Automated Multi Crop Irrigation Using IoT

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**Abstract**

Multi-crop water system is a fundamental part of present-day horticulture that assists increment with editing yield and ration water assets. The utilization of Web of Things (IoT) innovation in agribusiness has upset conventional water system techniques. In this undertaking, we propose a multi-crop water system framework that uses soil dampness sensors, mugginess sensors, temperature sensors, and an Arduino microcontroller to mechanize the water system process.

            The framework gathers information from the sensors and cycles it utilizing the Arduino microcontroller. The information is dissected to decide the dampness level, stickiness, and temperature of the dirt. In light of this information, the water system framework is controlled to convey the ideal measure of water to the harvests. The framework is associated with an IoT stage by means of a WIFI module which permits ranchers to remotely screen and control the water system framework.

            The proposed framework is supposed to increment crop yield by giving ideal water levels and lessening water wastage. The utilization of IoT innovation makes the framework practical, productive, and harmless to the ecosystem. The consequences of this task can possibly fundamentally affect current agribusiness by further developing harvest yields, decreasing water utilization, and advancing reasonable cultivating rehearses.

Likewise, we will see what and which sort of sensors can be utilized progressively on the off chance that we utilize this approach. Comparison of sensors, voltage utilization and their effectiveness are additionally portrayed.

**Keywords-**Arduino, NodeMCU, IOT, Soil moisture

# Introduction

Horticulture is finished for a huge scope in a considerable lot of the nations. Populace is developing consistently, consequently cultivating is important to create more food. Cultivating incorporates planting, manuring, water system, weeding and collecting out of which water system and manuring are the main ones which need a great deal of consideration. We really want to diminish how much work that ranchers should do and help the harvest's effectiveness using current innovations, like mechanization. We are combining current innovations, for example, robotizing processes, with agribusiness. In this way, to diminish the time spent on the water system and to yield great harvests by not excessively flooding, we are utilizing Soil dampness sensors. Additionally, factors like temperature and mugginess influence the development of harvests. High temperature causes shoot and root development hindrances and high mugginess causes diminished CO2 consumption and decreased happening. To stay away from these issues, we really want to constantly screen them with the goal that ranchers can make essential moves. Thus, here we are likewise utilizing temperature and stickiness sensors. We are redirecting the water to the harvest as indicated by the dampness values recorded. The situation with the siphon and upsides of stickiness and temperature sensors can be observed by ranchers on a page.

A DC shunt motor is a self-excited DC motor with field windings that are shunted to or linked in parallel with the motor’s armature winding.You can easily control the Speed of a Shunt motor. Despite the load changes, Shunt motors can maintain their constant speed. As the load increases the armature

# Methodology

The multi crop water system framework created in this study comprises of soil moisture sensors, humidity and temperature sensors, DC pumps, Arduino and NodeMCU. The soil moisture sensors are utilized to quantify the dirt dampness content, while the stickiness and temperature sensors are utilized to screen the developing circumstances.



Fig.1 Multi crop

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The DC pumps are utilized to water the yields, while the Arduino and NodeMCU sheets are utilized to control the framework's activity. The transfers are utilized to switch the DC siphons on and off. The framework works as follows: The soil moisture sensors constantly screen the dirt dampness content. On the off chance that the dampness content falls under a specific limit, the Arduino board conveys a message to the NodeMCU board to initiate the DC pumps. The pumps then water the harvests until the dampness content arrives at the ideal level.

The mugginess and temperature sensors screen the developing circumstances and change the water system plan in like manner. The whole framework can be checked.

