C:\Users\User\Documents\ENEL 387\ENEL 387 Final Report\Final Version Robot Code\Robot Code\Infrared.c

```
#include "stm32f10x.h"
      #include "clock.h"
     #include "ADC1.h"
     #include "PWM.h"
     #include "main.h"
     #include "I2C_stm32f10x.h"
6
     #include "Driver_I2C.h"
9
    void initInfrared()
10
11
      RCC->APB2ENR |= RCC_APB2ENR_IOPBEN ;
12
       //Turn PB7 into input, recieve from ultrasound echo
13
       GPIOB->CRH |= GPIO_CRH_CNF15_0;
14
15
16
       //Turn PB7 into input, recieve from ultrasound echo
17
       GPIOB->CRH |= GPIO_CRH_CNF14_0;
18
19
     }
```