

# Logika dziedzinowa do wnioskowania o termach z wiązaniem zmiennych

Domain-specific logic  
for terms with variable binding

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# Dwa style prowadzenia rozmowań

- ❶ Piszemy dla czytelnika
- ❷ Pomijamy detale
- ❸ Korzystamy z niejawnych założeń lub niedowiedzonych twierdzeń

- ❶ Piszemy dla komputera
- ❷ Musimy obsłużyć wszystkie detale
- ❸ Korzystamy tylko z jawnych założeń lub i dowiedzonych twierdzeń

# Dwa style prowadzenia rozmów

- ❶ Piszemy dla czytelnika
- ❷ Pomijamy detale
- ❸ Korzystamy z niejawnych założeń lub niedowiedzonych twierdzeń
- ❹ Prowadzimy rozmowę w konwencji nazw zmiennych Barendregta

- ❶ Piszemy dla komputera
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- ❹ ?

5.3.4 CONVENTION: Terms that differ only in the names of bound variables are interchangeable in all contexts.  $\square$

What this means in practice is that the name of any  $\lambda$ -bound variable can be changed to another name (consistently making the same change in the body of the  $\lambda$ ), at any point where this is convenient. For example, if we want to calculate  $[x \mapsto y z](\lambda y. x y)$ , we first rewrite  $(\lambda y. x y)$  as, say,  $(\lambda w. x w)$ . We then calculate  $[x \mapsto y z](\lambda w. x w)$ , giving  $(\lambda w. y z w)$ .

This convention renders the substitution operation “as good as total,” since whenever we find ourselves about to apply it to arguments for which it is undefined, we can rename as necessary, so that the side conditions are satisfied. Indeed, having adopted this convention, we can formulate the definition of substitution a little more tersely. The first clause for abstractions can be dropped, since we can always assume (renaming if necessary) that the bound variable  $y$  is different from both  $x$  and the free variables of  $s$ . This yields the final form of the definition.

5.3.5 DEFINITION [SUBSTITUTION]:

$$\begin{aligned} [x \mapsto s]x &= s \\ [x \mapsto s]y &= y && \text{if } y \neq x \\ [x \mapsto s](\lambda y. t_1) &= \lambda y. [x \mapsto s]t_1 && \text{if } y \neq x \text{ and } y \notin FV(s) \\ [x \mapsto s](t_1 t_2) &= [x \mapsto s]t_1 [x \mapsto s]t_2 \end{aligned} \quad \square$$

To avoid confusion between the new binding and any bindings that may already appear in  $\Gamma$ , we require that the name  $x$  be chosen so that it is distinct from the variables bound by  $\Gamma$ . Since our convention is that variables bound by  $\lambda$ -abstractions may be renamed whenever convenient, this condition can always be satisfied by renaming the bound variable if necessary.

LEMMA [PRESERVATION OF TYPES UNDER SUBSTITUTION]: If  $\Gamma, x:S \vdash t : T$  and  $\Gamma \vdash s : S$ , then  $\Gamma \vdash [x \mapsto s]t : T$ .  $\square$

*Proof:* By induction on a derivation of the statement  $\Gamma, x:S \vdash t : T$ . For a given derivation, we proceed by cases on the final typing rule used in the proof. The most interesting cases are the ones for variables and abstractions.

*Case T-ABS:*  $t = \lambda y:T_2. t_1$   
 $T = T_2 \rightarrow T_1$   
 $\Gamma, x:S, y:T_2 \vdash t_1 : T_1$

By convention 5.3.4, we may assume  $x \neq y$  and  $y \notin FV(s)$ . Using permutation on the given subderivation, we obtain  $\Gamma, y:T_2, x:S \vdash t_1 : T_1$ . Using weakening on the other given derivation ( $\Gamma \vdash s : S$ ), we obtain  $\Gamma, y:T_2 \vdash s : S$ . Now, by the induction hypothesis,  $\Gamma, y:T_2 \vdash [x \mapsto s]t_1 : T_1$ . By T-ABS,  $\Gamma \vdash \lambda y:T_2. [x \mapsto s]t_1 : T_2 \rightarrow T_1$ . But this is precisely the needed result, since, by the definition of substitution,  $[x \mapsto s]t = \lambda y:T_2. [x \mapsto s]t_1$ .

# 1 Simply Typed Lambda Calculus

Variables	$x, y \quad \dots$
Types	$A, B ::= a \mid A \rightarrow B$
Base Types	$a, b ::= \text{int}$
Variable Contexts	$\Gamma ::= \emptyset \mid \Gamma, x : A$
Source Terms	$E ::= x \mid \lambda x : A. E \mid E_1 E_2 \mid E_1 + E_2 \mid \bar{n}$
Runtime Terms	$e ::= x \mid \lambda x. e \mid e_1 e_2 \mid e_1 + e_2 \mid \bar{n}$
(Runtime) Values	$v ::= \lambda x. e \mid \bar{n}$

**Variables and Substitution** We use Barendregt's variable convention, which means we assume that all bound variables are distinct and maintain this invariant implicitly. Another way of saying this is: we will not worry about the formal details of variable names, alpha renaming, freshness, etc., and instead just assume that all variables bound in a variable context are distinct and that we keep it that way when we add a new variable to the context. Of course, getting such details right is very important when we mechanize our reasoning, but in this part of the course, we will not be using Coq, so we can avoid worrying about it.

# Rozwiązania problemu wiązania zmiennych w systemach formalnych

- Rachunek kombinatorów
- Reprezentacja De Bruijna
- Higher-Order Abstract Syntax
- Techniki nominalne

- Rozszerzenie logiki pierwszego rzędu o narzędzia do formalizacji i rozumowania na temat struktur syntaktycznych z wiązaniem nazw
- Matematyzacja pojęcia “wystarczająco świeżych nazw” zmiennych
- Opiera się o zamianę nazw i relację świeżości nazwy w termie.

