Practical Machine Learning Peer Graded Assignment

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Background

Using devices such as Jawbone Up, Nike FuelBand, and Fitbit it is now possible to collect a large amount of data about personal activity relatively inexpensively. These type of devices are part of the quantified self movement - a group of enthusiasts who take measurements about themselves regularly to improve their health, to find patterns in their behavior, or because they are tech geeks. One thing that people regularly do is quantify how much of a particular activity they do, but they rarely quantify how well they do it. In this project, your goal will be to use data from accelerometers on the belt, forearm, arm, and dumbell of 6 participants. They were asked to perform barbell lifts correctly and incorrectly in 5 different ways. More information is available from the website here: http://groupware.les.inf.puc-rio.br/har (see the section on the Weight Lifting Exercise Dataset).

Data

The training data for this project are available

here: https://d396qusza40orc.cloudfront.net/predmachlearn/pml-training.csv

The test data are available here: https://d396qusza40orc.cloudfront.net/predmachlearn/pml-testing.csv

The data for this project come from this source: http://groupware.les.inf.puc-rio.br/har

Load required packages for analysis

```
library(caret)
## Loading required package: lattice
## Loading required package: ggplot2
library(rpart)
library(ggplot2)
library(corrplot)
library(randomForest)
## randomForest 4.6-12
## Type rfNews() to see new features/changes/bug fixes.
## Attaching package: 'randomForest'
## The following object is masked from 'package:ggplot2':
##
## margin
library(rattle)
## Rattle: A free graphical interface for data mining with R.
## Version 4.1.0 Copyright (c) 2006-2015 Togaware Pty Ltd.
## Type 'rattle()' to shake, rattle, and roll your data.
set.seed(12345)
```

Load data

training raw <- read.csv("pml-training.csv")[,-1]</pre>

```
testing <- read.csv("pml-testing.csv")[,-1]
# check dimension of the training and test dataset
dim(training_raw)
dim(testing)
## [1] 19622 159
## [1] 20 159
```

