

Ic-252

## INTERPRETATION OF PROBABILITY

### 1. Frequency Interpretation



Estimate of prob. is completely dependent on samples.

### 2. Classical Interpretation



Estimate of prob. based on concepts of likelihood ; based on knowledge of physical world. (without doing an experiment)

## PROBABILITY THEORY

⇒ Sample Space :- Set consists of all possible outcomes for an Experiment.

Eg:- Roll of a dice = {1, 6, 2, 3, 4, 5} = S

⇒ Event:- A subset of Sample Space .

Events can be represented as sets A, B, C

⇒ this enables us to define operations on the sets.

Eg: →  $C = A \cup B$ : Event C is made up of outcomes of either A or B or both.

$C = A \cap B$ : Event C is made up of outcomes from both A and B.

$C = A^c$  : Set of outcomes which are not in A.

$A \cap B$  : Set of outcomes in A which are also in B.

## AXIOMS OF PROBABILITY

\* Axiom - 1

$$0 \leq P(E) \leq 1$$

\* Axiom - 2

$$P(S) = 1$$

\* Axiom - 3

If two events E & F are "Mutually exclusive" then,

$$P(E \cup F) = P(E) + P(F)$$

Axiom-3 is also true for  $n$  mutually exclusive events. i.e.

$$P(\varepsilon_1 \cup \varepsilon_2 \dots \cup \varepsilon_n) = \sum_{j=1}^n P(\varepsilon_j)$$

## PROPERTIES

1.  $P(\varepsilon^c) = 1 - P(\varepsilon)$

Proof :→

we know,  
 $S = \varepsilon^c + \varepsilon$

so,  $P(S) = P(\varepsilon^c + \varepsilon)$

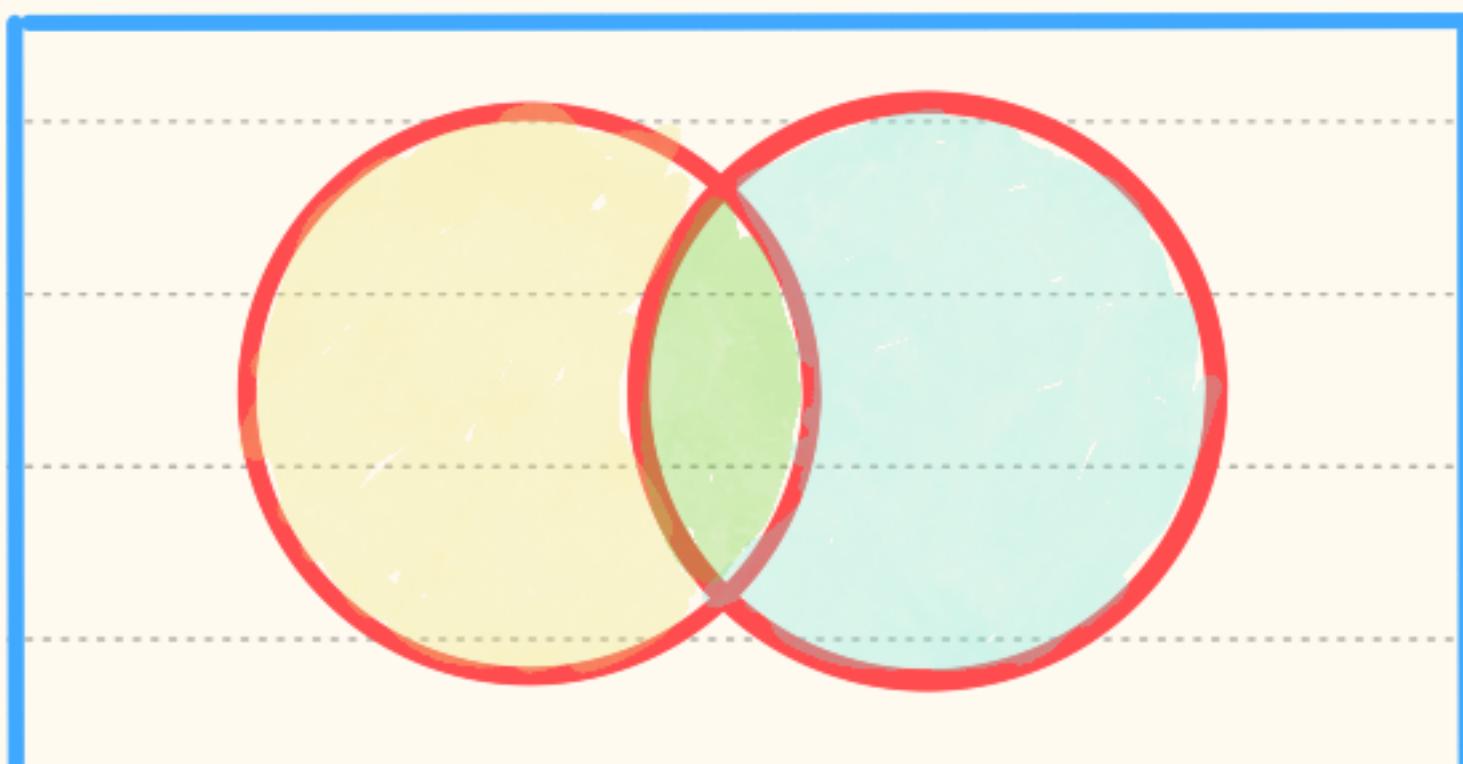
$$P(S) = P(\varepsilon^c) + P(\varepsilon) \quad [\text{Axiom-3}]$$

