

Chapter 1

Statistics

1.1 Basics

- $E(X) = \int x f(x)$ and $\text{Var}(X) = E((X - \mu)^2)$.
- Sample mean: $\bar{X} = \frac{1}{n} \sum X_i$.
- Sample variance: $S^2 = \frac{1}{n-1} \sum (X_i - \bar{X})^2$.
- Likelihood: Let X_i have joint pdf $f(\mathbf{x}; \theta)$. Given observed values x_i of X_i , the *likelihood* of θ is $L(\theta) = f(\mathbf{x}; \theta)$. The *maximum likelihood estimate* $\hat{\theta}(\mathbf{x})$ is the value of θ that maximizes $L(\theta)$.

1.2 Convergence of Random Variables

RVs X_n with cdf F_n .

- X_n *converges in distribution* to X (weakly) if

$$\lim F_n(x) = F(x)$$

for all x at which F is continuous.

- X_n *converges in probability* to X if for all $\epsilon > 0$,

$$\lim P(|X_n - X| > \epsilon) = 0.$$

- X_n *converges almost surely* to X (strongly) if

$$P(\lim X_n = X) = 1,$$

i.e., events for which X_n does not converge to X have probability 0.

1.3 Parameter Estimation

An *estimator* is any statistic $\hat{\theta} = \hat{\theta}(X)$ used to estimate θ .

1.3.1 Properties of estimators

Mean squared error

- $\text{MSE}(\hat{\theta}) = \text{E} \left[(\hat{\theta} - \theta)^2 \right]$.

Variance

- $\text{Var}(\hat{\theta}) = \text{E} \left[(\hat{\theta} - \text{E}(\hat{\theta}))^2 \right]$.

Bias

- $\text{Bias}(\hat{\theta}) = \text{E}(\hat{\theta}) - \theta$.
- Note that $\text{MSE}(\hat{\theta}) = \text{Var}(\hat{\theta}) + \text{Bias}(\hat{\theta})^2$.
- The unbiased estimator with the smallest variance is known as the *minimum-variance unbiased estimator* (MVUE).

Consistency

- An estimator T_n of θ is *weakly consistent* if T_n converges in probability to θ .
- T_n is *strongly consistent* if T_n converges almost surely to θ .

Asymptotic normality

- T_n is *asymptotically normal* if

$$\sqrt{n}(T_n - \theta) \xrightarrow{D} N(0, V).$$

- Recall: CLT says that sample mean \bar{X} is asymptotically normal.

Efficiency

- The *observed information* is

$$J(\theta) = -\frac{d^2 l}{d\theta^2}$$

for scalar parameter θ or

$$J(\theta)_{ij} = -\frac{\partial^2 l}{\partial \theta_i \partial \theta_j}$$

for $\theta = (\theta_1, \dots, \theta_p)$.

- The larger $J(\hat{\theta})$ is, the more concentrated $l(\theta)$ is about $\hat{\theta}$.
- The *expected* or *Fisher information* is

$$I(\theta) = \text{E} \left(-\frac{d^2 l}{d\theta^2} \right)$$

or

$$I(\theta)_{ij} = \text{E} \left(-\frac{\partial^2 l}{\partial \theta_i \partial \theta_j} \right).$$

- Equivalently, define *score* to be gradient of $l(\theta)$, i.e.,

$$s(\theta) = \frac{\partial l}{\partial \theta}.$$

Then expected value of score at θ is 0, i.e., $E(s | \theta) = 0$. The Fisher information is defined to be the variance of the score $\text{Var}(s(\theta)) = E(s(\theta)s(\theta)^T)$.

- The *Cramer-Rao bound* says that for an unbiased estimator,

$$\text{Var}(\hat{\theta}) \geq \frac{1}{I(\theta)}.$$

Generally, if $E(\hat{\theta}) = \psi(\theta)$, then

$$\text{Var}(\hat{\theta}) \geq \frac{(\psi'(\theta))^2}{I(\theta)} = \frac{(1 + b'(\theta))^2}{I(\theta)},$$

where b is the bias. In the unbiased multivariate case, the Cramer-Rao bound states that

$$\text{cov}(T(X)) \geq I(\theta)^{-1},$$

where $M \geq 0$ means that M is positive semidefinite, i.e., $\mathbf{x}^T M \mathbf{x} \geq 0$ for all \mathbf{x} .

