HWZ 1-65, 125, 145; Z-15, 2-3 Q., = (05 (xi', x,) Q = cos 90 cos 45 cos 45 X,, x, C's 90 COS 135 COS 45 0 52/2 52/2 0 -52/2 52/2 b = Oiphp = 0 5/2 /2/2 (1) aij' = Oip Oip apa = Q,p 9pg Qjq - Q.p apg Q2; - 0 5/2 52/ 0 2 1 0 52/ 52/2 0 - 5/2 52/ 0 4 2 0 52/2 52/2 = 0 3/2 3/2 0 /2 - 52 0 3/2 -1/2 / 0 5/2 5/2/2 1 52 - 52 $= 0 \frac{9/2}{0} - \frac{3/2}{2}$

$$= \begin{bmatrix} 2x, & 2x, & 0 \\ 0 & 2x, & 0 \\ 0 & 0 & 3x_3^2 \end{bmatrix}$$

tr (Du) = 2x, +2x, +3x,2 = 4x, +3x32

$$2-15 \qquad u = Ax^{2}, \quad v = Bxy, \quad w = Cxy2$$

$$e_{y} = \frac{1}{2} \left(\frac{\partial u_{x}}{\partial x_{y}} + \frac{\partial u_{y}}{\partial x_{y}} \right)$$

$$= \left(\frac{\partial v_{x}}{\partial x_{y}} + \frac{\partial v_{y}}{\partial x_{y}} \right) \frac{1}{2} \left(\frac{\partial v_{y}}{\partial x_{y}} + \frac{\partial v_{y}}{\partial x_{y}} \right)$$

$$= \left(\frac{\partial v_{x}}{\partial x_{y}} + \frac{1}{2} \frac{\partial v_{y}}{\partial x_{y}} + \frac{\partial v_{y}}{\partial x_{y}} \right)$$

$$= \left(\frac{\partial v_{x}}{\partial x_{y}} - \frac{\partial v_{y}}{\partial x_{y}} \right)$$

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$$2^{-3} = C_{x} = C_{y} = C_{y} \Rightarrow u = C_{1} \times + f_{y}$$

$$e_{2x} = e_{y} = d_{y} = -C_{2} \Rightarrow v = -C_{2}y + g(h)$$

$$e_{32} = e_{2} = d_{y} = 0 \Rightarrow w = h(x, y)$$

$$e_{12} = e_{xy} = \frac{1}{2} \left(\frac{\partial u}{\partial y} + \frac{\partial u}{\partial x} \right) = 0 \Rightarrow d_{y} + d_{x} \Rightarrow 0$$

$$d_{y} = -d_{x} = constant = a$$

$$f = a_{y} + d_{y}, \quad g = -a_{x} + d_{2}$$

$$e_{13} = e_{y2} = \frac{1}{2} \left(\frac{\partial u}{\partial x} + \frac{\partial w}{\partial x} \right) = 0 \Rightarrow d_{y} = 0$$

$$\Rightarrow h = f_{y}(x)$$

$$e_{13} = e_{x2} = \frac{1}{2} \left(\frac{\partial u}{\partial x} + \frac{\partial w}{\partial x} \right) = 0 \Rightarrow d_{y} = 0$$

$$\Rightarrow h = g_{y}(y)$$

$$\Rightarrow h = c_{x} + c_{x} + c_{x} + c_{y} + c_{y}$$

$$v = -c_{2}y - a_{x} + d_{2}$$

$$v = v_{0}$$

$$compare to e_{2}, \quad 22, q \Rightarrow q = -w_{2}$$

$$d_{y} = w_{0}$$

$$d_{z} = v_{0}$$

$$d_{z} = v_{0}$$