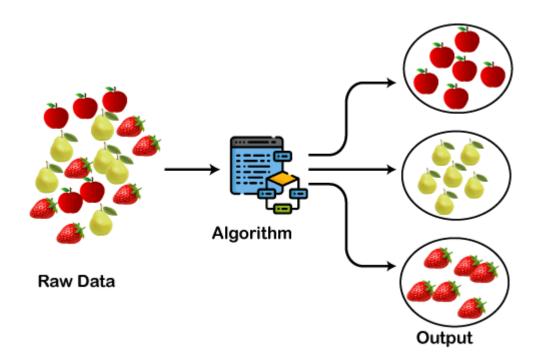
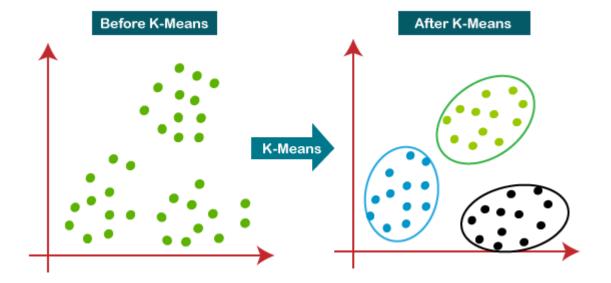
CLUSTERING

- Clustering can be achieved in the unsupervised learning method.
- Clustering defined as, way of grouping the data points into different clusters, consisting of similar data points. The objects with the possible similarities remain in a group that has less or no similarities with another group.



KMEANS:

- K-Means Clustering is an **Unsupervised Learning algorithm**, which **groups the unlabelled dataset into different clusters**.
- Here **K** defines the number of pre-defined clusters that need to be created in the process, as if K=2, there will be two clusters, and for K=3, there will be three clusters, and so on.
- It is an iterative process of assigning each data point to the groups and slowly data points get clustered based on similar features. The objective is to minimize the sum of distances between the data points and the cluster centroid, to identify the correct group each data point should belong to.



Pros:

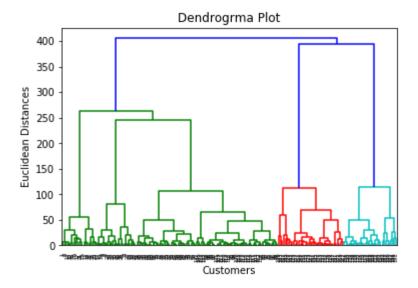
- High Performance
- Easy to Use
- Unlabelled Data
- Result Interpretation

Cons:

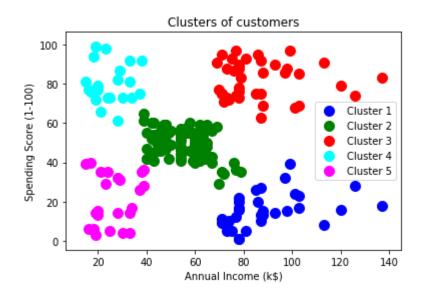
- Result Repeatability
- To much of Manual Effort Required
- Spherical Clustering Only
- Clusters Everything

AGGLOMERATIVE:

- Agglomerative is a **bottom-up** approach, in which the algorithm starts with taking all data points as single clusters and merging them until one cluster is left.
- we will find the optimal number of clusters using the Dendrogram for our model.



n_clusters=5: It defines the number of clusters, and we have taken here 5 because it is the optimal number of clusters.



Pros:

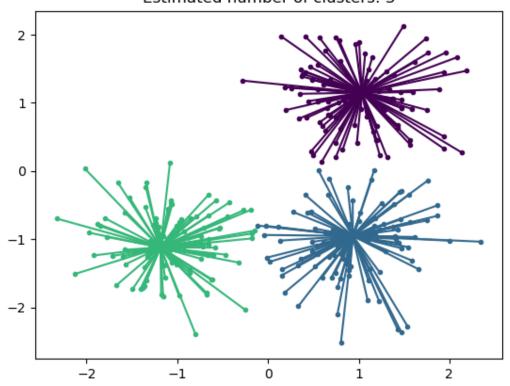
- We can obtain the optimal number of clusters from the model itself, human intervention not required.
- Dendrograms help us in clear visualization, which is practical and easy to understand.

- Not suitable for large datasets due to high time and space complexity.
- There is no mathematical objective for Hierarchical clustering.
- All the approaches to calculate the similarity between clusters has their own disadvantages.