- The *efficiency* of an unbiased estimator is

$$e(T) = \frac{1/I(\theta)}{\text{Var}(T)}.$$

By the Cramer-Rao bound, we know $e(T) \leq 1$. An estimator is *efficient* if $e(T) = 1$ for all θ , i.e., achieves Cramer-Rao bound for all θ . Thus, an efficient estimator is the MVUE (but not necessarily conversely).

Properties of MLEs

Let $\hat{\theta}$ be the MLE of θ . Then

- $\sqrt{n}(\hat{\theta} - \theta) \xrightarrow{D} N(0, I(\theta)^{-1})$, so $\hat{\theta}$ is asymptotically unbiased and asymptotically efficient.
- $\hat{\theta} \xrightarrow{P} \theta$, i.e., $\hat{\theta}$ is consistent.
- Invariance property: the MLE of $g(\theta)$ is $g(\hat{\theta})$.

1.4 Hypothesis Testing

X_i random sample from $f(x; \theta)$.

- Setup:
 - Null hypothesis $H_0: \theta \in \Theta_0$
 - Alternative hypothesis $H_1: \theta \in \Theta_1$
- Construct test statistic $t(\mathbf{X})$ such that large values of $t(\mathbf{X})$ cast doubt on H_0 .

- Let $t_{\text{obs}} = t(\mathbf{x})$.
- The p -value or *significance level* is

$$p = P(t(\mathbf{X}) \geq t_{\text{obs}} \mid H_0).$$

- Small p -value = observed values unlikely under H_0 .
- Can define *critical region* to be C such that we reject H_0 if and only if $\mathbf{x} \in C$.

1.4.1 Errors in hypothesis testing

Two types of error:

- Type I error: rejecting H_0 when H_0 is true
- Type II error: not rejecting H_0 when H_0 is false.

The *size* of a test is defined by

$$\begin{aligned}\alpha &= P(\text{type I error}) \\ &= P(\text{reject } H_0 \mid H_0 \text{ true}).\end{aligned}$$

The *power* of a test is $1 - \beta$, where

$$\begin{aligned}\beta &= P(\text{type II error}) \\ &= P(\text{don't reject } H_0 \mid H_1 \text{ true}).\end{aligned}$$

We want **small size** and **high power**.

For composite H_i , define the size

$$\alpha = \sup_{\theta \in \Theta_0} P(\text{reject } H_0 \mid \theta)$$

and the power function

$$w(\theta) = P(\text{reject } H_0 \mid \theta).$$

We want $w \approx 0$ for $\theta \in \Theta_0$ and $w \approx 1$ for $\theta \in \Theta_1$.

Student's t -test

Consider statistic

$$t = \frac{\bar{x} - \mu_0}{s/\sqrt{n}},$$

which has t -distribution with $n - 1$ degrees of freedom. Recall that a t -distribution is given by

$$T = \frac{Z}{\sqrt{V/\nu}},$$

where Z is standard normal and V is χ^2 with ν degrees of freedom.

Noncentral t -distribution

- Noncentral distributions describe how a test statistic is distributed when the null hypothesis is false.
- Noncentral t -distribution is given by

$$T = \frac{Z + \mu}{\sqrt{V/\nu}},$$

where μ is the noncentrality parameter.

- Under the alternative hypothesis, we get noncentral t -distribution with $n - 1$ degrees of freedom and noncentrality parameter

$$\delta = \frac{\mu - \mu_0}{\sigma/\sqrt{n}}.$$

This allows us to set the power as

$$\text{Power} = P(\text{reject } H_0 \mid H_1).$$

Note that as n increases, power increases.

