

spanny

abusing mdspan is within arms reach

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Getting Started

```
int main(int argc, char ** argv)
{
    rclcpp::init(argc, argv);

    auto node = std::make_shared<rclcpp::Node>("minimal_param_node");
    auto my_string = node->declare_parameter("my_string", "world");
    auto my_number = node->declare_parameter("my_number", 23);

    rclcpp::spin(node);
    rclcpp::shutdown();
}
```

30 lines of C++ boilerplate per parameter

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Before handling of dynamic parameters

Questions?

github.com/griswaldbrooks/spanny