$$1 = P(\varepsilon^c) + P(\varepsilon) \quad [\text{Axiom-2}]$$

$$\Rightarrow P(\varepsilon^c) = 1 - P(\varepsilon)$$

2.  $P(\varepsilon \cup F) = P(\varepsilon) + P(F) - P(\varepsilon \cap F)$

Proof:→



$$(\Sigma \cup F) = [\Sigma - \Sigma F] \cup [\Sigma F] \cup [F - \Sigma F] \quad \text{--- (1)}$$

$$\begin{aligned} P(\Sigma \cup F) &= P(\Sigma - \Sigma F) \cup P(\Sigma F) \cup P(F - \Sigma F) \\ &= P(\Sigma - \Sigma F) + P(\Sigma F) + P(F - \Sigma F) \quad \text{[Axiom-3]} \end{aligned} \quad \text{--- (2)}$$

$$\Sigma = (\Sigma - \Sigma F) \cup (\Sigma F)$$

$$P(\Sigma) = P(\Sigma - \Sigma F) + P(\Sigma F) \quad \text{--- (3)}$$

$$P(F) = P(F - \Sigma F) + P(\Sigma F) \quad \text{--- (4)}$$

$$\begin{aligned} \text{So, } P(\Sigma \cup F) &= P(\Sigma - \Sigma F) + P(\Sigma F) + P(F - \Sigma F) \\ &= P(\Sigma - \Sigma F) + P(\Sigma F) + P(F - \Sigma F) + P(\Sigma F) - P(\Sigma F) \\ &= P(\Sigma) + P(F) - P(\Sigma F) \end{aligned}$$

$$\text{So, } P(\Sigma \cup F) = P(\Sigma) + P(F) - P(\Sigma \cap F)$$

NOTE: → In Proof,  $P(\Sigma \cap F)$  is written as  $P(\Sigma F)$ .

# BAYES RULE

$$P(E|F) = \frac{P(E \cap F)}{P(F)}$$

$P(E|F)$  = Probability of event E if event F has happened.

$$P(E|F) = \frac{P(EF)}{P(F)}$$

$$\Rightarrow P(E|F) \cdot P(F) = P(EF) - \textcircled{1}$$

$$\Rightarrow P(F|E) \cdot P(E) = P(EF) - \textcircled{1}$$

$$P(E|F) \cdot P(F) = P(F|E) \cdot P(E)$$

$$P(E|F) = \frac{P(F|E) \cdot P(E)}{P(F)}$$

Bayes Rule

finding probability of event E given some measurement F.

$P(F|\varepsilon)$  is used because  $F$  can be noisy  
Hence, we should use another probability measure which quantifies the uncertainty in  $F$ .

