MAIN CONCEPTS OF SIMULATION

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SIMULATION INTRODUCTION

Varying Inputs

- Up until this point we have been assuming a rather unrealistic view of the real world – certainty.
- In a real world setting especially the business world the inputs and coefficients in a problem are rarely fixed quantities.
- Optimization techniques like sensitivity analysis reduced cost and shadow prices – are one approach to handling this problem.

Monte Carlo Simulations

- Uncertainty is foundational in Monte Carlo simulations.
- Simulations help us determine not only the full array of outcomes of a given decision, but the probabilities of these outcomes occurring.
- Some examples:
 - Risk analysis how rare certain outcomes actually are.
 - Model evaluation how good is our model compared to others.

Monte Carlo Simulations

Average Input Value

DETERMINISTIC MODEL

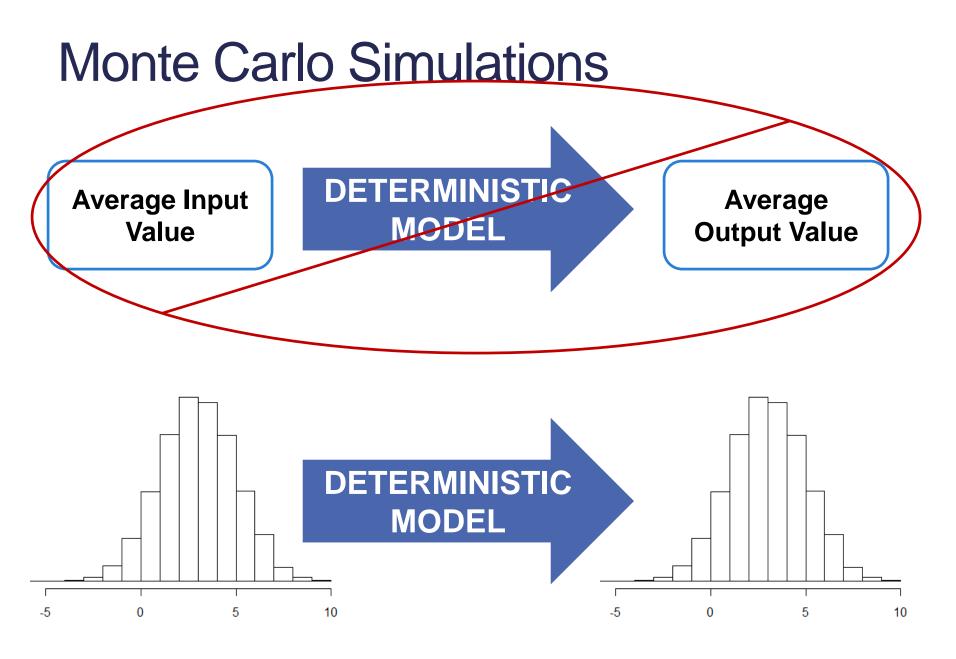
Average Output Value

Monte Carlo Simulations

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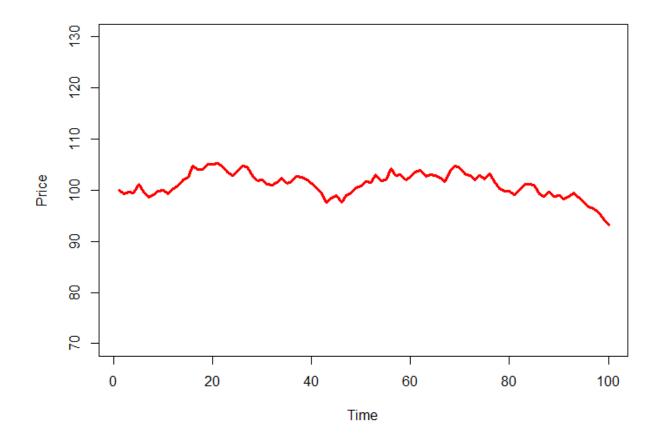
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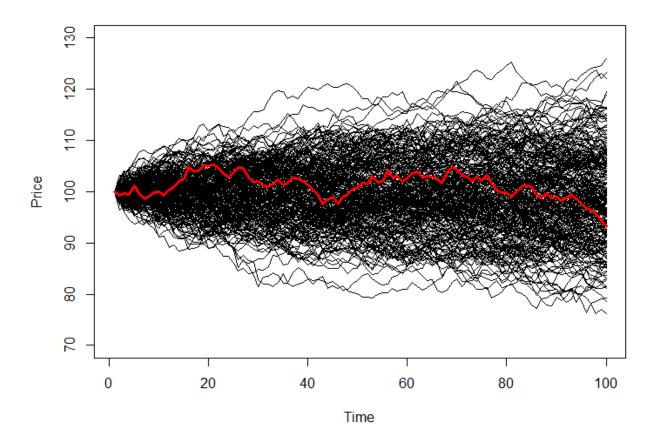


