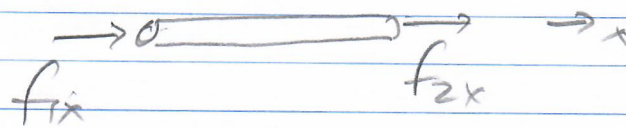


Step 4 - Element Stiffness matrix
(or element equations)

$$T = \sigma \cdot A$$

$$T = A E \left(\frac{u_2 - u_1}{L} \right)$$



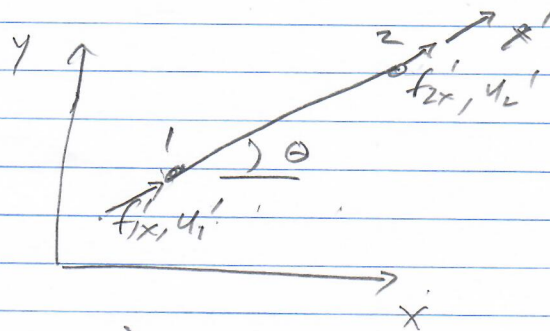
$$f_{1x} = -T = - \left(\frac{AE}{L} \right) (u_2 - u_1)$$

$$f_{2x} = T = \left(\frac{AE}{L} \right) (u_2 - u_1)$$

Matrix form

$$\begin{Bmatrix} f_{1x} \\ f_{2x} \end{Bmatrix} = \left(\frac{AE}{L} \right) \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{Bmatrix} u_1 \\ u_2 \end{Bmatrix}$$

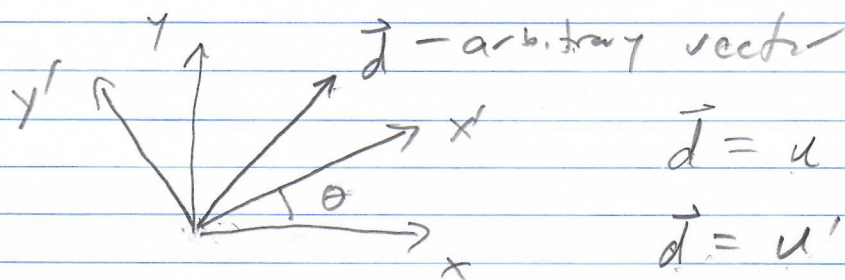
2-D (Plane) Truss



$$\begin{Bmatrix} f_{1x} \\ f_{1y} \\ f_{2x} \\ f_{2y} \end{Bmatrix} = \begin{bmatrix} ? \\ ? \\ ? \\ ? \end{bmatrix} \begin{Bmatrix} u_1 \\ v_1 \\ u_2 \\ v_2 \end{Bmatrix}$$

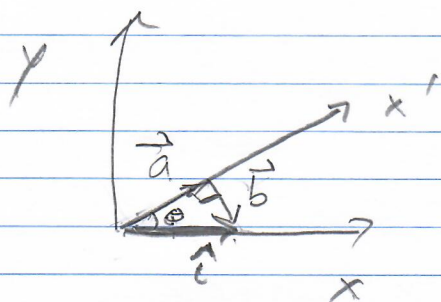
[K]

2-D vector transformation.



$$\vec{d} = u \hat{i} + v \hat{j}$$

$$\vec{d} = u' \hat{i}' + v' \hat{j}'$$



$$\vec{a} + \vec{b} = \hat{i}$$

$$|\vec{a}| = |\hat{i}| \cos \theta = \cos \theta$$

$$|\vec{b}| = -|\hat{i}| \sin \theta = -\sin \theta$$

$$\vec{a} = \cos \theta \hat{i}'$$

$$\vec{b} = -\sin \theta \hat{j}'$$

$$\hat{i} = \cos \theta \hat{i}' - \sin \theta \hat{j}'$$

Similarly

$$\hat{j} = \sin \theta \hat{i}' + \cos \theta \hat{j}'$$

$$\vec{d} = u (\cos \theta \hat{i}' - \sin \theta \hat{j}') + v (\sin \theta \hat{i}' + \cos \theta \hat{j}')$$

$$\vec{d} = \underbrace{(u \cos \theta + v \sin \theta)}_{u'} \hat{i}' + \underbrace{(-u \sin \theta + v \cos \theta)}_{v'} \hat{j}'$$