**Andrew M. Pitts**, *“Nominal logic, a first order theory of names and binding”*:

Names of what? Names of entities that may be subject to binding by some of the syntactical constructions under consideration. In Nominal Logic these sorts of names, the ones that may be bound and hence that may be subjected to swapping without changing the validity of predicates involving them, will be called atoms.



$$t ::= a \mid \lambda a.t \mid t \ t$$

$$(a \ b)c := \begin{cases} a & \text{if } c = b \\ b & \text{if } c = a \\ c & \text{wpp.} \end{cases}$$

$$(a \ b)(\lambda c.t) := \lambda((a \ b)c).((a \ b)t)$$

$$(a \ b)(t_1 \ t_2) := ((a \ b)t_1) ((a \ b)t_2)$$

$$\frac{a \neq b}{a \# b}$$

$$\frac{a \# t_1 \quad a \# t_2}{a \# t_1 \ t_2}$$

$$\frac{}{a \# \lambda a.t}$$

$$\frac{a \# t}{a \# \lambda b.t}$$

$$\frac{}{a =_{\alpha} a}$$

$$\frac{t_1 =_{\alpha} t'_1 \quad t_2 =_{\alpha} t'_2}{t_1 \ t_2 =_{\alpha} t'_1 \ t'_2}$$

$$\frac{(a \ b)t =_{\alpha} (a' \ b)t' \quad b \# t \quad b \# t'}{\lambda a.t =_{\alpha} \lambda a'.t'}$$

**Andrew M. Pitts**, “Nominal logic, a first order theory of names and binding”:

The fundamental assumption underlying Nominal Logic is that *the only predicates we ever deal with* (when describing properties of syntax) *are equivariant ones, in the sense that their validity is invariant under swapping* (i.e., transposing, or interchanging) *names*.

# Pomiędzy logiką nominalną a konwencją Barendgreta

- Logika nominalna umożliwia eleganckie wyrażanie alfa-równoważności, świeżości i innych podstawowych właściwości syntaktycznych, dzięki czemu może być używana jako baza do prowadzenia rozumowań o językach programowania.
- Ale najlepiej byłoby nie przejmować się w ogóle takimi sprawami, tak jak w konwencji Barendgreta, powiedzieć jedynie że zajmujemy się tylko “wystarczająco świeżymi nazwami” i nie martwić się o technalia.

# Pomiędzy logiką nominalną a konwencją Barendgreta

- Logika nominalna umożliwia eleganckie wyrażanie alfa-równoważności, świeżości i innych podstawowych właściwości syntaktycznych, dzięki czemu może być używana jako baza do prowadzenia rozumowań o językach programowania.
- Stajemy po środku i przedstawiamy wariant logiki nominalnej która oparta jest o półautomatyczne narzędzie do zajmowania się wybranymi własnościami syntaktycznymi, które nazywamy więzami.
- Ale najlepiej byłoby nie przejmować się w ogóle takimi sprawami, tak jak w konwencji Barendgreta, powiedzieć jedynie że zajmujemy się tylko “wystarczająco świeżymi nazwami” i nie martwić się o technikalnia.

$\alpha \# t$	Atom $\alpha$ jest <i>świeży</i> w termie $t$ , czyli nie ma wolnych wystąpień w $t$ jako wolna nazwa.
$t_1 = t_2$	Termy $t_1$ i $t_2$ są alfa-równoważne.
$t_1 \sim t_2$	Termy $t_1$ i $t_2$ mają taki sam kształt, czyli po wymazaniu atomów byłyby sobie równe.
$t_1 \prec t_2$	Kształt termu $t_1$ jest strukturalnie mniejszy od kształtu termu $t_2$ , czyli po wymazaniu atomów $t_1$ byłby równy jakiemuś podtermowi $t_2$ .
symbol $t$	Term $t$ jest jakimś symbolowem funkcyjnym.

$a$	$\in$	$Atom$	(atomy)
$X$	$\in$	$Var$	(zmienne)
$f$	$\in$	$Symb$	(symbole funkcyjne)
$\alpha$	$::=$	$\pi a$	(wyrażenia atomowe)
$\pi$	$::=$	$id \mid (\alpha \alpha)\pi$	(permutacje)
$t$	$::=$	$\alpha \mid \pi X \mid \alpha.t \mid t t \mid f$	(termy)
$s$	$::=$	$\_ \mid X \mid \_.s \mid s s \mid f$	(kształty)
$c$	$::=$	$\alpha \# t \mid t = t \mid t \sim t \mid t \prec t \mid \text{symbol } t$	(więzy)

Goal-reducing equality rules:

$$\frac{}{\mathcal{G}; \Delta \models a = a} \quad \frac{}{\mathcal{G}; \Delta \models X = X} \quad \frac{}{\mathcal{G}; \Delta \models f = f}$$

$$\frac{\mathcal{G}; \Delta \models t_1 = t_2 \quad \mathcal{G}; \Delta \models t'_1 = t'_2}{\mathcal{G}; \Delta \models t_1 t'_1 = t_2 t'_2}$$

$$\frac{\mathcal{G}; \Delta \models \alpha_1 \# \alpha_2.t_2 \quad \mathcal{G}; \Delta \models t_1 = (\alpha_1 \alpha_2)t_2}{\mathcal{G}; \Delta \models \alpha_1.t_1 = \alpha_2.t_2} \quad \frac{a \neq \alpha_1, a \neq \alpha_2; \Delta \models a = \alpha}{a = \alpha_1, a \neq \alpha_2; \Delta \models \alpha_2 = \alpha} \quad \frac{a = \alpha_2; \Delta \models \alpha_1 = \alpha}{\mathcal{G}; \Delta \models a = (\alpha_1 \alpha_2)\alpha}$$

$$\frac{\mathcal{G}; \Delta \models a = \pi^{-1}\alpha}{\mathcal{G}; \Delta \models \pi a = \alpha} \quad \frac{\mathcal{G}; \Delta \models X_1 = \pi_1^{-1}\pi_2 X_2}{\mathcal{G}; \Delta \models \pi_1 X_1 = \pi_2 X_2}$$

$$\frac{\mathcal{G}; \Delta \models \pi \text{ idempotent on } X}{\mathcal{G}; \Delta \models X = \pi X} \quad \frac{\forall a \in \pi. \mathcal{G}; \Delta \models a = \pi a \vee \mathcal{G}; \Delta \models a \# \pi X}{\mathcal{G}; \Delta \models \pi \text{ idempotent on } X}$$