- Each input inside of a model (or process) is assigned a range of possible values – the probability distribution of the inputs.
- We then analyze what happens to the decision from our model (or process) under all of these possible scenarios.
- Simulation analysis describes not only the outcomes of certain decisions, but also the probability distribution of those outcomes – the probability each of these outcomes occurs.

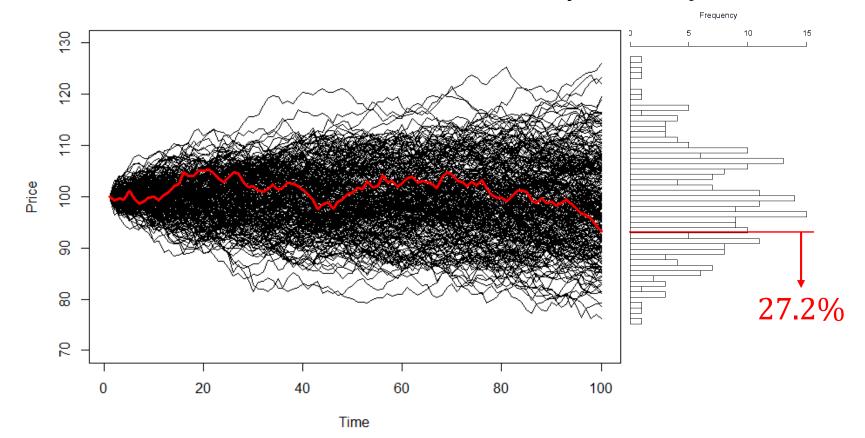
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- Follows a random walk for next 100 days with $\varepsilon_t \sim N(0,1)$.



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Outcome Distribution

- Simulation analysis describes not only the outcomes of certain decisions, but also the probability distribution of those outcomes – the probability each of these outcomes occurs.
- After the simulation analysis, the focus then turns to the probability distribution of the outcomes.
- Describe the characteristics of this new distribution mean, variance, skewness, kurtosis, percentiles, etc.

Example

- You want to invest \$1,000 in the US stock market for one year.
- You invest in a mutual fund that tries to produce the same return as the S&P500 Index.

$$P_1 = P_0 + r_{0,1} * P_0$$

OR

 $P_1 = P_0 * (1 + r_{0,1})$

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 OR
$$P_1 = P_0 * (1 + r_{0,1})$$
 Initial Investment Return

Selecting Distributions

- When designing your simulations the biggest choice comes from the decision of the distribution on the inputs that vary.
- 3 Methods:
 - Common Probability Distribution
 - 2. Historical (Empirical) Distribution
 - 3. Hypothesized Future Distribution

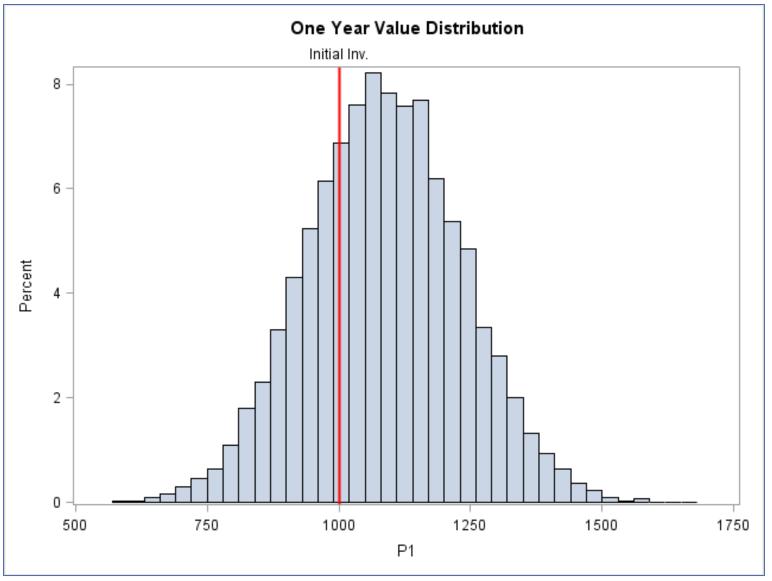
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$$P_1 = P_0 * (1 + r_{0,1})$$

 Assume annual returns follow a Normal distribution with historical mean of 8.79% and std. dev. of 14.75%.

