#### **NSLS-II Beamline Requirements**



Daron Chabot V4 Working Group Meeting Brookhaven National Lab 10/18/12





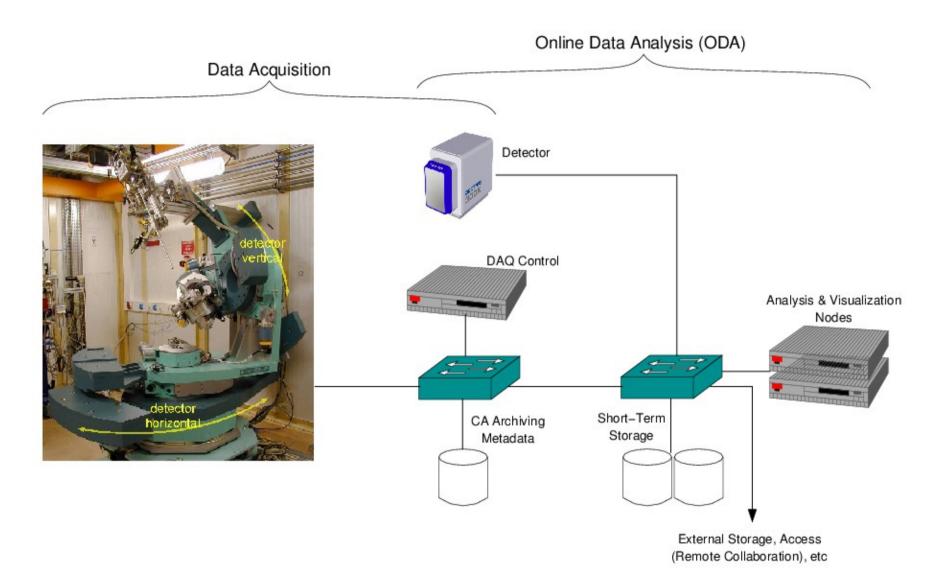
#### Outline

- The Problem(s)
- Approaches
  - Hardware
  - Software
- Time Line





## 10,000 ft View



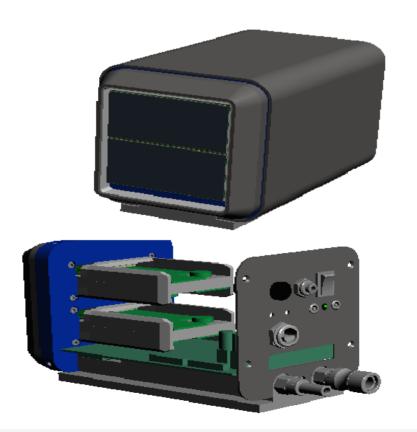


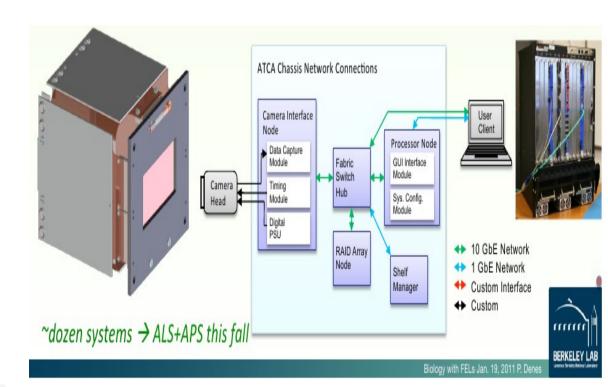


#### Zooming In: Next-Gen 2D Detectors

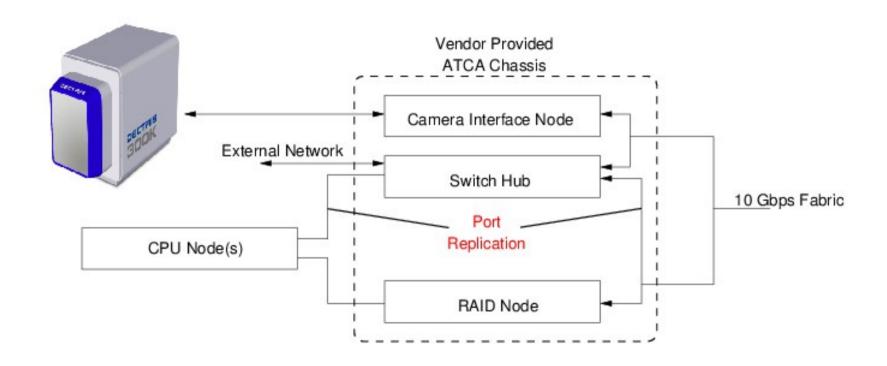
- Eiger (Dectris/PSI)
  - 1-4 Mpix @ 2-24 kHz
    - 47 Gbps @ 3 kHz (1Mpix)

