

Tutorial 1:

$$1. \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & * \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

" only one pivot only one pivot " I

A : Row reduced \rightarrow see in defn
of row-reduced echelon matrix

$$2. A = \begin{bmatrix} 3 & -1 & 2 \\ 2 & 1 & 1 \\ 1 & -3 & 0 \end{bmatrix} \quad y = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} \quad Ax = y$$

$$\text{let } A = \begin{bmatrix} 3 & -1 & 2 \\ 2 & 1 & 1 \\ 1 & -3 & 0 \end{bmatrix} \xrightarrow{R'_3 = R_3 - \frac{1}{3}R_1} \begin{bmatrix} 3 & -1 & 2 \\ 2 & 1 & 1 \\ 0 & -\frac{8}{3} & \frac{2}{3} \end{bmatrix} \xrightarrow{R'_2 = R_2 - \frac{2}{3}R_1} \begin{bmatrix} 3 & -1 & 2 \\ 0 & \frac{5}{3} & -\frac{1}{3}y_3 \\ 0 & -\frac{8}{3} & \frac{2}{3}y_3 \end{bmatrix}$$

$$\xrightarrow{R'_3 = R_3 + \frac{8}{5}R_2}$$

$$\begin{bmatrix} 3 & -1 & 2 \\ 0 & \frac{5}{3} & -\frac{1}{3}y_3 \\ 0 & 0 & -\frac{6}{5}y_3 \end{bmatrix}$$

$$y = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} \xrightarrow{R'_3 = R_3 - \frac{1}{3}R_1} \begin{bmatrix} y_1 \\ y_2 \\ y_3 - \frac{y_1}{3} \end{bmatrix} \xrightarrow{R'_2 = R_2 - \frac{2}{3}R_1} \begin{bmatrix} y_1 \\ y_2 - \frac{2}{3}y_1 \\ y_3 - \frac{y_1}{3} \end{bmatrix} \xrightarrow{R'_3 = R_3 + \frac{8}{5}R_2} \begin{bmatrix} y_1 \\ y_2 - \frac{2}{3}y_1 \\ y_3 - \frac{y_1}{3} + \frac{8}{5}(y_2 - \frac{2}{3}y_1) \end{bmatrix}$$

now for $y_3 - \frac{y_1}{3} + \frac{8}{5}(y_2 - \frac{2}{3}y_1) \neq 0$ it has a unique soln.

$$y_3 - \frac{y_1}{3} + \frac{8}{5}y_2 - \frac{16}{15}y_1 \neq 0$$

$$y_3 + \frac{8}{5}y_2 - \frac{21}{15}y_1 \neq 0$$

$$y_3 + \frac{8}{5}y_2 - \frac{7}{5}y_1 \neq 0$$

$$5y_3 + 8y_2 - 7y_1 \neq 0$$

3. A ($n \times n$) matrx

$$(P) \exists B \in \mathbb{R}^{n \times n} \text{ s.t. } BA = I$$

$$\text{as } BA = I$$

$$\text{if } AB = I \text{ then}$$

A is invertible.

$$\text{as } BA = I$$

$$BAB = B$$

$$ABAAB = AB$$

$$(AB)^2 = AB$$

$$\text{as } AB = (AB)^2 \\ AB = (AB)^n \quad \forall n \in \mathbb{N} \\ (AB)^2 - AB = 0$$

$$(AB)(AB - I) = 0 \\ AB = 0 \\ \text{or } AB = I$$

$$\text{but } AB \neq 0 \quad \text{as if } AB = 0 \\ AB \cdot A = 0 \\ A = 0$$

$$\text{but as } BA = I \\ A \neq 0 \quad *$$

$$\therefore AB = I = BA \\ \therefore A \text{ is invertible}$$

(ii) $AC = I$ similar to (i).

$$9. \quad A = \begin{bmatrix} 1 & -1 \\ 2 & \frac{1}{2} \\ 1 & 0 \end{bmatrix}_{3 \times 2} \quad B = \begin{bmatrix} 3 & 1 \\ -4 & 4 \end{bmatrix}_{2 \times 2} \quad \text{to find } C \text{ and } CA = B \\ \text{if unique.}$$

C has to be 2×3

$$\text{let } C = \begin{bmatrix} C_{11} & C_{12} & C_{13} \\ C_{21} & C_{22} & C_{23} \end{bmatrix}$$

$$\begin{bmatrix} C_{11} & C_{12} & C_{13} \\ C_{21} & C_{22} & C_{23} \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 2 & 2 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 3 & 1 \\ -4 & 4 \end{bmatrix}$$

$$C_{11} + 2C_{12} + C_{13} = 3$$

$$-C_{11} + 2C_{12} = 1$$

$$2C_{12} - 1 = C_{11}$$

$$2C_{12} - 1 + 2C_{12} + C_{13} = 3$$

$$4C_{12} + C_{13} = 5$$

$$C_{13} = 4 - 4C_{12}$$

$$C_{11} = 2C_{12} - 1$$

$$C_{12} = C_{22}$$

$$\left| \begin{array}{l} C_{21} + 2C_{22} + C_{23} = -4 \\ -C_{21} + 2C_{22} = 4 \\ 2C_{22} - 4 = C_{21} \\ 2C_{22} - 4 + 2C_{22} + C_{23} = -4 \\ 4C_{22} + C_{23} = 0 \\ C_{23} = -4C_{22} \\ C_{22} = C_{22} \\ C_{21} = 2C_{22} - 4 \end{array} \right.$$

$$\begin{bmatrix} 2C_{12} - 1 & C_{12} & 4 - 4C_{12} \\ 0 & 0 & 0 \end{bmatrix} + \begin{bmatrix} 0 & 0 & 0 \\ 2C_{22} - 4 & C_{22} & -4C_{22} \end{bmatrix}$$

$$= \begin{bmatrix} -1 & 0 & 4 \\ -4 & 0 & 0 \end{bmatrix} + C_{12} \begin{bmatrix} 2 & 1 & -4 \\ 0 & 0 & 0 \end{bmatrix} + C_{22} \begin{bmatrix} 0 & 0 & 0 \\ 2 & 1 & -4 \end{bmatrix}$$

5. $A \in M_{m \times n}$

$B \in M_{n \times m}$ $n < m$

AB is non-invertible.

AB is $m \times m$

AB $m \times m$ is non-invertible

$$\text{as } A \times B = A_{1*} \cdot B_{*1} + A_{2*} \cdot B_{*2} + \dots$$

as A, B can have max n pivots

$$A \cdot B = \begin{bmatrix} A_{1*} \\ \vdots \\ A_{m*} \end{bmatrix} \cdot \begin{bmatrix} B_{*1} & \cdots & B_{*m} \end{bmatrix}$$

row reduced form of A with n pivots is:

$$\begin{bmatrix} 1, 0 \\ 0, 1 \\ \vdots \end{bmatrix} \text{ for } B:$$

$$\begin{bmatrix} 1, 0 \\ 0, 1 \\ \vdots \end{bmatrix}$$

$$\gamma(A) \cdot \gamma(B) = \begin{bmatrix} 1, 0 \\ 0, 1 \\ \vdots \end{bmatrix}_{n \times n} \text{ so row reduced form of } A \cdot B \text{ can have max } n \text{ pivots.}$$

as $n < m$, AB is invertible

6. $B \in M_{n \times n}(\mathbb{C})$

(i) To prove: $B' = \{ A \in M_{n \times n}(\mathbb{C}) \mid AB = BA \}$
is a subspace.

proof: for $A, C \in B'$ $AB = BA$ and $CB = BC$

if $\alpha A + C \in B'$ (proved)

$$\begin{aligned} \text{now } (\alpha A + C)B &= \alpha AB + CB \\ &= \alpha BA + BC \\ &= B\alpha A + BC \\ &= BC\alpha A + BC \\ &= BC(\alpha A + C) \end{aligned}$$

$\therefore \alpha A + C \in B'$
 \therefore subspace

(ii) $B = \begin{bmatrix} 1 & 0 \\ 0 & \ddots \end{bmatrix}_{n \times n}$ to find: $B' = \{ A \in M_{n \times n}(\mathbb{C}) \mid AB = BA \}$
for $B = \begin{bmatrix} 1 & 0 \\ 0 & \ddots \end{bmatrix}_{n \times n}$

let $A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & \ddots & \cdots & a_{2n} \\ \vdots & \ddots & \ddots & \vdots \\ a_{n1} & \cdots & \cdots & a_{nn} \end{bmatrix}_{n \times n}$ & $a_{ij} \in \mathbb{C}$, $A \in M_{n \times n}(\mathbb{C})$

$$\text{now } AB = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ \vdots & \ddots & \cdots & \vdots \\ \vdots & \cdots & \cdots & a_{nn} \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 2 & 0 \\ \vdots & \vdots \\ 0 & n \end{bmatrix} = \begin{bmatrix} a_{11} & 2a_{12} & 3a_{13} & \cdots & na_{1n} \\ a_{21} & 2a_{22} & \cdots & \cdots & na_{2n} \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ na_{n1} & na_{n2} & \cdots & \cdots & na_{nn} \end{bmatrix}$$

$$BA = \begin{bmatrix} 1 & 0 \\ 2 & 0 \\ \vdots & \vdots \\ 0 & n \end{bmatrix} \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ \vdots & \vdots & \ddots & \vdots \\ \vdots & \cdots & \cdots & a_{nn} \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ 2a_{21} & \vdots & \vdots & \vdots \\ \vdots & \vdots & \ddots & \vdots \\ na_{n1} & na_{n2} & \cdots & na_{nn} \end{bmatrix}$$

for $AB = BA$

a_{11}, a_{nn} can be anything in \mathbb{C}

as $2a_{21} = a_{21}$

$\Rightarrow a_{21} = 0$ (similarly for others)

similarly a_{ii} can be any value.

$$\text{so } B' = \begin{bmatrix} a_1 & 0 \\ a_2 & \ddots \\ 0 & \cdots & a_n \end{bmatrix}$$

where diagonal element can be anything in \mathbb{C}

$$\text{so } \forall a_i \in \mathbb{C}, B'$$

$$7. x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \in M_{n \times 1}(\mathbb{C})$$

$$LA(x) = \{A \in M_{n \times n}(\mathbb{C}) \mid Ax = 0\}$$

(i) for $LA(x)$ to be a subspace of $M_{n \times n}(\mathbb{C})$:

let $\alpha \in \mathbb{C}$

$$A_1, A_2 \in LA(x)$$

then $A_1 x = 0$ and $A_2 x = 0$
 $\Rightarrow \alpha A_1 x = 0$ and $A_2 x = 0$
 $\Rightarrow (\alpha A_1 + A_2)x = 0$
 $\Rightarrow \alpha A_1 + A_2 \in LA(x)$
 $\therefore \text{proved.}$

