**TASK-0**

1. **TASK 0.1**

We installed all required software

1. Python

2. Numpy

3. OpenCV

4. PyOpenGL

5. Pillow

6. Pygame

To install

Type in command

pip install pathname.whl

1. **TASK-0.2**

**Camera Calibration**

1. Learn to find camera matrix and distortion matrix

>> camera matrix and distortion matrix are the intrinsic parameter of the camera

1. **Camera matrix –** It is 3\*3 matrix and it has information about the focal length and optical