

TensorFlow:-

In Single Layer Perceptron only contains i/p\_layer and o/p\_layer and there is no hidden\_layer present in b/w them. It is very basic form of ANN and easy to use. It makes dot.product of weighted sum of i/p\_layer and i/p\_values and after we add i/p\_layer\_bias then we feed in to the o/p containing activation function. It gives o/p in terms of -1 to 1 & 0 to 1.

First read those files 1)"<https://www.edureka.co/blog/deep-learning-with-python/>" ,  
2)"<https://www.geeksforgeeks.org/introduction-to-tensorflow/>" ,  
3)"<https://www.javatpoint.com/cost-function-in-machine-learning>" ,  
4)"<https://chromium.googlesource.com/external/github.com/tensorflow/tensorflow/+/r0.10/tensorflow/g3doc/tutorials/mnist/pros/index.md>"<-----this is very important,  
5)"<https://shreyasshetty.github.io/2016/10/30/Reduction-indices-in-tensorflow/>"  
6)"<https://github.com/jalammar/simpleTensorFlowClassificationExample/blob/master/Basic%20Classification%20Example%20with%20TensorFlow.ipynb>"

note:-

\*Learning rate:

There are multiple ways to select a good starting point for the learning rate. A naive approach is to try a few different values and see which one gives you the best loss without sacrificing speed of training. We might start with a large value like 0.1, then try exponentially lower values: 0.01, 0.001, etc. When we start training with a large learning rate, the loss doesn't improve and probably even grows while we run the first few iterations of training. When training with a smaller learning rate, at some point the value of the loss function starts decreasing in the first few iterations. This learning rate is the maximum we can use, any higher value doesn't let the training converge. Even this value is too high: it won't be good enough to train for multiple epochs because over time the network will require more fine-grained weight updates. Therefore, a reasonable learning rate to start training from will be probably 1-2 orders of magnitude lower.

\*Training data:

Maybe the number of training data is very less in volume for the model to learn, try including more data by sampling, augmentation techniques.

\*Epochs:

In your code, decrease the display\_step to 10, so for every 10 steps you will print the loss, if the loss is not changing much for continuous steps, you can bring the epochs number to that range where the loss is not changing. Else if you keep large number of epochs, your model will overfit.

\*Test Data:

Test data should be unseen data from the train instances. Try to give different variants of test data. Including train\_test\_split to 80/20 % and do data shuffling before splitting train and test data.

SINGLE LAYER PERCEPTRON

PROGRAMME:-

```

# Import the MINST dataset to see this datasets read
"https://www.tensorflow.org/tutorials/keras/classification"
from tensorflow.examples.tutorials.mnist import input_data
mnist = input_data.read_data_("/tmp/data/", one_hot=True)

import tensorflow as tf
import matplotlib.pyplot as plt

step.1:-
# Parameters :-First of all, we define some parameters for training our model, like:

learning_rate = 0.01
training_epochs = 25
batch_size = 100
display_step = 1          ##display_step to 1, so for every 1 steps you will print the
loss.
Step.2:-
# tf Graph Input :-Then we define placeholder nodes for feature and target vector.
x = tf.placeholder("float", [none, 784])          # MNIST data image of shape
28*28 = 784
y = tf.placeholder("float", [none, 10])          # 0-9 digits recognition =>
10 classes Bcz o/p has only 1D.

MODEL CREATION:-
Step.3:-
# Set model weights:-Then, we define variable nodes for weight and bias.
W = tf.Variable(tf.zeros([784, 10]))    ##Here 784 rows bcz i/p layer has 784
neurons is there,and then it fed to the o/p_layer of containing 10 neurons('
[784,10])
b = tf.Variable(tf.zeros([10]))          ##Here bias is adding after dot product of
i/p and i/p_layer weights,.'.it has 10_neuron o/p.So we need to add bias for only
shape of 10.i,e,,,tf.zeros([10])

Step.4:-
# Constructing the model
    ##linear_model is an operational node which calculates the hypothesis for
the linear regression model.
    ##linear_model = W*X + b
    ##output = tf.nn.activation_fun(tf.matmul(x, w)+b)
activation=tf.nn.softmaxx(tf.matmul (x, W)+b) # Softmax of function

Step.5:-
# Minimizing error using cross entropy
    ####(One of the commonly used loss functions for classification is
cross-entropy loss.for linear rigression we can use(1)Means_Errors, 2)MSE, 3)MAE)
    The binary Cost function is a special case of Categorical cross-entropy,
where there is only one output class. For example, classification between red
andblue.

