## WEEK 1 : LECTURE 4 Reinforcement Learning the type of learning where we learn to control the system therough total and error and the minimal feedback is called reinforcement learning them is not betorn't even slove all laurisuspect RL Franciscork Environment ( evaluation; STATE Agent ACTION secret feet a feet of the second in the second rearn prom close interaction Stochastic environment Noisy delayed scalar evaluation Icarn a policy (Maximize a measure of long torm performance) I took to see the southern and a conflore too Applications game playing (Backgammon-world's best player) Autonomous agents (Robot Navigation) Adaptive control (Helicopter pilot) Combinatorial Optimization (VISI placement) Intelligent Tutoring Systems LANG brown AND BRANCH

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