$$\vec{d} = u' \hat{i}' + v' \hat{j}'$$

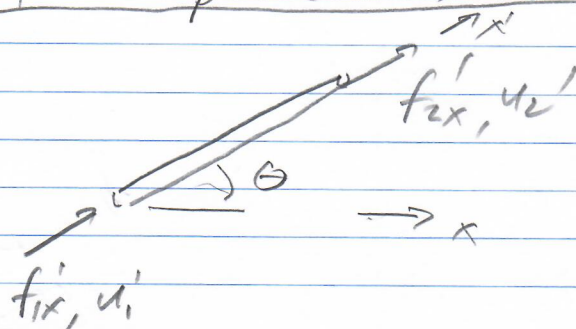
$$\begin{Bmatrix} d' \end{Bmatrix} = \begin{Bmatrix} u' \\ v' \end{Bmatrix} = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{Bmatrix} u \\ v \end{Bmatrix}$$

$$C = \cos \theta, S = \sin \theta$$

$$\{d'\} = \begin{Bmatrix} u_1' \\ v_1' \end{Bmatrix} = \begin{bmatrix} c & s \\ -s & c \end{bmatrix} \begin{Bmatrix} u \\ v \end{Bmatrix}$$

\uparrow
 $[T]$

Apply to plane truss element transformation matrix



$$\begin{Bmatrix} f_{1x}' \\ f_{2x}' \end{Bmatrix} = \frac{AE}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{Bmatrix} u_1' \\ u_2' \end{Bmatrix}$$

$$\begin{Bmatrix} u_1' \\ u_2' \end{Bmatrix}_{2 \times 1} = \begin{bmatrix} c & s & 0 & 0 \\ 0 & 0 & c & s \end{bmatrix}_{2 \times 4} \begin{Bmatrix} u_1 \\ v_1 \\ u_2 \\ v_2 \end{Bmatrix}_{4 \times 1} = \begin{bmatrix} T^* \end{bmatrix}_{2 \times 4} \{d\}_{4 \times 1}$$

$$\begin{Bmatrix} f_{1x}' \\ f_{2x}' \end{Bmatrix}_{2 \times 1} = \begin{bmatrix} c & s & 0 & 0 \\ 0 & 0 & c & s \end{bmatrix}_{2 \times 4} \begin{Bmatrix} f_{1x} \\ f_{1y} \\ f_{2x} \\ f_{2y} \end{Bmatrix}_{4 \times 1} = \begin{bmatrix} T^* \end{bmatrix}_{2 \times 4} \{f\}_{4 \times 1}$$

$$\begin{bmatrix} c & s & 0 & 0 \\ 0 & 0 & c & s \end{bmatrix} \begin{Bmatrix} f_{1x} \\ f_{1y} \\ f_{2x} \\ f_{2y} \end{Bmatrix} = \left(\frac{AE}{L} \right) \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} c & s & 0 & 0 \\ 0 & 0 & c & s \end{bmatrix} \begin{Bmatrix} u_1 \\ v_1 \\ u_2 \\ v_2 \end{Bmatrix}$$

expand $\begin{bmatrix} T^* \end{bmatrix}_{2 \times 4}$ to $\begin{bmatrix} T \end{bmatrix}_{4 \times 4}$

$$\begin{Bmatrix} u_1' \\ v_1' \\ u_2' \\ v_2' \end{Bmatrix} = \begin{matrix} & & & \\ & & & \\ & & & \\ & & & \end{matrix} \begin{matrix} c & s & 0 & 0 \\ -s & c & 0 & 0 \\ 0 & 0 & c & s \\ 0 & 0 & -s & c \end{matrix} \begin{matrix} u_1 \\ v_1 \\ u_2 \\ v_2 \end{matrix} = [T] \{d\}$$

4×4 4×1

$$\begin{Bmatrix} f_{1x}' \\ f_{1y}' \\ f_{2x}' \\ f_{2y}' \end{Bmatrix} = [T] \begin{Bmatrix} f_{1x} \\ f_{1y} \\ f_{2x} \\ f_{2y} \end{Bmatrix} = [T] \{f\}$$

$$\begin{Bmatrix} f_{1x}' \\ f_{1y}' \\ f_{2x}' \\ f_{2y}' \end{Bmatrix} = \frac{AE}{L} \begin{bmatrix} 1 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{Bmatrix} u_1' \\ v_1' \\ u_2' \\ v_2' \end{Bmatrix}$$

