

On estimating the structure factor of a point process, with applications to hyperuniformity

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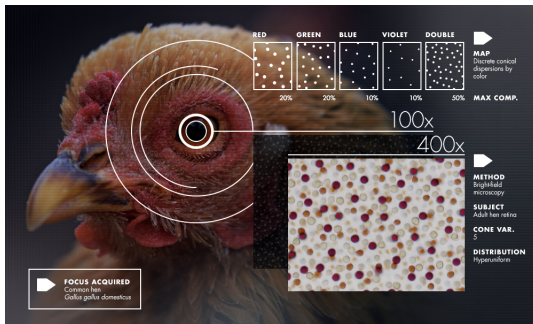
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Université de Paris, Map5, Paris, France.



- 1 Hyperuniformity
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Bird's-Eye

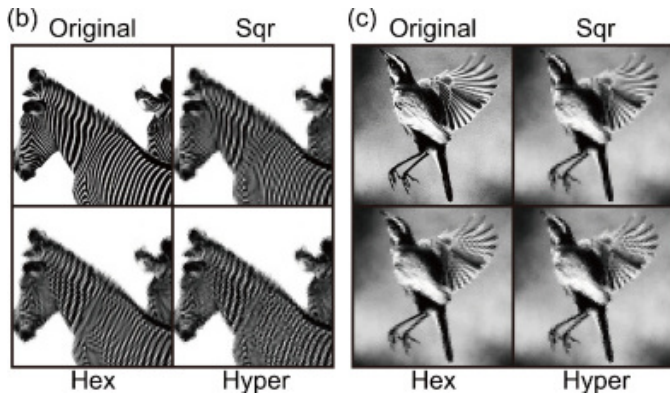
Motivations



Y. Jiao, T. Lau, H. Hatzikirou, M Meyer-Hermann, J. C. Corbo, and S. Torquato, *Avian photoreceptor patterns represent a disordered hyperuniform solution to a multiscale packing problem*, 2014.

Image reconstruction

Motivations



Ming-Jie Sun, Xin-Yu Zhao, and Li-Jing Li, *Imaging using hyperuniform sampling with a single-pixel camera*, 2018.

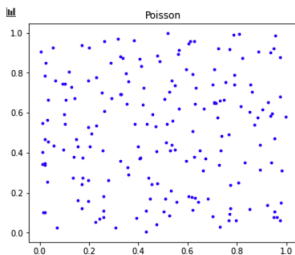
Numerical integration

Motivations

■ Monte Carlo integration:

$$\int f(x)\mu(dx) \approx \sum_{i=1}^N w_i f(\mathbf{x}_i)$$

■ Rate of convergence with a Poisson point process: $O(1/\sqrt{N})$



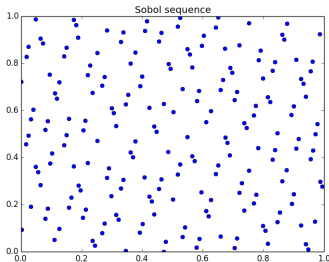
Numerical integration

Motivations

■ Monte Carlo integration:

$$\int f(x) \mu(dx) \approx \sum_{i=1}^N w_i f(\mathbf{x}_i)$$

■ Rate of convergence with Sobol sequence: $O(\log(N)^d / N)$



Structure Factor

Motivations

Let \mathcal{X} be a stationary point process of \mathbb{R}^d of intensity ρ ,

- Structure factor:

$$S(\mathbf{k}) = 1 + \rho \mathcal{F}(g - 1)(\mathbf{k}),$$

- Pair correlation function

$$\mathbb{E} \left[\sum_{\mathbf{x}, \mathbf{y} \in \mathcal{X}}^{\neq} f(\mathbf{x}, \mathbf{y}) \right] = \int_{\mathbb{R}^d \times \mathbb{R}^d} f(\mathbf{x} + \mathbf{y}, \mathbf{y}) \rho^2 g(\mathbf{x}) d\mathbf{x} d\mathbf{y},$$