(ii) To prove: $BA \in LA(x)$ whenever (left ideal)
 $A \in LA(x)$ and $B \in M_{n \times n}(\mathbb{C})$

proof: as $A \in LA(x)$
 $Ax = 0$

now if $B \in M_{n \times n}(\mathbb{C})$

then $B(Ax) = B \cdot 0 = 0$

$\Rightarrow (BA)x = 0 \Rightarrow BA \in LA(x)$

(iii) To prove: $LA(x) = M_{n \times n}(\mathbb{C}) \Leftrightarrow x = 0$

Proof: (\Rightarrow) given $LA(x) = M_{n \times n}(\mathbb{C})$
then

$$\begin{aligned} & I \in LA(x) \\ \text{so } & Ix = 0 \\ \Rightarrow & x = 0 \end{aligned}$$

$$\begin{aligned} (\Leftarrow) & x = 0, \forall A \in M_{n \times n}(\mathbb{C}) \\ & A \cdot 0 = 0 \\ & \therefore Ax = 0 \\ \text{so } & M_{n \times n}(\mathbb{C}) = LA(x) \end{aligned}$$

8. $A, B \in M_{n \times n}(\mathbb{C})$ s.t. $AB = 0$

(i) $BA = 0$

false: counter-example:

$$A = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \quad B = \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix} \quad AB = 0$$

$$BA = \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} = BA \neq 0$$

(ii) false (above)

(iii) Proof:

as B is invertible, $\exists C$ s.t. $BC = I = CB$

now,

$$\begin{aligned} \text{for } & AB = 0 \\ & ABC = 0, C = 0 \\ \Rightarrow & A(BC) = 0 \\ \Rightarrow & A \cdot I = 0 \\ \Rightarrow & A = 0 \end{aligned}$$

(iv) for $x \neq 0$ but $BAx = 0$

BA have to be non-invertible
as $|ABA| = |BA| = 0$
 BA is non-invertible
 \therefore possible.

as $AB = 0$

$$ABx_1 = 0$$

so for $x = Bx_1$

so for $Bx_1 \neq 0$

for $x \neq 0$

works.

for

$$Bx_1 = 0$$

if all $Bx_i \neq 0$

$$Bx_i = 0$$

$$AB = 0$$

then

$$ABx = 0$$

$\forall x \in \mathbb{R}^n$

Possible

$$\therefore x \neq 0 \quad ABx = 0$$

Tutorial - 2:

$$1. \begin{bmatrix} 1 & 2 & 1 & 2 \\ 1 & -1 & -1 & 1 \\ \frac{1}{2} & -\frac{5}{2} & -\frac{7}{4} & \frac{1}{4} \\ 0 & 2 & 0 & 6 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 1 & 2 \\ 0 & -3 & -2 & -1 \\ 0 & -7 & -6 & -3 \\ 0 & -6 & -4 & -2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 1 & 2 \\ 0 & -3 & -2 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

lin dep in \mathbb{R}^4

$$2. V \in M_{2 \times 2}(\mathbb{C}) = V$$

$$(i) \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$$

can form
 $v = \begin{bmatrix} v_1 & v_2 \\ v_3 & v_4 \end{bmatrix} \in V$

Note: ① Spans $V \Rightarrow$ Basis
 ② lin ind
 ③ $|Basis| = \dim$

$$\therefore \dim = 4$$

$$(ii) W = \{A \in M_{2 \times 2}(\mathbb{C}) \mid A_{11} + A_{22} = 0\}$$

$$W = \left\{ \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \mid a_{11} + a_{22} = 0 \right\}$$

$$= \left\{ \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & -a_{11} \end{bmatrix} \in M_{2 \times 2}(\mathbb{C}) \right\}$$

$$\left\{ \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \right\} \text{ can form } W.$$

$$\therefore \dim W = 3$$

also if $\alpha w_1 + \beta w_2 \in W$
 then w is a
 subspace.

$$\text{here } \alpha w_1 + \beta w_2$$

$$\begin{aligned} \alpha a_{11} + \beta b_{11} &= w_{11} \\ -\alpha a_{21} - \beta b_{21} &= w_{22} \end{aligned}$$

$$\text{as } w_{11} + w_{22} = 0$$

$$\alpha w_1 + \beta w_2 \leftarrow \cdots$$

$$3. X = \text{Span} \{a, x, x^2, \dots, x^n\}$$

$$Y = \left\{ f(x) \in X \mid f(x) = 0 \text{ at } x = t_1, t_2, \dots, t_j \text{ for } j < n \right\}$$

$$(i) f(t_i) = 0 \text{ also let}$$

$$f(x) \in Y$$

$$\text{and } g(x) \in Y$$

$$\text{then } \alpha f(x) + \beta g(x) \in Y$$

$$\text{as for } x = t_1, t_2, \dots, t_j$$

$$\text{both are zero}$$

$$\Rightarrow \alpha(0) + \beta(0) = 0$$

$X = \text{set of poly deg} < n$

$$Y = \{ \phi(x) \mid \phi(t_i) = 0, i \in \{1, 2, \dots, j\} \}$$

$$\phi(x) \in Y$$

$$(ii) f(x) = a(x-t_1)(x-t_2)\dots$$

\downarrow
remains same

$a \in \mathbb{R}$ s.t.

$$a \neq 0$$

$$\therefore \deg Y = 2$$

$$\text{as } \text{span } Y = \left\{ a, (x-t_1)(x-t_2)\dots(x-t_j) \right\}$$

$$(iii) \dim(X/Y) = \left\{ x \mid x \in X \right\}$$

\hookrightarrow polynomials

with zero = t_1, t_2, \dots, t_j

$$\text{span}(X/Y) = \left\{ a, x, x^2, \dots, x^{n-j}, (x-t_1)(x-t_2)\dots(x-t_j) \right\}$$

$$\deg(X/Y) = \frac{n-j+1}{n-j+2}$$

By span Y :

$$\Rightarrow f(x) = \prod_{i=1}^j (x-x_i) Q(x)$$

where,

$$Q(x) = \sum_{k=0}^{n-j-1} b_k x^k$$

$$f(x) = \prod_{i=1}^j (x-x_i) \left(\sum_{k=0}^{n-j-1} b_k x^k \right)$$

$$= \sum_{k=0}^{n-j-1} \left\{ \prod_{i=1}^j (x-x_i) \right\} x^k$$

4. V = vector space
 A = lin ind subset of V

A = basis of $V \Leftrightarrow A$ is a maximal lin ind subset of V

① $\text{span } A = V$
 ② A is lin ind

any addition of vector \rightarrow lin dep

Proof:

$(\Rightarrow) A$ = basis of V

$$\text{span } A = V$$

A is lin ind

let $\dim A = n$ so

$$A = \{v_1, v_2, \dots, v_n\}$$

$$\text{s.t. if } \sum a_i v_i = 0 \Rightarrow a_1 = a_2 = \dots = a_n = 0$$

now if we add v_{n+1} to A

$$\begin{aligned} & v_{n+1} \in V \\ & \text{then as } \text{span } A = V \\ & v_{n+1} = \sum b_i v_i \end{aligned}$$

then as v_{n+1} can be written as form

as $\text{span } A = V$ Note: Better

base:

$$\{1, t-t_1, (t-t_1)(t-t_2), \dots, (t-t_1)(t-t_2)\dots\}$$

$$\prod_{i=1}^{j-1} (t-t_i)$$

$\{v_1, v_2, \dots, v_n, v_{n+1}\}$ is lin dependent

$$\sum_{i=1}^n b_i v_i$$

so for $a_i = -b_i$

$\therefore A$ is maximal lin ind subset of V .

(\Leftarrow) if A is max lin ind subset of V .
then

if v_{n+1} is added
to A
 A is lin dependent
so $v_{n+1} = \sum_{i=1}^n a_i v_i$
 $\forall v_i \in A$

but as $v_{n+1} \in V$
 $\text{span } A = \sum_{i=1}^n a_i v_i = V$
 $\therefore A$ is basis of V

5. $\text{span}(A) = V$

$$A \subseteq V$$

A is a basis of $V \Leftrightarrow A$ is a minimal spanning set

① $\text{span } A = V$

② A is lin ind

① if we remove a vector
 $\text{span } A \neq V$

Proof:

(\Rightarrow) $\text{span } A = V$ and A is lin ind (as A is basis)

let

$A = \{v_1, v_2, \dots, v_n\}$, if we remove v_n (W.L.G.)

but as $v_n \in V$

$$\sum a_i v_i \neq v_n$$

$\therefore \text{span } A \neq V$

$\therefore A$ is a minimal spanning set of V .

(\Leftarrow) $\text{span } A = V$ and A is minimal spanning set
then if we prove A is lin ind then we are done.

$A = \{v_1, v_2, \dots, v_n\}$ s.t. $\text{span } A = V$
if we remove v_n (W.L.G.)

$\text{span} \{v_1, v_2, \dots, v_{n-1}\} \neq V$

if A was lin dependent
then $\sum_{i=1}^{n-1} a_i v_i = v_n$

$\therefore \text{span} \{v_1, v_2, \dots, v_{n-1}\} = V \quad *$

$\therefore A$ is lin ind.

$\therefore A$ is basis of V .

Tutorial - 3:

$$1. C([0,1]) = \{f: [0,1] \rightarrow \mathbb{C} \mid f \text{ is cont}\}$$

$$T: C([0,1]) \rightarrow \mathbb{C}$$

$$T(f) = \int_0^1 f(x)x^3 dx, \forall f \in C([0,1])$$

for $T(f)$ to be a linear map:

$$T(f+g) = T(f) + T(g)$$

$$\text{and } T(\lambda f) = \lambda T(f)$$

$$\begin{aligned} (i) \quad T(f+g) &= \int_0^1 [f+g](x) x^3 dx \\ &= \int_0^1 f(x) x^3 dx + \int_0^1 g(x) x^3 dx \\ &= T(f) + T(g) \end{aligned}$$

$$\begin{aligned} (ii) \quad T(\lambda f) &= \int_0^1 \lambda f(x) x^3 dx = \lambda \int_0^1 f(x) x^3 dx \\ &= \lambda T(f) \end{aligned}$$

$\therefore T(f)$ is a linear map.