```

To better understand it, let's suppose there is only a single output variable Y

Cross-entropy(D) = - y\*log(p) when y = 1

Cross-entropy(D) = - (1-y)\*log(1-p) when y = 0 )

Step.6:-

##We can specify a loss function just as easily. Loss indicates how bad the model's prediction was on a single example; we try to minimize that while training across all the examples. Here, our loss function is the cross-entropy between the target and the model's prediction:

```
cross_entropy = y*tf.log(activation) ##or## cross_entropy =  
tf.reduce_mean(-tf.reduce_sum(y_ * tf.log(y), reduction_indices=[1]))
```

For linear ligrression for finding loss we use Mean Square Error(MSE)  
loss = tf.reduce\_sum(tf.square(output - y))/2\*n\_samples

Step.7:-

#Note that tf.reduce\_sum sums across all classes and tf.reduce\_mean takes the average over these sums.reduction\_indices=[1] means indexing of row(0) or column(1) ,here 1 is specified bcz o/p or y is in the form of column.Therefore we need to assign reduction\_indices=[1]

```
cost = tf.reduce_mean(-tf.reduce_sum(cross_entropy, reduction_indice = 1))  
##is same as explained above
```

```
# t1 is a tensor [[1, 2, 3],  
#                [4, 5, 6],  
#                [7, 8, 9],  
#                [10, 11, 12]]  
t2 = tf.reduce_max(t1, reduction_indices=[0])  
# t2 is the tensor [10, 11, 12]  
t3 = tf.reduce_max(t1, reduction_indices=[1])  
# t3 is the tensor [3, 6, 9, 12]
```

Step.8:-

##Now that we have defined our model and training loss function, it is straightforward to train using TensorFlow. Because TensorFlow knows the entire computation graph, it can use automatic differentiation to find the gradients of the loss with respect to each of the variables.

```
optimizer = tf.train.GradientDescentOptimizer(learning_rate).minimize(cost)
```

### learning\_rate:-if we want to apply gradient decent the slope will calculate to measure low cost(loss).it will flow down untill minimum cost(loss) is reached.learning\_rate gives steps to reach low\_cost quickly. it will ecicutes in less time.

Step.9:-

```
#Plot settings
```

```
avg_set = []
```

```
epoch_set = []
```

```
step.10:-
```

```
# Initializing the variables where
```

```
init = tf.initialize_all_variables()
```

```
step.11:-
```

```
# Launching the graph
```

```
with tf.Session() as sess:
```

```
    sess.run(init)
```

```
Step.12:-
```

```
# Training of the cycle in the dataset
```

```
    for epoch in range(training_epochs):
```

```
        avg_cost = 0.
```

```
        total_batch = int(mnist.train.num_example/batch_size)
```

```
##num_example is equal to the number of test images you are feeding into the API.
```

```
Step.13:-
```

```
# Creating loops at all the batches in the code
```

```
    for i in range(total_batch):
```

```
batch_xs, batch_ys = mnist.train.next_batch(batch_size)
```

```
Step.14:-
```

```
# Fitting the training by the batch data
```

```
sess.run(optimizer, feed_dict = {x: batch_xs, y: batch_ys})
```

```
Step.15:-
```

```
    # Compute all the average of loss
```

```
avg_cost += sess.run(cost, feed_dict = {x: batch_xs, y: batch_ys})    ##total
```

```
batch    ##+= Add AND assignment operator. It adds the right operand to the left  
operand
```

```
    and assign the result to the left operand. C += A is equivalent to C = C +  
A.
```

```
Step.16:-
```

```
# Display the logs at each epoch steps ##in order to display logs(values like  
accuracy,loss,,ect are displayed in the tensorboard) at each epoch steps,we need to  
make display_step is equal to epoch.Therefore here we declared it as remainder of  
epoch & display_step is equal to 0.Then only it displays logs at each epoch steps.
```

```
    if epoch % display_step==0:
```

```
        print("Epoch:", '%04d' % (epoch+1), "cost=", "{:.9f}".format (avg_cost))
```

```
        avg_set.append(avg_cost) epoch_set.append(epoch+1)
```

```

##Here we assign or we add the value of avg_cost and epoch+1 into set
print ("Training phase finished")

plt.plot(epoch_set,avg_set, 'o', label = 'Logistics Regression Training')
plt.ylabel('cost')
plt.xlabel('epoch')
plt.legend()
plt.show()