- LBNL FastCCD
  - 2 Mpix @ 200 Fps
    - 6.4 Gbps





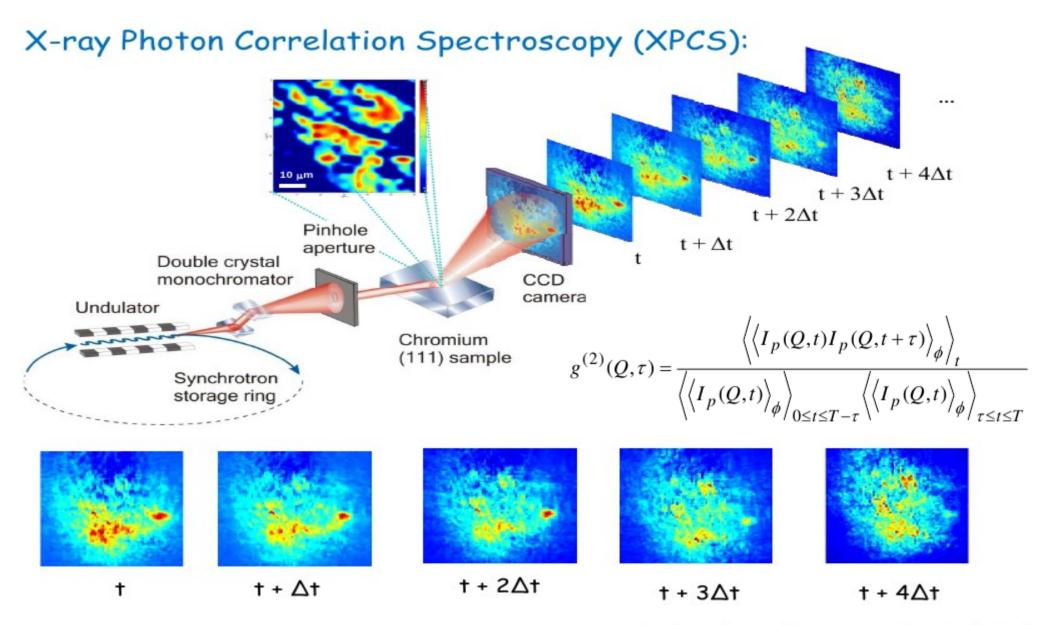
# Example: CSX







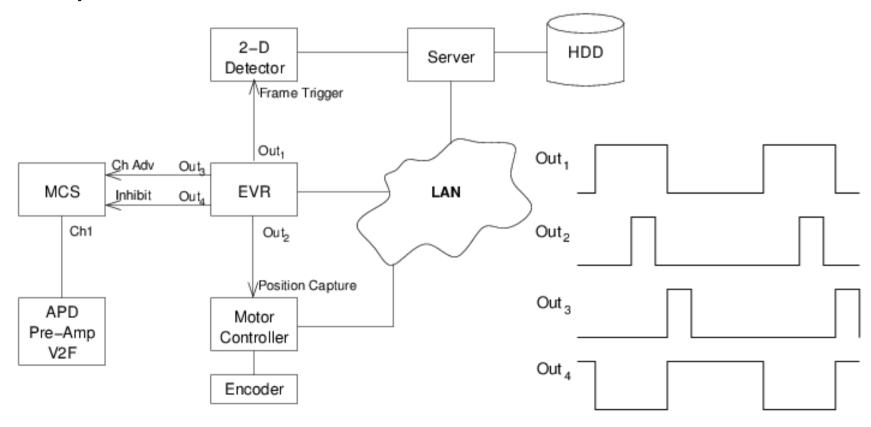
## Data Analysis Example



O. G. Shpyrko et al., Nature 447, 68 (2007)

#### 1000 ft View: Hardware Architecture

- Time-based data acquisition
  - EVR is the Master
  - Up to 1 kHz





## Software Components

Interface/Presentation "Macro" DAQ DAQ DAQ Data Implementation Config GUI CLI Presentation Library Manager Application/Services Data Acquisition Reader Looker Writer Reciprocal Space Meta-Control System Management Management PV HKL DiffCalc OPI Archiver MASAR CAC Traj. Gen. Manager Manager Manager Control System/Hardware EVR-DAQ 2D Detector HKL Motor Output Position

