

Abstract

We present a short note describing a condition number of the intersection of two Bézier curves. Since tangent intersections are to transversal intersections as multiple roots are to simple roots of a function, this condition number is infinite for non-transversal intersections.

Keywords: Bézier curve, Curve intersection, Condition number

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1 Introduction

Placeholder

2 Problem conditioning

Consider a smooth function $F : \mathbf{R}^n \rightarrow \mathbf{R}^n$ with Jacobian $F_{\mathbf{x}} = J$. We want to consider a special class of functions of the form $F(\mathbf{x}) = \sum_j c_j \phi_j(\mathbf{x})$ where the basis functions ϕ_j are also smooth functions on \mathbf{R}^n and each $c_j \in \mathbf{R}$. We want to consider the effects on a root $\alpha \in \mathbf{R}^n$ of a perturbation in one of the coefficients c_j . We examine the perturbed functions

$$G(\mathbf{x}, \delta) = F(\mathbf{x}) + \delta \phi_j(\mathbf{x}). \quad (2.1)$$

Since $G(\alpha, 0) = \mathbf{0}$, if J^{-1} exists at $\mathbf{x} = \alpha$ then the implicit function theorem tells us that we can define \mathbf{x} via

$$G(\mathbf{x}(\delta), \delta) = \mathbf{0}. \quad (2.2)$$

Taking the derivative with respect to δ we find that $\mathbf{0} = G_{\mathbf{x}} \mathbf{x}_\delta + G_\delta$. Plugging in $\delta = 0$ we find that $\mathbf{0} = J(\alpha) \mathbf{x}_\delta + \phi_j(\alpha)$, hence we conclude that

$$\mathbf{x}(\delta) = \alpha - J(\alpha)^{-1} \phi_j(\alpha) \delta + \mathcal{O}(\delta^2). \quad (2.3)$$

This gives a relative condition number (for the root) of

$$\frac{\|J(\alpha)^{-1} \phi_j(\alpha)\|}{\|\alpha\|}. \quad (2.4)$$

By considering perturbations in *all* of the coefficients: $|\delta_j| \leq \varepsilon |c_j|$, a similar analysis gives a root function

$$\mathbf{x}(\delta_0, \dots, \delta_n) = \alpha - J(\alpha)^{-1} \sum_{j=0}^n \delta_j \phi_j(\alpha) + \mathcal{O}(\varepsilon^2). \quad (2.5)$$

With this, we can define a root condition number

$$\kappa_\alpha = \lim_{\varepsilon \rightarrow 0} \left(\sup \frac{\|\delta \alpha\| / \varepsilon}{\|\alpha\|} \right) = \lim_{\varepsilon \rightarrow 0} \left(\sup \frac{\|J(\alpha)^{-1} \sum_j \delta_j \phi_j(\alpha)\| / \varepsilon}{\|\alpha\|} \right). \quad (2.6)$$

When $n = 1$, J^{-1} is simply $1/F'$ and we find

$$\kappa_{\alpha} = \frac{1}{|\alpha F'(\alpha)|} \sum_{j=0}^n |c_j \phi_j(\alpha)|. \quad (2.7)$$

This value is given by the triangle inequality applied to $\delta\alpha$ and equality can be attained since the sign of each $\delta_j = \pm c_j \varepsilon$ can be modified at will to make $\phi_j(\alpha) \delta_j = |\phi_j(\alpha) c_j| \varepsilon$.

When $n > 1$, the triangle inequality tells us that

$$\kappa_{\alpha} = \lim_{\varepsilon \rightarrow 0} \left(\sup \frac{\|\delta\alpha/\varepsilon\|}{\|\alpha\|} \right) \leq \frac{1}{\|\alpha\|} \sum_{j=0}^n |c_j| \|J(\alpha)^{-1} \phi_j(\alpha)\|. \quad (2.8)$$

However, this bound is only attainable if all $\phi_j(\alpha)$ are parallel. However, we'll seldom need to compute the exact condition number and are instead typically interested in the order of magnitude. In this case a lower bound

$$\frac{1}{\|\alpha\|} \max_j |c_j| \|J(\alpha)^{-1} \phi_j(\alpha)\| \quad (2.9)$$

for κ_{α} will suffice as an approximate condition number.