2. $X \leftarrow$ vector space over \mathbb{F}
 $x \in X$ and $x \neq \bar{0}$

$$\begin{aligned} T(x) &= \sum x_i \\ \text{then } T(x+y) &= \sum (x_i + y_i) \\ &= \sum x_i + \sum y_i \\ &= T(x) + T(y) \end{aligned}$$

$$\text{and } T(\lambda x) = \sum (\lambda x_i)$$

$$= \lambda \sum x_i$$

$$= \lambda T(x)$$

$\therefore T(x) \neq \bar{0}$ is a linear map.

$$3. C([-1,1]) = \{f: [-1,1] \rightarrow \mathbb{R} \mid f \text{ is cont}\}$$

$$P: C([-1,1]) \rightarrow C([-1,1])$$

$$(Pf)(x) = \frac{f(x) + f(-x)}{2}, \forall x \in [-1,1] \text{ and } f \in C([-1,1])$$

$$\begin{aligned} \text{now, } (P(f+g))(x) &= (f+g)(x) + (f+g)(-x) \\ &= \frac{f(x) + f(-x)}{2} + \frac{g(x) + g(-x)}{2} \\ &= (Pf)(x) + (Pg)(x) \end{aligned}$$

$$\text{define } C([0,1]) \rightarrow \mathbb{C} \text{ by } T(f) = \int_0^1 f(x)x^3 dx, \forall f \in C([0,1])$$

$$\text{claim: } T(\alpha f + g) = \alpha T(f) + T(g)$$

$$\forall f, g \in C([0,1])$$

$$\text{and } \alpha \in \mathbb{C}$$

$$T(\alpha f + g) = \int_0^1 (\alpha f + g)(x) x^3 dx$$

$$= \alpha \int_0^1 f(x) x^3 dx + \int_0^1 g(x) x^3 dx$$

$\therefore T$ is a linear map

Note: what we are trying to say is $T: V \rightarrow W$
 $T(V)$ becomes vector subspace of W .

let X be a vector space over \mathbb{F} . Since x_0 is a non-zero vector, $\{x\}$ is a l.i set in X

Extend, $\{x\}$ to basis B of X .

say $B = \{e_i\}_{i \in I} \cup \{x_0\}$. Define map

$$T: X \rightarrow \mathbb{F} \text{ by}$$

$$T\left(\sum_{i \in I_0, i \in I} c_i e_i + d \cdot x_0\right) = d$$

(i) well defined

$$x = y \Rightarrow T(x) = T(y)$$

since

$$T\left(\sum_{i \in I_0, i \in I} c_i e_i + d \cdot x_0\right)$$

$$= d_1$$

$$T\left(\sum_{i \in I_0, i \in I} c_i e_i + d_1 \cdot x_0\right)$$

$$= d_1$$

$$d_1 = d,$$

$$\therefore T(x) = T(y)$$

(ii) $T(\alpha x + y)$

$$\begin{aligned} &= T\left(\sum_{i \in I_0, i \in I} \alpha c_i e_i + (\alpha d_1 + d_2) x_0 + \sum_{i \in I_0, i \in I} \tilde{c}_i e_i\right) \\ &= \alpha d_1 + d_2 \\ &= \alpha T(x) + T(y) \end{aligned}$$

$$\text{and } (P(\lambda f))(x) = \lambda \frac{f(x) + f(-x)}{2}$$

Define $P: C([-1, 1]) \rightarrow C([-1, 1])$
by $(Pf)(x) = \frac{f(x) + f(-x)}{2}$

$$x \in [-1, 1] \quad = \lambda(Pf(x))$$

$$\text{now } (Pf)(x) = \frac{f(x) + f(-x)}{2}$$

we need to show that

$$P^2 = P$$

$$\Leftrightarrow P^2(f) = P(Pf) \quad P\left(\frac{f(x) + f(-x)}{2}\right) = \frac{1}{2}\left(\frac{f(x) + f(-x)}{2}\right)$$

$\forall f \in C[-1, 1]$

$$P(P(f)) = P(f)$$

$$P(Pf)(x) = \frac{(Pf)(x) + (Pf)(-x)}{2}$$

$$= \frac{Pf(x)}{2}$$

$$P(Pf) = P(f)$$

$$+ \frac{1}{2} \left(f(-x) + \frac{f(x)}{2} \right)$$

$$= \frac{f(x) + f(-x)}{2}$$

$$= (Pf)(x)$$

$$\therefore P^2 = P$$

4. $X \leftarrow$ vector space of polynomials

$$T: X \rightarrow \mathbb{C}^n$$

$$T(P) = (P(s_1), \dots, P(s_n)), \forall P \in X$$

$$(i) T(P_1 + P_2) = ((P_1 + P_2)(s_1), \dots, (P_1 + P_2)(s_n)) \\ = T(P_1) + T(P_2)$$

$$T(\lambda P) = (\lambda P(s_1), \dots, \lambda P(s_n)) = \lambda T(P)$$

$$(ii) T: X \rightarrow \mathbb{C}^n \text{ by}$$

$$T(P) = (P(s_1), \dots, P(s_n)), \forall P \in X$$

$$\text{Basis } X = \{1, x, \dots, x^{n-1}\}$$

$$\deg X = n$$

$$P = \sum_{i=0}^{n-1} \alpha_i x^i = \alpha_0 + \alpha_1 x + \dots + \alpha_{n-1} x^{n-1}$$

now, \mathbb{C}^n has deg of n .

$$(a) \deg X = \deg \mathbb{C}^n$$

$\Rightarrow X$ is isomorphic to \mathbb{C}^n

$\therefore T$ is one-one, onto and well defined

$$\therefore N_T = \{0\} \quad \therefore N_T \text{ is trivial.}$$

and T is onto, i.e. surjective.

Correction: $T: X \rightarrow \mathbb{C}^{n+1}$
 $s_0, s_1, s_2, \dots, s_n$ be
 distinct
 $T(P) = (P(s_0), P(s_1), \dots, P(s_n))$

$$(ii) N_T = \{P \in X \mid T(P) = (0, \dots, 0)\}$$

$$P(s_0) = 0, \dots, P(s_n) = 0$$

P of degree $n+1$ then
 by fundamental theorem of
 algebra it has $n+1$ roots

$$* \therefore P \notin N_T$$

$$\therefore N_T = \{0\}$$

$$\therefore \dim N_T = 0$$

N_T is trivial

By rank-nullity theorem

$$\dim N_T + \dim R_T = \dim X$$

$$\dim R_T + 0 = n$$

$$\dim R_T = n$$

but $\dim \mathbb{C}^{n+1} = n+1$
 \therefore Not surjective

Example: $v \in \mathbb{C}^{n+1}$
 $s.t. T(P) \neq v$
 $P(s_n) = 1$

$$(iii) \int_0^1 p(x) dx = m_1 p(t_1) + \dots + m_n p(t_n), \forall p \in X$$

$t_i \in [0, 1]$

$$\text{Proof: } \int_0^1 \sum_{i=0}^{n-1} \alpha_i x^i dx = \alpha_0 + \alpha_1 \int_0^1 x dx + \alpha_2 \int_0^1 x^2 dx$$

$$= \alpha_0 + \frac{\alpha_1}{2} + \frac{\alpha_2}{3} + \dots + \frac{\alpha_{n-1}}{n} \int_0^1 x^{n-1} dx$$

$$\text{now } m_1 p(t_1) + \dots + m_n p(t_n)$$

$$= m_1 (\alpha_0 + \alpha_1 t_1 + \dots + \alpha_{n-1} t_1^{n-1}) \\ + m_2 (\alpha_0 + \alpha_1 t_2 + \dots + \alpha_{n-1} t_2^{n-1}) \\ + m_3 (\alpha_0 + \alpha_1 t_3 + \dots + \alpha_{n-1} t_3^{n-1})$$

$$\vdots \\ \therefore m_n (\alpha_0 + \alpha_1 t_n + \dots + \alpha_{n-1} t_n^{n-1})$$

$$= \alpha_0 (m_1 + m_2 + \dots + m_n)$$

$$+ \alpha_1 (m_1 t_1 + m_2 t_2 + \dots + m_n t_n)$$

$$+ \alpha_2 (m_1 t_1^2 + m_2 t_2^2 + \dots + m_n t_n^2)$$

$$\vdots \\ \alpha_{n-1} (m_1 t_1^{n-1} + m_2 t_2^{n-1} + \dots + m_n t_n^{n-1})$$

for distinct $t_i \in [0, 1]$

Note: there are n equations, and n variables m_i . $\Rightarrow \Psi(p) = \sum m_j s_i(p)$

$\therefore \begin{bmatrix} 1 & t_1 & t_2 & \dots & t_n \\ t_1 & t_1^2 & t_1^3 & \dots & t_1^{n-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ t_{n-1} & t_{n-1}^2 & t_{n-1}^3 & \dots & t_{n-1}^{n-1} \end{bmatrix}$ if invertible then this exist

for $t_i \in (0, 1)$

$$t_1 \neq t_2 \neq t_3 \dots$$

and $t_i \neq t_j$ for $i \neq j$

\Rightarrow every column is different

\therefore the matrix is invertible.

we know $\dim(X) = n$
it follows that
 $\dim(\mathcal{X}') = n$
dual space
 $\downarrow p \rightarrow \int_0^1 p(x) dx$
 $\Psi(p) = \int_0^1 p(x) dx$

$\Psi: X \rightarrow \mathbb{C}$

linear

$$\Rightarrow \Psi \in \mathbb{C}'$$

$$\text{since } \Psi = \sum \alpha_j s_j$$

$$s_j: X \rightarrow \mathbb{C}, j=1, 2, \dots, n$$

$$p \rightarrow p(t_j)$$

$$\left\{ s_j \right\}_{j=1}^n$$

trial is ind. in dual space

$$\left\{ s_j \right\}_{j=1}^n$$

$$\Rightarrow \exists m_j, j=1, 2, \dots, n$$

$$\text{s.t. } \Psi = \sum_{j=1}^n m_j s_j$$

$$\Rightarrow \Psi(p) = \sum m_j s_j(p)$$

$$\int_0^1 p(x) dx$$

tutorial-4:1. $X \leftarrow$ finite dim. vector space

$$\exists M \in \alpha(X, X) \quad N \in \alpha(X, X)$$

linear map

similar if

$$\exists \text{ invertible } S \in \alpha(X, X) \text{ s.t.}$$

$$M = S N S^{-1}$$

(i) $M \sim N$ as $M = S N S^{-1}$ $M \sim N$ is M and N is similar① $M \sim M$ as for $S = I \in \alpha(X, X)$

$$M = I M I^{-1}$$

(Reference)