Example



Introduction to Simulation – SAS

```
data SPIndex;
    do i = 1 to 10000;
        r = RAND('Normal', 0.0879, 0.1475);
        P0 = 1000;
        P1 = P0*(1 + r);
        output;
    end;
run;
```

Introduction to Simulation – R

```
r <- rnorm(10000, 0.0879, 0.1475)
P0 <- 1000
P1 <- 1000*(1+r)
```



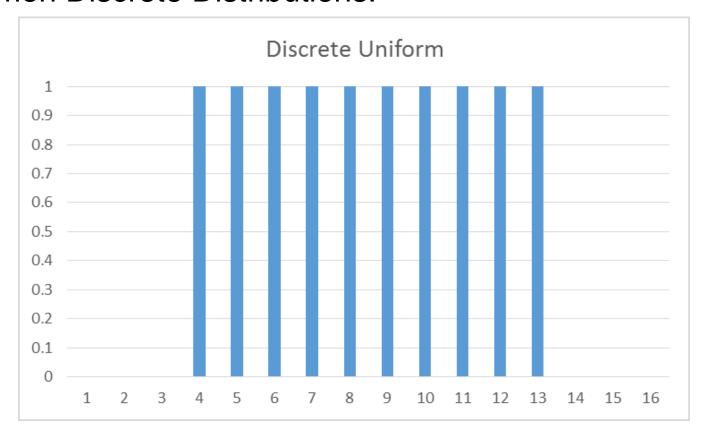
DISTRIBUTION SELECTION

Selecting Distributions

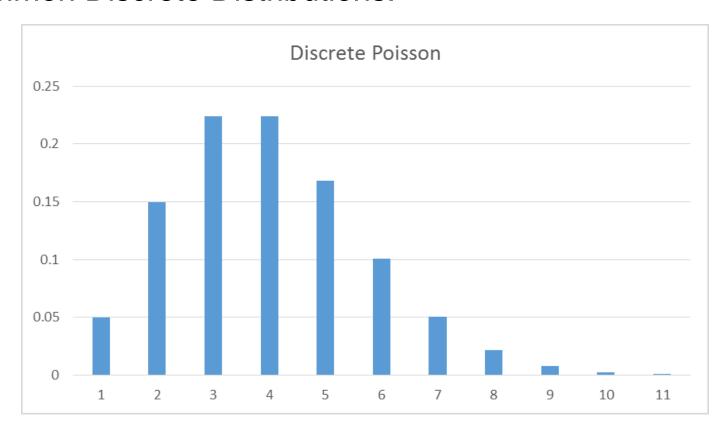
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- Common Discrete Distributions:
 - Uniform Distribution
 - Poisson Distribution

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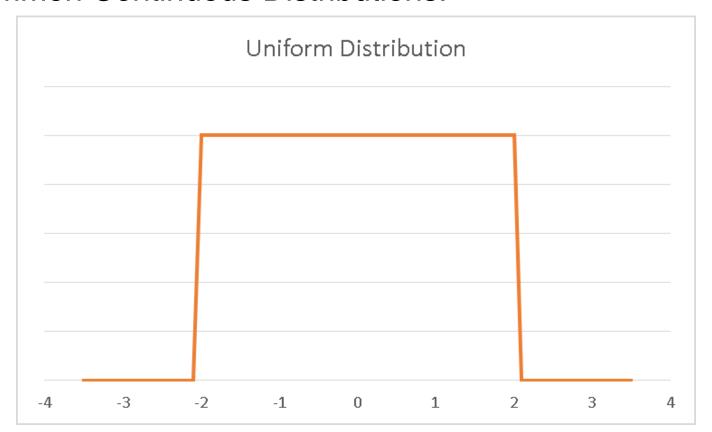


