

Batch Name : OM32

Module Name : Data Structures

=====

DS DAY-01:

+ Introduction to an DS:

- if we want to store marks of 100 students

int m1, m2, m3, m4, m5,, m100; //sizeof(int)*100 =
400 bytes

if we want to sort marks of 100 students =>

int marks[100]; //sizeof(int)*100 = 400 bytes

+ "array" => an array is a basic/linear data structure which is a collection of logically related similar type of elements gets stored into the memory at contiguous locations.

int arr[5];

arr : int []
arr[0] : int
arr[1] : int
.
.
.

primitive data types: char, int, float, double, void

non-primitive data types: array, structure, pointer, enum

- we want to store info of 100 students

rollno : int
name: char []/string
marks : float

+ "structure" => it is a basic/linear data structure, which is a collection of logically related similar and dissimilar type of data elements gets stored into the memory collectively as a single record/entity.

```
struct student
{
    int rollno;
    char name[ 32 ];
    float marks;
};
```

C => Array

C++ => Array

Java=> Array

Python => Array

=> data structures is a programming concept

=> to learn data structures is not learn any programming language, it is nothing but to learn an algorithm, data structure algorithms can be implemented in any programming language.

=> in this course we will use C programming language.

Prerequisite: C

Q. What is a Program?

Q. What is an algorithm?

Q. What is a Pseudocode?

- to traverse an array => to visit each array element sequentially from first element till last element.

+ "algorithm" => to do sum of array elements => any human user

step-1: initially take sum var as 0

step-2: traverse an array and add each array element sequentially into the sum variable
step-3: return final sum

+ "pseudocode" => to do sum of array elements => programmer user

Algorithm ArraySum(A, n){//whereas A is an array of size "n"

```
    sum = 0;
    for( index = 1 ; index <= n ; index++ ){
        sum += A[ index ];
    }
```

```
    return sum;
}
```

- pseudocode is a special form of an algorithm in which finite set of instructions can be written in human understandable language with some programming constraints.

+ "program" => to do sum of array elements => machine

```
int array_sum(int arr[], int size){
    int sum = 0;
    int index;

    for( index = 0 ; index < size ; index++ )
        sum += arr[ index ];

    return sum;
}
```

flowchart => it is a digramatic representation of an algorithm.

=> an algorithm is a solution of a given problem.

=> an algorithm = solution

- "one problem may has many solutions", and in this case there is a need to decide an efficient solution.

e.g. searching => to find/search a key element in a given collection/list of data elements.

1. linear search
2. binary search

e.g. sorting => to arrange data elements in a collection/list of elements either in an ascending order or in a descending order.

1. selection sort
 2. bubble sort
 3. insertion sort
 4. quick sort
 5. merge sort
- etc...

- to decide efficiency of an algorithms, we need to do their analysis
- there are two measures of an analysis of an algorithms:
 1. time complexity
 2. space complexity

linear search =>

step-1: accept key from user

step-2:

```
for( index = 1 ; index <= size ; index++ ){  
    //if matches with any array element  
    if( key == arr[ index ] )  
        return true;  
}
```

```
//if key do not matches with any array element  
return false;
```

if key is found in an array at very first pos

if size of an array = 10 => no. of comparisons = 1

if size of an array = 20 => no. of comparisons = 1

if size of an array = 50 => no. of comparisons = 1

.

.
if size of an array = $n \Rightarrow$ no. of comparisons = 1

for any input size array no. of comparisons in this case
= 1 \Rightarrow best case
running time of an algo in best case = $O(1)$.

+ worst case:

if either key is found in an array at last pos or key do
not found

if size of an array = 10 \Rightarrow no. of comparisons = 10

if size of an array = 20 \Rightarrow no. of comparisons = 20

if size of an array = 50 \Rightarrow no. of comparisons = 50

.
.

if size of an array = $n \Rightarrow$ no. of comparisons = n

no. of comparisons = depends on size of an array
for any input size array no. of comparisons in this case
= $n \Rightarrow$ worst case
running time of an algo in worst case = $O(n)$.

