IBMIRCSO28 10-11-50 Actificial Intelligence with Ohrur Agrawal Rythan SA Computer Science Lab test-1 and Engineering 8 Puzzle Problem A\* Algorithm At algorithm is an informed search algorithm / Heuristic algorithm. In informed algorithm, problem specific knowledge is known and used by search strategy to solve problem. In A\* algorithm, we use J(n)= q(n) + h(n) g(n) = Foctual cost to reach node n h(n) = Estimated/heuristic cost to reach goal node , from node v f(n) = Total estimated cost to reach goal node A\* algorithm is admissible, that is, it do not overestimate the bath cost, so it leads to optimal solution AI

1BM16(2058 We will have two classes Dhrur Agrawal Node } · Defining a node structure · Methods to en generate child nodes Puzzle). Class actually implementing the puzzle
Methods to calculate heuristic value and total f(n) det -init- (self, data, level, fual): # initializing the class Node: def generalechild ( self): # Getting blank space position It Then swapping to get children of class Puzzle: def -- init-- (self, size): #Initializing Iwo lists self. n = size self. open = [] self-close [] def Jual (self, stort, goal): # Gretting the f(n) return g(start) + h(start) det start-problem (self): # Get start state and goal state # Traverse through initial state (100+) fill the goal state.

DNIM Agranal Start with root node Cifchildis notinglist

place it in open list If it's not the goal state, generate the child calcultate (Ca) for each whild

child with least f(n) is selected and

continued further

· Place the explored node in closed

So, repeat process a till you get the goal state

AI