

ICT 3314

EMBEDDED SYSTEMS

Assignment 02

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ITT/2020/119

1381

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Question 1

No:	Date:
No:	
Question 1.	
Q1.	
prepare the SD card :	
<ul style="list-style-type: none">Download the Raspberry Pi imager from the official Raspberry Pi website.Insert an SD card into your computer using a card reader.use the Raspberry Pi imager to install the Raspberry Pi OS onto the SD card.	
Insert SD card.	
<ul style="list-style-type: none">Insert the prepared SD card into the SD card slot on the Raspberry Pi.	
Connect the peripherals	
<ul style="list-style-type: none">Plug in a keyboard and mouse into the USB ports on the Raspberry Pi.Connect a monitor or TV to the Raspberry Pi using an HDMI cable.	
Power the Raspberry Pi	
<ul style="list-style-type: none">Connect the power supply to the Raspberry Pi.It will turn on automatically when plugged in.	
Initial setup	
<ul style="list-style-type: none">The Raspberry Pi will boot into the OS. Follow the on-screen instructions to set up language, Wi-Fi, and other settings.	

02.

updates add the latest security patches to protect the system from threats.

Upgrades improve speed and make the system work better.

Updates ensure the systems support new software and hardware.

Bug fixes prevent crashes and keep the system running smoothly.

03).

A screenshot of a Mac desktop environment. In the center is a terminal window titled 'zsh' showing the output of a Python script named 'one.py'. The script prints 'LED initialized on GPIO 17' and then blinks an LED 5 times. To the left of the terminal is a code editor window for 'one.py' which contains the script's source code. The code defines a class 'LED' with methods 'on' and 'off' that print 'LED ON' and 'LED OFF' respectively. It also includes a loop that turns the LED on and off 5 times. The desktop background shows a landscape image, and there are several icons on the Dock at the bottom.

```
import time # Import time for delays
# Mock the LED class for simulation
class LED:
    def __init__(self, pin):
        self.pin = pin
        print(f"LED initialized on GPIO {pin}")

    def on(self):
        print("LED ON")

    def off(self):
        print("LED OFF")

# Initialize the LED on GPIO pin 17
led = LED(17)

# Blink the LED 5 times
for _ in range(5): # Use an underscore (_) as a variable when it's not needed
    led.on() # Turn the LED on
    time.sleep(1) # Wait for 1 second
    led.off() # Turn the LED off
    time.sleep(1) # Wait for 1 second
```

```
import time
```

```
class LED:
```

```
    def __init__(self, pin):
        self.pin = pin
        print(f"LED initialized on GPIO {pin}")

    def on(self):
        print("LED ON")

    def off(self):
        print("LED OFF")

led = LED(17)

for _ in range(5):
    led.on()
    time.sleep(1)
    led.off()
    time.sleep(1)
```

Question 2

Question 02

- Q1. Power off the Raspberry Pi - Always turn off the Raspberry Pi before connecting the camera module to avoid electrical damage.

Locate the CSI Port - Find the camera serial interface port on the Raspberry Pi board. It is usually near the HDMI Port and labeled "CAMERA".

Open the CSI Port connection - Gently lift the plastic clip on the CSI port to unlock it.

Insert the Ribbon cable - Align the metal contacts of the ribbon cable to face the CSI Port contacts.

Push down the plastic clip to lock the cable in place securely. Turn on the Raspberry Pi and ensure the camera module is detected using commands like `wget https://www.raspberrypi.org/wheezy/images/rpi-cam-test.ppm`

Precautions

DO NOT touch the camera lens to prevent smudges or scratches.