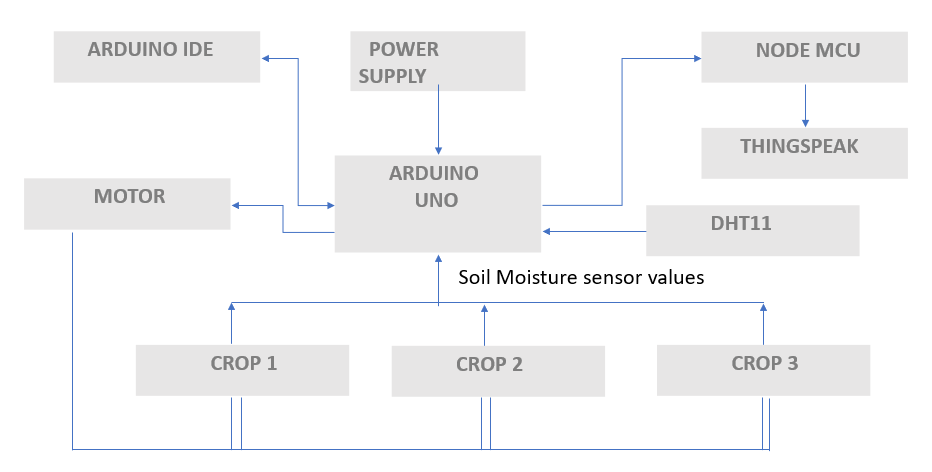


Fig.2.Block diagram of the irrigation system

Soil moisture sensor

Sensor used is resistive soil moisture sensor. Resistive soil dampness sensors are generally involved sensors in agribusiness to quantify the dampness content of the soil. These sensors work in view of the guideline of electrical conductivity in the dirt.

They comprise of two cathodes that are embedded into the dirt, and the obstruction between these terminal’s changes with the dampness level. As the dirt dampness builds, the conductivity of the dirt increments, bringing about a diminishing in the sensor's resistance. The opposition values are then connected with dampness levels utilizing adjustment bends or conditions.

Resistive soil dampness sensors are savvy and moderately easy to utilize and install. They are viable with different microcontrollers and Arduino loads up for information procurement and analysis. These sensors are flexible and can be utilized for an extensive variety of soil types and crops. They give constant estimations, empowering ranchers to screen soil dampness levels and pursue informed water system choices.

**Volumetric Water Content**

The volumetric water content is the extent of water volume to soil volume. Expecting a unit surface region, volumetric water content can be expressed as a proportion, rate, or profundity of water per profundity of soil, for example, crawls of water per foot of soil.

Analog Output = (ADC Value)/1023

               Moisture in percentage = 100 - (Analog output \* 100)

For zero moisture, we get a maximum value of 10-bit ADC, i.e., 1023. This, in turn, gives 0% moisture.

**Result**

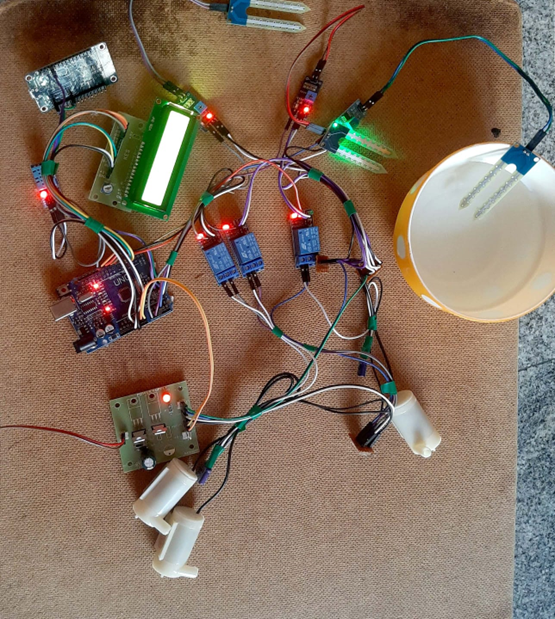
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Fig.3. Automated irrigation system