Goal-reducing freshness rules:

$$\frac{a_1 \neq a_2 \in \Delta}{\mathcal{G}; \Delta \models \alpha_1 \# \alpha_2} \quad \frac{a \# X \in \Delta}{\mathcal{G}; \Delta \models a \# X} \quad \frac{\text{symbol } X \in \Delta}{\mathcal{G}; \Delta \models a \# X} \quad \frac{}{\mathcal{G}; \Delta \models a \# f}$$

$$\frac{a \neq \alpha, \Delta \models a \# t}{\mathcal{G}; \Delta \models a \# \alpha.t} \quad \frac{\mathcal{G}; \Delta \models a \# t_1 \quad \mathcal{G}; \Delta \models a \# t_2}{\mathcal{G}; \Delta \models a \# t_1 t_2}$$

$$\frac{a \neq \alpha_1, a \neq \alpha_2; \Delta \models a \# \alpha}{a = \alpha_1, a \neq \alpha_2; \Delta \models \alpha_1 \# \pi X} \quad \frac{a \neq \alpha_1, a \neq \alpha_2; \Delta \models a \# \pi X}{a = \alpha_1, a \neq \alpha_2; \Delta \models \alpha_2 \# \pi X} \quad \frac{a = \alpha_2; \Delta \models \alpha_2 \# \pi X}{\mathcal{G}; \Delta \models a \# (\alpha_1 \alpha_2)\alpha}$$

Goal-reducing shape rules:

$$\frac{}{\mathcal{G}; \Delta \models \_ \sim \_} \quad \frac{}{\mathcal{G}; \Delta \models f \sim f}$$

$$\frac{X_1 \sim X_2 \in \Delta}{\mathcal{G}; \Delta \models X_1 \sim X_2} \quad \frac{X \sim s' \in \Delta \quad \mathcal{G}; \Delta \models s' \sim s}{\mathcal{G}; \Delta \models X \sim s} \quad \frac{\mathcal{G}; \Delta \models s_1 \sim s_2}{\mathcal{G}; \Delta \models \_ s_1 \sim \_ s_2} \quad \frac{\mathcal{G}; \Delta \models s_1 \sim s_2 \quad \mathcal{G}; \Delta \models s'_1 \sim s'_2}{\mathcal{G}; \Delta \models s_1 s'_1 \sim s_2 s'_2}$$

Goal-reducing subshape rules:

$$\frac{\mathcal{G}; \Delta \models s_1 \sim s_2}{\mathcal{G}; \Delta \models s_1 \prec \_ s_2} \quad \frac{\mathcal{G}; \Delta \models s_1 \prec s_2}{\mathcal{G}; \Delta \models s_1 \prec \_ s_2}$$

$$\frac{\mathcal{G}; \Delta \models s_1 \sim s_2}{\mathcal{G}; \Delta \models s_1 \prec s_2 s'_2} \quad \frac{\mathcal{G}; \Delta \models s_1 \sim s'_2}{\mathcal{G}; \Delta \models s_1 \prec s_2 s'_2} \quad \frac{\mathcal{G}; \Delta \models s_1 \prec s_2}{\mathcal{G}; \Delta \models s_1 \prec s_2 s'_2} \quad \frac{\mathcal{G}; \Delta \models s_1 \prec s'_2}{\mathcal{G}; \Delta \models s_1 \prec s_2 s'_2} \quad \frac{s_2 \prec X \in \Delta \quad \mathcal{G}; \Delta \models s_2 \sim X}{\mathcal{G}; \Delta \models s_1 \prec X} \quad \frac{s_2 \prec X \in \Delta \quad \mathcal{G}; \Delta \models s_2 \prec X}{\mathcal{G}; \Delta \models s_1 \prec X}$$

Goal-reducing symbol rules:

$$\frac{}{\mathcal{G}; \Delta \vdash \text{symbol } f} \quad \frac{\text{symbol } X \in \Delta}{\mathcal{G}; \Delta \vdash \text{symbol } X} \quad \frac{\text{symbol } X \in \Delta}{\mathcal{G}; \Delta \vdash a \# X}$$

Assumption-reducing equality rules:

$$\frac{X = \pi^{-1}t, \Gamma; \Delta \models C}{\pi X = t, \Gamma; \Delta \models C}$$

$$\frac{\pi \text{ idempotent on } X, \Gamma; \Delta \models C}{X = \pi X, \Gamma; \Delta \models C} \quad \frac{\mathcal{G}; \Delta \models \pi \text{ idempotent on } X \quad \Gamma; \Delta \models C}{\pi \text{ idempotent on } X, \Gamma; \Delta \models C}$$

$$\frac{(\forall a \in \pi. \Gamma; \Delta \models a = \pi a \vee a \# X), \Gamma; \Delta \models C}{\pi \text{ idempotent on } X, \Gamma; \Delta \models C}$$

$$\frac{\Gamma(X \mapsto t); \Delta(X \mapsto t) \models C(X \mapsto t)}{X = t, \Gamma; \Delta \models C}$$