② $M \sim N$ then

$$\text{for } S' = S^{-1}$$

$$N = S^{-1} M S$$

$$= S' M S'^{-1}$$

(Symmetric)

$$\therefore N \sim M$$

③ if $M \sim N$ and $N \sim P$
then

$$M = S_1 N S_1^{-1}$$

$$N = S_2 P S_2^{-1}$$

$$\text{then } M = S_1 (S_2 P S_2^{-1}) S_1^{-1}$$

$$= (S_1 S_2) P (S_1 S_2)^{-1}$$

$$S = S_1 S_2$$

as S_1, S_2 invertible
 S is also invertible

$$\therefore M \sim P$$

(transitive)

(ii) wlog N is invertible. i.e.

$$\exists B \text{ s.t.}$$

$$NB = BN = I$$

$$\text{and } B = N^{-1}$$

now,

$$M = S N S^{-1}$$

$$MN = S N S^{-1} N$$

$$\text{and } NM = \underbrace{N S N S^{-1}}_{S^{-1}}$$

$$\text{now } MN = N^{-1} N S N S^{-1} N = N^{-1} (N S N S^{-1}) N$$

$$MN = N^{-1} (NM) N$$

∴ MN and NM are

similar for

$$S^{-1} = N$$

$$(iii) A = PBP^{-1}$$

$$\text{then } Ax = 0 \Leftrightarrow PBP^{-1}x = 0$$

$$\Leftrightarrow BP^{-1}x = 0$$

$$\Leftrightarrow B(P^{-1}x) = 0$$

$$\text{here } Np^{-1} = 0$$

so the $\nexists x \text{ s.t. } Ax = 0$

$$\text{and } B(P^{-1}x) = 0$$

will have two same basis

as if B basis = $\{x_1, \dots, x_n\}$ basis for $P^{-1}x$ = $\{P^{-1}(x_1), \dots, P^{-1}(x_n)\}$

$$\therefore \dim N_A = \dim N_B$$

$$\Rightarrow \dim R_A = \dim R_B$$

$$I(X, X) \rightarrow I(X, X)$$

$$A \rightarrow SA$$

$$y \in NA \Rightarrow Ay = 0$$

$$\Rightarrow SAy = 0$$

$$\Rightarrow y \in NSA \Rightarrow NA \subseteq NSA$$

similarly if $y \in NSA$

$$\Rightarrow SAy = 0$$

$$\Rightarrow Ay = 0$$

$$\Rightarrow y \in NA$$

$$\therefore NA = NSA$$

$$\text{now } A \rightarrow AS$$

$$N_A \rightarrow NSA$$

2. $X \leftarrow$ vector space over F
 $\{x_i = \{x_1, \dots, x_n\}\}$

Basis $\nrightarrow 1 \leq i \leq n$

$l_i : X \rightarrow F$

$$l_i(x_j) = s_{i,j} \quad \forall j = 1, \dots, n$$

$$s_{i,j} = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases}$$

$\ell = \{l_1, \dots, l_n\} \leftarrow$ Basis of X'

$l_i \in X'$

as l_i is a linear function

$$\pi : \alpha(X, F) \rightarrow F \times \underbrace{F \times \dots \times F}_{(X')}$$

$\Gamma \rightarrow (\Gamma(x_1), \text{n times } \Gamma(x_n))$
 here we have already proved
 that this is isomorphic

now to prove that

$\ell = \{l_1, l_2, \dots, l_n\}$ is the basis
 ① it spans $\alpha(X, F)$

Now as $\pi(\Gamma(n)) = (\Gamma(x_1), \Gamma(x_2), \dots, \Gamma(x_n))$

$$\begin{aligned} \pi(l_i(n)) &= (l_i(x_1), \dots, l_i(x_n), \dots, l_i(x_n)) \\ &= (0, 0, \dots, 0, 1, 0, \dots, 0) \end{aligned} \quad \text{ith place}$$

then $\pi(l_i(n))$
 for all $i \in \{1, 2, \dots, n\}$ is like

$$\pi(l_1(n)) = (1, 0, \dots, 0)$$

$$\pi(l_2(n)) = (0, 1, \dots, 0)$$

$$\vdots$$

$$\pi(l_n(n)) = (0, 0, \dots, 1)$$

$$\text{now, as } \sum a_i \pi(l_i(n)) = \pi(\sum a_i l_i(n)) = \sum a_i \pi(l_i(n))$$

$\forall a_i \in F$

or it spans F .

as π is isomorphic

$\sum a_i l_i(n)$ spans $\alpha(X, F)$

Also as s_i 's are lin ind, $l_i(n)$ are linearly ind
 (from prev q)

$\therefore \ell$ is the basis

$$\begin{aligned} \{s_i\}_{i=1}^m &= \{s(e_i)\}_{i=1}^m \quad ASW=0 \\ &\uparrow \quad \Rightarrow w \in NA \\ \text{Bijection } &i \mapsto \omega = \sum c_i e_i \\ &w = \sum c_i (s(e_i)) \\ \therefore \text{span is proved.} \end{aligned}$$

for basis: independent set

$$\begin{aligned} \{s^{-1}e_i\}_{i=1}^m &\text{ is injective} \\ l_i : X \rightarrow F & \\ L = \sum \beta_i l_i &= \sum L(n_j) l_j \end{aligned}$$

3. $X \leftarrow n\text{-dim vector space over } F$.

(i) ℓ be a non-zero linear function

$$\ell: X \rightarrow F$$

$$\dim(X) = \dim(R_\ell) + \dim(N_\ell)$$

$$\text{as } \ell \neq 0 \Rightarrow \dim(N_\ell) \neq \dim(X)$$

$$\therefore \dim(N_\ell) < \dim(X)$$

$$\text{also } \dim(R_\ell) < \dim(X)$$

$$\dim(N_\ell) > 0$$

$$\dim(R_\ell) > 0$$

$$0 < \dim(N_\ell) < \dim(X)$$

(ii) To prove: $f: X \rightarrow F$

$$f = \alpha \ell \Leftrightarrow N_\ell \subseteq N_f$$

Proof: (\Rightarrow) given $f = \alpha \ell$

$$\begin{aligned} \text{then if } x \in N_\ell \\ \text{then } \ell(x) = 0 \\ \Rightarrow \alpha \ell(x) = 0 \\ \Rightarrow f(x) = 0 \\ \therefore x \in N_f \end{aligned}$$

$$\therefore N_\ell \subseteq N_f$$

$$(\Leftarrow) \quad f: X \rightarrow F$$

$$\ell: X \rightarrow F$$

and α be some number in F

$$\text{then}$$

$$\text{if } N_\ell \subseteq N_f$$

then

$$f(N_\ell) = 0$$

also as f is a linear map

$$f(\alpha'x + y) = \alpha'f(x) + f(y)$$

$$x + N_\ell \rightarrow f(x) \text{ and } \ell(x + N_\ell) = \ell(x) + \ell(N_\ell)$$

Overall defined

$$x - y \in N_\ell \text{ now as } f(x) = g(x) \cdot \ell(x)$$

$$\Rightarrow x - y \in N_f$$

$$\Rightarrow f(x) = f(y)$$

$$\tilde{f}: X \rightarrow F$$

$$N_\ell \hookrightarrow [x]$$

$$\tilde{f}([x]) = f(x) \neq 0$$

$$\tilde{f}([x]) = \ell(x) \neq 0$$

$$\frac{f(x)}{\ell(x)} = \alpha$$

$$f = \alpha \ell$$

$$\Leftrightarrow f(y) = \alpha \ell(y)$$

$$f(y) = \alpha' \ell(y)$$

$$= \frac{f(x)}{\ell(x)} \ell(y)$$

$$\text{here } f(y) = \tilde{f}([y])$$

$$= \tilde{f}(\lambda[x])$$

$$= \lambda f(x)$$

(iii) V be a subspace of X

$$\dim X = n$$

$$g: X \rightarrow F$$

$$Ng = V$$

(ii) (E)

assume $N_f \subseteq N_f$

since $\dim(N_f) = n-1$

as non-zero let basis $v = \{v_1, v_2, \dots, v_{n-1}\}$

if $f = 0$

$N_f: X \rightarrow F$

$\leftarrow N_f = X$

dim $X = n$

also basis of X

can be made as $\{v_1, \dots, v_{n-1}, x_n\}$

see here on ℓ is a linear map
non-zero $\ell: X \rightarrow F$

$$\exists x \in X \text{ s.t. } (x \neq 0)$$

$$\ell(x) \neq 0$$

Also $\ell(n) = F \Rightarrow \forall$

$\exists x \in X$ is onto one

$$x_0 = \ell(x)$$

$$\ell(y) = v$$

$$v = \frac{x_0}{x_0} \cdot v = x_0 \left(\frac{v}{x_0} \right)$$

$$\ell(y) = x_0 \cdot \frac{v}{x_0} = \ell(x) \frac{v}{x_0}$$

$$\ell(y) = \ell\left(\frac{x_0 v}{x_0}\right)$$

$\therefore \forall v \in F$

$$\exists x \frac{v}{x_0} \text{ s.t.}$$

$$\ell\left(\frac{x_0 v}{x_0}\right) = \ell(v) \therefore \text{onto}$$

This proves isomorphism $\tilde{f}: X \rightarrow F$

isomorphism $|X| \cong F$ as this is our

$$\dim\left(\frac{X}{N_f}\right) = 1$$

$$\dim(X) - \dim(N_f) = 1$$

$$\dim(N_f) = \dim(X) - 1$$

See this prof soln

$$f(\alpha x + y) = g(\alpha x + y) \ell(\alpha x + y)$$

$$= (\alpha g(x) + g(y)) (\alpha \ell(x) + \ell(y))$$

then

$$\alpha g(x) + g(y) \in F$$

if not then f is not a linear map

$$f(x) \ell(y) = f(x) \tilde{f}([y])$$

$$\ell(y)$$

$$= \frac{f(x)}{\ell(x)} \lambda \ell(y)$$

$$= \lambda f(x) = f(y)$$

mineral case now, $g(x) = g(\sum \alpha_i v_i + \alpha_n x_n)$
as $f=0$ for $\alpha_n = 0$

so my function is defined as this.

