

Clustering Algorithms

Part-1

Motivation

Problem: 3D Model Retrieval Given a 3D Model find the most similar models



Shape-net dataset



Generate shape representations of these 3d models

Perform clustering on the shape representations

Ranking of the 3D models within a particular cluster

Given a 3D model, retrieve top-n ranks of 3D model

Agenda

01

Overview of Clustering

Types of clustering

04

Affinity Propagation

Introduction

Pros and Cons

02

K-Family Algorithms

K-Means

K-Medoids and more

05

Spectral Clustering

Introduction

Pros and Cons

03

Mean Shift Algorithm

Short Introduction

Pros and Cons

What is clustering?

Definition [edit]

The notion of a "cluster" cannot be precisely defined, which is one of the reasons why there are so many clustering algorithms. [5] There is a common denominator: a group of data objects. However, different researchers employ different cluster models, and for each of these cluster models again different algorithms can be given. The notion of a cluster, as found by different algorithms, varies significantly in its properties. Understanding these "cluster models" is key to understanding the differences between the various algorithms. Typical cluster models include:

- . Connectivity models: for example, hierarchical clustering builds models based on distance connectivity.
- Centroid models: for example, the k-means algorithm represents each cluster by a single mean vector.
- Distribution models: clusters are modeled using statistical distributions, such as multivariate normal distributions used by the expectation-maximization algorithm.
- Density models: for example, DBSCAN and OPTICS defines clusters as connected dense regions in the data space.
- Subspace models: in biclustering (also known as co-clustering or two-mode-clustering), clusters are modeled with both cluster members and relevant attributes.
- Group models: some algorithms do not provide a refined model for their results and just provide the grouping information.
- Graph-based models: a clique, that is, a subset of nodes in a graph such that every two nodes in the subset are connected by an edge can be considered as a prototypical form of cluster. Relaxations of the complete connectivity requirement (a fraction of the edges can be missing) are known as quasi-cliques, as in the HCS clustering algorithm.
- Signed graph models: Every path in a signed graph has a sign from the product of the signs on the edges. Under the assumptions of balance theory, edges may change sign and result in a bifurcated graph.

 The weaker "clusterability axiom" (no cycle has exactly one negative edge) yields results with more than two clusters, or subgraphs with only positive edges.^[6]
- Neural models: the most well known unsupervised neural network is the self-organizing map and these models can usually be characterized as similar to one or more of the above models, and including subspace models when neural networks implement a form of Principal Component Analysis or Independent Component Analysis.

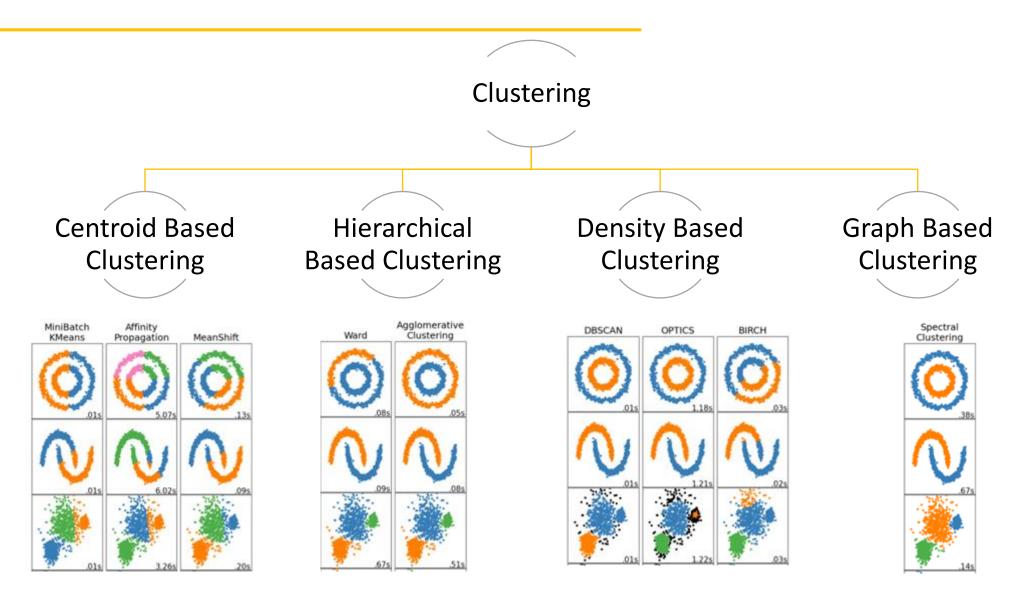
A "clustering" is essentially a set of such clusters, usually containing all objects in the data set. Additionally, it may specify the relationship of the clusters to each other, for example, a hierarchy of clusters embedded in each other. Clusterings can be roughly distinguished as:

