

Lecture 3

- Incompressible hydrodynamics.

The equations of dissipative hydrodynamics that we wrote down are:

continuity eqn

$$\partial_t \rho + \operatorname{div}(\rho \mathbf{v}) = 0$$

momentum eqn

$$\partial_t (\rho \mathbf{v}) + \operatorname{div}(\rho \mathbf{v} \mathbf{v} + \mu \delta_{ij} + \sigma_{ij}) = 0$$

$$\text{with } \sigma_{ij} = \eta \left(\partial_i v_j + \partial_j v_i - \frac{2}{3} \delta_{ij} \partial_k v_k \right)$$

$$+ \frac{1}{2} \delta_{ij} \partial_k v_k$$

energy

entropy eqn

$$\partial_t s + \operatorname{div}(s \mathbf{v} + \frac{Q}{T}) = 0$$

$$\text{with } Q = -k \nabla T - v_j \sigma_{ij}$$

with an equation of state

This makes a complete dynamical theory. The picture becomes a lot simpler if we consider incompressible fluids.

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The incompressible approximation:

$$\rho = \text{constant} = 1$$

$$\Rightarrow \nabla \cdot v = 0$$

The dynamical theory gets the following simplified form:

$$\partial_t(\rho v) + \operatorname{div}(\rho v_i v_j + \rho \delta_{ij} \bar{\sigma}_{ij}) = 0$$

$$\text{with } \sigma_{ij} = \eta (\partial_i v_j + \partial_j v_i)$$

$$\Rightarrow \rho [\partial_t v + (v \cdot \nabla) v] = -\nabla p + \eta \operatorname{div}(\partial_i v_j + \partial_j v_i)$$

$$\Rightarrow \partial_t v = -\frac{\nabla p}{\rho} + \frac{\eta}{\rho} \nabla^2 v$$

$\frac{\eta}{\rho} \equiv \nu$ is the kinematic viscosity.

We obtain the famous Navier-Stokes equation

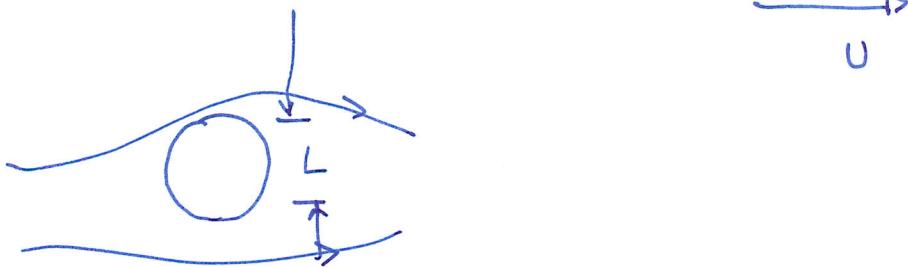
$$\boxed{\begin{aligned} \nabla \cdot v &= 0 \\ \partial_t v + (v \cdot \nabla) v &= -\nabla p + \nu \nabla^2 v \end{aligned}}$$

This makes a complete dynamical theory

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3.2 Reynold's number :

consider flow of an incompressible fluid around a sphere.



The boundary conditions are that the velocity is a constant at infinity, and both tangential and vertical component of velocity are zero at the surface of the sphere.

Let us try to non-dimensionalize the governing equations.

velocity : U

length : L

time : $\frac{L}{U}$

$\nu \rightarrow \tilde{\nu}$ $\tilde{\nu}$ \uparrow non-dimensional velocity.

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How should we non-dimensionalize pressure?

~~if~~ has the same dimension

Better take a curl of the governing equation

$$\cancel{\nabla \cdot} = \cancel{\nabla \cdot v} \quad \omega = \nabla \times v$$

③

$$\partial_t \omega + \nabla \times [(\vec{v} \cdot \nabla) \vec{v}] = 0 + v \nabla^2 \omega$$

Using vector identities you can show that-

$$\cancel{\nabla \times} (\vec{v} \cdot \nabla) \vec{v} = \cancel{\nabla \times \vec{v}} \omega \times \vec{v}$$

Hence :

$$\partial_t \omega + \nabla \times (\omega \times \vec{v}) = v \nabla^2 \omega$$

Now, non-dimensionaliz:

$$[\omega] = \frac{1}{T}$$

$$[\partial_t \omega] = \frac{1}{T^2}$$

$$\frac{1}{T^2} \tilde{\partial}_t \tilde{\omega} + \tilde{\nabla}$$

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$$\frac{1}{T} \frac{1}{T} \partial_t \omega + \frac{1}{L} \frac{1}{T} \frac{L}{T} \nabla \times (\omega \times v)$$

$$= \nu \frac{1}{L^2} \frac{1}{T} \nabla^2 \omega$$

$$\Rightarrow \partial_t \omega + \nabla \times (\omega \times v)$$

$$= \frac{\nu T}{L^2} \nabla^2 \omega$$

$$= \frac{\nu}{L^2} \frac{L}{U} \nabla^2 \omega = \frac{\nu}{UL} \nabla^2 \omega.$$

$$\Rightarrow \boxed{\partial_t \omega + \nabla \times (\omega \times v) = \frac{1}{Re} \nabla^2 \omega}$$

The whole problem reduces to a single dimensionless parameter, the Reynolds no.