For an example, consider

$$\phi_0 = \begin{bmatrix} x_0 \\ 2 \\ 0 \end{bmatrix}, \phi_1 = \begin{bmatrix} 0 \\ x_1 \\ 3 \end{bmatrix}, \phi_2 = \begin{bmatrix} 2 \\ 0 \\ x_2 \end{bmatrix}, F = \phi_0 + 2\phi_1 + 3\phi_2, \alpha = \begin{bmatrix} -6 \\ -1 \\ -2 \end{bmatrix}. \quad (2.10)$$

For a given ε , the maximum root perturbation occurs when $\delta_0 = \varepsilon, \delta_1 = 2\varepsilon, \delta_2 = -3\varepsilon$ and gives $\|J(\alpha)^{-1} \sum_j \delta_j \phi_j(\alpha)\| = 4\sqrt{10}\varepsilon \approx 12.65\varepsilon$. The pessimistic triangle inequality bound gives $\sum_j |c_j| \|J(\alpha)^{-1} \phi_j(\alpha)\| \approx 14.64\varepsilon$ and the maximum individual perturbation is $2\sqrt{10}\varepsilon \approx 6.325\varepsilon$ (this occurs when $\delta_0 = \delta_1 = 0, \delta_2 = \pm 3\varepsilon$).

In this general framework, we can define a condition number both for a simple root of a polynomial in Bernstein form and for the intersection of two planar Bézier curves. For the first, $\phi_j(s) = \binom{n}{j} (1-s)^{n-j} s^j$ the Bernstein basis functions, a polynomial $p(s) = \sum_j b_j \phi_j(s)$ with a simple root $\alpha \in (0, 1]$ has root condition number

$$\kappa_{\alpha} = \frac{1}{\alpha |p'(\alpha)|} \sum_{j=0}^n |b_j \phi_j(\alpha)| = \frac{\tilde{p}(\alpha)}{\alpha |p'(\alpha)|}. \quad (2.11)$$

For the intersection of a degree m curve $b_1(s)$ and a degree n curve $b_2(t)$, we have basis functions

$$\begin{aligned} \phi_{0,-1,1} &= \begin{bmatrix} B_{0,m}(s) \\ 0 \end{bmatrix}, \phi_{0,-1,2} = \begin{bmatrix} 0 \\ B_{0,m}(s) \end{bmatrix}, \dots, \\ \phi_{m,-1,1} &= \begin{bmatrix} B_{m,m}(s) \\ 0 \end{bmatrix}, \phi_{m,-1,2} = \begin{bmatrix} 0 \\ B_{m,m}(s) \end{bmatrix}, \\ \phi_{-1,0,1} &= \begin{bmatrix} -B_{0,n}(t) \\ 0 \end{bmatrix}, \phi_{-1,0,2} = \begin{bmatrix} 0 \\ -B_{0,n}(t) \end{bmatrix}, \dots, \\ \phi_{-1,n,1} &= \begin{bmatrix} -B_{n,n}(t) \\ 0 \end{bmatrix}, \phi_{-1,n,2} = \begin{bmatrix} 0 \\ -B_{n,n}(t) \end{bmatrix}. \end{aligned} \quad (2.12)$$

Since $F(s, t) = b_1(s) - b_2(t)$ we have Jacobian $J(s, t) = \begin{bmatrix} b'_1(s) & -b'_2(t) \end{bmatrix}$. We'll consider a transversal intersection $F(\alpha, \beta) = \mathbf{0}$ with $\det J(\alpha, \beta) \neq 0$. Since each of the ϕ_j is just a scalar multiple of the standard basis vectors, writing $J^{-1} = \begin{bmatrix} \mathbf{v}_1 & \mathbf{v}_2 \end{bmatrix}$, we have

$$\begin{aligned} J(\alpha, \beta)^{-1} \sum_j \delta_j \phi_j(\alpha, \beta) &= \left[\sum_{i=0}^m \delta_{i,-1,1} B_{i,m}(\alpha) + \sum_{j=0}^n \delta_{-1,j,1} B_{j,n}(\beta) \right] \mathbf{v}_1 \\ &\quad + \left[\sum_{i=0}^m \delta_{i,-1,2} B_{i,m}(\alpha) + \sum_{j=0}^n \delta_{-1,j,2} B_{j,n}(\beta) \right] \mathbf{v}_2 = \nu_1 \mathbf{v}_1 + \nu_2 \mathbf{v}_2. \end{aligned} \quad (2.13)$$

