

view_frames Result

Recorded at time: 1747415870.7407403

base_footprint

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

base_link

1brazo_robotico_link
2brazo_robotico_link
3brazo_robotico_link
5brazo_robotico_link
5mano_brazo_robotico_link
5mano_derecha_brazo_robotico_link
5mano_izquierda_brazo_robotico_link
arm_camera_base_link
arm_camera_frame
arm_camera_optical_frame
imu_link

2_1brazo_robotico_link
2_2brazo_robotico_link
3_1brazo_robotico_link
3_2brazo_robotico_link

connect_wheel_left_back_link
connect_wheel_right_back_link
connect_wheel_left_front_link
connect_wheel_right_front_link

2_2brazo_robotico_link
3_1brazo_robotico_link
3_2brazo_robotico_link

5brazo_robotico_link
5mano_brazo_robotico_link

5mano_derecha_brazo_robotico_link
5mano_izquierda_brazo_robotico_link

arm_camera_base_link
arm_camera_frame
arm_camera_optical_frame

imu_link

front_camera_base_link
front_camera_frame
front_camera_optical_frame

front_camera_base_link
front_camera_frame
front_camera_optical_frame

front_camera_base_link
front_camera_frame
front_camera_optical_frame

front_camera_base_link
front_camera_frame
front_camera_optical_frame

front_camera_base_link
front_camera_frame
front_camera_optical_frame

front_camera_base_link
front_camera_frame
front_camera_optical_frame

front_camera_base_link
front_camera_frame
front_camera_optical_frame