Competing Risks

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Overview

Introduction to competing risks: Overview

Multiple event types

- All of the methods we've used in class so far have been for studying the time until one event occurs
- Everything we've learned can be extended to multiple events or multiple types of events
- Today, we'll discuss the latter: what happens when there is more than one possible reason for failure?
- All of the methods you have and will learn in this course can be generalized as a particular type of *multi-state* analysis

Overview Estimation

Competing risks

- Consider the following examples:
 - Death from cancer vs. death from other causes
 - Supreme Court justices leaving due to death vs. retirement
 - Leaving a job due to retirement, injury, or being fired
 - Pump failure due to jamming, flooding, motor failure, or surge
- In all of these cases, there are multiple, mutually exclusive causes of failure
- These are examples of a competing risks problem, where each subject can experience only one of several possible events

Previous assumptions

- "Regardless, we assume [event time] and [censoring time] are independent"
- "Basically, we act as if subjects censored at time *t* were randomly selected to be censored from all subjects still at risk at time *t*"
- "Under independence ... there's actually no [mathematical] difference between fixed and random censoring"

What "independence" means

- On your HW, you focused on flooding failures and treated all other failure types as censored
- In this context, the independence assumption means that a censored pump and an uncensored pump have the same risk of flooding, regardless of the reason for censoring
- If censoring weren't independent, then a censored pump (say, that jammed) would a different risk of flooding than the uncensored pumps—the ones that actually flooded

Estimation

Independence

- By treating other failure types as censored, we're essentially implying that once a pump fails due to jamming, we still don't know when it would fail due to flooding—we assume that the event types are independent
- There is, of course, no test for this
- You can decide whether or not independence is reasonable; i.e., if subjects with a high risk of one event are equally likely to experience the other events
- For example, you could just assume that at any time, pumps that flooded aren't any more or less likely to have jammed, had a mechanical failure, or experienced a surge of water

Introduction to competing risks: Estimation

Data set

- In today's class, we'll model the tenure of Supreme Court justices and their reason for departure (as of 12/31/17)
- Response: how long do SCOUTS justices sit on the Court?
 - days is the tenure (in days, but we'll use years) on the Court,
 beginning on the day that the judicial oath was taken
 - status indicates the reason for leaving the Court: (0) currently sitting, (1) death, or (2) resignation/retirement
- Predictors:
 - nomage: age at nomination
 - nomyear: year of nomination
 - nomchief: indicator of whether or not the candidate was nominated as Chief Justice

Review

- Remember the two major functions in survival analysis: the survival function and the hazard function
- The survival function is the probability of the surviving beyond time *t*:

$$S(t) = \Pr(T > t)$$

$$= 1 - \Pr(T \le t)$$

$$= 1 - F(t)$$

• The hazard function is the conditional failure rate in an interval:

$$\lambda(t) = -\frac{d}{dt} \log S(t)$$

$$= -\frac{d}{dt} \log (1 - F(t))$$

$$= \frac{f(t)}{1 - F(t)}$$

Cause-specific hazards

- Since we are now dealing with different types of events, we need to extend what we already know to each possible event type
- For a particular event type *k*, the **cause-specific hazard** is the conditional failure rate *from cause k*:

$$\lambda_k(t) = \frac{f_k(t)}{1 - F(t)}$$

- Same interpretation as before, just cause-specific now; e.g., rate of death *when only death can happen*
- The overall hazard is just the sum of the cause-specific hazards:

$$\lambda(t) = \sum_k \lambda_k(t)$$

Cumulative incidence function

 Focusing again on cause-specific estimates, the cumulative incidence function (CIF) is the [unconditional!] probability that cause k occurs by time t:

$$F_k(t) = \Pr\left(T \le t, K = k\right) = \int_0^t \lambda_k(u) S(u) du$$

• The probability of *any* event by time *t* is just the sum of the individual CIFs:

$$F(t) = \sum_{k} F_k(t)$$

and it should be clear that $S(t) = 1 - F(t) = 1 - \sum_{k} F_k(t)$

Overall survival

$$S(t) = 1 - \sum_{k} F_k(t)$$

- Note that the survival function is still unconditional, since survival means surviving all of the risks, so there's no such thing "cause-specific" survival
- Thus, because *S*(*t*) will change when *any* event happens, the probability/incidence of cause *k* will also change—whereas it wouldn't if we just censored all non-*k* events (since censoring doesn't change the survival probability)