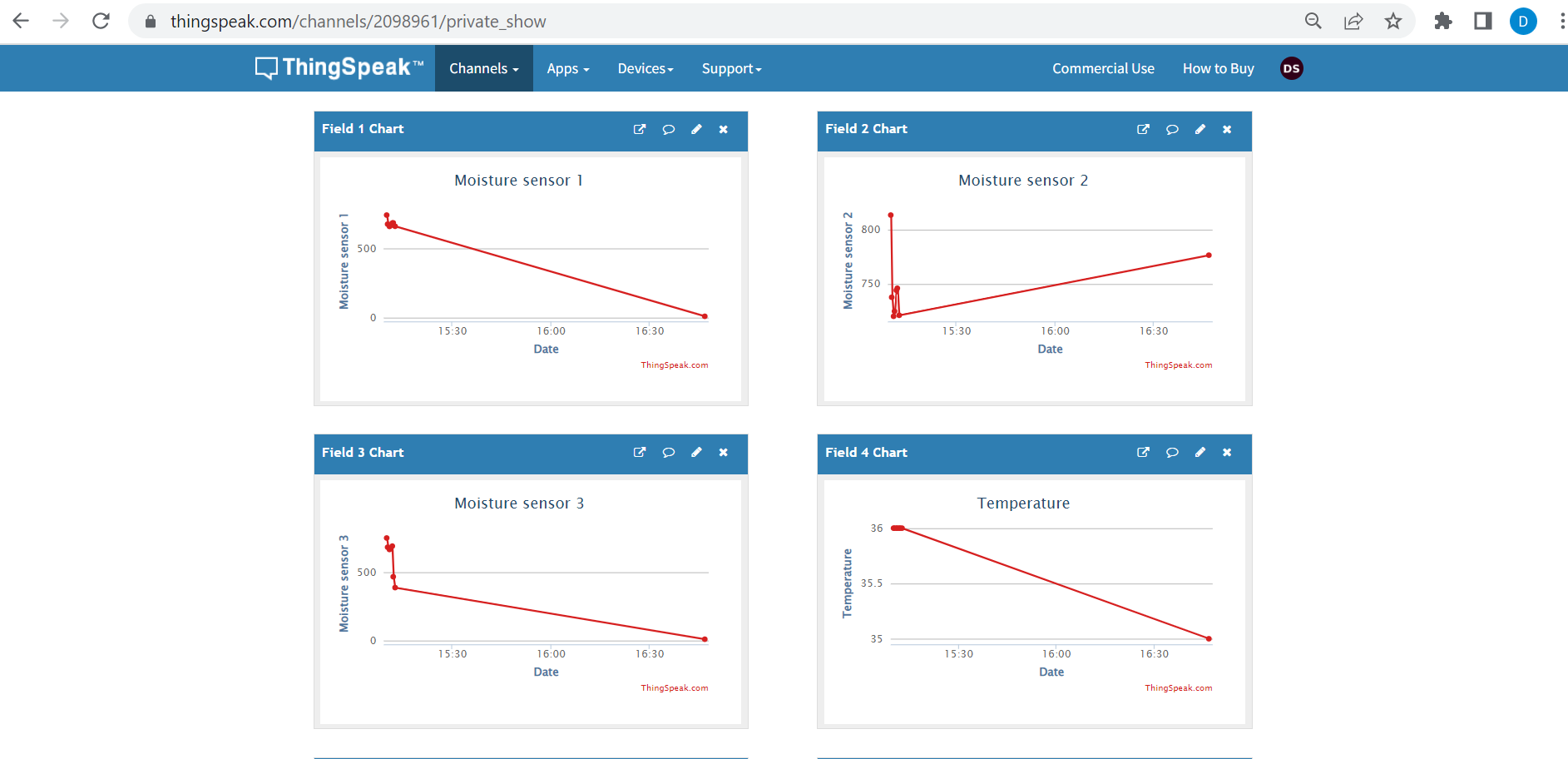


Fig.4. Sensor Readings

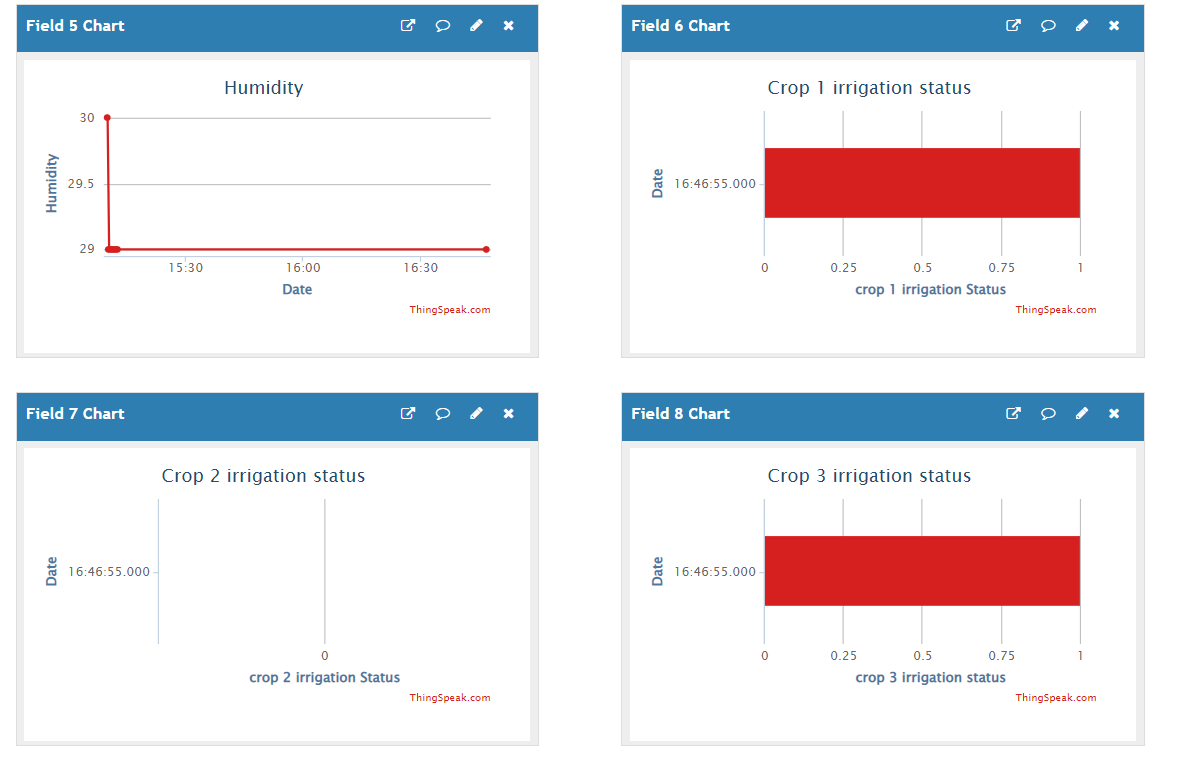


Fig.5. Crop irrigation status

# Real time usage

In practice, resistive moisture sensors cannot be used because of its less coverage area.

Sensors like Time Domain Reflectometry (TDR), Frequency Domain Reflectometry (FDR), gypsum blocks, neutron probes, amplitude domain reflectometry etc. are used because of the length of its probes, and can cover wide range.

Voltage and Accuracy levels of sensors are as follows:

TDR Sensor (Time Domain Reflectometry): TDR sensors are ordinarily used to gauge dampness content in soil. They work by sending electromagnetic heartbeats through the dirt and estimating the time it takes for the beats to reflect back. The voltage necessities for TDR sensors ordinarily range from 5 volts to 24 volts, with 12 volts being a typical voltage level. When appropriately adjusted, TDR sensors can accomplish an exactness of around ±2-3% volumetric water content (VWC) under ideal circumstances. Notwithstanding, it's vital to take note of that the exactness might shift relying upon soil type, saltiness levels, and sensor adjustment.