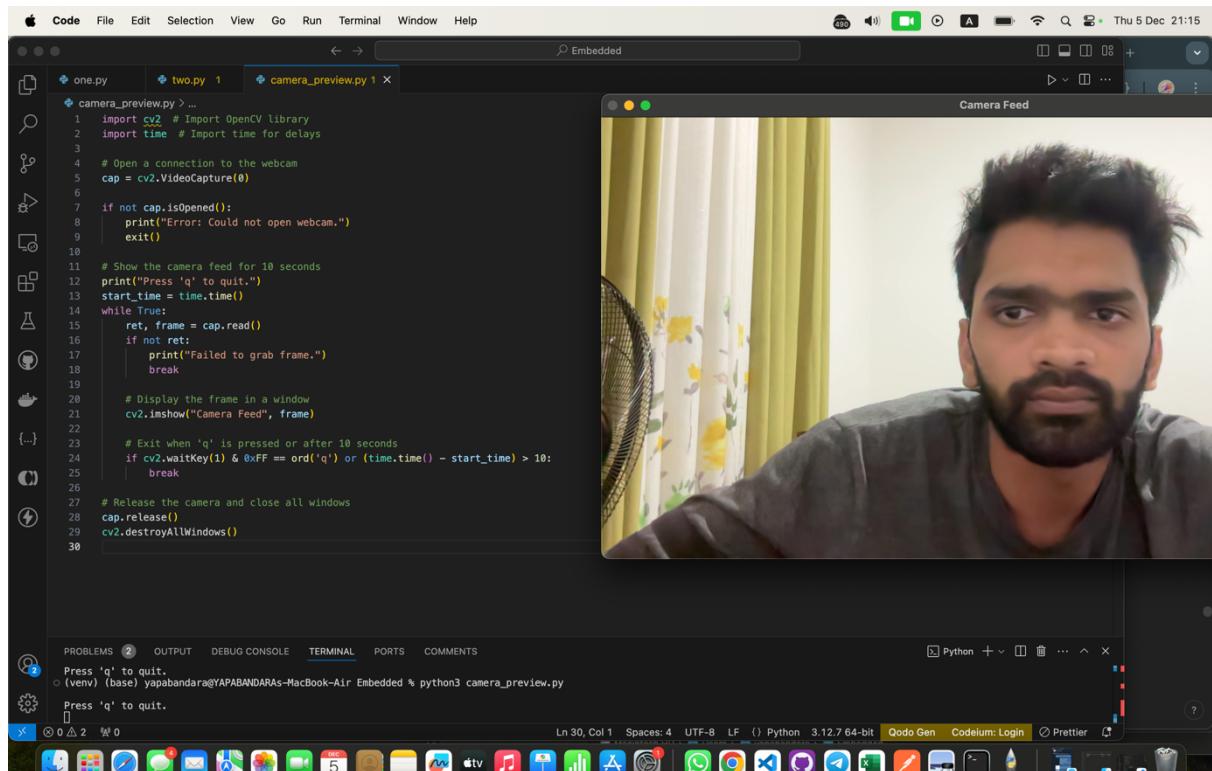
DO NOT bend or pull the cable too hard to avoid damage.

Check the alignment of the ribbon cable to avoid improper connections.

PREVENT static Electricity

USE correct port.