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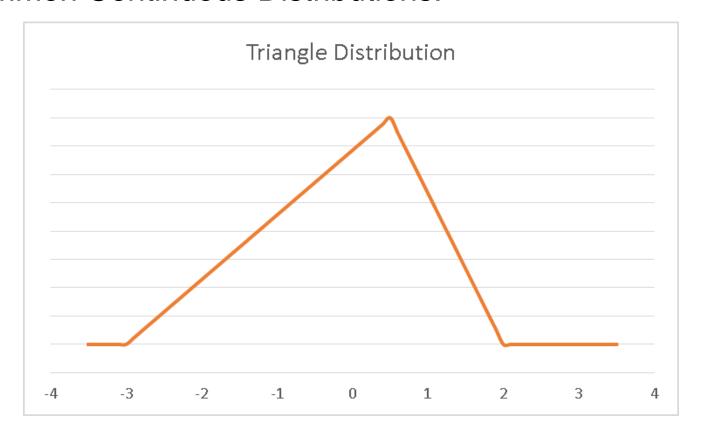


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- Common Continuous Distributions:
 - 1. Continuous Uniform Distribution
 - 2. Triangular Distribution
 - Student's t-Distribution
 - 4. Lognormal Distribution
 - Normal Distribution
 - Exponential Distribution
 - 7. Chi-Square Distribution
 - Beta Distribution

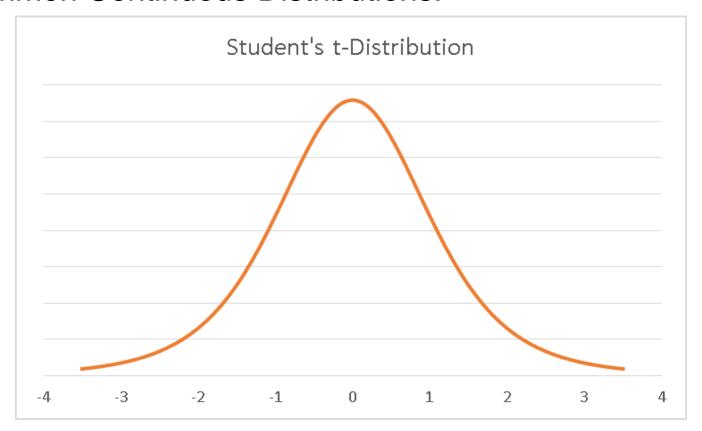
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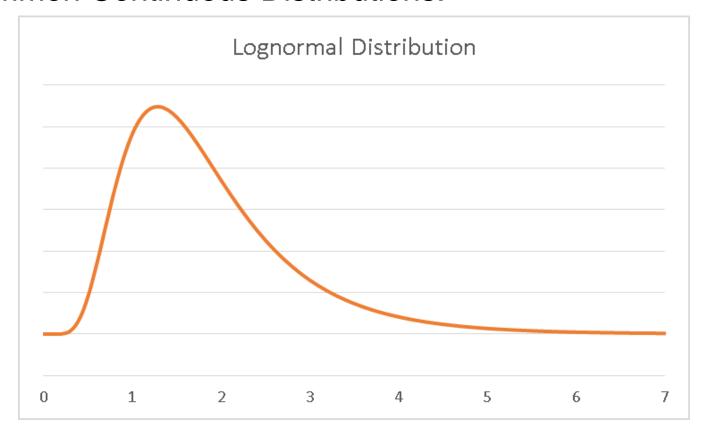
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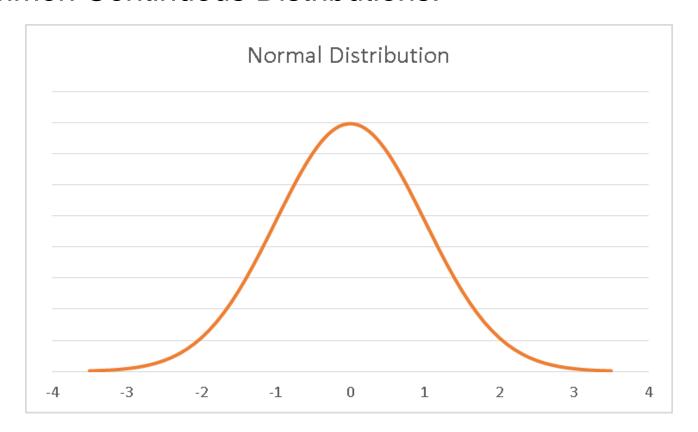
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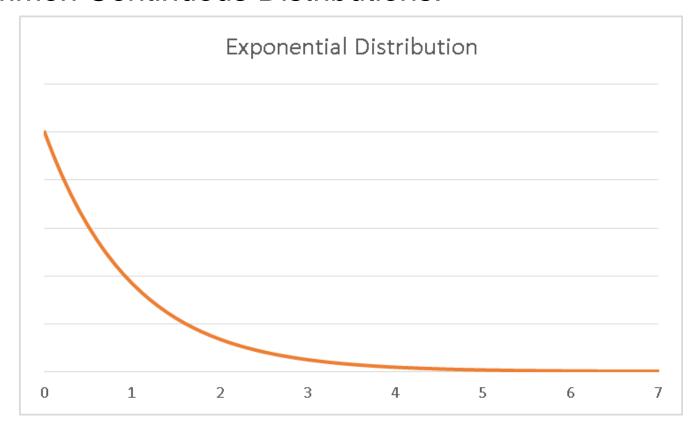
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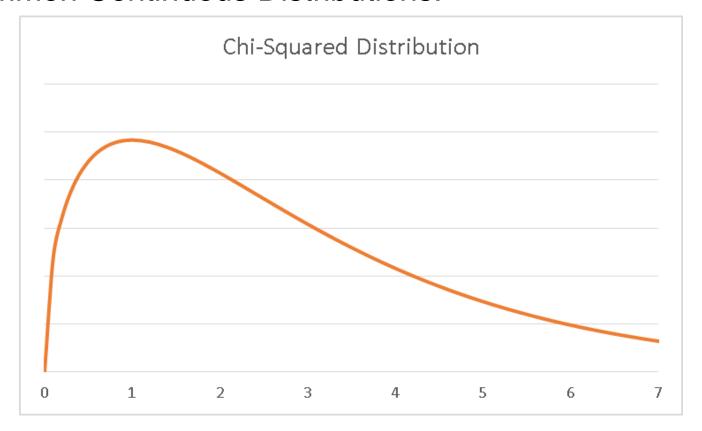
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Historical (Empirical) Distributions

