

A* ALGORITHM

IMPLEMENTATION

```
print("1BM22CS324")
print("V DHANUSH REDDY")
from collections import deque
import heapq

def solve_8puzzle_astar(initial_state):
    """
    Solves the 8-puzzle using A* Search with the misplaced tiles heuristic.

    Args:
        initial_state: A list of lists representing the initial state of the puzzle.

    Returns:
        A list of lists representing the solution path, or None if no solution is found.
    """

    def find_blank(state):
        """Finds the row and column of the blank tile (0)."""
        for row in range(3):
            for col in range(3):
                if state[row][col] == 0:
                    return row, col

    def get_neighbors(state):
        """Generates possible neighbor states by moving the blank tile."""
        row, col = find_blank(state)
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neighbors = []

# Possible moves: Up, Down, Left, Right
if row > 0: # Up
    new_state = [r[:] for r in state]
    new_state[row][col], new_state[row - 1][col] = new_state[row - 1][col],
new_state[row][col]
    neighbors.append(new_state)
if row < 2: # Down
    new_state = [r[:] for r in state]
    new_state[row][col], new_state[row + 1][col] = new_state[row + 1][col],
new_state[row][col]
    neighbors.append(new_state)
if col > 0: # Left
    new_state = [r[:] for r in state]
    new_state[row][col], new_state[row][col - 1] = new_state[row][col - 1],
new_state[row][col]
    neighbors.append(new_state)
if col < 2: # Right
    new_state = [r[:] for r in state]
    new_state[row][col], new_state[row][col + 1] = new_state[row][col + 1],
new_state[row][col]
    neighbors.append(new_state)

return neighbors

def misplaced_tiles_heuristic(state):
    """Calculates the number of misplaced tiles."""
    misplaced_count = 0
    for row in range(3):
        for col in range(3):
            if state[row][col] != 0 and state[row][col] != (row * 3 + col + 1):

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        misplaced_count += 1
    return misplaced_count

goal_state = [[1, 2, 3], [4, 5, 6], [7, 8, 0]]

# Print initial and goal states
print("Initial State:")
for row in initial_state:
    print(row)
print("\nGoal State:")
for row in goal_state:
    print(row)
print("\nStarting A* Search...\n")

priority_queue = [(misplaced_tiles_heuristic(initial_state), 0, initial_state, [])]
visited = set()

while priority_queue:
    _, cost, current_state, path = heapq.heappop(priority_queue)

    # Check if the goal state is reached
    if current_state == goal_state:
        return path + [current_state]

    # Mark the current state as visited
    visited.add(tuple(map(tuple, current_state)))

    # Explore neighbors
    for neighbor in get_neighbors(current_state):
        if tuple(map(tuple, neighbor)) not in visited:

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        new_cost = cost + 1

        heuristic_cost = misplaced_tiles_heuristic(neighbor)

        heapq.heappush(priority_queue, (new_cost + heuristic_cost, new_cost, neighbor,
path + [current_state]))

    return None # No solution found

# Example usage:
initial_state = [[1, 2, 3], [4, 0, 6], [7, 5, 8]]
solution = solve_8puzzle_astar(initial_state)
if solution:
    print("\nSolution found:")
    for state in solution:
        for row in state:
            print(row)
        print()
else:
    print("No solution found.")

```

OUTPUT:

```
1BM22CS324
V DHANUSH REDDY
Initial State:
[1, 2, 3]
[4, 0, 6]
[7, 5, 8]

Goal State:
[1, 2, 3]
[4, 5, 6]
[7, 8, 0]

Starting BFS...

Solution found:
[1, 2, 3]
[4, 0, 6]
[7, 5, 8]

[1, 2, 3]
[4, 5, 6]
[7, 0, 8]

[1, 2, 3]
[4, 5, 6]
[7, 8, 0]
```

OBSERVATION:

25-10-24

Week-3

② A* Algorithm

→ function A*search(problem) returns a solution or failure
node \leftarrow a node n with n state = problem.initial state, $neg=0$

frontier \leftarrow a priority queue ordered by ascending $g+h$, only element

loop do

if empty? (frontier) then return failure

$n \leftarrow \text{pop}(\text{frontier})$

if problem.goalTest(n .state) then
return solution(n)

for each action a in problem.action(n .state) do

$n' \leftarrow \text{childNode}(\text{problem}, n, a)$
insert(n' , $g(n') + h(n')$, frontier)

→ $f(n) = g(n) + h(n)$

$f(n)$ → evaluation cost function which gives the cheapest solution cost.