1.5 Bayesian Inference

- Unknown parameters are *random variables*.
- Probability model $f(\mathbf{x} \mid \theta)$ that is *conditional on* the value of θ .
- Prior density $\pi(\theta)$.
- After using observed data \mathbf{x} , get posterior density $\pi(\theta \mid \mathbf{x})$.
- We have

$$\begin{aligned}\pi(\theta \mid \mathbf{x}) &\propto f(\mathbf{x} \mid \theta) \times \pi(\theta) \\ \text{posterior} &\propto \text{likelihood} \times \text{prior}\end{aligned}$$

1.5.1 Prediction

- X_{n+1} future observation and $\mathbf{x} = (x_1, \dots, x_n)$ observed data.
- Assume, conditional on θ , that X_{n+1} has density $f(x_{n+1} \mid \theta)$ independent of X_1, \dots, X_n .
- The density of X_{n+1} given \mathbf{x} , called the *posterior predictive density*, is a conditional density denoted $f(x_{n+1} \mid \mathbf{x})$.
- Then

$$\begin{aligned}f(x_{n+1} \mid \mathbf{x}) &= \int f(x_{n+1}, \theta \mid \mathbf{x}) d\theta \\ &= \int f(x_{n+1} \mid \theta, \mathbf{x}) \pi(\theta \mid \mathbf{x}) d\theta \\ &= \int f(x_{n+1} \mid \theta) \pi(\theta \mid \mathbf{x}) d\theta\end{aligned}$$

1.5.2 Credible interval

- Bayesian alternative to confidence interval.
- A $100(1 - \alpha)\%$ credible set for θ is $jc \subset \Theta$ such that

$$P(\theta \in C \mid \mathbf{x}) = \int_C \pi(\theta \mid \mathbf{x}) d\theta = 1 - \alpha.$$

1.5.3 Hypothesis testing and Bayes factors

Setup

- Prior probabilities $P(H_i)$ such that $P(H_0) + P(H_1) = 1$.
- A prior for θ_i under H_i , denoted $\pi(\theta_i \mid H_i)$.
- A model for data \mathbf{x} under H_i , denoted $f(\mathbf{x} \mid \theta_i, H_i)$.

Bayes factor

- Prior odds of H_0 relative to H_1 is

$$\frac{P(H_0)}{P(H_1)}.$$

- Posterior odds of H_0 relative to H_1 is

$$\frac{P(H_0 \mid \mathbf{x})}{P(H_1 \mid \mathbf{x})}.$$

- Using Bayes' Theorem, get

$$\frac{P(H_0 \mid \mathbf{x})}{P(H_1 \mid \mathbf{x})} = \frac{P(\mathbf{x} \mid H_0)}{P(\mathbf{x} \mid H_1)} \times \frac{P(H_0)}{P(H_1)}$$

posterior odds = Bayes factor \times prior odds

where the Bayes factor of H_0 relative to H_1 is

$$B_{01} = \frac{P(\mathbf{x} \mid H_0)}{P(\mathbf{x} \mid H_1)}.$$

- The quantity

$$P(\mathbf{x} \mid H_i) = \int_{\Theta_i} f(\mathbf{x} \mid \theta_i, H_i) \pi(\theta_i \mid H_i) d\theta$$

is called the *marginal likelihood* for H_i .

Chapter 2

Linear Regression

- Observations

$$y_i = \beta_0 + \beta_1 x_{i1} + \cdots + \beta_p x_{ip} + \epsilon_i = x_i \cdot \beta + \epsilon_i,$$

i.e., $y = X\beta + \epsilon$.

- Loss function

$$L(\beta) = \text{MSE}(\beta) = \frac{1}{n} \|y - X\beta\|^2.$$

- Want $\hat{\beta}$ that minimizes $L(\beta)$:

- Find $\hat{\beta}$ such that

$$\frac{\partial L}{\partial \beta} = 0.$$

- Project y onto $\text{Col}(X)$.