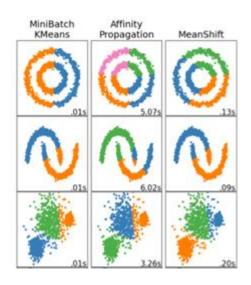
- Hard clustering: each object belongs to a cluster or not
- Soft clustering (also: fuzzy clustering): each object belongs to each cluster to a certain degree (for example, a likelihood of belonging to the cluster)

There are also finer distinctions possible, for example:

- Strict partitioning clustering: each object belongs to exactly one cluster
- Strict partitioning clustering with outliers: objects can also belong to no cluster, and are considered outliers
- Overlapping clustering (also: alternative clustering, multi-view clustering): objects may belong to more than one cluster; usually involving hard clusters
- Hierarchical clustering: objects that belong to a child cluster also belong to the parent cluster
- Subspace clustering: while an overlapping clustering, within a uniquely defined subspace, clusters are not expected to overlap

Types of Clustering

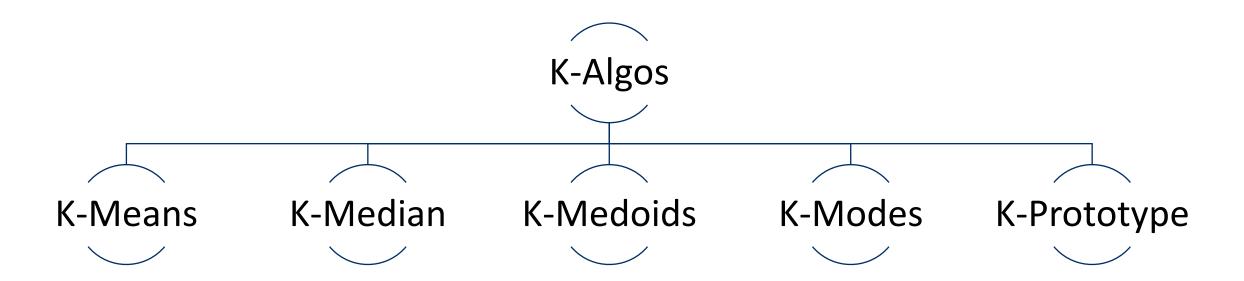




Centroid Based Clustering

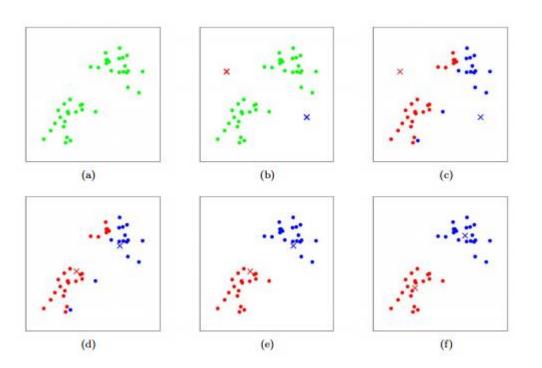
01

Family of K-Algos



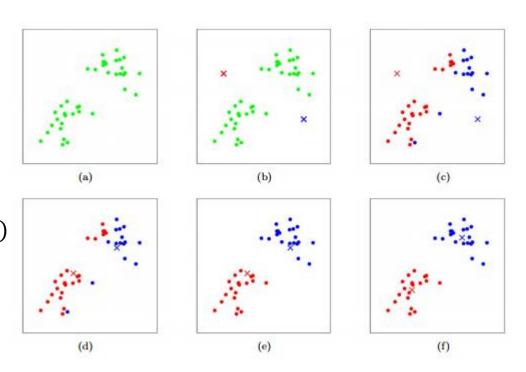
K-Means (Lloyd's) Algorithm

- 1. Specify the number of clusters to assign (k)
- 2. Randomly initialize k centroids
- 3. Loop:
 - 1. Assign each point to the closest centroid
 - 2. Compute new centroid (mean) of each cluster
- 4. Until the centroid position do not change



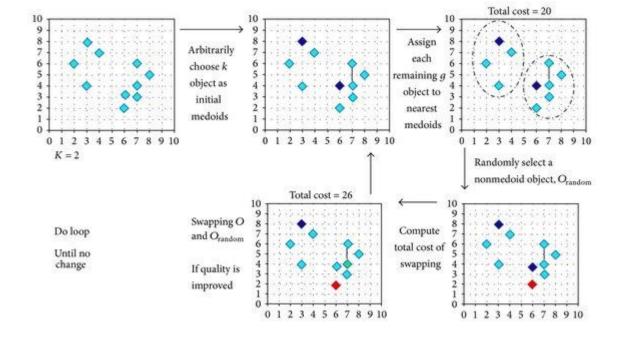
K-Median

- 1. Instead of using mean for each cluster to determine the centroid, one uses median.
- 2. Has the effect of using 1-norm distance metric instead of using squared 2-norm distance metric (used by k-means)
- 3. This method is more robust to outliers since median is more robust than mean