$$\frac{\Gamma(a_1 \mapsto a_2); \Delta(a_1 \mapsto a_2) \models C(a_1 \mapsto a_2)}{a_1 = a_2, \Gamma; \Delta \models C}$$

$$\frac{a \neq \alpha_1, a \neq \alpha_2, a = \alpha, \Gamma; \Delta \models C}{a = \alpha_1, a \neq \alpha_2, \alpha_2 = \alpha, \Gamma; \Delta \models C} \quad \frac{a = \alpha_2, \alpha_1 = \alpha, \Gamma; \Delta \models C}{a = (\alpha_1 \alpha_2)\alpha, \Gamma; \Delta \models C}$$

$$\frac{a = \pi^{-1}\alpha, \Gamma; \Delta \models C}{\pi a = \alpha, \Gamma; \Delta \models C}$$

$$\frac{a = t_1 t_2, \Gamma; \Delta \vdash C}{a = \alpha.t, \Gamma; \Delta \vdash C} \quad \frac{a = \alpha.t, \Gamma; \Delta \vdash C}{a = f, \Gamma; \Delta \vdash C}$$

$$\frac{a_1 \# a_2, t_2, t_1 = (\alpha_1 \alpha_2)t_2, \Gamma; \Delta \vdash C}{a_1.t_1 = \alpha_2 t_2, \Gamma; \Delta \vdash C}$$

$$\frac{t_1 = t_2, t'_1 = t'_2, \Gamma; \Delta \vdash C}{t_1 t'_1 = t_2 t'_2, \Gamma; \Delta \vdash C}$$

$$\frac{f_1 \neq f_2}{f_1 = f_2, \Gamma; \Delta \vdash C} \quad \frac{\Gamma; \Delta \vdash C}{f = f, \Gamma; \Delta \vdash C}$$

Assumption-reducing freshness rules:

$$\frac{\Gamma; \{a_1 \neq a_2\} \cup \Delta \vdash C}{a_1 \neq a_2, \Gamma; \Delta \vdash C} \quad \frac{\Gamma; \{a \# X\} \cup \Delta \vdash C}{a \# X, \Gamma; \Delta \vdash C} \quad \frac{\Gamma; \Delta \vdash C}{a \# f, \Gamma; \Delta \vdash C}$$

$$\frac{a \neq \alpha_1, a \neq \alpha_2, a \# \alpha, \Gamma; \Delta \vdash C}{a = \alpha_1, a \neq \alpha_2, \alpha_2 \# \alpha, \Gamma; \Delta \vdash C} \quad \frac{a \neq \alpha_1, a \neq \alpha_2, a \# \pi X, \Gamma; \Delta \vdash C}{a = \alpha_1, a \neq \alpha_2, \alpha_2 \# \pi X, \Gamma; \Delta \vdash C} \quad \frac{a = \alpha_2, \alpha_1 \# \pi X, \Gamma; \Delta \vdash C}{a = \alpha_2, \alpha_1 \# \pi X, \Gamma; \Delta \vdash C}$$

$$\frac{a \# (\alpha_1 \alpha_2)\alpha, \Gamma; \Delta \vdash C}{a \# \alpha, \Gamma; \Delta \vdash C} \quad \frac{a \# \alpha, \Gamma; \Delta \vdash C}{a \# \alpha, a \# t, \Gamma; \Delta \vdash C} \quad \frac{a \# t_1, \Gamma; \Delta \vdash C \quad a \# t_2, \Gamma; \Delta \vdash C}{a \# t_1 t_2, \Gamma; \Delta \vdash C}$$

Assumption-reducing shape rules:

$$\frac{\Gamma; \{X_1 \sim X_2\} \cup \Delta \vdash C}{X_1 \sim X_2, \Gamma; \Delta \vdash C} \quad \frac{\Gamma; \{X \sim s\} \cup \Delta \vdash C}{X \sim s, \Gamma; \Delta \vdash C}$$

$$\frac{\Gamma; \Delta \vdash C}{a_1 \sim a_2, \Gamma; \Delta \vdash C} \quad \frac{t_1 \sim t_2, \Gamma; \Delta \vdash C}{t_1 \sim t_2, \Gamma; \Delta \vdash C}$$

$$\frac{t_1 \sim t_2, \Gamma; \Delta \vdash C \quad t'_1 \sim t'_2, \Gamma; \Delta \vdash C}{t_1 t'_1 \sim t_2 t'_2, \Gamma; \Delta \vdash C}$$

$$\frac{f_1 \neq f_2}{f_1 \sim f_2, \Gamma; \Delta \vdash C} \quad \frac{f \sim f, \Gamma; \Delta \vdash C}{f \sim f, \Gamma; \Delta \vdash C}$$

Assumption-reducing subshape rules:

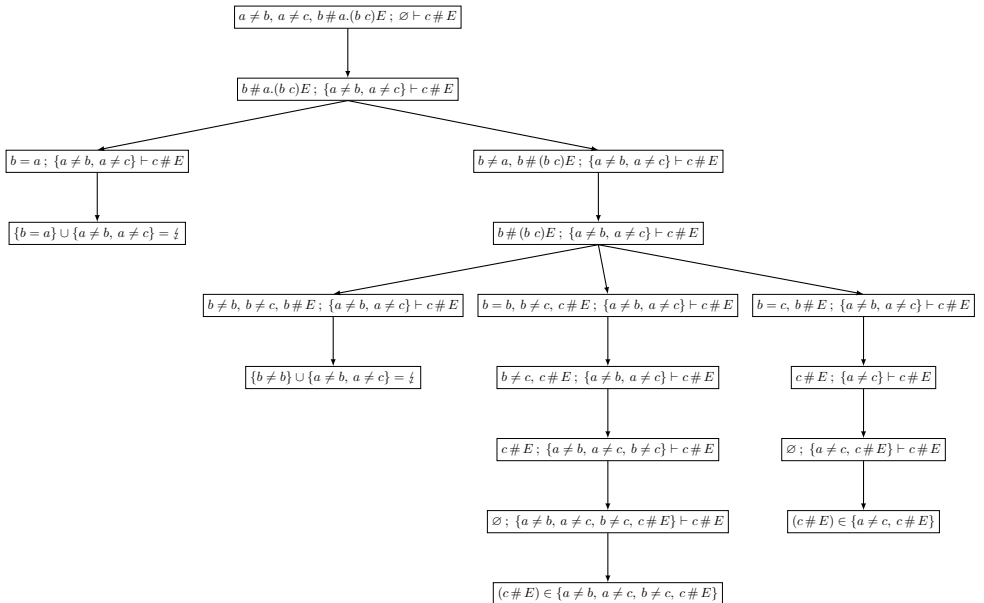
$$\frac{\Gamma; \{t < X\} \cup \Delta \vdash C}{t < X, \Gamma; \Delta \vdash C}$$

