



INTRODUCTION TO QUANTUM ERROR CORRECTION

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GROUPS AND HILBERT SPACES

Definition (Group). A group is a pair (G, \cdot) where G is a set and $\cdot : G^2 \rightarrow G$ is a binary operation such that (i) for all $g_1, g_2, g_3 \in G$, we have $g_1 \cdot (g_2 \cdot g_3) = (g_1 \cdot g_2) \cdot g_3$, (ii) there exists an $e \in G$ such that for all $g \in G$, $e \cdot g = g = g \cdot e$, and (iii) for all $g \in G$, there exists a $g^{-1} \in G$ so that $g \cdot g^{-1} = e = g^{-1} \cdot g$.

Definition (Homomorphism). A function $\phi : G \rightarrow G'$ between groups is a homomorphism if it preserves the respective operation functions of G and G' .

Definition (Isomorphism). A homomorphism ϕ is an isomorphism if it has an inverse ϕ^{-1} .

Definition (Centralizer). The centralizer $C_G(S)$ of a set $S \subseteq G$ is defined as

$$C_G(S) = \{g \in G : gs = sg \text{ for all } s \in S\}.$$

Definition (Normalizer). The normalizer $\mathcal{N}_G(S)$ of a subset $S \subseteq G$ is

$$\mathcal{N}_G(S) = \{g \in G : gSg^{-1} = S\},$$

where

$$gSg^{-1} = \{gsg^{-1} : s \in S\}.$$

Definition (Vector Space). A vector space over \mathbb{C} is a pair $((\mathcal{H}, +), \cdot)$, where $(\mathcal{H}, +)$ is a group under addition and $\cdot : \mathbb{C} \times \mathcal{H} \rightarrow \mathcal{H}$ is an “action” by the complex numbers which satisfies compatibility, identity, and distributivity of the action over addition for both the “vectors” in \mathcal{H} and the “scalars.”

Definition (Direct Sum). The direct sum $\mathcal{H}_1 \oplus \mathcal{H}_2$ takes two vector spaces and returns a third, larger space of tuples in \mathcal{H}_1 and \mathcal{H}_2 , respectively, and thus, is closed under both operations’ componentwise addition and scalar multiplication from \mathbb{C} . In general, the direct sum of spaces indexed by $i \in I$ is all tuples in \mathcal{H}_i with finitely many nonzero entries.

Definition (Finite-Dimensional Hilbert Space). A complex, finite-dimensional Hilbert space \mathcal{H} is a complex, finite-dimensional inner product space $(\mathcal{H}, \langle \cdot, \cdot \rangle)$.

KNILL-LAFLAMME SUBSPACE CONDITION

Definition (Superoperator). A superoperator is a bounded linear map $\Phi : \mathbb{B}(\mathcal{H}^A) \rightarrow \mathbb{B}(\mathcal{H}^B)$, where $\mathbb{B}(\mathcal{H})$ represents the space of bounded linear operators on \mathcal{H} . Since $\mathbb{B}(\mathcal{H})$ itself forms a Hilbert space, these maps describe the transformations between spaces of operators.

Definition (Quantum Channel). A quantum channel is a type of superoperator, represented as a bounded linear map $\mathcal{E} : \mathbb{B}(\mathcal{H}^A) \rightarrow \mathbb{B}(\mathcal{H}^B)$ that satisfies the following properties: (i) Completely Positive: The map \mathcal{E} is completely positive, meaning that for any auxiliary Hilbert space \mathcal{H}^C , the extended map $\mathcal{I}^C \otimes \mathcal{E}$ is positive, where \mathcal{I}^C is the identity map on $\mathbb{B}(\mathcal{H}^C)$, and (ii) Trace Preserving: The map \mathcal{E} is trace preserving, meaning that for any state ρ , $\text{tr}(\rho) = \text{tr}(\mathcal{E}(\rho))$.

Theorem (Choi-Jamiołkowski Isomorphism). A vector isomorphism Δ can be drawn between from superoperators in the set $\mathbb{B}(\mathbb{B}(\mathcal{H}^A) : \mathbb{B}(\mathcal{H}^B))$ to bounded operators in the set $\mathbb{B}(\mathcal{H}^A \otimes \mathcal{H}^B)$. This isomorphism sends every superoperator Φ to its Choi matrix J_Φ . The inverse map Δ^{-1} sends every Choi matrix to a superoperator $\Phi : \rho \mapsto \text{tr}_A((\rho^t \otimes I^B)(J))$.

Theorem (Kraus Representation). A superoperator $\Phi : \mathbb{B}(\mathcal{H}^A) \rightarrow \mathbb{B}(\mathcal{H}^B)$ is completely positive if and only if there exist Kraus operators $\{E_i : \mathcal{H}^A \rightarrow \mathcal{H}^B\}_{i=1}^r$ such that:

$$\Phi(X) = \sum_i E_i X E_i^\dagger, \quad \text{for all } X \in \mathbb{B}(\mathcal{H}^A).$$

Definition (Correctable Error). An error \mathcal{E} which can be corrected by a recovery operation \mathcal{R} via $(\mathcal{R} \circ \mathcal{E})(\rho) \propto \rho$ is called “correctable” as long as both are quantum channels and there exists a \mathbb{C} -linear subspace $\mathcal{C} \subseteq \mathcal{H}$ called the code space such that $\rho \in \mathbb{B}(\mathcal{C})$.