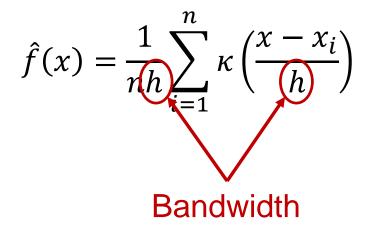
- If you are unsure of the distribution of the data you are trying to simulate, you can estimate it using kernel density estimation.
- Kernel density estimation is a non-parametric method of estimating distributions of data through smoothing out of data values.

Historical (Empirical) Distributions

The Kernel density estimator is as follows:

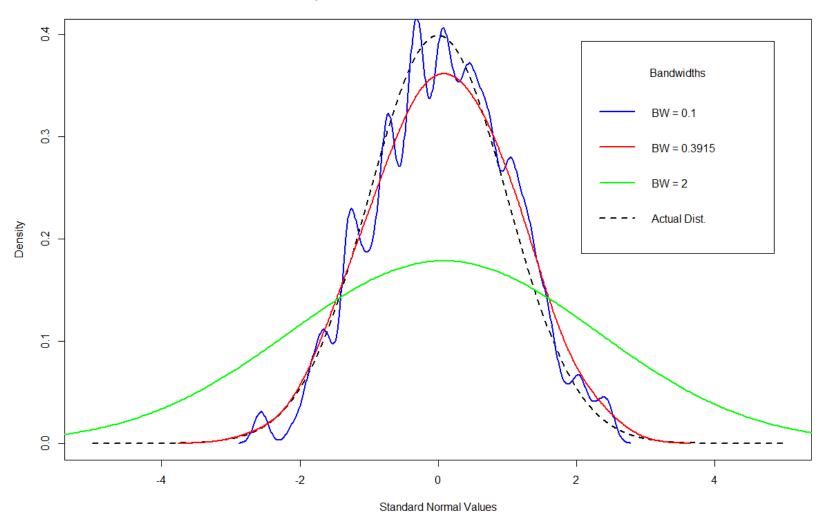
$$\hat{f}(x) = \frac{1}{nh} \sum_{i=1}^{n} \kappa \left(\frac{x - x_i}{h} \right)$$

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Bandwidth Comparison

Comparison of Bandwidths for Standard Normal



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Kernel Function

- Typical Kernel functions:
 - Normal
 - 2. Quadratic
 - Triangular
 - 4. Epanechnikov

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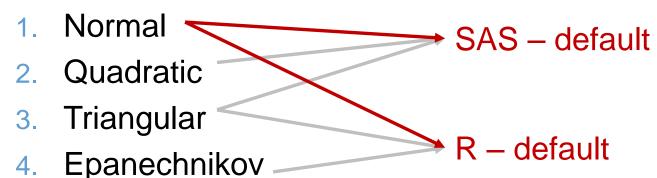


