

# Batch Name : OM32

# Module Name : Data Structures

=====

# DS DAY-01:

+ Introduction to an DS:

- if we want to store marks of 100 students

int m1, m2, m3, m4, m5, ....., m100; //sizeof(int)\*100 =  
400 bytes

if we want to sort marks of 100 students =>

int marks[ 100 ]; //sizeof(int)\*100 = 400 bytes

**+ "array" => an array is a basic/linear data structure which is a collection of logically related similar type of elements gets stored into the memory at contiguous locations.**

int arr[ 5 ];

arr : int []  
arr[ 0 ] : int  
arr[ 1 ] : int  
.  
.  
.

primitive data types: char, int, float, double, void

non-primitive data types: array, structure, pointer, enum

- we want to store info of 100 students

rollno : int  
name: char []/string  
marks : float

+ "structure" => it is a basic/linear data structure, which is a collection of logically related similar and dissimilar type of data elements gets stored into the memory collectively as a single record/entity.

```
struct student
{
    int rollno;
    char name[ 32 ];
    float marks;
};
```

C => Array

C++ => Array

Java=> Array

Python => Array

=> data structures is a programming concept

=> to learn data structures is not learn any programming language, it is nothing but to learn an algorithm, data structure algorithms can be implemented in any programming language.

=> in this course we will use C programming language.

Prerequisite: C

Q. What is a Program?

Q. What is an algorithm?

Q. What is a Pseudocode?

- to traverse an array => to visit each array element sequentially from first element till last element.

+ "algorithm" => to do sum of array elements => any human user

step-1: initially take sum var as 0

step-2: traverse an array and add each array element sequentially into the sum variable  
step-3: return final sum

+ "pseudocode" => to do sum of array elements => programmer user

Algorithm ArraySum(A, n){//whereas A is an array of size "n"

```
    sum = 0;
    for( index = 1 ; index <= n ; index++ ){
        sum += A[ index ];
    }
```

```
    return sum;
```

```
}
```

- pseudocode is a special form of an algorithm in which finite set of instructions can be written in human understandable language with some programming constraints.

+ "program" => to do sum of array elements => machine

```
int array_sum(int arr[], int size){
    int sum = 0;
    int index;

    for( index = 0 ; index < size ; index++ )
        sum += arr[ index ];

    return sum;
}
```

**flowchart => it is a digramatic representation of an algorithm.**

=> an algorithm is a solution of a given problem.

=> an algorithm = solution

- "one problem may has many solutions", and in this case there is a need to decide an efficient solution.

**e.g. searching => to find/search a key element in a given collection/list of data elements.**

1. linear search
2. binary search

**e.g. sorting => to arrange data elements in a collection/list of elements either in an ascending order or in a descending order.**

1. selection sort
  2. bubble sort
  3. insertion sort
  4. quick sort
  5. merge sort
- etc...

- to decide efficiency of an algorithms, we need to do their analysis

- there are two measures of an analysis of an algorithms:

1. time complexity
2. space complexity

**linear search =>**

step-1: accept key from user

step-2:

```
for( index = 1 ; index <= size ; index++ ){  
    //if matches with any array element  
    if( key == arr[ index ] )  
        return true;  
}
```

```
//if key do not matches with any array element  
return false;
```

if key is found in an array at very first pos

if size of an array = 10 => no. of comparisons = 1

if size of an array = 20 => no. of comparisons = 1

if size of an array = 50 => no. of comparisons = 1

.

.  
if size of an array =  $n \Rightarrow$  no. of comparisons = 1  
  
for any input size array no. of comparisons in this case  
= 1  $\Rightarrow$  best case  
running time of an algo in best case =  $O(1)$ .

+ worst case:

if either key is found in an array at last pos or key do  
not found

if size of an array = 10  $\Rightarrow$  no. of comparisons = 10

if size of an array = 20  $\Rightarrow$  no. of comparisons = 20

if size of an array = 50  $\Rightarrow$  no. of comparisons = 50

.  
.

if size of an array =  $n \Rightarrow$  no. of comparisons =  $n$

no. of comparisons = depends on size of an array  
for any input size array no. of comparisons in this case  
=  $n \Rightarrow$  worst case  
running time of an algo in worst case =  $O(n)$ .

+ asymptotic rules: (discrete maths)

"rule-1" : if running time of an algo is having any  
additive/subtractive/divisive/multiplicative constant  
then it can be neglected.

e.g.