Theorem (Knill-Laflamme). Let $\mathcal{E} : \mathbb{B}(\mathcal{H}) \rightarrow \mathbb{B}(\mathcal{H})$ be a quantum error channel with Kraus operators $\{E_i\}_{i=1}^r$, and let $P : \mathcal{H} \rightarrow \mathcal{C}$ be the orthogonal projection onto the code space $\mathcal{C} \subseteq \mathcal{H}$. Then, \mathcal{E} is correctable if and only if

$$PE_a^\dagger E_b P = \lambda_{ab} P,$$

where $[\lambda_{ab}] \in \mathbb{M}_r(\mathbb{C})$ is self-adjoint (Hermitian).

In other words, a quantum error \mathcal{E} ’s “correctability” is entirely determined by its Kraus operators and the projection. When the Knill-Laflamme condition is satisfied, a correctable error can be inputted into the recovery channel \mathcal{R} to return the code space \mathcal{C} to its previous state, as $\mathcal{R}(\mathcal{E}(\rho)) \propto \rho$ (which becomes $\mathcal{R}(\mathcal{E}(\rho)) = \rho$ when the partial trace is applied).

THE STABILIZER FORMALISM AND n -QUBIT PAULI GROUP

Definition (Pauli Group). The Pauli group is a multiplicative 2×2 matrix group defined by $\mathcal{P} = \langle X, Y, Z \rangle$, where

$$X = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad Y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad Z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}.$$

The Pauli group naturally acts on a 1-qubit system (with state space \mathbb{C}^2) via multiplication. Since an n -qubit system has state space $\mathbb{C}^2 \otimes \mathbb{C}^2 \otimes \dots \otimes \mathbb{C}^2$, the analog of the Pauli group for this space should somehow “live in” $\mathcal{P}_n \otimes \mathcal{P}_n \otimes \dots \otimes \mathcal{P}_n$ to act on this state space.

Definition (n -qubit Pauli Group). The n -qubit Pauli group is the set

$$\mathcal{P}_n = \left\{ \gamma \bigotimes_{i=1}^n \sigma_i : \sigma_i \in \mathcal{P} \text{ and } \gamma \in \{\pm 1, \pm i\} \right\}.$$

Definition (Stabilizer Subgroup). Let there be a subgroup $\mathcal{S} \leq \mathcal{P}_n$ that is abelian and such that $-I \notin \mathcal{S}$. Without loss of generality, assume $\mathcal{S} = \langle Z_1, \dots, Z_s \rangle$ for $s \leq n$, where Z_j denotes a 1-local action of Z on the j th qubit. We call \mathcal{S} a stabilizer subgroup.

Definition (Stabilizer Code Space). Given a stabilizer \mathcal{S} , define the associated code space by $\mathcal{C}(\mathcal{S}) = \text{span}\{v \in (\mathbb{C}^2)^{\otimes n} : Z_j v = v \text{ for all } 1 \leq j \leq s\}$. These are all vectors which are invariant under the action of the stabilizer \mathcal{S} .

Theorem (Stabilizer Formalism). An error \mathcal{E} with Kraus operators $\{E_i\}_{i=1}^r$ is correctable on the code space $\mathcal{C}(\mathcal{S})$ if and only if

$$E_a^\dagger E_b \in \text{span}\{\mathcal{P}_n \setminus \mathcal{N}_{\mathcal{P}_n}(\mathcal{S}) \cup \mathcal{S}\}.$$

OPERATOR QUANTUM ERROR CORRECTION

In general, motivated by the form of the so-called *noise commutant* \mathcal{A}' , we may form a Hilbert space decomposition

$$\mathcal{H} \simeq \bigoplus_j \mathcal{H}_j^A \otimes \mathcal{H}_j^B.$$

Pulling apart the sectors of the decomposition, we may simplify and fix a code space $\mathcal{H}^A \otimes \mathcal{H}^B$, yielding a new fixed partition

$$\mathcal{H} = \underbrace{(\mathcal{H}^A \otimes \mathcal{H}^B)}_{\mathcal{C}} \oplus \mathcal{C}^\perp.$$

We call \mathcal{H}^A a *noiseless subsystem*, thus stashing any information in the A -system of the code space. Then, letting $\mathcal{S} = \langle Z_1, Z_2, \dots, Z_s \rangle$ be an n -fold Pauli stabilizer, we may form the gauge group

$$\mathcal{G} = \langle i, Z_1, \dots, Z_s, X_{s+1}, Z_{s+1}, \dots, X_{s+r}, Z_{s+r} \rangle,$$

writing that there exist s stabilizer qubits, r gauge qubits, and $n - s - r$ logical qubits.

Theorem (Poulin’s Stabilizer Formalism). Given an error channel \mathcal{E} on \mathcal{H} , as above, a recovery channel \mathcal{R} exists if and only if for all a, b , the error Kraus operators satisfy

$$E_a^\dagger E_b \in \text{span}\{\mathcal{P}_n \setminus \mathcal{N}_{\mathcal{P}_n}(\mathcal{S}) \cup \mathcal{G}\}.$$

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