Get $\hat{\beta} = (X^T X)^{-1} X^T y$. For simple linear regression, i.e. $y = \beta_0 + \beta_1 x + \epsilon$, we get

$$\begin{aligned}\hat{\beta}_0 &= \bar{y} - \hat{\beta}_1 \bar{x}, \\ \hat{\beta}_1 &= \frac{\text{cov}(x, y)}{\text{Var}(x)} = \frac{\sum (x_i - \bar{x})(y_i - \bar{y})}{\sum (x_i - \bar{x})^2}.\end{aligned}$$

- Residual is $\hat{\epsilon} = y - X\hat{\beta}$. The residual/explained/total sum of squares is:
 - $\text{RSS} = \|\hat{\epsilon}\|^2$, i.e., variation in the error between the observed data and modeled values.
 - $\text{ESS} = \sum (\hat{y}_i - \bar{y}_i)$, i.e., how much variation there is in the modeled values.
 - $\text{TSS} = \sum (y_i - \bar{y})$, i.e., how much variation there is in the observed data.
 - In linear regression, $\text{TSS} = \text{RSS} + \text{ESS}$.
- Coefficient of determination is

$$R^2 = 1 - \frac{\text{RSS}}{\text{TSS}}.$$

Note that the baseline model always predicts \bar{y} , so $R^2 = 0$. Furthermore, adding features weakly decreases RSS, hence weakly increases R^2 . Instead, we could use adjusted R^2 :

$$\bar{R}^2 = 1 - \frac{\text{RSS}/\text{df}_{\text{res}}}{\text{TSS}/\text{df}_{\text{tot}}},$$

where df is degrees of freedom, so $\text{df}_{\text{res}} = n - p - 1$ and $\text{df}_{\text{tot}} = n - 1$.

- Assumptions:
 - **Weak exogeneity:** Predictor variables x can be treated as fixed values, and not random variables, i.e., x is error-free, i.e., $E(x\epsilon) = 0$. So no confounding variables.
 - **Linearity:** Mean of y is linear combination of parameters and x .
 - **Independence:** Observations are independent of each other.
 - **Homoscedasticity:** Constant variance of ϵ .
 - **Normality:** ϵ follow a normal distribution.
 - **No multicollinearity:** The independent variables are not highly correlated with each other.

Chapter 3

Natural Language Processing

- Solve sequence transduction, i.e., transforms an input sequence to an output sequence.
- Necessary to have some *memory*.

3.1 RNN

- At each time step, receive two inputs: word embedding of current word and hidden state.
- Let $x_t \in \mathbb{R}^n$ and $h_{t-1} \in \mathbb{R}^m$.
- Use weight matrix $W_x \in \mathbb{R}^{m \times n}$ and hidden-state-to-hidden-state matrix $W_h \in \mathbb{R}^{m \times m}$.
- Then

$$\begin{aligned}o_t &= W_{hh}h_{t-1} + W_{hx}x_t + b_h \\h_t &= \tanh(o_t) = \tanh(W_h \cdot [h_{t-1}, x_t] + b_h) \\y_t &= g(W_y h_t + b_y)\end{aligned}$$

for some activation function g .

- We can show that

$$\nabla_{W_{hh}}(h_t) = \sum_{t'=1}^{t-1} h_{t'} \left(W_{hh}^{t-t'-1} \tanh'(o_{t'+1}) \cdot \dots \cdot \tanh'(o_t) \right).$$

So the influence of $h_{t'}$ on h_t will be small if $t' \ll t$ as $\tanh(x)$ is small for $|x| > 2$, i.e., we have a *vanishing gradient problem*.

3.2 LSTM

- Introduce *cell state* to RNN.
- Information is added or removed to the cell state through *gates*.
- **Forget gate:**
 - Input: previous cell state C_{t-1} and x_t .

- Output: number in $[0, 1]$ for each entry in C_{t-1} , i.e., how much to forget.
- So we have

$$\begin{aligned} f_t &= \sigma(W_{hf}h_{t-1} + W_{xf}x_t + b_f) \\ &= \sigma(W_f \cdot [h_{t-1}, x_t] + b_f), \end{aligned}$$

where σ is the sigmoid function applied element-wise.