On

Position

Capture

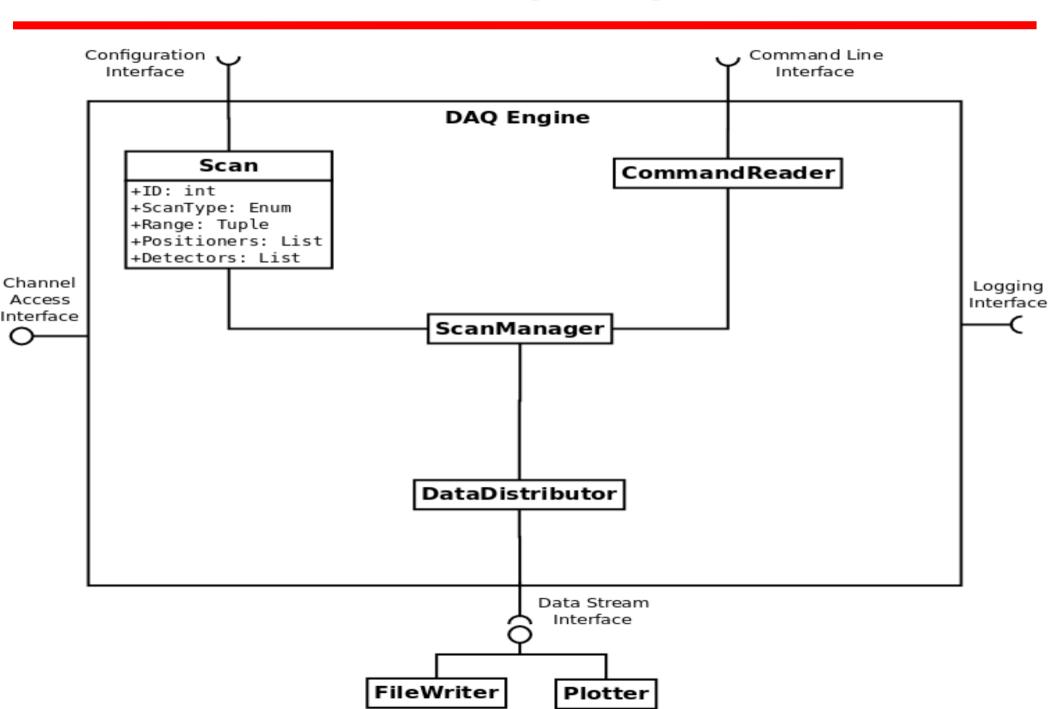
Level Shifter Integration

Support

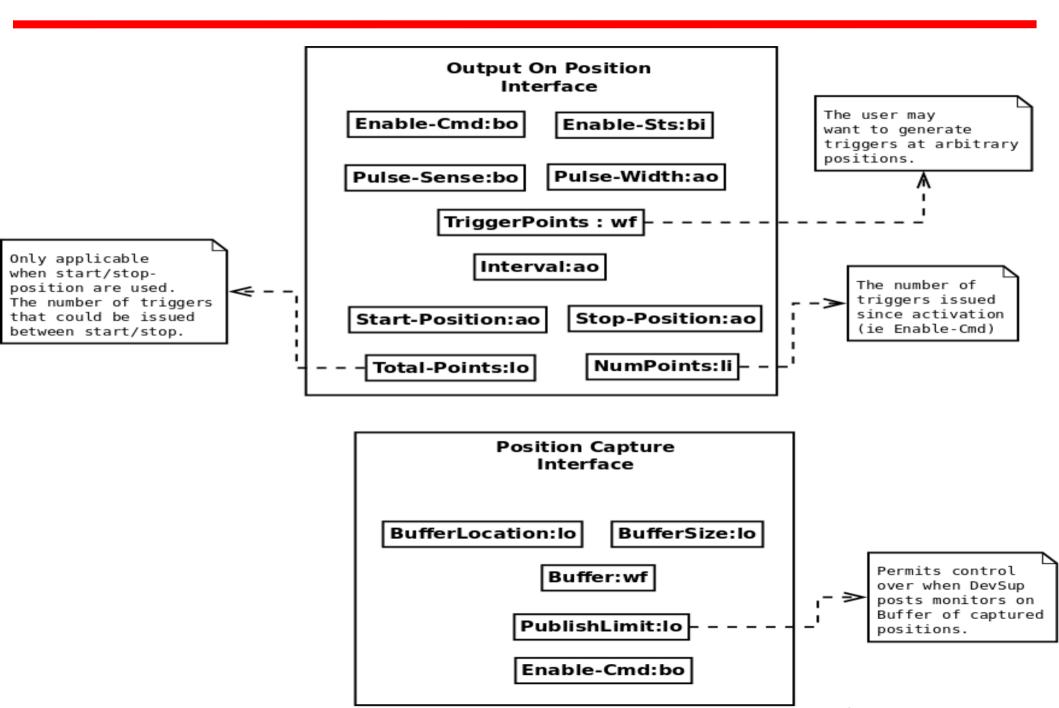
Support

Support

# Scanning Engine



# Fly Scanning: EPICS



## Scheduling

- Pkgs (optics) arriving Apr-Nov 2013
  - All Control System/Hardware pieces by 6/1/13
  - Mtr Support to include ID-Mono coordination
    - SRX and CSX-B (then SST & BMM)
- Cold commissioning Dec 2013
  - Meta-Control System Mgmt by 9/1/13
- Hot commissioning after Jan 2014