$$\frac{t_1 \sim t_2, \Gamma; \Delta \vdash C \quad t_1 \prec t_2, \Gamma; \Delta \vdash C}{t_1 \sim t_2, \Gamma; \Delta \vdash C} \quad \frac{t_1 \sim t_2, \Gamma; \Delta \vdash C \quad t_1 \prec t'_2, \Gamma; \Delta \vdash C}{t_1 \sim t_2 t'_2, \Gamma; \Delta \vdash C}$$

$$\frac{t < \alpha, \Gamma; \Delta \vdash C}{t < f, \Gamma; \Delta \vdash C}$$

Assumption-reducing symbol rules:

$$\frac{\Gamma; \{\text{symbol } X\} \cup \Delta \vdash C}{\text{symbol } X, \Gamma; \Delta \vdash C} \quad \frac{\Gamma; \Delta \vdash C}{\text{symbol } f, \Gamma; \Delta \vdash C}$$



$$\begin{aligned} \varphi ::= & \top \mid \perp \mid \varphi \vee \varphi \mid \varphi \wedge \varphi \mid \varphi \Rightarrow \varphi \\ & \mid \forall_A a. \varphi \mid \forall_T X. \varphi \mid \forall_\kappa P. \varphi \\ & \mid \exists_A a. \varphi \mid \exists_T X. \varphi \mid \exists_\kappa P. \varphi \\ & \mid \lambda_A a. \varphi \mid \lambda_T X. \varphi \mid \lambda P :: \kappa. \varphi \\ & \mid P \mid \varphi \alpha \mid \varphi t \mid \varphi \varphi \end{aligned}$$



$$\begin{aligned} \varphi ::= & \top \mid \perp \mid \varphi \vee \varphi \mid \varphi \wedge \varphi \mid \varphi \Rightarrow \varphi \\ & \mid \forall_A a. \varphi \mid \forall_T X. \varphi \mid \forall_\kappa P. \varphi \\ & \mid \exists_A a. \varphi \mid \exists_T X. \varphi \mid \exists_\kappa P. \varphi \\ & \mid \lambda_A a. \varphi \mid \lambda_T X. \varphi \mid \lambda P :: \kappa. \varphi \\ & \mid P \mid \varphi \alpha \mid \varphi t \mid \varphi \varphi \\ & \mid c \mid [c] \wedge \varphi \mid [c] \Rightarrow \varphi \end{aligned}$$

$$\begin{aligned} \varphi ::= & \top \mid \perp \mid \varphi \vee \varphi \mid \varphi \wedge \varphi \mid \varphi \Rightarrow \varphi \\ & \mid \forall_A a. \varphi \mid \forall_T X. \varphi \mid \forall_\kappa P. \varphi \\ & \mid \exists_A a. \varphi \mid \exists_T X. \varphi \mid \exists_\kappa P. \varphi \\ & \mid \lambda_A a. \varphi \mid \lambda_T X. \varphi \mid \lambda P :: \kappa. \varphi \\ & \mid P \mid \varphi \alpha \mid \varphi t \mid \varphi \varphi \\ & \mid c \mid [c] \wedge \varphi \mid [c] \Rightarrow \varphi \\ & \mid \text{fix } P(X) :: \kappa = \varphi \end{aligned}$$

# Dedukcija naturalna

$$\frac{\varphi \in \Theta}{\Gamma; \Theta \vdash \varphi} \text{ ASSUMPTION}$$

$$\frac{\Gamma; \Theta, \varphi_1 \vdash \varphi_2}{\Gamma; \Theta \vdash \varphi_1 \Rightarrow \varphi_2} \text{ IMPI}$$

$$\frac{\Gamma_1; \Theta_1 \vdash \varphi_1 \quad \Gamma_2; \Theta_2 \vdash \varphi_2}{\Gamma_1 \cup \Gamma_2; \Theta_2 \cup \Theta_2 \vdash \varphi_1 \wedge \varphi_2} \text{ ANDI}$$

$$\frac{\Gamma \models c}{\Gamma; \Theta \vdash c} \text{ CONSTR}$$

$$\frac{\Gamma, c; \Theta \vdash \varphi}{\Gamma; \Theta \vdash [c] \Rightarrow \varphi} \begin{matrix} \text{CONSTR} \\ \text{IMPI} \end{matrix}$$

$$\frac{\Gamma_1; \Theta_1 \vdash c \quad \Gamma_2; \Theta_2 \vdash \varphi}{\Gamma_1 \cup \Gamma_2; \Theta_2 \cup \Theta_2 \vdash [c] \wedge \varphi} \begin{matrix} \text{CONSTR} \\ \text{ANDI} \end{matrix}$$

$$\frac{}{\vdash \forall_A a, a'. (a = a') \vee (a \neq a')} \text{AXIOM COMPARE}$$

$$\frac{}{\vdash \forall_T X. \exists_A a. (a \# X)} \text{AXIOM FRESH}$$

$$\frac{}{\vdash \forall_T X. (\exists_A a. X = a) \vee (\exists_A a. \exists_T X'. X = a.X') \vee (\exists_T X_1, X_2. X = X_1 X_2) \vee (\text{symbol } X)} \text{AXIOM INVERSION}$$

$$\frac{\Gamma; \Theta, (\forall_T X'. [X' \prec X] \Rightarrow \varphi(X')) \vdash \varphi(X)}{\Gamma; \Theta \vdash \forall_T X. \varphi(X)} \text{INDUCTION}$$