K-Medoids Algorithm

- Select k points as the initial representative medoids
- 2. Loop:
 - 1. Assign each point to the closest medoid
 - 2. Randomly select a non-representative object (medoid)
 - 3. Compute the cost of the cluster after swapping the object
 - 4. If cost decreases, then swap them to form the new set of medoids
- 3. Until the convergence criteria



- Partitioning Around Medoids (PAM)
- CLARANS

K-Medoids Properties

- Centroids in k-means, which represents the cluster are virtual points, whereas, in case of medoids
 they represents points from the actual dataset which represents the clusters. Hence providing greater
 interpretability of clusters
- K-Means is sensitive to outliers, since one outlier may pull the centroid in its direction. K-Medoids however, are robust to them
- K-medoids can be used with arbitrary dissimilarity measures, whereas K-Means requires Euclidian distances for efficient solutions
- K-Medoids has been show to perform better than K-Means for Big Data (PDF) Analysis of K-Means and K-Medoids Algorithm For Big Data (researchgate.net)

K-Modes

person	hair color	eye color	skin color
P1	blonde	amber	fair
P2	brunette	gray	brown
Р3	red	green	brown
P4	black	hazel	brown
P5	brunette	amber	fair
P6	black	gray	brown
P7	red	green	fair
P8	black	hazel	fair

Leaders									
P1	blonde	amber	fair						
P7	red	green	fair						
P8	black	hazel	fair						
person	hair color	eye color	skin color						
P1	blonde	amber	fair						
P2	brunette	gray	brown						
Р3	red	green	brown						
P4	black	hazel	brown						
P5	brunette	amber	fair						
P6	black	gray	brown						
P7	red	green	fair						
P8	black	hazel	fair						

Leaders									
P1	P1 blonde		fair						
P7	red	green	fair						
P8	black	hazel	fair						
	<u> </u>								
person	hair color	V eye color	skin color						
P1	blonde	amber	fair						
P2	brunette	gray	brown						
P3	red	green	brown						
P4	black	hazel	brown						
P5	brunette	amber	fair						
P6	black	gray	brown						
P7	red	green	fair						
P8	black	hazel	fair						

	Leaders								
	P1	blonde	amber	fair					
	P7	red	green	fair					
	P8	black	hazel	fair					
	7 7								
р	erson	hair color	eye color	skin color					
	P1	blonde	V amber	fair					
	P2	brunette	gray	brown					
	Р3	red	green	brown					
	P4	black	hazel	brown					
	P5	brunette	amber	fair					
	P6	black	gray	brown					
	P7	red	green	fair					
	P8	black	hazel	fair					

- 1. K-Modes clustering is used when you have categorical data
- 2. The notion of distance metric is the "mode" of the numbers

	Cluster 1 (P1)	Cluster 2 (P7)	Cluster 3 (P8)	Cluster
P1	0 🇸	2	2	Cluster 1
P2	3 🎸	3	3	Cluster 1
Р3	3	1	3	Cluster 2
P4	3	3	1	Cluster 3
P5	1 🗸	2	2	Cluster 1
P6	3	3	2 🗸	Cluster 3
P7	2	0 🗸	2	Cluster 2
P8	2	2	0 🗸	Cluster 3

K-Modes Continued

Algorithm is implemented in **kmodes** package

person	hair color	eye color	skin color	
P1	blonde	amber	fair	
P2	brunette	gray	brown	
Р3	red	green	brown	
P4	black	hazel	brown	
P5	brunette	amber	fair	
Р6	black	gray	brown	
P7	red	green	fair	
P8	black	hazel	fair	

New Leaders								
	hair color	eye color	skin color					
Cluster 1	brunette	amber	fair					
Cluster 2	red	green	fair					
Cluster 3	black	hazel	brown					
\ \ \								
person	hair color	∨ eye color	skin color					
P1	blonde	amber	fair					
P2	brunette	gray	brown					
Р3	red	green	brown					
P4	black	hazel	brown					
P5	brunette	amber	fair					
P6	black	gray	brown					
P7	red	green	fair					
P8	black	k hazel						

New Leaders								
	hair color	eye color	skin color					
Cluster 1	brunette	amber	fair					
Cluster 2	red	green	fair					
Cluster 3	black	hazel	brown					

	Cluster 1	Cluster 2	Cluster 3	Cluster
P1	1 🎸	2	3	Cluster 1
P2	2 🍑	3	2	Cluster 1
Р3	3	1 🗸	2	Cluster 2
P4	3	3	0 🍑	Cluster 3
P5	0 🇸	2	3	Cluster 1
P6	3	3	1 🎸	Cluster 3
P7	2	0 🎸	3	Cluster 2
P8	2	2	1 🗸	Cluster 3

K-Prototype (Heterogeneous Data)