$g(n)$ → exact cost to reach node n from initial state.

$h(n)$ → estimation of assumed cost from current state (n) to reach goal.

$h(n)$ → no of misplaced tiles.

$h(n)$ → Manhattan distance.

Manhattan Distance

$$\begin{bmatrix} 2 & 8 & 3 \\ 1 & 6 & 4 \\ 7 & 0 & 5 \end{bmatrix}$$

initial

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 0 \end{bmatrix} f(n)=2$$

initial

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 0 \end{bmatrix}$$

Goal:

$$\begin{bmatrix} 1 & 2 & 3 \\ 0 & 5 & 6 \\ 4 & 7 & 8 \end{bmatrix} f(n)=4$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 0 & 8 \end{bmatrix} f(n)=2$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 0 & 6 \\ 7 & 5 & 8 \end{bmatrix}$$

$$f(n)=3$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 0 \end{bmatrix}$$

goal state

25/10

1) Misplaced tiles.

$$\begin{bmatrix} 2 & 8 & 3 \\ 1 & 6 & 4 \\ 7 & 0 & 5 \end{bmatrix} \quad \begin{matrix} g(n)=0 \\ h(n)=4 \\ f(n)=4 \end{matrix} \quad \begin{bmatrix} 1 & 2 & 3 \\ 8 & 0 & 4 \\ 7 & 6 & 5 \end{bmatrix} \quad \begin{matrix} \text{goal} \end{matrix}$$

initial

$$\begin{matrix} g(n)=1 \\ h(n)=5 \\ f(n)=6 \end{matrix} \downarrow \begin{bmatrix} 2 & 8 & 3 \\ 1 & 6 & 4 \\ 7 & 5 & 0 \end{bmatrix} \quad \begin{matrix} g(n)=1 \\ h(n)=5 \\ f(n)=6 \end{matrix} \downarrow \begin{bmatrix} 2 & 8 & 3 \\ 1 & 6 & 4 \\ 0 & 7 & 5 \end{bmatrix} \quad \begin{matrix} h(n)=3 \\ f(n)=4 \end{matrix} \downarrow \begin{bmatrix} 2 & 8 & 3 \\ 1 & 0 & 4 \\ 7 & 6 & 5 \end{bmatrix}$$

$$\begin{matrix} g(n)=2 \\ f(n)=6 \end{matrix} \downarrow \begin{bmatrix} 2 & 8 & 3 \\ 1 & 4 & 0 \\ 7 & 6 & 5 \end{bmatrix} \quad \begin{matrix} g(n)=2 \\ f(n)=6 \end{matrix} \downarrow \begin{bmatrix} 2 & 0 & 3 \\ 1 & 8 & 4 \\ 7 & 6 & 5 \end{bmatrix} \quad \begin{matrix} f(n)=5 \end{matrix} \downarrow \begin{bmatrix} 2 & 8 & 3 \\ 0 & 1 & 4 \\ 7 & 6 & 5 \end{bmatrix} \quad \begin{matrix} f(n)=5 \end{matrix} \downarrow \begin{bmatrix} 2 & 8 & 3 \\ 1 & 6 & 4 \\ 7 & 0 & 5 \end{bmatrix} \quad \begin{matrix} f(n)=6 \end{matrix}$$

$$\begin{matrix} g(n)=3 \\ f(n)=6 \end{matrix} \downarrow \begin{bmatrix} 0 & 2 & 3 \\ 1 & 8 & 4 \\ 7 & 6 & 5 \end{bmatrix} \quad \begin{matrix} f(n)=5 \end{matrix} \downarrow \begin{bmatrix} 2 & 3 & 0 \\ 1 & 8 & 4 \\ 7 & 6 & 5 \end{bmatrix} \quad \begin{matrix} f(n)=7 \end{matrix}$$

$$\begin{matrix} g(n)=4 \\ f(n)=5 \end{matrix} \downarrow \begin{bmatrix} 1 & 2 & 3 \\ 0 & 8 & 4 \\ 7 & 6 & 5 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 3 \\ 8 & 0 & 4 \\ 7 & 6 & 5 \end{bmatrix} \quad \text{solution found}$$