$t ::= \alpha \mid \pi X \mid \alpha.t \mid t t \mid f \quad (\text{termy})$

$$\frac{\Gamma; \Theta, (\forall_T X'. [X' \prec X] \Rightarrow \varphi(X')) \vdash \varphi(X)}{\Gamma; \Theta \vdash \forall_T X. \varphi(X)} \text{INDUCTION}$$

$$t ::= \alpha \mid \pi X \mid \alpha.t \mid t t \mid f \quad (\text{termy})$$

$$\begin{aligned} \forall P &:: (\forall_T X. \star) . \\ &(\forall_T X. (\forall_T Y. [Y \prec X] \Rightarrow P(Y)) \Rightarrow P(X)) \\ &\Rightarrow \forall_T X. P(X) \end{aligned}$$

$$t ::= \alpha \mid \pi X \mid \alpha.t \mid t t \mid f \quad (\text{termy})$$

$$\begin{aligned} \forall P &:: (\forall_T X. \star) . \\ &(\forall_T X. (\forall_T Y. [Y \prec X] \Rightarrow P(Y)) \Rightarrow P(X)) \\ &\Rightarrow \forall_T X. P(X) \end{aligned}$$

$$\begin{aligned} \forall P &:: (\forall_T X. \star) . \\ &(\forall_A a. P(a)) \\ \Rightarrow &(\forall_T X_1, X_2. P(X_1) \Rightarrow P(X_2) \Rightarrow P(X_1 X_2)) \\ \Rightarrow &(\forall_A a. \forall_T X. P(X) \Rightarrow P(a.X)) \\ \Rightarrow &(\forall_T X. [\text{symbol } X] \Rightarrow P(X)) \\ \Rightarrow &\forall_T X. P(X) \end{aligned}$$

$$t ::= \alpha \mid \pi X \mid \alpha.t \mid t t \mid f \quad (\text{termy})$$

$$\begin{aligned} \forall P &:: (\forall_T X. \star) . \\ &(\forall_T X. (\forall_T Y. [Y \prec X] \Rightarrow P(Y)) \Rightarrow P(X)) \\ &\Rightarrow \forall_T X. P(X) \end{aligned}$$

$$\begin{aligned} \forall P &:: (\forall_T X. \star) . \\ &(\forall_A a. P(a)) \\ &\Rightarrow (\forall_T X_1, X_2. P(X_1) \Rightarrow P(X_2) \Rightarrow P(X_1 X_2)) \\ &\Rightarrow (\forall_T \textcolor{red}{C}. \forall_A a. \forall_T X. [\textcolor{red}{a} \# \textcolor{red}{C}] \Rightarrow P(X) \Rightarrow P(a.X)) \\ &\Rightarrow (\forall_T X. [\text{symbol } X] \Rightarrow P(X)) \\ &\Rightarrow \forall_T X. P(X) \end{aligned}$$



$$t ::= \alpha \mid \pi X \mid \alpha.t \mid t t \mid f \quad (\text{termy})$$

$$\begin{aligned} \forall P &:: (\forall_T X. \star) . \\ &(\forall_T X. (\forall_T Y. [Y \prec X] \Rightarrow P(Y)) \Rightarrow P(X)) \\ &\Rightarrow \forall_T X. P(X) \end{aligned}$$

$$\begin{aligned} \forall P &:: (\forall_T X. \star) . \\ &(\forall_A a. P(a)) \\ &\Rightarrow (\forall_T X_1, X_2. P(X_1) \Rightarrow P(X_2) \Rightarrow P(X_1 X_2)) \\ &\Rightarrow (\forall_A a. \forall_T X. (\forall_T C. \exists_A a'. \exists_T X'. [a' \# C] \wedge [a.X = a'.X'] \wedge P(X')) \Rightarrow P(a.X)) \\ &\Rightarrow (\forall_T X. [\text{symbol } X] \Rightarrow P(X)) \\ &\Rightarrow \forall_T X. P(X) \end{aligned}$$

$$(\text{fix } P(X) :: \kappa = \varphi) t \equiv \varphi\{X \mapsto t\}\{P \mapsto (\text{fix } P(X) :: \kappa = \varphi)\} \quad \begin{array}{l} \text{FIXPOINT} \\ \text{UNWRAP} \end{array}$$

# Rekursja — punkt stały

$$(\text{fix } P(X) :: \kappa = \varphi) \, t \equiv \varphi\{X \mapsto t\}\{P \mapsto (\text{fix } P(X) :: \kappa = \varphi)\} \quad \begin{array}{l} \text{FIXPOINT} \\ \text{UNWRAP} \end{array}$$

$$\frac{\Gamma; \Sigma, (P :: \forall_T Y. [Y \prec X] \kappa\{X \mapsto Y\}) \vdash \varphi :: \kappa}{\Gamma; \Sigma \vdash (\text{fix } P(X) :: \kappa = \varphi) :: \forall_T X. \kappa} \quad \begin{array}{l} \text{KIND} \\ \text{FIXPOINT} \end{array}$$