- **Input and update gate:**

- Decide what and how much to add to the cell state.
- What to add:

$$\tilde{C}_t = \tanh(W_C \cdot [h_{t-1}, x_t] + b_C).$$

- How much to add:

$$i_t = \sigma(W_i \cdot [h_{t-1}, x_t] + b_i).$$

- Update cell state:

$$C_t = f_t \odot C_{t-1} + i_t \odot \tilde{C}_t,$$

where \odot is element-wise multiplication.

- **Output gate:**

- Decide what parts of cell state to output:

$$o_t = \sigma(W_o \cdot [h_{t-1}, x_t] + b_o).$$

- Actual output:

$$h_t = o_t \odot \tanh(C_t)$$

- Drawbacks: computational complexity, overfitting, dropout harder to implement, sensitive to different random weight initializations, inability to handle temporal dependencies that are longer than a few steps,

3.3 Seq2seq

- Input \rightarrow Encoder \rightarrow Context Vector \rightarrow Decoder \rightarrow Output
- Encoder and decoder are both RNNs or LSTMs.
- Last hidden state of encoder is context vector, which initializes decoder RNN.
- At each time step, decoder receives previous token (input of RNN) and uses previous hidden state. The output of RNN is fed through FNN to get embedding of word.
- Stop when EOS token is outputted.
- For back-propagation, *teacher forcing* is used, i.e., plug in correct words to decoder and stop at correct length.
- Drawbacks:
 - Bottleneck problem: for long input sequences, information would tend to be lost.
 - For the decoder, different information may be relevant at different steps.

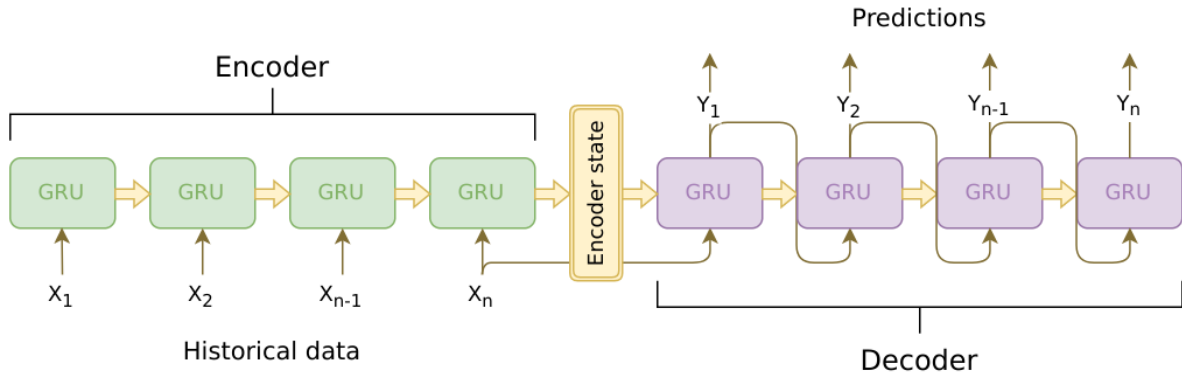


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3.4 Seq2seq with Attention

- At each decoder step, it decides which source parts are more important
- Concretely, at each t ,:
 - (i) Use previous token in RNN to update hidden state h_t .
 - (ii) Compute $\text{score}(h_t, s_k)$ between decoder hidden state h_t and all encoder hidden states s_1, \dots, s_m ;
 - (iii) Compute attention weights: softmax attention scores;
 - (iv) Compute attention vector a_t : weighted sum of encoder states.
 - (v) Use attention vector a_t and hidden state h_t in FNN to get output token.
- Popular score functions:
 - Dot-product: $\text{score}(h_t, s_k) = h_t^T s_k$.
 - Bilinear function: $\text{score}(h_t, s_k) = h_t^T W s_k$.
 - Multi-layer perceptron: $\text{score}(h_t, s_k) = v^T \tanh(W[h_t, s_k])$.
- Drawback: RNN is difficult to parallelize.