S. Coste, *Order, Fluctuations, Rigidities*, 2021.

S. Torquato, *Hyperuniform States of Matter*, 2018.

Structure Factor

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$$\mathbb{E} \left[\sum_{\substack{\neq \\ \mathbf{x}, \mathbf{y} \in \mathcal{X}}} f(\mathbf{x}, \mathbf{y}) \right] = \int_{\mathbb{R}^d \times \mathbb{R}^d} f(\mathbf{x} + \mathbf{y}, \mathbf{y}) \rho^2 g(\mathbf{x}) d\mathbf{x} d\mathbf{y},$$

- \mathcal{X} is hyperuniform iff

$$S(\mathbf{0}) = 0.$$

S. Coste, *Order, Fluctuations, Rigidities*, 2021.

S. Torquato, *Hyperuniform States of Matter*, 2018.

Hyperuniformity class

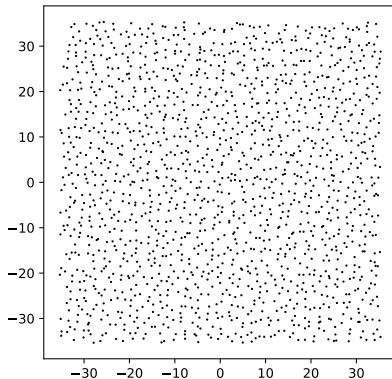
Motivations

\mathcal{X} is hyperuniform with $|S(\mathbf{k})| \sim c\|\mathbf{k}\|_2^\alpha$ in the neighborhood of 0 then,

α	$\text{Var}[\text{Card}(\mathcal{X} \cap B(0, R))]$	class
> 1	$O(R^{d-1})$	I
1	$O(R^{d-1} \log(R))$	II
$]0, 1[$	$O(R^{d-\alpha})$	III

Ginibre ensemble

Motivations



Ginibre ensemble

Motivations

- Intensity: $\rho_{\text{Ginibre}} = 1/\pi$
- Pair correlation function: $g_{\text{Ginibre}}(r) = 1 - \exp(-r^2)$
- Structure factor: $S_{\text{Ginibre}}(k) = 1 - \exp(-k^2/4)$
- Power decay: $\alpha_{\text{Ginibre}} = 2$
- Hyperuniform class: *I*

Scattering intensity

Estimators assuming stationarity

$\mathcal{X}_N = \{\mathbf{x}_i\}_1^N$ a realization of a **stationary** process \mathcal{X} of intensity ρ in $W = [-L/2, L/2]^d$.

■ Estimator:

$$\hat{S}_{\text{SI},s}(\mathbf{k}) \triangleq \frac{1}{N} \left| \sum_{j=1}^N e^{-i\langle \mathbf{k}, \mathbf{x}_j \rangle} \right|^2$$

■ Allowed wavevectors:

$$\mathbf{k} \in \left\{ \left(\frac{2\pi n_1}{L}, \dots, \frac{2\pi n_d}{L} \right) \text{ with, } \mathbf{n} = (n_1, \dots, n_d) \in \mathbb{Z}^d \setminus \{\mathbf{0}\} \right\}.$$

1- S. Torquato, *Hyperuniform States of Matter*, 2018.

2- M.A. Klatt and G. Last and D. Yogeshwaran, *Hyperuniform and Rigid Stable Matchings*, 2020.

- **Given:** $\mathcal{X}_N = \{\mathbf{x}_i\}_1^N$ a realization of a **stationary** point process \mathcal{X} of intensity ρ in $W = [-L/2, L/2]^d$.
- **Need:** Use \mathcal{X}_N to approximate $S(\mathbf{k}) = 1 + \rho \int_{\mathbb{R}^d} (g(\mathbf{r}) - 1) e^{-i\langle \mathbf{k}, \mathbf{r} \rangle} d\mathbf{r}$.