4×1

$$\begin{matrix} & & & \\ & & & \\ & & & \\ & & & \end{matrix} [T] \{f\} = \frac{AE}{L} \underbrace{\begin{bmatrix} 1 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}}_{[K']} [T] \{d\}$$

4×4 4×1 4×4 4×1

Need $[T]^{-1}$

(4 equations)

It can be shown

$$[T]^{-1} = [T]^T$$

$$\{f\} = [T]^T [K'] [T] \{d\}$$

4×1 4×4 4×4 4×4 4×1

$$\{f\} = \underbrace{[T]^T [k'] [T]} \{d\}$$

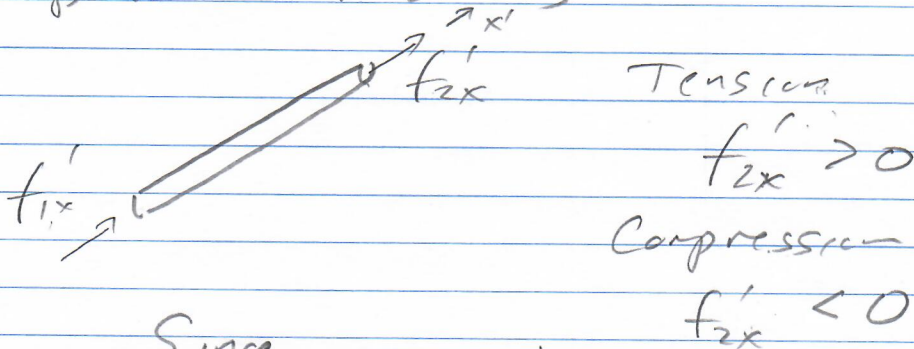
$$\{f\} = [K] \{d\}$$

4x4

element stiffness matrix
in global coordinate

$$[K] = \frac{AE}{L} \begin{bmatrix} c^2 & cs & -c^2 & -cs \\ & s^2 & -cs & -s^2 \\ \text{SYM} & & c^2 & cs \\ & & & s^2 \end{bmatrix}$$

Computation of stress



Since $\sigma > 0$ - tension
 $\sigma < 0$ - compression

$$\sigma = \frac{f_{2x}'}{A}$$

$$f_{2x}' = \frac{AE}{L} \begin{bmatrix} -1 & 1 \end{bmatrix} \begin{Bmatrix} u_1' \\ u_2' \end{Bmatrix}$$

$$\sigma = \frac{f_{2x}'}{A} = \frac{E}{L} \begin{bmatrix} -1 & 1 \end{bmatrix} \begin{Bmatrix} u_1' \\ u_2' \end{Bmatrix}$$

$$\begin{Bmatrix} u_1' \\ u_2' \end{Bmatrix} = \underset{2 \times 4}{[T^*]} \underset{4 \times 1}{\begin{Bmatrix} u_1 \\ v_1 \\ u_2 \\ v_2 \end{Bmatrix}}$$

$$\{d\} = \begin{bmatrix} c & s & 0 & 0 \\ 0 & 0 & c & s \end{bmatrix} \begin{Bmatrix} u_1 \\ v_1 \\ u_2 \\ v_2 \end{Bmatrix}$$

$$\sigma = \underset{1 \times 2}{\frac{E}{L} \begin{bmatrix} -1 & 1 \end{bmatrix}} \underset{2 \times 4}{\begin{bmatrix} c & s & 0 & 0 \\ 0 & 0 & c & s \end{bmatrix}} \begin{Bmatrix} u_1 \\ v_1 \\ u_2 \\ v_2 \end{Bmatrix}$$

$$\boxed{\sigma = \frac{E}{L} \begin{bmatrix} -c & -s & c & s \end{bmatrix} \begin{Bmatrix} u_1 \\ v_1 \\ u_2 \\ v_2 \end{Bmatrix}}$$

\uparrow $\{d\}$
 4×1