). Let $\tilde{f}(\omega)$ be the *Fourier transform* of a function $f(x) \in L^2_{\mathbb{R}}$.

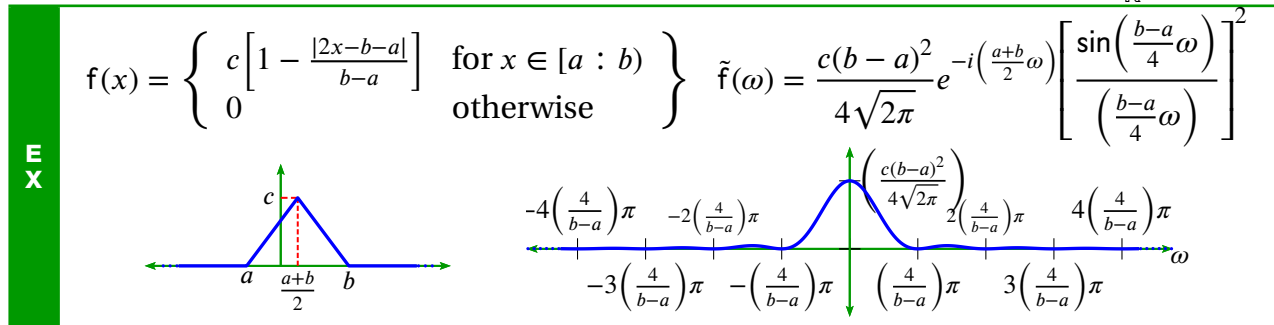


PROOF:

$$\begin{aligned}
 \tilde{f}(\omega) &= \tilde{\mathbf{F}}[f(x)](\omega) && \text{by definition of } \tilde{f}(\omega) \\
 &= e^{-i\left(\frac{a+b}{2}\omega\right)} \tilde{\mathbf{F}}\left[f\left(x - \frac{a+b}{2}\right)\right](\omega) && \text{by shift relation (Theorem 3.4 page 28)} \\
 &= e^{-i\left(\frac{a+b}{2}\omega\right)} \tilde{\mathbf{F}}\left[c \mathbb{1}_{[a:b]}\left(x - \frac{a+b}{2}\right)\right](\omega) && \text{by definition of } f(x) \\
 &= e^{-i\left(\frac{a+b}{2}\omega\right)} \tilde{\mathbf{F}}\left[c \mathbb{1}_{\left[-\frac{b-a}{2} : \frac{b-a}{2}\right]}(x)\right](\omega) && \text{by definition of } \mathbb{1} \text{ (Definition J.2 page 222)} \\
 &= \frac{1}{\sqrt{2\pi}} e^{-i\left(\frac{a+b}{2}\omega\right)} \int_{\mathbb{R}} c \mathbb{1}_{\left[-\frac{b-a}{2} : \frac{b-a}{2}\right]}(x) e^{-i\omega x} dx && \text{by definition of } \tilde{\mathbf{F}} \text{ (Definition 3.2 page 26)} \\
 &= \frac{1}{\sqrt{2\pi}} e^{-i\left(\frac{a+b}{2}\omega\right)} \int_{-\frac{b-a}{2}}^{\frac{b-a}{2}} c e^{-i\omega x} dx && \text{by definition of } \mathbb{1} \text{ (Definition J.2 page 222)} \\
 &= \frac{c}{\sqrt{2\pi}} e^{-i\left(\frac{a+b}{2}\omega\right)} \frac{1}{-i\omega} e^{-i\omega x} \Bigg|_{-\frac{b-a}{2}}^{\frac{b-a}{2}} \\
 &= \frac{2c}{\sqrt{2\pi}\omega} e^{-i\left(\frac{a+b}{2}\omega\right)} \left[\frac{e^{i\left(\frac{b-a}{2}\omega\right)} - e^{-i\left(\frac{b-a}{2}\omega\right)}}{2i} \right] \\
 &= \frac{c(b-a)}{\sqrt{2\pi}} e^{-i\left(\frac{a+b}{2}\omega\right)} \left[\frac{\sin\left(\frac{b-a}{2}\omega\right)}{\left(\frac{b-a}{2}\omega\right)} \right] && \text{by Euler formulas (Corollary D.2 page 113)}
 \end{aligned}$$

⇒

Example 3.2 (triangle). Let $\tilde{f}(\omega)$ be the *Fourier transform* of a function $f(x) \in L^2_{\mathbb{R}}$.



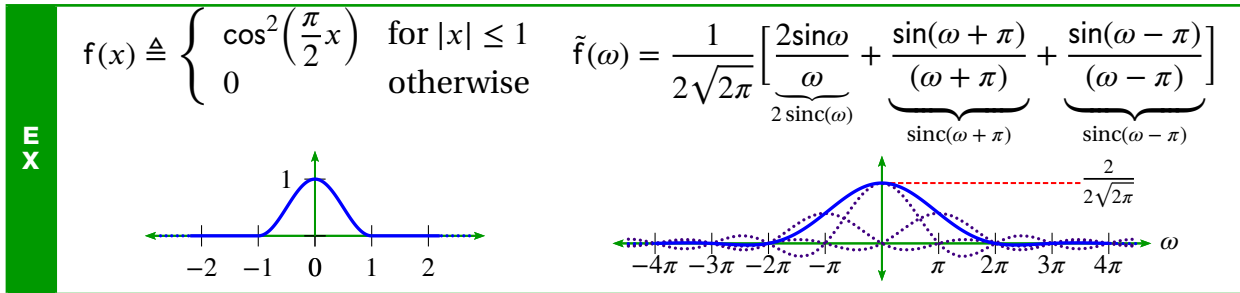
PROOF:

$$\tilde{f}(\omega) = \tilde{\mathbf{F}}[f(x)](\omega) \quad \text{by definition of } \tilde{f}(\omega)$$

$$\begin{aligned}
&= e^{-i\left(\frac{a+b}{2}\right)\omega} \tilde{\mathbf{F}}\left[\mathbf{f}\left(x - \frac{a+b}{2}\right)\right](\omega) && \text{by shift relation} && (\text{Theorem 3.4 page 28}) \\
&= \tilde{\mathbf{F}}\left[c\left(1 - \frac{|2x - b - a|}{b-a}\right)\mathbb{1}_{[a:b]}(x)\right](\omega) && \text{by definition of } \mathbf{f}(x) \\
&= c\tilde{\mathbf{F}}\left[\mathbb{1}_{\left[\frac{a}{2}:\frac{b}{2}\right]}(x) \star \mathbb{1}_{\left[\frac{a}{2}:\frac{b}{2}\right]}(x)\right](\omega) \\
&= c\sqrt{2\pi}\tilde{\mathbf{F}}\left[\mathbb{1}_{\left[\frac{a}{2}:\frac{b}{2}\right]}\right]\tilde{\mathbf{F}}\left[\mathbb{1}_{\left[\frac{a}{2}:\frac{b}{2}\right]}\right] && \text{by convolution theorem} && (\text{Theorem 9.2 page 72}) \\
&= c\sqrt{2\pi}\left(\tilde{\mathbf{F}}\left[\mathbb{1}_{\left[\frac{a}{2}:\frac{b}{2}\right]}\right]\right)^2 \\
&= c\sqrt{2\pi}\left(\frac{\left(\frac{b}{2} - \frac{a}{2}\right)}{\sqrt{2\pi}}e^{-i\left(\frac{a+b}{4}\right)\omega}\left[\frac{\sin\left(\frac{b-a}{4}\omega\right)}{\left(\frac{b-a}{4}\omega\right)}\right]\right)^2 && \text{by Rectangular pulse ex.} && \text{Example 3.1 page 33} \\
&= \frac{c(b-a)^2}{4\sqrt{2\pi}}e^{-i\left(\frac{a+b}{2}\right)\omega}\left[\frac{\sin\left(\frac{b-a}{4}\omega\right)}{\left(\frac{b-a}{4}\omega\right)}\right]^2
\end{aligned}$$

⇒

Example 3.3. Let a function \mathbf{f} be defined in terms of the cosine function (Definition D.1 page 107) as follows:



PROOF: Let $\mathbb{1}_A(x)$ be the *set indicator function* (Definition J.2 page 222) on a set A .

$$\begin{aligned}
\tilde{\mathbf{f}}(\omega) &\triangleq \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} \mathbf{f}(x) e^{-i\omega x} dx && \text{by definition of } \tilde{\mathbf{f}}(\omega) \text{ (Definition 3.2)} \\
&= \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} \cos^2\left(\frac{\pi}{2}x\right) \mathbb{1}_{[-1:1]}(x) e^{-i\omega x} dx && \text{by definition of } \mathbf{f}(x) \\
&= \frac{1}{\sqrt{2\pi}} \int_{-1}^1 \cos^2\left(\frac{\pi}{2}x\right) e^{-i\omega x} dx && \text{by definition of } \mathbb{1} \text{ (Definition J.2)} \\
&= \frac{1}{\sqrt{2\pi}} \int_{-1}^1 \left[\frac{e^{i\frac{\pi}{2}x} + e^{-i\frac{\pi}{2}x}}{2} \right]^2 e^{-i\omega x} dx && \text{by Corollary D.2 page 113} \\
&= \frac{1}{4\sqrt{2\pi}} \int_{-1}^1 [2 + e^{i\pi x} + e^{-i\pi x}] e^{-i\omega x} dx \\
&= \frac{1}{4\sqrt{2\pi}} \int_{-1}^1 2e^{-i\omega x} + e^{-i(\omega+\pi)x} + e^{-i(\omega-\pi)x} dx \\
&= \frac{1}{4\sqrt{2\pi}} \left[2\frac{e^{-i\omega x}}{-i\omega} + \frac{e^{-i(\omega+\pi)x}}{-i(\omega+\pi)} + \frac{e^{-i(\omega-\pi)x}}{-i(\omega-\pi)} \right]_{-1}^1 \\
&= \frac{1}{2\sqrt{2\pi}} \left[2\frac{e^{-i\omega} - e^{+i\omega}}{-2i\omega} + \frac{e^{-i(\omega+\pi)} - e^{+i(\omega+\pi)}}{-2i(\omega+\pi)} + \frac{e^{-i(\omega-\pi)} - e^{+i(\omega-\pi)}}{-2i(\omega-\pi)} \right]_{-1}^1
\end{aligned}$$

$$= \frac{1}{2\sqrt{2\pi}} \left[\underbrace{\frac{2\sin\omega}{\omega}}_{2\operatorname{sinc}(\omega)} + \underbrace{\frac{\sin(\omega+\pi)}{(\omega+\pi)}}_{\operatorname{sinc}(\omega+\pi)} + \underbrace{\frac{\sin(\omega-\pi)}{(\omega-\pi)}}_{\operatorname{sinc}(\omega-\pi)} \right]$$



Example 3.4. ¹³

E X	$\tilde{\mathbf{F}}[e^{-\alpha x }] = \frac{1}{\sqrt{2\pi}} \left[\frac{2\alpha}{\alpha^2 + \omega^2} \right]$
----------------	---

PROOF:

1. Proof using *Laplace Transform*:

$$\begin{aligned} \sqrt{2\pi}\tilde{\mathbf{F}}[e^{-\alpha|x|}] &\triangleq \left[\sqrt{2\pi} \right] \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} e^{-\alpha|x|} e^{-i\omega x} dx && \text{by definition of } \tilde{\mathbf{F}} && \text{(Definition 3.2 page 26)} \\ &= \left[\int_{\mathbb{R}} e^{-\alpha|x|} e^{-sx} dx \right]_{s=i\omega} \\ &= \left[\frac{2\alpha}{\alpha^2 - s^2} \right]_{s=i\omega} && \forall \mathbf{R}_e(s) \in (-\alpha : \alpha) && \text{by Corollary 2.9 page 21} \\ &= \frac{2\alpha}{\alpha^2 + \omega^2} && \text{because } s = i\omega \text{ is in } (-\alpha : \alpha) \end{aligned}$$

2. Alternate proof:

$$\begin{aligned} \sqrt{2\pi}\tilde{\mathbf{F}}[e^{-\alpha|x|}] &\triangleq \left[\sqrt{2\pi} \right] \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{-\alpha|x|} e^{-i\omega x} dx && \text{by definition of } \tilde{\mathbf{F}} && \text{(Definition 3.2 page 26)} \\ &= \int_{-\infty}^0 e^{-\alpha(-x)} e^{-i\omega x} dx + \int_0^{\infty} e^{-\alpha(x)} e^{-i\omega x} dx \\ &= \int_{-\infty}^0 e^{x(\alpha-i\omega)} dx + \int_0^{\infty} e^{x(-\alpha-i\omega)} dx \\ &= \left. \frac{e^{x(\alpha-i\omega)}}{\alpha-i\omega} \right|_{-\infty}^0 + \left. \frac{e^{x(-\alpha-i\omega)}}{-\alpha-i\omega} \right|_0^{\infty} && \text{by Fundamental Theorem of Calculus} \\ &= \left[\frac{1}{\alpha-i\omega} - 0 \right] + \left[0 - \frac{1}{-\alpha-i\omega} \right] \\ &= \left[\frac{1}{\alpha-i\omega} \right] \left[\frac{\alpha-i\omega}{\alpha-i\omega} \right] + \left[\frac{1}{\alpha+i\omega} \right] \left[\frac{\alpha+i\omega}{\alpha+i\omega} \right] \\ &= \frac{\alpha-i\omega}{\alpha^2+\omega^2} + \frac{\alpha+i\omega}{\alpha^2+\omega^2} \\ &= \left[\frac{2\alpha}{\alpha^2+\omega^2} \right] \end{aligned}$$



¹³<https://math.stackexchange.com/questions/4015842/>

CHAPTER 4

KL EXPANSION—CONTINUOUS CASE

4.1 Definitions

Definition 4.1. Let $x(t)$ be a RANDOM PROCESS with continuous AUTO-CORRELATION $R_{xx}(t, u)$ (Definition K.2 page 235).

DEF The **auto-correlation operator** \mathbf{R} of $x(t)$ is defined as

$$\mathbf{R}f \triangleq \int_{u \in \mathbb{R}} R_{xx}(t, u) f(u) du$$

Definition 4.2. Let $x(t)$ be a RANDOM PROCESS with AUTO-CORRELATION $R_{xx}(\tau)$ (Definition K.2 page 235).

DEF A RANDOM PROCESS $x(t)$ is **white** if

$$R_{xx}(\tau) = \delta(\tau)$$

If a random process $x(t)$ is **white** (Definition 4.2 page 37) and the set $\Psi = \{\psi_1(t), \psi_2(t), \dots, \psi_N(t)\}$ is **any** set of orthonormal basis functions, then the innerproducts $\langle n(t) | \psi_n(t) \rangle$ and $\langle n(t) | \psi_m(t) \rangle$ are **uncorrelated** for $m \neq n$. However, if $x(t)$ is **colored** (not white), then the innerproducts are not in general uncorrelated. But if the elements of Ψ are chosen to be the eigenfunctions of \mathbf{R} such that $\mathbf{R}\psi_n = \lambda_n \psi_n$, then by Theorem K.1 (page 236), the set $\{\psi_n(t)\}$ are **orthogonal** and the innerproducts **are uncorrelated** even though $x(t)$ is not white. This criterion is called the *Karhunen-Loève criterion* for $x(t)$.

4.2 Properties

Theorem 4.1. Let \mathbf{R} be an AUTO-CORRELATION operator.

THEM	$\left\{ \langle x y \rangle \triangleq \int_{t \in \mathbb{R}} x(t) y^*(t) dt \right\} \implies \left\{ \begin{array}{ll} (1). \langle \mathbf{R}x x \rangle \geq 0 & \text{(NON-NEGATIVE)} \\ (2). \langle \mathbf{R}x y \rangle = \langle x \mathbf{R}y \rangle & \text{(SELF-ADJOINT)} \end{array} \right. \text{ and } \left. \right\}$
-------------	--

 PROOF:

1. Proof that \mathbf{R} is *non-negative* under hypothesis (A):

$$\begin{aligned}
 \langle \mathbf{R}y | y \rangle &= \left\langle \int_{u \in \mathbb{R}} R_{xx}(t, u) y(u) \, du \mid y(t) \right\rangle && \text{by definition of } \mathbf{R} && (\text{Definition 4.1 page 37}) \\
 &= \left\langle \int_{u \in \mathbb{R}} E[x(t)x^*(u)] y(u) \, du \mid y(t) \right\rangle && \text{by definition of } R_{xx}(t, u) && (\text{Definition K.2 page 235}) \\
 &= E \left[\left\langle \int_{u \in \mathbb{R}} x(t)x^*(u) y(u) \, du \mid y(t) \right\rangle \right] && \text{by linearity of } \langle \Delta | \nabla \rangle \text{ and } \int && \\
 &= E \left[\int_{u \in \mathbb{R}} x^*(u) y(u) \, du \langle x(t) | y(t) \rangle \right] && \text{by additivity property of } \langle \Delta | \nabla \rangle && \\
 &= E[y(u) | x(u)] \langle x(t) | y(t) \rangle && \text{by local definition of } \langle \Delta | \nabla \rangle && \\
 &= E[x(u) | y(u)]^* \langle x(t) | y(t) \rangle && \text{by conjugate symmetry prop.} && \\
 &= E|\langle x(t) | y(t) \rangle|^2 && \text{by definition of } |\cdot| && (\text{Definition A.4 page 98}) \\
 &\geq 0 && \text{by strictly positive property of norms} &&
 \end{aligned}$$

2. Proof that \mathbf{R} is *self-adjoint* under hypothesis (A):

$$\begin{aligned}
 \langle [\mathbf{R}x](t) | y \rangle &= \left\langle \int_{u \in \mathbb{R}} R_{xx}(t, u) x(u) \, du \mid y(t) \right\rangle && \text{by definition of } \mathbf{R} && (\text{Definition 4.1 page 37}) \\
 &= \int_{u \in \mathbb{R}} x(u) \langle R_{xx}(t, u) | y(t) \rangle \, du && \text{by additive property of } \langle \Delta | \nabla \rangle && \\
 &= \int_{u \in \mathbb{R}} x(u) \langle y(t) | R_{xx}(t, u) \rangle^* \, du && \text{by conjugate symmetry prop.} && \\
 &= \langle x(u) | \langle y(t) | R_{xx}(t, u) \rangle \rangle && \text{by local definition of } \langle \Delta | \nabla \rangle && \\
 &= \left\langle x(u) \mid \int_{t \in \mathbb{R}} y(t) R_{xx}^*(t, u) \, dt \right\rangle && && \\
 &= \left\langle x(u) \mid \int_{t \in \mathbb{R}} y(t) R_{xx}(u, t) \, dt \right\rangle && \text{by property of } R_{xx} && (\text{Theorem K.1 page 236}) \\
 &= \left\langle x(u) \mid \underbrace{\mathbf{R}y}_{\mathbf{R}^*} \right\rangle && \text{by definition of } \mathbf{R} && (\text{Definition 4.1 page 37}) \\
 \implies \mathbf{R} &= \mathbf{R}^* && \text{by definition of adjoint } \mathbf{R}^* && (\text{Definition G.8 page 163}) \\
 \implies \mathbf{R} &\text{ is self-adjoint} && \text{by definition of self-adjoint} && (\text{Definition G.11 page 171})
 \end{aligned}$$

3. Proofs under hypothesis (B): substitute $\sum_{n \in \mathbb{Z}}$ operator for $\int_{t \in \mathbb{R}} dt$ operator in above proofs.

⇒

Theorem 4.2. ¹ Let $(\lambda_n)_{n \in \mathbb{Z}}$ be the eigenvalues and $(\psi_n)_{n \in \mathbb{Z}}$ be the eigenfunctions of operator \mathbf{R} such that $\mathbf{R}\psi_n = \lambda_n \psi_n$.

T H M	(1). $\lambda_n \in \mathbb{R}$	(REAL-VALUED)
	(2). $\lambda_n \neq \lambda_m \implies \langle \psi_n \psi_m \rangle = 0$	(ORTHOGONAL)
	(3). $\ \psi_n(t)\ ^2 > 0 \implies \lambda_n \geq 0$	(NON-NEGATIVE)
	(4). $\ \psi_n(t)\ ^2 > 0, \langle \mathbf{R}f f \rangle > 0 \implies \lambda_n > 0$	(\mathbf{R} POSITIVE DEFINITE $\implies \lambda_n$ POSITIVE)

✎ PROOF:

¹ Keener (1988) pages 114–119

1. Proof that eigenvalues are *real-valued*: Because \mathbf{R} is *self-adjoint*, its eigenvalues are real (Theorem G.18 page 171).
2. Proof that eigenfunctions associated with distinct eigenvalues are orthogonal: Because \mathbf{R} is *self-adjoint*, this property follows (Theorem G.18 page 171).
3. Proof that eigenvalues are *non-negative*:

$$\begin{aligned}
 0 &\leq \langle \mathbf{R}\psi_n | \psi_n \rangle && \text{by definition of } \textit{non-negative definite} \\
 &= \langle \lambda_n \psi_n | \psi_n \rangle && \text{by hypothesis} \\
 &= \lambda_n \langle \psi_n | \psi_n \rangle && \text{by definition of inner-products} \\
 &= \lambda_n \|\psi_n\|^2 && \text{by definition of norm induced by inner-product}
 \end{aligned}$$

4. Proof that eigenvalues are *positive* if \mathbf{R} is *positive definite*:

$$\begin{aligned}
 0 &< \langle \mathbf{R}\psi_n | \psi_n \rangle && \text{by definition of } \textit{positive definite} \\
 &= \langle \lambda_n \psi_n | \psi_n \rangle && \text{by hypothesis} \\
 &= \lambda_n \langle \psi_n | \psi_n \rangle && \text{by homogeneous property of } \langle \triangle | \nabla \rangle \\
 &= \lambda_n \|\psi_n\|^2 && \text{by induced norm theorem}
 \end{aligned}$$



Theorem 4.3 (Karhunen-Loève Expansion). ² Let \mathbf{R} be the AUTO-CORRELATION OPERATOR (Definition 4.1 page 37) of a RANDOM PROCESS $x(t)$. Let $(\lambda_n)_{n \in \mathbb{Z}}$ be the eigenvalues of \mathbf{R} and $(\psi_n)_{n \in \mathbb{Z}}$ are the eigenfunctions of \mathbf{R} such that $\mathbf{R}\psi_n = \lambda_n \psi_n$.

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$$\underbrace{\|\psi_n(t)\| = 1}_{\{\psi_n(t)\} \text{ are NORMALIZED}} \implies \underbrace{\mathbb{E} \left[\left| x(t) - \sum_{n \in \mathbb{Z}} \langle x(t) | \psi_n(t) \rangle \psi_n(t) \right|^2 \right]}_{\text{CONVERGENCE IN PROBABILITY}} = 0 \quad (\{\psi_n(t)\} \text{ is a BASIS for } x(t))$$

PROOF:

1. Define $\dot{x}_n \triangleq \langle x(t) | \psi_n(t) \rangle$
2. lemma: $\mathbb{E}[x(t)x(t)] = \sum_{n \in \mathbb{Z}} \lambda_n |\psi_n(t)|^2$. Proof:

$$\mathbb{E}[x(t)x(t)] = \sum_{n \in \mathbb{Z}} \lambda_n |\psi_n(t)|^2 \quad \begin{array}{l} \text{by } \textit{non-negative property} \text{ (Theorem 11.1 page 89)} \\ \text{and } \textit{Mercer's Theorem} \text{ (Theorem M.4 page 246)} \end{array}$$

² Keener (1988) pages 114–119

3. lemma:

$$\begin{aligned}
 & \mathbb{E} \left[\mathbf{x}(t) \left(\sum_{n \in \mathbb{Z}} \dot{\mathbf{x}}_n \psi_n(t) \right)^* \right] \\
 & \triangleq \mathbb{E} \left[\mathbf{x}(t) \left(\sum_{n \in \mathbb{Z}} \int_{u \in \mathbb{R}} \mathbf{x}(u) \psi_n^*(u) \, du \psi_n(t) \right)^* \right] && \text{by definition of } \dot{\mathbf{x}} && (\text{definition 1 page 91}) \\
 & = \sum_{n \in \mathbb{Z}} \left(\int_{u \in \mathbb{R}} \mathbb{E} [\mathbf{x}(t) \mathbf{x}^*(u)] \psi_n(u) \, du \right) \psi_n^*(t) && \text{by linearity} \\
 & \triangleq \sum_{n \in \mathbb{Z}} \left(\int_{u \in \mathbb{R}} \mathbf{R}_{\mathbf{xx}}(t, u) \psi_n(u) \, du \right) \psi_n^*(t) && \text{by definition of } \mathbf{R}_{\mathbf{xx}}(t, u) && (\text{Definition K.2 page 235}) \\
 & \triangleq \sum_{n \in \mathbb{Z}} (\mathbf{R} \psi_n(t) \psi_n^*(t)) && \text{by definition of } \mathbf{R} && (\text{Definition 4.1 page 37}) \\
 & = \sum_{n \in \mathbb{Z}} \lambda_n \psi_n(t) \psi_n^*(t) && \text{by property of eigen-system} \\
 & = \sum_{n \in \mathbb{Z}} \lambda_n |\psi_n(t)|^2
 \end{aligned}$$

4. lemma:

$$\begin{aligned}
 & \mathbb{E} \left[\sum_{n \in \mathbb{Z}} \dot{\mathbf{x}}_n \psi_n(t) \left(\sum_{m \in \mathbb{Z}} \dot{\mathbf{x}}_m \psi_m(t) \right)^* \right] \\
 & \triangleq \mathbb{E} \left[\sum_{n \in \mathbb{Z}} \int_{u \in \mathbb{R}} \mathbf{x}(u) \psi_n^*(u) \, du \psi_n(t) \left(\sum_{m \in \mathbb{Z}} \int_v \mathbf{x}(v) \psi_m^*(v) \, dv \psi_m(t) \right)^* \right] && \text{by definition of } \dot{\mathbf{x}} && (\text{definition 1 page 91}) \\
 & = \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} \int_u \left(\int_v \mathbb{E} [\mathbf{x}(u) \mathbf{x}^*(v)] \psi_m(v) \, dv \right) \psi_n^*(u) \, du \psi_n(t) \psi_m^*(t) && \text{by linearity} \\
 & = \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} \int_u \left(\int_v \mathbf{R}_{\mathbf{xx}}(u, v) \psi_m(v) \, dv \right) \psi_n^*(u) \, du \psi_n(t) \psi_m^*(t) && \text{by definition of } \mathbf{R}_{\mathbf{xx}}(t, u) && (\text{Definition K.2 page 235}) \\
 & = \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} \int_u (\mathbf{R} \psi_m(u)) \psi_n^*(u) \, du \psi_n(t) \psi_m^*(t) && \text{by definition of } \mathbf{R} && (\text{Definition 4.1 page 37}) \\
 & = \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} \int_u (\lambda_m \psi_m(u)) \psi_n^*(u) \, du \psi_n(t) \psi_m^*(t) && \text{by property of eigen-system} \\
 & = \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} \lambda_m \left(\int_{u \in \mathbb{R}} \psi_m(u) \psi_n^*(u) \, du \right) \psi_n(t) \psi_m^*(t) && \text{by linearity} \\
 & = \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} \lambda_m \|\psi(t)\|^2 \bar{\delta}_{mn} \psi_n(t) \psi_m^*(t) && \text{by orthogonal property} && (\text{Theorem 4.2 page 38}) \\
 & = \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} \lambda_m \bar{\delta}_{mn} \psi_n(t) \psi_m^*(t) && \text{by normalized hypothesis} \\
 & = \sum_{n \in \mathbb{Z}} \lambda_n \psi_n(t) \psi_n^*(t) && \text{by definition of Kronecker delta } \bar{\delta} && (\text{Definition H.12 page 194}) \\
 & = \sum_{n \in \mathbb{Z}} \lambda_n |\psi_n(t)|^2
 \end{aligned}$$

5. Proof that $\{\psi_n(t)\}$ is a *basis* for $\mathbf{x}(t)$:

$$\mathbb{E} \left(\left| \mathbf{x}(t) - \sum_{n \in \mathbb{Z}} \dot{\mathbf{x}}_n \psi_n(t) \right|^2 \right)$$

$$\begin{aligned}
&= \mathbb{E} \left(\left[x(t) - \sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(t) \right] \left[x(t) - \sum_{m \in \mathbb{Z}} \dot{x}_m \psi_m(t) \right]^* \right) \\
&= \mathbb{E} \left(x(t)x^*(t) - x(t) \left[\sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(t) \right]^* - x^*(t) \sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(t) + \left[\sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(t) \right] \left[\sum_{m \in \mathbb{Z}} \dot{x}_m \psi_m(t) \right]^* \right) \\
&= \mathbb{E}(x(t)x^*(t)) - \mathbb{E} \left[x(t) \left[\sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(t) \right]^* \right] - \mathbb{E} \left[x^*(t) \sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(t) \right] + \mathbb{E} \left[\sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(t) \left[\sum_{m \in \mathbb{Z}} \dot{x}_m \psi_m(t) \right]^* \right] \\
&\quad \text{by linearity of } \mathbb{E} \\
&= \underbrace{\sum_{n \in \mathbb{Z}} \lambda_n |\psi_n(t)|^2}_{\text{by (2) lemma}} - \underbrace{\sum_{n \in \mathbb{Z}} \lambda_n |\psi_n(t)|^2}_{\text{by (3) lemma}} - \underbrace{\left[\sum_{n \in \mathbb{Z}} \lambda_n |\psi_n(t)|^2 \right]^*}_{\text{by (3) lemma}} + \underbrace{\sum_{n \in \mathbb{Z}} \lambda_n |\psi_n(t)|^2}_{\text{by (4) lemma}} \\
&= 0
\end{aligned}$$



4.3 Quasi-basis

The *auto-correlation operator* \mathbf{R} (Definition 4.1 page 37) in the discrete case can be approximated using a *correlation matrix*. In the *zero-mean* case, this becomes

$$\mathbf{R} \triangleq \begin{bmatrix} \mathbb{E}[y_1 y_1] & \mathbb{E}[y_1 y_2] & \cdots & \mathbb{E}[y_1 y_n] \\ \mathbb{E}[y_2 y_1] & \mathbb{E}[y_2 y_2] & & \mathbb{E}[y_2 y_n] \\ \vdots & \vdots & \ddots & \vdots \\ \mathbb{E}[y_n y_1] & \mathbb{E}[y_n y_2] & \cdots & \mathbb{E}[y_n y_n] \end{bmatrix}$$

The eigen-vectors (and hence a quasi-basis) for \mathbf{R} can be found using a *Cholesky Decomposition*.

Proposition 4.1.³

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The AUTO-CORRELATION MATRIX \mathbf{R} is *Toeplitz*.

Remark 4.1. For more information about the properties of **Toeplitz matrices**, see

1. Grenander and Szegö (1958),
2. Widom (1965),
3. Gray (1971),
4. Smylie et al. (1973) page 408 (§“B. PROPERTIES OF THE TOEPLITZ MATRIX”),
5. GRENANDER AND SZEGÖ (1984),
6. HAYKIN AND KESLER (1979),
7. HAYKIN AND KESLER (1983),
8. S. LAWRENCE MARPLE (1987) PAGES 80–92 (§“3.8 THE TOEPLITZ MATRIX”),
9. BÖTTCHER AND SILBERMANN (1999) (ISBN:9780387985701),
10. GRAY (2006),
11. S. LAWRENCE MARPLE (2019) PAGES 80–93 (§“3.8 THE TOEPLITZ MATRIX”).

³See Clarkson (1993) page 131 (§“Appendix 3A — Positive Semi-Definite Form of the Autocorrelation Matrix”)

Part II

Continuous to Discrete Transforms

5.1 A basis for sampling

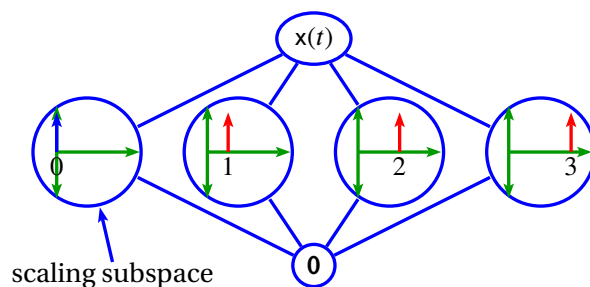
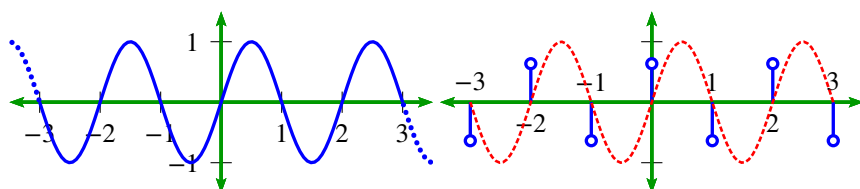
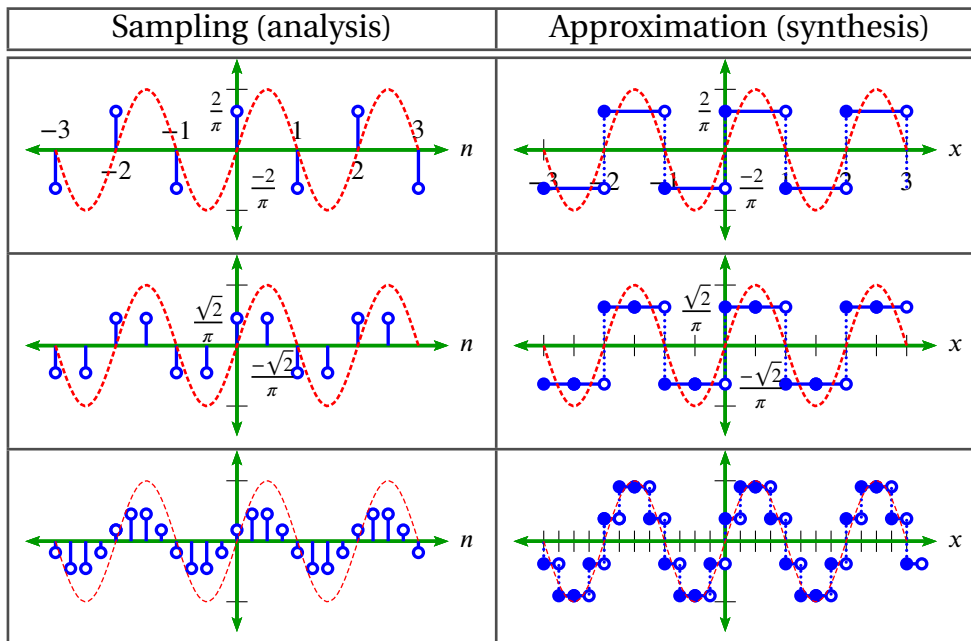


Figure 5.1: A basis for sampling

To perform **sampling**, we *project* continuous functions onto a very special basis to get a **sequence**, as illustrated in Figure 5.1 (page 45).

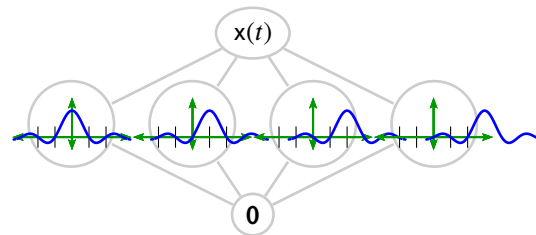
$$\begin{aligned}
 \dot{x}(n) &\triangleq \langle x(t) | \delta(t - n) \rangle \\
 &\triangleq \int_{t=-\infty}^{t=\infty} x(t) \delta(t - n) dt \\
 &= x(n)
 \end{aligned}$$





Approximation getting closer with higher sample rate! But can we ever get back the original? If so, how fast do we need to sample?

The **Sample Theorem** (Theorem 5.3 page 48) answers this question:



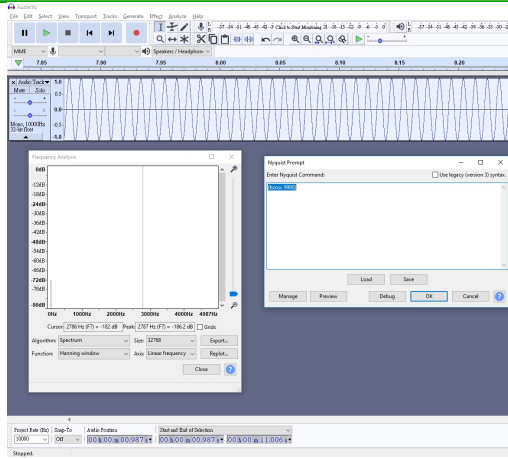
- 🔥 If your signal is **band-limited**, and
if you sample at a rate of *at least* $2\times$ the highest frequency (the *Nyquist frequency*), and
if you happen to have an *ideal* low-pass filter,
then you can get the original signal back (perfect synthesis!).
- 🔥 But if you don't sample fast enough, you get **aliasing**.

When aliasing occurs, a high frequency component can “masquerade” as (“pretend” to be, “im-personate”, “assume the identity” of, or “take on the alias” of) an entirely different low frequency component. That is, it forces a high frequency component to take up residence as an *alien* (*alias* and *alien* have the same Latin root *al* meaning “beyond”¹) in a low frequency location.

Example 5.1 (Aliasing using Audacity). Here is an experiment with aliasing you can try using the free program Audacity and the *Nyquist programming language plugin*.²

¹<https://www.etymonline.com/word/alias>, <https://www.etymonline.com/word/alien>

²Audacity®: “Free, open source, cross-platform audio software”. <https://www.audacityteam.org/>; Nyquist plugin: <https://www.audacityteam.org/about/nyquist/>

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X

1. Set Project Rate to 10000 (Hz)
2. Tracks → New Track → Mono Track
3. Select 1 second to 11 seconds
4. Effect → Nyquist prompt → (hzosc 9900)

In this case, the 9900 Hz sinusoid will be aliased to show up as a 100 Hz sinusoid (more impressive if you happen to have a good subwoofer handy).

5.2 Cardinal Series and Sampling

5.2.1 Cardinal series basis

The *Paley-Wiener* class of functions (next definition) are those with a bandlimited Fourier transform. The cardinal series forms an orthogonal basis for such a space (Theorem 5.2 page 48). In a *frame* $(\mathbf{x}_n)_{n \in \mathbb{Z}}$ with *frame operator* \mathbf{S} on a *Hilbert Space* \mathbf{H} with *inner product* $\langle \triangle | \nabla \rangle$, a function $f(x)$ in the space spanned by the frame can be represented by

$$f(x) = \sum_{n \in \mathbb{Z}} \underbrace{\langle f | \mathbf{S}^{-1} \mathbf{x}_n \rangle}_{\text{"Fourier coefficient"}} \mathbf{x}_n.$$

If the frame is *orthonormal* (giving an *orthonormal basis*), then $\mathbf{S} = \mathbf{S}^{-1} = \mathbf{I}$ and

$$f(x) = \sum_{n \in \mathbb{Z}} \langle f | \mathbf{x}_n \rangle \mathbf{x}_n.$$

In the case of the cardinal series, the *Fourier coefficients* (Definition H.11 page 194) are particularly simple—these coefficients are samples of f taken at regular intervals (Theorem 5.3 page 48). In fact, one could represent the coefficients using inner product notation with the *Dirac delta distribution* δ as follows:

$$\langle f(x) | \delta(x - n\tau) \rangle \triangleq \int_{\mathbb{R}} f(x) \delta(x - n\tau) dt \triangleq f(n\tau)$$

Definition 5.1.³

A function $f \in \mathbb{C}^{\mathbb{C}}$ is in the **Paley-Wiener** class of functions \mathbf{PW}_{σ}^p if there exists $F \in L^p(-\sigma : \sigma)$ such that

$$f(x) = \int_{-\sigma}^{\sigma} F(\omega) e^{ix\omega} d\omega \quad (f \text{ has a BANDLIMITED Fourier transform } F \text{ with bandwidth } \sigma)$$

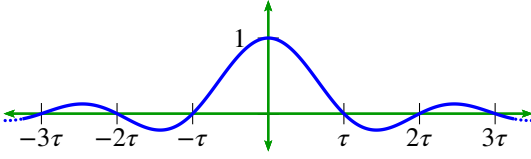
for $p \in [1 : \infty)$ and $\sigma \in (0 : \infty)$.

Theorem 5.1 (Paley-Wiener Theorem for Functions).⁴ Let f be an ENTIRE FUNCTION (the domain of f is the entire complex plane \mathbb{C}). Let $\sigma \in \mathbb{R}^+$.

³ Higgins (1996) page 52 (Definition 6.15)

⁴ Boas (1954) page 103 (6.8.1 Theorem of Paley and Wiener), Katznelson (2004) page 212 (7.4 Theorem), Zygmund (2002) pages 272–273 ((7·2) THEOREM OF PALEY-WIENER), Yosida (1980) page 161, Rudin (1987) page 375 (19.3 THEOREM), Young (2001) page 85 (THEOREM 18)

$$\text{THM} \quad \{f \in \mathcal{PW}_\sigma^2\} \iff \left\{ \begin{array}{l} 1. \exists C \in \mathbb{R}^+ \text{ such that } |f(z)| \leq C e^{\sigma|z|} \quad (\text{EXPONENTIAL TYPE}) \text{ and} \\ 2. f \in L^2_{\mathbb{R}} \end{array} \right\}$$



Theorem 5.2 (Cardinal sequence).⁵

$$\text{THM} \quad \left\{ \frac{1}{\tau} \geq 2\sigma \right\} \implies \text{The sequence } \left(\frac{\sin \left[\frac{\pi}{\tau}(x - n\tau) \right]}{\frac{\pi}{\tau}(x - n\tau)} \right)_{n \in \mathbb{Z}} \text{ is an ORTHONORMAL BASIS for } \mathcal{PW}_\sigma^2.$$

Theorem 5.3 (Sampling Theorem).⁶

$$\text{THM} \quad \left\{ \begin{array}{l} 1. f \in \mathcal{PW}_\sigma^2 \text{ and} \\ 2. \frac{1}{\tau} \geq 2\sigma \end{array} \right\} \implies f(x) = \underbrace{\sum_{n=1}^{\infty} f(n\tau) \frac{\sin \left[\frac{\pi}{\tau}(x - n\tau) \right]}{\frac{\pi}{\tau}(x - n\tau)}}_{\text{CARDINAL SERIES}}.$$

PROOF:

$$\text{Let } s(x) \triangleq \frac{\sin \left[\frac{\pi}{\tau}x \right]}{\frac{\pi}{\tau}x} \iff \tilde{s}(\omega) = \begin{cases} \tau & : |\omega| \leq \frac{1}{2\tau} \\ 0 & : \text{otherwise} \end{cases}$$

1. Proof that the set is *orthonormal*: see [Hardy \(1941\)](#)
2. Proof that the set is a *basis*:

$$\begin{aligned} f(x) &= \int_{\omega} \tilde{f}(\omega) e^{i\omega x} d\omega && \text{by inverse Fourier transform} && (\text{Theorem 3.1 page 27}) \\ &= \int_{\omega} \mathbf{T} \tilde{f}_d(\omega) \tilde{s}(\omega) e^{i\omega x} d\omega && \text{if } W \leq \frac{1}{2T} \\ &= \mathbf{T} f_d(x) \star s(x) && \text{by Convolution theorem} && (\text{Theorem 9.2 page 72}) \\ &= \mathbf{T} \int_u [f_d(u)] s(x-u) du && \text{by convolution definition} && (\text{Definition C.1 page 103}) \\ &= \mathbf{T} \int_u \left[\sum_{n \in \mathbb{Z}} f(u) \delta(u - n\tau) \right] s(x-u) du && \text{by sampling definition} && (\text{Theorem 5.4 page 49}) \\ &= \mathbf{T} \sum_{n \in \mathbb{Z}} \int_u f(u) s(x-u) \delta(u - n\tau) du \\ &= \mathbf{T} \sum_{n \in \mathbb{Z}} f(n\tau) s(x - n\tau) && \text{by prop. of Dirac delta} \end{aligned}$$

⁵ [Higgins \(1996\) page 52](#) (Definition 6.15), [Hardy \(1941\)](#) (orthonormality), [Higgins \(1985\) page 56](#) (H1.; historical notes)

⁶ [Whittaker \(1915\)](#), [Kotelnikov \(1933\)](#), [Whittaker \(1935\)](#), [Shannon \(1948\)](#) (Theorem 13), [Shannon \(1949\) page 11](#), [II \(1991\) page 1](#), [Nashed and Walter \(1991\)](#), [Higgins \(1996\) page 5](#), [Young \(2001\) pages 90–91](#) (THE PALEY-WIENER SPACE), [Papoulis \(1980\) pages 418–419](#) (The Sampling Theorem). The *sampling theorem* was “discovered” and published by multiple people: Nyquist in 1928 (DSP?), Whittaker in 1935 (interpolation theory), and Shannon in 1949 (communication theory). references: [Mallat \(1999\) page 43](#), [Oppenheim and Schaffer \(1999\) page 143](#).

$$= T \sum_{n \in \mathbb{Z}} f(n\tau) \frac{\sin \left[\frac{\pi}{\tau}(x - n\tau) \right]}{\frac{\pi}{\tau}(x - n\tau)} \quad \text{by definition of } s(x)$$

⇒

5.2.2 Sampling

Definition 5.2. ⁷ Let $\delta(x)$ be the DIRAC DELTA distribution.

DEF The **Shah Function** $\text{III}(x)$ is defined as $\text{III}(x) \triangleq \sum_{n \in \mathbb{Z}} \delta(x - n)$

If $f_d(x)$ is the function $f(x)$ sampled at rate $1/T$, then $\tilde{f}_d(\omega)$ is simply $\tilde{f}(\omega)$ replicated every $1/T$ Hertz and scaled by $1/T$. This is proven in Theorem 5.4 (next) and illustrated in Figure 5.2 (page 49).

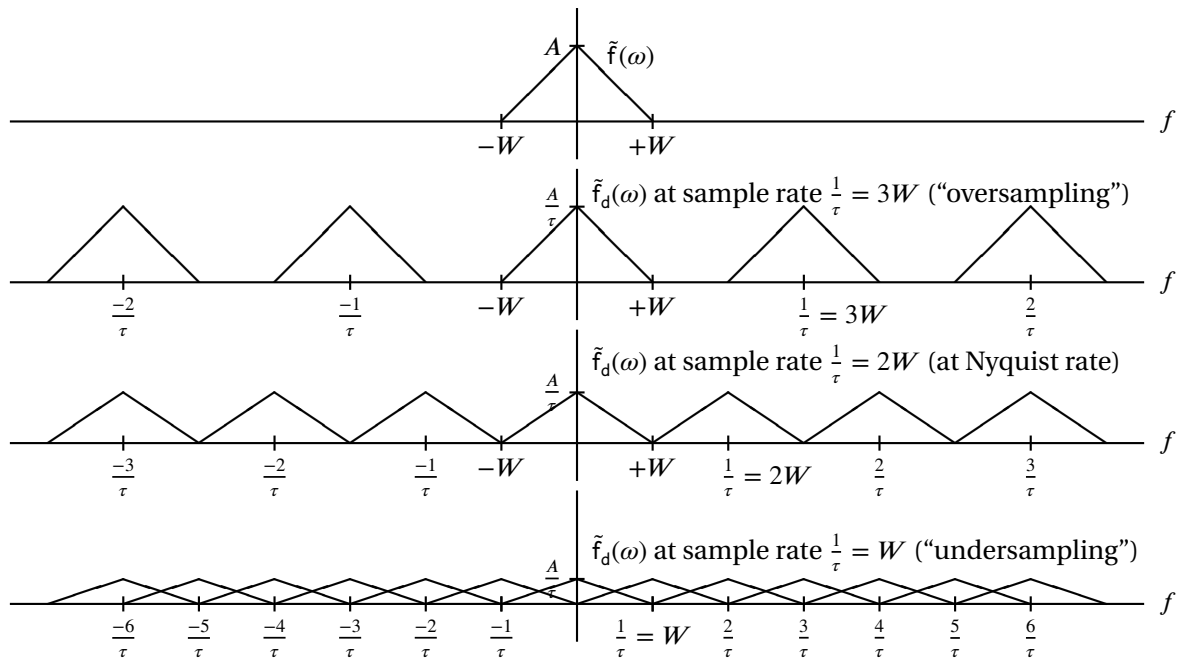


Figure 5.2: Sampling in frequency domain

Theorem 5.4. Let $f, f_d \in L^2_{\mathbb{R}}$ and $\tilde{f}, \tilde{f}_d \in L^2_{\mathbb{R}}$ be their respective fourier transforms. Let $f_d(x)$ be the **sampld** $f(x)$ such that

$$f_d(x) \triangleq \sum_{n \in \mathbb{Z}} f(x) \delta(x - n\tau).$$

T H M $\left\{ f_d(x) \triangleq f(x) \text{III}(x) \triangleq f(x) \sum_{n \in \mathbb{Z}} \delta(x - n\tau) \right\} \implies \left\{ \tilde{f}_d(\omega) = \frac{2\pi}{\tau} \sum_{n \in \mathbb{Z}} \tilde{f}\left(\omega - \frac{2\pi}{\tau}n\right) \right\}$

⁷ Bracewell (1978) page 77 <The sampling or replicating symbol $\text{III}(x)$ >, Córdoba (1989) 191. Note: The symbol III is the Cyrillic upper case “sha” character, which has been assigned Unicode location U+0428. Reference: <http://unicode.org/cldr/utility/character.jsp?a=0428>

✎ PROOF:

$$\begin{aligned}
 \tilde{f}_d(\omega) &\triangleq \int_t f_d(x) e^{-i\omega t} dt \\
 &= \int_t \left[\sum_{n \in \mathbb{Z}} f(x) \delta(x - n\tau) \right] e^{-i\omega t} dt \\
 &= \sum_{n \in \mathbb{Z}} \int_t f(x) \delta(x - n\tau) e^{-i\omega t} dt \\
 &= \sum_{n \in \mathbb{Z}} f(n\tau) e^{-i\omega n\tau} && \text{by definition of } \delta \\
 &= \frac{2\pi}{\tau} \sum_{n \in \mathbb{Z}} \tilde{f}\left(\omega + \frac{2\pi}{\tau}n\right) && \text{by IPSF} \quad (\text{Theorem J.3 page 231}) \\
 &= \frac{2\pi}{\tau} \sum_{n \in \mathbb{Z}} \tilde{f}\left(\omega - \frac{2\pi}{\tau}n\right)
 \end{aligned}$$

⇒

Suppose a waveform $f(x)$ is sampled at every time T generating a sequence of sampled values $f(n\tau)$. Then in general, we can *approximate* $f(x)$ by using interpolation between the points $f(n\tau)$. Interpolation can be performed using several interpolation techniques.

In general all techniques lead only to an approximation of $f(x)$. However, if $f(x)$ is *bandlimited* with bandwidth $W \leq \frac{1}{2T}$, then $f(x)$ is *perfectly reconstructed* (not just approximated) from the sampled values $f(n\tau)$ (Theorem 5.3 page 48).

CHAPTER 6

TAYLOR EXPANSIONS (TRANSFORMS)

6.1 Introduction

For modeling real-world processes above the quantum level, measurements are *continuous* in time—that is, the first derivative of a function over time representing the measurement *exists*.

But even for “simple” physical systems, it is not just the first derivative that matters. For example, the classical “vibrating string” vertical displacement $u(x, t)$ wave equation can be described as

$$\frac{\partial^2 u}{\partial x^2} - \frac{1}{c^2} \frac{\partial^2 u}{\partial t^2} = 0$$

Not only do physical systems demonstrate heavy dependence on the derivatives of their measurement functions, but also commonly exhibit *oscillation*, as demonstrated by sunspot activity over the last 300 years or earthquake activity (Figure 6.1 page 52).

In fact, derivatives and oscillations are fundamentally linked as demonstrated by the fact that all solutions of homogeneous second order differential equations are linear combinations of sine and cosine functions (Theorem D.3 page 110):

$$\left\{ \frac{d^2}{dx^2} f + f = 0 \right\} \iff \left\{ f(x) = f(0) \cos(x) + f'(0) \sin(x) \right\} \quad \forall f \in \mathcal{C}, \forall x \in \mathbb{R}$$

Derivatives are calculated *locally* about a point. Oscillations are observed *globally* over a range, and analyzed (decomposed) by projecting the function onto a sequence of basis functions—sinusoids in the case of Fourier Transform family. Projection is accomplished using inner products, and often these are calculated using *integration*. Note that derivatives and integrals are also fundamentally linked as demonstrated by the *Fundamental Theorem of Calculus*...which shows that integration can be calculated using anti-differentiation:

$$\int_a^b f(x) dx = F(b) - F(a) \quad \text{where } F(x) \text{ is the antiderivative of } f(x).$$

Brook Taylor showed that for *analytic* functions,¹ knowledge of the derivatives of a function at a location $x = a$ allows you to determine (predict) arbitrarily closely all the points $f(x)$ in the vicinity

¹ *analytic* functions: Functions for which all their derivatives exist.

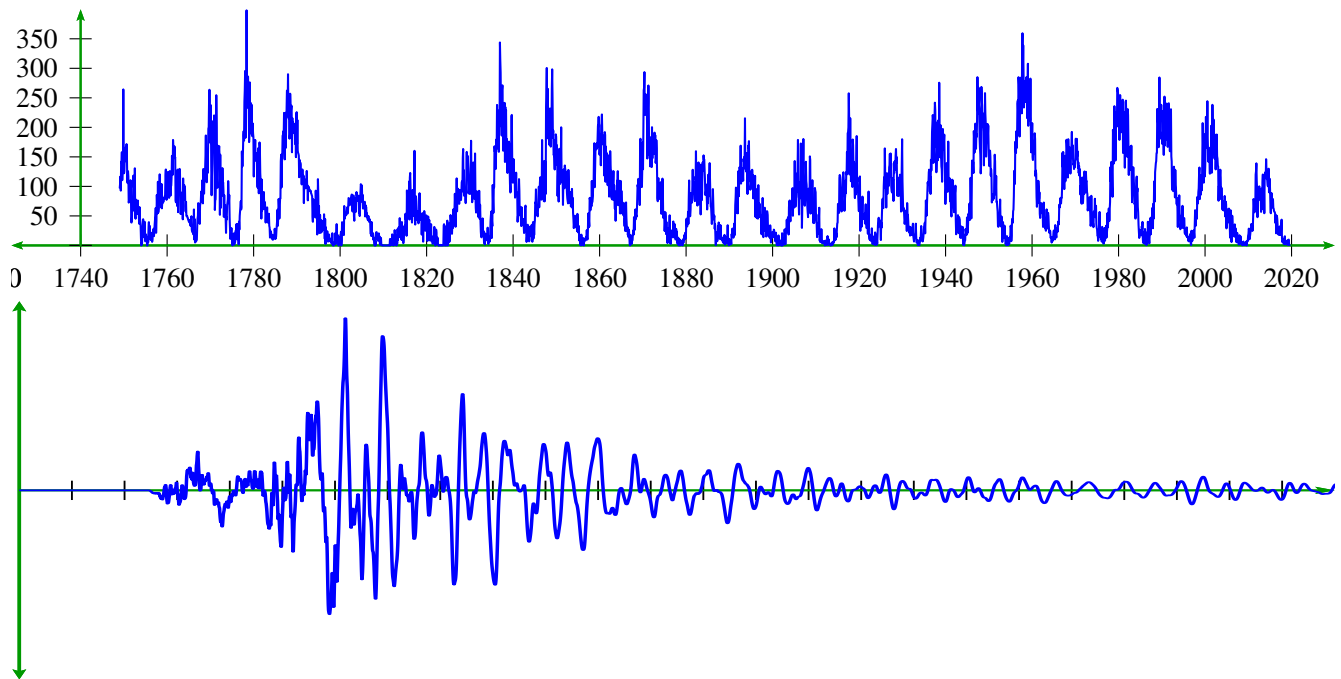


Figure 6.1: Sunspot and earthquake measurements

of $x = a$:²

$$f(x) = f(a) + \frac{1}{1!}f'(a)[x - a] + \frac{1}{2!}f''(a)[x - a]^2 + \frac{1}{3!}f'''(a)[x - a]^3 + \dots$$

On the other hand, the *Fourier Transform* is a kind of counter-part of the Taylor expansion:³

	Taylor coefficients	Fourier coefficients
	Depend on derivatives $\frac{d^n}{dx^n}f(x)$	Depend on integrals $\int_{x \in \mathbb{R}} f(x)e^{-i\omega x} dx$
	Behavior in the vicinity of a point.	Behavior over the entire function.
	Demonstrate trends locally.	Demonstrate trends globally, such as oscillations.
	Admits <i>analytic</i> functions only.	Admits <i>non-analytic</i> functions as well.
	Function must be <i>continuous</i> .	Function can be <i>discontinuous</i> .

6.2 Taylor Expansion

Theorem 6.1 (Taylor Series).⁴ Let \mathcal{C} be the space of all ANALYTIC functions and $\frac{d}{dx}$ in \mathcal{C} the DIFFERENTIATION OPERATOR.

A **Taylor Series** about the point $x = a$ of a function $f(x) \in \mathcal{C}$ is

$$f(x) = \sum_{n=0}^{\infty} \underbrace{\frac{\left[\frac{d^n}{dx^n} f\right](a)}{n!}}_{\text{coefficient}} \underbrace{(x-a)^n}_{\text{basis function}} \quad \forall a \in \mathbb{R}, f \in \mathcal{C}$$

A **Maclaurin Series** is a TAYLOR SERIES about the point $a = 0$.

² Robinson (1982) page 886

³ Robinson (1982) page 886

⁴ Flanigan (1983) page 221 (Theorem 15), Strichartz (1995) page 281, Sohrab (2003) page 317 (Theorem 8.4.9), Taylor (1715), Taylor (1717), Maclaurin (1742)

CHAPTER 7

FOURIER SERIES

“...et la nouveauté de l'objet, jointe à son importance, a déterminé la classe à couronner cet ouvrage, en observant cependant que la manière dont l'auteur parvient à ses équations n'est pas exempte de difficultés, et que son analyse, pour les intégrer, laisse encore quelque chose à désirer, soit relativement à la généralité, soit même du côté de la rigueur.”

A competition awards committee consisting of the mathematical giants [Lagrange](#), [Laplace](#), [Legendre](#), and others, commenting on [Fourier's 1807 landmark paper](#) *Dissertation on the propagation of heat in solid bodies* that introduced the *Fourier Series*.¹



“...and the innovation of the subject, together with its importance, convinced the committee to crown this work. By observing however that the way in which the author arrives at his equations is not free from difficulties, and the analysis of which, to integrate them, still leaves something to be desired, either relative to generality, or even on the side of rigour.”

7.1 Definition

The *Fourier Series* expansion of a periodic function is simply a complex trigonometric polynomial. In the special case that the periodic function is even, then the Fourier Series expansion is a cosine polynomial.

Definition 7.1.²

The **Fourier Series operator** $\hat{F} : L^2_{\mathbb{R}} \rightarrow \ell^2_{\mathbb{R}}$ is defined as

$$[\hat{F}f](n) \triangleq \frac{1}{\sqrt{\tau}} \int_0^{\tau} f(x) e^{-i \frac{2\pi}{\tau} nx} dx \quad \forall f \in \{f \in L^2_{\mathbb{R}} \mid f \text{ is periodic with period } \tau\}$$

¹ quote: [Lagrange et al. \(1812b\)](#) page 374, [Lagrange et al. \(1812a\)](#) page 112, [Kahane \(2008\)](#) page 199
translation: assisted by [Google Translate](#), [Castanedo \(2005\)](#) (chapter 2 footnote 5)
paper: [Fourier \(1807\)](#)

² [Katznelson \(2004\)](#) page 3

7.2 Inverse Fourier Series operator

Theorem 7.1. Let $\hat{\mathbf{F}}$ be the Fourier Series operator.

T H M

The **inverse Fourier Series** operator $\hat{\mathbf{F}}^{-1}$ is given by

$$[\hat{\mathbf{F}}^{-1}((\tilde{x}_n)_{n \in \mathbb{Z}})](x) \triangleq \frac{1}{\sqrt{\tau}} \sum_{n \in \mathbb{Z}} \tilde{x}_n e^{i \frac{2\pi}{\tau} nx} \quad \forall (\tilde{x}_n) \in \ell^2_{\mathbb{R}}$$

✎ **PROOF:** The proof of the pointwise convergence of the Fourier Series is notoriously difficult. It was conjectured in 1913 by Nikolai Luzin that the Fourier Series for all square summable periodic functions are pointwise convergent: [Luzin \(1913\)](#)

Fifty-three years later (1966) at a conference in Moscow, Lennart Axel Edvard Carleson presented one of the most spectacular results ever in mathematics; he demonstrated that the Luzin conjecture is indeed correct. Carleson formally published his result that same year: [Carleson \(1966\)](#)

Carleson's proof is expounded upon in Reyna's (2002) 175 page book: [de Reyna \(2002\)](#)

Interestingly enough, Carleson started out trying to disprove Luzin's conjecture. Carleson said this in an interview published in 2001:³ “Well, the problem of course presents itself already when you are a student and I was thinking of the problem on and off, but the situation was more interesting than that. The great authority in those days was Zygmund and he was completely convinced that what one should produce was not a proof but a counter-example. When I was a young student in the United States, I met Zygmund and I had an idea how to produce some very complicated functions for a counter-example and Zygmund encouraged me very much to do so. I was thinking about it for about 15 years on and off, on how to make these counter-examples work and the interesting thing that happened was that I suddenly realized why there should be a counter-example and how you should produce it. I thought I really understood what was the background and then to my amazement I could prove that this “correct” counter-example couldn't exist and therefore I suddenly realized that what you should try to do was the opposite, you should try to prove what was not fashionable, namely to prove convergence. The most important aspect in solving a mathematical problem is the conviction of what is the true result! Then it took like 2 or 3 years using the technique that had been developed during the past 20 years or so. It is actually a problem related to analytic functions basically even though it doesn't look that way.”

For now, if you just want some intuitive justification for the Fourier Series, and you can somehow imagine that the Dirichlet kernel generates a *comb* function of Dirac delta functions, then perhaps what follows may help (or not). It is certainly not mathematically rigorous and is by no means a real proof (but at least it is less than 175 pages).

$$\begin{aligned} [\hat{\mathbf{F}}^{-1} \hat{\mathbf{F}} \mathbf{x}](x) &= \hat{\mathbf{F}}^{-1} \left[\underbrace{\frac{1}{\sqrt{\tau}} \int_0^{\tau} \mathbf{x}(x) e^{-i \frac{2\pi}{\tau} nx} dx}_{\hat{\mathbf{F}} \mathbf{x}} \right] && \text{by definition of } \hat{\mathbf{F}} && \text{(Definition 7.1 page 53)} \\ &= \frac{1}{\sqrt{\tau}} \sum_{n \in \mathbb{Z}} \left[\frac{1}{\sqrt{\tau}} \int_0^{\tau} \mathbf{x}(u) e^{-i \frac{2\pi}{\tau} nu} du \right] e^{i \frac{2\pi}{\tau} nx} && \text{by definition of } \hat{\mathbf{F}}^{-1} \\ &= \frac{1}{\sqrt{\tau}} \sum_{n \in \mathbb{Z}} \frac{1}{\sqrt{\tau}} \int_0^{\tau} \mathbf{x}(u) e^{-i \frac{2\pi}{\tau} nu} e^{i \frac{2\pi}{\tau} nx} du \\ &= \frac{1}{\sqrt{\tau}} \sum_{n \in \mathbb{Z}} \frac{1}{\sqrt{\tau}} \int_0^{\tau} \mathbf{x}(u) e^{i \frac{2\pi}{\tau} n(x-u)} du \end{aligned}$$

³ [Carleson and Engquist \(2001\)](#)

$$\begin{aligned}
&= \int_0^\tau x(u) \underbrace{\frac{1}{\tau} \sum_{n \in \mathbb{Z}} e^{i \frac{2\pi}{\tau} n(x-u)}}_{\lim_{N \rightarrow \infty} D_n(x)} du \\
&= \int_0^\tau x(u) \left[\sum_{n \in \mathbb{Z}} \delta(x - u - n\tau) \right] du \\
&= \sum_{n \in \mathbb{Z}} \int_{u=0}^{u=\tau} x(u) \delta(x - u - n\tau) du \\
&= \sum_{n \in \mathbb{Z}} \int_{v=n\tau}^{v=n\tau+\tau} x(v - n\tau) \delta(x - v) dv && \text{where } v \triangleq u + n\tau \\
&= \sum_{n \in \mathbb{Z}} \int_{v=n\tau}^{v=(n+1)\tau} x(v - n\tau) \delta(x - v) dv && \text{where } v \triangleq u + n\tau \\
&= \sum_{n \in \mathbb{Z}} \int_{v=n\tau}^{v=(n+1)\tau} x(v) \delta(x - v) dv && \text{because } x \text{ is periodic with period } \tau \\
&= \int_{\mathbb{R}} x(v) \delta(x - v) dv \\
&= x(x) \\
&= \mathbf{I}\tilde{x}(n) && \text{by definition of } \mathbf{I} \quad (\text{Definition G.3 page 154})
\end{aligned}$$

$$\begin{aligned}
[\hat{\mathbf{F}}\hat{\mathbf{F}}^{-1}\tilde{x}](n) &= \hat{\mathbf{F}} \left[\frac{1}{\sqrt{\tau}} \sum_{k \in \mathbb{Z}} \tilde{x}(k) e^{i \frac{2\pi}{\tau} kx} \right] && \text{by definition of } \hat{\mathbf{F}}^{-1} \\
&= \frac{1}{\sqrt{\tau}} \int_0^\tau \left[\frac{1}{\sqrt{\tau}} \sum_{k \in \mathbb{Z}} \tilde{x}(k) e^{i \frac{2\pi}{\tau} kx} \right] e^{-i \frac{2\pi}{\tau} nx} dx && \text{by definition of } \hat{\mathbf{F}} \quad (\text{Definition 7.1 page 53}) \\
&= \frac{1}{\tau} \int_0^\tau \left[\sum_{k \in \mathbb{Z}} \tilde{x}(k) e^{i \frac{2\pi}{\tau} (k-n)x} \right] dx \\
&= \sum_{k \in \mathbb{Z}} \tilde{x}(k) \left[\frac{1}{\tau} \int_0^\tau e^{i \frac{2\pi}{\tau} (k-n)x} dx \right] \\
&= \sum_{k \in \mathbb{Z}} \tilde{x}(k) \frac{1}{\tau} \left[\frac{1}{i \frac{2\pi}{\tau} (k-n)} e^{i \frac{2\pi}{\tau} (k-n)x} \right]_0^\tau \\
&= \sum_{k \in \mathbb{Z}} \tilde{x}(k) \frac{1}{i 2\pi (k-n)} [e^{i 2\pi (k-n)} - 1] \\
&= \sum_{k \in \mathbb{Z}} \tilde{x}(k) \delta(k-n) \lim_{x \rightarrow 0} \left[\frac{e^{i 2\pi x} - 1}{i 2\pi x} \right] \\
&= \tilde{x}(n) \frac{\frac{d}{dx} (e^{i 2\pi x} - 1)}{\frac{d}{dx} (i 2\pi x)} \Big|_{x=0} && \text{by l'Hôpital's rule} \\
&= \tilde{x}(n) \frac{i 2\pi e^{i 2\pi x}}{i 2\pi} \Big|_{x=0} \\
&= \tilde{x}(n) \\
&= \mathbf{I}\tilde{x}(n) && \text{by definition of } \mathbf{I} \quad (\text{Definition G.3 page 154})
\end{aligned}$$



Theorem 7.2.

The Fourier Series adjoint operator $\hat{\mathbf{F}}^*$ is given by
 $\hat{\mathbf{F}}^* = \hat{\mathbf{F}}^{-1}$

✎ PROOF:

$$\begin{aligned}
 \langle \hat{\mathbf{F}}x(x) \mid \tilde{y}(n) \rangle_{\mathbb{Z}} &= \left\langle \frac{1}{\sqrt{\tau}} \int_0^\tau x(x) e^{-i\frac{2\pi}{\tau} nx} dx \mid \tilde{y}(n) \right\rangle_{\mathbb{Z}} && \text{by definition of } \hat{\mathbf{F}} && (\text{Definition 7.1 page 53}) \\
 &= \frac{1}{\sqrt{\tau}} \int_0^\tau x(x) \left\langle e^{-i\frac{2\pi}{\tau} nx} \mid \tilde{y}(n) \right\rangle_{\mathbb{Z}} dx && \text{by additivity property of } \langle \Delta \mid \nabla \rangle \\
 &= \int_0^\tau x(x) \frac{1}{\sqrt{\tau}} \left\langle \tilde{y}(n) \mid e^{-i\frac{2\pi}{\tau} nx} \right\rangle_{\mathbb{Z}}^* dx && \text{by property of } \langle \Delta \mid \nabla \rangle \\
 &= \int_0^\tau x(x) [\hat{\mathbf{F}}^{-1} \tilde{y}(n)]^* dx && \text{by definition of } \hat{\mathbf{F}}^{-1} && (\text{Theorem 7.1 page 54}) \\
 &= \left\langle x(x) \mid \underbrace{\hat{\mathbf{F}}^{-1} \tilde{y}(n)}_{\hat{\mathbf{F}}^*} \right\rangle_{\mathbb{R}}
 \end{aligned}$$

⇒

The Fourier Series operator has several nice properties:

🔥 $\hat{\mathbf{F}}$ is *unitary*⁴ (Corollary 7.1 page 56).

🔥 Because $\hat{\mathbf{F}}$ is unitary, it automatically has several other nice properties such as being *isometric*, and satisfying *Parseval's equation*, satisfying *Plancherel's formula*, and more (Corollary 7.2 page 56).

Corollary 7.1. Let \mathbf{I} be the identity operator and let $\hat{\mathbf{F}}$ be the Fourier Series operator with adjoint $\hat{\mathbf{F}}^*$.

COR $\{ \hat{\mathbf{F}}\hat{\mathbf{F}}^* = \hat{\mathbf{F}}^*\hat{\mathbf{F}} = \mathbf{I} \} \quad (\hat{\mathbf{F}} \text{ is } \mathbf{unitary} \dots \text{and thus also NORMAL and ISOMETRIC})$

✎ PROOF: This follows directly from the fact that $\hat{\mathbf{F}}^* = \hat{\mathbf{F}}^{-1}$ (Theorem 7.2 page 55).

⇒

Corollary 7.2. Let $\hat{\mathbf{F}}$ be the Fourier series operator with adjoint $\hat{\mathbf{F}}^*$ and inverse $\hat{\mathbf{F}}^{-1}$.

COR

$\mathcal{R}(\hat{\mathbf{F}})$	$=$	$\mathcal{R}(\hat{\mathbf{F}}^{-1})$	$=$	$L_{\mathbb{R}}^2$	
$\ \hat{\mathbf{F}}\ $	$=$	$\ \hat{\mathbf{F}}^{-1}\ $	$=$	1	(UNITARY)
$\langle \hat{\mathbf{F}}x \mid \hat{\mathbf{F}}y \rangle$	$=$	$\langle \hat{\mathbf{F}}^{-1}x \mid \hat{\mathbf{F}}^{-1}y \rangle$	$=$	$\langle x \mid y \rangle$	(PARSEVAL'S EQUATION)
$\ \hat{\mathbf{F}}x\ $	$=$	$\ \hat{\mathbf{F}}^{-1}x\ $	$=$	$\ x\ $	(PLANCHEREL'S FORMULA)
$\ \hat{\mathbf{F}}x - \hat{\mathbf{F}}y\ $	$=$	$\ \hat{\mathbf{F}}^{-1}x - \hat{\mathbf{F}}^{-1}y\ $	$=$	$\ x - y\ $	(ISOMETRIC)

✎ PROOF: These results follow directly from the fact that $\hat{\mathbf{F}}$ is unitary (Corollary 7.1 page 56) and from the properties of unitary operators (Theorem G.26 page 178).

⇒

7.3 Fourier series for compactly supported functions

Theorem 7.3.

THM The set $\left\{ \frac{1}{\sqrt{\tau}} e^{i\frac{2\pi}{\tau} nx} \mid n \in \mathbb{Z} \right\}$ is an ORTHONORMAL BASIS for all functions $f(x)$ with support in $[0 : \tau]$.

⁴unitary operators: Definition G.14 page 177

Part III

Discrete to Continuous Transforms

CHAPTER 8

DISCRETE TIME FOURIER TRANSFORM

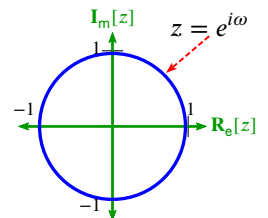
8.1 Definition

Definition 8.1.

DEF The *discrete-time Fourier transform* $\check{\mathbf{F}}$ of $(x_n)_{n \in \mathbb{Z}}$ is defined as

$$[\check{\mathbf{F}}(x_n)](\omega) \triangleq \sum_{n \in \mathbb{Z}} x_n e^{-i\omega n} \quad \forall (x_n)_{n \in \mathbb{Z}} \in \ell^2_{\mathbb{R}}$$

If we compare the definition of the *Discrete Time Fourier Transform* (Definition 8.1 page 59) to the definition of the Z-transform (Definition 9.4 page 70), we see that the DTFT is just a special case of the more general Z-Transform, with $z = e^{i\omega}$. If we imagine $z \in \mathbb{C}$ as a complex plane, then $e^{i\omega}$ is a unit circle in this plane. The “frequency” ω in the DTFT is the unit circle in the much larger z -plane, as illustrated to the right.



8.2 Properties

Proposition 8.1 (DTFT periodicity). Let $\check{x}(\omega) \triangleq \check{\mathbf{F}}[(x_n)](\omega)$ be the DISCRETE-TIME FOURIER TRANSFORM (Definition 8.1 page 59) of a sequence $(x_n)_{n \in \mathbb{Z}}$ in $\ell^2_{\mathbb{R}}$.

PRP

$$\underbrace{\check{x}(\omega) = \check{x}(\omega + 2\pi n)}_{\text{PERIODIC with period } 2\pi} \quad \forall n \in \mathbb{Z}$$

✎ PROOF:

$$\begin{aligned} \check{x}(\omega + 2\pi n) &= \sum_{m \in \mathbb{Z}} x_m e^{-i(\omega + 2\pi n)m} &= \sum_{m \in \mathbb{Z}} x_m e^{-i\omega m} \cancel{e^{-i2\pi nm}} \overset{1}{=} \\ &= \sum_{m \in \mathbb{Z}} x_m e^{-i\omega m} &= \check{x}(\omega) \end{aligned}$$

Theorem 8.1. Let $\check{x}(\omega) \triangleq \check{\mathbf{F}}[(x[n])](\omega)$ be the DISCRETE-TIME FOURIER TRANSFORM (Definition 8.1 page 59) of a sequence $(x_n)_{n \in \mathbb{Z}}$ in $\ell^2_{\mathbb{R}}$.

T
H
M

$$\left\{ \check{x}(\omega) \triangleq \check{\mathbf{F}}[(x[n])] \right\} \implies \left\{ \begin{array}{l} (1). \quad \check{\mathbf{F}}[(x[-n])] = \check{x}(-\omega) \quad \text{and} \\ (2). \quad \check{\mathbf{F}}[(x^*[n])] = \check{x}^*(-\omega) \quad \text{and} \\ (3). \quad \check{\mathbf{F}}[(x^*[-n])] = \check{x}^*(\omega) \end{array} \right\}$$

PROOF:

$$\begin{aligned} \check{\mathbf{F}}[(x[-n])] &\triangleq \sum_{n \in \mathbb{Z}} x[-n] e^{-i\omega n} && \text{by definition of DTFT} && (\text{Definition 8.1 page 59}) \\ &= \sum_{m \in \mathbb{Z}} x[m] e^{i\omega m} && \text{where } m \triangleq -n \implies n = -m \\ &= \sum_{m \in \mathbb{Z}} x[m] e^{-i(-\omega)m} \\ &\triangleq \check{x}(-\omega) && \text{by left hypothesis} \end{aligned}$$

$$\begin{aligned} \check{\mathbf{F}}[(x^*[n])] &\triangleq \sum_{n \in \mathbb{Z}} x^*[n] e^{-i\omega n} && \text{by definition of DTFT} && (\text{Definition 8.1 page 59}) \\ &= \left(\sum_{n \in \mathbb{Z}} x[n] e^{i\omega n} \right)^* && \text{by distributive property of *-algebras} && (\text{Definition F.3 page 148}) \\ &= \left(\sum_{n \in \mathbb{Z}} x[n] e^{-i(-\omega)n} \right)^* \\ &\triangleq \check{x}^*(-\omega) && \text{by left hypothesis} \end{aligned}$$

$$\begin{aligned} \check{\mathbf{F}}[(x^*[-n])] &\triangleq \sum_{n \in \mathbb{Z}} x^*[-n] e^{-i\omega n} && \text{by definition of DTFT} && (\text{Definition 8.1 page 59}) \\ &= \left(\sum_{n \in \mathbb{Z}} x[-n] e^{i\omega n} \right)^* && \text{by distributive property of *-algebras} && (\text{Definition F.3 page 148}) \\ &= \left(\sum_{m \in \mathbb{Z}} x[m] e^{-i\omega m} \right)^* && \text{where } m \triangleq -n \implies n = -m \\ &\triangleq \check{x}^*(\omega) && \text{by left hypothesis} \end{aligned}$$

⇒

Theorem 8.2. Let $\check{x}(\omega) \triangleq \check{\mathbf{F}}[(x[n])](\omega)$ be the DISCRETE-TIME FOURIER TRANSFORM (Definition 8.1 page 59) of a sequence $(x[n])_{n \in \mathbb{Z}}$ in $\ell^2_{\mathbb{R}}$.

T
H
M

$$\left\{ \begin{array}{l} (1). \quad \check{x}(\omega) \triangleq \check{\mathbf{F}}[(x[n])] \\ (2). \quad (x[n]) \text{ is REAL-VALUED} \end{array} \right\} \text{ and } \implies \left\{ \begin{array}{l} (1). \quad \check{\mathbf{F}}[(x[-n])] = \check{x}(-\omega) \quad \text{and} \\ (2). \quad \check{\mathbf{F}}[(x^*[n])] = \check{x}^*(-\omega) = \check{x}(\omega) \quad \text{and} \\ (3). \quad \check{\mathbf{F}}[(x^*[-n])] = \check{x}^*(\omega) = \check{x}(-\omega) \end{array} \right\}$$

PROOF:

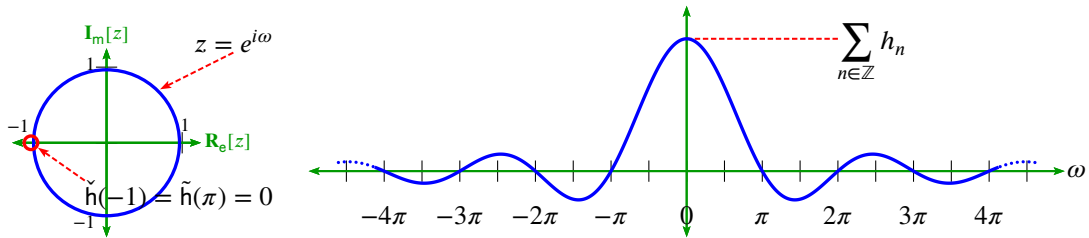
$$\begin{aligned} \check{\mathbf{F}}[(x[-n])] &\triangleq \sum_{n \in \mathbb{Z}} x[-n] e^{-i\omega n} && \text{by definition of DTFT} && (\text{Definition 8.1 page 59}) \\ &= \sum_{m \in \mathbb{Z}} x[m] e^{i\omega m} && \text{where } m \triangleq -n \implies n = -m \\ &= \sum_{m \in \mathbb{Z}} x[m] e^{-i(-\omega)m} \end{aligned}$$

$$\triangleq \tilde{x}(-\omega) \quad \text{by left hypothesis}$$

$$\begin{aligned} \tilde{x}^*(-\omega) &= \check{\mathbf{F}}(\mathbf{x}^*[n]) && \text{by Theorem 8.1 page 60} \\ &= \check{\mathbf{F}}(\mathbf{x}[n]) && \text{by } \textit{real-valued} \text{ hypothesis} \\ &= \tilde{x}(\omega) && \text{by definition of } \tilde{x}(\omega) \quad (\text{Definition 8.1 page 59}) \end{aligned}$$

$$\begin{aligned} \tilde{x}^*(\omega) &= \check{\mathbf{F}}(\mathbf{x}^*[-n]) && \text{by Theorem 8.1 page 60} \\ &= \check{\mathbf{F}}(\mathbf{x}[-n]) && \text{by } \textit{real-valued} \text{ hypothesis} \\ &= \tilde{x}(-\omega) && \text{by result (1)} \end{aligned}$$

⇒



Proposition 8.2. Let $\check{x}(z)$ be the Z-TRANSFORM (Definition 9.4 page 70) and $\check{x}(\omega)$ the DISCRETE-TIME FOURIER TRANSFORM (Definition 8.1 page 59) of (x_n) .

P R P	$\underbrace{\left\{ \sum_{n \in \mathbb{Z}} x_n = c \right\}}_{(1) \text{ time domain}}$	\iff	$\underbrace{\left\{ \check{x}(z) \Big _{z=1} = c \right\}}_{(2) \text{ } z \text{ domain}}$	\iff	$\underbrace{\left\{ \check{x}(\omega) \Big _{\omega=0} = c \right\}}_{(3) \text{ frequency domain}} \quad \forall (x_n)_{n \in \mathbb{Z}} \in \ell^2_{\mathbb{R}}, c \in \mathbb{R}$
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✎ PROOF:

1. Proof that (1) \implies (2):

$$\begin{aligned} \check{x}(z) \Big|_{z=1} &= \sum_{n \in \mathbb{Z}} x_n z^{-n} \Big|_{z=1} && \text{by definition of } \check{x}(z) \text{ (Definition 9.4 page 70)} \\ &= \sum_{n \in \mathbb{Z}} x_n && \text{because } z^n = 1 \text{ for all } n \in \mathbb{Z} \\ &= c && \text{by hypothesis (1)} \end{aligned}$$

2. Proof that (2) \implies (3):

$$\begin{aligned} \check{x}(\omega) \Big|_{\omega=0} &= \sum_{n \in \mathbb{Z}} x_n e^{-i\omega n} \Big|_{\omega=0} && \text{by definition of } \check{x}(\omega) \quad (\text{Definition 8.1 page 59}) \\ &= \sum_{n \in \mathbb{Z}} x_n z^{-n} \Big|_{z=1} \\ &= \check{x}(z) \Big|_{z=1} && \text{by definition of } \check{x}(z) \quad (\text{Definition 9.4 page 70}) \\ &= c && \text{by hypothesis (2)} \end{aligned}$$

3. Proof that (3) \implies (1):

$$\begin{aligned} \sum_{n \in \mathbb{Z}} x_n &= \sum_{n \in \mathbb{Z}} x_n e^{-i\omega n} \Big|_{\omega=0} \\ &= \check{x}(\omega) && \text{by definition of } \check{x}(\omega) && \text{(Definition 8.1 page 59)} \\ &= c && \text{by hypothesis (3)} \end{aligned}$$

\Rightarrow

Proposition 8.3. *If the coefficients are **real**, then the magnitude response (MR) is **symmetric**.*

\pencil PROOF:

$$\begin{aligned} |\tilde{h}(-\omega)| &\triangleq |\check{h}(z)|_{z=e^{-i\omega}} && \triangleq \left| \sum_{m \in \mathbb{Z}} x[m] z^{-m} \right|_{z=e^{-i\omega}} \\ &= \left| \sum_{m \in \mathbb{Z}} x[m] e^{i\omega m} \right| && = \left| \left(\sum_{m \in \mathbb{Z}} x^*[m] e^{-i\omega m} \right)^* \right| \\ &= \underbrace{\left| \left(\sum_{m \in \mathbb{Z}} x[m] e^{-i\omega m} \right)^* \right|}_{\text{if } x[m] \text{ is real}} && = \left| \sum_{m \in \mathbb{Z}} x[m] e^{-i\omega m} \right| \\ &\triangleq |\check{h}(z)|_{z=e^{-i\omega}} && \triangleq |\tilde{h}(\omega)| \end{aligned}$$

\Rightarrow

Proposition 8.4. ¹

P
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$$\underbrace{\sum_{n \in \mathbb{Z}} (-1)^n x_n = c}_{(1) \text{ in "time"}} \iff \underbrace{\check{x}(z)|_{z=-1} = c}_{(2) \text{ in "z domain"}} \iff \underbrace{\check{x}(\omega)|_{\omega=\pi} = c}_{(3) \text{ in "frequency"}}$$

$$\iff \underbrace{\left(\sum_{n \in \mathbb{Z}} h_{2n}, \sum_{n \in \mathbb{Z}} h_{2n+1} \right) = \left(\frac{1}{2} \left(\sum_{n \in \mathbb{Z}} h_n + c \right), \frac{1}{2} \left(\sum_{n \in \mathbb{Z}} h_n - c \right) \right)}_{(4) \text{ sum of even, sum of odd}}$$

$\forall c \in \mathbb{R}, (x_n)_{n \in \mathbb{Z}}, (y_n)_{n \in \mathbb{Z}} \in \ell^2_{\mathbb{R}}$

\pencil PROOF:

1. Proof that (1) \implies (2):

$$\begin{aligned} \check{x}(z)|_{z=-1} &= \sum_{n \in \mathbb{Z}} x_n z^{-n} \Big|_{z=-1} \\ &= \sum_{n \in \mathbb{Z}} (-1)^n x_n \\ &= c && \text{by (1)} \end{aligned}$$

¹ Chui (1992) page 123

2. Proof that (2) \implies (3):

$$\begin{aligned}
 \left. \sum_{n \in \mathbb{Z}} x_n e^{-i\omega n} \right|_{\omega=\pi} &= \sum_{n \in \mathbb{Z}} (-1)^n x_n \\
 &= \sum_{n \in \mathbb{Z}} (-1)^{-n} x_n &= \sum_{n \in \mathbb{Z}} z^{-n} x_n \Big|_{z=-1} \\
 &= c && \text{by (2)}
 \end{aligned}$$

3. Proof that (3) \implies (1):

$$\begin{aligned}
 \sum_{n \in \mathbb{Z}} (-1)^n x_n &= \sum_{n \in \mathbb{Z}} (-1)^{-n} x_n \\
 &= \sum_{n \in \mathbb{Z}} e^{-i\omega n} x_n \Big|_{\omega=\pi} \\
 &= c && \text{by (3)}
 \end{aligned}$$

4. Proof that (2) \implies (4):

(a) Define $A \triangleq \sum_{n \in \mathbb{Z}} h_{2n}$ $B \triangleq \sum_{n \in \mathbb{Z}} h_{2n+1}$.

(b) Proof that $A - B = c$:

$$\begin{aligned}
 c &= \sum_{n \in \mathbb{Z}} (-1)^n x_n && \text{by (2)} \\
 &= \underbrace{\sum_{n \in \mathbb{Z}_e} (-1)^n x_n}_{\text{even terms}} + \underbrace{\sum_{n \in \mathbb{Z}_o} (-1)^n x_n}_{\text{odd terms}} \\
 &= \sum_{n \in \mathbb{Z}} (-1)^{2n} x_{2n} + \sum_{n \in \mathbb{Z}} (-1)^{2n+1} x_{2n+1} \\
 &= \underbrace{\sum_{n \in \mathbb{Z}} x_{2n}}_A - \underbrace{\sum_{n \in \mathbb{Z}} x_{2n+1}}_B \\
 &\triangleq A - B && \text{by definitions of } A \text{ and } B
 \end{aligned}$$

(c) Proof that $A + B = \sum_{n \in \mathbb{Z}} x_n$:

$$\begin{aligned}
 \sum_{n \in \mathbb{Z}} x_n &= \sum_{n \text{ even}} x_n + \sum_{n \text{ odd}} x_n \\
 &= \underbrace{\sum_{n \in \mathbb{Z}} x_{2n}}_A + \underbrace{\sum_{n \in \mathbb{Z}} x_{2n+1}}_B \\
 &= A + B && \text{by definitions of } A \text{ and } B
 \end{aligned}$$

(d) This gives two simultaneous equations:

$$\begin{aligned}
 A - B &= c \\
 A + B &= \sum_{n \in \mathbb{Z}} x_n
 \end{aligned}$$

(e) Solutions to these equations give

$$\begin{aligned}\sum_{n \in \mathbb{Z}} x_{2n} &\triangleq A &= \frac{1}{2} \left(\sum_{n \in \mathbb{Z}} x_n + c \right) \\ \sum_{n \in \mathbb{Z}} x_{2n+1} &\triangleq B &= \frac{1}{2} \left(\sum_{n \in \mathbb{Z}} x_n - c \right)\end{aligned}$$

5. Proof that (2) \iff (4):

$$\begin{aligned}\sum_{n \in \mathbb{Z}} (-1)^n x_n &= \underbrace{\sum_{n \in \mathbb{Z}_e} (-1)^n x_n}_{\text{even terms}} + \underbrace{\sum_{n \in \mathbb{Z}_o} (-1)^n x_n}_{\text{odd terms}} \\ &= \sum_{n \in \mathbb{Z}} (-1)^{2n} x_{2n} + \sum_{n \in \mathbb{Z}} (-1)^{2n+1} x_{2n+1} \\ &= \sum_{n \in \mathbb{Z}} x_{2n} - \sum_{n \in \mathbb{Z}} x_{2n+1} \\ &= \frac{1}{2} \left(\sum_{n \in \mathbb{Z}} x_n + c \right) - \frac{1}{2} \left(\sum_{n \in \mathbb{Z}} x_n - c \right) && \text{by (3)} \\ &= c\end{aligned}$$



Lemma 8.1. Let $\tilde{f}(\omega)$ be the DTFT (Definition 8.1 page 59) of a sequence $(x_n)_{n \in \mathbb{Z}}$.