Algorithm is implemented in kmodes package

	Region	Country	Item Type	Sales Channel	Order Priority	Order Date	Order ID	Ship Date	Units Sold	Unit Price	Unit Cost	Total Revenue	Total Cost	Total Profit
0	Sub-Saharan Africa	Chad	Office Supplies	Online	L	1/27/2011	292494523	2/12/2011	4484	651.21	524.96	2920025.64	2353920.64	566105.00
1	Europe	Latvia	Beverages	Online	С	12/28/2015	361825549	1/23/2016	1075	47.45	31.79	51008.75	34174.25	16834.50
2	Middle East and North Africa	Pakistan	Vegetables	Offline	С	1/13/2011	141515767	2/1/2011	6515	154.06	90.93	1003700.90	592408.95	411291.95
3	Sub-Saharan Africa	Democratic Republic of the Congo	Household	Online	С	9/11/2012	500364005	10/6/2012	7683	668.27	502.54	5134318.41	3861014.82	1273303.59
4	Europe	Czech Republic	Beverages	Online	С	10/27/2015	127481591	12/5/2015	3491	47.45	31.79	165647.95	110978.89	54669.06

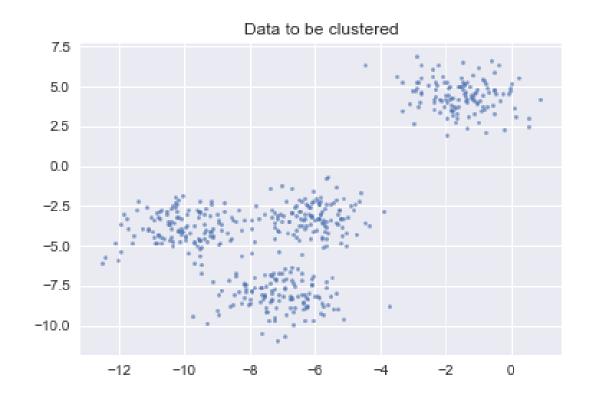
- Used when we have mix of continuous and categorical data
- 2. K-Prototype solves this using K-Means for continuous data and K-Modes for categorical data
- 3. The dissimilarity measure is the weighted combination of Euclidian distance and the dissimilarity of modes

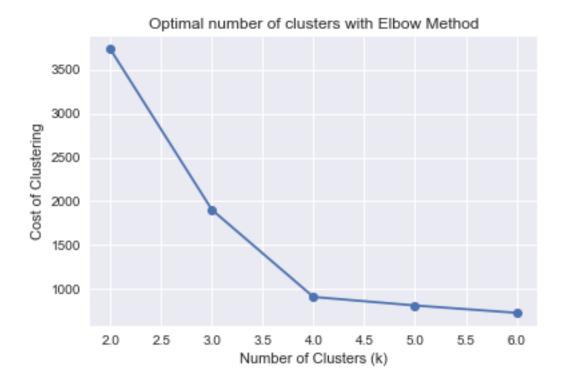
This problem can be solved using other types of clustering techniques like

- Gower's distance + K-Medoids
- Kamila
- LCA
- LCM
- MixMode

https://www.nature.com/articles/s41598-021-83340-8

How to find K? – Elbow Method





How good are the clusters? Silhouette Method

2.3.10.5. Silhouette Coefficient

If the ground truth labels are not known, evaluation must be performed using the model itself. The Silhouette Coefficient (sklearn.metrics.silhouette_score) is an example of such an evaluation, where a higher Silhouette Coefficient score relates to a model with better defined clusters. The Silhouette Coefficient is defined for each sample and is composed of two scores:

- a: The mean distance between a sample and all other points in the same class.
- **b**: The mean distance between a sample and all other points in the *next nearest cluster*.

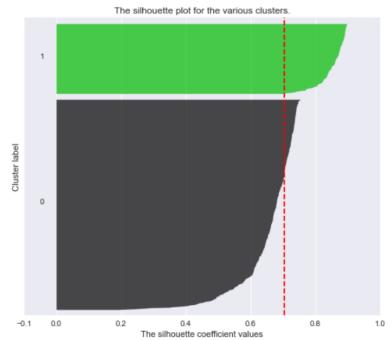
The Silhouette Coefficient s for a single sample is then given as:

$$s = \frac{b - a}{max(a, b)}$$

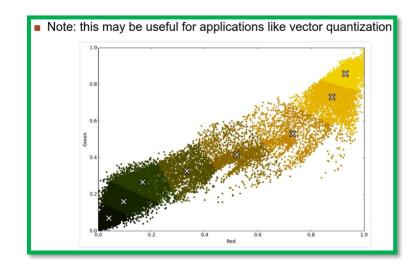
Silhouette Coefficient(SC) range from [-1, 1]

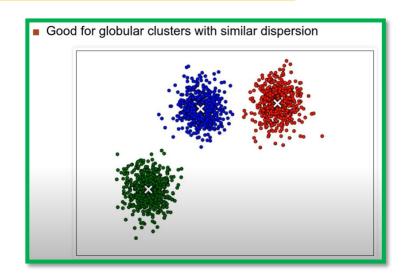
 $SC = +1 \rightarrow indicates$, sample is far away from neighbouring clusters $SC = 0 \rightarrow sample$ is on or very close to the decision boundary $SC = -1 \rightarrow samples$ might have been assigned to wrong clusters