# Rekursja — punkt stały

$$(\text{fix } P(X) :: \kappa = \varphi) t \equiv \varphi\{X \mapsto t\}\{P \mapsto (\text{fix } P(X) :: \kappa = \varphi)\} \quad \begin{array}{l} \text{FIXPOINT} \\ \text{UNWRAP} \end{array}$$

$$\frac{\Gamma; \Sigma, (P :: \forall_T Y. [Y \prec X] \kappa\{X \mapsto Y\}) \vdash \varphi :: \kappa}{\Gamma; \Sigma \vdash (\text{fix } P(X) :: \kappa = \varphi) :: \forall_T X. \kappa} \quad \begin{array}{l} \text{KIND} \\ \text{FIXPOINT} \end{array}$$

$$\frac{}{\Gamma; \Sigma \vdash c :: \star} \quad \begin{array}{l} \text{KIND} \\ \text{CONSTR} \end{array} \qquad \frac{\Gamma, c; \Sigma \vdash \varphi :: \star}{\Gamma; \Sigma \vdash [c] \wedge \varphi :: \star} \quad \begin{array}{l} \text{KIND} \\ \text{CONSTRAND} \end{array}$$

$$\frac{\Gamma; \Sigma \vdash \varphi :: \forall_T X. \kappa}{\Gamma; \Sigma \vdash \varphi t :: \kappa\{X \mapsto t\}} \quad \begin{array}{l} \text{KIND} \\ \text{APPTERM} \end{array} \qquad \frac{\Gamma \models c}{\Gamma \vdash [c] \kappa <: \kappa} \quad \begin{array}{l} \text{SUBKIND} \\ \text{REDUCE} \end{array}$$

# Studium przypadku: rachunek lambda z typami prostymi

```
let lambda_symbols = (* symbole używane w formalizacji STLC *)
  ["lam"; "app"; "base"; "arrow"; "nil"; "cons"]

let term_predicate = (* Term e *)
  "fix Term(e): * =
    var: ( $\exists$  a :atom. (e = a))
     $\vee$ 
    lam: ( $\exists$  a :atom.  $\exists$  e' :term. [e = lam (a.e')]  $\wedge$  (Term e'))
     $\vee$ 
    app: ( $\exists$  e1 e2 :term. [e = app e1 e2]  $\wedge$  (Term e1)  $\wedge$  (Term e2))"

let type_predicate = (* Type t *)
  "fix Type(t): * =
    base: (t = base)
     $\vee$ 
    arrow: ( $\exists$  t1 t2 :term. [t = arrow t1 t2]
       $\wedge$  (Type t1)  $\wedge$  (Type t2))"
```

# Indukcja dla $\lambda$ -termów

```
let term_predicate = (* Term e *)
  "fix Term(e): * =
    var: ( $\exists$  a :atom. (e = a))
     $\vee$ 
    lam: ( $\exists$  a :atom.  $\exists$  e' :term. [e = lam (a.e')]  $\wedge$  (Term e'))
     $\vee$ 
    app: ( $\exists$  e1 e2 :term. [e = app e1 e2]  $\wedge$  (Term e1)  $\wedge$  (Term e2))"

let lambda_ind_thm = lambda_thm
  " $\forall$  P :( $\forall$  _ :term. *).
    ( $\forall$  a :atom. P {a})
 $\Rightarrow$  ( $\forall$  t1 t2 :term. (Term t1)  $\Rightarrow$  (Term t2)  $\Rightarrow$ 
      (P t1)  $\Rightarrow$  (P t2)  $\Rightarrow$  P {app t1 t2})
 $\Rightarrow$  ( $\forall$  a :atom.  $\forall$  t :term. (Term t)  $\Rightarrow$ 
      ( $\forall$  c :term.  $\exists$  a' :atom.  $\exists$  t' :term. (Term t')  $\wedge$ 
        ([a' # c]  $\wedge$  [a.t = a'.t']  $\wedge$  P t'))
       $\Rightarrow$  P {lam (a.t)})
 $\Rightarrow$  ( $\forall$  t :term. (Term t)  $\Rightarrow$  P t)
```

# *Live Demo*

???

*Koniec*



# Logika więzów

$a \in Atom$  (atomy)  
 $X \in Var$  (zmienne)  
 $f \in Symb$  (symbole funkcyjne)

$\alpha ::= \pi a$  (wyrażenia atomowe)  
 $\pi ::= id \mid (\alpha \alpha)\pi$  (permutacje)  
 $t ::= \alpha \mid \pi X \mid \alpha.t \mid t t \mid f$  (termy)  
 $s ::= \_ \mid X \mid \_.s \mid s s \mid f$  (kształty)  
 $c ::= \alpha \# t \mid t = t \mid t \sim t \mid t \prec t \mid \text{symbol } t$  (więzy)

---

$\pi (\pi' a)$	$:=$	$(\pi \uplus \pi') a$
$\pi (\pi' X)$	$:=$	$(\pi \uplus \pi') X$
$\pi (\alpha.t)$	$:=$	$(\pi \alpha).(\pi t)$
$\pi (t_1 t_2)$	$:=$	$(\pi t_1) (\pi t_2)$
$\pi f$	$:=$	$f$

$ \pi a $	$:=$	$\_$
$ \pi X $	$:=$	$\bar{X}$
$ \alpha.t $	$:=$	$\_. t $
$ t_1 t_2 $	$:=$	$ t_1   t_2 $
$ f $	$:=$	$f$