L E M	$\underbrace{(x_n \in \mathbb{R})_{n \in \mathbb{Z}}}_{\text{REAL-VALUED sequence}} \implies \underbrace{ \tilde{x}(\omega) ^2 = \tilde{x}(-\omega) ^2}_{\text{EVEN}} \quad \forall (x_n)_{n \in \mathbb{Z}} \in \ell^2_{\mathbb{R}}$
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PROOF:

$$\begin{aligned}|\tilde{x}(\omega)|^2 &= |\tilde{x}(z)|^2 \Big|_{z=e^{i\omega}} \\ &= \tilde{x}(z) \tilde{x}^*(z) \Big|_{z=e^{i\omega}} \\ &= \left[\sum_{n \in \mathbb{Z}} x_n z^{-n} \right] \left[\sum_{m \in \mathbb{Z}} x_m z^{-n} \right]^* \Big|_{z=e^{i\omega}} \\ &= \left[\sum_{n \in \mathbb{Z}} x_n z^{-n} \right] \left[\sum_{m \in \mathbb{Z}} x_m^* (z^*)^{-m} \right] \Big|_{z=e^{i\omega}} \\ &= \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} x_n x_m^* z^{-n} (z^*)^{-m} \Big|_{z=e^{i\omega}} \\ &= \sum_{n \in \mathbb{Z}} \left[|x_n|^2 + \sum_{m>n} x_n x_m^* z^{-n} (z^*)^{-m} + \sum_{m<n} x_n x_m^* z^{-n} (z^*)^{-m} \right] \Big|_{z=e^{i\omega}} \\ &= \sum_{n \in \mathbb{Z}} \left[|x_n|^2 + \sum_{m>n} x_n x_m e^{i\omega(m-n)} + \sum_{m<n} x_n x_m e^{i\omega(m-n)} \right] \\ &= \sum_{n \in \mathbb{Z}} \left[|x_n|^2 + \sum_{m>n} x_n x_m e^{i\omega(m-n)} + \sum_{m>n} x_n x_m e^{-i\omega(m-n)} \right] \\ &= \sum_{n \in \mathbb{Z}} \left[|x_n|^2 + \sum_{m>n} x_n x_m (e^{i\omega(m-n)} + e^{-i\omega(m-n)}) \right]\end{aligned}$$

$$\begin{aligned}
&= \sum_{n \in \mathbb{Z}} \left[|x_n|^2 + \sum_{m > n} x_n x_m 2 \cos[\omega(m-n)] \right] \\
&= \sum_{n \in \mathbb{Z}} |x_n|^2 + 2 \sum_{n \in \mathbb{Z}} \sum_{m > n} x_n x_m \cos[\omega(m-n)]
\end{aligned}$$

Since \cos is real and even, then $|\check{x}(\omega)|^2$ must also be real and even. \Rightarrow

Theorem 8.3 (inverse DTFT). ² Let $\check{x}(\omega)$ be the DISCRETE-TIME FOURIER TRANSFORM (Definition 8.1 page 59) of a sequence $(x_n)_{n \in \mathbb{Z}} \in \ell^2_{\mathbb{R}}$. Let \check{x}^{-1} be the inverse of \check{x} .

T H M	$ \left\{ \check{x}(\omega) \triangleq \sum_{n \in \mathbb{Z}} x_n e^{-i\omega n} \right\} \Rightarrow \left\{ x_n = \frac{1}{2\pi} \int_{\alpha-\pi}^{\alpha+\pi} \check{x}(\omega) e^{i\omega n} d\omega \quad \forall \alpha \in \mathbb{R} \right\} \quad \forall (x_n)_{n \in \mathbb{Z}} \in \ell^2_{\mathbb{R}} $ <div style="display: flex; justify-content: space-around; margin-top: 10px;"> <div style="text-align: center;"> $\check{x}(\omega) \triangleq \check{\mathbf{F}}(x_n)$ </div> <div style="text-align: center;"> $(x_n) = \check{\mathbf{F}}^{-1} \check{\mathbf{F}}(x_n)$ </div> </div>
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PROOF:

$$\begin{aligned}
\frac{1}{2\pi} \int_{\alpha-\pi}^{\alpha+\pi} \check{x}(\omega) e^{i\omega n} d\omega &= \frac{1}{2\pi} \int_{\alpha-\pi}^{\alpha+\pi} \underbrace{\left[\sum_{m \in \mathbb{Z}} x_m e^{-i\omega m} \right]}_{\check{x}(\omega)} e^{i\omega n} d\omega && \text{by definition of } \check{x}(\omega) \\
&= \frac{1}{2\pi} \int_{\alpha-\pi}^{\alpha+\pi} \sum_{m \in \mathbb{Z}} x_m e^{-i\omega(m-n)} d\omega \\
&= \frac{1}{2\pi} \sum_{m \in \mathbb{Z}} x_m \int_{\alpha-\pi}^{\alpha+\pi} e^{-i\omega(m-n)} d\omega \\
&= \frac{1}{2\pi} \sum_{m \in \mathbb{Z}} x_m [2\pi \delta_{m-n}] \\
&= x_n
\end{aligned}$$

\Rightarrow

Theorem 8.4 (orthonormal quadrature conditions). ³ Let $\check{x}(\omega)$ be the DISCRETE-TIME FOURIER TRANSFORM (Definition 8.1 page 59) of a sequence $(x_n)_{n \in \mathbb{Z}} \in \ell^2_{\mathbb{R}}$. Let $\bar{\delta}_n$ be the KRONECKER DELTA FUNCTION at n (Definition H.12 page 194).

T H M	$ \begin{aligned} \sum_{m \in \mathbb{Z}} x_m y_{m-2n}^* &= 0 \iff \check{x}(\omega) \check{y}^*(\omega) + \check{x}(\omega + \pi) \check{y}^*(\omega + \pi) = 0 && \forall n \in \mathbb{Z}, \forall (x_n), (y_n) \in \ell^2_{\mathbb{R}} \\ \sum_{m \in \mathbb{Z}} x_m x_{m-2n}^* &= \bar{\delta}_n \iff \check{x}(\omega) ^2 + \check{x}(\omega + \pi) ^2 = 2 && \forall n \in \mathbb{Z}, \forall (x_n), (y_n) \in \ell^2_{\mathbb{R}} \end{aligned} $
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PROOF: Let $z \triangleq e^{i\omega}$.

² J.S.Chitode (2009) page 3-95 (3.6.2)

³ Daubechies (1992) pages 132–137 (5.1.20), (5.1.39)

1. Proof that $2 \sum_{n \in \mathbb{Z}} \left[\sum_{k \in \mathbb{Z}} x_k y_{k-2n}^* \right] e^{-i2\omega n} = \check{x}(\omega) \check{y}^*(\omega) + \check{x}(\omega + \pi) \check{y}^*(\omega + \pi)$:

$$\begin{aligned}
 & 2 \sum_{n \in \mathbb{Z}} \left[\sum_{k \in \mathbb{Z}} x_k y_{k-2n}^* \right] e^{-i2\omega n} \\
 &= 2 \sum_{k \in \mathbb{Z}} x_k \sum_{n \in \mathbb{Z}} y_{k-2n}^* z^{-2n} \\
 &= 2 \sum_{k \in \mathbb{Z}} x_k \sum_{n \text{ even}} y_{k-n}^* z^{-n} \\
 &= \sum_{k \in \mathbb{Z}} x_k \sum_{n \in \mathbb{Z}} y_{k-n}^* z^{-n} (1 + e^{i\pi n}) \\
 &= \sum_{k \in \mathbb{Z}} x_k \sum_{n \in \mathbb{Z}} y_{k-n}^* z^{-n} + \sum_{k \in \mathbb{Z}} x_k \sum_{n \in \mathbb{Z}} y_{k-n}^* z^{-n} e^{i\pi n} \\
 &= \sum_{k \in \mathbb{Z}} x_k \sum_{m \in \mathbb{Z}} y_m^* z^{-(k-m)} + \sum_{k \in \mathbb{Z}} x_k \sum_{m \in \mathbb{Z}} y_m^* e^{-i(\omega+\pi)(k-m)} \quad \text{where } m \triangleq k - n \\
 &= \sum_{k \in \mathbb{Z}} x_k z^{-k} \sum_{m \in \mathbb{Z}} y_m^* z^m + \sum_{k \in \mathbb{Z}} x_k e^{-i(\omega+\pi)k} \sum_{m \in \mathbb{Z}} y_m^* e^{+i(\omega+\pi)m} \\
 &= \sum_{k \in \mathbb{Z}} x_k e^{-i\omega k} \left[\sum_{m \in \mathbb{Z}} y_m^* e^{-i\omega m} \right]^* + \sum_{k \in \mathbb{Z}} x_k e^{-i(\omega+\pi)k} \left[\sum_{m \in \mathbb{Z}} y_m^* e^{-i(\omega+\pi)m} \right]^* \\
 &\triangleq \check{x}(\omega) \check{y}^*(\omega) + \check{x}(\omega + \pi) \check{y}^*(\omega + \pi)
 \end{aligned}$$

2. Proof that $\sum_{m \in \mathbb{Z}} x_m y_{m-2n}^* = 0 \implies \check{x}(\omega) \check{y}^*(\omega) + \check{x}(\omega + \pi) \check{y}^*(\omega + \pi) = 0$:

$$\begin{aligned}
 0 &= 2 \sum_{n \in \mathbb{Z}} \left[\sum_{k \in \mathbb{Z}} x_k y_{k-2n}^* \right] e^{-i2\omega n} && \text{by left hypothesis} \\
 &= \check{x}(\omega) \check{y}^*(\omega) + \check{x}(\omega + \pi) \check{y}^*(\omega + \pi) && \text{by item (1)}
 \end{aligned}$$

3. Proof that $\sum_{m \in \mathbb{Z}} x_m y_{m-2n}^* = 0 \iff \check{x}(\omega) \check{y}^*(\omega) + \check{x}(\omega + \pi) \check{y}^*(\omega + \pi) = 0$:

$$\begin{aligned}
 2 \sum_{n \in \mathbb{Z}} \left[\sum_{k \in \mathbb{Z}} x_k y_{k-2n}^* \right] e^{-i2\omega n} &= \check{x}(\omega) \check{y}^*(\omega) + \check{x}(\omega + \pi) \check{y}^*(\omega + \pi) && \text{by item (1)} \\
 &= 0 && \text{by right hypothesis}
 \end{aligned}$$

Thus by the above equation, $\sum_{n \in \mathbb{Z}} \left[\sum_{k \in \mathbb{Z}} x_k y_{k-2n}^* \right] e^{-i2\omega n} = 0$. The only way for this to be true is if $\sum_{k \in \mathbb{Z}} x_k y_{k-2n}^* = 0$.

4. Proof that $\sum_{m \in \mathbb{Z}} x_m x_{m-2n}^* = \bar{\delta}_n \implies |\check{x}(\omega)|^2 + |\check{x}(\omega' + \pi)|^2 = 2$:
Let $g_n \triangleq x_n$.

$$\begin{aligned}
 2 &= 2 \sum_{n \in \mathbb{Z}} \bar{\delta}_n e^{-i2\omega n} \\
 &= 2 \sum_{n \in \mathbb{Z}} \left[\sum_{k \in \mathbb{Z}} x_k y_{k-2n}^* \right] e^{-i2\omega n} && \text{by left hypothesis} \\
 &= \check{x}(\omega) \check{y}^*(\omega) + \check{x}(\omega + \pi) \check{y}^*(\omega + \pi) && \text{by item (1)}
 \end{aligned}$$

5. Proof that $\sum_{m \in \mathbb{Z}} x_m x_{m-2n}^* = \bar{\delta}_n \iff |\check{x}(\omega)|^2 + |\check{x}(\omega' + \pi)|^2 = 2$:
Let $g_n \triangleq x_n$.

$$\begin{aligned}
 2 \sum_{n \in \mathbb{Z}} \left[\sum_{k \in \mathbb{Z}} x_k y_{k-2n}^* \right] e^{-i2\omega n} &= \check{x}(\omega) \check{y}^*(\omega) + \check{x}(\omega + \pi) \check{y}^*(\omega + \pi) && \text{by item (1)} \\
 &= 2 && \text{by right hypothesis}
 \end{aligned}$$

Thus by the above equation, $\sum_{n \in \mathbb{Z}} \left[\sum_{k \in \mathbb{Z}} x_k y_{k-2n}^* \right] e^{-i2\omega n} = 1$. The only way for this to be true is if $\sum_{k \in \mathbb{Z}} x_k y_{k-2n}^* = \bar{\delta}_n$.

⇒

8.3 Derivatives

Theorem 8.5.⁴ Let $\check{x}(\omega)$ be the DTFT (Definition 8.1 page 59) of a sequence $(x_n)_{n \in \mathbb{Z}}$.

T H M	(A)	$\left[\frac{d}{d\omega} \right]^n \check{x}(\omega) \Big _{\omega=0} = 0$	\iff	$\sum_{k \in \mathbb{Z}} k^n x_k = 0$	(B)	$\forall n \in \mathbb{W}$
	(C)	$\left[\frac{d}{d\omega} \right]^n \check{x}(\omega) \Big _{\omega=\pi} = 0$	\iff	$\sum_{k \in \mathbb{Z}} (-1)^k k^n x_k = 0$	(D)	$\forall n \in \mathbb{W}$



✎ PROOF:

1. Proof that (A) \implies (B):

$$\begin{aligned}
 0 &= \left[\frac{d}{d\omega} \right]^n \check{x}(\omega) \Big|_{\omega=0} && \text{by hypothesis (A)} \\
 &= \left[\frac{d}{d\omega} \right]^n \sum_{k \in \mathbb{Z}} x_k e^{-i\omega k} \Big|_{\omega=0} && \text{by definition of } \check{x}(\omega) \text{ (Definition 8.1 page 59)} \\
 &= \sum_{k \in \mathbb{Z}} x_k \left[\frac{d}{d\omega} \right]^n e^{-i\omega k} \Big|_{\omega=0} \\
 &= \sum_{k \in \mathbb{Z}} x_k [(-i)^n k^n e^{-i\omega k}] \Big|_{\omega=0} \\
 &= (-i)^n \sum_{k \in \mathbb{Z}} k^n x_k
 \end{aligned}$$

2. Proof that (A) \longleftarrow (B):

$$\begin{aligned}
 \left[\frac{d}{d\omega} \right]^n \check{x}(\omega) \Big|_{\omega=0} &= \left[\frac{d}{d\omega} \right]^n \sum_{k \in \mathbb{Z}} x_k e^{-i\omega k} \Big|_{\omega=0} && \text{by definition of } \check{x} \\
 &= \sum_{k \in \mathbb{Z}} x_k \left[\left[\frac{d}{d\omega} \right]^n e^{-i\omega k} \right] \Big|_{\omega=0} \\
 &= \sum_{k \in \mathbb{Z}} x_k [(-i)^n k^n e^{-i\omega k}] \Big|_{\omega=0} \\
 &= (-i)^n \sum_{k \in \mathbb{Z}} k^n x_k \\
 &= 0 && \text{by hypothesis (B)}
 \end{aligned}$$

⁴  Vidakovic (1999) pages 82–83,  Mallat (1999) pages 241–242

3. Proof that (C) \implies (D):

$$\begin{aligned}
 0 &= \left[\frac{d}{d\omega} \right]^n \check{x}(\omega) \Big|_{\omega=\pi} && \text{by hypothesis (C)} \\
 &= \left[\frac{d}{d\omega} \right]^n \sum_{k \in \mathbb{Z}} x_k e^{-i\omega k} \Big|_{\omega=\pi} && \text{by definition of } \check{x} \text{ (Definition 8.1 page 59)} \\
 &= \sum_{k \in \mathbb{Z}} x_k \left[\frac{d}{d\omega} \right]^n e^{-i\omega k} \Big|_{\omega=\pi} \\
 &= \sum_{k \in \mathbb{Z}} x_k [(-i)^n k^n e^{-i\omega k}] \Big|_{\omega=\pi} \\
 &= \sum_{k \in \mathbb{Z}} x_k [(-i)^n k^n (-1)^k] \\
 &= (-i)^n \sum_{k \in \mathbb{Z}} (-1)^k k^n x_k
 \end{aligned}$$

4. Proof that (C) \Longleftarrow (D):

$$\begin{aligned}
 \left[\frac{d}{d\omega} \right]^n \check{x}(\omega) \Big|_{\omega=\pi} &= \left[\frac{d}{d\omega} \right]^n \sum_{k \in \mathbb{Z}} x_k e^{-i\omega k} \Big|_{\omega=\pi} && \text{by definition of } \check{x} \text{ (Definition 8.1 page 59)} \\
 &= \sum_{k \in \mathbb{Z}} x_k \left[\frac{d}{d\omega} \right]^n e^{-i\omega k} \Big|_{\omega=\pi} \\
 &= \sum_{k \in \mathbb{Z}} x_k [(-i)^n k^n e^{-i\omega k}] \Big|_{\omega=\pi} \\
 &= \sum_{k \in \mathbb{Z}} x_k [(-i)^n k^n (-1)^k] \\
 &= (-i)^n \sum_{k \in \mathbb{Z}} (-1)^k k^n x_k \\
 &= 0 && \text{by hypothesis (D)}
 \end{aligned}$$



CHAPTER 9

Z TRANSFORM

9.1 Convolution operator

Definition 9.1.¹ Let X^Y be the set of all functions from a set Y to a set X . Let \mathbb{Z} be the set of integers.

DEF A function f in X^Y is a **sequence** over X if $Y = \mathbb{Z}$.
A sequence may be denoted in the form $(x_n)_{n \in \mathbb{Z}}$ or simply as (x_n) .

Definition 9.2.² Let $(\mathbb{F}, +, \cdot, 0, 1)$ be a FIELD (Definition A.5 page 98).

DEF The **space of all absolutely square summable sequences** $\ell_{\mathbb{F}}^2$ over \mathbb{F} is defined as

$$\ell_{\mathbb{F}}^2 \triangleq \left\{ (x_n)_{n \in \mathbb{Z}} \mid \sum_{n \in \mathbb{Z}} |x_n|^2 < \infty \right\}$$

The space $\ell_{\mathbb{R}}^2$ is an example of a *separable Hilbert space*. In fact, $\ell_{\mathbb{R}}^2$ is the *only* separable Hilbert space in the sense that all separable Hilbert spaces are isomorphically equivalent. For example, $\ell_{\mathbb{R}}^2$ is isomorphic to $L_{\mathbb{R}}^2$, the *space of all absolutely square Lebesgue integrable functions*.

Definition 9.3.

DEF The **convolution operation** \star is defined as

$$(x_n) \star (y_n) \triangleq \left(\sum_{m \in \mathbb{Z}} x_m y_{n-m} \right)_{n \in \mathbb{Z}} \quad \forall (x_n)_{n \in \mathbb{Z}}, (y_n)_{n \in \mathbb{Z}} \in \ell_{\mathbb{R}}^2$$

Proposition 9.1. Let \star be the CONVOLUTION OPERATOR (Definition 9.3 page 69).

PRP $(x_n) \star (y_n) = (y_n) \star (x_n) \quad \forall (x_n)_{n \in \mathbb{Z}}, (y_n)_{n \in \mathbb{Z}} \in \ell_{\mathbb{R}}^2 \quad (\star \text{ is COMMUTATIVE})$

¹ Bromwich (1908) page 1, Thomson et al. (2008) page 23 (Definition 2.1), Joshi (1997) page 31

² Kubrusly (2011) page 347 (Example 5.K)

PROOF:

$$\begin{aligned}
 [x \star y](n) &\triangleq \sum_{m \in \mathbb{Z}} x_m y_{n-m} && \text{by Definition 9.3 page 69} \\
 &= \sum_{k \in \mathbb{Z}} x_{n-k} y(k) && \text{where } k \triangleq n - m \implies m = n - k \\
 &= \sum_{k \in \mathbb{Z}} x_{n-k} y(k) && \text{by commutativity of addition} \\
 &= \sum_{m \in \mathbb{Z}} x_{n-m} y_m && \text{by change of variables} \\
 &= \sum_{m \in \mathbb{Z}} y_m x_{n-m} && \text{by commutative property of the field over } \mathbb{C} \\
 &\triangleq (y \star x)_n && \text{by Definition 9.3 page 69}
 \end{aligned}$$

⇒

Proposition 9.2. Let \star be the CONVOLUTION OPERATOR (Definition 9.3 page 69). Let $\ell_{\mathbb{R}}^2$ be the set of ABSOLUTELY SUMMABLE sequences (Definition 9.2 page 69).

$$\left\{ \begin{array}{l} (A). \quad x(n) \in \ell_{\mathbb{R}}^2 \text{ and} \\ (B). \quad y(n) \in \ell_{\mathbb{R}}^2 \end{array} \right\} \implies \left\{ \sum_{k \in \mathbb{Z}} x[k]y[n+k] = x[-n] \star y(n) \right\}$$

PROOF:

$$\begin{aligned}
 \sum_{k \in \mathbb{Z}} x[k]y[n+k] &= \sum_{-p \in \mathbb{Z}} x[-p]y[n-p] && \text{where } p \triangleq -k \implies k = -p \\
 &= \sum_{p \in \mathbb{Z}} x[-p]y[n-p] && \text{by absolutely summable hypothesis (Definition 9.2 page 69)} \\
 &= \sum_{p \in \mathbb{Z}} x'[p]y[n-p] && \text{where } x'[n] \triangleq x[-n] \implies x[-n] = x'[n] \\
 &\triangleq x'[n] \star y[n] && \text{by definition of convolution } \star \text{ (Definition 9.3 page 69)} \\
 &\triangleq x[-n] \star y[n] && \text{by definition of } x'[n]
 \end{aligned}$$

⇒

9.2 Z-transform

Definition 9.4.³

The **z-transform** \mathbf{Z} of $(x_n)_{n \in \mathbb{Z}}$ is defined as

$$\underbrace{[\mathbf{Z}(x_n)](z) \triangleq \sum_{n \in \mathbb{Z}} x_n z^{-n}}_{\text{Laurent series}} \quad \forall (x_n) \in \ell_{\mathbb{R}}^2$$

Theorem 9.1. Let $X(z) \triangleq \mathbf{Z}x[n]$ be the Z-TRANSFORM of $x[n]$.

$$\left\{ \check{x}(z) \triangleq \mathbf{Z}(x[n]) \right\} \implies \left\{ \begin{array}{l} (1). \quad \mathbf{Z}(\alpha x[n]) = \alpha \check{x}(z) \quad \forall (x_n) \in \ell_{\mathbb{R}}^2 \text{ and} \\ (2). \quad \mathbf{Z}(x[n-k]) = z^{-k} \check{x}(z) \quad \forall (x_n) \in \ell_{\mathbb{R}}^2 \text{ and} \\ (3). \quad \mathbf{Z}(x[-n]) = \check{x}\left(\frac{1}{z}\right) \quad \forall (x_n) \in \ell_{\mathbb{R}}^2 \text{ and} \\ (4). \quad \mathbf{Z}(x^*[n]) = \check{x}^*\left(\frac{1}{z^*}\right) \quad \forall (x_n) \in \ell_{\mathbb{R}}^2 \text{ and} \\ (5). \quad \mathbf{Z}(x^*[-n]) = \check{x}^*\left(\frac{1}{z^*}\right) \quad \forall (x_n) \in \ell_{\mathbb{R}}^2 \end{array} \right\}$$

³Laurent series:  Abramovich and Aliprantis (2002) page 49

PROOF:

$$\begin{aligned}
 \alpha \mathbb{Z} \check{x}(z) &\triangleq \alpha \mathbf{Z} (x[n]) && \text{by definition of } \check{x}(z) \\
 &\triangleq \alpha \sum_{n \in \mathbb{Z}} x[n] z^{-n} && \text{by definition of } \mathbf{Z} \text{ operator} \\
 &\triangleq \sum_{n \in \mathbb{Z}} (\alpha x[n]) z^{-n} && \text{by } \textit{distributive} \text{ property} \\
 &\triangleq \mathbf{Z} (\alpha x[n]) && \text{by definition of } \mathbf{Z} \text{ operator} \\
 z^{-k} \check{x}(z) &= z^{-k} \mathbf{Z} (x[n]) && \text{by definition of } \check{x}(z) \quad (\text{left hypothesis}) \\
 &\triangleq z^{-k} \sum_{n=-\infty}^{n=+\infty} x[n] z^{-n} && \text{by definition of } \mathbf{Z} \quad (\text{Definition 9.4 page 70}) \\
 &= \sum_{n=-\infty}^{n=+\infty} x[n] z^{-n-k} \\
 &= \sum_{m-k=-\infty}^{m-k=+\infty} x[m-k] z^{-m} && \text{where } m \triangleq n+k \quad \implies n = m-k \\
 &= \sum_{m=-\infty}^{m=+\infty} x[m-k] z^{-m} \\
 &= \sum_{n=-\infty}^{n=+\infty} x[n-k] z^{-n} && \text{where } n \triangleq m \\
 &\triangleq \mathbf{Z} (x[n-k]) && \text{by definition of } \mathbf{Z} \quad (\text{Definition 9.4 page 70}) \\
 \mathbf{Z} (x^*[n]) &\triangleq \sum_{n \in \mathbb{Z}} x^*[n] z^{-n} && \text{by definition of } \mathbf{Z} \quad (\text{Definition 9.4 page 70}) \\
 &\triangleq \left(\sum_{n \in \mathbb{Z}} x[n] (z^*)^{-n} \right)^* && \text{by definition of } \mathbf{Z} \quad (\text{Definition 9.4 page 70}) \\
 &\triangleq \check{x}^*(z^*) && \text{by definition of } \mathbf{Z} \quad (\text{Definition 9.4 page 70}) \\
 \mathbf{Z} (x[-n]) &\triangleq \sum_{n \in \mathbb{Z}} x[-n] z^{-n} && \text{by definition of } \mathbf{Z} \quad (\text{Definition 9.4 page 70}) \\
 &= \sum_{-m \in \mathbb{Z}} x[m] z^m && \text{where } m \triangleq -n \quad \implies n = -m \\
 &= \sum_{m \in \mathbb{Z}} x[m] z^m && \text{by } \textit{absolutely summable} \text{ property} \quad (\text{Definition 9.2 page 69}) \\
 &= \sum_{m \in \mathbb{Z}} x[m] \left(\frac{1}{z} \right)^{-m} && \text{by } \textit{absolutely summable} \text{ property} \quad (\text{Definition 9.2 page 69}) \\
 &\triangleq \check{x} \left(\frac{1}{z} \right) && \text{by definition of } \mathbf{Z} \quad (\text{Definition 9.4 page 70}) \\
 \mathbf{Z} (x^*[-n]) &\triangleq \sum_{n \in \mathbb{Z}} x^*[-n] z^{-n} && \text{by definition of } \mathbf{Z} \quad (\text{Definition 9.4 page 70}) \\
 &= \sum_{-m \in \mathbb{Z}} x^*[m] z^m && \text{where } m \triangleq -n \quad \implies n = -m \\
 &= \sum_{m \in \mathbb{Z}} x^*[m] z^m && \text{by } \textit{absolutely summable} \text{ property} \quad (\text{Definition 9.2 page 69}) \\
 &= \sum_{m \in \mathbb{Z}} x^*[m] \left(\frac{1}{z} \right)^{-m} && \text{by } \textit{absolutely summable} \text{ property} \quad (\text{Definition 9.2 page 69}) \\
 &= \left(\sum_{m \in \mathbb{Z}} x[m] \left(\frac{1}{z^*} \right)^{-m} \right)^* && \text{by } \textit{absolutely summable} \text{ property} \quad (\text{Definition 9.2 page 69})
 \end{aligned}$$

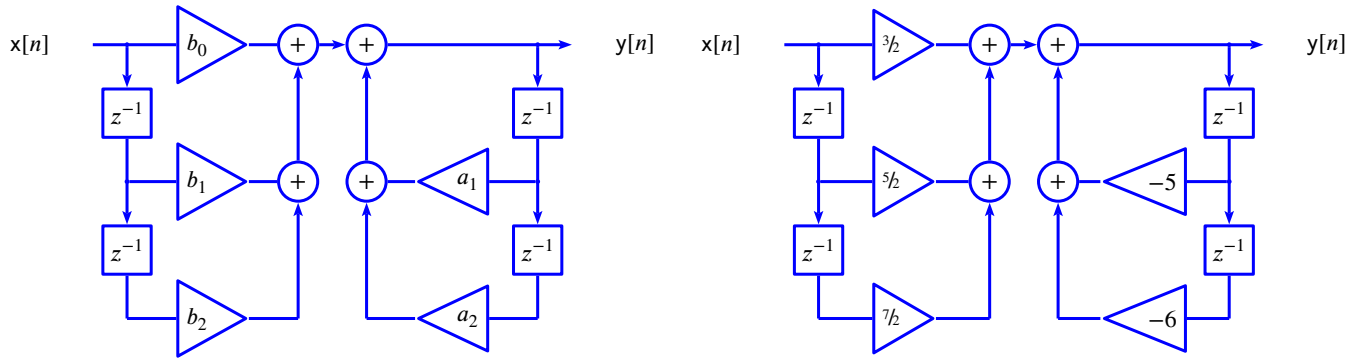


Figure 9.1: Direct form 1 order 2 IIR filters

$$\triangleq \check{x}^* \left(\frac{1}{z^*} \right)$$

by definition of \mathbf{Z}

(Definition 9.4 page 70)

⇒

Theorem 9.2 (convolution theorem). *Let \star be the convolution operator (Definition 9.3 page 69).*

T H M	$\underbrace{\mathbf{Z} \left((x_n) \star (y_n) \right)}_{\text{sequence convolution}} = \underbrace{\left(\mathbf{Z} (x_n) \right) \left(\mathbf{Z} (y_n) \right)}_{\text{series multiplication}} \quad \forall (x_n)_{n \in \mathbb{Z}}, (y_n)_{n \in \mathbb{Z}} \in \mathcal{C}_{\mathbb{R}}^2$
----------------------	--

✎ PROOF:

$$\begin{aligned}
 [\mathbf{Z}(x \star y)](z) &\triangleq \mathbf{Z} \left(\sum_{m \in \mathbb{Z}} x_m y_{n-m} \right) && \text{by definition of } \star && \text{(Definition 9.3 page 69)} \\
 &\triangleq \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} x_m y_{n-m} z^{-n} && \text{by definition of } \mathbf{Z} && \text{(Definition 9.4 page 70)} \\
 &= \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} x_m y_{n-m} z^{-n} && = \sum_{m \in \mathbb{Z}} \sum_{n \in \mathbb{Z}} x_m y_{n-m} z^{-n} \\
 &= \sum_{m \in \mathbb{Z}} \sum_{k \in \mathbb{Z}} x_m y_k z^{-(m+k)} && \text{where } k \triangleq n - m && \iff n = m + k \\
 &= \left[\sum_{m \in \mathbb{Z}} x_m z^{-m} \right] \left[\sum_{k \in \mathbb{Z}} y_k z^{-k} \right] \\
 &\triangleq [\mathbf{Z}(x_n)] [\mathbf{Z}(y_n)] && \text{by definition of } \mathbf{Z} && \text{(Definition 9.4 page 70)}
 \end{aligned}$$

⇒

9.3 From z-domain back to time-domain

$$\check{y}(z) = b_0 X(z) + b_1 z^{-1} X(z) + b_2 z^{-2} X(z) - a_1 z^{-1} Y(z) + a_2 z^{-2} Y(z)$$

$$y[n] = b_0 x[n] + b_1 x[n-1] + b_2 x[n-2] - a_1 y[n-1] - a_2 y[n-2]$$

Example 9.1. See Figure 9.1 (page 72)

$$\frac{3z^2 + 5z + 7}{2z^2 + 10z + 12} = \frac{3z^2 + 5z + 7}{2(z^2 + 5z + 6)} = \frac{(3/2 z^2 + 5/2 z + 7/2)}{z^2 + 5z + 6} = \frac{(3/2 + 5/2 z^{-1} + 7/2 z^{-2})}{1 + 5z^{-1} + 6z^{-2}}$$

9.4 Zero locations

The system property of *minimum phase* is defined in Definition 9.5 (next) and illustrated in Figure 9.2 (page 73).

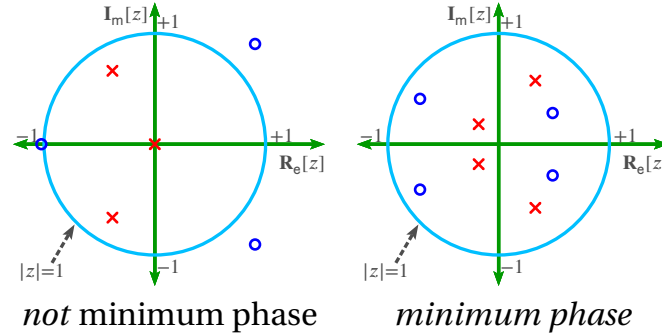


Figure 9.2: Minimum Phase filter

Definition 9.5. ⁴ Let $\check{x}(z) \triangleq \mathbf{Z}(x_n)$ be the Z TRANSFORM (Definition 9.4 page 70) of a sequence $(x_n)_{n \in \mathbb{Z}}$ in $\ell^2_{\mathbb{R}}$. Let $(z_n)_{n \in \mathbb{Z}}$ be the ZEROS of $\check{x}(z)$.

DEF

The sequence (x_n) is **minimum phase** if

$$|z_n| < 1 \quad \forall n \in \mathbb{Z}$$

$\check{x}(z)$ has all its ZEROS inside the unit circle

The impulse response of a minimum phase filter has most of its energy concentrated near the beginning of its support, as demonstrated next.

Theorem 9.3 (Robinson's Energy Delay Theorem). ⁵ Let $p(z) \triangleq \sum_{n=0}^N a_n z^{-n}$ and $q(z) \triangleq \sum_{n=0}^N b_n z^{-n}$ be polynomials.

THM

$$\left\{ \begin{array}{l} p \text{ is MINIMUM PHASE} \\ q \text{ is NOT minimum phase} \end{array} \right. \text{ and } \left. \right\} \Rightarrow \underbrace{\sum_{n=0}^{m-1} |a_n|^2}_{\substack{\text{"energy" of} \\ \text{the first } m \text{ co-} \\ \text{efficients of} \\ p(z)}} \geq \underbrace{\sum_{n=0}^{m-1} |b_n|^2}_{\substack{\text{"energy" of} \\ \text{the first } m \text{ co-} \\ \text{efficients of} \\ q(z)}} \quad \forall 0 \leq m \leq N$$

But for more *symmetry*, put some zeros inside and some outside the unit circle (Figure 9.3 page 74).

Example 9.2. An example of a minimum phase polynomial is the Daubechies-4 scaling function. The minimum phase polynomial causes most of the energy to be concentrated near the origin, making it very *asymmetric*. In contrast, the Symlet-4 has a design very similar to that of Daubechies-4, but the selected zeros are not all within the unit circle in the complex z plane. This results in a scaling function that is more symmetric and less contrated near the origin. Both scaling functions are illustrated in Figure 9.3 (page 74).

⁴ Farina and Rinaldi (2000) page 91, Dumitrescu (2007) page 36

⁵ Dumitrescu (2007) page 36, Robinson (1962), Robinson (1966) <??>, Claerbout (1976) pages 52–53

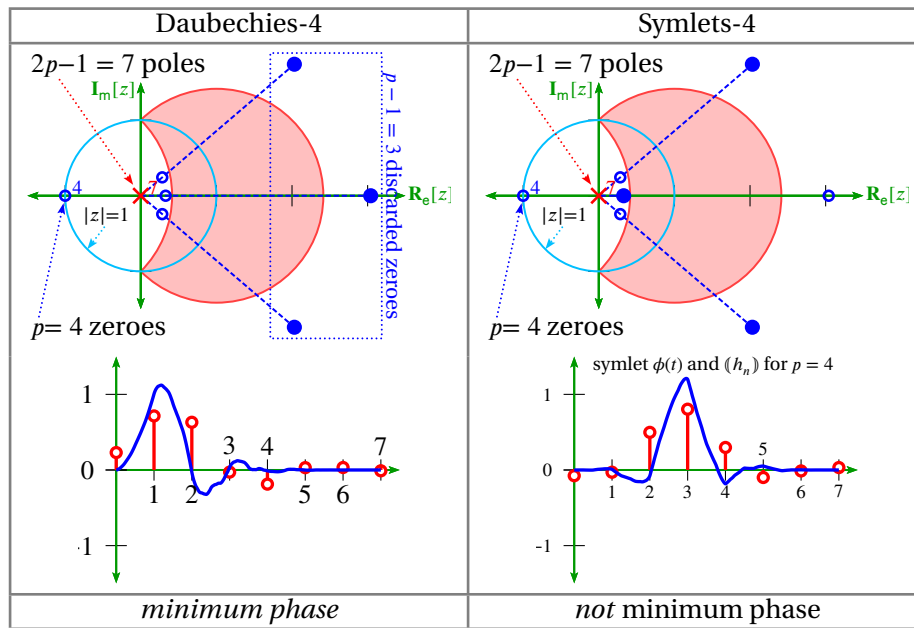


Figure 9.3: Daubechies-4 and Symlet-4 scaling functions pole-zero plots

9.5 Pole locations

Definition 9.6.

DEF

A filter (or system or operator) \mathbf{H} is **causal** if its current output does not depend on future inputs.

Definition 9.7.

DEF

A filter (or system or operator) \mathbf{H} is **time-invariant** if the mapping it performs does not change with time.

Definition 9.8.

DEF

An operation \mathbf{H} is **linear** if any output y_n can be described as a linear combination of inputs x_n as in

$$y_n = \sum_{m \in \mathbb{Z}} h(m)x(n-m).$$

For a filter to be *stable*, place all the poles *inside* the unit circle.

Theorem 9.4. A causal LTI filter is **stable** if all of its poles are **inside** the unit circle.

Example 9.3. Stable/unstable filters are illustrated in Figure 9.4 (page 75).

True or False? This filter has no poles:

$$H(z) = b_0 + b_1 z^{-1} + b_2 z^{-2}$$

$$H(z) = b_0 + b_1 z^{-1} + b_2 z^{-2} = \frac{z^2}{z^2} \times \frac{b_0 + b_1 z^{-1} + b_2 z^{-2}}{1} = \frac{b_0 z^2 + b_1 z^1 + b_2}{z^2}$$

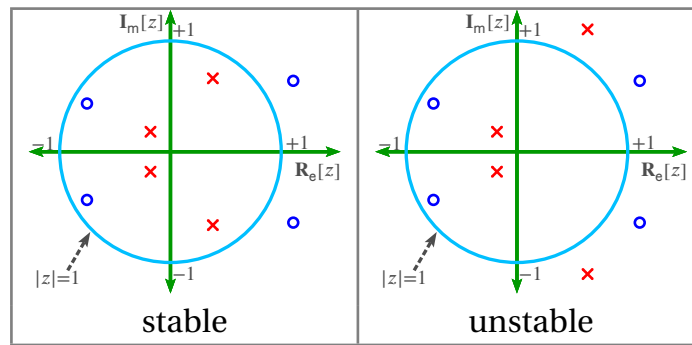


Figure 9.4: Pole-zero plot stable/unstable causal LTI filters (Example 9.3 page 74)

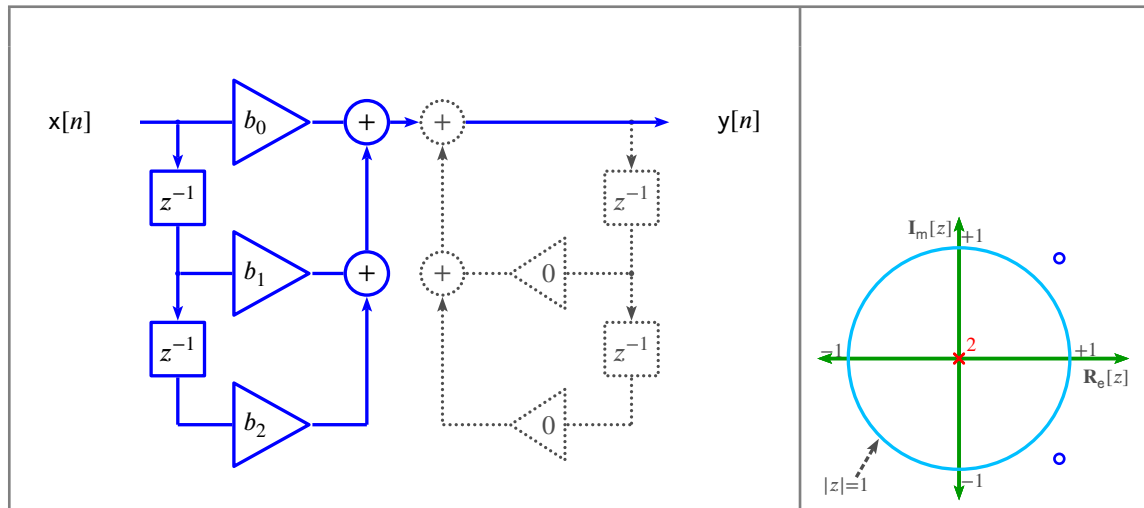


Figure 9.5: FIR filters

9.6 Mirroring for real coefficients

If you want real coefficients, choose poles and zeros in conjugate pairs (next).

Proposition 9.3.

$$\left\{ \begin{array}{l} \text{ZEROS and POLES} \\ \text{occur in CONJUGATE PAIRS} \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} \text{COEFFICIENTS} \\ \text{are REAL.} \end{array} \right\}$$

PROOF:

$$\begin{aligned} (z - p_1)(z - p_1^*) &= [z - (a + ib)][z - (a - ib)] \\ &= z^2 + [-a + ib - ib - a]z - [ib]^2 \end{aligned}$$

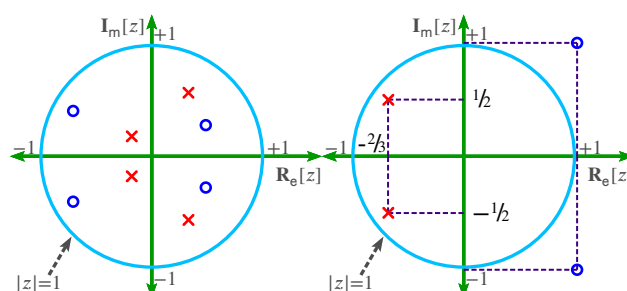


Figure 9.6: Conjugate pair structure yielding real coefficients

$$= z^2 - 2az + b^2$$



Example 9.4. See Figure 9.6 (page 75).

$$\begin{aligned} H(z) &= G \frac{[z - z_1][z - z_2]}{[z - p_1][z - p_2]} = G \frac{[z - (1+i)][z - (1-i)]}{[z - (-\frac{2}{3} + i\frac{1}{2})][z - (-\frac{2}{3} - i\frac{1}{2})]} \\ &= G \frac{z^2 - z[(1-i) + (1+i)] + (1-i)(1+i)}{z^2 - z[(-\frac{2}{3} + i\frac{1}{2}) + (-\frac{2}{3} - i\frac{1}{2})] + (-\frac{2}{3} + i\frac{1}{2})(-\frac{2}{3} - i\frac{1}{2})} \\ &= G \frac{z^2 - 2z + 2}{z^2 - \frac{4}{3}z + (\frac{4}{9} + \frac{1}{4})} = G \frac{z^2 - 2z + 2}{z^2 - \frac{4}{3}z + \frac{19}{12}} \end{aligned}$$

9.7 Rational polynomial operators

A digital filter is simply an operator on $\ell_{\mathbb{R}}^2$. If the digital filter is a causal LTI system, then it can be expressed as a rational polynomial in z as shown next.

Lemma 9.1. *A causal LTI operator \mathbf{H} can be expressed as a rational expression $\check{h}(z)$.*

$$\begin{aligned} \check{h}(z) &= \frac{b_0 + b_1 z^{-1} + b_2 z^{-2} + \cdots + b_N z^{-N}}{1 + a_1 z^{-1} + a_2 z^{-2} + \cdots + a_N z^{-N}} \\ &= \frac{\sum_{n=0}^N b_n z^{-n}}{1 + \sum_{n=1}^N a_n z^{-n}} \end{aligned}$$

A filter operation $\check{h}(z)$ can be expressed as a product of its roots (poles and zeros).

$$\begin{aligned} \check{h}(z) &= \frac{b_0 + b_1 z^{-1} + b_2 z^{-2} + \cdots + b_N z^{-N}}{1 + a_1 z^{-1} + a_2 z^{-2} + \cdots + a_N z^{-N}} \\ &= \alpha \frac{(z - z_1)(z - z_2) \cdots (z - z_N)}{(z - p_1)(z - p_2) \cdots (z - p_N)} \end{aligned}$$

where α is a constant, z_i are the zeros, and p_i are the poles. The poles and zeros of such a rational expression are often plotted in the z -plane with a unit circle about the origin (representing $z = e^{i\omega}$). Poles are marked with \times and zeros with \circ . An example is shown in Figure 9.7 page 77. Notice that in this figure the zeros and poles are either real or occur in complex conjugate pairs.

9.8 Filter Banks

Conjugate quadrature filters (next definition) are used in *filter banks*. If $\check{x}(z)$ is a *low-pass filter*, then the conjugate quadrature filter of $\check{y}(z)$ is a *high-pass filter*.



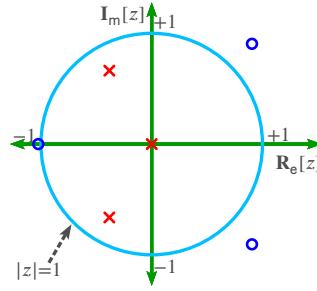


Figure 9.7: Pole-zero plot for rational expression with real coefficients

Definition 9.9. ⁶ Let $(x_n)_{n \in \mathbb{Z}}$ and $(y_n)_{n \in \mathbb{Z}}$ be SEQUENCES (Definition 9.1 page 69) in $\ell^2_{\mathbb{R}}$ (Definition 9.2 page 69).

The sequence (y_n) is a **conjugate quadrature filter** with shift N with respect to (x_n) if

$$y_n = \pm(-1)^n x_{N-n}^*$$

A CONJUGATE QUADRATURE FILTER is also called a **CQF** or a **Smith-Barnwell filter**.

Any triple $((x_n), (y_n), N)$ in this form is said to satisfy the

conjugate quadrature filter condition or the **CQF condition**.

Theorem 9.5 (CQF theorem). ⁷ Let $\check{y}(\omega)$ and $\check{x}(\omega)$ be the DTFTs (Definition 8.1 page 59) of the sequences $(y_n)_{n \in \mathbb{Z}}$ and $(x_n)_{n \in \mathbb{Z}}$, respectively, in $\ell^2_{\mathbb{R}}$ (Definition 9.2 page 69).

$$\begin{aligned}
 \underbrace{y_n = \pm(-1)^n x_{N-n}^*}_{(1) \text{ CQF in "time"}} &\iff \check{y}(z) = \pm(-1)^N z^{-N} \check{x}^*\left(\frac{-1}{z^*}\right) & (2) \text{ CQF in "z-domain"} \\
 &\iff \check{y}(\omega) = \pm(-1)^N e^{-i\omega N} \check{x}^*(\omega + \pi) & (3) \text{ CQF in "frequency"} \\
 &\iff x_n = \pm(-1)^N (-1)^n y_{N-n}^* & (4) \text{ "reversed" CQF in "time"} \\
 &\iff \check{x}(z) = \pm z^{-N} \check{y}^*\left(\frac{-1}{z^*}\right) & (5) \text{ "reversed" CQF in "z-domain"} \\
 &\iff \check{x}(\omega) = \pm e^{-i\omega N} \check{y}^*(\omega + \pi) & (6) \text{ "reversed" CQF in "frequency"}
 \end{aligned}$$

$\forall N \in \mathbb{Z}$

PROOF:

1. Proof that (1) \implies (2):

$$\begin{aligned}
 \check{y}(z) &= \sum_{n \in \mathbb{Z}} y_n z^{-n} && \text{by definition of } z\text{-transform} \quad (\text{Definition 9.4 page 70}) \\
 &= \sum_{n \in \mathbb{Z}} \underbrace{(\pm)(-1)^n x_{N-n}^*}_{\text{CQF}} z^{-n} && \text{by (1)} \\
 &= \pm \sum_{m \in \mathbb{Z}} (-1)^{N-m} x_m^* z^{-(N-m)} && \text{where } m \triangleq N - n \implies n = N - m \\
 &= \pm(-1)^N z^{-N} \sum_{m \in \mathbb{Z}} (-1)^{-m} x_m^* (z^{-1})^{-m} \\
 &= \pm(-1)^N z^{-N} \sum_{m \in \mathbb{Z}} x_m^* \left(-\frac{1}{z}\right)^{-m} \\
 &= \pm(-1)^N z^{-N} \left[\sum_{m \in \mathbb{Z}} x_m \left(-\frac{1}{z^*}\right)^{-m} \right]^*
 \end{aligned}$$

⁶ Strang and Nguyen (1996) page 109, Haddad and Akansu (1992) pages 256–259 (section 4.5), Vaidyanathan (1993) page 342 ((7.2.7), (7.2.8)), Smith and Barnwell (1984a), Smith and Barnwell (1984b), Mintzer (1985)

⁷ Strang and Nguyen (1996) page 109, Mallat (1999) pages 236–238 ((7.58), (7.73)), Haddad and Akansu (1992) pages 256–259 (section 4.5), Vaidyanathan (1993) page 342 ((7.2.7), (7.2.8))

$$= \pm(-1)^N z^{-N} \check{x}^* \left(\frac{-1}{z^*} \right)$$

by definition of z -transform (Definition 9.4 page 70)

2. Proof that (1) \Leftarrow (2):

$$\check{y}(z) = \pm(-1)^N z^{-N} \check{x}^* \left(\frac{-1}{z^*} \right)$$

by (2)

$$= \pm(-1)^N z^{-N} \left[\sum_{m \in \mathbb{Z}} x_m \left(\frac{-1}{z^*} \right)^{-m} \right]^*$$

by definition of z -transform (Definition 9.4 page 70)

$$= \pm(-1)^N z^{-N} \left[\sum_{m \in \mathbb{Z}} x_m^* (-z^{-1})^{-m} \right]$$

by definition of z -transform (Definition 9.4 page 70)

$$= \sum_{m \in \mathbb{Z}} (\pm)(-1)^{N-m} x_m^* z^{-(N-m)}$$

$$= \sum_{m \in \mathbb{Z}} (\pm)(-1)^n x_{N-n}^* z^{-n}$$

where $n = N - m \Rightarrow$

$$m \triangleq N - n$$

$$\Rightarrow x_n = \pm(-1)^n x_{N-n}^*$$

3. Proof that (1) \Rightarrow (3):

$$\check{y}(\omega) \triangleq \check{x}(z) \Big|_{z=e^{i\omega}}$$

by definition of $DTFT$ (Definition 8.1 page 59)

$$= \left[\pm(-1)^N z^{-N} \check{x} \left(\frac{-1}{z^*} \right) \right]_{z=e^{i\omega}}$$

by (2)

$$= \pm(-1)^N e^{-i\omega N} \check{x}(e^{i\pi} e^{i\omega})$$

$$= \pm(-1)^N e^{-i\omega N} \check{x}(e^{i(\omega+\pi)})$$

$$= \pm(-1)^N e^{-i\omega N} \check{x}(\omega + \pi)$$

by definition of $DTFT$ (Definition 8.1 page 59)

4. Proof that (1) \Rightarrow (6):

$$\check{x}(\omega) = \sum_{n \in \mathbb{Z}} y_n e^{-i\omega n}$$

by definition of $DTFT$ (Definition 8.1 page 59)

$$= \sum_{n \in \mathbb{Z}} \underbrace{\pm(-1)^n x_{N-n}^*}_{CQF} e^{-i\omega n}$$

by (1)

$$= \sum_{m \in \mathbb{Z}} \pm(-1)^{N-m} x_m^* e^{-i\omega(N-m)}$$

where $m \triangleq N - n \Rightarrow$

$$n = N - m$$

$$= \pm(-1)^N e^{-i\omega N} \sum_{m \in \mathbb{Z}} (-1)^m x_m^* e^{i\omega m}$$

$$= \pm(-1)^N e^{-i\omega N} \sum_{m \in \mathbb{Z}} e^{i\pi m} x_m^* e^{i\omega m}$$

$$= \pm(-1)^N e^{-i\omega N} \sum_{m \in \mathbb{Z}} x_m^* e^{i(\omega+\pi)m}$$

$$= \pm(-1)^N e^{-i\omega N} \left[\sum_{m \in \mathbb{Z}} x_m e^{-i(\omega+\pi)m} \right]^*$$

$$= \pm(-1)^N e^{-i\omega N} \check{x}^*(\omega + \pi)$$

by definition of $DTFT$ (Definition 8.1 page 59)

5. Proof that (1) \Leftarrow (3):

$$\begin{aligned}
 y_n &= \frac{1}{2\pi} \int_{-\pi}^{+\pi} \check{y}(\omega) e^{i\omega n} d\omega && \text{by inverse DTFT} && (\text{Theorem 8.3 page 65}) \\
 &= \frac{1}{2\pi} \int_{-\pi}^{+\pi} \underbrace{\pm (-1)^N e^{-iN\omega} \check{x}^*(\omega + \pi)}_{\text{right hypothesis}} e^{i\omega n} d\omega && \text{by right hypothesis} \\
 &= \pm (-1)^N \frac{1}{2\pi} \int_{-\pi}^{+\pi} \check{x}^*(\omega + \pi) e^{i\omega(n-N)} d\omega && \text{by right hypothesis} \\
 &= \pm (-1)^N \frac{1}{2\pi} \int_0^{2\pi} \check{x}^*(v) e^{i(v-\pi)(n-N)} dv && \text{where } v \triangleq \omega + \pi \implies \omega = v - \pi \\
 &= \pm (-1)^N e^{-i\pi(n-N)} \frac{1}{2\pi} \int_0^{2\pi} \check{x}^*(v) e^{iv(n-N)} dv \\
 &= \pm (-1)^N \underbrace{(-1)^N}_{e^{i\pi N}} \underbrace{(-1)^n}_{e^{-i\pi n}} \left[\frac{1}{2\pi} \int_0^{2\pi} \check{x}(v) e^{iv(N-n)} dv \right]^* \\
 &= \pm (-1)^n x_{N-n}^* && \text{by inverse DTFT} && (\text{Theorem 8.3 page 65})
 \end{aligned}$$

6. Proof that (1) \Leftrightarrow (4):

$$\begin{aligned}
 y_n = \pm (-1)^n x_{N-n}^* &\Leftrightarrow (\pm)(-1)^n y_n = (\pm)(\pm)(-1)^n (-1)^n x_{N-n}^* \\
 &\Leftrightarrow \pm (-1)^n y_n = x_{N-n}^* \\
 &\Leftrightarrow (\pm(-1)^n y_n)^* = (x_{N-n}^*)^* \\
 &\Leftrightarrow \pm (-1)^n y_n^* = x_{N-n} \\
 &\Leftrightarrow x_{N-n} = \pm (-1)^n y_n^* \\
 &\Leftrightarrow x_m = \pm (-1)^{N-m} y_{N-m}^* && \text{where } m \triangleq N - n \implies n = N - m \\
 &\Leftrightarrow x_m = \pm (-1)^{N-m} y_{N-m}^* \\
 &\Leftrightarrow x_m = \pm (-1)^N (-1)^m y_{N-m}^* \\
 &\Leftrightarrow x_n = \pm (-1)^N (-1)^n y_{N-n}^* && \text{by change of free variables}
 \end{aligned}$$

7. Proofs for (5) and (6): not included. See proofs for (2) and (3).



Theorem 9.6. ⁸ Let $\check{y}(\omega)$ and $\check{x}(\omega)$ be the DTFTs (Definition 8.1 page 59) of the sequences $(y_n)_{n \in \mathbb{Z}}$ and $(x_n)_{n \in \mathbb{Z}}$, respectively, in $\ell_{\mathbb{R}}^2$ (Definition 9.2 page 69).

T H M	Let $y_n = \pm (-1)^n x_{N-n}^*$ (CQF CONDITION, Definition 9.9 page 77). Then			
	{	(A) $\left[\frac{d}{d\omega} \right]^n \check{y}(\omega) \Big _{\omega=0} = 0$	\Leftrightarrow	$\left[\frac{d}{d\omega} \right]^n \check{x}(\omega) \Big _{\omega=\pi} = 0$ (B)
			\Leftrightarrow	$\sum_{k \in \mathbb{Z}} (-1)^k k^n x_k = 0$ (C)
			\Leftrightarrow	$\sum_{k \in \mathbb{Z}} k^n y_k = 0$ (D)
				$\forall n \in \mathbb{W}$

PROOF:

⁸ Vidakovic (1999) pages 82–83, Mallat (1999) pages 241–242

1. Proof that (A) \implies (B):

$$\begin{aligned}
 0 &= \left[\frac{d}{d\omega} \right]^n \check{y}(\omega) \Big|_{\omega=0} && \text{by (A)} \\
 &= \left[\frac{d}{d\omega} \right]^n (\pm)(-1)^N e^{-i\omega N} \check{x}^*(\omega + \pi) \Big|_{\omega=0} && \text{by CQF theorem (Theorem 9.5 page 77)} \\
 &= (\pm)(-1)^N \sum_{\ell=0}^n \binom{n}{\ell} \left[\frac{d}{d\omega} \right]^\ell [e^{-i\omega N}] \cdot \left[\frac{d}{d\omega} \right]^{n-\ell} [\check{x}^*(\omega + \pi)] \Big|_{\omega=0} && \text{by Leibnitz GPR (Lemma B.2 page 101)} \\
 &= (\pm)(-1)^N \sum_{\ell=0}^n \binom{n}{\ell} (-iN)^\ell e^{-i\omega N} \left[\frac{d}{d\omega} \right]^{n-\ell} [\check{x}^*(\omega + \pi)] \Big|_{\omega=0} \\
 &= (\pm)(-1)^N e^{-i0N} \sum_{\ell=0}^n \binom{n}{\ell} (-iN)^\ell \left[\frac{d}{d\omega} \right]^{n-\ell} [\check{x}^*(\omega + \pi)] \Big|_{\omega=0} \\
 &\implies \check{x}^{(0)}(\pi) = 0 \\
 &\implies \check{x}^{(1)}(\pi) = 0 \\
 &\implies \check{x}^{(2)}(\pi) = 0 \\
 &\implies \check{x}^{(3)}(\pi) = 0 \\
 &\implies \check{x}^{(4)}(\pi) = 0 \\
 &\quad \vdots \\
 &\implies \check{x}^{(n)}(\pi) = 0 \quad \text{for } n = 0, 1, 2, \dots
 \end{aligned}$$

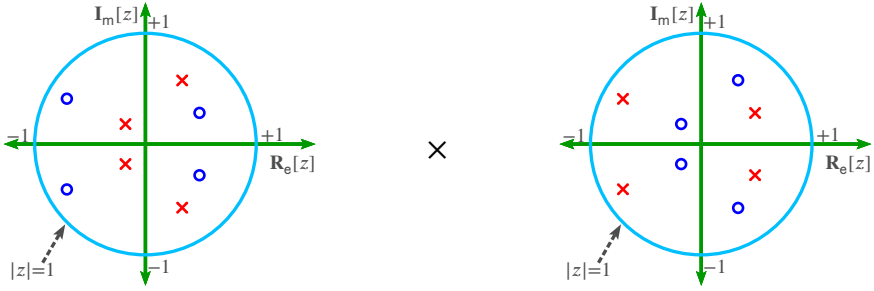
2. Proof that (A) \Leftarrow (B):

$$\begin{aligned}
 0 &= \left[\frac{d}{d\omega} \right]^n \check{x}(\omega) \Big|_{\omega=\pi} && \text{by (B)} \\
 &= \left[\frac{d}{d\omega} \right]^n (\pm)e^{-i\omega N} \check{y}^*(\omega + \pi) \Big|_{\omega=\pi} && \text{by CQF theorem (Theorem 9.5 page 77)} \\
 &= (\pm) \sum_{\ell=0}^n \binom{n}{\ell} \left[\frac{d}{d\omega} \right]^\ell [e^{-i\omega N}] \cdot \left[\frac{d}{d\omega} \right]^{n-\ell} [\check{y}^*(\omega + \pi)] \Big|_{\omega=\pi} && \text{by Leibnitz GPR (Lemma B.2 page 101)} \\
 &= (\pm) \sum_{\ell=0}^n \binom{n}{\ell} (-iN)^\ell e^{-i\omega N} \left[\frac{d}{d\omega} \right]^{n-\ell} [\check{y}^*(\omega + \pi)] \Big|_{\omega=\pi} \\
 &= (\pm)e^{-i\pi N} \sum_{\ell=0}^n \binom{n}{\ell} (-iN)^\ell \left[\frac{d}{d\omega} \right]^{n-\ell} [\check{y}^*(\omega + \pi)] \Big|_{\omega=\pi} \\
 &= (\pm)(-1)^N \sum_{\ell=0}^n \binom{n}{\ell} (-iN)^\ell \left[\frac{d}{d\omega} \right]^{n-\ell} [\check{y}^*(\omega + \pi)] \Big|_{\omega=\pi} \\
 &\implies \check{y}^{(0)}(0) = 0 \\
 &\implies \check{y}^{(1)}(0) = 0 \\
 &\implies \check{y}^{(2)}(0) = 0 \\
 &\implies \check{y}^{(3)}(0) = 0 \\
 &\implies \check{y}^{(4)}(0) = 0 \\
 &\quad \vdots \\
 &\implies \check{y}^{(n)}(0) = 0 \\
 &\implies \check{y}^{(n)}(0) = 0 \quad \text{for } n = 0, 1, 2, \dots
 \end{aligned}$$

3. Proof that (B) \iff (C): by Theorem 8.5 page 67

4. Proof that (A) \iff (D): by Theorem 8.5 page 67

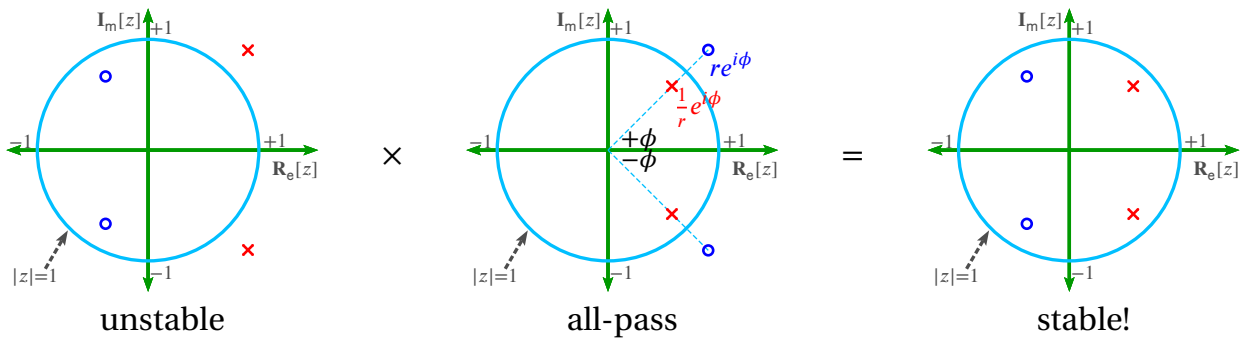
5. Proof that (CQF) \nLeftarrow (A): Here is a counterexample: $\check{y}(\omega) = 0$.



$$\frac{(z - z_1)(z - z_2)(z - z_3)(z - z_4)}{(z - p_1)(z - p_2)(z - p_3)(z - p_4)} \times \frac{(z - p_1)(z - p_2)(z - p_3)(z - p_4)}{(z - z_1)(z - z_2)(z - z_3)(z - z_4)} = 1$$

9.9 Inverting non-minimum phase filters

Minimum phase filters are easy to invert: each zero becomes a pole and each pole becomes a zero.



$$\begin{aligned}
 |A(z)|_{z=e^{i\omega}} &= \frac{1}{r} \left| \frac{z - re^{i\phi}}{z - \frac{1}{r}e^{i\phi}} \right|_{z=e^{i\omega}} = \left| \frac{z - re^{i\phi}}{rz - e^{i\phi}} \right|_{z=e^{i\omega}} \\
 &= \left| e^{i\phi} \left(\frac{e^{-i\phi}z - r}{rz - e^{i\phi}} \right) \right|_{z=e^{i\omega}} = \left| z \left(\frac{e^{-i\phi} - rz^{-1}}{rz - e^{i\phi}} \right) \right|_{z=e^{i\omega}} \\
 &= \left| -z \left(\frac{rz^{-1} - e^{-i\phi}}{rz - e^{i\phi}} \right) \right|_{z=e^{i\omega}} = \left| e^{i\pi} e^{i\omega} \left(\frac{re^{-i\omega} - e^{-i\phi}}{re^{i\omega} - e^{i\phi}} \right) \right| \\
 &= \left| \frac{1}{e^{-i\omega}} \left(\frac{re^{-i\omega} - e^{-i\phi}}{(re^{i\omega} - e^{i\phi})^*} \right) \right| = \left| \frac{re^{-i\omega} - e^{-i\phi}}{re^{-i\omega} - e^{-i\phi}} \right| = 1
 \end{aligned}$$

Part IV

Discrete to Discrete Transforms

CHAPTER 10

FAST WAVELET TRANSFORM (FWT)

The Fast Wavelet Transform can be computed using simple discrete filter operations (as a conjugate mirror filter).

Definition 10.1 (Wavelet Transform). *Let the wavelet transform $\mathbf{W} : \{f : \mathbb{R} \rightarrow \mathbb{C}\} \rightarrow \{w : \mathbb{Z}^2 \rightarrow \mathbb{C}\}$ be defined as¹*

DEF


$$[\mathbf{W}f](j, n) \triangleq \langle f(x) | \psi_{j,n}(x) \rangle$$


Definition 10.2. *The following relations are defined as described below:*

DEF

scaling coefficients	$v_j : \mathbb{Z} \rightarrow \mathbb{C}$	such that	$v_j(n) \triangleq \langle f(x) \phi_{j,n}(x) \rangle$
wavelet coefficients	$w_j : \mathbb{Z} \rightarrow \mathbb{C}$	such that	$w_j(n) \triangleq \langle f(x) \psi_{j,n}(x) \rangle$
scaling filter coefficients	$\bar{h} : \mathbb{Z} \rightarrow \mathbb{C}$	such that	$\bar{h}(n) \triangleq h(-n)$
wavelet filter coefficients	$\bar{g} : \mathbb{Z} \rightarrow \mathbb{C}$	such that	$\bar{g}(n) \triangleq g(-n)$






The scaling and wavelet filter coefficients at scale j are equal to the filtered and downsampled (Theorem ?? page ??) scaling filter coefficients at scale $j + 1$.²

 The convolution (Definition 9.3 page 69) of $v_{j+1}(n)$ with $\bar{h}(n)$ and then downsampling by 2 produces $v_j(n)$.

 The convolution of $v_{j+1}(n)$ with $\bar{g}(n)$ and then downsampling by 2 produces $w_j(n)$.

This is formally stated and proved in the next theorem.

¹Notice that this definition is similar to the definition of transforms of other analysis systems:

 Laplace Transform	$\mathcal{L}f(s) \triangleq \langle f(x) e^{sx} \rangle$	$\triangleq \int_{-\infty}^{\infty} f(x) e^{-sx} dx$
 Continuous Fourier Transform	$\mathcal{F}f(\omega) \triangleq \langle f(x) e^{i\omega x} \rangle$	$\triangleq \int_{-\infty}^{\infty} f(x) e^{-i\omega x} dx$
 Fourier Series Transform	$\mathcal{F}_s f(k) \triangleq \langle f(x) e^{i\frac{2\pi}{T} kx} \rangle$	$\triangleq \int_{-\infty}^{\infty} f(x) e^{-i\frac{2\pi}{T} kx} dx$
 Z-Transform	$\mathcal{Z}f(z) \triangleq \langle f(x) z^n \rangle$	$\triangleq \sum_n f(x) z^{-n}$
 Discrete Fourier Transform	$\mathcal{F}_d f(k) \triangleq \langle f(n) e^{i\frac{2\pi}{N} kn} \rangle$	$\triangleq \sum_n f(x) e^{-i\frac{2\pi}{N} kn}$

²  Mallat (1999) page 257,  Burrus et al. (1998) page 35

Theorem 10.1.

T H M	$v_j(n) = [\bar{h} \star v_{j+1}](2n)$
	$w_j(n) = [\bar{g} \star v_{j+1}](2n)$

PROOF:

$$\begin{aligned}
 v_j(n) &= \langle f(x) | \phi_{j,n}(x) \rangle \\
 &= \langle f(x) | \sqrt{2^j} \phi(2^j x - n) \rangle \\
 &= \left\langle f(x) | \sqrt{2^j} \sqrt{2} \sum_m h(m) \phi(2(2^j x - n) - m) \right\rangle \\
 &= \left\langle f(x) | \sum_m h(m) \sqrt{2^{j+1}} \phi(2^{j+1} x - 2n - m) \right\rangle \\
 &= \sum_m h(m) \langle f(x) | \sqrt{2^{j+1}} \phi(2^{j+1} x - 2n - m) \rangle \\
 &= \sum_m h(m) \langle f(x) | \phi_{j+1,2n+m}(x) \rangle \\
 &= \sum_m h(m) v_{j+1}(2n + m) \\
 &= \sum_p h(p - 2n) v_{j+1}(p) \\
 &= \sum_p \bar{h}(2n - p) v_{j+1}(p) \\
 &= [\bar{h} \star v_{j+1}](2n)
 \end{aligned}$$

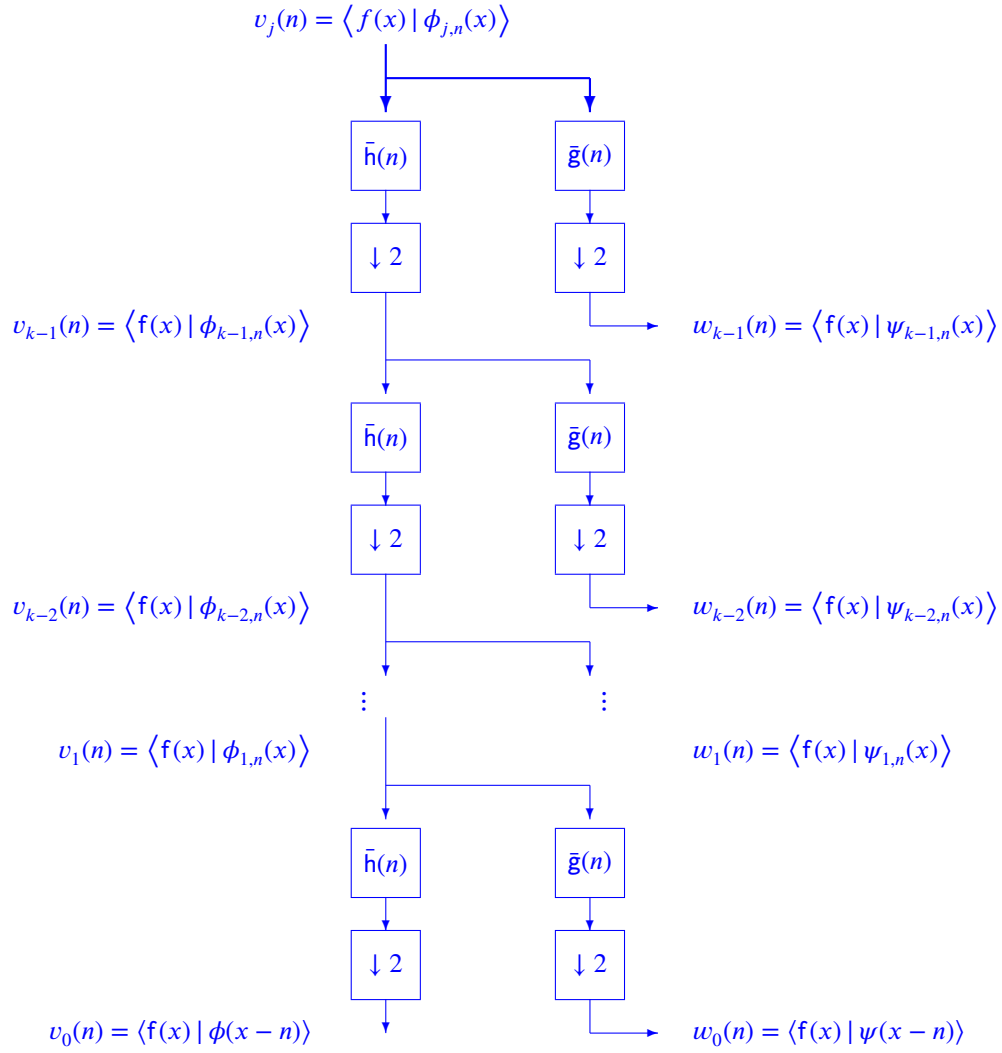
$$\text{let } p = 2n + m \iff m = p - 2n$$

$$\begin{aligned}
 w_j(n) &= \langle f(x) | \psi_{j,n}(x) \rangle \\
 &= \langle f(x) | \sqrt{2^j} \psi(2^j x - n) \rangle \\
 &= \left\langle f(x) | \sqrt{2^j} \sqrt{2} \sum_m g(m) \phi(2(2^j x - n) - m) \right\rangle \\
 &= \left\langle f(x) | \sum_m g(m) \sqrt{2^{j+1}} \phi(2^{j+1} x - 2n - m) \right\rangle \\
 &= \sum_m g(m) \langle f(x) | \sqrt{2^{j+1}} \phi(2^{j+1} x - 2n - m) \rangle \\
 &= \sum_m g(m) \langle f(x) | \phi_{j+1,2n+m}(x) \rangle \\
 &= \sum_m g(m) v_{j+1}(2n + m) \\
 &= \sum_p g(p - 2n) v_{j+1}(p) \\
 &= \sum_p \bar{g}(2n - p) v_{j+1}(p) \\
 &= [\bar{g} \star v_{j+1}](2n)
 \end{aligned}$$

$$\text{let } p = 2n + m \iff m = p - 2n$$

⇒

These filtering and downsampling operations are equivalent to the operations performed by a filter bank. Therefore, a filter bank can be used to implement a *Fast Wavelet Transform (FWT)*, as illustrated in Figure 10.1 (page 87).

Figure 10.1: k -Stage Fast Wavelet Transform

CHAPTER 11

KL EXPANSION—DISCRETE CASE

11.1 Definitions

Definition 11.1. Let $x(n)$ and $y(n)$ be RANDOM PROCESSES. Let $R_{xx}(n, m)$ be the AUTO-CORRELATION (Definition L.2 page 237) of $x(n)$.

DEF The **auto-correlation operator** \mathbf{R}_x of $y(n)$ is defined as

$$\mathbf{R}_x y(n) \triangleq \sum_{m \in \mathbb{Z}} R_{xx}(m, n) y(m)$$

Definition 11.2. Let $x(n)$ and $y(n)$ be RANDOM PROCESSES. Let $R_{xx}(n, m)$ be the AUTO-CORRELATION of $x(n)$.

DEF A RANDOM PROCESS $x(n)$ is **white** if

$$R_{xx}(m) = K \delta(m) \quad \text{for some } K > 0.$$

11.2 Properties

Theorem 11.1. Let \mathbf{R}_x be an AUTO-CORRELATION operator.

THM $\left\{ \langle x | y \rangle \triangleq \sum_{n \in \mathbb{Z}} x(n) y^*(n) \right\} \implies \left\{ \begin{array}{l} (1). \langle \mathbf{R}_x x | x \rangle \geq 0 \quad (\text{NON-NEGATIVE}) \quad \text{and} \\ (2). \langle \mathbf{R}_x x | y \rangle = \langle x | \mathbf{R}_x y \rangle \quad (\text{SELF-ADJOINT}) \end{array} \right\}$

 PROOF:

1. Proof that \mathbf{R}_x is non-negative:

$$\begin{aligned} \langle \mathbf{R}_x y | y \rangle &= \left\langle \sum_{m \in \mathbb{Z}} R_{xx}(n, m) y(m) \mid y(n) \right\rangle && \text{by definition of } \mathbf{R}_x && (\text{Definition 11.1 page 89}) \\ &= \left\langle \sum_{m \in \mathbb{Z}} E[x(n) x^*(m)] y(m) \mid y(n) \right\rangle && \text{by definition of } R_{xx}(n, m) && (\text{Definition K.2 page 235}) \\ &= E \left[\left\langle \sum_{m \in \mathbb{Z}} x(n) x^*(m) y(m) \mid y(n) \right\rangle \right] && \text{by linearity of } \langle \triangle \mid \nabla \rangle \text{ and } \sum \end{aligned}$$

$$\begin{aligned}
&= \mathbb{E} \left[\sum_{m \in \mathbb{Z}} x^*(m) y(m) \langle x(n) | y(n) \rangle \right] && \text{by additivity property of } \langle \Delta | \nabla \rangle \\
&= \mathbb{E} [\langle y(m) | x(m) \rangle \langle x(n) | y(n) \rangle] && \text{by local definition of } \langle \Delta | \nabla \rangle \\
&= \mathbb{E} [\langle x(m) | y(m) \rangle^* \langle x(n) | y(n) \rangle] && \text{by conjugate symmetry prop.} \\
&= \mathbb{E} |\langle x(n) | y(n) \rangle|^2 && \text{by definition of } |\cdot| \quad (\text{Definition A.4 page 98}) \\
&\geq 0 && \text{by strictly positive property of norms}
\end{aligned}$$

2. Proof that \mathbf{R}_x is *self-adjoint*:

$$\begin{aligned}
\langle [\mathbf{R}_x x](n) | y \rangle &= \left\langle \sum_{m \in \mathbb{Z}} R_{xx}(n, m) x(m) | y(n) \right\rangle && \text{by definition of } \mathbf{R}_x \quad (\text{Definition 11.1 page 89}) \\
&= \sum_{m \in \mathbb{Z}} x(m) \langle R_{xx}(n, m) | y(n) \rangle && \text{by additive property of } \langle \Delta | \nabla \rangle \\
&= \sum_{m \in \mathbb{Z}} x(m) \langle y(n) | R_{xx}(n, m) \rangle^* && \text{by conjugate symmetry prop.} \\
&= \langle x(m) | \langle y(n) | R_{xx}(n, m) \rangle \rangle && \text{by local definition of } \langle \Delta | \nabla \rangle \\
&= \left\langle x(m) | \sum_{n \in \mathbb{Z}} y(n) R_{xx}^*(n, m) \right\rangle \\
&= \left\langle x(m) | \sum_{n \in \mathbb{Z}} y(n) R_{xx}(m, n) \right\rangle && \text{by property of } R_{xx} \quad (\text{Theorem K.1 page 236}) \\
&= \left\langle x(m) | \underbrace{\mathbf{R}_x y}_{\mathbf{R}_x^* y} \right\rangle && \text{by definition of } \mathbf{R}_x \quad (\text{Definition 11.1 page 89}) \\
\Rightarrow \mathbf{R}_x &= \mathbf{R}_x^* && \text{by definition of adjoint } \mathbf{R}_x^* \quad (\text{Definition G.8 page 163}) \\
\Rightarrow \mathbf{R}_x &\text{ is self-adjoint} && \text{by definition of self-adjoint} \quad (\text{Definition G.11 page 171})
\end{aligned}$$

⇒

Theorem 11.2. Let $(\lambda_n)_{n \in \mathbb{Z}}$ be the EIGENVALUES and $(\psi_n)_{n \in \mathbb{Z}}$ be the EIGENFUNCTIONS of operator \mathbf{R}_x such that $\mathbf{R}_x \psi_n = \lambda_n \psi_n$ for all $n \in \mathbb{Z}$.

T H M	(1).	$\lambda_n \in \mathbb{R}$	(REAL-VALUED)
	(2).	$\lambda_n \neq \lambda_m \Rightarrow \langle \psi_n \psi_m \rangle = 0$	(ORTHOGONAL)
	(3).	$\ \psi_n\ ^2 > 0 \Rightarrow \lambda_n \geq 0$	(NON-NEGATIVE)
	(4).	$\ \psi_n(t)\ ^2 > 0, \langle \mathbf{R}_x f f \rangle > 0 \Rightarrow \lambda_n > 0$	(\mathbf{R}_x POSITIVE DEFINITE $\Rightarrow \lambda_n$ POSITIVE)

PROOF:

1. Proof that eigenvalues are *real-valued*:

$$\begin{aligned}
&\mathbf{R}_x \text{ is self-adjoint} && \text{by Theorem 11.1 page 89} \\
&\Rightarrow \text{eigenvalues of } \mathbf{R}_x \text{ are real} && (\text{Theorem G.18 page 171})
\end{aligned}$$

2. Proof that eigenfunctions associated with distinct eigenvalues are orthogonal: Because \mathbf{R}_x is *self-adjoint*, this property follows (Theorem G.18 page 171).

3. Proof that eigenvalues are *non-negative*:

$$\begin{aligned}
0 &\leq \langle \mathbf{R}_x \psi_n | \psi_n \rangle && \text{by definition of non-negative definite} \\
&= \langle \lambda_n \psi_n | \psi_n \rangle && \text{by definition of eigenvalue } (\mathbf{R}_x \psi_n = \lambda_n \psi_n) \\
&= \lambda_n \langle \psi_n | \psi_n \rangle && \text{by homogeneous property of inner products} \\
&= \lambda_n \|\psi_n\|^2 && \text{by definition of norm induced by inner-product}
\end{aligned}$$

4. Proof that eigenvalues are *positive* if \mathbf{R}_x is *positive definite*:

$$\begin{aligned}
 0 &< \langle \mathbf{R}_x \psi_n | \psi_n \rangle && \text{by definition of } \textit{positive definite} \\
 &= \langle \lambda_n \psi_n | \psi_n \rangle && \text{by hypothesis} \\
 &= \lambda_n \langle \psi_n | \psi_n \rangle && \text{by } \textit{homogeneous} \text{ property of } \langle \Delta | \nabla \rangle \\
 &= \lambda_n \|\psi_n\|^2 && \text{by } \textit{induced norm} \text{ theorem}
 \end{aligned}$$



Theorem 11.3 (Karhunen-Loève Expansion).¹ Let \mathbf{R}_x be the AUTO-CORRELATION OPERATOR (Definition 11.1 page 89) of a RANDOM PROCESS $x(n)$. Let $(\lambda_n)_{n \in \mathbb{Z}}$ be the eigenvalues of \mathbf{R}_x and $(\psi_n)_{n \in \mathbb{Z}}$ are the eigenfunctions of \mathbf{R}_x such that $\mathbf{R}_x \psi_n = \lambda_n \psi_n$.

T
H
M

$$\underbrace{\|\psi_n\| = 1}_{\{\psi_n(p)\} \text{ are NORMALIZED}} \implies \underbrace{\mathbb{E} \left[\left| x(m) - \sum_{n \in \mathbb{Z}} \langle x(m) | \psi_n(m) \rangle \psi_n(m) \right|^2 \right]}_{\text{CONVERGENCE IN PROBABILITY}} = 0 \quad (\{\psi_n(m)\} \text{ is a BASIS for } x(m))$$

PROOF:

1. Define $\dot{x}_n \triangleq \langle x(m) | \psi_n(m) \rangle \triangleq \sum_{m \in \mathbb{Z}} x(m) \psi_n(m)$

2. lemma: $\mathbb{E}[x(m)x(m)] = \sum_{n \in \mathbb{Z}} \lambda_n |\psi_n(m)|^2$. Proof: by *non-negative property* (Theorem 11.1 page 89) and *Mercer's Theorem* (Theorem M.4 page 246)

3. lemma:

$$\begin{aligned}
 &\mathbb{E} \left[x(p) \left(\sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(p) \right)^* \right] \\
 &\triangleq \mathbb{E} \left[x(p) \left(\sum_{n \in \mathbb{Z}} \int_{u \in \mathbb{R}} x(u) \psi_n^*(u) du \psi_n(p) \right)^* \right] && \text{by definition of } \dot{x} && (\text{definition 1 page 91}) \\
 &= \sum_{n \in \mathbb{Z}} \left(\int_{u \in \mathbb{R}} \mathbb{E}[x(p)x^*(u)] \psi_n(u) du \right) \psi_n^*(p) && \text{by } \textit{linearity} \\
 &\triangleq \sum_{n \in \mathbb{Z}} \left(\int_{u \in \mathbb{R}} R_{xx}(p, u) \psi_n(u) du \right) \psi_n^*(p) && \text{by definition of } R_{xx}(p, u) && (\text{Definition K.2 page 235}) \\
 &\triangleq \sum_{n \in \mathbb{Z}} (\mathbf{R}_x \psi_n(p) \psi_n^*(p)) && \text{by definition of } \mathbf{R}_x && (\text{Definition 11.1 page 89}) \\
 &= \sum_{n \in \mathbb{Z}} \lambda_n \psi_n(p) \psi_n^*(p) && \text{by property of } \textit{eigen-system} \\
 &= \sum_{n \in \mathbb{Z}} \lambda_n |\psi_n(p)|^2
 \end{aligned}$$

¹ Keener (1988) pages 114–119

4. lemma:

$$\begin{aligned}
& \mathbb{E} \left[\sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(p) \left(\sum_{m \in \mathbb{Z}} \dot{x}_m \psi_m(p) \right)^* \right] \\
& \triangleq \mathbb{E} \left[\sum_{n \in \mathbb{Z}} \int_{u \in \mathbb{R}} x(u) \psi_n^*(u) \, du \psi_n(p) \left(\sum_{m \in \mathbb{Z}} \int_v x(v) \psi_m^*(v) \, dv \psi_m(p) \right)^* \right] \quad \text{by definition of } \dot{x} \text{ (definition 1 page 91)} \\
& = \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} \int_u \left(\int_v \mathbb{E}[x(u)x^*(v)] \psi_m(v) \, dv \right) \psi_n^*(u) \, du \psi_n(p) \psi_m^*(p) \quad \text{by linearity} \\
& = \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} \int_u \left(\int_v R_{xx}(u, v) \psi_m(v) \, dv \right) \psi_n^*(u) \, du \psi_n(p) \psi_m^*(p) \quad \text{by definition of } R_{xx}(p, u) \text{ (Definition K.2 page 235)} \\
& = \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} \int_u (R_x \psi_m(u)) \psi_n^*(u) \, du \psi_n(p) \psi_m^*(p) \quad \text{by definition of } R_x \text{ (Definition 11.1 page 89)} \\
& = \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} \int_u (\lambda_m \psi_m(u)) \psi_n^*(u) \, du \psi_n(p) \psi_m^*(p) \quad \text{by property of eigen-system} \\
& = \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} \lambda_m \left(\int_{u \in \mathbb{R}} \psi_m(u) \psi_n^*(u) \, du \right) \psi_n(p) \psi_m^*(p) \quad \text{by linearity} \\
& = \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} \lambda_m \|\psi(p)\|^2 \bar{\delta}_{mn} \psi_n(p) \psi_m^*(p) \quad \text{by orthogonal property (Theorem 4.2 page 38)} \\
& = \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} \lambda_m \bar{\delta}_{mn} \psi_n(p) \psi_m^*(p) \quad \text{by normalized hypothesis} \\
& = \sum_{n \in \mathbb{Z}} \lambda_n \psi_n(p) \psi_n^*(p) \quad \text{by definition of Kronecker delta } \bar{\delta} \quad \text{(Definition H.12 page 194)} \\
& = \sum_{n \in \mathbb{Z}} \lambda_n |\psi_n(p)|^2
\end{aligned}$$

5. Proof that $\{\psi_n(p)\}$ is a *basis* for $x(p)$:

$$\begin{aligned}
& \mathbb{E} \left(\left| x(p) - \sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(p) \right|^2 \right) \\
& = \mathbb{E} \left(\left[x(p) - \sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(p) \right] \left[x(p) - \sum_{m \in \mathbb{Z}} \dot{x}_m \psi_m(p) \right]^* \right) \\
& = \mathbb{E} \left(x(p)x^*(p) - x(p) \left[\sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(p) \right]^* - x^*(p) \sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(p) + \left[\sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(p) \right] \left[\sum_{m \in \mathbb{Z}} \dot{x}_m \psi_m(p) \right]^* \right) \\
& = \mathbb{E}(x(p)x^*(p)) - \mathbb{E} \left[x(p) \left[\sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(p) \right]^* \right] - \mathbb{E} \left[x^*(p) \sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(p) \right] + \mathbb{E} \left[\sum_{n \in \mathbb{Z}} \dot{x}_n \psi_n(p) \left[\sum_{m \in \mathbb{Z}} \dot{x}_m \psi_m(p) \right]^* \right] \\
& \quad \text{by linearity of } \mathbb{E} \\
& = \underbrace{\sum_{n \in \mathbb{Z}} \lambda_n |\psi_n(p)|^2}_{\text{by (2) lemma}} - \underbrace{\sum_{n \in \mathbb{Z}} \lambda_n |\psi_n(p)|^2}_{\text{by (3) lemma}} - \underbrace{\left[\sum_{n \in \mathbb{Z}} \lambda_n |\psi_n(p)|^2 \right]^*}_{\text{by (3) lemma}} + \underbrace{\sum_{n \in \mathbb{Z}} \lambda_n |\psi_n(p)|^2}_{\text{by (4) lemma}} \\
& = 0
\end{aligned}$$

11.3 Quasi-basis

The *auto-correlation operator* \mathbf{R}_x (Definition 11.1 page 89) in the discrete case can be approximated using a *correlation matrix*. In the *zero-mean* case, this becomes

$$\mathbf{R}_x \triangleq \begin{bmatrix} E[y_1 y_1] & E[y_1 y_2] & \cdots & E[y_1 y_n] \\ E[y_2 y_1] & E[y_2 y_2] & & E[y_2 y_n] \\ \vdots & \vdots & \ddots & \vdots \\ E[y_n y_1] & E[y_n y_2] & \cdots & E[y_n y_n] \end{bmatrix}$$












The eigen-vectors (and hence a quasi-basis) for \mathbf{R}_x can be found using a *Cholesky Decomposition*.


Proposition 11.1.²

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The AUTO-CORRELATION MATRIX \mathbf{R}_x is *Toeplitz*.

Remark 11.1. For more information about the properties of **Toeplitz matrices**, see

1.  [Grenander and Szegö \(1958\)](#),
2.  [Widom \(1965\)](#),
3.  [Gray \(1971\)](#),
4.  [Smylie et al. \(1973\) page 408](#) (§“B. PROPERTIES OF THE TOEPLITZ MATRIX”),
5.  [GRENANDER AND SZEGÖ \(1984\)](#),
6.  [HAYKIN AND KESLER \(1979\)](#),
7.  [HAYKIN AND KESLER \(1983\)](#),
8.  [S. LAWRENCE MARPLE \(1987\) PAGES 80–92](#) (§“3.8 THE TOEPLITZ MATRIX”),
9.  [BÖTTCHER AND SILBERMANN \(1999\)](#) (ISBN:9780387985701),
10.  [GRAY \(2006\)](#),
11.  [S. LAWRENCE MARPLE \(2019\) PAGES 80–93](#) (§“3.8 THE TOEPLITZ MATRIX”).

²See  [Clarkson \(1993\) page 131](#) (§“Appendix 3A — Positive Semi-Definite Form of the Autocorrelation Matrix”)

Part V

Appendices

APPENDIX A

ALGEBRAIC STRUCTURES



“In this book, learned reader, you have the rules of algebra... It unties the knot not only where one term is equal to another or two to one but also where two are equal to two or three to one.... this most abstruse and unsurpassed treasury of the entire arithmetic being brought to light and, as in a theater, exposed to the sight of all...”

Gerolamo Cardano (1501–1576), Italian mathematician, physician, and astrologer ¹

A set together with one or more operations forms several standard mathematical structures:

group \supseteq *ring* \supseteq *commutative ring* \supseteq *integral domain* \supseteq *field*

Definition A.1. ² Let X be a set and $\diamond : X \times X \rightarrow X$ be an operation on X .