- **Given:** $\mathcal{X}_N = \{\mathbf{x}_i\}_1^N$ a realization of a **stationary** point process \mathcal{X} of intensity ρ in $W = [-L/2, L/2]^d$.
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- **Idea:**
 - 1 Use $\alpha_t(\mathbf{r}, W) = \int_{\mathbb{R}^d} t(\mathbf{r} + \mathbf{y}, W) t(\mathbf{y}, W) d\mathbf{y}$ s.t. $\lim_{L \rightarrow \infty} \alpha_t(\mathbf{r}, W) = 1$ and $\|t\|_2 = 1$:

$$\begin{aligned}
 S(\mathbf{k}) &= 1 + \rho \int_{\mathbb{R}^d} \lim_{L \rightarrow \infty} (g(\mathbf{r}) - 1) \alpha_t(\mathbf{r}, W) e^{-i\langle \mathbf{k}, \mathbf{r} \rangle} d\mathbf{r} \\
 &= \lim_{L \rightarrow \infty} \mathbb{E}[\widehat{S}(t, \mathbf{k})] - \underbrace{\rho \mathcal{F}(\alpha_t)(\mathbf{k}, W)}_{\epsilon_t(\mathbf{k}, L)}
 \end{aligned}$$

- 2 Reduce bias: Consider the zeros of $\epsilon_t(\mathbf{k}, L)$ as the set of allowed wavevectors of \widehat{S} , or remove the bias term.

Scattering intensity

Estimators assuming stationarity

- **Taper:** $t_0(\mathbf{x}, W) = \frac{1}{\sqrt{|W|}} \mathbb{1}_W(\mathbf{x})$.



$$S(\mathbf{k}) = \lim_{L \rightarrow \infty} \mathbb{E} \left[\underbrace{\frac{1}{\rho |W|} \left| \sum_{\mathbf{x} \in \mathcal{X} \cap W} e^{-i \langle \mathbf{k}, \mathbf{x} \rangle} \right|^2}_{\hat{S}_{\text{SI}}(\mathbf{k})} \right] - \underbrace{\rho \left(\prod_{j=1}^d \frac{\sin(k_j L/2)}{k_j \sqrt{L}/2} \right)^2}_{\epsilon_0(\mathbf{k}, L)}$$

- **Allowed wavevectors:**

$$\mathbb{A}_L = \{(k_1, \dots, k_d) \in (\mathbb{R}^d)^*, \exists j \in \{1, \dots, d\}, n \in \mathbb{Z}^* \text{ s.t. } k_j = \frac{2\pi n}{L}\}$$

Scattering intensity estimator

Estimators assuming stationarity

1 Estimator:

$$\hat{S}_{\text{SI}}(\mathbf{k}) = \frac{1}{\rho|W|} \left| \sum_{\mathbf{x} \in \mathcal{X} \cap W} e^{-i\langle \mathbf{k}, \mathbf{x} \rangle} \right|^2$$

2 Allowed wavevectors:

$$\mathbb{A}_{\mathbf{L}} = \left\{ (k_1, \dots, k_d) \in (\mathbb{R}^d)^*, \exists j \in \{1, \dots, d\}, n \in \mathbb{Z}^* \text{ s.t. } k_j = \frac{2\pi n}{L} \right\}.$$

Formulation in the literature:

1 Estimator:

$$\hat{S}_{\text{SI},s}(\mathbf{k}) \triangleq \frac{1}{N} \left| \sum_{j=1}^N e^{-i\langle \mathbf{k}, \mathbf{x}_j \rangle} \right|^2$$

2 Allowed wavevectors:

$$\mathbb{A}_{\mathbf{L}}^{\text{res}} = \left\{ \left(\frac{2\pi n_1}{L}, \dots, \frac{2\pi n_d}{L} \right) \text{ with, } \mathbf{n} = (n_1, \dots, n_d) \in \mathbb{Z}^d \setminus \{\mathbf{0}\} \right\}.$$