$O(n+3) \Rightarrow O(n)$

$O(n-5) \Rightarrow O(n)$

$O(2*n) \Rightarrow O(n)$

$O(n/2) \Rightarrow O(n)$

typedef unsigned long int size\_t;

## 2. binary search:

by means of calculating mid pos big size array gets divided logically into two subarray's => left subarray & right sub array  
left subarray => left to mid-1  
right subarray => mid+1 to right

for left subarray => value of left remains same, right = mid-1  
for right subarray => value of right remains same, left = mid+1

if( left == right ) => subarray contains only 1 ele and it is valid  
if( left <= right ) => subarray is valid  
in other words :  
if( left > right ) => subarray is invalid

#### # DS DAY-02:

**if size of an array = 1000**  
**iteration-1: search space = n => 1000**

[ 0 ..... 999 ]  
[ 0.... 499] [501 ..... 999]

**iteration-2: search space =  $n/2 = 500$**   
[ 0.... 499]  
[ 0...249] [ 251 .....499]

**iteration-3: search space =  $n/2 / 2 \Rightarrow n / 4 = 250$**   
[ 0...124] [ 126 ...249]

**iteration-4: search space =  $n/4 / 2 \Rightarrow n / 8 = 125$**

**after every iteration search space is getting reduced by half**

**$n \Rightarrow n/2 \Rightarrow n/4 \Rightarrow n/8 \dots$**

**$n \Rightarrow n / 2^0$**

**$n/2 \Rightarrow n / 2^1$**

**$n/4 \Rightarrow n / 2^2$**

**$n/8 \Rightarrow n / 2^3$**

**- search space is getting reduced exponentially**

- binary search is also called as logarithmic search, and hence we get time complexity of binary search in terms of  $\log$ .

# Rule  $\Rightarrow$  if any algo follows divide-and-conquer approach then we get time complexity of that algo in terms of  $\log$ .

Best Case  $\Rightarrow$  if key is found at root position in only 1 comparison  $\Rightarrow O(1) \Rightarrow \Omega(1)$ .

Worst Case  $\Rightarrow$  if either key is found at leaf position or key is not found  $\Rightarrow O(\log n) \Rightarrow O(\log n)$

Average case  $\Rightarrow$  if key is found at non-leaf position  $\Rightarrow O(\log n) \Rightarrow \Theta(\log n)$ .

+ Sorting Algorithms:

1. Selection Sort:

iteration-1: no. Of comparisons =  $n-1$

iteration-2: no. Of comparisons =  $n-2$

iteration-3: no. Of comparisons =  $n-3$

.

.

.

iteration- $(n-1)$ : no. Of comparisons = 1

total no. of comparisons =  $(n-1)+(n-2)+(n-3)+\dots+1$

arithmetic progression formula:

$\Rightarrow n(n-1) / 2$

$\Rightarrow (n^2 - n) / 2$

$\Rightarrow O( (n^2 - n) / 2 )$

$\Rightarrow O(n^2 - n)$  ...by neglecting divisive constant

$\Rightarrow O(n^2)$  .... by using rule of polynomial only leading term is considered

rule  $\Rightarrow$  if running time of an algo is having a polynomial, then in its time complexity of leading term will be considered.

e.g.

$O(n^3 + n^2 + n - 3) \Rightarrow O(n^3)$

$O(n^2 + 5) \Rightarrow O(n^2)$

## 2. Bubble Sort:

iteration-1: no. Of comparisons =  $n-1$

iteration-2: no. Of comparisons =  $n-2$

iteration-3: no. Of comparisons =  $n-3$

.

.

.

iteration-( $n-1$ ): no. Of comparisons = 1

total no. of comparisons =  $(n-1)+(n-2)+(n-3)+\dots+1$

by arithmetic progression formula:

$\Rightarrow n(n-1) / 2$

$\Rightarrow (n^2 - n) / 2$

$\Rightarrow O( (n^2 - n) / 2 )$

$\Rightarrow O(n^2 - n)$  ...by neglecting divisive constant

$\Rightarrow O(n^2)$  .... by using rule of polynomial only leading term is considered

for itr=0  $\Rightarrow$  pos=0,1,2,3,4

for itr=1  $\Rightarrow$  pos=0,1,2,3

for itr=2  $\Rightarrow$  pos=0,1,2

for itr=3  $\Rightarrow$  pos=0,1

.

.

.

for( pos=0 ; pos <  $6-1-itr$  ; pos++ )



10 20 30 40 50 60

iteration-1:

10 20 30 40 50 60

10 20 30 40 50 60

10 20 30 40 50 60

10 20 30 40 50 60

10 20 30 40 50 60

- if all pairs in an array are already inorder => there is no need of swapping => array is already sorted

- by basic algo/by design bubble is not efficient for already sorted input array, but it can be implemented efficiently by using logic of flag.

- best case occurs in bubble if array ele's are already sorted.

In this case only 1 iteration takes place and no. Of comparisons =  $n-1$

$T(n) = O(n-1)$

$T(n) = O(n) \Rightarrow \Omega(1)$ .

# DS DAY-03:

3. Insertion Sort:

Best Case - if array is already sorted

Input Array : 10 20 30 40 50 60

iteration-1:

10 20 30 40 50 60

10 20 30 40 50 60

no. of comparisons = 1

iteration-2:

10 20 30 40 50 60

10 20 30 40 50 60

no. of comparisons = 1

iteration-3:

10 20 30 40 50 60

10 20 30 40 50 60

no. of comparisons = 1

iteration-4:

10 20 30 40 50 60

10 20 30 40 50 60

no. of comparisons = 1

iteration-5:

10 20 30 40 50 60

10 20 30 40 50 60

no. of comparisons = 1

- in best case in each iteration only 1 comparison takes place and in max (n-1) no. Of iterations array elements gets arranged in a sorted manner.