AFFINITY PROPOGATION:

- Affinity Propagation, instead, takes as input measures of similarity between pairs of data points, and simultaneously considers all data points as potential exemplars.
- Real-valued messages are exchanged between data points until a high-quality set of exemplars and corresponding clusters gradually emerges

Estimated number of clusters: 3



• The inventors of affinity propagation showed it is **better for certain computer vision and computational biology tasks**, e.g. clustering of pictures of human faces and identifying regulated transcripts, than k-means, even when k-means was allowed many random restarts and initialized using PCA.

Pros:

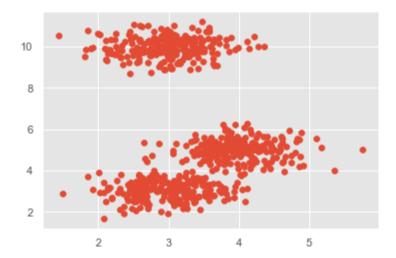
• The user doesn't need to specify the number of clusters (but does need to specify 'sample preference' and 'damping' hyperparameters).

Cons:

• The main disadvantage of Affinity Propagation is that it's quite slow and memory-heavy, making it difficult to scale to larger datasets.

MEANSHIFT:

- Mean-shift algorithm basically assigns the datapoints to the clusters iteratively by shifting points towards the highest density of datapoints i.e. cluster centroid.
- The difference between K-Means algorithm and Mean-Shift is that later one does not need to specify the number of clusters in advance because the number of clusters will be determined by the algorithm w.r.t data.



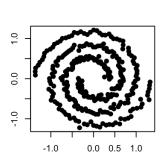
Pros:

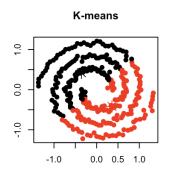
- It does not need to make any model assumption as like in K-means or Gaussian mixture.
- It can also model the complex clusters which have nonconvex shape.
- It only needs one parameter named bandwidth which automatically determines the number of clusters.
- No problem generated from outliers.

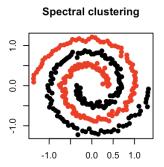
- ___We do not have any direct control on the number of clusters but in some applications, we need a specific number of clusters.
- It cannot differentiate between meaningful and meaningless modes.

SPECTRAL CLUSTERING:

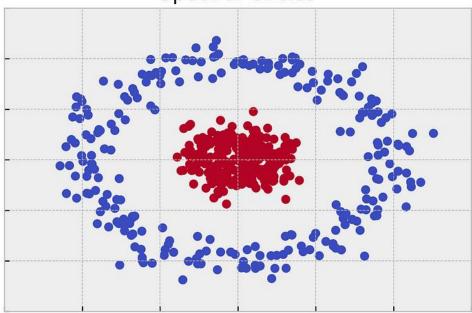
- Thus, spectral clustering is a graph partitioning problem.
- The nodes are then mapped to a low-dimensional space that can be easily segregated to form clusters. No assumption is made about the shape/form of the clusters.
- The goal of spectral clustering is to cluster data that is connected but not necessarily compact or clustered within convex boundaries.







Spectral Circles



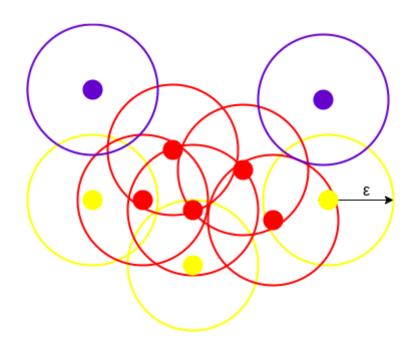
Pros:

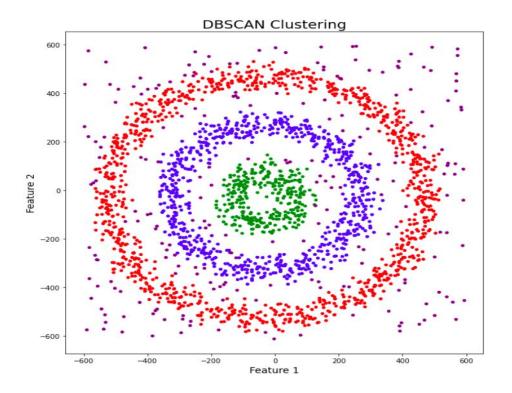
- practically work well even some assumptions are broken.
- simple, easy to implement.
- easy to interpret the clustering results.
- fast and efficient in terms of computational cost.

- uniform effect: often produce clusters with relatively uniform size even if the input data have different cluster size
- spherical assumption hard to satisfied: correlation between features break it, would put extra weights on correlated features
- cannot find non-convex clusters or clusters with unusual shapes
- different densities: may work poorly with clusters with different densities but spherical shape
- Sensitive to Outliers.

