

14/08/26 Exp4: Build a Simple Feed Forward Neural Network To Recognize Handwritten Character

Aim:

To design and implement a simple feed forward neural network for recognizing handwritten character using open source dataset.

Objective:

- * To Understand FFNN
- * To train an FFNN on handwritten character images.
- * To evaluate the network's performance using statistical metrics.
- * To visualize predictions for sample test images.

Pseudocode:

- 1) Import necessary libraries.
- 2) Load the handwritten character dataset (MNIST Digits Dataset)
- 3) Normalize the image pixel values.
- 4) Split the dataset into training and testing sets
- 5) Define the feed forward neural network architecture:

- Input layer (flattened image pixels)
- one or more hidden dense layers
- Output layer (number of character classes)

- 6) Compile the model with loss function, optimizer and metrics.
- 7) Train the model on training data.
- 8) Evaluate the model on Test data.
- 9) Visualize sample predictions.

Observation

Metric	Value
Accuracy	97.82% 97.82%

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This shows that

- * model successfully learned patterns of handwritten characters from the dataset
- * Normalization of pixels values helped improve training performance
- * Increasing No. of layers, neurons or training epochs may improve accuracy further.

Output

Epoch [1/5], Loss: 1.0594

Epoch [2/5], Loss: 0.3860

Epoch [3/5], Loss: 0.3290

Epoch [4/5], Loss: 0.2974

Epoch [5/5], Loss: 0.2726

Table

Parameter	Observation
Dataset Used	MNIST Handwritten Digits Dataset
Model Type	Feed Forward Neural Network (Fully Connected)
Training Accuracy	98. 97 . 82%
Activation Function	ReLU (Hidden Layer)

Result

Implemented simple FFNN for
recognizing handwritten digits using
open source dataset.

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Code

Notebook



Python 3 (ipykernel)

```
[29]: pip install torch torchvision torchaudio
```



Defaulting to user installation because normal site-packages is not writeable

Collecting torch

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Collecting torchvision

Downloading torchvision-0.23.0-cp310-cp310-manylinux_2_28_x86_64.whl.metadata (6.1 kB)

Collecting torchaudio

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Collecting filelock (from torch)

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Collecting networkx (from torch)

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```
[38]: import torch
import torch.nn as nn
import torch.optim as optim
```

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```
[38]: import torch
import torch.nn as nn
import torch.optim as optim
import torchvision
from torchvision import transforms
from torch.utils.data import DataLoader

[39]: transform = transforms.Compose([
    transforms.ToTensor(),
    transforms.Normalize((0.5,),(0.5,))
])

[40]: train_dataset = torchvision.datasets.MNIST(
    root='./data', train=True, transform=transform, download=True
)
test_dataset = torchvision.datasets.MNIST(
    root='./data', train=False, transform=transform, download=True
)

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[41]: train_loader = DataLoader(train_dataset, batch size=64, shuffle=True)
```

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Python 3 (ipykernel)

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```
[46]: import torch.nn as nn
class SimpleFFN(nn.Module):
    def __init__(self):
        super(SimpleFFN, self).__init__()
        self.flatten = nn.Flatten()
        self.fc1 = nn.Linear(28*28, 128)
        self.fc2 = nn.Linear(128, 64)
        self.fc3 = nn.Linear(64, 10)
        self.relu = nn.ReLU()

    def forward(self, x):
        x = self.flatten(x)
        x = self.relu(self.fc1(x))
        x = self.relu(self.fc2(x))
        x = self.fc3(x)
        return x

[47]: device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
model = SimpleFFN().to(device)

[68]: criterion = nn.CrossEntropyLoss()
optimizer = optim.SGD(model.parameters(), lr=0.01)
```




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Code

Notebook Python 3 (ipykernel)

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model = SimpleFFN().to(device)
```

```
[68]: criterion = nn.CrossEntropyLoss()
      optimizer = optim.SGD(model.parameters(), lr=0.01)
      epochs = 5
```

```
[69]: for epoch in range(epochs):
      running_loss = 0.0
      for images, labels in train_loader:
          images, labels = images.to(device), labels.to(device)

          # Forward
          outputs = model(images)
          loss = criterion(outputs, labels)

          # Backward and optimize
          optimizer.zero_grad()
          loss.backward()
          optimizer.step()

          running_loss += loss.item()

      print(f"Epoch [{epoch+1}/{epochs}], Loss: {running_loss/len(train_loader):.4f}")
```


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Code



Notebook



Python 3 (ipykernel)

Epoch [1/5], Loss: 0.0273

Epoch [2/5], Loss: 0.0266

Epoch [3/5], Loss: 0.0260

Epoch [4/5], Loss: 0.0252

Epoch [5/5], Loss: 0.0246

[70]: print("Training Finished")

Training Finished

[71]: correct, total = 0, 0

with torch.no_grad():

for images, labels in test_loader:

images, labels = images.to(device), labels.to(device)

outputs = model(images)

_, predicted = torch.max(outputs, 1)

total += labels.size(0)

correct += (predicted == labels).sum().item()

print(f"Test Accuracy: {100 * correct / total:.2f}%")

Test Accuracy: 97.82%