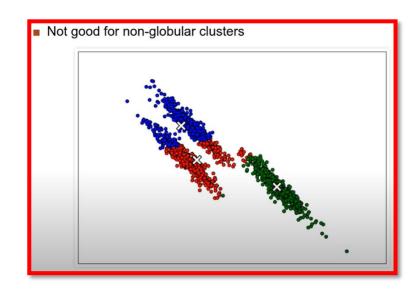


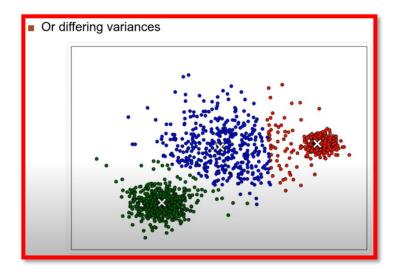


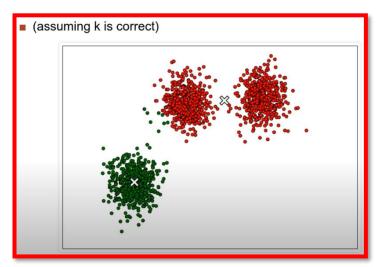
Pros and Cons of K-Family Algos





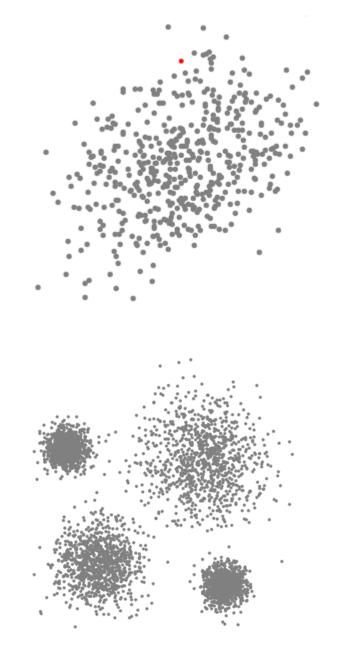






Mean Shift Algorithm

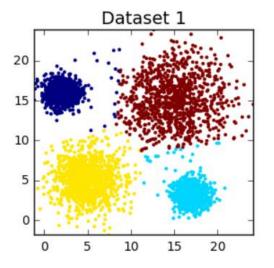
- 1. Initialize the centers randomly on the dataset
- 2. Loop:
 - 1. Around each centers is a ball (determined by the bandwidth parameter), calculate the density of the center.
 - 2. Update the center with the centroid calculated on the points inside the ball of the center
- 3. Until convergence

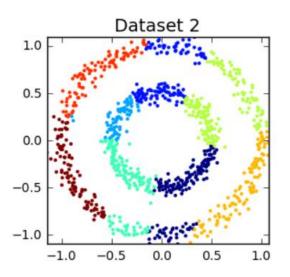


Pros and Cons of Mean Shift Clustering

- No need to pre-determine the Number of Clusters
- Can cluster data with varying density

- Still suffers from the problem of the data being globular in shape.
- Estimating bandwidth parameter is not easy.





Affinity Propagation Algorithm

Affinity Propagation is based on data points choosing the exemplar points

- Similarity Matrix (s)
- Responsibility Matrix (r)
- Availability Matrix (a)
- Criterion Matrix (c)

$$r(i,k) \leftarrow s(i,k) - \max_{\substack{k' \text{ such that } k' \neq k}} \left\{ a(i,k') + s(i,k') \right\},\tag{1}$$

$$a(k,k) \leftarrow \sum_{i' \text{ such that } i' \neq k} \{0, r(i',k)\},\tag{2}$$

$$r(i,k) \leftarrow s(i,k) - \max_{k' \text{ such that } k' \neq k} \left\{ a(i,k') + s(i,k') \right\}, \tag{1}$$

$$a(k,k) \leftarrow \sum_{i' \text{ such that } i' \neq k} \max \left\{ 0, r(i',k) \right\}, \tag{2}$$

$$a(i,k) \leftarrow \min \left\{ 0, r(k,k) + \sum_{i' \text{ such that } i' \notin \{i,k\}} \max \left\{ 0, r(i',k) \right\} \right\}$$

$$c(i,k) \leftarrow r(i,k) + a(i,k). \tag{4}$$

Working of Affinity Propogation

Table 1: Preferences of Five Participants

Participant	Tax	Fee	Interest	Quantity	Price
	Rate		Rate	Limit	Limit
Alice	3	4	3	2	1
Bob	4	3	5	1	1
Cary	3	5	3	3	3
Doug	2	1	3	3	2
Edna	1	1	3	2	3