```

Step.17:-

# Test the model

```
correct_prediction = tf.equal (tf.argmax (activation, 1),tf.argmax(y,1))
```

Parameters used in Test the model:-

1)argmax:-function returns indices of the max element of the array in a particular axis.

```
tf.argmax(array, axis = None, out = None)
```

Parameters :

array : Input array to work on

axis : [int, optional]Along a specified axis like 0 or 1

out : [array optional]Provides a feature to insert output to the out array and it should be of appropriate shape and dtype

2)tf.equal:-The tf. equal() operator is an elementwise operator. Assuming x and y are the same shape (as they are in your example) tf. equal(x, y) will produce a tensor with the same shape, where each element indicates whether the corresponding elements in x and y are equal.

Example `a = tf.equal([1., 2.], [1., 3.])`----->it gives o/p in the form of boolean i,e,, [ True False]

Actual explanation:- `correct_prediction = tf.equal (tf.argmax (activation, 1),tf.argmax(y,1))`:-

\*`tf.argmax(activation, 1)` means:-First it will gives the max index of

column(axis=1) in activation i,e,, our predicted value.example[1,2,3,4,5]

\*`tf.argmax(y,1)` means:-First it will gives the max index of column(axis=1) in y i,e,, our actual value.example[1,2,3,4,5]

\*`tf.equal (tf.argmax (activation, 1),tf.argmax(y,1))` means:-It will compair both pedicted and actual values if both are same it gives True or it gives False i,e,,[True,True,True,True,True]

Conclusion:-

From the above example it gives [True,True,True,True,True] it maens actual valu is equal to predicted value.i,e,, 100% accuracy(example is given by me)

Step.18:-Last step:-

```
# Calculating the accuracy of dataset
accuracy = tf.reduce_mean(tf.cast (correct_prediction, "float"))
print("Model accuracy:", accuracy.eval({x:mnist.test.images, y: mnist.test.labels}))
```

Parameters:-

\*tf.cast:-syntax:-tf.cast(x, dtype, name=None)

The "tf. cast" function casts a tensor to new type. Therefore due to this it will convert boolean data\_type into folat\_data\_type. in order to find mean of accuracy.

##last step is very very imp bcz we use paceholder .Therefore in the last we need to assign the datapoints.

here in our datasets we Import the Fashion MNIST dataset

This guide uses the Fashion MNIST dataset which contains 70,000 grayscale images in 10 categories. The images show individual articles of clothing at low resolution (28 by 28 pixels), as seen here:

Loading the dataset returns four NumPy arrays:

The train\_images and train\_labels arrays are the training set—the data the model uses to learn.

The model is tested against the test set, the test\_images, and test\_labels arrays. The images are 28x28 NumPy arrays, with pixel values ranging from 0 to 255. The labels are an array of integers, ranging from 0 to 9. These correspond to the class of clothing the image represents:

Label	Class
0	T-shirt/top
1	Trouser
2	Pullover
3	Dress
4	Coat
5	Sandal
6	Shirt
7	Sneaker
8	Bag
9	Ankle boot