3.5 Transformers

- Encoding component is a stack (six in original paper) of encoders with same structure but different weights. Decoding component is a stack of decoders of the same number.
- Encoders: Self-Attention \rightarrow FNN
 - First encoder receives embedding of words.
 - Other encoders receive output of encoder directly below.
- Decoders: Self-Attention \rightarrow Encoder-Decoder Attention \rightarrow FNN

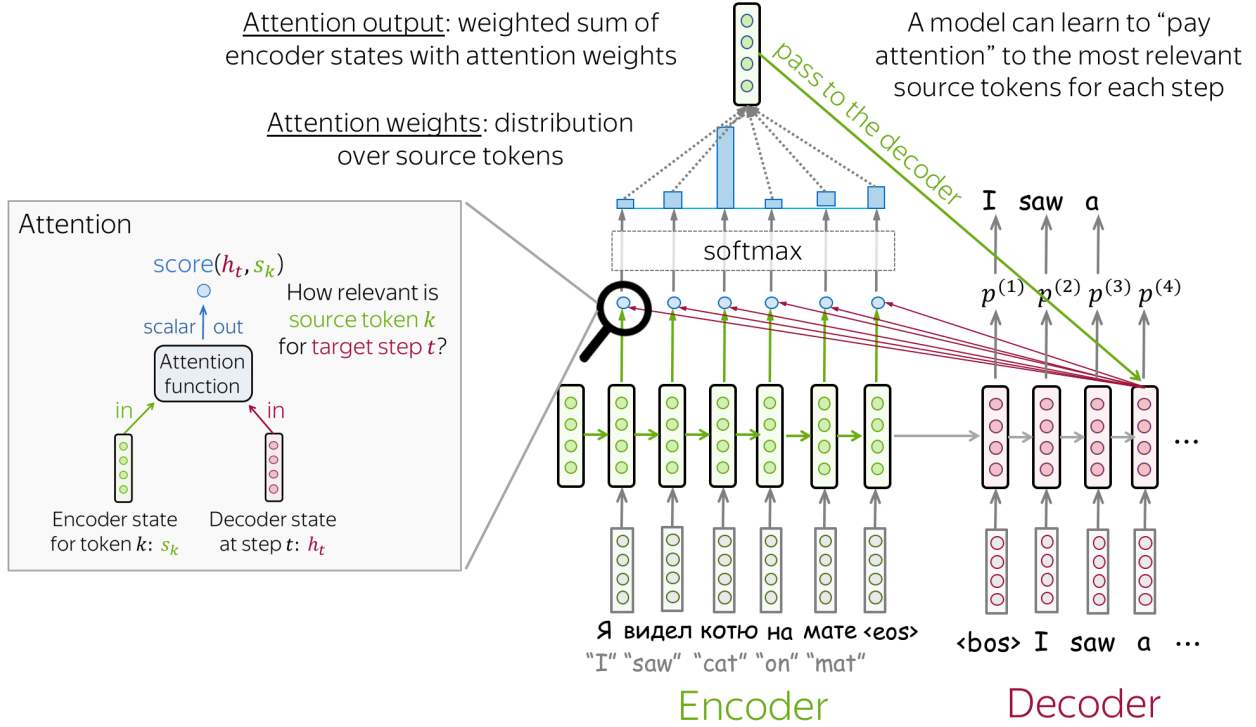


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3.5.1 Ingredients

Self-attention

Process:

1. Create three vectors from each of the encoder’s input vectors: Query, Key, and Value vectors.
2. Note: in original paper, input vectors are in \mathbb{R}^{512} , and QKV vectors are in \mathbb{R}^{64} .
3. Self-attention score between i -th and j -th word is $q_i \cdot k_j$ for all j .
4. Divide scores by square root of dimension (8; this gives more stable gradients) and softmax.
5. Multiply each value vector v_j by softmax scores.
6. Sum up the weighted value vectors. This is output of self-attention layer for i -th word.