DBSCAN:

- **DBSCAN** stands for **D**ensity-**B**ased **S**patial **C**lustering of **A**pplications with **N**oise.
- It can identify clusters in **large spatial datasets** by looking at the local density of the data points.
- The most exciting feature of DBSCAN clustering is that it is **robust to outliers**.
- DBSCAN creates a circle of *epsilon* radius around every data point and classifies them into **Core** point, **Border** point, and **Noise**.





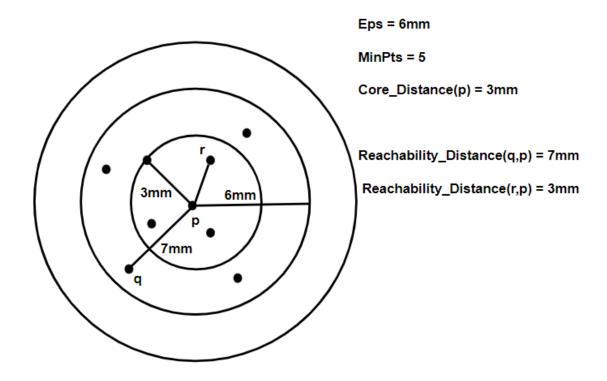
Pros:

- Handles irregularly shaped and sized clusters.
- Robust to outliers.
- Does not require the number of clusters to be specified.
- Less sensitive to initialization conditions.
- Relatively fast.

- Difficult to incorporate categorical features
- Requires a drop in density to detect cluster borders
- Struggles with clusters of varying density
- Struggles with high dimensional data

ORBITS:

- Ordering Points To Identify Cluster Structure (OPTICS)) is a density-based clustering technique that allows partitioning data into groups with similar characteristics.
- Its addresses one of the DBSCAN's major weaknesses. The problem of detecting meaningful clusters in data of varying density.
- In a density-based clustering, clusters are defined as dense regions of data points separated by low-density regions.
- It adds two more terms to the concepts of DBSCAN clustering. They are: **Core Distance and Reachability Distance**.



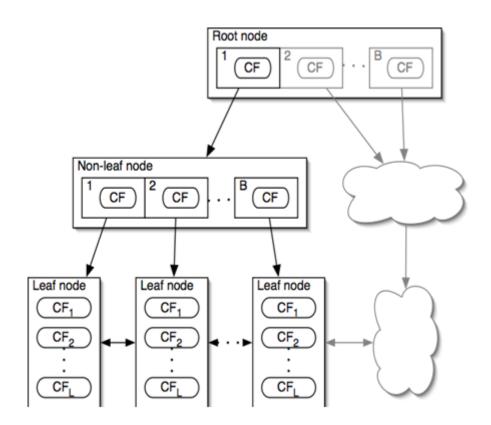
Pros:

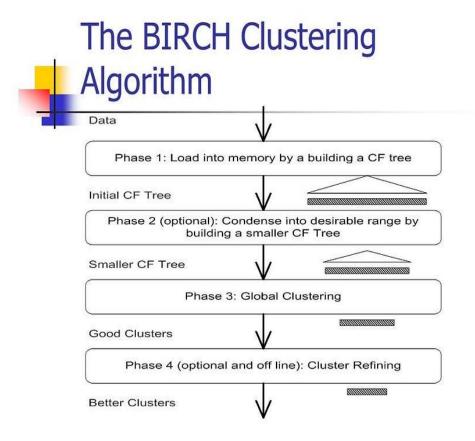
- OPTICS clustering doesn't require a predefined number of clusters in advance.
- Clusters can be of any shape, including non-spherical ones.
- Able to identify outliers (noise data)

- It fails if there are no density drops between clusters.
- It is also sensitive to parameters that define density(radius and the minimum number of points) and **proper parameter settings require domain knowledge**.

BIRCH:

- BIRCH defined as **Balanced Iterative Reducing and Clustering hierarchies.**
- BIRCH summarizes **large datasets into smaller**, **dense regions** called **Clustering Feature** (CF) entries.
- It is possible for a CF entry to be composed of other CF entries. Optionally, we can condense this initial CF tree into a smaller CF.
- **Global Clustering**: Applies an existing clustering algorithm on the leaves of the CF tree. A CF tree is a tree where each leaf node contains a subcluster. Every entry in a CF tree contains a pointer to a child node and a CF entry made up of the sum of CF entries in the child nodes. Optionally, we can refine these clusters.





Pros:

• Finds a good clustering with a single scan and improves the quality with a few additional scans.

Cons:

• works well only for **spherical shape clusters and numeric attributes**.