C:\Users\User\Documents\ENEL 387\ENEL 387 Final Report\Final Version Robot Code\Robot Code\LCD_IO_Init.h

```
#include "stm32f10x.h"
     #include "clock.h"
 4
     //Commands for Hitachi 44780 compatible LCD controllers
 5
     #define LCD_8B2L 0x38 // ; Enable 8 bit data, 2 display lines
     #define LCD_DCB 0x0F // ; Enable Display, Cursor, Blink
 6
 7
     #define LCD_MCR 0x06 // ; Set Move Cursor Right
8
     #define LCD_CLR 0x01 // ; Home and clear LCD
     #define LCD_LN1 0x80 // ;Set DDRAM to start of line 1
#define LCD_LN2 0xC0 // ; Set DDRAM to start of line 2
9
10
11
12
     // Control signal manipulation for LCDs on 352/384/387 board
     // PB0:RS PB1:ENA PB5:R/W*
13
     #define LCD CM ENA 0x00210002 //
14
15
     #define LCD CM DIS 0x00230000 //
16
     #define LCD DM ENA 0x00200003 //
17
     #define LCD DM DIS 0x00220001 //
18
19
     //Initializes the LCD input and output
20
     void LCD_IO_Init();
21
     void commandToLCD(uint8 t data, int CORD);
22
```