02)



```
import cv2
import time
cap = cv2.VideoCapture(0)
if not cap.isOpened():
    print("Error: Could not open webcam.")
    exit()
print("Press 'q' to quit.")
start_time = time.time()
while True:
    ret, frame = cap.read()
    if not ret:
        print("Failed to grab frame.")
        break
    # Display the frame in a window
    cv2.imshow("Camera Feed", frame)
    if cv2.waitKey(1) & 0xFF == ord('q') or (time.time() - start_time) > 10:
        break
# Release the camera and close all windows
cap.release()
cv2.destroyAllWindows()
```

```

cv2.imshow("Camera Feed", frame)

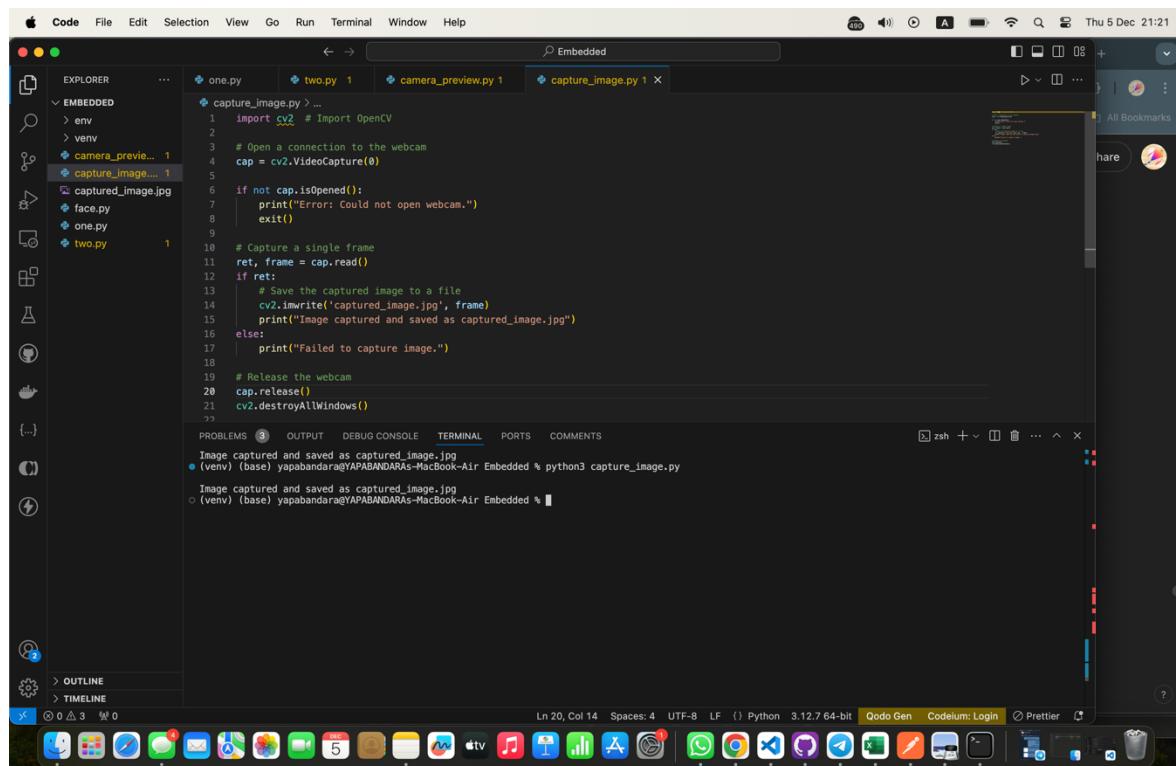
if cv2.waitKey(1) & 0xFF == ord('q') or (time.time() - start_time) > 10:
    break

cap.release()

cv2.destroyAllWindows()

```

03).



```

import cv2 # Import OpenCV
cap = cv2.VideoCapture(0)
if not cap.isOpened():
    print("Error: Could not open webcam.")
    exit()

```

```
ret, frame = cap.read()

if ret:

    cv2.imwrite('captured_image.jpg', frame)

    print("Image captured and saved as captured_image.jpg")

else:

    print("Failed to capture image.")

cap.release()

cv2.destroyAllWindows()
```

Q4.

a. Optimizes performance - configuration ensures that the camera operates at optimal resolution, frame rate and settings suitable for the application.

Resource management - Embedded systems often have limited resources (CPU, memory). Proper configuration avoids overloading the system by allocating resources efficiently.

Different cameras have unique settings. Configuration aligns the camera's capabilities with the embedded system's requirement.

Enhances functionality - configurations like video mode, focus, and encoding enable advanced features such as recording, streaming and image processing.

No: _____

Date: ___/___/___

b.

6.2 Camera API Functions

picam2.start()

prepares the camera module by allocating resources and initializing the hardware.

Activates the camera, allowing it to start capturing images or videos.

Enable streaming - Necessary for live video or image capturing functionality.

picam2.stop()

Releases Resources - Frees up system resources (memory, processing power) used by the camera module.

Ensures safety - properly shuts down the camera to prevent hardware damage or data corruption.

prepares for Reuse - Ensures the system is ready for

subsequent camera operations without errors.

Question 3

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Date: ____ / ____ / ____

Question 03

01) Image processing - Supports operation like filtering, edge detection, image transformation, and object recognition.

