Table 1: Anomaly localization results under pixel-level AUROC metric on MVTec-AD [4].

	Texture					Object										
	Carp.	Grid	Leat.	Tile	Wood	Bott.	Cable	Caps.	Haze.	Meta.	Pill	Screw	Toot.	Tran.	Zipp.	Mean
AnoGAN [31] SCADN [36]	54 64.9	58 79.6	64 76.3	50 67.7	62 67.2	86 69.6	78 81.4	84 68.7	87 88.4	76 75.4	87 74.7	80 87.6	90 90.1	80 68.9	78 67.0	74 75.2
SSIM-AE [6] VEVAE [21]	87 78	94 73	78 95	59 80	73 77	93 87	82 90	94 74	97 98	89 94	91 83	96 97	92 94	90 93	88 78	86 86
SMAI [20] VAE-Grad [12]	88 74	97 96	86 93	62 65	80 84	86 92	92 91	93 92	97 98	92 91	92 93	96 95	96 99	85 92	90 87	89 89
P-Net [40] KDAD [30]	57 95.6	98 91.8	89 98.1	97	98 84.8	99 96.3	70 82.4	84 95.9	97 94.6	79 86.4	91 89.6	100 96.0	99	82	90 93.9	89 90.7
Loc-Glo [34] FCDD [22]	96 96	78 91	90 98	80 91	81 88	93 97	94 90	90 93	84 95	91 94	93 81	96 86	96 94	100 88	99 92	91 92
PSVDD [37] SPADE [10]	92.6	96.2	97.4	91.4	90.8	98.1	96.8	95.8	97.5		95.1	95.7	98.1	97.0	95.1	95.7
ADTR(ours) ADTR+(ours)										97.0 96.8						

Qualitative results on MVTec-AD are shown in Fig. 4. Our approach successfully detects different kinds of anomalies with high localization accuracy. Especially, for the shown "Metal Nut" example, where the anomaly is a flipped normal sample, our approach detects the "flip" anomaly successfully though there are no obvious vision anomalies like texture disorder nor color change.

Quantitative results of anomaly localization are given in Tab. 1. Our approach is compared with AnoGAN [31], SCADN [36], SSIM-AE [6], VEVAE [21], SMAI [20], VAE-Grad [12], P-Net [40], KDAD [30], Loc-Glo [34], FCDD [22], PSVDD [37], SPADE [10]. With pure normal samples, ADTR stably outperforms the best baseline, SPADE [10], by 1.2%. With merely simple synthetic anomalies, the performance of ADTR+ is further improved by 0.3%.

Quantitative results of anomaly detection are shown in Tab. 2. Our approach is compared with GANomaly [2], SCADN [36], ARNet [14], SPADE [10], KDAD [30], PSVDD [37], TS [5]. ADTR considerably exceeds all baseline methods ($\geq 3.9\%$) with only normal samples. The performance of ADTR+ is improved by 0.5% with simple synthetic anomalies.

4.3 Anomaly Detection on CIFAR-10

To further validate the anomaly detection ability, we evaluate our model in the unsupervised one-class classification task of CIFAR-10 [18].

Setup. The setup is the same as that in Sec. 4.2 except the followings. First, the sizes of the image and feature map are 32×32 and 8×8 , respectively. Second, in anomaly-available case, the model is trained with the image-level loss, \mathcal{L}_{img} , in Eq. (9), where α and k are selected as 0.003 and 20, respectively.

Quantitative results on CIFAR-10 are shown in Tab. 3. The competitors include: VAE [3], KDE [7], AnoGAN [31], LSA [1], DSVDD [28], OCGAN [26], GradCon [19], Loc-Glo [34], TS [5], GT [15], KDAD [30]. ADTR surpasses KDAD [30] by a great margin (7.5%) when training in normal-sample-only case. In