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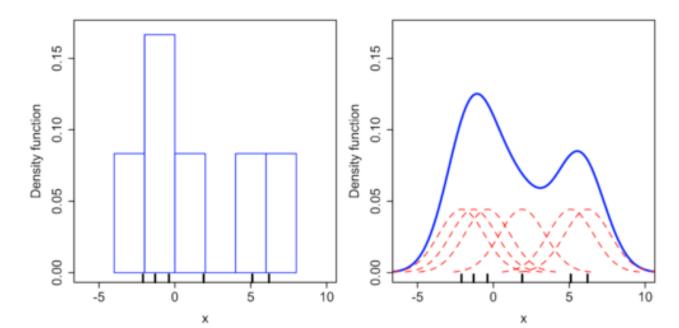
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Assume Normal Kernel function:



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 Once you have the Kernel density function, you can sample from this density function.

```
proc kde data=SPIndex;
     univar P1 / unistats;
run;
proc iml;
     start SmoothBootstrap(x, B, Bandwidth);
          N = 1000;
          s = Sample(x, N);
          eps = j(B, N);
          call randgen(eps, "Normal", 0, Bandwidth);
          return( s + eps );
     finish:
     use WORK.SPIndex;
     read all var {P1} into x;
     close WORK.SPIndex;
     call randseed (12345);
     y = SmoothBootstrap(x, 100, 25.55);
     Est y = y;
     create Smooth var {"Est y"};
     append;
     close Smooth;
quit;
```

```
Density.P1 <- density(P1, bw = "SJ-ste")
Density.P1

Est.P1 <- rkde(fhat=kde(P1, h=21.31), n=1000)
hist(Est.P1, breaks=50, main='Estimated One Year
Value Distribution', xlab='Final Value')</pre>
```

The Kernel density estimator is as follows:

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- Once you have the Kernel density function, you can sample from this density function.
- WARNING: Sample size matters!
 - 1. If you have large sample sizes, your bandwidth can be smaller and your estimates more accurate.
 - If you have small sample sizes, your bandwidth increases and estimates are more smoothed.

Hypothesized Future Distribution

- Maybe you know of an upcoming change that will occur in your variable so that the past information is not going to be the future distribution.
- Example:
 - The volatility of the market is forecasted to increase, so instead of a standard deviation of 14.75% it is 18.25%.
- In these situations, you can select any distribution of choice.



COMPOUNDING AND CORRELATIONS

Multiple Input Probability Distributions

- Complication arises when you are now simulating multiple inputs changing at the same time.
- Even when the distributions of these inputs are the same, the final result can still be hard to mathematically calculate – benefit of simulation.

Multiple Input Probability Distributions

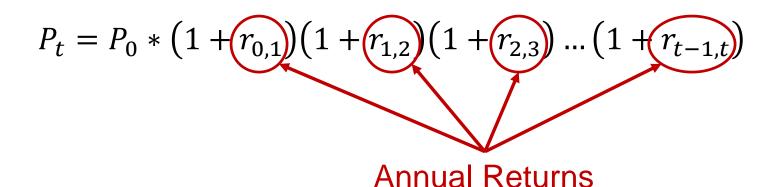
General Facts:

- 1. When a constant is added to a **random variable** (the variable with the distribution) then the distribution is the same, only shifted by the constant.
- 2. The addition of many distributions that are the same is rarely the same shape of distribution exception would be INDEPENDENT Normal distributions.
- 3. The product of many distributions that are the same is rarely the same shape of distribution exception would be INDEPENDENT lognormal distributions (popular in finance for this reason).

- You want to invest \$1,000 in the US stock market for thirty years.
- You invest in a mutual fund that tries to produce the same return as the S&P500 Index.