+ asymptotic rules: (discrete maths)

"rule-1" : if running time of an algo is having any
additive/subtractive/divisive/multiplicative constant
then it can be neglected.

e.g.

$O(n+3) \Rightarrow O(n)$

$O(n-5) \Rightarrow O(n)$

$O(2*n) \Rightarrow O(n)$

$O(n/2) \Rightarrow O(n)$

typedef unsigned long int size_t;

2. binary search:

by means of calculating mid pos big size array gets divided logically into two subarray's => left subarray & right sub array
left subarray => left to mid-1
right subarray => mid+1 to right

for left subarray => value of left remains same, right = mid-1
for right subarray => value of right remains same, left = mid+1

if(left == right) => subarray contains only 1 ele and it is valid
if(left <= right) => subarray is valid
in other words :
if(left > right) => subarray is invalid

DS DAY-02:

if size of an array = 1000
iteration-1: search space = n => 1000

[0 999]
[0.... 499] [501 999]

iteration-2: search space = $n/2 = 500$
[0.... 499]
[0...249] [251499]

iteration-3: search space = $n/2 / 2 \Rightarrow n / 4 = 250$
[0...124] [126 ...249]

iteration-4: search space = $n/4 / 2 \Rightarrow n / 8 = 125$

after every iteration search space is getting reduced by half

$n \Rightarrow n/2 \Rightarrow n/4 \Rightarrow n/8 \dots$

$n \Rightarrow n / 2^0$

$n/2 \Rightarrow n / 2^1$

$n/4 \Rightarrow n / 2^2$

$n/8 \Rightarrow n / 2^3$

- search space is getting reduced exponentially

- binary search is also called as logarithmic search, and hence we get time complexity of binary search in terms of \log .

Rule \Rightarrow if any algo follows divide-and-conquer approach then we get time complexity of that algo in terms of \log .

Best Case \Rightarrow if key is found at root position in only 1 comparison $\Rightarrow O(1) \Rightarrow \Omega(1)$.

Worst Case \Rightarrow if either key is found at leaf position or key is not found $\Rightarrow O(\log n) \Rightarrow O(\log n)$

Average case \Rightarrow if key is found at non-leaf position $\Rightarrow O(\log n) \Rightarrow \Theta(\log n)$.

+ Sorting Algorithms:

1. Selection Sort:

iteration-1: no. Of comparisons = $n-1$

iteration-2: no. Of comparisons = $n-2$

iteration-3: no. Of comparisons = $n-3$

.

.

.

iteration- $(n-1)$: no. Of comparisons = 1

total no. of comparisons = $(n-1)+(n-2)+(n-3)+\dots+1$

arithmetic progression formula:

$\Rightarrow n(n-1) / 2$

$\Rightarrow (n^2 - n) / 2$

$\Rightarrow O((n^2 - n) / 2)$

$\Rightarrow O(n^2 - n)$...by neglecting divisive constant

$\Rightarrow O(n^2)$ by using rule of polynomial only leading term is considered

rule \Rightarrow if running time of an algo is having a polynomial, then in its time complexity of leading term will be considered.

e.g.

$O(n^3 + n^2 + n - 3) \Rightarrow O(n^3)$

$O(n^2 + 5) \Rightarrow O(n^2)$

2. Bubble Sort:

iteration-1: no. Of comparisons = $n-1$

iteration-2: no. Of comparisons = $n-2$

iteration-3: no. Of comparisons = $n-3$

.

.

.

iteration-($n-1$): no. Of comparisons = 1

total no. of comparisons = $(n-1)+(n-2)+(n-3)+\dots+1$

by arithmetic progression formula:

$\Rightarrow n(n-1) / 2$

$\Rightarrow (n^2 - n) / 2$

$\Rightarrow O((n^2 - n) / 2)$

$\Rightarrow O(n^2 - n)$...by neglecting divisive constant

$\Rightarrow O(n^2)$ by using rule of polynomial only leading term is considered

for itr=0 \Rightarrow pos=0,1,2,3,4

for itr=1 \Rightarrow pos=0,1,2,3

for itr=2 \Rightarrow pos=0,1,2

for itr=3 \Rightarrow pos=0,1

.