Clean data

```
# remove predictors that have many missing/NA values or non-unique values
NZV <- nearZeroVar(training raw)
training <- training_raw[, -NZV]</pre>
testing <- testing[, -NZV]
# remove cases that have many missing/NA values
NaValues <- sapply(training, function(x) mean(is.na(x))) > 0.9
training <- training[, NaValues == "FALSE"]</pre>
testing <- testing[, NaValues == "FALSE"]
# remove id and time variables
training <- training[,-c(1:5)]
testing <- testing[,-c(1:5)]
# check dimension of the cleaned up dataset
dim(training)
## [1] 19622 53
dim(testing)
## [1] 20 53
# take a look at the training dataset
head(training)
## roll_belt pitch_belt yaw_belt total_accel_belt gyros_belt_x gyros_belt_y
## 1
      1.41 8.07 -94.4
                                3
                                      0.00
                                               0.00
## 2
     1.41
            8.07 -94.4
                                3
                                      0.02
                                               0.00
## 3
     1.42 8.07 -94.4
                                3
                                      0.00
                                               0.00
      1.48 8.05 -94.4
                                3
                                      0.02
## 4
                                               0.00
## 5
      1.48
             8.07 -94.4
                                3
                                      0.02
                                               0.02
## 6 1.45
             8.06 -94.4
                                3
                                      0.02
                                               0.00
## gyros_belt_z accel_belt_x accel_belt_y accel_belt_z magnet_belt_x
## 1
       -0.02
                -21
                          4
                                 22
                                         -3
                                 22
                                         -7
## 2
       -0.02
                 -22
                          4
## 3
       -0.02
                 -20
                          5
                                 23
                                         -2
       -0.03
                 -22
                          3
                                 21
                                         -6
## 4
## 5
       -0.02
                 -21
                          2
                                 24
                                         -6
## 6
       -0.02
                 -21
                                          0
                          4
                                 21
## magnet_belt_y magnet_belt_z roll_arm pitch_arm yaw_arm total_accel_arm
## 1
         599
                 -313 -128 22.5 -161
                                                34
## 2
         608
                 -311 -128 22.5 -161
                                                34
                 -305 -128
## 3
         600
                               22.5 -161
                                                34
## 4
         604
                 -310 -128
                               22.1 -161
                                                34
## 5
         600
                 -302 -128
                               22.1 -161
                                                34
## 6
         603
                 -312 -128
                               22.0 -161
                                                34
```

```
## gyros_arm_x gyros_arm_y gyros_arm_z accel_arm_x accel_arm_y accel_arm_z
                        -0.02
                                 -288
## 1
        0.00
                0.00
                                          109
                                                  -123
## 2
        0.02
                -0.02
                        -0.02
                                 -290
                                          110
                                                  -125
        0.02
##3
                -0.02
                        -0.02
                                 -289
                                          110
                                                  -126
## 4
        0.02
                -0.03
                         0.02
                                 -289
                                                  -123
                                          111
## 5
        0.00
                -0.03
                                 -289
                                                  -123
                         0.00
                                          111
## 6
        0.02
                -0.03
                         0.00
                                 -289
                                          111
                                                  -122
## magnet arm x magnet arm y magnet arm z roll dumbbell pitch dumbbell
        -368
                                 13.05217
                                             -70.49400
## 1
                  337
                           516
## 2
        -369
                  337
                           513
                                 13.13074
                                             -70.63751
## 3
        -368
                  344
                           513
                                 12.85075
                                             -70.27812
## 4
        -372
                  344
                           512
                                 13.43120
                                             -70.39379
## 5
        -374
                  337
                           506
                                 13.37872
                                             -70.42856
## 6
        -369
                  342
                                             -70.81759
                           513
                                  13.38246
## yaw_dumbbell total_accel_dumbbell gyros_dumbbell_x gyros_dumbbell_y
## 1 -84.87394
                          37
                                            -0.02
## 2 -84.71065
                         37
                                    0
                                            -0.02
                         37
                                            -0.02
## 3 -85.14078
                                    0
                          37
                                    0
## 4 -84.87363
                                            -0.02
## 5 -84.85306
                          37
                                    0
                                            -0.02
## 6 -84.46500
                         37
                                    0
                                            -0.02
## gyros dumbbell z accel dumbbell x accel dumbbell y accel dumbbell z
## 1
           0.00
                     -234
                                  47
                                           -271
## 2
           0.00
                      -233
                                  47
                                           -269
## 3
          0.00
                      -232
                                  46
                                           -270
## 4
          -0.02
                      -232
                                  48
                                           -269
## 5
          0.00
                      -233
                                  48
                                           -270
##6
           0.00
                      -234
                                  48
                                           -269
## magnet_dumbbell_x magnet_dumbbell_y magnet_dumbbell_z roll_forearm
## 1
           -559
                       293
                                   -65
                                           28.4
## 2
           -555
                       296
                                           28.3
                                   -64
##3
           -561
                       298
                                   -63
                                           28.3
## 4
           -552
                       303
                                   -60
                                           28.1
## 5
           -554
                       292
                                   -68
                                           28.0
##6
           -558
                       294
                                   -66
                                           27.9
## pitch_forearm yaw_forearm total_accel_forearm gyros_forearm_x
## 1
        -63.9
                 -153
                                        0.03
                               36
## 2
        -63.9
                 -153
                               36
                                        0.02
## 3
        -63.9
                 -152
                                36
                                        0.03
## 4
        -63.9
                 -152
                                36
                                        0.02
## 5
        -63.9
                 -152
                               36
                                        0.02
##6
        -63.9
                 -152
                                36
                                        0.02
## gyros_forearm_y gyros_forearm_z accel_forearm_x accel_forearm_y
## 1
          0.00
                                192
                                          203
                    -0.02
## 2
          0.00
                    -0.02
                                192
                                          203
##3
          -0.02
                     0.00
                                          204
                                196
## 4
          -0.02
                     0.00
                                189
                                          206
## 5
          0.00
                    -0.02
                                189
                                          206
## 6
          -0.02
                    -0.03
                                193
                                          203
## accel_forearm_z magnet_forearm_x magnet_forearm_y magnet_forearm_z
## 1
          -215
                      -17
                                654
                                           476
## 2
          -216
                                           473
                      -18
                                661
```

```
-18
                              658
                                        469
## 3
         -213
## 4
         -214
                    -16
                                        469
                              658
         -214
                    -17
## 5
                              655
                                        473
                    -9
         -215
## 6
                             660
                                        478
## classe
## 1
## 2
      Α
## 3
## 4
## 5
      Α
## 6
```

Prepare data partition, for later validation

```
inTrain <- createDataPartition(y= training$classe, p = 0.7, list = FALSE)
training <- training[inTrain, ]
crossvalidation <- training[-inTrain, ]</pre>
```

