

# 8 PUZZLE GAME

## IMPLEMENTATION

```
print("IBM22CS324")
print("V DHANUSH REDDY")
from collections import deque

def solve_8puzzle_bfs(initial_state):
    """
    Solves the 8-puzzle using Breadth-First Search.

    Args:
        initial_state: A list of lists representing the initial state of the puzzle.

    Returns:
        A list of lists representing the solution path, or None if no solution is found.
    """

    def find_blank(state):
        """Finds the row and column of the blank tile (0)."""
        for row in range(3):
            for col in range(3):
                if state[row][col] == 0:
                    return row, col

    def get_neighbors(state):
        """Generates possible neighbor states by moving the blank tile."""
        row, col = find_blank(state)
        neighbors = []
```

```

# Possible moves: Up, Down, Left, Right

if row > 0: # Up
    new_state = [r[:] for r in state]

    new_state[row][col], new_state[row - 1][col] = new_state[row - 1][col],
new_state[row][col]

    neighbors.append(new_state)

if row < 2: # Down
    new_state = [r[:] for r in state]

    new_state[row][col], new_state[row + 1][col] = new_state[row + 1][col],
new_state[row][col]

    neighbors.append(new_state)

if col > 0: # Left
    new_state = [r[:] for r in state]

    new_state[row][col], new_state[row][col - 1] = new_state[row][col - 1],
new_state[row][col]

    neighbors.append(new_state)

if col < 2: # Right
    new_state = [r[:] for r in state]

    new_state[row][col], new_state[row][col + 1] = new_state[row][col + 1],
new_state[row][col]

    neighbors.append(new_state)

```

```

return neighbors

```

```

goal_state = [[1, 2, 3], [4, 5, 6], [7, 8, 0]]

```

```

# Print initial and goal states

```

```

print("Initial State:")

```

```

for row in initial_state:

```

```

    print(row)

```

```

print("\nGoal State:")

```

```
for row in goal_state:
```

```
    print(row)
```

```
print("\nStarting BFS...\n")
```

```
queue = deque([(initial_state, [])])
```

```
visited = set()
```

```
while queue:
```

```
    current_state, path = queue.popleft()
```

```
    # Check if the goal state is reached
```

```
    if current_state == goal_state:
```

```
        return path + [current_state]
```

```
    # Mark the current state as visited
```

```
    visited.add(tuple(map(tuple, current_state)))
```

```
    # Explore neighbors
```

```
    for neighbor in get_neighbors(current_state):
```

```
        if tuple(map(tuple, neighbor)) not in visited:
```

```
            queue.append((neighbor, path + [current_state]))
```

```
return None # No solution found
```

```
# Example usage:
```

```
initial_state = [[1, 2, 3], [4, 0, 6], [7, 5, 8]]
```

```
solution = solve_8puzzle_bfs(initial_state)
```

```
if solution:
```

```
    print("\nSolution found:")
```

```
    for state in solution:
```

```
        for row in state:
            print(row)
        print()
    else:
        print("No solution found.")
```

### OUTPUT:

```
1BM22CS324
V DHANUSH REDDY
Initial State:
[1, 2, 3]
[4, 0, 6]
[7, 5, 8]

Goal State:
[1, 2, 3]
[4, 5, 6]
[7, 8, 0]

Starting BFS...

Solution found:
[1, 2, 3]
[4, 0, 6]
[7, 5, 8]

[1, 2, 3]
[4, 5, 6]
[7, 0, 8]

[1, 2, 3]
[4, 5, 6]
[7, 8, 0]
```

## OBSERVATION:

Implement 8-puzzle problem using BFS &

DFS

→ BFS Algorithm

Loop  
if fringe is empty return failure  
Node  $\leftarrow$  remove-first(fringe)  
if Node is a goal  
then return the path from initial state to Node.  
else generate all successors of Node  
and add generated nodes to back of fringe

End Loop.

→ DFS Algorithm

Loop.

If fringe is empty return failure.  
Node  $\leftarrow$  remove-first(fringe)  
if Node is a goal  
then return the path from initial state to Node.

else

generate all successors of Node  
and add generated nodes to the front of fringe.

End Loop.