Each image is mapped to a singlelabel. Since the class names are not included with the dataset, store them here to use later when plotting the images:

read this "<https://www.tensorflow.org/tutorials/keras/classification>"

also refer:-

- 1)"<https://stackoverflow.com/questions/59646219/test-set-accuracy-of-1-how-to-debug>"
- 2)"<https://www.codementor.io/blog/tensorboard-integration-5fh168wqvi>"
- 3)"<https://github.com/jalammar/simpleTensorFlowClassificationExample/blob/master/Basic%20Classification%20Example%20with%20TensorFlow.ipynb>"
- 4)"<https://stackoverflow.com/questions/41708572/tensorflow-questions-regarding-tf-argmax-and-tf-equal>"

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## Hidden Layer Perceptron in

TensorFlow:-

The only difference we need to observe b/w Simple Layer Perceptron and Hidden Layer Perceptron is:-

1) In Simple Layer Perceptron there is no hidden layer present. it includes accept i/p and by weighted sum of i/p and bias it will directly gives o/p.

2) In Hidden Layer Perceptron there is an hidden layer in b/w i/p and o/p. bcz of increasing efficiency, it provides backpropagation.

\*Backpropagation:- The hidden neural network is set up in some techniques. In many cases, weighted inputs are randomly assigned. On the other hand, they are fine-tuned and calibrated through a process called backpropagation.

\*o/p of Hidden Layer Perceptron is equal to hidlayer\_1 or hidlayer\_n weighted sum and bias of Simple Layer Perceptron o/p.

Formula:-

$$O/P = ((O/P \text{ of Simple Layer Perceptron}) * W_{\text{hidlayer1}}) + B_{\text{hidlayer1}}$$
  
-----This is very imp

The code for the hidden layers of the perceptron is shown below:

```
#Importing the essential modules in the hidden layer
```

```
import tensorflow as tf
```

```
import numpy as np
```

```
import matplotlib.pyplot as plt
```

```
import math, random
```

```
np.random.seed(1000) ##it
```

```
is used to give same values in all iteration
```

```
function_to_learn = lambda x: np.cos(x) + 0.1*np.random.randn(*x.shape) ##it
```

```
is the function used in this program
```

```
layer_1_neurons = 10 ##10
```

```
neurons contained in layer 1 or in hidden_layer
```

```
NUM_points = 1000
```

```
##Total number of points
```

```
#Train the parameters of hidden layer
```

```
batch_size = 100
```

```
NUM_EPOCHS = 1500
```

```
all_x = np.float32(np.random.uniform(-2*math.pi, 2*math.pi, (1, NUM_points))).T
```

```
#####random.uniform(low=0.0(-2pi), high=1.0(2pi), size=None(1,1000))we use 2pi means
```

```
radian of 360_degree.bcz we use cos() fun. Therefore here we selected the random
```

```
range b/w (-360deg to +360deg)
```

Draw samples from a uniform distribution. Samples are uniformly distributed over

the half-open interval [low, high) (includes low, but excludes high). In other words, any value within the given interval is equally likely to be drawn by uniform.

vvvimp point:-

Here we use shape is (1,NUM\_points) or (1,1000).bcz in our i/p\_layer consists of only one neurons so it will accept only one value but we have i/p\_value for i/p\_layer has 1000\_or\_NUM\_points. .'we need to give shape of (1,1000)shape for i/p\_layer's i/p.

```
np.random.shuffle(all_x) ###please
read"https://valueml.com/shuffle-the-training-data-in-tensorflow/#:~:text=shuffle()%20will%20randomly%20shuffle,the%20data%20of%20our%20datasets.&text=As%20we%20can%20see%2C%20The,only%20one%20output%5By%5D."
###Data
```

shuffling satisfies the purpose of variance reduction. It's goal is to keep the model general and makes sure that it doesn't overfit a lot. Training, testing and validation are the phases that our presented dataset will be further splitting into, in our machine learning model. We need to shuffle these datasets well, avoiding any possible elements in the split datasets before training the ML model.

```
train_size = int(900)
#Train the first 700 points in the set
x_training = all_x[:train_size]
y_training = function_to_learn(x_training)

#Training the last 300 points in the given set
x_validation = all_x[train_size:]
y_validation = function_to_learn(x_validation)
```

```
plt.figure(1)
plt.scatter(x_training, y_training, c = 'blue', label = 'train')
plt.scatter(x_validation, y_validation, c = 'pink', label = 'validation')
plt.legend()
plt.show()
```

```
X = tf.placeholder(tf.float32, [None, 1], name = "X")
Y = tf.placeholder(tf.float32, [None, 1], name = "Y")
```