Tapered estimator

Estimators assuming stationarity

General case

- Tapered estimator:

$$S(\mathbf{k}) = \lim_{L \rightarrow \infty} \mathbb{E} \left[\underbrace{\frac{1}{\rho} \left| \sum_{j=1}^N t(\mathbf{x}_j, W) e^{-i\langle \mathbf{k}, \mathbf{x}_j \rangle} \right|^2}_{\hat{S}_T(t, \mathbf{k})} \right] - \underbrace{\rho |\mathcal{F}(t)(\mathbf{k}, W)|^2}_{\epsilon_t(\mathbf{k}, L)}.$$

- Debiased tapered estimator:

- 1 Directly debiased:

$$\hat{S}_{\text{DDT}}(t, \mathbf{k}) \triangleq \frac{1}{\rho} \left| \sum_{j=1}^N t(\mathbf{x}_j, W) e^{-i\langle \mathbf{k}, \mathbf{x}_j \rangle} - \rho \mathcal{F}(t)(\mathbf{k}, W) \right|^2.$$

- 2 Undirectly debiased:

$$\hat{S}_{\text{UDT}}(t, \mathbf{k}) \triangleq \frac{1}{\rho} \left| \sum_{j=1}^N t(\mathbf{x}_j, W) e^{-i\langle \mathbf{k}, \mathbf{x}_j \rangle} \right|^2 - \rho |\mathcal{F}(t)(\mathbf{k}, W)|^2.$$

Preprint: T. Rajala and S. C. Olhede and D. John Murrell *Spectral estimation for spatial point patterns*, 2020.

Multitapered estimator

Estimators assuming stationarity

More generally,

- Family of orthogonal tapers: $(t_q)_{q=1}^P$
- Multitapered estimator:

$$\hat{S}_{\text{MT}}((t_q)_{q=1}^P, \mathbf{k}) = \frac{1}{P} \sum_{q=1}^P \hat{S}_{\text{T}}(t_q, \mathbf{k}).$$

Preprint: T. Rajala and S. C. Olhede and D. John Murrell, *Spectral estimation for spatial point patterns*, 2020.

Estimator assuming stationarity

Tests: Estimators

- Tapered estimator:

$$\hat{S}_T(\mathbf{k}) \triangleq \frac{1}{\rho} \left| \sum_{j=1}^N t(\mathbf{x}_j, W) e^{-i\langle \mathbf{k}, \mathbf{x}_j \rangle} \right|^2.$$

- Debiased tapered estimator:

- 1 Directly debiased:

$$\hat{S}_{DDT}(t, \mathbf{k}) \triangleq \frac{1}{\rho} \left| \sum_{j=1}^N t(\mathbf{x}_j, W) e^{-i\langle \mathbf{k}, \mathbf{x}_j \rangle} - \rho \mathcal{F}(t)(\mathbf{k}, W) \right|^2.$$

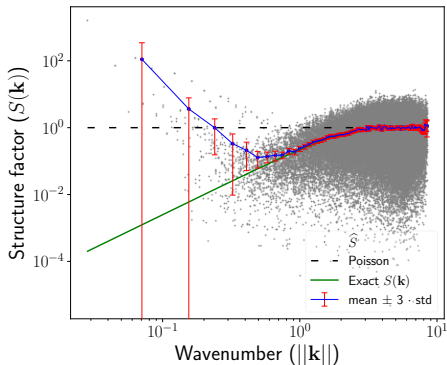
- 2 Undirectly debiased:

$$\hat{S}_{UDT}(t, \mathbf{k}) \triangleq \frac{1}{\rho} \left| \sum_{j=1}^N t(\mathbf{x}_j, W) e^{-i\langle \mathbf{k}, \mathbf{x}_j \rangle} \right|^2 - \rho |\mathcal{F}(t)(\mathbf{k}, W)|^2.$$

- Multitapered estimators $\hat{S}_{MT}((t_q)_{q=1}^P, \mathbf{k}) = \frac{1}{P} \sum_{q=1}^P \hat{S}(t_q, \mathbf{k})$.