# Semantyczne termy

$A$	$\in$	$SemAtom$	(wolne atomy)
$n$	$\in$	$Nat$	(związane atomy)
$T$	$::=$	$A \mid n \mid \$T \mid T@T \mid f$	(semantyczne termy)
$S$	$::=$	$\_ \mid \$S \mid S@S \mid f$	(semantyczne kształty)
$\rho$	$\in$	$(Atom \rightarrow SemAtom) \times (Var \rightarrow SemTerm)$	(interpretacje)

$$\begin{aligned}
 \llbracket \pi \ a \rrbracket_\rho &:= \llbracket \pi \rrbracket_\rho(\rho(a)) \\
 \llbracket \pi \ X \rrbracket_\rho &:= \llbracket \pi \rrbracket_\rho(\rho(X)) \\
 \llbracket \alpha.t \rrbracket_\rho &:= \$(\llbracket t \rrbracket_\rho \uparrow) \{ \llbracket \alpha \rrbracket_\rho \mapsto 0 \} \\
 \llbracket t_1 \ t_2 \rrbracket_\rho &:= \llbracket t_1 \rrbracket_\rho @ \llbracket t_2 \rrbracket_\rho \\
 \llbracket f \rrbracket_\rho &:= f
 \end{aligned}$$

$$\begin{aligned}
 |A| &:= \_ \\
 |n| &:= \_ \\
 |\$T| &:= \$|T| \\
 |T_1 @ T_2| &:= |T_1| @ |T_2| \\
 |f| &:= f
 \end{aligned}$$

$$\llbracket id \rrbracket_\rho(A) := A$$

$$\begin{aligned}
 \llbracket \pi \ \# (\alpha_1 \ \alpha_2) \rrbracket_\rho(A) &:= \llbracket \pi \rrbracket_\rho(A') \\
 \text{where } A_1 &:= \llbracket \alpha_1 \rrbracket_\rho \\
 \text{and } A_2 &:= \llbracket \alpha_2 \rrbracket_\rho \\
 \text{and } A' &:= \begin{cases} A_2 & \text{if } A = A_1 \\ A_1 & \text{if } A = A_2 \\ A & \text{wpp.} \end{cases}
 \end{aligned}$$

# Model logiki więzów

$\rho$	$::$	$(Atom \rightarrow SemAtom) \times (Var \rightarrow SemTerm)$	(interpretacje)
$\Gamma$	$::=$	$\emptyset \mid c, \Gamma$	(środowisko więzów)

---

$$\rho \models \alpha \# t \quad \text{iff} \quad \llbracket \alpha \rrbracket_\rho \notin \text{FreeAtoms}(\llbracket t \rrbracket_\rho)$$

$$\rho \models t_1 = t_2 \quad \text{iff} \quad \llbracket t_1 \rrbracket_\rho = \llbracket t_2 \rrbracket_\rho$$

$$\rho \models t_1 \sim t_2 \quad \text{iff} \quad |\llbracket t_1 \rrbracket_\rho| = |\llbracket t_2 \rrbracket_\rho|$$

$$\rho \models t_1 \prec t_2 \quad \text{iff} \quad |\llbracket t_1 \rrbracket_\rho| \text{ jest ścisłym podkształtem } |\llbracket t_2 \rrbracket_\rho|$$

$$\rho \models \text{symbol } t \quad \text{iff} \quad |\llbracket t \rrbracket_\rho| \text{ jest symbolem funkcyjnym}$$

---

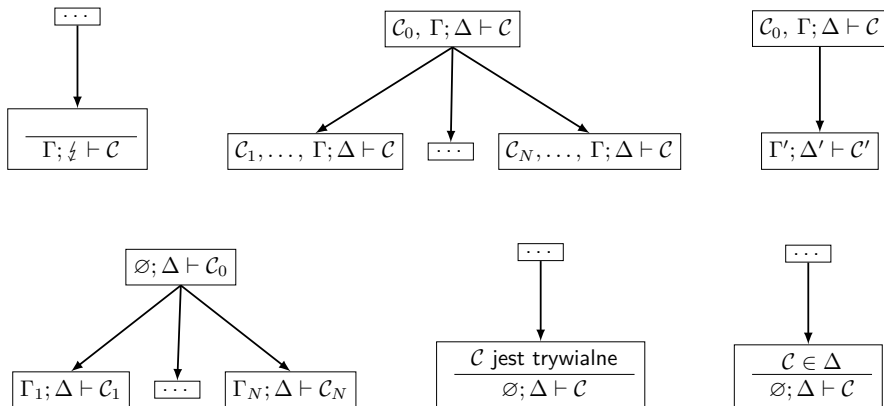
$$\rho \models \Gamma \quad \text{iff} \quad \forall c \in \Gamma. \rho \models c$$

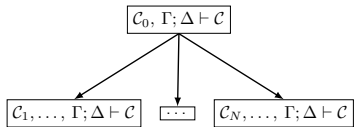
$$\Gamma \models c \quad \text{iff} \quad \forall \rho. \rho \models \Gamma \implies \rho \models c$$

# Solver — Syntaktyczny algorytm rozwiązywania więzów

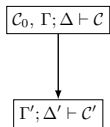
$\mathcal{C} ::= \alpha \# t \mid t = t \mid s \sim s \mid s \prec s \mid \text{symbol } t$

$\Gamma \models \mathcal{C} \stackrel{?}{=} \Gamma; \emptyset \vdash \mathcal{C}$





$$\begin{array}{c}
 a \neq \alpha_1, a \neq \alpha_2, a = \alpha, \Gamma; \Delta \vdash \mathcal{C} \\
 a = \alpha_1, a \neq \alpha_2, \alpha_2 = \alpha, \Gamma; \Delta \vdash \mathcal{C} \\
 a = \alpha_2, \alpha_1 = \alpha, \Gamma; \Delta \vdash \mathcal{C} \\
 \hline
 a = (\alpha_1 \ \alpha_2)\alpha, \Gamma; \Delta \vdash \mathcal{C}
 \end{array}$$



$$\frac{\Gamma\{X \mapsto t\}; \Delta\{X \mapsto t\} \vdash \mathcal{C}\{X \mapsto t\}}{X = t, \Gamma; \Delta \vdash \mathcal{C}}$$

...

...