where

$$|\nu_k|/\varepsilon \leq \sum_{i=0}^m |c_{i,-1,k}| B_{i,m}(\alpha) + \sum_{j=0}^n |c_{-1,j,k}| B_{j,n}(\beta) = \mu_k \quad (2.14)$$

and the bound can be attained for both $k = 1, 2$ by making the signs of the δ_j agree. If we name the components of each curve via $b_1(s) = [x_1(s) \ y_1(s)]^T$ and $b_2(t) = [x_2(t) \ y_2(t)]^T$ then we see that $\mu_1 = \tilde{x}_1(\alpha) + \tilde{x}_2(\beta)$ and $\mu_2 = \tilde{y}_1(\alpha) + \tilde{y}_2(\beta)$. Thus we have condition number

$$\kappa_{\alpha,\beta} = \frac{1}{\sqrt{\alpha^2 + \beta^2}} \max_{|\nu_k| \leq \mu_k} \|\nu_1 \mathbf{v}_1 + \nu_2 \mathbf{v}_2\|_2 \quad (2.15)$$

$$= \sqrt{\frac{\max_{|\nu_k| \leq \mu_k} \nu_1^2 (\mathbf{v}_1 \cdot \mathbf{v}_1) + 2\nu_1 \nu_2 (\mathbf{v}_1 \cdot \mathbf{v}_2) + \nu_2^2 (\mathbf{v}_2 \cdot \mathbf{v}_2)}{\alpha^2 + \beta^2}}. \quad (2.16)$$

Since J^{-1} is invertible, we know \mathbf{v}_1 and \mathbf{v}_2 are not parallel which can be used to show that the only internal critical point of the function to be maximized in (2.16) is $\nu_1 = \nu_2 = 0$, which is the global minimum. Along the boundary of the rectangle $[-\mu_1, \mu_1] \times [-\mu_2, \mu_2]$, we fix one of ν_1 or ν_2 and the resulting univariate function is an up-opening parabola, hence any critical point must be a local minimum. Thus we know the maximum occurs at two of the four corners of the rectangle:

$$\kappa_{\alpha,\beta} = \sqrt{\frac{\mu_1^2 (\mathbf{v}_1 \cdot \mathbf{v}_1) + 2\mu_1 \mu_2 |\mathbf{v}_1 \cdot \mathbf{v}_2| + \mu_2^2 (\mathbf{v}_2 \cdot \mathbf{v}_2)}{\alpha^2 + \beta^2}}. \quad (2.17)$$

As far as the author can tell, a condition number for the intersection of two planar Bézier curves has not been described in the Computer Aided Geometric Design (CAGD) literature. In [Hig02, Chapter 25, Equation 25.11] a more generic condition number is defined for the root of a nonlinear algebraic system that is similar to the definition above.

For an example, consider the line $b_1(s) = [2s \ 2s]^T$ and improperly parameterized line $b_2(t) = [4t^2 \ 2 - 4t^2]^T$ which intersect at $\alpha = \beta = 1/2$. At the intersection we have $J^{-1} = \frac{1}{8} \begin{bmatrix} 2 & 2 \\ -1 & 1 \end{bmatrix}$, so that $\mathbf{v}_1 \cdot \mathbf{v}_1 = \mathbf{v}_2 \cdot \mathbf{v}_2 = 5/64$ and $\mathbf{v}_1 \cdot \mathbf{v}_2 = 3/64$. Since the x -component of $F(s, t)$ can be written as $2s - 4t^2 = 2B_{1,1}(s) - 4B_{2,2}(t)$ and the y -component as $2s + 4t^2 - 2 = 2B_{1,1}(s) - 2B_{0,2}(t) - 2B_{1,2}(t) + 2B_{2,2}(t)$ we have

$$\mu_1 = 2B_{1,1}(\alpha) + 4B_{2,2}(\beta) = 2 \quad (2.18)$$

$$\mu_2 = 2B_{1,1}(\alpha) + 2B_{0,2}(\beta) + 2B_{1,2}(\beta) + 2B_{2,2}(\beta) = 3. \quad (2.19)$$

Following (2.17), this gives $\kappa_{\alpha,\beta} = \sqrt{202}/8 \approx 1.78$.

References

[Hig02] Nicholas J. Higham. *Accuracy and Stability of Numerical Algorithms*. Society for Industrial and Applied Mathematics, Jan 2002.