Scattering intensity

Tests: Estimators

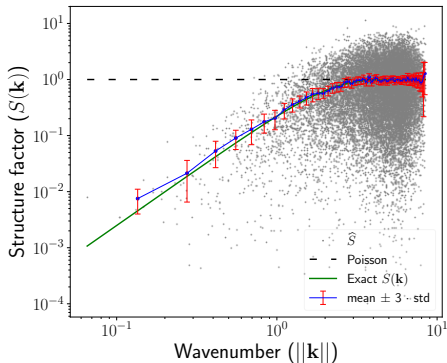


Scattering intensity on arbitrary wavevectors

<https://github.com/For-a-few-DPPs-more/structure-factor>

Scattering intensity

Tests: Estimators

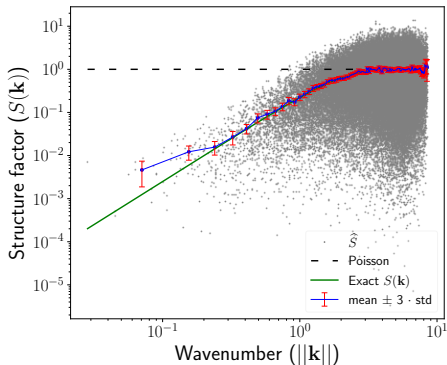


Scattering intensity on allowed wavevectors

<https://github.com/For-a-few-DPPs-more/structure-factor>

Scattering intensity

Tests: Estimators

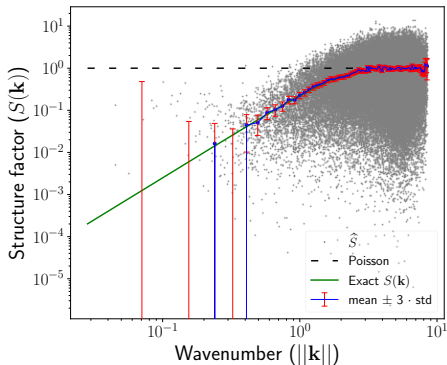


Scattering intensity directly debiased

<https://github.com/For-a-few-DPPs-more/structure-factor>

Scattering intensity

Tests: Estimators

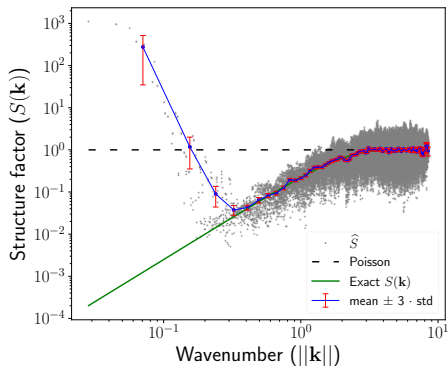


Scattering intensity undirectly debiased

<https://github.com/For-a-few-DPPs-more/structure-factor>

Multitapered estimator

Tests: Estimators

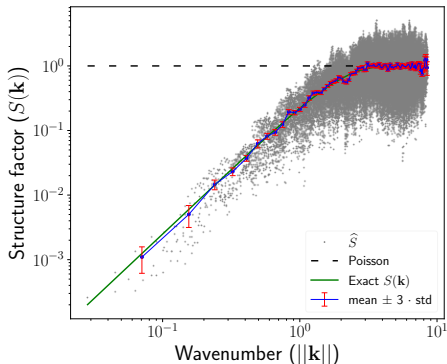


Multitapered estimator

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Multitapered estimator

Tests: Estimators

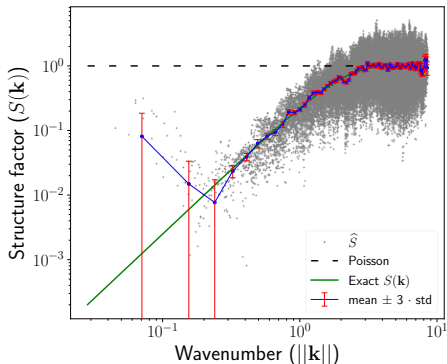


Multitapered estimator directly debiased

<https://github.com/For-a-few-DPPs-more/structure-factor>

Multitapered estimator

Tests: Estimators



Multitapered estimator undirectly debiased

<https://github.com/For-a-few-DPPs-more/structure-factor>

Integrated mean square error

Comparison of the estimators

Estimators	$\widehat{\text{iVar}}$	$\text{CI}[\widehat{\text{iMSE}}]$
$\widehat{S}_{\text{SI}}(2\pi\mathbf{n}/L)$	0.32	0.32 ± 0.02
$\widehat{S}_{\text{DDT}}(t_0)$	0.32	0.33 ± 0.03
$\widehat{S}_{\text{DDT}}(t_1)$	0.34	0.35 ± 0.06
$\widehat{S}_{\text{DDMT}}((t_q)_1^4)$	0.08	0.08 ± 0.007
	Ginibre ensemble	

Sample integrated variance and MSE for the variants of the scattering intensity across 50 samples from the Ginibre ensemble.

Integrated mean square error