The pair (X, \diamond) is a **group** if

- | | | | | |
|------------|-----------------------------------|---|-------------------------|------------------------|
| DEF | 1. $\exists e \in X$ such that | $e \diamond x = x \diamond e = x$ | $\forall x \in X$ | (IDENTITY element) and |
| | 2. $\exists (-x) \in X$ such that | $(-x) \diamond x = x \diamond (-x) = e$ | $\forall x \in X$ | (INVERSE element) and |
| | 3. | $x \diamond (y \diamond z) = (x \diamond y) \diamond z$ | $\forall x, y, z \in X$ | (ASSOCIATIVE) |

Definition A.2. ³ Let $+$: $X \times X \rightarrow X$ and \cdot : $X \times X \rightarrow X$ be operations on a set X . Furthermore, let the operation \cdot also be represented by juxtaposition as in $a \cdot b \equiv ab$.

The triple $(X, +, \cdot)$ is a **ring** if

- | | | | | |
|------------|-----------------------------|-------------------------|---|-----|
| DEF | 1. $(X, +)$ is a group. | | (additive group) | and |
| | 2. $x(yz) = (xy)z$ | $\forall x, y, z \in X$ | (ASSOCIATIVE with respect to \cdot) | and |
| | 3. $x(y + z) = (xy) + (xz)$ | $\forall x, y, z \in X$ | (\cdot is LEFT DISTRIBUTIVE over $+$) | and |
| | 4. $(x + y)z = (xz) + (yz)$ | $\forall x, y, z \in X$ | (\cdot is RIGHT DISTRIBUTIVE over $+$). | |

Definition A.3. ⁴

¹ quote: Cardano (1545) page 1
image: <http://en.wikipedia.org/wiki/Image:Cardano.jpg>

² Durbin (2000) page 29

³ Durbin (2000) pages 114–115

⁴ Durbin (2000) page 118

DEF

A triple $(X, +, \cdot)$ is a **commutative ring** if

1. $(X, +, \cdot)$ is a RING and
2. $xy = yx \quad \forall x, y \in X$ (COMMUTATIVE).

Definition A.4. ⁵ Let R be a COMMUTATIVE RING (Definition A.3 page 97).

DEF

A function $|\cdot|$ in $\mathbb{R}^{\mathbb{R}}$ is an **absolute value** (or **modulus**) if

1. $|x| \geq 0 \quad x \in \mathbb{R}$ (NON-NEGATIVE) and
2. $|x| = 0 \iff x = 0 \quad x \in \mathbb{R}$ (NONDEGENERATE) and
3. $|xy| = |x| \cdot |y| \quad x, y \in \mathbb{R}$ (HOMOGENEOUS / SUBMULTIPLICATIVE) and
4. $|x + y| \leq |x| + |y| \quad x, y \in \mathbb{R}$ (SUBADDITIVE / TRIANGLE INEQUALITY)

Definition A.5. ⁶

DEF

The structure $F \triangleq (X, +, \cdot, 0, 1)$ is a **field** if

1. $(X, +, \cdot)$ is a ring (ring) and
2. $xy = yx \quad \forall x, y \in X$ (commutative with respect to \cdot) and
3. $(X \setminus \{0\}, \cdot)$ is a group (group with respect to \cdot).



Definition A.6. ⁷ Let $V = (F, +, \cdot)$ be a VECTOR SPACE and $\otimes : V \times V \rightarrow V$ be a vector-vector multiplication operator.



An **algebra** is any pair (V, \otimes) that satisfies (\otimes is represented by juxtaposition)

DEF

1. $(ux)y = u(xy) \quad \forall u, x, y \in V$ (ASSOCIATIVE) and
2. $u(x + y) = (ux) + (uy) \quad \forall u, x, y \in V$ (LEFT DISTRIBUTIVE) and
3. $(u + x)y = (uy) + (xy) \quad \forall u, x, y \in V$ (RIGHT DISTRIBUTIVE) and
4. $\alpha(xy) = (\alpha x)y = x(\alpha y) \quad \forall x, y \in V \text{ and } \alpha \in F$ (SCALAR COMMUTATIVE) .

⁵  Cohn (2002) page 312

⁶  Durbin (2000) page 123,  Weber (1893)

⁷  Abramovich and Aliprantis (2002) page 3,  Michel and Herget (1993) page 56

APPENDIX B

CALCULUS

Definition B.1. Let \mathbb{R} be the set of real numbers, \mathcal{B} the set of BOREL SETS on \mathbb{R} , and μ the standard BOREL MEASURE on \mathcal{B} . Let $\mathbb{R}^{\mathbb{R}}$ be as in Definition J.1 page 221.

The **space of Lebesgue square-integrable functions** $L^2_{(\mathbb{R}, \mathcal{B}, \mu)}$ (or $L^2_{\mathbb{R}}$) is defined as

$$L^2_{\mathbb{R}} \triangleq L^2_{(\mathbb{R}, \mathcal{B}, \mu)} \triangleq \left\{ f \in \mathbb{R}^{\mathbb{R}} \mid \left(\int_{\mathbb{R}} |f|^2 \right)^{\frac{1}{2}} d\mu < \infty \right\}.$$

The **standard inner product** $\langle \triangle | \nabla \rangle$ on $L^2_{\mathbb{R}}$ is defined as

$$\langle f(x) | g(x) \rangle \triangleq \int_{\mathbb{R}} f(x) g^*(x) dx.$$

The **standard norm** $\|\cdot\|$ on $L^2_{\mathbb{R}}$ is defined as $\|f(x)\| \triangleq \langle f(x) | f(x) \rangle^{\frac{1}{2}}$

Definition B.2. Let $f(x)$ be a FUNCTION in $\mathbb{R}^{\mathbb{R}}$.

$$\frac{d}{dx} f(x) \triangleq f'(x) \triangleq \lim_{\varepsilon \rightarrow 0} \frac{f(x + \varepsilon) - f(x)}{\varepsilon}$$

Proposition B.1.

$$\left\{ \begin{array}{l} (1). \quad f(x) \text{ is CONTINUOUS} \quad \text{and} \\ (2). \quad \underbrace{f(a+x) = f(a-x)}_{\text{SYMMETRIC about a point } a} \end{array} \right\} \implies \left\{ \begin{array}{l} (1). \quad f'(a+x) = -f'(a-x) \quad (\text{ANTI-SYMMETRIC about } a) \\ (2). \quad f'(a) = 0 \end{array} \right\}$$

 PROOF:

$$\begin{aligned} f'(a+x) &= \lim_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} [f(a+x+\varepsilon) - f(a+x-\varepsilon)] \\ &= \lim_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} [f(a-x-\varepsilon) - f(a-x+\varepsilon)] && \text{by hypothesis (2)} \\ &= -\lim_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} [f(a-x+\varepsilon) - f(a-x-\varepsilon)] \\ &= -f'(a-x) \end{aligned}$$

$$\begin{aligned} f'(a) &= \frac{1}{2} f'(a+0) + \frac{1}{2} f'(a-0) \\ &= \frac{1}{2} [f'(a+0) - f'(a+0)] && \text{by previous result} \end{aligned}$$

$$= 0$$



Lemma B.1.

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$$f(x) \text{ is INVERTIBLE} \implies \left\{ \frac{d}{dy} f^{-1}(y) = \frac{1}{\frac{d}{dx} f[f^{-1}(y)]} \right\}$$

PROOF:

$$\begin{aligned} \frac{d}{dy} f^{-1}(y) &\triangleq \lim_{\varepsilon \rightarrow 0} \frac{f^{-1}(y + \varepsilon) - f^{-1}(y)}{\varepsilon} && \text{by definition of } \frac{d}{dy} && (\text{Definition B.2 page 99}) \\ &= \lim_{\delta \rightarrow 0} \frac{1}{\left[\frac{f(x + \delta) - f(x)}{\delta} \right]} \bigg|_{x \triangleq f^{-1}(y)} && \text{because in the limit, } \frac{\Delta y}{\Delta x} = \left(\frac{\Delta x}{\Delta y} \right)^{-1} \\ &\triangleq \frac{1}{\frac{d}{dx} f(x)} \bigg|_{x \triangleq f^{-1}(y)} && \text{by definition of } \frac{d}{dx} && (\text{Definition B.2 page 99}) \\ &= \frac{1}{\frac{d}{dx} f[f^{-1}(y)]} && \text{because } x \triangleq f^{-1}(y) \end{aligned}$$



Theorem B.1.¹ Let f be a continuous function in $L^2_{\mathbb{R}}$ and $f^{(n)}$ the n th derivative of f .

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$$\int_{[0:1]^n} f^{(n)} \left(\sum_{k=1}^n x_k \right) dx_1 dx_2 \cdots dx_n = \sum_{k=0}^n (-1)^{n-k} \binom{n}{k} f(k) \quad \forall n \in \mathbb{N}$$

PROOF: Proof by induction:

1. Base case ...proof for $n = 1$ case:

$$\begin{aligned} \int_{[0:1]} f^{(1)}(x) dx &= f(1) - f(0) && \text{by Fundamental theorem of calculus} \\ &= (-1)^{1+1} \binom{1}{1} f(1) + (-1)^{1+0} \binom{1}{0} f(0) \\ &= \sum_{k=0}^1 (-1)^{n-k} \binom{n}{k} f(k) \end{aligned}$$

¹ Chui (1992) page 86 (item (ii)), Prasad and Iyengar (1997) pages 145–146 (Theorem 6.2 (b))

2. Induction step ...proof that n case $\implies n + 1$ case:

$$\begin{aligned}
 & \int_{[0:1]^{n+1}} f^{(n+1)} \left(\sum_{k=1}^{n+1} x_k \right) dx_1 dx_2 \cdots dx_{n+1} \\
 &= \int_{[0:1]^n} \left[\int_0^1 f^{(n+1)} \left(x_{n+1} + \sum_{k=1}^n x_k \right) dx_{n+1} \right] dx_1 dx_2 \cdots dx_n \\
 &= \int_{[0:1]^n} \left[f^{(n)} \left(x_{n+1} + \sum_{k=1}^n x_k \right) \right]_{x_{n+1}=0}^{x_{n+1}=1} dx_1 dx_2 \cdots dx_n \quad \text{by Fundamental theorem of calculus} \\
 &= \int_{[0:1]^n} \left[f^{(n)} \left(1 + \sum_{k=1}^n x_k \right) - f^{(n)} \left(0 + \sum_{k=1}^n x_k \right) \right] dx_1 dx_2 \cdots dx_n \\
 &= \sum_{k=0}^n (-1)^{n-k} \binom{n}{k} f(k+1) - \sum_{k=0}^n (-1)^{n-k} \binom{n}{k} f(k) \quad \text{by induction hypothesis} \\
 &= \sum_{m=1}^{n+1} (-1)^{n-m+1} \binom{n}{m-1} f(m) + \sum_{k=0}^n (-1)(-1)^{n-k} \binom{n}{k} f(k) \quad \text{where } m \triangleq k+1 \implies k = m-1 \\
 &= \left[f(n+1) + \sum_{k=1}^n (-1)^{n-k+1} \binom{n}{k-1} f(k) \right] + \left[(-1)^{n+1} f(0) + \sum_{k=1}^n (-1)^{n-k+1} \binom{n}{k} f(k) \right] \\
 &= f(n+1) + (-1)^{n+1} f(0) + \sum_{k=1}^n (-1)^{n-k+1} \underbrace{\left[\binom{n}{k-1} + \binom{n}{k} \right]}_{\text{use Stifel formula}} f(k) \\
 &= (-1)^0 \binom{n+1}{n+1} f(n+1) + (-1)^{n+1} \binom{n+1}{0} f(0) + \sum_{k=1}^n (-1)^{n-k+1} \binom{n+1}{k} f(k) \quad \text{by Stifel formula} \\
 &= \sum_{k=0}^{n+1} (-1)^{n-k+1} \binom{n+1}{k} f(k)
 \end{aligned}$$

⇒

Some proofs invoke differentiation multiple times. This is simplified thanks to the *Leibniz rule*, also called the *generalized product rule (GPR, next lemma)*. The Leibniz rule is remarkably similar in form to the *binomial theorem*.

Lemma B.2 (Leibniz rule / generalized product rule). ² Let $f(x), g(x) \in \mathbf{L}_{\mathbb{R}}^2$ with derivatives $f^{(n)}(x) \triangleq \frac{d^n}{dx^n} f(x)$ and $g^{(n)}(x) \triangleq \frac{d^n}{dx^n} g(x)$ for $n = 0, 1, 2, \dots$, and $\binom{n}{k} \triangleq \frac{n!}{(n-k)!k!}$ (binomial coefficient). Then

$$\frac{d^n}{dx^n} [f(x)g(x)] = \sum_{k=0}^n \binom{n}{k} f^{(k)}(x) g^{(n-k)}(x)$$

Example B.1.

$$\frac{d^3}{dx^3} [f(x)g(x)] = f'''(x)g(x) + 3f''(x)g'(x) + 3f'(x)g''(x) + f(x)g'''(x)$$

Theorem B.2 (Leibniz integration rule). ³

² Ben-Israel and Gilbert (2002) page 154, Leibniz (1710)

³ Flanders (1973) page 615 (1.1), Talvila (2001), Knapp (2005b) page 389 (Chapter VII), Protter and Morrey (2012) page 422 (Leibniz Rule. Theorem 1.), <http://planetmath.org/encyclopedia/DifferentiationUnderIntegralSign.html>

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$$\frac{d}{dx} \int_{a(x)}^{b(x)} g(t) \, dt = g[b(x)]b'(x) - g[a(x)]a'(x)$$

APPENDIX C

CONVOLUTION

C.1 Definition

Definition C.1. ¹

DEF

The *convolution operation* is defined as

$$[f \star g](x) \triangleq f(x) \star g(x) \triangleq \int_{u \in \mathbb{R}} f(u)g(x - u) \, du \qquad \forall f, g \in L^2_{(\mathbb{R}, \mathcal{B}, \mu)}$$

C.2 Properties

Theorem C.1. ²

THM

$f \star g$	$=$	$g \star f$	(COMMUTATIVE)
$f \star (g \star h)$	$=$	$(g \star g) \star h$	(ASSOCIATEVE)
$(\alpha f) \star g$	$=$	$\alpha(f \star g) = f \star (\alpha g)$	$\forall \alpha \in \mathbb{C}$
$f \star (g + h)$	$=$	$(f \star g) + (f \star h)$	(DISTRIBUTIVE)

¹ [Bachman et al. \(2002\) page 268](#) (Definition 5.2.1, but with $1/2\pi$ scaling factor), [Bachman \(1964\) page 6](#), [Bracewell \(1978\) page 224](#) (Table 11.1 Theorems for the Laplace Transform)

² [Bachman et al. \(2002\) pages 268–270](#)

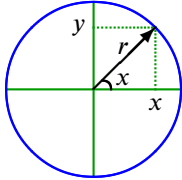
APPENDIX D

TRIGONOMETRIC FUNCTIONS

D.1 Definition Candidates

There are several ways of defining the sine and cosine functions, including the following:¹

1. **Planar geometry:** Trigonometric functions are traditionally introduced as they have come to us historically—that is, as related to the parameters of triangles.²



$$\begin{aligned}\cos x &\triangleq \frac{x}{r} \\ \sin x &\triangleq \frac{y}{r}\end{aligned}$$

2. **Complex exponential:** The cosine and sine functions are the real and imaginary parts of the complex exponential such that³

$$\cos x \triangleq \mathbf{R}_e e^{ix} \quad \sin x \triangleq \mathbf{I}_m(e^{ix})$$

3. **Polynomial:** Let $\sum_{n=0}^{\infty} x_n \triangleq \lim_{N \rightarrow \infty} \sum_{n=0}^N x_n$ in some topological space. The sine and cosine functions can be defined in terms of *Taylor expansions* such that⁴

$$\begin{aligned}\cos(x) &\triangleq \sum_{n=0}^{\infty} \frac{(-1)^n}{(2n)!} x^{2n} = 1 - \frac{x^2}{2} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots \\ \sin(x) &\triangleq \sum_{n=0}^{\infty} \frac{(-1)^n}{(2n+1)!} x^{2n+1} = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots\end{aligned}$$

¹The term *sine* originally came from the Hindu word *jiva* and later adapted to the Arabic word *jiba*. Abrabic-Latin translator [Robert of Chester](#) apparently confused this word with the Arabic word *jaib*, which means “bay” or “inlet”—thus resulting in the Latin translation *sinus*, which also means “bay” or “inlet”. Reference: [Boyer and Merzbach \(1991\) page 252](#)

²[Abramowitz and Stegun \(1972\) page 78](#)

³[Euler \(1748\)](#)

⁴[Rosenlicht \(1968\) page 157, Abramowitz and Stegun \(1972\) page 74](#)

4. **Product of factors:** Let $\prod_{n=0}^{\infty} x_n \triangleq \lim_{N \rightarrow \infty} \prod_{n=0}^N x_n$ in some topological space. The sine and cosine functions can be defined in terms of a product of factors such that⁵

$$\cos(x) \triangleq \prod_{n=1}^{\infty} \left[1 - \left(\frac{x}{(2n-1)\frac{\pi}{2}} \right)^2 \right] \quad \sin(x) \triangleq x \prod_{n=1}^{\infty} \left[1 - \left(\frac{x}{n\pi} \right)^2 \right]$$

5. **Partial fraction expansion:** The sine function can be defined in terms of a partial fraction expansion such that⁶

$$\sin(x) \triangleq \frac{1}{\frac{1}{x} + 2x \sum_{n=1}^{\infty} \frac{(-1)^n}{x^2 - (n\pi)^2}} \quad \cos(x) \triangleq \underbrace{\left(\frac{1}{x} + 2x \sum_{n=1}^{\infty} \frac{1}{x^2 - (n\pi)^2} \right)}_{\cot(x)} \sin(x)$$




6. **Differential operator:** The sine and cosine functions can be defined as solutions to differential equations expressed in terms of the differential operator $\frac{d}{dx}$ such that

$$\begin{array}{llll} \cos(x) \triangleq f(x) & \text{where} & \underbrace{\frac{d^2}{dx^2}f + f = 0}_{\text{differential equation}} & \underbrace{f(0) = 1}_{\text{1st initial condition}} & \underbrace{\left[\frac{d}{dx}f \right](0) = 0}_{\text{2nd initial condition}} \\ \sin(x) \triangleq g(x) & \text{where} & \underbrace{\frac{d^2}{dx^2}g + g = 0}_{\text{differential equation}} & \underbrace{g(0) = 0}_{\text{1st initial condition}} & \underbrace{\left[\frac{d}{dx}g \right](0) = 1}_{\text{2nd initial condition}} \end{array}$$

7. **Integral operator:** The sine and cosine functions can be defined as inverses of integrals of square roots of rational functions such that⁷

$$\begin{array}{ll} \cos(x) \triangleq f^{-1}(x) & \text{where } f(x) \triangleq \underbrace{\int_x^1 \sqrt{\frac{1}{1-y^2}} dy}_{\arccos(x)} \\ \sin(x) \triangleq g^{-1}(x) & \text{where } g(x) \triangleq \underbrace{\int_0^x \sqrt{\frac{1}{1-y^2}} dy}_{\arcsin(x)} \end{array}$$



For purposes of analysis, it can be argued that the more natural approach for defining harmonic functions is in terms of the differentiation operator $\frac{d}{dx}$ (Definition D.1 page 107). Support for such an approach includes the following:

-  Both sine and cosine are very easily represented analytically as polynomials with coefficients involving the operator $\frac{d}{dx}$ (Theorem D.1 page 108).
-  All solutions of homogeneous second order differential equations are linear combinations of sine and cosine (Theorem D.3 page 110).
-  Sine and cosine themselves are related to each other in terms of the differentiation operator (Theorem D.4 page 111).

⁵  Abramowitz and Stegun (1972) page 75

⁶  Abramowitz and Stegun (1972) page 75

⁷  Abramowitz and Stegun (1972) page 79

-  The complex exponential function is a solution of a second order homogeneous differential equation (Definition D.4 page 112).
-  Sine and cosine are orthogonal with respect to an innerproduct generated by an integral operator—which is a kind of inverse differential operator (Section D.6 page 120).

D.2 Definitions

Definition D.1. ⁸ Let \mathcal{C} be the SPACE OF ALL CONTINUOUSLY DIFFERENTIABLE REAL FUNCTIONS and $\frac{d}{dx} \in \mathcal{C}^{\mathcal{C}}$ the differentiation operator.

The function $f \in \mathcal{C}^{\mathcal{C}}$ is the **cosine** function $\cos(x) \triangleq f(x)$ if

DEF

1. $\frac{d^2}{dx^2}f + f = 0$ (second order homogeneous differential equation) and
2. $f(0) = 1$ (first initial condition) and
3. $\left[\frac{d}{dx}f\right](0) = 0$ (second initial condition).

Definition D.2. ⁹ Let \mathcal{C} and $\frac{d}{dx} \in \mathcal{C}^{\mathcal{C}}$ be defined as in definition of $\cos(x)$ (Definition D.1 page 107).

The function $f \in \mathcal{C}^{\mathcal{C}}$ is the **sine** function $\sin(x) \triangleq f(x)$ if

DEF

1. $\frac{d^2}{dx^2}f + f = 0$ (second order homogeneous differential equation) and
2. $f(0) = 0$ (first initial condition) and
3. $\left[\frac{d}{dx}f\right](0) = 1$ (second initial condition).

Definition D.3. ¹⁰

Let π (“pi”) be defined as the element in \mathbb{R} such that

DEF

- (1). $\cos\left(\frac{\pi}{2}\right) = 0$ and
- (2). $\pi > 0$ and
- (3). π is the **smallest** of all elements in \mathbb{R} that satisfies (1) and (2).

D.3 Basic properties


Lemma D.1. ¹¹ Let \mathcal{C} be the SPACE OF ALL CONTINUOUSLY DIFFERENTIABLE REAL FUNCTIONS and $\frac{d}{dx} \in \mathcal{C}^{\mathcal{C}}$ the differentiation operator.



LEM

$$\left\{ \begin{aligned} &\left\{ \frac{d^2}{dx^2}f + f = 0 \right\} \iff \\ &\left\{ \begin{aligned} f(x) &= \underbrace{[f](0) \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n}}{(2n)!}}_{\text{even terms}} + \underbrace{\left[\frac{d}{dx}f\right](0) \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n+1}}{(2n+1)!}}_{\text{odd terms}} \\ &= \left(f(0) + \left[\frac{d}{dx}f\right](0)x \right) - \left(\frac{f(0)}{2!}x^2 + \frac{\left[\frac{d}{dx}f\right](0)}{3!}x^3 \right) + \left(\frac{f(0)}{4!}x^4 + \frac{\left[\frac{d}{dx}f\right](0)}{5!}x^5 \right) \dots \end{aligned} \right\} \end{aligned} \right.$$

⁸  Rosenlicht (1968) page 157,  Flanigan (1983) pages 228–229

⁹  Rosenlicht (1968) page 157,  Flanigan (1983) pages 228–229

¹⁰  Rosenlicht (1968) page 158

¹¹  Rosenlicht (1968) page 156,  Liouville (1839)

✎ PROOF: Let $f'(x) \triangleq \frac{d}{dx}f(x)$.

$$\begin{aligned} f'''(x) &= -\left[\frac{d}{dx}f\right](x) \\ f^{(4)}(x) &= -\left[\frac{d}{dx}f\right](x) = -\left[\frac{d^2}{dx^2}f\right](x) = f(x) \end{aligned}$$

1. Proof that $\left[\frac{d^2}{dx^2}f\right](x) + f(x) = 0 \implies f(x) = \sum_{n=0}^{\infty} (-1)^n \left[\frac{f(0)}{(2n)!} x^{2n} + \frac{\left[\frac{d}{dx}f\right](0)}{(2n+1)!} x^{2n+1} \right]$:

$$\begin{aligned} f(x) &= \sum_{n=0}^{\infty} \frac{f^{(n)}(0)}{n!} x^n \quad \text{by Taylor expansion} \\ &= f(0) + \left[\frac{d}{dx}f\right](0)x - \frac{\left[\frac{d^2}{dx^2}f\right](0)}{2!}x^2 - \frac{f^{(3)}(0)}{3!}x^3 + \frac{f^{(4)}(0)}{4!}x^4 + \frac{f^{(5)}(0)}{5!}x^5 - \dots \\ &= f(0) + \left[\frac{d}{dx}f\right](0)x - \frac{f(0)}{2!}x^2 - \frac{\left[\frac{d}{dx}f\right](0)}{3!}x^3 + \frac{f(0)}{4!}x^4 + \frac{\left[\frac{d}{dx}f\right](0)}{5!}x^5 - \dots \\ &= f(x) = \sum_{n=0}^{\infty} (-1)^n \left[\frac{f(0)}{(2n)!} x^{2n} + \frac{\left[\frac{d}{dx}f\right](0)}{(2n+1)!} x^{2n+1} \right] \end{aligned}$$

2. Proof that $\left[\frac{d^2}{dx^2}f\right](x) + f(x) = 0 \iff f(x) = \sum_{n=0}^{\infty} (-1)^n \left[\frac{f(0)}{(2n)!} x^{2n} + \frac{\left[\frac{d}{dx}f\right](0)}{(2n+1)!} x^{2n+1} \right]$:

$$\begin{aligned} \left[\frac{d^2}{dx^2}f\right](x) &= \frac{d}{dx} \frac{d}{dx} [f(x)] \\ &= \frac{d}{dx} \frac{d}{dx} \sum_{n=0}^{\infty} (-1)^n \left[\frac{f(0)}{(2n)!} x^{2n} + \frac{\left[\frac{d}{dx}f\right](0)}{(2n+1)!} x^{2n+1} \right] \quad \text{by right hypothesis} \\ &= \sum_{n=1}^{\infty} (-1)^n \left[\frac{(2n)(2n-1)f(0)}{(2n)!} x^{2n-2} + \frac{(2n+1)(2n)\left[\frac{d}{dx}f\right](0)}{(2n+1)!} x^{2n-1} \right] \\ &= \sum_{n=1}^{\infty} (-1)^n \left[\frac{f(0)}{(2n-2)!} x^{2n-2} + \frac{\left[\frac{d}{dx}f\right](0)}{(2n-1)!} x^{2n-1} \right] \\ &= \sum_{n=0}^{\infty} (-1)^{n+1} \left[\frac{f(0)}{(2n)!} x^{2n} + \frac{\left[\frac{d}{dx}f\right](0)}{(2n+1)!} x^{2n+1} \right] \\ &= -f(x) \quad \text{by right hypothesis} \end{aligned}$$

⇒

Theorem D.1 (Taylor series for cosine/sine). ¹²

T H M	$\cos(x) = \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n}}{(2n)!} = 1 - \frac{x^2}{2} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots \quad \forall x \in \mathbb{R}$
	$\sin(x) = \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n+1}}{(2n+1)!} = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots \quad \forall x \in \mathbb{R}$

¹² Rosenlicht (1968) page 157

PROOF:

$$\begin{aligned}
 \cos(x) &= \underbrace{f(0) \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n}}{(2n)!}}_{\text{even terms}} + \underbrace{\left[\frac{d}{dx} f \right](0) \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n+1}}{(2n+1)!}}_{\text{odd terms}} && \text{by Lemma D.1 page 107} \\
 &= 1 \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n}}{(2n)!} + 0 \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n+1}}{(2n+1)!} && \text{by cos initial conditions (Definition D.1 page 107)} \\
 &= \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n}}{(2n)!} \\
 \sin(x) &= \underbrace{f(0) \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n}}{(2n)!}}_{\text{even terms}} + \underbrace{\left[\frac{d}{dx} f \right](0) \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n+1}}{(2n+1)!}}_{\text{odd terms}} && \text{by Lemma D.1 page 107} \\
 &= 0 \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n}}{(2n)!} + 1 \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n+1}}{(2n+1)!} && \text{by sin initial conditions (Definition D.2 page 107)} \\
 &= \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n+1}}{(2n+1)!}
 \end{aligned}$$

⇒

Theorem D.2. ¹³

T H M	$\cos(0) = 1$	$\cos(-x) = \cos(x) \quad \forall x \in \mathbb{R} \quad (\text{EVEN})$
	$\sin(0) = 0$	$\sin(-x) = -\sin(x) \quad \forall x \in \mathbb{R} \quad (\text{ODD})$

PROOF:

$$\begin{aligned}
 \cos(0) &= 1 - \frac{x^2}{2} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots \Big|_{x=0} && \text{by Taylor series for cosine} && (\text{Theorem D.1 page 108}) \\
 &= 1 \\
 \sin(0) &= x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots \Big|_{x=0} && \text{by Taylor series for sine} && (\text{Theorem D.1 page 108}) \\
 &= 0 \\
 \cos(-x) &= 1 - \frac{(-x)^2}{2} + \frac{(-x)^4}{4!} - \frac{(-x)^6}{6!} + \dots && \text{by Taylor series for cosine} && (\text{Theorem D.1 page 108}) \\
 &= 1 - \frac{x^2}{2} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots \\
 &= \cos(x) && \text{by Taylor series for cosine} && (\text{Theorem D.1 page 108}) \\
 \sin(-x) &= (-x) - \frac{(-x)^3}{3!} + \frac{(-x)^5}{5!} - \frac{(-x)^7}{7!} + \dots && \text{by Taylor series for sine} && (\text{Theorem D.1 page 108}) \\
 &= - \left[x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots \right] \\
 &= \sin(x) && \text{by Taylor series for sine} && (\text{Theorem D.1 page 108})
 \end{aligned}$$

⇒

Lemma D.2. ¹⁴

L E M	$\cos(1) > 0$	$x \in (0 : 2) \implies \sin(x) > 0$
	$\cos(2) < 0$	

¹³ Rosenlicht (1968) page 157

¹⁴ Rosenlicht (1968) page 158

✎ PROOF:

$$\begin{aligned}\cos(1) &= 1 - \frac{x^2}{2} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots \Big|_{x=1} && \text{by Taylor series for cosine} && (\text{Theorem D.1 page 108}) \\ &= 1 - \frac{1}{2} + \frac{1}{4!} - \frac{1}{6!} + \dots \\ &> 0\end{aligned}$$

$$\begin{aligned}\cos(2) &= 1 - \frac{x^2}{2} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots \Big|_{x=2} && \text{by Taylor series for cosine} && (\text{Theorem D.1 page 108}) \\ &= 1 - \frac{4}{2} + \frac{16}{24} - \frac{64}{720} + \dots \\ &< 0\end{aligned}$$

$$\begin{aligned}x \in (0 : 2) &\implies \text{each term in the sequence } \left(\left(x - \frac{x^3}{3!} \right), \left(\frac{x^5}{5!} - \frac{x^7}{7!} \right), \left(\frac{x^9}{9!} - \frac{x^{11}}{11!} \right), \dots \right) \text{ is } > 0 \\ &\implies \sin(x) > 0\end{aligned}$$

⇒

Proposition D.1. *Let π be defined as in Definition D.3 (page 107).*

- P** (A). The value π **exists** in \mathbb{R} .
R (B). $2 < \pi < 4$.
P

✎ PROOF:

$$\begin{aligned}\cos(1) &> 0 && \text{by Lemma D.2 page 109} \\ \cos(2) &< 0 && \text{by Lemma D.2 page 109} \\ &\implies 1 < \frac{\pi}{2} < 2 \\ &\implies 2 < \pi < 4\end{aligned}$$

⇒


Theorem D.3. ¹⁵ *Let \mathcal{C} be the space of all continuously differentiable real functions and $\frac{d}{dx} \in \mathcal{C}^{\mathcal{C}}$ the differentiation operator. Let $f'(0) \triangleq \left[\frac{d}{dx} f \right](0)$.*

T $\left\{ \frac{d^2}{dx^2} f + f = 0 \right\} \iff \left\{ f(x) = f(0) \cos(x) + f'(0) \sin(x) \right\} \quad \forall f \in \mathcal{C}, \forall x \in \mathbb{R}$
M

✎ PROOF:

1. Proof that $\left[\frac{d^2}{dx^2} f \right](x) = -f(x) \implies f(x) = f(0)\cos(x) + \left[\frac{d}{dx} f \right](0)\sin(x)$:

$$\begin{aligned}f(x) &= f(0) \underbrace{\sum_{n=0}^{\infty} (-1)^n \frac{x^{2n}}{(2n)!}}_{\cos(x)} + \left[\frac{d}{dx} f \right](0) \underbrace{\sum_{n=0}^{\infty} (-1)^n \frac{x^{2n+1}}{(2n+1)!}}_{\sin(x)} && \text{by left hypothesis and Lemma D.1 page 107} \\ &= f(0)\cos x + \left[\frac{d}{dx} f \right](0)\sin x && \text{by definitions of cos and sin (Definition D.1 page 107, Definition D.2 page 107)}\end{aligned}$$

¹⁵  Rosenlicht (1968) page 157.

2. Proof that $\frac{d^2}{dx^2}f = -f \iff f(x) = f(0)\cos(x) + \left[\frac{d}{dx}f\right](0)\sin(x)$:

$$f(x) = f(0)\cos x + \left[\frac{d}{dx}f\right](0)\sin x \quad \text{by right hypothesis}$$

$$= f(0) \underbrace{\sum_{n=0}^{\infty} (-1)^n \frac{x^{2n}}{(2n)!}}_{\cos(x)} + \left[\frac{d}{dx}f\right](0) \underbrace{\sum_{n=0}^{\infty} (-1)^n \frac{x^{2n+1}}{(2n+1)!}}_{\sin(x)}$$

$$\implies \frac{d^2}{dx^2}f + f = 0$$

by Lemma D.1 page 107

\Rightarrow

Remark D.1. The general solution for the *non-homogeneous* equation $\frac{d^2}{dx^2}f(x) + f(x) = g(x)$ with initial conditions $f(a) = 1$ and $f'(a) = \rho$ is $f(x) = \cos(x) + \rho\sin(x) + \int_a^x g(y)\sin(x-y) dy$. This type of equation is called a *Volterra integral equation of the second type*. References: [Folland \(1992\)](#) page 371, [Liouville \(1839\)](#). Volterra equation references: [Pedersen \(2000\)](#) page 99, [Lalescu \(1908\)](#), [Lalescu \(1911\)](#)

Theorem D.4. ¹⁶ Let $\frac{d}{dx} \in \mathcal{C}^{\mathcal{C}}$ be the differentiation operator.

T H M	$\frac{d}{dx}\cos(x) = -\sin(x) \quad \forall x \in \mathbb{R} \quad \left \quad \frac{d}{dx}\sin(x) = \cos(x) \quad \forall x \in \mathbb{R} \quad \right \quad \cos^2(x) + \sin^2(x) = 1 \quad \forall x \in \mathbb{R}$
-------------	--

PROOF:

$$\frac{d}{dx}\cos(x) = \frac{d}{dx} \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n}}{(2n)!} \quad \text{by Taylor series} \quad (\text{Theorem D.1 page 108})$$

$$= \sum_{n=1}^{\infty} (-1)^n \frac{2nx^{2n-1}}{(2n)!} = \sum_{n=1}^{\infty} (-1)^n \frac{x^{2n-1}}{(2n-1)!} = \sum_{n=0}^{\infty} (-1)^{n+1} \frac{x^{2n}}{(2n)!}$$

$$= -\sin(x) \quad \text{by Taylor series} \quad (\text{Theorem D.1 page 108})$$

$$\frac{d}{dx}\sin(x) = \frac{d}{dx} \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n+1}}{(2n+1)!} \quad \text{by Taylor series} \quad (\text{Theorem D.1 page 108})$$

$$= \sum_{n=0}^{\infty} (-1)^n \frac{(2n+1)x^{2n}}{(2n+1)!} = \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n}}{(2n)!}$$

$$= \cos(x) \quad \text{by Taylor series} \quad (\text{Theorem D.1 page 108})$$

$$\frac{d}{dx} [\cos^2(x) + \sin^2(x)] = -2\cos(x)\sin(x) + 2\sin(x)\cos(x)$$

$$= 0$$

$$\implies \cos^2(x) + \sin^2(x) \text{ is constant}$$

$$\implies \cos^2(x) + \sin^2(x)$$

$$= \cos^2(0) + \sin^2(0)$$

$$= 1 + 0 = 1$$

by Theorem D.2 page 109

\Rightarrow

Proposition D.2.

P R P	$\sin\left(\frac{\pi}{2}\right) = 1$
-------------	--------------------------------------

¹⁶ [Rosenlicht \(1968\)](#) page 157

✎ PROOF:

$$\begin{aligned}
 \sin(\pi/2) &= \pm \sqrt{\sin^2(\pi/2) + 0} \\
 &= \pm \sqrt{\sin^2(\pi/2) + \cos^2(\pi/2)} && \text{by definition of } \pi && (\text{Definition D.3 page 107}) \\
 &= \pm \sqrt{1} && \text{by Theorem D.4 page 111} \\
 &= \pm 1 \\
 &= 1 && \text{by Lemma D.2 page 109}
 \end{aligned}$$

⇒

D.4 The complex exponential

Definition D.4.

The function $f \in \mathbb{C}^{\mathbb{C}}$ is the **exponential function** $\exp(ix) \triangleq f(x)$ if

DEF

1. $\frac{d^2}{dx^2} f + f = 0$ (second order homogeneous differential equation) and
2. $f(0) = 1$ (first initial condition) and
3. $\left[\frac{d}{dx} f\right](0) = i$ (second initial condition).

Theorem D.5 (Euler's Identity).¹⁷

THM

$$e^{ix} = \cos(x) + i\sin(x) \quad \forall x \in \mathbb{R}$$

✎ PROOF:

$$\begin{aligned}
 \exp(ix) &= f(0) \cos(x) + \left[\frac{d}{dx} f\right](0) \sin(x) && \text{by Theorem D.3 page 110} \\
 &= \cos(x) + i\sin(x) && \text{by Definition D.4 page 112}
 \end{aligned}$$

⇒

Proposition D.3.

PRP

$$e^{-i\pi/2} = -i \mid e^{i\pi/2} = i$$

✎ PROOF:

$$\begin{aligned}
 e^{i\pi/2} &= \cos(\pi/2) + i\sin(\pi/2) && \text{by Euler's Identity (Theorem D.5 page 112)} \\
 &= 0 + i && \text{by Theorem D.2 (page 109) and Proposition D.2 (page 111)} \\
 e^{-i\pi/2} &= \cos(-\pi/2) + i\sin(-\pi/2) && \text{by Euler's Identity (Theorem D.5 page 112)} \\
 &= \cos(\pi/2) - i\sin(\pi/2) && \text{by Theorem D.2 page 109} \\
 &= 0 - i && \text{by Theorem D.2 (page 109) and Proposition D.2 (page 111)}
 \end{aligned}$$

⇒

Corollary D.1.

COR

$$e^{ix} = \sum_{n \in \mathbb{W}} \frac{(ix)^n}{n!} \quad \forall x \in \mathbb{R}$$

¹⁷  Euler (1748),  Bottazzini (1986) page 12

PROOF:

$$\begin{aligned}
 e^{ix} &= \cos(x) + i\sin(x) && \text{by Euler's Identity} && (\text{Theorem D.5 page 112}) \\
 &= \underbrace{\sum_{n \in \mathbb{W}} \frac{(-1)^n x^{2n}}{(2n)!}}_{\cos(x)} + i \underbrace{\sum_{n \in \mathbb{W}} \frac{(-1)^n x^{2n+1}}{(2n+1)!}}_{\sin(x)} && \text{by Taylor series} && (\text{Theorem D.1 page 108}) \\
 &= \sum_{n \in \mathbb{W}} \frac{(i^2)^n x^{2n}}{(2n)!} + \sum_{n \in \mathbb{W}} \frac{i(i^2)^n x^{2n+1}}{(2n+1)!} && && \\
 &= \sum_{n \in \mathbb{W} \cap \mathbb{Z}_e} \frac{(ix)^n}{n!} + \sum_{n \in \mathbb{W} \cap \mathbb{Z}_o} \frac{(ix)^n}{n!} && && \\
 &= \sum_{n \in \mathbb{W}} \frac{(ix)^n}{n!} && &&
 \end{aligned}$$

⇒

Corollary D.2 (Euler formulas). ¹⁸

COR	$\cos(x) = \mathbf{R}_e(e^{ix}) = \frac{e^{ix} + e^{-ix}}{2} \quad \forall x \in \mathbb{R} \quad \bigg \quad \sin(x) = \mathbf{I}_m(e^{ix}) = \frac{e^{ix} - e^{-ix}}{2i} \quad \forall x \in \mathbb{R}$
------------	---

PROOF:

$$\begin{aligned}
 \mathbf{R}_e(e^{ix}) &\triangleq \frac{e^{ix} + (e^{ix})^*}{2} = \frac{e^{ix} + e^{-ix}}{2} && \text{by definition of } \mathfrak{R} && (\text{Definition F.5 page 149}) \\
 &= \frac{\cos(x) + i\sin(x)}{2} + \frac{\cos(-x) + i\sin(-x)}{2} && \text{by Euler's Identity} && (\text{Theorem D.5 page 112}) \\
 &= \frac{\cos(x) + i\sin(x)}{2} + \frac{\cos(x) - i\sin(x)}{2} && && \\
 &= \cos(x) && && \\
 \mathbf{I}_m(e^{ix}) &\triangleq \frac{e^{ix} - (e^{ix})^*}{2i} = \frac{e^{ix} - e^{-ix}}{2i} && \text{by definition of } \mathfrak{I} && (\text{Definition F.5 page 149}) \\
 &= \frac{\cos(x) + i\sin(x)}{2i} - \frac{\cos(-x) + i\sin(-x)}{2i} && \text{by Euler's Identity} && (\text{Theorem D.5 page 112}) \\
 &= \frac{\cos(x) + i\sin(x)}{2i} - \frac{\cos(x) - i\sin(x)}{2i} && && \\
 &= \sin(x) && &&
 \end{aligned}$$

⇒

Theorem D.6. ¹⁹

THEM	$e^{(\alpha+\beta)} = e^\alpha e^\beta \quad \forall \alpha, \beta \in \mathbb{C}$
-------------	--

PROOF:

$$\begin{aligned}
 e^\alpha e^\beta &= \left(\sum_{n \in \mathbb{W}} \frac{\alpha^n}{n!} \right) \left(\sum_{m \in \mathbb{W}} \frac{\beta^m}{m!} \right) && \text{by Corollary D.1 page 112} \\
 &= \sum_{n \in \mathbb{W}} \sum_{k=0}^n \frac{\alpha^k}{k!} \frac{\beta^{n-k}}{(n-k)!} \\
 &= \sum_{n \in \mathbb{W}} \sum_{k=0}^n \frac{n!}{n!} \frac{\alpha^k}{k!} \frac{\beta^{n-k}}{(n-k)!}
 \end{aligned}$$

¹⁸ Euler (1748), Bottazzini (1986) page 12

¹⁹ Rudin (1987) page 1

$$\begin{aligned}
&= \sum_{n \in \mathbb{W}} \frac{1}{n!} \sum_{k=0}^n \frac{n!}{k!(n-k)!} \alpha^k \beta^{n-k} \\
&= \sum_{n \in \mathbb{W}} \frac{1}{n!} \sum_{k=0}^n \binom{n}{k} \alpha^k \beta^{n-k} \\
&= \sum_{n \in \mathbb{W}} \frac{(\alpha + \beta)^n}{n!} \\
&= e^{\alpha + \beta}
\end{aligned}$$

by the *Binomial Theorem*

by Corollary D.1 page 112



D.5 Trigonometric Identities

Theorem D.7 (shift identities).

T H M	$\cos\left(x + \frac{\pi}{2}\right) = -\sin x \quad \forall x \in \mathbb{R}$	$\sin\left(x + \frac{\pi}{2}\right) = \cos x \quad \forall x \in \mathbb{R}$
	$\cos\left(x - \frac{\pi}{2}\right) = \sin x \quad \forall x \in \mathbb{R}$	$\sin\left(x - \frac{\pi}{2}\right) = -\cos x \quad \forall x \in \mathbb{R}$

PROOF:

$$\begin{aligned}
\cos\left(x + \frac{\pi}{2}\right) &= \frac{e^{i\left(x + \frac{\pi}{2}\right)} + e^{-i\left(x + \frac{\pi}{2}\right)}}{2} \\
&= \frac{e^{ix} e^{i\frac{\pi}{2}} + e^{-ix} e^{-i\frac{\pi}{2}}}{2} \\
&= \frac{e^{ix}(i) + e^{-ix}(-i)}{2} \\
&= \frac{e^{ix} - e^{-ix}}{-2i} \\
&= -\sin x
\end{aligned}$$

by *Euler formulas*

(Corollary D.2 page 113)

by $e^{\alpha\beta} = e^{\alpha}e^{\beta}$ result

(Theorem D.6 page 113)

by Proposition D.3 page 112

$$\begin{aligned}
\cos\left(x - \frac{\pi}{2}\right) &= \frac{e^{i\left(x - \frac{\pi}{2}\right)} + e^{-i\left(x - \frac{\pi}{2}\right)}}{2} \\
&= \frac{e^{ix} e^{-i\frac{\pi}{2}} + e^{-ix} e^{+i\frac{\pi}{2}}}{2} \\
&= \frac{e^{ix}(-i) + e^{-ix}(i)}{2} \\
&= \frac{e^{ix} - e^{-ix}}{2i} \\
&= \sin x
\end{aligned}$$

by *Euler formulas*

(Corollary D.2 page 113)

by *Euler formulas*

(Corollary D.2 page 113)

by $e^{\alpha\beta} = e^{\alpha}e^{\beta}$ result

(Theorem D.6 page 113)

by Proposition D.3 page 112

$$\begin{aligned}
\sin\left(x + \frac{\pi}{2}\right) &= \cos\left(\left[x + \frac{\pi}{2}\right] - \frac{\pi}{2}\right) \\
&= \cos(x)
\end{aligned}$$

by *Euler formulas*

(Corollary D.2 page 113)

by previous result

$$\begin{aligned}
\sin\left(x - \frac{\pi}{2}\right) &= -\cos\left(\left[x - \frac{\pi}{2}\right] + \frac{\pi}{2}\right) \\
&= -\cos(x)
\end{aligned}$$

by previous result



Theorem D.8 (product identities).T
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$$\begin{aligned}
(A). \quad \cos x \cos y &= \frac{1}{2} \cos(x - y) + \frac{1}{2} \cos(x + y) \quad \forall x, y \in \mathbb{R} \\
(B). \quad \cos x \sin y &= -\frac{1}{2} \sin(x - y) + \frac{1}{2} \sin(x + y) \quad \forall x, y \in \mathbb{R} \\
(C). \quad \sin x \cos y &= \frac{1}{2} \sin(x - y) + \frac{1}{2} \sin(x + y) \quad \forall x, y \in \mathbb{R} \\
(D). \quad \sin x \sin y &= \frac{1}{2} \cos(x - y) - \frac{1}{2} \cos(x + y) \quad \forall x, y \in \mathbb{R}
\end{aligned}$$

 PROOF:

1. Proof for (A) using *Euler formulas* (Corollary D.2 page 113)
(algebraic method requiring *complex number system* \mathbb{C}):

$$\begin{aligned}
\cos x \cos y &= \left(\frac{e^{ix} + e^{-ix}}{2} \right) \left(\frac{e^{iy} + e^{-iy}}{2} \right) && \text{by Euler formulas} && (\text{Corollary D.2 page 113}) \\
&= \frac{e^{i(x+y)} + e^{i(x-y)} + e^{i(-x+y)} + e^{i(-x-y)}}{4} \\
&= \frac{e^{i(x+y)} + e^{-i(x+y)}}{4} + \frac{e^{i(x-y)} + e^{-i(x-y)}}{4} \\
&= \frac{2\cos(x+y)}{4} + \frac{2\cos(x-y)}{4} && \text{by Euler formulas} && (\text{Corollary D.2 page 113}) \\
&= \frac{1}{2} \cos(x+y) + \frac{1}{2} \cos(x-y)
\end{aligned}$$

2. Proof for (A) using *Volterra integral equation* (Theorem D.3 page 110)
(differential equation method requiring only *real number system* \mathbb{R}):

$$\begin{aligned}
f(x) &\triangleq \frac{1}{2} \cos(x-y) + \frac{1}{2} \cos(x+y) \\
\Rightarrow \frac{d}{dx} f(x) &= -\frac{1}{2} \sin(x-y) - \frac{1}{2} \sin(x+y) && \text{by Theorem D.4 page 111} \\
\Rightarrow \frac{d^2}{dx^2} f(x) &= -\frac{1}{2} \cos(x-y) - \frac{1}{2} \cos(x+y) && \text{by Theorem D.4 page 111} \\
\Rightarrow \frac{d^2}{dx^2} f(x) + f(x) &= 0 && \text{by additive inverse property} \\
\Rightarrow \underbrace{\frac{1}{2} \cos(x-y) + \frac{1}{2} \cos(x+y)}_{f(x)} &= \underbrace{[\frac{1}{2} \cos(0-y) + \frac{1}{2} \cos(0+y)] \cos(x)}_{f''(0)} + \underbrace{[-\frac{1}{2} \sin(0-y) - \frac{1}{2} \sin(0+y)] \sin(x)}_{f'(0)} \\
\Rightarrow \frac{1}{2} \cos(x-y) + \frac{1}{2} \cos(x+y) &= \cos y \cos x + 0 \sin(x) \\
\Rightarrow \cos x \cos y &= \frac{1}{2} \cos(x-y) + \frac{1}{2} \cos(x+y)
\end{aligned}$$

3. Proof for (B) using *Euler formulas* (Corollary D.2 page 113):

$$\begin{aligned}
\sin x \sin y &= \left(\frac{e^{ix} - e^{-ix}}{2i} \right) \left(\frac{e^{iy} - e^{-iy}}{2i} \right) && \text{by Corollary D.2 page 113} \\
&= \frac{e^{i(x+y)} - e^{i(x-y)} - e^{i(-x+y)} + e^{i(-x-y)}}{-4} \\
&= \frac{e^{i(x+y)} + e^{-i(x+y)} - e^{i(x-y)} - e^{-i(x-y)}}{-4} \\
&= \frac{e^{i(x+y)} + e^{-i(x+y)}}{-4} - \frac{e^{i(x-y)} + e^{-i(x-y)}}{-4} \\
&= \frac{2\cos(x+y)}{4} - \frac{2\cos(x-y)}{4} \\
&= \frac{1}{2} \cos(x+y) - \frac{1}{2} \cos(x-y)
\end{aligned}$$

by Corollary D.2 page 113

4. Proofs for (C) and (D) using (A) and (B):

$$\begin{aligned}
\cos x \sin y &= \cos(x) \cos\left(y - \frac{\pi}{2}\right) && \text{by shift identities} && (\text{Theorem D.7 page 114}) \\
&= \frac{1}{2} \cos\left(x + y - \frac{\pi}{2}\right) + \frac{1}{2} \cos\left(x - y + \frac{\pi}{2}\right) && \text{by (A)} \\
&= \frac{1}{2} \sin(x + y) - \frac{1}{2} \sin(x - y) && \text{by shift identities} && (\text{Theorem D.7 page 114}) \\
\sin x \cos y &= \cos y \sin x \\
&= \frac{1}{2} \sin(y + x) - \frac{1}{2} \sin(y - x) && \text{by (B)} \\
&= \frac{1}{2} \sin(x + y) + \frac{1}{2} \sin(x - y) && \text{by Theorem D.2 page 109}
\end{aligned}$$

**Proposition D.4.**

P R P	(A). $\cos(\pi) = -1$	(C). $\cos(2\pi) = 1$	(E). $e^{i\pi} = -1$
	(B). $\sin(\pi) = 0$	(D). $\sin(2\pi) = 0$	(F). $e^{i2\pi} = 0$

PROOF:

$$\begin{aligned}
\cos(\pi) &= -1 + 1 + \cos(\pi) \\
&= -1 + 2\left[\frac{1}{2}\cos(\pi/2 - \pi/2) + \frac{1}{2}\cos(\pi/2 + \pi/2)\right] && \text{by } \cos(0) = 1 \text{ result} && (\text{Theorem D.2 page 109}) \\
&= -1 + 2\cos(\pi/2)\cos(\pi/2) && \text{by product identities} && (\text{Theorem D.8 page 114}) \\
&= -1 + 2(0)(0) && \text{by definition of } \pi && (\text{Definition D.3 page 107}) \\
&= -1 \\
\sin(\pi) &= 0 + \sin(\pi) \\
&= 2\left[-\frac{1}{2}\sin(\pi/2 - \pi/2) + \frac{1}{2}\sin(\pi/2 + \pi/2)\right] && \text{by } \sin(0) = 0 \text{ result} && (\text{Theorem D.2 page 109}) \\
&= 2\cos(\pi/2)\sin(\pi/2) && \text{by product identities} && (\text{Theorem D.8 page 114}) \\
&= 2(0)\sin(\pi/2) && \text{by definition of } \pi && (\text{Definition D.3 page 107}) \\
&= 0 \\
\cos(2\pi) &= 1 + \cos(2\pi) - 1 \\
&= 2\left[\frac{1}{2}\cos(\pi - \pi) + \frac{1}{2}\cos(\pi + \pi)\right] - 1 && \text{by } \cos(0) = 1 \text{ result} && (\text{Theorem D.2 page 109}) \\
&= 2\cos(\pi)\cos(\pi) - 1 && \text{by product identities} && (\text{Theorem D.8 page 114}) \\
&= 2(-1)(-1) - 1 && \text{by (A)} \\
&= 1 \\
\sin(2\pi) &= 0 + \sin(2\pi) \\
&= 2\left[\frac{1}{2}\sin(\pi - \pi) + \frac{1}{2}\sin(\pi + \pi)\right] && \text{by } \sin(0) = 0 \text{ result} && (\text{Theorem D.2 page 109}) \\
&= 2\sin(\pi)\cos(\pi) && \text{by product identities} && (\text{Theorem D.8 page 114}) \\
&= 2(0)(-1) && \text{by (A) and (B)} \\
&= 0 \\
e^{i\pi} &= \cos(\pi) + i\sin(\pi) && \text{by Euler's Identity} && (\text{Theorem D.5 page 112}) \\
&= -1 + 0 \\
&= -1 && \text{by (A) and (B)} \\
e^{i2\pi} &= \cos(2\pi) + i\sin(2\pi) && \text{by Euler's Identity} && (\text{Theorem D.5 page 112}) \\
&= 1 + 0 \\
&= 1 && \text{by (C) and (D)}
\end{aligned}$$



Theorem D.9 (double angle formulas). ²⁰T
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(A).	$\cos(x + y) = \cos x \cos y - \sin x \sin y$	$\forall x, y \in \mathbb{R}$
(B).	$\sin(x + y) = \sin x \cos y + \cos x \sin y$	$\forall x, y \in \mathbb{R}$
(C).	$\tan(x + y) = \frac{\tan x + \tan y}{1 - \tan x \tan y}$	$\forall x, y \in \mathbb{R}$

✎ PROOF:

1. Proof for (A) using *product identities* (Theorem D.8 page 114).

$$\begin{aligned}
 \cos(x + y) &= \underbrace{\frac{1}{2}\cos(x + y) + \frac{1}{2}\cos(x + y)}_{\cos(x + y)} + \underbrace{\frac{1}{2}\cos(x - y) - \frac{1}{2}\cos(x - y)}_0 \\
 &= \left[\frac{1}{2}\cos(x - y) + \frac{1}{2}\cos(x + y) \right] - \left[\frac{1}{2}\cos(x - y) - \frac{1}{2}\cos(x + y) \right] \\
 &= \cos x \cos y - \sin x \sin y \qquad \text{by Theorem D.8 page 114}
 \end{aligned}$$

2. Proof for (A) using *Volterra integral equation* (Theorem D.3 page 110):

$$\begin{aligned}
 f(x) \triangleq \cos(x + y) &\implies \frac{d}{dx}f(x) = -\sin(x + y) && \text{by Theorem D.4 page 111} \\
 &\implies \frac{d^2}{dx^2}f(x) = -\cos(x + y) && \text{by Theorem D.4 page 111} \\
 &\implies \frac{d^2}{dx^2}f(x) + f(x) = 0 && \text{by additive inverse property} \\
 &\implies \cos(x + y) = \cos y \cos x - \sin y \sin x && \text{by Theorem D.3 page 110} \\
 &\implies \cos(x + y) = \cos x \cos y - \sin x \sin y && \text{by commutative property}
 \end{aligned}$$

3. Proof for (B) and (C) using (A):

$$\begin{aligned}
 \sin(x + y) &= \cos\left(x - \frac{\pi}{2} + y\right) && \text{by shift identities (Theorem D.7 page 114)} \\
 &= \cos\left(x - \frac{\pi}{2}\right)\cos(y) - \sin\left(x - \frac{\pi}{2}\right)\sin(y) && \text{by (A)} \\
 &= \sin(x)\cos(y) + \cos(x)\sin(y) && \text{by shift identities (Theorem D.7 page 114)}
 \end{aligned}$$

$$\begin{aligned}
 \tan(x + y) &= \frac{\sin(x + y)}{\cos(x + y)} \\
 &= \frac{\sin x \cos y + \cos x \sin y}{\cos x \cos y - \sin x \sin y} && \text{by (A)} \\
 &= \left(\frac{\sin x \cos y + \cos x \sin y}{\cos x \cos y - \sin x \sin y} \right) \left(\frac{\cos x \cos y}{\cos x \cos y} \right) \\
 &= \frac{\frac{\sin x \cos y}{\cos x \cos y} + \frac{\cos x \sin y}{\cos x \cos y}}{\frac{\cos x \cos y}{\cos x \cos y} - \frac{\sin x \sin y}{\cos x \cos y}} = \frac{\frac{\sin x}{\cos x} + \frac{\sin y}{\cos y}}{1 - \frac{\sin x}{\cos x} \frac{\sin y}{\cos y}} = \frac{\tan x + \tan y}{1 - \tan x \tan y}
 \end{aligned}$$

⇒

Theorem D.10 (trigonometric periodicity).T
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(A).	$\cos(x + M\pi) = (-1)^M \cos(x)$	$\forall x \in \mathbb{R}, \quad M \in \mathbb{Z}$	(D).	$\cos(x + 2M\pi) = \cos(x)$	$\forall x \in \mathbb{R}, \quad M \in \mathbb{Z}$
(B).	$\sin(x + M\pi) = (-1)^M \sin(x)$	$\forall x \in \mathbb{R}, \quad M \in \mathbb{Z}$	(E).	$\sin(x + 2M\pi) = \sin(x)$	$\forall x \in \mathbb{R}, \quad M \in \mathbb{Z}$
(C).	$e^{i(x + M\pi)} = (-1)^M e^{ix}$	$\forall x \in \mathbb{R}, \quad M \in \mathbb{Z}$	(F).	$e^{i(x + 2M\pi)} = e^{ix}$	$\forall x \in \mathbb{R}, \quad M \in \mathbb{Z}$

²⁰Expressions for $\cos(\alpha + \beta)$, $\sin(\alpha + \beta)$, and $\sin^2 x$ appear in works as early as **Ptolemy** (circa 100AD). Reference: http://en.wikipedia.org/wiki/History_of_trigonometric_functions

✎ PROOF:

1. Proof for (A):

(a) $M = 0$ case: $\cos(x + 0\pi) = \cos(x) = (-1)^0 \cos(x)$

(b) Proof for $M > 0$ cases (by induction):

i. Base case $M = 1$:

$$\begin{aligned} \cos(x + \pi) &= \cos x \cos \pi - \sin x \sin \pi && \text{by double angle formulas} && (\text{Theorem D.9 page 117}) \\ &= \cos x (-1) - \sin x (0) && \text{by } \cos \pi = -1 \text{ result} && (\text{Proposition D.4 page 116}) \\ &= (-1)^1 \cos x \end{aligned}$$

ii. Inductive step...Proof that M case $\implies M + 1$ case:

$$\begin{aligned} \cos(x + [M + 1]\pi) &= \cos([x + \pi] + M\pi) \\ &= (-1)^M \cos(x + \pi) && \text{by induction hypothesis (M case)} \\ &= (-1)^M (-1) \cos(x) && \text{by base case (item (1b)i) page 118} \\ &= (-1)^{M+1} \cos(x) \\ &\implies M + 1 \text{ case} \end{aligned}$$

(c) Proof for $M < 0$ cases: Let $N \triangleq -M \dots \implies N > 0$.

$$\begin{aligned} \cos(x + M\pi) &\triangleq \cos(x - N\pi) && \text{by definition of } N \\ &= \cos(x) \cos(-N\pi) - \sin(x) \sin(-N\pi) && \text{by double angle formulas} && (\text{Theorem D.9 page 117}) \\ &= \cos(x) \cos(N\pi) + \sin(x) \sin(N\pi) && \text{by Theorem D.2 page 109} \\ &= \cos(x) \cos(0 + N\pi) + \sin(x) \sin(0 + N\pi) \\ &= \cos(x) (-1)^N \cos(0) + \sin(x) (-1)^N \sin(0) && \text{by } M \geq 0 \text{ results} && (\text{item (1b) page 118}) \\ &= (-1)^N \cos(x) && \text{by } \cos(0)=1, \sin(0)=0 \text{ results} && (\text{Theorem D.2 page 109}) \\ &\triangleq (-1)^{-M} \cos(x) && \text{by definition of } N \\ &= (-1)^M \cos(x) \end{aligned}$$

(d) Proof using complex exponential:

$$\begin{aligned} \cos(x + M\pi) &= \frac{e^{i(x+M\pi)} + e^{-i(x+M\pi)}}{2} && \text{by Euler formulas} && (\text{Corollary D.2 page 113}) \\ &= e^{iM\pi} \left[\frac{e^{ix} + e^{-ix}}{2} \right] && \text{by } e^{\alpha\beta} = e^\alpha e^\beta \text{ result} && (\text{Theorem D.6 page 113}) \\ &= (e^{i\pi})^M \cos x && \text{by Euler formulas} && (\text{Corollary D.2 page 113}) \\ &= (-1)^M \cos x && \text{by } e^{i\pi} = -1 \text{ result} && (\text{Proposition D.4 page 116}) \end{aligned}$$

2. Proof for (B):

(a) $M = 0$ case: $\sin(x + 0\pi) = \sin(x) = (-1)^0 \sin(x)$

(b) Proof for $M > 0$ cases (by induction):

i. Base case $M = 1$:

$$\begin{aligned} \sin(x + \pi) &= \sin x \cos \pi + \cos x \sin \pi && \text{by double angle formulas} && (\text{Theorem D.9 page 117}) \\ &= \sin x (-1) - \cos x (0) && \text{by } \sin \pi = 0 \text{ results} && (\text{Proposition D.4 page 116}) \\ &= (-1)^1 \sin x \end{aligned}$$

ii. Inductive step...Proof that M case $\implies M + 1$ case:

$$\begin{aligned}
 \sin(x + [M + 1]\pi) &= \sin([x + \pi] + M\pi) \\
 &= (-1)^M \sin(x + \pi) && \text{by induction hypothesis (M case)} \\
 &= (-1)^M (-1) \sin(x) && \text{by base case (item (2b)i) page 118} \\
 &= (-1)^{M+1} \sin(x) \\
 &\implies M + 1 \text{ case}
 \end{aligned}$$

(c) Proof for $M < 0$ cases: Let $N \triangleq -M \dots \implies N > 0$.

$$\begin{aligned}
 \sin(x + M\pi) &\triangleq \sin(x - N\pi) && \text{by definition of } N \\
 &= \sin(x)\sin(-N\pi) - \sin(x)\sin(-N\pi) && \text{by double angle formulas (Theorem D.9 page 117)} \\
 &= \sin(x)\sin(N\pi) + \sin(x)\sin(N\pi) && \text{by Theorem D.2 page 109} \\
 &= \sin(x)\sin(0 + N\pi) + \sin(x)\sin(0 + N\pi) \\
 &= \sin(x)(-1)^N \sin(0) + \sin(x)(-1)^N \sin(0) && \text{by } M \geq 0 \text{ results (item (2b) page 118)} \\
 &= (-1)^N \sin(x) && \text{by } \sin(0)=1, \sin(0)=0 \text{ results (Theorem D.2 page 109)} \\
 &\triangleq (-1)^{-M} \sin(x) && \text{by definition of } N \\
 &= (-1)^M \sin(x)
 \end{aligned}$$

(d) Proof using complex exponential:

$$\begin{aligned}
 \sin(x + M\pi) &= \frac{e^{i(x+M\pi)} - e^{-i(x+M\pi)}}{2i} && \text{by Euler formulas (Corollary D.2 page 113)} \\
 &= e^{iM\pi} \left[\frac{e^{ix} - e^{-ix}}{2i} \right] && \text{by } e^{\alpha\beta} = e^\alpha e^\beta \text{ result (Theorem D.6 page 113)} \\
 &= (e^{i\pi})^M \sin x && \text{by Euler formulas (Corollary D.2 page 113)} \\
 &= (-1)^M \sin x && \text{by } e^{i\pi} = -1 \text{ result (Proposition D.4 page 116)}
 \end{aligned}$$

3. Proof for (C):

$$\begin{aligned}
 e^{i(x+M\pi)} &= e^{iM\pi} e^{ix} && \text{by } e^{\alpha\beta} = e^\alpha e^\beta \text{ result (Theorem D.6 page 113)} \\
 &= (e^{i\pi})^M (e^{ix}) \\
 &= (-1)^M e^{ix} && \text{by } e^{i\pi} = -1 \text{ result (Proposition D.4 page 116)}
 \end{aligned}$$

4. Proofs for (D), (E), and (F):

$$\begin{aligned}
 \cos(i(x + 2M\pi)) &= (-1)^{2M} \cos(ix) = \cos(ix) && \text{by (A)} \\
 \sin(i(x + 2M\pi)) &= (-1)^{2M} \sin(ix) = \sin(ix) && \text{by (B)} \\
 e^{i(x+2M\pi)} &= (-1)^{2M} e^{ix} = e^{ix} && \text{by (C)}
 \end{aligned}$$


Theorem D.11 (half-angle formulas/squared identities).

T H M	(A). $\cos^2 x = \frac{1}{2}(1 + \cos 2x) \quad \forall x \in \mathbb{R}$	(C). $\cos^2 x + \sin^2 x = 1 \quad \forall x \in \mathbb{R}$
	(B). $\sin^2 x = \frac{1}{2}(1 - \cos 2x) \quad \forall x \in \mathbb{R}$	

PROOF:

$$\begin{aligned}
 \cos^2 x &\triangleq (\cos x)(\cos x) = \frac{1}{2}\cos(x - x) + \frac{1}{2}\cos(x + x) && \text{by product identities (Theorem D.8 page 114)} \\
 &= \frac{1}{2}[1 + \cos(2x)] && \text{by } \cos(0) = 1 \text{ result (Theorem D.2 page 109)} \\
 \sin^2 x &= (\sin x)(\sin x) = \frac{1}{2}\cos(x - x) - \frac{1}{2}\cos(x + x) && \text{by product identities (Theorem D.8 page 114)} \\
 &= \frac{1}{2}[1 - \cos(2x)] && \text{by } \cos(0) = 1 \text{ result (Theorem D.2 page 109)} \\
 \cos^2 x + \sin^2 x &= \frac{1}{2}[1 + \cos(2x)] + \frac{1}{2}[1 - \cos(2x)] = 1 && \text{by (A) and (B)} \\
 &&& \text{note: see also Theorem D.4 page 111}
 \end{aligned}$$



D.6 Planar Geometry

The harmonic functions $\cos(x)$ and $\sin(x)$ are *orthogonal* to each other in the sense

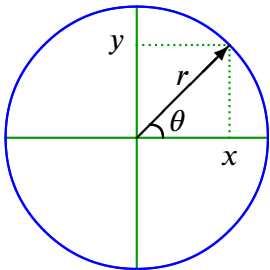
$$\begin{aligned}
 \langle \cos(x) | \sin(x) \rangle &= \int_{-\pi}^{+\pi} \cos(x) \sin(x) \, dx \\
 &= \frac{1}{2} \int_{-\pi}^{+\pi} \sin(x-x) \, dx + \frac{1}{2} \int_{-\pi}^{+\pi} \sin(x+x) \, dx && \text{by Theorem D.8 page 114} \\
 &= \frac{1}{2} \int_{-\pi}^{+\pi} \sin(0) \, dx + \frac{1}{2} \int_{-\pi}^{+\pi} \sin(2x) \, dx \\
 &= -\frac{1}{2} \cdot \frac{1}{2} \cos(2x) \Big|_{-\pi}^{+\pi} \cos(2x) \\
 &= -\frac{1}{4} [\cos(2\pi) - \cos(-2\pi)] \\
 &= 0
 \end{aligned}$$

Because $\cos(x)$ and $\sin(x)$ are orthogonal, they can be conveniently represented by the x and y axes in a plane—because perpendicular axes in a plane are also orthogonal. Vectors in the plane can be represented by linear combinations of $\cos x$ and $\sin x$. Let $\tan x$ be defined as

$$\tan x \triangleq \frac{\sin x}{\cos x}.$$

We can also define a value θ to represent the angle between such a vector and the x -axis such that

$$\theta = \tan^{-1} \left(\frac{\sin \theta}{\cos \theta} \right)$$



$$\begin{array}{ll}
 \cos \theta & \triangleq \frac{x}{r} & \sec \theta & \triangleq \frac{r}{x} \\
 \sin \theta & \triangleq \frac{y}{r} & \csc \theta & \triangleq \frac{r}{y} \\
 \tan \theta & \triangleq \frac{y}{x} & \cot \theta & \triangleq \frac{x}{y}
 \end{array}$$

D.7 Trigonometric functions of complex numbers

Definition D.5. ²¹

DEF	$\cosh(z) \triangleq \frac{e^z + e^{-z}}{2} \quad \forall z \in \mathbb{C}$
	$\sinh(z) \triangleq \frac{e^z - e^{-z}}{2} \quad \forall z \in \mathbb{C}$

²¹ Saxelby (1920) page 225

Theorem D.12. ²²T
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$\cosh(ix)$	$=$	$\cos(x)$	$\forall x \in \mathbb{R}$
$\sinh(ix)$	$=$	$i \sin(x)$	$\forall x \in \mathbb{R}$
$\cos(ix)$	$=$	$\cosh(x)$	$\forall x \in \mathbb{R}$
$\sin(ix)$	$=$	$i \sinh(x)$	$\forall x \in \mathbb{R}$
$\cos(x + iy)$	$=$	$\cos(x)\cosh(y) - i\sin(x)\sinh(y)$	$\forall x, y \in \mathbb{R}$
$\sin(x + iy)$	$=$	$\sin(x)\cosh(y) + i\cos(x)\sinh(y)$	$\forall x, y \in \mathbb{R}$

✎ PROOF:

$$\cosh(ix) \triangleq \frac{e^{ix} + e^{-ix}}{2}$$

$$= \cos(x)$$

by definition of $\cosh(x)$

(Definition D.5 page 120)

$$\sinh(ix) \triangleq \frac{e^{ix} - e^{-ix}}{2}$$

by *Euler's Identity*

(Theorem D.5 page 112)

$$\triangleq i \left[\frac{e^{ix} - e^{-ix}}{2i} \right]$$

by definition of $\sinh(x)$

(Definition D.5 page 120)

$$= i \sin(x)$$

by definition of $\sinh(x)$

(Definition D.5 page 120)

by *Euler's Identity*

(Theorem D.5 page 112)

$$\cos(ix) \triangleq \frac{e^{iix} + e^{-iix}}{2}$$

by *Euler's Identity*

(Theorem D.5 page 112)

$$= \frac{e^{-x} + e^x}{2}$$

$$= \frac{e^x + e^{-x}}{2}$$

$$\triangleq \cosh(x)$$

by definition of $\cosh(x)$

(Definition D.5 page 120)

$$\sin(ix) \triangleq \frac{e^{iix} - e^{-iix}}{2i}$$

by *Euler's Identity*

(Theorem D.5 page 112)

$$= \frac{e^{-x} - e^x}{2i}$$

$$= -(-i^2) \left[\frac{e^x - e^{-x}}{2i} \right]$$

$$= i \left[\frac{e^x - e^{-x}}{2} \right]$$

$$\triangleq i \sinh(x)$$

by definition of $\cosh(x)$

(Definition D.5 page 120)

$$\cos(x + iy) = \cos(x)\cos(iy) - \sin(x)\sin(iy)$$

by *double angle formulas*

(Theorem D.9 page 117)

$$= \cos(x)\cosh(y) - i\sin(x)\sinh(y)$$

by previous results

$$\sin(x + iy) = \sin(x)\cos(iy) + \cos(x)\sin(iy)$$

by *double angle formulas*

(Theorem D.9 page 117)

$$= \sin(x)\cosh(y) + i\cos(x)\sinh(y)$$

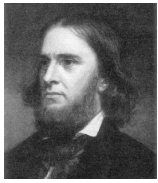
by previous results



²²https://proofwiki.org/wiki/Cosine_of_Complex_Number, https://proofwiki.org/wiki/Sine_of_Complex_Number, Saxelby (1920) pages 416–417



D.8 The power of the exponential



“Gentlemen, that is surely true, it is absolutely paradoxical; we cannot understand it, and we don't know what it means. But we have proved it, and therefore we know it must be the truth.”

Benjamin Peirce (1809–1880), American Harvard University mathematician after proving $e^{i\pi} = -1$ in a lecture. ²³



“Young man, in mathematics you don't understand things. You just get used to them.”

John von Neumann (1903–1957), Hungarian-American mathematician, as allegedly told to Gary Zukav by Felix T. Smith, Head of Molecular Physics at Stanford Research Institute, about a “physicist friend”. ²⁴

The following corollary presents one of the most amazing relations in all of mathematics. It shows a simple and compact relationship between the transcendental numbers π and e , the imaginary number i , and the additive and multiplicative identity elements 0 and 1. The fact that there is any relationship at all is somewhat amazing; but for there to be such an elegant one is truly one of the wonders of the world of numbers.

Corollary D.3. ²⁵

COR

 $e^{i\pi} + 1 = 0$

PROOF:

$$\begin{aligned} e^{ix} \Big|_{x=\pi} &= [\cos x + i \sin x]_{x=\pi} \\ &= -1 + i \cdot 0 \\ &= -1 \end{aligned}$$

by Euler's Identity (Theorem D.5 page 112)

by Proposition D.4 page 116

⇒

There are many transforms available, several of them integral transforms $[Af](s) \triangleq \int_t f(s)\kappa(t, s) \, ds$ using different kernels $\kappa(t, s)$. But of all of them, two of the most often used themselves use an exponential kernel:

- ① The *Laplace Transform* with kernel $\kappa(t, s) \triangleq e^{st}$
- ② The *Fourier Transform* with kernel $\kappa(t, \omega) \triangleq e^{i\omega t}$.

²³ quote: Kasner and Newman (1940) page 104

image: http://www-history.mcs.st-andrews.ac.uk/history/PictDisplay/Peirce_Benjamin.html


²⁴ quote: Zukav (1980) page 208


image: http://en.wikipedia.org/wiki/John_von_Neumann

The quote appears in a footnote in Zukav (1980) that reads like this: Dr. Felix Smith, Head of Molecular Physics, Stanford Research Institute, once related to me the true story of a physicist friend who worked at Los Alamos after World War II. Seeking help on a difficult problem, he went to the great Hungarian mathematician, John von Neumann, who was at Los Alamos as a consultant. “Simple,” said von Neumann. “This can be solved by using the method of characteristics.” After the explanation the physicist said, “I’m afraid I don’t understand the method of characteristics.” “Young man,” said von Neumann, “in mathematics you don’t understand things, you just get used to them.”

²⁵ Euler (1748), Euler (1988) (chapter 8?), http://www.daviddarling.info/encyclopedia/E/Eulers_formula.html

Of course, the Fourier kernel is just a special case of the Laplace kernel with $s = i\omega$ ($i\omega$ is a unit circle in s if s is depicted as a plane with real and imaginary axes). What is so special about exponential kernels? Is it just that they were discovered sooner than other kernels with other transforms? The answer in general is “no”. The exponential has two properties that makes it extremely special:

 The exponential is an eigenvalue of any *linear time invariant* (LTI) operator (Theorem D.13 page 123).

 The exponential generates a *continuous point spectrum* for the *differential operator*.

Theorem D.13. ²⁶ Let \mathbf{L} be an operator with kernel $h(t, \omega)$ and
 $\check{h}(s) \triangleq \langle h(t, \omega) | e^{st} \rangle$ (LAPLACE TRANSFORM).

T H M	$\left\{ \begin{array}{l} 1. \quad \mathbf{L} \text{ is LINEAR and} \\ 2. \quad \mathbf{L} \text{ is TIME-INVARIANT} \end{array} \right\} \implies \left\{ \mathbf{L}e^{st} = \underbrace{\check{h}^*(-s)}_{\text{eigenvalue}} \underbrace{e^{st}}_{\text{eigenvector}} \right\}$
----------------------	---

 PROOF:

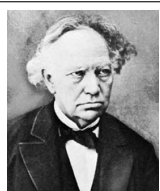
$\begin{aligned} [\mathbf{L}e^{st}](s) &= \langle e^{su} h(t; u), s \rangle \\ &= \langle e^{su} h(t - u, s) \rangle \\ &= \langle e^{s(t-v)} h(v, s) \rangle \\ &= e^{st} \langle e^{-sv} h(v, s) \rangle \\ &= \langle h(v, s) e^{-sv} \rangle^* e^{st} \\ &= \langle h(v, s) e^{(-s)v} \rangle^* e^{st} \\ &= \check{h}^*(-s) e^{st} \end{aligned}$	<p>by linear hypothesis</p> <p>by time-invariance hypothesis</p> <p>let $v = t - u \implies u = t - v$</p> <p>by additivity of $\langle \Delta \nabla \rangle$</p> <p>by conjugate symmetry of $\langle \Delta \nabla \rangle$</p> <p>by definition of $\check{h}(s)$</p>
--	---

⇒

²⁶  Mallat (1999) page 2, ...page 2 online: <http://www.cmap.polytechnique.fr/~mallat/WTintro.pdf>

APPENDIX E

TRIGONOMETRIC POLYNOMIALS



“I turn aside with a shudder of horror from this lamentable plague of functions which have no derivatives.”

Charles Hermite (1822 – 1901), French mathematician, in an 1893 letter to Stieltjes, in response to the “pathological” everywhere continuous but nowhere differentiable *Weierstrass functions* $f(x) = \sum_{n=0}^{\infty} a^n \cos(b^n \pi x)$.¹

E.1 Trigonometric expansion

Theorem E.1 (DeMoivre's Theorem).

T H M $(re^{ix})^n = r^n(\cos nx + i \sin nx) \quad \forall r, x \in \mathbb{R}$

PROOF:

$$\begin{aligned} (re^{ix})^n &= r^n e^{inx} \\ &= r^n (\cos nx + i \sin nx) \end{aligned} \quad \text{by Euler's identity (Theorem D.5 page 112)}$$



The cosine with argument nx can be expanded as a polynomial in $\cos(x)$ (next).

Theorem E.2 (trigonometric expansion).²

¹ quote: Hermite (1893)
translation: Lakatos (1976) page 19
image: <http://www-groups.dcs.sx-and.ac.uk/~history/PictDisplay/Hermite.html>
² Rivlin (1974) page 3 (1.8)

$$\begin{aligned}\cos(nx) &= \sum_{k=0}^{\lfloor \frac{n}{2} \rfloor} \sum_{m=0}^k (-1)^{k+m} \binom{n}{2k} \binom{k}{m} (\cos x)^{n-2(k-m)} & \forall n \in \mathbb{W} \text{ and } x \in \mathbb{R} \\ \sin(nx) &= \sum_{k=0}^{\lfloor \frac{n}{2} \rfloor} \sum_{m=0}^k (-1)^{k+m} \binom{n}{2k} \binom{k}{m} (\sin x)^{n-2(k-m)} & \forall n \in \mathbb{W} \text{ and } x \in \mathbb{R}\end{aligned}$$

 PROOF:

$$\begin{aligned}\cos(nx) &= \Re(\cos nx + i \sin nx) \\ &= \Re(e^{inx}) \\ &= \Re[(e^{ix})^n] \\ &= \Re[(\cos x + i \sin x)^n] \\ &= \Re \left[\sum_{k \in \mathbb{Z}} \binom{n}{k} (\cos x)^{n-k} (i \sin x)^k \right] \\ &= \Re \left[\sum_{k \in \mathbb{Z}} i^k \binom{n}{k} \cos^{n-k} x \sin^k x \right] \\ &= \Re \left[\sum_{k \in \{0, 4, \dots, n\}} \binom{n}{k} \cos^{n-k} x \sin^k x + i \sum_{k \in \{1, 5, \dots, n\}} \binom{n}{k} \cos^{n-k} x \sin^k x \right. \\ &\quad \left. - \sum_{k \in \{2, 6, \dots, n\}} \binom{n}{k} \cos^{n-k} x \sin^k x + -i \sum_{k \in \{3, 7, \dots, n\}} \binom{n}{k} \cos^{n-k} x \sin^k x \right] \\ &= \sum_{k \in \{0, 4, \dots, n\}} \binom{n}{k} \cos^{n-k} x \sin^k x - \sum_{k \in \{2, 6, \dots, n\}} \binom{n}{k} \cos^{n-k} x \sin^k x \\ &= \sum_{k \in \{0, 2, \dots, n\}} \binom{n}{k} (-1)^{\frac{k}{2}} \cos^{n-k} x \sin^k x \\ &= \sum_{k=0}^{\lfloor \frac{n}{2} \rfloor} \binom{n}{2k} (-1)^k \cos^{n-2k} x \sin^{2k} x \\ &= \sum_{k=0}^{\lfloor \frac{n}{2} \rfloor} \binom{n}{2k} (-1)^k \cos^{n-2k} x (1 - \cos^2 x)^k \\ &= \left[\sum_{k=0}^{\lfloor \frac{n}{2} \rfloor} \binom{n}{2k} (-1)^k \cos^{n-2k} x \right] \left[\sum_{m=0}^k \binom{k}{m} (-1)^m \cos^{2m} x \right] \\ &= \sum_{k=0}^{\lfloor \frac{n}{2} \rfloor} \sum_{m=0}^k (-1)^{k+m} \binom{n}{2k} \binom{k}{m} \cos^{n-2(k-m)} x\end{aligned}$$

$$\begin{aligned}\sin(nx) &= \cos\left(nx - \frac{\pi}{2}\right) \\ &= \cos\left(n \left[x - \frac{\pi}{2n}\right]\right) \\ &= \sum_{k=0}^{\lfloor \frac{n}{2} \rfloor} \sum_{m=0}^k (-1)^{k+m} \binom{n}{2k} \binom{k}{m} \cos^{n-2(k-m)} \left(x - \frac{\pi}{2n}\right)\end{aligned}$$

$$\begin{aligned}
&= \sum_{k=0}^{\lfloor \frac{n}{2} \rfloor} \sum_{m=0}^k (-1)^{k+m} \binom{n}{2k} \binom{k}{m} \cos^{n-2(k-m)} \left(nx - \frac{\pi}{2} \right) \\
&= \sum_{k=0}^{\lfloor \frac{n}{2} \rfloor} \sum_{m=0}^k (-1)^{k+m} \binom{n}{2k} \binom{k}{m} \sin^{n-2(k-m)} (nx)
\end{aligned}$$



Example E.1.

E X	$\cos 5x = 16\cos^5 x - 20\cos^3 x + 5\cos x$
	$\sin 5x = 16\sin^5 x - 20\sin^3 x + 5\sin x.$

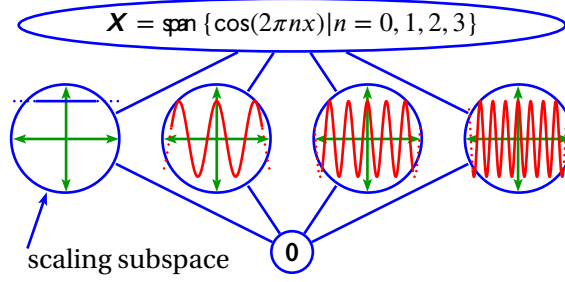
PROOF:

1. Proof using *DeMoivre's Theorem* (Theorem E.1 page 125):

$$\begin{aligned}
&\cos 5x + i \sin 5x \\
&= e^{i5x} \\
&= (e^{ix})^5 \\
&= (\cos x + i \sin x)^5 \\
&= \sum_{k=0}^5 \binom{5}{k} [\cos x]^{5-k} [i \sin x]^k \\
&= \binom{5}{0} [\cos x]^{5-0} [i \sin x]^0 + \binom{5}{1} [\cos x]^{5-1} [i \sin x]^1 + \binom{5}{2} [\cos x]^{5-2} [i \sin x]^2 + \\
&\quad \binom{5}{3} [\cos x]^{5-3} [i \sin x]^3 + \binom{5}{4} [\cos x]^{5-4} [i \sin x]^4 + \binom{5}{5} [\cos x]^{5-5} [i \sin x]^5 \\
&= 1\cos^5 x + i5\cos^4 x \sin x - 10\cos^3 x \sin^2 x - i10\cos^2 x \sin^3 x + 5\cos x \sin^4 x + i1\sin^5 x \\
&= [\cos^5 x - 10\cos^3 x \sin^2 x + 5\cos x \sin^4 x] + i [5\cos^4 x \sin x - 10\cos^2 x \sin^3 x + \sin^5 x] \\
&= [\cos^5 x - 10\cos^3 x(1 - \cos^2 x) + 5\cos x(1 - \cos^2 x)(1 - \cos^2 x)] + \\
&\quad i [5(1 - \sin^2 x)(1 - \sin^2 x)\sin x - 10(1 - \sin^2 x)\sin^3 x + \sin^5 x] \\
&= [\cos^5 x - 10(\cos^3 x - \cos^5 x) + 5\cos x(1 - 2\cos^2 x + \cos^4 x)] + \\
&\quad i [5(1 - 2\sin^2 x + \sin^4 x)\sin x - 10(\sin^3 x - \sin^5 x) + \sin^5 x] \\
&= [\cos^5 x - 10(\cos^3 x - \cos^5 x) + 5(\cos x - 2\cos^3 x + \cos^5 x)] + \\
&\quad i [5(\sin x - 2\sin^3 x + \sin^5 x) - 10(\sin^3 x - \sin^5 x) + \sin^5 x] \\
&= \underbrace{[16\cos^5 x - 20\cos^3 x + 5\cos x]}_{\cos 5x} + i \underbrace{[16\sin^5 x - 20\sin^3 x + 5\sin x]}_{\sin 5x}
\end{aligned}$$

2. Proof using trigonometric expansion (Theorem E.2 page 125):

$$\begin{aligned}
\cos 5x &= \sum_{k=0}^{\lfloor \frac{5}{2} \rfloor} \sum_{m=0}^k (-1)^{k+m} \binom{5}{2k} \binom{k}{m} (\cos x)^{5-2(k-m)} \\
&= \sum_{k=0}^2 \sum_{m=0}^k (-1)^{k+m} \binom{5}{2k} \binom{k}{m} (\cos x)^{5-2(k-m)} \\
&= (-1)^0 \binom{5}{0} \binom{0}{0} \cos^5 x + (-1)^1 \binom{5}{2} \binom{1}{0} \cos^3 x + (-1)^2 \binom{5}{4} \binom{2}{1} \cos^5 x + \\
&\quad (-1)^2 \binom{5}{4} \binom{2}{0} \cos^1 x + (-1)^3 \binom{5}{6} \binom{3}{1} \cos^3 x + (-1)^4 \binom{5}{8} \binom{4}{2} \cos^5 x
\end{aligned}$$

Figure E.1: Lattice of harmonic cosines $\{\cos(nx) | n = 0, 1, 2, \dots\}$

$$\begin{aligned}
 &= +(1)(1)\cos^5 x - (10)(1)\cos^3 x + (10)(1)\cos^5 x + (5)(1)\cos x - (5)(2)\cos^3 x + (5)(1)\cos^5 x \\
 &= +(1 + 10 + 5)\cos^5 x + (-10 - 10)\cos^3 x + 5\cos x \\
 &= 16\cos^5 x - 20\cos^3 x + 5\cos x
 \end{aligned}$$

⇒

Example E.2. ³

E	X	n	$\cos nx$	polynomial in $\cos x$	n	$\cos nx$	polynomial in $\cos x$
		0	$\cos 0x = 1$		4	$\cos 4x = 8\cos^4 x - 8\cos^2 x + 1$	
		1	$\cos 1x = \cos^1 x$		5	$\cos 5x = 16\cos^5 x - 20\cos^3 x + 5\cos x$	
		2	$\cos 2x = 2\cos^2 x - 1$		6	$\cos 6x = 32\cos^6 x - 48\cos^4 x + 18\cos^2 x - 1$	
		3	$\cos 3x = 4\cos^3 x - 3\cos x$		7	$\cos 7x = 64\cos^7 x - 112\cos^5 x + 56\cos^3 x - 7\cos x$	

✎ PROOF:

$$\begin{aligned}
 \cos 2x &= \sum_{k=0}^{\lfloor \frac{2}{2} \rfloor} \sum_{m=0}^k (-1)^{k+m} \binom{3}{2k} \binom{k}{m} (\cos x)^{2-2(k-m)} \\
 &= (-1)^0 \binom{3}{0} \binom{0}{0} \cos^2 x + (-1)^1 \binom{3}{2} \binom{1}{0} \cos^0 x + (-1)^2 \binom{3}{2} \binom{1}{1} \cos^2 x \\
 &= +(1)(1)\cos^2 x - (1)(1) + (1)(1)\cos^2 x \\
 &= 2\cos^2 x - 1
 \end{aligned}$$

$$\begin{aligned}
 \cos 3x &= \sum_{k=0}^{\lfloor \frac{3}{2} \rfloor} \sum_{m=0}^k (-1)^{k+m} \binom{3}{2k} \binom{k}{m} (\cos x)^{3-2(k-m)} \\
 &= (-1)^0 \binom{3}{0} \binom{0}{0} \cos^3 x + (-1)^1 \binom{3}{2} \binom{1}{0} \cos^1 x + (-1)^2 \binom{3}{2} \binom{1}{1} \cos^3 x \\
 &= +\binom{3}{0} \binom{0}{0} \cos^3 x - \binom{3}{2} \binom{1}{0} \cos^1 x + \binom{3}{2} \binom{1}{1} \cos^3 x \\
 &= +(1)(1)\cos^3 x - (3)(1)\cos^1 x + (3)(1)\cos^3 x \\
 &= 4\cos^3 x - 3\cos x
 \end{aligned}$$

$$\cos 4x = \sum_{k=0}^{\lfloor \frac{4}{2} \rfloor} \sum_{m=0}^k (-1)^{k+m} \binom{4}{2k} \binom{k}{m} (\cos x)^{4-2(k-m)}$$

³ Abramowitz and Stegun (1972) page 795, Guillemin (1957) page 593 ((21)), Sloane (2014) (<http://oeis.org/A039991>), Sloane (2014) (<http://oeis.org/A028297>)

$$\begin{aligned}
&= \sum_{k=0}^2 \sum_{m=0}^k (-1)^{k+m} \binom{4}{2k} \binom{k}{m} (\cos x)^{4-2(k-m)} \\
&= (-1)^{0+0} \binom{4}{2 \cdot 0} \binom{0}{0} (\cos x)^{4-2(0-0)} + (-1)^{1+0} \binom{4}{2 \cdot 1} \binom{1}{0} (\cos x)^{4-2(1-0)} \\
&\quad + (-1)^{1+1} \binom{4}{2 \cdot 1} \binom{1}{1} (\cos x)^{4-2(1-1)} + (-1)^{2+0} \binom{4}{2 \cdot 2} \binom{2}{0} (\cos x)^{4-2(2-0)} \\
&\quad + (-1)^{2+1} \binom{4}{2 \cdot 2} \binom{2}{1} (\cos x)^{4-2(2-1)} + (-1)^{2+2} \binom{4}{2 \cdot 2} \binom{2}{2} (\cos x)^{4-2(2-2)} \\
&= (1)(1)\cos^4 x - (6)(1)\cos^2 x + (6)(1)\cos^4 x + (1)(1)\cos^0 x - (1)(2)\cos^2 x + (1)(1)\cos^4 x \\
&= 8\cos^4 x - 8\cos^2 x + 1
\end{aligned}$$

$$\cos 5x = 16\cos^5 x - 20\cos^3 x + 5\cos x \quad \text{see Example E.1 page 127}$$

$$\begin{aligned}
\cos 6x &= \sum_{k=0}^{\lfloor \frac{6}{2} \rfloor} \sum_{m=0}^k (-1)^{k+m} \binom{6}{2k} \binom{k}{m} (\cos x)^{6-2(k-m)} \\
&= (-1)^0 \binom{6}{0} \binom{0}{0} \cos^6 x + (-1)^1 \binom{6}{2} \binom{1}{0} \cos^4 x + (-1)^2 \binom{6}{2} \binom{1}{1} \cos^6 x + (-1)^2 \binom{6}{4} \binom{2}{0} \cos^2 x + \\
&\quad (-1)^3 \binom{6}{4} \binom{2}{1} \cos^4 x + (-1)^4 \binom{6}{4} \binom{2}{2} \cos^6 x + (-1)^3 \binom{6}{6} \binom{3}{0} \cos^0 x + (-1)^4 \binom{6}{6} \binom{3}{1} \cos^2 x + \\
&\quad (-1)^5 \binom{6}{6} \binom{3}{2} \cos^4 x + (-1)^6 \binom{6}{6} \binom{3}{3} \cos^6 x \\
&= + (1)(1)\cos^6 x - (15)(1)\cos^4 x + (15)(1)\cos^6 x + (15)(1)\cos^2 x - (15)(2)\cos^4 x + (15)(1)\cos^6 x \\
&\quad - (1)(1)\cos^0 x + (1)(3)\cos^2 x - (1)(3)\cos^4 x + (1)(1)\cos^6 x \\
&= 32\cos^6 x - 48\cos^4 x + 18\cos^2 x - 1
\end{aligned}$$

$$\begin{aligned}
\cos 7x &= \sum_{k=0}^{\lfloor \frac{7}{2} \rfloor} \sum_{m=0}^k (-1)^{k+m} \binom{7}{2k} \binom{k}{m} (\cos x)^{7-2(k-m)} \\
&= \sum_{k=0}^3 \sum_{m=0}^k (-1)^{k+m} \binom{7}{2k} \binom{k}{m} (\cos x)^{7-2(k-m)} \\
&= (-1)^0 \binom{7}{0} \binom{0}{0} \cos^7 x + (-1)^1 \binom{7}{2} \binom{1}{0} \cos^5 x + (-1)^2 \binom{7}{2} \binom{1}{1} \cos^7 x + (-1)^2 \binom{7}{4} \binom{2}{0} \cos^3 x \\
&\quad + (-1)^3 \binom{7}{4} \binom{2}{1} \cos^5 x + (-1)^4 \binom{7}{4} \binom{2}{2} \cos^7 x + (-1)^3 \binom{7}{6} \binom{3}{0} \cos^1 x + (-1)^4 \binom{7}{6} \binom{3}{1} \cos^3 x \\
&\quad + (-1)^5 \binom{7}{6} \binom{3}{2} \cos^5 x + (-1)^6 \binom{7}{6} \binom{3}{3} \cos^7 x \\
&= (1)(1)\cos^7 x - (21)(1)\cos^5 x + (21)(1)\cos^7 x + (35)(1)\cos^3 x \\
&\quad - (35)(2)\cos^5 x + (35)(1)\cos^7 x - (7)(1)\cos^1 x + (7)(3)\cos^3 x \\
&\quad - (7)(3)\cos^5 x + (7)(1)\cos^7 x \\
&= (1 + 21 + 35 + 7)\cos^7 x - (21 + 70 + 21)\cos^5 x + (35 + 21)\cos^3 x - (7)\cos^1 x \\
&= 64\cos^7 x - 112\cos^5 x + 56\cos^3 x - 7\cos x
\end{aligned}$$

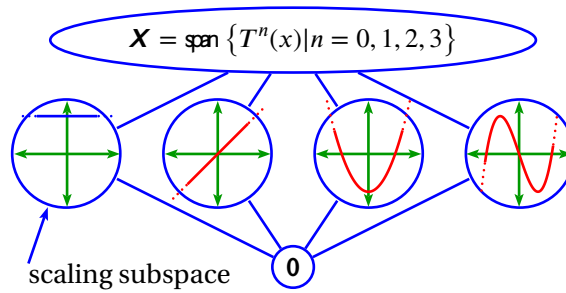


Figure E.2: Lattice of Chebyshev polynomials $\{T_n(x) | n = 0, 1, 2, 3\}$

Note: Trigonometric expansion of $\cos(nx)$ for particular values of n can also be performed with the free software package *Maxima*TM using the syntax illustrated to the right:⁴

```
1 trigexpand(cos(2*x));
2 trigexpand(cos(3*x));
3 trigexpand(cos(4*x));
4 trigexpand(cos(5*x));
5 trigexpand(cos(6*x));
6 trigexpand(cos(7*x));
```

Definition E.1.