Table 3: Responsibility Matrix

Participant	Alice	Bob	Cary	Doug	Edna
Alice	-16	-1	1	-6	-11
Bob	10	-15	-10	-10	-15
Cary	11	-11	-16	-12	-15
Doug	-9	-14	-15	-19	9
Edna	-14	-19	-18	14	-19

$$r(i,k) \leftarrow s(i,k) - \max_{k' \text{ such that } k' \neq k} \{a(i,k') + s(i,k')\},$$

Table 5: Criterion Matrix

Participant	Alice	Bob	Cary	Doug	Edna
Alice	5	-16	-15	-11	-21
Bob	5	-15	-25	-15	-25
Cary	5	-26	-15	-17	-25
Doug	-9	-29	-30	-5	-10
Edna	-14	-34	-33	-5	-10

Participant	Alice	Bob	Cary	Doug	Edna
Alice	-22	-7	-6	-12	-17
Bob	-7	-22	-17	-17	-22
Cary	-6	-17	-22	-18	-21
Doug	-12	-17	-18	-22	-3
Edna	-17	-22	-21	-3	-22

Table 4: Availability Matrix

Participant	Alice	Bob	Cary	Doug	Edna
Alice	21	-15	-16	-5	-10
Bob	-5	0	-15	-5	-10
Cary	-6	-15	1	-5	-10
Doug	0	-15	-15	14	-19
Edna	0	-15	-15	-19	9

$$c(i,k) \leftarrow r(i,k) + a(i,k)$$
.

$$a(k,k) \leftarrow \sum_{i' \text{ such that } i' \neq k} \max\{0, r(i',k)\}, \quad a(i,k) \leftarrow \min\left\{0, r(k,k) + \sum_{i' \text{ such that } i' \neq \{i,k\}} \max\{0, r(i',k)\}\right\}$$

Parameters of Affinity Propagation

class sklearn.cluster. AffinityPropagation(*, damping=0.5, max_iter=200, convergence_iter=15, copy=True, preference=None, affinity='euclidean', verbose=False, random_state='warn') [source]

Perform Affinity Propagation Clustering of data.

Read more in the User Guide.

Parameters

damping : float, default=0.5

Damping factor (between 0.5 and 1) is the extent to which the current value is maintained relative to incoming values (weighted 1 - damping). This in order to avoid numerical oscillations when updating these values (messages).

max iter: int, default=200

Maximum number of iterations.

convergence_iter : int, default=15

Number of iterations with no change in the number of estimated clusters that stops the convergence.

copy: bool, default=True

Make a copy of input data.

preference : array-like of shape (n_samples,) or float, default=None

Preferences for each point - points with larger values of preferences are more likely to be chosen as exemplars. The number of exemplars, ie of clusters, is influenced by the input preferences value. If the preferences are not passed as arguments, they will be set to the median of the input similarities.

affinity: {'euclidean', 'precomputed'}, default='euclidean'

Which affinity to use. At the moment 'precomputed' and euclidean are supported. 'euclidean' uses the negative squared euclidean distance between points.

verbose: bool, default=False

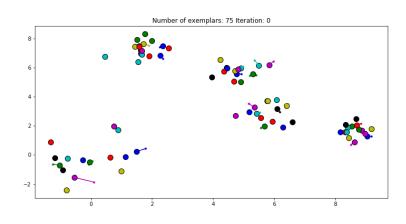
Whether to be verbose.

random_state : int, RandomState instance or None, default=0

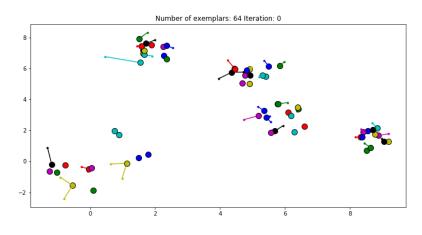
Pseudo-random number generator to control the starting state. Use an int for reproducible results across function calls. See the Glossary.

New in version 0.23: this parameter was previously hardcoded as 0.

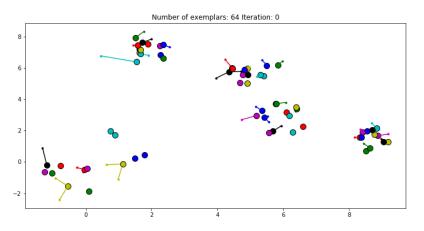
Choosing Preference is difficult



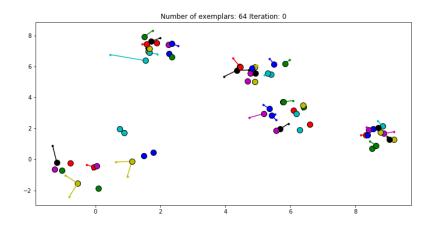
preference = 0



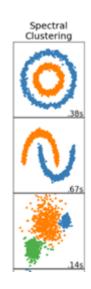
preference = -70



preference = median(S)