Chances of labelling  $c_i$  for measurement  $F$ .

$$P(c_i|F) = \frac{P(c_i F)}{P(F)} = \frac{P(F|c_i) P(c_i)}{P(F)}$$

$$S = \bigcup_{i=1}^R c_i \quad (\text{Also expressed as } \underline{\bigcup_i c_i})$$

Union of Mutually exclusive events

$$F = \bigcup_i F c_i$$

$$P(F) = \sum_i P(F c_i)$$

$$P(F) = \sum_i P(c_i) P(F|c_i) = \sum_{j=1}^R P(F \cap B_j)$$

Total probability of  $F$  over the sample space  $S$ .

Likelihood:  $P(F|C_i)$  assuming  $F \rightarrow C_i$   
what are chances of this corresponding

Prior: chances of that class actually being present.

Theorem: → Multiplication rule of P.

\*

$$P(A_1 \cap A_2 \cap \dots \cap A_n) = P(A_1) P(A_2 | A_1) P(A_3 | A_2 \cap A_1) \dots P(A_n | A_1 \cap A_2 \cap \dots \cap A_{n-1})$$

Proof: →

$$\begin{aligned} RHS &= P(A_1) \cdot \frac{P(A_2 \cap A_1)}{P(A_1)} \cdot \frac{P(A_3 \cap A_2 \cap A_1)}{P(A_2 \cap A_1)} \cdot \dots \cdot \frac{P(A_n \cap A_2 \cap \dots \cap A_{n-1})}{P(A_1 \cap A_2 \cap \dots \cap A_{n-1})} \\ &= P(A_1 \cap A_2 \cap A_3 \cap \dots \cap A_n) \end{aligned}$$

Assumption →  $P(A_1 \cap \dots \cap A_{n-1}) > 0$

This would make all the terms in denominator  $> 0$ .

# Conditional Version of Law of Total Probability.

$$P(A|C) = \sum_{j=1}^k P(B_j|C) P(A|B_j \cap C)$$

Proof:

$$\frac{P(A \cap C)}{P(C)} = \sum_{j=1}^k \frac{P(B_j \cap C)}{P(C)} \frac{P(A \cap B_j \cap C)}{P(B_j \cap C)}$$

$$= \sum_{j=1}^k \frac{P(A \cap B_j \cap C)}{P(C)}$$

$$= \sum_{j=1}^k P(A \cap B_j | C)$$

$$= \sum_{j=1}^k P(A|C, B_j)$$

$$= P(A|C)$$

Related to  
Concept of  
Total Prob.

# INDEPENDENCE

If:

$$P(A|B) = P(A) \quad \text{--- (I)}$$

i.e. A is not dependent on B.

$$P(A \cap B) = P(A) P(B) \quad \text{--- (II)}$$

Practical Example in DS:  $P(F_i | c_i)$

→ Likelihood of one attribute over a class.

A case of multiple attributes :

$$P(F_1, F_2, \dots, F_n | c)$$

→ Likelihood of many attributes over one class.

If  $F_1, F_2, \dots, F_n$  are independent then,

$$P(F_1 \cap F_2 \cap F_3 \cap \dots \cap F_n | c) = P(F_1 | c) P(F_2 | c) \dots P(F_n | c)$$

Decomposition of high-dimensional likelihood  
in low-dimensional likelihood.

# INDEPENDENCE OF COMPLEMENT

If A and B are independent then A and  $B^c$  are independent.

$$\Rightarrow P(A B^c) = P(A) P(B^c)$$

Proof:  $\rightarrow A = AB \cup AB^c$

$$\Rightarrow P(A) = P(AB) + P(AB^c)$$

$$\Rightarrow P(A) = P(A)P(B) + P(AB^c)$$

$$\Rightarrow P(AB^c) = P(A)(1 - P(B))$$

$$\Rightarrow P(AB^c) = P(A)P(B^c)$$

\* NOTE: →

Mutually exclusiveness and Independence are two completely different things.