- * The limit of $Re \rightarrow 0$ is not the same as $Re = 0$ because this is a problem of singular perturbation theory. In other words $Re \rightarrow \infty$, which implies $v \rightarrow 0$ is ~~not~~ \pm the problem does not reduce to ideal problem.

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The vorticity eqn :

$$\partial_t \omega + \nabla \times (\omega \times v) = \frac{1}{Re} \nabla^2 \omega$$

$$\Rightarrow \partial_t \omega = \nabla \times (\omega \times v) + \frac{1}{Re} \nabla^2 \omega$$

Is exactly the same as the eqn. for the magnetic field

$$\partial_t B = \nabla \times (v \times B) + \frac{1}{Re_m} \nabla^2 B.$$

where Re_m = magnetic Reynold's number

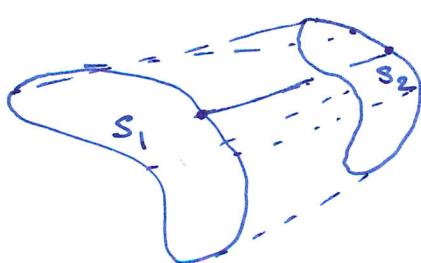
$$= \frac{UL}{\eta}$$

In the ideal case, $v = 0$

$$\partial_t \omega + \nabla \times (\omega \times v) = 0$$

Kelvin's vorticity theorem :

consider an open surface in a fluid, that



The surface is made out of fluid parcels.

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With time the parcels will move.

The flux of vorticity through this surface will remain a constant in time

$$\int_{S_1} \omega \cdot \hat{n} ds = \int_{S_2} \omega \cdot \hat{n} ds$$

$$\text{or } D_t \int_S \omega \cdot \hat{n} ds = 0$$

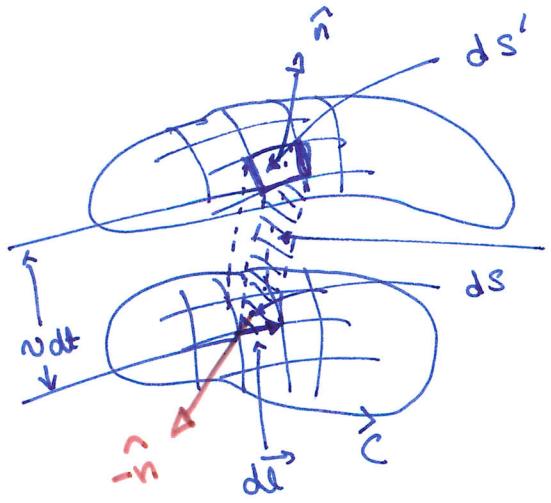
proof

$$D_t \int_S \omega \cdot \hat{n} ds \\ = \int_S \frac{\partial \omega}{\partial t} \cdot \hat{n} ds + \cancel{\int_S \omega \cdot D_t(\hat{n} ds)}$$

$$= - \int \nabla \times (\omega \times v) \cdot \hat{n} ds + \text{2nd term}$$

$$= - \oint_C (\omega \times v) \cdot dt + \text{(2nd term)}$$

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$$\oint d\ell \times \vec{v} dt$$

clearly :

$$\hat{n}' ds' - \hat{n} ds + \left(\begin{array}{c} \text{vertical} \\ \text{area} \end{array} \right) = 0$$

$$\omega \cdot \frac{d}{dt} (\hat{n} ds)$$

$$\hat{n}' ds' - ds \hat{n} - dt \oint \vec{v} \times d\ell = 0$$

$$D_T(\hat{n} ds) = \lim_{dt \rightarrow 0} \frac{\hat{n}' ds' - \hat{n} ds}{dt}$$

$$= \oint \vec{v} \times d\ell$$

$$\int \omega \cdot D_T(\hat{n} ds) = \int \oint \omega \cdot (\vec{v} \times d\ell)$$

$$= \int \oint (\omega \times v) \cdot dl$$

$$= \oint_C (\omega \times v) \cdot dl$$

(Because all the inner contributions cancel out)

#D $D_T \oint \omega \cdot \hat{n} ds$

$$\Rightarrow \oint_C \omega \cdot \hat{n} ds = 0$$

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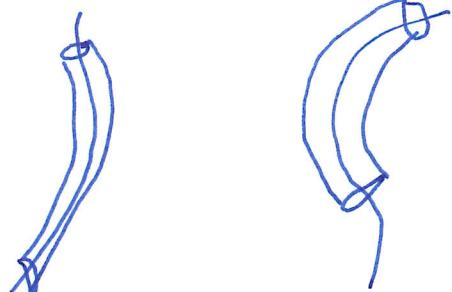
In other words

$$\int_S \omega \cdot \hat{n} dS = \int_S (\nabla \times v) \cdot \hat{n} dS \\ = \oint_C v \cdot dl \equiv \text{circulation}$$

Circulation is a conserved quantity in ideal hydrodynamics.