$$P_t = P_0 * (1 + r_{0,1})(1 + r_{1,2})(1 + r_{2,3}) \dots (1 + r_{t-1,t})$$

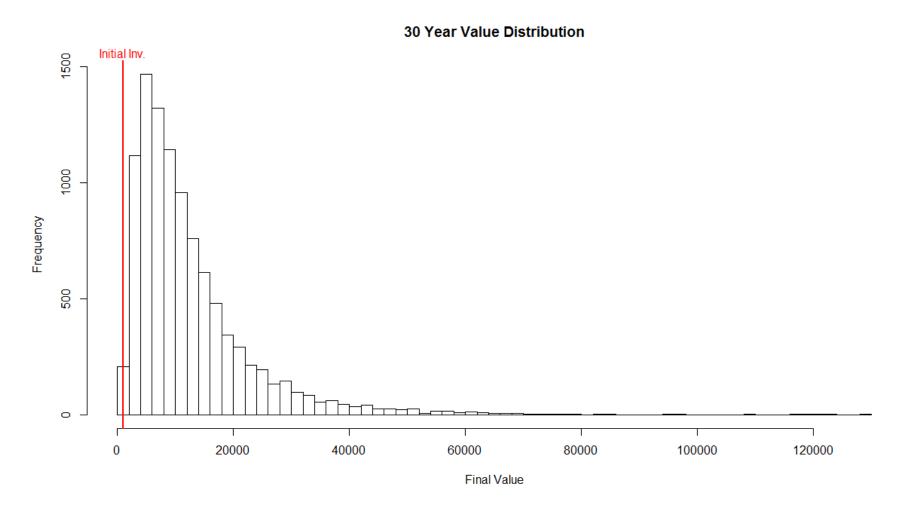
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$$P_t = P_0 * (1 + r_{0,1})(1 + r_{1,2})(1 + r_{2,3}) \dots (1 + r_{t-1,t})$$

 Assume annual returns follow a Normal distribution with historical mean of 8.79% and std. dev. of 14.75% every year.



Multiple Input Prob. Distribution – SAS

```
data SPIndex30;
   do i = 1 to 10000;
       P0 = 1000;
        r = RAND('Normal', 0.0879, 0.1475);
       Pt = P0*(1 + r);
       do j = 1 to 29;
           r = RAND('Normal', 0.0879, 0.1475);
           Pt = Pt*(1 + r);
       end;
       output;
   end;
run;
```

Multiple Input Prob. Distribution – R

```
P30 <- rep(0,10000)
for(i in 1:10000) {
  PO <- 1000
  r \leftarrow rnorm(n=1, mean=0.0879, sd=0.1475)
  Pt < - P0*(1 + r)
  for(j in 1:29) {
    r < -rnorm(n=1, mean=0.0879, sd=0.1475)
    Pt < - Pt^*(1 + r)
  P30[i] <- Pt
```

Correlated Inputs

- Not all inputs are independent of each other.
- Having correlations between your input variables adds even more complication to the simulation and final distribution.
- May need to simulate random variables that have correlation with each other.

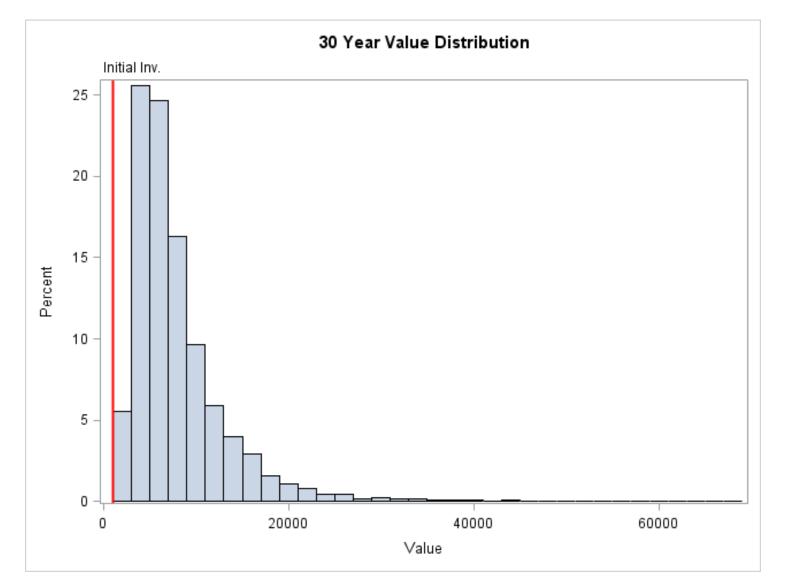
- You want to invest \$1,000 in the US stock market or US
 Treasury bonds for thirty years.
- You invest a certain percentage in a mutual fund that tries to produce the same return as the S&P500 Index and the rest in US Treasury bonds.

$$P_{t,S} = P_{0,S} * (1 + r_{0,1})(1 + r_{1,2})(1 + r_{2,3}) \dots (1 + r_{t-1,t})$$

$$P_{t,B} = P_{0,B} * (1 + r_{0,1})(1 + r_{1,2})(1 + r_{2,3}) \dots (1 + r_{t-1,t})$$

$$P_{t} = P_{t,S} + P_{t,B}$$

- You want to invest \$1,000 in the US stock market or US
 Treasury bonds for thirty years.
- You invest a certain percentage in a mutual fund that tries to produce the same return as the S&P500 Index and the rest in US Treasury bonds.
- Treasury bonds perceived as safer investment so when stock market does poorly more people invest in bonds – negatively correlated.
- Assume mutual fund Normal(8.79%, 14.75%).
- Assume Treasury Bond Normal(4.00%, 7.00%).
- Assume correlation of -0.2.



