Table of Contents

List of Symbols **12**

List of Abbreviations **15**

1 Introduction **17**
1.1 Historical Notes 17
1.2 Overview of the Work 20
1.3 Contributions of the Author 21
1.4 Related Publications 22

2 Digital Waveguide Modeling **25**
2.1 Waveguide Modeling of Strings 25
2.1.1 Wave Equation and the Traveling Wave Solution 25
2.1.2 Incorporating Losses and Dispersion 26
2.1.3 Karplus–Strong Algorithm and Its Extensions 27
2.1.4 Calibration of the Waveguide String Model 29
2.1.5 Excitation Signal of the Waveguide String Model 32
2.1.6 Discussion 33
2.2 Waveguide Modeling of Cylindrical Tubes 34
2.2.1 The One-Dimensional Wave Equation 35
2.2.2 A Model Composed of Coupled Uniform Tube Sections 35
2.2.3 KL Scattering Junction for Volume Velocity Waves 36
2.2.4 KL Scattering Junction for Pressure Waves 38
2.2.5 Boundary Conditions of a Cylindrical Tube 39
2.2.6 General Properties of the Cylindrical Tube Model 40
2.2.7 Sparse Tube Model 41
2.2.8 Extensions to the Basic KL Model 42
2.3 Junction of Three Acoustic Tubes 42
2.3.1 Three-Port Scattering Junction for Volume Velocity 43
2.3.2 Three-Port Scattering Junction for Sound Pressure 44
2.3.3 Side Branch in a Uniform Tube 45
2.4 Waveguide Modeling of Conical Tubes 48
2.4.1 Traveling Wave Solution for Spherical Waves 49
2.4.2 Junction of Conical Tube Sections 50
2.4.3 Reflection Function with Taper Discontinuity Only 52
2.4.4 Closed and Open End of a Truncated Conical Tube 53
2.4.5 Discrete-Time Reflection and Transmission Filters 54
2.4.6 Stability of the Reflection Filter 56
2.4.7 Modeling the Ends of a Conical Tube 56
2.4.8 Conclusions and Discussion 57
2.5 Waveguide Models for Wind Instruments 58
2.5.1 Need for Finger-Hole Models 59
2.5.2 Modeling of a Single Woodwind Finger Hole 59
2.5.3 Discrete-Time Scattering Junction 61
2.6 Relation to Other Methods 62

2.6.1 Comparison of Waveguide Filters and Wave Digital Filters 63
2.6.2 Reverberation and Simulation of Room Acoustics 63
2.7 Conclusions 64

3 Fractional Delay Filters 65
3.1 Ideal Fractional Delay 65
3.1.1 Continuous-Time System for Arbitrary Delay 65
3.1.2 Discrete-Time System for Arbitrary Delay 66
3.1.3 Fractional Delay and Shannon Reconstruction 68
3.1.4 Characteristics of the Ideal Fractional Delay Element 69
3.1.5 Conclusion and Discussion 71
3.2 Design Methods for Fractional Delay FIR Filters 71
3.2.1 Least Squared Integral Error Design 72
3.2.2 LS Design with Reduced Bandwidth 75
3.2.3 Windowing the Ideal Impulse Response 75
3.2.4 General Least Squares FIR Approximation of a Complex Frequency Response 76
3.2.5 Minimax Design of FIR FD Filters 79
3.2.6 Other Methods for the Design of FIR FD Filters 81
3.3 Maximally Flat FD FIR Filter: Lagrange Interpolation 82
3.3.1 Derivation of the Maximally Flat Fractional Delay FIR Filter 82
3.3.2 Classical Approach 84
3.3.3 Symmetry of the Lagrange Interpolation Coefficients 85
3.3.4 Computation of Coefficients for a Lagrange Interpolator 86
3.3.5 Windowing Approach to Lagrange Interpolation 87
3.3.6 Approximation Errors of Lagrange Interpolation 90
3.3.7 Farrow Structure of Lagrange Interpolation 95
3.3.8 Related Polynomial Interpolation Techniques 102
3.3.9 Conclusion and Discussion 103
3.4 Design Methods for Fractional Delay Allpass Filters 105
3.4.1 Properties of the Discrete-Time Allpass Filter 105
3.4.2 Design of Fractional Delay Allpass Filters 106
3.4.3 Maximally Flat Group Delay Design of FD Allpass Filters 107
3.4.4 Choice of Optimal Range for D in the Thiran Interpolator 110
3.4.5 Discussion 113
3.5 Time-Varying Fractional Delay Filters 114
3.5.1 Consequences of Changing Filter Coefficients 114
3.5.2 Implementation of a Variable Delay Using FIR Filters 114
3.5.3 Transients in Time-Varying Recursive FD Filters 116
3.5.4 Transient Elimination Methods for Time-Varying Recursive Filters 117
3.5.5 A Novel and Efficient Method for Elimination of Transients 121
3.5.6 Examples with a Time-Varying Thiran Allpass Filter 125
3.6 Conclusions 126

4 Fractional Delay Waveguide Filters 128
4.1 Deinterpolation 128
4.1.1 Introduction to Deinterpolation 128
4.1.2 Deinterpolation Versus Interpolation 130
4.1.3 Implementing Deinterpolation Using an FIR Filter 131
4.1.4 Adding a Signal to a Fractional Point of a Delay Line Using an FIR Deinterpolator 133
4.1.5 Discussion 134
4.2 Fractional Delay Waveguide Systems 135
4.2.1 Variable-Length Digital Waveguide 135
4.2.2 Connecting Waveguides at Arbitrary Points 136
4.3 Interpolated Waveguide Tube Model 137
4.3.1 Interpolated Scattering Junction 138
4.3.2 Implementing the FD Scattering Junction Using FIR Filters 140
4.3.3 Transfer Functions of FIR Interpolators and Deinterpolators 142
4.3.4 Choice of FIR FD Filter Design 144
4.3.5 Reflection and Transmission Functions 145
4.3.6 Analysis of Errors Due to FD Approximation 148
4.3.7 Simulation of a Two-Tube System Using FIR FD Filters 150
4.3.8 Conclusion 153
4.4 Interpolated Finger-Hole Model 153
4.4.1 FIR-Type Fractional-Delay Finger-Hole Model 154
4.4.2 Approximation Error Due to FD Filters 155
4.4.3 Implementation Issues 157
4.5 Fractional Delay Operations with Allpass Filters 158
4.5.1 Implementing a Variable Delay Line Using an Allpass Filter 158
4.5.2 Implementing Interpolation and Deinterpolation with Allpass Filters 159
4.6 Interpolated Waveguide Model: Allpass Filter Approach 160
4.6.1 Derivation of the Allpass Fractional Delay Junction 160
4.6.2 Approximation Errors due to an Allpass Fractional Delay Junction 162
4.6.3 Simulation of a Two-Tube Model with Allpass Filters 163
4.6.4 Alternative Allpass Filter Structure 165
4.7 Allpass Fractional Delay Finger-Hole Model 166
4.8 Conclusions 168

5 Conclusions and Further Research 169
5.1 Summary and Conclusions 169
5.2 Suggestions for Future Work 170

References 172

Appendix A. Bandlimited Squared Integral Error of FIR FD Filters 184

Appendix B. Effective Length of the Infinite Impulse Response 186

Index 193