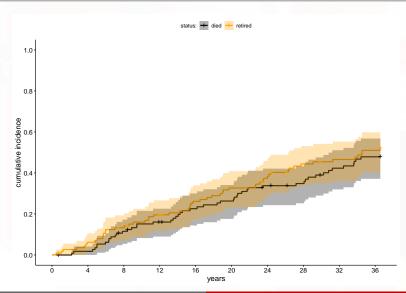
Estimating the CIF

We can estimate the CIFs using the nonparametric estimates of $\hat{S}(t)$, $\hat{\lambda}(t)$ that we learned previously:

$$\hat{F}_k(t) = \sum_{t_m \le t} \hat{\lambda}_k(t_m) \hat{S}(t_{m-1})$$

where the cause-specific hazard $\lambda_k(t) = \frac{d_{kt}}{r_t}$ is the number of cause-k events at time t divided by the overall risk set at time t

Estimating the CIF (con't)



Cause-specific hazard model Fine-Gray model

Modeling competing risks: Cause-specific hazard model

The usual Cox regression model

- A typical modeling approach for competing risks is to use separate Cox regression models for each cause, treating the other events as censored
- What this approach is actually doing is modeling the effects of predictors on the cause-specific hazard:

$$\lambda_{ik}(t) = \lambda_{0k}(t)e^{\mathbf{x}_i^{\mathsf{T}}\boldsymbol{\beta}}$$

 When doing this, we're focused on just one cause, basically ignoring anything else that can happen; e.g., we create a hypothetical world where death is the only reason Supreme Court justices ever leave the Court

Cause-specific model: death

	exp(coef)	lower .95	upper .95
nomage	1.075	1.025	1.127
nomyear	0.988	0.983	0.993
nomchief	0.642	0.260	1.587

- Older justices are at a higher risk of dying in office (HR 95% CI: [1.025, 1.127])
- The risk of dying in office decreases each year (HR 95% CI: [0.983, 0.993])
- (When only death can occur)

Modeling competing risks: Fine-Gray model

Sub-hazards

• By treating non-*k* events as censored, you are modeling the cause-specific hazard:

$$\lambda_k(t) = -\frac{d}{dt}(\log(1 - F(t)))$$

which is the rate of, say, death at time *t* for those still at risk at time *t*

• Instead, let's take the CIFs and look at the **sub-hazard**:

$$\lambda_k^s(t) = -\frac{d}{dt}(\log(1 - F_k(t)))$$

which can be thought of as the rate of death at time *t* conditional on **not having died yet**—so justices departing for reasons other than death *are still "allowed" to die!*

Proportional sub-hazard model

• In the **Fine-Gray model** (FG), we thus replace the cause-specific hazard with the sub-hazard to get a "proportional sub-hazard" (PSH) model:

$$\lambda_{ik}^{s}(t) = \lambda_{0k}^{s}(t)e^{\mathbf{x}_{i}^{\mathsf{T}}\boldsymbol{\beta}}$$

- By using the CIFs rather than overall survival (i.e., $1 F_k(t)$ vs. 1 F(t)), the risk set is adjusted to account for different events happening
- In this framework, the risks are essentially balanced by looking at the *probability* of one specific cause in the presence of other causes by keeping failures from other causes "at risk" for the particular one we're focused on
- When using CIFs, we don't need to assume the competing risks are independent!

Sub-hazard model: death

	exp(coef)	lower .95	upper .95
nomage nomyear	1.007 0.991	0.968 0.986	1.048 0.996
nomchief	0.850	0.358	2.020

- Nomination age doesn't have much of an effect on the probability of dying in office (HR 95% CI: [0.968, 1.048])
- Dying in office becomes a little less likely each year (HR 95% CI: [0.986, 0.996])
- (When either death or retirement can happen)