- Careful about only using summary statistics to evaluate the decisions to be made from simulations.
- Need to look at whole picture whole distribution.
- Example:
 - Which is "better" 50/50 stocks/bonds (Strategy A) or 30/70 stocks/bonds (Strategy B)?

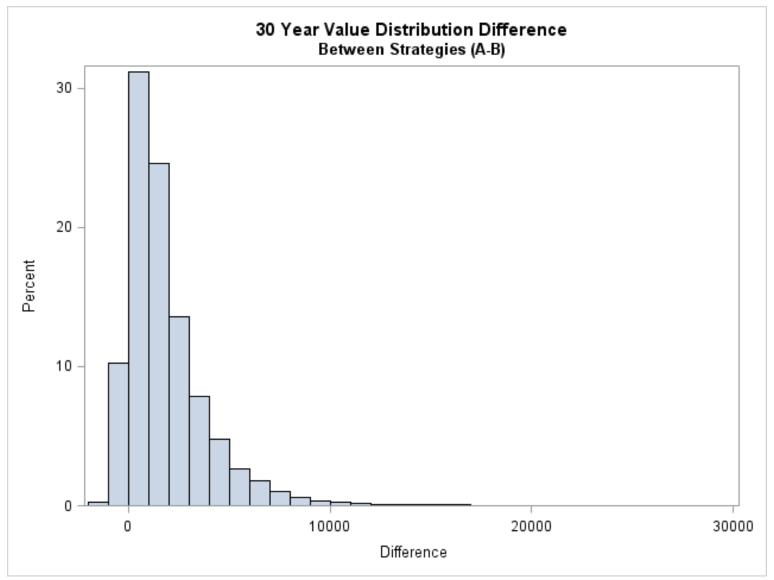
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 - Which is "better" 50/50 stocks/bonds (Strategy A) or 30/70 stocks/bonds (Strategy B)?
 - Mean return of Strategy A \$7,904
 - Mean return of Strategy B \$6,042
 - C.V. of returns for Strategy A 66.51%
 - C.V. of returns for Strategy B 52.35%

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 - Mean return of Strategy A \$7,904
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 - C.V. of returns for Strategy A 66.51%
 - C.V. of returns for Strategy B 52.35%
 - Strategy A has higher return but APPEARS riskier.

- Careful about only using summary statistics to evaluate the decisions to be made from simulations.
- Need to look at whole picture whole distribution.
- Example:
 - Which is "better" 50/50 stocks/bonds (Strategy A) or 30/70 stocks/bonds (Strategy B)?
 - 5th Percentile of Strategy A \$2,944
 - 5th Percentile of Strategy B \$2,839
 - 95th Percentile of Strategy A \$17,558
 - 95th Percentile of Strategy B \$11,719
 - Strategy A has less downside, but higher upside.

- Careful about only using summary statistics to evaluate the decisions to be made from simulations.
- Need to look at whole picture whole distribution.
- Standard deviation is not always a good measure of riskiness.
- Higher standard deviation not necessarily bad if the largest deviations from the mean are on the upside!

Example – Difference (A – B)





HOW MANY AND HOW LONG?

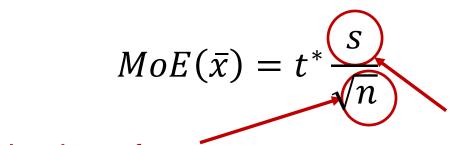
- The possible number of outcomes for a simulation output variable is basically infinite.
- We need to get a "sampling" of these values.
- Accuracy of the estimates depends on the number of simulated values.
- How many simulations do you need to run?

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- Imagine you are interested in the mean value of the output distribution from your simulation.
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Number of simulated values

Standard deviation from simulated values

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$$MoE(\bar{x}) \neq \underbrace{t^*}_{\sqrt{n}}^{S}$$

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