FDR Sensor (Frequency Domain Reflectometry): FDR sensors are additionally utilized for estimating soil dampness content. They work by examining the recurrence reaction of the dirt water framework. FDR sensors ordinarily require a power supply voltage going from 12 volts to 24 volts. Like TDR sensors, the precision of FDR sensors can be around ±2-3% VWC, if they are very much aligned and utilized in appropriate soil conditions. Nonetheless, similarly as with any sensor, varieties can happen in view of explicit elements and adjustment techniques.

Gypsum Sensor: Gypsum sensors, or gypsum blocks, are frequently utilized for checking soil dampness levels. These sensors comprise of gypsum material with implanted cathodes. The voltage necessities for gypsum sensors are as a rule in the scope of 1.5 volts to 9 volts, with 3 volts being a typical voltage level. The exactness of gypsum blocks can go from ±3-5% VWC under ideal circumstances. Be that as it may, gypsum blocks might be impacted by soil saltiness, temperature, and different elements, which can present some level of mistake in estimations.

Neutron Probes: Neutron probes are utilized for soil dampness estimations in view of the neutron balance rule. These tests regularly utilize a little radioactive source to transmit quick neutrons into the dirt and identify the sluggish neutrons that are created through communication with soil dampness. Neutron tests ordinarily require a high-voltage power supply in the scope of a few hundred volts to a couple of kilovolts, contingent upon the particular test model.

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| --- | --- | --- | --- |
| Sensor | Method | Advantages |  |
| Gypsum Blocks | Two electrodes inside the porous material such as gypsum measures the resistance itself  -The water from the soil moves into the gypsum decreases the resistance and water pulled from the gypsum increases the resistance  -Low resistance means higher moisture level and vice versa | -Minimal expense  - precise in mud soil  - simple to work  - low power utilization | - duration is around 1 to 2 years  -  low accuracy in Sandy soils  - less repeatability |
| Electrical Conductivity Probes | -Measure the current of electricity between two probes (direct contact with soil)  -More moisture has better the conductivity and vice versa | -  high accuracy in clay soil  - low cost | - very sensitive to the spacing of the groups and soil type  - less repeatability |
| Dielectric:  Capacitance | -Two electrodes of dielectric have direct contact with soil and high oscillating frequency is applied to the electrodes and measures resonant frequency  -The resonant frequency vary by moisture level of soil  -Large change in frequency have higher moisture level and vice versa | -  high accuracy  - good for research use  -  read soil volumetric water content directly  - low maintenance | - expensive  - not practical for controlling irrigation system |
| Dielectric: TDR | -Measurement of time travel along the length of the probe rod by electromagnetic pulse  -More travel time in higher moisture level and vice versa | -  high accuracy  - good for research use  -  read soil volumetric water content directly  - low maintenance | - expensive  - not practical for controlling irrigation system  -Very complex |

# Conclusion

The multi-crop water system framework created in this study exhibits the capability of IoT innovation to improve the productivity and viability of water system frameworks. The framework's capacity to control dampness levels and keep up with ideal developing circumstances for different harvests can prompt huge enhancements in crop yield and water usage. We could guide the water to different yields as per soil dampness sensor values. Also, ranchers could remotely screen the situation with water system through the Wi-Fi module.

At long last, we might reach the inference that mechanizing water system utilizing IoT innovation will simplify it. We utilized nodemcu in this framework, which will communicate sensor readings from distances in excess of 500 m. Subsequently, by executing the recommended strategy, we can assist ranchers with saving time and decrease water squander. It additionally diminishes work necessities while further developing yield development productivity.

Practically speaking, resistive dampness sensors cannot be utilized due to its less inclusion area. So, real time utilization sensors are likewise recorded and compared. The voltage utilization and precision of the ongoing sensors are additionally depicted.

**Future Work**

With the given data of sensors and with additional innovative work, the framework can be increased for use in bigger horticultural settings, prompting a more supportable and useful farming industry.

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