| CONTACT<br>INFORMATION     | dhernandez0@gmail.com<br>Barcelona, Catalonia, Spain  | https://www.danihernandez.eu<br>Nationality: Spanish  |
|----------------------------|---|---|
| Professional<br>Experience | Senior Research Engineer Slamcore, Remote   | May 2020-Currently                                    |
|                            | • Computer Vision, Deep learning, Panoptic Segmentation, CUDA, TensorRT.  |   |
|                            | Research Engineer March 2019-February 2020 Huawei Noah's Ark lab, London, United Kingdom  • Computer Vision, Deep learning, Color Constancy (Auto White Balance).                                     |   |
|                            | PhD Internship Element AI (ServiceNow), Montreal, Canada • Computer Vision, Deep learning.  | June 2018-December 2018                               |
|                            | PhD Internship Mercedes-Benz Group AG, Stuttgart, Germany  • Developed a factor and more accurate version of the  | January 2017-July 2017 Stivel World (Computer Vision) |
|                            | • Developed a faster and more accurate version of the   | Stixer world (Computer Vision).                       |
|                            | Assistant Professor<br>Universitat Autònoma de Barcelona, Spain   | 2015-2018   |
| Education                  | <ul> <li>PhD in Computer Vision</li> <li>Universitat Autònoma de Barcelona, Spain</li> <li>Thesis title: Embedded 3D Reconstruction for Autonomic: Adapt to GPU and parallelize (CUDA) com</li> </ul> | _   |
|                            | MSc in Computer Vision<br>Universitat Autònoma de Barcelona, Spain  | 2015  |
|                            | Bachelor of Computer Science<br>Universitat Autònoma de Barcelona, Spain  | 2014  |
| Publications               | Journal Papers Self-Supervised Depth Completion for Active Ste In IEEE Robotics and Automation Letters (2022) (RA-I   |   |
|                            | 3D Perception with Slanted Stixels on GPU<br>In IEEE Transactions on Parallel and Distributed System  | <b>2021</b> as (2021) ( <b>TPDS</b> )                 |
|                            | Slanted Stixels: A way to represent steep streets<br>In International Journal of Computer Vision (2019) (IJC  | <b>2019</b> CV)                                       |
|                            | Conference Papers  A Multi-Hypothesis Approach to Color Constanc In Computer Vision and Pattern Recognition 2020 (CV)   |   |
|                            | Slanted Stixels: Representing San Francisco's Steepest Streets In British Machine Vision Conference 2017 (BMVC) Awarded as Best Industry Paper  |   |
|                            | GPU-accelerated real-time stixel computation In Winter Conference on Applications of Computer Vision  | 2017 (WACV)   |
|                            | Embedded real-time stereo estimation via Semi-C<br>In International Conference on Computational Science 2   | _   |
| SKILLS                     | Python, C/C++, CUDA, Matlab, OpenCV, numpy, PyT   | forch, Tensorflow                                     |
| Awards                     | Extraordinary PhD Prize - Universitat Autònoma<br>Best Industrial Paper Award - BMVC  | a de Barcelona 2023<br>2017                           |