In matrix form, suppose our input is $X \in \mathbb{R}^{n \times d}$, where n is the sequence length and d is the embedding dimension. (So rows of X are the inputs.) The QKV matrices are given by $W_Q, W_K, W_V \in \mathbb{R}^{d \times d_k}$. Then the QKV vectors

$$\begin{aligned} Q &= XW_Q \\ K &= XW_K \\ V &= XW_V \end{aligned}$$

are in $\mathbb{R}^{n \times d_k}$. For each attention head, we have

$$\text{Attention}(Q, K, V) = \text{softmax} \left(\frac{QK^T}{\sqrt{d_k}} \right) \times V \in \mathbb{R}^{n \times d_k},$$

i.e., aggregate values weighted by attention.

Multi-headed attention

Do h parallel attention heads, with different weight matrices for each head.

$$\text{MultiHead}(Q, K, V) = \text{Concat}(\text{head}_1, \dots, \text{head}_h) \times W_O,$$

where

$$\text{head}_i = \text{Attention}(Q_i, K_i, V_i)$$

is output of each attention head and $W_O \in \mathbb{R}^{hd_k \times d}$. Note that $\text{MultiHead}(Q, K, V) \in \mathbb{R}^{n \times d}$.

Positional encoding

Transformers are permutation-invariant, so we add positional encoding to input embeddings.

FNN

Output of attention fed into FNN:

$$\text{FNN}(x) = \text{ReLU}(xW_1 + b_1)W_2 + b_2.$$

Residual connections & layer normalization

Each sub-layer (attention or feedforward) is followed by

$$\text{LayerNorm}(x + \text{Sublayer}(x)).$$

Given $x \in \mathbb{R}^d$, the layer norm is

$$\text{LayerNorm}(x) = \frac{x - \mu}{\sqrt{\sigma^2 + \epsilon}} \cdot \gamma + \beta,$$

where

$$\mu = \frac{\sum x_i}{d} \text{ (mean over features)}$$

$$\sigma^2 = \frac{\sum (x_i - \mu)^2}{d} \text{ (variance over features)}$$

γ, β : learned scaling and shifting parameters

ϵ : small constant to prevent division by zero.

3.5.2 Original Architecture

Encoder Layer:

- Input Embedding + Positional Encoding
- Multi-Head Self-Attention \rightarrow Residual + Layer Norm
- Feed-Forward Network \rightarrow Residual + Layer Norm

Decoder Layer:

- Masked Multi-Head Self-Attention (prevent peeking at future tokens)
- Multi-Head Encoder-Decoder Attention \rightarrow Residual + Layer Norm
- Feed-Forward Network \rightarrow Residual + Layer Norm

3.5.3 Modern Architecture

- Input Embedding
- Layer Norm \rightarrow Self-Attention \rightarrow Residual
 - Grouped-Query Attention
 - Rotary Embeddings
- Layer Norm \rightarrow FNN \rightarrow Residual

Grouped-query attention

- Use same W_K and W_V across heads, and each head has its own W_Q .
- Better: divide heads into groups. Heads in the same group share W_K and W_V

Rotary positional embeddings

- Training done in batches, with fixed context size.
- Use padding for inputs smaller than context size.
- Instead, use separation token.
- Then rotary positional embeddings added to Q and K .

3.5.4 Other Techniques

Sparse attention

Instead of global autoregressive self-attention, use local autoregressive self-attention in some layers.

Mixture of experts (MOE)

- Instead of a single monolithic feedforward layer in the transformer block, use a set of expert networks, and route the input to only a few of them.
- A router (a smaller FNN) calculates which experts to turn on.
- Could do model merging by doing a weighted average of experts using weights from the router.