$N_f = x \in N_e$
if $\dim N_f = n$ now
 $\dim N_e = n$
then $N_f \cong N_e$
 $\tilde{f}: \frac{x}{N_f} \rightarrow \mathbb{C}$

$$\tilde{f}: \frac{x}{N_e} \rightarrow \mathbb{C}$$

$$l + N_e \mapsto l(n)$$

$$\tilde{f}: \frac{x}{N_e} \rightarrow \mathbb{C} \quad x + N_e \mapsto f(x)$$

$$(iv) g: \mathbb{R}^2 \rightarrow \mathbb{R}$$

N_g is line $ax + by = 0$, $a, b \in \mathbb{R}$

$$g(x, y) = ax + by$$

$$g\left(\begin{pmatrix} x \\ y \end{pmatrix}\right) = ax + by$$

$$\text{then } \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} = \begin{pmatrix} x_2 \\ y_2 \end{pmatrix} \Rightarrow ax_1 = ax_2 \quad \text{and} \quad by_1 = by_2$$

$$\Rightarrow ax_1 + by_1 = ax_2 + by_2$$

∴ well defined

$$\text{now, } g\left(\begin{pmatrix} x \\ y \end{pmatrix} + \alpha\left(\begin{pmatrix} x' \\ y' \end{pmatrix}\right)\right) = g\left(\begin{pmatrix} x + \alpha x' \\ y + \alpha y' \end{pmatrix}\right) = a(x + \alpha x') + b(y + \alpha y')$$

$$= ax + by + \alpha(ax' + by')$$

$$= g\left(\begin{pmatrix} x \\ y \end{pmatrix}\right) + \alpha g\left(\begin{pmatrix} x' \\ y' \end{pmatrix}\right)$$

(iii) Let $V \subseteq X$ with $\dim(V) = n-1$

$$\frac{x}{V} \xrightarrow{f_1} \mathbb{C} \quad f_1(\beta[x_0]) = \beta \alpha \underset{\substack{\text{general} \\ \text{select}}}{=} f_1([x_0])$$

$$4. T(x_1, x_2) = (-x_2, x_1) \quad \text{in the Quotient space}$$

$$(i) T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

∴ T is a 2×2 matrix

$$\text{now } T(e_1) = (0, 1)$$

$$T(e_2) = (-1, 0)$$

$$\text{now } T\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}\right) = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$T\left(\begin{pmatrix} 0 \\ 1 \end{pmatrix}\right) = \begin{pmatrix} -1 \\ 0 \end{pmatrix}$$

$$\text{then } T\left(\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}\right) = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

$$\Rightarrow T(I) = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

$$\therefore A_x = T(x)$$

$$\text{s.t. } A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

$$A\left(\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}\right) = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} -x_2 \\ x_1 \end{pmatrix}$$

$$\begin{aligned} \Sigma \alpha_i v_i + \alpha_n x_n &= \Sigma \beta_i v_i + \beta_n x_n \quad (\alpha_n = \beta_n) \\ \Rightarrow g(\Sigma \alpha_i v_i + \alpha_n x_n) &= g(\Sigma \beta_i v_i + \beta_n x_n) \end{aligned}$$

(2) linear map :

$$\begin{aligned} g(\alpha x + y) &= g(\alpha \Sigma \alpha_i v_i + \alpha(\alpha_n x_n)) \\ &\quad + \Sigma \alpha_i v_i + \alpha_n x_n \\ &= \alpha \alpha_n + \alpha'_n \\ &= \alpha g(\) + g(\) \end{aligned}$$

is well defined or not

$$x + N_e = y + N_e \Leftrightarrow x - y \in N_e \subseteq N_f \Rightarrow f(x) = f(y)$$

as basis(N_e)

$$\begin{aligned} &= \{x_1, \dots, x_{n-1}\} \quad \text{Note } \frac{x}{N_e} \rightarrow x_n + N_e \\ &\text{if } f(x_n + N_e) = 0 \quad \text{basis } \frac{x}{N_e} \\ &\Rightarrow f(x_n) = 0 \quad \text{if } f(x_n + N_e) \neq 0 \\ &\Rightarrow x_n \in N_f \quad \text{basis } \frac{x}{N_e} \\ &\tilde{f} = \alpha \tilde{f} \text{ on } \frac{x}{N_e} \end{aligned}$$

$$\Rightarrow l(n) = \alpha f(n), \forall n \in X$$

$$x \xrightarrow{\pi} \frac{x}{V} \xrightarrow{f_1} \mathbb{C}$$

$$x \mapsto x + V$$

$$f := f_1 \circ \pi$$

$$f(x_0) = f_1(\pi(x_0)) = \alpha \neq 0$$

$$\text{now } Ng = V$$

$$\begin{aligned} &\leftarrow x \geq \text{Prove} \rightarrow \ker(f_1 \circ \pi) = \ker(\pi) \\ &\text{almost } n-1 \quad \leftarrow \text{to prove.} \end{aligned}$$

f_1 is injective

$\pi \leftarrow$ surjective

$$f_1(\pi(y)) = 0$$

$$\Rightarrow \pi(y) = 0$$

$$\Rightarrow y + V = 0 \Rightarrow y \in V$$

$$(ii) \quad T(\pi_L) = \sum_{i=1}^n A_{iL} \pi_i$$

wrt π_L bases

$$T\left(\begin{pmatrix} 1 \\ 2 \end{pmatrix}\right) = \begin{pmatrix} -2 \\ 1 \end{pmatrix} = A_{11} \begin{pmatrix} 1 \\ 2 \end{pmatrix} + A_{21} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$T\left(\begin{pmatrix} 1 \\ -1 \end{pmatrix}\right) = \begin{pmatrix} -1 \\ 1 \end{pmatrix} = A_{12} \begin{pmatrix} 1 \\ 2 \end{pmatrix} + A_{22} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$-2 = A_{11} + A_{21}$$

$$1 = 2A_{11} - A_{21}$$

$$\boxed{-\frac{1}{3} = A_{11}}$$

$$1 = -\frac{2}{3} - A_{21}$$

$$\boxed{A_{21} = -\frac{5}{3}}$$

$$-1 = 2A_{12} + 2A_{22}$$

$$1 = 2A_{12} - A_{22}$$

$$\boxed{-3 = 3A_{22}}$$

$$\boxed{A_{22} = -1}$$

$$\boxed{A_{12} = 0}$$

doubt
(see how to do
this properly)

$$\therefore A = \begin{bmatrix} -1/3 & 0 \\ -5/3 & -1 \end{bmatrix}$$

Tutorial - 5:

1. $\det(A) = D(A*_1, A*_2, \dots, A*_n)$

now

$$D(\alpha A*_1, A*_2, \dots, A*_n)$$

$$= \alpha D(A*_1, \dots, A*_n)$$

similarly $\alpha^n D(A*_1, \dots, A*_n) = D(\alpha A*_1, \alpha A*_2, \dots, \alpha A*_n)$

$$\alpha^n \det(A) = \det(\alpha A)$$

2. $A^2 = 0$

now $\det(\alpha I - A)$

Note A is 2×2 , so $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$

$$\text{s.t. } A^2 = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} a^2 + bc & ab + bd \\ ac + cd & d^2 + cb \end{bmatrix}$$

$$\text{also } \det(\alpha I - A) = \det\left(\begin{bmatrix} a-\alpha & -b \\ -c & \alpha-d \end{bmatrix}\right)$$

$\det(A) = \sum_{\sigma \in S_2} \text{sgn}(\sigma) a_{\sigma(1)1} a_{\sigma(2)2}$ for 2×2 matrix

$$= a_{11}a_{22} - a_{12}a_{21}$$

$$(I - A) = (I - a_{11})(I - a_{22})$$

$$- a_{12}a_{21}$$

$$= c^2 - ca_{22} - ca_{11} + a_{11}a_{22}$$

$$- a_{12}a_{21}$$

$$= c^2 - ca_{22} - ca_{11}$$

$$= c^2 \text{ as } a_{11} = -a_{21}$$

$$= (\alpha - a)(\alpha - d) - (-c)(-b)$$

$$= \alpha^2 - \alpha d - \alpha a + ad - cb$$

$$= \alpha^2 - \alpha(a+d) + ad - cb$$

$$\alpha^2 = d^2 = -bc$$

$$a+d=0$$

$$\text{or } c=0, b=0$$

as if $a+d=0$
then

$$\alpha^2 - \alpha(0) + (a)(-\alpha) + a^2 = \alpha^2$$

if $c=0, b=0$

then resulting zero

$\therefore \alpha^2$ only

$$\therefore \det(\alpha I - A) = \alpha^2$$

$$\text{or } \det(I - A) = c^2$$

3. As $\det(A^T) = \det(A)$

here $\det(A^T) = \det(-A) = (-1)^n \det(A) = \det(A)$

$$\Rightarrow \det(A) = 0$$

as n is odd

4. $AA^T = I$

→ orthogonal

$$\det(AA^T) = 1$$

$$\Rightarrow \det(A) \det(A^T) = 1$$

$$\Rightarrow \det(A)^2 = 1$$

$$\Rightarrow \det(A) = \pm 1$$

if $\det(A) = -1$ then let $A = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$ and $A^T = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$

$$A^T = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$$

5. S_n permutation group of n -symbols

$$\text{sgn}: S_n \rightarrow \{\pm 1\}$$
$$\sigma \mapsto \text{sgn}(\sigma)$$

now let $N(\sigma_1)$ be number of 2-cycles in σ_1 ,
and $N(\sigma_2)$ be number of 2-cycles in σ_2
Note not unique and for

$$N(\sigma_1 \sigma_2) \equiv N(\sigma_1) + N(\sigma_2) \pmod{2}$$

$$\& (-1)^{N(\sigma_1 \sigma_2)} = (-1)^{N(\sigma_1)} \cdot (-1)^{N(\sigma_2)}$$

$$\therefore \text{sgn}(\sigma_1 \circ \sigma_2) = \overset{\longleftarrow}{\text{sgn}(\sigma_1)} \cdot \text{sgn}(\sigma_2)$$
$$\forall \sigma_1, \sigma_2 \in S_n$$

Tutorial 6:

1. $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ (linear map)
 $\det(T(\alpha_1), \dots, T(\alpha_n)) = c \det(\alpha_1, \dots, \alpha_n)$
 $c = \det(T(e_1), T(e_2), \dots, T(e_n))$

as

$$\begin{aligned} \det(T(\alpha_1), \dots, T(\alpha_n)) &= \det \begin{bmatrix} T\alpha_1 & T\alpha_2 & \dots & T\alpha_n \end{bmatrix} \\ &= \det[T] \begin{bmatrix} \alpha_1 & \alpha_2 & \dots & \alpha_n \end{bmatrix} \\ &= \det[T] \det[\alpha_1 \alpha_2 \dots \alpha_n] \left(\frac{\det(AB)}{\det(A) \det(B)} \right) \\ &= \det(T(e_1), T(e_2), \dots, T(e_n)) \\ &\quad \det(\alpha_1, \alpha_2, \dots, \alpha_n) \end{aligned}$$

