## Untitled12

January 23, 2024

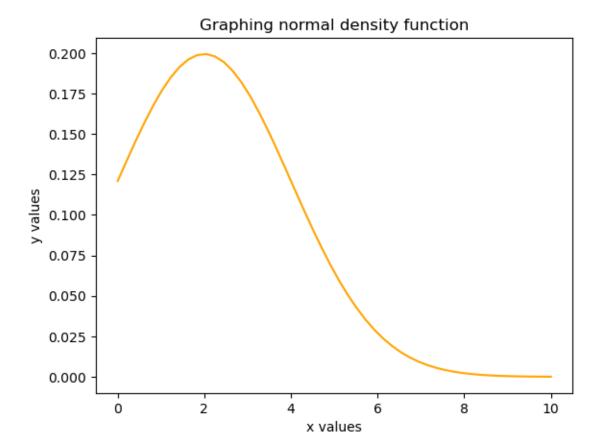
## 0.12098536225957168

```
#Graphing normal density function for mean value of 2 and variance value of 2.

"Mean and variance values can be adjusted to change the shape of the graph."

import numpy as np
import matplotlib.pyplot as plt
mean=2
variance=2

def normal_density(mean,variance,x):
    return (1/(np.sqrt(2*np.pi*(variance**2)))*np.exp((-(x-mean)**2)/
    (2*variance**2)))
x=np.linspace (0,10)
plt.plot (x, normal_density(mean,variance,x), color= "orange")
plt.ylabel ("y values")
plt.xlabel ("x values")
plt.title ("Graphing normal density function")
plt.show ()
```



The solution is: 0.4772498666120617

```
[40]: #Using code from above, and adjusting parameters to fit part 4:
      #Set bounds of the integral. The lower bound is 162 cm and the upper bound is _{\sqcup}
      →190 cm.
      a=162
      b = 190
      #Adjusting the mean and variance values based on values provided in the question
      mean=171
      variance= 7.1
      #Redefining the same function as above
      def normal_density(mean, variance, x):
          return (1/(np.sqrt(2*np.pi*(variance**2)))*np.exp((-(x-mean)**2)/
       →(2*variance**2)))
      #Setting up the integration code using trapezoid rule
      def integration_by_trapezoid (func,a,b,num_points=5000): #num_points is the_u
       \hookrightarrowamount of points scattered in the array of x values
          x_coordinates= np.linspace(a,b,num_points+1) #x coordinates scattered_
       ⇔across a and b, num_points+1 amount of coordinates
          the_integral=np.trapz(func(x_coordinates), x_coordinates) #using trapezoid_
       →rule to return the integral
          return the integral
      def normal density1 (x): #making normal density a function of x to use in_
       ⇔probability function
          return normal_density(mean, variance, x)
```

```
#Coding for probability
func_prob = integration_by_trapezoid(normal_density1, a, b)
print(f'The solution is: {func_prob}')
```

The solution is: 0.8938058711189701

[]:[