DEF The n th **Chebyshev polynomial of the first kind** is defined as

$$T_n(x) \triangleq \cos nx \quad \text{where} \quad \cos x \triangleq x$$

Theorem E.3.⁵ Let $T_n(x)$ be a CHEBYSHEV POLYNOMIAL with $n \in \mathbb{W}$.

THM n is EVEN $\implies T_n(x)$ is EVEN.
 n is ODD $\implies T_n(x)$ is ODD.

Example E.3. Let $T_n(x)$ be a Chebyshev polynomial with $n \in \mathbb{W}$.

$T_0(x) = 1$	$T_4(x) = 8x^4 - 8x^2 + 1$
$T_1(x) = x$	$T_5(x) = 16x^5 - 20x^3 + 5x$
$T_2(x) = 2x^2 - 1$	$T_6(x) = 32x^6 - 48x^4 + 18x^2 - 1$
$T_3(x) = 4x^3 - 3x$	

PROOF: Proof of these equations follows directly from Example E.2 (page 128).

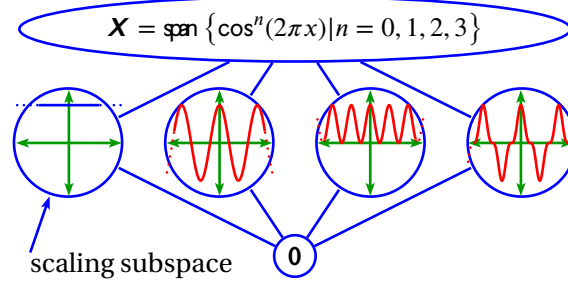
E.2 Trigonometric reduction

Theorem E.2 (page 125) showed that $\cos nx$ can be expressed as a polynomial in $\cos x$. Conversely, Theorem E.4 (next) shows that a polynomial in $\cos x$ can be expressed as a linear combination of $(\cos nx)_{n \in \mathbb{Z}}$.

Theorem E.4 (trigonometric reduction).

⁴ [maxima](#) pages 157–158 (10.5 Trigonometric Functions)

⁵ [Rivlin \(1974\) page 5](#) (1.13), [Süli and Mayers \(2003\) page 242](#) (Lemma 8.2), [Davidson and Donsig \(2010\) page 222](#) (exercise 10.7.A(a))

Figure E.3: Lattice of exponential cosines $\{\cos^n x | n = 0, 1, 2, 3\}$

$$\begin{aligned} \cos^n x &= \frac{1}{2^n} \sum_{k=0}^n \binom{n}{k} \cos[(n-2k)x] \\ &= \begin{cases} \frac{1}{2^n} \binom{n}{\frac{n}{2}} + \frac{1}{2^{n-1}} \sum_{k=0}^{\frac{n}{2}-1} \binom{n}{k} \cos[(n-2k)x] & \text{for } n \text{ even} \\ \frac{1}{2^{n-1}} \sum_{k=0}^{\lfloor \frac{n}{2} \rfloor} \binom{n}{k} \cos[(n-2k)x] & \text{for } n \text{ odd} \end{cases} \end{aligned}$$

PROOF:

$$\begin{aligned} \cos^n x &= \left(\frac{e^{ix} + e^{-ix}}{2} \right)^n \\ &= \operatorname{Re} \left[\left(\frac{e^{ix} + e^{-ix}}{2} \right)^n \right] \\ &= \operatorname{Re} \left[\frac{1}{2^n} \sum_{k=0}^n \binom{n}{k} e^{i(n-k)x} e^{-ikx} \right] \\ &= \operatorname{Re} \left[\frac{1}{2^n} \sum_{k=0}^n \binom{n}{k} e^{i(n-2k)x} \right] \\ &= \operatorname{Re} \left[\frac{1}{2^n} \sum_{k=0}^n \binom{n}{k} (\cos[(n-2k)x] + i \sin[(n-2k)x]) \right] \\ &= \operatorname{Re} \left[\frac{1}{2^n} \sum_{k=0}^n \binom{n}{k} \cos[(n-2k)x] + i \frac{1}{2^n} \sum_{k=0}^n \binom{n}{k} \sin[(n-2k)x] \right] \\ &= \frac{1}{2^n} \sum_{k=0}^n \binom{n}{k} \cos[(n-2k)x] \\ &= \begin{cases} \frac{1}{2^n} \binom{n}{\frac{n}{2}} + \frac{1}{2^{n-1}} \sum_{k=0}^{\frac{n}{2}-1} \binom{n}{k} \cos[(n-2k)x] & : \quad n \text{ even} \\ \frac{1}{2^{n-1}} \sum_{k=0}^{\lfloor \frac{n}{2} \rfloor} \binom{n}{k} \cos[(n-2k)x] & : \quad n \text{ odd} \end{cases} \end{aligned}$$

⇒

Example E.4. ⁶

⁶ Abramowitz and Stegun (1972) page 795, Sloane (2014) (<http://oeis.org/A100257>), Sloane (2014) (<http://oeis.org/A008314>)

E X	n	$\cos^n x$	trigonometric reduction	n	$\cos^n x$	trigonometric reduction
	0	$\cos^0 x$	$= 1$	4	$\cos^4 x$	$= \frac{\cos 4x + 4\cos 2x + 3}{2^3}$
	1	$\cos^1 x$	$= \cos x$	5	$\cos^5 x$	$= \frac{\cos 5x + 5\cos 3x + 10\cos x}{2^4}$
	2	$\cos^2 x$	$= \frac{\cos 2x + 1}{2}$	6	$\cos^6 x$	$= \frac{\cos 6x + 6\cos 4x + 15\cos 2x + 10}{2^5}$
	3	$\cos^3 x$	$= \frac{\cos 3x + 3\cos x}{2^2}$	7	$\cos^7 x$	$= \frac{\cos 7x + 7\cos 5x + 21\cos 3x + 35\cos x}{2^6}$

✎ PROOF:

$$\begin{aligned}
 \cos^0 x &= \frac{1}{2^n} \sum_{k=0}^n \binom{n}{k} \cos([n-2k]x) \Big|_{n=0} \\
 &= \frac{1}{2^0} \sum_{k=0}^0 \binom{0}{k} \cos[(0-2k)x] \\
 &= \binom{0}{0} \cos[(0-2 \cdot 0)x] \\
 &= 1
 \end{aligned}$$

$$\begin{aligned}
 \cos^1 x &= \frac{1}{2^n} \sum_{k=0}^n \binom{n}{k} \cos([n-2k]x) \Big|_{n=1} \\
 &= \frac{1}{2^1} \sum_{k=0}^1 \binom{1}{k} \cos[(1-2k)x] \\
 &= \frac{1}{2} \left[\binom{1}{0} \cos[(1-2 \cdot 0)x] + \binom{1}{1} \cos[(1-2 \cdot 1)x] \right] \\
 &= \frac{1}{2} [1\cos x + 1\cos(-x)] \\
 &= \frac{1}{2} (\cos x + \cos x) \\
 &= \cos x
 \end{aligned}$$

$$\begin{aligned}
 \cos^2 x &= \frac{1}{2^n} \sum_{k=0}^n \binom{n}{k} \cos([n-2k]x) \Big|_{n=2} \\
 &= \frac{1}{2^2} \sum_{k=0}^2 \binom{2}{k} \cos([2-2k]x) \\
 &= \frac{1}{2^2} \left[\binom{2}{0} \cos([2-2 \cdot 0]x) + \binom{2}{1} \cos([2-2 \cdot 1]x) + \binom{2}{2} \cos([2-2 \cdot 2]x) \right] \\
 &= \frac{1}{2^2} [1\cos(2x) + 2\cos(0x) + 1\cos(-2x)] \\
 &= \frac{1}{2^2} [\cos(2x) + 2 + \cos(2x)] \\
 &= \frac{1}{2} [\cos(2x) + 1]
 \end{aligned}$$

$$\begin{aligned}
 \cos^3 x &= \frac{1}{2^n} \sum_{k=0}^n \binom{n}{k} \cos([n-2k]x) \Big|_{n=3} \\
 &= \frac{1}{2^3} \sum_{k=0}^3 \binom{3}{k} \cos([3-2k]x)
 \end{aligned}$$

$$\begin{aligned}
&= \frac{1}{2^3} [1\cos(3x) + 3\cos(1x) + 3\cos(-1x) + 1\cos(-3x)] \\
&= \frac{1}{2^3} [\cos(3x) + 3\cos(x) + 3\cos(x) + \cos(3x)] \\
&= \frac{1}{2^2} [\cos(3x) + 3\cos(x)] \\
\cos^4 x &= \frac{1}{2^n} \sum_{k=0}^n \binom{n}{k} \cos([n-2k]x) \Big|_{n=4} \\
&= \frac{1}{2^4} \sum_{k=0}^4 \binom{4}{k} \cos([4-2k]x) \\
&= \frac{1}{2^4} [1\cos(4x) + 4\cos(2x) + 6\cos(0x) + 4\cos(-2x) + 1\cos(-4x)] \\
&= \frac{1}{2^3} [\cos(4x) + 4\cos(2x) + 3] \\
\cos^5 x &= \frac{1}{2^{5-1}} \sum_{k=0}^{\lfloor \frac{5}{2} \rfloor} \binom{5}{k} \cos[(5-2k)x] \\
&= \frac{1}{16} \sum_{k=0}^2 \binom{5}{k} \cos[(5-2k)x] \\
&= \frac{1}{16} \left[\binom{5}{0} \cos 5x + \binom{5}{1} \cos 3x + \binom{5}{2} \cos x \right] \\
&= \frac{1}{16} [\cos 5x + 5\cos 3x + 10\cos x] \\
\cos^6 x &= \frac{1}{2^6} \binom{6}{\frac{6}{2}} + \frac{1}{2^{6-1}} \sum_{k=0}^{\frac{6}{2}-1} \binom{6}{k} \cos[(6-2k)x] \\
&= \frac{1}{2^6} \binom{6}{3} + \frac{1}{2^5} \sum_{k=0}^2 \binom{6}{k} \cos[(6-2k)x] \\
&= \frac{1}{64} 20 + \frac{1}{32} \left[\binom{6}{0} \cos 6x + \binom{6}{1} \cos 4x + \binom{6}{2} \cos 2x \right] \\
&= \frac{1}{32} [\cos 6x + 6\cos 4x + 15\cos 2x + 10] \\
\cos^7 x &= \frac{1}{2^{7-1}} \sum_{k=0}^{\lfloor \frac{7}{2} \rfloor} \binom{7}{k} \cos[(7-2k)x] \\
&= \frac{1}{64} \sum_{k=0}^2 \binom{7}{k} \cos[(7-2k)x] \\
&= \frac{1}{64} \left[\binom{7}{0} \cos 7x + \binom{7}{1} \cos 5x + \binom{7}{2} \cos 3x + \binom{7}{3} \cos x \right] \\
&= \frac{1}{64} [\cos 7x + 7\cos 5x + 21\cos 3x + 35\cos x]
\end{aligned}$$


Note: Trigonometric reduction of $\cos^n(x)$ for particular values of n can also be performed with the free software package *Maxima*TM using the syntax illustrated to the right.⁷

```

1 trigreduce((cos(x))^2);
2 trigreduce((cos(x))^3);
3 trigreduce((cos(x))^4);
4 trigreduce((cos(x))^5);
5 trigreduce((cos(x))^6);
6 trigreduce((cos(x))^7);

```

⁷ http://maxima.sourceforge.net/docs/manual/en/maxima_15.html

 [maxima](#) page 158 <10.5 Trigonometric Functions>



E.3 Spectral Factorization

Theorem E.5 (Fejér-Riesz spectral factorization).⁸ Let $[0, \infty) \subsetneq \mathbb{R}$ and

$$p(e^{ix}) \triangleq \sum_{n=-N}^N a_n e^{inx} \quad (\text{Laurent trigonometric polynomial order } 2N)$$

$$q(e^{ix}) \triangleq \sum_{n=1}^N b_n e^{inx} \quad (\text{standard trigonometric polynomial order } N)$$

T H M	$p(e^{ix}) \in [0, \infty) \quad \forall x \in [0, 2\pi] \quad \implies \quad \begin{cases} \exists (b_n)_{n \in \mathbb{Z}} \text{ such that} \\ p(e^{ix}) = q(e^{ix}) q^*(e^{ix}) \end{cases} \quad \forall x \in \mathbb{R}$
----------------------	---

PROOF:

1. Proof that $a_n = a_{-n}^*$ ($(a_n)_{n \in \mathbb{Z}}$ is *Hermitian symmetric*):

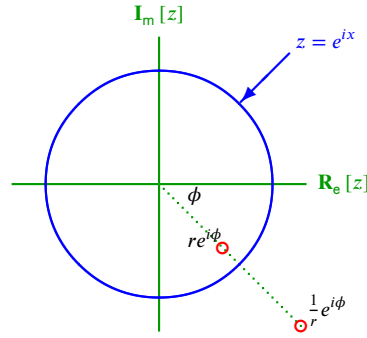
Let $a_n \triangleq r_n e^{i\phi_n}$, $r_n, \phi_n \in \mathbb{R}$. Then

$$\begin{aligned}
 p(e^{inx}) &\triangleq \sum_{n=-N}^N a_n e^{inx} \\
 &= \sum_{n=-N}^N r_n e^{i\phi_n} e^{inx} \\
 &= \sum_{n=-N}^N r_n e^{inx + \phi_n} \\
 &= \sum_{n=-N}^N r_n \cos(nx + \phi_n) + i \sum_{n=-N}^N r_n \sin(nx + \phi_n) \\
 &= \sum_{n=-N}^N r_n \cos(nx + \phi_n) + i \underbrace{\left[r_0 \sin(0x + \phi_0) + \sum_{n=1}^N r_n \sin(nx + \phi_n) + \sum_{n=1}^N r_{-n} \sin(-nx + \phi_{-n}) \right]}_{\text{imaginary part must equal 0 because } p(x) \in \mathbb{R}} \\
 &= \sum_{n=-N}^N r_n \cos(nx + \phi_n) + i \underbrace{\left[r_0 \sin(\phi_0) + \sum_{n=1}^N r_n \sin(nx + \phi_n) - \sum_{n=1}^N r_{-n} \sin(nx - \phi_{-n}) \right]}_{\implies r_n = r_{-n}, \phi_n = -\phi_{-n} \implies a_n = a_{-n}^*, a_0 \in \mathbb{R}}
 \end{aligned}$$

2. Because the coefficients $(c_n)_{n \in \mathbb{Z}}$ are *Hermitian symmetric*, the zeros of $P(z)$ occur in *conjugate reciprocal pairs*. This means that if $\sigma \in \mathbb{C}$ is a zero of $P(z)$ ($P(\sigma) = 0$), then $\frac{1}{\sigma^*}$ is also a zero of $P(z)$ ($P\left(\frac{1}{\sigma^*}\right) = 0$). In the complex z plane, this relationship means zeros are reflected across the unit circle such that

$$\frac{1}{\sigma^*} = \frac{1}{(re^{i\phi})^*} = \frac{1}{r} \frac{1}{e^{-i\phi}} = \frac{1}{r} e^{i\phi}$$

⁸ Pinsky (2002) pages 330–331



3. Because the zeros of $p(z)$ occur in conjugate reciprocal pairs, $p(e^{ix})$ can be factored:

$$\begin{aligned}
 p(e^{ix}) &= p(z)|_{z=e^{ix}} \\
 &= z^{-N} C \prod_{n=1}^N (z - \sigma_n) \prod_{n=1}^N \left(z - \frac{1}{\sigma_n^*} \right) \Big|_{z=e^{ix}} \\
 &= C \prod_{n=1}^N (z - \sigma_n) \prod_{n=1}^N z^{-1} \left(z - \frac{1}{\sigma_n^*} \right) \Big|_{z=e^{ix}} \\
 &= C \prod_{n=1}^N (z - \sigma_n) \prod_{n=1}^N \left(1 - \frac{1}{\sigma_n^*} z^{-1} \right) \Big|_{z=e^{ix}} \\
 &= C \prod_{n=1}^N (z - \sigma_n) \prod_{n=1}^N (z^{-1} - \sigma_n^*) \left(-\frac{1}{\sigma_n^*} \right) \Big|_{z=e^{ix}} \\
 &= \left[C \prod_{n=1}^N \left(-\frac{1}{\sigma_n^*} \right) \right] \left[\prod_{n=1}^N (z - \sigma_n) \right] \left[\prod_{n=1}^N \left(\frac{1}{z^*} - \sigma_n \right) \right]^* \Big|_{z=e^{ix}} \\
 &= \left[C_2 \prod_{n=1}^N (z - \sigma_n) \right] \left[C_2 \prod_{n=1}^N \left(\frac{1}{z^*} - \sigma_n \right) \right]^* \Big|_{z=e^{ix}} \\
 &= q(z) q^* \left(\frac{1}{z^*} \right) \Big|_{z=e^{ix}} \\
 &= q(e^{ix}) q^*(e^{ix})
 \end{aligned}$$



E.4 Dirichlet Kernel



“Dirichlet alone, not I, nor Cauchy, nor Gauss knows what a completely rigorous proof is. Rather we learn it first from him. When Gauss says he has proved something it is clear; when Cauchy says it, one can wager as much pro as con; when Dirichlet says it, it is certain.”

Carl Gustav Jacob Jacobi (1804–1851), Jewish-German mathematician ⁹

⁹ quote: Schubring (2005) page 558

image: http://en.wikipedia.org/wiki/File:Carl_Jacobi.jpg, public domain

The *Dirichlet Kernel* is critical in proving what is not immediately obvious in examining the Fourier Series—that for a broad class of periodic functions, a function can be recovered from (with uniform convergence) its Fourier Series analysis.

Definition E.2. ¹⁰

DEF

The *Dirichlet Kernel* $D_n \in \mathbb{R}^{\mathbb{W}}$ with period τ is defined as

$$D_n(x) \triangleq \frac{1}{\tau} \sum_{k=-n}^n e^{i\frac{2\pi}{\tau}kx}$$

Proposition E.1. ¹¹ Let D_n be the DIRICHLET KERNEL with period τ (Definition E.2 page 136).

PRP

$$D_n(x) = \frac{1}{\tau} \frac{\sin\left(\frac{\pi}{\tau}[2n+1]x\right)}{\sin\left(\frac{\pi}{\tau}x\right)}$$

PROOF:

$$\begin{aligned} D_n(x) &\triangleq \frac{1}{\tau} \sum_{k=-n}^n e^{i\frac{2\pi}{\tau}kx} && \text{by definition of } D_n && (\text{Definition E.2 page 136}) \\ &= \frac{1}{\tau} \sum_{k=0}^{2n} e^{i\frac{2\pi}{\tau}(k-n)x} = \frac{1}{\tau} e^{-i\frac{2\pi n}{\tau}x} \sum_{k=0}^{2n} e^{i\frac{2\pi}{\tau}kx} = \frac{1}{\tau} e^{-i\frac{2\pi n}{\tau}x} \sum_{k=0}^{2n} \left(e^{i\frac{2\pi}{\tau}x}\right)^k \\ &= \frac{1}{\tau} e^{-i\frac{2\pi n}{\tau}x} \frac{1 - \left(e^{i\frac{2\pi}{\tau}x}\right)^{2n+1}}{1 - e^{i\frac{2\pi}{\tau}x}} && \text{by geometric series} \\ &= \frac{1}{\tau} e^{-i\frac{2\pi n}{\tau}x} \frac{1 - e^{i\frac{2\pi}{\tau}(2n+1)x}}{1 - e^{i\frac{2\pi}{\tau}x}} = \frac{1}{\tau} e^{-i\frac{2\pi n}{\tau}x} \left(\frac{e^{i\frac{\pi}{\tau}(2n+1)x}}{e^{i\frac{\pi}{\tau}x}} \right) \frac{e^{-i\frac{\pi}{\tau}(2n+1)x} - e^{i\frac{\pi}{\tau}(2n+1)x}}{e^{-i\frac{\pi}{\tau}x} - e^{i\frac{\pi}{\tau}x}} \\ &= \frac{1}{\tau} e^{-i\frac{2\pi n}{\tau}x} \left(e^{i\frac{2\pi n}{\tau}x} \right) \frac{-2i \sin\left[\frac{\pi}{\tau}(2n+1)x\right]}{-2i \sin\left[\frac{\pi}{\tau}x\right]} = \frac{1}{\tau} \frac{\sin\left[\frac{\pi}{\tau}(2n+1)x\right]}{\sin\left[\frac{\pi}{\tau}x\right]} \end{aligned}$$

⇒

Proposition E.2. ¹² Let D_n be the DIRICHLET KERNEL with period τ (Definition E.2 page 136).

PRP

$$\int_0^\tau D_n(x) dx = 1$$

PROOF:

$$\begin{aligned} \int_0^\tau D_n(x) dx &\triangleq \int_0^\tau \frac{1}{\tau} \sum_{k=-n}^n e^{i\frac{2\pi}{\tau}kx} dx && \text{by definition of } D_n \text{ (Definition E.2 page 136)} \\ &= \frac{1}{\tau} \sum_{k=-n}^n \int_{-\frac{\tau}{2}}^{\frac{\tau}{2}} e^{i\frac{2\pi}{\tau}kx} dx \\ &= \frac{1}{\tau} \sum_{k=-n}^n \int_{-\frac{\tau}{2}}^{\frac{\tau}{2}} \cos\left(\frac{2\pi}{\tau}kx\right) + i \sin\left(\frac{2\pi}{\tau}kx\right) dx \end{aligned}$$

¹⁰ Katznelson (2004) page 14, Heil (2011) pages 443–444, Folland (1992) pages 33–34

¹¹ Katznelson (2004) page 14, Heil (2011) page 444, Folland (1992) page 34

¹² Bruckner et al. (1997) pages 620–621

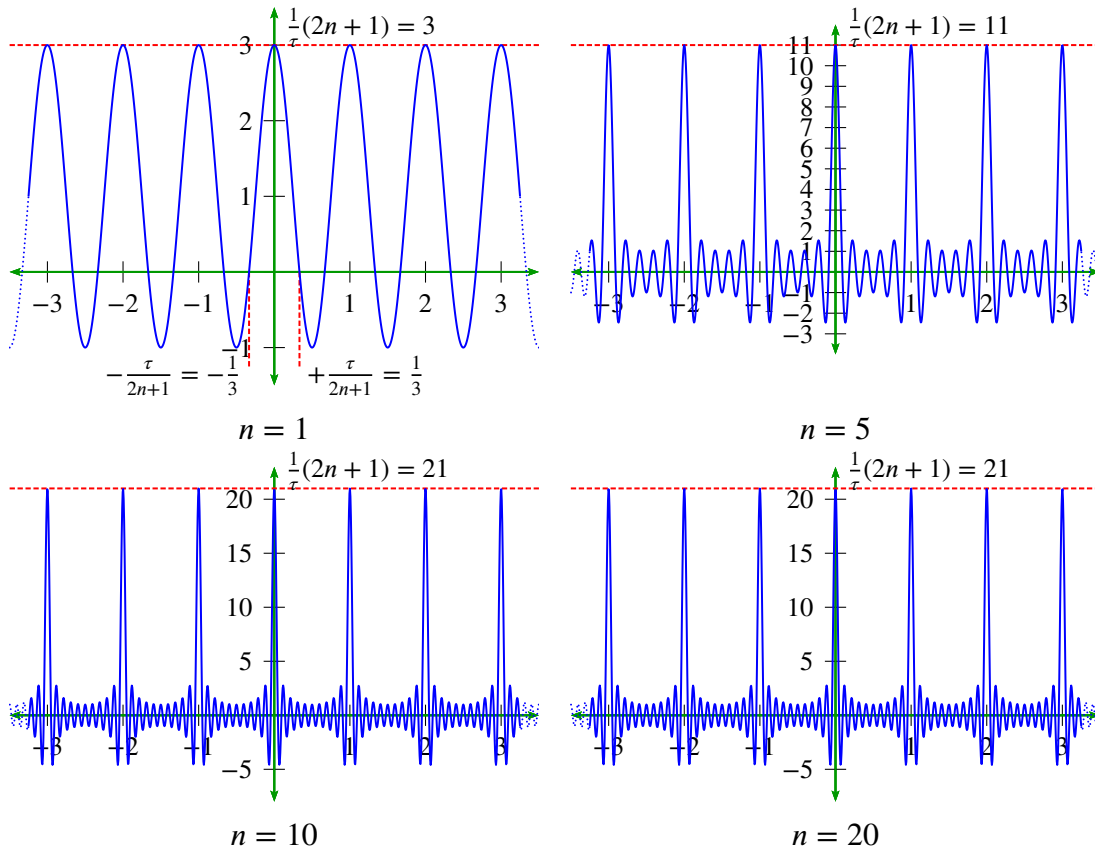


Figure E.4: D_n function for $N = 1, 5, 10, 20$. $D_n \rightarrow \text{comb}$. (See Proposition E.1 page 136).

$$\begin{aligned}
 &= \frac{1}{\tau} \sum_{k=-n}^n \int_{-\frac{\tau}{2}}^{\frac{\tau}{2}} \cos\left(\frac{2\pi}{\tau} kx\right) dx \\
 &= \frac{1}{\tau} \sum_{k=-n}^n \left. \frac{\sin\left(\frac{2\pi}{\tau} kx\right)}{\frac{2\pi}{\tau} k} \right|_{-\frac{\tau}{2}}^{\frac{\tau}{2}} \\
 &= \frac{1}{\tau} \sum_{k=-n}^n \left[\frac{\sin\left(\frac{2\pi}{\tau} k \frac{\tau}{2}\right)}{\frac{2\pi}{\tau} k} - \frac{\sin\left(-\frac{2\pi}{\tau} k \frac{\tau}{2}\right)}{\frac{2\pi}{\tau} k} \right] \\
 &= \frac{1}{\tau} \sum_{k=-n}^n \left[\frac{\sin(\pi k)}{\pi k} + \frac{\sin(\pi k)}{\pi k} \right] \\
 &= \frac{1}{2} \left[2 \frac{\sin(\pi k)}{\pi k} \right]_{k=0} \\
 &= 1
 \end{aligned}$$

⇒

Proposition E.3. Let D_n be the DIRICHLET KERNEL with period τ (Definition E.2 page 136). Let w_N (the “WIDTH” of $D_n(x)$) be the distance between the two points where the center pulse of $D_n(x)$ intersects the x axis.

P R P	$D_n(0) = \frac{1}{\tau}(2n+1)$
	$w_n = \frac{2\tau}{2n+1}$

 PROOF:

$$\begin{aligned}
 D_n(0) &= D_n(x) \Big|_{t=0} \\
 &= \frac{1}{\tau} \frac{\sin \left[\frac{\pi}{\tau} (2n+1)x \right]}{\sin \left[\frac{\pi}{\tau} t \right]} \Big|_{t=0} && \text{by Proposition E.1 page 136} \\
 &= \frac{1}{\tau} \frac{\frac{d}{dx} \sin \left[\frac{\pi}{\tau} (2n+1)x \right]}{\frac{d}{dx} \sin \left[\frac{\pi}{\tau} t \right]} \Big|_{t=0} && \text{by l'Hôpital's rule} \\
 &= \frac{1}{\tau} \frac{\frac{\pi}{\tau} (2n+1) \cos \left[\frac{\pi}{\tau} (2n+1)x \right]}{\cos \left[\frac{\pi}{\tau} t \right]} \Big|_{t=0} \\
 &= \frac{1}{\tau} \frac{\frac{\pi}{\tau} (2n+1)}{\frac{\pi}{\tau}} \frac{1}{1} \\
 &= \frac{1}{\tau} (2n+1)
 \end{aligned}$$

The center pulse of kernel $D_n(x)$ intersects the x axis at

$$t = \pm \frac{\tau}{(2n+1)}$$

which implies

$$w_n = \frac{\tau}{2n+1} + \frac{\tau}{2n+1} = \frac{2\tau}{(2n+1)}.$$




Proposition E.4. ¹³ Let D_n be the DIRICHLET KERNEL with period τ (Definition E.2 page 136).

P R P	$D_n(x) = D_n(-x) \quad (D_n \text{ is an EVEN function})$
-------------	--

 PROOF:

$$\begin{aligned}
 D_n(x) &= \frac{1}{\tau} \frac{\sin \left[\frac{\pi}{\tau} (2n+1)x \right]}{\sin \left[\frac{\pi}{\tau} t \right]} && \text{by Proposition E.1 page 136} \\
 &= \frac{1}{\tau} \frac{-\sin \left[-\frac{\pi}{\tau} (2n+1)x \right]}{-\sin \left[-\frac{\pi}{\tau} t \right]} && \text{because } \sin x \text{ is an } \textit{odd} \text{ function} \\
 &= \frac{1}{\tau} \frac{\sin \left[\frac{\pi}{\tau} (2n+1)(-x) \right]}{\sin \left[\frac{\pi}{\tau} (-x) \right]} \\
 &= D_n(-x) && \text{by Proposition E.1 page 136}
 \end{aligned}$$



¹³  Bruckner et al. (1997) pages 620–621

E.5 Trigonometric summations

Theorem E.6 (Lagrange trigonometric identities). ¹⁴



**T
H
M**

$$\begin{aligned}\sum_{n=0}^{N-1} \cos(nx) &= \frac{1}{2} + \frac{\sin\left(\left[N - \frac{1}{2}\right]x\right)}{2\sin\left(\frac{1}{2}x\right)} = \frac{\sin\left(\left[N - \frac{1}{2}\right]x\right) + \sin\left(\frac{1}{2}x\right)}{2\sin\left(\frac{1}{2}x\right)} \quad \forall x \in \mathbb{R} \\ \sum_{n=0}^{N-1} \sin(nx) &= \frac{1}{2} \cot\left(\frac{1}{2}x\right) + \frac{\cos\left(\left[N - \frac{1}{2}\right]x\right)}{2\sin\left(\frac{1}{2}x\right)} = \frac{\cos\left(\left[N - \frac{1}{2}\right]x\right) + \cos\left(\frac{1}{2}x\right)}{2\sin\left(\frac{1}{2}x\right)} \quad \forall x \in \mathbb{R}\end{aligned}$$

 **PROOF:**

$$\begin{aligned}\sum_{n=0}^{N-1} \cos(nx) &= \sum_{n=0}^{N-1} \Re e^{inx} = \Re \sum_{n=0}^{N-1} e^{inx} = \Re \sum_{n=0}^{N-1} (e^{ix})^n \\ &= \Re \left[\frac{1 - e^{iNx}}{1 - e^{ix}} \right] && \text{by geometric series} \\ &= \Re \left[\left(\frac{e^{i\frac{1}{2}Nx}}{e^{i\frac{1}{2}x}} \right) \left(\frac{e^{-i\frac{1}{2}Nx} - e^{i\frac{1}{2}Nx}}{e^{-i\frac{1}{2}x} - e^{i\frac{1}{2}x}} \right) \right] \\ &= \Re \left[\left(e^{i\frac{1}{2}(N-1)x} \right) \left(\frac{-i\frac{1}{2}\sin\left(\frac{1}{2}Nx\right)}{-i\frac{1}{2}\sin\left(\frac{1}{2}x\right)} \right) \right] \\ &= \cos\left(\frac{1}{2}(N-1)x\right) \left(\frac{\sin\left(\frac{1}{2}Nx\right)}{\sin\left(\frac{1}{2}x\right)} \right) \\ &= \frac{-\frac{1}{2}\sin\left(-\frac{1}{2}x\right) + \frac{1}{2}\sin\left(\left[N - \frac{1}{2}\right]x\right)}{\sin\left(\frac{1}{2}x\right)} && \text{by product identities} \quad (\text{Theorem D.8 page 114}) \\ &= \frac{1}{2} + \frac{\sin\left(\left[N - \frac{1}{2}\right]x\right)}{2\sin\left(\frac{1}{2}x\right)}\end{aligned}$$

$$\begin{aligned}\sum_{n=0}^{N-1} \sin(nx) &= \sum_{n=0}^{N-1} \Im e^{inx} = \Im \sum_{n=0}^{N-1} e^{inx} = \Im \sum_{n=0}^{N-1} (e^{ix})^n \\ &= \Im \left[\frac{1 - e^{iNx}}{1 - e^{ix}} \right] && \text{by geometric series} \\ &= \Im \left[\left(\frac{e^{i\frac{1}{2}Nx}}{e^{i\frac{1}{2}x}} \right) \left(\frac{e^{-i\frac{1}{2}Nx} - e^{i\frac{1}{2}Nx}}{e^{-i\frac{1}{2}x} - e^{i\frac{1}{2}x}} \right) \right] \\ &= \Im \left[\left(e^{i(N-1)x/2} \right) \left(\frac{-\frac{1}{2}i\sin\left(\frac{1}{2}Nx\right)}{-\frac{1}{2}i\sin\left(\frac{1}{2}x\right)} \right) \right]\end{aligned}$$

¹⁴ [Muniz \(1953\)](#) page 140 (“Lagrange's Trigonometric Identities”),  [Jeffrey and Dai \(2008\)](#) pages 128–130 (2.4.1.6 Sines, Cosines, and Tagents of Multiple Angles; (14), (13))

$$\begin{aligned}
&= \sin\left(\frac{(N-1)x}{2}\right) \left(\frac{\sin\left(\frac{1}{2}Nx\right)}{\sin\left(\frac{1}{2}x\right)} \right) \\
&= \frac{\frac{1}{2}\cos\left(-\frac{1}{2}x\right) - \frac{1}{2}\cos\left(\left[N - \frac{1}{2}\right]x\right)}{\sin\left(\frac{1}{2}x\right)} && \text{by product identities} \quad (\text{Theorem D.8 page 114}) \\
&= \frac{1}{2} \cot\left(\frac{1}{2}x\right) + \frac{\cos\left(\left[N - \frac{1}{2}\right]x\right)}{2\sin\left(\frac{1}{2}x\right)}
\end{aligned}$$

Note that these results (summed with indices from $n = 0$ to $n = N - 1$) are compatible with [Muniz (1953) page 140 (summed with indices from $n = 1$ to $n = N$) as demonstrated next:

$$\begin{aligned}
\sum_{n=0}^{N-1} \cos(nx) &= \sum_{n=1}^N \cos(nx) + [\cos(0x) - \cos(Nx)] \\
&= \left[-\frac{1}{2} + \frac{\sin\left(\left[N + \frac{1}{2}\right]x\right)}{2\sin\left(\frac{1}{2}x\right)} \right] + [\cos(0x) - \cos(Nx)] && \text{by [Muniz (1953) page 140]} \\
&= \left(1 - \frac{1}{2}\right) + \frac{\sin\left(\left[N + \frac{1}{2}\right]x\right) - 2\sin\left(\frac{1}{2}x\right)\cos(Nx)}{2\sin\left(\frac{1}{2}x\right)} \\
&= \frac{1}{2} + \frac{\sin\left(\left[N + \frac{1}{2}\right]x\right) - 2\left[\sin\left(\left[\frac{1}{2} - N\right]x\right) + \sin\left(\left[\frac{1}{2} + N\right]x\right)\right]}{2\sin\left(\frac{1}{2}x\right)} && \text{by Theorem D.8 page 114} \\
&= \frac{1}{2} + \frac{\sin\left(\frac{1}{2}[2N - 1]x\right)}{2\sin\left(\frac{1}{2}x\right)} && \Rightarrow \text{above result}
\end{aligned}$$

$$\begin{aligned}
\sum_{n=0}^{N-1} \sin(nx) &= \sum_{n=1}^N \sin(nx) + [\sin(0x) - \sin(Nx)] \\
&= \frac{1}{2} \cot\left(\frac{1}{2}x\right) - \frac{\cos\left(\left[N + \frac{1}{2}\right]x\right)}{2\sin\left(\frac{1}{2}x\right)} + [0 - \sin(Nx)] && \text{by [Muniz (1953) page 140]} \\
&= \frac{1}{2} \cot\left(\frac{1}{2}x\right) - \frac{\cos\left(\left[N + \frac{1}{2}\right]x\right) - 2\sin\left(\frac{1}{2}x\right)\sin(Nx)}{2\sin\left(\frac{1}{2}x\right)} \\
&= \frac{1}{2} \cot\left(\frac{1}{2}x\right) - \frac{\cos\left(\left[N + \frac{1}{2}\right]x\right) - \left[\cos\left(\left[\frac{1}{2} - N\right]x\right) - \cos\left(\left[\frac{1}{2} + N\right]x\right)\right]}{2\sin\left(\frac{1}{2}x\right)} \\
&= \frac{1}{2} \cot\left(\frac{1}{2}x\right) + \frac{\cos\left(\left[N - \frac{1}{2}\right]x\right)}{2\sin\left(\frac{1}{2}x\right)} && \Rightarrow \text{above result}
\end{aligned}$$

⇒

Theorem E.7. ¹⁵

¹⁵ [Jeffrey and Dai (2008) pages 128–130 <2.4.1.6 Sines, Cosines, and Tagents of Multiple Angles; (16) and (17)>



T H M

$$\begin{aligned}\sum_{n=0}^{N-1} \cos(nx + y) &= \cos(y) \left[\frac{1}{2} + \frac{\sin\left(\left[N - \frac{1}{2}\right]x\right)}{2\sin\left(\frac{1}{2}x\right)} \right] - \sin(y) \left[\frac{1}{2} \cot\left(\frac{1}{2}x\right) + \frac{\cos\left(\left[N - \frac{1}{2}\right]x\right)}{2\sin\left(\frac{1}{2}x\right)} \right] & \forall x \in \mathbb{R} \\ \sum_{n=0}^{N-1} \sin(nx + y) &= \cos(y) \left[\frac{1}{2} + \frac{\sin\left(\left[N - \frac{1}{2}\right]x\right)}{2\sin\left(\frac{1}{2}x\right)} \right] + \sin(y) \left[\frac{1}{2} \cot\left(\frac{1}{2}x\right) + \frac{\cos\left(\left[N - \frac{1}{2}\right]x\right)}{2\sin\left(\frac{1}{2}x\right)} \right] & \forall x \in \mathbb{R}\end{aligned}$$

PROOF:

$$\begin{aligned}\sum_{n=0}^{N-1} \cos(nx + y) &= \sum_{n=0}^{N-1} [\cos(nx)\cos(y) - \sin(nx)\sin(y)] && \text{by double angle formulas} && (\text{Theorem D.9 page 117}) \\ &= \cos(y) \sum_{n=0}^{N-1} \cos(nx) - \sin(y) \sum_{n=0}^{N-1} \sin(nx) \\ \sum_{n=0}^{N-1} \sin(nx + y) &= \sum_{n=0}^{N-1} [\cos(nx)\cos(y) + \sin(nx)\sin(y)] && \text{by double angle formulas} && (\text{Theorem D.9 page 117}) \\ &= \cos(y) \sum_{n=0}^{N-1} \cos(nx) + \sin(y) \sum_{n=0}^{N-1} \sin(nx)\end{aligned}$$

⇒

Corollary E.1 (Summation around unit circle).

T H M

$$\begin{aligned}\sum_{n=0}^{N-1} \cos\left(\theta + \frac{2nM\pi}{N}\right) &= \sum_{n=0}^{N-1} \sin\left(\theta + \frac{2nM\pi}{N}\right) = \sum_{n=0}^{N-1} \cos\left(\theta + \frac{2nM\pi}{N}\right) \sin\left(\theta + \frac{2nM\pi}{N}\right) = 0 && \forall \theta \in \mathbb{R} \\ &&& \forall M \in \mathbb{N} \\ \sum_{n=0}^{N-1} \cos^2\left(\theta + \frac{2nM\pi}{N}\right) &= \sum_{n=0}^{N-1} \sin^2\left(\theta + \frac{2nM\pi}{N}\right) = \frac{N}{2} && \forall \theta \in \mathbb{R} \\ &&& \forall M \in \mathbb{N}\end{aligned}$$

PROOF:

$$\begin{aligned}\sum_{n=0}^{N-1} \cos\left(\theta + \frac{2nM\pi}{N}\right) &= \cos(\theta) \sum_{n=0}^{N-1} \cos\left(\frac{2nM\pi}{N}\right) - \sin(\theta) \sum_{n=0}^{N-1} \sin\left(\frac{2nM\pi}{N}\right) && \text{by Theorem D.9 page 117} \\ &= \cos(\theta) \left[\frac{1}{2} + \frac{\sin\left(\left[N - \frac{1}{2}\right] \frac{2M\pi}{N}\right)}{2\sin\left(\frac{1}{2} \frac{2M\pi}{N}\right)} \right] - \sin(\theta) \left[\frac{1}{2} \cot\left(\frac{1}{2} \frac{2M\pi}{N}\right) + \frac{\cos\left(\left[N - \frac{1}{2}\right] \frac{2M\pi}{N}\right)}{2\sin\left(\frac{1}{2} \frac{2M\pi}{N}\right)} \right] && \text{by Theorem E.6 page 139} \\ &= \cos(\theta) \left[\frac{1}{2} - \frac{\sin\left(\frac{M\pi}{N} - 2M\pi\right)}{2\sin\left(\frac{M\pi}{N}\right)} \right] - \sin(\theta) \left[\frac{1}{2} \cot\left(\frac{M\pi}{N}\right) - \frac{\cos\left(\frac{M\pi}{N} - 2M\pi\right)}{2\sin\left(\frac{M\pi}{N}\right)} \right] \\ &= \cos(\theta) \left[\frac{1}{2} - \frac{1}{2} \frac{\sin\left(\frac{M\pi}{N}\right)}{\sin\left(\frac{M\pi}{N}\right)} \right] - \sin(\theta) \left[\frac{1}{2} \cot\left(\frac{M\pi}{N}\right) - \frac{1}{2} \cot\left(\frac{M\pi}{N}\right) \right] && \text{by trigonometric periodicity} \\ &&& (\text{Theorem D.10 page 117}) \\ &= \cos(\theta)[0] - \sin(\theta)[0] \\ &= 0\end{aligned}$$

$$\begin{aligned}
\sum_{n=0}^{N-1} \sin\left(\theta + \frac{2nM\pi}{N}\right) &= \sum_{n=0}^{N-1} \cos\left(\theta - \frac{\pi}{2} + \frac{2nM\pi}{N}\right) && \text{by shift identities} && (\text{Theorem D.7 page 114}) \\
&= \sum_{n=0}^{N-1} \cos\left(\phi + \frac{2nM\pi}{N}\right) && \text{where } \phi \triangleq \theta - \frac{\pi}{2} \\
&= 0 && \text{by previous result}
\end{aligned}$$

$$\begin{aligned}
&\sum_{n=0}^{N-1} \cos\left(\theta + \frac{2nM\pi}{N}\right) \sin\left(\theta + \frac{2nM\pi}{N}\right) \\
&= -\frac{1}{2} \sum_{n=0}^{N-1} \sin\left(\left[\theta + \frac{2nM\pi}{N}\right] - \left[\theta + \frac{2nM\pi}{N}\right]\right) + \frac{1}{2} \sum_{n=0}^{N-1} \sin\left(\left[\theta + \frac{2nM\pi}{N}\right] + \left[\theta + \frac{2nM\pi}{N}\right]\right) && \text{by Theorem D.8 page 114} \\
&= -\frac{1}{2} \sum_{n=0}^{N-1} \sin(0) + \frac{1}{2} \sum_{n=0}^{N-1} \sin\left(2\theta + \frac{4nM\pi}{N}\right) \\
&= \frac{1}{2} \sin(2\theta) \sum_{n=0}^{N-1} \sin\left(\frac{4nM\pi}{N}\right) + \frac{1}{2} \cos(2\theta) \sum_{n=0}^{N-1} \sin\left(\frac{4nM\pi}{N}\right) && \text{by Theorem D.9 page 117} \\
&= \cos(2\theta) \left[\frac{1}{2} + \frac{\sin\left(\left[N - \frac{1}{2}\right] \frac{4M\pi}{N}\right)}{2\sin\left(\frac{1}{2} \frac{2M\pi}{N}\right)} \right] - \sin(2\theta) \left[\frac{1}{2} \cot\left(\frac{1}{2} \frac{4M\pi}{N}\right) + \frac{\cos\left(\left[N - \frac{1}{2}\right] \frac{4M\pi}{N}\right)}{2\sin\left(\frac{1}{2} \frac{4M\pi}{N}\right)} \right] && \text{by Theorem E.6 page 139} \\
&= \cos(2\theta) \left[\frac{1}{2} - \frac{\sin\left(\frac{2M\pi}{N} - 4M\pi\right)}{2\sin\left(\frac{2M\pi}{N}\right)} \right] - \sin(2\theta) \left[\frac{1}{2} \cot\left(\frac{2M\pi}{N}\right) - \frac{\cos\left(\frac{2M\pi}{N} - 4M\pi\right)}{2\sin\left(\frac{2M\pi}{N}\right)} \right] \\
&= \cos(\theta) \left[\frac{1}{2} - \frac{1}{2} \frac{\sin\left(\frac{2M\pi}{N}\right)}{\sin\left(\frac{2M\pi}{N}\right)} \right] - \sin(\theta) \left[\frac{1}{2} \cot\left(\frac{2M\pi}{N}\right) - \frac{1}{2} \cot\left(\frac{2M\pi}{N}\right) \right] && \text{by trigonometric periodicity} \\
&&& (\text{Theorem D.10 page 117}) \\
&= \cos(\theta)[0] - \sin(\theta)[0] \\
&= 0
\end{aligned}$$

$$\begin{aligned}
\sum_{n=0}^{N-1} \cos^2\left(\theta + \frac{2nM\pi}{N}\right) &= \frac{1}{2} \sum_{n=0}^{N-1} \left[1 + \cos\left(2\theta + \frac{4nM\pi}{N}\right) \right] && \text{by Theorem D.11 page 119} \\
&= \frac{1}{2} \sum_{n=0}^{N-1} \left[1 + \cos(2\theta) \cos\left(\frac{4nM\pi}{N}\right) - \sin(2\theta) \sin\left(\frac{4nM\pi}{N}\right) \right] && \text{by Theorem D.9 page 117} \\
&= \frac{1}{2} \sum_{n=0}^{N-1} 1 + \frac{1}{2} \cos(2\theta) \sum_{n=0}^{N-1} \cos\left(\frac{4nM\pi}{N}\right) - \frac{1}{2} \sin(2\theta) \sum_{n=0}^{N-1} \sin\left(\frac{4nM\pi}{N}\right) \\
&= \left[\frac{1}{2} \sum_{n=0}^{N-1} 1 \right] + \frac{1}{2} \cos(2\theta) 0 - \frac{1}{2} \sin(2\theta) 0 && \text{by previous results} \\
&= \frac{N}{2}
\end{aligned}$$

$$\begin{aligned}
\sum_{n=0}^{N-1} \sin^2\left(\theta + \frac{2nM\pi}{N}\right) &= \sum_{n=0}^{N-1} \cos^2\left(\theta - \frac{\pi}{2} + \frac{2nM\pi}{N}\right) && \text{by shift identities (Theorem D.7 page 114)} \\
&= \sum_{n=0}^{N-1} \cos^2\left(\phi + \frac{2nM\pi}{N}\right) && \text{where } \phi \triangleq \theta - \frac{\pi}{2} \\
&= \frac{N}{2} && \text{by previous result}
\end{aligned}$$



E.6 Summability Kernels

Definition E.3. ¹⁶ Let $(\kappa_n)_{n \in \mathbb{Z}}$ be a sequence of CONTINUOUS 2π PERIODIC functions.

The sequence $(\kappa_n)_{n \in \mathbb{Z}}$ is a **summability kernel** if

DEF

1. $\frac{1}{2\pi} \int_0^{2\pi} \kappa_n(x) dx = 1 \quad \forall n \in \mathbb{Z}$ and
2. $\frac{1}{2\pi} \int_0^{2\pi} |\kappa_n(x)| dx \in \mathbb{R} \quad \forall n \in \mathbb{Z}$ and
3. $\lim_{n \rightarrow \infty} \int_{\delta}^{2\pi-\delta} |\kappa_n(x)| dx = 0 \quad \forall n \in \mathbb{Z}, 0 < \delta < \pi$

Theorem E.8. ¹⁷ Let $(\kappa_n)_{n \in \mathbb{Z}}$ be a sequence. Let \mathbb{T} be the quotient $\mathbb{R}/2\pi\mathbb{Z}$.

THM

- $$\left. \begin{array}{l} 1. f \in L^1(\mathbb{T}) \\ 2. (\kappa_n) \text{ is a summability kernel} \end{array} \right\} \text{ and } \Rightarrow f(x) = \lim_{n \rightarrow \infty} \frac{1}{2\pi} \int_{\mathbb{T}} \kappa_n(x) f(x-x) dx$$

The *Dirichlet kernel* (Definition E.2 page 136) is *not* a summability kernel. Examples of kernels that *are* summability kernels include

1. *Fejér's kernel* (Definition E.4 page 143)
2. *de la Vallée Poussin kernel* (Definition E.5 page 145)
3. *Jackson kernel* (Definition E.6 page 145)
4. *Poisson kernel* (Definition E.7 page 145.)

Definition E.4. ¹⁸

Fejér's kernel K_n is defined as

DEF

$$K_n(x) \triangleq \sum_{k=-n}^{k=n} \left(1 - \frac{|k|}{n+1}\right) e^{ikx}$$

Proposition E.5. ¹⁹ Let K_n be Fejér's kernel (Definition E.4 page 143).

PRP

$$K_n(x) = \frac{1}{n+1} \left(\frac{\sin \frac{n+1}{2} x}{\sin \frac{1}{2} x} \right)^2$$

¹⁶ Cerdà (2010) page 56, Katznelson (2004) page 10, de Reyna (2002) page 21, Walnut (2002) pages 40–41, Heil (2011) page 440, Istrăţescu (1987) page 309

¹⁷ Katznelson (2004) page 11

¹⁸ Katznelson (2004) page 12

¹⁹ Katznelson (2004) page 12, Heil (2011) page 448

✎ PROOF:

1. Lemma: Proof that $\sin^2 \frac{x}{2} \equiv \frac{-1}{4}(e^{-ix} - 2 + e^{ix})$:

$$\begin{aligned} \sin^2 \frac{x}{2} &\equiv \left(\frac{e^{-i\frac{x}{2}} - e^{+i\frac{x}{2}}}{2i} \right)^2 && \text{by Euler Formulas (Corollary D.2 page 113)} \\ &\equiv \frac{-1}{4} \left(e^{-2i\frac{x}{2}} - 2e^{-i\frac{x}{2}}e^{i\frac{x}{2}} + e^{2i\frac{x}{2}} \right) \\ &\equiv \frac{-1}{4} (e^{-ix} - 2 + e^{ix}) : \end{aligned}$$

2. Lemma:

$$2|k| - |k+1| - |k-1| = \begin{cases} -2 & \text{for } k = 0 \\ 0 & \text{for } k \in \mathbb{Z} \setminus 0 \end{cases}$$

3. Proof that $K_n(x) = \frac{1}{n+1} \left(\frac{\sin \frac{n+1}{2}x}{\sin \frac{1}{2}x} \right)^2$:

$$\begin{aligned} &-4(n+1) \left(\sin \frac{1}{2}x \right)^2 K_n(x) \\ &= -4(n+1) \left(\frac{-1}{4} \right) (e^{-ix} - 2 + e^{ix}) K_n(x) && \text{by item (1)} \\ &= (n+1) (e^{-ix} - 2 + e^{ix}) \sum_{k=-n}^{k=n} \left(1 - \frac{|k|}{n+1} \right) e^{ikx} && \text{by Definition E.4} \\ &= (n+1) \frac{1}{n+1} (e^{-ix} - 2 + e^{ix}) \sum_{k=-n}^{k=n} (n+1 - |k|) e^{ikx} \\ &= e^{-ix} \sum_{k=-n}^{k=n} (n+1 - |k|) e^{ikx} - 2 \sum_{k=-n}^{k=n} (n+1 - |k|) e^{ikx} e^{ix} \sum_{k=-n}^{k=n} (n+1 - |k|) e^{ikx} \\ &= \sum_{k=-n}^{k=n} (n+1 - |k|) e^{i(k-1)x} - 2 \sum_{k=-n}^{k=n} (n+1 - |k|) e^{ikx} \sum_{k=-n}^{k=n} (n+1 - |k|) e^{i(k+1)x} \\ &= \sum_{k=-n-1}^{k=n-1} (n+1 - |k+1|) e^{ikx} - 2 \sum_{k=-n}^{k=n} (n+1 - |k|) e^{ikx} \sum_{k=-n+1}^{k=n+1} (n+1 - |k-1|) e^{ikx} \\ &= \underbrace{e^{-i(n+1)x}}_{k=-n-1} + \underbrace{2e^{-inx}}_{k=-n} + \sum_{k=-n+1}^{k=n-1} (n+1 - |k+1|) e^{ikx} + \\ &\quad \underbrace{-2e^{-inx}}_{k=-n} + \underbrace{-2e^{inx}}_{k=n} - 2 \sum_{k=-n+1}^{k=n-1} (n+1 - |k|) e^{ikx} + \\ &\quad \underbrace{e^{i(n+1)x}}_{k=n+1} + \underbrace{2e^{inx}}_{k=n} + \sum_{k=-n+1}^{k=n-1} (n+1 - |k-1|) e^{ikx} \\ &= e^{-i(n+1)x} + \sum_{k=-n+1}^{k=n-1} (n+1 - |k+1|) e^{ikx} + \\ &\quad -2 \sum_{k=-n+1}^{k=n-1} (n+1 - |k|) e^{ikx} + \\ &\quad e^{i(n+1)x} + \sum_{k=-n+1}^{k=n-1} (n+1 - |k-1|) e^{ikx} \end{aligned}$$

$$\begin{aligned}
&= e^{-i(n+1)x} + e^{i(n+1)x} + \sum_{k=-n+1}^{k=n-1} [(n+1-|k+1|) - 2(n+1-|k|) + (n+1-|k-1|)] e^{ikx} \\
&= e^{-i(n+1)x} + e^{i(n+1)x} + \sum_{k=-n+1}^{k=n-1} (2|k| - |k+1| - |k-1|) e^{ikx} \\
&= e^{-i(n+1)x} + e^{i(n+1)x} - 2 \quad \text{by item (2)} \\
&= -4 \left(\sin \frac{n+1}{2} x \right)^2 \quad \text{by item (1)}
\end{aligned}$$



Definition E.5. ²⁰ Let K_n be FEJÉR'S KERNEL (Definition E.4 page 143).

DEF The *de la Vallée Poussin kernel* V_n is defined as

$$V_n(x) \triangleq 2K_{2n+1}(x) - K_n(x)$$

Definition E.6. ²¹ Let K_n be FEJÉR'S KERNEL (Definition E.4 page 143).

DEF The *Jackson kernel* J_n is defined as

$$J_n(x) \triangleq \|K_n\|^{-2} K_n^2(x)$$

Definition E.7. ²²

DEF The *Poisson kernel* P is defined as

$$P(r, x) \triangleq \sum_{k \in \mathbb{Z}} r^{|k|} e^{ikx}$$

²⁰ Katznelson (2004) page 16

²¹ Katznelson (2004) page 17

²² Katznelson (2004) page 16

APPENDIX F

NORMED ALGEBRAS

F.1 Algebras

All *linear spaces* are equipped with an operation by which vectors in the spaces can be added together. Linear spaces also have an operation that allows a scalar and a vector to be “multiplied” together. But linear spaces in general have no operation that allows two vectors to be multiplied together. A linear space together with such an operator is an **algebra**.¹


There are many many possible algebras—many more than one can shake a stick at, as indicated by Michiel Hazewinkel in his book, *Handbook of Algebras*: “Algebra, as we know it today (2005), consists of many different ideas, concepts and results. A reasonable estimate of the number of these different items would be somewhere between 50,000 and 200,000. Many of these have been named and many more could (and perhaps should) have a “name” or other convenient designation.”²

Definition F.1.³ Let A be an ALGEBRA.


DEF An algebra A is **unital** if $\exists u \in A$ such that $ux = xu = x \quad \forall x \in A$


Definition F.2.⁴ Let A be an UNITAL ALGEBRA (Definition F.1 page 147) with unit e .

DEF The **spectrum** of $x \in A$ is $\sigma(x) \triangleq \{ \lambda \in \mathbb{C} \mid \lambda e - x \text{ is not invertible} \}$.
 The **resolvent** of $x \in A$ is $\rho_x(\lambda) \triangleq (\lambda e - x)^{-1} \quad \forall \lambda \notin \sigma(x)$.
 The **spectral radius** of $x \in A$ is $r(x) \triangleq \sup \{ |\lambda| \mid \lambda \in \sigma(x) \}$.

¹  Fuchs (1995) page 2

²  Hazewinkel (2000) page v

³  Folland (1995) page 1

⁴  Folland (1995) pages 3–4

F.2 Star-Algebras

Definition F.3.⁵ Let A be an ALGEBRA.


The pair $(A, *)$ is a ****-algebra***, or ***star-algebra***, if

1. $(x + y)^* = x^* + y^* \quad \forall x, y \in A$ (DISTRIBUTIVE) and
2. $(\alpha x)^* = \bar{\alpha} x^* \quad \forall x \in A, \alpha \in \mathbb{C}$ (CONJUGATE LINEAR) and
3. $(xy)^* = y^* x^* \quad \forall x, y \in A$ (ANTIAUTOMORPHIC) and
4. $x^{**} = x \quad \forall x \in A$ (INVOLUTORY)

The operator $*$ is called an ***involution*** on the algebra A .

Proposition F.1.⁶ Let $(A, *)$ be an UNITAL *-ALGEBRA.

PRP x is invertible $\implies \begin{cases} 1. x^* \text{ is INVERTIBLE } \forall x \in A \text{ and} \\ 2. (x^*)^{-1} = (x^{-1})^* \quad \forall x \in A \end{cases}$

 **PROOF:** Let e be the unit element of $(A, *)$.

1. Proof that $e^* = e$:

$$\begin{aligned}
 x e^* &= (x e^*)^{**} && \text{by involutory property of } * && (\text{Definition F.3 page 148}) \\
 &= (x^* e^{**})^* && \text{by antiautomorphic property of } * && (\text{Definition F.3 page 148}) \\
 &= (x^* e)^* && \text{by involutory property of } * && (\text{Definition F.3 page 148}) \\
 &= (x^*)^* && \text{by definition of } e \\
 &= x && \text{by involutory property of } * && (\text{Definition F.3 page 148}) \\
 e^* x &= (e^* x)^{**} && \text{by involutory property of } * && (\text{Definition F.3 page 148}) \\
 &= (e^{**} x^*)^* && \text{by antiautomorphic property of } * && (\text{Definition F.3 page 148}) \\
 &= (e x^*)^* && \text{by involutory property of } * && (\text{Definition F.3 page 148}) \\
 &= (x^*)^* && \text{by definition of } e \\
 &= x && \text{by involutory property of } * && (\text{Definition F.3 page 148})
 \end{aligned}$$


2. Proof that $(x^*)^{-1} = (x^{-1})^*$:


$$\begin{aligned}
 (x^{-1})^* (x^*) &= [x (x^{-1})]^* && \text{by antiautomorphic and involution properties of } * && (\text{Definition F.3 page 148}) \\
 &= e^* \\
 &= e && \text{by item (1) page 148} \\
 (x^*) (x^{-1})^* &= [x^{-1} x]^* && \text{by antiautomorphic and involution properties of } * && (\text{Definition F.3 page 148}) \\
 &= e^* \\
 &= e && \text{by item (1) page 148}
 \end{aligned}$$




Definition F.4.⁷ Let $(A, \|\cdot\|)$ be a *-ALGEBRA (Definition F.3 page 148).

 An element $x \in A$ is ***hermitian*** or ***self-adjoint*** if $x^* = x$.

 An element $x \in A$ is ***normal*** if $xx^* = x^*x$.

 An element $x \in A$ is a ***projection*** if $xx = x$ (INVOLUTORY) and $x^* = x$ (HERMITIAN).

⁵  Rickart (1960) page 178,  Gelfand and Naimark (1964), page 241

⁶  Folland (1995) page 5

⁷  Rickart (1960) page 178,  Gelfand and Naimark (1964), page 242

Theorem F.1. ⁸ Let $(A, \|\cdot\|)$ be a $*$ -ALGEBRA (Definition F.3 page 148).

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$$\underbrace{x = x^* \text{ and } y = y^*}_{x \text{ and } y \text{ are HERMITIAN}} \implies \begin{cases} x + y = (x + y)^* & (x + y \text{ is self adjoint}) \\ x^* = (x^*)^* & (x^* \text{ is self adjoint}) \\ xy = (xy)^* & (xy \text{ is HERMITIAN}) \\ xy = yx & \text{commutative} \end{cases}$$

 PROOF:

$$\begin{aligned} (x + y)^* &= x^* + y^* && \text{by distributive property of } * && (\text{Definition F.3 page 148}) \\ &= x + y && \text{by left hypothesis} \end{aligned}$$

$$(x^*)^* = x \quad \text{by involutory property of } * \quad (\text{Definition F.3 page 148})$$

Proof that $xy = (xy)^* \implies xy = yx$

$$\begin{aligned} xy &= (xy)^* && \text{by left hypothesis} \\ &= y^* x^* && \text{by antiautomorphic property of } * && (\text{Definition F.3 page 148}) \\ &= yx && \text{by left hypothesis} \end{aligned}$$

Proof that $xy = (xy)^* \iff xy = yx$

$$\begin{aligned} (xy)^* &= (yx)^* && \text{by left hypothesis} \\ &= x^* y^* && \text{by antiautomorphic property of } * && (\text{Definition F.3 page 148}) \\ &= xy && \text{by left hypothesis} \end{aligned}$$



Definition F.5 (Hermitian components). ⁹ Let $(A, \|\cdot\|)$ be a $*$ -ALGEBRA (Definition F.3 page 148).

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$$\begin{aligned} \text{The real part of } x \text{ is defined as } \mathbf{R}_e x &\triangleq \frac{1}{2}(x + x^*) \\ \text{The imaginary part of } x \text{ is defined as } \mathbf{I}_m x &\triangleq \frac{1}{2i}(x - x^*) \end{aligned}$$

Theorem F.2. ¹⁰ Let $(A, *)$ be a $*$ -ALGEBRA (Definition F.3 page 148).

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$$\begin{aligned} \mathbf{R}_e x &= (\mathbf{R}_e x)^* && \forall x \in A && (\mathbf{R}_e x \text{ is HERMITIAN}) \\ \mathbf{I}_m x &= (\mathbf{I}_m x)^* && \forall x \in A && (\mathbf{I}_m x \text{ is HERMITIAN}) \end{aligned}$$

 PROOF:

$$\begin{aligned} (\mathbf{R}_e x)^* &= \left(\frac{1}{2}(x + x^*) \right)^* && \text{by definition of } \mathfrak{R} && (\text{Definition F.5 page 149}) \\ &= \frac{1}{2}(x^* + x^{**}) && \text{by distributive property of } * && (\text{Definition F.3 page 148}) \\ &= \frac{1}{2}(x^* + x) && \text{by involutory property of } * && (\text{Definition F.3 page 148}) \\ &= \mathbf{R}_e x && \text{by definition of } \mathfrak{R} && (\text{Definition F.5 page 149}) \\ (\mathbf{I}_m x)^* &= \left(\frac{1}{2i}(x - x^*) \right)^* && \text{by definition of } \mathfrak{I} && (\text{Definition F.5 page 149}) \end{aligned}$$

⁸  Michel and Herget (1993) page 429

⁹  Michel and Herget (1993) page 430,  Rickart (1960) page 179,  Gelfand and Naimark (1964), page 242

¹⁰  Michel and Herget (1993) page 430,  Halmos (1998) page 42

$$\begin{aligned}
&= \frac{1}{2i}(x^* - x^{**}) && \text{by } \textit{distributive} \text{ property of } * && (\text{Definition F.3 page 148}) \\
&= \frac{1}{2i}(x^* - x) && \text{by } \textit{involutory} \text{ property of } * && (\text{Definition F.3 page 148}) \\
&= \mathbf{I}_m x && \text{by definition of } \mathfrak{I} && (\text{Definition F.5 page 149})
\end{aligned}$$

⇒

Theorem F.3 (Hermitian representation). ¹¹ Let $(A, *)$ be a $*$ -ALGEBRA (Definition F.3 page 148).

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$$a = x + iy \iff x = \mathbf{R}_e a \text{ and } y = \mathbf{I}_m a$$

✎ PROOF:

🔥 Proof that $a = x + iy \implies x = \mathbf{R}_e a$ and $y = \mathbf{I}_m a$:

$$\begin{aligned}
&\implies a = x + iy && \text{by left hypothesis} \\
&\implies a^* = (x + iy)^* && \text{by definition of } \textit{adjoint} && (\text{Definition F.4 page 148}) \\
&\quad = x^* - iy^* && \text{by } \textit{distributive} \text{ property of } * && (\text{Definition F.3 page 148}) \\
&\quad = x - iy && \text{by Theorem F.2 page 149} \\
&\implies x = a - iy && \text{by solving for } x \text{ in } a = x + iy \text{ equation} \\
&\quad x = a^* + iy && \text{by solving for } x \text{ in } a^* = x - iy \text{ equation} \\
&\implies x + x = a + a^* && \text{by adding previous 2 equations} \\
&\implies 2x = a + a^* && \text{by solving for } x \text{ in previous equation} \\
&\implies x = \frac{1}{2}(a + a^*) \\
&\quad = \mathbf{R}_e a && \text{by definition of } \mathfrak{R} && (\text{Definition F.5 page 149})
\end{aligned}$$

$$\begin{aligned}
&\quad iy = a - x && \text{by solving for } iy \text{ in } a = x + iy \text{ equation} \\
&\quad iy = -a^* + x && \text{by solving for } iy \text{ in } a^* = x - iy \text{ equation} \\
&\implies iy + iy = a - a^* && \text{by adding previous 2 equations} \\
&\implies y = \frac{1}{2i}(a - a^*) && \text{by solving for } iy \text{ in previous equations} \\
&\quad = \mathbf{I}_m a && \text{by definition of } \mathfrak{I} && (\text{Definition F.5 page 149})
\end{aligned}$$

🔥 Proof that $a = x + iy \iff x = \mathbf{R}_e a$ and $y = \mathbf{I}_m a$:

$$\begin{aligned}
x + iy &= \mathbf{R}_e a + i \mathbf{I}_m a && \text{by right hypothesis} \\
&= \underbrace{\frac{1}{2}(a + a^*)}_{\mathbf{R}_e a} + i \underbrace{\frac{1}{2i}(a - a^*)}_{\mathbf{I}_m a} && \text{by definition of } \mathfrak{R} \text{ and } \mathfrak{I} && (\text{Definition F.5 page 149}) \\
&= \left(\frac{1}{2}a + \frac{1}{2}a\right) + \left(\frac{1}{2}a^* - \frac{1}{2}a^*\right) \xrightarrow{0} \\
&= a
\end{aligned}$$

⇒

¹¹ Michel and Herget (1993) page 430, Rickart (1960) page 179, Gelfand and Neumark (1943b) page 7

F.3 Normed Algebras

Definition F.6. ¹² Let A be an algebra.

DEF The pair $(A, \|\cdot\|)$ is a **normed algebra** if

$$\|xy\| \leq \|x\| \|y\| \quad \forall x, y \in A \quad (\text{multiplicative condition})$$

A normed algebra $(A, \|\cdot\|)$ is a **Banach algebra** if $(A, \|\cdot\|)$ is also a Banach space.

Proposition F.2.

PRP $(A, \|\cdot\|)$ is a normed algebra \implies multiplication is **continuous** in $(A, \|\cdot\|)$

 PROOF:

1. Define $f(x) \triangleq zx$. That is, the function f represents multiplication of x times some arbitrary value z .
2. Let $\delta \triangleq \|x - y\|$ and $\epsilon \triangleq \|f(x) - f(y)\|$.
3. To prove that multiplication (f) is *continuous* with respect to the metric generated by $\|\cdot\|$, we have to show that we can always make ϵ arbitrarily small for some $\delta > 0$.
4. And here is the proof that multiplication is indeed continuous in $(A, \|\cdot\|)$:

$$\begin{aligned} \|f(x) - f(y)\| &\triangleq \|zx - zy\| && \text{by definition of } f && (\text{item (1) page 151}) \\ &= \|z(x - y)\| \\ &\leq \|z\| \|x - y\| && \text{by definition of normed algebra} && (\text{Definition F.6 page 151}) \\ &\triangleq \|z\| \delta && \text{by definition of } \delta && (\text{item (2) page 151}) \\ &\leq \epsilon && \text{for some value of } \delta > 0 \end{aligned}$$



Theorem F.4 (Gelfand-Mazur Theorem). ¹³ Let \mathbb{C} be the field of complex numbers.

THM $\left. \begin{array}{l} (A, \|\cdot\|) \text{ is a Banach algebra} \\ \text{every nonzero } x \in A \text{ is invertible} \end{array} \right\} \implies A \cong \mathbb{C} \quad (A \text{ is isomorphic to } \mathbb{C})$

F.4 C* Algebras




Definition F.7. ¹⁴





DEF The triple $(A, \|\cdot\|, *)$ is a **C* algebra** if

1. $(A, \|\cdot\|)$ is a Banach algebra and
2. $(A, *)$ is a *-algebra and
3. $\|x^*x\| = \|x\|^2 \quad \forall x \in A$

A C* algebra $(A, \|\cdot\|, *)$ is also called a **C star algebra**.

¹²  Rickart (1960) page 2,  Berberian (1961) page 103 (Theorem IV.9.2)

¹³  Folland (1995) page 4,  Mazur (1938) (statement),  Gelfand (1941) (proof)

¹⁴  Folland (1995) page 1,  Gelfand and Naimark (1964), page 241,  Gelfand and Neumark (1943a),  Gelfand and Neumark (1943b)

Theorem F.5. ¹⁵ *Let A be an algebra.*

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$(A, \|\cdot\|, *)$ is a C^* *algebra* $\implies \|x^*\| = \|x\|$

 PROOF:

$$\begin{aligned}
 \|x\| &= \frac{1}{\|x\|} \|x\|^2 \\
 &= \frac{1}{\|x\|} \|x^* x\| && \text{by definition of } C^* \text{-algebra} && (\text{Definition F.7 page 151}) \\
 &\leq \frac{1}{\|x\|} \|x^*\| \|x\| && \text{by definition of normed algebra} && (\text{Definition F.6 page 151}) \\
 &= \|x^*\| \\
 \|x^*\| &\leq \|x^{**}\| && \text{by previous result} \\
 &= \|x\| && \text{by involution property of } * && (\text{Definition F.3 page 148})
 \end{aligned}$$



¹⁵  Folland (1995) page 1,  Gelfand and Neumark (1943b) page 4,  Gelfand and Neumark (1943a)

APPENDIX G

OPERATORS ON LINEAR SPACES



“And I am not afraid to say that there is a way to advance algebra as far beyond what Vieta and Descartes have left us as Vieta and Descartes carried it beyond the ancients... we need still another analysis which is distinctly geometrical or linear, and which will express situation directly as algebra expresses magnitude directly.”

Gottfried Leibniz (1646–1716), German mathematician, in a September 8, 1679 letter to Christian Huygens. ¹

G.1 Operators on linear spaces

G.1.1 Operator Algebra

An operator is simply a function that maps from a linear space to another linear space (or to the same linear space).

Definition G.1. ² Let $(\mathbb{F}, +, \cdot, 0, 1)$ be a FIELD (Definition A.5 page 98). Let X be a set, let $+$ be an OPERATOR (Definition G.2 page 154) in X^{X^2} , and let \otimes be an operator in $X^{\mathbb{F} \times X}$.








¹ quote:  Leibniz (1679) pages 248–249

image: http://en.wikipedia.org/wiki/File:Gottfried_Wilhelm_von_Leibniz.jpg, public domain

²  Kubrusly (2001) pages 40–41 (Definition 2.1 and following remarks),  Haaser and Sullivan (1991) page 41,  Halmos (1948) pages 1–2,  Peano (1888a) (Chapter IX),  Peano (1888b) pages 119–120,  Banach (1922) pages 134–135

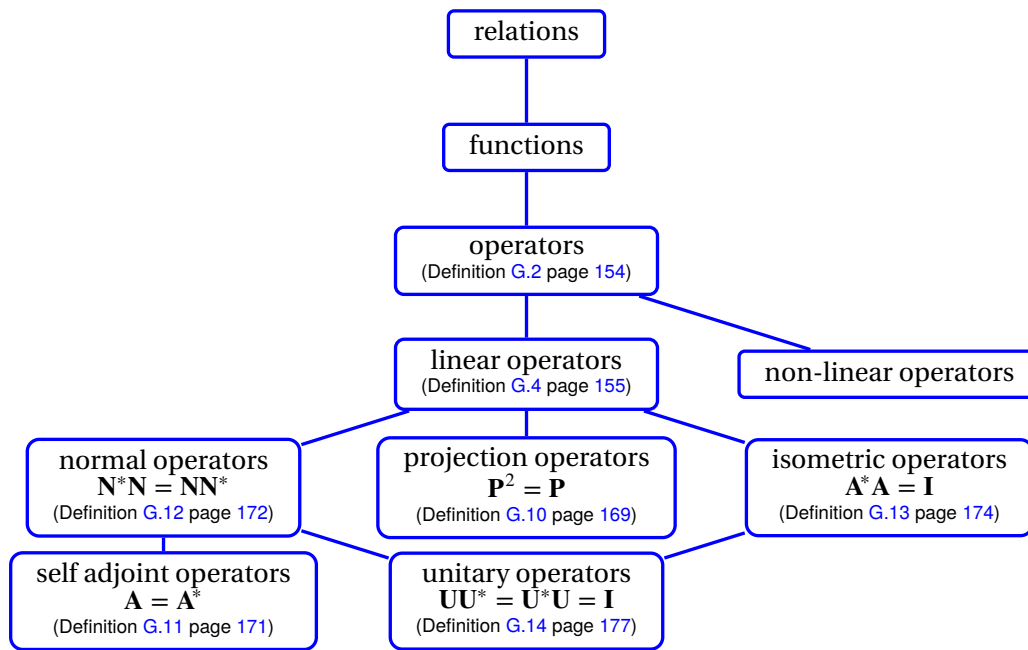


Figure G.1: Some operator types

The structure $\Omega \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ is a **linear space** over $(\mathbb{F}, +, \cdot, 0, 1)$ if

- | | | | | | | | |
|-------------|----|-------------------|-----------|---|--|-------------------------------|---|
| D
E
F | 1. | $\exists 0 \in X$ | such that | $x + 0 = x$ | $\forall x \in X$ | (+ IDENTITY) | * |
| | 2. | $\exists y \in X$ | such that | $x + y = 0$ | $\forall x \in X$ | (+ INVERSE) | |
| | 3. | | | $(x + y) + z = x + (y + z)$ | $\forall x, y, z \in X$ | (+ is ASSOCIATIVE) | |
| | 4. | | | $x + y = y + x$ | $\forall x, y \in X$ | (+ is COMMUTATIVE) | |
| | 5. | | | $1 \cdot x = x$ | $\forall x \in X$ | (· IDENTITY) | |
| | 6. | | | $\alpha \cdot (\beta \cdot x) = (\alpha \cdot \beta) \cdot x$ | $\forall \alpha, \beta \in S \text{ and } x \in X$ | (· ASSOCIATES with ·) | |
| | 7. | | | $\alpha \cdot (x + y) = (\alpha \cdot x) + (\alpha \cdot y)$ | $\forall \alpha \in S \text{ and } x, y \in X$ | (· DISTRIBUTES over +) | |
| | 8. | | | $(\alpha + \beta) \cdot x = (\alpha \cdot x) + (\beta \cdot x)$ | $\forall \alpha, \beta \in S \text{ and } x \in X$ | (· PSEUDO-DISTRIBUTES over +) | |

The set X is called the **underlying set**. The elements of X are called **vectors**. The elements of \mathbb{F} are called **scalars**. A linear space is also called a **vector space**. If $\mathbb{F} \triangleq \mathbb{R}$, then Ω is a **real linear space**. If $\mathbb{F} \triangleq \mathbb{C}$, then Ω is a **complex linear space**.

Definition G.2. ³

D E F A function A in Y^X is an **operator** in Y^X if X and Y are both LINEAR SPACES (Definition G.1 page 153).

Two operators A and B in Y^X are **equal** if $Ax = Bx$ for all $x \in X$. The inverse relation of an operator A in Y^X always exists as a *relation* in 2^{X^Y} , but may not always be a *function* (may not always be an operator) in Y^X .

The operator $I \in X^X$ is the *identity* operator if $Ix = x$ for all $x \in X$.

Definition G.3. ⁴ Let X^X be the set of all operators with from a LINEAR SPACE X to X . Let I be an operator in X^X . Let $\mathbb{I}(X)$ be the IDENTITY ELEMENT in X^X .

D E F I is the **identity operator** in X^X if $I = \mathbb{I}(X)$.

³ Heil (2011) page 42

⁴ Michel and Herget (1993) page 411

G.1.2 Linear operators

Definition G.4. ⁵ Let $\mathbf{X} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ and $\mathbf{Y} \triangleq (Y, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ be linear spaces.

An operator $\mathbf{L} \in \mathbf{Y}^{\mathbf{X}}$ is **linear** if

1. $\mathbf{L}(\mathbf{x} + \mathbf{y}) = \mathbf{L}\mathbf{x} + \mathbf{L}\mathbf{y} \quad \forall \mathbf{x}, \mathbf{y} \in \mathbf{X} \quad (\text{ADDITIVE}) \quad \text{and}$
2. $\mathbf{L}(\alpha \mathbf{x}) = \alpha \mathbf{L}\mathbf{x} \quad \forall \mathbf{x} \in \mathbf{X}, \quad \forall \alpha \in \mathbb{F} \quad (\text{HOMOGENEOUS}).$

The set of all linear operators from \mathbf{X} to \mathbf{Y} is denoted $\mathcal{L}(\mathbf{X}, \mathbf{Y})$ such that $\mathcal{L}(\mathbf{X}, \mathbf{Y}) \triangleq \{\mathbf{L} \in \mathbf{Y}^{\mathbf{X}} | \mathbf{L} \text{ is linear}\}$.

Theorem G.1. ⁶ Let \mathbf{L} be an operator from a linear space \mathbf{X} to a linear space \mathbf{Y} , both over a field \mathbb{F} .

$$\{\mathbf{L} \text{ is LINEAR}\} \implies \left\{ \begin{array}{l} 1. \mathbf{L}\mathbf{0} = \mathbf{0} \quad \text{and} \\ 2. \mathbf{L}(-\mathbf{x}) = -(\mathbf{L}\mathbf{x}) \quad \forall \mathbf{x} \in \mathbf{X} \quad \text{and} \\ 3. \mathbf{L}(\mathbf{x} - \mathbf{y}) = \mathbf{L}\mathbf{x} - \mathbf{L}\mathbf{y} \quad \forall \mathbf{x}, \mathbf{y} \in \mathbf{X} \quad \text{and} \\ 4. \mathbf{L}\left(\sum_{n=1}^N \alpha_n \mathbf{x}_n\right) = \sum_{n=1}^N \alpha_n (\mathbf{L}\mathbf{x}_n) \quad \mathbf{x}_n \in \mathbf{X}, \alpha_n \in \mathbb{F} \end{array} \right\}$$

 PROOF:

1. Proof that $\mathbf{L}\mathbf{0} = \mathbf{0}$:

$$\begin{aligned} \mathbf{L}\mathbf{0} &= \mathbf{L}(\mathbf{0} \cdot \mathbf{0}) && \text{by additive identity property} \\ &= \mathbf{0} \cdot (\mathbf{L}\mathbf{0}) && \text{by homogeneous property of } \mathbf{L} \quad (\text{Definition G.4 page 155}) \\ &= \mathbf{0} && \text{by additive identity property} \end{aligned}$$

2. Proof that $\mathbf{L}(-\mathbf{x}) = -(\mathbf{L}\mathbf{x})$:

$$\begin{aligned} \mathbf{L}(-\mathbf{x}) &= \mathbf{L}(-1 \cdot \mathbf{x}) && \text{by additive inverse property} \\ &= -1 \cdot (\mathbf{L}\mathbf{x}) && \text{by homogeneous property of } \mathbf{L} \quad (\text{Definition G.4 page 155}) \\ &= -(\mathbf{L}\mathbf{x}) && \text{by additive inverse property} \end{aligned}$$

3. Proof that $\mathbf{L}(\mathbf{x} - \mathbf{y}) = \mathbf{L}\mathbf{x} - \mathbf{L}\mathbf{y}$:

$$\begin{aligned} \mathbf{L}(\mathbf{x} - \mathbf{y}) &= \mathbf{L}(\mathbf{x} + (-\mathbf{y})) && \text{by additive inverse property} \\ &= \mathbf{L}(\mathbf{x}) + \mathbf{L}(-\mathbf{y}) && \text{by linearity property of } \mathbf{L} \quad (\text{Definition G.4 page 155}) \\ &= \mathbf{L}\mathbf{x} - \mathbf{L}\mathbf{y} && \text{by item (2)} \end{aligned}$$

4. Proof that $\mathbf{L}\left(\sum_{n=1}^N \alpha_n \mathbf{x}_n\right) = \sum_{n=1}^N \alpha_n (\mathbf{L}\mathbf{x}_n)$:

(a) Proof for $N = 1$:

$$\begin{aligned} \mathbf{L}\left(\sum_{n=1}^N \alpha_n \mathbf{x}_n\right) &= \mathbf{L}(\alpha_1 \mathbf{x}_1) && \text{by } N = 1 \text{ hypothesis} \\ &= \alpha_1 (\mathbf{L}\mathbf{x}_1) && \text{by homogeneous property of } \mathbf{L} \quad (\text{Definition G.4 page 155}) \end{aligned}$$

⁵  Kubrusly (2001) page 55,  Aliprantis and Burkinshaw (1998) page 224,  Hilbert et al. (1927) page 6,  Stone (1932) page 33

⁶  Berberian (1961) page 79 (Theorem IV.1.1)

(b) Proof that N case $\implies N + 1$ case:

$$\begin{aligned}
 \mathbf{L}\left(\sum_{n=1}^{N+1} \alpha_n \mathbf{x}_n\right) &= \mathbf{L}\left(\alpha_{N+1} \mathbf{x}_{N+1} + \sum_{n=1}^N \alpha_n \mathbf{x}_n\right) \\
 &= \mathbf{L}(\alpha_{N+1} \mathbf{x}_{N+1}) + \mathbf{L}\left(\sum_{n=1}^N \alpha_n \mathbf{x}_n\right) \quad \text{by linearity property of } \mathbf{L} \quad (\text{Definition G.4 page 155}) \\
 &= \alpha_{N+1} \mathbf{L}(\mathbf{x}_{N+1}) + \sum_{n=1}^N \mathbf{L}(\alpha_n \mathbf{x}_n) \quad \text{by left } N + 1 \text{ hypothesis} \\
 &= \sum_{n=1}^{N+1} \mathbf{L}(\alpha_n \mathbf{x}_n)
 \end{aligned}$$

\Rightarrow

Theorem G.2.⁷ Let $\mathcal{L}(\mathbf{X}, \mathbf{Y})$ be the set of all linear operators from a linear space \mathbf{X} to a linear space \mathbf{Y} . Let $\mathcal{N}(\mathbf{L})$ be the NULL SPACE of an operator \mathbf{L} in $\mathbf{Y}^{\mathbf{X}}$ and $\mathcal{J}(\mathbf{L})$ the IMAGE SET of \mathbf{L} in $\mathbf{Y}^{\mathbf{X}}$.

