# Calculus 3 Study Guide

# **Coordinate Systems**

## **Polar Coordinates**

#### Note:

Polar coordinates describe a point in 2D space using two values:

- r: the distance from the origin
- $\theta$ : the angle from the positive x-axis

This system is ideal for problems with circular or rotational symmetry, such as spirals or radial fields.

#### Polar to Cartesian

- $x = r \cos \theta$
- $y = r \sin \theta$

### Cartesian to Polar

- $r = \sqrt{x^2 + y^2}$
- $\tan \theta = \frac{x}{y} \to \theta = \tan^{-1} \left(\frac{x}{y}\right)$

**Example 1:** Convert the Cartesian point (3,3) into Polar coordiantes.

$$r = \sqrt{x^2 + y^2} = \sqrt{3^2 + 3^2} = \sqrt{18} = 3\sqrt{2}$$
  
 $\theta = \tan^{-1}\left(\frac{x}{y}\right) = \tan^{-1}\left(\frac{3}{3}\right) = \tan^{-1}(1) = \frac{\pi}{4}$   
**Answer:**  $(3\sqrt{2}, \frac{\pi}{4})$ 

**Example 2:** Convert the Polar point  $(2, \frac{\pi}{3})$  to Cartesian coordinates.

$$x = r\cos\theta = 2\cos\left(\frac{\pi}{3}\right) = 2 \cdot \frac{1}{2} = 1$$
$$y = r\sin\theta = 2\sin\left(\frac{\pi}{3}\right) = 2 \cdot \frac{\sqrt{3}}{2} = \sqrt{3}$$

Answer:  $(1, \sqrt{3})$ 

# **Cylindrical Coordinates**

#### Note

Polar coordinates describe a point in 3D space using three values:

- r: The distance from the origin in the xy-plane
- $\theta$ : The angle from the positive x-axis in the xy-plane (same as polar coordinates)
- z: The height above (or below) the xy-plane

This system is useful for objects with circular symmetry around the z-axis, like cylinders and spirals.

## Cylindrical to Cartesian

- $x = r \cos \theta$
- $y = r \sin \theta$
- $\bullet$  z=z

## Cartesian to Cylindrical

- $r = \sqrt{x^2 + y^2}$
- $\tan \theta = \frac{x}{y} \to \theta = \tan^{-1} \left(\frac{x}{y}\right)$
- $\bullet$  z=z

## **Spherical Coordinates**

## Note:

Spherical coordinates describe a point in 3D space using three values:

- $\rho$ : the ditance from the origin
- $\theta$ : the angle from the positive x-axis in the xy-plane (same as polar coordinates)
- $\phi$ : the angle from the postive z-axis down to the point

This system is useful for problems with radial symmetry, like spheres and cones.

## Spherical to Cartesian

- $x = \rho \sin \phi \cos \theta$
- $y = \rho \sin \phi \sin \theta$
- $z = \rho \cos \phi$

## Cartesian to Spherical

- $\bullet \ \rho = \sqrt{x^2 + y^2 + z^2}$
- $\tan \theta = \frac{x}{y} \to \theta = \tan^{-1} \left(\frac{x}{y}\right)$
- $\phi = \arccos\left(\frac{z}{\sqrt{x^2 + y^2 + z^2}}\right)$