.

.

for(pos=0 ; pos < $6-1-itr$; pos++)

10 20 30 40 50 60

iteration-1:

10 20 30 40 50 60

10 20 30 40 50 60

10 20 30 40 50 60

10 20 30 40 50 60

10 20 30 40 50 60

- if all pairs in an array are already inorder => there is no need of swapping => array is already sorted

- by basic algo/by design bubble is not efficient for already sorted input array, but it can be implemented efficiently by using logic of flag.

- best case occurs in bubble if array ele's are already sorted.

In this case only 1 iteration takes place and no. Of comparisons = $n-1$

$T(n) = O(n-1)$

$T(n) = O(n) \Rightarrow \Omega(1)$.

DS DAY-03:

3. Insertion Sort:

Best Case - if array is already sorted

Input Array : 10 20 30 40 50 60

iteration-1:

10 20 30 40 50 60

10 20 30 40 50 60

no. of comparisons = 1

iteration-2:

10 20 30 40 50 60

10 20 30 40 50 60

no. of comparisons = 1

iteration-3:

10 20 30 40 50 60

10 20 30 40 50 60

no. of comparisons = 1

iteration-4:

10 20 30 40 50 60

10 20 30 40 50 60

no. of comparisons = 1

iteration-5:

10 20 30 40 50 60

10 20 30 40 50 60

no. of comparisons = 1

- in best case in each iteration only 1 comparison takes place and in max (n-1) no. Of iterations array elements gets arranged in a sorted manner.

Total no. of comparisons = $1 \times (n-1) = n-1$

$T(n) = O(n-1) = O(n) = \Omega(n)$.

4. Merge Sort:

by means of calculating mid pos big size array gets divided logically into two subarray's => left subarray and right subarray

left subarray => left to mid

right subarray => mid+1 to right

for left subarray => value of left remains same, and
right = mid

for right subarray => value of right remains same, and
left = mid+1

5. Quick Sort:

- we can apply partitioning on any partition only if size of an array/partition is greater than 1 i.e. only if left > right.

if(left == right) => partition contains only 1

if(left < right) => partition contains more 1 ele's

if(left > right) => partition is invalid

worst case occurs in quick sort if array is already sorted or array elements are exists exactly in a reverse order.

Pass-1:

```
[ 10 20 30 40 50 60 ]  
[ LP ] 10 [ 20 30 40 50 60 ]
```

Pass-2:

```
[ 20 30 40 50 60 ]  
[ LP ] 20 [ 30 40 50 60 ]
```

Pass-3:

```
[ 30 40 50 60 ]  
[ LP ] 30 [ 40 50 60 ]
```

Pass-4:

```
[ 40 50 60 ]  
[ LP ] 40 [ 50 60 ]
```

Pass-5:

```
[ 50 60 ]  
[ LP ] 50 [ 60 ]
```

DS DAY-04:

```
int arr[ 100 ];
```

addition operation on an array is not efficient as takes $O(n)$ time

Why Linked List ?

Linked List must be dynamic and addition & deletion operations should perform on it efficiently i.e. expected time is $\Rightarrow O(1)$.

What is a Linked List ?

Singly Linear Linked List:

```
if( head == NULL )  $\Rightarrow$  list is empty
```

Q. What is NULL ?

- NULL is a predefined macro whose value is 0 which is typecasted into a void *

```
#define NULL ((void *)0)
```

```
data : int  
next : *type
```

```
struct node  
{  
    int data;//4 bytes  
    struct node *next;//4 bytes  
};
```

```
sizeof(struct node) = 8 bytes  
sizeof(struct node *) = 4 bytes
```

```
to store an addr of int type var => int *
```

```
to store an addr of char type of var => char *
```

```
to store an addr of float type var => float *
```

```
.  
.
```

```
to store an addr of struct node type var => struct node *
```

```
to store an addr of type var => type *
```

```
sizeof(char) = 1 byte  
sizeof(int) = 4 bytes  
sizeof(float) = 4 bytes  
sizeof(double) = 8 bytes
```

```
sizeof(char *) = 4 bytes  
sizeof(int *) = 4 bytes  
sizeof(float *) = 4 bytes  
sizeof(double *) = 4 bytes  
sizeof(sturct node *) = 4 bytes
```

```
sizeof(type *) = 4 bytes (on 32-bit compiler)
```

- We can perform basic 2 operations on Linked List:

1. addition : to add node into the linked list

- we can add node into the linked list by 3 ways

- i. add node into the linked list at last position
- ii. add node into the linked list at first position
- iii. add node into the linked list at specific (in between) position.