#first layer

#Number of neurons = 10

```
w_h = tf.Variable(tf.random_uniform([1, layer_1_neurons], minval = -1, maxval = 1,
dtype = tf.float32))
```

```
##tf.random.uniform(shape, minval=0, maxval=None,
```

```
dtype=tf.dtypes.float32, seed=None, name=None) in this case we use
```

sigmoid



activation fun. Therefore the o/p is given b/w -1 to +1(minval = -1, maxval = 1)

Here why we took [1, layer\_1\_neurons] or [1,10] is given for w\_h is bcz it has only "1" i/p\_neuron\_layer and "10" neuron in the o/p or i/p\_hidden\_layer.

```
b_h = tf.Variable(tf.zeros([1, layer_1_neurons], dtype = tf.float32)) ##Bias of hidden layer. Why (1,10) shape is same as above it will add bias for 1 neuron in i/p
```

```
h = tf.nn.sigmoid(tf.matmul(X, w_h) + b_h) ##O/P of hidden layer(next it will fed as i/p for o/p layer)
```

#output layer

#Number of neurons = 10

```
w_o = tf.Variable(tf.random_uniform([layer_1_neurons, 1],\ minval = -1, maxval = 1, dtype = tf.float32)) ##Weight of o/p layer
```

\*Here we have shape for hidden\_layer's o/p is [layer\_1\_neurons, 1] or [10,1]. bcz in the hidden layer we have 10 neurons. '.' it will produce 10 column o/p, and this hidden\_o/p fed to o/p\_layer consist of only one neurons. so it will deduce to 1. '.' we have shape [10,1]

```
b_o = tf.Variable(tf.zeros([1, 1], dtype = tf.float32)) ##bias of o/p layer ##it was shape of [1,1]. bcz bias is added after dot.product. '.' after dot. we have only one value. '.' it has only 1 row, 1 column o/p.[1,1]
```

#building the model

```
model = tf.matmul(h, w_o) + b_o ##o/p of model(from o/p_layer)=(dot.product of(o/p of hidden_layer(h)
```

and weighted sum of o/p\_layer(w\_o))+Bias of o/p\_layer)

#minimize the cost function (model - Y)

```
train_op = tf.train.AdamOptimizer().minimize(tf.nn.l2_loss(model - Y)) ##Adam is an alternative of gradient_decent ##(model - y)--->Mean loss for regression
```

& cross entropy for classification

#Starting the Learning phase

```
sess = tf.Session() sess.run(tf.initialize_all_variables())
```

errors = []

for i in range(NUM\_EPOCHS):

for start, end in zip(range(0, len(x\_training), batch\_size), range(batch\_size, len(x\_training), batch\_size)):

sess.run(train\_op, feed\_dict = {X: x\_training[start:end],\ Y: y\_training[start:end]})

###Zip: Creates a Dataset by zipping together datasets. Useful

in scenarios where you have features and labels and you  
need to provide the pair of feature and label for  
training the  
model.

```
cost = sess.run(tf.nn.l2_loss(model - y_validation),\ feed_dict =
{X:x_validation})
errors.append(cost)

if i%100 == 0:
    ###i%100==0 means, Display loss for every epoch(nothing but display_steps)
    print("epoch %d, cost = %g" % (i, cost))
    ##it prints epoch and cost values in tensor_board

plt.plot(errors,label='MLP Function Approximation') plt.xlabel('epochs')
plt.ylabel('cost')
plt.legend()
plt.show()
```

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Read for reference

```
1)"https://www.tensorflow.org/api_docs/python/tf/random/uniform"
2)"https://towardsdatascience.com/building-efficient-data-pipelines-using-tensorflow-8f647f03b4ce"
3)"https://valueml.com/shuffle-the-training-data-in-tensorflow/#:~:text=shuffle()%20will%20randomly%20shuffle,the%20data%20of%20our%20datasets.&text=As%20we%20can%20see%20The,only%20one%20output%5By%5D."
```

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