Chapter 4

Fourier Transform

- Let $x(t)$ be a complex-valued function. Then its Fourier transform is

$$X(\omega) = \int_{-\infty}^{\infty} x(t)e^{-i\omega t} dt.$$

The inverse Fourier transform is

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega)e^{i\omega t} d\omega.$$

- For a sequence of discrete time signals, use discrete-time Fourier transform:

$$X(\omega) = \sum_{n=-\infty}^{\infty} x[n]e^{-i\omega n}.$$

The output is continuous in ω and periodic. The inverse DTFT is:

$$x[n] = \frac{1}{2\pi} \int_{2\pi} X(\omega)e^{i\omega n} d\omega.$$

- Discrete Fourier transform converts a finite sequence of equally-spaced samples of a function into a same-length sequence of equally-spaced samples of the DTFT. It is given by

$$\begin{aligned} X[k] &= \sum_{n=0}^{N-1} x[n]e^{-2\pi i kn/N} \\ &= \sum_{n=0}^{N-1} x[n]W_N^{kn}, \end{aligned}$$

where $W_N = e^{-2\pi i/N}$. The inverse transform is given by

$$\frac{1}{N} \sum_{k=0}^{N-1} X[k]W_N^{-kn}.$$

- The fast Fourier transform is based on the idea that the N -th roots of unity W_N^k have nice properties when N is a power of 2. In vector form,

$$\mathbf{X}[k] = \mathbf{W}_N \mathbf{x}[n],$$

where $W_N = V(W_N^0, \dots, W_N^{N-1})$ is a Vandermonde matrix. The computational complexity is $O(N \log N)$ vs. $O(N^2)$ of definition of DFT.

- Limitation of Fourier transform is that it lacks temporal resolution. A way to overcome this is the short-time Fourier transform.

– Continuous case:

$$\text{STFT}\{x(t)\}(\tau, \omega) = \int_{-\infty}^{\infty} x(t)w(t - \tau)e^{-i\omega t} dt,$$

where w is the window function, usually Hann or Gaussian window.

– Discrete case:

$$\text{STFT}\{x[n]\}(k, \omega) = \sum_{n=-\infty}^{\infty} x[n]w[n - k]e^{-i\omega n}.$$

Uncertainty principle: there is a trade-off between temporal and frequency resolution.

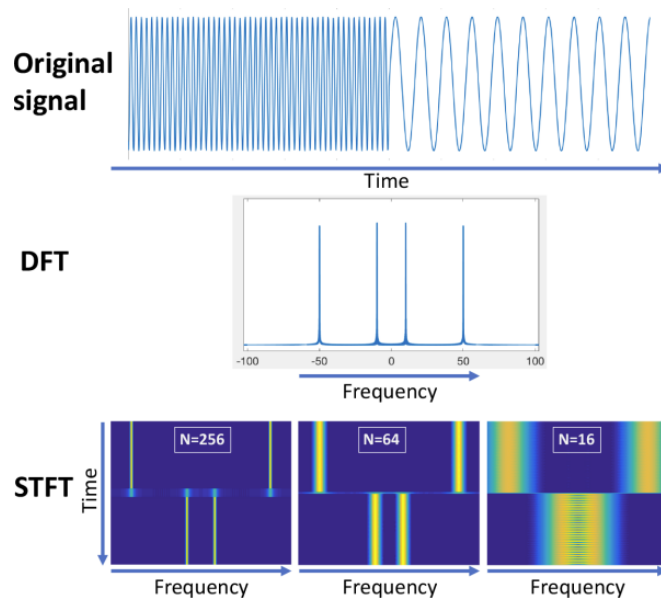


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- Spectrograms:
 - Divide a time-domain signal into segments of equal length.
 - Apply FFT to each segment, transforming the data from the time domain to the frequency domain.
 - Each segment corresponds to vertical line in spectrogram.
 - For window width w , $\text{spectrogram}(t) = |\text{STFT}(t)|^2$.
- Nyquist–Shannon sampling theorem
 - Sampling rate must be at least twice the bandwidth of the signal to avoid aliasing.
 - Let $x(t)$ have Fourier transform $X(f)$. Suppose $X_{1/T}(f)$ is the DTFT of sample sequence $x[n]$.
 - For DTFT, copies of X_f are shifted by multiples of the sampling rate f_s and added.

- If Nyquist–Shannon is not satisfied, copies will overlap.
- Any frequency component above $f_s/2$ is indistinguishable from a lower-frequency component (i.e., alias).

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