Total no. of comparisons =  $1 \times (n-1) = n-1$

$T(n) = O(n-1) = O(n) = \Omega(n)$ .

#### 4. Merge Sort:

by means of calculating mid pos big size array gets divided logically into two subarray's => left subarray and right subarray

left subarray => left to mid

right subarray => mid+1 to right

for left subarray => value of left remains same, and  
right = mid

for right subarray => value of right remains same, and  
left = mid+1

#### 5. Quick Sort:

- we can apply partitioning on any partition only if size of an array/partition is greater than 1 i.e. only if left > right.

if( left == right ) => partition contains only 1

if( left < right ) => partition contains more 1 ele's

if( left > right ) => partition is invalid

worst case occurs in quick sort if array is already sorted or array elements are exists exactly in a reverse order.

Pass-1:

```
[ 10 20 30 40 50 60 ]  
[ LP ] 10 [ 20 30 40 50 60 ]
```

Pass-2:

```
[ 20 30 40 50 60 ]  
[ LP ] 20 [ 30 40 50 60 ]
```

Pass-3:

```
[ 30 40 50 60 ]  
[ LP ] 30 [ 40 50 60 ]
```

Pass-4:

```
[ 40 50 60 ]  
[ LP ] 40 [ 50 60 ]
```

Pass-5:

```
[ 50 60 ]  
[ LP ] 50 [ 60 ]
```

# DS DAY-04:

```
int arr[ 100 ];
```

addition operation on an array is not efficient as takes  $O(n)$  time

Why Linked List ?

Linked List must be dynamic and addition & deletion operations should perform on it efficiently i.e. expected time is  $\Rightarrow O(1)$ .

What is a Linked List ?

Singly Linear Linked List:

```
if( head == NULL )  $\Rightarrow$  list is empty
```

Q. What is NULL ?

- NULL is a predefined macro whose value is 0 which is typecasted into a void \*

```
#define NULL ((void *)0)
```

```
data : int  
next : *type
```

```
struct node  
{  
    int data;//4 bytes  
    struct node *next;//4 bytes  
};
```

```
sizeof(struct node) = 8 bytes  
sizeof(struct node *) = 4 bytes
```

```
to store an addr of int type var => int *
```

```
to store an addr of char type of var => char *
```

```
to store an addr of float type var => float *
```

```
.  
.
```

```
to store an addr of struct node type var => struct node *
```

```
to store an addr of type var => type *
```

```
sizeof(char) = 1 byte  
sizeof(int) = 4 bytes  
sizeof(float) = 4 bytes  
sizeof(double) = 8 bytes
```

```
sizeof(char *) = 4 bytes  
sizeof(int *) = 4 bytes  
sizeof(float *) = 4 bytes  
sizeof(double *) = 4 bytes  
sizeof(sturct node *) = 4 bytes
```

```
sizeof(type *) = 4 bytes (on 32-bit compiler)
```

**- We can perform basic 2 operations on Linked List:**

**1. addition : to add node into the linked list**

**- we can add node into the linked list by 3 ways**

- i. add node into the linked list at last position
- ii. add node into the linked list at first position
- iii. add node into the linked list at specific (in between) position.

**2. deletion : to delete node from linked list**

**- we can delete node from the linked list by 3 ways**

- i. delete node from the linked list which is at first position
- ii. delete node from the linked list which is at last position
- iii. delete node from the linked list which is at specific (in between) position

**i. add node into the linked list at last position:**

- we can add as many as we want number of nodes into the slll at last position in  **$O(n)$**  time.

Best Case :  $\Omega(1)$   
Worst Case :  $O(n)$   
Average Case :  $\Theta(n)$

**ii. add node into the linked list at first position:**

- we can add as many as we want number of nodes into the slll at first position in  **$O(1)$**  time.

Best Case :  $\Omega(1)$   
Worst Case :  $O(1)$   
Average Case :  $\Theta(1)$

**iii. add node into the linked list at specific (in between) position:**

- we can add as many as we want number of nodes into the slll at specific position in  **$O(n)$**  time.

Best Case :  $\Omega(1)$  - if pos = 1

Worst Case :  $O(n)$  - if  $pos = count\_nodes() + 1$   
Average Case :  $\Theta(n)$  - if  $pos$  is in between  $pos$

Procedure => Function

C Programming Language => **Procedure Oriented Programming Language** => Logic of a program gets divided into functions

C++ Programming Language => Object Oriented Programming Language => Logic of a program gets divided into an objects.

=> to traverse a linked list => to visit each node in a linked list sequentially from first node max till last node.

- we can start traversal of a linked list from first node
- we get an addr of first node always from head

Rule in a Linked List Programming => **make before break**  
i.e. always creates new links first (links associated with newly created node) and then only break old links.