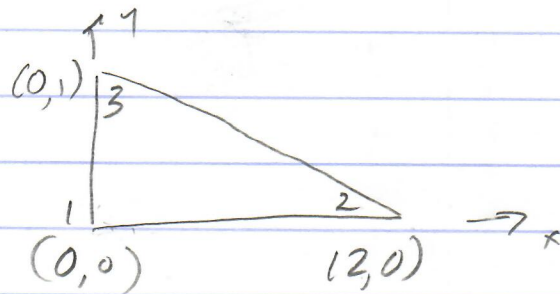


HW 5 6-3c, 6-11b, 6-13

6.3c



$i, j, m \Rightarrow 1, 2, 3$

$$t = 1 \text{ in}$$

$$A = 1 \text{ in}^2$$

$$[k] = tA [B]^T [D] [B]$$

$6 \times 6$                        $6 \times 3$        $3 \times 3$        $3 \times 6$

$$[D] = \frac{E}{1-\nu^2} \begin{bmatrix} 1 & \nu & 0 \\ \nu & 1 & 0 \\ 0 & 0 & (1-\nu)/2 \end{bmatrix}$$

$$[B] = \frac{1}{2A} \begin{bmatrix} \beta_1 & 0 & \beta_2 & 0 & \beta_3 & 0 \\ 0 & \gamma_1 & 0 & \gamma_2 & 0 & \gamma_3 \\ \gamma_1 & \beta_1 & \gamma_2 & \beta_2 & \gamma_3 & \beta_3 \end{bmatrix}$$

$$\beta_1 = y_2 - y_3 = -1, \quad \gamma_1 = x_3 - x_2 = -2$$

$$\beta_2 = y_3 - y_2 = +1, \quad \gamma_2 = x_1 - x_3 = 0$$

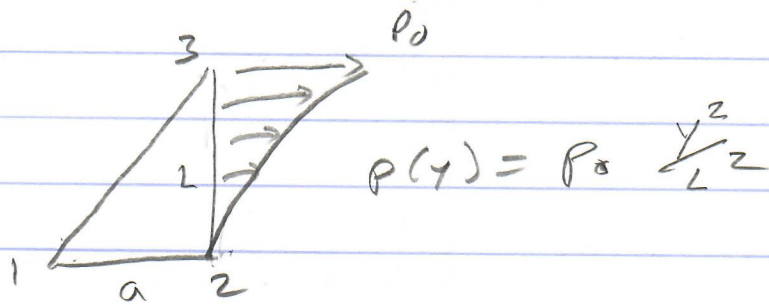
$$\beta_3 = y_1 - y_2 = 0, \quad \gamma_3 = x_2 - x_1 = 2$$

$$2A = \begin{vmatrix} 1 & x_1 & x_1 \\ 1 & x_2 & y_2 \\ 1 & x_3 & y_3 \end{vmatrix} = \begin{vmatrix} 1 & 0 & 0 \\ 1 & 2 & 0 \\ 1 & 0 & 1 \end{vmatrix} = 2$$

$$A = 1 \text{ in}^2$$

See Matlab script & output for results

6.11c



$$\{f_s\}_{6 \times 1} = t \int_0^L [N_s]^T \{T_s\} dy$$

$$= t \int_0^L \begin{bmatrix} N_1 & 0 \\ 0 & N_1 \\ N_2 & 0 \\ 0 & N_2 \\ N_3 & 0 \\ 0 & N_3 \end{bmatrix} \begin{Bmatrix} p_0 y^2 / L^2 \\ 0 \end{Bmatrix} dy$$

$6 \times 2$

$$N_1 = \frac{1}{2A} (\alpha_1 + \beta_1 x + \gamma_1 y) = 0 \text{ along } 2-3$$

$$N_2 = \frac{1}{2A} (\alpha_2 + \beta_2 x + \gamma_2 y) = \frac{a(L-y)}{2A}$$

$$N_3 = \frac{1}{2A} (\alpha_3 + \beta_3 x + \gamma_3 y) = \frac{ay}{2A}$$

$$N_2 = \frac{a(L-y)}{2A} = \frac{a(L-y)}{aL} = 1 - y/L$$

$$N_3 = \frac{ay}{aL} = y/L$$

$$\{f_s\}_{6 \times 1} = t \int_0^L \begin{bmatrix} 0 & 0 \\ 0 & 0 \\ 1-y/L & 0 \\ 0 & 1-y/L \\ y/L & 0 \\ 0 & y/L \end{bmatrix} \begin{Bmatrix} p_0 y^2 / L^2 \\ 0 \end{Bmatrix} dy = \begin{Bmatrix} 0 \\ 0 \\ f_{s2x} \\ 0 \\ f_{s3x} \\ 0 \end{Bmatrix}_{6 \times 1}$$