  - HKL, DAQ, and basic "macros" by 9/1/13
  - Data presentation (basic!) by 9/1/13





### Summary

- New detectors pose a challenge
  - Demand for "instant feedback" even more so
- DAQ must become more broad
  - Greater degree of hardware participation
  - Software must permit interactive exploration
    - Applies to acquisition and analysis
- Collaborative efforts seem to be a must have





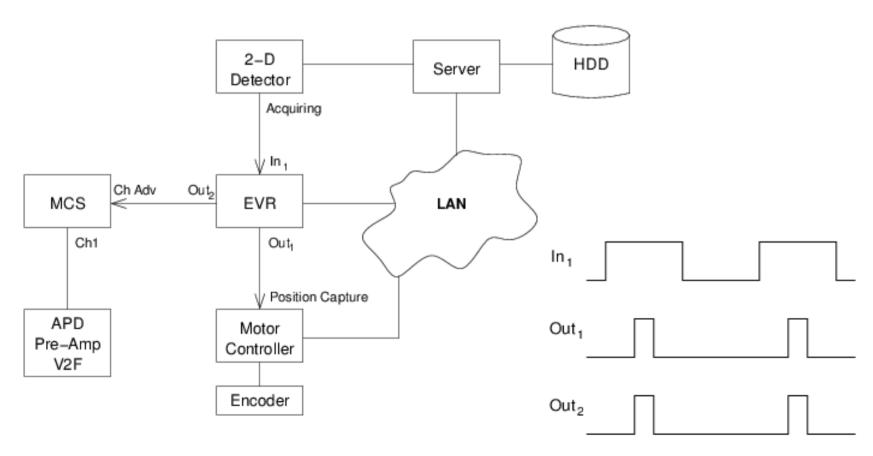
Feel free to throw stones...:-)