- * The same equation is obeyed by the magnetic field hence in ideal MHD the flux of a magnetic field through a surface is conserved. This is called the theorem of "flux freezing".
(Alfvén 1942)
- * Possible consequences of flux freezing.

The magnetic field is slaved to the flow. If you know how the flow goes you can predict the field.



Two fluid parcels on the same field line remain on it.

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- * If a structure collapses under gravity its magnetic field can become very intense.

The vorticity eqn:

$$\partial_t \omega + \nabla \times (\omega \times v) = \nu \nabla^2 \omega$$

$$\nabla \cdot v = 0$$

$$\omega = \nabla \times v$$

makes a complete dynamical theory.

- * We obtain v by the Biot-Savart law.
- * In the non-ideal case ~~the~~ vorticity diffuses.

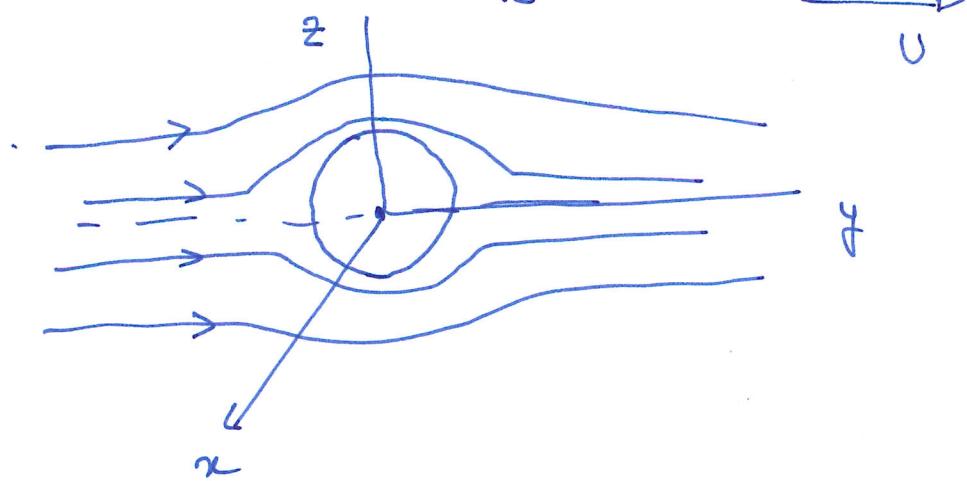
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Some solutions of the Navier-Stokes eqn.

1. Stokes eqn.

$$\nabla \cdot \mathbf{v} = 0$$

$$\partial_t \mathbf{v} = \frac{1}{Re} \nabla^2 \mathbf{v} - \nabla p$$



Look for stationary solutions:

$$\nabla \cdot \mathbf{v} = 0$$

$$\frac{1}{Re} \nabla^2 \mathbf{v} - \nabla p = 0$$

Look for solutions in the following form:

$$v_i = U_{ij} a_j, \quad p = \Pi_j a_j$$

where \vec{a} is a constant vector.

$$U_{ij} = \delta_{ij} \nabla^2 x - \frac{\partial^2}{\partial x_i \partial x_j} x$$

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$$\nabla \cdot v = \frac{\partial}{\partial x_j} \delta_{ij} \overset{2}{\nabla} x^i a_i$$

$$\nabla \cdot v = \frac{\partial}{\partial x_i} \left[\delta_{ij} \overset{2}{\nabla} x^i a_j - \frac{\overset{2}{\nabla} x^i}{\partial x_i \partial x_j} a_j \right]$$

$$= \left[\delta_{ij} \overset{2}{\nabla} \frac{\partial x^i}{\partial x_j} a_j - \frac{\overset{2}{\nabla} a^i}{\partial x_j} \overset{2}{\nabla} x^i a_j \right] = 0$$

$$\overset{2}{\nabla} v = \left[\delta_{ij} \overset{4}{\nabla} x^i - \frac{\partial}{\partial x_i \partial x_j} \overset{2}{\nabla} x^i \right] a_j$$

choose $\Pi_j = \frac{\partial}{\partial x_j} \overset{2}{\nabla}$

Then we obtain

$$\boxed{\overset{4}{\nabla} x = 0}$$

a biharmonic eqn.