$$preference = -1000$$



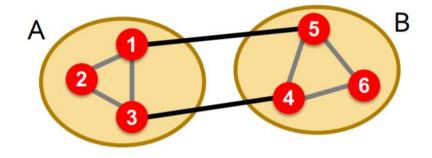
Graph Based Clustering

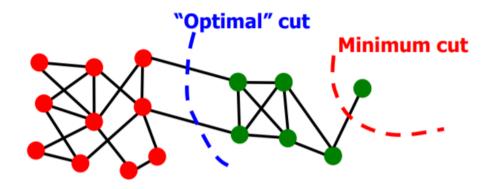
02

Spectral Clustering

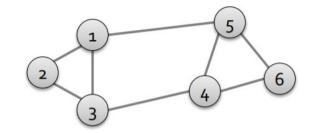
Three basic stages:

- 1) Pre-processing
 - Construct a matrix representation of the graph
- 2) Decomposition
 - Compute eigenvalues and eigenvectors of the matrix
 - Map each point to a lower-dimensional representation based on one or more eigenvectors
- 3) Grouping
 - Assign points to two or more clusters, based on the new representation





Working



A

	1	2	3	4	5	6
1	0	1	1	0	1	0
2	1	0	1	0	0	0
3	1	1	0	1	0	0
4	0	0	1	0	1	1
5	1	0	0	1	0	1
6	0	0	0	1	1	0

D

	1	2	3	4	5	6
1	3	0	0	0	0	0
2	0	2	0	0	0	0
3	0	0	3	0	0	o
4	0	0	0	3	0	0
5	0	0	0	0	3	0
6	0	0	0	0	0	2

1) Pre-processing:

 Build Laplacian matrix L of the graph





	1	2	3	4	5	6
1	3	-1	-1	0	-1	0
2	-1	2	-1	0	0	0
3	-1	-1	3	-1	0	0
4	0	0	-1	3	-1	-1
5	-1	0	0	-1	3	-1
6	0	0	0	-1	-1	2

2)
Decomposition:

Find eigenvalues λ
 and eigenvectors x
 of the matrix L

 Map vertices to corresponding components of x₂

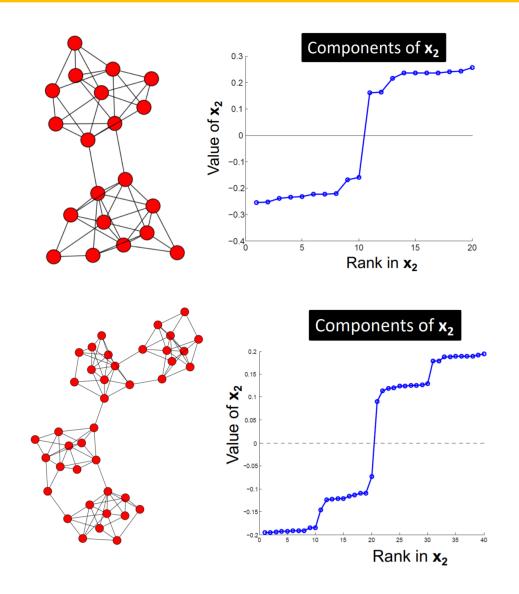


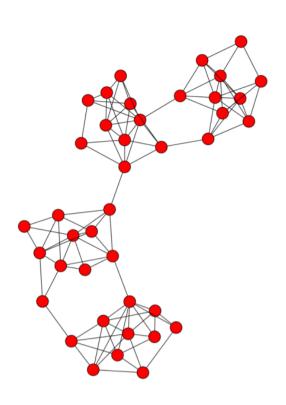
1	0.3
2	0.6
3	0.3
4	-0.3
5	-0.3
6	-0.6

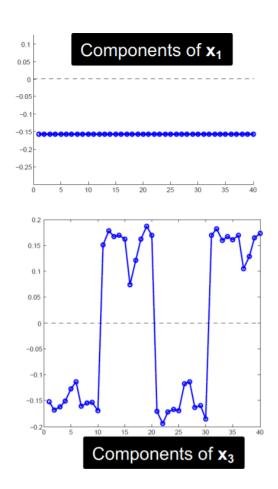
							_
							_
X =	0.4	0.3	-0.5	-0.2	-0.4	-0.5	
	0.4	0.6	0.4	-0.4	0.4	0.0	
	0.4	0.3	0.1	0.6	-0.4	0.5	
	0.4	-0.3	0.1	0.6	0.4	-0.5	l
	0.4	-0.3	-0.5	-0.2	0.4	0.5	
	0.4	0.6	0.4	-0.4	-0.4	0.0	l

How do we now find the clusters?