2. $A, B \in M_{n \times n}(\mathbb{C})$, $\lambda, \beta \in \mathbb{C}$ s.t

(i) λ is eigenvalue of A , β is eigenvalue of B

or $Ax = \lambda x$ (for some $x \in \mathbb{C}^n$)
 $By = \beta y$ (for some $y \in \mathbb{C}^n$)

$$A = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} \quad A - \lambda I = \begin{bmatrix} -\lambda & 1 \\ -2 & -3 - \lambda \end{bmatrix}$$

$$\begin{aligned} 3\lambda + \lambda^2 - (-2) &= 0 \\ \lambda^2 + 3\lambda + 2 &= 0 \\ \lambda^2 + \lambda + 2\lambda + 2 &= 0 \\ \lambda(\lambda + 1) + 2(\lambda + 1) &= 0 \\ \Rightarrow \lambda &= -2, -1 \end{aligned}$$

now, $A = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix}$

$$B = \begin{bmatrix} 1 & 4 \\ 3 & 2 \end{bmatrix} \quad \beta = 5, -2$$

then $A + B = \begin{bmatrix} 1 & 5 \\ 1 & -1 \end{bmatrix}$

$$(A + B) - \lambda'(I) = \begin{bmatrix} 1 - \lambda' & 5 \\ 1 & -1 - \lambda' \end{bmatrix}$$

$$(1 - \lambda')(-1 - \lambda') - 5 = 0$$

$$-(1 + \lambda')(1 - \lambda') = 5$$

$$-(1 - \lambda'^2) = 5$$

$$\lambda'^2 - 1 = 5$$

$$\lambda'^2 = 6$$

$$\lambda' = \pm \sqrt{6} \neq \lambda + \beta$$

$$(iii) AB = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix} = \begin{bmatrix} 3 & 2 \\ -11 & -14 \end{bmatrix}$$

$$(3-\lambda)(-14-\lambda) - (-11)(2) = 0$$

$$-42 - 3\lambda + 14\lambda + \lambda^2 + 22 = 0$$

$$\lambda = -11 \pm \frac{\sqrt{121+80}}{2}$$

$$= \frac{-11 \pm \sqrt{201}}{2} \rightarrow$$

Not
Perfect
square

3. λ ← eigenvalue of $A \in M_{n \times n}$ (IF)

λ^n ← eigenvalue of A^n
for some $x \neq 0$

$$\Rightarrow A^n x = \lambda^n x$$

$$A^2 x = A(Ax) = A(\lambda x)$$

$$= \lambda(Ax)$$

$$= \lambda \cdot \lambda x$$

$$= \lambda^2 x$$

for $n=2$ true

say $n=k$ true

$$\text{then, } A^k x = \lambda^k x$$

$$\text{for } A^{k+1} x = A(A^k x)$$

$$= A(\lambda^k x)$$

$$= \lambda^k (A x)$$

$$= \lambda^{k+1} x$$

∴ By induction

$$\lambda^n x = A^n x$$

or λ^n is eigenvalue of A^n

P → polynomial

$$P(A) = \sum_{i=0}^n \alpha_i A^i$$

for $A^0 = I$

$$P(A)x = \sum \alpha_i A^i x$$

$$= \sum \alpha_i \lambda^i x$$

$$P(A)x = P(\lambda)x$$

or $P(\lambda)$ is an eigenvalue of $P(A)$

4. $A \in M_{n \times n}(\mathbb{C})$, nilpotent matrix

$$A^r = 0 \quad r \in \mathbb{N}$$

Say λ is an eigenvalue of A
then

$$Ax = \lambda x$$

$$\lambda \neq 0, x \neq 0$$

$$\Rightarrow A^r x = \lambda^r x$$

$$\Rightarrow 0 = \lambda^r x$$

for this $\lambda \neq 0, x \neq 0$
not possible
so no eigenvalues.

5. $M \sim N$
 $S M S^{-1} = N$

$$\det(N - \lambda I) = \det(S N S^{-1} - \lambda I)$$

$$= \det(M - \lambda I)$$

$$\chi_N(\lambda) = \chi_M(\lambda)$$

\therefore same eigenvalues

Tutorial 7:

1. similar matrices
 $M \in \mathbb{C}^{n \times n}$

$$\exists S \in M_{n \times n}(\mathbb{C}) \text{ s.t } S^{-1}MS = N$$

$$\chi_N(S) = \det(N - S\mathbb{I})$$

$$\begin{aligned}\chi_N(t) &= \det(S^{-1}) \det(N - t\mathbb{I}) \\ &= \det(S^{-1}NS^T - tS^{-1}\mathbb{I}) \\ &= \det(N - t\mathbb{I})\end{aligned}$$

$$\therefore \chi_N(t) = \chi_M(t)$$

\therefore same eigenvalues.

2. as $\det T = \det T^T$

$$\det(T + \mathbb{I}t)^T = \det(T^T + \mathbb{I}t)$$

or

$$\chi_{T^T} = \chi_T$$

3. $T \in M_{n \times n}(\mathbb{C})$

n distinct eigenvalues $\{\lambda_1, \dots, \lambda_n\}$

first generally:

then as $T \sim \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}$, $\exists S \in M_{n \times n}(\mathbb{C})$ s.t.

$$STS^{-1} = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}$$

$$\Rightarrow TS = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}S$$

$$\Rightarrow TS^{-1} = \lambda_i S^{-1}$$

as S is invertible

or: $\{S^{-1}, \dots, S^{-n}\}$ form a basis of \mathbb{C}^n

$$h = \sum_{i=1}^n \alpha_i S^{-1}$$

this means that $T^m h = T^m (\sum \alpha_i S^{-1})$

$$\begin{aligned}&= \sum \alpha_i T^m S^{-1} \\ &= \sum \alpha_i \lambda_i^m S^{-1}\end{aligned}$$

(i) if $|\lambda_i| < 1 \forall i \in \{1, 2, \dots, n\}$

$$\text{as } \lambda_i^m \rightarrow 0$$

$$\text{Or } \sum \alpha_i \lambda_i^m S^{-1} \rightarrow 0$$

$$\therefore T^m h \rightarrow 0$$

as $m \rightarrow \infty$
 $\forall h \in \mathbb{C}^n$

(ii) for $r > 0$, $\exists n_0 = \max \left\{ \left\lceil \log_{|\lambda_i|} \left(\frac{r}{n_1 |\alpha_1| \|S\|_1} \right) \right\rceil + 1 \right\}$

s.t. a new j:

$$\begin{aligned} |\sum_{i=1}^n \lambda_i^m s_{ji}| &= \sum_{i=1}^n |\lambda_i| |\lambda_i^{m-1} s_{ji}| \\ &> \sum_{i=1}^n |\lambda_i| \left(\frac{r}{(n)(\lambda_i + 1)} \right) |\lambda_i| \\ &= \sum_{i=1}^n \frac{r}{n} = r \end{aligned}$$

$|\sum_{i=1}^n \lambda_i^m s_{ji}| > r$
or even row $\rightarrow \infty$
 $\therefore T^m n \text{ as } m \rightarrow \infty$
and $n \neq 0 \in \mathbb{C}^n$
 $\rightarrow \infty$

4. $Tf = \lambda f$ for T to have eigenvalues ($\neq 0$)

$$\int_0^x f(t) dt = \lambda f(x)$$

Note: $f(0) = 0 \quad \text{--- } \textcircled{1}$

$$\Rightarrow f(x) = \lambda f'(x)$$

$$\text{now, } \int \frac{1}{\lambda} = \int \frac{f'(x)}{f(x)}$$

$$\begin{aligned} \frac{1}{\lambda} x + C &= \ln |f(x)| \\ \Rightarrow f(x) &= C e^{x/\lambda} \end{aligned}$$

$$\text{Now } f(0) = 0 \Rightarrow C e^{0/\lambda} = 0$$

$\nexists x \in \mathbb{R}$
as $\lambda \neq 0 \Rightarrow C = 0$

but for $C=0$
 $f \equiv 0$ (eigenvector should be non zero)
 \therefore No eigenvalue of T .

5. $A, B \in M_{n \times n}(\mathbb{K})$

$$\begin{aligned} C &= (I - AB)^{-1} \\ C(I - AB) &= I \\ C - CAB &= I \\ C &= I + CAB \quad \text{--- } \textcircled{1} \end{aligned}$$

$$\begin{aligned} \text{now, } [I + BCA][I - BA] &= I - BA + BCA - BCA BA \\ &= I - BA + BCA(I - BA) \\ &= (I - BA)(I + BCA) \quad \text{--- } \textcircled{2} \end{aligned}$$

$$\text{and } I - BA + BCA - BCA BA = I - BA + BCA - BCA(I - BA) \quad \text{from } \textcircled{1}$$
$$= I$$

Tutorial Sheet 8:

1. $A \in M_{2 \times 2}(\mathbb{C})$ rank 1 matrix

or

$$A = \begin{bmatrix} a & ab \\ b & ab \end{bmatrix}$$

now,

$$\det(A - \lambda I) = (a-\lambda)(ab-\lambda) - ab = ab - a\lambda - tb\lambda + \lambda^2 - t^2ab$$

$$= 0$$

$$\lambda^2 = a\lambda + tb\lambda$$

$$\Rightarrow \lambda = 0 \text{ or } \lambda = a + tb$$

as λ has 2 distinct values $\Rightarrow A$ is diagonal

$\Rightarrow A$ is diagonalizable

2.

$$T = \begin{bmatrix} 0 & 0 & 0 & 0 \\ a & 0 & 0 & 0 \\ 0 & b & 0 & 0 \\ 0 & 0 & c & 0 \end{bmatrix} \rightarrow \text{Real matrix}$$

$$\chi_T(t) = \det \begin{bmatrix} t & 0 & 0 & 0 \\ -a & t & 0 & 0 \\ 0 & -b & t & 0 \\ 0 & 0 & -c & t \end{bmatrix}$$