## Hardware Architecture (1)

- Position Capture (0.1-0.5 kHz)
  - Detector is Master

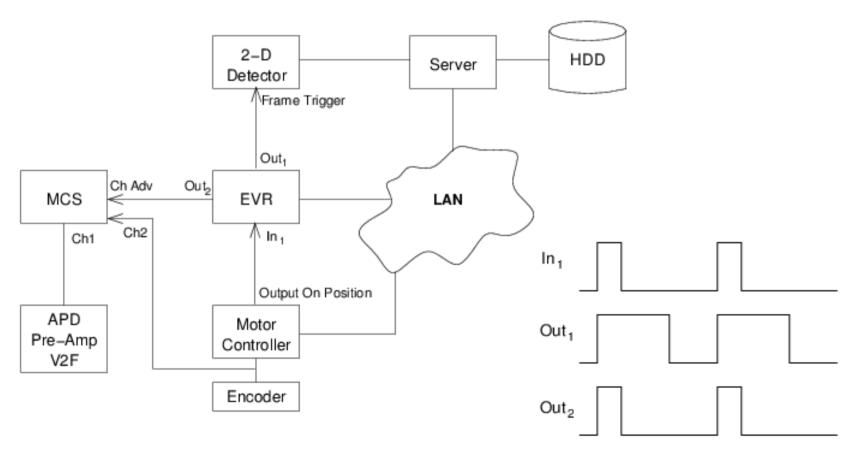






# Hardware Architecture (2)

- Output on Position (< 1kHz)</li>
  - Motor Controller is the Master





## Reciprocal Space

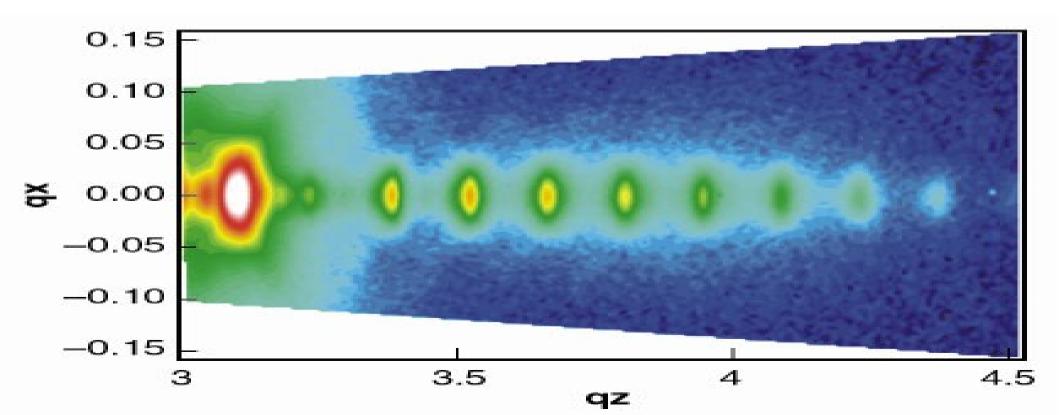
- "Q-space" or "k-space"
- Crystallography defines reciprocal axes as [ h k
  I ]
  - Orientation of [h k l] maps to several physical axes:
    - Multiple diffractometer angles + detector position
- No existing representation in V3 EPICS
  - Cannot archive, save/restore, alarm, etc





# Reciprocal Space (2)

- Many scanning operations are defined in terms of Reciprocal Space operations
  - "scan from [1 0 0] to [8 0 0] in 100 steps"
  - "scan circularly around the [0 0 2] vector"



## Hardware Filtering

 Proactive collaboration with detector vendors can produce powerful results