T H M	$\mathcal{L}(\mathbf{X}, \mathbf{Y})$	is a linear space	(space of linear transforms)
	$\mathcal{N}(\mathbf{L})$	is a linear subspace of \mathbf{X}	$\forall \mathbf{L} \in \mathbf{Y}^{\mathbf{X}}$
	$\mathcal{J}(\mathbf{L})$	is a linear subspace of \mathbf{Y}	$\forall \mathbf{L} \in \mathbf{Y}^{\mathbf{X}}$

 PROOF:

1. Proof that $\mathcal{N}(\mathbf{L})$ is a linear subspace of \mathbf{X} :

- (a) $\mathbf{0} \in \mathcal{N}(\mathbf{L}) \implies \mathcal{N}(\mathbf{L}) \neq \emptyset$
- (b) $\mathcal{N}(\mathbf{L}) \triangleq \{\mathbf{x} \in \mathbf{X} \mid \mathbf{L}\mathbf{x} = \mathbf{0}\} \subseteq \mathbf{X}$
- (c) $\mathbf{x} + \mathbf{y} \in \mathcal{N}(\mathbf{L}) \implies \mathbf{0} = \mathbf{L}(\mathbf{x} + \mathbf{y}) = \mathbf{L}(\mathbf{y} + \mathbf{x}) \implies \mathbf{y} + \mathbf{x} \in \mathcal{N}(\mathbf{L})$
- (d) $\alpha \in \mathbb{F}, \mathbf{x} \in \mathcal{N}(\mathbf{L}) \implies \mathbf{0} = \mathbf{L}\mathbf{x} \implies \mathbf{0} = \alpha \mathbf{L}\mathbf{x} \implies \mathbf{0} = \mathbf{L}(\alpha \mathbf{x}) \implies \alpha \mathbf{x} \in \mathcal{N}(\mathbf{L})$

2. Proof that $\mathcal{J}(\mathbf{L})$ is a linear subspace of \mathbf{Y} :

- (a) $\mathbf{0} \in \mathcal{J}(\mathbf{L}) \implies \mathcal{J}(\mathbf{L}) \neq \emptyset$
- (b) $\mathcal{J}(\mathbf{L}) \triangleq \{\mathbf{y} \in \mathbf{Y} \mid \exists \mathbf{x} \in \mathbf{X} \text{ such that } \mathbf{y} = \mathbf{L}\mathbf{x}\} \subseteq \mathbf{Y}$
- (c) $\mathbf{x} + \mathbf{y} \in \mathcal{J}(\mathbf{L}) \implies \exists \mathbf{v} \in \mathbf{X} \text{ such that } \mathbf{L}\mathbf{v} = \mathbf{x} + \mathbf{y} = \mathbf{y} + \mathbf{x} \implies \mathbf{y} + \mathbf{x} \in \mathcal{J}(\mathbf{L})$
- (d) $\alpha \in \mathbb{F}, \mathbf{x} \in \mathcal{J}(\mathbf{L}) \implies \exists \mathbf{x} \in \mathbf{X} \text{ such that } \mathbf{y} = \mathbf{L}\mathbf{x} \implies \alpha \mathbf{y} = \alpha \mathbf{L}\mathbf{x} = \mathbf{L}(\alpha \mathbf{x}) \implies \alpha \mathbf{x} \in \mathcal{J}(\mathbf{L})$

\Rightarrow

Example G.1.⁸ Let $\mathcal{C}([a : b], \mathbb{R})$ be the set of all *continuous* functions from the closed real interval $[a : b]$ to \mathbb{R} .

E X $\mathcal{C}([a : b], \mathbb{R})$ is a linear space.

Theorem G.3.⁹ Let $\mathcal{L}(\mathbf{X}, \mathbf{Y})$ be the set of linear operators from a linear space \mathbf{X} to a linear space \mathbf{Y} . Let $\mathcal{N}(\mathbf{L})$ be the NULL SPACE of a linear operator $\mathbf{L} \in \mathcal{L}(\mathbf{X}, \mathbf{Y})$.

T H M	$\mathbf{L}\mathbf{x} = \mathbf{L}\mathbf{y}$	\iff	$\mathbf{x} - \mathbf{y} \in \mathcal{N}(\mathbf{L})$
	\mathbf{L} is INJECTIVE	\iff	$\mathcal{N}(\mathbf{L}) = \{\mathbf{0}\}$

⁷ Michel and Herget (1993) pages 98–104, Berberian (1961) pages 80–85 (Theorem IV.1.4 and Theorem IV.3.1)

⁸ Eidelman et al. (2004) page 3

⁹ Berberian (1961) page 88 (Theorem IV.1.4)

✎ PROOF:

1. Proof that $\mathbf{L}x = \mathbf{L}y \implies x - y \in \mathcal{N}(\mathbf{L})$:

$$\begin{aligned} \mathbf{L}(x - y) &= \mathbf{L}x - \mathbf{L}y && \text{by Theorem G.1 page 155} \\ &= \mathbf{0} && \text{by left hypothesis} \\ \implies x - y &\in \mathcal{N}(\mathbf{L}) && \text{by definition of Null Space} \end{aligned}$$

2. Proof that $\mathbf{L}x = \mathbf{L}y \iff x - y \in \mathcal{N}(\mathbf{L})$:

$$\begin{aligned} \mathbf{L}y &= \mathbf{L}y + \mathbf{0} && \text{by definition of linear space (Definition G.1 page 153)} \\ &= \mathbf{L}y + \mathbf{L}(x - y) && \text{by right hypothesis} \\ &= \mathbf{L}y + (\mathbf{L}x - \mathbf{L}y) && \text{by Theorem G.1 page 155} \\ &= (\mathbf{L}y - \mathbf{L}y) + \mathbf{L}x && \text{by associative and commutative properties (Definition G.1 page 153)} \\ &= \mathbf{L}x \end{aligned}$$

3. Proof that \mathbf{L} is *injective* $\iff \mathcal{N}(\mathbf{L}) = \{\mathbf{0}\}$:

$$\begin{aligned} \mathbf{L} \text{ is injective} &\iff \{(\mathbf{L}x = \mathbf{L}y \iff x = y) \mid \forall x, y \in X\} \\ &\iff \{[\mathbf{L}x - \mathbf{L}y = \mathbf{0} \iff (x - y) = \mathbf{0}] \mid \forall x, y \in X\} \\ &\iff \{[\mathbf{L}(x - y) = \mathbf{0} \iff (x - y) = \mathbf{0}] \mid \forall x, y \in X\} \\ &\iff \mathcal{N}(\mathbf{L}) = \{\mathbf{0}\} \end{aligned}$$

⇒

Theorem G.4. ¹⁰ Let W, X, Y , and Z be linear spaces over a field \mathbb{F} .

T H M	1. $\mathbf{L}(\mathbf{M}\mathbf{N}) = (\mathbf{L}\mathbf{M})\mathbf{N}$	$\forall \mathbf{L} \in \mathcal{L}(Z, W), \mathbf{M} \in \mathcal{L}(Y, Z), \mathbf{N} \in \mathcal{L}(X, Y)$	(ASSOCIATIVE)
	2. $\mathbf{L}(\mathbf{M} \dot{+} \mathbf{N}) = (\mathbf{L}\mathbf{M}) \dot{+} (\mathbf{L}\mathbf{N})$	$\forall \mathbf{L} \in \mathcal{L}(Y, Z), \mathbf{M} \in \mathcal{L}(X, Y), \mathbf{N} \in \mathcal{L}(X, Y)$	(LEFT DISTRIBUTIVE)
	3. $(\mathbf{L} \dot{+} \mathbf{M})\mathbf{N} = (\mathbf{L}\mathbf{N}) \dot{+} (\mathbf{M}\mathbf{N})$	$\forall \mathbf{L} \in \mathcal{L}(Y, Z), \mathbf{M} \in \mathcal{L}(Y, Z), \mathbf{N} \in \mathcal{L}(X, Y)$	(RIGHT DISTRIBUTIVE)
	4. $\alpha(\mathbf{L}\mathbf{M}) = (\alpha\mathbf{L})\mathbf{M} = \mathbf{L}(\alpha\mathbf{M})$	$\forall \mathbf{L} \in \mathcal{L}(Y, Z), \mathbf{M} \in \mathcal{L}(X, Y), \alpha \in \mathbb{F}$	(HOMOGENEOUS)

✎ PROOF:

1. Proof that $\mathbf{L}(\mathbf{M}\mathbf{N}) = (\mathbf{L}\mathbf{M})\mathbf{N}$: Follows directly from property of *associative* operators.

2. Proof that $\mathbf{L}(\mathbf{M} \dot{+} \mathbf{N}) = (\mathbf{L}\mathbf{M}) \dot{+} (\mathbf{L}\mathbf{N})$:


$$\begin{aligned} [\mathbf{L}(\mathbf{M} \dot{+} \mathbf{N})]x &= \mathbf{L}[(\mathbf{M} \dot{+} \mathbf{N})x] \\ &= \mathbf{L}[(\mathbf{M}x) \dot{+} (\mathbf{N}x)] \\ &= [\mathbf{L}(\mathbf{M}x)] \dot{+} [\mathbf{L}(\mathbf{N}x)] && \text{by additive property Definition G.4 page 155} \\ &= [(\mathbf{L}\mathbf{M})x] \dot{+} [(\mathbf{L}\mathbf{N})x] \end{aligned}$$

3. Proof that $(\mathbf{L} \dot{+} \mathbf{M})\mathbf{N} = (\mathbf{L}\mathbf{N}) \dot{+} (\mathbf{M}\mathbf{N})$: Follows directly from property of *associative* operators.

4. Proof that $\alpha(\mathbf{L}\mathbf{M}) = (\alpha\mathbf{L})\mathbf{M}$: Follows directly from *associative* property of linear operators.

5. Proof that $\alpha(\mathbf{L}\mathbf{M}) = \mathbf{L}(\alpha\mathbf{M})$:

$$\begin{aligned} [\alpha(\mathbf{L}\mathbf{M})]x &= \alpha[(\mathbf{L}\mathbf{M})x] \\ &= \mathbf{L}[\alpha(\mathbf{M}x)] && \text{by homogeneous property Definition G.4 page 155} \\ &= \mathbf{L}[(\alpha\mathbf{M})x] \\ &= [\mathbf{L}(\alpha\mathbf{M})]x \end{aligned}$$

¹⁰  Berberian (1961) page 88 (Theorem IV.5.1)



Theorem G.5 (Fundamental theorem of linear equations).¹¹ Let $\mathcal{Y}^{\mathcal{X}}$ be the set of all operators from a linear space \mathcal{X} to a linear space \mathcal{Y} . Let $\mathcal{N}(\mathbf{L})$ be the NULL SPACE of an operator \mathbf{L} in $\mathcal{Y}^{\mathcal{X}}$ and $\mathcal{J}(\mathbf{L})$ the IMAGE SET of \mathbf{L} in $\mathcal{Y}^{\mathcal{X}}$.

$$\text{THM} \quad \dim \mathcal{J}(\mathbf{L}) + \dim \mathcal{N}(\mathbf{L}) = \dim \mathcal{X} \quad \forall \mathbf{L} \in \mathcal{Y}^{\mathcal{X}}$$

PROOF: Let $\{\psi_k | k = 1, 2, \dots, p\}$ be a basis for \mathcal{X} constructed such that $\{\psi_{p-n+1}, \psi_{p-n+2}, \dots, \psi_p\}$ is a basis for $\mathcal{N}(\mathbf{L})$.

Let $p \triangleq \dim \mathcal{X}$.

Let $n \triangleq \dim \mathcal{N}(\mathbf{L})$.

$$\begin{aligned} \dim \mathcal{J}(\mathbf{L}) &= \dim \{y \in \mathcal{Y} | \exists x \in \mathcal{X} \text{ such that } y = \mathbf{L}x\} \\ &= \dim \left\{ y \in \mathcal{Y} | \exists (\alpha_1, \alpha_2, \dots, \alpha_p) \text{ such that } y = \mathbf{L} \sum_{k=1}^p \alpha_k \psi_k \right\} \\ &= \dim \left\{ y \in \mathcal{Y} | \exists (\alpha_1, \alpha_2, \dots, \alpha_p) \text{ such that } y = \sum_{k=1}^p \alpha_k \mathbf{L} \psi_k \right\} \\ &= \dim \left\{ y \in \mathcal{Y} | \exists (\alpha_1, \alpha_2, \dots, \alpha_p) \text{ such that } y = \sum_{k=1}^{p-n} \alpha_k \mathbf{L} \psi_k + \sum_{k=1}^n \alpha_k \mathbf{L} \psi_k \right\} \\ &= \dim \left\{ y \in \mathcal{Y} | \exists (\alpha_1, \alpha_2, \dots, \alpha_p) \text{ such that } y = \sum_{k=1}^{p-n} \alpha_k \mathbf{L} \psi_k + \mathbf{0} \right\} \\ &= p - n \\ &= \dim \mathcal{X} - \dim \mathcal{N}(\mathbf{L}) \end{aligned}$$

Note: This “proof” may be missing some necessary detail.



G.2 Operators on Normed linear spaces

G.2.1 Operator norm

Definition G.5.¹² Let $\mathcal{V} = (\mathcal{X}, \mathbb{F}, \hat{+}, \cdot)$ be a linear space and \mathbb{F} be a field with absolute value function $|\cdot| \in \mathbb{R}^{\mathbb{F}}$ (Definition A.4 page 98).

A **norm** is any functional $\|\cdot\|$ in $\mathbb{R}^{\mathcal{X}}$ that satisfies

- | | | | | |
|----|--|--|------------------------------------|-----|
| 1. | $\ \mathbf{x}\ \geq 0$ | $\forall \mathbf{x} \in \mathcal{X}$ | (STRICTLY POSITIVE) | and |
| 2. | $\ \mathbf{x}\ = 0 \iff \mathbf{x} = \mathbf{0}$ | $\forall \mathbf{x} \in \mathcal{X}$ | (NONDEGENERATE) | and |
| 3. | $\ a\mathbf{x}\ = a \ \mathbf{x}\ $ | $\forall \mathbf{x} \in \mathcal{X}, a \in \mathbb{C}$ | (HOMOGENEOUS) | and |
| 4. | $\ \mathbf{x} + \mathbf{y}\ \leq \ \mathbf{x}\ + \ \mathbf{y}\ $ | $\forall \mathbf{x}, \mathbf{y} \in \mathcal{X}$ | (SUBADDITIVE/triangle inequality). | |

A **normed linear space** is the pair $(\mathcal{V}, \|\cdot\|)$.

¹¹ Michel and Herget (1993) page 99

¹² Aliprantis and Burkinshaw (1998) pages 217–218, Banach (1932a) page 53, Banach (1932b) page 33, Banach (1922) page 135

Definition G.6. ¹³ Let $\mathcal{L}(X, Y)$ be the space of linear operators over normed linear spaces X and Y .
¹⁴

DEF

The **operator norm** $\|\cdot\|$ is defined as

$$\|A\| \triangleq \sup_{x \in X} \{\|Ax\| \mid \|x\| \leq 1\} \quad \forall A \in \mathcal{L}(X, Y)$$

The pair $(\mathcal{L}(X, Y), \|\cdot\|)$ is the **normed space of linear operators** on (X, Y) .

Proposition G.1 (next) shows that the functional defined in Definition G.6 (previous) is a *norm* (Definition G.5 page 158).

Proposition G.1. ¹⁵ Let $(\mathcal{L}(X, Y), \|\cdot\|)$ be the normed space of linear operators over the normed linear spaces $X \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$ and $Y \triangleq (Y, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$.

PRP

The functional $\|\cdot\|$ is a **norm** on $\mathcal{L}(X, Y)$. In particular,

- | | | | | |
|----|--------------------------------------|--|-----------------|-----|
| 1. | $\ A\ \geq 0$ | $\forall A \in \mathcal{L}(X, Y)$ | (NON-NEGATIVE) | and |
| 2. | $\ A\ = 0 \iff A \dot{=} 0$ | $\forall A \in \mathcal{L}(X, Y)$ | (NONDEGENERATE) | and |
| 3. | $\ \alpha A\ = \alpha \ A\ $ | $\forall A \in \mathcal{L}(X, Y), \alpha \in \mathbb{F}$ | (HOMOGENEOUS) | and |
| 4. | $\ A \dot{+} B\ \leq \ A\ + \ B\ $ | $\forall A \in \mathcal{L}(X, Y)$ | (SUBADDITIVE). | |

Moreover, $(\mathcal{L}(X, Y), \|\cdot\|)$ is a **normed linear space**.

PROOF:

1. Proof that $\|A\| > 0$ for $A \neq 0$:

$$\begin{aligned} \|A\| &\triangleq \sup_{x \in X} \{\|Ax\| \mid \|x\| \leq 1\} \\ &> 0 \end{aligned}$$

by definition of $\|\cdot\|$ (Definition G.6 page 159)

2. Proof that $\|A\| = 0$ for $A \dot{=} 0$:

$$\begin{aligned} \|A\| &\triangleq \sup_{x \in X} \{\|Ax\| \mid \|x\| \leq 1\} \\ &= \sup_{x \in X} \{\|0x\| \mid \|x\| \leq 1\} \\ &= 0 \end{aligned}$$

by definition of $\|\cdot\|$ (Definition G.6 page 159)

3. Proof that $\|\alpha A\| = |\alpha| \|A\|$:

$$\begin{aligned} \|\alpha A\| &\triangleq \sup_{x \in X} \{\|\alpha Ax\| \mid \|x\| \leq 1\} \\ &= \sup_{x \in X} \{|\alpha| \|Ax\| \mid \|x\| \leq 1\} \\ &= |\alpha| \sup_{x \in X} \{\|Ax\| \mid \|x\| \leq 1\} \\ &= |\alpha| \|A\| \end{aligned}$$

by definition of $\|\cdot\|$ (Definition G.6 page 159)

by definition of $\|\cdot\|$ (Definition G.6 page 159)

by definition of sup

by definition of $\|\cdot\|$ (Definition G.6 page 159)

¹³ Rudin (1991) page 92, Aliprantis and Burkinshaw (1998) page 225

¹⁴ The operator norm notation $\|\cdot\|$ is introduced (as a Matrix norm) in

Horn and Johnson (1990) page 290

¹⁵ Rudin (1991) page 93

4. Proof that $\|A \dot{+} B\| \leq \|A\| + \|B\|$:

$$\begin{aligned}
 \|A \dot{+} B\| &\triangleq \sup_{x \in X} \{ \|(A \dot{+} B)x\| \mid \|x\| \leq 1 \} && \text{by definition of } \|\cdot\| \text{ (Definition G.6 page 159)} \\
 &= \sup_{x \in X} \{ \|Ax + Bx\| \mid \|x\| \leq 1 \} \\
 &\leq \sup_{x \in X} \{ \|Ax\| + \|Bx\| \mid \|x\| \leq 1 \} && \text{by definition of } \|\cdot\| \text{ (Definition G.6 page 159)} \\
 &\leq \sup_{x \in X} \{ \|Ax\| \mid \|x\| \leq 1 \} + \sup_{x \in X} \{ \|Bx\| \mid \|x\| \leq 1 \} \\
 &\triangleq \|A\| + \|B\| && \text{by definition of } \|\cdot\| \text{ (Definition G.6 page 159)}
 \end{aligned}$$

⇒

Lemma G.1. Let $(\mathcal{L}(X, Y), \|\cdot\|)$ be the normed space of linear operators over normed linear spaces $X \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$ and $Y \triangleq (Y, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$.

LEM $\|L\| = \sup_x \{ \|Lx\| \mid \|x\| = 1 \} \quad \forall x \in \mathcal{L}(X, Y)$

PROOF: 16

1. Proof that $\sup_x \{ \|Lx\| \mid \|x\| \leq 1 \} \geq \sup_x \{ \|Lx\| \mid \|x\| = 1 \}$:

$$\sup_x \{ \|Lx\| \mid \|x\| \leq 1 \} \geq \sup_x \{ \|Lx\| \mid \|x\| = 1 \} \quad \text{because } A \subseteq B \implies \sup A \leq \sup B$$

2. Let the subset $Y \subsetneq X$ be defined as

$$Y \triangleq \left\{ y \in X \mid \begin{array}{l} 1. \ \|Ly\| = \sup_{x \in X} \{ \|Lx\| \mid \|x\| \leq 1 \} \text{ and} \\ 2. \ 0 < \|y\| \leq 1 \end{array} \right\}$$

3. Proof that $\sup_x \{ \|Lx\| \mid \|x\| \leq 1 \} \leq \sup_x \{ \|Lx\| \mid \|x\| = 1 \}$:

$$\begin{aligned}
 \sup_{x \in X} \{ \|Lx\| \mid \|x\| \leq 1 \} &= \|Ly\| && \text{by definition of set } Y \\
 &= \frac{\|y\|}{\|y\|} \|Ly\| \\
 &= \|y\| \left\| \frac{1}{\|y\|} Ly \right\| && \text{by homogeneous property (page 158)} \\
 &= \|y\| \left\| L \frac{y}{\|y\|} \right\| && \text{by homogeneous property (page 155)} \\
 &\leq \|y\| \sup_{y \in Y} \left\{ \left\| L \frac{y}{\|y\|} \right\| \right\} && \text{by definition of supremum} \\
 &= \|y\| \sup_{y \in Y} \left\{ \left\| L \frac{y}{\|y\|} \right\| \mid \left\| \frac{y}{\|y\|} \right\| = 1 \right\} && \text{because } \left\| \frac{y}{\|y\|} \right\| = 1 \text{ for all } y \in Y \\
 &\leq \sup_{y \in Y} \left\{ \left\| L \frac{y}{\|y\|} \right\| \mid \left\| \frac{y}{\|y\|} \right\| = 1 \right\} && \text{because } 0 < \|y\| \leq 1 \\
 &\leq \sup_{x \in X} \{ \|Lx\| \mid \|x\| = 1 \} && \text{because } \frac{y}{\|y\|} \in X \quad \forall y \in Y
 \end{aligned}$$

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email



Many many thanks to former NCTU Ph.D. student [Chien Yao](#) (Chinese: 姚建; PinYin: Yáo Jiàn) for his brilliant help with this proof. (If you are viewing this text as a pdf file, zoom in on the figure to the left to see text from Chien Yao's 2007 April 16 email.)

4. By (1) and (3),

$$\sup_{x \in X} \{\|Lx\| \mid \|x\| \leq 1\} = \sup_{x \in X} \{\|Lx\| \mid \|x\| = 1\}$$

⇒

Proposition G.2. ¹⁷ Let \mathbf{I} be the identity operator in the normed space of linear operators $(\mathcal{L}(X, X), \|\cdot\|)$.

P R P	$\ \mathbf{I}\ = 1$
-------------	----------------------

PROOF:

$$\begin{aligned} \|\mathbf{I}\| &\triangleq \sup \{\|\mathbf{I}x\| \mid \|x\| \leq 1\} && \text{by definition of } \|\cdot\| \text{ (Definition G.6 page 159)} \\ &= \sup \{\|x\| \mid \|x\| \leq 1\} && \text{by definition of } \mathbf{I} \text{ (Definition G.3 page 154)} \\ &= 1 \end{aligned}$$

⇒

Theorem G.6. ¹⁸ Let $(\mathcal{L}(X, Y), \|\cdot\|)$ be the normed space of linear operators over normed linear spaces X and Y .

T H M	$\ Lx\ \leq \ \mathbf{L}\ \ x\ \quad \forall L \in \mathcal{L}(X, Y), x \in X$ $\ \mathbf{KL}\ \leq \ \mathbf{K}\ \ \mathbf{L}\ \quad \forall K, L \in \mathcal{L}(X, Y)$
-------------	--

PROOF:

1. Proof that $\|Lx\| \leq \|\mathbf{L}\| \|x\|$:

$$\begin{aligned} \|Lx\| &= \frac{\|x\|}{\|x\|} \|Lx\| \\ &= \|x\| \left\| \frac{1}{\|x\|} Lx \right\| && \text{by property of norms} \\ &= \|x\| \left\| L \frac{x}{\|x\|} \right\| && \text{by property of linear operators} \\ &\triangleq \|x\| \|Ly\| && \text{where } y \triangleq \frac{x}{\|x\|} \\ &\leq \|x\| \sup_y \|Ly\| && \text{by definition of supremum} \\ &= \|x\| \sup_y \{\|Ly\| \mid \|y\| = 1\} && \text{because } \|y\| = \left\| \frac{x}{\|x\|} \right\| = \frac{\|x\|}{\|x\|} = 1 \\ &\triangleq \|x\| \|\mathbf{L}\| && \text{by definition of operator norm} \end{aligned}$$

¹⁷ Michel and Herget (1993) page 410

¹⁸ Rudin (1991) page 103, Aliprantis and Burkinshaw (1998) page 225

2. Proof that $\|KL\| \leq \|K\| \|L\|$:

$$\begin{aligned}
 \|KL\| &\triangleq \sup_{x \in X} \{ \|(KL)x\| \mid \|x\| \leq 1 \} && \text{by Definition G.6 page 159 } (\|\cdot\|) \\
 &= \sup_{x \in X} \{ \|K(Lx)\| \mid \|x\| \leq 1 \} \\
 &\leq \sup_{x \in X} \{ \|K\| \|Lx\| \mid \|x\| \leq 1 \} && \text{by 1.} \\
 &\leq \sup_{x \in X} \{ \|K\| \|L\| \|x\| \mid \|x\| \leq 1 \} && \text{by 1.} \\
 &= \sup_{x \in X} \{ \|K\| \|L\| 1 \mid \|x\| \leq 1 \} && \text{by definition of sup} \\
 &= \|K\| \|L\| && \text{by definition of sup}
 \end{aligned}$$

⇒

G.2.2 Bounded linear operators

Definition G.7. ¹⁹ Let $(\mathcal{L}(X, Y), \|\cdot\|)$ be a normed space of linear operators.

DEF

An operator B is **bounded** if $\|B\| < \infty$.

The quantity $\mathcal{B}(X, Y)$ is the set of all **bounded linear operators** on (X, Y) such that

$$\mathcal{B}(X, Y) \triangleq \{L \in \mathcal{L}(X, Y) \mid \|L\| < \infty\}.$$

Theorem G.7. ²⁰ Let $(\mathcal{L}(X, Y), \|\cdot\|)$ be the set of linear operators over normed linear spaces $X \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$ and $Y \triangleq (Y, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$.

THEM

The following conditions are all EQUIVALENT:

- | | | |
|---|--|--------|
| 1. L is continuous at a SINGLE POINT $x_0 \in X$ | $\forall L \in \mathcal{L}(X, Y)$ | \iff |
| 2. L is CONTINUOUS (at every point $x \in X$) | $\forall L \in \mathcal{L}(X, Y)$ | \iff |
| 3. $\ L\ < \infty$ (L is BOUNDED) | $\forall L \in \mathcal{L}(X, Y)$ | \iff |
| 4. $\exists M \in \mathbb{R}$ such that $\ Lx\ \leq M \ x\ $ | $\forall L \in \mathcal{L}(X, Y), x \in X$ | |

✎ PROOF:

1. Proof that 1 \implies 2:

$$\begin{aligned}
 \epsilon &> \|Lx - Lx_0\| && \text{by hypothesis 1} \\
 &= \|L(x - x_0)\| && \text{by linearity (Definition G.4 page 155)} \\
 &= \|L(x + y - x_0 - y)\| \\
 &= \|L(x + y) - L(x_0 + y)\| && \text{by linearity (Definition G.4 page 155)} \\
 &\implies L \text{ is continuous at point } x + y \\
 &\implies L \text{ is continuous at every point in } X && \text{(hypothesis 2)}
 \end{aligned}$$

2. Proof that 2 \implies 1: obvious:

¹⁹ Rudin (1991) pages 92–93

²⁰ Aliprantis and Burkinshaw (1998) page 227

3. Proof that 4 \Rightarrow 2:²¹

$$\begin{aligned}
 \|Lx\| \leq M \|x\| &\Rightarrow \|L(x-y)\| \leq M \|x-y\| && \text{by hypothesis 4} \\
 &\Rightarrow \|Lx - Ly\| \leq M \|x-y\| && \text{by linearity of } L \text{ (Definition G.4 page 155)} \\
 &\Rightarrow \|Lx - Ly\| \leq \epsilon \text{ whenever } M \|x-y\| < \epsilon \\
 &\Rightarrow \|Lx - Ly\| \leq \epsilon \text{ whenever } \|x-y\| < \frac{\epsilon}{M} && \text{(hypothesis 2)}
 \end{aligned}$$

4. Proof that 3 \Rightarrow 4:

$$\begin{aligned}
 \|Lx\| &\leq \underbrace{\|L\|}_M \|x\| && \text{by Theorem G.6 page 161} \\
 &= M \|x\| && \text{where } M \triangleq \|L\| < \infty \text{ (by hypothesis 1)}
 \end{aligned}$$

5. Proof that 1 \Rightarrow 3:²²

$$\begin{aligned}
 \|L\| = \infty &\Rightarrow \{\|Lx\| \mid \|x\| \leq 1\} = \infty \\
 &\Rightarrow \exists (x_n) \text{ such that } \|x_n\| = 1 \text{ and } \|L\| = \{\|Lx_n\| \mid \|x_n\| \leq 1\} = \infty \\
 &\Rightarrow \|x_n\| = 1 \text{ and } \infty = \|L\| = \|Lx_n\| \\
 &\Rightarrow \|x_n\| = 1 \text{ and } \|Lx_n\| \geq n \\
 &\Rightarrow \frac{1}{n} \|x_n\| = \frac{1}{n} \text{ and } \frac{1}{n} \|Lx_n\| \geq 1 \\
 &\Rightarrow \left\| \frac{x_n}{n} \right\| = \frac{1}{n} \text{ and } \left\| L \frac{x_n}{n} \right\| \geq 1 \\
 &\Rightarrow \lim_{n \rightarrow \infty} \left\| \frac{x_n}{n} \right\| = 0 \text{ and } \lim_{n \rightarrow \infty} \left\| L \frac{x_n}{n} \right\| \geq 1 \\
 &\Rightarrow L \text{ is not continuous at } 0
 \end{aligned}$$

But by hypothesis, L is continuous. So the statement $\|L\| = \infty$ must be *false* and thus $\|L\| < \infty$ (L is *bounded*).



G.2.3 Adjoints on normed linear spaces

Definition G.8. Let $\mathcal{B}(X, Y)$ be the space of BOUNDED LINEAR OPERATORS on normed linear spaces X and Y . Let X^* be the TOPOLOGICAL DUAL SPACE of X .

DEF B^* is the *adjoint* of an operator $B \in \mathcal{B}(X, Y)$ if

$$f(Bx) = [B^*f](x) \quad \forall f \in X^*, x \in X$$

Theorem G.8.²³ Let $\mathcal{B}(X, Y)$ be the space of BOUNDED LINEAR OPERATORS on NORMED LINEAR SPACES X and Y .

THEM	$(A \circ B)^* = A^* \circ B^*$	$\forall A, B \in \mathcal{B}(X, Y)$
	$(\lambda A)^* = \lambda A^*$	$\forall A, B \in \mathcal{B}(X, Y)$
	$(AB)^* = B^*A^*$	$\forall A, B \in \mathcal{B}(X, Y)$

²¹ Bollobás (1999) page 29

²² Aliprantis and Burkinshaw (1998) page 227

²³ Bollobás (1999) page 156

✎ PROOF:

$$[A \circ B]^* f(x) = f([A \circ B]x) \quad \text{by definition of adjoint} \quad (\text{Definition G.8 page 163})$$

$$= f(Ax + Bx) \quad \text{by definition of linear operators} \quad (\text{Definition G.4 page 155})$$

$$= f(Ax) + f(Bx) \quad \text{by definition of linear functional}$$

$$= A^* f(x) + B^* f(x) \quad \text{by definition of adjoint} \quad (\text{Definition G.8 page 163})$$

$$= [A^* + B^*] f(x) \quad \text{by definition of linear functional}$$

$$[\lambda A]^* f(x) = f([\lambda A]x) \quad \text{by definition of adjoint} \quad (\text{Definition G.8 page 163})$$

$$= \lambda f(Ax) \quad \text{by definition of linear functional}$$

$$= [\lambda A^*] f(x) \quad \text{by definition of adjoint} \quad (\text{Definition G.8 page 163})$$

$$[AB]^* f(x) = f([AB]x) \quad \text{by definition of adjoint} \quad (\text{Definition G.8 page 163})$$

$$= f(A[Bx]) \quad \text{by definition of linear operators} \quad (\text{Definition G.4 page 155})$$

$$= [A^* f](Bx) \quad \text{by definition of adjoint} \quad (\text{Definition G.8 page 163})$$

$$= B^* [A^* f](x) \quad \text{by definition of adjoint} \quad (\text{Definition G.8 page 163})$$

$$= [B^* A^*] f(x) \quad \text{by definition of adjoint} \quad (\text{Definition G.8 page 163})$$

⇒

Theorem G.9. ²⁴ Let $\mathcal{B}(X, Y)$ be the space of BOUNDED LINEAR OPERATORS on normed linear spaces X and Y . Let B^* be the adjoint of an operator B .

T H M	$\ B\ = \ B^*\ \quad \forall B \in \mathcal{B}(X, Y)$
-------------	---

✎ PROOF:

$$\|B\| \triangleq \sup \{ \|Bx\| \mid \|x\| \leq 1 \} \quad \text{by Definition G.6 page 159}$$

$$\triangleq \sup \{ |g(Bx; y^*)| \mid \|x\| \leq 1, \|y^*\| \leq 1 \}$$

$$= \sup \{ |f(x; B^* y^*)| \mid \|x\| \leq 1, \|y^*\| \leq 1 \}$$

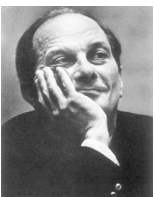
$$\triangleq \sup \{ \|B^* y^*\| \mid \|x\| \leq 1, \|y^*\| \leq 1 \}$$

$$= \sup \{ \|B^* y^*\| \mid \|y^*\| \leq 1 \}$$

$$\triangleq \|B^*\| \quad \text{by Definition G.6 page 159}$$

⇒

G.2.4 More properties



“Beginning with the third year of studies, most of my mathematical work was really started in conversations with Mazur and Banach. And according to Banach some of my own contributions were characterized by a certain “strangeness” in the formulation of problems and in the outline of possible proofs. As he told me once some years later, he was surprised how often these “strange” approaches really worked.”

Stanislaus M. Ulam (1909–1984), Polish mathematician ²⁵

²⁴ Rudin (1991) page 98

Theorem G.10 (Mazur-Ulam theorem).²⁶ Let $\phi \in \mathcal{L}(X, Y)$ be a function on normed linear spaces $(X, \|\cdot\|_X)$ and $(Y, \|\cdot\|_Y)$. Let $I \in \mathcal{L}(X, X)$ be the identity operator on $(X, \|\cdot\|_X)$.

T H M	$\left. \begin{array}{l} 1. \underbrace{\phi^{-1}\phi = \phi\phi^{-1} = I}_{\text{bijective}} \\ 2. \underbrace{\ \phi x - \phi y\ _Y = \ x - y\ _X}_{\text{isometric}} \quad \forall x, y \in X \end{array} \right\} \text{ and } \Rightarrow \underbrace{\phi([1 - \lambda]x + \lambda y) = [1 - \lambda]\phi x + \lambda\phi y}_{\text{affine}} \quad \forall \lambda \in \mathbb{R}$
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PROOF: Proof not yet complete.

1. Let ψ be the *reflection* of z in X such that $\psi x = 2z - x$

(a) $\|\psi x - z\| = \|x - z\|$

2. Let $\lambda \triangleq \sup_g \{\|gz - z\|\}$

3. Proof that $g \in W \implies g^{-1} \in W$:

Let $\hat{x} \triangleq g^{-1}x$ and $\hat{y} \triangleq g^{-1}y$.

$\ g^{-1}x - g^{-1}y\ = \ \hat{x} - \hat{y}\ $	by definition of \hat{x} and \hat{y}
$= \ g\hat{x} - g\hat{y}\ $	by left hypothesis
$= \ gg^{-1}x - gg^{-1}y\ $	by definition of \hat{x} and \hat{y}
$= \ x - y\ $	by definition of g^{-1}

4. Proof that $gz = z$:

$2\lambda = 2 \sup \{\ gz - z\ \}$	by definition of λ item (2)
$\leq 2\ gz - z\ $	by definition of sup
$= \ 2z - 2gz\ $	
$= \ \psi gz - gz\ $	by definition of ψ item (1)
$= \ g^{-1}\psi gz - g^{-1}gz\ $	by item (3)
$= \ g^{-1}\psi gz - z\ $	by definition of g^{-1}
$= \ \psi g^{-1}\psi gz - z\ $	
$= \ g^*z - z\ $	
$\leq \lambda$	by definition of λ item (2)
$\implies 2\lambda \leq \lambda$	
$\implies \lambda = 0$	
$\implies gz = z$	

5. Proof that $\phi\left(\frac{1}{2}x + \frac{1}{2}y\right) = \frac{1}{2}\phi x + \frac{1}{2}\phi y$:

$$\begin{aligned} \phi\left(\frac{1}{2}x + \frac{1}{2}y\right) &= \\ &= \frac{1}{2}\phi x + \frac{1}{2}\phi y \end{aligned}$$

²⁵ quote: [Ulam \(1991\)](#) page 33

image: <http://www-history.mcs.st-andrews.ac.uk/Biographies/Ulam.html>

²⁶ [Oikhberg and Rosenthal \(2007\)](#) page 598, [Väisälä \(2003\)](#) page 634, [Giles \(2000\)](#) page 11, [Dunford and Schwartz \(1957\)](#) page 91, [Mazur and Ulam \(1932\)](#)

6. Proof that $\phi([1 - \lambda]\mathbf{x} + \lambda\mathbf{y}) = [1 - \lambda]\phi\mathbf{x} + \lambda\phi\mathbf{y}$:

$$\begin{aligned}\phi([1 - \lambda]\mathbf{x} + \lambda\mathbf{y}) &= \\ &= [1 - \lambda]\phi\mathbf{x} + \lambda\phi\mathbf{y}\end{aligned}$$

⇒

Theorem G.11 (Neumann Expansion Theorem).²⁷ Let $\mathbf{A} \in \mathbf{X}^{\mathbf{X}}$ be an operator on a linear space \mathbf{X} . Let $\mathbf{A}^0 \triangleq \mathbf{I}$.

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$$\left. \begin{array}{l} 1. \quad \mathbf{A} \in \mathcal{B}(\mathbf{X}, \mathbf{X}) \quad (\mathbf{A} \text{ is bounded}) \\ 2. \quad \|\mathbf{A}\| < 1 \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} 1. \quad (\mathbf{I} - \mathbf{A})^{-1} \text{ exists} \\ 2. \quad \|(\mathbf{I} - \mathbf{A})^{-1}\| \leq \frac{1}{1 - \|\mathbf{A}\|} \\ 3. \quad (\mathbf{I} - \mathbf{A})^{-1} = \sum_{n=0}^{\infty} \mathbf{A}^n \\ \text{with uniform convergence} \end{array} \right.$$

G.3 Operators on Inner product spaces

G.3.1 General Results

Definition G.9.²⁸ Let $\Omega \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ be a linear space.

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A function $\langle \triangle | \nabla \rangle \in \mathbb{F}^{X \times X}$ is an **inner product** on Ω if

1. $\langle \mathbf{x} | \mathbf{x} \rangle \geq 0 \quad \forall \mathbf{x} \in X$ (non-negative) and
2. $\langle \mathbf{x} | \mathbf{x} \rangle = 0 \iff \mathbf{x} = \mathbf{0} \quad \forall \mathbf{x} \in X$ (nondegenerate) and
3. $\langle \alpha \mathbf{x} | \mathbf{y} \rangle = \alpha \langle \mathbf{x} | \mathbf{y} \rangle \quad \forall \mathbf{x}, \mathbf{y} \in X, \forall \alpha \in \mathbb{C}$ (homogeneous) and
4. $\langle \mathbf{x} + \mathbf{y} | \mathbf{u} \rangle = \langle \mathbf{x} | \mathbf{u} \rangle + \langle \mathbf{y} | \mathbf{u} \rangle \quad \forall \mathbf{x}, \mathbf{y}, \mathbf{u} \in X$ (additive) and
5. $\langle \mathbf{x} | \mathbf{y} \rangle = \langle \mathbf{y} | \mathbf{x} \rangle^* \quad \forall \mathbf{x}, \mathbf{y} \in X$ (conjugate symmetric).

An inner product is also called a **scalar product**.

An **inner product space** is the pair $(\Omega, \langle \triangle | \nabla \rangle)$.

Theorem G.12.²⁹ Let $\mathbf{A}, \mathbf{B} \in \mathcal{B}(\mathbf{X}, \mathbf{X})$ be BOUNDED LINEAR OPERATORS on an inner product space $\mathbf{X} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$.

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$$\begin{aligned} \langle \mathbf{B}\mathbf{x} | \mathbf{x} \rangle &= 0 \quad \forall \mathbf{x} \in X & \iff & \mathbf{B}\mathbf{x} = \mathbf{0} \quad \forall \mathbf{x} \in X \\ \langle \mathbf{A}\mathbf{x} | \mathbf{x} \rangle &= \langle \mathbf{B}\mathbf{x} | \mathbf{x} \rangle \quad \forall \mathbf{x} \in X & \iff & \mathbf{A} = \mathbf{B} \end{aligned}$$

✎ PROOF:

²⁷ Michel and Herget (1993) page 415

²⁸ Haaser and Sullivan (1991) page 277, Aliprantis and Burkinshaw (1998) page 276, Peano (1888b) page 72

²⁹ Rudin (1991) page 310 (Theorem 12.7, Corollary)

1. Proof that $\langle \mathbf{B}x | x \rangle = 0 \implies \mathbf{B}x = \mathbf{0}$:

$$\begin{aligned}
 0 &= \langle \mathbf{B}(x + \mathbf{B}x) | (x + \mathbf{B}x) \rangle + i \langle \mathbf{B}(x + i\mathbf{B}x) | (x + i\mathbf{B}x) \rangle && \text{by left hypothesis} \\
 &= \{ \langle \mathbf{B}x + \mathbf{B}^2x | x + \mathbf{B}x \rangle \} + i \{ \langle \mathbf{B}x + i\mathbf{B}^2x | x + i\mathbf{B}x \rangle \} && \text{by Definition G.4 page 155} \\
 &= \{ \langle \mathbf{B}x | x \rangle + \langle \mathbf{B}x | \mathbf{B}x \rangle + \langle \mathbf{B}^2x | x \rangle + \langle \mathbf{B}^2x | \mathbf{B}x \rangle \} && \text{by Definition G.9 page 166} \\
 &\quad + i \{ \langle \mathbf{B}x | x \rangle - i \langle \mathbf{B}x | \mathbf{B}x \rangle + i \langle \mathbf{B}^2x | x \rangle - i^2 \langle \mathbf{B}^2x | \mathbf{B}x \rangle \} \\
 &= \{ 0 + \langle \mathbf{B}x | \mathbf{B}x \rangle + \langle \mathbf{B}^2x | x \rangle + 0 \} + i \{ 0 - i \langle \mathbf{B}x | \mathbf{B}x \rangle + i \langle \mathbf{B}^2x | x \rangle - i^2 0 \} && \text{by left hypothesis} \\
 &= \{ \langle \mathbf{B}x | \mathbf{B}x \rangle + \langle \mathbf{B}^2x | x \rangle \} + \{ \langle \mathbf{B}x | \mathbf{B}x \rangle - \langle \mathbf{B}^2x | x \rangle \} \\
 &= 2 \langle \mathbf{B}x | \mathbf{B}x \rangle \\
 &= 2 \|\mathbf{B}x\|^2 \\
 &\implies \mathbf{B}x = \mathbf{0} && \text{by Definition G.5 page 158}
 \end{aligned}$$

2. Proof that $\langle \mathbf{B}x | x \rangle = 0 \iff \mathbf{B}x = \mathbf{0}$: by property of inner products.

3. Proof that $\langle \mathbf{A}x | x \rangle = \langle \mathbf{B}x | x \rangle \implies \mathbf{A} \doteq \mathbf{B}$:

$$\begin{aligned}
 0 &= \langle \mathbf{A}x | x \rangle - \langle \mathbf{B}x | x \rangle && \text{by left hypothesis} \\
 &= \langle \mathbf{A}x - \mathbf{B}x | x \rangle && \text{by additivity property of } \langle \triangle | \nabla \rangle \text{ (Definition G.9 page 166)} \\
 &= \langle (\mathbf{A} - \mathbf{B})x | x \rangle && \text{by definition of operator addition} \\
 \implies (\mathbf{A} - \mathbf{B})x &= \mathbf{0} && \text{by item 1} \\
 \implies \mathbf{A} &= \mathbf{B} && \text{by definition of operator subtraction}
 \end{aligned}$$

4. Proof that $\langle \mathbf{A}x | x \rangle = \langle \mathbf{B}x | x \rangle \iff \mathbf{A} \doteq \mathbf{B}$:

$$\langle \mathbf{A}x | x \rangle = \langle \mathbf{B}x | x \rangle \quad \text{by } \mathbf{A} \doteq \mathbf{B} \text{ hypothesis}$$



G.3.2 Operator adjoint

A fundamental concept of operators on inner product spaces is the *operator adjoint* (Proposition G.3 page 167). The adjoint of an operator is a kind of generalization of the conjugate of a complex number in that

Both are *star-algebras* (Theorem G.13 page 168).

Both support decomposition into “real” and “imaginary” parts (Theorem F.3 page 150).

Structurally, the operator adjoint provides a convenient symmetric relationship between the *range space* and *Null Space* of an operator (Theorem G.14 page 169).

Proposition G.3. ³⁰ Let $\mathcal{B}(\mathbf{H}, \mathbf{H})$ be the space of BOUNDED LINEAR OPERATORS (Definition G.7 page 162) on a HILBERT SPACE \mathbf{H} .

P R P An operator \mathbf{B}^* is the **adjoint** of $\mathbf{B} \in \mathcal{B}(\mathbf{H}, \mathbf{H})$ if
 $\langle \mathbf{B}x | y \rangle = \langle x | \mathbf{B}^*y \rangle \quad \forall x, y \in \mathbf{H}.$

PROOF:

³⁰ Michel and Herget (1993) page 220, Rudin (1991) page 311, Giles (2000) page 182, von Neumann (1929) page 49, Stone (1932) page 41

1. For fixed y , $f(x) \triangleq \langle x | y \rangle$ is a *functional* in \mathbb{F}^X .
2. \mathbf{B}^* is the *adjoint* of \mathbf{B} because

$$\begin{aligned}
 \langle \mathbf{B}x | y \rangle &\triangleq f(\mathbf{B}x) \\
 &\triangleq \mathbf{B}^*f(x) && \text{by definition of operator adjoint} && (\text{Definition G.8 page 163}) \\
 &= \langle x | \mathbf{B}^*y \rangle
 \end{aligned}$$



Example G.2.

In matrix algebra (“linear algebra”)

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- The inner product operation $\langle x | y \rangle$ is represented by $y^H x$.
- The linear operator is represented as a matrix \mathbf{A} .
- The operation of \mathbf{A} on a vector x is represented as $\mathbf{A}x$.
- The adjoint of matrix \mathbf{A} is the Hermitian matrix \mathbf{A}^H .

PROOF:

$$\langle \mathbf{A}x | y \rangle \triangleq y^H \mathbf{A}x = [(\mathbf{A}x)^H y]^H = [x^H \mathbf{A}^H y]^H = (\mathbf{A}^H y)^H x \triangleq \langle x | \mathbf{A}^H y \rangle$$



Structures that satisfy the four conditions of the next theorem are known as **-algebras* (“*star-algebras*” (Definition F.3 page 148). Other structures which are **-algebras* include the *field of complex numbers* \mathbb{C} and any *ring of complex square* $n \times n$ *matrices*.³¹

Theorem G.13 (operator star-algebra).³² *Let \mathbf{H} be a HILBERT SPACE with operators $\mathbf{A}, \mathbf{B} \in \mathcal{B}(\mathbf{H}, \mathbf{H})$ and with adjoints $\mathbf{A}^*, \mathbf{B}^* \in \mathcal{B}(\mathbf{H}, \mathbf{H})$. Let $\bar{\alpha}$ be the complex conjugate of some $\alpha \in \mathbb{C}$.*

*The pair $(\mathbf{H}, *)$ is a *-ALGEBRA (STAR-ALGEBRA). In particular,*

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- | | | | | |
|----|---|---|--------------------|-----|
| 1. | $(\mathbf{A} \dot{+} \mathbf{B})^* = \mathbf{A}^* + \mathbf{B}^*$ | $\forall \mathbf{A}, \mathbf{B} \in \mathbf{H}$ | (DISTRIBUTIVE) | and |
| 2. | $(\alpha \mathbf{A})^* = \bar{\alpha} \mathbf{A}^*$ | $\forall \mathbf{A}, \mathbf{B} \in \mathbf{H}$ | (CONJUGATE LINEAR) | and |
| 3. | $(\mathbf{A}\mathbf{B})^* = \mathbf{B}^* \mathbf{A}^*$ | $\forall \mathbf{A}, \mathbf{B} \in \mathbf{H}$ | (ANTI-AUTOMORPHIC) | and |
| 4. | $\mathbf{A}^{**} = \mathbf{A}$ | $\forall \mathbf{A}, \mathbf{B} \in \mathbf{H}$ | (INVOLUTARY) | |

PROOF:

$$\begin{aligned}
 \langle x | (\mathbf{A} \dot{+} \mathbf{B})^* y \rangle &= \langle (\mathbf{A} \dot{+} \mathbf{B})x | y \rangle && \text{by definition of adjoint} && (\text{Proposition G.3 page 167}) \\
 &= \langle \mathbf{A}x | y \rangle + \langle \mathbf{B}x | y \rangle && \text{by definition of inner product} && (\text{Definition G.9 page 166}) \\
 &= \langle x | \mathbf{A}^* y \rangle + \langle x | \mathbf{B}^* y \rangle && \text{by definition of operator addition} \\
 &= \langle x | \mathbf{A}^* y + \mathbf{B}^* y \rangle && \text{by definition of inner product} && (\text{Definition G.9 page 166}) \\
 &= \langle x | (\mathbf{A}^* + \mathbf{B}^*) y \rangle && \text{by definition of operator addition}
 \end{aligned}$$

$$\begin{aligned}
 \langle x | (\alpha \mathbf{A})^* y \rangle &= \langle (\alpha \mathbf{A})x | y \rangle && \text{by definition of adjoint} && (\text{Proposition G.3 page 167}) \\
 &= \langle \alpha(\mathbf{A}x) | y \rangle && \text{by definition of scalar multiplication} \\
 &= \alpha \langle \mathbf{A}x | y \rangle && \text{by definition of inner product} && (\text{Definition G.9 page 166}) \\
 &= \alpha \langle x | \mathbf{A}^* y \rangle && \text{by definition of adjoint} && (\text{Proposition G.3 page 167}) \\
 &= \langle x | \alpha^* \mathbf{A}^* y \rangle && \text{by definition of inner product} && (\text{Definition G.9 page 166})
 \end{aligned}$$

³¹ Sakai (1998) page 1

³² Halmos (1998) pages 39–40, Rudin (1991) page 311

$\langle x (AB)^* y \rangle = \langle (AB)x y \rangle$	by definition of adjoint	(Proposition G.3 page 167)
$= \langle A(Bx) y \rangle$	by definition of operator multiplication	
$= \langle (Bx) A^* y \rangle$	by definition of adjoint	(Proposition G.3 page 167)
$= \langle x B^* A^* y \rangle$	by definition of adjoint	(Proposition G.3 page 167)
$\langle x A^{**} y \rangle = \langle A^* x y \rangle$	by definition of adjoint	(Proposition G.3 page 167)
$= \langle y A^* x \rangle^*$	by definition of inner product	(Definition G.9 page 166)
$= \langle Ay x \rangle^*$	by definition of adjoint	(Proposition G.3 page 167)
$= \langle x Ay \rangle$	by definition of inner product	(Definition G.9 page 166)

⇒

Theorem G.14. ³³ Let Y^X be the set of all operators from a linear space X to a linear space Y . Let $\mathcal{N}(\mathbf{L})$ be the NULL SPACE of an operator \mathbf{L} in Y^X and $\mathcal{J}(\mathbf{L})$ the IMAGE SET of \mathbf{L} in Y^X .

T H M	$\mathcal{N}(\mathbf{A}) = \mathcal{J}(\mathbf{A}^*)^\perp$
	$\mathcal{N}(\mathbf{A}^*) = \mathcal{J}(\mathbf{A})^\perp$

 PROOF:

$$\begin{aligned}
 \mathcal{J}(\mathbf{A}^*)^\perp &= \{y \in H \mid \langle y | u \rangle = 0 \quad \forall u \in \mathcal{J}(\mathbf{A}^*)\} \\
 &= \{y \in H \mid \langle y | \mathbf{A}^* x \rangle = 0 \quad \forall x \in H\} \\
 &= \{y \in H \mid \langle \mathbf{A} y | x \rangle = 0 \quad \forall x \in H\} && \text{by definition of } \mathbf{A}^* && \text{(Proposition G.3 page 167)} \\
 &= \{y \in H \mid \mathbf{A} y = 0\} \\
 &= \mathcal{N}(\mathbf{A}) && \text{by definition of } \mathcal{N}(\mathbf{A})
 \end{aligned}$$

$$\begin{aligned}
 \mathcal{J}(\mathbf{A})^\perp &= \{y \in H \mid \langle y | u \rangle = 0 \quad \forall u \in \mathcal{J}(\mathbf{A})\} \\
 &= \{y \in H \mid \langle y | \mathbf{A} x \rangle = 0 \quad \forall x \in H\} && \text{by definition of } \mathcal{J} \\
 &= \{y \in H \mid \langle \mathbf{A}^* y | x \rangle = 0 \quad \forall x \in H\} && \text{by definition of } \mathbf{A}^* && \text{(Proposition G.3 page 167)} \\
 &= \{y \in H \mid \mathbf{A}^* y = 0\} \\
 &= \mathcal{N}(\mathbf{A}^*) && \text{by definition of } \mathcal{N}(\mathbf{A}^*)
 \end{aligned}$$


⇒





G.4 Special Classes of Operators

G.4.1 Projection operators

Definition G.10. ³⁴ Let $\mathcal{B}(X, Y)$ be the space of BOUNDED LINEAR OPERATORS on normed linear spaces X and Y . Let \mathbf{P} be a bounded linear operator in $\mathcal{B}(X, Y)$.

D E F	\mathbf{P} is a projection operator if $\mathbf{P}^2 = \mathbf{P}$.
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³³  Rudin (1991) page 312

³⁴  Rudin (1991) page 126 (5.15 Projections),  Kubrusly (2001) page 70,  Bachman and Narici (1966) page 26,  Halmos (1958) page 73 (S41. Projections)

Theorem G.15. ³⁵ Let $\mathcal{B}(\mathbf{X}, \mathbf{Y})$ be the space of BOUNDED LINEAR OPERATORS on normed linear spaces \mathbf{X} and \mathbf{Y} . Let \mathbf{P} be a bounded linear operator in $\mathcal{B}(\mathbf{X}, \mathbf{Y})$ with NULL SPACE $\mathcal{N}(\mathbf{P})$ and IMAGE SET $\mathcal{J}(\mathbf{P})$.

T H M	1. $\mathbf{P}^2 = \mathbf{P}$ (\mathbf{P} is a projection operator) and	}	\implies	{	1. $\mathcal{J}(\mathbf{P}) = \mathbf{X}$ and
	2. $\mathbf{\Omega} = \mathbf{X} \hat{+} \mathbf{Y}$ (\mathbf{Y} compliments \mathbf{X} in $\mathbf{\Omega}$) and				2. $\mathcal{N}(\mathbf{P}) = \mathbf{Y}$ and
	3. $\mathbf{P}\mathbf{\Omega} = \mathbf{X}$ (\mathbf{P} projects onto \mathbf{X})				3. $\mathbf{\Omega} = \mathcal{J}(\mathbf{P}) \hat{+} \mathcal{N}(\mathbf{P})$

PROOF:

$$\begin{aligned}
 \mathcal{J}(\mathbf{P}) &= \mathbf{P}\mathbf{\Omega} \\
 &= \mathbf{P}(\mathbf{\Omega}_1 + \mathbf{\Omega}_2) \\
 &= \mathbf{P}\mathbf{\Omega}_1 + \mathbf{P}\mathbf{\Omega}_2 \\
 &= \mathbf{\Omega}_1 + \{0\} \\
 &= \mathbf{\Omega}_1
 \end{aligned}$$

$$\begin{aligned}
 \mathcal{N}(\mathbf{P}) &= \{x \in \mathbf{\Omega} | \mathbf{P}x = 0\} \\
 &= \{x \in (\mathbf{\Omega}_1 + \mathbf{\Omega}_2) | \mathbf{P}x = 0\} \\
 &= \{x \in \mathbf{\Omega}_1 | \mathbf{P}x = 0\} + \{x \in \mathbf{\Omega}_2 | \mathbf{P}x = 0\} \\
 &= \{0\} + \mathbf{\Omega}_2 \\
 &= \mathbf{\Omega}_2
 \end{aligned}$$

\Rightarrow

Theorem G.16. ³⁶ Let $\mathcal{B}(\mathbf{X}, \mathbf{Y})$ be the space of BOUNDED LINEAR OPERATORS on normed linear spaces \mathbf{X} and \mathbf{Y} . Let \mathbf{P} be a bounded linear operator in $\mathcal{B}(\mathbf{X}, \mathbf{Y})$.

T H M	$\mathbf{P}^2 = \mathbf{P}$ \iff $(\mathbf{I} - \mathbf{P})^2 = (\mathbf{I} - \mathbf{P})$
	\mathbf{P} is a projection operator $(\mathbf{I} - \mathbf{P})$ is a projection operator

PROOF:

Proof that $\mathbf{P}^2 = \mathbf{P} \implies (\mathbf{I} - \mathbf{P})^2 = (\mathbf{I} - \mathbf{P})$:

$$\begin{aligned}
 (\mathbf{I} - \mathbf{P})^2 &= (\mathbf{I} - \mathbf{P})(\mathbf{I} - \mathbf{P}) \\
 &= \mathbf{I}(\mathbf{I} - \mathbf{P}) + (-\mathbf{P})(\mathbf{I} - \mathbf{P}) \\
 &= \mathbf{I} - \mathbf{P} - \mathbf{P}\mathbf{I} + \mathbf{P}^2 \\
 &= \mathbf{I} - \mathbf{P} - \mathbf{P} + \mathbf{P} && \text{by left hypothesis} \\
 &= \mathbf{I} - \mathbf{P}
 \end{aligned}$$

Proof that $\mathbf{P}^2 = \mathbf{P} \iff (\mathbf{I} - \mathbf{P})^2 = (\mathbf{I} - \mathbf{P})$:

$$\begin{aligned}
 \mathbf{P}^2 &= \underbrace{\mathbf{I} - \mathbf{P} - \mathbf{P} + \mathbf{P}^2}_{(\mathbf{I} - \mathbf{P})^2} - (\mathbf{I} - \mathbf{P} - \mathbf{P}) \\
 &= (\mathbf{I} - \mathbf{P})^2 - (\mathbf{I} - \mathbf{P} - \mathbf{P}) \\
 &= (\mathbf{I} - \mathbf{P}) - (\mathbf{I} - \mathbf{P} - \mathbf{P}) && \text{by right hypothesis} \\
 &= \mathbf{P}
 \end{aligned}$$

\Rightarrow

³⁵ Michel and Herget (1993) pages 120–121

³⁶ Michel and Herget (1993) page 121

Theorem G.17. ³⁷ Let H be a HILBERT SPACE and P an operator in H^H with adjoint P^* , NULL SPACE $\mathcal{N}(P)$, and IMAGE SET $\mathcal{J}(P)$.

If P is a PROJECTION OPERATOR, then the following are equivalent:

- | | | | | |
|----------------------|----|---|------------------------|--------|
| T
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M | 1. | $P^* = P$ | (P is SELF-ADJOINT) | \iff |
| | 2. | $P^*P = PP^*$ | (P is NORMAL) | \iff |
| | 3. | $\mathcal{J}(P) = \mathcal{N}(P)^\perp$ | | \iff |
| | 4. | $\langle Px x \rangle = \ Px\ ^2 \quad \forall x \in X$ | | |

✎PROOF: This proof is incomplete at this time.

Proof that (1) \implies (2):

$$\begin{aligned} P^*P &= P^{**}P^* && \text{by (1)} \\ &= PP^* && \text{by Theorem G.13 page 168} \end{aligned}$$

Proof that (1) \implies (3):

$$\begin{aligned} \mathcal{J}(P) &= \mathcal{N}(P^*)^\perp && \text{by Theorem G.14 page 169} \\ &= \mathcal{N}(P)^\perp && \text{by (1)} \end{aligned}$$

Proof that (3) \implies (4):

Proof that (4) \implies (1):

\Rightarrow

G.4.2 Self Adjoint Operators

Definition G.11. ³⁸ Let $B \in \mathcal{B}(H, H)$ be a BOUNDED operator with adjoint B^* on a HILBERT SPACE H .

DEF The operator B is said to be **self-adjoint** or **hermitian** if $B \stackrel{\circ}{=} B^*$.

Example G.3 (Autocorrelation operator). Let $x(t)$ be a random process with autocorrelation

$$R_{xx}(t, u) \triangleq \underbrace{E[x(t)x^*(u)]}_{\text{expectation}}$$

Let an autocorrelation operator R be defined as $[Rf](t) \triangleq \int_{\mathbb{R}} \underbrace{R_{xx}(t, u)}_{\text{kernel}} f(u) du$.

EX $R = R^*$ (The auto-correlation operator R is self-adjoint)

Theorem G.18. ³⁹ Let $S : H \rightarrow H$ be an operator over a HILBERT SPACE H with eigenvalues $\{\lambda_n\}$ and eigenfunctions $\{\psi_n\}$ such that $S\psi_n = \lambda_n\psi_n$ and let $\|x\| \triangleq \sqrt{\langle x | x \rangle}$.

T H M	{	$\left\{ \begin{array}{l} S = S^* \\ S \text{ is self-adjoint} \end{array} \right\}$	\implies	{	1.	$\langle Sx x \rangle \in \mathbb{R}$	(the hermitian quadratic form of S is REAL-VALUED)
					2.	$\lambda_n \in \mathbb{R}$	(eigenvalues of S are REAL-VALUED)
					3.	$\lambda_n \neq \lambda_m \implies \langle \psi_n \psi_m \rangle = 0$	(eigenvectors are ORTHOGONAL)
					$\}$		

³⁷ Rudin (1991) page 314

³⁸ Historical works regarding self-adjoint operators: von Neumann (1929) page 49, “linearer Operator R selbstadjungiert oder Hermitesche”, Stone (1932) page 50 (“self-adjoint transformations”)

³⁹ Lax (2002) pages 315–316, Keener (1988) pages 114–119, Bachman and Narici (1966) page 24 (Theorem 2.1), Bertero and Boccacci (1998) page 225 (“9.2 SVD of a matrix ... If all eigenvectors are normalized...”)

✎ PROOF:

1. Proof that $\mathbf{S} = \mathbf{S}^* \implies \langle \mathbf{S}\mathbf{x} | \mathbf{x} \rangle \in \mathbb{R}$:

$$\begin{aligned} \langle \mathbf{x} | \mathbf{S}\mathbf{x} \rangle &= \langle \mathbf{S}\mathbf{x} | \mathbf{x} \rangle && \text{by left hypothesis} \\ &= \langle \mathbf{x} | \mathbf{S}\mathbf{x} \rangle^* && \text{by definition of } \langle \triangle | \nabla \rangle \text{ Definition G.9 page 166} \end{aligned}$$

2. Proof that $\mathbf{S} = \mathbf{S}^* \implies \lambda_n \in \mathbb{R}$:

$$\begin{aligned} \lambda_n \|\psi_n\|^2 &= \lambda_n \langle \psi_n | \psi_n \rangle && \text{by definition} \\ &= \langle \lambda_n \psi_n | \psi_n \rangle && \text{by definition of } \langle \triangle | \nabla \rangle \text{ Definition G.9 page 166} \\ &= \langle \mathbf{S}\psi_n | \psi_n \rangle && \text{by definition of eigenpairs} \\ &= \langle \psi_n | \mathbf{S}\psi_n \rangle && \text{by left hypothesis} \\ &= \langle \psi_n | \lambda_n \psi_n \rangle && \text{by definition of eigenpairs} \\ &= \lambda_n^* \langle \psi_n | \psi_n \rangle && \text{by definition of } \langle \triangle | \nabla \rangle \text{ Definition G.9 page 166} \\ &= \lambda_n^* \|\psi_n\|^2 && \text{by definition} \end{aligned}$$

3. Proof that $\mathbf{S} = \mathbf{S}^* \implies [\lambda_n \neq \lambda_m \implies \langle \psi_n | \psi_m \rangle = 0]$:

$$\begin{aligned} \lambda_n \langle \psi_n | \psi_m \rangle &= \langle \lambda_n \psi_n | \psi_m \rangle && \text{by definition of } \langle \triangle | \nabla \rangle \text{ Definition G.9 page 166} \\ &= \langle \mathbf{S}\psi_n | \psi_m \rangle && \text{by definition of eigenpairs} \\ &= \langle \psi_n | \mathbf{S}\psi_m \rangle && \text{by left hypothesis} \\ &= \langle \psi_n | \lambda_m \psi_m \rangle && \text{by definition of eigenpairs} \\ &= \lambda_m^* \langle \psi_n | \psi_m \rangle && \text{by definition of } \langle \triangle | \nabla \rangle \text{ Definition G.9 page 166} \\ &= \lambda_m \langle \psi_n | \psi_m \rangle && \text{because } \lambda_m \text{ is real} \end{aligned}$$

This implies for $\lambda_n \neq \lambda_m \neq 0$, $\langle \psi_n | \psi_m \rangle = 0$.

⇒

G.4.3 Normal Operators

Definition G.12. ⁴⁰ Let $\mathcal{B}(\mathbf{X}, \mathbf{Y})$ be the space of BOUNDED LINEAR OPERATORS on normed linear spaces \mathbf{X} and \mathbf{Y} . Let \mathbf{N}^* be the adjoint of an operator $\mathbf{N} \in \mathcal{B}(\mathbf{X}, \mathbf{Y})$.

DEF \mathbf{N} is *normal* if $\mathbf{N}^*\mathbf{N} = \mathbf{N}\mathbf{N}^*$.

Theorem G.19. ⁴¹ Let $\mathcal{B}(\mathbf{H}, \mathbf{H})$ be the space of BOUNDED LINEAR OPERATORS on a HILBERT SPACE \mathbf{H} . Let $\mathcal{N}(\mathbf{N})$ be the NULL SPACE of an operator \mathbf{N} in $\mathcal{B}(\mathbf{H}, \mathbf{H})$ and $\mathcal{I}(\mathbf{N})$ the IMAGE SET of \mathbf{N} in $\mathcal{B}(\mathbf{H}, \mathbf{H})$.

THM $\underbrace{\mathbf{N}^*\mathbf{N} = \mathbf{N}\mathbf{N}^*}_{\mathbf{N} \text{ is normal}} \iff \|\mathbf{N}^*\mathbf{x}\| = \|\mathbf{N}\mathbf{x}\| \quad \forall \mathbf{x} \in \mathbf{H}$

⁴⁰ Rudin (1991) page 312, Michel and Herget (1993) page 431, Dieudonné (1969) page 167, Frobenius (1878), Frobenius (1968) page 391

⁴¹ Rudin (1991) pages 312–313

✎ PROOF:

1. Proof that $\mathbf{N}^*\mathbf{N} = \mathbf{N}\mathbf{N}^* \implies \|\mathbf{N}^*\mathbf{x}\| = \|\mathbf{N}\mathbf{x}\|$:

$$\begin{aligned}
 \|\mathbf{N}\mathbf{x}\|^2 &= \langle \mathbf{N}\mathbf{x} | \mathbf{N}\mathbf{x} \rangle && \text{by definition} \\
 &= \langle \mathbf{x} | \mathbf{N}^*\mathbf{N}\mathbf{x} \rangle && \text{by Proposition G.3 page 167 (definition of } \mathbf{N}^*) \\
 &= \langle \mathbf{x} | \mathbf{N}\mathbf{N}^*\mathbf{x} \rangle && \text{by left hypothesis (} \mathbf{N} \text{ is normal)} \\
 &= \langle \mathbf{N}\mathbf{x} | \mathbf{N}^*\mathbf{x} \rangle && \text{by Proposition G.3 page 167 (definition of } \mathbf{N}^*) \\
 &= \|\mathbf{N}^*\mathbf{x}\|^2 && \text{by definition}
 \end{aligned}$$

2. Proof that $\mathbf{N}^*\mathbf{N} = \mathbf{N}\mathbf{N}^* \iff \|\mathbf{N}^*\mathbf{x}\| = \|\mathbf{N}\mathbf{x}\|$:

$$\begin{aligned}
 \langle \mathbf{N}^*\mathbf{N}\mathbf{x} | \mathbf{x} \rangle &= \langle \mathbf{N}\mathbf{x} | \mathbf{N}^*\mathbf{x} \rangle && \text{by Proposition G.3 page 167 (definition of } \mathbf{N}^*) \\
 &= \langle \mathbf{N}\mathbf{x} | \mathbf{N}\mathbf{x} \rangle && \text{by Theorem G.13 page 168 (property of adjoint)} \\
 &= \|\mathbf{N}\mathbf{x}\|^2 && \text{by definition} \\
 &= \|\mathbf{N}^*\mathbf{x}\|^2 && \text{by right hypothesis } (\|\mathbf{N}^*\mathbf{x}\| = \|\mathbf{N}\mathbf{x}\|) \\
 &= \langle \mathbf{N}^*\mathbf{x} | \mathbf{N}^*\mathbf{x} \rangle && \text{by definition} \\
 &= \langle \mathbf{N}\mathbf{N}^*\mathbf{x} | \mathbf{x} \rangle && \text{by Proposition G.3 page 167 (definition of } \mathbf{N}^*)
 \end{aligned}$$

⇒

Theorem G.20. ⁴² Let $\mathcal{B}(\mathbf{H}, \mathbf{H})$ be the space of BOUNDED LINEAR OPERATORS on a HILBERT SPACE \mathbf{H} . Let $\mathcal{N}(\mathbf{N})$ be the NULL SPACE of an operator \mathbf{N} in $\mathcal{B}(\mathbf{H}, \mathbf{H})$ and $\mathcal{I}(\mathbf{N})$ the IMAGE SET of \mathbf{N} in $\mathcal{B}(\mathbf{H}, \mathbf{H})$.

T H M	$ \underbrace{\mathbf{N}^*\mathbf{N} = \mathbf{N}\mathbf{N}^*}_{\mathbf{N} \text{ is normal}} \implies \underbrace{\mathcal{N}(\mathbf{N}^*) = \mathcal{N}(\mathbf{N})}_{\mathbf{N} \text{ and } \mathbf{N}^* \text{ have the same Null Space}} $
----------------------	---

✎ PROOF:

$$\begin{aligned}
 \mathcal{N}(\mathbf{N}^*) &= \{ \mathbf{x} | \mathbf{N}^*\mathbf{x} = 0 \quad \forall \mathbf{x} \in \mathbf{X} \} && \text{by definition of Null Space} \\
 &= \{ \mathbf{x} | \|\mathbf{N}^*\mathbf{x}\| = 0 \quad \forall \mathbf{x} \in \mathbf{X} \} && \text{by definition of } \|\cdot\| \text{ (Definition G.5 page 158)} \\
 &= \{ \mathbf{x} | \|\mathbf{N}\mathbf{x}\| = 0 \quad \forall \mathbf{x} \in \mathbf{X} \} \\
 &= \{ \mathbf{x} | \mathbf{N}\mathbf{x} = 0 \quad \forall \mathbf{x} \in \mathbf{X} \} && \text{by definition of } \|\cdot\| \text{ (Definition G.5 page 158)} \\
 &= \mathcal{N}(\mathbf{N}) && \text{by definition of Null Space } \mathcal{N}
 \end{aligned}$$

⇒

Theorem G.21. ⁴³ Let $\mathcal{B}(\mathbf{H}, \mathbf{H})$ be the space of BOUNDED LINEAR OPERATORS on a HILBERT SPACE \mathbf{H} . Let $\mathcal{N}(\mathbf{N})$ be the NULL SPACE of an operator \mathbf{N} in $\mathcal{B}(\mathbf{H}, \mathbf{H})$ and $\mathcal{I}(\mathbf{N})$ the IMAGE SET of \mathbf{N} in $\mathcal{B}(\mathbf{H}, \mathbf{H})$.

T H M	$ \underbrace{\left\{ \mathbf{N}^*\mathbf{N} = \mathbf{N}\mathbf{N}^* \right\}}_{\mathbf{N} \text{ is normal}} \implies \left\{ \underbrace{\lambda_n \neq \lambda_m \implies \langle \psi_n \psi_m \rangle = 0}_{\text{eigenfunctions associated with distinct eigenvalues are orthogonal}} \right\} $
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✎ PROOF: The proof in (1) is flawed. This implies that (2) is also flawed. Rudin (1991) page 313 claims both to be true.

⁴² Rudin (1991) pages 312–313

⁴³ Rudin (1991) pages 312–313

1. Proof that $\mathbf{N}^*\mathbf{N} = \mathbf{N}\mathbf{N}^* \implies \mathbf{N}^*\psi = \lambda^*\psi$:

$$\begin{aligned}
 \mathbf{N}\psi &= \lambda\psi \\
 \iff \\
 0 &= \mathcal{N}(\mathbf{N} - \lambda\mathbf{I}) \\
 &= \mathcal{N}([\mathbf{N} - \lambda\mathbf{I}]^*) && \text{by } \mathcal{N}(\mathbf{N}) = \mathcal{N}(\mathbf{N}^*) \\
 &= \mathcal{N}(\mathbf{N}^* - [\lambda\mathbf{I}]^*) && \text{by Theorem G.13 page 168} \\
 &= \mathcal{N}(\mathbf{N}^* - \lambda^*\mathbf{I}^*) && \text{by Theorem G.13 page 168} \\
 &= \mathcal{N}(\mathbf{N}^* - \lambda^*\mathbf{I}) \\
 \implies \\
 (\mathbf{N}^* - \lambda^*\mathbf{I})\psi &= 0 \\
 \iff \mathbf{N}^*\psi &= \lambda^*\psi
 \end{aligned}$$

2. Proof that $\mathbf{N}^*\mathbf{N} = \mathbf{N}\mathbf{N}^* \implies [\lambda_n \neq \lambda_m \implies \langle \psi_n | \psi_m \rangle = 0]$:

$$\begin{aligned}
 \lambda_n \langle \psi_n | \psi_m \rangle &= \langle \lambda_n \psi_n | \psi_m \rangle && \text{by definition of } \langle \triangle | \nabla \rangle \text{ Definition G.9 page 166} \\
 &= \langle \mathbf{N}\psi_n | \psi_m \rangle && \text{by definition of eigenpairs} \\
 &= \langle \psi_n | \mathbf{N}^*\psi_m \rangle && \text{by Proposition G.3 page 167 (definition of adjoint)} \\
 &= \langle \psi_n | \lambda_m^*\psi_m \rangle && \text{by (4.)} \\
 &= \lambda_m \langle \psi_n | \psi_m \rangle && \text{by definition of } \langle \triangle | \nabla \rangle \text{ Definition G.9 page 166}
 \end{aligned}$$

This implies for $\lambda_n \neq \lambda_m \neq 0$, $\langle \psi_n | \psi_m \rangle = 0$.

⇒

G.4.4 Isometric operators

An operator on a pair of normed linear spaces is *isometric* (next definition) if it is an *isometry*.

Definition G.13. Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$ and $(Y, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$ be NORMED LINEAR SPACES (Definition G.5 page 158).

DEF An operator $\mathbf{M} \in \mathcal{L}(X, Y)$ is *isometric* if $\|\mathbf{M}\mathbf{x}\| = \|\mathbf{x}\| \quad \forall \mathbf{x} \in X$.



Theorem G.22.⁴⁴ Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$ and $(Y, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$ be NORMED LINEAR SPACES. Let \mathbf{M} be a linear operator in $\mathcal{L}(X, Y)$.

THM $\underbrace{\|\mathbf{M}\mathbf{x}\| = \|\mathbf{x}\| \quad \forall \mathbf{x} \in X}_{\text{isometric in length}} \iff \underbrace{\|\mathbf{M}\mathbf{x} - \mathbf{M}\mathbf{y}\| = \|\mathbf{x} - \mathbf{y}\| \quad \forall \mathbf{x}, \mathbf{y} \in X}_{\text{isometric in distance}}$

✎ PROOF:

1. Proof that $\|\mathbf{M}\mathbf{x}\| = \|\mathbf{x}\| \implies \|\mathbf{M}\mathbf{x} - \mathbf{M}\mathbf{y}\| = \|\mathbf{x} - \mathbf{y}\|$:

$$\begin{aligned}
 \|\mathbf{M}\mathbf{x} - \mathbf{M}\mathbf{y}\| &= \|\mathbf{M}(\mathbf{x} - \mathbf{y})\| && \text{by definition of linear operators (Definition G.4 page 155)} \\
 &= \|\mathbf{M}\mathbf{u}\| && \text{let } \mathbf{u} \triangleq \mathbf{x} - \mathbf{y} \\
 &= \|\mathbf{x} - \mathbf{y}\| && \text{by left hypothesis}
 \end{aligned}$$

⁴⁴  Kubrusly (2001) page 239 (Proposition 4.37),  Berberian (1961) page 27 (Theorem IV.7.5)

2. Proof that $\|\mathbf{M}\mathbf{x}\| = \|\mathbf{x}\| \iff \|\mathbf{M}\mathbf{x} - \mathbf{M}\mathbf{y}\| = \|\mathbf{x} - \mathbf{y}\|$:

$$\begin{aligned}
 \|\mathbf{M}\mathbf{x}\| &= \|\mathbf{M}(\mathbf{x} - \mathbf{0})\| \\
 &= \|\mathbf{M}\mathbf{x} - \mathbf{M}\mathbf{0}\| && \text{by definition of linear operators (Definition G.4 page 155)} \\
 &= \|\mathbf{x} - \mathbf{0}\| && \text{by right hypothesis} \\
 &= \|\mathbf{x}\|
 \end{aligned}$$



Isometric operators have already been defined (Definition G.13 page 174) in the more general normed linear spaces, while Theorem G.22 (page 174) demonstrated that in a normed linear space \mathbf{X} , $\|\mathbf{M}\mathbf{x}\| = \|\mathbf{x}\| \iff \|\mathbf{M}\mathbf{x} - \mathbf{M}\mathbf{y}\| = \|\mathbf{x} - \mathbf{y}\|$ for all $\mathbf{x}, \mathbf{y} \in \mathbf{X}$. Here in the more specialized inner product spaces, Theorem G.23 (next) demonstrates two additional equivalent properties.

Theorem G.23. ⁴⁵ *Let $\mathcal{B}(\mathbf{X}, \mathbf{X})$ be the space of BOUNDED LINEAR OPERATORS on a normed linear space $\mathbf{X} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$. Let \mathbf{N} be a bounded linear operator in $\mathcal{L}(\mathbf{X}, \mathbf{X})$, and \mathbf{I} the identity operator in $\mathcal{L}(\mathbf{X}, \mathbf{X})$. Let $\|\mathbf{x}\| \triangleq \sqrt{\langle \mathbf{x} | \mathbf{x} \rangle}$.*

*The following conditions are all **equivalent**:*

- | | | | | |
|-------------|----|---|--|---|
| T
H
M | 1. | $\mathbf{M}^*\mathbf{M} = \mathbf{I}$ | | \iff |
| | 2. | $\langle \mathbf{M}\mathbf{x} \mathbf{M}\mathbf{y} \rangle = \langle \mathbf{x} \mathbf{y} \rangle$ | $\forall \mathbf{x}, \mathbf{y} \in X$ | $(\mathbf{M} \text{ is surjective}) \iff$ |
| | 3. | $\ \mathbf{M}\mathbf{x} - \mathbf{M}\mathbf{y}\ = \ \mathbf{x} - \mathbf{y}\ $ | $\forall \mathbf{x}, \mathbf{y} \in X$ | $(\text{isometric in distance}) \iff$ |
| | 4. | $\ \mathbf{M}\mathbf{x}\ = \ \mathbf{x}\ $ | $\forall \mathbf{x} \in X$ | $(\text{isometric in length})$ |

PROOF:

1. Proof that (1) \implies (2):

$$\begin{aligned}
 \langle \mathbf{M}\mathbf{x} | \mathbf{M}\mathbf{y} \rangle &= \langle \mathbf{x} | \mathbf{M}^*\mathbf{M}\mathbf{y} \rangle && \text{by Proposition G.3 page 167 (definition of adjoint)} \\
 &= \langle \mathbf{x} | \mathbf{I}\mathbf{y} \rangle && \text{by (1)} \\
 &= \langle \mathbf{x} | \mathbf{y} \rangle && \text{by Definition G.3 page 154 (definition of I)}
 \end{aligned}$$

2. Proof that (2) \implies (4):

$$\begin{aligned}
 \|\mathbf{M}\mathbf{x}\| &= \sqrt{\langle \mathbf{M}\mathbf{x} | \mathbf{M}\mathbf{x} \rangle} && \text{by definition of } \|\cdot\| \\
 &= \sqrt{\langle \mathbf{x} | \mathbf{x} \rangle} && \text{by right hypothesis} \\
 &= \|\mathbf{x}\| && \text{by definition of } \|\cdot\|
 \end{aligned}$$

3. Proof that (2) \iff (4):

$$\begin{aligned}
 4 \langle \mathbf{M}\mathbf{x} | \mathbf{M}\mathbf{y} \rangle &= \|\mathbf{M}\mathbf{x} + \mathbf{M}\mathbf{y}\|^2 - \|\mathbf{M}\mathbf{x} - \mathbf{M}\mathbf{y}\|^2 + i \|\mathbf{M}\mathbf{x} + i\mathbf{M}\mathbf{y}\|^2 - i \|\mathbf{M}\mathbf{x} - i\mathbf{M}\mathbf{y}\|^2 && \text{by polarization id.} \\
 &= \|\mathbf{M}(\mathbf{x} + \mathbf{y})\|^2 - \|\mathbf{M}(\mathbf{x} - \mathbf{y})\|^2 + i \|\mathbf{M}(\mathbf{x} + i\mathbf{y})\|^2 - i \|\mathbf{M}(\mathbf{x} - i\mathbf{y})\|^2 && \text{by Definition G.4} \\
 &= \|\mathbf{x} + \mathbf{y}\|^2 - \|\mathbf{x} - \mathbf{y}\|^2 + i \|\mathbf{x} + i\mathbf{y}\|^2 - i \|\mathbf{x} - i\mathbf{y}\|^2 && \text{by left hypothesis}
 \end{aligned}$$

4. Proof that (3) \iff (4): by Theorem G.22 page 174

⁴⁵ Michel and Herget (1993) page 432 (Theorem 7.5.8), Kubrusly (2001) page 391 (Proposition 5.72)

5. Proof that (4) \implies (1):

$$\begin{aligned}
 \langle \mathbf{M}^* \mathbf{M} \mathbf{x} \mid \mathbf{x} \rangle &= \langle \mathbf{M} \mathbf{x} \mid \mathbf{M}^{**} \mathbf{x} \rangle && \text{by Proposition G.3 page 167 (definition of adjoint)} \\
 &= \langle \mathbf{M} \mathbf{x} \mid \mathbf{M} \mathbf{x} \rangle && \text{by Theorem G.13 page 168 (property of adjoint)} \\
 &= \|\mathbf{M} \mathbf{x}\|^2 && \text{by definition} \\
 &= \|\mathbf{x}\|^2 && \text{by left hypothesis with } y = 0 \\
 &= \langle \mathbf{x} \mid \mathbf{x} \rangle && \text{by definition} \\
 &= \langle \mathbf{I} \mathbf{x} \mid \mathbf{x} \rangle && \text{by Definition G.3 page 154 (definition of } \mathbf{I} \text{)} \\
 \implies \mathbf{M}^* \mathbf{M} &= \mathbf{I} && \forall \mathbf{x} \in X
 \end{aligned}$$

\Rightarrow

Theorem G.24. ⁴⁶ Let $\mathcal{B}(X, Y)$ be the space of BOUNDED LINEAR OPERATORS on normed linear spaces X and Y . Let \mathbf{M} be a bounded linear operator in $\mathcal{B}(X, Y)$, and \mathbf{I} the identity operator in $\mathcal{L}(X, X)$. Let Λ be the set of eigenvalues of \mathbf{M} . Let $\|\mathbf{x}\| \triangleq \sqrt{\langle \mathbf{x} \mid \mathbf{x} \rangle}$.

T H M	$ \underbrace{\mathbf{M}^* \mathbf{M} = \mathbf{I}}_{\mathbf{M} \text{ is isometric}} \implies \begin{cases} \ \mathbf{M}\ = 1 & \text{(UNIT LENGTH) and} \\ \lambda = 1 & \forall \lambda \in \Lambda \end{cases} $
----------------------	---

\pencil PROOF:

1. Proof that $\mathbf{M}^* \mathbf{M} = \mathbf{I} \implies \|\mathbf{M}\| = 1$:

$$\begin{aligned}
 \|\mathbf{M}\| &= \sup_{\mathbf{x} \in X} \{ \|\mathbf{M} \mathbf{x}\| \mid \|\mathbf{x}\| = 1 \} && \text{by Definition G.6 page 159} \\
 &= \sup_{\mathbf{x} \in X} \{ \|\mathbf{x}\| \mid \|\mathbf{x}\| = 1 \} && \text{by Theorem G.23 page 175} \\
 &= \sup_{\mathbf{x} \in X} \{ 1 \} \\
 &= 1
 \end{aligned}$$

2. Proof that $|\lambda| = 1$: Let (\mathbf{x}, λ) be an eigenvector-eigenvalue pair.

$$\begin{aligned}
 1 &= \frac{1}{\|\mathbf{x}\|} \|\mathbf{x}\| \\
 &= \frac{1}{\|\mathbf{x}\|} \|\mathbf{M} \mathbf{x}\| && \text{by Theorem G.23 page 175} \\
 &= \frac{1}{\|\mathbf{x}\|} \|\lambda \mathbf{x}\| && \text{by definition of } \lambda \\
 &= \frac{1}{\|\mathbf{x}\|} |\lambda| \|\mathbf{x}\| && \text{by homogeneous property of } \|\cdot\| \\
 &= |\lambda|
 \end{aligned}$$

\Rightarrow

Example G.4 (One sided shift operator). ⁴⁷ Let X be the set of all sequences with range \mathbb{W} $(0, 1, 2, \dots)$ and shift operators defined as

$$\begin{aligned}
 1. \quad \mathbf{S}_r(x_0, x_1, x_2, \dots) &\triangleq (0, x_0, x_1, x_2, \dots) && \text{(right shift operator)} \\
 2. \quad \mathbf{S}_l(x_0, x_1, x_2, \dots) &\triangleq (x_1, x_2, x_3, \dots) && \text{(left shift operator)}
 \end{aligned}$$

E X	<ol style="list-style-type: none"> 1. \mathbf{S}_r is an isometric operator. 2. $\mathbf{S}_r^* = \mathbf{S}_l$
----------------	---

⁴⁶ Michel and Herget (1993) page 432

⁴⁷ Michel and Herget (1993) page 441

✎ PROOF:

1. Proof that $\mathbf{S}_r^* = \mathbf{S}_l$:

$$\begin{aligned}
 \langle \mathbf{S}_r(x_0, x_1, x_2, \dots) | (y_0, y_1, y_2, \dots) \rangle &= \langle (0, x_0, x_1, x_2, \dots) | (y_0, y_1, y_2, \dots) \rangle \\
 &= \sum_{n=1}^{\infty} x_{n-1} y_n^* \\
 &= \sum_{n=0}^{\infty} x_n y_{n+1}^* \\
 &= \sum_{n=0}^{\infty} x_n y_{n+1}^* \\
 &= \langle (x_0, x_1, x_2, \dots) | (y_1, y_2, y_3, \dots) \rangle \\
 &= \left\langle (x_0, x_1, x_2, \dots) | \underbrace{\mathbf{S}_l(y_0, y_1, y_2, \dots)}_{\mathbf{S}_r^*} \right\rangle
 \end{aligned}$$

2. Proof that \mathbf{S}_r is isometric ($\mathbf{S}_r^* \mathbf{S}_r = \mathbf{I}$):

$$\begin{aligned}
 \mathbf{S}_r^* \mathbf{S}_r &= \mathbf{S}_l \mathbf{S}_r \\
 &= \mathbf{I}
 \end{aligned}$$

by 1.

⇒

G.4.5 Unitary operators

Definition G.14. ⁴⁸ Let $\mathcal{B}(\mathbf{X}, \mathbf{Y})$ be the space of BOUNDED LINEAR OPERATORS on normed linear spaces \mathbf{X} and \mathbf{Y} . Let \mathbf{U} be a bounded linear operator in $\mathcal{B}(\mathbf{X}, \mathbf{Y})$, and \mathbf{I} the identity operator in $\mathcal{B}(\mathbf{X}, \mathbf{X})$.

DEF The operator \mathbf{U} is **unitary** if $\mathbf{U}^* \mathbf{U} = \mathbf{U} \mathbf{U}^* = \mathbf{I}$.

Proposition G.4. Let $\mathcal{B}(\mathbf{X}, \mathbf{Y})$ be the space of BOUNDED LINEAR OPERATORS on normed linear spaces \mathbf{X} and \mathbf{Y} . Let \mathbf{U} and \mathbf{V} be BOUNDED LINEAR OPERATORS in $\mathcal{B}(\mathbf{X}, \mathbf{Y})$.

PRP $\left. \begin{array}{l} \mathbf{U} \text{ is UNITARY} \\ \mathbf{V} \text{ is UNITARY} \end{array} \right\} \text{ and } \Rightarrow (\mathbf{UV}) \text{ is UNITARY.}$

✎ PROOF:

$$\begin{aligned}
 (\mathbf{UV})(\mathbf{UV})^* &= (\mathbf{UV})(\mathbf{V}^* \mathbf{U}^*) && \text{by Theorem G.8 page 163} \\
 &= \mathbf{U}(\mathbf{V} \mathbf{V}^*) \mathbf{U}^* && \text{by associative property} \\
 &= \mathbf{U} \mathbf{I} \mathbf{U}^* && \text{by definition of unitary operators (Definition G.14 page 177)} \\
 &= \mathbf{I} && \text{by definition of unitary operators (Definition G.14 page 177)}
 \end{aligned}$$

$$\begin{aligned}
 (\mathbf{UV})^*(\mathbf{UV}) &= (\mathbf{V}^* \mathbf{U}^*)(\mathbf{UV}) && \text{by Theorem G.8 page 163} \\
 &= \mathbf{V}^*(\mathbf{U}^* \mathbf{U}) \mathbf{V} && \text{by associative property} \\
 &= \mathbf{V}^* \mathbf{I} \mathbf{V} && \text{by definition of unitary operators (Definition G.14 page 177)} \\
 &= \mathbf{I} && \text{by definition of unitary operators (Definition G.14 page 177)}
 \end{aligned}$$

⁴⁸ Rudin (1991) page 312, Michel and Herget (1993) page 431, Autonne (1901) page 209, Autonne (1902), Schur (1909), Steen (1973)



Theorem G.25. ⁴⁹ Let $\mathcal{B}(H, H)$ be the space of BOUNDED LINEAR OPERATORS on a HILBERT SPACE H . Let $\mathcal{J}(U)$ be the IMAGE SET of U .

If U is a **bounded linear operator** ($U \in \mathcal{B}(H, H)$), then the following conditions are **equivalent**:

T H M

- | | | |
|--|--------------------------|--------------------------------|
| 1. $UU^* = U^*U = I$ | (UNITARY) | \iff |
| 2. $\langle Ux Uy \rangle = \langle U^*x U^*y \rangle = \langle x y \rangle$ | and $\mathcal{J}(U) = X$ | (SURJECTIVE) \iff |
| 3. $\ Ux - Uy\ = \ U^*x - U^*y\ = \ x - y\ $ | and $\mathcal{J}(U) = X$ | (ISOMETRIC IN DISTANCE) \iff |
| 4. $\ Ux\ = \ x\ $ | and $\mathcal{J}(U) = X$ | (ISOMETRIC IN LENGTH) |

PROOF:

1. Proof that (1) \implies (2):

(a) $\langle Ux | Uy \rangle = \langle U^*x | U^*y \rangle = \langle x | y \rangle$ by Theorem G.23 (page 175).