# INDEPENDENCE OF MULTIPLE EVENTS

Example of 3 sets:

$$\text{If } P(A \cap B \cap C) = P(A) P(B) P(C)$$

$$\& P(A \cap B) = P(A) P(B)$$

$$\& P(B \cap C) = P(B) P(C)$$

$$\& P(C \cap A) = P(C) P(A)$$

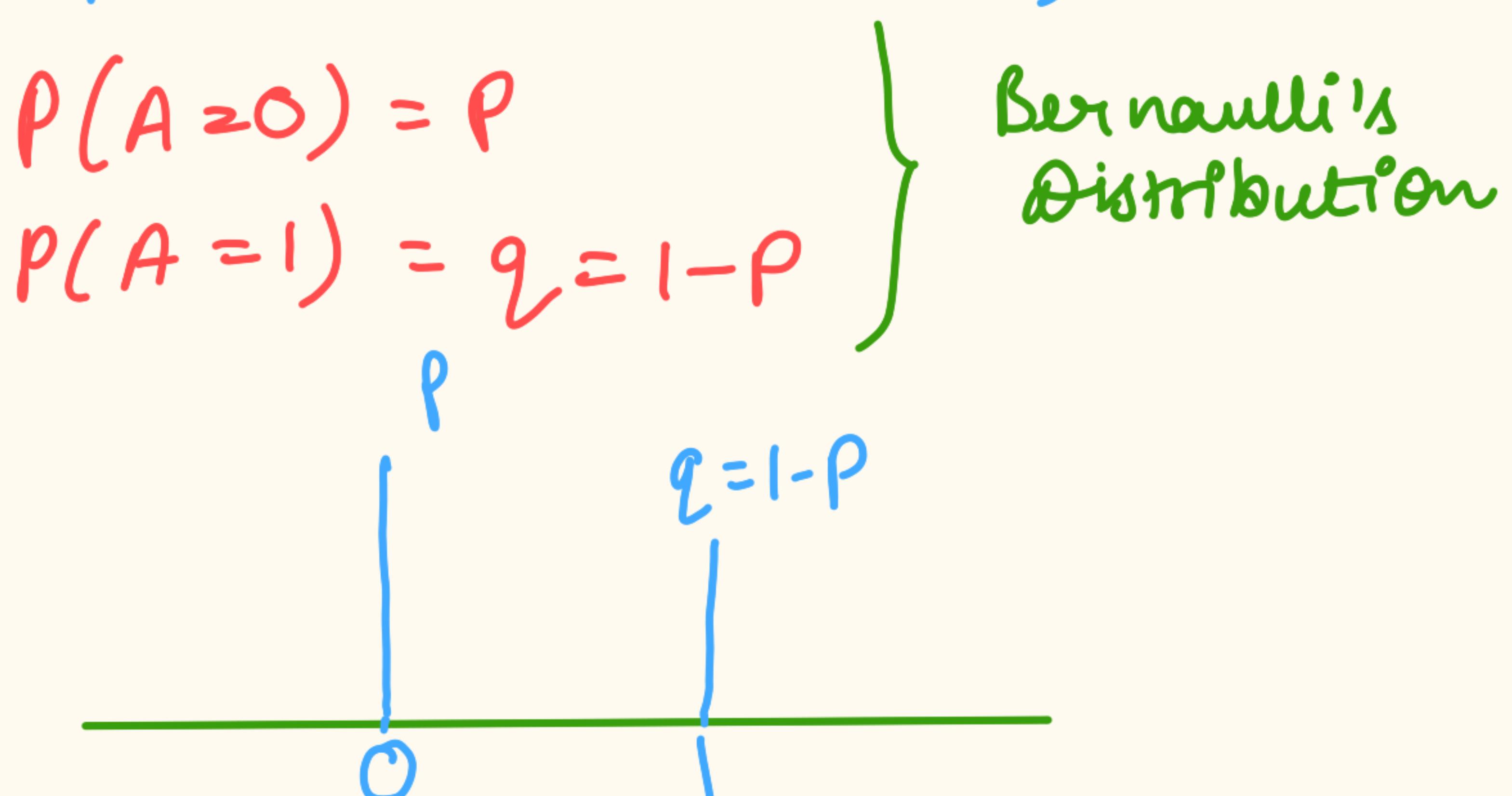
Then A, B, C are Independent.