Now $t^4 = t^4$
 $t^4 = 0$
 $\Rightarrow \lambda = 0$ is only eigenvalue of T

or by the formula

$$P(t) = \underbrace{(t-a)}_{\text{minimal poly of } T}, \text{ poly of } T$$

$$\Rightarrow P(T) = T = 0$$

$$\Rightarrow a = b = c = 0$$

3. A is 2×2 symmetric i.e. $A^T = A$

To prove: A is diagonalisable

Proof: As $A^T = A$

$$\begin{bmatrix} a & b \\ b & d \end{bmatrix} = A \quad \text{as } A = A^T$$

now

$$\chi_A(t) = \begin{vmatrix} a-t & b \\ b & d-t \end{vmatrix} = ad - at - dt + t^2 - b^2$$

$$= 0$$

$$t^2 - (a+d)t + ad - b^2 = 0$$

$$\lambda = (a+d) \pm \sqrt{a^2 + d^2 + 2ad - 4ad + b^2}$$

$$\lambda = \frac{a+d \pm \sqrt{(a-d)^2 + b^2}}{2}$$

\therefore diff $\lambda \Rightarrow A \sim$ diagonal matrix

4. $A \in M_{n \times n}(\mathbb{C})$ s.t
 $A^k = 0$ for some $k \in \mathbb{N}$

or as $A^k = 0$ we have a polynomial

$$f(x) = x^k \\ \text{s.t } f(A) = A^k = 0$$

$$\text{or } f(x) \in \langle p \rangle$$

minimal poly of A

$$\text{then } p(x) \mid f(x)$$

$$p(x) \mid x^k \Rightarrow p(x) = x^m \text{ where } m \leq k$$

as roots of minimal poly = eigenvalues

$$p(x) = x^m = 0 \\ \Rightarrow x = 0$$

or $x = 0$ is the eigenvalue of A

$$Ax = 0 \\ \text{for some } x \neq 0$$

$$\Rightarrow \chi_A(x) = x^n$$

$$\text{as deg } \chi_A = n$$

& also

roots of $\chi_A(x)$
 $=$ roots
 $\text{of } p(x)$

\Rightarrow By Cayley Hamilton theorem

$$\chi_A(A) = 0 \\ \Rightarrow A^n = 0$$

5. $N \in M_{2 \times 2}(\mathbb{C})$ s.t $N^2 = 0$ or $N \sim \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$

assume that $N \neq 0$ then

$\exists x \neq 0$ in \mathbb{C}^2 s.t
 $Nx \neq 0$

$\{x, Nx\}$ basis for \mathbb{C}^2

or N is cyclic nilpotent $\therefore N \sim \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$

$$\text{as } T\mathbf{x} = 0 \cdot \mathbf{x} + (1) (T\mathbf{x})$$

$$T^2\mathbf{x} = 0 \cdot \mathbf{x} + (0) T\mathbf{x}$$

$$\text{or } T \sim \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

6. $T: M_{n \times n}(F) \rightarrow M_{n \times n}(F)$ defined by

$$B \xrightarrow{T} AB$$

\uparrow
fixed

if $\lambda \in \sigma(T)$ true $\exists C \in M_{n \times n}(F) \neq 0$

$$\text{s.t. } T(C) = AC = \lambda C$$

$$\text{or } AC = \lambda C$$

$$(A - \lambda I)C = 0$$

$$\text{as } C \neq 0 \Rightarrow A - \lambda I = 0$$

$$\Rightarrow \lambda \in \sigma(A)$$

$$\therefore \lambda \in \sigma(T) \Rightarrow \lambda \in \sigma(A)$$

now if $\lambda \in \sigma(A)$ true

$$A - \lambda I = 0$$

$$\Rightarrow (A - \lambda I)C = 0 \text{ for non-zero } C$$

$$\Rightarrow T(C) - \lambda(C) = 0$$

$$\Rightarrow T(C) = \lambda(C)$$

$$\Rightarrow \lambda \in \sigma(T)$$

$$\text{so } \sigma(T) = \sigma(A)$$

as eigenvalues same \Rightarrow roots of minimal polynomial of T
 $=$ roots of minimal polynomial of A

as roots same & minimal poly. Both

$$\Rightarrow P_T = P_A$$

Tutorial - 9 :

1.
 (a) $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & -2 \\ 0 & 1 & 3 \end{bmatrix}$ $\chi_A(t) = -(t-2)(t-1)^2$
 now

Nullity $(A - I) = 2$
 OR
 $\text{R.M}(A - I) = 2$

$\therefore \begin{bmatrix} (1) \\ (1) \\ (2) \end{bmatrix}$

(b) $\begin{bmatrix} 1 & 2 & 0 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 1 \end{bmatrix}$ $\chi_A(t) = (t-1)^4$

now nullity $\begin{bmatrix} 0 & 2 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix} = 1 = \text{R.M}(A)$
 $A - I$

$\therefore J = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$

(c) $\begin{bmatrix} 0 & 1 & 1 \\ 2 & 1 & -1 \\ -6 & -5 & 3 \end{bmatrix}$ $\chi_A(\lambda) = -(\lambda-2)(\lambda^2-2\lambda-2)$
 $= -(\lambda-2)(\lambda - \left(\frac{2+\sqrt{4+8}}{2}\right))(\lambda - \left(\frac{2-\sqrt{12}}{2}\right))$
 $= -(\lambda-2)(\lambda-1-\sqrt{3})(\lambda-1+\sqrt{3})$

$P_A(\lambda) = (\lambda-2)(\lambda-1-\sqrt{3})(\lambda-1+\sqrt{3})$

$J = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 1+\sqrt{3} & 0 \\ 0 & 0 & 1-\sqrt{3} \end{bmatrix}$

2. $\chi_A(\lambda) = (\lambda)^n$
 $P_A(\lambda) = (\lambda)^n$
 $\text{R.M}(A) = 1$

$J = \begin{bmatrix} 0 & 1 & & \\ & 0 & 1 & \\ & & 0 & 1 \end{bmatrix}_{n \times n}$

x_1 , s.t. $Ax_1 = 0$
 x_2 , s.t.
 $x_1 = Ax_2$

$$\begin{array}{l} \text{true } T^n x \\ \text{true } T^{n-2} x \quad \text{as } x_1 = T^{n-1} x \\ \vdots \qquad \vdots \\ x_n = x \end{array} \quad \frac{\cancel{T^n x}}{\cancel{x} \neq 0}$$

3. $J_r(\lambda)$ = Jordan block of λ with $r \times r$

$$J_r(\lambda) = \begin{bmatrix} \lambda & & & \\ & \ddots & & \\ & & \ddots & \\ & & & \lambda \end{bmatrix}_{r \times r}$$

$$T \sim \begin{bmatrix} J_{n_1}(\alpha) & 0 & 0 & 0 \\ 0 & J_{n_2}(\alpha) & 0 & 0 \\ 0 & 0 & J_{m_1}(\beta) & 0 \\ 0 & 0 & 0 & J_{m_2}(\beta) \end{bmatrix}$$

true minimal polynomial of

$$P_T(\lambda) = (\lambda - \alpha)^{s_1} (\lambda - \beta)^{s_2}$$

$$s_1 = \max\{n_1, n_2\}$$

$$s_2 = \max\{m_1, m_2\}$$

4. minimal poly

$$P_A(x) = (x-1)^3 (x-2)^2$$

of 5×5

$$\text{so } \chi_A(x) = (x-1)^3 (x-2)^2$$

$$\text{so } J = \begin{bmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} & 0 \\ 0 & \begin{pmatrix} 2 & 1 \\ 0 & 2 \end{pmatrix} \end{bmatrix}_{5 \times 5}$$

$$5. (x-1)^3 (x-2)^2 = \chi_A(x)$$

true Jordan forms:

$$P_A(x) = (x-1)(x-2)$$

$$\begin{pmatrix} (1, 1) & (1, 1) \\ (1, 1) & (2, 2) \end{pmatrix}$$

$$P_A(x) = (x-1)^2 (x-2)$$

$$\begin{pmatrix} (1, 1) & (1, 1) \\ (1, 1) & (2, 2) \end{pmatrix}$$

$$(x-1)^3 (x-2)^2$$

$$\begin{pmatrix} (1, 1) & (1, 1) & (1, 1) \\ (1, 1) & (0, 1, 1) & (0, 1, 1) \\ (0, 0, 1) & (0, 0, 1) & (0, 0, 1) \end{pmatrix}$$

$$\begin{pmatrix} (1, 1) & (1, 1) & (2, 1) \\ (1, 1) & (1, 1) & (0, 2) \end{pmatrix}$$

$$\rho_A(n) = (n-1)^3(n-2)$$

$$\left[\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 2 \\ 2 \end{pmatrix} \begin{pmatrix} 2 \\ 2 \end{pmatrix} \right]$$

$$(n-1)^3(n-2)^2$$

$$\left[\begin{pmatrix} 1 & 1 & 6 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \\ 2 \end{pmatrix} \begin{pmatrix} 0 \\ 2 \end{pmatrix} \right]$$

Tutorial-10:1. V is f.d. IPSfor $x, y \in V$

$$\text{To prove: } \langle x | y \rangle = \frac{1}{4} \sum_{k=0}^3 i^k \|x + i^k y\|^2$$

Proof:

$$\langle x | y \rangle = \operatorname{Re} \langle x | y \rangle + i \operatorname{Im} \langle x | y \rangle$$

$$\begin{aligned} \text{now, } \|x + y\|^2 &= \langle x + y | x + y \rangle \\ &= \|x\|^2 + 2\operatorname{Re} \langle x | y \rangle + \|y\|^2 \\ \|x - y\|^2 &= \|x\|^2 - 2\operatorname{Re} \langle x | y \rangle + \|y\|^2 \\ \Rightarrow \frac{\|x + y\|^2 - \|x - y\|^2}{4} &= \operatorname{Re} \langle x | y \rangle \\ \Rightarrow \frac{1}{4} \left[\|x + y\|^2 + i^2 \|x + i^2 y\|^2 \right] &= \operatorname{Re} \langle x | y \rangle \end{aligned}$$

$$\langle x | y \rangle = \operatorname{Re} \langle x | y \rangle + i \operatorname{Im} \langle x | y \rangle$$

$$i \langle x | y \rangle = i \operatorname{Re} \langle x | y \rangle - i \operatorname{Im} \langle x | y \rangle$$

$$\begin{aligned} \langle x | iy \rangle &= -i \operatorname{Re} \langle x | y \rangle + i \operatorname{Im} \langle x | y \rangle \\ &= \operatorname{Re} \langle x | iy \rangle + i \operatorname{Im} \langle x | iy \rangle \end{aligned}$$

$$\Rightarrow \operatorname{Re} \langle x | iy \rangle = \operatorname{Im} \langle x | y \rangle$$

$$\Rightarrow i \operatorname{Re} \langle x | iy \rangle = i \|x + iy\|^2 + \underbrace{i^3 \|x + i^3 y\|^2}_4$$

$$\begin{aligned} \text{now } \langle x | y \rangle &= \operatorname{Re} \langle x | y \rangle + i \operatorname{Im} \langle x | y \rangle \\ &= \operatorname{Re} \langle x | y \rangle + i [\operatorname{Re} \langle x | iy \rangle] \\ \langle x | y \rangle &= \frac{1}{4} \sum_{c=0}^3 i^c \|x + i^c y\|^2 \end{aligned}$$

