10/09/2028 Laby: Build a CHN model to Classify Cate Dogimen

Aim: To Build and train CNN model
that classify images into a categories:
cat & dog.

Objective :

- D) To undoustand the auchitecture of Convolutional Newral Network
- To preprocess image datasets gord braining and testing
- 3) To implement a CNN modul using Py Torsch
- 4) To evaluate the performance of model using accuracy & loss.

Bosudocode

BEONN

- 1) Imposit necessary libraries (Touch, Touchlession, Touch. nn )
- 2) Load the dataset
- 3) Gurate a class CHN with
  - Convolutional Rayor + ReLu + Har Pooling
  - Fully Connected Rayous
  - Output layor with a newrons
- 4) Grain the data
  Initialize model, loss gunction
  For each epoch:

Forward Pass

Compute Loss

Back propagate loss

Update weights

Print training loss

- Evaluate model on Test data
Calculate accuracy

## Observation

- Dataset
  - a Dataset contains image of cats and dogs
  - normalized byfore training
- a) At beginning of training, CHN hod randomly initialized weights, which resulted in high training loss and low accuracy
- 3) As Multiple epoches, CNN layor begain to extract meaning ful pratures such as edges, textures, shape.
- 4) Polling layous helped reduce dimensionality while retaining most important peature
- decreases while actuacy improves.