For  $n$  general sets  $(A_1, A_2, \dots, A_n)$

If Independence of all subsets of  $\{A_1, A_2, A_3, \dots, A_n\}$  follows then  $\{A_1, A_2, \dots, A_n\}$  are independent.

## DISTRIBUTIONS

Independence  $\rightarrow$  a distribution of two independent events (Yes/No)



↳ Repeat this experiment (which has 2 outcomes) multiple times.

↳ One way to consider probability in such a scenario is given by Binomial Distribution.

## BINOMIAL DISTRIBUTION

If an exp. with 2 outcomes with probability  $p$  and  $q(1-p)$  is repeated  $k$  times, prob. of  $k$  success in  $n$  exp. is given by binomial dis.

Assumption: Each trial is Independent.

## BIRTHDAY PAIRING

Total No. of possible states = 365

No. of person =  $k$

Total no. of states =  $(365)^k$

↳ Total no. of outcomes.

To calculate no. of cases where atleast 2 share a birthday.

$$= 1 - \left[ \text{No. of cases in which no 2 people share a birthday.} \right]$$

$365^k P_k$  is no. of cases where no

two people share birthdays,

So, Probability that atleast 2 people share a birthday =  $\left[ 1 - \frac{365 p_k}{(365)^k} \right]$

Assumption  $1L < 365$ .

## BINOMIAL DISTRIBUTION

Eg: → out of 10 trials, prob. of one instance could be as follows,

$$P(n, k, p) = \underbrace{p \times p \times p \times p}_{4 \text{ times}} \times \underbrace{(1-p)(1-p)\dots}_{6 \text{ times}} = (1-p)$$

Other scenarios: → Different ways of selecting  $k$  out of  $n$ .

So, Eg: →  $P(1-p)(p) \dots$   
1)  $P(p)(1-p)\dots$   
etc.

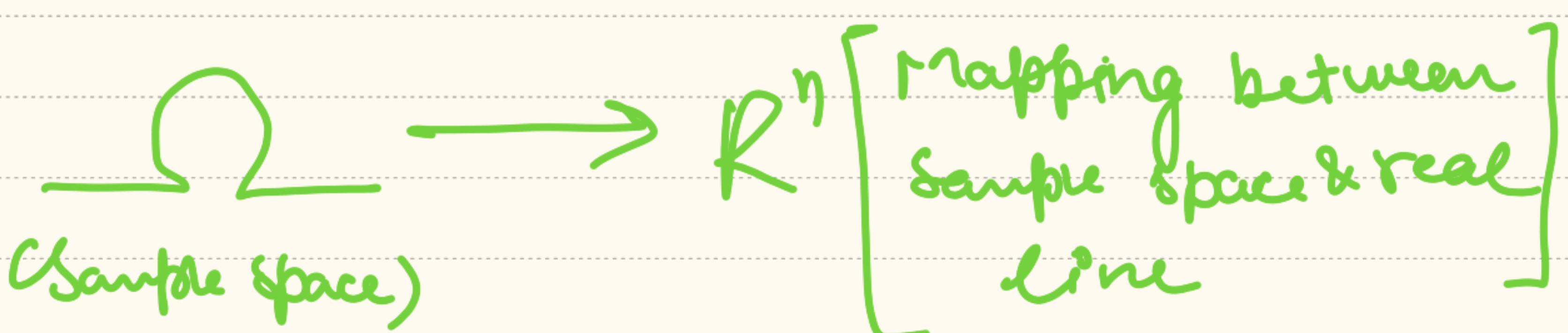
So,

Overall Probability ( $P(p, n, k)$ )

$$\text{So, } P(p, n, k) = {}^n C_R p^k (1-p)^{n-k}$$

Assigning probabilities to numbers on range of numbers rather than in terms of outcomes, events . . .

→ Mapping between the space of events , outcomes etc. to the space of numbers.