(b) Proof that $\mathcal{J}(U) = X$:

$$\begin{aligned}
 X &\supseteq \mathcal{J}(U) && \text{because } U \in X^X \\
 &\supseteq \mathcal{J}(UU^*) \\
 &= \mathcal{J}(I) && \text{by left hypothesis } (U^*U = UU^* = I) \\
 &= X && \text{by Definition G.3 page 154 (definition of } I)
 \end{aligned}$$

2. Proof that (2) \iff (3) \iff (4): by Theorem G.23 page 175.

3. Proof that (3) \implies (1):

(a) Proof that $\|Ux - Uy\| = \|x - y\| \implies U^*U = I$: by Theorem G.23 page 175

(b) Proof that $\|U^*x - U^*y\| = \|x - y\| \implies UU^* = I$:

$$\begin{aligned}
 \|U^*x - U^*y\| = \|x - y\| &\implies U^{**}U^* = I && \text{by Theorem G.23 page 175} \\
 &UU^* = I && \text{by Theorem G.13 page 168}
 \end{aligned}$$



Theorem G.26. Let $\mathcal{B}(H, H)$ be the space of BOUNDED LINEAR OPERATORS on a HILBERT SPACE H . Let U be a bounded linear operator in $\mathcal{B}(H, H)$, $\mathcal{N}(U)$ the NULL SPACE of U , and $\mathcal{J}(U)$ the IMAGE SET of U .

T H M

$$\underbrace{UU^* = U^*U = I}_{U \text{ is unitary}} \implies \left\{ \begin{array}{lll} U^{-1} = U^* & \text{and} \\ \mathcal{J}(U) = \mathcal{J}(U^*) = X & \text{and} \\ \mathcal{N}(U) = \mathcal{N}(U^*) = \{0\} & \text{and} \\ \|U\| = \|U^*\| = 1 & \text{(UNIT LENGTH)} \end{array} \right\}$$

PROOF:

1. Note that U , U^* , and U^{-1} are all both *isometric* and *normal*:

$$\begin{aligned}
 U^*U &= I \implies U \text{ is isometric} \\
 UU^* &= U^*U = I \implies U^* \text{ is isometric} \\
 U^{-1} &= U^* \implies U^{-1} \text{ is isometric}
 \end{aligned}$$

$$\begin{aligned}
 U^*U &= UU^* = I \implies U \text{ is normal} \\
 UU^* &= U^*U = I \implies U^* \text{ is normal} \\
 U^{-1} &= U^* \implies U^{-1} \text{ is normal}
 \end{aligned}$$

⁴⁹ Rudin (1991) pages 313–314 (Theorem 12.13), Knapp (2005a) page 45 (Proposition 2.6)

2. Proof that $\mathbf{U}^*\mathbf{U} = \mathbf{U}\mathbf{U}^* = \mathbf{I} \implies \mathcal{J}(\mathbf{U}) = \mathcal{J}(\mathbf{U}^*) = \mathbf{H}$: by Theorem G.25 page 178.

3. Proof that $\mathbf{U}^*\mathbf{U} = \mathbf{U}\mathbf{U}^* = \mathbf{I} \implies \mathcal{N}(\mathbf{U}) = \mathcal{N}(\mathbf{U}^*) = \mathcal{N}(\mathbf{U}^{-1})$:

$$\begin{aligned}\mathcal{N}(\mathbf{U}^*) &= \mathcal{N}(\mathbf{U}) && \text{because } \mathbf{U} \text{ and } \mathbf{U}^* \text{ are both normal and by Theorem G.20 page 173} \\ &= \mathcal{J}(\mathbf{U})^\perp && \text{by Theorem G.14 page 169} \\ &= X^\perp && \text{by above result} \\ &= \{\emptyset\}\end{aligned}$$

4. Proof that $\mathbf{U}^*\mathbf{U} = \mathbf{U}\mathbf{U}^* = \mathbf{I} \implies \|\mathbf{U}^{-1}\| = \|\mathbf{U}^*\| = \|\mathbf{U}\| = 1$:

Because \mathbf{U} , \mathbf{U}^* , and \mathbf{U}^{-1} are all isometric and by Theorem G.24 page 176.



Example G.5 (Rotation matrix). ⁵⁰

$$\underbrace{\left\{ \mathbf{R}_\theta \triangleq \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix} \right\}}_{\text{rotation matrix } \mathbf{R}_\theta : \mathbb{R}^2 \rightarrow \mathbb{R}^2} \implies \left\{ \begin{array}{ll} (1). & \mathbf{R}_\theta^{-1} = \mathbf{R}_{-\theta} \quad \text{and} \\ (2). & \mathbf{R}_\theta^* = \mathbf{R}_\theta^{-1} \quad (\mathbf{R} \text{ is unitary}) \end{array} \right\}$$

PROOF:

$$\begin{aligned}\mathbf{R}^* &= \mathbf{R}^H \\ &= \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix}^H && \text{by definition of } \mathbf{R} \\ &= \begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix} && \text{by definition of Hermetian transpose operator } H \\ &= \begin{bmatrix} \cos(-\theta) & -\sin(-\theta) \\ \sin(-\theta) & \cos(-\theta) \end{bmatrix} && (\text{Theorem D.2 page 109}) \\ &= \mathbf{R}_{-\theta} && \text{by definition of } \mathbf{R} \\ &= \mathbf{R}^{-1} && \text{by 1.}\end{aligned}$$



Example G.6. ⁵¹ Let \mathbf{A} and \mathbf{B} be matrix operators.

$$\underbrace{\left\{ \mathbf{A} \triangleq \begin{bmatrix} \cos\phi & -\sin\phi & 0 \\ \sin\phi & \cos\phi & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \mathbf{B} \triangleq \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \right\}}_{\text{Both } \mathbf{A} \text{ and } \mathbf{B} \text{ are unitary.}}$$

\mathbf{A} is a rotation operator. \mathbf{B} is a reflection operator.

Example G.7. Examples of Fredholm integral operators include

$$\begin{array}{lll} 1. & \text{Fourier Transform} & [\tilde{\mathbf{F}}\mathbf{x}](f) = \int_{t \in \mathbb{R}} \mathbf{x}(t) e^{-i2\pi f t} dt \quad \kappa(t, f) = e^{-i2\pi f t} \\ 2. & \text{Inverse Fourier Transform} & [\tilde{\mathbf{F}}^{-1}\tilde{\mathbf{x}}](t) = \int_{f \in \mathbb{R}} \tilde{\mathbf{x}}(f) e^{i2\pi f t} df \quad \kappa(f, t) = e^{i2\pi f t} \\ 3. & \text{Laplace operator} & [\mathbf{L}\mathbf{x}](s) = \int_{t \in \mathbb{R}} \mathbf{x}(t) e^{-st} dt \quad \kappa(t, s) = e^{-st} \end{array}$$

Example G.8 (Translation operator). Let $\mathbf{X} = \mathbf{L}_{\mathbb{R}}^2$ and $\mathbf{T} \in \mathbf{X}^{\mathbf{X}}$ be defined as

$$\mathbf{T}f(x) \triangleq f(x-1) \quad \forall f \in \mathbf{L}_{\mathbb{R}}^2 \quad (\text{translation operator})$$

⁵⁰ Noble and Daniel (1988) page 311

⁵¹ Gel'fand (1963) page 4, Gelfand et al. (2018) page 4

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X

1. $\mathbf{T}^{-1}\mathbf{f}(x) = \mathbf{f}(x+1) \quad \forall \mathbf{f} \in \mathcal{L}_{\mathbb{R}}^2$ (inverse translation operator)
2. $\mathbf{T}^* = \mathbf{T}^{-1}$ (\mathbf{T} is invertible)
3. $\mathbf{T}^*\mathbf{T} = \mathbf{T}\mathbf{T}^* = \mathbf{I}$ (\mathbf{T} is unitary)

PROOF:

1. Proof that $\mathbf{T}^{-1}\mathbf{f}(x) = \mathbf{f}(x+1)$:

$$\begin{aligned}\mathbf{T}^{-1}\mathbf{T} &= \mathbf{I} \\ \mathbf{T}\mathbf{T}^{-1} &= \mathbf{I}\end{aligned}$$

2. Proof that \mathbf{T} is unitary:

$$\begin{aligned}\langle \mathbf{T}\mathbf{f}(x) | \mathbf{g}(x) \rangle &= \langle \mathbf{f}(x-1) | \mathbf{g}(x) \rangle && \text{by definition of } \mathbf{T} \\ &= \int_x \mathbf{f}(x-1) \mathbf{g}^*(x) \, dx \\ &= \int_x \mathbf{f}(x) \mathbf{g}^*(x+1) \, dx \\ &= \langle \mathbf{f}(x) | \mathbf{g}(x+1) \rangle \\ &= \left\langle \mathbf{f}(x) | \underbrace{\mathbf{T}^{-1}\mathbf{g}(x)}_{\mathbf{T}^*} \right\rangle && \text{by 1.}\end{aligned}$$

⇒

Example G.9 (Dilation operator). Let $\mathbf{X} = \mathcal{L}_{\mathbb{R}}^2$ and $\mathbf{T} \in \mathbf{X}^{\mathbf{X}}$ be defined as

$$\mathbf{D}\mathbf{f}(x) \triangleq \sqrt{2}\mathbf{f}(2x) \quad \forall \mathbf{f} \in \mathcal{L}_{\mathbb{R}}^2 \quad (\text{dilation operator})$$

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1. $\mathbf{D}^{-1}\mathbf{f}(x) = \frac{1}{\sqrt{2}}\mathbf{f}\left(\frac{1}{2}x\right) \quad \forall \mathbf{f} \in \mathcal{L}_{\mathbb{R}}^2$ (inverse dilation operator)
2. $\mathbf{D}^* = \mathbf{D}^{-1}$ (\mathbf{D} is invertible)
3. $\mathbf{D}^*\mathbf{D} = \mathbf{D}\mathbf{D}^* = \mathbf{I}$ (\mathbf{D} is unitary)

PROOF:

1. Proof that $\mathbf{D}^{-1}\mathbf{f}(x) = \frac{1}{\sqrt{2}}\mathbf{f}\left(\frac{1}{2}x\right)$:

$$\begin{aligned}\mathbf{D}^{-1}\mathbf{D} &= \mathbf{I} \\ \mathbf{D}\mathbf{D}^{-1} &= \mathbf{I}\end{aligned}$$

2. Proof that \mathbf{D} is unitary:

$$\begin{aligned}\langle \mathbf{D}\mathbf{f}(x) | \mathbf{g}(x) \rangle &= \left\langle \sqrt{2}\mathbf{f}(2x) | \mathbf{g}(x) \right\rangle && \text{by definition of } \mathbf{D} \\ &= \int_x \sqrt{2}\mathbf{f}(2x) \mathbf{g}^*(x) \, dx \\ &= \int_{u \in \mathbb{R}} \sqrt{2}\mathbf{f}(u) \mathbf{g}^*\left(\frac{1}{2}u\right) \frac{1}{2} \, du && \text{let } u \triangleq 2x \implies dx = \frac{1}{2} du \\ &= \int_{u \in \mathbb{R}} \mathbf{f}(u) \left[\frac{1}{\sqrt{2}}\mathbf{g}\left(\frac{1}{2}u\right) \right]^* \, du \\ &= \left\langle \mathbf{f}(x) | \frac{1}{\sqrt{2}}\mathbf{g}\left(\frac{1}{2}x\right) \right\rangle \\ &= \left\langle \mathbf{f}(x) | \underbrace{\mathbf{D}^{-1}\mathbf{g}(x)}_{\mathbf{D}^*} \right\rangle && \text{by 1.}\end{aligned}$$



Example G.10 (Delay operator). Let \mathbf{X} be the set of all sequences and $\mathbf{D} \in \mathbf{X}^{\mathbf{X}}$ be a delay operator.

E X The delay operator $\mathbf{D} ((x_n)_{n \in \mathbb{Z}}) \triangleq ((x_{n-1})_{n \in \mathbb{Z}})$ is unitary.

PROOF: The inverse \mathbf{D}^{-1} of the delay operator \mathbf{D} is

$$\mathbf{D}^{-1} ((x_n)_{n \in \mathbb{Z}}) \triangleq ((x_{n+1})_{n \in \mathbb{Z}}).$$

$$\begin{aligned} \langle \mathbf{D}((x_n)) | (y_n) \rangle &= \langle (x_{n-1}) | (y_n) \rangle && \text{by definition of } \mathbf{D} \\ &= \sum_n x_{n-1} y_n^* \\ &= \sum_n x_n y_{n+1}^* \\ &= \langle (x_n) | (y_{n+1}) \rangle \\ &= \left\langle (x_n) | \underbrace{\mathbf{D}^{-1}}_{\mathbf{D}^*} (y_n) \right\rangle \end{aligned}$$

Therefore, $\mathbf{D}^* = \mathbf{D}^{-1}$. This implies that $\mathbf{D}\mathbf{D}^* = \mathbf{D}^*\mathbf{D} = \mathbf{I}$ which implies that \mathbf{D} is unitary.

Example G.11 (Fourier transform). Let $\tilde{\mathbf{F}}$ be the *Fourier Transform* and $\tilde{\mathbf{F}}^{-1}$ the *inverse Fourier Transform* operator (Theorem 7.1 page 54)

$$[\tilde{\mathbf{F}}\mathbf{x}](f) \triangleq \int_t \mathbf{x}(t) \underbrace{e^{-i2\pi ft}}_{\kappa(t,f)} dt \quad [\tilde{\mathbf{F}}^{-1}\tilde{\mathbf{x}}](t) \triangleq \int_f \tilde{\mathbf{x}}(f) \underbrace{e^{i2\pi ft}}_{\kappa^*(t,f)} df.$$

E X $\tilde{\mathbf{F}}^* = \tilde{\mathbf{F}}^{-1}$ (the Fourier Transform operator $\tilde{\mathbf{F}}$ is unitary)

PROOF:

$$\begin{aligned} \langle \tilde{\mathbf{F}}\mathbf{x} | \tilde{\mathbf{y}} \rangle &= \left\langle \int_t \mathbf{x}(t) e^{-i2\pi ft} dt | \tilde{\mathbf{y}}(f) \right\rangle \\ &= \int_t \mathbf{x}(t) \langle e^{-i2\pi ft} | \tilde{\mathbf{y}}(f) \rangle dt \\ &= \int_t \mathbf{x}(t) \int_f e^{-i2\pi ft} \tilde{\mathbf{y}}^*(f) df dt \\ &= \int_t \mathbf{x}(t) \left[\int_f e^{i2\pi ft} \tilde{\mathbf{y}}(f) df \right]^* dt \\ &= \left\langle \mathbf{x}(t) | \int_f \tilde{\mathbf{y}}(f) e^{i2\pi ft} df \right\rangle \\ &= \left\langle \mathbf{x} | \underbrace{\tilde{\mathbf{F}}^{-1} \tilde{\mathbf{y}}}_{\tilde{\mathbf{F}}^*} \right\rangle \end{aligned}$$

This implies that $\tilde{\mathbf{F}}$ is unitary ($\tilde{\mathbf{F}}^* = \tilde{\mathbf{F}}^{-1}$).

G.5 Operator order

Definition G.15. ⁵² Let $P \in Y^X$ be an operator.

DEF P is **positive** if $\langle Px | x \rangle \geq 0 \forall x \in X$.
This condition is denoted $P \geq 0$.

Theorem G.27. ⁵³

THM $\underbrace{P \geq 0 \text{ and } Q \geq 0}_{P \text{ and } Q \text{ are both positive}} \implies \begin{cases} (P + Q) \geq 0 & ((P + Q) \text{ is positive}) \\ A^*PA \geq 0 & \forall A \in \mathcal{B}(X, X) \quad (A^*PA \text{ is positive}) \\ A^*A \geq 0 & \forall A \in \mathcal{B}(X, X) \quad (A^*A \text{ is positive}) \end{cases}$


 PROOF:

$\langle (P + Q)x x \rangle = \langle Px x \rangle + \langle Qx x \rangle$	by additive property of $\langle \triangle \nabla \rangle$ (Definition G.9 page 166)
$\geq \langle Px x \rangle$	by left hypothesis
≥ 0	by left hypothesis
$\langle A^*PAx x \rangle = \langle PAx Ax \rangle$	by definition of adjoint (Proposition G.3 page 167)
$= \langle Py y \rangle$	where $y \triangleq Ax$
≥ 0	by left hypothesis
$\langle Ix x \rangle = \langle x x \rangle$	by definition of I (Definition G.3 page 154)
≥ 0	by non-negative property of $\langle \triangle \nabla \rangle$ (Definition G.9 page 166)
$\implies I$ is positive	
$\langle A^*Ax x \rangle = \langle A^*IAx x \rangle$	by definition of I (Definition G.3 page 154)
≥ 0	by two previous results



Definition G.16. ⁵⁴ Let $A, B \in \mathcal{B}(X, Y)$ be BOUNDED operators.

DEF $A \geq B$ (“ A is greater than or equal to B ”) if
 $A - B \geq 0$ (“ $(A - B)$ is positive”)

⁵²  Michel and Herget (1993) page 429 (Definition 7.4.12)

⁵³  Michel and Herget (1993) page 429

⁵⁴  Michel and Herget (1993) page 429

APPENDIX H

LINEAR COMBINATIONS

H.1 Linear combinations in linear spaces

A *linear space* (Definition G.1 page 153) in general is not equipped with a *topology*. Without a topology, it is not possible to determine whether an *infinite sum* of vectors converges. Therefore in this section (dealing with linear spaces), all definitions related to sums of vectors will be valid for *finite* sums only (finite “ N ”).

Definition H.1. ¹ Let $\{\mathbf{x}_n \in X \mid n=1,2,\dots,N\}$ be a set of vectors in a LINEAR SPACE $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$.

DEF A vector $\mathbf{x} \in X$ is a **linear combination** of the vectors in $\{\mathbf{x}_n\}$ if there exists $\{\alpha_n \in \mathbb{F} \mid n=1,2,\dots,N\}$ such that
$$\mathbf{x} = \sum_{n=1}^N \alpha_n \mathbf{x}_n.$$

Definition H.2. ² Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ be a linear space and Y be a subset of X .

DEF The **linear span** of Y is defined as $\text{span} Y \triangleq \left\{ \sum_{\gamma \in I} \alpha_\gamma \mathbf{y}_\gamma \mid \alpha_\gamma \in \mathbb{F}, \mathbf{y}_\gamma \in Y \right\}$.
The set Y **spans** a set A if $A \subseteq \text{span} Y$.

Proposition H.1. ³ Let $\{\mathbf{x}_n \in X \mid n=1,2,\dots,N\}$ be a set of vectors in a LINEAR SPACE $\mathbf{L} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$.

- PRP**
1. $\text{span}\{\mathbf{x}_n\}$ is a LINEAR SPACE (Definition G.1 page 153) and
 2. $\text{span}\{\mathbf{x}_n\}$ is a LINEAR SUBSPACE of \mathbf{L} .

Definition H.3. ⁴ Let $\mathbf{L} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ be a LINEAR SPACE.

DEF The set $Y \triangleq \{\mathbf{x}_n \in X \mid n=1,2,\dots,N\}$ is **linearly independent** in \mathbf{L} if
$$\left\{ \sum_{n=1}^N \alpha_n \mathbf{x}_n = \mathbf{0} \right\} \implies \{\alpha_1 = \alpha_2 = \dots = \alpha_N = 0\}.$$

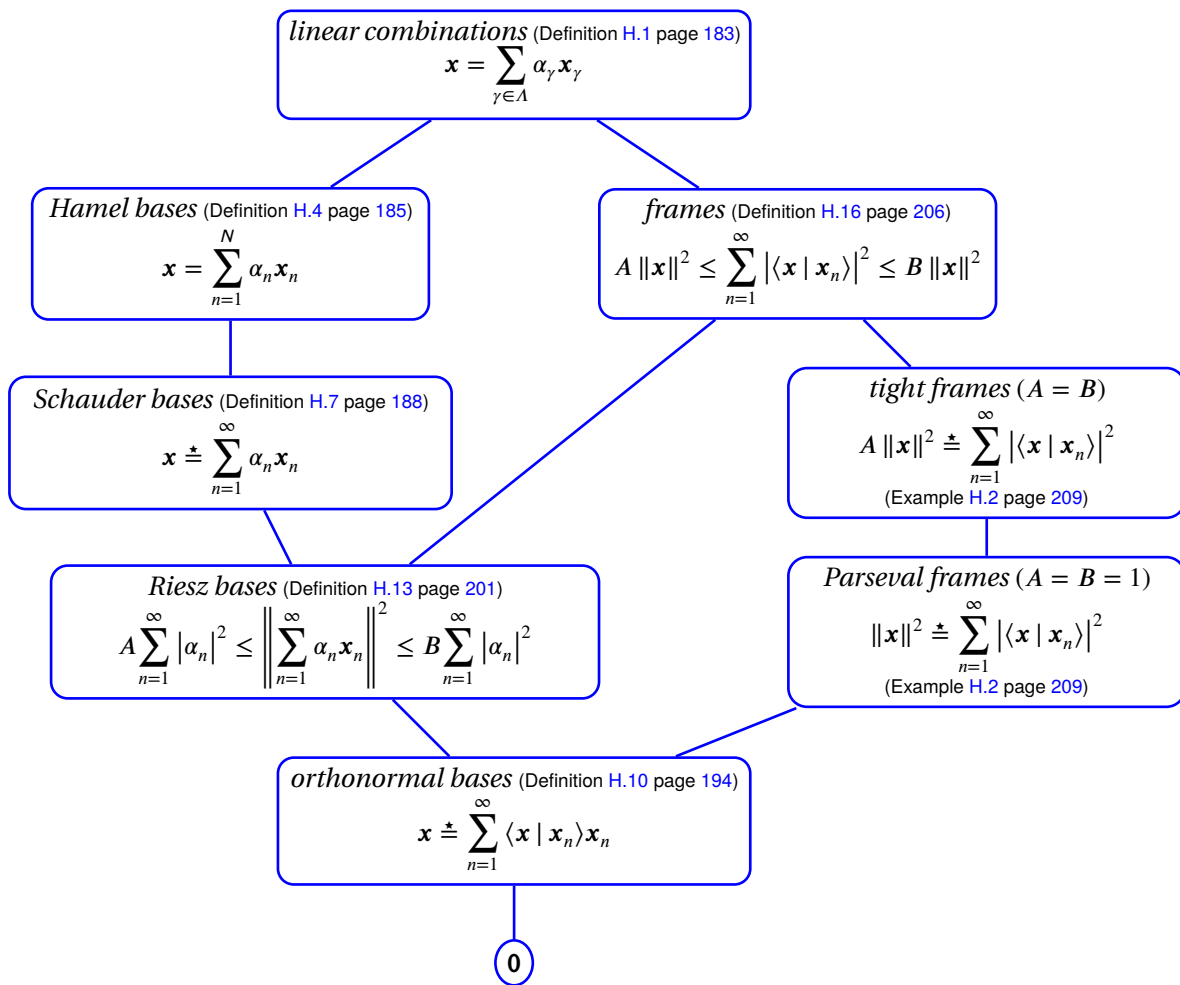
The set Y is **linearly dependent** in \mathbf{L} if Y is not linearly independent in \mathbf{L} .

¹ Berberian (1961) page 11 (Definition I.4.1), Kubrusly (2001) page 46

² Michel and Herget (1993) page 86 (3.3.7 Definition), Kurdila and Zabrankin (2005) page 44, Searcoid (2002) page 71 (Definition 3.2.5—more general definition)

³ Kubrusly (2001) page 46

⁴ Bachman and Narici (1966) pages 3–4, Christensen (2003) page 2, Heil (2011) page 156 (Definition 5.7)

Figure H.1: Lattice of *linear combinations*

Definition H.4. ⁵ Let $\{\mathbf{x}_n \in X \mid n=1,2,\dots,N\}$ be a set of vectors in a LINEAR SPACE $\mathbf{L} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$.

DEF

The set $\{\mathbf{x}_n\}$ is a **Hamel basis** for \mathbf{L} if

1. $\{\mathbf{x}_n\}$ SPANS \mathbf{L} (Definition H.2 page 183) and
2. $\{\mathbf{x}_n\}$ is LINEARLY INDEPENDENT in \mathbf{L} (Definition H.1 page 183) .

A HAMEL BASIS is also called a **linear basis**.

Definition H.5. ⁶ Let $\mathbf{L} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ be a LINEAR SPACE. Let \mathbf{x} be a VECTOR in \mathbf{L} and $Y \triangleq \{\mathbf{x}_n \in X \mid n=1,2,\dots,N\}$ be a set of vectors in \mathbf{L} .

DEF

The expression $\sum_{n=1}^N \alpha_n \mathbf{x}_n$ is the **expansion** of \mathbf{x} on Y in \mathbf{L} if $\mathbf{x} = \sum_{n=1}^N \alpha_n \mathbf{x}_n$.

In this case, the sequence $(\alpha_n)_{n=1}^N$ is the **coordinates** of \mathbf{x} with respect to Y in \mathbf{L} .
If $\alpha_N \neq 0$, then N is the **dimension** $\dim \mathbf{L}$ of \mathbf{L} .

Theorem H.1. ⁷ Let $\{\mathbf{x}_n \mid n=1,2,\dots,N\}$ be a HAMEL BASIS (Definition H.4 page 185) for a LINEAR SPACE $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$.

THM

$$\left\{ \mathbf{x} = \sum_{n=1}^N \alpha_n \mathbf{x}_n = \sum_{n=1}^N \beta_n \mathbf{x}_n \right\} \implies \underbrace{\alpha_n = \beta_n \quad \forall n=1,2,\dots,N}_{\text{coordinates of } \mathbf{x} \text{ are UNIQUE}} \quad \forall \mathbf{x} \in X$$

 PROOF:

$$\begin{aligned} \mathbf{0} &= \mathbf{x} - \mathbf{x} \\ &= \sum_{n=1}^N \alpha_n \mathbf{x}_n - \sum_{n=1}^N \beta_n \mathbf{x}_n \\ &= \sum_{n=1}^N (\alpha_n - \beta_n) \mathbf{x}_n \\ &\implies \{\mathbf{x}_n\} \text{ is linearly dependent if } (\alpha_n - \beta_n) \neq 0 \quad \forall n = 1, 2, \dots, N \\ &\implies (\alpha_n - \beta_n) = 0 \quad \forall n = 1, 2, \dots, N \quad (\text{because } \{\mathbf{x}_n\} \text{ is a basis and therefore must be linearly independent}) \\ &\implies \alpha_n = \beta_n \text{ for } n = 1, 2, \dots, N \end{aligned}$$



Theorem H.2. ⁸ Let $\mathbf{L} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ be a LINEAR SPACE.

THM

$$\left\{ \begin{array}{l} 1. \quad \{\mathbf{x}_n \in X \mid n=1,2,\dots,N\} \text{ is a HAMEL BASIS for } \mathbf{L} \\ 2. \quad \{\mathbf{y}_n \in X \mid n=1,2,\dots,M\} \text{ is a set of LINEARLY INDEPENDENT vectors in } \mathbf{L} \end{array} \right\} \text{ and } \left\{ \begin{array}{l} 1. \quad M \leq N \\ 2. \quad M = N \implies \{\mathbf{y}_n \mid n=1,2,\dots,M\} \text{ is a BASIS for } \mathbf{L} \\ 3. \quad M \neq N \implies \{\mathbf{y}_n \mid n=1,2,\dots,M\} \text{ is NOT a basis for } \mathbf{L} \end{array} \right\} \text{ and } \left\{ \begin{array}{l} \text{and} \\ \text{and} \end{array} \right\}$$

 PROOF:

⁵ Hamel (1905), Bachman and Narici (1966) page 4, Kubrusly (2001) pages 48–49 (Section 2.4), Young (2001) page 1, Carothers (2005) page 25, Heil (2011) page 125 (Definition 4.1)

⁶ Hamel (1905), Bachman and Narici (1966) page 4, Kubrusly (2001) pages 48–49 (Section 2.4), Young (2001) page 1, Carothers (2005) page 25, Heil (2011) page 125 (Definition 4.1)

⁷ Michel and Herget (1993) pages 89–90 (Theorem 3.3.25)

⁸ Michel and Herget (1993) pages 90–91 (Theorem 3.3.26)

1. Proof that $\{y_1, x_1, \dots, x_{N-1}\}$ is a *basis* for L :

(a) Proof that $\{y_1, x_1, \dots, x_{N-1}\}$ *spans* L :

i. Because $\{x_n | n=1,2,\dots,N\}$ is a *basis* for L , there exists $\beta \in \mathbb{F}$ and $\{\alpha_n \in \mathbb{F} | n=1,2,\dots,N\}$ such that

$$\beta y_1 + \sum_{n=1}^N \alpha_n x_n = 0.$$

ii. Select an n such that $\alpha_n \neq 0$ and renumber (if necessary) the above indices such that

$$x_n = -\frac{\beta}{\alpha_n} y_1 + \sum_{n=1}^{N-1} \frac{\alpha_n}{\alpha_n} x_n.$$

iii. Then, for any $y \in X$, we can write

$$\begin{aligned} y &= \sum_{n=1}^N \gamma_n x_n \\ &= \left(\sum_{n=1}^{N-1} \gamma_n x_n \right) + \gamma_N \left(-\frac{\beta}{\alpha_n} y_1 - \sum_{n=1}^{N-1} \frac{\alpha_n}{\alpha_n} x_n \right) \\ &= -\frac{\beta \gamma_N}{\alpha_n} y_1 + \sum_{n=1}^{N-1} \left(\gamma_n - \frac{\alpha_n \gamma_N}{\alpha_n} \right) x_n \\ &= \delta y_1 + \sum_{n=1}^{N-1} \delta_n x_n \end{aligned}$$

iv. This implies that $\{y_1, x_1, \dots, x_{N-1}\}$ *spans* L :

(b) Proof that $\{y_1, x_1, \dots, x_{N-1}\}$ is *linearly independent*:

i. If $\{y_1, x_1, \dots, x_{N-1}\}$ is *linearly dependent*, then there exists $\{\epsilon, \epsilon_1, \dots, \epsilon_{N-1}\}$ such that

$$\epsilon y_1 + \left(\sum_{n=1}^{N-1} \epsilon_n x_n \right) + 0 x_n = 0.$$

ii. item (1(b)i) implies that the coordinate of y_1 associated with x_n is 0.

$$y_1 = -\left(\sum_{n=1}^{N-1} \frac{\epsilon_n}{\epsilon} x_n \right) + 0 x_n = 0.$$

iii. item (1(a)i) implies that the coordinate of y_1 associated with x_n is *not* 0.

$$y_1 = -\sum_{n=1}^N \frac{\alpha_n}{\beta} x_n.$$

iv. This implies that item (1(b)i) (that the set is linearly dependent) is *false* because item (1(b)ii) and item (1(b)iii) *contradict* each other.

v. This implies $\{y_1, x_1, \dots, x_{N-1}\}$ is *linearly independent*.

2. Proof that $\{y_1, y_2, x_1, \dots, x_{N-2}\}$ is a *basis*: Repeat item (1).

3. Suppose $m = n$. Proof that $\{y_1, y_2, \dots, y_M\}$ is a *basis*: Repeat item (1) $M - 1$ times.

4. Proof that $M \neq N$:

(a) Suppose that $M = N + 1$.

(b) Then because $\{y_n | n=1,2,\dots,N\}$ is a *basis*, there exists $\{\zeta_n | n=1,2,\dots,N+1\}$ such that

$$\sum_{n=1}^{N+1} \zeta_n y_n = 0.$$

(c) This implies that $\{y_n | n=1,2,\dots,N+1\}$ is *linearly dependent*.

(d) This implies that $\{y_n|_{n=1,2,\dots,N+1}\}$ is *not* a basis.

(e) This implies that $M \neq N$.

5. Proof that $M \neq N \implies \{y_n|_{n=1,2,\dots,M}\}$ is *not* a basis for L :

(a) Proof that $M > N \implies \{y_n|_{n=1,2,\dots,M}\}$ is *not* a basis for L : same as in item (4).

(b) Proof that $M < N \implies \{y_n|_{n=1,2,\dots,M}\}$ is *not* a basis for L :

i. Suppose $m = N - 1$.

ii. Then $\{y_n|_{n=1,2,\dots,N-1}\}$ is a *basis* and there exists λ such that

$$\sum_{n=1}^N \lambda_{n \in \mathbb{Z}} y_{n \in \mathbb{Z}} = 0.$$

iii. This implies that $\{y_n|_{n=1,2,\dots,N}\}$ is *linearly dependent* and is *not* a basis.

iv. But this contradicts item (3), therefore $M \neq N - 1$.

v. Because $M = N$ yields a basis but $M = N - 1$ does not, $M < N - 1$ also does not yield a basis.

⇒

Corollary H.1. ⁹ Let $L \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}))$ be a linear space.

COR	$\left\{ \begin{array}{l} 1. \{x_n \in X _{n=1,2,\dots,N}\} \text{ is a HAMEL BASIS for } L \text{ and} \\ 2. \{y_n \in X _{n=1,2,\dots,M}\} \text{ is a HAMEL BASIS for } L \end{array} \right\} \implies \{N = M\}$ <p style="text-align: center; margin-top: 5px;">(all Hamel bases for L have the same number of vectors)</p>
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✎ PROOF: This follows from Theorem H.2 (page 185).

⇒

H.2 Bases in topological linear spaces

A linear space supports the concept of the *span* of a set of vectors (Definition H.2 page 183). In a topological linear space $\Omega \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), T)$, a set A is said to be *total* in Ω if the span of A is *dense* in Ω . In this case, A is said to be a *total set* or a *complete set*. However, this use of “complete” in a “complete set” is not equivalent to the use of “complete” in a “complete metric space”.¹⁰ In this text, except for these comments and Definition H.6, “complete” refers to the metric space definition only.

If a set is both *total* and *linearly independent* (Definition H.3 page 183) in Ω , then that set is a *Hamel basis* (Definition H.4 page 185) for Ω .

Definition H.6. ¹¹ Let A^- be the CLOSURE of a A in a TOPOLOGICAL LINEAR SPACE $\Omega \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), T)$. Let $\text{span } A$ be the SPAN (Definition H.2 page 183) of a set A .

DEF	<p>A set of vectors A is total (or complete or fundamental) in Ω if</p> $(\text{span } A)^- = \Omega \quad (\text{SPAN of } A \text{ is DENSE in } \Omega).$
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⁹ Kubrusly (2001) page 52 (Theorem 2.7), Michel and Herget (1993) page 91 (Theorem 3.3.31)

¹⁰ Haaser and Sullivan (1991) pages 296–297 (6-Orthogonal Bases), Rynne and Youngson (2008) page 78 (Remark 3.50), Heil (2011) page 21 (Remark 1.26)

¹¹ Young (2001) page 19 (Definition 1.5.1), Sohrab (2003) page 362 (Definition 9.2.3), Gupta (1998) page 134 (Definition 2.4), Bachman and Narici (1966) pages 149–153 (Definition 9.3, Theorems 9.9 and 9.10)

H.3 Schauder bases in Banach spaces

Definition H.7. ¹² Let $\mathbf{B} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$ be a BANACH SPACE. Let $\dot{=}$ represent STRONG CONVERGENCE in \mathbf{B} .

The countable set $\{x_n \in X \mid n \in \mathbb{N}\}$ is a **Schauder basis** for \mathbf{B} if for each $x \in X$

1. $\exists (\alpha_n \in \mathbb{F})_{n \in \mathbb{N}}$ such that $x \dot{=} \sum_{n=1}^{\infty} \alpha_n x_n$ (STRONG CONVERGENCE in \mathbf{B}) and
2. $\left\{ \sum_{n=1}^{\infty} \alpha_n x_n \dot{=} \sum_{n=1}^{\infty} \beta_n x_n \right\} \Rightarrow \{(\alpha_n) = (\beta_n)\}$ (COEFFICIENT FUNCTIONALS are UNIQUE)

In this case, $\sum_{n=1}^{\infty} \alpha_n x_n$ is the **expansion** of x on $\{x_n \mid n \in \mathbb{N}\}$ and

the elements of (α_n) are the **coefficient functionals** associated with the basis $\{x_n\}$. Coefficient functionals are also called **coordinate functionals**.

In a Banach space, the existence of a Schauder basis implies that the space is *separable* (Theorem H.3 page 188). The question of whether the converse is also true was posed by Banach himself in 1932,¹³ and became known as “*The basis problem*”. This remained an open question for many years. The question was finally answered some 41 years later in 1973 by Per Enflo (University of California at Berkeley), with the answer being “no”. Enflo constructed a counterexample in which a separable Banach space does *not* have a Schauder basis.¹⁴ Life is simpler in Hilbert spaces where the converse is true: a Hilbert space has a Schauder basis *if and only if* it is separable (Theorem H.11 page 201).

Theorem H.3. ¹⁵ Let $\mathbf{B} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$ be a BANACH SPACE. Let \mathbb{Q} be the field of rational numbers.

$$\left\{ \begin{array}{l} 1. \mathbf{B} \text{ has a SCHAUDER BASIS and} \\ 2. \mathbb{Q} \text{ is DENSE in } \mathbb{F}. \end{array} \right\} \Rightarrow \{ \mathbf{B} \text{ is SEPARABLE} \}$$

PROOF:

1. lemma:

$$\left| \left\{ x \mid \exists (\alpha_n \mathbb{Q})_{n \in \mathbb{N}} \text{ such that } \lim_{N \rightarrow \infty} \left\| x - \sum_{n=1}^N \alpha_n x_n \right\| = 0 \right\} \right| = |\mathbb{Q} \times \mathbb{N}|$$

$$= |\mathbb{Z} \times \mathbb{Z}|$$

$$= |\mathbb{Z}|$$

$$= \text{countably infinite}$$

¹² Carothers (2005) pages 24–25, Christensen (2003) pages 46–49 (Definition 3.1.1 and page 49), Young (2001) page 19 (Section 6), Singer (1970) page 17, Schauder (1927), Schauder (1928)

¹³ Banach (1932a) page 111

¹⁴ Enflo (1973), Lindenstrauss and Tzafriri (1977) pages 84–95 (Section 2.d)

¹⁵ Bachman et al. (2002) page 112 (3.4.8), Giles (2000) page 17, Heil (2011) page 21 (Theorem 1.27)

2. remainder of proof:

\mathcal{B} has a Schauder basis $(\mathbf{x}_n)_{n \in \mathbb{N}}$

\Rightarrow for every $\mathbf{x} \in \mathcal{B}$, there exists $(\alpha_n \in \mathbb{F})_{n \in \mathbb{N}}$ such that $\mathbf{x} \doteq \sum_{n=1}^{\infty} \alpha_n \mathbf{x}_n$ by Definition H.7 page 188

\Rightarrow for every $\mathbf{x} \in \mathcal{B}$, there exists $(\alpha_n \in \mathbb{F})_{n \in \mathbb{N}}$ such that $\lim_{N \rightarrow \infty} \left\| \mathbf{x} - \sum_{n=1}^N \alpha_n \mathbf{x}_n \right\| = 0$

\Rightarrow for every $\mathbf{x} \in \mathcal{B}$, there exists $(\alpha_n \in \mathbb{Q})_{n \in \mathbb{N}}$ such that $\lim_{N \rightarrow \infty} \left\| \mathbf{x} - \sum_{n=1}^N \alpha_n \mathbf{x}_n \right\| = 0$ because $\mathbb{Q}^- = \mathbb{F}$

$\Rightarrow \mathcal{B} = \left\{ \mathbf{x} \mid \exists (\alpha_n \mathbb{Q})_{n \in \mathbb{N}} \text{ such that } \lim_{N \rightarrow \infty} \left\| \mathbf{x} - \sum_{n=1}^N \alpha_n \mathbf{x}_n \right\| = 0 \right\}$

$\Rightarrow \mathcal{B} = \left\{ \mathbf{x} \mid \exists (\alpha_n \mathbb{Q})_{n \in \mathbb{N}} \text{ such that } \mathbf{x} = \lim_{N \rightarrow \infty} \sum_{n=1}^N \alpha_n \mathbf{x}_n \right\}^-$

$\Rightarrow \mathcal{B}$ is separable by (1) lemma page 188

\Rightarrow

Definition H.8. ¹⁶ Let $\{\mathbf{x}_n \mid n \in \mathbb{N}\}$ and $\{\mathbf{y}_n \mid n \in \mathbb{N}\}$ be SCHAUDER BASES of a BANACH SPACE $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$.

DEF $\{\mathbf{x}_n\}$ is **equivalent** to $\{\mathbf{y}_n\}$
if there exists a BOUNDED INVERTIBLE operator \mathbf{R} in $\mathbf{X}^{\mathbf{X}}$ such that $\mathbf{R}\mathbf{x}_n = \mathbf{y}_n \quad \forall n \in \mathbb{Z}$

Theorem H.4. ¹⁷ Let $\{\mathbf{x}_n \mid n \in \mathbb{N}\}$ and $\{\mathbf{y}_n \mid n \in \mathbb{N}\}$ be SCHAUDER BASES of a BANACH SPACE $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \|\cdot\|)$.

THM $\{\{\mathbf{x}_n\} \text{ is EQUIVALENT to } \{\mathbf{y}_n\}\}$
 $\iff \left\{ \sum_{n=1}^{\infty} \alpha_n \mathbf{x}_n \text{ is CONVERGENT} \iff \sum_{n=1}^{\infty} \alpha_n \mathbf{y}_n \text{ is CONVERGENT} \right\}$

Lemma H.1. ¹⁸ Let $\Omega \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), T)$ be a topological linear space. Let $\text{span } A$ be the SPAN of a set A (Definition H.2 page 183). Let $\tilde{\mathbf{f}}(\omega)$ and $\tilde{\mathbf{g}}(\omega)$ be the FOURIER TRANSFORMS (Definition 3.2 page 26) of the functions $\mathbf{f}(x)$ and $\mathbf{g}(x)$, respectively, in $\mathbf{L}_{\mathbb{R}}^2$ (Definition B.1 page 99). Let $\check{\mathbf{a}}(\omega)$ be the DTFT (Definition 8.1 page 59) of a sequence $(a_n)_{n \in \mathbb{Z}}$ in $\ell_{\mathbb{R}}^2$ (Definition 9.2 page 69).

LEM $\left\{ \begin{array}{l} (1). \quad \{\mathbf{T}^n \mathbf{f} \mid n \in \mathbb{Z}\} \text{ is a SCHAUDER BASIS for } \Omega \text{ and} \\ (2). \quad \{\mathbf{T}^n \mathbf{g} \mid n \in \mathbb{Z}\} \text{ is a SCHAUDER BASIS for } \Omega \end{array} \right\} \implies \left\{ \begin{array}{l} \exists (a_n)_{n \in \mathbb{Z}} \text{ such that} \\ \tilde{\mathbf{f}}(\omega) = \check{\mathbf{a}}(\omega) \tilde{\mathbf{g}}(\omega) \end{array} \right\}$

\P PROOF: Let \mathbf{V}_0' be the space spanned by $\{\mathbf{T}^n \phi \mid n \in \mathbb{Z}\}$.

$$\begin{aligned} \tilde{\mathbf{f}}(\omega) &\triangleq \tilde{\mathbf{F}}\mathbf{f} && \text{by definition of } \tilde{\mathbf{F}} && (\text{Definition 3.2 page 26}) \\ &= \tilde{\mathbf{F}} \sum_{n \in \mathbb{Z}} a_n \mathbf{T}g && \text{by (2)} \\ &= \sum_{n \in \mathbb{Z}} a_n \tilde{\mathbf{F}}\mathbf{T}g \end{aligned}$$

¹⁶ Young (2001) page 25 (Definition 1.8.1, Theorem 1.8.7)

¹⁷ Young (2001) page 25 (Definition 1.8.1, Theorem 1.8.7)

¹⁸ Daubechies (1992) page 140

$$= \underbrace{\sum_{n \in \mathbb{Z}} a_n e^{-i\omega n}}_{\check{a}(\omega)} \tilde{\mathbf{F}} \tilde{\mathbf{g}} \quad (\text{Corollary J.1 page 229})$$

$$= \check{a}(\omega) \tilde{\mathbf{g}}(\omega) \quad \text{by definition of } \tilde{\mathbf{F}} \text{ and } \tilde{\mathbf{g}} \quad (\text{Definition 8.1 page 59}) (\text{Definition 3.2 page 26})$$

$$\begin{aligned} \mathbf{V}_0 &\triangleq \left\{ f(x) \mid f(x) = \sum_{n \in \mathbb{Z}} b_n \mathbf{T}^n g(x) \right\} \\ &= \left\{ f(x) \mid \tilde{\mathbf{F}} f(x) = \tilde{\mathbf{F}} \sum_{n \in \mathbb{Z}} b_n \mathbf{T}^n g(x) \right\} \\ &= \{ f(x) \mid \tilde{f}(\omega) = \tilde{b}(\omega) \tilde{g}(\omega) \} \\ &= \{ f(x) \mid \tilde{f}(\omega) = \tilde{b}(\omega) \check{a}(\omega) \tilde{f}(\omega) \} \\ &= \{ f(x) \mid \tilde{f}(\omega) = \check{c}(\omega) \tilde{f}(\omega) \} \quad \text{where } \check{c}(\omega) \triangleq \tilde{b}(\omega) \check{a}(\omega) \\ &= \left\{ f(x) \mid f(x) = \sum_{n \in \mathbb{Z}} c_n f(x - n) \right\} \\ &\triangleq \mathbf{V}'_0 \end{aligned}$$



H.4 Linear combinations in inner product spaces

Definition H.9. Let $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \Delta \mid \nabla \rangle)$ be an INNER PRODUCT SPACE (Definition G.9 page 166).

DEF Two vectors \mathbf{x} and \mathbf{y} in X are **orthogonal** if

$$\langle \mathbf{x} \mid \mathbf{y} \rangle = \begin{cases} 0 & \text{for } \mathbf{x} \neq \mathbf{y} \\ c \in \mathbb{F} \setminus 0 & \text{for } \mathbf{x} = \mathbf{y} \end{cases}$$

In an *inner product space*, *orthogonality* is a special case of *linear independence*; or alternatively, linear independence is a generalization of orthogonality (next theorem).

Theorem H.5. ¹⁹ Let $\{\mathbf{x}_n \in X \mid n=1,2,\dots,N\}$ be a set of vectors in an INNER PRODUCT SPACE (Definition G.9 page 166) $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \Delta \mid \nabla \rangle)$.

THM $\left\{ \begin{array}{l} \{\mathbf{x}_n\} \text{ is ORTHOGONAL} \\ (\text{Definition H.9 page 190}) \end{array} \right\} \implies \left\{ \begin{array}{l} \{\mathbf{x}_n\} \text{ is LINEARLY INDEPENDENT} \\ (\text{Definition H.1 page 183}) \end{array} \right\}$

PROOF:

1. Proof using *Pythagorean theorem*:

Let $(\alpha_n)_{n \in \mathbb{N}}$ be a sequence with at least one nonzero element.

¹⁹ Aliprantis and Burkinshaw (1998) page 283 (Corollary 32.8), Kubrusly (2001) page 352 (Proposition 5.34)

$$\begin{aligned}
\left\| \sum_{n=1}^N \alpha_n \mathbf{x}_n \right\|^2 &= \sum_{n=1}^N \|\alpha_n \mathbf{x}_n\|^2 && \text{by left hypoth. and Pythagorean Theorem} \\
&= \sum_{n=1}^N |\alpha_n|^2 \|\mathbf{x}_n\|^2 && \text{by definition of } \|\cdot\| \quad (\text{Definition G.5 page 158}) \\
&> 0 \\
\Rightarrow \sum_{n=1}^N \alpha_n \mathbf{x}_n &\neq 0 \\
\Rightarrow (\mathbf{x}_n)_{n \in \mathbb{N}} &\text{ is linearly independent by definition of linear independence} \quad (\text{Definition H.3 page 183})
\end{aligned}$$

2. Alternative proof:

$$\begin{aligned}
\sum_{n=1}^N \alpha_n \mathbf{x}_n = \mathbf{0} &\Rightarrow \left\langle \sum_{n=1}^N \alpha_n \mathbf{x}_n \mid \mathbf{x}_m \right\rangle = \langle \mathbf{0} \mid \mathbf{x}_m \rangle \\
&\Rightarrow \sum_{n=1}^N \alpha_n \langle \mathbf{x}_n \mid \mathbf{x}_m \rangle = 0 \\
&\Rightarrow \sum_{n=1}^N \alpha_n \delta(k-m) = 0 \\
&\Rightarrow \alpha_m = 0 \quad \text{for } m = 1, 2, \dots, N
\end{aligned}$$

⇒

Theorem H.6 (Bessel's Equality).²⁰ Let $\{\mathbf{x}_n \in X \mid n=1,2,\dots,N\}$ be a set of vectors in an INNER PRODUCT SPACE (Definition G.9 page 166) $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle \mid \nabla \rangle)$ and with $\|\mathbf{x}\| \triangleq \sqrt{\langle \mathbf{x} \mid \mathbf{x} \rangle}$.

$$\text{THM} \quad \left\{ \begin{array}{l} \{\mathbf{x}_n\} \text{ is ORTHONORMAL} \\ (\text{Definition H.9 page 190}) \end{array} \right\} \Rightarrow \left\{ \underbrace{\left\| \mathbf{x} - \sum_{n=1}^N \langle \mathbf{x} \mid \mathbf{x}_n \rangle \mathbf{x}_n \right\|^2}_{\text{approximation error}} = \|\mathbf{x}\|^2 - \sum_{n=1}^N |\langle \mathbf{x} \mid \mathbf{x}_n \rangle|^2 \quad \forall \mathbf{x} \in X} \right\}$$

PROOF:

$$\begin{aligned}
&\left\| \mathbf{x} - \sum_{n=1}^N \langle \mathbf{x} \mid \mathbf{x}_n \rangle \mathbf{x}_n \right\|^2 \\
&= \|\mathbf{x}\|^2 + \left\| \sum_{n=1}^N \langle \mathbf{x} \mid \mathbf{x}_n \rangle \mathbf{x}_n \right\|^2 - 2\Re \left\langle \mathbf{x} \mid \sum_{n=1}^N \langle \mathbf{x} \mid \mathbf{x}_n \rangle \mathbf{x}_n \right\rangle && \text{by polar identity} \\
&= \|\mathbf{x}\|^2 + \left\| \sum_{n=1}^N \langle \mathbf{x} \mid \mathbf{x}_n \rangle \mathbf{x}_n \right\|^2 - 2\Re \left[\left(\sum_{n=1}^N \langle \mathbf{x} \mid \mathbf{x}_n \rangle \right)^* \langle \mathbf{x} \mid \mathbf{x}_n \rangle \right] && \text{by property of } \langle \triangle \mid \nabla \rangle \quad (\text{Definition G.9 page 166}) \\
&= \|\mathbf{x}\|^2 + \sum_{n=1}^N \|\langle \mathbf{x} \mid \mathbf{x}_n \rangle \mathbf{x}_n\|^2 - 2\Re \left[\left(\sum_{n=1}^N \langle \mathbf{x} \mid \mathbf{x}_n \rangle \right)^* \langle \mathbf{x} \mid \mathbf{x}_n \rangle \right] && \text{by Pythagorean Theorem}
\end{aligned}$$

²⁰ Bachman et al. (2002) page 103, Pedersen (2000) pages 38–39

$$\begin{aligned}
&= \|x\|^2 + \sum_{n=1}^N \|\langle x | x_n \rangle x_n\|^2 - 2\Re \left(\sum_{n=1}^N \langle x | x_n \rangle^* \langle x | x_n \rangle \right) \\
&= \|x\|^2 + \sum_{n=1}^N |\langle x | x_n \rangle|^2 \underbrace{\|x_n\|^2}_1 - 2\Re \left(\sum_{n=1}^N \langle x | x_n \rangle^* \langle x | x_n \rangle \right) \quad \text{by property of } \|\cdot\| \quad (\text{Definition G.5 page 158}) \\
&= \|x\|^2 + \sum_{n=1}^N |\langle x | x_n \rangle|^2 \cdot 1 - 2\Re \left(\sum_{n=1}^N \langle x | x_n \rangle^* \langle x | x_n \rangle \right) \quad \text{by def. of orthonormality} \quad (\text{Definition H.9 page 190}) \\
&= \|x\|^2 + \sum_{n=1}^N |\langle x | x_n \rangle|^2 - 2\Re \sum_{n=1}^N |\langle x | x_n \rangle|^2 \\
&= \|x\|^2 + \sum_{n=1}^N |\langle x | x_n \rangle|^2 - 2 \sum_{n=1}^N |\langle x | x_n \rangle|^2 \quad \text{because } |\cdot| \text{ is real} \\
&= \|x\|^2 - \sum_{n=1}^N |\langle x | x_n \rangle|^2
\end{aligned}$$

⇒

Theorem H.7 (Bessel's inequality).²¹ Let $\{x_n \in X \mid n=1,2,\dots,N\}$ be a set of vectors in an INNER PRODUCT SPACE (Definition G.9 page 166) $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ and with $\|x\| \triangleq \sqrt{\langle x | x \rangle}$.

T H M	$ \left\{ \begin{array}{l} \{x_n\} \text{ is ORTHONORMAL} \\ (\text{Definition H.9 page 190}) \end{array} \right\} \implies \left\{ \sum_{n=1}^N \langle x x_n \rangle ^2 \leq \ x\ ^2 \quad \forall x \in X \right\} $
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✎ PROOF:

$$\begin{aligned}
0 &\leq \left\| x - \sum_{n=1}^N \langle x | x_n \rangle x_n \right\|^2 && \text{by definition of } \|\cdot\| && (\text{Definition G.5 page 158}) \\
&= \|x\|^2 - \sum_{n=1}^N |\langle x | x_n \rangle|^2 && \text{by Bessel's Equality} && (\text{Theorem H.6 page 191})
\end{aligned}$$

⇒

The *Best Approximation Theorem* (next) shows that

- 🔗 the best sequence for representing a vector is the sequence of projections of the vector onto the sequence of basis functions
- 🔗 the error of the projection is orthogonal to the projection.

Theorem H.8 (Best Approximation Theorem).²² Let $\{x_n \in X \mid n=1,2,\dots,N\}$ be a set of vectors in an INNER PRODUCT SPACE (Definition G.9 page 166) $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ and with $\|x\| \triangleq \sqrt{\langle x | x \rangle}$.

²¹ 📖 Giles (2000) pages 54–55 (3.13 Bessel's inequality), 📖 Bollobás (1999) page 147, 📖 Aliprantis and Burkinshaw (1998) page 284

²² 📖 Walter and Shen (2001) pages 3–4, 📖 Pedersen (2000) page 39, 📖 Edwards (1995) pages 94–100, 📖 Weyl (1940)

T H M

$$\left\{ \begin{array}{c} \{\mathbf{x}_n\} \text{ is} \\ \text{ORTHONORMAL} \\ \text{(Definition H.9 page 190)} \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} 1. \arg \min_{(\alpha_n)_{n=1}^N} \left\| \mathbf{x} - \sum_{n=1}^N \alpha_n \mathbf{x}_n \right\| = \underbrace{(\langle \mathbf{x} | \mathbf{x}_n \rangle)_{n=1}^N}_{\text{best } \alpha_n = \langle \mathbf{x} | \mathbf{x}_n \rangle} \quad \forall \mathbf{x} \in X \quad \text{and} \\ 2. \underbrace{\left(\sum_{n=1}^N \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n \right)}_{\text{approximation}} \perp \underbrace{\left(\mathbf{x} - \sum_{n=1}^N \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n \right)}_{\text{approximation error}} \quad \forall \mathbf{x} \in X \end{array} \right\}$$

PROOF:

1. Proof that $(\langle \mathbf{x} | \mathbf{x}_n \rangle)$ is the best sequence:

$$\begin{aligned} & \left\| \mathbf{x} - \sum_{n=1}^N \alpha_n \mathbf{x}_n \right\|^2 \\ &= \|\mathbf{x}\|^2 - 2\Re \left\langle \mathbf{x} \left| \sum_{n=1}^N \alpha_n \mathbf{x}_n \right. \right\rangle + \left\| \sum_{n=1}^N \alpha_n \mathbf{x}_n \right\|^2 \\ &= \|\mathbf{x}\|^2 - 2\Re \left(\sum_{n=1}^N \alpha_n^* \langle \mathbf{x} | \mathbf{x}_n \rangle \right) + \sum_{n=1}^N \|\alpha_n \mathbf{x}_n\|^2 \quad \text{by Pythagorean Theorem} \\ &= \|\mathbf{x}\|^2 - 2\Re \left(\sum_{n=1}^N \alpha_n^* \langle \mathbf{x} | \mathbf{x}_n \rangle \right) + \sum_{n=1}^N |\alpha_n|^2 + \underbrace{\left[\sum_{n=1}^N |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 - \sum_{n=1}^N |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 \right]}_0 \\ &= \left[\|\mathbf{x}\|^2 - \sum_{n=1}^N |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 \right] + \sum_{n=1}^N \left[|\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 - 2\Re [\alpha_n^* \langle \mathbf{x} | \mathbf{x}_n \rangle] + |\alpha_n|^2 \right] \\ &= \left[\|\mathbf{x}\|^2 - \sum_{n=1}^N |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 \right] + \sum_{n=1}^N \left[|\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 - \alpha_n^* \langle \mathbf{x} | \mathbf{x}_n \rangle - \alpha_n \langle \mathbf{x} | \mathbf{x}_n \rangle^* + |\alpha_n|^2 \right] \\ &= \left\| \mathbf{x} - \sum_{n=1}^N \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n \right\|^2 + \sum_{n=1}^N |\langle \mathbf{x} | \mathbf{x}_n \rangle - \alpha_n|^2 \quad \text{by Bessel's Equality} \quad (\text{Theorem H.6 page 191}) \\ &\geq \left\| \mathbf{x} - \sum_{n=1}^N \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n \right\|^2 \end{aligned}$$

2. Proof that the approximation and approximation error are orthogonal:

$$\begin{aligned} \left\langle \sum_{n=1}^N \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n \left| \mathbf{x} - \sum_{n=1}^N \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n \right. \right\rangle &= \left\langle \sum_{n=1}^N \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n \left| \mathbf{x} \right. \right\rangle - \left\langle \sum_{n=1}^N \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n \left| \sum_{n=1}^N \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n \right. \right\rangle \\ &= \sum_{n=1}^N \langle \mathbf{x} | \mathbf{x}_n \rangle^* \langle \mathbf{x} | \mathbf{x}_n \rangle - \sum_{n=1}^N \sum_{m=1}^N \langle \mathbf{x} | \mathbf{x}_n \rangle \langle \mathbf{x} | \mathbf{x}_m \rangle^* \langle \mathbf{x}_n | \mathbf{x}_m \rangle \\ &= \sum_{n=1}^N |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 - \sum_{n=1}^N \sum_{m=1}^N \langle \mathbf{x} | \mathbf{x}_n \rangle \langle \mathbf{x} | \mathbf{x}_m \rangle^* \bar{\delta}_{nm} \\ &= \sum_{n=1}^N |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 - \sum_{n=1}^N |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 \\ &= 0 \end{aligned}$$



H.5 Orthonormal bases in Hilbert spaces

Definition H.10. Let $\{\mathbf{x}_n \in X \mid n=1,2,\dots,N\}$ be a set of vectors in an INNER PRODUCT SPACE (Definition G.9 page 166) $\Omega \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \Delta \mid \nabla \rangle)$.

DEF

The set $\{\mathbf{x}_n\}$ is an **orthogonal basis** for Ω if $\{\mathbf{x}_n\}$ is ORTHOGONAL and is a SCHAUDER BASIS for Ω .

The set $\{\mathbf{x}_n\}$ is an **orthonormal basis** for Ω if $\{\mathbf{x}_n\}$ is ORTHONORMAL and is a SCHAUDER BASIS for Ω .

Definition H.11. ²³ Let $H \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \Delta \mid \nabla \rangle)$ be a Hilbert space.

DEF

Suppose there exists a set $\{\mathbf{x}_n \in X \mid n \in \mathbb{N}\}$ such that $\mathbf{x} \triangleq \sum_{n=1}^{\infty} \langle \mathbf{x} \mid \mathbf{x}_n \rangle \mathbf{x}_n$.

Then the quantities $\langle \mathbf{x} \mid \mathbf{x}_n \rangle$ are called the **Fourier coefficients** of \mathbf{x} and the sum $\sum_{n=1}^{\infty} \langle \mathbf{x} \mid \mathbf{x}_n \rangle \mathbf{x}_n$ is called the **Fourier expansion** of \mathbf{x} or the **Fourier series** for \mathbf{x} .

Definition H.12.

DEF

The **Kronecker delta function** $\bar{\delta}_n$ is defined as $\bar{\delta}_n \triangleq \begin{cases} 1 & \text{for } n = 0 \\ 0 & \text{otherwise} \end{cases}$ and $\forall n \in \mathbb{Z}$

Lemma H.2 (Perfect reconstruction). Let $\{\mathbf{x}_n \in X \mid n \in \mathbb{N}\}$ be a set of vectors in a HILBERT SPACE $H \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \Delta \mid \nabla \rangle)$.

LEM

$$\left\{ \begin{array}{l} (1). \quad (\mathbf{x}_n) \text{ is a BASIS for } H \\ (2). \quad (\mathbf{x}_n) \text{ is ORTHONORMAL} \end{array} \right\} \text{ and } \Rightarrow \mathbf{x} \triangleq \sum_{n=1}^{\infty} \underbrace{\langle \mathbf{x} \mid \mathbf{x}_n \rangle}_{\text{Fourier coefficient}} \mathbf{x}_n \quad \forall \mathbf{x} \in X$$

Fourier expansion

PROOF:

$$\begin{aligned} \langle \mathbf{x} \mid \mathbf{x}_n \rangle &= \left\langle \sum_{m \in \mathbb{Z}} \alpha_m \mathbf{x}_m \mid \mathbf{x}_n \right\rangle && \text{by left hypothesis (1)} \\ &= \sum_{m \in \mathbb{Z}} \alpha_m \langle \mathbf{x}_m \mid \mathbf{x}_n \rangle && \text{by homogeneous property of } \langle \Delta \mid \nabla \rangle \quad (\text{Definition G.9 page 166}) \\ &= \sum_{m \in \mathbb{Z}} \alpha_m \bar{\delta}_{n-m} && \text{by left hypothesis (2)} \quad (\text{Definition H.9 page 190}) \\ &= \alpha_n \end{aligned}$$



Proposition H.2. ²⁴ Let $\{\mathbf{x}_n \in X \mid n \in \mathbb{N}\}$ be a set of vectors in a HILBERT SPACE $H \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \Delta \mid \nabla \rangle)$.

²³ Fabian et al. (2010) page 27 (Theorem 1.55), Young (2001) page 6, Young (1980) page 6

²⁴ Han et al. (2007) pages 93–94 (Proposition 3.11)

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$$\underbrace{\|x\|^2 \triangleq \sum_{n=1}^{\infty} |\langle x | x_n \rangle|^2}_{\text{PARSEVAL FRAME}} \iff \underbrace{x \triangleq \sum_{n=1}^{\infty} \langle x | x_n \rangle x_n}_{\text{FOURIER EXPANSION (Definition H.11 page 194)}} \quad \forall x \in X$$

 PROOF:

1. Proof that *Parseval frame* \iff *Fourier expansion*

$$\begin{aligned} \|x\|^2 &\triangleq \langle x | x \rangle && \text{by definition of } \|\cdot\| \\ &= \left\langle \sum_{n=1}^{\infty} \langle x | x_n \rangle x_n \mid x \right\rangle && \text{by right hypothesis} \\ &\triangleq \sum_{n=1}^{\infty} \langle x | x_n \rangle \langle x | x_n \rangle && \text{by property of } \langle \triangle | \nabla \rangle \\ &\triangleq \sum_{n=1}^{\infty} \langle x | x_n \rangle \langle x | x_n \rangle^* && \text{by property of } \langle \triangle | \nabla \rangle \\ &\triangleq \sum_{n=1}^{\infty} |\langle x | x_n \rangle|^2 && \text{by property of } \mathbb{C} \quad (\text{Definition F.7 page 151}) \end{aligned}$$

2. Proof that *Parseval frame* \implies *Fourier expansion*

(a) Let $(e_n)_{n \in \mathbb{N}}$ be the *standard orthonormal basis* such that the n th element of e_n is 1 and all other elements are 0.

(b) Let \mathbf{M} be an operator in H such that $\mathbf{M}x \triangleq \sum_{n=1}^{\infty} \langle x | x_n \rangle e_n$.

(c) lemma: \mathbf{M} is *isometric*. Proof:

$$\begin{aligned} \|\mathbf{M}x\|^2 &= \left\| \sum_{n=1}^{\infty} \langle x | x_n \rangle e_n \right\|^2 && \text{by definition of } \mathbf{M} \quad (\text{item (2b) page 195}) \\ &= \sum_{n=1}^{\infty} \|\langle x | x_n \rangle e_n\|^2 && \text{by Pythagorean Theorem} \\ &= \sum_{n=1}^{\infty} |\langle x | x_n \rangle|^2 \|e_n\|^2 && \text{by homogeneous property of } \|\cdot\| \quad (\text{Definition G.5 page 158}) \\ &= \sum_{n=1}^{\infty} |\langle x | x_n \rangle|^2 && \text{by definition of orthonormal} \quad (\text{Definition H.9 page 190}) \\ &= \|x\|^2 && \text{by Parseval frame hypothesis} \\ \implies \mathbf{M} \text{ is isometric} &&& \text{by definition of isometric} \quad (\text{Definition G.13 page 174}) \end{aligned}$$

(d) Let $(u_n)_{n \in \mathbb{N}}$ be an *orthonormal basis* for H .

(e) Proof for *Fourier expansion*:

$$\begin{aligned}
 x &= \sum_{n=1}^{\infty} \langle x | u_n \rangle u_n && \text{by } \textit{Fourier expansion} \text{ (Proposition H.3 page 198)} \\
 &= \sum_{n=1}^{\infty} \langle Mx | Mu_n \rangle u_n && \text{by (2c) lemma page 195 and Theorem G.23 page 175} \\
 &= \sum_{n=1}^{\infty} \left\langle \sum_{m=1}^{\infty} \langle x | x_m \rangle e_m \mid \sum_{k=1}^{\infty} \langle u_n | x_k \rangle e_k \right\rangle u_n && \text{by item (2b) page 195} \\
 &= \sum_{n=1}^{\infty} \sum_{m=1}^{\infty} \langle x | x_m \rangle \sum_{k=1}^{\infty} \langle u_n | x_k \rangle^* \langle e_m | e_k \rangle u_n && \text{by Definition G.9 page 166} \\
 &= \sum_{n=1}^{\infty} \sum_{m=1}^{\infty} \langle x | x_m \rangle \langle u_n | x_m \rangle^* u_n && \text{by item (2a) page 195 and Definition H.9 page 190} \\
 &= \sum_{n=1}^{\infty} \sum_{m=1}^{\infty} \langle x | x_m \rangle \langle x_m | u_n \rangle u_n && \text{by Definition G.9 page 166} \\
 &= \sum_{m=1}^{\infty} \langle x | x_m \rangle \sum_{n=1}^{\infty} \langle x_m | u_n \rangle u_n \\
 &= \sum_{m=1}^{\infty} \langle x | x_m \rangle x_m && \text{by item (2d) page 195}
 \end{aligned}$$

⇒

When is a set of orthonormal vectors in a Hilbert space H *total*? Theorem H.9 (next) offers some help.

Theorem H.9 (The Fourier Series Theorem).²⁵ Let $\{x_n \in X \mid n \in \mathbb{N}\}$ be a set of vectors in a HILBERT SPACE $H \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ and let $\|x\| \triangleq \sqrt{\langle x | x \rangle}$.

T H M	{	(A) $\{x_n\}$ is ORTHONORMAL in H \implies	}	
		(1). $(\text{span}\{x_n\})^- = H$		$(\{x_n\} \text{ is TOTAL in } H)$
		\iff (2). $\langle x y \rangle \stackrel{*}{=} \sum_{n=1}^{\infty} \langle x x_n \rangle \langle y x_n \rangle^* \quad \forall x, y \in X$		(GENERALIZED PARSEVAL'S IDENTITY)
		\iff (3). $\ x\ ^2 \stackrel{*}{=} \sum_{n=1}^{\infty} \langle x x_n \rangle ^2 \quad \forall x \in X$		(PARSEVAL'S IDENTITY)
		\iff (4). $x \stackrel{*}{=} \sum_{n=1}^{\infty} \langle x x_n \rangle x_n \quad \forall x \in X$		(FOURIER SERIES EXPANSION)

✎PROOF:

²⁵ [Bachman and Narici \(1966\) pages 149–155](#) (Theorem 9.12), [Kubrusly \(2001\) pages 360–363](#) (Theorem 5.48), [Aliprantis and Burkinshaw \(1998\) pages 298–299](#) (Theorem 34.2), [Christensen \(2003\) page 57](#) (Theorem 3.4.2), [Berberian \(1961\) pages 52–53](#) (Theorem II§8.3), [Heil \(2011\) pages 34–35](#) (Theorem 1.50), [Bracewell \(1978\) page 112](#) (Rayleigh's theorem)

1. Proof that (1) \implies (2):

$$\begin{aligned}
 \langle \mathbf{x} | \mathbf{y} \rangle &\stackrel{*}{=} \left\langle \sum_{n=1}^{\infty} \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n \mid \sum_{m=1}^{\infty} \langle \mathbf{y} | \mathbf{x}_m \rangle \mathbf{x}_m \right\rangle && \text{by (A) and (1)} \\
 &\stackrel{*}{=} \sum_{n=1}^{\infty} \langle \mathbf{x} | \mathbf{x}_n \rangle \left\langle \mathbf{x}_n \mid \sum_{m=1}^{\infty} \langle \mathbf{y} | \mathbf{x}_m \rangle \mathbf{x}_m \right\rangle && \text{by property of } \langle \cdot | \cdot \rangle \quad (\text{Definition G.9 page 166}) \\
 &\stackrel{*}{=} \sum_{n=1}^{\infty} \langle \mathbf{x} | \mathbf{x}_n \rangle \sum_{m=1}^{\infty} \langle \mathbf{y} | \mathbf{x}_m \rangle^* \langle \mathbf{x}_n | \mathbf{x}_m \rangle && \text{by property of } \langle \cdot | \cdot \rangle \quad (\text{Definition G.9 page 166}) \\
 &\stackrel{*}{=} \sum_{n=1}^{\infty} \langle \mathbf{x} | \mathbf{x}_n \rangle \sum_{m=1}^{\infty} \langle \mathbf{y} | \mathbf{x}_m \rangle^* \bar{\delta}_{mn} && \text{by (A)} \\
 &\stackrel{*}{=} \sum_{n=1}^{\infty} \langle \mathbf{x} | \mathbf{x}_n \rangle \langle \mathbf{y} | \mathbf{x}_n \rangle^* && \text{by definition of } \bar{\delta}_n \quad (\text{Definition H.12 page 194})
 \end{aligned}$$

2. Proof that (2) \implies (3):

$$\begin{aligned}
 \|\mathbf{x}\|^2 &\triangleq \langle \mathbf{x} | \mathbf{x} \rangle && \text{by definition of induced norm} \\
 &= \sum_{n=1}^{\infty} \langle \mathbf{x} | \mathbf{x}_n \rangle \langle \mathbf{x} | \mathbf{x}_n \rangle^* && \text{by (2)} \\
 &= \sum_{n=1}^{\infty} |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2
 \end{aligned}$$

3. Proof that (3) \iff (4) *not* using (A): by Proposition H.2 page 194

4. Proof that (3) \implies (1) (proof by contradiction):

(a) Suppose $\{\mathbf{x}_n\}$ is *not total*.

(b) Then there must exist a vector \mathbf{y} in H such that the set $B \triangleq \{\mathbf{x}_n\} \cup \mathbf{y}$ is *orthonormal*.

(c) Then $1 = \|\mathbf{y}\|^2 \neq \sum_{n=1}^{\infty} |\langle \mathbf{y} | \mathbf{x}_n \rangle|^2 = 0$.

(d) But this contradicts (3), and so $\{\mathbf{x}_n\}$ must be *total* and (3) \implies (1).

5. Extraneous proof that (3) \implies (4) (this proof is not really necessary here):

$$\begin{aligned}
 \left\| \mathbf{x} - \sum_{n=1}^{\infty} \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n \right\|^2 &= \|\mathbf{x}\|^2 - \sum_{n=1}^{\infty} |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 && \text{by Bessel's Equality} \quad (\text{Theorem H.6 page 191}) \\
 &= 0 && \text{by (3)} \\
 \implies \mathbf{x} &\stackrel{*}{=} \sum_{n=1}^{\infty} \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n && \text{by definition of } \stackrel{*}{=}
 \end{aligned}$$

6. Extraneous proof that (A) \implies (4) (this proof is not really necessary here)

(a) The sequence $\sum_{n=1}^N |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2$ is *monotonically increasing* in n .

(b) By Bessel's inequality (page 192), the sequence is upper bounded by $\|\mathbf{x}\|^2$:

$$\sum_{n=1}^N |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 \leq \|\mathbf{x}\|^2$$

- (c) Because this sequence is both monotonically increasing and bounded in n , it must equal its bound in the limit as n approaches infinity:

$$\lim_{N \rightarrow \infty} \sum_{n=1}^N |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 = \|\mathbf{x}\|^2 \quad (\text{H.1})$$

- (d) If we combine this result with *Bessel's Equality* (Theorem H.6 page 191) we have

$$\begin{aligned} \lim_{N \rightarrow \infty} \left\| \mathbf{x} - \sum_{n=1}^N \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n \right\|^2 &= \|\mathbf{x}\|^2 - \lim_{N \rightarrow \infty} \sum_{n=1}^N |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 \quad \text{by Bessel's Equality (Theorem H.6 page 191)} \\ &= \|\mathbf{x}\|^2 - \|\mathbf{x}\|^2 \quad \text{by equation (H.1) page 198} \\ &= 0 \end{aligned}$$

⇒

Proposition H.3 (Fourier expansion). *Let $\{\mathbf{x}_n \in X \mid n \in \mathbb{N}\}$ be a set of vectors in a HILBERT SPACE $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \Delta | \nabla \rangle)$.*

$$\underbrace{\{\mathbf{x}_n\} \text{ is an ORTHONORMAL BASIS for } H}_{(A)} \implies \underbrace{\left\{ \mathbf{x} \doteq \sum_{n=1}^{\infty} \alpha_n \mathbf{x}_n \right\}}_{(1)} \iff \underbrace{\left\{ \alpha_n = \langle \mathbf{x} | \mathbf{x}_n \rangle \right\}}_{(2)}$$

✎ PROOF:

1. Proof that (1) \implies (2): by Lemma H.2 page 194
2. Proof that (1) \impliedby (2):

$$\begin{aligned} \left\| \mathbf{x} - \sum_{n=1}^{\infty} \alpha_n \mathbf{x}_{n \in \mathbb{Z}} \right\|^2 &= \left\| \mathbf{x} - \sum_{n=1}^{\infty} \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_{n \in \mathbb{Z}} \right\|^2 \quad \text{by right hypothesis} \\ &= \|\mathbf{x}\|^2 - \sum_{n=1}^{\infty} |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 \quad \text{by Bessel's equality} \quad (\text{Theorem H.6 page 191}) \\ &= 0 \quad \text{by Parseval's Identity} \quad (\text{Theorem H.9 page 196}) \\ &\stackrel{\text{def}}{\iff} \mathbf{x} \doteq \sum_{n=1}^{\infty} \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n \quad \text{by definition of strong convergence} \end{aligned}$$

⇒

Proposition H.4 (Riesz-Fischer Theorem).²⁶ *Let $\{\mathbf{x}_n \in X \mid n \in \mathbb{N}\}$ be a set of vectors in a HILBERT SPACE $(X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \Delta | \nabla \rangle)$.*

$$\underbrace{\{\mathbf{x}_n\} \text{ is an ORTHONORMAL BASIS for } H}_{(A)} \implies \underbrace{\left\{ \sum_{n=1}^{\infty} |\alpha_n|^2 < \infty \right\}}_{(1)} \iff \underbrace{\left\{ \exists \mathbf{x} \in H \text{ such that } \alpha_n = \langle \mathbf{x} | \mathbf{x}_n \rangle \right\}}_{(2)}$$

✎ PROOF:

²⁶ Young (2001) page 6

1. Proof that (1) \implies (2):

(a) If (1) is true, then let $\mathbf{x} \triangleq \sum_{n \in \mathbb{N}} \alpha_n \mathbf{x}_n$.

(b) Then

$$\begin{aligned}
 \langle \mathbf{x} | \mathbf{x}_n \rangle &= \left\langle \sum_{m \in \mathbb{N}} \alpha_m \mathbf{x}_m | \mathbf{x}_n \right\rangle && \text{by definition of } \mathbf{x} \\
 &= \sum_{m \in \mathbb{N}} \alpha_m \langle \mathbf{x}_m | \mathbf{x}_n \rangle && \text{by homogeneous property of } \langle \triangle | \nabla \rangle \quad (\text{Definition G.9 page 166}) \\
 &= \sum_{m \in \mathbb{N}} \alpha_m \bar{\delta}_{mn} && \text{by (A)} \\
 &= \sum_{m \in \mathbb{N}} \alpha_n && \text{by definition of } \bar{\delta} \quad (\text{Definition H.12 page 194})
 \end{aligned}$$

2. Proof that (1) \longleftarrow (2):

$$\begin{aligned}
 \sum_{n \in \mathbb{N}} |\alpha_n|^2 &= \sum_{n \in \mathbb{N}} |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 && \text{by (2)} \\
 &\leq \|\mathbf{x}\|^2 && \text{by Bessel's Inequality} \quad (\text{Theorem H.7 page 192}) \\
 &\leq \infty
 \end{aligned}$$

\Rightarrow

Theorem H.10. ²⁷

All SEPARABLE HILBERT SPACES are ISOMORPHIC. That is,

T H M	$ \left\{ \begin{array}{l} \mathbf{X} \text{ is a separable Hilbert space} \\ \mathbf{Y} \text{ is a separable Hilbert space} \end{array} \right\} \text{ and } $	$ \implies \left\{ \begin{array}{l} \text{there is a BIJECTIVE operator } \mathbf{M} \in \mathbf{Y}^{\mathbf{X}} \text{ such that} \\ (1). \quad \mathbf{y} = \mathbf{M}\mathbf{x} \quad \forall \mathbf{x} \in \mathbf{X}, \mathbf{y} \in \mathbf{Y} \quad \text{and} \\ (2). \quad \ \mathbf{M}\mathbf{x}\ = \ \mathbf{x}\ \quad \forall \mathbf{x} \in \mathbf{X} \quad \text{and} \\ (3). \quad \langle \mathbf{M}\mathbf{x} \mathbf{M}\mathbf{y} \rangle = \langle \mathbf{x} \mathbf{y} \rangle \quad \forall \mathbf{x} \in \mathbf{X}, \mathbf{y} \in \mathbf{Y} \end{array} \right\} $
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 PROOF:

1. Let $\mathbf{X} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ be a separable Hilbert space with orthonormal basis $\{\mathbf{x}_n\}_{n \in \mathbb{N}}$.
Let $\mathbf{Y} \triangleq (Y, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ be a separable Hilbert space with orthonormal basis $\{\mathbf{y}_n\}_{n \in \mathbb{N}}$.


2. Proof that there exists *bijective* operator \mathbf{M} and its inverse \mathbf{M}^{-1} between $\{\mathbf{x}_n\}$ and $\{\mathbf{y}_n\}$:

(a) Let \mathbf{M} be defined such that $\mathbf{y}_n \triangleq \mathbf{M}\mathbf{x}_n$.

(b) Thus \mathbf{M} is a *bijection* between $\{\mathbf{x}_n\}$ and $\{\mathbf{y}_n\}$.

(c) Because \mathbf{M} is a *bijection* between $\{\mathbf{x}_n\}$ and $\{\mathbf{y}_n\}$, \mathbf{M} has an inverse operator \mathbf{M}^{-1} between $\{\mathbf{x}_n\}$ and $\{\mathbf{y}_n\}$ such that $\mathbf{x}_n = \mathbf{M}^{-1}\mathbf{y}_n$.

3. Proof that \mathbf{M} and \mathbf{M}^{-1} are *bijective* operators between \mathbf{X} and \mathbf{Y} :

²⁷  Young (2001) page 6

(a) Proof that \mathbf{M} maps \mathbf{X} into \mathbf{Y} :

$$\begin{aligned}
 \mathbf{x} \in \mathbf{X} &\iff \mathbf{x} \triangleq \sum_{n \in \mathbb{N}} \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n && \text{by Fourier expansion} && (\text{Theorem H.9 page 196}) \\
 &\implies \exists \mathbf{y} \in \mathbf{Y} \text{ such that } \langle \mathbf{y} | \mathbf{y}_n \rangle = \langle \mathbf{x} | \mathbf{x}_n \rangle && \text{by Riesz-Fischer Thm.} && (\text{Proposition H.4 page 198}) \\
 &\implies \\
 \mathbf{y} &= \sum_{n \in \mathbb{N}} \langle \mathbf{y} | \mathbf{y}_n \rangle \mathbf{y}_n && \text{by Fourier expansion} && (\text{Theorem H.9 page 196}) \\
 &= \sum_{n \in \mathbb{N}} \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{y}_n && \text{by Riesz-Fischer Thm.} && (\text{Proposition H.4 page 198}) \\
 &= \sum_{n \in \mathbb{N}} \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{M} \mathbf{x}_n && \text{by definition of } \mathbf{M} && (\text{item (2a) page 199}) \\
 &= \mathbf{M} \sum_{n \in \mathbb{N}} \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n && \text{by prop. of linear ops.} && (\text{Theorem G.1 page 155}) \\
 &= \mathbf{M} \mathbf{x} && \text{by definition of } \mathbf{x}
 \end{aligned}$$

(b) Proof that \mathbf{M}^{-1} maps \mathbf{Y} into \mathbf{X} :

$$\begin{aligned}
 \mathbf{y} \in \mathbf{Y} &\iff \mathbf{y} \triangleq \sum_{n \in \mathbb{N}} \langle \mathbf{y} | \mathbf{y}_n \rangle \mathbf{y}_n && \text{by Fourier expansion} && (\text{Theorem H.9 page 196}) \\
 &\implies \exists \mathbf{x} \in \mathbf{X} \text{ such that } \langle \mathbf{x} | \mathbf{x}_n \rangle = \langle \mathbf{y} | \mathbf{y}_n \rangle && \text{by Riesz-Fischer Thm.} && (\text{Proposition H.4 page 198}) \\
 &\implies \\
 \mathbf{x} &= \sum_{n \in \mathbb{N}} \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n && \text{by Fourier expansion} && (\text{Theorem H.9 page 196}) \\
 &= \sum_{n \in \mathbb{N}} \langle \mathbf{y} | \mathbf{y}_n \rangle \mathbf{x}_n && \text{by Riesz-Fischer Thm.} && (\text{Proposition H.4 page 198}) \\
 &= \sum_{n \in \mathbb{N}} \langle \mathbf{y} | \mathbf{y}_n \rangle \mathbf{M}^{-1} \mathbf{y}_n && \text{by definition of } \mathbf{M}^{-1} && (\text{item (2c) page 199}) \\
 &= \mathbf{M}^{-1} \sum_{n \in \mathbb{N}} \langle \mathbf{y} | \mathbf{y}_n \rangle \mathbf{y}_n && \text{by prop. of linear ops.} && (\text{Theorem G.1 page 155}) \\
 &= \mathbf{M}^{-1} \mathbf{y} && \text{by definition of } \mathbf{y}
 \end{aligned}$$

4. Proof for (2):

$$\begin{aligned}
 \|\mathbf{M} \mathbf{x}\|^2 &= \left\| \mathbf{M} \sum_{n \in \mathbb{N}} \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n \right\|^2 && \text{by Fourier expansion} && (\text{Theorem H.9 page 196}) \\
 &= \left\| \sum_{n \in \mathbb{N}} \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{M} \mathbf{x}_n \right\|^2 && \text{by property of linear operators} && (\text{Theorem G.1 page 155}) \\
 &= \left\| \sum_{n \in \mathbb{N}} \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{y}_n \right\|^2 && \text{by definition of } \mathbf{M} && (\text{item (2a) page 199}) \\
 &= \sum_{n \in \mathbb{N}} |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 && \text{by Parseval's Identity} && (\text{Proposition H.4 page 198}) \\
 &= \left\| \sum_{n \in \mathbb{N}} \langle \mathbf{x} | \mathbf{x}_n \rangle \mathbf{x}_n \right\|^2 && \text{by Parseval's Identity} && (\text{Proposition H.4 page 198}) \\
 &= \|\mathbf{x}\|^2 && \text{by Fourier expansion} && (\text{Theorem H.9 page 196})
 \end{aligned}$$

5. Proof for (3): by (2) and Theorem G.23 page 175

Theorem H.11. ²⁸ Let H be a HILBERT SPACE.

T H M H has a SCHAUDER BASIS $\iff H$ is SEPARABLE

Theorem H.12. ²⁹ Let H be a HILBERT SPACE.

T H M H has an ORTHONORMAL BASIS $\iff H$ is SEPARABLE

H.6 Riesz bases in Hilbert spaces

Definition H.13. ³⁰ Let $\{x_n \in X \mid n \in \mathbb{N}\}$ be a set of vectors in a SEPARABLE HILBERT SPACE $H \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), (\Delta \mid \nabla))$.

D E F $\{x_n\}$ is a **Riesz basis** for H if $\{x_n\}$ is EQUIVALENT (Definition H.8 page 189) to some ORTHONORMAL BASIS (Definition H.10 page 194) in H .

Definition H.14. ³¹ Let $(x_n \in X)_{n \in \mathbb{N}}$ be a sequence of vectors in a SEPARABLE HILBERT SPACE $H \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), (\Delta \mid \nabla))$.

D E F The sequence (x_n) is a **Riesz sequence** for H if

$$\exists A, B \in \mathbb{R}^+ \text{ such that } A \sum_{n=1}^{\infty} |\alpha_n|^2 \leq \left\| \sum_{n=1}^{\infty} \alpha_n x_n \right\|^2 \leq B \sum_{n=1}^{\infty} |\alpha_n|^2 \quad \forall (\alpha_n)_{n \in \mathbb{N}} \in \ell_{\mathbb{F}}^2.$$

Definition H.15. Let $X \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), (\Delta \mid \nabla))$ be an INNER PRODUCT SPACE (Definition G.9 page 166).

D E F The sequences $(x_n \in X)_{n \in \mathbb{Z}}$ and $(y_n \in X)_{n \in \mathbb{Z}}$ are **biorthogonal** with respect to each other in X if $\langle x_n \mid y_m \rangle = \delta_{nm}$

Lemma H.3. ³² Let $\{x_n \mid n \in \mathbb{N}\}$ be a sequence in a HILBERT SPACE $X \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), (\Delta \mid \nabla))$. Let $\{y_n \mid n \in \mathbb{N}\}$ be a sequence in a HILBERT SPACE $Y \triangleq (Y, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), (\Delta \mid \nabla))$. Let

L E M $\left\{ \begin{array}{l} \text{(i). } \{x_n\} \text{ is TOTAL in } X \text{ and} \\ \text{(ii). There exists } A > 0 \text{ such that } A \sum_{n \in C} |a_n|^2 \leq \left\| \sum_{n \in C} a_n x_n \right\|^2 \text{ for finite } C \text{ and} \\ \text{(iii). There exists } B > 0 \text{ such that } \left\| \sum_{n=1}^{\infty} b_n y_n \right\|^2 \leq B \sum_{n=1}^{\infty} |b_n|^2 \quad \forall (b_n)_{n \in \mathbb{N}} \in \ell_{\mathbb{F}}^2 \end{array} \right\} \implies$

$\left\{ \begin{array}{l} \text{(1). } \mathbf{R}^\circ \text{ is a linear bounded operator that maps from } \text{span}\{x_n\} \text{ to } \text{span}\{y_n\} \\ \text{where } \mathbf{R}^\circ \sum_{n \in C} c_n x_n \triangleq \sum_{n \in C} c_n y_n, \text{ for some sequence } (c_n) \text{ and finite set } C \text{ and} \\ \text{(2). } \mathbf{R} \text{ has a unique extension to a bounded operator } \mathbf{R} \text{ that maps from } X \text{ to } Y \text{ and} \\ \text{(3). } \|\mathbf{R}^\circ\| \leq \frac{B}{A} \text{ and} \\ \text{(4). } \|\mathbf{R}\| \leq \frac{B}{A} \end{array} \right\}$

²⁸ [Bachman et al. \(2002\) page 112](#) (3.4.8), [Berberian \(1961\) page 53](#) (Theorem II\$8.3)

²⁹ [Kubrusly \(2001\) page 357](#) (Proposition 5.43)

³⁰ [Young \(2001\) page 27](#) (Definition 1.8.2), [Christensen \(2003\) page 63](#) (Definition 3.6.1), [Heil \(2011\) page 196](#) (Definition 7.9)

³¹ [Christensen \(2003\) pages 66–68](#) (page 68 and (3.24) on page 66), [Wojtaszczyk \(1997\) page 20](#) (Definition 2.6)

³² [Christensen \(2003\) pages 65–66](#) (Lemma 3.6.5)

Theorem H.13. ³³ Let $\{\mathbf{x}_n \in X \mid n \in \mathbb{N}\}$ be a set of vectors in a SEPARABLE HILBERT SPACE $H \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle \mid \nabla \rangle)$.

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$$\left\{ \begin{array}{l} \{\mathbf{x}_n\} \text{ is a RIESZ BASIS} \\ \text{for } H \end{array} \right\} \iff \left\{ \begin{array}{l} (1). \quad \{\mathbf{x}_n\} \text{ is TOTAL in } H \quad \text{and} \\ (2). \quad \exists A, B \in \mathbb{R}^+ \text{ such that } \forall (\alpha_n) \in \ell_{\mathbb{F}}^2, \\ A \sum_{n=1}^{\infty} |\alpha_n|^2 \leq \left\| \sum_{n=1}^{\infty} \alpha_n \mathbf{x}_n \right\|^2 \leq B \sum_{n=1}^{\infty} |\alpha_n|^2 \end{array} \right\}$$

 PROOF:

1. Proof for (\implies) case:

(a) Proof that *Riesz basis hypothesis* \implies (1): all bases for H are *total* in H .