2. deletion : to delete node from linked list

- we can delete node from the linked list by 3 ways

- i. delete node from the linked list which is at first position
- ii. delete node from the linked list which is at last position
- iii. delete node from the linked list which is at specific (in between) position

i. add node into the linked list at last position:

- we can add as many as we want number of nodes into the slll at last position in **$O(n)$** time.

Best Case : $\Omega(1)$
Worst Case : $O(n)$
Average Case : $\Theta(n)$

ii. add node into the linked list at first position:

- we can add as many as we want number of nodes into the slll at first position in **$O(1)$** time.

Best Case : $\Omega(1)$
Worst Case : $O(1)$
Average Case : $\Theta(1)$

iii. add node into the linked list at specific (in between) position:

- we can add as many as we want number of nodes into the slll at specific position in **$O(n)$** time.

Best Case : $\Omega(1)$ - if pos = 1

Worst Case : $O(n)$ - if $pos = count_nodes() + 1$
Average Case : $\Theta(n)$ - if pos is in between pos

Procedure => Function

C Programming Language => **Procedure Oriented Programming Language** => Logic of a program gets divided into functions

C++ Programming Language => Object Oriented Programming Language => Logic of a program gets divided into an objects.

=> to traverse a linked list => to visit each node in a linked list sequentially from first node max till last node.

- we can start traversal of a linked list from first node
- we get an addr of first node always from head

Rule in a Linked List Programming => **make before break**
i.e. always creates new links first (links associated with newly created node) and then only break old links.

DS DAY-05:

2. deletion : to delete node from linked list

- we can delete node from the linked list by 3 ways

i. delete node from the linked list which is at first position: $O(1)$

Best Case : $\Omega(1)$

Worst Case : $O(1)$

Average Case : $\Theta(1)$

ii. delete node from the linked list which is at last position : $O(n)$

Best Case : $\Omega(1)$ - if list contains only 1 node

Worst Case : $O(n)$

Average Case : $\Theta(n)$

iii. delete node from the linked list which is at specific position : $O(n)$

Best Case : $\Omega(1)$ - if pos = 1
Worst Case : $O(n)$
Average Case : $\Theta(n)$

SCLL:

if(head == NULL) => list is empty
if(head != NULL) => list is not empty

if(head == head->next) => list contains only one node
otherwise list contains more than one nodes.

- all operations/algos we applied on SLLL, we can apply on SCLL as well exactly as it is except in SCLL we need to maintained/take care about next part of last node always.

DLLL:

```
struct node
{
    struct node *prev;
    type data; //any primitive / non-primitive type
    struct node *next;
};
```

sizeof(struct node) = 12 bytes on 32-bit compiler

if(head == NULL) => list is empty
if(head != NULL) => list is not empty

if(head->next == NULL) => list contains only one node
otherwise list contains more than one nodes.

- all operations/algos we applied on SLLL, we can apply on DLLL as well exactly as it is except in DLLL we need maintain forward link as well as backward link of each node i.e. next part as well as prev part of each node.

DCLL:

```
if( head == NULL ) => list is empty
if( head != NULL ) => list is not empty
```

```
if( head == head->next ) => list contains only one node
otherwise list contains more than one nodes.
```

- all operations/algo's we applied on SLLL, we can apply on DCLL as well exactly as it is except in DCLL we need maintain forward link as well as backward link of each node i.e. next part as well as prev part of each node and we need maintains prev part of first node and next part of last node.

Optional Home Work => Implement SCLL, DLLL & DCLL addition & deletion operations.