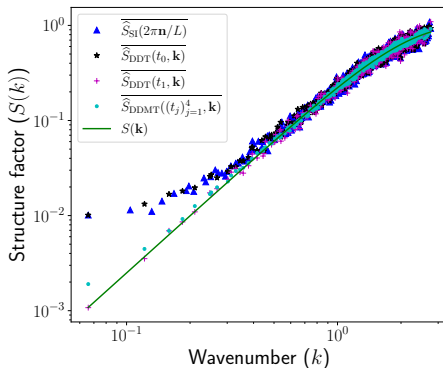
Comparison of the estimators

Estimators	T -score	p -value
$\hat{S}_{\text{DDMT}}((t_q)_1^4), \hat{S}_{\text{SI}}(2\pi\mathbf{n}/L)$	-29.53	3×10^{-33}
$\hat{S}_{\text{DDMT}}((t_q)_1^4), \hat{S}_{\text{DDT}}(t_0)$	-22.40	10^{-27}
$\hat{S}_{\text{DDMT}}((t_q)_1^4), \hat{S}_{\text{DDT}}(t_1)$	-12.18	9×10^{-17}
	Ginibre ensemble	

Paired t -tests for the variants of the scattering intensity.

Integrated mean square error

Comparison of the estimators



Means of the estimators across 50 samples from the Ginibre ensemble.

Effective hyperuniformity

Tests: Hyperuniformity

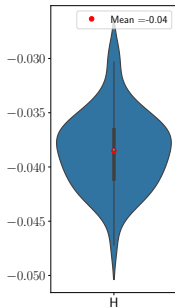
$$\mathcal{X} \text{ is effectively hyperuniform} \iff H = \frac{\hat{S}(0)}{\hat{S}(k_{peak})} \leq 10^{-3},$$

- $\hat{S}(0)$ is a linear extrapolation of the estimated structure factor \hat{S} in $k = 0$.
- k_{peak} is the location of the first dominant peak value of \hat{S} .

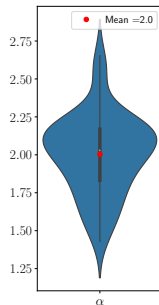
S. Torquato, *Hyperuniform States of Matter*, 2018.

Hyperuniformity

Tests: Hyperuniformity



(a) H index



(b) Power decay

<https://github.com/For-a-few-DPPs-more/structure-factor>

Python Package

Code

- 1 Open-source Python toolbox called `structure_factor`¹
- 2 Available on Github and PyPI²
- 3 Detailed documentation³
- 4 Jupyter notebook tutorial⁴

¹<https://github.com/For-a-few-DPPs-more/structure-factor>

²<https://pypi.org/project/structure-factor/>

³<https://for-a-few-dpps-more.github.io/structure-factor/>

⁴<https://github.com/For-a-few-DPPs-more/structure-factor/tree/main/notebooks>

THANK YOU



Github



Documentation



Preprint

<https://github.com/For-a-few-DPPs-more/structure-factor>
<https://for-a-few-dpps-more.github.io/structure-factor/>
<https://arxiv.org/abs/2203.08749>