Video Analysis - includes motion detection, background subtraction, and object tracking.

Supports reading and processing video streams from cameras or pre-recorded files.

Computer Vision Algorithms - implements popular algorithm for tasks like feature detection (SIFT, SURF), optical flow, and stereo vision.

Real time performance - optimized for speed, making it suitable for real time applications like robotics, augmented reality and surveillance.

open source and extensible.

03)

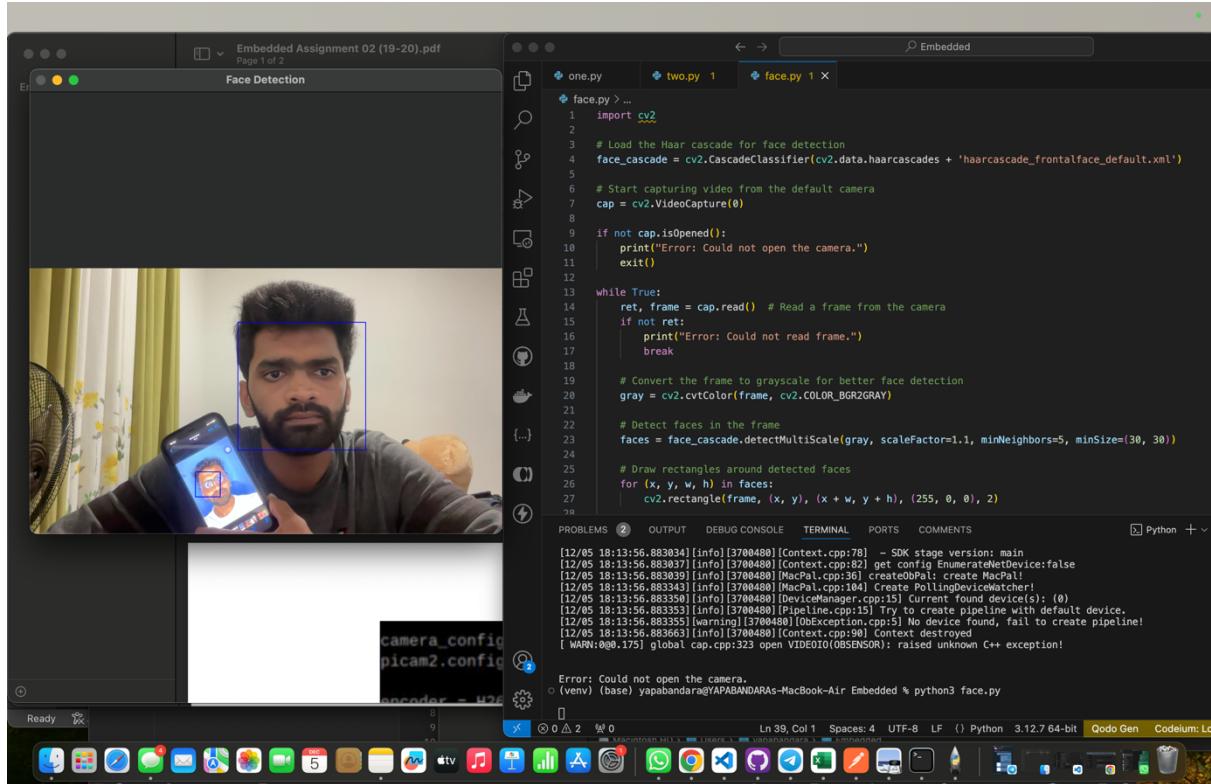
function & name - detect_face(img)

Purpose - The function detect faces in an image and draws rectangles around them.

face detection - face_cascade.detectMultiScale(img)

Drawing rectangles - each detected face function uses cv2.rectangle to draw a white rectangle around the face.

02).



```
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cap = cv2.VideoCapture(0)

if not cap.isOpened():

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ret, frame = cap.read()

if ret:

    cv2.imwrite('captured_image.jpg', frame)

    print("Image captured and saved as captured_image.jpg")

else:

    print("Failed to capture image.")

cap.release()

cv2.destroyAllWindows()
```