## Result

implemented - Build CNIN model to classify Cat & Dog image.

```
[]
          from google.colab import drive
         drive.mount('/content/drive')
     → Mounted at /content/drive
[]
          !ls /content/drive/MyDrive/
                                            'Mark sheets '
          '5th sem'
                             'Documents '
          'Certificate '
                             'Fda project'
                                             PetImages
                            IMG_1432.png
           Classroom
                                             SE
          'Colab Notebooks' 'Internship'
                                            'STUDENT PORTFOLIO - RA2311047010018.gdoc'
[]
         data_dir = "/content/drive/MyDrive/PetImages"
[]
          import torch
         import torch.nn as nn
          import torch.optim as optim
          from torch.utils.data import DataLoader, random split
          from torchvision import datasets, transforms
          import matplotlib.pyplot as plt
[ ]
         transform = transforms.Compose([
              transforms.Resize((128,128)), # resize images
              transforms.ToTensor(),
                                             # convert to tensor
             transforms.Normalize ((0.5,), (0.5,)) # normalize
         1)
[]
         data_dir = "/content/drive/MyDrive/PetImages"
[]
         Start coding or generate with AI.
[ ]
          !ls /content/drive/MyDrive/PetImages
          !ls /content/drive/MyDrive/PetImages/Cat |
                                                     head
          !ls /content/drive/MyDrive/PetImages/Dog
                                                     head
```

```
!ls /content/drive/MyDrive/PetImages
    !ls /content/drive/MyDrive/PetImages/Cat |
                                                 head
    !ls /content/drive/MyDrive/PetImages/Dog |
                                                 head
→ Cat Dog
    0.jpg
    10000.jpg
    10001.jpg
    10002.jpg
    10003.jpg
    10004.jpg
    10005.jpg
    10006.jpg
    10007.jpg
    10008.jpg
    0.jpg
    10000.jpg
    10001.jpg
    10002.jpg
    10003.jpg
    10004.jpg
    10005.jpg
    10006.jpg
    10007.jpg
    10008.jpg
```

```
from torchvision import datasets
    from torchvision import transforms
    from PIL import Image
    import os
    transform = transforms.Compose([
        transforms.Resize((128, 128)),
        transforms. ToTensor()
    1)
    def pil_loader(path):
        try:
            with open(path, 'rb') as f:
                img = Image.open(f)
                return img.convert('RGB')
        except Exception as e:
            print("Skipping corrupted file:", path)
            return None
```

```
!ls /content/drive/MyDrive
    !ls /content/drive/MyDrive/PetImages
    !ls /content/drive/MyDrive/PetImages/Dog | head
                                      'Mark sheets '
    '5th sem'
                       'Documents '
    'Certificate '
                       'Fda project'
                                       PetImages
                       IMG_1432.png
     Classroom
                                       SE
    'Colab Notebooks' 'Internship'
                                      'STUDENT PORTFOLIO - RA2311047010018.gdoc'
    Cat Dog
    0.jpg
    10000.jpg
    10001.jpg
    10002.jpg
    10003.jpg
    10004.jpg
    10005.jpg
    10006.jpg
    10007.jpg
    10008.jpg
    data_dir = "/content/drive/MyDrive/PetImages"
    !ls /content/drive/MyDrive/PetImages
→ Cat Dog
    !ls /content/drive/MyDrive/PetImages/Dog | wc -l
→ 3454
    !ls /content/drive/MyDrive/PetImages/Cat/ | wc -l
→ 5644
   from torchvision import datasets, transforms
    dataset = datasets.ImageFolder(root=data_dir, transform=transform)
```

```
train size = int(0.8 * len(dataset))
    test_size = len(dataset) - train_size
    train dataset, test dataset = random split(dataset, [train size, test size])
    train_loader = DataLoader(train_dataset, batch_size=32, shuffle=True)
    test_loader = DataLoader(test_dataset, batch_size=32, shuffle=False)
    print("Classes:", dataset.classes)
    print("Training samples:", len(train_dataset))
    print("Testing samples:", len(test_dataset))
→ Classes: ['Cat', 'Dog']
   Training samples: 7278
   Testing samples: 1820
Class SimpleCNN(nn.Module):
        def __init__(self, num_classes=2):
            super(SimpleCNN, self). init ()
            self.conv1 = nn.Conv2d(3, 32, kernel_size=3, stride=1, padding=1)
            self.pool = nn.MaxPool2d(2, 2)
            self.conv2 = nn.Conv2d(32, 64 kornal circ-2 stride-1 padding=1)
            self.fc1 = nn.Linear(64 * (parameter) num_classes: int led twice → 32x32
            self.fc2 = nn.Linear(128, num classes)
            self.relu = nn.ReLU()
        def forward(self, x):
            x = self.pool(self.relu(self.conv1(x)))
            x = self.pool(self.relu(self.conv2(x)))
           x = x.view(x.size(0), -1) # Flatten
            x = self.relu(self.fc1(x))
            x = self.fc2(x)
            return x
```

```
device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
model = SimpleCNN(num_classes=len(dataset.classes)).to(device)
```

```
device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
   model = SimpleCNN(num_classes=len(dataset.classes)).to(device)
    criterion = nn.CrossEntropyLoss()
    optimizer = optim.Adam(model.parameters(), lr=0.001)
   epochs = 5
    from tqdm import tqdm
    for epoch in range(epochs):
       model.train()
       running loss = 0.0
       for images, labels in tqdm(train_loader, desc=f"Epoch {epoch+1}/{epochs}"):
           images, labels = images.to(device), labels.to(device)
           optimizer.zero_grad()
           outputs = model(images)
           loss = criterion(outputs, labels)
           loss.backward()
           optimizer.step()
           running_loss += loss.item()
       print(f"Epoch {epoch+1}/{epochs}, Loss: {running_loss/len(train_loader):.4f}")
                       228/228 [31:57<00:00, 8.41s/it]
→ Epoch 1/5: 100%
   Epoch 1/5, Loss: 0.6830
   Epoch 2/5: 100%
                        | 228/228 [00:42<00:00, 5.41it/s]
   Epoch 2/5, Loss: 0.6382
                        228/228 [00:41<00:00, 5.43it/s]
   Epoch 3/5: 100%
   Epoch 3/5, Loss: 0.6020
                        228/228 [00:42<00:00, 5.39it/s]
    Epoch 4/5: 100%
   Epoch 4/5, Loss: 0.5469
   Epoch 5/5: 100% 228/228 [00:42<00:00, 5.38it/s] Epoch 5/5, Loss: 0.5029
   model.eval()
```

```
model.eval()
correct, total = 0, 0
with torch.no_grad():
    for images, labels in test_loader:
        images, labels = images.to(device), labels.to(device)
```

```
model.eval()
    correct, total = 0, 0
    with torch.no_grad():
        for images, labels in test_loader:
            images, labels = images.to(device), labels.to(device)
            outputs = model(images)
            _, predicted = torch.max(outputs, 1)
            total += labels.size(0)
            correct += (predicted == labels).sum().item()
    print(f"Test Accuracy: {100 * correct / total:.2f}%")
→ Test Accuracy: 72.53%
   import matplotlib.pyplot as plt
plt.figure(figsize=(10,4))
→ <Figure size 1000x400 with 0 Axes>
```

<Figure size 1000x400 with 0 Axes>