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# John A. Lee Michel Verleysen

# Nonlinear Dimensionality Reduction



John Lee Molecular Imaging and Experimental Radiotherapy Université catholique de Louvain Avenue Hippocrate 54/69 B-1200 Bruxelles Belgium john.lee@uclouvain.be

Michel Verleysen Machine Learning Group – DICE Université catholique de Louvain Place du Levant 3 B-1348 Louvain-la-Neuve Belgium michel.verleysen@uclouvain.be

Series Editors:

Michael Jordan Division of Computer Science and Department of Statistics Cornell University University of California, Berkeley Berkeley, CA 94720 USA

Jon Kleinberg Department of Computer Science Ithaca, NY 14853 USA

Bernhard Schölkopf Max Planck Institute for Biological Cybernetics Spemannstrasse 38 72076 Tübingen Germany

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#### Preface

Methods of dimensionality reduction are innovative and important tools in the fields of data analysis, data mining, and machine learning. They provide a way to understand and visualize the structure of complex data sets. Traditional methods like principal component analysis and classical metric multidimensional scaling suffer from being based on linear models. Until recently, very few methods were able to reduce the data dimensionality in a nonlinear way. However, since the late 1990s, many new methods have been developed and nonlinear dimensionality reduction, also called manifold learning, has become a hot topic. New advances that account for this rapid growth are, for example, the use of graphs to represent the manifold topology, and the use of new metrics like the geodesic distance. In addition, new optimization schemes, based on kernel techniques and spectral decomposition, have led to spectral embedding, which encompasses many of the recently developed methods.

This book describes existing and advanced methods to reduce the dimensionality of numerical databases. For each method, the description starts from intuitive ideas, develops the necessary mathematical details, and ends by outlining the algorithmic implementation. Methods are compared with each other with the help of different illustrative examples.

The purpose of the book is to summarize clear facts and ideas about well-known methods as well as recent developments in the topic of nonlinear dimensionality reduction. With this goal in mind, methods are all described from a unifying point of view, in order to highlight their respective strengths and shortcomings.

The book is primarily intended for statisticians, computer scientists, and data analysts. It is also accessible to other practitioners having a basic background in statistics and/or computational learning, such as psychologists (in psychometry) and economists.

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## **Notations**

 $\hat{\mathbf{X}}$ 

Estimation of X

```
\mathbb{N}
        The set of positive natural numbers: \{0, 1, 2, 3, \ldots\}
\mathbb{R}
        The set of real numbers
        Known or unknown random variables taking their values in \mathbb{R}
y, x
\mathbf{A}
        A matrix
        An entry of the matrix \mathbf{A}
a_{i,i}
        (located at the crossing of the ith row and the jth column)
N
        Number of points in the data set
M
        Number of prototypes in the codebook C
        Dimensionality of the data space (which is usually \mathbb{R}^D)
D
        Dimensionality of the latent space (which is usually \mathbb{R}^{P})
P
        (or its estimation as the intrinsic dimension of the data)
\mathbf{I}_D
        D-dimensional identity matrix
\mathbf{I}_{P\times D} Rectangular matrix containing the first P rows of \mathbf{I}_D
        N-dimensional column vector containing ones everywhere
\mathbf{1}_N
        Random vector in the known data space: \mathbf{y} = [y_1, \dots, y_d, \dots, y_D]^T
\mathbf{y}
        Random vector in the unknown latent space: \mathbf{x} = [x_1, \dots, x_p, \dots, x_P]^T
        The ith vector of the data set
\mathbf{y}(i)
\mathbf{x}(i)
        (Unknown) latent vector that generated \mathbf{y}(i)
\hat{\mathbf{x}}(i)
        The estimate of \mathbf{x}(i)
\mathcal{Y}
        The data set \mathcal{Y} = \{\dots, \mathbf{y}(i), \dots\}_{1 \le i \le N}
\mathcal{X}
        The (unknown) set of latent vectors that generated \mathcal{Y}
\hat{\mathcal{X}}
        Estimation of \mathcal{X}
\mathbf{Y}
        The data set in matrix notation: \mathcal{Y} = [\dots, \mathbf{y}(i), \dots]_{1 \le i \le N}
\mathbf{X}
        The (unknown) ordered set of latent vectors that generated Y
```