(b) Proof that *Riesz basis hypothesis* \implies (2):

i. Let $(\mathbf{u}_n)_{n \in \mathbb{N}}$ be an *orthonormal basis* for H .





ii. Let \mathbf{R} be a *bounded bijective operator* such that $\mathbf{x}_n = \mathbf{R}\mathbf{u}_n$.

iii. Proof for upper bound B :

$$\begin{aligned} \left\| \sum_{n=1}^{\infty} \alpha_n \mathbf{x}_n \right\|^2 &= \left\| \sum_{n=1}^{\infty} \alpha_n \mathbf{R}\mathbf{u}_n \right\|^2 && \text{by definition of } \mathbf{R} && \text{(item (1(b)ii))} \\ &= \left\| \mathbf{R} \sum_{n=1}^{\infty} \alpha_n \mathbf{u}_n \right\|^2 && \text{by Theorem G.1 page 155} \\ &\leq \|\mathbf{R}\|^2 \left\| \sum_{n=1}^{\infty} \alpha_n \mathbf{u}_n \right\|^2 && \text{by Theorem G.6 page 161} \\ &= \|\mathbf{R}\|^2 \sum_{n=1}^{\infty} \|\alpha_n \mathbf{u}_n\|^2 && \text{by Pythagorean Theorem} \\ &= \|\mathbf{R}\|^2 \sum_{n=1}^{\infty} |\alpha_n|^2 \|\mathbf{u}_n\|^2 && \text{by homogeneous property of norms (Definition G.5 page 158)} \\ &= \underbrace{\|\mathbf{R}\|^2}_B \sum_{n=1}^{\infty} |\alpha_n|^2 && \text{by definition of orthonormality (Definition H.9 page 190)} \end{aligned}$$

iv. Proof for lower bound A :

$$\begin{aligned} \left\| \sum_{n=1}^{\infty} \alpha_n \mathbf{x}_n \right\|^2 &= \frac{\|\mathbf{R}^{-1}\|^2}{\|\mathbf{R}^{-1}\|^2} \left\| \sum_{n=1}^{\infty} \alpha_n \mathbf{x}_n \right\|^2 && \text{because } \|\mathbf{R}^{-1}\| > 0 && \text{(Proposition G.1 page 159)} \\ &\geq \frac{1}{\|\mathbf{R}^{-1}\|^2} \left\| \mathbf{R}^{-1} \sum_{n=1}^{\infty} \alpha_n \mathbf{x}_n \right\|^2 && \text{by Theorem G.6 page 161} \\ &= \frac{1}{\|\mathbf{R}^{-1}\|^2} \left\| \mathbf{R}^{-1} \sum_{n=1}^{\infty} \alpha_n \mathbf{R}\mathbf{u}_n \right\|^2 && \text{by definition of } \mathbf{R} && \text{(item (1(b)ii) page 202)} \\ &= \frac{1}{\|\mathbf{R}^{-1}\|^2} \left\| \mathbf{R}^{-1} \mathbf{R} \sum_{n=1}^{\infty} \alpha_n \mathbf{u}_n \right\|^2 && \text{by property of linear operators (Theorem G.1 page 155)} \end{aligned}$$

³³  Young (2001) page 27 (Theorem 1.8.9),  Christensen (2003) page 66 (Theorem 3.6.6),  Heil (2011) pages 197–198 (Theorem 7.13),  Christensen (2008) pages 61–62 (Theorem 3.3.7)

$$\begin{aligned}
&= \frac{1}{\|\mathbf{R}^{-1}\|^2} \left\| \sum_{n=1}^{\infty} \alpha_n \mathbf{u}_n \right\|^2 && \text{by definition of inverse op.} && (\text{Definition G.3 page 154}) \\
&= \frac{1}{\|\mathbf{R}^{-1}\|^2} \sum_{n=1}^{\infty} \|\alpha_n \mathbf{u}_n\|^2 && \text{by Pythagorean Theorem} \\
&= \frac{1}{\|\mathbf{R}^{-1}\|^2} \sum_{n=1}^{\infty} |\alpha_n|^2 \|\mathbf{u}_n\|^2 && \text{by } \|\cdot\| \text{ homogeneous prop.} && (\text{Definition G.5 page 158}) \\
&= \underbrace{\frac{1}{\|\mathbf{R}^{-1}\|^2}}_A \sum_{n=1}^{\infty} |\alpha_n|^2 && \text{by def. of orthonormality} && (\text{Definition H.9 page 190})
\end{aligned}$$

2. Proof for (\implies) case:

- Let $\{\mathbf{u}_n\}_{n \in \mathbb{N}}$ be an *orthonormal basis* for \mathbf{H} .
- Using (2) and Lemma H.3 (page 201), construct an bounded extension operator \mathbf{R} such that $\mathbf{R}\mathbf{u}_n = \mathbf{x}_n$ for all $n \in \mathbb{N}$.
- Using (2) and Lemma H.3 (page 201), construct an bounded extension operator \mathbf{S} such that $\mathbf{S}\mathbf{x}_n = \mathbf{u}_n$ for all $n \in \mathbb{N}$.
- Then, $\mathbf{R}\mathbf{V}\mathbf{x} = \mathbf{V}\mathbf{R}\mathbf{x} \implies \mathbf{V} = \mathbf{R}^{-1}$, and so \mathbf{R} is a bounded invertible operator
- and $\{\mathbf{x}_n\}$ is a *Riesz sequence*.

\Rightarrow

Theorem H.14. ³⁴ Let $\mathbf{H} \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ be a SEPARABLE HILBERT SPACE.

$$\left\{ \begin{array}{l} (\mathbf{x}_n \in \mathbf{H})_{n \in \mathbb{Z}} \text{ is a} \\ \text{RIESZ BASIS for } \mathbf{H} \end{array} \right\} \implies \left\{ \begin{array}{l} \text{There exists } (\mathbf{y}_n \in \mathbf{H})_{n \in \mathbb{Z}} \text{ such that} \\ (1). \ (\mathbf{x}_n) \text{ and } (\mathbf{y}_n) \text{ are BIORTHOGONAL} \quad \text{and} \\ (2). \ (\mathbf{y}_n) \text{ is also a RIESZ BASIS for } \mathbf{H} \quad \text{and} \\ (3). \ \exists B > A > 0 \quad \text{such that} \\ A \sum_{n=1}^{\infty} |a_n|^2 \leq \left\| \sum_{n=1}^{\infty} a_n \mathbf{x}_n \right\|^2 = \left\| \sum_{n=1}^{\infty} a_n \mathbf{y}_n \right\|^2 \leq B \sum_{n=1}^{\infty} |a_n|^2 \\ \forall (a_n)_{n \in \mathbb{N}} \in \ell_{\mathbb{F}}^2 \end{array} \right\}$$


\Rightarrow PROOF:

1. Proof for (1):

- Let \mathbf{e}_n be the *unit vector* in \mathbf{H} such that the n th element of \mathbf{e}_n is 1 and all other elements are 0.
- Let \mathbf{M} be an operator on \mathbf{H} such that $\mathbf{M}\mathbf{e}_n = \mathbf{x}_n$.
- Note that \mathbf{M} is *isometric*, and as such $\|\mathbf{M}\mathbf{x}\| = \|\mathbf{x}\| \quad \forall \mathbf{x} \in \mathbf{H}$.
- Let $\mathbf{y}_n \triangleq (\mathbf{M}^{-1})^* \mathbf{e}_n$.
- Then,

$$\begin{aligned}
\langle \mathbf{y}_n | \mathbf{x}_m \rangle &= \langle (\mathbf{M}^{-1})^* \mathbf{e}_n | \mathbf{M}\mathbf{e}_m \rangle \\
&= \langle \mathbf{e}_n | \mathbf{M}^{-1} \mathbf{M}\mathbf{e}_m \rangle \\
&= \langle \mathbf{e}_n | \mathbf{e}_m \rangle \\
&= \delta_{nm} \\
&\implies \{\mathbf{x}_n\} \text{ and } \{\mathbf{y}_n\} \text{ are biorthogonal}
\end{aligned}$$

by Definition H.9 page 190

³⁴  Wojtaszczyk (1997) page 20 \langle Lemma 2.7(a) \rangle

2. Proof for (3):

$$\begin{aligned}
 \left\| \sum_{n \in \mathbb{Z}} \alpha_n y_n \right\| &= \left\| \sum_{n \in \mathbb{Z}} \alpha_n (\mathbf{M}^{-1})^* e_n \right\| && \text{by definition of } y_n && \text{(Proposition 1d page 203)} \\
 &= \left\| (\mathbf{M}^{-1})^* \sum_{n \in \mathbb{Z}} \alpha_n e_n \right\| && \text{by property of linear ops.} \\
 &= \left\| \sum_{n \in \mathbb{Z}} \alpha_n e_n \right\| && \text{because } (\mathbf{M}^{-1})^* \text{ is isometric} && \text{(Definition G.13 page 174)} \\
 &= \left\| \mathbf{M} \sum_{n \in \mathbb{Z}} \alpha_n e_n \right\| && \text{because } \mathbf{M} \text{ is isometric} && \text{(Definition G.13 page 174)} \\
 &= \left\| \sum_{n \in \mathbb{Z}} \alpha_n \mathbf{M} e_n \right\| && \text{by property of linear operators} \\
 &= \left\| \sum_{n \in \mathbb{Z}} \alpha_n x_n \right\| && \text{by definition of } \mathbf{M} \\
 &\Rightarrow \{y_n\} \text{ is a Riesz basis} && \text{by left hypothesis}
 \end{aligned}$$

3. Proof for (2): by (3) and definition of *Riesz basis* (Definition H.13 page 201)

⇒

Proposition H.5. ³⁵ Let $\{x_n | n \in \mathbb{N}\}$ be a set of vectors in a HILBERT SPACE $H \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$.

$$\left\{ \begin{array}{l} \{x_n\} \text{ is a RIESZ BASIS for } H \text{ with} \\ A \sum_{n=1}^{\infty} |a_n|^2 \leq \left\| \sum_{n=1}^{\infty} a_n x_n \right\|^2 \leq B \sum_{n=1}^{\infty} |a_n|^2 \\ \forall \{a_n\} \in \ell_{\mathbb{F}}^2 \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} \{x_n\} \text{ is a FRAME for } H \text{ with} \\ \frac{1}{B} \|x\|^2 \leq \sum_{n=1}^{\infty} |\langle x | x_n \rangle|^2 \leq \frac{1}{A} \|x\|^2 \\ \underbrace{\hspace{10em}}_{\text{STABILITY CONDITION}} \\ \forall x \in H \end{array} \right\}$$

✎ PROOF:

1. Let $\{y_n | n \in \mathbb{N}\}$ be a *Riesz basis* that is *biorthogonal* to $\{x_n | n \in \mathbb{N}\}$ (Theorem H.14 page 203).

2. Let $x \triangleq \sum_{n=1}^{\infty} a_n y_n$.

3. lemma:

$$\begin{aligned}
 \sum_{n=1}^{\infty} |\langle x | x_n \rangle|^2 &= \sum_{n=1}^{\infty} \left| \left\langle \sum_{m=1}^{\infty} a_m y_m | x_n \right\rangle \right|^2 && \text{by definition of } x && \text{(item (2) page 204)} \\
 &= \sum_{n=1}^{\infty} \left| \sum_{m=1}^{\infty} a_m \langle y_m | x_n \rangle \right|^2 && \text{by homogeneous property of } \langle \triangle | \nabla \rangle && \text{(Definition G.9 page 166)} \\
 &= \sum_{n=1}^{\infty} \left| \sum_{m=1}^{\infty} a_m \delta_{mn} \right|^2 && \text{by definition of biorthogonal} && \text{(Definition H.15 page 201)} \\
 &= \sum_{n=1}^{\infty} |a_n|^2 && \text{by definition of } \delta && \text{(Definition H.12 page 194)}
 \end{aligned}$$

³⁵  Igari (1996) page 220 (Lemma 9.8),  Wojtaszczyk (1997) pages 20–21 (Lemma 2.7(a))

4. Then

$$\begin{aligned}
 A \sum_{n=1}^{\infty} |a_n|^2 &\leq \left\| \sum_{n=1}^{\infty} a_n \mathbf{x}_n \right\|^2 \leq B \sum_{n=1}^{\infty} |a_n|^2 && \text{by definition of } \{\mathbf{y}_n\} \text{ (item (1) page 204)} \\
 \Rightarrow A \sum_{n=1}^{\infty} |a_n|^2 &\leq \left\| \sum_{n=1}^{\infty} a_n \mathbf{y}_n \right\|^2 \leq B \sum_{n=1}^{\infty} |a_n|^2 && \text{by definition of } \{\mathbf{y}_n\} \text{ (item (1) page 204)} \\
 \Rightarrow A \sum_{n=1}^{\infty} |a_n|^2 &\leq \|\mathbf{x}\|^2 \leq B \sum_{n=1}^{\infty} |a_n|^2 && \text{by definition of } \mathbf{x} \text{ (item (2) page 204)} \\
 \Rightarrow A \sum_{n=1}^{\infty} |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 &\leq \|\mathbf{x}\|^2 \leq B \sum_{n=1}^{\infty} |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 && \text{by (3) lemma} \\
 \Rightarrow \frac{1}{B} \|\mathbf{x}\|^2 &\leq \sum_{n=1}^{\infty} |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 \leq \frac{1}{A} \|\mathbf{x}\|^2
 \end{aligned}$$

⇒

Theorem H.15 (Battle-Lemarié orthogonalization).³⁶ Let $\tilde{f}(\omega)$ be the FOURIER TRANSFORM (Definition 3.2 page 26) of a function $f \in L^2_{\mathbb{R}}$.

T H M	$ \left\{ \begin{array}{l} 1. \{ \mathbf{T}^n \mathbf{g} n \in \mathbb{Z} \} \text{ is a RIESZ BASIS for } L^2_{\mathbb{R}} \text{ and} \\ 2. \tilde{f}(\omega) \triangleq \frac{\tilde{g}(\omega)}{\sqrt{2\pi \sum_{n \in \mathbb{Z}} \tilde{g}(\omega + 2\pi n) ^2}} \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} \{ \mathbf{T}^n f n \in \mathbb{Z} \} \\ \text{is an ORTHONORMAL BASIS for } L^2_{\mathbb{R}} \end{array} \right\} $
-------------	--

PROOF:

1. Proof that $\{ \mathbf{T}^n f | n \in \mathbb{Z} \}$ is orthonormal:

$$\begin{aligned}
 \tilde{S}_{\phi\phi}(\omega) &= 2\pi \sum_{n \in \mathbb{Z}} |\tilde{f}(\omega + 2\pi n)|^2 && \text{by Theorem I.1 page 213} \\
 &= 2\pi \sum_{n \in \mathbb{Z}} \left| \frac{\tilde{g}(\omega + 2\pi n)}{\sqrt{2\pi \sum_{m \in \mathbb{Z}} |\tilde{g}(\omega + 2\pi(n-m))|^2}} \right|^2 && \text{by left hypothesis} \\
 &= \sum_{n \in \mathbb{Z}} \left| \frac{\tilde{g}(\omega + 2\pi n)}{\sqrt{\sum_{m \in \mathbb{Z}} |\tilde{g}(\omega + 2\pi m)|^2}} \right|^2 \\
 &= \sum_{n \in \mathbb{Z}} \left| \frac{1}{\sqrt{\sum_{m \in \mathbb{Z}} |\tilde{g}(\omega + 2\pi m)|^2}} \right|^2 |\tilde{g}(\omega + 2\pi n)|^2 \\
 &= \frac{1}{\sum_{m \in \mathbb{Z}} |\tilde{g}(\omega + 2\pi m)|^2} \sum_{n \in \mathbb{Z}} |\tilde{g}(\omega + 2\pi n)|^2 \\
 &= 1 \\
 &\Rightarrow \{ f_n | n \in \mathbb{Z} \} \text{ is orthonormal} && \text{by Theorem I.3 page 219}
 \end{aligned}$$

³⁶ Wojtaszczyk (1997) page 25 (Remark 2.4), Vidakovic (1999) page 71, Mallat (1989) page 72, Mallat (1999) page 225, Daubechies (1992) page 140 ((5.3.3))

2. Proof that $\{\mathbf{T}^n \mathbf{f} \mid n \in \mathbb{Z}\}$ is a basis for V_0 : by Lemma H.1 page 189.



H.7 Frames in Hilbert spaces

Definition H.16. ³⁷ Let $\{\mathbf{x}_n \in X \mid n \in \mathbb{N}\}$ be a set of vectors in a HILBERT SPACE $H \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \Delta \mid \nabla \rangle)$.

The set $\{\mathbf{x}_n\}$ is a **frame** for H if (STABILITY CONDITION)

$$\exists A, B \in \mathbb{R}^+ \quad \text{such that} \quad A \|\mathbf{x}\|^2 \leq \sum_{n=1}^{\infty} |\langle \mathbf{x} \mid \mathbf{x}_n \rangle|^2 \leq B \|\mathbf{x}\|^2 \quad \forall \mathbf{x} \in X.$$

The quantities A and B are **frame bounds**.

The quantity A' is the **optimal lower frame bound** if

$$A' = \sup \{A \in \mathbb{R}^+ \mid A \text{ is a lower frame bound}\}.$$

The quantity B' is the **optimal upper frame bound** if

$$B' = \inf \{B \in \mathbb{R}^+ \mid B \text{ is an upper frame bound}\}.$$

A frame is a **tight frame** if $A = B$.

A frame is a **normalized tight frame** (or a **Parseval frame**) if $A = B = 1$.

A frame $\{\mathbf{x}_n \mid n \in \mathbb{N}\}$ is an **exact frame** if for some $m \in \mathbb{Z}$, $\{\mathbf{x}_n \mid n \in \mathbb{N}\} \setminus \{\mathbf{x}_m\}$ is NOT a frame.

A frame is a *Parseval frame* (Definition H.16) if it satisfies *Parseval's Identity* (Theorem H.9 page 196). All orthonormal bases are Parseval frames (Theorem H.9 page 196); but not all Parseval frames are orthonormal bases.

Definition H.17. Let $\{\mathbf{x}_n\}$ be a **frame** (Definition H.16 page 206) for the HILBERT SPACE $H \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \Delta \mid \nabla \rangle)$. Let S be an OPERATOR on H .

S is a frame operator for $\{\mathbf{x}_n\}$ if
$$S\mathbf{f}(x) = \sum_{n \in \mathbb{Z}} \langle \mathbf{f} \mid \mathbf{x}_n \rangle \mathbf{x}_n \quad \forall \mathbf{f} \in H.$$

Theorem H.16. ³⁸ Let S be a FRAME OPERATOR (Definition H.17 page 206) of a FRAME $\{\mathbf{x}_n\}$ (Definition H.16 page 206) for the HILBERT SPACE $H \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \Delta \mid \nabla \rangle)$.

T H M (1). S is INVERTIBLE. and
(2).
$$\mathbf{f}(x) = \sum_{n \in \mathbb{Z}} \langle \mathbf{f} \mid S^{-1} \mathbf{x}_n \rangle \mathbf{x}_n = \sum_{n \in \mathbb{Z}} \langle \mathbf{f} \mid \mathbf{x}_n \rangle S^{-1} \mathbf{x}_n \quad \forall \mathbf{f} \in H$$

Theorem H.17. ³⁹ Let $\{\mathbf{x}_n \in X \mid n=1,2,\dots,N\}$ be a set of vectors in a HILBERT SPACE $H \triangleq (X, +, \cdot, (\mathbb{F}, \dot{+}, \dot{\times}), \langle \Delta \mid \nabla \rangle)$.

T H M $\{\mathbf{x}_n\}$ is a FRAME for $\text{span}\{\mathbf{x}_n\}$.

✎ PROOF:

³⁷ Young (2001) pages 154–155, Christensen (2003) page 88 (Definitions 5.1.1, 5.1.2), Heil (2011) pages 204–205 (Definition 8.2), Jørgensen et al. (2008) page 267 (Definition 12.22), Duffin and Schaeffer (1952) page 343, Daubechies et al. (1986) page 1272

³⁸ Christensen (2008) pages 100–102 (Theorem 5.1.7)

³⁹ Christensen (2003) page 3

1. Upper bound: Proof that there exists B such that $\sum_{n=1}^N |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 \leq B \|\mathbf{x}\|^2 \quad \forall \mathbf{x} \in H$:

$$\begin{aligned} \sum_{n=1}^N |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 &\leq \sum_{n=1}^N \langle \mathbf{x}_n | \mathbf{x}_n \rangle \langle \mathbf{x} | \mathbf{x} \rangle && \text{by Cauchy-Schwarz inequality} \\ &= \underbrace{\left\{ \sum_{n=1}^N \|\mathbf{x}_n\|^2 \right\}}_B \|\mathbf{x}\|^2 \end{aligned}$$

2. Lower bound: Proof that there exists A such that $A \|\mathbf{x}\|^2 \leq \sum_{n=1}^N |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 \quad \forall \mathbf{x} \in H$:

$$\begin{aligned} \sum_{n=1}^N |\langle \mathbf{x} | \mathbf{x}_n \rangle|^2 &= \sum_{n=1}^N \left| \left\langle \mathbf{x}_n \mid \frac{\mathbf{x}}{\|\mathbf{x}\|} \right\rangle \right|^2 \|\mathbf{x}\|^2 \\ &\geq \underbrace{\left(\inf_y \left\{ \sum_{n=1}^N |\langle \mathbf{x}_n | \mathbf{y} \rangle|^2 \mid \|\mathbf{y}\| = 1 \right\} \right)}_A \|\mathbf{x}\|^2 \end{aligned}$$

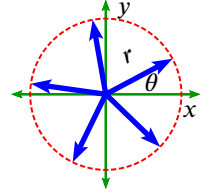
Example H.1. Let $(\mathbb{R}^2, +, \cdot, (\mathbb{R}, +, \cdot), \langle \Delta | \nabla \rangle)$ be an inner product space with $\left\langle \begin{bmatrix} x_1 \\ y_1 \end{bmatrix} \mid \begin{bmatrix} x_2 \\ y_2 \end{bmatrix} \right\rangle \triangleq x_1 x_2 + y_1 y_2$. Let S be the *frame operator* (Definition H.17 page 206) with *inverse* S^{-1} .

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Let $N \in \{3, 4, 5, \dots\}$, $\theta \in \mathbb{R}$, and $r \in \mathbb{R}^+$ ($r > 0$).

Let $\mathbf{x}_n \triangleq r \begin{bmatrix} \cos(\theta + 2n\pi/N) \\ \sin(\theta + 2n\pi/N) \end{bmatrix} \quad \forall n \in \{0, 1, \dots, N-1\}$.

Then, $(\mathbf{x}_0, \mathbf{x}_1, \dots, \mathbf{x}_{N-1})$ is a **tight frame** for \mathbb{R}^2 with *frame bound* $A = \frac{Nr^2}{2}$.



Moreover, $S = \frac{Nr^2}{2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$, $S^{-1} = \frac{2}{Nr^2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$, and $\mathbf{v} = \frac{2}{Nr^2} \sum_{n=0}^{N-1} \langle \mathbf{v} | \mathbf{x}_n \rangle \mathbf{x}_n \quad \forall \mathbf{v} \in \mathbb{R}^2$.

PROOF:

1. Proof that $(\mathbf{x}_0, \mathbf{x}_1, \dots, \mathbf{x}_{N-1})$ is a *tight frame* with *frame bound* $A = \frac{Nr^2}{2}$: Let $\mathbf{v} \triangleq (x, y) \in \mathbb{R}^2$.

$$\begin{aligned} \sum_{n=0}^{N-1} |\langle \mathbf{v} | \mathbf{x}_n \rangle|^2 &\triangleq \sum_{n=0}^{N-1} \left| \mathbf{v}^H r \begin{bmatrix} \cos\left(\theta + \frac{2n\pi}{N}\right) \\ \sin\left(\theta + \frac{2n\pi}{N}\right) \end{bmatrix} \right|^2 && \text{by definitions of } \mathbf{v} \text{ of } \langle \mathbf{y} | \mathbf{x} \rangle \\ &\triangleq \sum_{n=0}^{N-1} r^2 \left| x \cos\left(\theta + \frac{2n\pi}{N}\right) + y \sin\left(\theta + \frac{2n\pi}{N}\right) \right|^2 && \text{by definition of } \mathbf{y}^H \mathbf{x} \text{ operation} \\ &= r^2 x^2 \sum_{n=0}^{N-1} \cos^2\left(\theta + \frac{2n\pi}{N}\right) + r^2 y^2 \sum_{n=0}^{N-1} \sin^2\left(\theta + \frac{2n\pi}{N}\right) + r^2 xy \sum_{n=0}^{N-1} \cos\left(\theta + \frac{2n\pi}{N}\right) \sin\left(\theta + \frac{2n\pi}{N}\right) \\ &= r^2 x^2 \frac{N}{2} + r^2 y^2 \frac{N}{2} + r^2 xy 0 && \text{by Corollary E.1 page 141} \\ &= (x^2 + y^2) \frac{Nr^2}{2} = \underbrace{\left(\frac{Nr^2}{2} \right)}_A \mathbf{v}^H \mathbf{v} \triangleq \underbrace{\left(\frac{Nr^2}{2} \right)}_A \|\mathbf{v}\|^2 && \text{by definition of } \|\mathbf{v}\| \end{aligned}$$

2. Proof that $S = \frac{Nr^2}{2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$:

(a) Let $\mathbf{e}_1 \triangleq \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and $\mathbf{e}_2 \triangleq \begin{bmatrix} 0 \\ 1 \end{bmatrix}$.

(b) lemma: $\mathbf{S}\mathbf{e}_1 = \frac{Nr^2}{2}\mathbf{e}_1$. Proof:

$$\begin{aligned} \mathbf{S}\mathbf{e}_1 &= \sum_{n=0}^{N-1} \langle \mathbf{e}_1 | \mathbf{x}_n \rangle \mathbf{x}_n \\ &= \sum_{n=0}^{N-1} r \cos\left(\theta + \frac{2n\pi}{N}\right) r \begin{bmatrix} \cos\left(\theta + \frac{2n\pi}{N}\right) \\ \sin\left(\theta + \frac{2n\pi}{N}\right) \end{bmatrix} = r^2 \sum_{n=0}^{N-1} \begin{bmatrix} \cos^2\left(\theta + \frac{2n\pi}{N}\right) \\ \cos\left(\theta + \frac{2n\pi}{N}\right) \sin\left(\theta + \frac{2n\pi}{N}\right) \end{bmatrix} \\ &= r^2 \begin{bmatrix} N/2 \\ 0 \end{bmatrix} = \frac{Nr^2}{2} \mathbf{e}_1 \quad \text{by Summation around unit circle (Corollary E.1 page 141)} \end{aligned}$$

(c) lemma: $\mathbf{S}\mathbf{e}_2 = \frac{Nr^2}{2}\mathbf{e}_2$. Proof:

$$\begin{aligned} \mathbf{S}\mathbf{e}_2 &= \sum_{n=0}^{N-1} \langle \mathbf{e}_2 | \mathbf{x}_n \rangle \mathbf{x}_n \\ &= \sum_{n=0}^{N-1} r \sin\left(\theta + \frac{2n\pi}{N}\right) r \begin{bmatrix} \cos\left(\theta + \frac{2n\pi}{N}\right) \\ \sin\left(\theta + \frac{2n\pi}{N}\right) \end{bmatrix} = r^2 \sum_{n=0}^{N-1} \begin{bmatrix} \sin\left(\theta + \frac{2n\pi}{N}\right) \cos\left(\theta + \frac{2n\pi}{N}\right) \\ \sin^2\left(\theta + \frac{2n\pi}{N}\right) \end{bmatrix} \\ &= r^2 \begin{bmatrix} 0 \\ N/2 \end{bmatrix} = \frac{Nr^2}{2} \mathbf{e}_2 \quad \text{by Summation around unit circle (Corollary E.1 page 141)} \end{aligned}$$

(d) Complete the proof of item (2) using Eigendecomposition $\mathbf{S} = \mathbf{Q}\mathbf{A}\mathbf{Q}^{-1}$:

$$\mathbf{S}\mathbf{e}_1 = \frac{Nr^2}{2}\mathbf{e}_1 \quad \text{by (2c) lemma}$$

$$\Rightarrow \mathbf{e}_1 \text{ is an eigenvector of } \mathbf{S} \text{ with eigenvalue } \frac{Nr^2}{2}$$

$$\mathbf{S}\mathbf{e}_2 = \frac{Nr^2}{2}\mathbf{e}_2 \quad \text{by (2c) lemma}$$

$$\Rightarrow \mathbf{e}_2 \text{ is an eigenvector of } \mathbf{S} \text{ with eigenvalue } \frac{Nr^2}{2}$$

$$\mathbf{S} = \underbrace{\begin{bmatrix} | & | \\ \mathbf{e}_1 & \mathbf{e}_2 \\ | & | \end{bmatrix}}_{\mathbf{Q}} \underbrace{\begin{bmatrix} \frac{Nr^2}{2} & 0 \\ 0 & \frac{Nr^2}{2} \end{bmatrix}}_{\mathbf{A}} \underbrace{\begin{bmatrix} | & | \\ \mathbf{e}_1 & \mathbf{e}_2 \\ | & | \end{bmatrix}^{-1}}_{\mathbf{Q}^{-1}} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} \frac{Nr^2}{2} & 0 \\ 0 & \frac{Nr^2}{2} \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}^{-1} = \frac{Nr^2}{2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

3. Proof that $\mathbf{S}^{-1} = \frac{2}{Nr^2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$:

$$\mathbf{S}\mathbf{S}^{-1} = \frac{Nr^2}{2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \frac{2}{Nr^2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \triangleq \mathbf{I}_2 \quad \text{by item (2)}$$

$$\mathbf{S}^{-1}\mathbf{S} = \frac{2}{Nr^2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \frac{Nr^2}{2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \triangleq \mathbf{I}_2 \quad \text{by item (2)}$$

4. Proof that $\mathbf{v} = \frac{2}{Nr^2} \sum_{n=0}^{N-1} (\mathbf{v}^H \mathbf{x}_n) \mathbf{x}_n$:

$$\mathbf{v} = \sum_{n=0}^{N-1} \langle \mathbf{v} | \mathbf{S}^{-1} \mathbf{x}_n \rangle \mathbf{x}_n = \sum_{n=0}^{N-1} \left\langle \mathbf{v} \middle| \frac{2}{Nr^2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \mathbf{x}_n \right\rangle \mathbf{x}_n \quad \text{by item (3)}$$

$$= \frac{2}{Nr^2} \sum_{n=0}^{N-1} \langle \mathbf{v} | \mathbf{x}_n \rangle \mathbf{x}_n = \frac{2}{Nr^2} \sum_{n=0}^{N-1} (\mathbf{v}^H \mathbf{x}_n) \mathbf{x}_n \quad \text{by definition of } \langle \mathbf{y} | \mathbf{x} \rangle$$



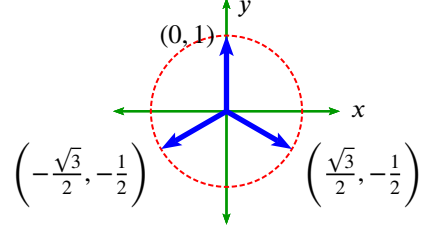
Example H.2 (Peace Frame/Mercedes Frame).⁴⁰ Let $(\mathbb{R}^2, +, \cdot, (\mathbb{R}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ be an inner product space with $\langle (x_1, y_1) | (x_2, y_2) \rangle \triangleq x_1 y_1 + x_2 y_2$. Let \mathbf{S} be the *frame operator* (Definition H.17 page 206) with *inverse* \mathbf{S}^{-1} .

Let $\mathbf{x}_1 \triangleq \frac{1}{2} \begin{bmatrix} 0 \\ 2 \end{bmatrix}$, $\mathbf{x}_2 \triangleq \frac{1}{2} \begin{bmatrix} -\sqrt{3} \\ -1 \end{bmatrix}$, and $\mathbf{x}_3 \triangleq \frac{1}{2} \begin{bmatrix} \sqrt{3} \\ -1 \end{bmatrix}$.

Then, $(\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3)$ is a **tight frame** for \mathbb{R}^2 with *frame bound* $A = \frac{3}{2}$.

Moreover, $\mathbf{S} = \frac{3}{2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$, $\mathbf{S}^{-1} = \frac{2}{3} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$,

and $\mathbf{v} = \frac{2}{3} \sum_{n=1}^3 \langle \mathbf{v} | \mathbf{x}_n \rangle \mathbf{x}_n \triangleq \frac{2}{3} \sum_{n=1}^3 (\mathbf{v}^H \mathbf{x}_n) \mathbf{x}_n \quad \forall \mathbf{v} \in \mathbb{R}^2$.



**E
X**

PROOF:

1. This frame is simply a special case of the frame presented in Example H.1 (page 207) with $r = 1$, $N = 3$, and $\theta = \pi/2$.
2. Let's give it a try! Let $\mathbf{v} \triangleq \begin{bmatrix} 1 \\ 1 \end{bmatrix}$.

$$\begin{aligned}
 \sum_{n=1}^3 \langle \mathbf{v} | \mathbf{S}^{-1} \mathbf{x}_n \rangle \mathbf{x}_n &= \frac{2}{3} \sum_{n=1}^3 (\mathbf{v}^H \mathbf{x}_n) \mathbf{x}_n && \text{by Example H.1 page 207} \\
 &= (\mathbf{v}^H \mathbf{x}_1) \mathbf{x}_1 + (\mathbf{v}^H \mathbf{x}_2) \mathbf{x}_2 + (\mathbf{v}^H \mathbf{x}_3) \mathbf{x}_3 \\
 &= \frac{2}{3} \left(\left(\mathbf{v}^H \frac{1}{2} \begin{bmatrix} 0 \\ 2 \end{bmatrix} \right) \mathbf{x}_1 + \left(\mathbf{v}^H \frac{1}{2} \begin{bmatrix} -\sqrt{3} \\ -1 \end{bmatrix} \right) \mathbf{x}_2 + \left(\mathbf{v}^H \frac{1}{2} \begin{bmatrix} \sqrt{3} \\ -1 \end{bmatrix} \right) \mathbf{x}_3 \right) \\
 &= \frac{2}{3} \cdot \frac{1}{2} \left(\left(\mathbf{v}^H \begin{bmatrix} 0 \\ 2 \end{bmatrix} \right) \mathbf{x}_1 + \left(\mathbf{v}^H \begin{bmatrix} -\sqrt{3} \\ -1 \end{bmatrix} \right) \mathbf{x}_2 + \left(\mathbf{v}^H \begin{bmatrix} \sqrt{3} \\ -1 \end{bmatrix} \right) \mathbf{x}_3 \right) \\
 &= \frac{1}{3} \left((2) \frac{1}{2} \begin{bmatrix} 0 \\ 2 \end{bmatrix} + (-\sqrt{3} - 1) \frac{1}{2} \begin{bmatrix} -\sqrt{3} \\ -1 \end{bmatrix} + (\sqrt{3} - 1) \frac{1}{2} \begin{bmatrix} \sqrt{3} \\ -1 \end{bmatrix} \right) \\
 &= \frac{1}{6} \begin{bmatrix} 2(0) & + & (-\sqrt{3} - 1)(-\sqrt{3}) & + & (\sqrt{3} - 1)(\sqrt{3}) \\ 2(2) & + & (-\sqrt{3} - 1)(-1) & + & (\sqrt{3} - 1)(-1) \end{bmatrix} \\
 &= \frac{1}{6} \begin{bmatrix} 0 & + & (3 + \sqrt{3}) & + & (3 - \sqrt{3}) \\ 4 & + & (1 + \sqrt{3}) & + & (1 - \sqrt{3}) \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \triangleq \mathbf{v}
 \end{aligned}$$



In Example H.1 (page 207) and Example H.2 (page 209), the frame operator \mathbf{S} and its inverse \mathbf{S}^{-1} were computed. In general however, it is not always necessary or even possible to compute these, as illustrated in Example H.3 (next).

Example H.3.⁴¹ Let $(\mathbb{R}^2, +, \cdot, (\mathbb{R}, \dot{+}, \dot{\times}), \langle \triangle | \nabla \rangle)$ be an inner product space with $\langle (x_1, y_1) | (x_2, y_2) \rangle \triangleq x_1 y_1 + x_2 y_2$. Let \mathbf{S} be the *frame operator* (Definition H.17 page 206) with *inverse* \mathbf{S}^{-1} .

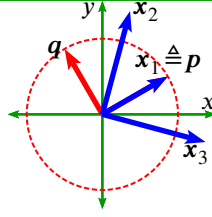
⁴⁰ Heil (2011) pages 204–205 ($r = 1$ case), Byrne (2005) page 80 ($r = 1$ case), Han et al. (2007) page 91 (Example 3.9, $r = \sqrt{2/3}$ case)

⁴¹ Christensen (2003) pages 7–8 (?)

EX

Let p and q be *orthonormal* vectors in $X \triangleq \text{span}\{p, q\}$.

Let $x_1 \triangleq p$, $x_2 \triangleq p + q$, and $x_3 \triangleq p - q$. Then, $\{x_1, x_2, x_3\}$ is a **frame** for X with *frame bounds* $A = 0$ and $B = 5$.



Moreover,

$$S^{-1}x_1 = \frac{1}{3}p \quad \text{and}$$

$$S^{-1}x_2 = \frac{1}{3}p + \frac{1}{2}q \quad \text{and}$$

$$S^{-1}x_3 = \frac{1}{3}p - \frac{1}{2}q.$$

PROOF:

1. Proof that (x_1, x_2, x_3) is a *frame* with *frame bounds* $A = 0$ and $B = 5$:

$$\begin{aligned} \sum_{n=1}^3 |\langle v | x_n \rangle|^2 &\triangleq |\langle v | p \rangle|^2 + |\langle v | p + q \rangle|^2 + |\langle v | p - q \rangle|^2 && \text{by definitions of } x_1, x_2, \text{ and } x_3 \\ &= |\langle v | p \rangle|^2 + |\langle v | p \rangle + \langle v | q \rangle|^2 + |\langle v | p \rangle - \langle v | q \rangle|^2 && \text{by additivity of } \langle \triangle | \nabla \rangle \text{ (Definition G.9 page 166)} \\ &= |\langle v | p \rangle|^2 + (|\langle v | p \rangle|^2 + |\langle v | q \rangle|^2 + \langle v | p \rangle \langle v | q \rangle^* + \langle v | q \rangle \langle v | p \rangle^*) \\ &\quad + (|\langle v | p \rangle|^2 + |\langle v | q \rangle|^2 - \langle v | p \rangle \langle v | q \rangle^* - \langle v | q \rangle \langle v | p \rangle^*) \\ &= 3|\langle v | p \rangle|^2 + 2|\langle v | q \rangle|^2 \\ &\leq 3\|v\| \|p\| + 2\|v\| \|q\| && \text{by CS Inequality} \\ &= \|v\| (3\|p\| + 2\|q\|) \\ &= 5\|v\| && \text{by orthonormality of } p \text{ and } q \end{aligned}$$

2. lemma: $Sp = 3p$, $Sq = 2q$, $S^{-1}p = \frac{1}{3}p$, and $S^{-1}q = \frac{1}{2}q$. Proof:

$$\begin{aligned} Sp &\triangleq \sum_{n=1}^3 \langle p | x_n \rangle x_n \\ &= \langle p | p \rangle p + \langle p | p + q \rangle (p + q) + \langle p | p - q \rangle (p - q) \\ &= (1)p + (1 + 0)(p + q) + (1 - 0)(p - q) \\ &= 3p \\ \Rightarrow S^{-1}p &= \frac{1}{3}p \\ Sq &\triangleq \sum_{n=1}^3 \langle q | x_n \rangle x_n \\ &= \langle q | p \rangle p + \langle q | p + q \rangle (p + q) + \langle q | p - q \rangle (p - q) \\ &= (0)q + (0 + 1)(p + q) + (0 - 1)(p - q) \\ &= 2q \\ \Rightarrow S^{-1}q &= \frac{1}{2}q \end{aligned}$$

3. Remark: Without knowing p and q , from (2) lemma it follows that it is not possible to compute S or S^{-1} explicitly.
4. Proof that $S^{-1}x_1 = \frac{1}{3}p$, $S^{-1}x_2 = \frac{1}{3}p + \frac{1}{2}q$ and $S^{-1}x_3 = \frac{1}{3}p - \frac{1}{2}q$:

$$\begin{aligned} S^{-1}x_1 &\triangleq S^{-1}p && \text{by definition of } x_1 \\ &= \frac{1}{3}p && \text{by (2) lemma} \\ S^{-1}x_2 &\triangleq S^{-1}(p + q) && \text{by definition of } x_2 \\ &= \frac{1}{3}p + \frac{1}{2}q && \text{by (2) lemma} \end{aligned}$$

$$\begin{aligned}
 \mathbf{S}^{-1}\mathbf{x}_3 &\triangleq \mathbf{S}^{-1}(\mathbf{p} - \mathbf{q}) && \text{by definition of } \mathbf{x}_2 \\
 &= \frac{1}{3}\mathbf{p} - \frac{1}{2}\mathbf{q} && \text{by (2) lemma}
 \end{aligned}$$

5. Check that $\mathbf{v} = \sum_n \langle \mathbf{v} | \mathbf{x}_n \rangle \mathbf{x}_n = \langle \mathbf{v} | \mathbf{p} \rangle \mathbf{p} + \langle \mathbf{v} | \mathbf{q} \rangle \mathbf{q}$:

$$\begin{aligned}
 \mathbf{v} &= \sum_{n=1}^3 \langle \mathbf{v} | \mathbf{S}^{-1}\mathbf{x}_n \rangle \mathbf{x}_n \\
 &= \langle \mathbf{v} | \mathbf{S}^{-1}\mathbf{p} \rangle \mathbf{p} + \langle \mathbf{v} | \mathbf{S}^{-1}(\mathbf{p} + \mathbf{q}) \rangle (\mathbf{p} + \mathbf{q}) + \langle \mathbf{v} | \mathbf{S}^{-1}(\mathbf{p} - \mathbf{q}) \rangle (\mathbf{p} - \mathbf{q}) \\
 &= \left\langle \mathbf{v} \left| \frac{1}{3}\mathbf{p} \right. \right\rangle \mathbf{p} + \left\langle \mathbf{v} \left| \frac{1}{3}\mathbf{p} + \frac{1}{2}\mathbf{q} \right. \right\rangle (\mathbf{p} + \mathbf{q}) + \left\langle \mathbf{v} \left| \frac{1}{3}\mathbf{p} - \frac{1}{2}\mathbf{q} \right. \right\rangle (\mathbf{p} - \mathbf{q}) \\
 &= \left(\frac{1}{3} + \frac{1}{3} + \frac{1}{3} \right) \langle \mathbf{v} | \mathbf{p} \rangle \mathbf{p} + \left(\frac{1}{3} - \frac{1}{3} \right) \langle \mathbf{v} | \mathbf{p} \rangle \mathbf{q} + \left(\frac{1}{2} - \frac{1}{2} \right) \langle \mathbf{v} | \mathbf{q} \rangle \mathbf{p} + \left(\frac{1}{2} + \frac{1}{2} \right) \langle \mathbf{v} | \mathbf{q} \rangle \mathbf{q} \\
 &= \langle \mathbf{v} | \mathbf{p} \rangle \mathbf{p} + \langle \mathbf{v} | \mathbf{q} \rangle \mathbf{q}
 \end{aligned}$$



I.1 Correlation

Definition I.1 and Definition I.2 define four quantities. In this document, the quantities' notation and terminology are similar to those used in the study of *random processes*.

Definition I.1.¹ Let $\langle \triangle | \nabla \rangle$ be the STANDARD INNER PRODUCT in $L^2_{\mathbb{R}}$ (Definition B.1 page 99).

DEF $R_{fg}(n) \triangleq \langle f(x) | T^n g(x) \rangle, \quad n \in \mathbb{Z}; \quad f, g \in L^2_{\mathbb{F}},$ is the ***cross-correlation function*** of f and g .
 $R_{ff}(n) \triangleq \langle f(x) | T^n f(x) \rangle, \quad n \in \mathbb{Z}; \quad f \in L^2_{\mathbb{F}},$ is the ***autocorrelation function*** of f .

Definition I.2.² Let $R_{fg}(n)$ and $R_{ff}(n)$ be the sequences defined in Definition I.1 page 213. Let $\mathbf{Z}((x_n))$ be the Z-TRANSFORM (Definition 9.4 page 70) of a sequence $(x_n)_{n \in \mathbb{Z}}$.

DEF $\check{S}_{fg}(z) \triangleq \mathbf{Z}[R_{fg}(n)], \quad f, g \in L^2_{\mathbb{F}},$ is the ***complex cross-power spectrum*** of f and g .
 $\check{S}_{ff}(z) \triangleq \mathbf{Z}[R_{ff}(n)], \quad f \in L^2_{\mathbb{F}},$ is the ***complex auto-power spectrum*** of f .

I.2 Power Spectrum

Definition I.3.³ Let $\check{S}_{fg}(z)$ and $\check{S}_{ff}(z)$ be the functions defined in Definition I.2 page 213.

DEF $\tilde{S}_{fg}(\omega) \triangleq \check{S}_{fg}(e^{i\omega}), \quad \forall f, g \in L^2_{\mathbb{F}},$ is the ***cross-power spectrum*** of f and g .
 $\tilde{S}_{ff}(\omega) \triangleq \check{S}_{ff}(e^{i\omega}), \quad \forall f \in L^2_{\mathbb{F}},$ is the ***auto-power spectrum*** of f .

Theorem I.1.⁴ Let $\tilde{S}_{fg}(\omega)$ and $\tilde{S}_{ff}(\omega)$ be defined as in Definition I.3 (page 213).

Let $\tilde{f}(\omega)$ be the FOURIER TRANSFORM (Definition 3.2 page 26) of a function $f(x) \in L^2_{\mathbb{F}}$.

THM

$$\begin{aligned} \tilde{S}_{fg}(\omega) &= 2\pi \sum_{n \in \mathbb{Z}} \tilde{f}(\omega + 2\pi n) \tilde{g}^*(\omega + 2\pi n) \quad \forall f, g \in L^2_{\mathbb{F}} \\ \tilde{S}_{ff}(\omega) &= 2\pi \sum_{n \in \mathbb{Z}} |\tilde{f}(\omega + 2\pi n)|^2 \quad \forall f \in L^2_{\mathbb{F}} \end{aligned}$$

¹ Chui (1992) page 134, Papoulis (1991) pages 294–332 <(10-29), (10-169)>

² Chui (1992) page 134, Papoulis (1991) page 334 <(10-178)>

³ Chui (1992) page 134, Papoulis (1991) page 333 <(10-179)>

⁴ Chui (1992) page 135

✎PROOF: Let $z \triangleq e^{i\omega}$.

$$\begin{aligned}
 \tilde{S}_{fg}(\omega) &\triangleq \check{S}_{fg}(z) && \text{by definition of } \tilde{S}_{fg} && (\text{Definition I.3 page 213}) \\
 &= \sum_{n \in \mathbb{Z}} R_{fg}(n) z^{-n} && \text{by definition of } \check{S}_{fg} && (\text{Definition I.2 page 213}) \\
 &= \sum_{n \in \mathbb{Z}} \langle f(x) | g(x-n) \rangle z^{-n} && \text{by definition of } \tilde{S}_{fg} && (\text{Definition I.3 page 213}) \\
 &= \sum_{n \in \mathbb{Z}} \langle \tilde{F}[f(x)] | \tilde{F}[g(x-n)] \rangle z^{-n} && \text{by unitary property of } \tilde{F} && (\text{Theorem 3.3 page 27}) \\
 &= \sum_{n \in \mathbb{Z}} \langle \tilde{f}(v) | e^{-ivn} \tilde{g}(v) \rangle z^{-n} && \text{by shift relation} && (\text{Theorem 3.4 page 28}) \\
 &= \sum_{n \in \mathbb{Z}} \sqrt{2\pi} \left[\frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} \tilde{f}(v) \tilde{g}^*(v) e^{ivn} dv \right] z^{-n} && \text{by definition of } \mathcal{L}_{\mathbb{R}}^2 && (\text{Definition B.1 page 99}) \\
 &= \sqrt{2\pi} \sum_{n \in \mathbb{Z}} \left[\tilde{F}^{-1} \left(\sqrt{2\pi} \tilde{f}(v) \tilde{g}^*(v) \right) \right]_{u=n} e^{-i\omega n} && \text{by Theorem 3.1 page 27} && \\
 &= 2\pi \sum_{n \in \mathbb{Z}} \tilde{f}(\omega + 2\pi n) \tilde{g}^*(\omega + 2\pi n) && \text{by IPSF with } \tau = 1 && (\text{Theorem J.3 page 231})
 \end{aligned}$$

$$\begin{aligned}
 \tilde{S}_{ff}(\omega) &= \tilde{S}_{fg}(\omega) \Big|_{g=f} && \text{by definition of } \tilde{S}_{fg}(\omega) && (\text{Definition I.3 page 213}) \\
 &= 2\pi \sum_{n \in \mathbb{Z}} \tilde{f}(\omega + 2\pi n) \tilde{g}^*(\omega + 2\pi n) \Big|_{g=f} && \text{by previous result} && \\
 &= 2\pi \sum_{n \in \mathbb{Z}} \tilde{f}(\omega + 2\pi n) \tilde{f}^*(\omega + 2\pi n) && && \\
 &= 2\pi \sum_{n \in \mathbb{Z}} |\tilde{f}(\omega + 2\pi n)|^2 && \text{because } |z|^2 \triangleq zz^* \quad \forall z \in \mathbb{C} &&
 \end{aligned}$$

⇒

Proposition I.1. Let $\tilde{S}_{ff}(\omega)$ be defined as in Definition I.3 (page 213).

P R P	$\tilde{S}_{ff}(\omega) \geq 0$ (NON-NEGATIVE)
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✎PROOF:

$$\begin{aligned}
 \tilde{S}_{ff}(\omega) &= 2\pi \sum_{n \in \mathbb{Z}} |\tilde{f}(\omega + 2\pi n)|^2 && \text{by Theorem I.1 page 213} \\
 &\geq 0 && \text{because } |z| \geq 0 \quad \forall z \in \mathbb{C}
 \end{aligned}$$

⇒

Proposition I.2. Let $\tilde{S}_{fg}(\omega)$ and $\tilde{S}_{ff}(\omega)$ be defined as in Definition I.3 (page 213).

P R P	$\tilde{S}_{fg}(\omega + 2\pi) = \tilde{S}_{fg}(\omega)$ (PERIODIC with period 2π) $\tilde{S}_{ff}(\omega + 2\pi) = \tilde{S}_{ff}(\omega)$ (PERIODIC with period 2π)
-------------	--

✎ PROOF:

$$\begin{aligned}
 \tilde{S}_{fg}(\omega + 2\pi) &= 2\pi \sum_{n \in \mathbb{Z}} \tilde{f}(\omega + 2\pi + 2\pi n) \tilde{g}^*(\omega + 2\pi + 2\pi n) && \text{by Theorem I.1 page 213} \\
 &= 2\pi \sum_{n \in \mathbb{Z}} \tilde{f}[\omega + 2\pi(n+1)] \tilde{g}^*[\omega + 2\pi(n+1)] \\
 &= 2\pi \sum_{m \in \mathbb{Z}} \tilde{f}[\omega + 2\pi m] \tilde{g}^*[\omega + 2\pi m] && \text{where } m \triangleq n+1 \\
 &= \tilde{S}_{fg}(\omega) && \text{by Theorem I.1 page 213} \\
 \tilde{S}_{ff}(\omega + 2\pi) &= \tilde{S}_{fg}(\omega + 2\pi) \Big|_{g=f} \\
 &= \tilde{S}_{fg}(\omega) \Big|_{g=f} && \text{by previous result} \\
 &= \tilde{S}_{ff}(\omega)
 \end{aligned}$$

⇒

Proposition I.3. Let $\tilde{S}_{fg}(\omega)$ and $\tilde{S}_{ff}(\omega)$ be defined as in Definition I.3 (page 213).

P R P	$f, g \text{ are real} \implies \tilde{S}_{fg}(-\omega) = \tilde{S}_{gf}(\omega)$	
	$f \text{ is real} \implies \tilde{S}_{ff}(-\omega) = \tilde{S}_{ff}(\omega)$	(SYMMETRIC about 0)
	$f, g \text{ are real} \implies \tilde{S}_{fg}(\pi - \omega) = \tilde{S}_{gf}(\pi + \omega)$	
	$f \text{ is real} \implies \tilde{S}_{ff}(\pi - \omega) = \tilde{S}_{ff}(\pi + \omega)$	(SYMMETRIC about π)

✎ PROOF:

$$\begin{aligned}
 \tilde{S}_{fg}(-\omega) &= 2\pi \sum_{n \in \mathbb{Z}} \tilde{f}(-\omega + 2\pi n) \tilde{g}^*(-\omega + 2\pi n) && \text{by Theorem I.1 page 213} \\
 &= 2\pi \sum_{n \in \mathbb{Z}} \tilde{f}^*(\omega - 2\pi n) \tilde{g}(\omega - 2\pi n) && \text{by hypothesis and Theorem 3.5 page 28} \\
 &= 2\pi \sum_{m \in \mathbb{Z}} \tilde{g}(\omega + 2\pi m) \tilde{f}^*(\omega + 2\pi m) && \text{where } m \triangleq -n \\
 &= \tilde{S}_{gf}(\omega) && \text{by Theorem I.1 page 213}
 \end{aligned}$$

$$\begin{aligned}
 \tilde{S}_{fg}(\pi - \omega) &= 2\pi \sum_{n \in \mathbb{Z}} \tilde{f}(\pi - \omega + 2\pi n) \tilde{g}^*(\pi - \omega + 2\pi n) && \text{by Theorem I.1 page 213} \\
 &= 2\pi \sum_{n \in \mathbb{Z}} \tilde{f}^*(-\pi + \omega - 2\pi n) \tilde{g}(-\pi + \omega - 2\pi n) && \text{by hypothesis and Theorem 3.5 page 28} \\
 &= 2\pi \sum_{n \in \mathbb{Z}} \tilde{f}^*(\pi + \omega - 2\pi - 2\pi n) \tilde{g}(\pi + \omega - 2\pi - 2\pi n) \\
 &= 2\pi \sum_{n \in \mathbb{Z}} \tilde{f}^*(\pi + \omega + 2\pi(-n-1)) \tilde{g}(\pi + \omega + 2\pi(-n-1)) \\
 &= 2\pi \sum_{m \in \mathbb{Z}} \tilde{g}(\pi + \omega + 2\pi m) \tilde{f}^*(\pi + \omega + 2\pi m) && \text{where } m \triangleq -n-1 \\
 &= \tilde{S}_{gf}(\pi + \omega) && \text{by Theorem I.1 page 213}
 \end{aligned}$$

$$\begin{aligned}
 \tilde{S}_{ff}(-\omega) &= \tilde{S}_{fg}(-\omega) \Big|_{g=f} \\
 &= \tilde{S}_{gf}(+\omega) \Big|_{g=f} && \text{by previous result} \\
 &= \tilde{S}_{ff}(+\omega) && \text{by definition of } g \text{ (} g \triangleq f \text{)}
 \end{aligned}$$

$$\tilde{S}_{ff}(\pi - \omega) = \tilde{S}_{fg}(\pi - \omega) \Big|_{g=f}$$

$$\begin{aligned}
&= \tilde{S}_{gf}(\pi + \omega) \Big|_{g \triangleq f} \\
&= \tilde{S}_{ff}(\pi + \omega)
\end{aligned}$$

by previous result

by definition of g ($g \triangleq f$)

⇒

Proposition I.4. Let $\tilde{S}_{ff}(\omega)$ be the AUTO-POWER SPECTRUM (Definition I.3 page 213) of a function $f(x) \in L^2_{\mathbb{R}}$ and $\tilde{S}'_{ff}(\omega) \triangleq \frac{d}{d\omega} \tilde{S}_{ff}(\omega)$ (Definition B.2 page 99).

P R O P	$\left\{ \begin{array}{l} (a). \text{ } f \text{ is REAL and} \\ (b). \text{ } \tilde{S}_{ff}(\omega) \text{ is CONTINUOUS at } \omega = 0 \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} (1). \tilde{S}'_{ff}(0) = 0 \text{ and} \\ (2). \underbrace{\tilde{S}'_{ff}(\omega) = -\tilde{S}'_{ff}(-\omega)}_{\text{ANTI-SYMMETRIC about 0}} \quad \forall \omega \in \mathbb{R} \end{array} \right\}$
	$\left\{ \begin{array}{l} (c). \text{ } f \text{ is REAL and} \\ (d). \text{ } \tilde{S}_{ff}(\omega) \text{ is CONTINUOUS at } \omega = \pi \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} (3). \tilde{S}'_{ff}(\pi) = 0 \text{ and} \\ (4). \underbrace{\tilde{S}'_{ff}(\pi + \omega) = -\tilde{S}'_{ff}(\pi - \omega)}_{\text{ANTI-SYMMETRIC about } \pi} \quad \forall \omega \in \mathbb{R} \end{array} \right\}$

PROOF: This follows from Proposition I.3 (page 215) and Proposition B.1 (page 99).

⇒

Theorem I.2 (next) is a major result and provides strong motivation for bothering with *power spectrum* functions in the first place. In particular, the *auto-power spectrum* being *bounded* provides a necessary and sufficient condition for a sequence of functions $(\phi(x - n))_{n \in \mathbb{Z}}$ to be a *Riesz basis* (Definition H.13 page 201) for the *span* ~~span~~ $(\phi(x - n))$ of the sequence.

Theorem I.2.⁵ Let $\tilde{S}_{ff}(\omega)$ be defined as in Definition I.3 (page 213). Let $\|\cdot\|$ be defined as in Definition B.1 (page 99). Let $0 < A < B$.

T H M	$\left\{ A \sum_{n \in \mathbb{N}} a_n ^2 \leq \left\ \sum_{n \in \mathbb{Z}} a_n \phi(x - n) \right\ ^2 \leq B \sum_{n \in \mathbb{N}} \alpha_n ^2 \quad \forall (a_n) \in \ell^2_{\mathbb{F}} \right\} \iff \{ A \leq \tilde{S}_{\phi\phi}(\omega) \leq B \}$
	$(\phi(x - n)) \text{ is a RIESZ BASIS for } \text{span}(\phi(x - n)) \text{ (Theorem H.13 page 202)}$

PROOF:

1. lemma:

$$\begin{aligned}
\left\| \sum_{n \in \mathbb{Z}} a_n \phi(x - n) \right\|^2 &= \left\| \tilde{\mathbf{F}} \sum_{n \in \mathbb{Z}} a_n \phi(x - n) \right\|^2 \\
&= \|\tilde{\mathbf{a}}(\omega) \tilde{\phi}(\omega)\|^2 \\
&= \int_{\mathbb{R}} |\tilde{\mathbf{a}}(\omega) \tilde{\phi}(\omega)|^2 d\omega \\
&= \sum_{n \in \mathbb{Z}} \int_0^{2\pi} |\tilde{\mathbf{a}}(\omega + 2\pi n) \tilde{\phi}(\omega + 2\pi n)|^2 d\omega \\
&= \int_0^{2\pi} \sum_{n \in \mathbb{Z}} |\tilde{\mathbf{a}}(\omega + 2\pi n)|^2 |\tilde{\phi}(\omega + 2\pi n)|^2 d\omega \\
&= \int_0^{2\pi} \sum_{n \in \mathbb{Z}} |\tilde{\mathbf{a}}(\omega)|^2 |\tilde{\phi}(\omega + 2\pi n)|^2 d\omega
\end{aligned}$$

because $\tilde{\mathbf{F}}$ is *unitary* (Theorem 3.2 page 27)

by Proposition J.13 page 229

by definition of $\|\cdot\|$

by Proposition 8.1 page 59

⁵ Wojtaszczyk (1997) pages 22–23 (Proposition 2.8), Igari (1996) page 219 (Lemma 9.6), Pinsky (2002) page 306 (Theorem 6.4.8)

$$\begin{aligned}
&= \int_0^{2\pi} |\check{a}(\omega)|^2 \frac{1}{2\pi} 2\pi \sum_{n \in \mathbb{Z}} |\tilde{\phi}(\omega + 2\pi n)|^2 d\omega \\
&= \frac{1}{2\pi} \int_0^{2\pi} |\check{a}(\omega)|^2 \tilde{S}_{\phi\phi}(\omega) d\omega
\end{aligned}$$

by definition of $\tilde{S}_{\phi\phi}(\omega)$ (Theorem 1.1 page 213)

2. lemma:

$$\begin{aligned}
\frac{1}{2\pi} \int_0^{2\pi} |\check{a}(\omega)|^2 d\omega &= \frac{1}{2\pi} \int_0^{2\pi} \left| \sum_{n \in \mathbb{Z}} a_n e^{-i\omega n} \right|^2 d\omega && \text{by def. of DTFT (Definition 8.1 page 59)} \\
&= \frac{1}{2\pi} \int_0^{2\pi} \left[\sum_{n \in \mathbb{Z}} a_n e^{-i\omega n} \right] \left[\sum_{m \in \mathbb{Z}} a_m e^{-i\omega m} \right]^* d\omega \\
&= \frac{1}{2\pi} \int_0^{2\pi} \left[\sum_{n \in \mathbb{Z}} a_n e^{-i\omega n} \right] \left[\sum_{m \in \mathbb{Z}} a_m^* e^{i\omega m} \right] d\omega \\
&= \frac{1}{2\pi} \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} a_n a_m^* \int_0^{2\pi} e^{-i\omega(n-m)} d\omega \\
&= \frac{1}{2\pi} \sum_{n \in \mathbb{Z}} \sum_{m \in \mathbb{Z}} a_n a_m^* 2\pi \delta_{nm} \\
&= \sum_{n \in \mathbb{Z}} |a_n|^2
\end{aligned}$$

by definition of $\bar{\delta}$ (Definition H.12 page 194)

3. Proof for (\Leftarrow) case:

$$\begin{aligned}
\boxed{A \sum_{n \in \mathbb{Z}} |a_n|^2} &= \frac{A}{2\pi} \int_0^{2\pi} |\check{a}(\omega)|^2 d\omega && \text{by (2) lemma page 217} \\
&= \frac{1}{2\pi} \int_0^{2\pi} |\check{a}(\omega)|^2 A d\omega \\
&\leq \frac{1}{2\pi} \int_0^{2\pi} |\check{a}(\omega)|^2 \tilde{S}_{\phi\phi}(\omega) d\omega && \text{by right hypothesis} \\
&= \left\| \sum_{n \in \mathbb{Z}} a_n \phi(x - n) \right\|^2 && \text{by (1) lemma page 216} \\
&= \frac{1}{2\pi} \int_0^{2\pi} |\check{a}(\omega)|^2 \tilde{S}_{\phi\phi}(\omega) d\omega && \text{by (1) lemma page 216} \\
&\leq \frac{1}{2\pi} \int_0^{2\pi} |\check{a}(\omega)|^2 B d\omega && \text{by right hypothesis} \\
&= \frac{B}{2\pi} \int_0^{2\pi} |\check{a}(\omega)|^2 d\omega \\
&= \boxed{B \sum_{n \in \mathbb{Z}} |a_n|^2} && \text{by (2) lemma page 217}
\end{aligned}$$

4. Proof for (\Rightarrow) case:

- (a) Let $Y \triangleq \{\omega \in [0 : 2\pi] | \tilde{S}_{\phi\phi}(\omega) > \alpha\}$
and $X \triangleq \{\omega \in [0 : 2\pi] | \tilde{S}_{\phi\phi}(\omega) < \alpha\}$
- (b) Let $\mathbb{1}_{A(x)}$ be the *set indicator* (Definition J.2 page 222) of a set A .
Let $(b_n)_{n \in \mathbb{Z}}$ be the *inverse DTFT* (Theorem 8.3 page 65) of $\mathbb{1}_Y(\omega)$ such that
 $\mathbb{1}_Y(\omega) \triangleq \sum_{n \in \mathbb{N}} b_n e^{-i\omega n} \triangleq \tilde{b}(\omega).$

Let $(a_n)_{n \in \mathbb{Z}}$ be the *inverse DTFT* (Theorem 8.3 page 65) of $\mathbb{1}_X(\omega)$ such that

$$\mathbb{1}_X(\omega) \triangleq \sum_{n \in \mathbb{Z}} a_n e^{-i\omega n} \triangleq \check{a}(\omega).$$

(c) Proof that $\alpha \leq B$:

Let $\mu(A)$ be the *measure* of a set A .

$$\begin{aligned}
 \boxed{B} \sum_{n \in \mathbb{Z}} |b_n|^2 &\geq \left\| \sum_{n \in \mathbb{Z}} b_n \phi(x - n) \right\|^2 && \text{by left hypothesis} \\
 &= \frac{1}{2\pi} \int_0^{2\pi} |\tilde{b}(\omega)|^2 \tilde{S}_{\phi\phi}(\omega) d\omega && \text{by (1) lemma page 216} \\
 &= \frac{1}{2\pi} \int_0^{2\pi} |\mathbb{1}_Y(\omega)|^2 \tilde{S}_{\phi\phi}(\omega) d\omega && \text{by definition of } \mathbb{1}_Y(\omega) \quad (\text{item (4b) page 217}) \\
 &= \frac{1}{2\pi} \int_Y |1|^2 \tilde{S}_{\phi\phi}(\omega) d\omega && \text{by definition of } \mathbb{1}_Y(\omega) \quad (\text{item (4b) page 217}) \\
 &\geq \frac{\alpha}{2\pi} \mu(Y) && \text{by definition of } Y \quad (\text{item (4a) page 217}) \\
 &= \int_0^{2\pi} |\mathbb{1}_Y(\omega)|^2 d\omega && \text{by definition of } \mathbb{1}_Y(\omega) \quad (\text{item (4b) page 217}) \\
 &= \int_0^{2\pi} \left| \sum_{n \in \mathbb{Z}} b_n e^{-i\omega n} \right|^2 d\omega && \text{by definition of } (b_n) \quad (\text{item (4b) page 217}) \\
 &= \int_0^{2\pi} |\tilde{b}(\omega)|^2 d\omega && \text{by definition of } \tilde{b}(\omega) \quad (\text{item (4b) page 217}) \\
 &= \boxed{\alpha} \sum_{n \in \mathbb{Z}} |b_n|^2 && \text{by (2) lemma page 217}
 \end{aligned}$$

(d) Proof that $\tilde{S}_{\phi\phi}(\omega) \leq B$:

(i). $\tilde{S}_{\phi\phi}(\omega) > \alpha$ whenever $\omega \in Y$ (item (4a) page 217).

(ii). But even then, $\alpha \leq B$ (item (4c) page 218).

(iii). So, $\tilde{S}_{\phi\phi}(\omega) \leq B$.

(e) Proof that $A \leq \alpha$:

Let $\mu(A)$ be the *measure* of a set A .

$$\begin{aligned}
 \boxed{A} \sum_{n \in \mathbb{Z}} |a_n|^2 &\leq \left\| \sum_{n \in \mathbb{Z}} a_n \phi(x - n) \right\|^2 && \text{by left hypothesis} \\
 &= \frac{1}{2\pi} \int_0^{2\pi} |\check{a}(\omega)|^2 \tilde{S}_{\phi\phi}(\omega) d\omega && \text{by (1) lemma page 216} \\
 &= \frac{1}{2\pi} \int_0^{2\pi} |\mathbb{1}_X(\omega)|^2 \tilde{S}_{\phi\phi}(\omega) d\omega && \text{by definition of } \mathbb{1}_X(\omega) \quad (\text{Definition J.2 page 222}) \\
 &= \frac{1}{2\pi} \int_X |1|^2 \tilde{S}_{\phi\phi}(\omega) d\omega && \text{by definition of } \mathbb{1}_X(\omega) \quad (\text{Definition J.2 page 222}) \\
 &\leq \frac{\alpha}{2\pi} \mu(X) && \text{by definition of } X \quad (\text{item (4a) page 217}) \\
 &= \int_0^{2\pi} |\mathbb{1}_X(\omega)|^2 d\omega && \text{by definition of } \mathbb{1}_X(\omega) \quad (\text{Definition J.2 page 222}) \\
 &= \int_0^{2\pi} \left| \sum_{n \in \mathbb{Z}} a_n e^{-i\omega n} \right|^2 d\omega && \text{by definition of } (a_n) \quad ((2) \text{ lemma page 217}) \\
 &= \int_0^{2\pi} |\check{a}(\omega)|^2 d\omega && \text{by definition of } \check{a}(\omega) \quad ((2) \text{ lemma page 217})
 \end{aligned}$$

$$= \boxed{\alpha} \sum_{n \in \mathbb{Z}} |a_n|^2 \quad \text{by (2) lemma page 217}$$

(f) Proof that $A \leq \tilde{S}_{\phi\phi}(\omega)$:

- (i). $\tilde{S}_{\phi\phi}(\omega) < \alpha$ whenever $\omega \in X$ (item (4a) page 217).
- (ii). But even then, $A \leq \alpha$ (item (4e) page 218).
- (iii). So, $A \leq \tilde{S}_{\phi\phi}(\omega)$.

⇒

In the case that f and g are *orthonormal*, the spectral density relations simplify considerably (next).

Theorem I.3.⁶ Let \tilde{S}_{ff} and \tilde{S}_{fg} be the SPECTRAL DENSITY FUNCTIONS (Definition I.3 page 213).

**T
H
M**

$$\begin{aligned} \langle f(x) | f(x-n) \rangle &= \tilde{\delta}_n \quad (\langle f(x-n) \rangle \text{ is ORTHONORMAL}) &\iff \tilde{S}_{ff}(\omega) &= 1 \quad \forall f \in L^2_{\mathbb{F}} \\ \langle f(x) | g(x-n) \rangle &= 0 \quad (f(x) \text{ is ORTHOGONAL to } \langle g(x-n) \rangle) &\iff \tilde{S}_{fg}(\omega) &= 0 \quad \forall f, g \in L^2_{\mathbb{F}} \end{aligned}$$

✎ PROOF:

1. Proof that $\langle f(x) | f(x-n) \rangle = \tilde{\delta}_n \iff \tilde{S}_{ff}(\omega) = 1$: This follows directly from Theorem I.2 (page 216) with $A = B = 1$ (by Parseval's Identity Theorem H.9 page 196 since $\{T^n f\}$ is *orthonormal*)
2. Alternate proof that $\langle f(x) | f(x-n) \rangle = \tilde{\delta}_n \implies \tilde{S}_{ff}(\omega) = 1$:

$$\begin{aligned} \tilde{S}_{ff}(\omega) &= \sum_{n \in \mathbb{Z}} R_{ff}(n) e^{-i\omega n} && \text{by definition of } \tilde{S}_{fg} && \text{(Definition I.3 page 213)} \\ &= \sum_{n \in \mathbb{Z}} \langle f(x) | f(x-n) \rangle e^{-i\omega n} && \text{by definition of } R_{ff} && \text{(Definition I.1 page 213)} \\ &= \sum_{n \in \mathbb{Z}} \tilde{\delta}_n e^{-i\omega n} && \text{by left hypothesis} \\ &= 1 && \text{by definition of } \tilde{\delta} && \text{(Definition H.12 page 194)} \end{aligned}$$

3. Alternate proof that $\langle f(x) | f(x-n) \rangle = \tilde{\delta}_n \iff \tilde{S}_{ff}(\omega) = 1$:

$$\begin{aligned} &\langle f(x) | f(x-n) \rangle \\ &= \langle \tilde{F}f(x) | \tilde{F}f(x-n) \rangle && \text{by unitary property of } \tilde{F} && \text{(Theorem 3.3 page 27)} \\ &= \langle \tilde{f}(\omega) | e^{-i\omega n} \tilde{f}(\omega) \rangle && \text{by shift property of } \tilde{F} && \text{(Theorem 3.4 page 28)} \\ &= \int_{\mathbb{R}} \tilde{f}(\omega) e^{i\omega n} \tilde{f}^*(\omega) d\omega && \text{by definition of } \langle \triangle | \nabla \rangle && \text{(Definition B.1 page 99)} \\ &= \int_{\mathbb{R}} |\tilde{f}(\omega)|^2 e^{i\omega n} d\omega \\ &= \sum_{n \in \mathbb{Z}} \int_{2\pi n}^{2\pi(n+1)} |\tilde{f}(\omega)|^2 e^{i\omega n} d\omega \\ &= \sum_{n \in \mathbb{Z}} \int_0^{2\pi} |\tilde{f}(u+2\pi n)|^2 e^{i(u+2\pi n)n} du && \text{where } u \triangleq \omega - 2\pi n \implies \omega = u + 2\pi n \\ &= \frac{1}{2\pi} \int_0^{2\pi} \left[2\pi \sum_{n \in \mathbb{Z}} |\tilde{f}(u+2\pi n)|^2 \right] e^{iun} e^{i2\pi n^2} du \\ &= \frac{1}{2\pi} \int_0^{2\pi} \tilde{S}_{ff}(\omega) e^{iun} du && \text{by Theorem I.1 page 213} \end{aligned}$$

⁶ Hernández and Weiss (1996) page 50 (PROPOSITION 2.1.11), WOJTASZCZYK (1997) PAGE 23 (COROLLARY 2.9), IGARI (1996) PAGES 214–215 (LEMMA 9.2), PINSKY (2002) PAGE 306 (COROLLARY 6.4.9)

$$= \frac{1}{2\pi} \int_0^{2\pi} e^{iun} du$$

$$= \bar{\delta}_n$$

by right hypothesis

by definition of $\bar{\delta}$

(Definition H.12 page 194)

4. Proof that $\langle f(x) | g(x - n) \rangle = 0 \implies \tilde{S}_{fg}(\omega) = 0$:

$$\tilde{S}_{fg}(\omega) = \sum_{n \in \mathbb{Z}} R_{fg}(n) e^{-i\omega n}$$

by definition of \tilde{S}_{fg}

(Definition I.3 page 213)

$$= \sum_{n \in \mathbb{Z}} \langle f(x) | g(x - n) \rangle e^{-i\omega n}$$

by definition of R_{fg}

(Definition I.1 page 213)

$$= \sum_{n \in \mathbb{Z}} 0 e^{-i\omega n}$$

by left hypothesis

$$= 0$$

5. Proof that $\langle f(x) | g(x - n) \rangle = 0 \iff \tilde{S}_{fg}(\omega) = 0$:

$$\langle f(x) | g(x - n) \rangle$$

$$= \langle \tilde{F}f(x) | \tilde{F}g(x - n) \rangle$$

by unitary property of \tilde{F}

(Theorem 3.3 page 27)

$$= \langle \tilde{f}(\omega) | e^{-i\omega n} \tilde{g}(\omega) \rangle$$

by shift property of \tilde{F}

(Theorem 3.4 page 28)

$$= \int_{\mathbb{R}} \tilde{f}(\omega) e^{i\omega n} \tilde{g}^*(\omega) d\omega$$

by definition of $\langle \triangle | \nabla \rangle$

(Definition B.1 page 99)

$$= \int_{\mathbb{R}} \tilde{f}(\omega) \tilde{g}^*(\omega) e^{i\omega n} d\omega$$

$$= \sum_{n \in \mathbb{Z}} \int_{2\pi n}^{2\pi(n+1)} \tilde{f}(\omega) \tilde{g}^*(\omega) e^{i\omega n} d\omega$$

$$= \sum_{n \in \mathbb{Z}} \int_0^{2\pi} \tilde{f}(u + 2\pi n) \tilde{g}^*(u + 2\pi n) e^{i(u+2\pi n)n} du$$

where $u \triangleq \omega - 2\pi n \implies \omega = u + 2\pi n$

$$= \frac{1}{2\pi} \int_0^{2\pi} \left[2\pi \sum_{n \in \mathbb{Z}} \tilde{f}(u + 2\pi n) \tilde{g}^*(u + 2\pi n) \right] e^{iun} e^{i2\pi n^2} du$$

$$= \frac{1}{2\pi} \int_0^{2\pi} \tilde{S}_{fg}(u) e^{iun} du$$

by Theorem I.1 page 213

$$= \frac{1}{2\pi} \int_0^{2\pi} 0 \cdot e^{iun} du$$

by right hypothesis

$$= 0$$



APPENDIX J

TRANSVERSAL OPERATORS

“Je me plaisois surtout aux mathématiques, à cause de la certitude et de l'évidence de leurs raisons: mais je ne remarquois point encore leur vrai usage; et, pensant qu'elles ne servoient qu'aux arts mécaniques, je m'étonnois de ce que leurs fondements étant si fermes et si solides, on n'avoit rien bâti dessus de plus relevé.”



“I was especially delighted with the mathematics, on account of the certitude and evidence of their reasonings; but I had not as yet a precise knowledge of their true use; and thinking that they but contributed to the advancement of the mechanical arts, I was astonished that foundations, so strong and solid, should have had no loftier superstructure reared on them.”



René Descartes, philosopher and mathematician (1596–1650) ¹

J.1 Families of Functions

This text is largely set in the space of *Lebesgue square-integrable functions* $\mathcal{L}_{\mathbb{R}}^2$ (Definition B.1 page 99). The space $\mathcal{L}_{\mathbb{R}}^2$ is a subspace of the space $\mathbb{R}^{\mathbb{R}}$, the set of all functions with *domain* \mathbb{R} (the set of real numbers) and *range* \mathbb{R} . The space $\mathbb{R}^{\mathbb{R}}$ is a subspace of the space $\mathbb{C}^{\mathbb{C}}$, the set of all functions with *domain* \mathbb{C} (the set of complex numbers) and *range* \mathbb{C} . That is, $\mathcal{L}_{\mathbb{R}}^2 \subseteq \mathbb{R}^{\mathbb{R}} \subseteq \mathbb{C}^{\mathbb{C}}$. In general, the notation Y^X represents the set of all functions with domain X and range Y (Definition J.1 page 221). Although this notation may seem curious, note that for finite X and finite Y , the number of functions (elements) in Y^X is $|Y^X| = |Y|^{|X|}$.

Definition J.1. Let X and Y be sets.

DEF The space Y^X represents the set of all functions with DOMAIN X and RANGE Y such that $Y^X \triangleq \{f(x)|f(x) : X \rightarrow Y\}$

¹ quote:  Descartes (1637b)
translation:  Descartes (1637c) (part I, paragraph 10)
image: http://en.wikipedia.org/wiki/File:Frans_Hals_-_Portret_van_Ren%C3%A9_Descartes.jpg, public domain

Definition J.2. ² Let X be a set.

DEF

The **indicator function** $\mathbb{1} \in \{0, 1\}^{2^X}$ is defined as

$$\mathbb{1}_A(x) = \begin{cases} 1 & \text{for } x \in A \\ 0 & \text{for } x \notin A \end{cases} \quad \begin{matrix} \forall x \in X, A \in 2^X \\ \forall x \in X, A \in 2^X \end{matrix}$$

The indicator function $\mathbb{1}$ is also called the **characteristic function**.

J.2 Definitions and algebraic properties

Much of the wavelet theory developed in this text is constructed using the **translation operator** \mathbf{T} and the **dilation operator** \mathbf{D} (next).

Definition J.3. ³

DEF

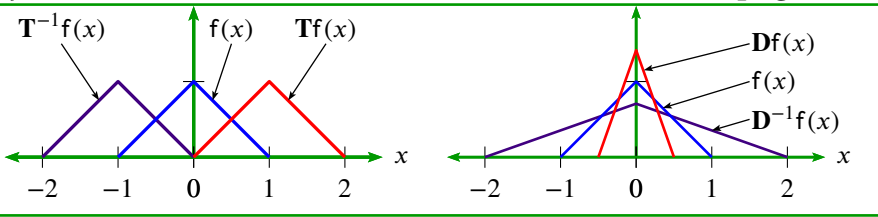
\mathbf{T}_τ is a **translation operator** on $\mathbb{C}^\mathbb{C}$ if $\mathbf{T}_\tau f(x) \triangleq f(x - \tau) \quad \forall f \in \mathbb{C}^\mathbb{C}.$

\mathbf{D}_α is a **dilation operator** on $\mathbb{C}^\mathbb{C}$ if $\mathbf{D}_\alpha f(x) \triangleq f(\alpha x) \quad \forall f \in \mathbb{C}^\mathbb{C}.$

Moreover, $\mathbf{T} \triangleq \mathbf{T}_1$ and $\mathbf{D} \triangleq \sqrt{2}\mathbf{D}_2$.

Example J.1. Let \mathbf{T} and \mathbf{D} be defined as in Definition J.3 (page 222).

EX



Proposition J.1. Let \mathbf{T}_τ be a TRANSLATION OPERATOR (Definition J.3 page 222).

PRP

$$\sum_{n \in \mathbb{Z}} \mathbf{T}_\tau^n f(x) = \sum_{n \in \mathbb{Z}} \mathbf{T}_\tau^n f(x + \tau) \quad \forall f \in \mathbb{R}^\mathbb{R} \quad \left(\sum_{n \in \mathbb{Z}} \mathbf{T}_\tau^n f(x) \text{ is PERIODIC with period } \tau \right)$$

PROOF:

$$\begin{aligned} \sum_{n \in \mathbb{Z}} \mathbf{T}_\tau^n f(x + \tau) &= \sum_{n \in \mathbb{Z}} f(x - n\tau + \tau) && \text{by definition of } \mathbf{T}_\tau && \text{(Definition J.3 page 222)} \\ &= \sum_{m \in \mathbb{Z}} f(x - m\tau) && \text{where } m \triangleq n - 1 && \implies n = m + 1 \\ &= \sum_{m \in \mathbb{Z}} \mathbf{T}_\tau^m f(x) && \text{by definition of } \mathbf{T}_\tau && \text{(Definition J.3 page 222)} \end{aligned}$$

⇒

In a linear space, every operator has an *inverse*. Although the inverse always exists as a *relation*, it may not exist as a *function* or as an *operator*. But in some cases the inverse of an operator is itself an operator. The inverses of the operators \mathbf{T} and \mathbf{D} both exist as operators, as demonstrated next.

² Aliprantis and Burkinshaw (1998) page 126, Hausdorff (1937) page 22, de la Vallée-Poussin (1915) page 440

³ Walnut (2002) pages 79–80 (Definition 3.39), Christensen (2003) pages 41–42, Wojtaszczyk (1997) page 18 (Definitions 2.3, 2.4), Kammler (2008) page A-21, Bachman et al. (2002) page 473, Packer (2004) page 260, Zayed (2004) page 639, Heil (2011) page 250 (Notation 9.4), Casazza and Lammers (1998) page 74, Goodman et al. (1993a) page 639, Heil and Walnut (1989) page 633 (Definition 1.3.1), Dai and Lu (1996) page 81, Dai and Larson (1998) page 2

Proposition J.2 (transversal operator inverses). *Let \mathbf{T} and \mathbf{D} be as defined in Definition J.3 page 222.*

P
R
P

\mathbf{T} has an INVERSE \mathbf{T}^{-1} in $\mathbb{C}^{\mathbb{C}}$ expressed by the relation

$$\mathbf{T}^{-1}\mathbf{f}(x) = \mathbf{f}(x+1) \quad \forall f \in \mathbb{C}^{\mathbb{C}} \quad (\text{translation operator inverse}).$$

\mathbf{D} has an INVERSE \mathbf{D}^{-1} in $\mathbb{C}^{\mathbb{C}}$ expressed by the relation

$$\mathbf{D}^{-1}\mathbf{f}(x) = \frac{\sqrt{2}}{2} \mathbf{f}\left(\frac{1}{2}x\right) \quad \forall f \in \mathbb{C}^{\mathbb{C}} \quad (\text{dilation operator inverse}).$$

 PROOF:

1. Proof that \mathbf{T}^{-1} is the inverse of \mathbf{T} :

$$\begin{aligned} \mathbf{T}^{-1}\mathbf{T}\mathbf{f}(x) &= \mathbf{T}^{-1}\mathbf{f}(x-1) && \text{by definition of } \mathbf{T} && (\text{Definition J.3 page 222}) \\ &= \mathbf{f}([x+1]-1) \\ &= \mathbf{f}(x) \\ &= \mathbf{f}([x-1]+1) \\ &= \mathbf{T}\mathbf{f}(x+1) && \text{by definition of } \mathbf{T} && (\text{Definition J.3 page 222}) \\ &= \mathbf{T}\mathbf{T}^{-1}\mathbf{f}(x) \\ \implies \mathbf{T}^{-1}\mathbf{T} &= \mathbf{I} = \mathbf{T}\mathbf{T}^{-1} \end{aligned}$$

2. Proof that \mathbf{D}^{-1} is the inverse of \mathbf{D} :

$$\begin{aligned} \mathbf{D}^{-1}\mathbf{D}\mathbf{f}(x) &= \mathbf{D}^{-1}\sqrt{2}\mathbf{f}(2x) && \text{by definition of } \mathbf{D} && (\text{Definition J.3 page 222}) \\ &= \left(\frac{\sqrt{2}}{2}\right)\sqrt{2}\mathbf{f}\left(2\left[\frac{1}{2}x\right]\right) \\ &= \mathbf{f}(x) \\ &= \sqrt{2}\left[\frac{\sqrt{2}}{2}\mathbf{f}\left(\frac{1}{2}[2x]\right)\right] \\ &= \mathbf{D}\left[\frac{\sqrt{2}}{2}\mathbf{f}\left(\frac{1}{2}x\right)\right] && \text{by definition of } \mathbf{D} && (\text{Definition J.3 page 222}) \\ &= \mathbf{D}\mathbf{D}^{-1}\mathbf{f}(x) \\ \implies \mathbf{D}^{-1}\mathbf{D} &= \mathbf{I} = \mathbf{D}\mathbf{D}^{-1} \end{aligned}$$



Proposition J.3. *Let \mathbf{T} and \mathbf{D} be as defined in Definition J.3 page 222.*

Let $\mathbf{D}^0 = \mathbf{T}^0 \triangleq \mathbf{I}$ be the IDENTITY OPERATOR.

P
R
P

$$\mathbf{D}^j\mathbf{T}^n\mathbf{f}(x) = 2^{j/2}\mathbf{f}(2^jx-n) \quad \forall j,n \in \mathbb{Z}, f \in \mathbb{C}^{\mathbb{C}}$$

J.3 Linear space properties

Proposition J.4. *Let \mathbf{T} and \mathbf{D} be as in Definition J.3 page 222.*

P
R
P

$$\mathbf{D}^j\mathbf{T}^n[\mathbf{f}g] = 2^{-j/2} [\mathbf{D}^j\mathbf{T}^n\mathbf{f}] [\mathbf{D}^j\mathbf{T}^n\mathbf{g}] \quad \forall j,n \in \mathbb{Z}, f,g \in \mathbb{C}^{\mathbb{C}}$$

 PROOF:

$$\begin{aligned} \mathbf{D}^j\mathbf{T}^n[\mathbf{f}(x)\mathbf{g}(x)] &= 2^{j/2}\mathbf{f}(2^jx-n)\mathbf{g}(2^jx-n) && \text{by Proposition J.3 page 223} \\ &= 2^{-j/2} [2^{j/2}\mathbf{f}(2^jx-n)] [2^{j/2}\mathbf{g}(2^jx-n)] \\ &= 2^{-j/2} [\mathbf{D}^j\mathbf{T}^n\mathbf{f}(x)] [\mathbf{D}^j\mathbf{T}^n\mathbf{g}(x)] && \text{by Proposition J.3 page 223} \end{aligned}$$

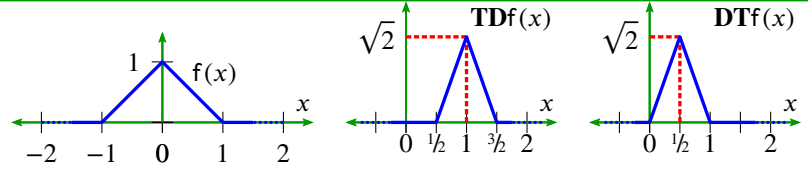


In general the operators \mathbf{T} and \mathbf{D} are *noncommutative* ($\mathbf{TD} \neq \mathbf{DT}$), as demonstrated by Counterexample J.1 (next) and Proposition J.5 (page 224).

Counterexample J.1.

CNT

As illustrated to the right,
it is **not** always true that
 $\mathbf{TD} = \mathbf{DT}$:



Proposition J.5 (commutator relation). ⁴ Let \mathbf{T} and \mathbf{D} be as in Definition J.3 page 222.

PRP

$$\begin{aligned} \mathbf{D}^j \mathbf{T}^n &= \mathbf{T}^{2^{-j/2}n} \mathbf{D}^j \quad \forall j, n \in \mathbb{Z} \\ \mathbf{T}^n \mathbf{D}^j &= \mathbf{D}^j \mathbf{T}^{2^j n} \quad \forall n, j \in \mathbb{Z} \end{aligned}$$

PROOF:

$$\begin{aligned} \mathbf{D}^j \mathbf{T}^{2^j n} f(x) &= 2^{j/2} f(2^j x - 2^j n) \\ &= 2^{j/2} f(2^j [x - n]) \\ &= \mathbf{T}^n 2^{j/2} f(2^j x) \\ &= \mathbf{T}^n \mathbf{D}^j f(x) \end{aligned}$$

by Proposition J.4 page 223

by *distributivity* of the field $(\mathbb{R}, +, \cdot, 0, 1)$

(Definition A.6 page 98)

by definition of \mathbf{T}

(Definition J.3 page 222)

by definition of \mathbf{D}

(Definition J.3 page 222)

$$\begin{aligned} \mathbf{D}^j \mathbf{T}^n f(x) &= 2^{j/2} f(2^j x - n) \\ &= 2^{j/2} f(2^j [x - 2^{-j/2}n]) \\ &= \mathbf{T}^{2^{-j/2}n} 2^{j/2} f(2^j x) \\ &= \mathbf{T}^{2^{-j/2}n} \mathbf{D}^j f(x) \end{aligned}$$

by Proposition J.4 page 223

by *distributivity* of the field $(\mathbb{R}, +, \cdot, 0, 1)$

(Definition A.6 page 98)

by definition of \mathbf{T}

(Definition J.3 page 222)

by definition of \mathbf{D}

(Definition J.3 page 222)



J.4 Inner product space properties

In an inner product space, every operator has an *adjoint* (Proposition G.3 page 167) and this adjoint is always itself an operator. In the case where the adjoint and inverse of an operator \mathbf{U} coincide, then \mathbf{U} is said to be *unitary* (Definition G.14 page 177). And in this case, \mathbf{U} has several nice properties (see Proposition J.9 and Theorem J.1 page 227). Proposition J.6 (next) gives the adjoints of \mathbf{D} and \mathbf{T} , and Proposition J.7 (page 225) demonstrates that both \mathbf{D} and \mathbf{T} are unitary. Other examples of unitary operators include the *Fourier Transform operator* $\tilde{\mathbf{F}}$ (Corollary 3.1 page 27) and the *rotation matrix operator* (Example G.5 page 179).

Proposition J.6. Let \mathbf{T} be the TRANSLATION OPERATOR (Definition J.3 page 222) with ADJOINT \mathbf{T}^* and \mathbf{D} the DILATION OPERATOR with ADJOINT \mathbf{D}^* (Definition G.8 page 163).

