

Insertion in BTree

B tree is a self-balancing search tree. It is a fat tree, in which a node holds many key values.

'M' is the order of the tree and most of the B tree properties are dependent on M. It is usually implemented in secondary memory to reduce disk access time.

As, a single node stores $M-1$ key values and have maximum M children, height of B tree is low and time complexity for following operations are -

Search	$O(\log n)$
Insert	$O(\log n)$
Delete	$O(\log n)$

Implementing using two classes - BTree Node, BTree.

```
class BTreeNode
```

```
{
```

```
    int *keys; // Array for storing key values
```

```
    int t; // Minimum degree
```

```
    BTreeNode **C; // Array of child pointers
```

```
    int n; // current number of keys
```

```
    bool leaf; // is true when node is leaf node
```

```
};
```

```
friend class BTree;
```

};

class BTree

{

BTreeNode* root;

int t;

// Function to traverse

// Function to search for key value

// Function to insert

};

~~void BTreeNode~~

void BTree::insert(int data)

{

if (root == NULL)

{ // Inserting the value

root = new BTreeNode(t, true);

root->keys[0] = data;

root->n = 1;

}

else // tree is not empty

{

if (root->n == 2 * t - 1) // root is full

{

// Allocate memory for new root

// Make old root as child of new root

// Split ~~the~~ old root and move

middle key value to new root

// insert the new key value to
appropriate child of new root.

```

    }
    else // If root is not full,
        root → insertNonFull (data);
    }
}

```

// Two functions to support insertion
 // splitChild() and insertNonFull()

```

void BTreeNode::splitChild(int i, BTreeNode *y)
{
    // New node going to store (t-1) keys of y
    BTreeNode *z = new BTreeNode(y → t, y → leaf);
    z → n = t-1;
}

```

// Copy the last (t-1) keys of y to z
 for (int j=0; j < t-1; j++)
 z → keys[j] = y → keys[j+t];

// copy last t children of y to z
 if (y → leaf == false)
 {

for (int j=0; j < t; j++)
 z → C[j] = y → C[j+t];
 y → n = t-1; // Reduce number of keys

// Create space for new child
 for (int j=n; j >= i+1; j--)
~~keys[j+1] = keys[j];~~
 C[j+1] = C[j];
 C[i+1] = z;

// Find location of newkey and move all greater keys one space ahead

```
for (int j = n-1; j >= i; j--)
    keys[j+1] = keys[j];
```

```
keys[i] = newkey;
```

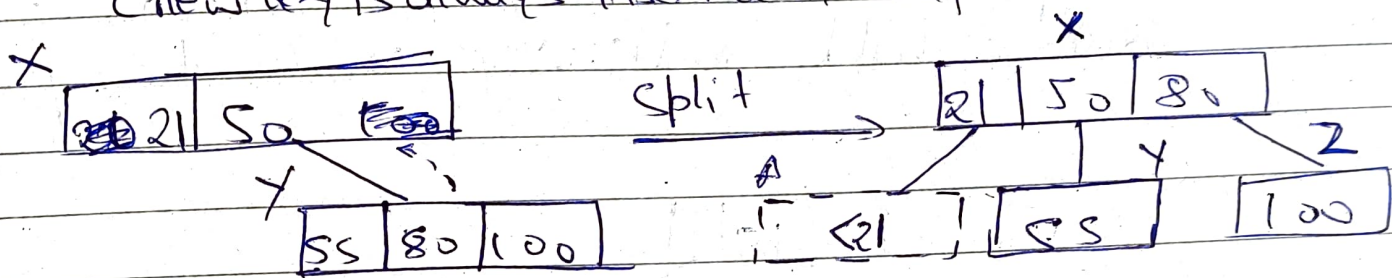
```
n = n+1;
```

```
}
```

Insertion is implemented using proactive insertion algorithm where before going down, we split the current node if it is full.

Advantage

- 1 Do not traverse a node twice
- 2 Always have a free space in the leaf node (new key is always inserted at leaf node)



- 1 Initialize X as root
- 2 While X is not leaf, do following
 - a) Find the child of X that is going to be traversed next. Let the child be Y .
 - b) If Y is not full, change X to point to Y .
 - c) If Y is full, split it and change X to point to one of the two parts of Y . If k is smaller than midkey in Y , the set X as first part of Y , else second part of Y .
- 3 The loop in step 2 stops when X is leaf. X must have space for 1 extra key as we have been splitting all nodes in advance.