| $\mathcal{M}$ $\mathbf{m}$ $E_x\{x\}$ $\mu_x(x)$                                 | A manifold (noted as a set)<br>The functional notation of $\mathcal{M}$ : $\mathbf{y} = \mathbf{m}(\mathbf{x})$<br>The expectation of the random variable $x$<br>The mean value of the random variable $x$ |
|--|--|
| $\mu_X(x)$   | (computed with its known values $x(i)$ , $i = 1,, N$ )   |
| $\mu_i$  | The <i>i</i> th-order centered moment  |
| $\mu_i'$   | The $i$ th-order raw moment  |
| $egin{array}{c} \hat{	ext{C}}_{	ext{xy}} \ \hat{	ext{C}}_{	ext{xy}} \end{array}$ | The covariance matrix between the random vectors ${\bf x}$ and ${\bf y}$   |
| $\hat{	extbf{C}}_{	extbf{xy}}$   | The estimate of the covariance matrix  |
| $f(\mathbf{x}), \mathbf{f}(\mathbf{x})$  | Uni- or multivariate function of the random vector $\mathbf{x}$  |
| $\frac{\partial f(\mathbf{x})}{\partial x_n}$                                    | Partial derivative of $f$ with respect to $x_p$  |
| $ abla_{\mathbf{x}} f(\mathbf{x})$   | Gradient vector of $f$ with respect to $\mathbf{x}$  |
| $\mathbf{H}_{\mathbf{x}}f(\mathbf{x})$   | Hessian matrix of $f$ with respect to $\mathbf{x}$   |
| $\mathbf{J_x}\mathbf{f}(\mathbf{x})$   | Jacobian matrix of $\mathbf{f}$ with respect to $\mathbf{x}$   |
|  | Scalar product between the two vectors $\mathbf{y}(i)$ and $\mathbf{y}(j)$   |
| $d(\mathbf{y}(i), \mathbf{y}(j))$  | Distance function between the two vectors $\mathbf{y}(i)$ and $\mathbf{y}(j)$  |
|  | (often a spatial distance, like the Euclidean one)   |
| 5/ / 1   | shortened as $d_{\mathbf{y}}(i,j)$ or $d_{\mathbf{y}}$ when the context is clear   |
|  | Geodesic or graph distance between $\mathbf{y}(i)$ and $\mathbf{y}(j)$   |
| $\mathcal{C},\mathcal{G}$  | Codebook (noted as a set) in the data and latent spaces  |
| $\mathbf{C}, \mathbf{G}$   | Codebook (noted as a matrix) in the data and latent spaces   |
| $\mathbf{c}(r),\ \mathbf{g}(r)$  | Coordinates of the rth prototypes in the codebook  |
|  | (respectively, in the data and latent spaces)  |

## Acronyms

DR Dimensionality reduction

LDR Linear dimensionality reduction

NLDR Nonlinear dimensionality reduction

ANN Artificial neural networks
EVD Eigenvalue decomposition
SVD Singular value decomposition

SVM Support vector machines

VQ Vector quantization

 $\begin{array}{lll} {\rm CCA} & {\rm Curvilinear\ component\ analysis} & & {\it NLDR\ method} \\ {\rm CDA} & {\rm Curvilinear\ distance\ analysis} & & {\it NLDR\ method} \\ \end{array}$ 

 ${\bf EM} \quad {\bf Expectation\text{-}maximization} \quad \quad \textit{optimization technique}$ 

GTM Generative topographic mapping NLDR method
HLLE Hessian LLE (see LLE) NLDR method
KPCA Kernel PCA (see PCA) NLDR method
LE Laplacian eigenmaps NLDR method
LLE Locally linear embedding NLDR method

MDS Multidimensional scaling LDR/NLDR method MLP Multilayer perceptron ANN for function approx.

MVU Maximum variance unfolding (see SDE) NLDR method NLM (Sammon's) nonlinear mapping NLDR method PCA Principal component analysis LDR method

RBFN Radial basis function network

ANN for function approx.

SDE Semidefinite embedding NLDR method

SDP Semidefinite programming optimization technique

SNE Stochastic neighbor embedding NLDR method SOM (Kohonen's) self-organizing map NLDR method

TRN Topology-representing network ANN