2. V is IPS with ONB $\{x_1, \dots, x_n\} = B$
 $\alpha_1, \alpha_2, \dots, \alpha_n \in F$ (scalars)

Let $x = \sum_{i=1}^n c_i x_i$ true
To find: $x \in V$ s.t. $\langle x, x_i \rangle = \alpha_i \quad \forall i = 1, \dots, n$

$$\langle x | x_i \rangle = c_i \langle x_i | x_i \rangle$$

putting $c_i = \alpha_i$ we get

$$x = \sum \alpha_i x_i \quad \text{s.t.} \quad \langle x | x_i \rangle = \alpha_i$$

This is unique as if $x = \sum c_i x_i$
 $x = \sum \alpha_i x_i$ true
 $c_i = \alpha_i \quad \forall i$

3. (a) $\langle A | B \rangle = \text{tr}(AB^*)$ is inner product on $M_{n \times n}(\mathbb{C})$:

$$\begin{aligned} \textcircled{1} \quad \langle A + B | C \rangle &= \text{tr}((A+B)C^*) \\ &= \text{tr}(AC^* + BC^*) \\ &= \text{tr}(AC^*) + \text{tr}(BC^*) \\ &= \langle A | C \rangle + \langle B | C \rangle \end{aligned}$$

$$\begin{aligned} \textcircled{2} \quad \langle A | A \rangle &= \text{tr}(AA^*) = \sum_i \left(\sum_j a_{ij} a_{ji}^* \right) \\ &= \sum_i \left(\sum_j a_{ij} \bar{a}_{ij} \right) \end{aligned}$$

$$\text{as } a_{ij} \bar{a}_{ij} \geq 0 \Rightarrow \langle A | A \rangle \geq 0$$

$$\begin{aligned} \textcircled{3} \quad \langle CA | B \rangle &= \text{tr}(CA B^*) \\ &= C \text{tr}(AB^*) \\ &= C \langle A | B \rangle \end{aligned}$$

$$\textcircled{4} \quad \langle \overline{A} | B \rangle = \overline{\text{tr}(AB^*)} = \text{tr}(\overline{AB^*}) = \text{tr}(\overline{B} \overline{A^*})^T = \overline{\text{tr}((AB^*)^*)} = \overline{\text{tr}(BA^*)} = \langle B | A \rangle$$

$$(b) W = \text{span} \left\{ \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 1 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 0 \end{bmatrix}, \dots, \begin{bmatrix} 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 0 \end{bmatrix} \right\}$$

$$W^\perp = \{ \alpha \in V \mid \langle \alpha | B \rangle = 0 \ \forall B \in W \}$$

↓
autocomplement of W

$$\langle \alpha | B \rangle = 0 \ \forall B \in W$$

$$\Rightarrow \langle A | B \rangle = \text{tr}(AB^*) = 0 \ \forall B \in W$$

as this is true for every $B \in W$
for $B = \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 1 \end{bmatrix}$

$$B^* = \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 1 \end{bmatrix}$$

$$AB^* = \begin{bmatrix} a_{11} & a_{12} & \dots & : \\ a_{21} & : & & \\ \vdots & & & \\ \dots & a_{nn} & & \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 1 \end{bmatrix}$$

$$\text{tr}(AB^*) = a_{11} = 0 \quad \text{or} \quad a_{11} = 0$$

similarly $a_{ii} = 0 \ \forall i$

$\therefore W^\perp = \text{Subspace of all matrices with diagonal 0.}$

9. In \mathbb{C}^3

To find: orthonormal Basis (ONB) for

$$W = \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \\ i \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 1+i \end{pmatrix} \right\}$$

$$\alpha_1 = \begin{pmatrix} 1 \\ 0 \\ i \end{pmatrix}$$

$$\alpha_2 = \begin{pmatrix} 2 \\ 1 \\ 1+i \end{pmatrix} - \frac{\langle (2, 1, 1+i), (1, 0, i) \rangle}{\langle (1, 0, i), (1, 0, i) \rangle} \begin{pmatrix} 1 \\ 0 \\ i \end{pmatrix}$$

$$= \begin{pmatrix} 2 \\ 1 \\ 1+i \end{pmatrix} - \frac{\langle 2 \cdot 1 + 1 \cdot 0 + (1+i)(-i) \rangle}{\langle (1, 1 + i, -i) \rangle} \begin{pmatrix} 1 \\ 0 \\ i \end{pmatrix}$$

$$= \begin{pmatrix} 2 \\ 1 \\ 1+i \end{pmatrix} - \frac{(3-i)}{2} \begin{pmatrix} 1 \\ 0 \\ i \end{pmatrix}$$

$$= \begin{pmatrix} 2 - (3-i)/2 \\ 1 \\ 1+i - (3-i)/2 \end{pmatrix} = \begin{pmatrix} 2-3/2+i/2 \\ 1 \\ 1+i-3i/2-1/2 \end{pmatrix}$$

$$= \begin{pmatrix} 1/2+i/2 \\ 1 \\ 1/2-i/2 \end{pmatrix}$$

$$\frac{\alpha_1}{\|\alpha_1\|} = \frac{(1, 0, i)}{\sqrt{1 \cdot 1 + i(-i)}} = \frac{(1, 0, i)}{\sqrt{2}}$$

$$\frac{\alpha_2}{\|\alpha_2\|} = \frac{(1+i, 2, 1-i)}{\sqrt{1+i+4+1+i}} = \frac{(1+i, 2, 1-i)}{\sqrt{8}} = \frac{(1+i, 2, 1-i)}{2\sqrt{2}}$$

$$= \frac{(1/2+i/2, 1, 1/2-i/2)}{\sqrt{2}}$$

$$\therefore \text{ONB} = \left\{ \frac{\alpha_1}{\|\alpha_1\|}, \frac{\alpha_2}{\|\alpha_2\|} \right\}$$

(b) Best approximation of $(0, i, 0)$ in W is:

$$\beta = \langle \frac{\alpha_1}{\|\alpha_1\|} | (0, i, 0) \rangle \frac{\alpha_1}{\|\alpha_1\|} + \langle \frac{\alpha_2}{\|\alpha_2\|} | (0, i, 0) \rangle \frac{\alpha_2}{\|\alpha_2\|}$$

$$= \frac{1}{\sqrt{2}} \times \frac{1}{\sqrt{2}} \left\langle \left(\frac{1+i}{2}, 1, \frac{1-i}{2} \right) \middle| (0, i, 0) \right\rangle \left(\frac{1+i}{2}, 1, \frac{1-i}{2} \right)$$

$$= \frac{1}{2}(i) \left(\frac{1+i}{2}, 1, \frac{1-i}{2} \right)$$

5. $M_{n \times n}(\mathbb{C})$ IPS
 $\langle A | B \rangle = \text{tr}(AB^*) \quad \forall A, B \in M_{n \times n}(\mathbb{C})$

$$\begin{matrix} T_P: M_{n \times n}(\mathbb{C}) & \longrightarrow & M_{n \times n}(\mathbb{C}) \\ A & \longmapsto & P^{-1}AP \end{matrix}$$

P is
inv't

$$\text{now } \langle T_P(A) | B \rangle = \langle A | (T_P)^*(B) \rangle$$

$$\begin{aligned} & \text{to } (P^{-1}AP B^*) = \langle T_P(A) | B \rangle \\ & = \text{tr}(A P B^* P^{-1}) \\ & = \text{tr}(A [(P^*)^{-1} B P^*]^*) \\ & = \langle A | (P^*)^{-1} B P^* \rangle \\ & = \langle A | T_{P^*}(B) \rangle = \langle A | (T_P)^*(B) \rangle \\ & \Rightarrow (T_P)^* = (T_P)^* \end{aligned}$$

6. (ii) $A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$

then $A^* = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} = A \quad \therefore \text{Normal}$

now $\det(A - \lambda I) = (\lambda-1)^2 - 1 = (\lambda-1-1)(\lambda-1+1) = (\lambda-2)(\lambda)$

or \exists Basis s.t
 $A \sim \begin{bmatrix} 2 & 0 \\ 0 & 0 \end{bmatrix}$

now, $A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$

then $\text{Null} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} = \left\{ \lambda \mid \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \right\}$

$$x_1 + x_2 = 0$$

$\text{Null} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} = \text{span} \left\{ \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right\}$

so one of the U row is $\begin{pmatrix} 1 \\ -1 \end{pmatrix} \frac{1}{\sqrt{2}}$

now $\begin{array}{c} \nearrow (1,1) \\ \searrow (-1,-1) \\ \hline \end{array}$ is \perp to $(1, -1)$

$$\Leftrightarrow \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ 1/\sqrt{2} & -1/\sqrt{2} \end{bmatrix} = U \quad \text{s.t.} \quad \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ 1/\sqrt{2} & -1/\sqrt{2} \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} = \begin{bmatrix} \cdot & \cdot \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & 0 \end{bmatrix}$$

$$(ii) B = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} \quad B^* = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$$

$\therefore B$ is normal

$$\text{now, } (x-1)(x-1) - (-2)(-2) = 0 \\ = (x-1)^2 - (2)^2 \\ = (x-1-2)(x-1+2) \\ = (x-3)(x+1)$$

$$\chi_B(x) = (x+1)(x-3)$$

$$\text{now } \text{num} \begin{bmatrix} 2 & 2 \\ 2 & 2 \end{bmatrix} = \text{span} \left\{ \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right\}$$

$$\text{num} \begin{bmatrix} -2 & 2 \\ 2 & -2 \end{bmatrix} = \text{span} \left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\}$$

$$\text{or } V = \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ 1/\sqrt{2} & -1/\sqrt{2} \end{bmatrix}$$

7. Normal Or $AA^* = A^*A$
and $A^m = 0$
for some $m \in \mathbb{N}$

then $m=1$ (trivial)

for $m>1$ we have

$$\begin{aligned} AA^* &= A^*A \\ \text{if } A^m &= 0 \end{aligned}$$

now as $\exists U \text{ s.t}$

$$U^* A V = I$$

$\uparrow \quad \uparrow$
diagonal
orthonormal Basis
(unitary operator)

$$\text{now } U^* A V = I$$

as A is nilpotent

$$(U^* A V)^m = U^* A^m V = 0$$

or
 $U^* A V$ is nilpotent

$$\text{diagonal matrix } 1^m = 0 \Rightarrow a_{ii}^m = 0$$

$$\therefore 1 \text{ is } 0 \Rightarrow U^* A V = 0 \Rightarrow U^* A = 0 \Rightarrow A = 0 \quad \therefore A \in D.$$