Now we can train our models given the preprocess with PCA

```
# decision trees
model_tree <- train(classe~., data = training, method = "rpart")
# print result of model prediction on original training and crossvalidation dataset
predict_training_tree <- predict(model_tree, training)</pre>
confusionmatrix_training_tree <- confusionMatrix(predict_training_tree, training$classe)</pre>
predict_crossvalidation_tree <- predict(model_tree, crossvalidation)</pre>
confusionmatrix_cv_tree <- confusionMatrix(predict_crossvalidation_tree, crossvalidation$classe)
print(confusionmatrix_cv_tree)
## Confusion Matrix and Statistics
##
##
        Reference
## Prediction A B C D E
       A 1074 319 345 319 100
##
##
       B 11 276 20 128 91
##
       C 67 207 354 259 205
##
       D 0 0 0 0 0
##
       E 9 0 0 0 326
##
## Overall Statistics
##
##
          Accuracy: 0.4939
##
            95% CI: (0.4785, 0.5093)
## No Information Rate: 0.2825
##
   P-Value [Acc > NIR] : < 2.2e-16
##
##
            Kappa: 0.3393
## Mcnemar's Test P-Value: NA
```

```
##
## Statistics by Class:
##
##
             Class: A Class: B Class: C Class: D Class: E
## Sensitivity
                 0.9251 0.34414 0.49235 0.0000 0.45152
                 0.6328 0.92443 0.78237 1.0000 0.99734
## Specificity
## Pos Pred Value
                    0.4979 0.52471 0.32418 NaN 0.97313
## Neg Pred Value
                    0.9555 0.85324 0.87906 0.8282 0.89510
                   0.2825 0.19513 0.17494 0.1718 0.17567
## Prevalence
## Detection Rate
                    0.2613 0.06715 0.08613 0.0000 0.07932
## Detection Prevalence 0.5248 0.12798 0.26569 0.0000 0.08151
## Balanced Accuracy 0.7789 0.63428 0.63736 0.5000 0.72443
# random forest
model rf <- train(classe~., data = training, method = "rf")
# print result of model prediction on original training and crossvalidation dataset
predict_training_rf <- predict(model_rf, training)</pre>
confusionmatrix training rf <- confusionMatrix(predict training rf, training$classe)
predict crossvalidation rf <- predict(model rf, crossvalidation)</pre>
confusionmatrix_cv_rf <- confusionMatrix(predict_crossvalidation_rf, crossvalidation$classe)
print(confusionmatrix cv rf)
## Confusion Matrix and Statistics
##
##
       Reference
## Prediction A B C D E
##
       A 1161 0 0 0 0
##
       B 0 802 0 0 0
##
       C 0 0 719
                    0 0
##
       D 0 0 0 706 0
##
       E 0 0 0 0 722
##
## Overall Statistics
##
##
          Accuracy: 1
##
           95% CI: (0.9991, 1)
## No Information Rate: 0.2825
##
   P-Value [Acc > NIR] : < 2.2e-16
##
##
           Kappa: 1
## Mcnemar's Test P-Value: NA
##
## Statistics by Class:
##
             Class: A Class: B Class: C Class: D Class: E
## Sensitivity
                 1.0000 1.0000 1.0000 1.0000 1.0000
## Specificity
                 1.0000 1.0000 1.0000 1.0000 1.0000
## Pos Pred Value 1.0000 1.0000 1.0000 1.0000
## Neg Pred Value
                    1.0000 1.0000 1.0000 1.0000 1.0000
## Prevalence 0.2825 0.1951 0.1749 0.1718 0.1757
## Detection Rate 0.2825 0.1951 0.1749 0.1718 0.1757
## Detection Prevalence 0.2825 0.1951 0.1749 0.1718 0.1757
```

Conclusion

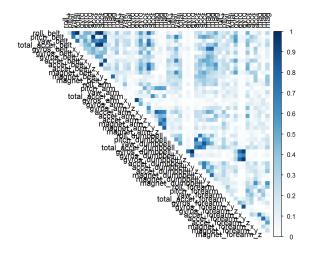
The confusionmatrix showed that the accuracy of the random forest models is better than the decision tree model. Therefore, we used this model to predict on the testing dataset.

Predict on testing dataset

```
predict_testing <- predict(model_rf, testing)
predict_testing
## [1] B A B A A E D B A A B C B A E E A B B B
## Levels: A B C D E</pre>
```

Appendix

```
# explore the remianing predictors
# check the factor variables
predictor_factor <- which(sapply(training, class) == "factor")
# explore correlation between predictors
predictor_cor <- abs(cor(training[,-predictor_factor]))
# turn lower tri to 0
predictor_cor[lower.tri(predictor_cor, diag = TRUE)] <- 0
# visualize result
corrplot(predictor_cor, method = "color", type = "upper", cl.lim = c(0,1), tl.col = rgb(0, 0, 0))</pre>
```



```
## roll_belt
              1 10
## total_accel_belt 4 10
## accel_belt_y 9 10
## pitch_belt 2 11
## accel_belt_x 8 11
## gyros_arm_x 18 19
## accel_arm_x 21 24
## magnet_arm_y 25 26
## gyros_dumbbell_x 31 33
## pitch_dumbbell 28 34
## yaw_dumbbell 29 36
## gyros_dumbbell_x 31 46
## gyros_dumbbell_z 33 46
## gyros_forearm_y 45 46
# Therefore, there are highly correlated predictors, principal component analysis is necessary.
```