Examples







Spectral Clustering in sklearn

sklearn.cluster.SpectralClustering

class sklearn.cluster.SpectralClustering($n_clusters=8$, *, eigen_solver=None, $n_components=None$, random_state=None, $n_cinit=10$, gamma=1.0, affinity='rbf', $n_cinit=10$, eigen_tol=0.0, assign_labels='kmeans', degree=3, coef0=1, kernel_params=None, $n_cinit=10$, $n_cinit=10$,

affinity: str or callable, default='rbf'

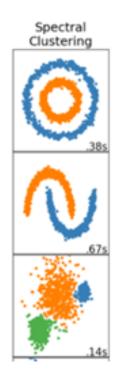
How to construct the affinity matrix.

- 'nearest_neighbors': construct the affinity matrix by computing a graph of nearest neighbors.
- 'rbf': construct the affinity matrix using a radial basis function (RBF) kernel.
- 'precomputed': interpret x as a precomputed affinity matrix, where larger values indicate greater similarity between instances.
- 'precomputed_nearest_neighbors': interpret x as a sparse graph of precomputed distances, and construct a binary affinity matrix from the n_neighbors nearest neighbors of each instance.
- one of the kernels supported by pairwise_kernels.

Only kernels that produce similarity scores (non-negative values that increase with similarity) should be used. This property is not checked by the clustering algorithm.

Pros and Cons

Pros

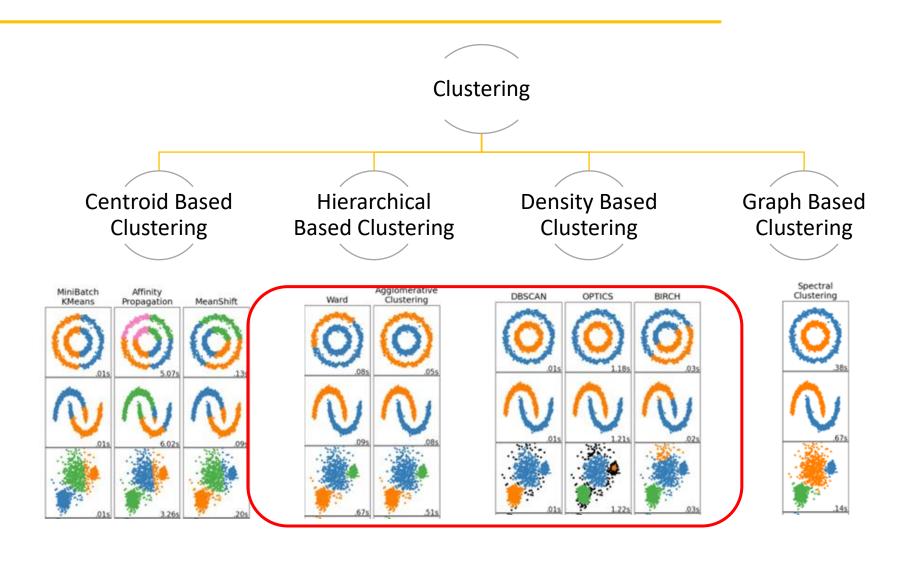


- Doesn't assume the shape of the data.
- Doesn't need the actual data, can work with similarity matrix or adjacency matrix

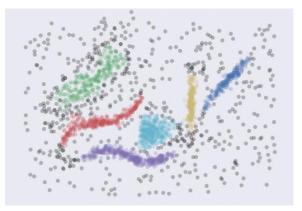
Cons

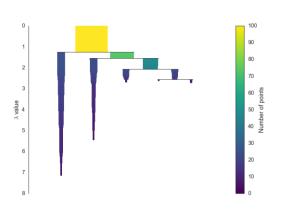
- Can be costly to compute
- Nosiy dataset causes problems
- Good for datasets containing inherent graph like structures

What will we see in Part-2

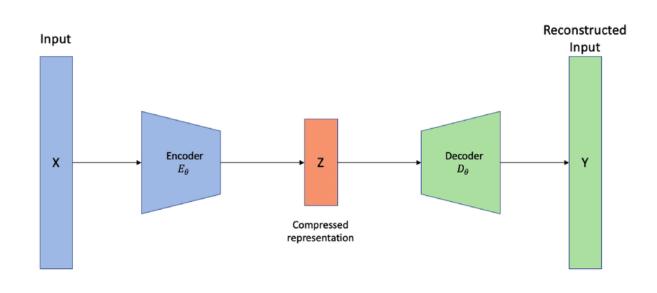


HDBSCAN

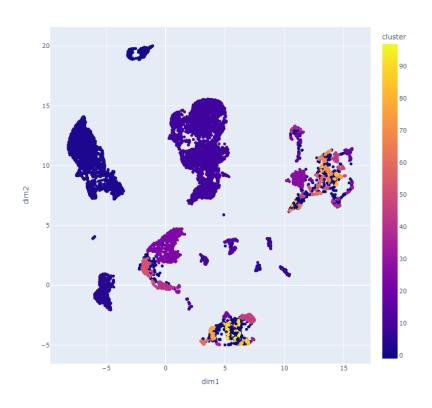




Clustering of 3D-data



Auto-encoder on 3D data



Clustering on Compressed Representation

Thank You