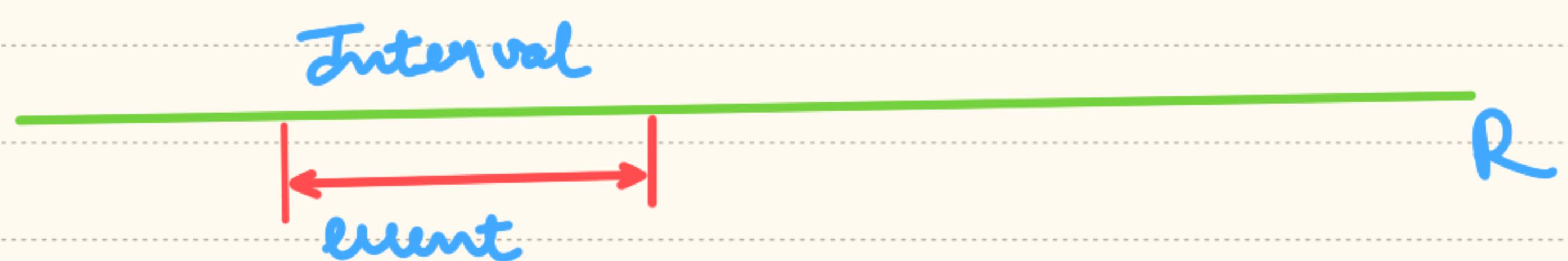
a function  $\Rightarrow$  Random Variable

Eg:  $\rightarrow$  R.V is the sum of the face values on the two dice. (Discrete Values)

$\rightarrow$  R.V. Recorded temperature on a sensor.

We could also plot the events on a real line to get R.V.

Eg.



Eg:  $\rightarrow$  Prop of Continuous R.V.

Like,  $P(a \leq X \leq b)$  ] Assigning prob.  
 $P(X \geq c)$   
 $P(X < c)$  } to different intervals on  $R$ .

Distribution function(f) or Cumulative distribution function(CDF)

$$f_X(x) = P\{X \leq x\}$$

Random Variable  
Defines Interval

## Properties of Distribution functions

1.  $F(+\infty) = 1 \text{ & } F(-\infty) = 0$

Proof:  $\rightarrow F(+\infty) = P(x \leq +\infty) = 1$   
 $F(-\infty) = P(x \leq -\infty) = 0$

2. It is a non decreasing function of  $x$ :

$x_1 < x_2$  then  $F(x_1) \leq F(x_2)$ .

Proof:  $\rightarrow$  since,  $x < x_1$  is subset of  
 $x < x_2$  so, probability of  $x \leq x_2$   
would be either equal to or greater  
than probability of  $x \leq x_1$ .

3.  $P(x_1 < x \leq x_2) = F(x_2) - F(x_1)$

Proof:  $\rightarrow$  since, Both are mutually exclusive

$$\{x \leq x_2\} = \{x < x_1\} \cup \{x_1 < x \leq x_2\}$$

$$\text{so, } P(x \leq x_2) = P(x \leq x_1) + P(x_1 < x \leq x_2)$$

$$\text{so, } F(x_2) = F(x_1) + P(x_1 < x \leq x_2)$$

Hence, Proved

# Continuous Random Variable

$$P(x \in B) = \int_B f(x) dx$$

$$P(a \leq x \leq b) = \int_a^b f(x) dx$$

$$P(X=a) = \int_a^a f(x) dx = 0$$

$$F(a) = P(X \in (-\infty, a]) = \int_{-\infty}^a f(x) dx$$

From fundamental theorem of calculus,

$$\frac{d}{da}(F(a)) = f(a)$$

↳ Described  $f(x)$  in terms  
of  $F(x)$ , This  $f(x)$  is probability  
density function. (P.d.f)

$$\star\star P\{x_1 < x(\xi) \leq x_2\} = F_x(x_2) - F_x(x_1)$$

$$P\{x_1 < x(\xi) \leq x_2\} = \int_{x_1}^{x_2} f_x(u) dx$$

$$\star\star P(x \leq x \leq x + \Delta x) \approx f(x) \Delta x$$

If  $\Delta x$  is sufficiently small,

$$f(x) = \lim_{\Delta x \rightarrow 0} \frac{P(x \leq x \leq x + \Delta x)}{\Delta x}$$

$$P(x=a) \neq f(a)$$

$$f(a) = \lim_{\Delta a \rightarrow 0} \frac{P(a \leq x \leq a + \Delta a)}{\Delta a}$$