PRP

$$\begin{aligned} \mathbf{T}^* f(x) &= f(x + 1) \quad \forall f \in \mathcal{L}^2_{\mathbb{R}} \quad (\text{TRANSLATION OPERATOR ADJOINT}) \\ \mathbf{D}^* f(x) &= \frac{\sqrt{2}}{2} f\left(\frac{1}{2}x\right) \quad \forall f \in \mathcal{L}^2_{\mathbb{R}} \quad (\text{DILATION OPERATOR ADJOINT}) \end{aligned}$$

⁴ Christensen (2003) page 42 (equation (2.9)), Dai and Larson (1998) page 21, Goodman et al. (1993a) page 641, Goodman et al. (1993b) page 110

✎ PROOF:

1. Proof that $\mathbf{T}^* \mathbf{f}(x) = \mathbf{f}(x + 1)$:

$$\begin{aligned}
 \langle \mathbf{g}(x) | \mathbf{T}^* \mathbf{f}(x) \rangle &= \langle \mathbf{g}(u) | \mathbf{T}^* \mathbf{f}(u) \rangle && \text{by change of variable } x \rightarrow u \\
 &= \langle \mathbf{T} \mathbf{g}(u) | \mathbf{f}(u) \rangle && \text{by definition of adjoint } \mathbf{T}^* \quad (\text{Definition G.8 page 163}) \\
 &= \langle \mathbf{g}(u - 1) | \mathbf{f}(u) \rangle && \text{by definition of } \mathbf{T} \quad (\text{Definition J.3 page 222}) \\
 &= \langle \mathbf{g}(x) | \mathbf{f}(x + 1) \rangle && \text{where } x \triangleq u - 1 \implies u = x + 1 \\
 \implies \mathbf{T}^* \mathbf{f}(x) &= \mathbf{f}(x + 1)
 \end{aligned}$$

2. Proof that $\mathbf{D}^* \mathbf{f}(x) = \frac{\sqrt{2}}{2} \mathbf{f}\left(\frac{1}{2}x\right)$:

$$\begin{aligned}
 \langle \mathbf{g}(x) | \mathbf{D}^* \mathbf{f}(x) \rangle &= \langle \mathbf{g}(u) | \mathbf{D}^* \mathbf{f}(u) \rangle && \text{by change of variable } x \rightarrow u \\
 &= \langle \mathbf{D} \mathbf{g}(u) | \mathbf{f}(u) \rangle && \text{by definition of } \mathbf{D}^* \quad (\text{Definition G.8 page 163}) \\
 &= \left\langle \sqrt{2} \mathbf{g}(2u) | \mathbf{f}(u) \right\rangle && \text{by definition of } \mathbf{D} \quad (\text{Definition J.3 page 222}) \\
 &= \int_{u \in \mathbb{R}} \sqrt{2} \mathbf{g}(2u) \mathbf{f}^*(u) \, du && \text{by definition of } \langle \triangle | \nabla \rangle \\
 &= \int_{x \in \mathbb{R}} \mathbf{g}(x) \left[\sqrt{2} \mathbf{f}\left(\frac{x}{2}\right) \frac{1}{2} \right]^* \, dx && \text{where } x = 2u \\
 &= \left\langle \mathbf{g}(x) | \frac{\sqrt{2}}{2} \mathbf{f}\left(\frac{x}{2}\right) \right\rangle && \text{by definition of } \langle \triangle | \nabla \rangle \\
 \implies \mathbf{D}^* \mathbf{f}(x) &= \frac{\sqrt{2}}{2} \mathbf{f}\left(\frac{x}{2}\right)
 \end{aligned}$$

⇒

Proposition J.7.⁵ Let \mathbf{T} and \mathbf{D} be as in Definition J.3 (page 222).
Let \mathbf{T}^{-1} and \mathbf{D}^{-1} be as in Proposition J.2 (page 223).

P \mathbf{T} is UNITARY in $L_{\mathbb{R}}^2$ ($\mathbf{T}^{-1} = \mathbf{T}^*$ in $L_{\mathbb{R}}^2$).
R \mathbf{D} is UNITARY in $L_{\mathbb{R}}^2$ ($\mathbf{D}^{-1} = \mathbf{D}^*$ in $L_{\mathbb{R}}^2$).
P

✎ PROOF:

$$\begin{aligned}
 \mathbf{T}^{-1} &= \mathbf{T}^* && \text{by Proposition J.2 page 223 and Proposition J.6 page 224} \\
 \implies \mathbf{T} &\text{ is unitary} && \text{by the definition of unitary operators (Definition G.14 page 177)} \\
 \\
 \mathbf{D}^{-1} &= \mathbf{D}^* && \text{by Proposition J.2 page 223 and Proposition J.6 page 224} \\
 \implies \mathbf{D} &\text{ is unitary} && \text{by the definition of unitary operators (Definition G.14 page 177)}
 \end{aligned}$$

⇒

J.5 Normed linear space properties

Proposition J.8. Let \mathbf{D} be the DILATION OPERATOR (Definition J.3 page 222).

P $\left\{ \begin{array}{ll} (1). \mathbf{D} \mathbf{f}(x) = \sqrt{2} \mathbf{f}(x) & \text{and} \\ (2). \mathbf{f}(x) \text{ is CONTINUOUS} \end{array} \right\} \iff \{ \mathbf{f}(x) \text{ is a CONSTANT} \} \quad \forall \mathbf{f} \in L_{\mathbb{R}}^2$
R
P

⁵ Christensen (2003) page 41 (Lemma 2.5.1), Wojtaszczyk (1997) page 18 (Lemma 2.5)

✎ PROOF:

1. Proof that (1) \Leftarrow *constant* property:

$$\begin{aligned} \mathbf{D}f(x) &\triangleq \sqrt{2}f(2x) && \text{by definition of } \mathbf{D} && (\text{Definition J.3 page 222}) \\ &= \sqrt{2}f(x) && \text{by } \textit{constant} \text{ hypothesis} \end{aligned}$$

2. Proof that (2) \Leftarrow *constant* property:

$$\begin{aligned} \|f(x) - f(x+h)\| &= \|f(x) - f(x)\| && \text{by } \textit{constant} \text{ hypothesis} \\ &= \|0\| \\ &= 0 && \text{by } \textit{nondegenerate} \text{ property of } \|\cdot\| \\ &\leq \varepsilon \\ &\implies \forall h > 0, \exists \varepsilon \text{ such that } \|f(x) - f(x+h)\| < \varepsilon \\ &\stackrel{\text{def}}{\iff} f(x) \text{ is } \textit{continuous} \end{aligned}$$

3. Proof that (1,2) \implies *constant* property:

(a) Suppose there exists $x, y \in \mathbb{R}$ such that $f(x) \neq f(y)$.

(b) Let $(x_n)_{n \in \mathbb{N}}$ be a sequence with limit x and $(y_n)_{n \in \mathbb{N}}$ a sequence with limit y

(c) Then

$$\begin{aligned} 0 &< \|f(x) - f(y)\| && \text{by assumption in item (3a) page 226} \\ &= \lim_{n \rightarrow \infty} \|f(x_n) - f(y_n)\| && \text{by (2) and definition of } (x_n) \text{ and } (y_n) \text{ in item (3b) page 226} \\ &= \lim_{n \rightarrow \infty} \|f(2^m x_n) - f(2^\ell y_n)\| \quad \forall m, \ell \in \mathbb{Z} \quad \text{by (1)} \\ &= 0 \end{aligned}$$

(d) But this is a *contradiction*, so $f(x) = f(y)$ for all $x, y \in \mathbb{R}$, and $f(x)$ is *constant*.

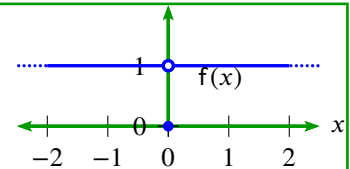
⇒

Remark J.1.

REM In Proposition J.8 page 225, it is not possible to remove the *continuous* constraint outright, as demonstrated by the next two counterexamples.

Counterexample J.2. Let $f(x)$ be a function in $\mathbb{R}^{\mathbb{R}}$.

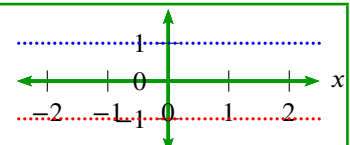
CNT Let $f(x) \triangleq \begin{cases} 0 & \text{for } x = 0 \\ 1 & \text{otherwise.} \end{cases}$
Then $\mathbf{D}f(x) \triangleq \sqrt{2}f(2x) = \sqrt{2}f(x)$, but $f(x)$ is *not constant*.



Counterexample J.3. Let $f(x)$ be a function in $\mathbb{R}^{\mathbb{R}}$.

Let \mathbb{Q} be the set of *rational numbers* and $\mathbb{R} \setminus \mathbb{Q}$ the set of *irrational numbers*.

CNT Let $f(x) \triangleq \begin{cases} 1 & \text{for } x \in \mathbb{Q} \\ -1 & \text{for } x \in \mathbb{R} \setminus \mathbb{Q}. \end{cases}$
Then $\mathbf{D}f(x) \triangleq \sqrt{2}f(2x) = \sqrt{2}f(x)$, but $f(x)$ is *not constant*.



Proposition J.9 (Operator norm). *Let \mathbf{T} and \mathbf{D} be as in Definition J.3 page 222. Let \mathbf{T}^{-1} and \mathbf{D}^{-1} be as in Proposition J.2 page 223. Let \mathbf{T}^* and \mathbf{D}^* be as in Proposition J.6 page 224. Let $\|\cdot\|$ and $\langle \triangle | \nabla \rangle$ be as in Definition B.1 page 99. Let $\|\cdot\|$ be the operator norm (Definition G.6 page 159) induced by $\|\cdot\|$.*

$$\|\mathbf{T}\| = \|\mathbf{D}\| = \|\mathbf{T}^*\| = \|\mathbf{D}^*\| = \|\mathbf{T}^{-1}\| = \|\mathbf{D}^{-1}\| = 1$$

PROOF: These results follow directly from the fact that \mathbf{T} and \mathbf{D} are *unitary* (Proposition J.7 page 225) and from Theorem G.25 page 178 and Theorem G.26 page 178. \Rightarrow

Theorem J.1. *Let \mathbf{T} and \mathbf{D} be as in Definition J.3 page 222.*

Let \mathbf{T}^{-1} and \mathbf{D}^{-1} be as in Proposition J.2 page 223. Let $\|\cdot\|$ and $\langle \triangle | \nabla \rangle$ be as in Definition B.1 page 99.

T H M	1.	$\ \mathbf{T}f\ $	$=$	$\ \mathbf{D}f\ $	$=$	$\ f\ $	$\forall f \in L^2_{\mathbb{R}}$	(ISOMETRIC IN LENGTH)
	2.	$\ \mathbf{T}f - \mathbf{T}g\ $	$=$	$\ \mathbf{D}f - \mathbf{D}g\ $	$=$	$\ f - g\ $	$\forall f, g \in L^2_{\mathbb{R}}$	(ISOMETRIC IN DISTANCE)
	3.	$\ \mathbf{T}^{-1}f - \mathbf{T}^{-1}g\ $	$=$	$\ \mathbf{D}^{-1}f - \mathbf{D}^{-1}g\ $	$=$	$\ f - g\ $	$\forall f, g \in L^2_{\mathbb{R}}$	(ISOMETRIC IN DISTANCE)
	4.	$\langle \mathbf{T}f \mathbf{T}g \rangle$	$=$	$\langle \mathbf{D}f \mathbf{D}g \rangle$	$=$	$\langle f g \rangle$	$\forall f, g \in L^2_{\mathbb{R}}$	(SURJECTIVE)
	5.	$\langle \mathbf{T}^{-1}f \mathbf{T}^{-1}g \rangle$	$=$	$\langle \mathbf{D}^{-1}f \mathbf{D}^{-1}g \rangle$	$=$	$\langle f g \rangle$	$\forall f, g \in L^2_{\mathbb{R}}$	(SURJECTIVE)

PROOF: These results follow directly from the fact that \mathbf{T} and \mathbf{D} are *unitary* (Proposition J.7 page 225) and from Theorem G.25 page 178 and Theorem G.26 page 178. \Rightarrow

Proposition J.10. *Let \mathbf{T} be as in Definition J.3 page 222. Let \mathbf{A}^* be the ADJOINT (Definition G.8 page 163) of an operator \mathbf{A} . Let the property “SELF ADJOINT” be defined as in Definition G.11 (page 171).*

$$\left(\sum_{n \in \mathbb{Z}} \mathbf{T}^n \right) = \left(\sum_{n \in \mathbb{Z}} \mathbf{T}^n \right)^* \quad \left(\text{The operator } \left[\sum_{n \in \mathbb{Z}} \mathbf{T}^n \right] \text{ is SELF-ADJOINT} \right)$$

PROOF:

$$\begin{aligned}
 \left\langle \left(\sum_{n \in \mathbb{Z}} \mathbf{T}^n \right) f(x) \mid g(x) \right\rangle &= \left\langle \sum_{n \in \mathbb{Z}} f(x-n) \mid g(x) \right\rangle && \text{by definition of } \mathbf{T} && \text{(Definition J.3 page 222)} \\
 &= \left\langle \sum_{n \in \mathbb{Z}} f(x+n) \mid g(x) \right\rangle && \text{by commutative property} && \text{(Definition A.5 page 98)} \\
 &= \sum_{n \in \mathbb{Z}} \langle f(x+n) \mid g(x) \rangle && \text{by additive property of } \langle \triangle | \nabla \rangle \\
 &= \sum_{n \in \mathbb{Z}} \langle f(u) \mid g(u-n) \rangle && \text{where } u \triangleq x+n \\
 &= \left\langle f(u) \mid \sum_{n \in \mathbb{Z}} g(u-n) \right\rangle && \text{by additive property of } \langle \triangle | \nabla \rangle \\
 &= \left\langle f(x) \mid \sum_{n \in \mathbb{Z}} g(x-n) \right\rangle && \text{by change of variable: } u \rightarrow x \\
 &= \left\langle f(x) \mid \sum_{n \in \mathbb{Z}} \mathbf{T}^n g(x) \right\rangle && \text{by definition of } \mathbf{T} && \text{(Definition J.3 page 222)} \\
 &\Leftrightarrow \left(\sum_{n \in \mathbb{Z}} \mathbf{T}^n \right) = \left(\sum_{n \in \mathbb{Z}} \mathbf{T}^n \right)^* && \text{by definition of adjoint} && \text{(Proposition G.3 page 167)} \\
 &\Leftrightarrow \left(\sum_{n \in \mathbb{Z}} \mathbf{T}^n \right) \text{ is self-adjoint} && \text{by definition of self-adjoint} && \text{(Definition G.11 page 171)}
 \end{aligned}$$

J.6 Fourier transform properties

Proposition J.11. Let \mathbf{T} and \mathbf{D} be as in Definition J.3 page 222.

Let \mathbf{B} be the TWO-SIDED LAPLACE TRANSFORM defined as $[\mathbf{B}f](s) \triangleq \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x)e^{-sx} dx$.

P R P	1.	$\mathbf{B}\mathbf{T}^n = e^{-sn}\mathbf{B}$	$\forall n \in \mathbb{Z}$
	2.	$\mathbf{B}\mathbf{D}^j = \mathbf{D}^{-j}\mathbf{B}$	$\forall j \in \mathbb{Z}$
	3.	$\mathbf{D}\mathbf{B} = \mathbf{B}\mathbf{D}^{-1}$	$\forall n \in \mathbb{Z}$
	4.	$\mathbf{B}\mathbf{D}^{-1}\mathbf{B}^{-1} = \mathbf{B}^{-1}\mathbf{D}^{-1}\mathbf{B} = \mathbf{D}$	$\forall n \in \mathbb{Z}$ (\mathbf{D}^{-1} is SIMILAR to \mathbf{D})
	5.	$\mathbf{D}\mathbf{B}\mathbf{D} = \mathbf{D}^{-1}\mathbf{B}\mathbf{D}^{-1} = \mathbf{B}$	$\forall n \in \mathbb{Z}$

PROOF:

$$\mathbf{B}\mathbf{T}^n f(x) = \mathbf{B}f(x-n) \quad \text{by definition of } \mathbf{T} \quad (\text{Definition J.3 page 222})$$

$$= \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x-n)e^{-sx} dx \quad \text{by definition of } \mathbf{B}$$

$$= \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(u)e^{-s(u+n)} du \quad \text{where } u \triangleq x-n$$

$$= e^{-sn} \left[\frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(u)e^{-su} du \right] \quad \text{by definition of } \mathbf{B}$$

$$= e^{-sn} \mathbf{B}f(x)$$

$$\mathbf{B}\mathbf{D}^j f(x) = \mathbf{B}[2^{j/2} f(2^j x)] \quad \text{by definition of } \mathbf{D} \quad (\text{Definition J.3 page 222})$$

$$= \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} [2^{j/2} f(2^j x)] e^{-sx} dx \quad \text{by definition of } \mathbf{B}$$

$$= \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} [2^{j/2} f(u)] e^{-s2^{-j}2^j} du \quad \text{let } u \triangleq 2^j x \implies x = 2^{-j}u$$

$$= \frac{\sqrt{2}}{2} \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(u)e^{-s2^{-j}u} du$$

$$= \mathbf{D}^{-1} \left[\frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(u)e^{-su} du \right] \quad \text{by Proposition J.6 page 224 and Proposition J.7 page 225}$$

$$= \mathbf{D}^{-j} \mathbf{B}f(x) \quad \text{by definition of } \mathbf{B}$$

$$\mathbf{D}\mathbf{B}f(x) = \mathbf{D} \left[\frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x)e^{-sx} dx \right] \quad \text{by definition of } \mathbf{B}$$

$$= \frac{\sqrt{2}}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x)e^{-2sx} dx \quad \text{by definition of } \mathbf{D} \quad (\text{Definition J.3 page 222})$$

$$= \frac{\sqrt{2}}{\sqrt{2\pi}} \int_{\mathbb{R}} f\left(\frac{u}{2}\right) e^{-su\frac{1}{2}} du \quad \text{let } u \triangleq 2x \implies x = \frac{1}{2}u$$

$$= \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} \left[\frac{\sqrt{2}}{2} f\left(\frac{u}{2}\right) \right] e^{-su} du$$

$$= \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} [\mathbf{D}^{-1}f](u) e^{-su} du \quad \text{by Proposition J.6 page 224 and Proposition J.7 page 225}$$

$$= \mathbf{B}\mathbf{D}^{-1}f(x) \quad \text{by definition of } \mathbf{B}$$

$$\mathbf{B}^{-1}\mathbf{D}^{-1}\mathbf{B} = \mathbf{B}^{-1}\mathbf{B}\mathbf{D} \quad \text{by previous result}$$

$$= \mathbf{D} \quad \text{by definition of operator inverse} \quad (\text{Definition G.3 page 154})$$

$$\mathbf{B}\mathbf{D}^{-1}\mathbf{B}^{-1} = \mathbf{D}\mathbf{B}\mathbf{B}^{-1} \quad \text{by previous result}$$

$$= \mathbf{D} \quad \text{by definition of operator inverse} \quad (\text{Definition G.3 page 154})$$

$$\mathbf{D}\mathbf{B}\mathbf{D} = \mathbf{D}\mathbf{D}^{-1}\mathbf{B}$$

$$= \mathbf{B}$$

$$\mathbf{D}^{-1}\mathbf{B}\mathbf{D}^{-1} = \mathbf{D}^{-1}\mathbf{D}\mathbf{B}$$

$$= \mathbf{B}$$

by previous result

by definition of operator inverse (Definition G.3 page 154)

by previous result

by definition of operator inverse (Definition G.3 page 154)

⇒

Corollary J.1. Let \mathbf{T} and \mathbf{D} be as in Definition J.3 page 222. Let $\tilde{f}(\omega) \triangleq \tilde{\mathbf{F}}f(x)$ be the FOURIER TRANSFORM (Definition 3.2 page 26) of some function $f \in \mathcal{L}_{\mathbb{R}}^2$ (Definition B.1 page 99).

- | | |
|-------------|---|
| C
O
R | 1. $\tilde{\mathbf{F}}\mathbf{T}^n = e^{-i\omega n}\tilde{\mathbf{F}}$ |
| | 2. $\tilde{\mathbf{F}}\mathbf{D}^j = \mathbf{D}^{-j}\tilde{\mathbf{F}}$ |
| | 3. $\mathbf{D}\tilde{\mathbf{F}} = \tilde{\mathbf{F}}\mathbf{D}^{-1}$ |
| | 4. $\mathbf{D} = \tilde{\mathbf{F}}\mathbf{D}^{-1}\tilde{\mathbf{F}}^{-1} = \tilde{\mathbf{F}}^{-1}\mathbf{D}^{-1}\tilde{\mathbf{F}}$ |
| | 5. $\tilde{\mathbf{F}} = \mathbf{D}\tilde{\mathbf{F}}\mathbf{D} = \mathbf{D}^{-1}\tilde{\mathbf{F}}\mathbf{D}^{-1}$ |

PROOF: These results follow directly from Proposition J.11 page 228 with $\tilde{\mathbf{F}} = \mathbf{B}|_{s=i\omega}$.

⇒

Proposition J.12. Let \mathbf{T} and \mathbf{D} be as in Definition J.3 page 222. Let $\tilde{f}(\omega) \triangleq \tilde{\mathbf{F}}f(x)$ be the FOURIER TRANSFORM (Definition 3.2 page 26) of some function $f \in \mathcal{L}_{\mathbb{R}}^2$ (Definition B.1 page 99).

P R P	$\tilde{\mathbf{F}}\mathbf{D}^j\mathbf{T}^nf(x) = \frac{1}{2^{j/2}}e^{-i\frac{\omega}{2^j}n}\tilde{f}\left(\frac{\omega}{2^j}\right)$
-------------	---

PROOF:

$$\begin{aligned}\tilde{\mathbf{F}}\mathbf{D}^j\mathbf{T}^nf(x) &= \mathbf{D}^{-j}\tilde{\mathbf{F}}\mathbf{T}^nf(x) \\ &= \mathbf{D}^{-j}e^{-i\omega n}\tilde{\mathbf{F}}f(x) \\ &= \mathbf{D}^{-j}e^{-i\omega n}\tilde{f}(\omega) \\ &= 2^{-j/2}e^{-i2^{-j}\omega n}\tilde{f}(2^{-j}\omega)\end{aligned}$$

by Corollary J.1 page 229 (3)

by Corollary J.1 page 229 (3)

by Proposition J.2 page 223

⇒

Proposition J.13. Let \mathbf{T} be the translation operator (Definition J.3 page 222). Let $\tilde{f}(\omega) \triangleq \tilde{\mathbf{F}}f(x)$ be the FOURIER TRANSFORM (Definition 3.2 page 26) of a function $f \in \mathcal{L}_{\mathbb{R}}^2$. Let $\check{a}(\omega)$ be the DTFT (Definition 8.1 page 59) of a sequence $(a_n)_{n \in \mathbb{Z}} \in \ell_{\mathbb{R}}^2$ (Definition 9.2 page 69).

P R P	$\tilde{\mathbf{F}} \sum_{n \in \mathbb{Z}} a_n \mathbf{T}^n \phi(x) = \check{a}(\omega) \tilde{\phi}(\omega) \quad \forall (a_n) \in \ell_{\mathbb{R}}^2, \phi(x) \in \mathcal{L}_{\mathbb{R}}^2$
-------------	--

PROOF:

$$\begin{aligned}\tilde{\mathbf{F}} \sum_{n \in \mathbb{Z}} a_n \mathbf{T}^n \phi(x) &= \sum_{n \in \mathbb{Z}} a_n \tilde{\mathbf{F}}\mathbf{T}^n \phi(x) \\ &= \sum_{n \in \mathbb{Z}} a_n e^{-i\omega n} \tilde{\mathbf{F}}\phi(x) \\ &= \left[\sum_{n \in \mathbb{Z}} a_n e^{-i\omega n} \right] \tilde{\phi}(\omega) \\ &= \check{a}(\omega) \tilde{\phi}(\omega)\end{aligned}$$

by Corollary J.1 page 229

by definition of $\tilde{\phi}(\omega)$

by definition of DTFT (Definition 8.1 page 59)

⇒

Definition J.4. Let $L^2_{(\mathbb{R}, \mathcal{B}, \mu)}$ be the SPACE OF LEBESGUE SQUARE-INTEGRABLE FUNCTIONS (Definition B.1 page 99). Let $\ell^2_{\mathbb{R}}$ be the SPACE OF ALL ABSOLUTELY SQUARE SUMMABLE SEQUENCES OVER \mathbb{R} (Definition B.1 page 99).

DEF S is the **sampling operator** in $\ell^2_{\mathbb{R}}$ if $[\mathbf{S}f(x)](n) \triangleq f\left(\frac{2\pi}{\tau}n\right) \quad \forall f \in L^2_{(\mathbb{R}, \mathcal{B}, \mu)}, \tau \in \mathbb{R}^+$

Theorem J.2 (Poisson Summation Formula—PSF).⁶ Let $\tilde{f}(\omega)$ be the FOURIER TRANSFORM (Definition 3.2 page 26) of a function $f(x) \in L^2_{\mathbb{R}}$. Let S be the SAMPLING OPERATOR (Definition J.4 page 230).

THM

$$\underbrace{\sum_{n \in \mathbb{Z}} T_{\tau}^n f(x)}_{\text{summation in "time"}} = \underbrace{\sum_{n \in \mathbb{Z}} f(x + n\tau)}_{\text{operator notation}} = \underbrace{\sqrt{\frac{2\pi}{\tau}} \hat{\mathbf{F}}^{-1} \mathbf{S} \tilde{\mathbf{F}}[f(x)]}_{\text{summation in "frequency"}} = \underbrace{\frac{\sqrt{2\pi}}{\tau} \sum_{n \in \mathbb{Z}} \tilde{f}\left(\frac{2\pi}{\tau}n\right) e^{i\frac{2\pi}{\tau}nx}}_{\text{summation in "frequency"}}$$

PROOF:

1. lemma: If $h(x) \triangleq \sum_{n \in \mathbb{Z}} f(x + n\tau)$ then $h \equiv \hat{\mathbf{F}}^{-1} \hat{\mathbf{F}} h$. Proof:

Note that $h(x)$ is *periodic* with period τ . Because h is periodic, it is in the domain of $\hat{\mathbf{F}}$ and thus $h \equiv \hat{\mathbf{F}}^{-1} \hat{\mathbf{F}} h$.

2. Proof of PSF (this theorem—Theorem J.2):

$$\begin{aligned} \sum_{n \in \mathbb{Z}} f(x + n\tau) &= \hat{\mathbf{F}}^{-1} \hat{\mathbf{F}} \sum_{n \in \mathbb{Z}} f(x + n\tau) && \text{by (1) lemma page 230} \\ &= \hat{\mathbf{F}}^{-1} \left[\underbrace{\frac{1}{\sqrt{\tau}} \int_0^{\tau} \left(\sum_{n \in \mathbb{Z}} f(x + n\tau) \right) e^{-i\frac{2\pi}{\tau}kx} dx}_{\hat{\mathbf{F}}[\sum_{n \in \mathbb{Z}} f(x + n\tau)]} \right] && \text{by definition of } \hat{\mathbf{F}} \quad (\text{Definition 7.1 page 53}) \\ &= \hat{\mathbf{F}}^{-1} \left[\frac{1}{\sqrt{\tau}} \sum_{n \in \mathbb{Z}} \int_0^{\tau} f(x + n\tau) e^{-i\frac{2\pi}{\tau}kx} dx \right] \\ &= \hat{\mathbf{F}}^{-1} \left[\frac{1}{\sqrt{\tau}} \sum_{n \in \mathbb{Z}} \int_{u=n\tau}^{u=(n+1)\tau} f(u) e^{-i\frac{2\pi}{\tau}k(u-n\tau)} du \right] && \text{where } u \triangleq x + n\tau \implies x = u - n\tau \\ &= \hat{\mathbf{F}}^{-1} \left[\frac{1}{\sqrt{\tau}} \sum_{n \in \mathbb{Z}} e^{i2\pi kn} \int_{u=n\tau}^{u=(n+1)\tau} f(u) e^{-i\frac{2\pi}{\tau}ku} du \right] \\ &= \sqrt{\frac{2\pi}{\tau}} \hat{\mathbf{F}}^{-1} \left[\underbrace{\frac{1}{\sqrt{2\pi}} \int_{u \in \mathbb{R}} f(u) e^{-i\left(\frac{2\pi}{\tau}k\right)u} du}_{[\tilde{\mathbf{F}}f]\left(\frac{2\pi}{\tau}k\right)} \right] && \text{by evaluation of } \hat{\mathbf{F}}^{-1} \quad (\text{Theorem 7.1 page 54}) \\ &= \sqrt{\frac{2\pi}{\tau}} \hat{\mathbf{F}}^{-1} \left[[\tilde{\mathbf{F}}f(x)]\left(\frac{2\pi}{\tau}k\right) \right] && \text{by definition of } \tilde{\mathbf{F}} \quad (\text{Definition 3.2 page 26}) \\ &= \sqrt{\frac{2\pi}{\tau}} \hat{\mathbf{F}}^{-1} \mathbf{S} \tilde{\mathbf{F}} f && \text{by definition of } S \quad (\text{Definition J.4 page 230}) \\ &= \frac{\sqrt{2\pi}}{\tau} \sum_{n \in \mathbb{Z}} \tilde{f}\left(\frac{2\pi}{\tau}n\right) e^{i\frac{2\pi}{\tau}nx} && \text{by evaluation of } \hat{\mathbf{F}}^{-1} \quad (\text{Theorem 7.1 page 54}) \end{aligned}$$

⇒

⁶ Andrews et al. (2001) page 624, Knapp (2005b) page 389, Lasser (1996) page 254, Rudin (1987) pages 194–195, Folland (1992) page 337

Theorem J.3 (Inverse Poisson Summation Formula—IPSF). ⁷

Let $\tilde{f}(\omega)$ be the FOURIER TRANSFORM (Definition 3.2 page 26) of a function $f(x) \in L^2_{\mathbb{R}}$.

T
H
M

$$\underbrace{\sum_{n \in \mathbb{Z}} T_{2\pi/\tau}^n \tilde{f}(\omega) \triangleq \sum_{n \in \mathbb{Z}} \tilde{f}\left(\omega - \frac{2\pi}{\tau}n\right)}_{\text{summation in "frequency"}} = \underbrace{\frac{\tau}{\sqrt{2\pi}} \sum_{n \in \mathbb{Z}} f(n\tau) e^{-i\omega n\tau}}_{\text{summation in "time"}}$$

 PROOF:

1. lemma: If $h(\omega) \triangleq \sum_{n \in \mathbb{Z}} \tilde{f}\left(\omega + \frac{2\pi}{\tau}n\right)$, then $h \equiv \hat{\mathbf{F}}^{-1} \hat{\mathbf{F}} h$. Proof:


Note that $h(\omega)$ is periodic with period $2\pi/\tau$:

$$h\left(\omega + \frac{2\pi}{\tau}\right) \triangleq \sum_{n \in \mathbb{Z}} \tilde{f}\left(\omega + \frac{2\pi}{\tau} + \frac{2\pi}{\tau}n\right) = \sum_{n \in \mathbb{Z}} \tilde{f}\left(\omega + (n+1)\frac{2\pi}{\tau}\right) = \sum_{n \in \mathbb{Z}} \tilde{f}\left(\omega + \frac{2\pi}{\tau}n\right) \triangleq h(\omega)$$

Because h is periodic, it is in the domain of $\hat{\mathbf{F}}$ and is equivalent to $\hat{\mathbf{F}}^{-1} \hat{\mathbf{F}} h$.

2. Proof of IPSF (this theorem—Theorem J.3):

$$\begin{aligned} & \sum_{n \in \mathbb{Z}} \tilde{f}\left(\omega + \frac{2\pi}{\tau}n\right) \\ &= \hat{\mathbf{F}}^{-1} \hat{\mathbf{F}} \sum_{n \in \mathbb{Z}} \tilde{f}\left(\omega + \frac{2\pi}{\tau}n\right) && \text{by (1) lemma page 231} \\ &= \hat{\mathbf{F}}^{-1} \left[\underbrace{\sqrt{\frac{\tau}{2\pi}} \int_0^{\frac{2\pi}{\tau}} \sum_{n \in \mathbb{Z}} \tilde{f}\left(\omega + \frac{2\pi}{\tau}n\right) e^{-i\omega \frac{2\pi}{\tau}k} d\omega}_{\hat{\mathbf{F}}\left[\sum_{n \in \mathbb{Z}} \tilde{f}\left(\omega + \frac{2\pi}{\tau}n\right)\right]} \right] && \text{by definition of } \hat{\mathbf{F}} \quad (\text{Definition 7.1 page 53}) \\ &= \hat{\mathbf{F}}^{-1} \left[\sqrt{\frac{\tau}{2\pi}} \sum_{n \in \mathbb{Z}} \int_0^{\frac{2\pi}{\tau}} \tilde{f}\left(\omega + \frac{2\pi}{\tau}n\right) e^{-i\omega T k} d\omega \right] \\ &= \hat{\mathbf{F}}^{-1} \left[\sqrt{\frac{\tau}{2\pi}} \sum_{n \in \mathbb{Z}} \int_{u=\frac{2\pi}{\tau}n}^{u=\frac{2\pi}{\tau}(n+1)} \tilde{f}(u) e^{-i\left(u-\frac{2\pi}{\tau}n\right)Tk} du \right] && \text{where } u \triangleq \omega + \frac{2\pi}{\tau}n \implies \omega = u - \frac{2\pi}{\tau}n \\ &= \hat{\mathbf{F}}^{-1} \left[\sqrt{\frac{\tau}{2\pi}} \sum_{n \in \mathbb{Z}} \underbrace{e^{i2\pi nk}}_{\rightarrow 1} \int_{\frac{2\pi}{\tau}n}^{\frac{2\pi}{\tau}(n+1)} \tilde{f}(u) e^{-iurk} du \right] \\ &= \hat{\mathbf{F}}^{-1} \left[\sqrt{\frac{\tau}{2\pi}} \int_{\mathbb{R}} \tilde{f}(u) e^{-iurk} du \right] \\ &= \sqrt{\tau} \hat{\mathbf{F}}^{-1} \left[\underbrace{\frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} \tilde{f}(u) e^{iu(-\tau k)} du}_{[\hat{\mathbf{F}}^{-1}\tilde{f}](-k\tau)} \right] \\ &= \sqrt{\tau} \hat{\mathbf{F}}^{-1} [[\hat{\mathbf{F}}^{-1}\tilde{f}](-k\tau)] && \text{by value of } \hat{\mathbf{F}}^{-1} \quad (\text{Theorem 3.1 page 27}) \\ &= \sqrt{\tau} \hat{\mathbf{F}}^{-1} \mathbf{S} \hat{\mathbf{F}}^{-1} \tilde{f} && \text{by definition of } \mathbf{S} \quad (\text{Definition J.4 page 230}) \\ &= \sqrt{\tau} \hat{\mathbf{F}}^{-1} \mathbf{S} f(x) && \text{by definition of } \tilde{\mathbf{F}} \quad (\text{Definition 3.2 page 26}) \\ &= \sqrt{\tau} \hat{\mathbf{F}}^{-1} f(-k\tau) && \text{by definition of } \mathbf{S} \quad (\text{Definition J.4 page 230}) \\ &= \sqrt{\tau} \frac{1}{\sqrt{\frac{2\pi}{\tau}}} \sum_{k \in \mathbb{Z}} f(-k\tau) e^{i2\pi \frac{1}{\tau} k \omega} && \text{by definition of } \hat{\mathbf{F}}^{-1} \quad (\text{Theorem 7.1 page 54}) \end{aligned}$$

⁷  Gauss (1900) page 88

$$= \frac{\tau}{\sqrt{\frac{2\pi}{\tau}}} \sum_{k \in \mathbb{Z}} f(-k\tau) e^{ik\tau\omega}$$

$$= \frac{\tau}{\sqrt{2\pi}} \sum_{m \in \mathbb{Z}} f(m\tau) e^{-i\omega m\tau}$$

by definition of $\hat{\mathbf{F}}^{-1}$ (Theorem 7.1 page 54)let $m \triangleq -k$

⇒

Remark J.2. The left hand side of the *Poisson Summation Formula* (Theorem J.2 page 230) is very similar to the *Zak Transform Z*:⁸

$$(\mathbf{Z}f)(t, \omega) \triangleq \sum_{n \in \mathbb{Z}} f(x + n\tau) e^{i2\pi n\omega}$$

Remark J.3. A generalization of the *Poisson Summation Formula* (Theorem J.2 page 230) is the **Selberg Trace Formula**.⁹

J.7 Basis theory properties

Example J.2 (linear functions).¹⁰ Let \mathbf{T} be the *translation operator* (Definition J.3 page 222). Let $\mathcal{L}(\mathbb{C}, \mathbb{C})$ be the set of all *linear functions* in $L^2_{\mathbb{R}}$.

- | | |
|----------------|---|
| E
X | 1. $\{x, \mathbf{T}x\}$ is a <i>basis</i> for $\mathcal{L}(\mathbb{C}, \mathbb{C})$ and |
| | 2. $f(x) = f(1)x - f(0)\mathbf{T}x \quad \forall f \in \mathcal{L}(\mathbb{C}, \mathbb{C})$ |

✎ **PROOF:** By left hypothesis, f is *linear*; so let $f(x) \triangleq ax + b$

$$\begin{aligned} f(1)x - f(0)\mathbf{T}x &= f(1)x - f(0)(x - 1) \\ &= (ax + b)|_{x=1} x - (ax + b)|_{x=0} (x - 1) \\ &= (a + b)x - b(x - 1) \\ &= ax + bx - bx + b \\ &= ax + b \\ &= f(x) \end{aligned}$$

by Definition J.3 page 222

by left hypothesis and definition of f by left hypothesis and definition of f

⇒

Example J.3 (Cardinal Series). Let \mathbf{T} be the *translation operator* (Definition J.3 page 222). The *Paley-Wiener* class of functions \mathbf{PW}_{σ}^2 are those functions which are “*bandlimited*” with respect to their Fourier transform (Definition 3.2 page 26). The cardinal series forms an orthogonal basis for such a space. The *Fourier coefficients* (Definition H.11 page 194) for a projection of a function f onto the Cardinal series basis elements is particularly simple—these coefficients are samples of $f(x)$ taken at regular intervals. In fact, one could represent the coefficients using inner product notation with the *Dirac delta distribution* δ as follows:

$$\langle f(x) | \mathbf{T}^n \delta(x) \rangle \triangleq \int_{\mathbb{R}} f(x) \delta(x - n) dx \triangleq f(n)$$

- | | |
|----------------|---|
| E
X | 1. $\left\{ \mathbf{T}^n \frac{\sin(\pi x)}{\pi x} \right\}_{n \in \mathbb{N}}$ is a <i>basis</i> for \mathbf{PW}_{σ}^2 and |
| | 2. $f(x) = \underbrace{\sum_{n=1}^{\infty} f(n) \mathbf{T}^n \frac{\sin(\pi x)}{\pi x}}_{\text{Cardinal series}} \quad \forall f \in \mathbf{PW}_{\sigma}^2, \sigma \leq \frac{1}{2}$ |

⁸ Janssen (1988) page 24, Zayed (1996) page 482

⁹ Lax (2002) page 349, Selberg (1956), Terras (1999)

¹⁰ Higgins (1996) page 2 (1.1 General introduction)

Example J.4 (Fourier Series).

E X

(1). $\{\mathbf{D}_n e^{ix} \mid n \in \mathbb{Z}\}$ is a *basis* for $L(0 : 2\pi)$ and

(2). $f(x) = \frac{1}{\sqrt{2\pi}} \sum_{n \in \mathbb{Z}} \alpha_n \mathbf{D}_n e^{ix} \quad \forall x \in (0 : 2\pi), f \in L(0 : 2\pi)$ where

$$\alpha_n \triangleq \frac{1}{\sqrt{2\pi}} \int_0^{2\pi} f(x) \mathbf{D}_n e^{-ix} dx \quad \forall f \in L(0 : 2\pi)$$

 **PROOF:** See Theorem 7.1 page 54. 

Example J.5 (Fourier Transform). ¹¹

E X

(1). $\{\mathbf{D}_\omega e^{ix} \mid \omega \in \mathbb{R}\}$ is a *basis* for $L^2_{\mathbb{R}}$ and

(2). $f(x) = \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} \tilde{f}(\omega) \mathbf{D}_x e^{i\omega} d\omega \quad \forall f \in L^2_{\mathbb{R}}$ where

$$\tilde{f}(\omega) \triangleq \frac{1}{\sqrt{2\pi}} \int_{\mathbb{R}} f(x) \mathbf{D}_\omega e^{-ix} dx \quad \forall f \in L^2_{\mathbb{R}}$$

Example J.6 (Gabor Transform). ¹²

E X

(1). $\left\{ \left(\mathbf{T}_\tau e^{-\pi x^2} \right) (\mathbf{D}_\omega e^{ix}) \mid \tau, \omega \in \mathbb{R} \right\}$ is a *basis* for $L^2_{\mathbb{R}}$ and

(2). $f(x) = \int_{\mathbb{R}} G(\tau, \omega) \mathbf{D}_x e^{i\omega} d\omega \quad \forall x \in \mathbb{R}, f \in L^2_{\mathbb{R}}$ where

$$G(\tau, \omega) \triangleq \int_{\mathbb{R}} f(x) \left(\mathbf{T}_\tau e^{-\pi x^2} \right) (\mathbf{D}_\omega e^{-ix}) dx \quad \forall x \in \mathbb{R}, f \in L^2_{\mathbb{R}}$$

Example J.7 (wavelets). Let $\psi(x)$ be a *wavelet*.

E X

(1). $\{\mathbf{D}^k \mathbf{T}^n \psi(x) \mid k, n \in \mathbb{Z}\}$ is a *basis* for $L^2_{\mathbb{R}}$ and

(2). $f(x) = \sum_{k \in \mathbb{Z}} \sum_{n \in \mathbb{Z}} \alpha_{k,n} \mathbf{D}^k \mathbf{T}^n \psi(x) \quad \forall f \in L^2_{\mathbb{R}}$ where

$$\alpha_n \triangleq \int_{\mathbb{R}} f(x) \mathbf{D}^k \mathbf{T}^n \psi^*(x) dx \quad \forall f \in L^2_{\mathbb{R}}$$

¹¹ cross reference: Definition 3.2 page 26

¹²  Gabor (1946),  Qian and Chen (1996) (Chapter 3),  Forster and Massopust (2009) page 32 (Definition 1.69)

APPENDIX K

CONTINUOUS RANDOM PROCESSES

K.1 Definitions

Definition K.1. ¹ Let (Ω, \mathbb{E}, P) be a PROBABILITY SPACE.

DEF

The function $x : \Omega \rightarrow \mathbb{R}$ is a **random variable**.

The function $y : \mathbb{R} \times \Omega \rightarrow \mathbb{R}$ is a **random process**.

The random process $x(t, \omega)$, where t commonly represents time and $\omega \in \Omega$ is an outcome of an experiment, can take on more specialized forms depending on whether t and ω are fixed or allowed to vary. These forms are illustrated in Figure K.1 [page 235](#)² and Figure K.2 [page 236](#).

$x(t, \omega)$	fixed t	variable t
fixed ω	number	time function
variable ω	random variable	random process

Figure K.1: Specialized forms of a random process $x(t, \omega)$

Definition K.2. ³ Let $x(t)$ and $y(t)$ be random processes.

DEF

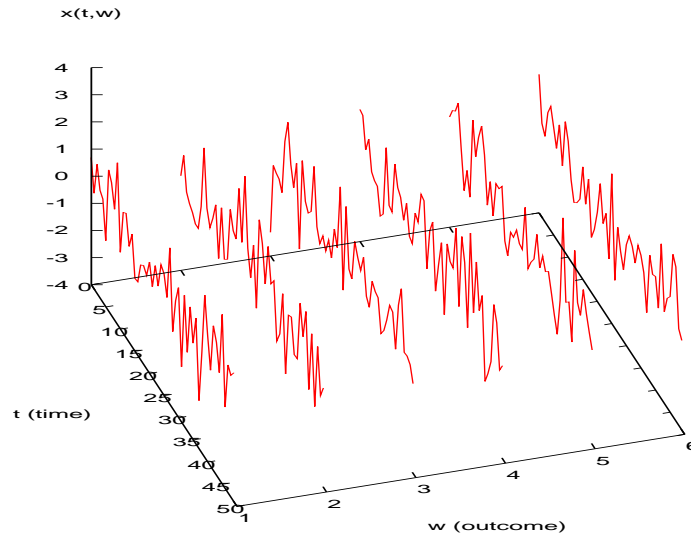
The **mean** $\mu_X(t)$ of $x(t)$ is $\mu_X(t) \triangleq E[x(t)]$

The **cross-correlation** $R_{xy}(t)$ of $x(t)$ and $y(t)$ is $R_{xy}(t, u) \triangleq E[x(t)y^*(u)]$

The **auto-correlation function** $R_{xx}(t)$ of $x(t)$ is $R_{xx}(t, u) \triangleq E[x(t)x^*(u)]$

Remark K.1. ⁴ The equation $\int_{u \in \mathbb{R}} R_{xx}(t, u)f(u) \, du$ is a *Fredholm integral equation of the first kind* and $R_{xx}(t, u)$ is the *kernel* of the equation.

¹ [Papoulis \(1991\) page 63](#), [Papoulis \(1991\) page 285](#)
² [Papoulis \(1991\) pages 285–286](#)
³ [Papoulis \(1984\) page 216](#) $\langle R_{xy}(t_1, t_2) = E\{x(t_1)y^*(t_2)\}$ (9-35)
⁴ [Fredholm \(1900\)](#), [Fredholm \(1903\) page 365](#), [Michel and Herget \(1993\) page 97](#), [Keener \(1988\) page 101](#)

Figure K.2: Example of a random process $x(t, \omega)$

K.2 Properties

Theorem K.1. Let $x(t)$ and $y(t)$ be random processes with cross-correlation $R_{xy}(t, u)$ and let $R_{xx}(t, u)$ be the auto-correlation of $x(t)$.

T H M	$R_{xx}(t, u) = R_{xx}^*(u, t)$ (CONJUGATE SYMMETRIC)
	$R_{xy}(t, u) = R_{yx}^*(u, t)$

PROOF:

$$\begin{aligned}
 R_{xx}(t, u) &\triangleq E[x(t)x^*(u)] &= E[x^*(u)x(t)] &= (E[x(u)x^*(t)])^* &\triangleq R_{xx}^*(u, t) \\
 R_{xy}(t, u) &\triangleq E[x(t)y^*(u)] &= E[y^*(u)x(t)] &= (E[y(u)x^*(t)])^* &\triangleq R_{yx}^*(u, t)
 \end{aligned}$$

⇒

APPENDIX L _____

RANDOM SEQUENCES



“We are quite in danger of sending highly trained and highly intelligent young men out into the world with tables of erroneous numbers under their arms, and with a dense fog in the place where their brains ought to be. In this century, of course, they will be working on guided missiles and advising the medical profession on the control of disease, and there is no limit to the extent to which they could impede every sort of national effort.”

Ronald A. Fisher, (1890–1962), Statistician, at a lecture in 1958 at Michigan State University ¹

L.1 Definitions

Definition L.1.

DEF A **random sequence** $x(n) \in \Omega$ is a SEQUENCE over a PROBABILITY SPACE (Ω, \mathbb{E}, P) (Definition ?? page ??).

Definition L.2. ² Let $x(n)$ and $y(n)$ be RANDOM SEQUENCES.

DEF	The mean	$\mu_X(n)$	of $x(n)$ is	$\mu_X(n) \triangleq E[x(n)]$
	The variance	$\sigma_X^2(n)$	of $x(n)$ is	$\sigma_X^2(n) \triangleq E\left([x(n) - \mu_X(n)]^2\right)$
	The cross-correlation	$R_{xy}(n, m)$	of $x(n)$ and $y(n)$ is	$R_{xy}(n, m) \triangleq E[x(n+m)y^*(n)]$
	The auto-correlation	$R_{xx}(n, m)$	of $x(n)$ is	$R_{xx}(n, m) \triangleq R_{xy}(n, m) _{y=x}$

¹quote: [Yates and Mather (1963) page 107. image: <http://www.genetics.org/content/154/4/1419>

² [Papoulis (1984) page 263 $\langle R_{xy}(m) = E\{x(m)y^*(0)\}$], [Wilks (1963) page 77 §3.4 “Moments of two-dimensional random variables”], [Cadzow (1987) page 341 $\langle r_{xy}(m) = E[x(m)y^*(0)]$], [MatLab (2018b) $\langle R_{xy}(m) = E\{x_{n+m}y_n^*\}$], [MatLab (2018a) $\langle R_{xy}(m) = E\{x_{n+m}y_n^*\}$]

L.2 Properties

Theorem L.1.

T H M	$R_{xx}(n, m) = R_{xx}^*(n + m, -m)$
	$R_{xy}(n, m) = R_{yx}^*(n + m, -m)$

PROOF:

$R_{xy}(n, m) \triangleq E[x(n+m)y^*(n)]$	by definition of $R_{xy}(n, m)$	(Definition L.2 page 237)
$= E[y^*(n)x(n+m)]$	by <i>commutative</i> property of $(\mathbb{C}, +, \cdot, 0, 1)$	(Definition A.5 page 98)
$= (E[y(n)x^*(n+m)])^*$	by <i>distributive</i> property of *-algebras	(Definition F.3 page 148)
$= (E[y(n+m-m)x^*(n+m)])^*$	by <i>additive identity</i> property of $(\mathbb{R}, +, \cdot, 0, 1)$	(Definition A.5 page 98)
$\triangleq R_{yx}^*(n+m, -m)$	by definition of $R_{xy}(n, m)$	(Definition L.2 page 237)

$R_{xx}(n, m) = R_{xy}(n, m) _{y=x}$	by $y = x$ constraint	
$= R_{xy}^*(n+m, -m) _{y=x}$	by previous result	
$= R_{xx}^*(n+m, -m)$	by $y = x$ constraint	



L.3 Wide Sense Stationary processes

Definition L.3. Let $x(n)$ be a RANDOM SEQUENCE with MEAN $\mu_X(n)$ and VARIANCE $\sigma_X^2(n)$ (Definition L.2 page 237).

D E F	$x(n)$ is wide sense stationary (WSS) if		
	1.	$\mu_X(n)$ is CONSTANT with respect to n	(STATIONARY IN THE 1ST MOMENT) and
	2.	$\sigma_X^2(n)$ is CONSTANT with respect to n	(STATIONARY IN THE 2ND MOMENT)

Definition L.4.³ Let $x(n)$ be a RANDOM SEQUENCE with statistics $\mu_X(n)$, $\sigma_X^2(n)$, $R_{xx}(n, m)$, and $R_{xy}(n, m)$ (Definition L.2 page 237).

D E F	$\{ x \text{ and } y \text{ are WIDE SENSE STATIONARY} \} \implies$			
	(1).	The mean	μ_X of $x(n)$ is	$\mu_X \triangleq E[x(0)]$
	(2).	The variance	σ_X^2 of $x(n)$ is	$\sigma_X^2 \triangleq E\left([x(0) - \mu_X]^2\right)$
	(4).	The cross-correlation	$R_{xy}(m)$ of $x(n)$ and $y(n)$ is	$R_{xy}(m) \triangleq E[x(m)y^*(0)]$
	(3).	The auto-correlation	$R_{xx}(m)$ of $x(n)$ is	$R_{xx}(m) \triangleq R_{xy}(m) _{y=x}$

Remark L.1. The $R_{xy}(n, m)$ of Definition L.2 (page 237) and the $R_{xy}(m)$ of Definition L.4 (page 238) (etc.) are examples of *function overload*—that is, functions that use the same mnemonic but are distinguished by different domains. Perhaps a more common example of function overload is the “+” mnemonic. Traditionally it is used with domain of the natural numbers \mathbb{N} as in $3 + 2$. Later it was extended for domain real numbers \mathbb{R} as in $\sqrt{3} + \sqrt{2}$, or even complex numbers \mathbb{C} as in

³ Papoulis (1984) page 263 $\langle R_{xy}(\tau) = E\{x(t+\tau)y^*(t)\} \rangle$, Cadzow (1987) page 341 $\langle r_{xy}(n) = E[x(k+n)y^*(k)] \rangle$ (10.41)

$(\sqrt{3} + i\sqrt{2}) + (e + i\pi)$. And it was even more dramatically extended for use with domain $\mathbb{R}^N \times \mathbb{R}^M$ in “linear algebra” as in

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} + \begin{bmatrix} 5 & 6 \\ 7 & 8 \end{bmatrix} = \begin{bmatrix} 6 & 8 \\ 10 & 12 \end{bmatrix}$$

*Remark L.2.*⁴ The definition for $R_{xy}(m)$ can be defined with the conjugate $*$ on either x or y , or on neither or both; and moreover x may either lead or lag y . In total, there are $2 \times 2 \times 2 = 8$ different ways to define $R_{xy}(m)$.⁵ and $R_{xx}(m)$ involve complex numbers. This may seem curious when typical ADCs provide real-valued sequences. Note however that complex-valued sequences often come up in signal processing due to some common system architectures:

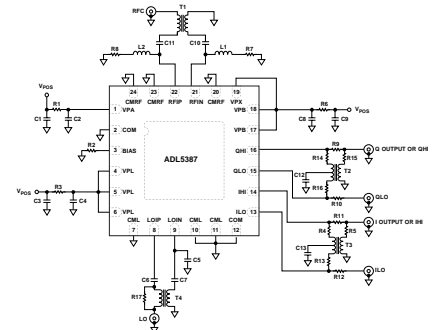
1. The presence of an *FFT* operator in the signal processing path
2. The *complex envelope* $x_l(t)$ of a modulated *narrowband* communications signal $x(t)$.
3. Communications channel processing involving phase discrimination (e.g. PSK and QAM).

In the case of a narrowband signal $x(t)$ modulated by a sinusoid at center frequency f_c , we have three canonical forms. These can be shown to be equivalent:

$$\begin{aligned} x(t) &\triangleq \underbrace{a(t)\cos[2\pi f_c t + \phi(t)]}_{\text{amplitude-phase form}} && \text{amplitude and phase form} \\ &= \underbrace{a(t)\cos[\phi(t)]}_{p(t)}\cos[2\pi f_c t] - \underbrace{a(t)\sin[\phi(t)]}_{q(t)}\sin[2\pi f_c t] && \text{by double angle formulas (Theorem D.9 page 117)} \\ &= \underbrace{p(t)\cos[2\pi f_c t] - q(t)\sin[2\pi f_c t]}_{\text{quadrature form}} && \text{quadrature form} \\ &= \mathbf{R}_e([p(t) + iq(t)][\cos(2\pi f_c t) + i\sin(2\pi f_c t)]) && \text{by definitions of } \mathbf{R}_e \\ &= \underbrace{\mathbf{R}_e[x_l(t)e^{i2\pi f_c t}]}_{\text{complex envelope form}} && \text{by Euler's identity (Theorem D.5 page 112)} \end{aligned}$$

Note that in these equivalent forms, the *complex envelope* $x_l(t)$ is conveniently represented as a *complex-valued* function in terms of the *quadrature component* $p(t)$ and the *inphase component* $q(t)$ such that $x_l(t) = p(t) + iq(t)$.

Example L.1. In practice (with real hardware), you will likely first have access to the quadrature components $p(t)$ and $q(t)$. Take for example the *Analog Devices ADL5387 Quadrature Demodulator* and evaluation board, as illustrated to the right.⁶ Note that *quadrature component* $p(t)$ is available at connector “Q OUTPUT” and *in-phase component* $q(t)$ is available at connector “I OUTPUT”.



⁴ S. Lawrence Marple (1987) pages 51–53 (“APPENDIX 2.A SOURCE OF COMPLEX-VALUED SIGNALS”), S. Lawrence Marple (2019) pages 48–50 (§“2.12 Extra: Source of Complex-Valued Signals”), Greenhoe (2019b) (Chapter 2: Narrowband Signals)

⁵ Greenhoe (2019a)

⁶ Diagram extracted from Devices (2016). Extraction notes: pdftk ADL5387.pdf cat 24 output page24.pdf

pdfcrop --margins "-50 -120 -60 -260" --clip page24.pdf image.pdf

gswin32c.exe -sDEVICE=pdfwrite -dNOPAUSE -dBATCH -dSAFER -dCompatibilityLevel=1.5 -

sOutputFile=ADL5387_page24_schematic.pdf image.pdf

Proposition L.1. Let $y(n)$ be a RANDOM SEQUENCE, $x(n)$ a RANDOM SEQUENCE with AUTO-CORRELATION $R_{xx}(n, m)$, and R_{xy} the CROSS-CORRELATION of x and y .

$$\left\{ \begin{array}{l} x \text{ and } y \text{ are} \\ \text{WIDE SENSE STATIONARY} \\ \text{(WSS) (Definition ?? page ??)} \end{array} \right\} \Rightarrow \left\{ \begin{array}{ll} R_{xx}(n, m) = R_{xx}(m) & \forall n \in \mathbb{Z} \\ R_{xy}(n, m) = R_{xy}(m) & \forall n \in \mathbb{Z} \end{array} \right\}$$

(Definition L.2 page 237) (Definition L.4 page 238)

PROOF:

$$\begin{aligned} R_{xy}(n, m) &\triangleq E[x[n+m]y^*[n]] && \text{by definition of } R_{xy}(n, m) && \text{(Definition L.2 page 237)} \\ &= E[x[n-n+m]y^*[n-n]] && \text{by wide sense stationary hypothesis} \\ &= E[x[m]y^*[0]] \\ &\triangleq R_{xy}(m) && \text{by definition of } R_{xy}(m) && \text{(Definition L.4 page 238)} \\ R_{xx}(n, m) &= R_{xy}(n, m)|_{y=x} \\ &= R_{xy}(m)|_{y=x} && \text{by previous result} \\ &= R_{xx}(m) \end{aligned}$$

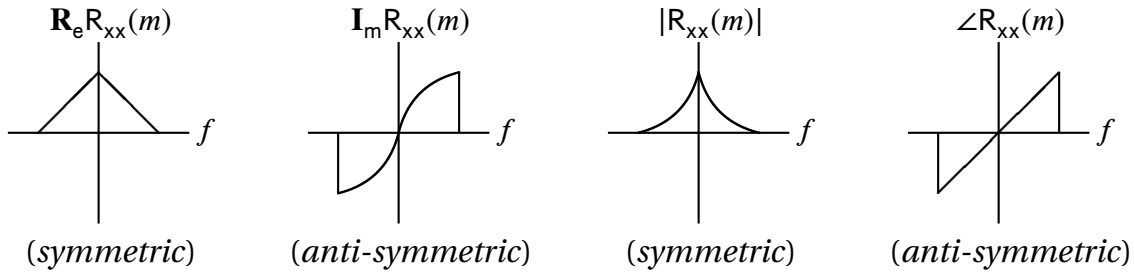


Figure L.1: auto-correlation $R_{xx}(m)$

Corollary L.1. Let $x(n)$ be a RANDOM SEQUENCE with AUTO-CORRELATION $R_{xx}(n, m)$, $y(n)$ a RANDOM SEQUENCE with AUTO-CORRELATION $R_{yy}(n, m)$, and $R_{xy}(n, m)$ the CROSS-CORRELATION of x and y . Let S be a SYSTEM with input $x(n)$ and output $y(n)$.

$$\left\{ \begin{array}{l} \text{(A). } x \text{ is WSS} \\ \text{(B). } y \text{ is WSS} \\ \text{(C). } S \text{ is LTI} \end{array} \right\} \Rightarrow \left\{ \begin{array}{lll} (1). R_{xy}(m) = R_{yx}^*(-m) & & \text{and} \\ (2). R_{xx}(m) = R_{xx}^*(-m) & \text{(CONJUGATE SYMMETRIC)} & \text{and} \\ (3). R_e R_{xx}(m) = R_e R_{xx}(-m) & \text{(SYMMETRIC)} & \text{and} \\ (4). I_m R_{xx}(m) = -I_m R_{xx}(-m) & \text{(ANTI-SYMMETRIC)} & \text{and} \\ (5). |R_{xx}(m)| = |R_{xx}(-m)| & \text{(SYMMETRIC)} & \text{and} \\ (6). \angle R_{xx}(m) = -\angle R_{xx}(-m) & \text{(ANTI-SYMMETRIC)} & \end{array} \right\}$$

PROOF:

$$\begin{aligned} R_{xy}(m) &= R_{xy}(n, m) && \text{by Proposition L.1 page 240} && \text{and hypotheses (A),(B)} \\ &= R_{yx}^*(n+m, -m) && \text{by Theorem L.1 page 238} && \text{and hypothesis (B)} \\ &= R_{yx}^*(-m) && \text{by Proposition L.1 page 240} && \text{and hypothesis (A)} \\ R_{xx}(m) &= R_{xx}(n, m) && \text{by Proposition L.1 page 240} && \text{and hypothesis (A)} \\ &= R_{xx}^*(n+m, -m) && \text{by Theorem L.1 page 238} && \text{and hypothesis (B)} \\ &= R_{xx}^*(-m) && \text{by Proposition L.1 page 240} && \text{and hypothesis (A)} \end{aligned}$$

L.4 Spectral density

Definition L.5. Let $x(n)$ and $y(n)$ be WIDE SENSE STATIONARY RANDOM SEQUENCES with auto-correlation $R_{xx}(m)$ and cross-correlation $R_{xy}(m)$. Let \mathbf{Z} be the Z-TRANSFORM OPERATOR (Definition 9.4 page 70).

DEF The **z-domain cross spectral density (CSD)** $\check{S}_{xy}(z)$ of x and y is

$$\check{S}_{xy}(z) \triangleq \mathbf{Z}R_{xy}(m) \triangleq \sum_{m \in \mathbb{Z}} R_{xy}(m)z^{-m}$$

 The **z-domain power spectral density (PSD)** $\check{S}_{xx}(z)$ of x is $\check{S}_{xx}(z) \triangleq \check{S}_{xy}(z)|_{y(n)=x(n)}$

Definition L.6. Let $x(n)$ and $y(n)$ be WIDE SENSE STATIONARY RANDOM SEQUENCES with auto-correlation $R_{xx}(m)$ and cross-correlation $R_{xy}(m)$. Let $\check{\mathbf{F}}$ be the DISCRETE TIME FOURIER TRANSFORM (DTFT) operator (Definition 8.1 page 59).

DEF The **auto-spectral density** $\check{S}_{xx}(z)$ of x is $\check{S}_{xx}(z) \triangleq \check{\mathbf{F}}R_{xx}(m) \triangleq \sum_{m \in \mathbb{Z}} R_{xx}(m)e^{-iom}$
 The **cross spectral density (CSD)** $\check{S}_{xy}(z)$ of x and y is $\check{S}_{xy}(z) \triangleq \check{\mathbf{F}}R_{xy}(m) \triangleq \sum_{m \in \mathbb{Z}} R_{xy}(m)e^{-iom}$
 The **auto-spectral density** is also called **power spectral density (PSD)**.

Theorem L.2. Let S be a system with IMPULSE RESPONSE $h(n)$, INPUT $x(n)$, and OUTPUT $y(n)$.

THM $\{ x \text{ and } y \text{ are WIDE SENSE STATIONARY} \} \implies \left\{ \begin{array}{l} (1). \check{S}_{xx}(z) = \check{S}_{xx}^*\left(\frac{1}{z^*}\right) \text{ and} \\ (2). \check{S}_{yx}(z) = \check{S}_{xy}^*\left(\frac{1}{z^*}\right) \end{array} \right\}$

PROOF:

$$\begin{aligned}
 \check{S}_{yx}(z) &\triangleq \mathbf{Z}R_{yx}(m) && \text{by definition of } \check{S}_{xy}(z) && (\text{Definition L.6 page 241}) \\
 &\triangleq \sum_{m \in \mathbb{Z}} R_{yx}(m)z^{-m} && \text{by definition of } \mathbf{Z} && (\text{Definition 9.4 page 70}) \\
 &\triangleq \sum_{m \in \mathbb{Z}} R_{xy}^*(-m)z^{-m} && \text{by Corollary L.1 page 240} \\
 &= \left[\sum_{m \in \mathbb{Z}} R_{xy}(-m)(z^*)^{-m} \right]^* && \text{by antiautomorphic property of } ^* \text{-algebras} && (\text{Definition F.3 page 148}) \\
 &= \left[\sum_{-p \in \mathbb{Z}} R_{xy}(p)(z^*)^p \right]^* && \text{where } p \triangleq -m && \implies m = -p \\
 &= \left[\sum_{p \in \mathbb{Z}} R_{xy}(p)(z^*)^p \right]^* && \text{by absolutely summable property} && (\text{Definition 9.2 page 69}) \\
 &= \left[\sum_{p \in \mathbb{Z}} R_{xy}(p)\left(\frac{1}{z^*}\right)^{-p} \right]^* \\
 &= \check{S}_{xy}^*\left(\frac{1}{z^*}\right) && \text{by definition of } \mathbf{Z} && (\text{Definition 9.4 page 70}) \\
 \check{S}_{xx}(z) &= \check{S}_{xy}(z)|_{y=x} \\
 &= \check{S}_{yx}^*(z)|_{y=x} \\
 &= \check{S}_{xy}^*\left(\frac{1}{z^*}\right)|_{y=x} && \text{by (2)—previous result}
 \end{aligned}$$

$$= \check{S}_{xx}^* \left(\frac{1}{z^*} \right)$$



Corollary L.2. Let S be a system with IMPULSE RESPONSE $h(n)$, INPUT $x(n)$, and OUTPUT $y(n)$.

COR	$\left\{ \begin{array}{l} \text{(A). } h \text{ is LTI and} \\ \text{(B). } x \text{ and } y \text{ are WSS} \end{array} \right\} \implies \left\{ \begin{array}{l} \text{(1). } \check{S}_{xy}^*(\omega) = \check{S}_{yx}(\omega) \quad (\text{CONJUGATE-SYMMETRIC}) \quad \text{and} \\ \text{(2). } \check{S}_{xx}^*(\omega) = \check{S}_{xx}(\omega) \quad (\text{CONJUGATE SYMMETRIC}) \quad \text{and} \\ \text{(3). } \check{S}_{xx}(\omega) \in \mathbb{R} \quad (\text{REAL-VALUED}) \end{array} \right\}$
------------	---

PROOF:

$\begin{aligned} \check{S}_{xy}^*(\omega) &= \check{S}_{xy}^*(z) \Big _{z=e^{i\omega}} \\ &= \check{S}_{yx}^* \left(\frac{1}{z^*} \right) \Big _{z=e^{i\omega}} \\ &= \check{S}_{yx} \left(\frac{1}{z^*} \right) \Big _{z=e^{i\omega}} \\ &= \check{S}_{yx} \left(\frac{1}{e^{i\omega^*}} \right) \\ &= \check{S}_{yx}(e^{i\omega}) \\ &= \check{S}_{yx}(\omega) \end{aligned}$	<p>by definition of <i>DTFT</i></p> <p>by Theorem L.2 page 241</p> <p>by <i>involutory</i> property of *-algebras</p>	<p>(Definition 8.1 page 59)</p>
$\begin{aligned} \check{S}_{xx}^*(\omega) &= \check{S}_{xx}^*(z) \Big _{z=e^{i\omega}} \\ &= \check{S}_{xx}^* \left(\frac{1}{z^*} \right) \Big _{z=e^{i\omega}} \\ &= \check{S}_{xx} \left(\frac{1}{z^*} \right) \Big _{z=e^{i\omega}} \\ &= \check{S}_{xx} \left(\frac{1}{e^{i\omega^*}} \right) \\ &= \check{S}_{xx}(e^{i\omega}) \\ &= \check{S}_{xx}(\omega) \end{aligned}$	<p>by definition of <i>DTFT</i></p> <p>by Theorem L.2 page 241</p> <p>by <i>involutory</i> property of *-algebras</p>	<p>(Definition 8.1 page 59)</p> <p>(Definition 8.1 page 59)</p> <p>(Definition F.3 page 148)</p>
$\begin{aligned} \check{S}_{xx}^*(\omega) &= \check{S}_{xy}^*(\omega) \Big _{y=x} \\ &= \check{S}_{yx}(\omega) \Big _{y=x} \\ &= \check{S}_{xx}(\omega) \end{aligned}$	<p>by definition of <i>DTFT</i></p> <p>by previous result</p>	<p>(Definition 8.1 page 59)</p>



L.5 Spectral Power

The term “*spectral power*” is a bit of an oxymoron because “spectral” deals with leaving the time-domain for the frequency-domain, howbeit the concept of power is solidly founded on the concept of time in that power = energy per time.

However, the *Plancherel Formula*, or more generally *Parseval's Identity* (Proposition H.2 page 194), demonstrates that power in time can also be calculated in frequency.⁷ So, it makes some sense to speak of the term “spectral power”. Moreover, one way to estimate this power is to average the Fourier Transforms of the product $|x(n)|^2 = x(n)x^*(n)$...that is, to use an estimate of the auto-spectral density $\check{S}_{xx}(\omega)$. Thus, an alternate name for *auto-spectral density* is **power spectral density** (PSD).

⁷<https://math.stackexchange.com/questions/3785037/>

APPENDIX M

SPECTRAL THEORY

M.1 Operator Spectrum

Definition M.1. ¹ Let $\mathbf{A} \in \mathcal{B}(\mathbf{X}, \mathbf{Y})$ be an operator over the linear spaces $\mathbf{X} = (X, F, \oplus, \otimes)$ and $\mathbf{Y} \triangleq (Y, F, \oplus, \otimes)$. Let $\mathcal{N}(\mathbf{A})$ be the NULL SPACE of \mathbf{A} .


DEF An **eigenvalue** of \mathbf{A} is any value λ such that there exists \mathbf{x} such that $\mathbf{A}\mathbf{x} = \lambda\mathbf{x}$.
 The **eigenspace** H_λ of \mathbf{A} at eigenvalue λ is $\mathcal{N}(\mathbf{A} - \lambda\mathbf{I})$.
 An **eigenvector** of \mathbf{A} associated with eigenvalue λ is any element of $\mathcal{N}(\mathbf{A} - \lambda\mathbf{I})$.

Example M.1. ² Let \mathbf{D} be the differential operator.

EX The set $\{e^{\lambda x} | \lambda \in \mathbb{C}\}$ are the eigenvectors of \mathbf{D} .
 $\rho(\mathbf{D}) = \emptyset$ (\mathbf{D} has no non-spectral points whatsoever)
 $\sigma_p(\mathbf{D}) = \sigma(\mathbf{D})$ (the spectrum of \mathbf{D} is all eigenvalues)
 $\sigma_c(\mathbf{D}) = \emptyset$ (\mathbf{D} has no continuous spectrum)
 $\sigma_r(\mathbf{D}) = \emptyset$ (\mathbf{D} has no resolvent spectrum)


 **PROOF:**

$$\begin{aligned} (\mathbf{D} - \lambda\mathbf{I})e^{\lambda x} &= \mathbf{D}e^{\lambda x} - \lambda\mathbf{I}e^{\lambda x} \\ &= \lambda e^{\lambda x} - \lambda e^{\lambda x} \\ &= 0 \end{aligned} \quad \forall \lambda \in \mathbb{C}$$

This theorem and proof needs more work and investigation to prove/disprove its claims. 

Definition M.2. ³ Let $\mathbf{A} \in \mathcal{B}(\mathbf{X}, \mathbf{Y})$ be an operator over the linear spaces $\mathbf{X} = (X, F, \oplus, \otimes)$ and $\mathbf{Y} \triangleq (Y, F, \oplus, \otimes)$.

¹  Bollobás (1999) page 168,  Descartes (1637a),  Descartes (1954),  Cayley (1858),  Hilbert (1904) page 67,  Hilbert (1912),

²  Pedersen (2000) page 79

³  Michel and Herget (1993) page 439

quantity	$\mathcal{N}(\mathbf{A} - \lambda\mathbf{I}) = \{0\}$ ($x = 0$ is the only solution)	$\overline{\mathcal{R}(\mathbf{A} - \lambda\mathbf{I})} = \mathbf{X}$ (dense)	$(\mathbf{A} - \lambda\mathbf{I})^{-1} \in \mathcal{B}(\mathbf{X}, \mathbf{Y})$ (continuous/bounded)
$\rho(\mathbf{A})$ (resolvent set)	1	1	1
$\sigma_p(\mathbf{A})$ (point spectrum)	0		
$\sigma_r(\mathbf{A})$ (residual spectrum)	1	0	
$\sigma_c(\mathbf{A})$ (continuous spectrum)	1	1	0

Table M.1: Spectrum of an operator \mathbf{A}

The **resolvent set** $\rho(\mathbf{A})$ of operator \mathbf{A} is defined as

$$\rho(\mathbf{A}) \triangleq \left\{ \lambda \in F \mid \begin{array}{ll} 1. \mathcal{N}(\mathbf{A} - \lambda\mathbf{I}) = \{0\} & \text{(no non-zero eigenvectors)} \\ 2. \overline{\mathcal{R}(\mathbf{A} - \lambda\mathbf{I})} = \mathbf{X} & \text{(the range is dense in } \mathbf{X} \text{).} \\ 3. (\mathbf{A} - \lambda\mathbf{I})^{-1} \in \mathcal{B}(\mathbf{X}, \mathbf{Y}) & \text{(inverse is continuous/bounded).} \end{array} \right\}$$

The **spectrum** $\sigma(\mathbf{A})$ of operator \mathbf{A} is defined as

$$\sigma(\mathbf{A}) \triangleq F \setminus \rho(\mathbf{A}).$$

Definition M.3. ⁴ Let $\mathbf{A} \in \mathcal{B}(\mathbf{X}, \mathbf{Y})$ be an operator over the linear spaces $\mathbf{X} = (X, F, \oplus, \otimes)$ and $\mathbf{Y} \triangleq (Y, F, \oplus, \otimes)$.

The **point spectrum** $\sigma_p(\mathbf{A})$ of operator \mathbf{A} is defined as

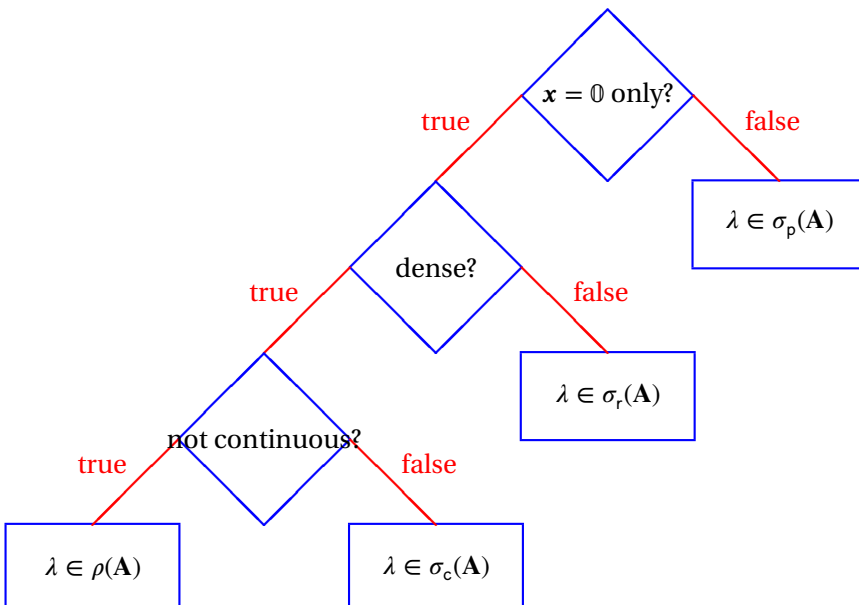
$$\sigma_p(\mathbf{A}) \triangleq \left\{ \lambda \in F \mid 1. \mathcal{N}(\mathbf{A} - \lambda\mathbf{I}) \supsetneq \{0\} \quad \text{(has non-zero eigenvector)} \right\}$$

The **residual spectrum** $\sigma_r(\mathbf{A})$ of operator \mathbf{A} is defined as

$$\sigma_r(\mathbf{A}) \triangleq \left\{ \lambda \in F \mid \begin{array}{ll} 1. \mathcal{N}(\mathbf{A} - \lambda\mathbf{I}) = \{0\} & \text{(no non-zero eigenvectors)} \\ 2. \overline{\mathcal{R}(\mathbf{A} - \lambda\mathbf{I})} \neq \mathbf{X} & \text{(not dense in } \mathbf{X} \text{—has gaps).} \end{array} \right\}$$

The **continuous spectrum** $\sigma_c(\mathbf{A})$ of operator \mathbf{A} is defined as

$$\sigma_c(\mathbf{A}) \triangleq \left\{ \lambda \in F \mid \begin{array}{ll} 1. \mathcal{N}(\mathbf{A} - \lambda\mathbf{I}) = \{0\} & \text{(no non-zero eigenvectors)} \\ 2. \overline{\mathcal{R}(\mathbf{A} - \lambda\mathbf{I})} = \mathbf{X} & \text{(dense in } \mathbf{X} \text{).} \\ 3. (\mathbf{A} - \lambda\mathbf{I})^{-1} \notin \mathcal{B}(\mathbf{X}, \mathbf{Y}) & \text{(not continuous / not bounded)} \end{array} \right\}$$



The spectral components' definitions are illustrated in the figure to the left and summarized in Table M.1 (page 244). Let a family of operators $\mathbf{B}(\lambda)$ be defined with respect to an operator \mathbf{A} such that $\mathbf{B}(\lambda) \triangleq (\mathbf{A} - \lambda\mathbf{I})$. Normally, we might expect a “normal” or “regular” or even “mundane” operator $\mathbf{B}(\lambda)$ to have the properties

1. $\mathbf{B}(\lambda)\mathbf{x} = 0$ if and only if $\mathbf{x} = 0$
2. $\mathbf{B}(\lambda)\mathbf{x}$ spans virtually all of \mathbf{X} as we vary \mathbf{x}
3. $\mathbf{B}^{-1}(\lambda)$ is continuous.

After all, these are the properties that we would have if $\mathbf{B}(\lambda)$ were simply an affine operator in the

⁴ Bollobás (1999) page 168, Hilbert (1906) pages 169–172

field of real numbers— such as $[\mathbf{B}(\lambda)](x) \triangleq [\lambda](x) = \lambda x$ which is 0 if and only if $x = 0$, has range $\mathcal{R}(\lambda) = \mathbb{R}$, and its inverse $\lambda^{-1}x$ is continuous.

If for some λ the operator $\mathbf{B}(\lambda)$ does have all these “regular” properties, then that λ part of the *resolvent set* of \mathbf{A} and λ is called *regular*. However if for some λ the operator $\mathbf{B}(\lambda)$ fails any of these conditions, then that λ part of the *spectrum* of \mathbf{A} . And which conditions it fails determines which component of the spectrum it is in.

Theorem M.1. ⁵ Let $\mathbf{A} \in \mathcal{B}(\mathbf{X}, \mathbf{Y})$ be an operator.

$$\sigma(\mathbf{A}) = \sigma_p(\mathbf{A}) \cup \sigma_c(\mathbf{A}) \cup \sigma_r(\mathbf{A})$$

Theorem M.2 (Spectral Theorem). ⁶ Let $\mathbf{N} \in Y^X$ be an operator.

$$\left. \begin{array}{l} \text{(A). } \underbrace{\mathbf{N}^*\mathbf{N} = \mathbf{N}\mathbf{N}^*}_{\mathbf{N} \text{ is NORMAL}} \\ \text{(B). } \mathbf{N} \text{ is COMPACT} \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} \text{(1). } \mathbf{N} = \sum_n \lambda_n \mathbf{P}_n \\ \text{(2). } \sum_n \mathbf{P}_n = \mathbf{I} \\ \text{(3). } \mathbf{P}_n \mathbf{P}_m = \delta_{n-m} \mathbf{P}_n \\ \text{(4). } \dim(\mathbf{H}_n) < \infty \\ \text{(5). } \left| \{ \lambda_n | \lambda_n \neq 0 \} \right| \text{ is COUNTABLY INFINITE} \end{array} \right.$$

where

$$\begin{aligned} (\lambda_n)_{n \in \mathbb{Z}} &\triangleq \sigma_p(\mathbf{N}) && \text{(eigenvalues of } \mathbf{N}) \\ \mathbf{H}_n &\triangleq \mathcal{N}(\mathbf{N} - \lambda_n \mathbf{I}) && (\lambda_n \text{ is the eigenspace of } \mathbf{N} \text{ at } \lambda_n \text{ in } \mathbf{Y}) \\ \mathbf{H}_n &= \mathbf{P}_n \mathbf{Y} && (\mathbf{P}_n \text{ is the projection operator that generates } \mathbf{H}_n) \end{aligned}$$

M.2 Fredholm kernels

Definition M.4. ⁷

A **Fredholm operator** \mathbf{K} is defined as

$$[\mathbf{K}f](t) \triangleq \underbrace{\int_a^b \underbrace{\kappa(t, s)}_{\text{kernel}} f(s) \, ds}_{\text{Fredholm integral equation of the first kind}^8} \quad \forall f \in L_2([a, b])$$

Example M.2. Examples of Fredholm operators include

1. Fourier Transform $[\tilde{\mathbf{F}}x](f) = \int_t x(t) e^{-i2\pi f t} \, dt \quad \kappa(t, f) = e^{-i2\pi f t}$
2. Inverse Fourier Transform $[\tilde{\mathbf{F}}^{-1}\tilde{x}](t) = \int_f \tilde{x}(f) e^{i2\pi f t} \, df \quad \kappa(f, t) = e^{i2\pi f t}$
3. Laplace operator $[\mathbf{L}x](s) = \int_t x(t) e^{-st} \, dt \quad \kappa(t, s) = e^{-st}$
4. autocorrelation operator $[\mathbf{R}x](t) = \int_s R(t, s)x(s) \, ds \quad \kappa(t, s) = R(t, s)$

Theorem M.3. Let \mathbf{K} be a Fredholm operator with kernel $\kappa(t, s)$ and adjoint \mathbf{K}^* .

$$[\mathbf{K}f](t) = \int_A \kappa(t, s)f(s) \, ds \quad \Longleftrightarrow \quad [\mathbf{K}^*f](t) = \int_A \kappa^*(s, t)f(s) \, ds$$

⁵ Michel and Herget (1993) page 440

⁶ Michel and Herget (1993) page 457, Bollobás (1999) page 200, Hilbert (1906), Hilbert (1912), von Neumann (1929), de Witt (1659)

⁷ Michel and Herget (1993) page 425

⁸The equation $\int_u \kappa(t, s)f(s) \, ds$ is a **Fredholm integral equation of the first kind** and $\kappa(t, u)$ is the **kernel** of the equation. References: Fredholm (1900), Fredholm (1903) page 365, Michel and Herget (1993) page 97, Keener (1988) page 101

✎ PROOF:

$$\begin{aligned}
 [\mathbf{K}f](t) &= \int_A \kappa(t, s) f(s) \, ds \\
 \Leftrightarrow \langle [\mathbf{K}f](t) \mid g(t) \rangle &= \left\langle \int_s \kappa(t, s) f(s) \, ds \mid g(t) \right\rangle && \text{by left hypothesis} \\
 &= \int_s f(s) \langle \kappa(t, s) \mid g(t) \rangle \, ds && \text{by additivity property of } \langle \Delta \mid \nabla \rangle \\
 &= \int_s f(s) \langle g(t) \mid \kappa(t, s) \rangle^* \, ds && \text{by conjugate symmetry property of } \langle \Delta \mid \nabla \rangle \\
 &= \langle f(s) \mid \langle g(t) \mid \kappa(t, s) \rangle \rangle && \text{by local definition of } \langle \Delta \mid \nabla \rangle \\
 &= \left\langle f(s) \mid \underbrace{\int_t \kappa^*(t, s) g(t) \, dt}_{[\mathbf{K}^*g](s)} \right\rangle && \text{by local definition of } \langle \Delta \mid \nabla \rangle \\
 \Leftrightarrow [\mathbf{K}^*g](s) &= \int_A \kappa^*(t, s) g(t) \, dt && \text{by right hypothesis} \\
 \Leftrightarrow [\mathbf{K}^*g](\sigma) &= \int_A \kappa^*(\tau, \sigma) g(\tau) \, d\tau && \text{by change of variable: } \tau = t, \sigma = s \\
 \Leftrightarrow [\mathbf{K}^*f](t) &= \int_A \kappa^*(s, t) f(s) \, ds && \text{by change of variable: } t = \sigma, s = \tau, f = g
 \end{aligned}$$

⇒

Corollary M.1. ⁹ Let \mathbf{K} be an Fredholm operator with kernel $\kappa(t, s)$ and adjoint \mathbf{K}^* .

C O R	$ \underbrace{\mathbf{K} = \mathbf{K}^*}_{\mathbf{K} \text{ is self-adjoint}} \quad \Leftrightarrow \quad \underbrace{\kappa(t, s) = \kappa^*(s, t)}_{\text{kernel is conjugate symmetric}} $
----------------------	---

✎ PROOF:

$$\begin{aligned}
 \mathbf{K} = \mathbf{K}^* &\Leftrightarrow \int_A \kappa(t, s) f(s) \, ds = \int_A \kappa^*(s, t) f(s) \, ds && \text{by Theorem M.3 page 245} \\
 &\Leftrightarrow \kappa(t, s) = \kappa^*(s, t)
 \end{aligned}$$

⇒

Theorem M.4 (Mercer's Theorem). ¹⁰ Let \mathbf{K} be an Fredholm operator with kernel $\kappa(t, s)$ and eigen-system $((\lambda_n, \phi_n(t)))_{n \in \mathbb{Z}}$.

T H M	$ \left\{ \begin{array}{l} \text{(A). } \underbrace{\int_a^b \int_a^b \kappa(t, s) f(t) f^*(s) \, dt}_{\text{positive}} \geq 0 \quad \text{and} \\ \text{(B). } \kappa(t, s) \text{ is CONTINUOUS on } [a : b] \times [a : b] \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} \text{(1). } \kappa(t, s) = \sum_n \lambda_n \phi_n(t) \phi_n^*(s) \quad \text{and} \\ \text{(2). } \kappa(t, s) \text{ CONVERGES ABSOLUTELY and UNIFORMLY on } [a : b] \times [a : b] \end{array} \right\} $
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⁹ Michel and Herget (1993) page 430

¹⁰ Gohberg et al. (2003) page 198, Courant and Hilbert (1930) pages 138–140, Mercer (1909) page 439

Back Matter



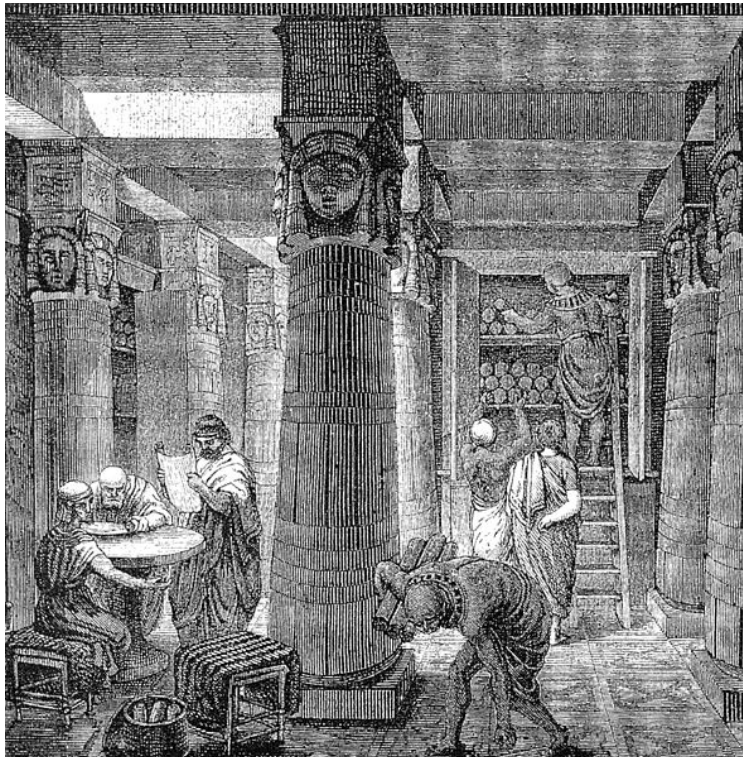
“It appears to me that if one wants to make progress in mathematics, one should study the masters and not the pupils.”

Niels Henrik Abel (1802–1829), Norwegian mathematician ¹¹

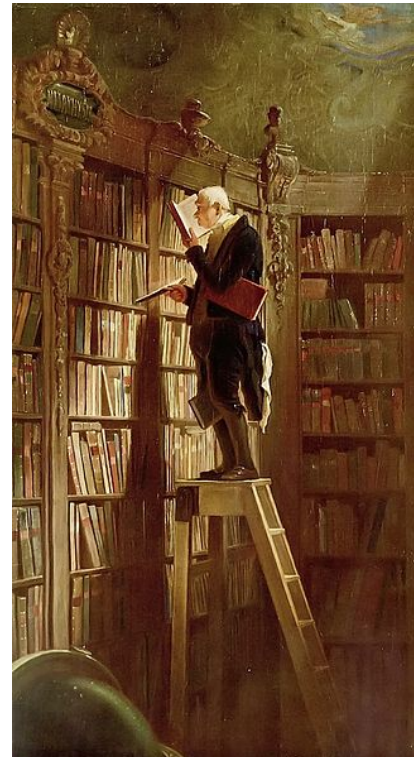


“When evening comes, I return home and go to my study. On the threshold I strip naked, taking off my muddy, sweaty workaday clothes, and put on the robes of court and palace, and in this graver dress I enter the courts of the ancients and am welcomed by them, and there I taste the food that alone is mine, and for which I was born. And there I make bold to speak to them and ask the motives of their actions, and they, in their humanity reply to me. And for the space of four hours I forget the world, remember no vexation, fear poverty no more, tremble no more at death; I pass indeed into their world.”

Niccolò Machiavelli (1469–1527), Italian political philosopher, in a 1513 letter to friend Francesco Vettori. ¹²



ancient library of Alexandria



The Book Worm by Carl Spitzweg, circa 1850

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¹¹ quote: [Simmons \(2007\)](#) page 187.

image: http://en.wikipedia.org/wiki/Image:Niels_Henrik_Abel.jpg, public domain

¹² quote: [Machiavelli \(1961\)](#) page 139?.

image: http://commons.wikimedia.org/wiki/File:Santi_di_Tito_-_Niccolo_Machiavelli%27s_portrait_headcrop.jpg, public domain

¹³ <http://en.wikipedia.org/wiki/File:Ancientlibraryalex.jpg>, public domain http://en.wikipedia.org/wiki/File:Carl_Spitzweg_021.jpg, public domain



“To sit alone in the lamplight with a book spread out before you, and hold intimate converse with men of unseen generations—such is a pleasure beyond compare.”

[Yoshida Kenko \(Urabe Kaneyoshi\)](#) (1283? – 1350?), Japanese author and Buddhist monk ¹⁴

¹⁴ quote: [Kenko \(circa 1330\)](#)
image: http://en.wikipedia.org/wiki/Yoshida_Kenko

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