Node 2

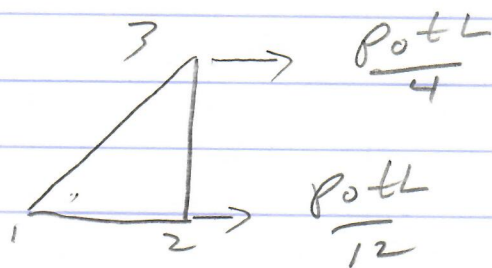
$$\begin{aligned}
 f_{s2x} &= t \int_0^L \left(1 - \frac{y}{L}\right) p_0 \frac{y^2}{L^2} dy \\
 &= t \int_0^L \frac{p_0 y^2}{L^2} - \frac{p_0 y^3}{L^3} dy \\
 &= \frac{p_0 t}{L^3} \int_0^L (L y^2 - y^3) dy \\
 &= \frac{p_0 t}{L^3} \left[ L \left( \frac{y^3}{3} \right) - \frac{y^4}{4} \right] \\
 &= p_0 t L \left( \frac{y^3}{3} - \frac{y^4}{4} \right) \Bigg|_0^L \\
 &= p_0 t L \left( \frac{L^3}{3} - \frac{L^4}{4} \right)
 \end{aligned}$$

$$f_{s2x} = \frac{p_0 t L}{12}$$

Node 3

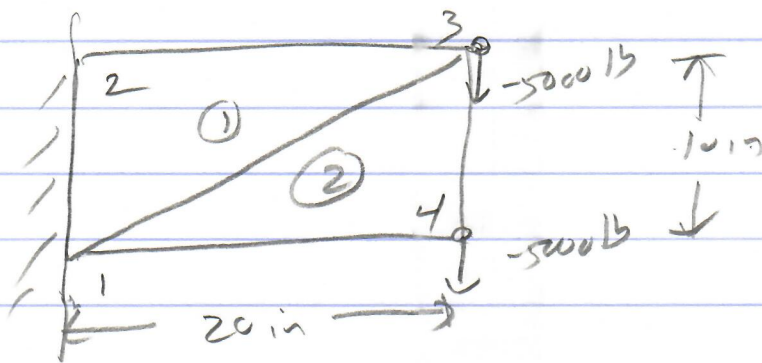
$$\begin{aligned}
 f_{s3x} &= t \int_0^L \left(\frac{y}{L}\right) \left(p_0 \frac{y^2}{L^2}\right) dy \\
 &= \frac{p_0 t}{L^3} \int_0^L y^3 dy
 \end{aligned}$$

$$f_{s3x} = \frac{p_0 t L}{4}$$





6.13



Global eq (refer to ex. 6-2)

$$\begin{Bmatrix} 0 \\ -5000 \text{ lb} \\ 0 \\ -5000 \text{ lb} \end{Bmatrix} = \frac{375,000}{0.91} \begin{bmatrix} 48 & 0 & -28 & 14 \\ & 87 & 12 & -80 \\ \text{sym} & & 48 & -26 \\ & & & 87 \end{bmatrix} \begin{Bmatrix} u_3 \\ v_3 \\ u_4 \\ v_4 \end{Bmatrix}$$

Element 1

$$\begin{Bmatrix} \sigma_x \\ \sigma_y \\ \tau_{xy} \end{Bmatrix} = \underset{3 \times 3}{[D]} \underset{3 \times 6}{[B]} \underset{6 \times 1}{\begin{Bmatrix} 0 \\ 0 \\ u_3 \\ v_3 \\ 0 \\ 0 \end{Bmatrix}} \quad \left( \begin{array}{l} \text{Note} \\ u_3 = d(1) \\ v_3 = d(2) \end{array} \right)$$

Element 2

$$\begin{Bmatrix} \sigma_x \\ \sigma_y \\ \tau_{xy} \end{Bmatrix} = \underset{3 \times 3}{[D]} \underset{3 \times 6}{[B]} \underset{6 \times 1}{\begin{Bmatrix} 0 \\ u_4 \\ v_4 \\ u_3 \\ v_3 \\ 0 \end{Bmatrix}} \quad \left( \begin{array}{l} \text{Note} \\ u_4 = d(3) \\ v_4 = d(4) \end{array} \right)$$

See Matlab script &amp; output for results